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Evaluation of water flux predictive models developed using eddy

2 covariance observations and machine learning: a meta-analysis

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17 Abstract.

18 With the rapid accumulation of water flux observations from global eddy-covariance flux sites, many studies 19 have used data-driven approaches to model site-scale water fluxes with various predictors and machine learning 20 algorithms used. However, systematic evaluation of such models is still limited. We therefore performed a meta-21 analysis of 32 such studies, derived 139 model records, and evaluated the impact of various features on model 22 accuracy throughout the modeling flow. SVM (average R-squared = 0.82) and RF (average R-squared = 0.81) 23 outperformed over evaluated algorithms with sufficient sample size in both cross-study and intra-study (with the 24 same training datasetdata) comparisons. The average accuracy of the model applied to arid regions is higher 25 than in other climate classestypes. The average accuracy of the model was slightly lower for forest sites 26 (average R-squared = 0.76) than for eroplands and grassland sites grasslands (average R-squared = 0.8and 0.79), but higher than for shrubshrubland sites (average R-squared = 0.67). Among various predictor 27 28 variables, the use of net/sun radiationUsing Rn/Rs, precipitation, air temperatureTa, and the fraction of absorbed 29 photosynthetically active radiation FAPAR improved the model accuracy. Among the different validation 30 methods, random The combined use of Ta and Rn/Rs is very effective especially in forests, while in grasslands 31 the combination of Ws and Rn/Rs is also effective. Random cross-validation showsshowed higher model 32 accuracy than spatial cross-validation and temporal cross-validation, but spatial cross-validation is more 33 important for the application for water flux predictive models when used for in spatial extrapolation. The 34 findings of this study are promising to guide future research on such machine learning-based modeling.

35 1 Introduction

36 Evapotranspiration (ET) is one of the most important indicator components of the water cycle in terrestrial 37 ecosystems. It also represents the key variable in linking ecosystem functioning, carbon and climate feedbacks, 38 agricultural management, and water resources (Fisher et al., 2017). The quantification of ET for regional, 39 continents, or the globe can improve our understanding of the water, heat, and carbon interactions, which is 40 important for global change research (Xu et al., 2018). Information on ET has been used in many fields, 41 including, but not limited to, droughts and heatwaves (Miralles et al., 2014), regional water balance closures 42 (Chen et al., 2014; Sahoo et al., 2011), agricultural management (Allen et al., 2011), water resources 43 management (Anderson et al., 2012), biodiversity patterns (Gaston, 2000). In addition, accurate large-scale and 44 long-time series ET prediction at high spatial and temporal resolution has been of great interest (Fisher et al., 45 2017). 46

47 Currently, there are three main approaches for simulation and spatial and temporal prediction of ET: (i) physical 48 models based on remote sensing such as surface energy balance models (Minacapilli et al., 2009; Wagle et al., 49 2017), Penman-Monteith equation (Mu et al., 2011; Zhang et al., 2010), Priestley-Taylor equation (Miralles et 50 al., 2011); (ii) process-based land surface models, biogeochemical models and hydrological models (Barman et 51 al., 2014; Pan et al., 2015; Sándor et al., 2016; Chen et al., 2019); and (iii) the observation-based machine 52 learning modeling approach with in situ eddy covariance (EC) observations of water flux (Jung et al., 2011; Li 53 et al., 2018; Van Wijk and Bouten, 1999; Xie et al., 2021; Xu et al., 2018; Yang et al., 2006; Zhang et al., 2021). 54 For remote sensing based physical models and process based land surface models, some physical processes

55 have not been well characterized due to the lack of understanding of the detailed mechanisms influencing ET 56 under different environmental conditions. (Jung et al., 2011; Li et al., 2018; Van Wijk and Bouten, 1999; Xie et 57 al., 2021; Xu et al., 2018; Yang et al., 2006; Zhang et al., 2021). For remote sensing-based physical models and 58 process-based land surface models, some physical processes have not been well characterized due to the lack of 59 understanding of the detailed mechanisms influencing ET under different environmental conditions. For 60 example, the inaccurate representation and estimation of stomatal conductance (Li et al., 2019) and the 61 linearization (McColl, 2020) of the Clausius-Clapeyron relation in the Penman-Monteith equation may 62 introduce both empirical and conceptual errors into estimates of ET. Limited by complicated assumptions and 63 model parametrizations, these process-based models face challenges in the accuracy of their ET estimations over 64 heterogeneous landscapes (Pan et al., 2020; Zhang et al., 2021). Therefore, many researchers have used data-65 driven approaches for the simulation and prediction of ET with the accumulation of a large volume of measured 66 site-scale observational data of water fluxes in the past decades. Various machine learning models have been 67 developed to simulate water fluxes at the flux site scale. Besides, various predictor variables (e.g., 68 meteorological factors, vegetation conditions, and moisture supply conditions) have been incorporated into such 69 models for upscaling (Fang et al., 2020; Jung et al., 2009) of water flux to a larger scale or understanding the 70 driving mechanisms with the variable importance analysis performed in such models. 71 72 However, to date, the systematic assessment of the uncertainty in the processes of water flux prediction models 73 constructed using the machine learning approach is limited. Although considerable effort has been invested in 74 improving the accuracy of such prediction models, our understanding of the expected accuracy of such models 75 under different conditions is still limited. It is still not easy for us to give the general guidelines for selecting 76 appropriate predictor variables and models. Ouestions such as 'Which predictor variables are the best in water 77 flux simulations?' and 'How to improve the prediction accuracy of water flux effectively?' etc. still confuse the 78 researchers in the field. Therefore, we should synthesize the findings from published-such studies to determine 79 which predictor variables, machine learning models, and other features can significantly improve the prediction

accuracy of water flux. Also, we are interested in understanding under which specific conditions they are more
effective.

A variety of features <u>may affectcontrol</u> the accuracy of such models, including the predictor variables used, the
 inherent heterogeneity within the dataset, the plant functional type (PFT) of the flux sites, the method of model
 construction and validation, and the <u>machine learning</u> algorithm chosen:

86 a) Predictor variables used: Compared to process-based models, the data used may have a more significant 87 impact on the final model performance in data-driven models. Various biophysical covariates and other 88 environmental factors have been used for the simulation and prediction of water fluxes. The most 89 commonly used factors include mainly precipitation (Prec), air temperature (Ta), wind speed (Ws), net/sun 90 radiation (Rn/Rs), soil temperature (Ts), soil texture, vapor-pressure deficit (VPD), the fraction of absorbed 91 photosynthetically active radiation (FAPAR), vegetation index (e.g., Normalized Difference Vegetation 92 Index (NDVI,-), Enhanced Vegetation Index (EVI),-)), Leaf area index (LAI,), and carbon fluxes (e.g., 93 Gross Primary Productivity (GPP)-)). These used predictor variables and their complex interactions drive

94 the fluctuations and variability of water fluxes. They affect the accuracy of water flux simulations in two

95 ways: their actual impact on water fluxes at the process-based level and their spatio-temporal resolution and 96 inherent accuracy. The relationship between water fluxes and these variables at the process-based driving mechanism level is very different under different PFTs, different climate types, and different 97 98 hydrometeorological conditions. For example, in irrigated croplands in arid regions, water fluxes may be 99 highly correlated with irrigation practices, and thus soil moisture may be a very important predictor 100 variable, and its importance may be significantly higher than in other PFTs. And in models that incorporate 101 data from multiple PFTs, some variables that play important roles in multiple PFTs may have higher 102 importance. In terms of data spatial and temporal resolution, the data for these predictor variables may have 103 different scales. In terms of spatial resolution, meteorological observations such as precipitation and air 104 temperature are at the flux site scale, while factors extracted from satellite remote sensing and reanalysis 105 climate datasets cover a much larger spatial scale (i.e. the grid-scale). This leads to considerable differences in the degree of spatial match between different variables and the site scale EC observations (approximately 106 107 100 m x 100 m). It is therefore difficult for some variables to be fairly compared in the subsequent 108 importance analysis of driving factors. In terms of temporal resolution, the importance of predictor 109 variables with different temporal resolutions may be variable for models with different time scales (e.g., 110 half-hourly, daily, and monthly models). For example, the daily or 8-day NDVI data based on MODIS 111 satellite imagery may better capture the temporal dynamics of water fluxes concerning vegetation growth 112 than the 16-daily NDVI data derived from Landsat images. Besides, data on non-temporal dynamic 113 variables such as soil texture cannot explain temporal variability in water fluxes in the data-driven 114 simulations, although soil texture may be important in the interpretation of the actual driving mechanisms 115 of ET (which may need to be quantified in detail in ET simulations by process-based models). In addition, 116 some inherent accuracy issues (e.g., remote sensing-based NDVI may not be effective at high values) of the 117 predictors may propagate into the consequent machine learning models, thus affecting the modeling and our 118 understanding of its importance. Therefore, it is necessary to consider the spatial and temporal resolution of 119 the data and their inherent accuracy for the predictors used in different studies in the systematic evaluation 120 of data-driven water flux simulations. 121 b) The volume of the dataset, inherent heterogeneity of the dataset, and how the model is validated validation: 122 the volume and inherent spatiotemporal heterogeneity of the training dataset (with more variability and 123 extremes incorporated) may affect model accuracy. Typically, training data with larger regions, multiple 124 sites, multiple PFTs, and longer year spans may have a higher degree of imbalance (Kaur et al., 2019; Van 125 Hulse et al., 2007; Virkkala et al., 2021; Zeng et al., 2020)(Kaur et al., 2019; Van Hulse et al., 2007; 126 Virkkala et al., 2021; Zeng et al., 2020). And in machine learning, in general, modeling with unbalanced 127 data (with significant differences in the distribution between the training and validation sets) may result in 128 lower model accuracy. Currently, the most common ways of model validation include spatial, temporal, and 129 random cross-validation. Spatial validation is mainly to evaluate the ability of the model to be applied in 130 different regions or flux sites with different PFT types, and one of the common methods is 'leave one site 131 out' (Fang et al., 2020; Papale et al., 2015; Zhang et al., 2021). If the data of the site left out for validation 132 differs significantly from the distribution of the training data set, the expected accuracy of the model 133 applied at that site may be low because the trained model may not capture the specific and local 134

relationships between the water flux and the various predictor variables at that site. For temporal validation,

- 135 to assess the ability of the models to adapt to the interannual variability, typically some years of data are 136 used for training and the remaining years for model validation (Lu and Zhuang, 2010). If a year with 137 extreme climate is used for validation, the accuracy may be low because the training dataset may not 138 contain such extreme climate conditions. In the case of PFTs that are significantly affected by human 139 activities, such as cropland, the possible different crops grown and different land use practices (e.g., 140 irrigation) across years can also lead to low accuracy in temporal validation. K fold cross validation is 141 commonly used in random cross-validation to assess the fitness of the model to the spatio temporal 142 variability. In this case, different values of K may also affect the model accuracy. For example, for an 143 unbalanced dataset, the average model accuracy obtained from a 10 fold (K = 10) validation approach is 144 likely to be higher than that of a 3 fold (K = 3) validation approach.
- c) Various machine learning algorithms: Some machine learning algorithms may have specific advantages
 when applied to model the relationships between water fluxes and covariates. For example, neural networks
 may have an advantage in nonlinear fitting, while random forests maycan avoid serious overfitting due to
 the introduction of randomnessproblems. However, which algorithm is better overall in different situations
 (i.e. applied to different data sets)? Which algorithm is generally more accurate than the others when using
 the same data set? A comprehensive evaluation of this is necessary-important.
- 151
- 152 Therefore, to systematically and comprehensively assess the impact of various features in such modeling, we
- 153 perform a meta-analysis of published water flux simulation studies that combine the flux site water flux
- 154 observations, various predictors, and machine learning. The accuracy of model records collected from the
- 155 literature was linked with various model features to assess the impacts of predictor data types, algorithms, and
- 156 other features on model accuracy. The findings of this study may be promising to improve our understanding of
- 157 the impact of various features of the models to guide future research on such machine learning-based modeling.

158 2 Methodology

159	2.1 Protocol for selecting the sample of articles
160	We applied a general query (on December 1st, 2021) on title, abstract, and keywords to include articles with the
161	"OR" operator applied among expressions (Table 1) in the Scopus database. Preferred Reporting Items for
162	Systematic Reviews and Meta-Analyses (PRISMA) (Moher et al., 2009) isare followed when filtering the
163	papers. We first excluded articles that obviously did not fit the topic of this study based on the abstract, and then
164	performed the article screening with the full-text reading.
165	
166	The inclusion of articles follows the following criteria:
167	<u>a)</u> Articles were filtered for those with water fluxes (or latent heat) simulated, with multi-variable.
168	b) The water flux or latent heat observations used in the prediction models should be from the eddy-
169	covariance flux measurements.
170	c) Articles focusing only on gap-filling (Hui et al., 2004) techniques (i.e., the objective was not simulation
171	and extrapolation of water fluxes using machine learning) were excluded.

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172	<u>d</u>)	Only articles that used multivariate regression used, (with the number of covariates greater than or equal to
173		3) were included.
174	<u>e)</u>	The determination coefficient (R-squared) of the validation step should be reported as the metric of model
175		performance (Shi et al., 2021; Tramontana et al., 2016; Zeng et al., 2020), and published in English
176		journals. (Shi et al., 2021; Tramontana et al., 2016; Zeng et al., 2020) in the articles.
177	<u>f)</u>	The articles should be published in English-language journals.
178		
179	Alth	hough RMSE is also often used for model accuracy assessment, its dependence on the magnitude of water
180	flux	values makes it difficult to use for fair comparisons between studies. For example, due to the difference in
181	the	range of ET values, models developed from flux stations in dry grasslands will typically have lower RMSE
182	<u>thar</u>	models developed by flux stations based on forests in humid regions. Therefore, RMSE may not be a good
183	met	ric for cross-study comparisons in this meta-analysis.
183	met	ric for cross-study comparisons in this meta-analysis.

Table 1. Article search: '[A1 OR A2 OR A3...] AND [B1 OR B2 <u>OR B3</u>...] AND [C1 OR C2 <u>OR C3 OR C4</u>...]'

ID	Α	В	С
1	Water flux	Eddy covariance	Machine learning
2	Evapotranspiration	Flux tower	Support Vector
3	Latent heat	Flux site	Neural Network
4			Random Forest

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187 **2.2 Features of the prediction processes evaluated**

188 The various features (Table 2) involved in the water flux modeling framework (Fig. 1) include the PFTs of the

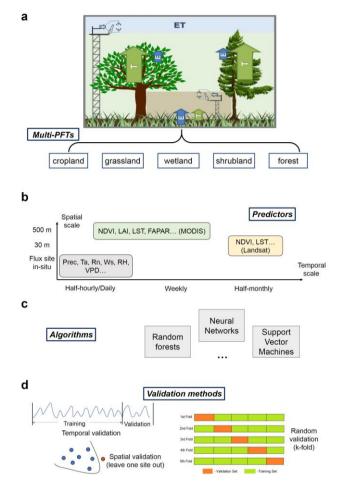
189 sites, the predictors used, the machine learning algorithms, the validation methods, and other features. Each

190 model for which R-squared is reported is treated as a data record. If multiple algorithms were applied to the

191 same dataset, then multiple records were extracted. Models using different data or features are also recorded as192 multiple records.

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194 Figure 1. Features of the machine learning-based water flux prediction process. (a) the eddy-covariance-based

195 water flux observations of various plant function types (PFTs), modified from Paul-Limoges et al., 2020. ET,

196 evapotranspiration. E, evaporation. T, transpiration. (b) Predictors and their spatial and temporal resolution. (c)

197 The machine learning algorithms used for the modeling, such as neural networks, random forests, etc. (d) The

198 model validation methods used including the spatial, temporal, and random cross-validations.

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Table 2. Description of information extracted from the included papers.

Field/ Feature	Definition <u>& Categories adopted</u>	Categories adopted Harmonization	-	带格式的:行距:单倍行距
Climate	Climate zonezones of the study location			带格式表格
Cimilate	derived from the Köppen climate			带格式的: 行距:单倍行距
	classification (Peel et al., 2007)			
Plant functional	PFT of the flux sites: 1-forest, 2-	1-forest, 2-grassland, 3-cropland, 4-	•	带格式的: 行距:单倍行距
type (PFT)	grassland, 3-cropland, 4-wetland, 5-	wetland, 5-shrubland, 6-savannah, and		
	shrubland, 6-savannah, and multi-PFTs	multi-PFTsThe categorization is based on		

Location	More precise location (with the latitude and longitude of the center of the studied sites)): latitude, longitude	the descriptions in the article. For example, cropland for various crops is classified as 'cropland', and both woody savannah and savannah are classified as 'savannah'. latitude, longitude	(带格式的: 行距: 单倍行距
Algorithms	Random Forests (RF), Multiple Linear Regressions (MLR), Artificial Neural Networks (ANN), Support Vector Machines (SVM), Cubist, model tree ensembles (MTE), K-nearest neighbors (KNN), long short-term memory (LSTM), gradient boosting regression tree (GBRT), extra tree regressor (ETR), Gaussian process regression (GPR), Bayesian model averaging (BMA), extreme learning machine (ELM), and deep belief network (DBN),Algorithm families used	Various model algorithms with parameter optimization or other improvements are categorized as their algorithm family. For example, various improved models of RF algorithms are classified as RF, rather than as another algorithm family. Random Forests (RF), Multiple Linear Regressions (MLR), Artificial Neural Networks (ANN), Support Vector Machines (SVM), Cubist, model tree ensembles (MTE), K- nearest neighbors (KNN), long short-term memory (LSTM), gradient boosting regression tree (GBRT), extra tree regressor (ETR), Gaussian process regression (GPR), Bayesian model averaging (BMA), extreme learning machine (ELM), and deep belief network	(带格式的: 行距:单倍行距)(带格式的:行距:单倍行距)
Sites number	Number of the flux sites used	(DBN) ←	带格式的: 行距:单倍行距
Spatial scale	Area representatively covered by the flux sites: local (less than 100 x 100 km), regional, global (continent-scale and global scale)	local (less than 100 x 100 km), regional, global (continent scale and global scale)The spatial scale is roughly categorized based on the area covered by the site. The model is classified as 'global' only when the spatial extent reaches the continental scale.	带格式的: 行距: 单倍行距
Temporal scale	The temporal scale of the model: <u>half-hourly</u> , hourly, daily, 4-daily, 8-daily, monthly, seasonally (i.e., 0.02, 0.04, 1, 4, 8, 30, 90 days)	half-hourly, hourly, daily, 4 daily, 8 daily, monthly, seasonally (i.e., 0.02, 0.04, 1, 4, 8, 30, 90 days)Models with a temporal scale greater than one month and less than one year are classified as seasonal scale models.	(带格式的: 行距:单倍行距
Year span	The span of years of the flux data used	Year span is calculated as the span from the earliest to the latest year of available flux data.	带格式的: 行距:单倍行距
Site year	Describe the volume of total flux data with the number of sites and years aggregated.	•	带格式的: 行距: 单倍行距
Cross-validation	Describe the chosen method of cross- validation: <u>Spatial (e.g., 'leave one site</u> <u>out'), temporal (e.g., 'leave one year</u> out'), random (e.g., 'k-fold')-	Spatial (e.g., 'leave one site out'), temporal (e.g., 'leave one year out'), random (e.g., 'k-fold')	(带格式的: 行距: 单倍行距
Training/validation	Describe the ratio of the data volume in the training and validation sets.	In spatial validation, this ratio is represented by the ratio of the number of sites used for training to the number of sites used for validation. In temporal validation, this is represented by the ratio of the span of time periods used for	带格式的: 行距:单倍行距

		training to the span of time periods used for validation.				
Satellite images	Describe the source of satellite images used to derive NDVI, EVI, LAI, LST, etc: Landsat, MODIS, AVHRR	Landsat, MODIS, AVHRR		带格式的:	行距: 单倍谷	亍距
Biophysical predictors	LAI, NDVI/EVI, enhanced vegetation index (EVI), the fraction of absorbed photosynthetically active radiation/photosynthetically active radiation (FAPAR/PAR), leaf area index (LAI), Carbon fluxes (CF) including NEE/GPP, etc.	Used (recorded as '1') or not used (recorded as '0')The predictor variables of different measurement methods are categorized according to their definitions. For example, both using the NDVI calculated based on satellite remote sensing bands and in situ measurements were classified as the use of 'NDVI'.	=	带格式的:	行距: 单倍行	亍距
Meteorological variables	precipitation (Prec), net radiation/solar radiation (Rn/Rs), air temperature (Ta), vapour-pressure deficit (VPD), relative humidity (RH), etc.	Used (recorded as '1') or not used (recorded as '0')The way meteorological data are measured is not differentiated. For example, both using Ta from reanalysis data and Ta measured at flux sites were classified as the use of Ta.	-	带格式的:	行距: 单倍行	亍距
Ancillary data	Describe the ancillary variables used: soil texture, terrain (DEM), soil moisture/land surface water index (SM/LSWI), etc.	Used (recorded as '1') or not used (recorded as '0')Both the use of in situ measured soil moisture and the use of remote sensing-based LSWI was classified as using surface moisture- related indicators SM/LSWI.		一 带格式的:	行距: 单倍行	〕距
Top three variables	Describe the interpretation of the		1			
in the ranking of	importance of variables reported in the					
importance of predictors	machine learning models.					
Accuracy measure	Accuracy measure used to assess the model performance: <u>R-squared (in the validation phase)</u>	R-squared (in the validation phase)		带格式的: 带格式表格	行距:单倍谷	行距

202 3 Results

203 **3.1 Articles included in the meta-analysis**

A total of 32 articles (see <u>Supplement InformationTable S1</u>) containing a total of 139 model records were

included. The geographical scope of these articles was mainly Europe, North America, and China (Fig. 2).

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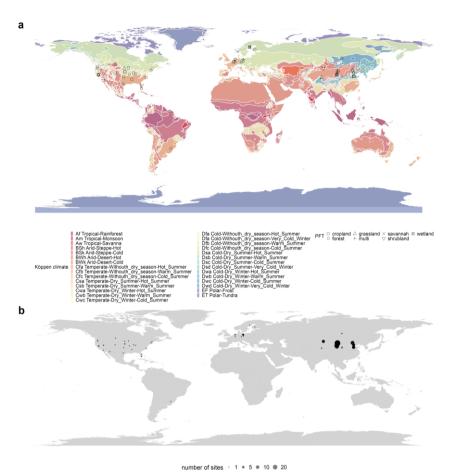


Figure 2. Location of the included studies in the meta-analysis. (a) PFTs and the climate zones (from Köppen
climate classification) of these studies and (b) the number of flux sites included in each study. Global and
continental-scale studies (e.g., models developed based on FLUXNET of the global scale) are not shown on the
map due to the difficulty of identifying specific locations.

211 **3.2 The formal Meta-analysis**

212	We formally assessed the impact of the features (e.g., algorithms, study area, PFTs, the volume of data used,
213	validation methods, predictor variables, etc.) used in the different models based on differences of R-squared.
214	

215 <u>3.2.1 Algorithms</u>

206

216	SVM and RF outperformed (Fig. 3a) across studies (lightly better than other algorithms with sufficient sample
217	size in Fig. 3a such as ANN). These three machine learning algorithms (i.e., ANN, SVM, RF) were significantly
218	more accurate than the traditional MLR. Other algorithms such as MTE, ELM, Cubist, etc. also correspond to

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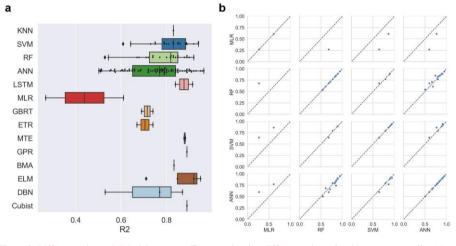
high accuracy, but with limited evidence sample size, (Fig. 3a). In the internal comparison (different algorithms

applied to the same data set) in single studies, we also find that SVM and RF were significantlyslightly more

accurate than ANN (Fig. 3b), and all these three (i.e., ANN, SVM, RF) are significantlyconsiderably more

accurate than MLR. Overall, SVM and RF have shown higher accuracy in water flux simulations.-<u>in both inter</u>

223 and intra-study comparisons with sufficient sample size as evidence.



224

225 Figure 3. Differences in model Model accuracy (R-squared) using different various algorithms across studies (a) 226 and internal comparisons of the model accuracy (R squared) of selected pairs of algorithms within individual 227 studies (b). Regression algorithms Algorithms: Random Forests (RF), Multiple Linear Regressions (MLR), 228 Artificial Neural Networks (ANN), Support Vector Machines (SVM), Bayesian model averaging (BMA), 229 Cubist, model tree ensembles (MTE), K-nearest neighbors (KNN), long short term memory (LSTM), gradient 230 boosting regression tree (GBRT), extra tree regressor (ETR), K-nearest neighbors (KNN), long short-term 231 memory (LSTM), Gaussian process regression (GPR), Bayesian model averaging (BMA), extreme learning 232 machine (ELM), and deep belief network (DBN). 233

234 3.2.2 Climate types and PFTs

235 We found higher average model accuracy in arid climate zones (Fig. 4a), such as the Cold semi-arid (steppe) 236 climate (BSk) and Cold desert climate (BWk-). Most of these studies were located in northwest China and the 237 western USA. It may be caused by the simpler relationship between water fluxes and biophysical covariates in 238 arid regions. In arid zones, due to the high potential ET, the variability in the actual ET may be largely explained 239 by water availability (moisture supply) and vegetation change with the effect of variability in thermal conditions 240 reduced. As for the various PFTs, the average model accuracy was slightly lower for forest types than for 241 cropland and grassland types (Fig. 4b) possibly because some remote sensing-based predictors such as FAPAR 242 and LAI have limited accuracy when applied to forest types (Fig. 5). The lowest average accuracy was found for 243 shrub sites, which may be related to the difficulty of remote sensing based NDVI, etc., to quantify the 244 physiological and ecological conditions of shrubs,4b). The lowest average accuracy was found for shrub sites,

245 which may be related to the difficulty of the remote sensing-based vegetation index (e.g., NDVI) to quantify the

246 <u>physiological and ecological conditions of shrubs (Zeng et al., 2022)</u>, and the heterogeneity of the spatial

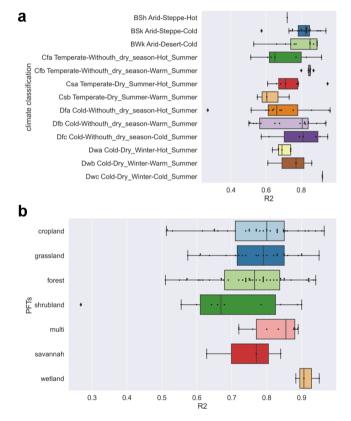
247 distribution of shrubs within the EC observation area may also cause difficulties in capturing their relationships

248 with biophysical variables. We also found high model accuracy for the wetland type, although records as

249 evidence to support this finding may be limited. Compared to other PFTs, the more steady and adequate water

250 availability in the wetland type may make the variations of water fluxes less explained by other biophysical

251 covariates.



252

253 Figure 4. Differences in model accuracy (R-squared) of (a) various climate zones (classified by Köppen climate

254 classification) across studies and (b) PFTs. BSh, Hot semi-arid (steppe) climate. BSk, Cold semi-arid (steppe)

255 climate. BWk, Cold desert climate. Cfa, Humid subtropical climate. Cfb, Temperate oceanic climate. Csa, Hot-

256 summer Mediterranean climate. Csb, Warm-summer Mediterranean climate. Dfa, Hot-summer humid

257 continental climate. Dfb, Warm-summer humid continental climate. Dfc, Subarctic climate. Dwa, Monsoon-

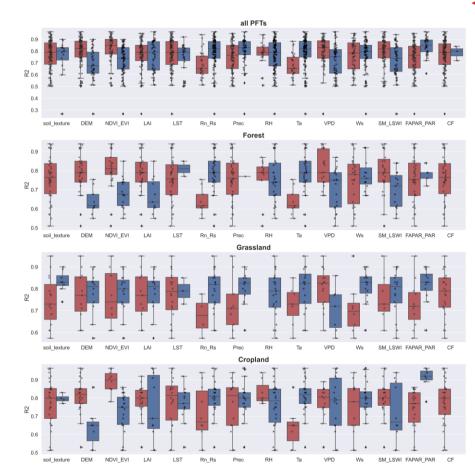
258 influenced hot-summer humid continental climate. Dwb, Monsoon-influenced warm-summer humid continental

259 climate. Dwc, Monsoon-influenced subarctic climate.

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261 Among 3.3.3 Predictors and their combinations

262 <u>On one hand, for</u> the <u>variouseffects of individual</u> predictors, the use of Rn/Rs, Prec, Ta, and FAPAR 263 <u>significantly</u>-improved the accuracy of the model (Fig. <u>5S1</u>). This pattern partially changed in the different 264 PFTs. In the forest sites, the accuracy of the models with Rn/Rs and Ta used was <u>significantly</u>-higher than that 265 of the models with Rn/Rs and Ta not used. For the grassland sites, the use of Ws, FAPAR, Prec, and Rn/Rs 266 <u>significantly</u>-improved the model accuracy. For the cropland sites, Ta and FAPAR were more important for 267 improving the model accuracy.



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Figure 5. The impact of the various predictors used in models of different PFTs (all data, forest, grassland, and
cropland) on R-squared. Dark blue boxes indicate that the predictor was used in the model, while dark red boxes
indicate that the predictor was not used. Predictors: precipitation (Prec), soil moisture/land surface water index
(SM_LSWI), net radiation/solar radiation (Rn_Rs), enhanced vegetation index (EVI), air temperature (Ta),
vapor-pressure deficit (VPD), the fraction of absorbed photosynthetically active radiation/photosynthetically

active radiation (FAPAR_PAR), relative humidity (RH), carbon flux (CF), leaf area index (LAI).

274 275 276 277 On the other hand, the evaluation of the effect of individual predictors on model accuracy is not necessarily 278 reliable because some predictor variables are used together (e.g., the high model accuracy corresponding to a 279 particular variable may be because it is often used together with another variable that plays the dominant role in 280 improving accuracy). Therefore, we tested for independence between the use of variables and assessed the effect 281 of the combination of variables on model accuracy. We calculated the correlation matrix (Fig. S2) between the 282 use of various predictors (not used is set as 0 and used is set as 1). We found there was a dependence between 283 the use of some predictors, the use of NDVI/EVI, LAI, and SM was significantly negatively correlated with the 284 use of Rn/Rs and Ta (Fig. S2). It indicated that many of the models that used Rn/Rs and Ta did not use 285 NDVI/EVI, LAI, and SM, and the models that used NDVI/EVI, LAI, and SM also happened to not use Rn/Rs 286 and Ta. Given this dependence, we evaluated the effect of the combination of variables on the model accuracy 287 (Fig. 5). In Fig. 5, the three variable combinations on the left side are mainly meteorological variables while the 288 three variable combinations on the right side are mainly vegetation-related variables based on remote sensing 289 (e.g., NDVI, EVI, LAI, LSWI). We found that, overall, the accuracy of the models using only meteorological 290 variable combinations was higher than that of the models using only remote sensing-based vegetation-related 291 variables. It demonstrated the importance of using meteorological variables in machine learning-based ET 292 prediction (probably especially for models with small time scales such as hourly scale, and daily scale). For 293 example, in the forest type, the combination of Ta and Rn/Rs is very effective compared to using only remote 294 sensing-based vegetation index variable combinations. The combination of Ta and Rn/Rs is also effective in the 295 grassland and cropland types. The combination of Ws and Rn/Rs played an important role in the grassland type 296 for improving model accuracy. Despite this, it does not negate the positive role of remote sensing-based 297 vegetation-related variables in ET prediction. This effectiveness can be dependent on the time scale of the model 298 as well as the PFTs. In models with large time scales (monthly scale, seasonal scale) and PFTs in which ET is 299 sensitive to vegetation dynamics, remote sensing-based vegetation-related variables may also be of high 300 importance. 301

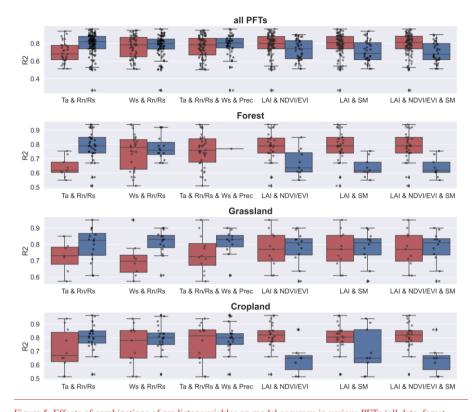
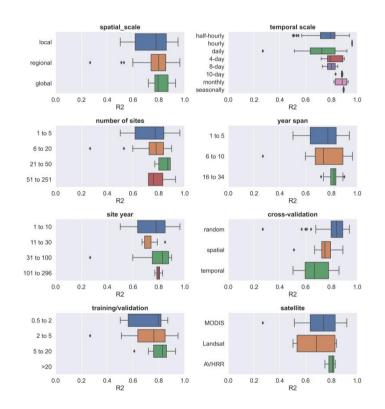


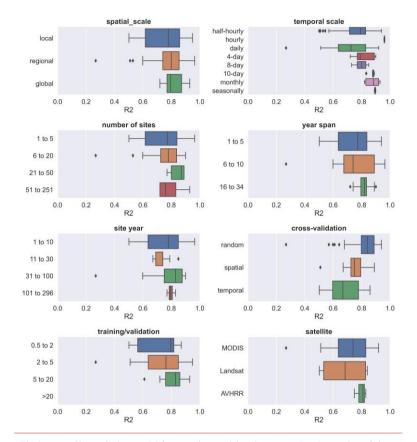
Figure 5. Effects of combinations of predictor variables on model accuracy in various PFTs (all data, forest,
grassland, and cropland). Dark blue boxes indicate that the predictors were together used in the model (e.g., for
'Ta & Rn/Rs', the dark blue box represents Ta and Rn/Rs were together used in the model), while dark red
boxes indicate the other conditions (i.e., the combination was not used). Predictors: precipitation (Prec), soil
moisture/remote sensing-based land surface water index (SM), net radiation/solar radiation (Rn/Rs), enhanced
vegetation index (EVI), air temperature (Ta), leaf area index (LAI), Normalized Difference Vegetation
Index/Enhanced Vegetation Index (NDVI/EVI).

310 3.3.4 Other model features

311 We also evaluated the impact of some other features on accuracy. The differences in accuracy of models with 312 different spatial scales, year spans, number of sites, and volume of data (Fig. 6) appear to be insignificant. This 313 seems to be related to the fact that in large-_scale water flux simulations, the sites of similar PFTs are selected 314 such as for modeling multiple forest sites across Europe (Van Wijk and Bouten, 1999) which focus on 'forest' 315 and multiple grassland sites across arid northern China (Xie et al., 2021; Zhang et al., 2021) which focus on 316 'grassland', rather than mixing different PFT types to train models as the way in machine learning modeling of 317 carbon fluxes (Zeng et al., 2020)(Zeng et al., 2020). In terms of the time scales of the models, the 4-day, 8-day, 318 and monthly scales appear to correspond to higher accuracy compared to the half-hourly and daily scales. Also, 319 the variability of the accuracy of the half hourly and daily scale models is higher. The higher the ratio of the 320 volume of data in the training and validation sets, the higher the model accuracy. Compared to the models using 321 Landsat data, the models using MODIS data showed slightly higher accuracy probably due to the advantage of 322 MODIS data in capturing the temporal dynamics of biophysical covariates. There were significant differences in 323 the accuracy of the models using different cross-validation methods, with the models using random cross-324 validation showing higher accuracy than those using temporal cross-validation. This suggests that interannual 325 variability may have a high impact on the models in water flux simulations. The driving mechanism of ET may 326 vary significantly across years, and the inclusion of some extreme climatic conditions in the training set may be 327 important for model accuracy and robustness. 328



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Figure 6. The <u>impacts effects</u> of other <u>model</u> features (i.e. spatial scale, <u>temporal scale</u>, number of sites, <u>temporal</u> scale, year span, site year, <u>eross</u>-validation method, training/validation<u>ratio</u>, and satellite imagery<u>used</u>) on the

333 model performance. <u>R-squared.</u>

334 <u>3.3.5 Linear correlation of quantitative features and R-squared</u>

335 We also analyzed the linear correlation (Fig. 7) between multiple quantitative features and the R-squared. We

- 336 <u>found that the magnitude of the linear correlation coefficients between the use of predictor combinations and the</u>
- 337 <u>R-squared was higher than other features. The use of the predictor combination 'Ta and Rn/Rs' significantly</u>
- 338 improved the model accuracy. 'Temporal scale', 'time span', 'training/validation ratio', and 'number of sites'
- 339 <u>showed weak positive correlations with R-squared (not significant, p-value > 0.1). The positive correlation</u>
- 340 <u>between 'temporal scale' and R-squared is higher among these features, although not significant. It should also</u>
- 341 <u>be paid more attention to in future studies. The feature 'training/validation ratio' and 'time span' are also</u>
- 342 positively correlated (although not significantly) with the R-squared, suggesting the importance of the volume of
- 343 data in the training set in a data-driven machine learning model. Larger 'training/validation ratio' and 'time span'
- 344 <u>may correspond to greater proportional coverage of the scenarios/conditions in the training set over the</u>
- 345 <u>validation set, and thus correspond to higher accuracy.</u>

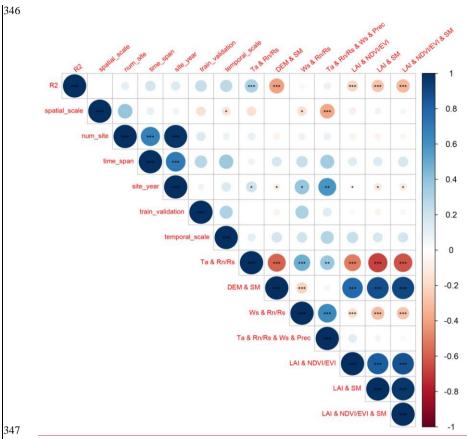


Figure 7. Evaluation of linear correlations between multiple features and the R-squared records with the
 statistical significance test. For the feature 'spatial scale', the 'local' scale was set to 1, the 'regional' scale'

statistical significance test. For the feature 'spatial scale', the 'local' scale was set to 1, the 'regional' scale was
set to 2, and the 'global' scale was set to 3 in the analysis of linear correlation. For the use of various predictor
combinations with '&', the value for 'together used' is set as 1 and other conditions are set as 0 (e.g., for the
feature 'Ta & Rn/Rs & Ws & Prec', if Ta, Rn/Rs, Ws, and Prec were used together in the model, the value is set

353 <u>as 1). Significance: the p-value < 0.01 (***), 0.05 (**), and 0.1 (*).</u>

354 4 Discussions

With the accumulation of in situ EC observations around the world, compared to remote sensing or process model-based approaches, the study of ET simulations based on data-driven approaches has received more attention from researchers in the last decade. Many studies have combined EC observations, various predictors, and machine learning algorithms to improve the prediction accuracy of site-scale water fluxes. To date, the results of these studies have not been comprehensively evaluated to provide clear guidance for feature selection in water flux prediction models. To better understand the approach and guide future research, we performed a 361 meta-analysis of such studies. Machine learning-based water flux simulations and predictions still suffer from 362 high uncertainty. By investigating the expected improvements that can be achieved by incorporating different 363 features, we can avoid practices that may reduce model accuracy in future research.

364 **4.1 Opportunities and challenges in the site-scale water flux simulation**

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In the above meta-analysis of the models, we found that water flux simulations based on EC observations can achieve high accuracy but also have high uncertainty through the modeling workflow. The R-squared of many water flux simulation models exceeds 0.8, possibly higher than some remote sensing-based and process-based models, and possibly higher than carbon flux simulations in the same modeling framework. This suggests that in general, these currently used biophysical and meteorological variables are closely related to water fluxes.such as the net ecosystem exchange (Shi et al., 2022) in the same modeling framework.

372 Biophysical and meteorological variables are considered both important in ET simulations. This study found 373 that models using a combination of meteorological variables had higher accuracy than models using only 374 remotely sensed vegetation dynamic information. However, due to the high proportion of models with small 375 temporal scales (e.g., half-hourly scale, hourly scale, and daily scale) in this study, this advantage of the 376 combination of meteorological variables may be more suitable for small temporal scales. A possible explanation 377 is that vegetation-related variables such as NDVI and LAI at the daily scale, 8-day scale, and 16-day scale have 378 limited explanatory ability for hourly or daily-scale variability in ET. At a small temporal scale, the use of 379 combinations of meteorological variables can capture moisture and energy conditions that control the rapid 380 fluctuations of ET and thus has a dominant role in hourly or daily-scale ET prediction. This also corroborates 381 the high accuracy of some physic-based ET estimation models (Rigden and Salvucci, 2015) that use only 382 meteorological variables and not vegetation-related variables such NDVI (only an estimate of vegetation height 383 derived from land cover maps is used to represent vegetation conditions (Rigden and Salvucci, 2015)). 384

385 There are differences in model accuracy among different PFTs. For example, in forest sites, limitations in data 386 accuracy of factors were possible because some remote sensing-based predictors such as FAPAR and LAI have 387 limited accuracy when applied to forest types(Liu et al., 2018b).NDVI, FAPAR, and LAI have limited accuracy 388 when applied to forest types (Liu et al., 2018b; Zeng et al., 2022). In addition, factors such as crown density, 389 which may significantly affect the proportion of soil evaporation, transpiration, and evaporation of canopy 390 interception, were not considered in these models, which may also lead to low model accuracy. This suggests 391 that in water flux simulation, the driving mechanisms of water fluxes in different PFTs do affect the accuracy of 392 machine learning models, and we need to consider more the actual and specific influencing factors in specific 393 PFTs. More variables that can quantify the ratio of evaporation and transpiration should be considered for 394 inclusion, which also appears to improve the mechanistic interpretability of such machine learning models. 395 Several studies A previous study (Zhao et al., 2019) have has combined the physics-based approach (e.g., 396 Penman-Monteith equation) and machine learning to build hybrid models to improve interpretability. We should 397 make full use of empirical knowledge and experiences from process-based models to improve the accuracy and 398 interpretability of the machine learning approach. 399

设置了格式:字体:10磅,加粗 **带格式的:**标题2,行距:单倍行距 400 The impact of differences in different satellite images on model accuracy and performance may be limited since 401 most studies used windows of 2 km x 2 km or 3 km x 3km when extracting covariates based on satellite remote 402 sensing(Walther et al., 2021) and the effects of differences in image resolution were smoothed out (i.e., the 403 differences in values averaged over a 2 km window may not be significant at 30m and 500m resolutions). 404 However, the coarse resolution of MODIS images may not be effective when the extraction window is smaller 405 (e.g., 200 m) to reduce the inconsistency of the flux footprint extent and the extracted covariates from remote 406 sensing images due to the non-homogeneity of the underlying conditions (Chu et al., 2021). Compared to the 407 16 daily temporal scale of Landsat data, the daily or 8 daily temporal scale of MODIS data may improve the 408 accuracy slightly possibly because more temporal dynamic information is explained. The inclusion of some 409 ancillary variables that do not have the temporal dimension (e.g., soil texture, topographic variables) may be of 410 more limited use unless the model includes many flux sites for which the spatial variability of the ancillary 411 variables is large enough and does affect water fluxes. 412 413 Among the different validation methods, random cross-validation has higher accuracy than spatial cross-414 validation and temporal cross-validation. However, spatial cross-validation and temporal cross-validation may 415 be able to better help us recognize the robustness of the model when extrapolated (i.e., applied to new stations 416 and new years). The lower accuracy in the temporal cross-validation approach implies that we need to focus on 417 interannual hydrological and meteorological variability in the water flux simulations. In cropland sites, we may 418 also need to pay more attention to the effects of interannual variability in anthropogenic cropping patterns. If 419 some extreme weather years are not included, the robustness of the model when extrapolated to other years may 420 be challenged, especially in the context of the various extreme weather events of recent years. This can also 421 inform the siting of future flux stations. Regions where climate extremes may occur and biogeographic types not 422 covered by existing flux observation networks should be given more attention to achieve global-scale, accurate 423 and robust machine learning-based spatio-temporal prediction of water fluxes. 424 4.2 Uncertainties and limitations of this meta-analysis 425 4.2.1 The potential uncertainties and limitations of the results of this meta-analysis are as follows:

426 Thelimited, number of available literature and model records that can be collected:

427 e) Despite many articles and model records collected through our efforts to perform this meta-analysis,
428 there still appears to be a long way to go to finally and completely understand the various mechanisms involved
429 in water flux simulation with machine learning. Some of the insights provided by this study can be not robust
430 (due to the limited sample size available when the goal is to assess the effects of multiple features), but this does
431 not negate the fact that this study does obtain some meaningful findings. Therefore, researchers should treat the
432 results of this study with caution, as they were obtained only statistically. Overall, it is still positive to conduct a
433 meta-analysis of such studies, considering their rapid growth in the number and lack of guiding directions.

434 4.2.2 Publication bias and weighting

435 b) Publication bias and weighting: Due to the relatively limited number of articles that could be included
 436 in the meta-analysis, this study did not focus much on publication bias. Meta-analytic studies in other fields

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438 Field and Gillett, 2010) to determine the weighting inof the literature in a comprehensive assessment. However, 439 most of the articles did not publicly provide flux observations or share developed models. Meta-analysis studies 440 in other fields typically measure the impact of included studies based on sample size and variance of 441 experimental results (Adams et al., 1997; Don et al., 2011; Liu et al., 2018a). In this study, due to the lack of a 442 convincing manner to determine weights among articles, we assigned the same weight to the results for all the 443 literature. 444 4.2.3 Uncertainties in the information of the extracted features: First, as most studies used far more water 445 flux observation records than 446 At the number of covariates in their regression models, we did not adjustinformation extraction level, the R-447 squared in this study to an adjusted R squared. Secondly, following issues may also introduce uncertainties: 448 a) Uncertainties caused by data quality control (e.g. gap-filling (Hui et al., 2004)) and differences in the eddy 449 covariance observation instruments used to observe water fluxes, etc., are difficult to assess effectively. 450 Thirdly, theare difficult to assess effectively. Gap-filling is a commonly used technique to fill in low-451 guality data in flux observations (Chen et al., 2012; Hui et al., 2004). However, the impact of this practice 452 on machine learning-based ET prediction models is unclear, due to the difficulty of directly assessing how 453 this technique is performed in various studies by this meta-analysis. Typically, models with small time 454 scales (e.g., hourly scale, daily scale) can exclude low-quality observations and use only high-quality data. 455 However, for models with large time scales (e.g., monthly scales), gap-filling (e.g., based on 456 meteorological data) may be unavoidable. This may lead to decrease in training data purity and introduce 457 uncertainty in the subsequent prediction model development. 458 Systematic uncertainties caused by the energy balance closure (EBC) issue in eddy-covariance flux b) 459 measurements are also difficult to assess by this meta-analysis. EBC is a common problem (Eshonkulov et 460 al., 2019) in eddy-covariance flux observations. For that reason, the latent heat flux measured potentially 461 underestimates ET. Some prediction models corrected EBC (e.g., using Bowen ratio preserving (Mauder et 462 al., 2013, 2018) and energy balance residuals (Charuchittipan et al., 2014; Mauder et al., 2018)) in the 463 processing of training data, but some did not. How this will affect the accuracy of the prediction model is

typically measure the quality of journals and the public availability of research data (Borenstein et al., 2011;

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necessary for future studies.

into the assessment. Fourth, the

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not clear due to multiple factors that need to be evaluated that influence EBC (Foken, 2008), including

measurement errors of the energy balance components, incorrect sensor configurations, influences of

heterogeneous canopy height, unconsidered energy storage terms in the soil-plant-atmosphere system,

related to PFT, topography, flux footprint area, etc., to select the appropriate correction method is

c) As most studies used far more water flux observation records than the number of covariates in their

regression models, we did not adjust the R-squared in this study to an adjusted R-squared.

inadequate time averaging intervals, and long-wave eddies (Jacobs et al., 2008; Foken, 2008; Eshonkulov

et al., 2019). To reduce this uncertainty, more attention to flux site characteristics (Eshonkulov et al., 2019)

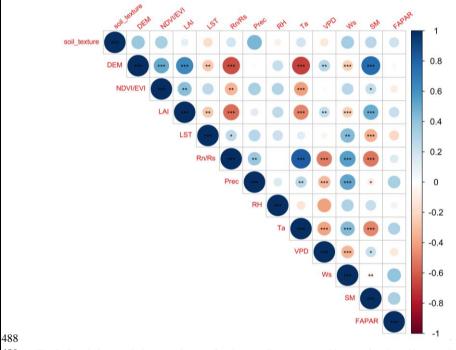
The various specific ways in which the parameters of the model are optimized are not differentiated. They

are broadly categorized into different families or kinds of algorithms, which may also introduce uncertainty

476	e)e) The assessment of some features is not detailed due to the limitations of the available model records. For
477	example, the classification of PFT could be more detailed. 'Forest' could be further classified as broadleaf
478	forest, coniferous forest, etc. while 'cropland' could be further classified as rainfed and irrigated cropland
479	based on differences in their response mechanisms of water fluxes to environmental factors.

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480 d) Independence between features: There is dependence between some of the features being evaluated, which 481 may affect the assessment of the impact of single features on the accuracy of the model. We found that the 482 use of NDVI/EVI, LAI, VPD, and SM was significantly negatively correlated with the use of Rn/Rs and Ta 483 (Fig. 7) when unused was set to 0 and used was set to 1. It means that many of the models that used Rn/Rs 484 and Ta did not use NDVI/EVI, LAI, VPD, and SM, and the models that used NDVI/EVI, LAI, VPD, and 485 SM also happened to not use Rn/Rs and Ta. It can indirectly explain the fact that the accuracy of the models 486 with NDVI/EVI, LAI, VPD, and SM is even lower than that of the models without NDVI/EVI, LAI, VPD, 487 and SM in the above analysis (Fig. 5) because of the disturbance from the use of Rn/Rs and Ta.



⁴⁸⁹ Fig. 7. Correlation matrix between the use of various predictors (not used is set as 0 and used is set as 1) which

491 Significance: the p-value < 0.01 (***), 0.05 (**), and 0.1 (*).

⁴⁹⁰ may introduce uncertainty in the assessment of the impact of an individual predictor on model performance.

492 5 Conclusion

493	We performed a meta-analysis of the site-scale water flux simulations combining in situ flux observations,
494	meteorological, biophysical, and ancillary predictors, and machine learning. The main conclusions are as
495	follows:
496	a)1. SVM (average R-squared = 0.82) and RF (average R-squared = 0.81) outperformed over evaluated \checkmark
497	algorithms with sufficient sample size in both cross-study and intra-study (with the same training dataset)
498	comparisons.
499	b)2. The average accuracy of the model applied to arid regions is higher than <u>in</u> other climate <u>classestypes</u> .
500	e)3. The average accuracy of the model was slightly lower for forest sites (average R-squared = 0.76) than for
501	cropland and grassland sites (average R-squared = 0.8 and 0.79), but higher than for shrub sites (average R-
502	squared $= 0.67$).
503	d)4Among various predictor variables, the use of Rn/Rs, Prec, Ta, and FAPAR improved the model accuracy.
504	The combination of Ta and Rn/Rs is very effective especially in the forest type, while in the grassland type
505	the combination of Ws and Rn/Rs is also effective.

- 506 507 e)<u>5.</u> Among the different validation methods, random cross-validation shows higher model accuracy than spatial cross-validation and temporal cross-validation.
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519 Author Contributions

- 520 Haiyang Shi: Conceptualization, Methodology, Data, Writing. Geping Luo: Conceptualization, Supervision,
- 521 Revision. Olaf Hellwich: Methodology. Alishir Kurban: Supervision. Tim Van De Voorde: Supervision. Philippe
- 522 De Maeyer: Supervision, Revision. Xiaofei Ma, Xiuliang Yuan, Yuangang Wang, Wenqiang Zhang, Mingjuan
- 523 Xie, Chen Zhang, Yu Zhang: Data.
- 524 HS and GL were responsible for the conceptualization, methodology, formal analysis, investigation, visualization,
- 525 and writing. OH contributed to the investigation. XM, XY, YW, WZ, MX, CZ and YZ processed the data. AK,
- 526 TVDV and PDM provided supervision.

527 Competing interests

528 The authors declare that they have no conflict of interest.

529 Code availability

- 530 <u>The codes that were used for all analyses are available from the first author (shihaiyang16@mails.ucas.ac.cn)</u>
- 531 <u>upon request.</u>

532 Data availability

- 533 The data used in this study can be accessed by contacting the first author (shihaiyang16@mails.ucas.ac.cn)
- 534 based on reasonableupon request.
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