



Determining the threshold of issuing flash flood 1 warnings based people's response on 2 process simulation 3 4 Ruikang Zhang^{a, b}, Dedi Liu^{a, b, c*}, Lihua Xiong^{a, b}, Jie Chen^{a, b}, Hua Chen^{a, b}, Jiabo 5 Yin^{a, b} 6 7 8 ^a State Key Laboratory of Water Resources Engineering and Management, Wuhan University, 9 Wuhan, China 10 ^bHubei Provincial Key Lab of Water System Science for Sponge City Construction, Wuhan 11 University, Wuhan, China 12 ^c Department of Earth Science, University of the Western Cape, Robert Sobukwe Road, 13 Bellville 7535, Republic of South Africa 14 15 * Correspondence to Dedi Liu: dediliu@whu.edu.cn 16





17 Abstract: The effectiveness of flash flood warnings depends on the people's response 18 processes to the warnings. And false warnings and missed events cause the people's 19 negative responses. It is crucial to find a way to determine the threshold of issuing the 20 warnings that reduces the false warning ratio and the missed event ratio, especially for uncertain flash flood forecasting. However, most studies determine the warning 21 22 threshold based on the natural processes of flash floods rather than the social 23 processes of warning responses. Therefore, an agent-based model (ABM) was 24 proposed to simulate the people's response processes to the warnings. And a 25 simulation chain of "rainstorm probability forecasting - decision on issuing warnings warning response processes" was conducted to determine the warning threshold based 26 27 on the ABM. Liulin Town in China was selected as a case study to demonstrate the 28 proposed method. The results show that the optimal warning threshold decreases as 29 the forecasting accuracy increases. And as the forecasting variance or the variance of 30 the forecasting variance increases, the optimal warning threshold decreases (increases) 31 for low (high) forecasting accuracy. Adjusting the warning threshold according to the 32 people's tolerance levels of the failed warnings can improve warning effectiveness, 33 but the prerequisite is to increase the forecasting accuracy and decrease the 34 forecasting variance. The proposed method provides valuable insights into the 35 determination of warning threshold for improving the effectiveness of flash flood 36 warnings.

Keywords: Threshold of issuing warnings; Flash flood warnings; People's response
processes; Evacuation; Agent-based model





39 1. Introduction

40 With the intensification of climate change and human activities (Slater et al., 41 2021), flash floods have become one of the most serious disasters threatening 42 economic and social security (Borga et al., 2019). Flash flood warning has been taken 43 as an effective and economical means of preventing flash flood disasters (Yin et al., 2023). By issuing warnings before the occurrence of flash floods, people are advised 44 to or ordered to evacuate for reducing the casualties. However, the people's responses 45 46 to the warnings are complex processes including receiving the warnings, 47 understanding the warnings, trusting the warnings, and personalizing the flood risk (Mileti, 1995; Parker et al., 2009). And these complex processes might hinder the 48 49 evacuation and undermine the effectiveness of the warnings (Cools et al., 2016). To 50 improve the effectiveness of flash flood warnings, extensive studies have been done 51 to pursue higher accuracy and longer lead time of flash flood forecasting (Han and 52 Coulibaly, 2017; Lei et al., 2018). Unfortunately, the people's responses to the warnings have rarely been explored and have become a bottleneck in improving the 53 54 effectiveness of the warnings and reducing casualties (Bodoque et al., 2019; Wang et 55 al., 2022).

56 The people's negative responses to the warnings have been mainly attributed to 57 the uncertainties of the flash flood forecasting and the warnings. The uncertainties of flash flood forecasting are from the uncertainties of meteorological forecasting, 58 59 observation data, initial conditions, hydrological and hydraulic model structure, model 60 parameters, and so on (Boelee et al., 2019). To describe the uncertainties of flood 61 forecasting, a probabilistic flood forecasting was proposed and had been widely 62 applied in the issuing warnings by the disaster prevention administrators (Krzysztofowicz, 2001). If the probability of flash flood disasters from the 63 probabilistic flood forecasting exceeds a preset threshold, the procedure of the issuing 64 65 warning will be triggered (Coccia and Todini, 2011; Todini, 2017). If the threshold is 66 set low, even a low forecasted probability of flash flood disasters can exceed the threshold, and lots of warnings with only the low probability of flash flood disaster 67 will be issued, resulting in an increase in the false warning ratio. In contrast, if the 68 69 threshold is set high, only the flash flood disasters with high forecasted probability 70 can be warned, and some flash flood disasters with not low probability will be missed, 71 leading to an increase in the missed event ratio (Potter et al., 2021). These two





72 increases from both the false warning ratio and the missed event ratio can decrease the 73 people's responses to the warnings and expand the casualties. Simmons and Sutter 74 (2009) conducted a statistical analysis of tornado data from 1986 to 2004, and they 75 found that tornadoes with a higher false warning ratio killed and injured more people. 76 LeClerc and Joslyn (2015) explored the cry wolf effect in weather-related decision 77 making through a controlled experimental approach. And their experiments revealed 78 that the decreasing false warning ratio could increase people's trust in the warnings 79 when the trust level was in the medium range, while both too high and too low false 80 warning ratios led to inferior decision making. Ripberger et al. (2015) found that the 81 false warning ratio and the missed event ratio significantly reduced people's trust in 82 the National Weather Service, and suppressed their positive responses via a large 83 regional survey. However, it is impossible to simultaneously reduce the false warning 84 ratio and the missed event ratio at a certain level of forecasting, as there is a trade-off 85 between these two ratios as described above. Therefore, it is crucial to find a way to 86 determine an appropriate threshold that balances the false warning ratio and the 87 missed event ratio for improving the positive warning responses and reducing the 88 disaster casualties.

89 Extensive methods have been proposed to determine the threshold of issuing 90 flood warnings for balancing the false warning ratio and the missed event ratio (Duc Anh et al., 2020; Ke et al., 2020; Ramos Filho et al., 2021; Tekeli and Fouli, 2017; 91 92 Young et al., 2021). The methods have gradually evolved from fixed threshold 93 determination methods to dynamic threshold determination methods, and from 94 data-driven methods to simulation-based methods (Cheng, 2013). However, these 95 methods only determined the threshold of issuing warnings based on the natural 96 processes of flash floods, while ignoring the social processes of warning responses. 97 The goal of flash flood warnings is to stimulate the people's responses to the warnings 98 for reducing casualties. Even a reliable warning cannot be effective without people's 99 positive responses to it. To our best knowledge, there are very few methods to 100 determine the threshold based on people's response process simulation. Roulston and 101 Smith (2004) generalized the warning release into an improved classical binary 102 cost-loss problem, where the people's warning response level was expressed as a 103 function of false warning ratio, and this warning response level variable was included 104 in the cost-loss analysis. And the threshold of issuing warnings was derived with the 105 goal of minimizing the cost loss ratio under different scenarios. Sawada et al. (2022)





106 proposed a stylized model that coupled natural and social systems to determine the 107 threshold of issuing warnings. In this stylized model, the warning response level was 108 attributed to be influenced by both the success rate of the warning and the flood 109 experience, and then was mapped to flood losses through an empirical equation. 110 However, these studies only described the warning response level through empirical equations or conceptual models, instead of describing the warning response processes 111 112 through process-based models. To reflect the characteristics of flash flood disaster 113 prevention and the flash flood warning responses, it is necessary to simulate the 114 people's response processes of receiving warnings, making evacuation decisions, 115 implementing evacuation, and being submerged by flash floods (or reaching shelters). Agent-based model (ABM) is a modeling framework for complex systems by 116 117 simulating the dynamic interactions between automatic decision-making agents and 118 between these agents and the environment in a distributed micro level (Janssen and 119 Ostrom, 2006). As the warning responses are related to a learning process, and also to personal flood experience and risk perception, ABM is suitable for understanding the 120 121 dynamic processes through simulating the individual decision-making (Anshuka et al., 122 2022). Additionally, ABM can describe the spatially explicit social-hydrological 123 processes, such as the dissemination of warning information, the selection of 124 evacuation routes, and the distribution of flash flood inundation (Sivapalan and 125 Bloeschl, 2015). Thus, ABM is an effective tool for simulating the people's response 126 processes to flash flood warnings (Du et al., 2017; Yang et al., 2018; Zhuo and Han, 127 2020).

128 The aim of this study is to propose a method for determining the threshold of 129 issuing warnings (called warning threshold hereafter) based on the people's response 130 process simulation. A process-based ABM is developed to simulate people's response processes to flash flood warnings (section 2.1). A simulation chain of "rainstorm 131 132 probability forecasting - decision on issuing warnings - warning response processes" 133 is conducted to determine the warning threshold based on the ABM (section 2.2). 134 Liulin Town in China is selected as a case study to demonstrate the proposed method, 135 and to provide valuable insights into the determination of warning threshold for 136 improving the effectiveness of flash flood warnings.





137 2. Methodology

138 2.1. An ABM development for simulating people's response 139 processes to flash flood warnings

140 To simulate the people's response processes to flash flood warnings (i.e., 141 including the receiving warnings, the making evacuation decisions, the implementing 142 evacuation, and the being submerged by flash floods/the reaching shelters), an ABM 143 is developed by coupling social and natural sub-systems.

144 2.1.1. Agents and their environments in the ABM

145 There are two types of agents in the ABM: resident and authority. The resident agents refer to the people threatened by flash floods. After receiving flash flood 146 147 warnings, the agents will decide whether and when to evacuate. If they decide to 148 evacuate, they will move along the roads towards the shelters. After issuing the 149 warnings, the flash flood will occur and might wash away the agents who have not successfully arrived at shelters. The probability of casualties can be estimated based 150 151 on the velocity and the depth of the flash flood. The authority agents represent the local authorities that mandate to prevent the flash flood disasters. 152

The environment in the ABM are the residences, road networks, shelters, and floodwater. The residence agents are initially randomly distributed in the residences. The resident agents who have decided to evacuate will move along the road network instead of freely moving within the ABM area. The shelters are the destinations for evacuation. The flash flood water not only affects the evacuation decisions and behaviors of the resident agents but also causes casualties to the resident agents.

159 2.1.2. Sub-modules of the ABM

Early warning sub-module. Early warning sub-module simulates the process of 160 161 issuing warnings. Owing to the uncertainties of flash flood forecasting, there are 162 multiple stages of warning in a warning system. Rainstorm red, ready-to-evacuate, 163 and immediate-evacuation warnings are successively issued in the ABM. The times of 164 issuing these three warnings are determined by three parameters: lead time of rainstorm red warning (indicated as lead - time - w1), ready-to-evacuate warning 165 166 (indicated as lead - time - w2), and immediate-evacuation warning (indicated as 167 lead -time - w3).

168 Social sub-module. Social sub-module simulates the people's psychological and





169 behavioral response processes to the warnings. The j-th agent¹ will decide to evacuate when his/her overall evacuation intention $(S_i, S_i \in [0, 3])$ exceeds a 170 threshold, τ , or the water depth near him/her exceeds a threshold, *EDT*. There are 171 two components in S_i : evacuation intention arising from receiving warnings (S_i^W , 172 $S_j^{W} \in \{1, 2, 3\}$), and evacuation intention arising from observing neighbors (S_j^{N}) , 173 $S_i^N \in [0, 1]$). The value of S_i^W is related to the socio-demographic and 174 socio-psychological attributes of the i-th agent (SSC) and the stages of the 175 receiving warning from the early warning sub-module (WT). The relationship can be 176 described by a random forest algorithm. The value of S_i^N equals to the proportion of 177 178 the *i*-th agent's neighbors who have decided to evacuate. The weights of the influence of S_{j}^{W} and S_{j}^{N} on the S_{j} are represented by parameters α_{j} and β_{j} , 179 respectively, and $\alpha_i + \beta_i = 1$. Finally, the overall evacuation intention of the *j*-th 180 181 agent at time t, $S_{i,t}$, is a linear combination of overall evacuation intention at time 182 t-1 $(S_{j,t-1})$ and current information. Learning rate, θ_j , measures the weight given by the j-th agent to the obtained information at the current time. If the j-th agent 183 has decided to evacuate, he/she will walk along the shortest road network to the 184 185 shelters. His/her walking speed is estimated by the spatial-grid evacuation model 186 (SGEM) that has been developed by the City University of Hong Kong and Wuhan 187 University (Lo et al., 2004). Flood sub-module. As flash flood can affect the people's evacuation behaviors 188

189 and cause casualties, the flash flood process is simulated in the flood sub-module. The 190 Hydrologic Engineering Center's River Analysis System (HEC-RAS) software is 191 gaining popularity due to its capabilities to simulate unsteady flow efficiently, and 192 identify and visualize flood-prone areas (Hicks and Peacock, 2005; Maidment, 2017). 193 The HEC-RAS model has been applied for flood forecasting and warning (Oleyiblo 194 and Li, 2010). And it has been adopted in our flood sub-module. The river geometries 195 such as centerlines, bank lines, and cross-sectional lines are the major parameters 196 proceeded in the HEC-RAS model to generate flood-prone areas. The spatiotemporal

¹ The agent refers to the resident agent by default





197 changes in the depth and velocity of flash floods are simulated by the HEC-RAS

198 model after the warnings.

199 2.1.3. Casualty rate estimation module

200 Based on the spatiotemporal distribution of the people outputted from the social 201 sub-module and the spatiotemporal distribution of floodwater outputted from the 202 flood sub-module, the casualty probability of an agent can be estimated via a logistic 203 regression equation as follows:

204
$$f(z) = \frac{1}{1 + e^{15.48 - z}}$$
(1)

where $z = \beta_0 + \beta_1 \times h + \beta_2 \times u$, $\beta_0 = -12.37$, $\beta_1 = 22.036$, $\beta_2 = 11.517$. The flood water depth is represented by h ($h \in [0.28, 0.85]$ (m)), and the flood water velocity is denoted by u ($u \in [0.50, 2.00]$ (m/s)). The *j*-th agent is taken as casualty if the h exceeds 0.85 m or u exceeds 2.00 m/s around him/her. The casualty rate is estimated as the proportion of the casualties. A detail description of the ABM can be retrieved from Zhang et al. (2024)

211 2.1.4. A surrogate model development for the ABM

212 Due to the complexity of the ABM, running this model once requires a 213 significant amount of time (Confalonieri et al., 2010). To simulate multiple flash flood 214 events, it is necessary to improve the computational efficiency of the ABM. Thus, a 215 Bayesian method developed by Oakley and O'Hagan (2004) is used to develop a 216 Gaussian process (GP) emulation as a surrogate model of the ABM. The GP 217 emulation can simulate the warning response processes more efficiently than the 218 original ABM (O'Hagan, 2006). In general, the GP emulation can be represented by 219 an equation: $D = f_{GP}(\mathbf{x})$ where D is the casualty rate at the end of the simulation and x are a set of parameters of the ABM. 220

A global sensitivity analysis of the ABM reveals that the weight of warning influence, α , is the most sensitive parameter for the casualty rate (Zhang et al., 2024). Furthermore, rainfall, P, is the driving factor causing flash floods. Therefore, if there is a flash flood disaster and its corresponding warnings are issued, the ABM can be simplified into a two-parameter surrogate model: $D = f_{GP}^2(\alpha, P)$. If there is a flash flood disaster and no warning is issued, the ABM can be simplified into a one-parameter surrogate model: $D = f_{GP}^1(P)$.





228 2.2. Simulation chain of "rainstorm probability forecasting -

229 decision on issuing warnings - warning response processes"

230 2.2.1. Simulation of the rainstorm probability forecasting

231 Flash floods often occur if there are sufficient rainstorms in a small basin over a 232 few hours (Collier, 2007; Younis et al., 2008). As the total flood generation and 233 routing time is very short, flash flood warnings have to be dependent on the rainstorm 234 forecasting for an enough lead time (Zhai et al., 2018). Therefore, the rainstorm 235 forecasting determines the flash flood warning decisions. The probabilistic forecasting 236 is preferred over the deterministic one as it considers forecasting uncertainties and it is beneficial for rational decisions (Krzysztofowicz, 2001). A random probabilistic 237 238 forecasting generator based on Ambühl (2010) is employed to forecast the probability 239 distribution of rainfall as follows:

240
$$F \sim N(P + N(\mu_{PA}, \sigma_{PA}^2), N(\mu_{PP}, \sigma_{PP}^2))$$
 (2)

where *F* is the forecasted rainfall, *N*(.) is the Gaussian distribution, *P* is the actual rainfall, $N(\mu_{PA}, \sigma_{PA}^2)$ reflects the forecasting accuracy, and $N(\mu_{PP}, \sigma_{PP}^2)$ reflects the forecasting precision. Although Ambühl (2010) used the gamma distribution to simulate the forecasting precision, the Gaussian distribution can help improve the interpretability of the results. Negative $N(\mu_{PP}, \sigma_{PP}^2)$ is truncated to 1.0×10^{-6} to eliminate the negative values of variance.

We set $\mu_{PA}=0$ assuming the unbiased forecasting according to Sawada et al. (2022). If the mean of the F (i.e., $P+N(0,\sigma_{PA}^2)$) is taken as the forecasting tendency value, the accuracy of the forecasting tendency value will be reflected by σ_{PA} . The variance of the F (i.e., $N(\mu_{PP}, \sigma_{PP}^2)$) determines the band-width of the F. The larger $N(\mu_{PP}, \sigma_{PP}^2)$, the greater the band-width value of the F. The variance of the forecasting values is determined by μ_{PP} , while the variance of the variance of the forecasting values is determined by σ_{PP} .

254 2.2.2. Simulation of the decision on issuing warnings

There is a damage threshold, δ . If the *P* exceeds this threshold, flash flood disasters will occur and cause damages. The probabilistic forecasting system can provide the probability that the forecasted rainfall exceeds the δ (i.e., the probability of flash flood disasters, denoted by *Prob*). If the *Prob* is larger than a





- 259 preset threshold, λ , the warning administrators will issue the warnings. Thus, the λ 260 is the warning threshold. The warning outcomes are dependent on a contingency table 261 (shown in **Table 1**). The outcomes are dependent on two conditions: first, whether the 262 *Prob* is above the λ or not (i.e., whether to issue warnings or not); and second, whether the P exceeds the δ or not (i.e., whether to occur a flash flood disaster or 263 264 not). The interplay of the two conditions leads to four warning outcomes: true 265 negative (no warning), false negative (missed event), false positive (false warning), and true positive (successful warning). The missed events and the false warnings are 266 267 collectively taken as failed warnings here.
- 268 **Table 1.** Contingency table defining the warning outcomes ^a

	$P < \delta$	$P \ge \delta$
$Prob < \lambda$	True negative (no warning)	False negative (missed event)
	0	Damage
$Prob \ge \lambda$	False positive (false warning)	True positive (successful warning)
	Cost	Cost + residual damage
A Coata and da		And there are highlighted in italies

^a Costs and damages associated with each outcome. And they are highlighted in italics.

270 2.2.3. Simulation of the warning response processes

271 According to the four warning outcomes in Table 1, the warning response 272 processes are simulated by the surrogate model of the ABM for estimating the 273 casualty rate, D. If the warning outcome is true negative or false positive, the 274 casualty rate is negligible as the actual rainfall, P, is smaller than the damage 275 threshold, δ . It should be noted that false positive can cause opportunity cost as 276 there are behavior responses to the warnings (i.e., evacuation behaviors). As this study 277 only focuses on the casualty rate, the opportunity cost has been ignored. If the 278 warning outcome is false negative, there is a flash flood disaster but no warning is 279 issued. In this case, the one-parameter surrogate model (i.e., $D = f_{GP}^{(1)}(P)$) is 280 employed to simulate the warning response processes for estimating the casualty rate. 281 If the warning outcome is true positive, there is a flash flood disaster and its 282 corresponding warnings are issued. The casualty rate is mitigated by evacuation. The two-parameter surrogate model (i.e., $D = f_{GP}^2(\alpha, P)$) is used to simulate the warning 283 284 response processes for estimating the casualty rate. In general, the casualty rate can be 285 described by the following equation:

286
$$D = \begin{cases} 0 & \text{for true negative or false positve} \\ f_{GP}^{1}(P) & \text{for false negative} \\ f_{GP}^{2}(\alpha, P) & \text{for true positive} \end{cases}$$
(3)





287 We assume that past warning outcomes affect people's trust levels in the 288 warnings. Existing studies have found that the recent false warning ratio undermines 289 people's trust levels in the warnings and their preparedness actions (Jauernic and Van 290 den Broeke, 2017; LeClerc and Joslyn, 2015; Lim et al., 2019; Ripberger et al., 2015). 291 It is reasonable to assume that people's past experiences with successful (or failed) 292 warnings increase (or decrease) their trust levels in the warnings. A person's trust 293 level in the warnings can be described by the parameter α representing the weight 294 assigned to the warning information. Therefore, α after experiencing a flash flood 295 at the t+1 time can be described by the following equation:

296
$$\alpha(t+1) = \begin{cases} \alpha(t) & \text{for true negative} \\ \alpha(t) - \chi_{FN} & \text{for false negative} \\ \alpha(t) - \chi_{FP} & \text{for false positive} \\ \alpha(t) + \chi_{TP} & \text{for true positive} \end{cases}$$
(4)

297 where χ_{FN} , χ_{FP} , and χ_{TP} are increments of α for false negative, false positive, 298 and true positive, respectively. If α is larger than one, it is truncated to one. If α 299 is smaller than zero, it is truncated to zero.

300 2.2.4. Performance metrices of the warning

Three metrices are used to evaluate the warning performance: the relative casualty rate (D_r) , missed event ratio (*MER*), and false warning ratio (*FWR*). The D_r is defined as:

 $D_r = \frac{D_w}{D_n}$ (5)

where D_w is the average casualty rate of multiple flash floods if there is a flash flood warning. And the casualty rate of each flash flood can be estimated by equation (3). D_n is the average casualty rate of multiple flash floods if there is no flash flood warning in place (i.e., the casualty rate is dependent only on the natural variability). The casualty rate of each flash flood can be estimated by the following equation (6).

310
$$D_n = \begin{cases} 0 & \text{if } P < \delta \\ f_{GP}^1(P) & \text{if } P \ge \delta \end{cases}$$
(6)

The lower the value of D_r , the more effective the flash flood warning is. If the objective of flash flood warning is the minimizing the casualties, the optimal warning threshold is the threshold where the D_r is the lowest.

3





314 Besides D_r , the MER and FWR are used to evaluate the performance of the

315 flash flood warning. They are defined by equations (7) and (8):

$$316 MER = \frac{O_{FN}}{O_{TP} + O_{FN}} (7)$$

17
$$FWR = \frac{O_{FP}}{O_{FP} + O_{TP}}$$
(8)

318 where O_{FN} , O_{TP} , O_{FP} are the total number of false negative, true positive, and

- 319 false positive events, respectively.
- 320 **3. Case study**

321 **3.1.** Study area

322 Liulin Town located in Suixian Country, Hubei Province, China was selected as 323 our study area. The Lang River goes through Liulin Town as shown in Figure 1(a) 324 and the red rectangular box indicates the location of the town. The average annual 325 rainfall is 1,100 mm. Rainfall is unevenly distributed throughout the year, and mainly 326 concentrates from June to August. The upstream valley of Liulin Town is wider than 327 that of the downstream. And this river geomorphology hinders flood discharge and 328 easily causes the flash flood disaster when a rainstorm occurs. Residences in the town 329 are located on both sides of Langhe River. In the prevention and control map of flash 330 flood disasters in Suixian County, two communities in Liulin Town are listed as 331 high-risk and relatively high-risk areas. Especially, an extreme rainstorm with a 332 volume of 503 mm from 2:00 a.m. to 9:00 a.m. on August 12, 2021 (hereafter called 333 the 8.12 event) caused a severe flash flood disaster in the town. Unfortunately, 21 334 people were dead and four people were still missing in this disaster although flash 335 flood warnings had been issued (Wei, 2021). Exploring the way to determine the 336 threshold of issuing flash flood warnings in the town will provide valuable 337 information on flash flood disaster prevention for reducing the casualties.







338 339

Figure 1. Location of the (a) Lang River Basin and (b) Liulin Town

340 **3.2.** Setting of the ABM

341 To set up the environment of the ABM, the residences and road network (see 342 Figure 1) were imported into the model after processing a digital archive (i.e., World 343 Imagery Wayback). To prevent evacuation across the river, two shelters were set up at high place on both sides of the Langhe River. And they should not be submerged by 344 345 floods. The parameters of the ABM were set according to calibration, empirical data, 346 and related literature (see Table 2). The lead time of the three stages of warning and 347 evacuation depth threshold were parameterized from the two-month surveying 348 expertise and experience in the study area. The three hyperparameters of the random 349 forest model were calibrated by the empirical data from our survey. A sampling 350 without replacement was conducted on the empirical data and the sample was used to 351 assign the initial SSC values of the agents. The random forest model calibration, the 352 survey, and the method of assigning SSC values were detailed in Zhang et al. (2024). 353 The values of θ_i and p_i of the *j*-th agent were sampled from the Gaussian 354 distributions according to the exiting literature (Du et al., 2017). $S_i = 2$ is set to 355 indicate no decision making on evacuation for the j-th agent in the empirical data 356 while $S_i > 2$ means the evacuation decision of the agent. Hence, the value of τ was set to 2. A global sensitivity analysis has been performed to explore the relative 357 358 impacts of these parameters on the casualty rate and can be retrieved from Zhang et al. 359 (2024).

360





361 **Table 2.** Fixed ABM parameters

Sub-module	Parameters	Symbol	Values	Remark
Early	Lead time of rainstorm red	<i>lead-time-w</i> l	120 min	Author
warning	warning			estimation ^a
	Lead time of	lead -time-w2	60 min	Author
	ready-to-evacuate warning			estimation ^a
	Lead time of	lead -time-w3	30 min	Author
	immediate-evacuation			estimation ^a
	warning			
Random	Number of trees	ntree	500	Calibration
forest	Number of candidate variables	mtry	6/1/6 ^b	Calibration
	Minimum size of nodes	nodesize	10/1/10 ^b	Calibration
	Socio-demographic and socio-psychological	SSC		Empirical data
	characteristics of resident			
	agents	2		
Opinion	Learning rate	heta	$0.5(0.1)^{\circ}$	Literature
dynamics				reference (Du et
		n	0 1 (0 1) 6	al., 2017)
	Probability of receiving	p	0.1 (0.1)	Literature
	early warnings			reference (Du et
	F 2 4 1 11	_	2	al., 2017)
0.1	Evacuation threshold	t ID	2	Empirical data
Others	Visual range	VR	40 m	Literature
				reference (Wu et
				al., 2022)
	Evacuation depth	EDT	0.28 m	Author
	threshold			estimation ^a

a These estimations are from the two-month surveying expertise and experience of the authors in the study area. ${}^{b}x_{1}/x_{2}/x_{3}$ indicates the values of the factors are x_{1} , x_{2} , and x_{3} for the rainstorm red, the ready-to-evacuate, and the immediate-evacuation warnings, respectively. ${}^{c}x_{1}(x_{2})$ indicates the values of the factors are sampled from a normal distribution with mean value of x_{1} and variance of x_{2}

The flood-module of the ABM was formed by a two-dimensional (2D) 367 hydrodynamic model in the Langhe River Basin through HEC-RAS. Terrain 368 information was obtained from the digital elevation model (DEM) at a spatial 369 resolution of 12.5 m provided by the Advanced Land Observing Satellite (ALOS). 370 371 Cells with size of 30 m were generated within the 2D flow areas. The Manning's 372 coefficient was set to a unified comprehensive value of 0.045. The upstream boundary 373 condition was set as the rainstorm process. The hyetograph was selected by the 374 measured rainfall process of the 8.12 event. Specifically, the hourly rainfall was greater than 30.0 mm from 2:00 to 7:00 on August 11, 2021 and the 6-h rainfall was 375 376 up to 462.6 mm (see Figure 2). The 6-h rainfall process was input into the HEC-RAS 377 as the hyetograph. As Baiguo River reservoir is in the outlet, the downstream 378 boundary condition was set as the normal water level of the reservoir. The





379 spatiotemporal changes in the depth and velocity of flash floods were exported after



380 running the model at a temporal interval of 2 min and spatial resolution of 12.5 m.



Figure 2. The rainfall process from 19:00 on August 11 to 19:00 on August 12, 2021
of Liulin Meteorological Station

The ABM was run by covering the processes from issuing warnings to flash flood at a time step of 1 min and spatial resolution of 9.6 m. And 500 agents were assumed to be involved in the simulations. Due to the inherent randomness of the ABM, the averages of the outputs from the repeating 1,000 times for running the ABM were obtained to ensure stable outputs.

389 3.3. Rainfall data

390 A series of rainfall data was imported into the ABM for simulating a series of 391 possible flash flood disasters. Synthetic rainfall series are required to ensure the 392 representative of the extreme events. The annual maximum 6-h rainfall, P, was 393 assumed to follow the Pearson III distribution. Its values of mean and C_{y} in the 394 basin above Liulin Town were estimated to be 80 mm and 0.6, respectively, according 395 to Atlas of Statistical Parameters of rainstorm in Hubei Province (2008). C_s / C_y was 396 taken as 3.5 in Hubei Province. 1,000 synthetic rainstorm events were randomly 397 generated by the Pearson III distribution, and the result was shown in Figure 3.







398

399 Figure 3. 1,000 synthetic series of rainstorm events

400 3.4. Model test experiments

401 To determine the warning threshold under different forecasting skills for minimizing the relative casualty rate, three possible values of each of the three 402 403 parameters (i.e., σ_{PA} , μ_{PP} , and σ_{PP}) were prepared to reflect different forecasting 404 skills (see Table 3) and their interactive effects on the determination of warning 405 threshold were tested. Rainstorm red warning is the highest level of meteorological 406 risk warning in the mainland of China. When the rainstorm red warning is issued, 407 floods tend to cause damage and the residents in flood risk area are advised to 408 evacuate (Wang et al., 2020). If the 6-hour rainfall is up to 150 mm, the rainstorm red 409 warning will be issued (Shanghai Meteorological Bureau, 2019). Thus, the value of 410 δ was taken as 150 mm in the case study.

411 Table 3. Model test experiment for determining the warning threshold under different

412 forecasting skills

Parameters	Symbol	Values
The accuracy of the forecasting tendency value	$\sigma_{\scriptscriptstyle P\!A}$	$\{0.05, 0.10, 0.15\}$
The variance of the forecasting values		$\{0.0, 0.1, 0.2\}$
The variance of the variance of the forecasting values	$\sigma_{_{PP}}$	$\{0.0, 0.1, 0.2\}$
Damage threshold	δ	150 mm
Increment of α for false negative	$\chi_{\scriptscriptstyle FN}$	0.1
Increment of α for false positive	$\chi_{\scriptscriptstyle FP}$	0.1
Increment of α for true positive	$\chi_{\scriptscriptstyle TP}$	0.1

413 Besides the uncertainties of the forecasting, there are uncertainties in people's

414 response processes to the uncertain forecasting. To determine the warning threshold

415 under different forecasting skills and tolerance levels of the failed warnings, the





- 416 warning threshold was determined under different σ_{PA} and combinations of 417 parameters related to the increments of α (i.e., χ_{FN} , χ_{FP} , and χ_{TP}) through Exp1 418 in **Table 4**, and under different μ_{PP} and combinations of parameters related to the 419 increments of α through Exp 2 in **Table 4**. The higher the χ_{FN} and χ_{FP} , the 420 lower the tolerance levels of the people towards the missed event and the false 421 warnings, respectively. 422 **Table 4**. Model test experiment for determining the warning threshold under different
- 423 forecasting skills and tolerance levels of the failed warnings

Parameters	Symbol	Values		
	-	Exp1	Exp2	
The accuracy of the forecasting tendency value	$\sigma_{\scriptscriptstyle P\!A}$	{0.05, 0.10, 0.15}	0.075	
The variance of the forecasting values	$\mu_{\scriptscriptstyle PP}$	0.15	$\{0.0, 0.1, 0.2\}$	
The variance of the variance of the forecasting values	$\sigma_{\scriptscriptstyle PP}$	0.075	0.075	
Damage threshold	δ	150 mm	150 mm	
Increments of α for false negative, false positive, and true positive	$\chi_{\scriptscriptstyle FN}$ / $\chi_{\scriptscriptstyle FP}$ / $\chi_{\scriptscriptstyle TP}$	{0.1/0.1/0.1, 0.8/0.8/0.1, 0.8/0.1/0.1, 0.1/0.8/0.1}	{0.1/0.1/0.1, 0.8/0.8/0.1, 0.8/0.1/0.1, 0.1/0.8/0.1}	

424 **4. Results and discussions**

425 4.1. The casualty rate from people's response process simulation

To determine the warning threshold based on the people's response process 426 427 simulation, the ABM with different values of P and α were run to generate corresponding casualty rates, and these simulations were taken as sample data to train 428 429 the GP emulation as a surrogate model of the ABM, as shown in Figure 4. And it has 430 shown the variation of casualty rate with α under different P. There are three 431 stages of change in the casualty rate as α increases regardless of P. When α increases from 0.0 to 0.4, the casualty rate slowly decreases; but as α continues to 432 433 increase to 0.6, the rate of decline becomes faster. When α is greater than or equal 434 to 0.6, everyone arrives at the shelters before the flash flood disaster arrives and there 435 are no casualties regardless of P. This result implies that it is very important and effective to enhance people's trust levels in the warnings when people have similar 436 437 trust levels in warning information and their neighbors. When people's trust in 438 warning information decreases, their evacuation decisions will become more 439 dependent on whether their neighbors are evacuating or not. In other words, the





- 440 increase in the overall evacuation intention (S) of agents requires their neighbors to
- 441 take evacuation actions. However, taking evacuation actions requires the increase in
- 442 S in turn. Thus, waiting for others' evacuation ultimately leads to neither an increase
- 443 in *S* nor the implementation of evacuation actions.



444

445 Figure 4. The casualty rate under different values of P and α from ABM 446 simulations

Because the casualty rate is zero when α is greater than or equal to 0.6 447 448 regardless of P, the one-parameter and two-parameter GP emulations were trained 449 for α with a value less than 0.6 and the results were shown in Figure 5. The 450 training result for one-parameter GP emulation shows that there are also three stages in the increase of casualty rate as P increases. When P increases from 150 to 200 451 452 mm, the casualty rate increases; but if P increases from 200 to 260 mm, the 453 casualty rate remains almost unchanged. When P exceeds 260 mm and continues to 454 increase, the casualty rate starts to increase again. This result indicates that there is 455 spatial heterogeneity of flood risk levels in the case study. It is necessary to classify 456 flood risk zones and distinguish water level or rainfall thresholds for triggering 457 evacuation according to different flood risk levels. The training result for 458 two-parameter GP emulation shows the complex responses of casualty rate to changes 459 in α and P. When α is less than 0.4, there are three stages of changes in the 460 casualty rate as P increases. As α increases from 0.4 to 0.6, the relationship 461 between P and casualty rate tends to be linearly positive, and the difference in





- 462 casualty rates under different P gradually reduces. This result means that the trust 463 level in the warnings becomes the dominant factor in determining the casualty rate 464 when the people's trust levels in the warnings and their neighbors are similar (i.e.,
- 465 when the value of α is the range of 0.4 to 0.6).



466

467 Figure 5. Trained (a) one-parameter and (b) two-parameter GP emulations for468 casualty rate

469 4.2. Determining the warning threshold under different 470 forecasting skills for minimizing casualties

471 To determine the warning threshold under different forecasting skills for 472 minimizing casualties, 250-member Monte Carlo simulations were performed on the 473 simulation chain of "rainstorm probability forecasting - decision on issuing warnings -474 warning response processes" by randomly perturbing the warning threshold, λ , 475 under different values of parameters controlling the forecasting skills (see Figure 6). 476 Different rows represent different values of μ_{PP} , and there is a larger forecasting 477 variance in the sub-graph of the lower row. Similarly, there is a larger variance of the 478 forecasting variance in the sub-graph of the right column compared to the sub-graph 479 of the left column. The highest forecasting accuracy is represented by the green 480 curves, followed by the yellow curves, and finally the red curves. In all the sub-graphs, 481 there is the highest relative casualty rate in the red curves, followed by the yellow 482 curves, and finally the green curves. Therefore, the lower the forecasting accuracy, the 483 higher the relative casualty rate. The optimal warning threshold can be taken as the 484 value of λ where the relative casualty rate, D_{μ} is lowest. The optimal warning 485 thresholds are the lowest in the green curves, followed by the yellow curves, and

502





486 finally the red curves in all the sub-graphs. Thus, the lower the forecasting accuracy, 487 the higher the optimal warning threshold. The reasons can be found in Figure 7. As 488 the warning threshold decreases, the number of false warnings and successful warnings increases, and more warnings are issued. However, if the forecasting 489 490 accuracy is low, the proportion of false warnings is higher than that of successful 491 warnings among the additional warnings issued. For example, as the warning 492 threshold decreases, the green curve for low forecasting accuracy rises faster than that 493 for high forecasting accuracy. This means that if the forecasting accuracy is low, as 494 the warning threshold decreases, the increase speed of false warnings is higher than 495 that of successful warnings. In addition, when the warning threshold is less than 0.7, 496 the green curve begins to rise rapidly for $\sigma_{PA} = 0.15$, while it does not start to rise 497 rapidly until the warning threshold is less than 0.5 for $\sigma_{PA} = 0.15$. Therefore, when 498 the forecasting accuracy is low, a high warning threshold should be set. As the 499 forecasting accuracy increases, lowering the warning threshold can result in more 500 successful warnings without significantly increasing false warnings, thereby 501 improving the effectiveness of flash flood warnings.



Figure 6. The relationship between the relative casual rate, D_r , and the warning threshold, λ , under different values of σ_{PA} , μ_{PP} , and σ_{PP} . Different rows and columns represent different values of μ_{PP} and σ_{PP} , respectively. Different colors





- 506 represent different values of σ_{PA} . Each dot shows the result of the individual Monte
- 507 Carlo simulation



508

509 Figure 7. The changes in the number of false negative, false positive, and true 510 positive events as warning threshold decreases, λ under different values of σ_{PA} . 511 The range of λ is reversed from 0.9 to 0.1

512 In terms of the impacts of the forecasting variance (see Figure 6), there is a 513 larger forecasting variance and a higher relative casualty rate of three colored curves 514 in the sub-graph of the lower row. Thus, the larger the forecasting variance, the higher 515 the relative casualty rate. For the optimal warning threshold, the differences in the 516 optimal warning thresholds of these three colored curves are smaller in the sub-graph 517 of the lower row. For instance, as the forecasting variance increases, the optimal 518 warning thresholds for the red curves decrease while the optimal warning thresholds 519 for the green curves increase. This result means that the larger the forecasting 520 variance, the lower the optimal warning threshold for low forecasting accuracy, while 521 the larger the forecasting variance, the higher the optimal warning threshold for high 522 forecasting accuracy. When the forecasting accuracy is at a low level, a large 523 forecasting variance is actually beneficial for improving the forecasting skills. High 524 forecasting skill means that more successful warnings and fewer false warnings are 525 issued after lowering the warning threshold. Therefore, if the forecasting accuracy is 526 at a low level, as the forecasting variance increases, the warning threshold can be 527 lowered. On the contrary, if the forecasting accuracy is at a high level, as the forecast 528 variance increases, increasing the warning threshold can significantly decrease the 529 false warnings and improve the effectiveness of flash flood warnings. Finally, we 530 focused on the impacts of the variance of the forecasting variance. Similar to the 531 impacts of the forecasting variance, the larger the variance of the forecasting variance,





the higher the relative casualty rate. As the variance of the forecasting variance
increases, the optimal warning threshold tends to decrease for low forecasting
accuracy or to increase for high forecasting accuracy.

The impacts of the three parameters (i.e., σ_{PA} , μ_{PP} , and σ_{PP}) on the shape of 535 536 the relationship curve between D_r and λ can be analyzed as follows. As shown in 537 Figure 6, σ_{PA} determines the height of the curve, while μ_{PP} and σ_{PP} determine 538 the width of the curve. Specifically, as the forecasting accuracy increases, the 539 stationary point of the curve moves down and the curve becomes higher; as the 540 forecasting variance or the variance of the forecasting variance increases, the curve 541 becomes narrower. If the forecasting accuracy is high and the forecasting variance and 542 the variance of the forecasting variance are large, the curve will become high and 543 narrow, such as the green curve for $\mu_{PP} = 0.2$ and $\sigma_{PP} = 0.2$. And there is only a 544 low relative casualty rate near the optimal warning threshold in this green curve. Thus, it is more important to determine the optimal warning threshold for minimizing 545 546 casualties if the forecasting accuracy is higher, and the forecasting variance and the 547 variance of the forecasting variance are larger.

548 4.3. Determining the warning threshold under different 549 forecasting skills and tolerance levels of the failed warnings for 550 minimizing casualties

551 To determine the warning threshold under different forecasting skills and 552 tolerance levels of the failed warnings for minimizing casualties, the simulation chain of "rainstorm probability forecasting - decision on issuing warnings - warning 553 554 response processes" was run with random values of λ under different σ_{PA} and 555 combinations of parameters related to the increments of α (i.e., χ_{FN} , χ_{FP} , and 556 χ_{TP}) (see Figure 8), and different μ_{PP} and combinations of parameters related to the increments of α (i.e., χ_{FN} , χ_{FP} , and χ_{TP}) (see Figure 9). Owing to the similar 557 roles of $\mu_{\scriptscriptstyle PP}$, and $\sigma_{\scriptscriptstyle PP}$, the effects of $\sigma_{\scriptscriptstyle PP}$ on the determination of warning 558 559 threshold were not explored here. As shown in Figure 8, the optimal warning 560 thresholds for the yellow curves are the lowest. The yellow curves represent scenarios 561 that people's trust in warnings is sensitive to false negative events and people have a 562 low tolerance level for the missed events. To reduce the missed event ratio, the





563 warning threshold should be lowered (see Figure 8g). Therefore, the warning threshold should be lowered for increasing people's trust levels in warnings and 564 565 reducing casualties if people have a lower tolerance level for the missed events. 566 Similarly, the warning threshold should be increased if the people's tolerance levels 567 for the false warnings become lower (see the red curves). And if the people's tolerance for both the missed events and the false warnings decreases to the same level, the 568 569 optimal warning threshold remains almost unchanged, but the relative casualty rate overall increases (see the blue curves). As for the relative casualty rate, the relative 570 571 casualty rates of the yellow curves are lower than those of the red curves. This result 572 suggests that compared to the missed events, the people's low tolerance levels for the 573 false warnings are less conducive to the effectiveness of flash flood warnings. As 574 shown in **Figure 7**, the number of false warnings is greater than the number of missed 575 events in general. Therefore, if the people's tolerance levels for the false warnings is 576 low, their trust levels in warnings are more likely to decrease, leading to the effects of 577 "cry wolf".

578 By comparing Figure 8a and Figure 8b, the overall height of the curves 579 decreases when the forecasting accuracy decreases, as discussed in the last paragraph 580 of section 4.2. However, compared to green curve, the heights of other curves 581 decrease more significantly. And the relative casualty rates are high at any warning 582 threshold (i.e., $D_r > 0.75$) except for the green curve when the σ_{PA} increases from 583 0.05 to 0.1. It is more pronounced when the σ_{PA} further increases to 0.15. Therefore, 584 as the forecasting accuracy decreases, the benefits gained by adjusting the warning 585 threshold based on the people's tolerance levels of the failed warnings decreases. In 586 other words, no matter how the warning threshold is adjusted, the relative casualty 587 rate is high and the effectiveness of warning is at a low level.

588







Figure 8. (a-c) The relationship between the warning threshold, λ and the relative casualty rate, D_r under different σ_{PA} and combinations of parameters related to the increments of α (i.e., χ_{FN} , χ_{FP} , and χ_{TP}). (d-f) Same as (a-c) but for time-averaged α . (g-i) The relationship between the warning threshold, λ , and the false warning ratio, *FWR*, and the missed event ratio, *MER*, under different σ_{PA} . Each dot shows the result of the individual Monte Carlo simulation

595 In terms of the effects of the forecasting variance and the tolerance levels of the 596 failed warnings on the determination of warning threshold as shown in **Figure 9**, the 597 warning threshold should be decreased if people have a lower tolerance level for the 598 missed events, and vice versa. And compared to the missed events, the people's low 599 tolerance levels for the false warnings are less conducive to the effectiveness of flash 600 flood warnings. These findings are consistent with the results in Figure 8. 601 Furthermore, we find that the difference in the optimal warning thresholds of these 602 colored curves decreases as the forecasting variance increases as shown in Figure 603 **9a-Figure 9c.** As discussed in the last paragraph of section 4.2, the curve becomes 604 narrower as the forecasting variance increases. If the width of the curves decreases, 605 the difference between their optimal warning thresholds will also decrease. Therefore,





as the forecasting variance increases, the difference in the optimal warning thresholds
of these curves will decrease, and the adjustment space for the warning threshold
based on the people's tolerance levels will also decrease.

If the green curve represents the result of the baseline scenario where both χ_{FN} 609 610 and χ_{FP} equal 0.1, increment of the values of χ_{FN} and χ_{FP} (i.e., lowering 611 tolerance levels for the missed events and the false warnings) will result in a series of 612 curves, and these curves will be enveloped by the green curve in Figure 9. Therefore, 613 only when the green curve is high enough, can the relative casualty rate of this series 614 of curves be low enough, and the effectiveness of flash flood warnings be sufficiently 615 improved. And only when the green curve is wide enough, can the difference in the 616 optimal warning threshold for this series of curves be large enough, and there can be 617 enough room for adjustment the warning threshold. In summary, by increasing the 618 height and width of the green curve, the adjustable room for the warning threshold 619 will be larged and the effectiveness of flash flood warnings will be improved. As the 620 forecasting accuracy increases, the green curve becomes higher. And as the 621 forecasting variance decreases, the green curve becomes wider. Therefore, under the 622 premise of improving the forecasting skills (i.e., increasing forecasting accuracy and 623 decreasing forecasting variance), adjusting the warning threshold based on the 624 people's tolerance levels of the failed warnings is one of the ways to improve the 625 effectiveness of flash flood warnings.







Figure 9. (a-c) The relationship between the warning threshold, λ and the relative casualty rate, D_r under different μ_{PP} and combinations of parameters related to the increments of α (i.e., χ_{FN} , χ_{FP} , and χ_{TP}). (d-f) Same as (a-c) but for time-averaged α . (g-i) The relationship between the warning threshold, λ , and the false warning ratio, *FWR*, and the missed event ratio, *MER*, under different μ_{PP} . Each dot shows the result of the individual Monte Carlo simulation

633 **5.** Conclusions

626

A method has been proposed to determine the warning threshold for minimizing casualties based on the people's response process simulation. A process-based ABM was developed to simulate people's response processes to flash flood warnings. A simulation chain of "rainstorm probability forecasting - decision on issuing warnings warning response processes" was conducted to determine the warning threshold based on the ABM. The main conclusions are as follows.

640 The casualty rate is jointly controlled by the warning information source and 641 precipitation. If the people's trust levels in official warnings are below a certain 642 threshold, precipitation is the dominant factor in controlling the casualty rate. If the





people have a similar level of trust in official warnings and neighbor behaviors, the
credibility of the warning information source is the dominant factor in controlling the
casualty rate.

646 The warning threshold has been determined under different forecasting skills for 647 minimizing casualties. The lower the forecasting accuracy, the higher the optimal 648 warning threshold. And the larger the forecasting variance or the variance of the 649 forecasting variance, the higher (lower) the optimal warning threshold for high (low) 650 forecasting accuracy. Furthermore, the impact pattern of forecasting skills on the 651 shape of the relationship curve between the relative casualty rate and the warning 652 threshold has been revealed: the curve becomes higher as the forecasting accuracy 653 increases, and the curve becomes narrower as the forecasting variance or the variance 654 of the forecasting variance increases.

655 The warning threshold has been determined under different forecasting skills and tolerance levels of the failed warnings for minimizing casualties. The warning 656 657 threshold should be decreased (increased) if people have a lower tolerance level for 658 the missed events (the false warnings). However, if the forecasting accuracy is low 659 and the forecasting variance is large, the space for adjusting the warning threshold is 660 limited, and no matter how the warning threshold is adjusted, the casualty rate 661 remains at a high level, and the effectiveness of flash flood warnings is limited. 662 Therefore, under the premise of improving the forecasting skills, adjusting the 663 warning threshold based on the people's tolerance levels of the failed warnings is one 664 of the ways to improve the effectiveness of flash flood warnings.

665 Although our study provides valuable insights into the determination of warning threshold for minimizing casualties, it should be noted that there are some 666 assumptions underlying the simulation method. The parameters of ABM were 667 668 assumed to be time invariant except for α . Updating the values of these parameters 669 based on past warning outcomes will provide more information for determining the 670 warning threshold. The hyetograph was selected as the measured rainfall process of 671 the 8.12 event. More uneven hyetographs should be taken in the flash flood 672 simulation, and the impact of hyetograph on the warning threshold determination can 673 be explored in further research. The casualty rate caused by pluvial floods varies with 674 different spatial distribution of rainfall. The people's trust levels in the warnings were 675 assumed to be only affected by the past warning outcomes. There are other factors 676 (e.g., social education and government authority) that should be incorporate into the





- 677 estimation of the people's trust levels. Therefore, there are still works can be done in
- 678 the future.

679 Code availability

- 680 The code that supports the findings of this study is available from the 681 corresponding author upon reasonable request.
- 682 Date availability
- 683 Data will be made available on request.

684 Author contribution

Ruikang Zhang: Conceptualization, Formal analysis, Methodology, Writing – original draft, Visualization, Funding acquisition. Dedi Liu: Conceptualization, Data curation, Formal analysis, Funding acquisition, Methodology, Supervision, Writing review & editing. Lihua Xiong: Project administration, Supervision. Jie Chen: Data support, Methodology, Writing - review & editing. Hua Chen: Validation, Writing review & editing, Supervision. Jiabo Yin: Validation, Writing - review & editing. All authors contributed to the interpretation of the results and to the text.

692 **Competing interests**

693 The authors declare that they have no conflict of interest.

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