Disentangling coastal groundwater level dynamics on a global data set

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Abstract

Groundwater level (GWL) dynamics result from a complex interplay between groundwater systems and the Earth system. This study aims to identify common hydrogeological patterns and to gain a deeper understanding of the underlying similarities and their link to physiographic, climatic, and anthropogenic controls of eoastal groundwater in coastal regions. The most striking aspects of GWL dynamics and their controls were identified through a combination of statistical metrics, calculated from about 8,000 groundwater hydrographs, and pattern recognition using clustering algorithms, classification using Random Forest, and explanation using machine learning techniques and SHapley Additive exPlanations (SHAP). Overall, Hydrogeological similarity was defined by four different GWL dynamicsclusters representing distinct patterns emerge, independent of the different seasons, time series lengths, and periods of GWL dynamics. We show in this study that similar GWL dynamics These clusters can be observed around the worldglobally across different continents and climate zones, but -simultaneously vary regionally and locally, suggesting a complicated interplay of controlling factors. The main controls differentiating GWL dynamics were identified, but we also provide evidence for the currently limited ability to explain GWL dynamics on large spatial scales, which we attribute mainly to uncertainties in the explanatory data. Finally, with different combinations of site characteristics, but also that the main factors differentiating these patterns can be identified. Three of the identified patterns exhibit high short term and interannual variability and are most common in regions with low terrain elevation and shallow groundwater depth. Climate and soil characteristics are most important in differentiating these patterns. (This study provides new insights into the hydrogeological behavior of groundwater in coastal regions and guidesance for systematic and holistic groundwater monitoring and modelling and motivatesing to consider various different aspects of GWL dynamics when, for example, when estimating predicting climate-driven induced GWL changes , and to use explainable machine learning techniques to deal with GWL complexity - especially when information on potential controls is limited or needs to be verified.

Kommentiert [AN1]: In response to reviewer 1 who found some of the information in the abstract unclear, we have added a slightly more comprehensive introduction of our methodology to improve understanding of the meanings of our findings that follow.

Kommentiert [AN2]: We improved this part of the abstract in accordance with the reviewers recommendation to focus more on the meanings of our findings including limitations.

1. Introduction

When GWL dynamics are tracked over time using groundwater hydrographs, the quantitative status of groundwater resources can be determined. Groundwater resources are exploited tapped and measured locally, and GWL dynamics are subject responded to the contraction of the contractio

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to processes in their immediate local and regional environment (Bear, 2012), such as groundwater recharge rates, groundwater flow and pumping, and seawater intrusion (SWI) in coastal aquifers (Costall et al., 2020; Parisi et al., 2023). Hence, they are strongly location-bound, and there is "a need for groundwater assessments at the field level" (United Nations, 2022). To this end, it is common practice in local studies to incorporate direct information from the groundwater system combined with expert knowledge of potential controls into numerical, statistical, or machine learning models (e.g. in Knowling et al. (2015). Güler et al. (2012), and Lee et al. (2019). Knowling et al., 2015; Güler et al., 2012-and-Lee et al., 2019; However, comprehensive knowledge of aquifer processes at the local scale is often lacking, posing even greater challenges for regional, continental, or global assessments of groundwater systems. Such larger scales are important, for example, concerning large or transboundary aquifer systems, global virtual water trade, and international frameworks such as the UN Sustainable Development Goals (Donnelly et al., 2018; Nimmo et al., 2021). A systemic understanding of aquifer properties is the key to sustainable groundwater management and governance (Guppy et al., 2018; Elshall et al., 2020). Generalized scientific understanding of processes currently relies heavily on aggregating and upscaling local knowledge of groundwater's interactions bidirectional connections with the land surface and submarine processes Earth system. (Smerdon, 2017; Lall et al., 2020; Gleeson et al., 2020); however, is often lacking direct observation-based evidence.

While it is largely unclear how GWL dynamics compare at large scales, the classification of GWL time series applied on such scales holds the potential to provide valuable insights into hydrogeological similarity (Barthel et al., 2021). For instance, these insights can prove valuable in assessing the coherence of large-scale process-based models by focusing on similarities in patterns and spatial trends, rather than solely relying on the magnitude of aggregated errors, effectively mitigating the commensurability problem (Gleeson et al., 2021). In contrast, process understanding is limited when only the long-term mean or trend of GWL dynamics is usedconsidered (Lischeid et al., 2021; Gleeson et al., 2021; Baulon et al., 2022a).

The present study provides, for the first time, a classification of GWL dynamics from the global scale, follows this idea and is motivated by (a) a large amount of GWL data available today – although not yet centralized and freely accessible for many regions of the world (United Nations, 2022) – and (b) the advancement of data-driven methods in earth-Earth system sciences, which are not only capable of finding patterns unseen by humans but are also increasingly capable of explaining them (Reichstein et al., 2019; Shen et al., 2018). Previous studies have successfully applied inductive classification approaches (Olden et al., 2012), synthesizing different aspects of GWL dynamics at local to regional scales to investigate physiographic, climatic, and anthropogenic controls of GWL dynamics (Giese et al., 2020; Haaf et al., 2020; Ascott et al., 2020; Wunsch et al., 2021; Sorensen et al., 2021; Bosserelle et al., 2023), the function of groundwater in ecosystems (Martens et al., 2013), and errunoff processes (Rinderer et al., 2019).

The primary focus of this study is to unveil GWL dynamics on global, regional, and local scales by analyzing local data that is distributed globally. The importance and vulnerability of coastal groundwater, which serves as a vital freshwater resource for ecosystems and large coastal communities with increasing water demands from groundwater (Oude Essink et al., 2010; Famiglietti, 2014; Ferguson and Gleeson, 2012; Moosdorf and Oehler, 2017), prompts this study to focus on disentangling GWL dynamics in coastal regions. Other studies have pointed out that understanding processes is limited when only the long-

Kommentiert [AN3]: Added references as recommended by reviewer 1

Kommentiert [AN4]: Corrected citation style

Kommentiert [AN5]: Added Bosserelle et al. 2023 to the list (recently published).

65 term mean or trend of GWL dynamics is used (Lischeid et al., 2021; Gleeson et al., 2021; Baulon et al., 2022a). In this study, www.e seek to aim at answering the following research questions:

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- 1. How is hydrogeological similarity observed on a global scale, and what are the implications of scaling on similarity patterns?
- 2. What are the key controlling factors for GWL dynamics patterns on a global scale, and how do they explain the variations observed at smaller scales?
- 3. What are the current opportunities and barriers to deriving generalizations of dynamics-control relationships in groundwater using data-driven approaches?

This study accesses The basis for answering these research questions is a newly compiled large and diverse dataset of about 8,000 GWL time series of coastal aquifers from five continents. Information from the compiled and pre-processed time series (Sect. 2.1) was analyzed holistically using a set of previously defined statistical metrics from Heudorfer et al. (2019) that were Heudorfer et al. 2019 computed from individual groundwater hydrographs (Sect. 2.2), thereby reducing their dimensionality (Wang et al., 2006). Sect. 3.1 derives GWL dynamics patterns in coastal regions by using unsupervised clustering techniques (Sect. 2.3) to group GWL time series based on information derived from these aforementioned statistical metrics (Sect. 2.3). The importance and vulnerability of coastal groundwater, which serves as a vital freshwater resource for ecosystems and large coastal communities with increasing water demands from groundwater (Oude Essink et al., 2010; Famiglietti, 2014; Ferguson and Gleeson, 2012; Moosdorf and Oehler, 2017), prompts this study to focus on disentangling GWL dynamics in coastal regions. To deepen our understanding and elucidate key controlling factors for GWL dynamics, To explain these findings, independent data encompassing various potential controls of GWL dynamics and associated surface processes were obtained from global map products (Sect. 2.4) and were used to predict clusters in a Random Forest (RF) classification task (Sect. 2.5) with the results being presented in Sect. 3.2. The RF approach is a robust choice for classifying groundwater dynamics, widely acknowledged in water science. With its capacity to capture non-linear dependencies and manage uncertainties such as unknown feature importance, overfitting, and outliers, RF provides a reliable tool for exploring complex interactions in natural processes (Tyralis et al., 2019). SHAP values were calculated for the RF model (Sect. 2.6). These are used to explain relationships between predicted clusters and descriptive features in Sect. 3.3. Such approaches of explainable machine learning have been rarely used, but are increasingly and successfully applied in hydrology (Worland et al., 2019; Yang and Chui, 2021; Wunsch et al., 2022; Liu et al., 2022; Haaf et al., 2023). These are used to explain relationships between predicted clusters and descriptive features in Sect. 3.3. We then discuss hydrogeological similarity results and the scaling effect (Sect. 4.1), evaluate derived explanations for GWL dynamics patterns (Sect. 4.2), and contextualize our findings within the framework of a case study region (Sect. 4.3). Section 5 provides concluding remarks.

Kommentiert [AN6]: Changes in this part of the introduction in response to the reviewer's recommendation to provide more clarity about our objectives and related methodology in the introduction:

- The position of two sentences has been changed for readability.

- A few (half) sentences have been added to clarify the novelty and objectives (including related methodology) of this study.

Kommentiert [AN7]: Explanation for using the RF approach added as recommended by reviewer 1.

Kommentiert [AN8]: Moved from the methods section to include the explanation of the use of explanable machine learning in the introduction (see previous comment regarding the RF approach).

95 2. Data and methods

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The design of this study consists of the calculation of statistical metrics (hereafter referred to as indices) using compiled GWL time series, and the clustering of GWL dynamics by applying unsupervised algorithms on the calculated indices. Subsequently, the clustering result that best differentiates characteristic groups of GWL dynamics was fed into an RF classifier together with local and regional natural and anthropogenic characteristics (hereafter referred to as attributes) from global map products that are potentially related to GWL dynamics. SHAP values were derived to understand the salient controls of each group of GWL dynamics. Unless stated otherwise, data pre-processing, modelling, and visualizations were done using Python (Python Software Foundation, 2021).

2.1 GWL time series and pre-processing

The GWL time series data set analyzed in this study was compiled from the national or and state governmental agencies listed in Table A1, in the years 2019 to 2022. Although attempts were made to find data for all coastal regions in the world, data collection focused on regions with a long coastline and large quantities of digitally available data. The wells from the compiled data set are mainly located in northwestern Europe (Belgium, Denmark, France, Germany, Ireland, Netherlands, and Sweden), but also in Australia, South Africa, Brazil, Canada, and the United States. The wells are part of the GWL monitoring networks of the respective countries, but anthropogenic impact on GWL dynamics cannot be ruled out for all wells. In addition, wells 110 may be affected by SWI and thus have variable density (Post et al., 2007). However, density gradients are not analyzed in this study, because our focus is on absolute variations of the GWL. The GWL time series were selected based on the following criteria:

- a) Availability of secondary information (in convertible units for homogenization):
 - Latitude and longitude of the well location (with variable accuracy)
 - Reference vertical point/datum to measure the GWL depth
 - Date of observation
- b) Well location and situation:
 - Selection of wells located at the global coasts: Well is located within 100 km distance of the shoreline. This follows the definitions of Martínez et al. (2007) and Mangor et al. (2017), which focus on ecological, economic, and social importance concerning coastal water resource planning. Thus, we did not aim to select aquifers directly related to marine processes, such as SWI.-
 - Selection of shallow aquifers with mean GWLs less than 100 m below ground surface. It is important to note that this criterion is used as a directional guideline rather than an exact marker, as there is uncertainty of up to a few meters in the absolute groundwater depth of observations referenced to sea level that were converted to ground surface reference with elevation data from the Shuttle Radar Topography Mission (SRTM) (Kulp and Strauss, 2018; Rodriguez et al., 2006; source-specific information in the Supplement).

Kommentiert [AN9]: Added explanation in response to

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- c) Temporal availability:
 - Data must be available for at least four complete calendar years during the period-within the years 1979 to -
 - Time series must not have more than ten percent missing observations with data gap lengths of no larger than two weeks after aggregation to weekly time steps.

To obtain a homogeneous data set, fFurther source-specific pre-processing steps were necessary because of due to the very diverse data presentation, for example, regarding format, labels, and units. The reader is referred to the Supplement for notes on groundwater data collection and pre-processing. Potential anomalies or change points of the individual time series that indicate human activities, measurement, or reporting errors were removed using Density-Based Spatial Clustering of Applications with Noise (DBSCAN; Ester et al., 1996) combined with — due to the large number of time series — visual inspection of suspicious time series, because we set the parameters rather conservatively, i.e. with the parameters set, DBSCAN detected outliers in more time series than we would have identified visually -(Fig. A1). In line with recent publications, a The systematic and additional visual inspection of groundwater time series was found to be beneficial, in line with recent publications (Barthel et al., 2022; Berendrecht et al., 2022; Lehr and Lischeid, 2020; Retike et al., 2022). Subsequently, temporal availability criteria were checked once again, with remaining data gaps being linearly interpolated and time series were transformed to the 0-1 scale for calculating indices.

2.2 Indices

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We calculated a total of 45 indices for all GWL time series using an unpublished R package (R Core Team, 2021) that was developed with the study conducted by Heudorfer et al. (2019). These indices statistically aggregate and describe various aspects of groundwater hydrographs; its their structure (e.g., interannual fluctuation heights and changes), distribution (e.g., alignment of the GWL with upper or lower fluctuation limits), and its shape (e.g., steepness of hydrograph increases and decreases). For more detailed descriptions of the used indices (Table B1), we refer to Heudorfer et al. (2019). In addition, there are other promising signature-based time series characterizations for hydroclimatic time series, as selected and explored in Papacharalampous and Tyralis (2022), Papacharalampous et al. (2023) and Wunsch et al. (2021).

2.1), which is at the lower end of the time period of four to eight years recommended in Heudorfer et al. (2019) Heudorfer et al. (2019). We decided to use short periods to enable a larger pool of time series to be taken into account for the global similarity analysis. The calculated set of indices transforms groundwater information into 45 static metrics. The resulting index value ranges were compared to those of Heudorfer et al. (2019) for quality control (Fig. B1). As a second n-outlier treatment besides applying DBSCAN to the original time series (see Sect. 2.1), time series with index values in the outermost 0.001 % of the index value distribution (4 * σ) were discarded.

For our approach, the indices were computed from weekly aggregated time series with a length of at least four years (Sect.

Kommentiert [AN10]: Clarified (requested by reviewers).

Kommentiert [AN11]: Clarified (requested by reviewer 1).

Kommentiert [AN12]: Added information for clarification of outlier treatments as requested by reviewer 1.

2.3 Cluster analysis

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Clustering of the indices was performed to find a generalized but robust representation of differing GWL dynamics in coastal regions. No specific indices were selected a priori to capture GWL dynamics holistically. This decision was made, because indices differ in their ability to describe GWL dynamics depending on the flow system and the groundwater regime (Heudorfer et al., 2019; Giese et al., 2020; Haaf et al., 2020). For a similar reason, Papacharalampous et al. (2023) recommended using a large variety of time series characteristics for similarity analysis in hydrology.

A Principal Component Analysis (PCA) was applied to index values after standardization to avoid redundancies among the 45 indices (Heudorfer et al., 2019; Fig. B2) and to reduce the number of features for clustering. The number of Principle Components (PCs) to be retained was set based on the scree plot and variance explained, yielding a dimensionality-reduced dataset, where indices are mapped as score values on the significant PCs. This was followed by a systematic search for the best aggregation on the scores using three different unsupervised clustering algorithms – agglomerative hierarchical clustering using the Ward criterion, k-means, and Gaussian mixture. Unsupervised methods aim to learn more about the internal dependencies among the explanatory variables (Bergen et al., 2019), meaning that no expectations regarding the number or patterns of clusters were pre-set. Instead, evaluation metrics (Rousseeuw, 1987; Caliński and Harabasz, 1974; Davies and Bouldin, 1979) were used to find the best arrangement of data points into clusters via optimizing within-cluster and between-cluster similarity and dissimilarity.

2.4 Attribute data

175 Understanding GWL dynamics requires integrated information from its manifold controls. These are typically represented by attribute data from hydrogeology climate, landuse and landcover, soil and lithology, surface waters, topography, subsurface structures, and (hydro)geology and anthropogenic activity (Moeck et al., 2020; Rajaee et al., 2019; Díaz-Alcaide and Martínez-Santos, 2019). For river catchments, such datasets have already been collected for the regional scale (Addor et al., 2017; Klingler et al., 2021) and the global scale, most notably the HydroATLAS (Linke et al., 2019). However, to date, there are no global datasets available that encompass the above-mentioned attributes specifically for groundwater studies (Haaf et al., 2020). Therefore, attributes mainly describing natural and anthropogenic characteristics and processes at the surface were collected from a variety of recent highest-resolution datasets available at the global scale (Table 1). These were used as proxies for global groundwater-specific datasets in this study.

While river catchments are typically well-defined by topography, subsurface catchments are often complex and vary on small scales (Vahdat-Aboueshagh et al., 2021). Despite recent efforts to develop a similar approach for calculating watersheds with a better representation for groundwater (Nölscher et al., 2022; Huggins et al., 2023), at the moment there is no best-accepted method for groundwater-relevant delineation of various surface attributes on large scales. One approach to defining the contributing area of a groundwater well is to rely on the immediate vicinity and place a circular buffer of selected diameter around the monitoring site (Johnson and Belitz, 2009; Knoll et al., 2019). Using this approach, we extracted attributes were

Kommentiert [AN13]: Moved to the top of this list (recommended by reviewer 1).

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extracted as averages averages from buffers of a 500 meters bufferradius placed around the well sites. The prepared attributes are of numerical and categorical type and contain information from multiple periods that have been unified where possible. The spatial resolution of the underlying source data is less than 30 arcseconds, which is about 1,000 meters, except for hydrological data, which is derived from grids with a spatial resolution of only 1800 arcseconds (approximately 55 km). Singleor multi-dimensional or multidimensional raster data and spatial vector data were downloaded and processed for the well

locations as follows (applied to each dataset as indicated in column * in Table 1):

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- +-Average (median or majority) raster values were extracted for buffer geometries using the "zonal statistics" tool in ArcGIS Pro (Esri, 2022) usingwith a cell size of 250 m.
- ²Earth Engine Python API was accessed to directly calculate median raster values for buffer geometries and data download.
- ³-Average (median or majority) values from geospatial vector data were extracted for buffer geometries using the "spatial join" tool in ArcGIS Pro.
- ⁴Distance was calculated between well points and polylines using the "near" tool in ArcGIS Pro.
- ⁵-Multidimensional rasters were aggregated to a single raster layer that presents the median or majority of superimposed raster cells of the period from 1981 to the latest available temporal dimension ("make multidimensional raster" tool and "raster aggregation" tool in ArcGIS Pro). Thereafter, we -6 cCalculated the median of multiple raster files using the "cell statistics" tool in ArcGIS Pro.-6
- For the distance of the well location to the closest river, we selected rRivers that have a catchment area of at least 10 km² or an average river flow of at least 0.1 m³ /sec-1, or both.

Table 1 List (alphabetically by attribute category) of numeric (num) and categorical (cat) attributes used to relate GWL dynamics 210 to controls and processes in this study. Single or multidimensional raster data and spatial vector data were downloaded and processed for well locations as follows (*): Average (median or majority) raster values were extracted for buffer geometries using the zonal statistics tool in ArcGIS Pro (Esri, 2022) using a cell-size of 250 m. 2-Earth Engine Python API was accessed to directly calculate median raster values for buffer geometries and data download. Average (median or majority) values from geospatial vector data were extracted for buffer geometries using the spatial join tool in ArcGIS Pro. Distance was calculated between well points and polylines using the near tool in ArcGIS Pro. Multidimensional raster were aggregated to a single raster layer that 215 presents the median or majority of superimposed raster cells of the period from 1981 to the latest available temporal dimension (make multidimensional raster tool and raster aggregation tool in ArcGIS Pro). 6 Calculated the median of multiple raster files using the cell statistics tool in ArcGIS Pro. 6 Rivers that have a catchment area of at least 10 km² or an average river flow of at least 0.1

category attribute name short description unit period source source data reference (avertemporal (conv spatial type resolution erted) aged) resolution anthropopulation density population density 2000 annual 30 arc sec CIESIN persons num (2018)pogenic km-2 (AQUAS irrigated area serviced by num 2000 multi-annual irrigation 5 acr min (<u>≈10 km)</u> groundwater TAT. 2021)Sie bert et al. (2015)

Kommentiert [AN14]: Clarified (requested by reviewer 1).

Kommentiert [AN15]: Inserted the Table 1 caption in the text as recommended by the reviewers

Kommentiert [AN16]: Added approximated linear units as requested by reviewer 1

Kommentiert [AN17]: Corrected reference

	groundwater_abstr action	actual net abstraction from groundwater	kg m ⁻² a ⁻¹	num	1981- 2016	monthly	1800 arc sec <u>(≈55</u> <u>km)</u>	Müller Schmied et al. (2020)	5,1
climate	temperature_mean	mean annual daily mean air temperatures	°C	num	1981- 2010	period average	30 arc sec (≈1 km)	Karger et al. (2017)	1
	temperature_max	highest temperature of any monthly daily mean maximum temperature	°C	num	1981- 2010	period average	30 arc sec (≈1 km)	Karger et al. (2017)	1
	temperature_min	lowest temperature of any monthly daily mean maximum minimum temperature	°C	num	1981- 2010	period average	30 arc sec (≈1 km)	Karger et al. (2017)	1
	precipitation	accumulated precipitation amount	kg m ⁻² a ⁻¹	num	1981- 2010	period average	30 arc sec (≈1 km)	Karger et al. (2017)	1
	PET	evapotranspiration of reference crop (ET0)	mm day ⁻¹	num	1970- 2000	period average	30 arc sec (≈1 km)	Trabucco and Zomer (2019)	1
	aridity	aridity index (high for more humid conditions, and low for more arid conditions)	-	num	1970- 2000	period average	30 arc sec (≈1 km)	Trabucco and Zomer (2019)	1
landuse and landcover	landuse	major landuse class	-	cat	1981- 2019	annual	30 arc sec (≈1 km)	Winkler et al. (2020)	5,1
	ecosystem	major terrestrial ecosystem class	-	cat	-	-	7.5 arc sec (≈250 m)	Sayre et al. (2020)	1
soil and lithology	soc	soil organic carbon 0-5 cm mean	dg kg ⁻¹	num		-	7.5 arc sec (≈250 m)	Poggio et al. (2020)	2,3
	bdod	bulk density 0-5 cm mean	dg cm ⁻³	num		-	7.5 arc sec (≈250 m)	Poggio et al. (2020)	2,3
	clay	clay content 0-5 cm mean	g kg ⁻¹	num	-	-	7.5 arc sec (≈250 m)	Poggio et al. (2020)	2,3
	sand	sand content 0-5 cm mean	g kg ⁻¹	num	-	-	7.5 arc sec (≈250 m)	Poggio et al. (2020)	2,3
	silt	silt content 0-5 cm mean	g kg ⁻¹	num	-	-	7.5 arc sec (≈250 m)	Poggio et al. (2020)	2,3
	lithology	major lithological class	-	cat	-	-	polygons	Hartmann and Moosdorf (2012)	3
	unconsol_sediment	unconsolidated sediments major class	-	cat	-	-	polygons	Börker et al. (2018)	3
	permeability	surface permeability	log(k) m²	num	-		polygons	Huscroft et al. (2018)	3
surface waters	streamflow	mean annual river discharge	m ³ s ⁻¹	num	1981- 2015	annual	30 arc sec (≈1 km)	Barbaross a et al. (2018)	5,1
	distance_coast	distance of well location to the coastline	km	num	-		polyline	Lehner and Grill (2013)	4

Kommentiert [AN18]: Corrected

	distance_stream	distance of well location to the closest river	km	num	-		polyline	Lehner and Grill (2013)	4,6
	runoff	runoff from land (sum of runoff components)	kg m ⁻² a ⁻¹	num	1981- 2016	monthly	1800 arc sec <u>(≈55</u> <u>km)</u>	Müller Schmied et al. (2020)	5,1
	TWS	total water storage (sum of all water storage compartments)	kg m ⁻²	num	1981- 2016	monthly	1800 arc sec <u>(≈55</u> <u>km)</u>	Müller Schmied et al. (2020)	5,1
topo- graphy and sub-	bedrock_depth	absolute depth to bedrock	cm	num	-	-	7.5 arc sec (≈250 m)	Shanggua n et al. (2017)	1
surface depths	wtd	water table depth to the shallow groundwater table	m	num	-	-	30 arc sec (≈1 km)	Fan et al. (2013)	5, 1
	elevation	elevation	m	num	1994	-	1 arc sec (≈30 m)	Farr et al. (2007)	2,3
	slope	steepness of elevation surface	<u>-</u> 2	num	1994	-	1 arc sec (≈30 m)	Farr et al. (2007)	2,3

2.5 Random Forest model

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clusters (Sect. 2.3),-using ta set of attributes (Sect. 2.4). Well locations were considered for the RF classification (Breiman, 2001) only when data for all attributes were available. Furthermore, to avoid multiple clusters for a single combination of 225 attributes, the cluster with the highest frequency was selected. The instance was retained if the identified cluster constituted more than 50 % of all clusters associated with that specific combination of attributes. The categorical attributes landuse, ecosystem, unconsolidated sediment, and lithology were pre-processed for their use in the RF model using one-hot encoding. The RF model was optimized and evaluated with a stratified split of the dataset into a group for training and optimization (80 % of the data) and a group for testing (20 % of the data), taking into account an imbalanced dataset, where not all clusters have equal numbers of wells assigned and where regions are not represented equally by the dataset. For model optimization, hyperparameters were tuned within a <u>5five</u>-fold cross-validation framework. RF is a tree-based method that contains structures for feature selection (Breiman, 2001). No explicit feature selection was applied during pre-processing or model optimization, driven by the objective of exploring the relative importance and effects of all potential controls as well as their collective impacts on GWL dynamics. Evaluation during model optimization and with the testing data of the optimized model was carried out using the model accuracy, calculated as the total number of correctly assigned classes divided by the sample number. In addition, the optimized model, i.e. the success of the classifier, was evaluated with metrics for the individual clusters: precision; recall; F1-score. Here, precision is the number of correctly-identified wells per cluster divided by all the times the model

From n identified clusters (Sect. 2.3), tThe classification task was to assign the correct cluster from out of From n identified

Kommentiert [AN19]: Corrected sentence.

predicts that cluster. Recall is the number of correctly-identified wells per cluster divided by the total number of wells in that cluster. The F1-score is twice the multiplication of precision and recall (2 * precision * recall) divided by the sum of precision and recall. RF in general works reasonably well when using the default values of hyperparameters in common algorithms (Probst et al., 2019). However, performance improvements can still be achieved by tuning especially the number of trees that should be set high enough for robust results and the number of features considered for each time the tree is split. Up to 2,000 trees were tested in combination with either all features or their square root being considered when looking for the best split using two different splitting criteria ("Gini" impurity and "Entropy": Breiman, 2001).

Kommentiert [AN20]: Reviewer 2 asked for the Gini criterion and a reference in the results section, however we already provide the reference and information about the use for the criterion here

245 2.6 SHAP analysis

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SHapley Additive exPlanations (SHAP) values (Lundberg et al., 2020) were used to investigate the feature attributions (feature importance and feature effects) to explain the RF classification. Such approaches of explainable machine learning have been rarely used, but are increasingly and successfully applied in hydrology (Worland et al., 2019; Yang and Chui, 2021; Wunsch et al., 2022; Liu et al., 2022; Haaf et al., 2023). The three-dimensional space of SHAP values for the multiclass problem of this study is given by the number of clusters, the number of samples, and the number of features, i.e. attributes. Larger SHAP values for a specific cluster correspond to a higher probability of the cluster label. SHAP values of the samples that are part of the test dataset were analyzed collectively to explain how attributes impact the classification of the model. This corresponds to a global explanation of the model. For some analyses, SHAP values were combined for the attribute categories listed in Table 1. The SHAP values of individual instances, i.e. for well sites, were combined with regional information to discuss the extent to which the generalized GWL dynamics derived through the indices approach of this study can be explained in a case study region. When explaining controls of GWL dynamics from SHAP values, it is important to consider the interrelationships between the features. From the point of redundant features, the model is mainly trained on the feature with the most significant information in combination with other selected features. Hence variables that combine information included in other features are generally ranked higher and reduce the ranking of the other redundant features.

Kommentiert [AN21]: We changed the position of figures and Table 2 to follow the recommendation by reviewer 1 to display figures/tables after they have been explained

260 **3. Results**

3.1 Identification of groundwater level dynamics patterns

Application of the time series selection criteria from Sect. 2.1 resulted in a set of 8,574 GWL time series for which 45 indices were calculated, respectively. After removing time series with extreme index values (Sect. 2.2), a dataset with indices for 7,888 time series remained. The value ranges for <u>each of</u> the different indices are comparable to those found by Heudorfer et al. (2019) (Fig. B1). Several indices showed a strong linear correlation (Fig. B2). From the PCA, five PCs represented 70_% of the variability of the linearly combined indices, while the first three PCs already described more than half of the variability

(Fig. C1). The top five PCs served as input for the three clustering algorithms. The threese algorithms yielded similar results, where the highest cluster separation was achieved with three or four clusters (CL). K-means yielded the best cluster separation compared to hierarchical clustering and Gaussian mixture on all three evaluation criteria for cluster separation (Fig. C2). Comparing the cluster membership of wells, cluster composition based on k-means clustering is found to be quite similar to hierarchical clustering for most well sites (Fig. C3). The various characteristics of GWL dynamics can be assumed to exhibit complex and non-linear interlinkages in the multidimensional space.

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Given the nature of the data set, the success of the different clustering approaches for disentangling GWL dynamics can be mainly attributed to the following two aspects. Firstly, it is plausible that the data distribution may not strictly follow Gaussian distributions because already individual indices show nonlinear behavior (Fig. B1; Haaf et al., 2020), limiting the effectiveness of Gaussian mixture models. In such cases, the characteristics of the dataset can favor clustering algorithms such as k-means and hierarchical clustering that are more flexible with regard to the range of cluster shapes and sizes. Secondly, multidimensional datasets with complex and non-linear interlinkages may often lack clearly defined and compact clusters (Campello et al., 2020). This , which becomes evident when upon analyzing the scatter plot of the first three PCs (Fig. C3). This , makinges clustering for with k-means and hierarchical clustering challenging. However, despite this limitation, these algorithms still exhibit advantages in terms of capturing the distribution requirements of the GWL dynamics dataset and k-means best disentangles the main patterns within GWL dynamics. Therefore, k-means was chosen to cluster the indices.

The predominant cluster differs between the coastal regions represented in this study. In regions with a high density of wells, usually all clusters are present (Fig. 1). Therefore, similar patterns of GWL dynamics are found in coastal aquifers across the globe. Regional spatial patterns, i.e. geographically concentrated clusters, are visible for South Africa and Australia where most wells belong to cluster CL3 and within Europe, where most of the wells in the dataset are located. For example, in Germany wells assigned to CL3 are mostly located around the Baltic Sea and further inland, while the other clusters are pronounced along the exposed west coast. In the Netherlands and Belgium, most wells belong to CL1 and CL2. Most wells in north-eastern France are assigned to CL3, whereas most wells in north-western France are assigned to CL2. Each cluster represents a distinct pattern of GWL dynamics, regardless of shifted or opposing seasons in different regions, as shown in Fig. 2. where, fF or example, the double hump in the average annual hydrograph of North America with time series from wells being located mainly in the upper latitudes could be attributed to snowmelt and is found in all clusters. Patterns are the most precise (smallest confidence intervals) for the European dataset.

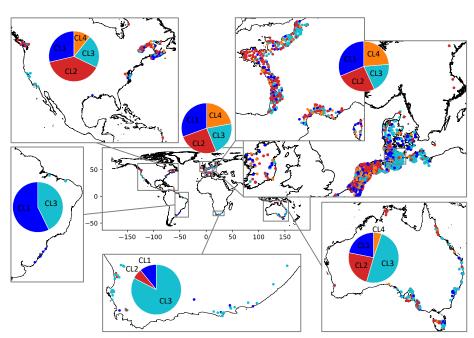


Figure 1 Assignment of clusters to well locations globally (center) and in coastal regions in North America, Europe (enlarged map of France and northwestern Europe), Australia, South Africa, and Brazil. Due to the large scale, overlapping dots are not jittered, but well points are shuffled to prevent the same clusters from being constantly drawn over others.

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GWLs in three out of four clusters can be located either mostly at their upper (CL1) or lower (CL4) boundary during the year 300 with high GWLs in winter and spring to low GWLs in summer, or the GWL fluctuates around its annual median during the year with high interannual amplitude (CL2). In contrast, are the GWLs of CL3 are characterized by, where the maximum of the water levels is being reached later in the year.

Kommentiert [AN22]: Figure improved for color vision deficiencies (revision of color schemes demanded by Polina Shvedko when uploaded files were validated). In addition to the color scheme of the clusters, the gray background map has been replaced, making the clusters stand out better

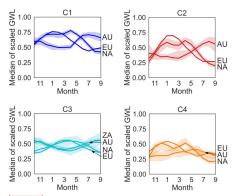


Figure 2 Annual hydrographs (median and 95,% confidence interval) from averaged groundwater depths of scaled GWL time series for each month per cluster, calculated and plotted for different the coastal regions in North America (NA), Europe (EU), South Africa (SAZA), and Australia (AU) when at least ten time series associated with the respective cluster were available.

The clusters can be distinguished with respect to multiple features of the hydrograph, expressed by indices. Thus, the salient pattern of each cluster is defined by several indices, not by an individual one. However, some individual indices allow to separate clusters or groups of clusters better than the others. Fig. 3 shows how different aspects of GWL dynamics, each described by multiple indices (Table B1), contribute to disentangling patterns of GWL dynamics. Many indices of multiple components clearly separate clusters concerning the hydrograph *structure*, including the regularity of the seasonal amplitude (*parde.seasonality*) that is small for CL1 and CL3 and largest for CL2, the size of the global amplitude of the unscaled GWL that is comparatively small for CL4, the manifestation of interannual variation (e.g. from Base Flow Stability BFS that implies that interannual variation is rather stable in CL3 and unstable in CL4) and different order of flashiness (e.g. from Base Flow Index BFI) where the baseflow component is large for CL3 and small for CL4). From the time series distribution aspect, GWL dynamics from CL1 can be characterized as upper bounded, while GWL dynamics from CL4 are slightly lower bounded (e.g. from median). Dispersion over the range of GWLs (e.g. from the range of duration curve (fdc.range) between different percentiles) is smallest in CL1 and largest in CL2. The shape of GWL time series in terms of both scale (hydrograph magnitude – sqr.avg) and slope (e.g. from rise.avg) distinguish the clusters quite well from each other. For example, CL3 is particularly noticeable for combining GWL time series with a small slope while CL4 combines such with a large slope.

Kommentiert [AN23]: Color scheme improved.

Kommentiert [AN24]: Added to follow the request by reviewer

Kommentiert [AN25]: Added to follow the request by reviewer

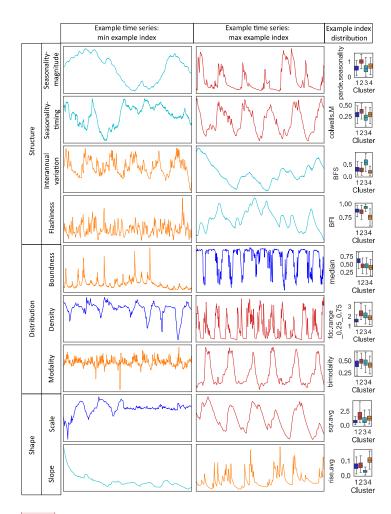


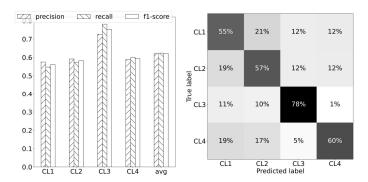
Figure 3 Example groundwater time series from the European continent illustrate typical scaled GWL time series where one aspect from each component of the Heudorfer et al. (2019) typology of GWL dynamics (Table B1) is weak (left column) and strong (right column), using with an example index from that component that is displayed showing within-cluster variability (see Fig. C4 for within-cluster variability for all indices).

Kommentiert [AN26]: Color scheme improved.

3.2 Classification of groundwater level dynamics patterns

In the classification task using RF, controls of GWL dynamics were investigated using more than 5,000 unique cluster-attribute relationships. Stable classification accuracy during hyperparameter tuning was achieved with more than 100 trees. Both splitting criteria that were tested performed equally well in terms of classification accuracy, whereas the consideration of different features for the splits lead to a significantly better higher accuracy (Fig. D1). The final model of this study was set up using the Gini criterion, randomly varied subsets (square root) of features for each split and 700 trees.

With the final model, approximately 62.% of the clusters on average were classified correctly, i.e. were assigned to the correct cluster out of four. Comparing the model's result accuracy to a scenario where descriptors were shuffled shows an improvement in accuracy of about 60.%. By shuffling the attributes, the relationships between the descriptors and the target variable (clusters) are disrupted, and any observed accuracy in the shuffled model is purely due to chance. These results suggest the presence of moderately strong linkages between the attributes and clusters describing distinct GWL dynamic patterns within the RF model. Fig. 4 shows that the classification performance is distributed slightly partly unequally across the different clusters. From the confusion matrix, it can be seen that CL3 is most often (78.%) predicted correctly and, if not, is either confused with CL1 or CL2, but almost not with CL4. The other clusters are predicted correctly similarly often, with accuracies ranging from 55.% to 60.%. Recall and precision of the clusters are quite similar. Considering the slightly different support of each cluster, the classification performs on average similarly well in terms of false positive cluster assignments (e.g. a well site is classified as CL1 when it actually belongs to another cluster), and false negative assignments (e.g. a well site that belongs to CL1 is not classified as CL1 but to as another cluster). Overall, tThere is are only not much minor differences in classification performance between among the different various coastal regions.



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Figure 4 Performance of the classification task using Random Forest (Breiman, 2001). Left: Evaluation metrics of classification (precision, recall, and f1-score) given per cluster and for the weighted average (performance metrics weighted accordingly to the support of each cluster). Right: Normalized confusion matrix. Rows represent the actual cluster, while columns represent the

predicted cluster. Thus, the percentages of correctly predicted classes are represented on the diagonal elements and the confusion (i.e. misclassification) is represented on the off-diagonal elements.

3.3 Model explanations from SHAP values

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SHAP values that were calculated for the classification model are used in the discussion to explain the importance and effects of different controls on GWL dynamics, while general results for the RF model are presented here.

Firstly, bBy analyzing the correlation of SHAP values, we can detect where feature importance may be affected by information redundancy (Fig. E1). In this study, the redundancy among features tends to be small or moderate, and patterns are not very consistent across the clusters. Specifically, the redundancy between feature groups (in correspondence with categories of attributes in Table 1) is minimal for cluster CL3 in the model, whereas it is more evident for cluster CL4. In the case of cluster CL2 exhibits, there is a redundant contributions of from anthropogenic features with and features derived from surface waters, with climate features being additionally redundant to the prediction of cluster CL1.

Secondly, tThree groups of features are ranked higher in terms of overall feature importance in the global model compared to the remaining three groups (Fig. E2). These are topography and subsurface depths, followed by soil and lithology, and climate, with only minor differences in the importance of the features between the clusters. The largest difference is that the feature group topography and subsurface depths are about twice as important in the model for predicting CL3 compared to as the other three clusters. F, for which these clusters, the feature groups soil and lithology and climate are as similarly important as topography and subsurface depths. Therefore, features of the group topography and subsurface depths primarily play a role in distinguishing CL3 from the other clusters.

More in-depth insights into how the model can distinguish the clusters and in particular CL1, CL2, and CL4 from each other through the various features can be derived when using SHAP values to link the feature impacts to their effects (Table 2; Fig. E3). From the individual features, elevation, slope, and water table depth (wtd) are most important within the feature group topography and subsurface depths, soil fractions and the (non)occurrence of specific unconsolidated sediments are most important within the feature group soil and lithology, temperature is most important within the feature group climate, irrigation is most important within the feature group anthropogenic, distance to the coast is most important within the feature group surface waters and the (non)occurrence of a specific terrestrial ecosystem type is most important within the feature group landway and landcover.

The most significant effects that features have on predicting clusters in the RF model are those that best separate clusters from each other (Table 2). CL3 is best distinguished from the other clusters by a comparatively large elevation, large wtd, and large slope. In addition, some effects specifically separate (a) CL3 from CL4, (b) CL4 from CL1 and CL2, and (c) CL1 from CL2, although the latter is the least successful in the model (largest confusion values of CL1 and CL2 in Fig. 4). Thirdly, prevailing effects that features have on the prediction of clusters in the RF model (Table 2) are those that separate CL3 from the other clusters, effects that specifically separate CL3 from CL4, effects that separate CL4 from CL1 and CL2, and effects that separate CL1 from CL2, although the latter is least successful in the model (largest confusion values in Fig. 4). CL3 is best distinguished

Kommentiert [AN27]: Rephrased sentences. The reviewers found it misleading.

from the other clusters by a comparatively large elevation, large water level depth, and large slope. In comparison with CL2, CL3 combines well locations with lower minimum and average temperatures and sediments typical for glaciofluvial deposits. In comparison with CL1, CL3 combines well locations with less precipitation, more coarse-grained soils and less anthropogenic activity. Feature effects between CL3 and CL4 are most often oppositecontrary, although less pronounced for climate. Where CL1-CL2 is predicted, there are also comparatively more coarse-grained soils, and rather not sediments typical for aeolian deposits, and anthropogenic activity is low. These characteristics from soil and lithology as well as anthropogenic activity also separate CL4 from CL2. Less differentiates CL4 from CL1. It is noticeable that the distance of the well to the coast is generally higher in CL4 compared to CL1. The typical well locations in CL1 and CL2 differ in their soil fractions (finer-grained soils in CL1) and anthropogenic activity (larger in CL1).

Table 2 Qualitative description of the more important and in their effects more differentiable features, starting with the feature group with the greatest importance for the model (Fig. E2), for the prediction of the individual clusters in comparison based on Fig. E3. "<" and ">" mark smaller and larger feature values for one or more clusters compared to one or more other clusters, while there is no unique clear information for —. *aridity index: see Table 1.

category	attribute/feature (name)	CL1	CL2	CL3	CL4
topography and subsurface depths	elevation	<	<	>	<
	wtd	<	<	>	<
	slope		<	>	<
soil and lithology	soil fractiongrain size (clay; silt; sand)	<	>	>	<
	aeolian deposits (unconsol_sediment_Ae)		<	<	>
	glaciofluviale deposits (unconsol_sediment_Gf)		<	>	
climate	temperature (_min; _mean)		>	<	
	precipitation	>		<	
	aridity*	>	>	<	>
anthropogenic	irrigation	>		<	>
	population_density		<	<	>
surface waters	distance_coast	<			>
landuse and landcover	cold temperate moist grassland on plains	>		<	>

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LastlyFinally, SHAP values for individual wells that are all located in the same region in northern Germany (Fig. 5) can be used to understand to what extenthow the results of the feature importance and effects also derived from the global data set apply regionally. We analyzed the SHAP values were analyzed for of four well sites from the case study region that have located in northern Germany (Fig. 5) with the highest model's probability of being predicted by the model for predicting each cluster in the test dataset (Figs. E4-E7). While the wells that are most likely to be predicted as CL1 and CL3 belong to are also included in these clusters, whereas the wells that are most likely to be predicted as CL2 and CL4 belong to are part of CL3. Thus, although CL3 is overall the best-identified cluster by the model (Fig. 4), in the case study region, where most of the wells belong to CL3, it is confused with CL2 and CL4 for the example wells. Theat CL1 is correctly prediction of CL1ed is

Kommentiert [AN28]: Corrected

due to the low elevation and wtd at the well location as well as the presence of grassland (Fig. E4). Due to these characteristics, the well is also not predicted to be CL3, while the region/sand mean temperatures around 10 °C also favor CL3 at this well site. The statistically averaged temperatures, which should be very constant for the region, can sometimes favor and sometimes disfavor all clusters. According to local feature importance in this region, temperature is the most important attribute following elevation and wtd for the prediction of GWL dynamics types at specific wells. However, when analyzing SHAP values for a model trained on a global dataset, we are primarily examining the global context for a local feature, not the local context.

Besides confirming temperature, With these characteristics, the model predicts CL1 and CL3 over CL2 and CL4 in the case study region. CL3 is also correctly predicted where its prediction probability is largest, because of comparably large at the well location both-elevation in the study region and anthropogenic activity are high-andbecause there is no irrigation (Fig. E6). In contrast, a CL3 well is incorrectly predicted at the other well location as CL2 with low elevation and a population density that is below average for the region (Fig. E5). Another hen the opposite is true. As CL4, CL3 well is also incorrectly predicted as CL4 with when-low elevation is low and and one of the highest clay contents for the region (Fig. E7) is high. The described correlations relationships are in line or not contradictory to the global correlations of Table 2.

Kommentiert [AN29]: We improved this paragraph because reviewer 1 found some sentences misleading. We added a clarification of what it means to analyse SHAP values for a model trained on global data at specific locations for clarification.

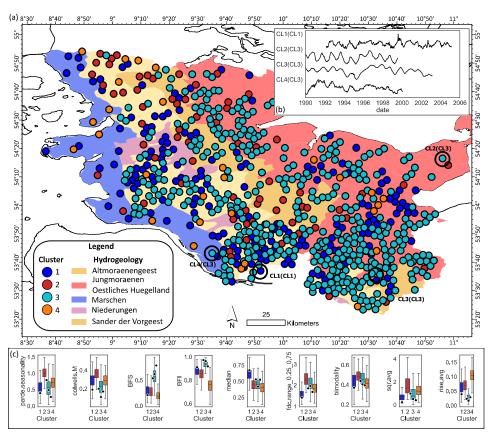


Figure 5 GWL dynamics patterns in the German federal state Schleswig-Holstein. (a) Cluster assignment to well locations and hydrogeology map of the German federal state Schleswig-Holstein (LfU-SH, 2003). Overlapping well markers are jittered at a minimum spacing of 500 meters and thus no longer represent the original well locations. Lighter cluster colors mark lower aquifer storeys. The cluster number in parentheses marks the true cluster from k-means clustering. (b) Exemplary time series of each cluster from the encircled well sites in (a). (c) Within-cluster variability of the example indices that each represent a component of the Heudorfer et al. 2019 typology from Fig. 3 plotted with indices values (dots) of the encircled well sites in (a) where the dots between CL2 and CL3, and between CL4 and CL3 mark the wells that have the highest probability for CL2 and CL4 in the RF model but belong to CL3 according to the indices clustering (see Fig. C5 for within-cluster variability for all indices that are plotted together with indices values of the selected well sites).

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Kommentiert [AN30]: Figure improved for color vision deficiencies.

4. Discussion

4.1 Hydrogeological similarity and scaling effect

Four predominant types of GWL dynamics were identified for coastal wells distributed across five continents. Our results show, that shallow aquifers exhibit more diverse GWL dynamics than deeper aquifers. This suggests that absolute GWL depth is less determinant in differentiating global GWL dynamics than might be assumed based on the clustering of direct time series from a single particular region, as in Rinderer et al. (2019) where in particular mean water level and amplitude of variation determine clusters of GWL dynamics.

Based on the spatial distribution of clusters, wells exhibit distinct regional structures that strongly imply the presence of underlying spatial controls, e.g. CL3 type GWL dynamics in northern Germany tend to coincide with Geest land, while CL1 type GWL dynamics are more often found in the marshlands (Fig. 5a). Another example is that the topographical elevated Veluwe region in the center of the Netherlands is the only region at the North Sea where many wells are assigned to CL3 (Fig. 1). However, GWL dynamics of different types are also frequently found in wells within a very short distance from each other or even on top of each other (in the case of multiple groundwater storeys). This means that the diversity of GWL dynamics can be larger locally than between two wells in different climate zones on different continents, likely due to the significant influence of heterogeneous hydrological conditions. Therefore, in addition to The first is more surprising than the second because it suggests a small-scale separation of groundwater landscapes. In line with the findings by Wunsch et al. (2021), it is shown, this result shows that nearby wells do not necessarily have a higher degree of similarity in GWL dynamics compared to more distant wells <u>even when these wells are located on different continents</u>. Regionally similar, but locally diverse GWL dynamics highlight the complexity of generalizing GWL dynamics on different spatial scales. Yet, the fact that our results 445 include spatial patterns at local, regional, and global scales (considering the globally distributed clusters of GWL dynamic types), speaks forpoints to the usefulness of our approach in finding generalizations beyond specific geographic contexts. We therefore conclude that our approach is robust their robustness-with respect to scale dependency. Before, studies on GWL dynamics have resulted in system understanding at local and regional scales (Wunsch et al., 2021; Giese et al., 2020; Haaf et al., 2020). Although-While this may be more straightforward for applied groundwater management and monitoring at these scales, this study is the first to provide insights into generalizations of GWL dynamics using a global dataset.

The methodological approach underlying the GWL dynamics analysis offers much potential but also has limitations and uncertainties with respect to the validity of the generalizations generated. We found that using indices for analyzing GWL dynamics is efficient, and offers comparability and interpretability. In these terms, this approach might be superior compared to directly analyzing GWL time series or only focusing on the long-term mean or trends. Heterogeneous time series with different seasons, time series lengths, and periods can be combined in this methodological approach with robust results as previous studies have shown (Heudorfer et al., 2019; Wunsch et al., 2021), thereby reducing the dimension of the time series and potentially better establishing cause-and-effect relationships. From the clustering results, we can see that indices

Kommentiert [AN31]: Clarified as recommended by reviewer 1.

Kommentiert [AN32]: Reviewer 1 asked us to stress more on spatial patterns at different scales. We therefore rephrased parts of this section in order to provide more detailed and clarified information (and also added a sentence to the introduction).

successfully separate between climatic forcing (as present in seasonality) and physiographic forcing, while in practice it remains challenging to identify what drives GWL dynamics at various scales and settings (Blumstock et al., 2016; Moeck et al., 2020) and to distinguish between the impacts of climatic and other natural factors versus anthropogenic impacts on GWL dynamics and trends (Wriedt, 2017; Lischeid et al., 2021). Furthermore, from a global perspective, GWL time series are rarely sufficiently long to recognize the dimension of climate change. Although indices are also affected by the length of the GWL time series (Heudorfer et al., 2019), they can help to identify time series with "high-amplitude, low-frequency variability," such as in the Normandy (Paris Basin, France; compare Baulon et al., 2022b). Groundwater well sites with dominant interannual variations from multi-annual to decadal scales identified by Baulon et al. (2022b) in this area match well sites with CL3 type GWL dynamics found in this study (Fig. C6). At these well sites, the likelihood of approaching short-term groundwater drought is greater-higher if the prevailing low-frequency variability is associated with a downward phase, while the annual groundwater-levelGWL status and last winter's groundwater recharge have less influence on short-term drought (Baulon et al., 2022b). Overall, we can therefore assume that longer residence times are typical characteristics for CL3-type aguifers

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The methodological approach underlying the GWL dynamics analysis offers much potential but also has limitations and uncertainties with respect to the validity of the generalizations generated.

Despite that general robustness of indices was found starting at time series with a minimum length of four years (Heudorfer et al., 2019), uncertainties remain regarding the representativeness of the generalizations for individual wells with this time series period length, but less so for the generalizations themselves. Furthermore, Heudorfer et al. (2019) originally defined some of the indices for time series with daily resolution, and decadal GWL dynamics are only indirectly represented by indices in our study (e.g. seasonality in the annual hydrograph). Therefore, further investigation of the effects of different temporal resolutions and time series lengths, as performed in Papacharalampous et al. (2023) for hydroclimatic time series, would be of interest. With respect to the groundwater systems and processes represented by the GWL dynamics patterns, it should be emphasized that there may be a bias in favor of the typical GWL dynamics in northwestern Europe because most of the wells in the dataset are located there.

Classification of specific groundwater processes requires input data specifically related to and known to be influential to these processes. However, there are major limitations with available GWL data, particularly in terms of time series length, and data resolution. Furthermore, from a global perspective, GWL time series are rarely sufficiently long to recognize the dimension of climate change, making it difficult to establish an effective monitoring and management strategy. High-resolution time series are, for example, required for analyzing the interaction of groundwater with the sea (Haehnel et al., 2023). Accounting for SWI in GWL dynamics pattern analysis is best supported by pattern recognition or correction together with groundwater chemistry data (Narvaez-Montoya et al., 2023; Parisi et al., 2023). However, the expansion of studies on this topic is currently hampered by the lack of GWL time series with high temporal resolution and long time series length currently hinders the expansion of such studies as well as the availability of qualitative groundwater data together with GWL data, among other

Kommentiert [AN33]: Added sentence for clarification as it was asked for by reviewer 1.

Kommentiert [AN34]: Moved here from above for a clearer separation of the implications of the results and the potential of our approach from the limitations and recommendations, because the reviewers additionally explained some limitations of this study (e.g. regarding SWI and anthropogenic impact in GWL dynamics) and asked for more clarity about this studys limitations.

Kommentiert [AN35]: Moved here from below because it fits better with the subsequent paragraph.

Kommentiert [AN36]: Added another reference from the list

challenges in groundwater monitoring practice (Rau et al., 2020). Several studies have shown the degradation of groundwater in qualitative and quantitative terms due to its overexploitation (Alfarrah and Walraevens, 2018; Peters et al., 2022; Xanke and Liesch, 2022), but it was beyond the scope of this study to focus on changes in groundwater systems. Furthermore, more indepth analyses of the individual indices could help to find out to what extent and in which indices specific processes such as SWI or anthropogenic influence are manifested and thus contribute to a classification.

Furthermore; The with respect to the groundwater systems and processes represented by the GWL dynamics patterns, it should be emphasized that there may be a bias in favor of the typical GWL dynamics in northwestern Europe because most of the wells in the dataset are located there, indices-cClustering analysis has been conducted in this study was instrumental in capturing the major GWL dynamics patterns observed in GWL dynamics of coastal regions worldwide-this study. The utilization of the k-means algorithm has enabled us to represent these patterns at a high level, providing valuable generalizations. However, if in other research questions the necessary level of pattern recognition is smaller, clustering algorithms that do not require both clearly distributed data and clearly defined clusters have the potential to identify additional clusters and uncover more nuanced dynamics within the dataset.

4.2 Cause-and-effect relationships

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We <u>further</u> analyzed whether the identified types of GWL dynamics are meaningful, i.e., consistent with expected patterns (Yang and Chui, 2021), although machine learning can also reveal undetected and previously unexplained patterns. We generally expect patterns as a result of the multitude of natural and anthropogenic factors influencing GWL dynamics.

Meaningful GWL dynamics <u>further hold have the</u> potential to derive cause-and-effect relationships between GWL dynamics and their driving forces, a topic for which observation-based evidence is comparatively scarce. <u>I that are comparatively rare yet.</u> Thus, in this study, driving forces were linked to GWL dynamics patterns in an RF classification task. Here, many different environmental attributes describing surface and <u>to a smaller extent</u> subsurface processes, potentially associated with groundwater recharge and discharge, were used to explain (dis)similarities within and between the identified patterns.

While comparing individual aspects of the hydrograph with potential controlling factors can only explain specific aspects of GWL dynamics (e.g. Haaf et al. (2020) related flashiness (BFI) to focused recharge as a consequence of depressions or connectivity to streams), the holistic analysis of various GWL dynamics aspects against controls enables the estimation of the influence of multiple controls on processes defining groundwater quantity over time.

Since GWL dynamics in coastal regions can be similar in different regions globally, similar GWL dynamics are not necessarily the result of the same cause-and-effect relationships. Rather, it can be expected that there are complex interlinkages of multiple controls that favour hydrogeological similarity at different manifestations of the individual attributes. We, therefore, confirm our initial expectation that similar GWL dynamics derived from indices are associated with multiple processes and, vice versa, that the important controls and processes can be identified and distinguished by a combination of indices. This is in line with previous findings with hydro-climatic time series (McMillan, 2020; Beck et al., 2016).

Kommentiert [AN37]: Added literature as recommended by reviewer 1 to underline this important topic.

Kommentiert [AN38]: We have included additional information in response to Reviewer 1's questions raised about the usefulness of this study and the impact of the management of the indices in this study for/on the visibility of specific phenomena such as SWI and anthropogenic impact.

Kommentiert [AN39]: Revised sentence for clarification

is related to hierarchical relationships where climate, topography, and soil conditions have a greater influence on the location occurence and characteristics of surface waters and as well as landuse and landcover than the other way around (Fig. E2). This implies that the direct influencing factors offer more explanatory power. Then again, direct influencing factors in the attribute dataset are more often based on actual observations and often have a higher resolution, (e.g. the minor explanatory power of attributes from surface waters might also be related to a coarse spatial resolution of about 55 km). From the importance of $elevation \ and \ water \ table \ depth, \ especially \ for \ the \ determination \ of \ CL3 \ type \ dynamics \ and \ differentiation \ from \ other \ dynamics$ that are more often found in near-surface aquifers, it can be concluded that these attributes mainly describe the increasing damping effect of groundwater recharge with increasingly long soil passages. The generally high importance of climatic attributes for GWL dynamics in this study—either only in the long term or also in short periods—is scientific consensus making climate change usually part of assessments of changes in groundwater systems (Riedel and Weber, 2020). Also, within the group of climatic attributes, the importance of direct attributes such as temperature outweighs derived attributes such as the aridity index. According to Table 2, certain types of unconsolidated sediments and a terrestrial ecosystem can distinctly indicate or exclude specific GWL dynamics types. These manifestations of categorical attributes are likely to serve as proxies for the general importance of their class. Due to the multitude of manifestations, only the most common ones likely appear in the importance ranking in Fig. E3 (e.g. aeolian deposits mainly exist in the Netherlands which also provides the most wells in the dataset). Anthropogenic activities such as irrigation and groundwater pumping typically have a localized effect. They have the potential to overprint different types of GWL dynamics even when the hydrogeological setting is the same (Sorensen et al., 2021). Together with small-scale lithological and hydrogeological peculiarities, they likely contribute the most to the variability of GWL dynamics patterns on a small scale locally and regionally. Sect. 4.1 emphasizes the importance of the data basis, including its current limitations, for assessing certain processes. FFrom the comparably minor importance of anthropogenic attributes for GWL dynamics, it ean-could be assumed that global groundwater quantity is less influenced by anthropogenic than by natural controls. On the one hand, ;-but this was also the expectation with using data derived from monitoring networks and

525 The results have shown, that relationships between GWL dynamics patterns and controls can be generalized for the global scale to some extent. Notably, the importance of different attribute categories (Table 1: Fig. E2) for shaping GWL dynamics

Kommentiert [AN40]: Moved here from below.

Kommentiert [AN41]: See comment in Sect 4.1: Reviewer 1 noted the significance of anthropogenic activity in groundwater degradation and questioned whether the use of indices in this study may have affected the visibility of this phenomenon. We refer to Sect 4.1 where we now highlight this topic, including recommended literature, and where we discuss how the design of the indicesclustering approach constitutes what patterns can be derived. We changed the order of sentences in this paragraph because it fits better with the argumentation in connection with the Sect. 4.1 paragraph.

after quality control. However, anthropogenic influence is difficult to disentangle from natural controls also in this study. On the other hand, it is unclear how much of the explanatory content of the anthropogenic attributes is based on anthropogenic activities and how much is due to correlations with natural controls (Fig. E1). Such interactions could be that irrigation is higher in dry climates and that there are more sealed surfaces where population density is high. HoweverTherefore,

anthropogenic influenceimpact is difficult to disentangle from natural controls also in this study. Anthropogenic activities such

as irrigation and groundwater pumping typically have a localized effect. They have the potential to overprint different types

of GWL dynamics even when the hydrogeological setting is the same (Sorensen et al., 2021). Together with small-scale

lithological and hydrogeological peculiarities, they likely contribute the most to the GWL dynamic patterns on a small scale.

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Moderate accuracy of the RF model means that parts of the GWL dynamics derived from indices are not well predicted based on the used attributes. Hence, machine learning tools that are trained to find cause-and-effect relationships face the same challenge of process-based groundwater models: limited availability and quality of explanatory data, especially subsurface information. Even if there is great progress in the availability and quality of geoscientific data, surface attributes derived for the global scale are still biased by uncertainty in the data itself (Peng et al., 2017), coarse spatial resolution, (e.g. here the minor explanatory power of attributes from surface waters might also be related to a coarse spatial resolution of about 55 km) and by the period they cover. In the presented approach no dynamic attributes were used because they are not available for all attribute et al., 2014). That explanatory information is missing in the RF model for differentiating GWL dynamics at the local to regional scale can be observed, for example, in the case study region in Northern Germany (Fig. 5), where Furthermore, as explained in Section 2.4, studies of global scope such as this one face limitations in accurately defining subsurface catchments, the temperature should not vary significantly between well locations. However, according to SHAP values, temperature is the most important following elevation and water table depth (WTD) for the prediction of GWL dynamics types at specific wells (Fig. E4-E7).

4.3 Case study

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Finally, the question also arises to what extent it is possible to explain the generalized GWL dynamics derived with the indices_ clustering approach of this study also regionally if attributes were only good enough. The inclusion of regional context using the case study from northern Germany (Fig. 5) serves a dual purpose in our study. First, in Sect. 4.1 we assessed the robustness and validity of our proposed approach for identifying GWL dynamics on different scales. In this section, the case study serves as a critical testbed for understanding the chances and limitations of extrapolating explanations for patterns of GWL dynamics from the global to the regional scale. A ground-truthing of the GWL dynamics patterns using expert knowledge from the case study region in northern Germany will shed light on this in the following. This case study was selected because a 580 hydrogeological map and related hydrogeological information exist (LfU-SH, 2003), and information on the aquifer storey of the wells included in the GWL time series source dataset includes information on the aquifer storey of the wellsare available, and at the same time, the well density is high, and the accuracy of the RF model is about the same in this region as globally. These conditions, which allows the study of spatial patterns and the ground-truthing of the GWL dynamics patterns using expert knowledge.

To a large extent, the near-surface aquifer in this area is a pore aquifer of silicate type formed during the Ice Age (LfU-SH, 2003; Otto, 2001). The hydrogeological situation of the shallow groundwater can broadly be divided from west to east into three major landscapes: (a) low-lying marshlands (Marschen), (b) slightly raised Geest landscapes (Altmoraenengeest), the

Kommentiert [AN42]: The discussion about temperature was removed in accordance with the revised section 3.3.

Kommentiert [AN43]: We added this aspect of limitations with the RF modelling approach in the discussion as suggested by reviewer 1.

Kommentiert [AN44]: The two reviewers found it difficult to understand the purpose of the case study and asked for more information. To address this, we have included/revised these sentences for clarification.

lower outwash plain (Sander der Vorgeest) and intervening depression zones comprising the river valleys (Niederungen) and (c) morainic uplands with stronger relief (Jungmoraenen Oestliches Huegelland).

Fig. 5a shows that the-GWL dynamics in the marshlands predominantly belong to CL1 (59 %), especially in the upper two aquifer storeys (68 %) and close to the sea, followed by CL3 (20 %) which combines more GWL dynamics of the lower aquifer storeys (60 %) and well sites at the border to the Geest. The Geest and uplands are characterized by GWL dynamics that mainly belong to CL3, with some exceptions including the Geest landscape in the north close to the Danish border (GWL dynamics are of mixed type), the area around the major depression in the north (GWL dynamics mainly belong to CL1) and the eastern uplands at the southernmost bay (GWL dynamics mainly belong to CL1). In the lower Geest, GWL dynamics belong more often to CL2 (23 %) than in other landscapes. As in the marshlands, type CL3 GWL dynamics are more often associated with lower aquifer storeys compared to the other clusters in these areas (63-78 %), with the difference that CL3 is also present to a similar degree in the upper aquifer storeys in the Geest and uplands (45-67 %). Fig. 5b displays example time series of wells that the RF model identifies as having the highest probability for each cluster. The cluster in parentheses indicates the actual cluster that is based-, among others, on_the indices values shown in Fig. 5c. In cases where CL3 was mistaken for CL2 and CL4, the example wells mostly exhibited have indices within the CL3 distribution (Fig. 5c). While there are minimal visual differences in the time series between CL2 and CL3 at the well location where CL2 is predicted, some distinctions can be observed in Fig. 5b when CL3 is misidentified as CL4.

The inability of the RF model to correctly predict these instances can therefore mainly be attributed to two factors. Firstly, the GWL dynamics at the predicted wells for CL2 and CL4 reside closer to the border between different dynamic types, making them more challenging to differentiate. This is confirmed by some very similar indices values to CL3. Secondly, the laek limited of explanatory potential provided by the attributes can be assumed to also contribute to the model's failure: Expert information suggests that small-scale differences in GWL dynamics in the case study region can be explained by lower aquifer storeys with good hydraulic connections to upper storeys and surface waters. The presence of both CL1 and CL3 dynamics in the higher Geest and upland regions, regardless of groundwater storey, can be attributed to differences in the soil covering, water table depth, and the existence of both unconfined and confined upper aquifers in these landscapes (LfU-SH, 2003). Comparing the ground-truthing withHowever, the RF model, offers some global explanations that apply to this regional context as well. For instance, in the marshlands and the northern depression zone, where impermeable sediments of small to medium

thickness overlay the aquifer (LfU-SH, 2003), the prevalence of CL1 and CL4 type wells is higher (Table 2).

5. Conclusions

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In summary, this study provides new insights into the hydrogeological behavior and the hydrogeological similarity of groundwater-in coastal regions. It utilizes an unprecedented dataset of GWL time series and demonstrates the development of a global information archive on GWL dynamics. With the presented methodology, the integration of both local variations and global patterns shed light on how similarities in GWL dynamics can be linked to the impacts and effects of various controlling

Kommentiert [AN45]: Additional information added.

Kommentiert [AN46]: Added to clarify the sentence

factors of groundwater recharge and discharge processes. We demonstrated that the proposed methodology allows capturing the GWL dynamics patterns at different granularity for high-level generalizations while retaining the potential to uncover more nuanced dynamics-controls relationships at smaller scales within the dataset. These findings can aid in developing broader frameworks for effective groundwater management. For example, by identifying regions with common characteristics and highlighting essential hydrograph features for global modeling.

Our results indicate-show that hydrogeological similarity manifests is a globally phenomenon that, with respect to the aquifers

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dynamics. Similar patterns clusters are observed globally across different environments continents and climate zoness globally, while GWL dynamics can be highly variable regionally and locallyspecific cluster compositions vary among regions, suggesting a complex interlinkages interplay of controlling factors. Therefore, it is important to consider GWL dynamics patterns at multiple scales as extrapolating GWL dynamics from a single well to the surrounding area may sometimes be less appropriate than inferring GWL dynamics from global relationships. However, establishing global may not be valid. General patterns and similarities in GWL dynamics identified for coastal aquifers at the global scale can assist in developing broader

near the coastline, can be divided intothrough the identification of four clusters representing distinct patterns of GWL

frameworks for groundwater management. Overall, dynamics-control relationships remains a challenge. We found that these

are mainly dominated by (a) topography and groundwater depth mainly determining the responsiveness of groundwater systems to impacts on the water cycle that well separates a single cluster from three others, and (b) climate and soil characteristics, which that differentiate these three clusters with high short-term and interannual variability. However, groundwater management typically requires a more accurate precisely explainationed of GWL dynamics by controlling factors, beyond what than is currently achievable possible with the available attribute data available from at the global scale. At present particular, disentangling the influence of anthropogenic activities impacts from the natural controls of in GWL dynamics, e.g. to and accurately predicting the impact of climate change on GWLs without incorrectly accounting for

smaller compared to natural characteristics in this study, more in-depth analyses were beyond the scope of this study. When analyzing certain processes, including SWI, it is important to pay attention to the data basis (selection of groundwater data and indices). To address the explanatory limitations of data-driven analysis and the prediction of GWL dynamics, we suggest using attributes closely related to actual observations and the direct influencing factors in combination with explainable machine learning techniques and

water withdrawals, <u>remains a challenge in the field of machine learning, which is of great importance for sustainable groundwater management.</u> While the overall importance of anthropogenic activities on GWL dynamics was found to be

We suggest relying more on groundwater hydrographs and derived indices for understanding GWL processes when attribute data areis scarce or associated with large uncertainties. Overall, Additionally, machine learning techniques combined with hydrograph information show promise for improving our understanding and predictive capabilities in addressing GWL complexities, especially at large spatial scales. We have demonstrated some physical explainability and plausibility of indexderived GWL dynamics across different scales. However, the main limitation of this study's approach is the limited explanatory power of the available attributes describing potential controls of GWL dynamics. Attributes derived solely from natural and

Kommentiert [AN47]: Extended outlook on the usefulness of this study with regard to water management, as this remained an open question for the reviewers.

Kommentiert [AN48]: We have clarified that while it is theoretically possible to extrapolate generalizations, it is currently limited due to a lack of explanatory data. Previously, we stated that there is a potential for unmonitored sites, which the reviewers correctly found to be too strong of a statement and which we therefore removed from the conclusions.

Kommentiert [AN49]: Moved from the end of Sect. 4.3 because from the reviewers comments, we realized that this information should be part of the conclusions.

Kommentiert [AN50]: Added in response to the reviewers general comment to be clearer about the scope and limitations of this study.

Kommentiert [AN51]: Moved from the end of Sect. 4.3 because from the reviewers comments, we realized that this information should be part of the conclusions.

anthropogenic characteristics at the surface alone may not fully capture the salient controls, particularly considering the low resolutions currently available for large spatial scales and that there is still no best way of identifying groundwater catchment areas at the surface without detailed information provided by bore profiles. One way to deal with this limitation is by utilizing attributes that directly represent influencing factors or attributes closer to actual observations in combination with machine learning techniques. At present, disentangling the influence of anthropogenic activities from the natural controls of GWL dynamics and accurately predicting the impact of climate change on GWLs without incorrectly accounting for water withdrawals remains a challenge in the field of machine learning, which is of great importance for sustainable groundwater management.

Furthermore, this study emphasizes the challenges posed by limited, especially subsurface, data in capturing the complexity of GWL dynamics. While hydrogeological similarity offers potential for transferring GWL dynamics from monitored to unmonitored sites, planning

Appendix A: Groundwater data

Table A1 List (country-wise alphabetical) of governmental agencies or portals from which groundwater data were obtained.

		country	access
			year
1	Australian Groundwater Explorer, Bureau of Meteorology	Australia	2021
	(http://www.bom.gov.au/water/groundwater/explorer)		
2	DOV, Datenbank Ondergrond Vlaanderen (https://www.dov.vlaanderen.be)	Belgium	2020
3	RIMAS, Integrated Groundwater Monitoring Database, Servicio Geologico de Brazil	Brazil	2022
	(http://rimasweb.cprm.gov.br/layout/pesquisa_complexa.php?rimas=true)		
4	Department of Environment and Climate Change, Nova Scotia (https://beta.novascotia.ca)	Canada	2021
<u>4</u> 5	GIN, Groundwater Information Network, Canada (http://gw-info.net)	Canada	2021
6	Ministry of Environment and Climate Change Strategy, British Columbia	Canada	2021
	(https://www2.gov.bc.ca/gov)		
7	GEUS, Geological Survey of Denmark and Greenland (https://eng.geus.dk)	Denmark	2019
8	ADES, Portail national d'accès aux données sur les eaux souterraines, France	France	2020
	(https://ades.eaufrance.fr)		
9	LLUR, Landesamt für Landwirtschaft, Umwelt und ländliche Räume des Landes Schleswig-	Germany	2020
	Holstein (https://www.schleswig-holstein.de/DE/landesregierung/ministerien-	-	
	behoerden/LLUR/llur node.html)		
10	NLWKN, Niedersächsischer Landesbetrieb für Wasserwirtschaft, Küsten- und Naturschutz	Germany	2021
	(https://www.nlwkn.niedersachsen.de)		
11	Staatliches Amt für Landwirtschaft und Umwelt Mittleres Mecklenburg (https://www.stalu-	Germany	2020
	mv.de/mm)		
12	Staatliches Amt für Landwirtschaft und Umwelt Vorpommern (https://www.stalu-mv.de/vp)	Germany	2021
13	Environmental Protection Agency, Ireland (https://www.epa.ie)	Ireland	2020
14	Hydstra, Department of Water and Sanitation, South Africa	South Africa	2021
15	Geological Survey of Sweden (https://www.sgu.se)	Sweden	2021
16	DINOloket, Geological Survey of the Netherlands (https://www.dinoloket.nl)	The	2020
		Netherlands	
17	California Department of Water Resources (https://wdl.water.ca.gov)	United States	2022
		of America	

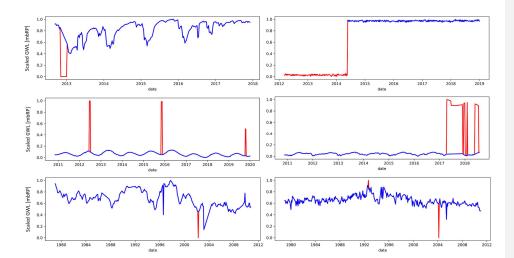


Figure A1 Examples of time series outlier removal with DBSCAN (scikit-learn library in Python): Raw (scaled) time series are shown in blue, and the anomalies identified by DBSCAN (Ester et al., 1996) are shown in red. The use of DBSCAN is less successful or difficult to verify in the bottom two examples (left: The first abrupt change in direction of the GWL between 1996 and 2000 is not identified as an outlier, although one would expect one based on the magnitude and position of the change; right: From visual inspection, it is unclear whether the identified outliers in both directions are due to measurement error, human activity or reflect natural behavior of the groundwater system e.g. to extreme events). In summary, like other tested outlier detection methods, DBSCAN does not allow us to detect all types of outliers and anomalies that we would expect should be removed to represent undisturbed GWL dynamics. With the parameters set, we can successfully detect most density-dependent outliers, but many values were incorrectly identified as outliers. Therefore, we performed a visual inspection of all time series where DBSCAN identified potential outliers.

680 Appendix B: Indices

Table B1 List of GWL dynamics typology and indices used in this study. Differing names in brackets refer to deviating abbreviations in Heudorfer et al. (2019).

aspect	component	indices names
distribution	boundness	fdc.slope_0.8_1 (dc.slp.u); fdc.slope_0_0.1 (dc.slp.l); l1; l3; median (med);
		peakts.avg
distribution	density	colwells.C (colwell.C); fdc.range_0.1_0.9 (dc.rng.01.09); fdc.range_0.2_0.8
		(dc.rng.02.08); fdc.range_0.25_0.75 (dc.rng.025.075); fdc.slope_0.3_0.7
		(dc.slp.m); 12; 14; meanann.max (avg.ann.max)

Kommentiert [AN52]: Explanation added because reviewer 1 asked for it.

distribution	modality	bimodality (bimod); dip; silverman (bandwd)
shape	scale	peakbasetime.avg (peakbase.avg); pulse.dur.high (pulse.dur.h); pulse.dur.low
		(pulse.dur.l); sqr.avg
shape	slope	fall.avg; fall.cv; reces.const; recov.const; rise.avg; rise.cv
structure	amplitude	amp.max
structure	flashiness	baker2 (baker); BFI; Lyapunov; pathlength2; reversals.avg (rev.avg);
		reversals.cv (rev.cv)
structure	interannual variation	autocorrelation (autocor); BFS; Hurst; intannfluc.y (iaf.y); pulse.count.high
		(pulse.count.h); pulse.count.low (pulse.count.l)
structure	seasonality-magnitude	cvmon.min; intannfluc.s (iaf.s); parde.seasonality (parde)
structure	seasonality-timing	colwells.M; varjulday.max (newly introduced instead of varjuld.min: CV of
		date of annual maximum head)

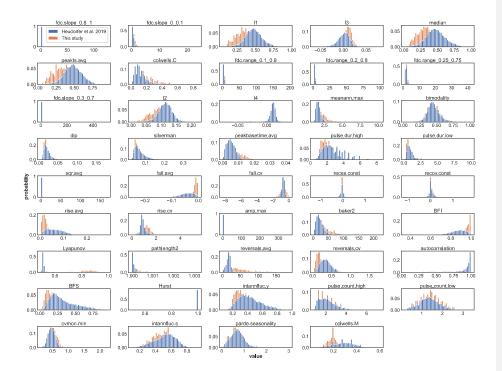
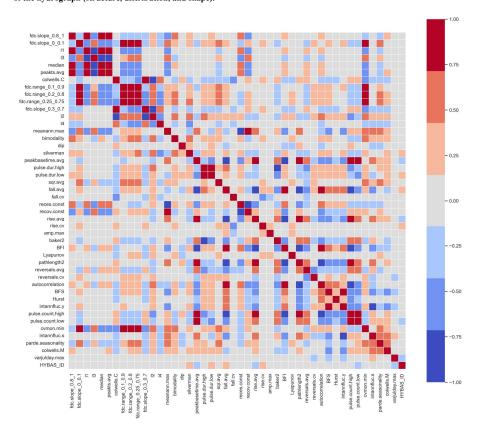


Figure B1 Comparison of the value distributions of the indices calculated in this study (Table B1) with the values published by Heudorfer et al. (2019) (data set: Haaf and Heudorfer, 2018). The magnitude and variability of values for many indices are similar. Shifted or significantly different ranges of values are observed for some indices. Such differences exist for indices of different aspects of the hydrograph (structure, distribution, and shape).



690 Figure B2 Correlation matrix of the index values calculated in this study.

Appendix C: Clustering

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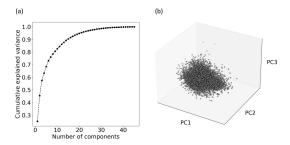


Figure C1 Principal Component <u>component Analysis analysis (PCA)</u> with the indices dataset. (a) Cumulative explained variance with an increasing number of Principal Components (PCs). (b) Dataset value space of the first three PCs (which together explain more than 50% of the variance of the dataset).

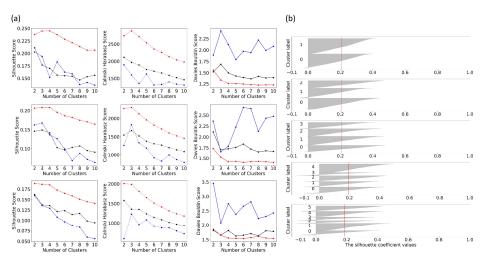


Figure C2 Evaluation metrics – Silhouette (Rousseeuw, 1987), Calinski-Harabasz (Caliński and Harabasz, 1974) and Davies-Bouldin (Davies and Bouldin, 1979) – used to find the best cluster separation. The Silhouette score ranges from -1 to 1, where a higher value indicates better-defined clusters. Better clustering results are also indicated by higher values for the Calinski-Harabasz score and lower values for the Davies-Bouldin score. (a) Metrics are shown for different proportions of explained variance represented by Principal Components (PCs) (top to bottom hinerow: 60.%, 70.%, and 80.%) and for different clustering algorithms (k-means (red), Gaussian mixture (blue) and hierarchical clustering (black)). (b) Silhouette scores for various clusters using the k-means algorithm and PCs representing 70.% of explained variance.

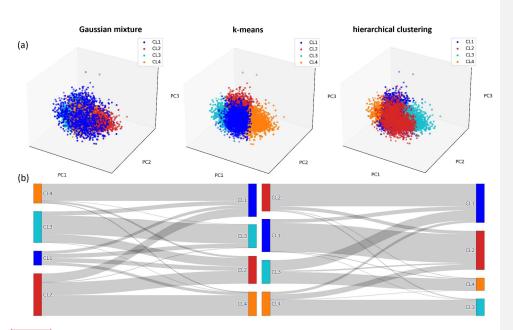


Figure C3 Assignment of the time series to four different clusters by three algorithms (Gaussian mixture, k-means, and hierarchical clustering). (a) Illustrative cluster assignment within the range of values of the first three principal components (PCs) of the dataset. (b) Sankey plot allows comparison of the quantitative distribution of the samples among the clusters (left between Gaussian mixture and k-means and right between k-means and hierarchical clustering). The majority of samples are assigned to the same cluster for k-means and hierarchical clustering (shown in different order).

Kommentiert [AN53]: Color scheme improved.

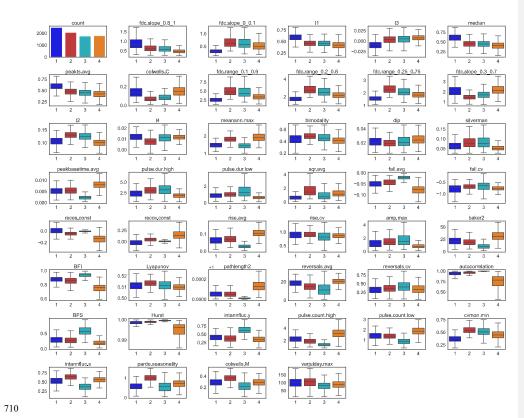


Figure C4 Within-cluster variability of all indices used for clustering.

Kommentiert [AN54]: Color scheme improved.



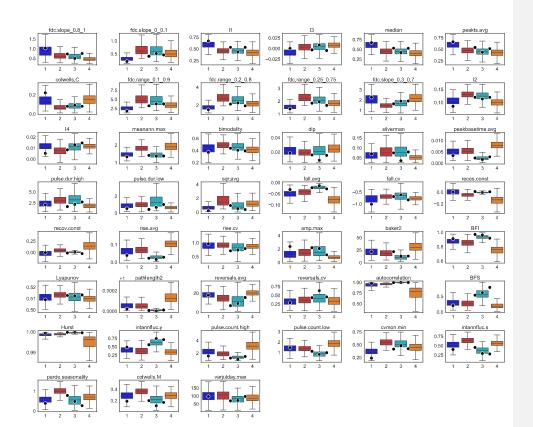


Figure C5 Within-cluster variability of all indices used for clustering (Fig. C4) plotted with indices values (dots) of the four example wells from the case study region in northern Germany (Fig. 5a). The points drawn between CL2 and CL3 and between CL4 and CL3 are wells with the highest probability for CL2 and CL4 in the Random Forest model but belong to CL3 according to the indicesclustering.

Kommentiert [AN55]: Color scheme improved.

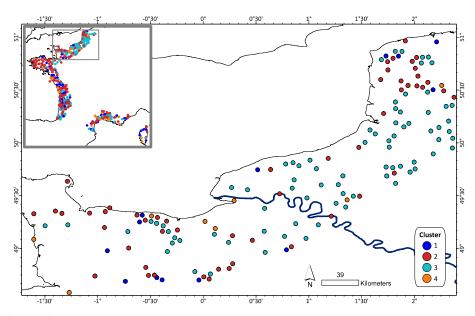


Figure C6 Assignment of clusters to well locations in the Normandy, Paris Basin displayed with the Seine riverRiver. Overlapping well markers were jittered at a minimum spacing of 500-1000 meters and thus no longer represent the original well locations. The window in the upper left corner shows the Normandy region in the north of France.

Kommentiert [AN56]: Figure improved for color vision deficiencies. Additionally improved visual positioning of the region.

Kommentiert [AN57]: Reviewer 1 noted that some wells were located in the ocean, so we increased the spacing for jittering.

Appendix D: Random Forest classification

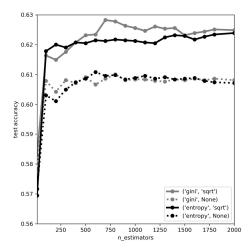


Figure D1 Random Forest hyperparameter tuning within a 5five-fold cross-validation framework using the training data.

Kommentiert [AN58]: Color scheme improved.

Appendix E: SHAP

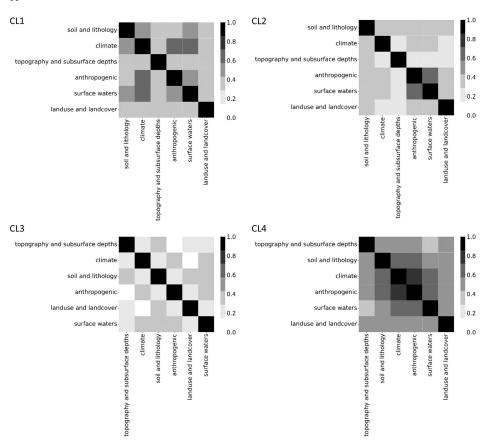


Figure E1 Absolute spearman Spearman correlation of SHAP values for aggregated features (SHAP values added up for features from the same attribute categories from Table 1).

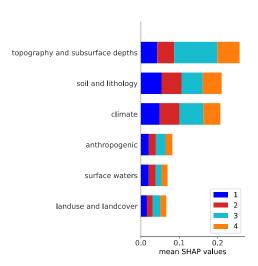


Figure E2 Overall SHAP feature importance stacked for individual clusters for aggregated features (SHAP values added up for features from the same attribute categories from Table 1).

Kommentiert [AN59]: Color scheme improved.

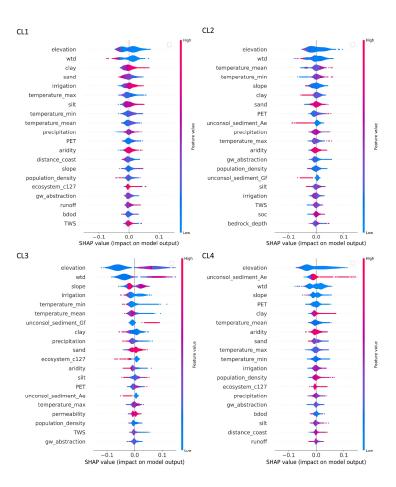


Figure E3 Violin plots show the distribution of SHAP feature importance and feature effect for the twenty highest-ranked features of each cluster. SHAP values describe the impact of a given feature on the prediction of the model for a given cluster (the prediction of "True" for the selected cluster). A red color corresponds to high feature values and a blue color corresponds to low feature values (i.e., for one-hot-encoded features, a value of 0 (blue) corresponds to the presence of the feature class and a value of 1 (red) corresponds to the absence of the feature class). Overlapping instances widen the violin shape in the direction of the y-axis and the violin at that position is colored according to the average feature value. SHAP values were not aggregated for this figure.

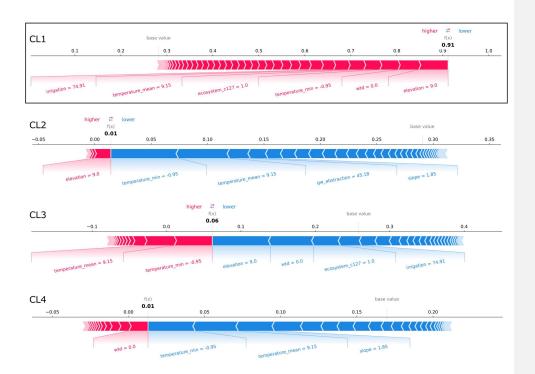


Figure E4 SHAP force plots explaining the correct prediction of the CL1 exemplary well site from the case study region in northern Germany (Fig. 5a), (from top to bottom: CL1, CL2, CL3, and CL4). At this well site, the probability that CL1 is predicted is the largest in the case study (test dataset). The average scores of all classifications made by the Random Forest model for the training dataset are 0.28, 0.29, 0.26, and 0.17 respectively (base values). The model's probability scores for predicting the clusters at the exemplary well site (bold printed numbers) sum up to 100%. Features that are important for the respective predictions are displayed with their values. Their importance and effect can be assessed by the SHAP values visualized by bar length and color (i.e. the larger the feature's share of the bar the more important; red represents rejecting effect and blue represents supporting effect).

Kommentiert [AN60]: We removed few unneccessary or - without additional information provided in the text - misleading words/sentences from some of the Figure captions as the reviewers have noted that these are sometimes too long.

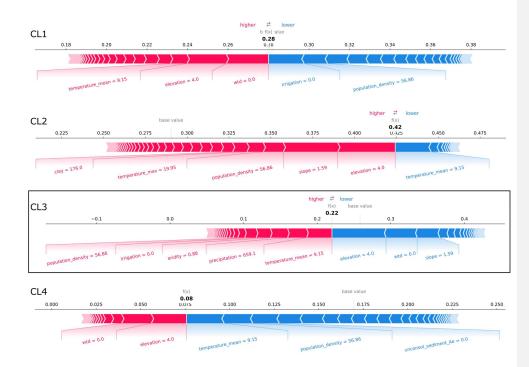


Figure E5 SHAP force plots explaining the prediction of the CL3 exemplary well site from the case study region in northern Germany (Fig. 5a) (from top to bottom: CL1, CL2, CL3, and CL4) that is confused with CL2. At this well site, the probability that CL2 is predicted is the largest in the case study (test dataset). The average scores of all classifications made by the Random Forest model for the training dataset are 0.28, 0.29, 0.26, and 0.17 respectively (base values). The model's probability scores for predicting the clusters at the exemplary well site (bold printed numbers) sum up to 100_{-} %. Features that are important for the respective predictions are displayed with their values. Their importance and effect can be assessed by the SHAP values visualized by bar length and color (i.e. the larger the feature's share of the bar the more important; red represents rejecting effect and blue represents supporting effect).

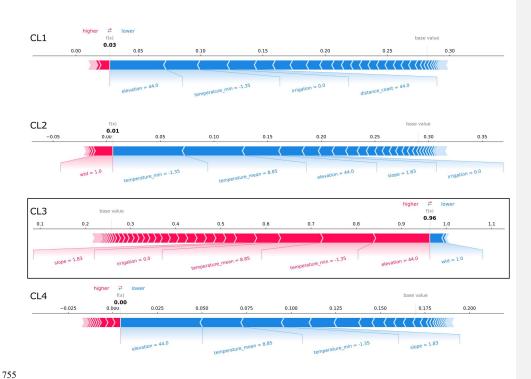


Figure E6 SHAP force plots explaining the correct prediction of the CL3 exemplary well site from the case study region in northern Germany (Fig. 5a) (from top to bottom: CL1, CL2, CL3, and CL4). At this well site, the probability that CL3 is predicted is the largest in the case study (test dataset). The average scores of all classifications made by the Random Forest model for the training dataset are 0.28, 0.29, 0.26, and 0.17 respectively (base values). The model's probability scores for predicting the clusters at the exemplary well site (bold printed numbers) sum up to 100 %. Features that are important for the respective predictions are displayed with their values. Their importance and effects can be assessed by the SHAP values visualized by bar length and color (i.e. the larger the feature's share of the bar the more important; red represents rejecting effect and blue represents supporting effect).

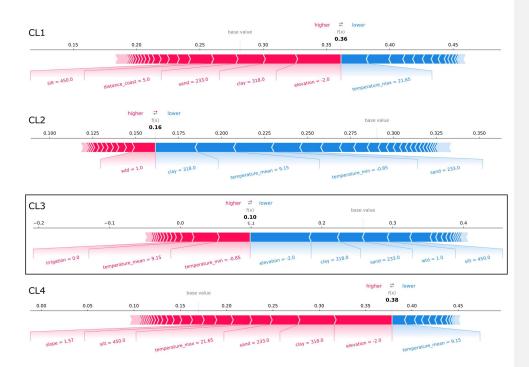


Figure E7 SHAP force plots explaining the prediction of the CL3 exemplary well site from the case study region in northern Germany (Fig. 5a) (from top to bottom: CL1, CL2, CL3, and CL4) that is confused with CL4. At this well site, the probability that CL4 is predicted is the largest in the case study (test dataset). The average scores of all classifications made by the Random Forest model for the training dataset are 0.28, 0.29, 0.26, and 0.17 respectively (base values). The model's probability scores for predicting the clusters at the exemplary well site (bold printed numbers) sum up to 100_%. Features that are important for the respective predictions are displayed with their values. Their importance and effects can be assessed by the SHAP values visualized by bar length and color (i.e. the larger the feature's share of the bar the more important; red represents rejecting effect and blue represents supporting effect).

Code and data availability

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We provide data to reproduce the results of this study (indices, attributes, clusters from k-means) at Zenodo (https://doi.org/10.5281/zenodo.8173404). Some of the data use agreements do not allow us to publish the original GWL time series and well locations. However, the groundwater data are available for free either via the web services or via request from governmental agencies listed in Table A1 (further information provided in the Supplement). Map data with information on

attributes are available through the references listed in Table 1. The R code to-for calculatinge index values is available upon request from EH and BH. The Python code used for modelling and plotting is available upon can be requested from AN. All The Python packages used in this research study (pandas, numpy, geopandas, sklearn, matplotlib, plotly, seaborn, scipy, shap) are freely available online.

Author contribution

AN collected and pre-processed the groundwater and attribute data, conceptualized the study, wrote the code, validated and visualized the results, and wrote the original paper draft. EH and BH contributed to the conceptualization. SB and JH supervised the work. All authors performed review and editing tasks.

85 Competing interests

The authors declare that they have no conflict of interest.

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