



1 **Karst aquifer discharge response to rainfall interpreted as anomalous transport**

2 Dan Elhanati<sup>1</sup>, Nadine Goeppert<sup>2, 3</sup>, Brian Berkowitz<sup>1</sup>

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4 <sup>1</sup>Department of Earth and Planetary Sciences, Weizmann Institute of Science, Rehovot, Israel

5 <sup>2</sup>Institute of Applied Geosciences, Division of Hydrogeology, Karlsruhe Institute of  
6 Technology (KIT), Karlsruhe, Germany

7 <sup>3</sup>Institute of Geological Sciences, Hydrogeology, Free University Berlin, Germany

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9 Correspondence to: Dan Elhanati (dan.elhanati@gmail.com)

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13 **Abstract**

14 The discharge measured in karst springs is known to exhibit distinctive long tails during  
15 recession times following distinct discharge peaks of short duration. The long-tail behavior is  
16 generally attributed to the occurrence of tortuous, ramified flow paths that develop in the  
17 underground structure of karst systems. Modeling the discharge behavior poses unique  
18 difficulties because of the poorly-delineated flow path geometry and generally scarce  
19 information on the hydraulic properties of catchment-scale systems. In a different context,  
20 modeling of long-tailed behavior has been addressed in studies of chemical transport. Here, an  
21 adaptation of a continuous time random walk – particle tracking (CTRW-PT) framework for  
22 anomalous transport is proposed, which offers a robust means to quantify long-tailed  
23 breakthrough curves that often arise during chemical species transport under various flow  
24 scenarios. A theoretical analogy is first established between partially water-saturated karst flow,  
25 characterized by temporally varying water storage, and chemical transport involving  
26 accumulation and release of a chemical tracer. This analogy is then used to develop and  
27 implement a CTRW-PT model. Application of this numerical model to examination of three  
28 years of summer rainfall and discharge data from a karst aquifer system – the Disnerschroef  
29 high alpine site in the Austrian Alps – is shown to yield robust fits between modeled and  
30 measured discharge values. In particular, the analysis underscores the predominance of slow  
31 diffusive flow over rapid conduit flow. The study affirms the analogy between partially  
32 saturated karst flow and chemical transport, exemplifying the compatibility of the CTRW-PT  
33 model for this purpose. Within the specific context of the Disnerschroef karst system, these  
34 findings highlight the predominance of slow diffusive flow over rapid conduit flow. The  
35 agreement between measured and simulated data supports the proposed analogy between  
36 partially saturated karst flow and chemical transport; it also highlights the potential ability of  
37 the anomalous transport framework to further enhance modeling of flow and transport in karst  
38 systems.



## 39 **1 Introduction**

40 Aquifers consist of various geological formations through which water can flow and carry  
41 chemical species. The abundance of structural heterogeneities, ranging from intricate grain  
42 arrangements at the pore scale to larger geologic structures and discontinuities at the meso- and  
43 macroscopic scales, introduces irregular and tortuous flow paths that cannot be delineated  
44 without a full physical description of the system. Achieving an accurate representation of flow  
45 and transport therefore becomes increasingly difficult with an increase in the scale and  
46 complexity of the groundwater system.

47 Karst systems, in particular, are known as structurally complex aquifers. They are composed  
48 of many interconnected conduits, fractures and voids formed through the dissolution of soluble  
49 rocks like limestone, dolostone and gypsum, which leads to the occurrence of multiple and  
50 ramified flow paths (Bakalowicz, 2005). Karst terrains are usually described, in a vertical  
51 cross-section, by distinct hydrological layers whose structure affect the response of the system  
52 to incoming precipitation: (1) the surface soil layer; (2) the interface between the soil layer and  
53 the deeper saturated zone (epikarst); and (3) the deep underground, mostly phreatic, zone  
54 (endokarst). The soil and epikarst layers, known collectively as the exokarst, are known to  
55 exhibit lateral flow of water above and below ground, until water reaches fractures or conduits  
56 that allow them to flow rapidly to the endokarst. This allows for some water to infiltrate  
57 downwards, while some may remain in the vadose zone and be subjected to both percolation  
58 and evapotranspiration (Jukić and Denić-Jukić, 2009). The epikarst and endokarst layers each  
59 consist of a primary (matrix) porosity composed of all bulk pores, a secondary porosity  
60 composed of the smaller joints and fissure developed during diagenesis and/or by tectonic  
61 processes, and a tertiary porosity of large fractures and voids (conduits) created due to  
62 karstification (Ford and Williams, 2007). The different types of porosities usually exhibit  
63 distinct flow patterns: rapid flow in the conduits and slow diffusive flow in the smaller fissures  
64 and the matrix. The different karst layers may exhibit a changing role in facilitating the flow or  
65 retention of water through the system as a function of water level or recharge intensity  
66 (Hartmann et al., 2014).

67 To date, various hydrological models have been developed specifically for karst systems, to  
68 describe the commonly observed flow and transport patterns that are specific to karst systems.  
69 In particular, distributed models rely on creating a grid of cells with different hydrological  
70 parameters (e.g., Anderson & Radić, 2022; Chen et al., 2017; Kaufmann & Turk, 2016), while



71 lumped parameter models parameterize the characteristics of the system. Lumped parameter  
72 models are based on different system conceptualizations (e.g., Chen and Goldscheider, 2014;  
73 Cinkus et al., 2023b; Fleury et al., 2009; Jukić and Denić-Jukić, 2009; Mazzilli et al., 2019;  
74 Rimmer and Salingar, 2006; Tritz et al., 2011), as well as neural network approaches (e.g.,  
75 Afzaal et al., 2020; Cinkus et al., 2023b; Kratzert et al., 2018; Renard and Bertrand, 2017;  
76 Wunsch et al., 2022). A common, significant feature encountered in karst systems – which is  
77 difficult to capture in models – is the interplay of rapid and slow flow which manifests as long-  
78 tailed measurements of both discharge rates (e.g., Frank et al., 2021) and chemical tracer  
79 concentrations (e.g., Goepfert et al., 2020) observed at karst springs.

80 In many systems that exhibit highly variable spatial velocity distributions or temporal  
81 behaviors, measurements of long tails in arrival times may be encountered. In the context of  
82 chemical transport in porous media, long tails in the arrival time of chemical tracers have long  
83 been a subject of study. Anomalous transport, which describes chemical transport that deviates  
84 from the behavior described by the traditional Advection-Dispersion Equation (ADE), is  
85 prevalent in many system and transport scenarios (Berkowitz et al., 2006); deviations from  
86 solutions of traditional transport equations were observed even for non-dispersive diffusion  
87 (Cortis and Knudby, 2006). It has been shown that higher subsurface heterogeneity increases  
88 the degree of anomalous transport by inducing longer than expected (for Fickian transport)  
89 arrival times (Edery et al., 2016, 2014). Traditional ADE based models, which rely on  
90 averaging the physical traits of the medium into a single coefficient, do not accurately predict  
91 transport in many cases. To correctly describe long-tailed events, various modeling approaches  
92 have been developed. Among these, the Continuous Time Random Walk (CTRW) framework  
93 has emerged as suitable for simulating diverse transport scenarios, including the behavior of a  
94 long-time field-scale hydrological catchment (Dentz et al., 2023). The CTRW framework  
95 accounts for anomalous transport behavior and offers a more physically realistic representation  
96 of the transport processes that are encountered in real-world groundwater systems. The  
97 framework defines waiting time and step length distributions that are applied in random walks  
98 which are continuous in time, thereby capturing the complexity of transport processes  
99 (Berkowitz et al., 2006).

100 In the current study, the CTRW framework, which has been developed to model anomalous  
101 chemical transport, is utilized to quantify long-tailing of water flow in karst systems. In this  
102 context, data from the Disnerschroef alpine study site in Vorarlberg, Austria are revisited  
103 (Frank et al., 2021). This high-alpine karst system has been thoroughly studied and offers a



104 well-defined spatial catchment. The known extent of its recharge basin and the corresponding  
105 single spring which serves as its outlet allow for measurements of both recharge and discharge.  
106 Previous studies (e.g., Frank et al., 2021) identified a distinct discharge response approximately  
107 5.5 hours after a rainfall event, with variations in electrical conductivity, indicative of fresh  
108 rainfall arriving at the spring outlet, observed ~8 hours post-event. While existing models  
109 provided a good overall fit and illuminated the divide between epikarst-to-conduit and matrix-  
110 to-conduit flows, they were less effective in matching the long tails.

111 Accurate modeling of water movement in these complex subsurface landscapes is crucial, as  
112 many regions rely on karst systems for drinking water (Stevanović, 2019). Here, a theoretical  
113 and practical development of the CTRW framework is proposed as an approach to simulate the  
114 intricate dynamics of water movement in karst environments.

## 115 **2 Conceptual and mathematical development**

116 The conceptual development of the CTRW framework to model water flow in karst systems is  
117 founded on a proposed ansatz in which water flow is conceptualized as distinct “water parcels”  
118 that travel along the available flow paths. Local volumes along the flow paths, e.g., caverns,  
119 conduits, and voids, allow for the accumulation and release of water parcels, and define mobile  
120 and immobile zones for water flow. The ansatz asserts that the accumulation and release of  
121 water parcels in the various volumes in the karst system resemble the accumulation and release  
122 of a chemical tracer over time in a porous medium. As shown in Fig. 1, a cavern acting as a  
123 storage region for water parcels is analogous to tracer parcels accumulating in an immobile (or  
124 less mobile) zone. For both cases, it should be noted that local accumulation of water parcels  
125 or increase in concentration of a chemical will increase their respective fluxes in the immediate  
126 local vicinity. Under similar hydraulic conditions both fluxes create distinctive long tails when  
127 measured over a control plane at the system outlet, which is primarily a result of the structural  
128 heterogeneity of the system.

129 Characterizing the flow of water through an infinitesimal control volume can be formulated in  
130 terms of a balance equation that equates the net rate of fluid flow in the control volume to the  
131 time rate of change of fluid mass storage within it:

$$132 \quad -\frac{\partial(\rho q_x)}{\partial x} - \frac{\partial(\rho q_y)}{\partial y} - \frac{\partial(\rho q_z)}{\partial z} = \frac{\partial(\rho n)}{\partial t} \quad (1)$$

133 where  $n$  is porosity,  $\rho$  water density, and the three components of the specific discharge  $q$  are  
134 described as  $q_x$ ,  $q_y$  and  $q_z$ . This equation describes the mass balance in a fully saturated domain,



135 in which the void volume ( $V_v$ ) is completely filled with water ( $V_w=V_v$ ). The moisture content  
 136 ( $\theta = \frac{V_w}{V_{tot}}$ ) in these cases is equal to the porosity, and the degree of saturation ( $\theta' = \frac{\theta}{n}$ ) is equal  
 137 to 1.

138 For partially saturated flow, the degree of saturation is less than 1 and the moisture content is  
 139 smaller than  $n$  (as  $V_w < V_v$ ). Adjusting the equation for partially saturated transient flow yields:

$$140 \quad -\frac{\partial(\rho q_x)}{\partial x} - \frac{\partial(\rho q_y)}{\partial y} - \frac{\partial(\rho q_z)}{\partial z} = \frac{\partial(\rho \theta' n)}{\partial t} . \quad (2)$$

141 Substituting  $\theta' = \frac{\theta}{n}$ :

$$142 \quad -\frac{\partial(\rho q_x)}{\partial x} - \frac{\partial(\rho q_y)}{\partial y} - \frac{\partial(\rho q_z)}{\partial z} = \frac{\partial(\rho \theta)}{\partial t} . \quad (3)$$

143 Deriving a description for a chemical tracer transport in a similar control volume is achieved  
 144 by a mass balance equation:

$$145 \quad -\frac{\partial F_x}{\partial x} - \frac{\partial F_y}{\partial y} - \frac{\partial F_z}{\partial z} = n \frac{\partial C}{\partial t} . \quad (4)$$

146 The chemical mass flux (in one direction) is defined by advection and diffusion terms:

$$147 \quad F_i = q_i C - n D_i \frac{\partial C}{\partial i} . \quad (5)$$

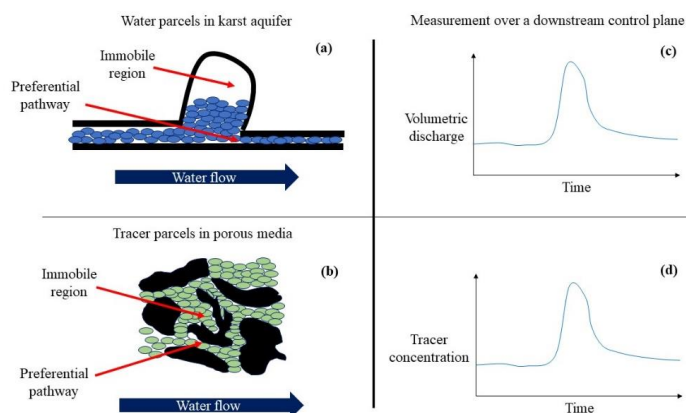
148 Substituting (5) into (4) yields

$$149 \quad \frac{\partial}{\partial x} \left( n D_x \frac{\partial C}{\partial x} \right) - \frac{\partial}{\partial x} (q_x C) + \frac{\partial}{\partial y} \left( n D_y \frac{\partial C}{\partial y} \right) - \frac{\partial}{\partial y} (q_y C) + \frac{\partial}{\partial z} \left( n D_z \frac{\partial C}{\partial z} \right) - \frac{\partial}{\partial z} (q_z C) = n \frac{\partial C}{\partial t} . \quad (6)$$

150 By drawing the analogy in the ansatz between the dynamics of water parcels and chemical  
 151 tracers, and noting the similar forms of Eqs. (3) and (4), the description of the mass balance of  
 152 water in a partially saturated domain is (at least) mathematically analogous to the description  
 153 of the mass balance of a chemical tracer in a saturated domain. This results in the intrinsic  
 154 connection of  $C \Leftrightarrow \rho \theta$ . In a 1D direction, the analogy of the mass flux can be thus defined:  
 155  $\rho q_x \equiv n D_x \frac{\partial C}{\partial x} - q_x C$ . This connection incorporates hydrodynamic dispersion, which is  
 156 inherent in chemical transport resulting in observed long tails, into the description of the  
 157 partially saturated water parcels moving within the conceptual karst domain. Thus, the analogy  
 158 of chemical transport and water flow is expected to show long tailing in simple flow scenarios,  
 159 and was established even for pure diffusion (Cortis and Knudby, 2006).



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161

162 **Figure 1.** Schematic illustration of (a) water parcels (blue ovals) in a karst aquifer; and (b)  
163 chemical tracer parcels (green ovals) in porous media (black grains) flowing through  
164 preferential pathways and accumulating in adjunct immobile regions. The resulting  
165 (schematic) measurements of the (c) temporal volumetric discharge and (d) tracer  
166 concentration that are measured at the spring outlet further downstream.

167

168 Thus, transport equations – either advection-dispersion equations (ADE; Eq. (6)) for Fickian  
169 transport, or a CTRW formulation for non-Fickian transport (see Sect. 3.1) can be used, where  
170 the chemical tracer concentrations that these equations solve for  $C(x,t)$  are conceptually  
171 identical to the relative concentration of water parcels. The concentration at a specific point is  
172 translated to a volume of water, so that a classical breakthrough curve  $C(t)$  is reinterpreted as  
173 the (volumetric) amount of water per time reaching the domain outlet (or measurement plane).

### 174 3 Methods

#### 175 3.1 CTRW-PT simulations

176 In this study, a particle tracking (PT) implementation of the CTRW framework was employed  
177 to devise a model capable of simulating spring discharge using the rainfall data as input. The  
178 CTRW-PT model, characterized by stochastically defined particle transitions, is a Lagrangian  
179 approach to solving the partial differential equations defined in the CTRW mathematical  
180 framework. The movement of the particles, representing water parcels as described in the  
181 ansatz (see Sect. 2), is described by equations that define the probability of particles to make



182 transitions in both space and time (Elhanati et al., 2023). For 1D cases, the transport is governed  
183 by two probability density functions,  $p(s)$  and  $\psi(t)$ , which define the particle movement in space  
184 and time, respectively. An exponential form for  $p(s)$  and a truncated power law (TPL) form for  
185  $\psi(t)$  are used:

$$186 \quad p(s) = \lambda_s^2 \exp(-\lambda_s s), \quad (7)$$

$$187 \quad \psi(t) = C \frac{\exp(-t/t_2)}{(1+t/t_1)^{1+\beta}}. \quad (8)$$

188 Here,  $\lambda_s^2$  and  $C$  serve as normalization factors for  $p(s)$  and  $\psi(t)$ , respectively. The TPL is  
189 governed by  $\beta$ , the power law exponent ( $0 < \beta < 2$ ), which is a measure of the non-Fickian  
190 nature of the transport,  $t_1$ , the characteristic transition time, and  $t_2$ , the cutoff time to initiate  
191 transition to Fickian transport. The particle velocity,  $v_\psi$ , and the generalized dispersion,  $D_\psi$ ,  
192 are defined as the first and second spatial moments of the chemical species plume in the flow  
193 direction (Berkowitz et al., 2006) For a 1D system:

$$194 \quad v_\psi = \frac{\bar{s}_x}{\bar{t}} = \frac{\int_0^\infty p(s)s^2 ds}{\int_0^\infty \psi(t)t dt}, \quad (9)$$

$$195 \quad D_\psi = \frac{1}{2} \frac{\bar{s}_x^2}{\bar{t}} = \frac{1}{2} \frac{\int_0^\infty p(s)s^3 ds}{\int_0^\infty \psi(t)t dt}, \quad (10)$$

196 where  $\bar{s}_x$  and  $\bar{t}$  are the mean step size and time, respectively.

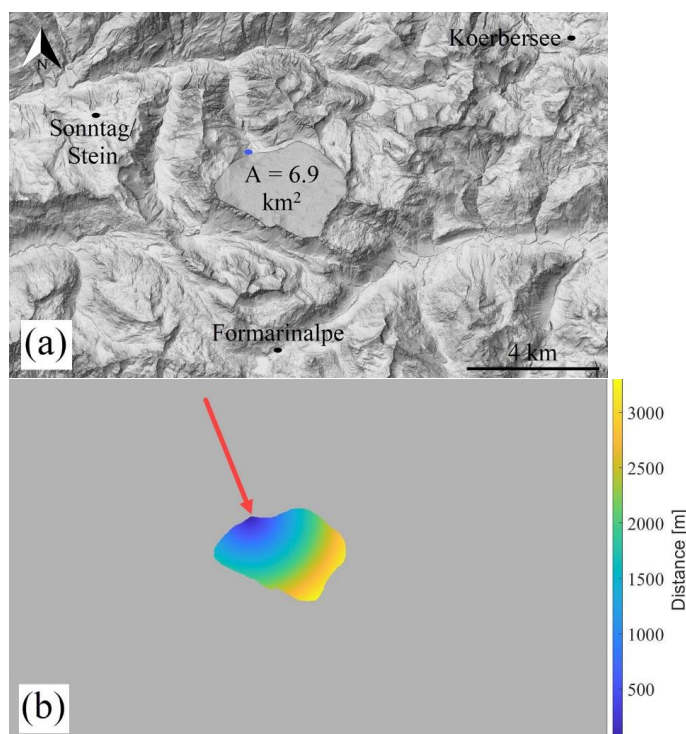
197 Inserting the probability density functions (Eqs. 7 and 8) into Eqs. 9 and 10, and defining  $\tau_2 \equiv$   
198  $t_2/t_1$  yields a mathematical relation among  $v_\psi$ ,  $D_\psi$ ,  $\beta$ ,  $\tau_2$ ,  $t_1$ ,  $t_2$  and  $\lambda_s$  (see Nissan et al., 2017  
199 for a full mathematical development). By treating the first four variables ( $v_\psi$ ,  $D_\psi$ ,  $\beta$ ,  $\tau_2$ ) as  
200 fitting parameters, the other three ( $t_1$ ,  $t_2$ ,  $\lambda_s$ ) are immediately determined, allowing  
201 optimization of the CTRW-PT model to a specific flow scenario (see Table 1).

202 The intricate three-dimensional flow field of a karst system can be conceptualized in a model  
203 that considers the relationships between storage and discharge. These kinds of models, known  
204 as lumped models, have been extensively used in simulation of karst systems (Hartmann et al.,  
205 2014). Herein, a similar approach is applied, i.e., conceptualizing the system as a series of  
206 specific physical transitions. However, in the context of the CTRW-PT model, an equivalent  
207 medium to the karst system is defined in the form of a one-dimensional domain. Water is  
208 introduced into the domain along its entire extent and flows to the domain outlet.





209 The 1D conceptualization is facilitated by the well-defined spatial characteristics of the system,  
210 namely the catchment area and spring outlet (Fig. 2a). The distance of each point on the surface  
211 of the catchment to the spring outlet is calculated (Fig. 2b), which yields a distances frequency  
212 histogram (Fig. 3). A normal distribution, fitted to the histogram using MATLAB, dictates how  
213 new particles are introduced into the system along the 1D domain (physically unrealistic,  
214 negative sampled values are set to 0). The actual underground flow path between each point  
215 and the outlet spring is longer than the linear distance between the two points, as the water  
216 must travel through the tortuous path through the existing conduits and fissures. The distances  
217 are therefore multiplied by an empirical tortuosity factor ( $L$ ), which serves as an optimization  
218 parameter (see Table 1).

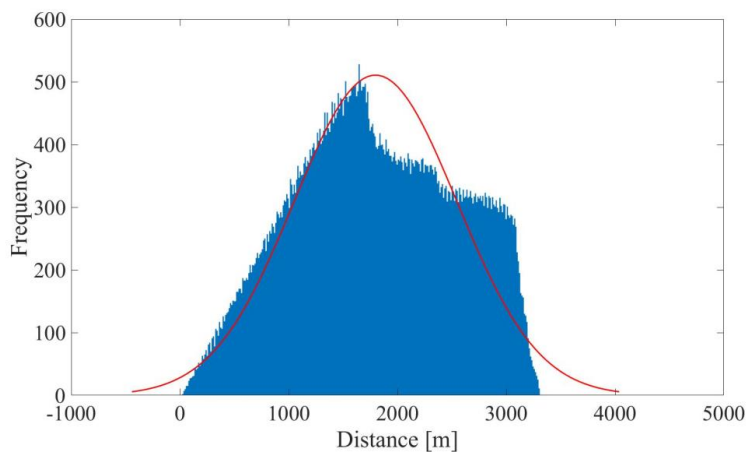


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220 **Figure 2.** (a) Map of the Disnerg Schroef study area. The three weather stations in which rainfall  
221 was measured are marked with black dots, the measured spring outlet is marked with a blue  
222 dot (basemap: Land Vorarlberg – data.vorarlberg.gv.at); (b) Distances from the catchment  
223 area to the spring outlet. The distances are marked by a color scale. The spring outlet is marked  
224 by a red arrow.



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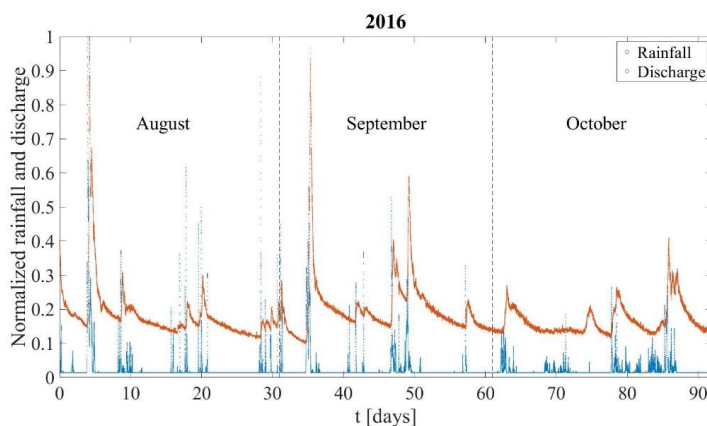


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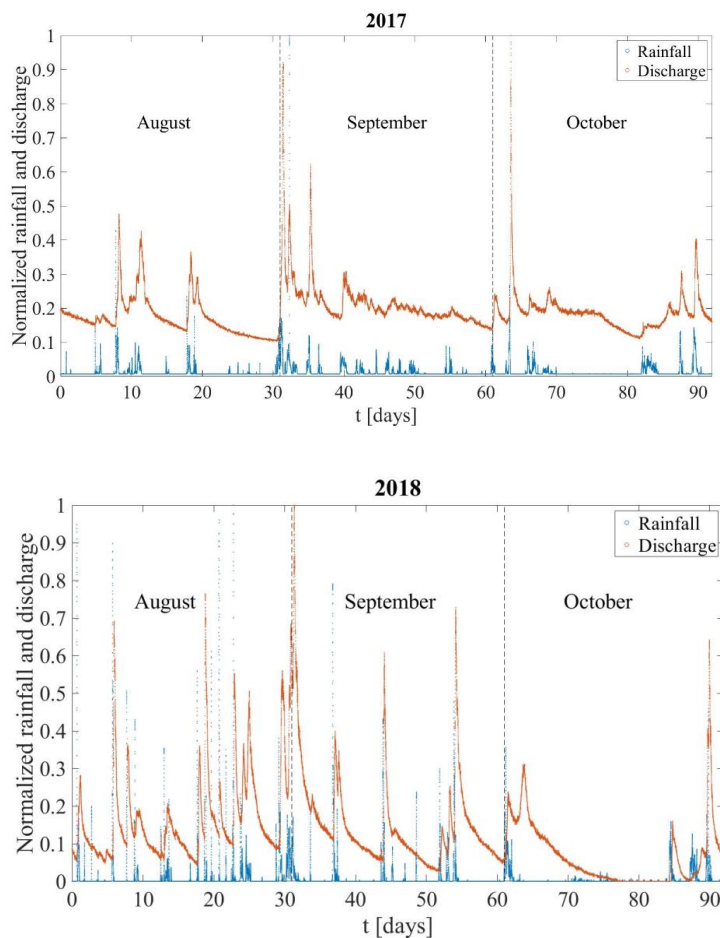
227 **Figure 3.** Distribution of distances from catchment area to spring outlet. The red line represents  
228 a fitted normal distribution ( $\mu=1.8\times 10^3$ ;  $\sigma=747$ ).

229 Discharge at the spring is sampled every 15 minutes ( $\text{L s}^{-1}$ ). The discharge minimum represents  
230 baseflow conditions. Raw rainfall data from three nearby weather stations (Fig. 2a) are  
231 measured in millimeters per 15 minutes. The data from the three stations are averaged, and the  
232 catchment area is used to convert the data into liters per second (Fig. 4). To achieve higher  
233 temporal simulation resolution, linear interpolation was used to resample the time series to  
234 match a smaller simulation time step (100 s).

235



236



237

238 **Figure 4.** Rainfall and discharge curves for the 2016, 2017 and 2018 datasets. The data are  
 239 normalized according to the maximum rainfall and discharge values, respectively, for each of  
 240 the three years.

241

242 For an ideal system, in which all incoming rainwater is discharged through the spring outlet,  
 243 the ratio of total rainwater to total discharge is expected to be unity. However, considering the  
 244 uncertainty in the contributions of hydraulic parameters to the catchment water budget, e.g.,  
 245 flow to deeper parts of the aquifer and/or other springs, and evapotranspiration, the rainfall  
 246 function must be adjusted by a calculated observed recharge capacity to yield the recharge  
 247 function:

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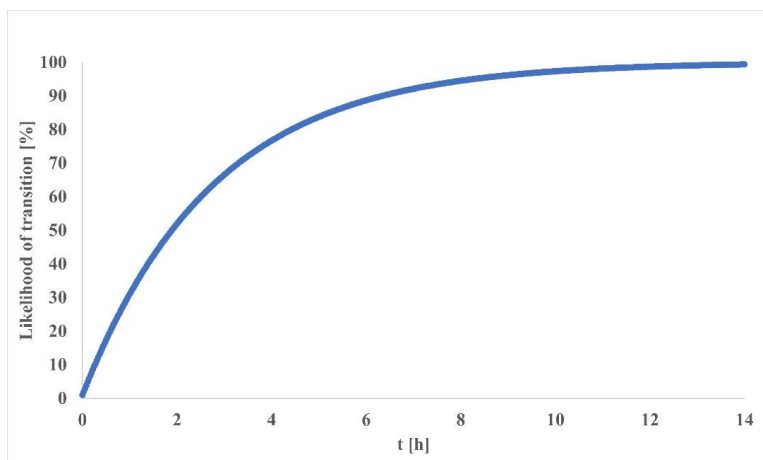
$$recharge(t) = rainfall(t) \times \frac{\sum discharge(t) - baseflow}{\sum rainfall(t)} \quad (11)$$



249 where  $rainfall(t)$  and  $discharge(t)$  are the measured rainfall and discharge time series. The ratio  
250 multiplying the rainfall function is defined here as the recharge capacity parameter. The  
251 baseflow was subtracted from the total discharge for the recharge capacity calculation, to  
252 account for the background discharge not related to the spring response to rainfall.

253 A common procedure in lumped karst models separates the flow into slow and fast components,  
254 representing the diffusive flow in the matrix and smaller fissures and the rapid flow in the  
255 conduits, respectively (Hartmann et al., 2014). The CTRW-PT, as opposed to lumped models,  
256 does not utilize water flow reservoirs, and operates by tracking the motion of particles that  
257 represent water parcels. Therefore, the model was adapted to implement a similar approach:  
258 two different sets of CTRW parameters, which govern the probability density functions for  
259 particle movement (see Eqs. 7-10), are defined to represent the two flow regimes. Each particle  
260 in the simulation is defined as “slow” or “fast”, and therefore obeys the corresponding set of  
261 CTRW parameters (see Table 1). Newly introduced particles are divided between fast and slow  
262 flow, according to a set ratio ( $SF_r$ ), and they advance in space and time by their corresponding  
263 set of CTRW parameters. Furthermore, each slow particle has a likelihood to transition into a  
264 fast particle ( $SF_f$ ) in each simulation iteration, by changing the set of CTRW parameters that  
265 the particle obeys. The transition from slow to fast flow illustrates the flow of water from the  
266 matrix/fissures to the conduits.

267 As depicted in Fig. 5, the likelihood of particle transition increases rapidly, with slow particles  
268 consistently transitioning into fast particles. For a transition likelihood of 0.01% and a  
269 simulation time step of 100 s, the likelihood for a single particle to make a transition surpasses  
270 99% after 458 steps which amount to 45,800 seconds (~12.7 hours). In comparison, the data  
271 and simulations presented in this study span a duration of 7,951,400 seconds (~92 days). These  
272 two parameters, governing the division of water between fast and slow flow and the transition  
273 of water from the matrix/fissures to the conduits, are pivotal in allowing the CTRW-PT model  
274 to simulate karst data.



275

276 **Figure 5.** Likelihood of particle transition from slow regime to fast regime ( $SF_i$ ) as a function  
277 time, representing a particle transition from slow matrix/fissure flow to fast conduit flow.

278

### 279 3.2 Model optimization and comparison to field measurements

280 Each particle represents a volume of water. The volume per particle was calculated by dividing  
281 the total observed rainfall volume by the number of simulation particles. This enables a  
282 comparison between simulated and observed recharge by volume. Given the presence of  
283 numerous model parameters (refer to Table 1), optimization is achieved by minimizing the  
284 Root Mean Squared Error (RMSE) between observed and simulated discharge using different  
285 combinations of parameter values. The 2016 dataset was first utilized for parameter  
286 optimization, while the 2017 and 2018 datasets served as targets for validation, by considering  
287 them for prediction using the optimized parameters from the 2016 dataset.

288 The Nash-Sutcliffe efficiency (NSE) was calculated for the optimized simulations, as a  
289 measure of the goodness of fit. It is described as a normalized variant of the mean squared  
290 error:

$$291 \quad NSE = 1 - \frac{\sum(x_s(t) - x_o(t))^2}{\sum(x_o(t) - \mu_o)^2} \quad (12)$$

292 where  $x_s$  is the simulated discharge,  $x_o$  is the observed discharge and  $\mu_o$  is the observed mean.  
293 The NSE performance criterion is widely used in hydrological studies and does not induce  
294 counterbalancing errors (Cinkus et al., 2023a).



295 **4 Results and Discussion**

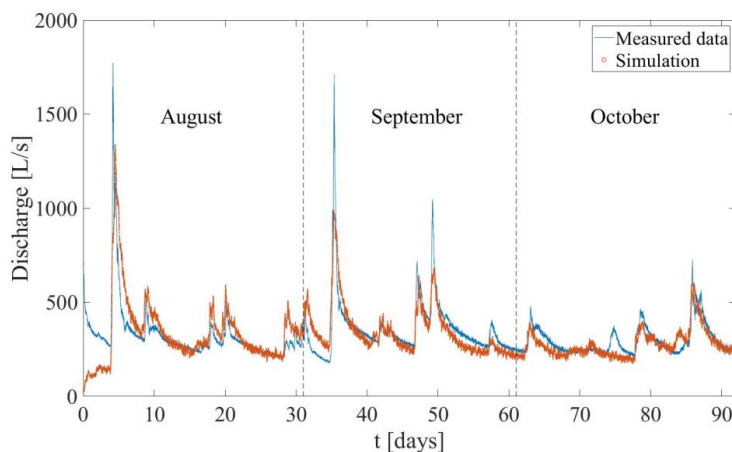
296 **4.1 Optimized simulations of measured discharge**

297 The optimized simulation for the 2016 dataset yields a fit (Fig. 6) that captures both the rapid  
 298 response of the spring discharge to rainfall events and the protracted relaxation times  
 299 characterized by the long tails evident after rainfall events. The optimized model parameters  
 300 for the slow diffusive and fast conduit flow components are detailed in Table 1.

301 **Table 1.** *Optimized model parameters.*

Parameter	Optimized value	Description
$v_{\psi}^f$	360 m h <sup>-1</sup>	Fast $v_{\psi}$
$D_{\psi}^f$	36 m <sup>2</sup> h <sup>-1</sup>	Fast $D_{\psi}$
$\beta^f$	1.7	Fast $\beta$
$\tau_2^f$	10 <sup>6</sup>	Fast $\tau_2$
$v_{\psi}^s$	18 m h <sup>-1</sup>	Slow $v_{\psi}$
$D_{\psi}^s$	3.6 x 10 <sup>8</sup> m <sup>2</sup> h <sup>-1</sup>	Slow $D_{\psi}$
$\beta^s$	1.2	Slow $\beta$
$\tau_2^s$	10 <sup>8</sup>	Slow $\tau_2$
$L$	1.6	Tortuosity
$SF_r$	0.95	Slow to fast particle ratio
$SF_l$	0.01 %	Slow to fast particle transition likelihood

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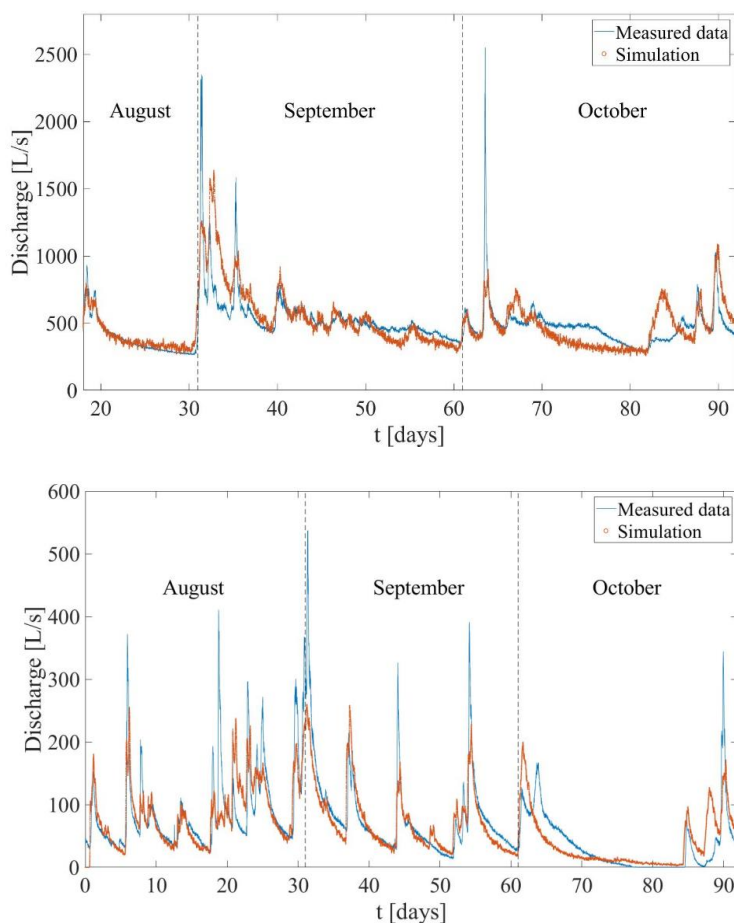
304 **Figure 6.** *Measured and simulated spring discharge for the 2016 dataset (NSE=0.5).*



305 The differences between the fast and slow flow components, as illustrated by the respective  
306 optimized CTRW parameters, elucidate the contribution of each flow component to the  
307 volumetric discharge. The fast flow velocity parameter ( $v_{\psi}^f = 360 \text{ m h}^{-1}$ ) is much larger than  
308 the slow flow velocity parameter ( $v_{\psi}^s = 18 \text{ m h}^{-1}$ ), and shows how incoming rain can rapidly  
309 flow to the spring outlet, when travelling through the large conduits. The slow diffusive flow,  
310 however, has a much longer travel time than the fast flow. Another clear difference between  
311 the two components which is evident from the optimized values is the degree of anomalous  
312 transport. The fast flow  $\beta$  (1.7) and  $\tau_2$  ( $10^6$ ) parameters lead to a more symmetrical contribution  
313 to the resulting discharge around the peak following the recharge event, compared to the slow  
314 flow parameters ( $\beta=1.2$ ,  $\tau_2=10^8$ ), which create a long tail after the discharge peak. The slow  
315 flow is also much more dispersive ( $D_{\psi}^s = 3.6 \times 10^8 \text{ m}^2 \text{ h}^{-1}$ ) compared to the fast flow ( $D_{\psi}^f =$   
316  $36 \text{ m}^2 \text{ h}^{-1}$ ), which contributes further to the long discharge tails. The optimized parameters  
317 show a strong prominence of the slow flow over the fast flow: 95% of newly introduced  
318 particles are introduced as slow particles ( $SF_i$ ), with a 0.01% likelihood for a slow particle to  
319 transition at each iteration to a fast regime ( $SF_i$ ).

320 The fit obtained for the 2016 dataset modeling is satisfactory considering the inherent  
321 uncertainty associated with the input data. The three weather stations used to measure the  
322 precipitation are not located inside the catchment area, and different precipitation data were  
323 measured at each station, which can be seen by examining the cross-correlation coefficients  
324 between the 2016 discharge and rainfall data: 0.20, 0.22 and 0.15 for stations Koerbersee,  
325 Formarinalpe, Sonntag/Stein, respectively (Fig. 2a). While an average of the three stations  
326 provides an acceptable estimate of the recharge over the given time period, the variability of  
327 local rain events is overlooked, which may be common in the high mountainous topography.  
328 This is especially true in extreme rain events, in which variations of onset, duration, and total  
329 discharge of an event can induce different responses of the modeled discharge.

330 The same set of CTRW parameters optimized for the 2016 data – without further adjustment –  
331 was employed to interpret the 2017 and 2018 datasets (Fig. 7). Both datasets show that the  
332 simulated discharge after rainfall events predicts the onset, length and volume of the measured  
333 discharge. This is especially true for the many discharge peaks exhibited by the 2018 data.



334

335 **Figure 7.** Measured and simulated spring discharge for the 2017 (top;  $NSE=0.33$ ) and 2018  
336 (bottom;  $NSE=0.63$ ) datasets. Note that due to the large differences in maximum discharge  
337 between the three years, the vertical scales in Fig. 6 and in Fig. 7 are adjusted accordingly.

338

339 The recharge capacity parameter (applied to calculate the recharge function from the measured  
340 rainwater; see Eq. 11) was calculated as 0.43 and 0.45 for the 2016 and 2017 datasets,  
341 respectively. These values suggest that ~40% of the incoming rainfall reaches the outlet spring,  
342 with the remaining water reaching deeper parts of the aquifer that are less mobile. The drier  
343 2018 dataset, however, displayed a much lower value of 0.19. The variability of the recharge  
344 capacity parameter in different time periods, as a function of the rainfall pattern and amount,





345 highlights the importance of this parameter to the correct prediction of the system discharge  
346 response to rainfall.

#### 347 **4.2 Prominence of the slow flow component in the Disnergenschroef system**

348 The prominence of the slow component in this karst system is evident from both the high  $SF_r$   
349 and low  $SF_l$ . The consistency of this finding, across the three datasets (Fig. 6 and 7), agrees  
350 with the analysis by Frank et al. (2021) of the recharge/discharge relationship. They observed  
351 that while the flow from epikarst to conduit and matrix is highly variable and rainfall-  
352 dependent, the matrix to conduit flow remains relatively constant up to a threshold. The  
353 coupling of the two flow processes produces a distinctive discharge pattern characterized by a  
354 sharp rapid peak after a rainfall event, followed by a long tail during recession and a return to  
355 baseflow. The current analysis is similar and further emphasizes that the volumetric  
356 contribution of the slow flow is substantial, particularly influencing the extended tails. In  
357 contrast, the fast flow plays a more straightforward role, contributing predominantly to  
358 discharge peaks by quickly expelling introduced rainwater from the system.

359 Given the importance of karst systems for human consumption, monitoring and prediction of  
360 system discharge is especially important during high and low flow scenarios. These extreme  
361 events can have consequences on water quality, including over-consumption during dry periods  
362 and increases in turbidity and bacterial activity in high flow conditions (Pronk et al., 2006).  
363 The frequency of both dry periods and heavy rainfall events has been shown to rise due to  
364 climate change (Stoll et al., 2011), and this may well increase in the near future. In this context,  
365 the high peaks and long tails associated with these flow conditions have proven to be the most  
366 difficult to correctly predict, across different karst modeling approaches (Jeannin et al., 2021).  
367 The results presented of the CTRW modeling exhibits the long tails associated with low water  
368 flow. The 2018 dataset, in particular, which represents a dry summer compared to the other two  
369 datasets, exemplifies the robustness of the model in predicting low flow conditions.

#### 370 **4.3 The contribution of the slow and fast flow components to simulated discharge**

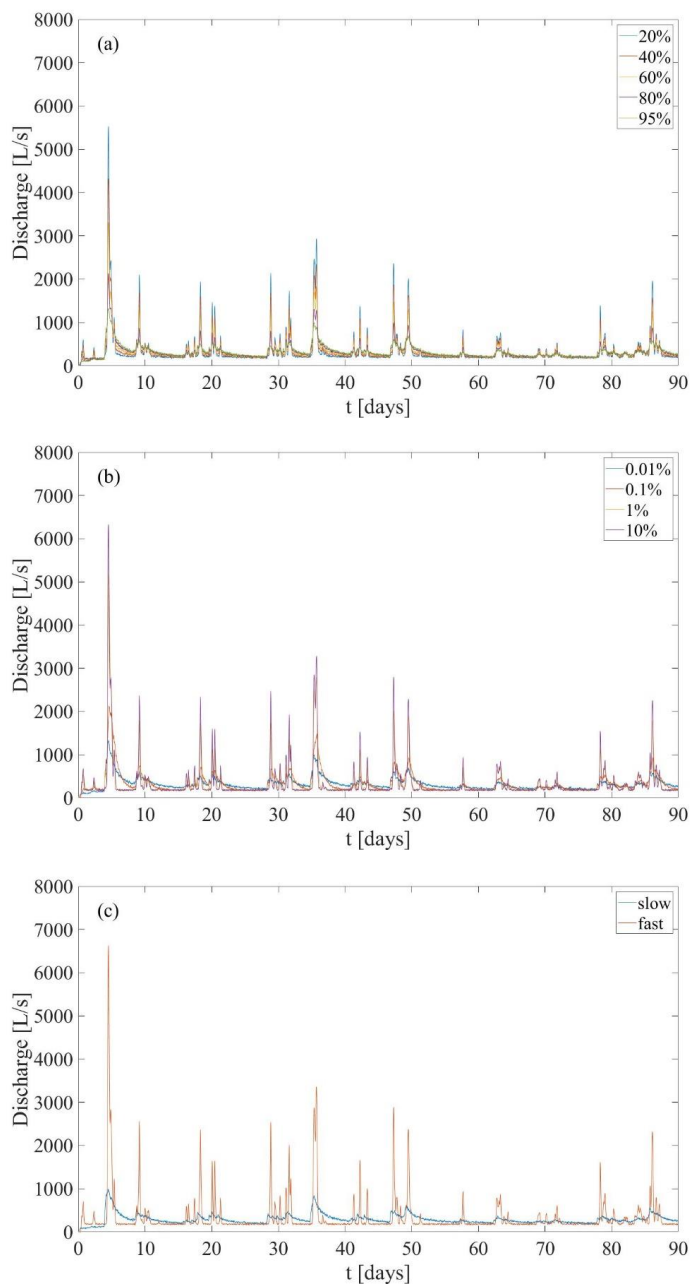
371 The results for all three datasets do not show agreement between the maximum simulated and  
372 observed discharge values that are found immediately after high recharge events. The better fit  
373 of the long tails compared to the high peaks is evident in the improvement of the NSE values  
374 presented above (0.50, 0.33, 0.63 for 2016, 2017 and 2018, respectively), when calculated for  
375 the data without the prominent peaks (0.75, 0.60, 0.65 for 2016, 2017 and 2018, respectively).  
376 The dry 2018 dataset is the least affected from removing the peak for the NSE calculation



377 because the peaks are low relatively to the 2016 and 2017 datasets. The fast response of  
378 discharge to the incoming rain in karst systems after high recharge events has been described  
379 in previous studies as a piston effect (Aquilina et al., 2006; Hartmann et al., 2014). Incoming  
380 rain creates a rise in discharge before the rainwater reaches the outlet, as the increase in  
381 hydraulic head pushes out water that was retained in the system before the rain. This effect was  
382 shown specifically in the Disnergschroef system by Frank et al. (2021) which measured a 2.5-  
383 hour difference between the first response of spring discharge to a rainfall event, to the arrival  
384 of the rainwater to the outlet. The model herein does not take this effect into account, which  
385 creates the negative bias in modeling the high peaks. While outside the scope of this study, this  
386 can be addressed in the future by adding a third flow component, or by altering the CTRW  
387 parameters of the particles present in the system prior to the rainfall event to represent the  
388 increase in flow velocity.

389 To further examine the effect of both the slow and fast flow components on the simulated  
390 discharge, simulations that examine the  $SF_1$  and  $SF_r$  parameters across a wider range were  
391 conducted (Fig. 8). Simulations that contained only fast or slow particles (Fig. 8a), clearly show  
392 that fast flow discharge responds very quickly to rainfall and produces no observable tails. In  
393 contrast, the slow flow produces very long tails. It is noteworthy that the first response of the  
394 slow flow is similar to the fast flow, as particles that are introduced to the system close to the  
395 outlet have a very short length to travel to reach the outlet. Mixing of both flow regimes, either  
396 by directly splitting the particles between the two regimes as they are introduced (Fig. 8b) or  
397 by changing the transition likelihood (Fig. 8c) produces an intermediate response: as more of  
398 the flow is slow, longer tails are found but the peaks are smaller.

399



400

401 **Figure 8.** Simulation sensitivity to slow and fast particle contribution, based on the 2016  
402 rainfall data. Simulations containing only one kind of particle (a), Slow/Fast ratio (b) and  
403 transition likelihood from slow to fast (c) demonstrate the importance of the slow flow for the  
404 observed long tails in the discharge data.



405 **5 Conclusions**

406 An analogy between partially saturated water flow in karst aquifers and anomalous chemical  
407 transport is established, allowing for the adaption of the CTRW-PT model to water flow in  
408 general, and for karst discharge response to rainfall specifically. The model was calibrated on  
409 one summer season of measurements of spring outlet discharge response to incoming rain; it  
410 was then used to predict the long tails observed in discharge measurements following rainfall  
411 events in two subsequent summer seasons.

412 The investigation of the Disnergshroef karst system has showed that slow diffusive flow is a  
413 predominant contributor to the volumetric discharge response to recharge events, in  
414 comparison to fast conduit flow. This finding highlights the nuanced interplay between fast and  
415 slow flow components in karst systems, and how they both evolve over time and as a function  
416 of the recharge intensity.

417 The theoretical and practical advancements presented here offer a potentially robust tool to  
418 further assess long-tailed rainfall-discharge responses in karst systems and other complex,  
419 catchment-scale systems.

420

421



422 **Data availability**

423 The data on which this article is based are available online on Zenodo:  
424 <https://zenodo.org/doi/10.5281/zenodo.10635639> (Elhanati and Berkowitz, 2024).

425 **Author contribution**

426 DE, NG and BB formulated the ideas which originated the project and defined the goals and  
427 aims of the study. DE developed and implemented the methodology and carried out the data  
428 analysis. DE and BB drafted the initial manuscript. All authors took part in reviewing and  
429 editing the final manuscript.

430 **Competing interests**

431 BB is a member of the editorial board of the journal.

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440

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