A study on the drag coefficient in wave attenuation by vegetation

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Abstract. Vegetation in wetlands is a large-scale nature-based resource providing a myriad of services for human beings and the environment, such as dissipating incoming wave energy and protecting coastal areas. For understanding wave height attenuation by vegetation, there are two main traditional calibration approaches to the drag effect acting on the vegetation. One of them is based on the rule that wave height decays through the vegetated area by a reciprocal function and another by an exponential function. In both functions, the local wave height reduces with distance from the beginning of the vegetation depending on a damping factor (Eqs. (1) and (4)). These two damping factors α' and α' which are usually obtained from calibration by measured local wave height are linked to the drag coefficient -C_D-and measurable parameters, respectively-(Eqs. (3) and (5)). So there are two methods to predict C_D the drag coefficient that quantify quantifies the effect of the vegetation can be calculated by different methods, following by connecting this coefficient to hydraulic parameters to make it predictable. In this study, two relations between these two damping factorsa new equation is derived that connects these two damping factors (Eq.(12)). The different relations and methods to predicting calculate the drag coefficient C_D have had been investigated by 99 laboratory experiments. Finally, different relations between \mathcal{E}_D the drag coefficient and relevant parameters (Re, KC, and Ur) have been were analyzed. The results show that emergent conditions should be considered when studying the drag coefficient; traditional methods which had overlooked this condition cannot perform well when the vegetation was emerged. The new method based on the relation between these two damping factors performed as well as etapproximately equals k' only for fully submerged vegetation, while the new equation can be used for both emerged and submerged canopy. It appears that the methods for predicting C_0 by Dean (1979) and Kobayashi et al. (1993) are consistent with the well-recognized method by Dalrymple et al. (1984) for emerged and submerged vegetation, vegetated canopy. But when the vegetation emerges, only the new method based on Eq. (12) leads to almost the same results as Dalrymple et al. (1984). Hence, Eq. (12) has built a bridge between these two approaches for the wave attenuation by vegetation and has proved applicable to emergent conditions of vegetation as well. Additionally, the Keulegan-Carpenter number can be a suitable hydraulic parameter to predict the drag coefficient only the experimental setup especially the densities of the vegetation can affect the prediction equations.

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1 Introduction

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To meet the current wave prevention requirements, it is of practical to construct ecological safety barriers with wetland vegetation based on natural conditions. Vegetation in wetlands can enhance the toughness of the coast and save construction investment effectively by dissipating incoming wave energy (e.g., Reguero et al., 2018). Practice also has proved that vegetation in wetlands can provide services such as enhance—enhancing coastal ecosystem and biodiversity, enhanceenhancing fisheries and forestry production, increase—increasing bank stability, and promote—promoting tourism economy, whereas the vegetated area occupies—floodplainland resources in floodplain (Schaubroeck, 2017; Keesstra, 2018). Hence, it is necessary to better understand the mechanism of wave attenuation to promote the efficiency of the nature-based solution.

Wave attenuation by vegetation is mainly induced by the drag force provided by the vegetation acting on water motion, as investigated in different researches such as numerical modeling (e.g., Wu et al., 2016; Suzuki et al., 2019), laboratory experiment (e.g., Hu et al., 2014; Wu and Cox, 2015, 2016), or field study (e.g., Danielsen et al., 2005; Quartel et al., 2007). The drag force is closely related to the drag coefficient C_D which quantifies the drag or resistance of vegetation in water (Chen et al., 2018). This coefficient is one of the most uncertain parameters in the complicated interaction between the vegetated area and water because the drag effect can be fairly different on various time and space scales.

The calibration method for the drag coefficient is based on the perspective of wave energy dissipation and wave height reduction which will be discussed in Section 2, while Dean (1979) and Kobayashi et al. (1993) proposed that local wave height decaying through the vegetated eanopy-area following a reciprocal function and exponential function, respectively. These two calibration functions describe local wave height with a distance from the beginning of vegetation and a factor reflecting the damping—, so the corresponding factor can be calibrated based on measured wave height through the vegetated area. The damping factor $\underline{\alpha}'$ from the reciprocal function and the exponential damping factor \underline{k}' from the exponential function are often linked to the drag coefficient C_D and measurable parameters such as water depth and density of stems. For instance, Dean (1979) proposed an equationa method to predict calculate C_D based on the damping factor and the model laterhad been developed by researchers such as Knutson et al. (1982), Dalrymple et al. (1984), and Losada et al. (2016). Overall, the drag coefficient can be calculated by calibrating $\underline{\alpha}'$ or \underline{k}' using measured local wave height, then the researchers built non-liner relations between C_D and hydraulic parameters such as the Reynolds number (e.g., Hu et al., 2014; He et al., 2019). In this way, the drag of vegetation in water becomes predictable based on the non-linear relations and the values of these hydraulic parameters different equations for these damping factors had been obtained under different operating conditions.

Zhang et al. (2021) has-had compared these two calibration approaches by these two featured functions directly and yielded a connection between $\underline{\alpha}$ the damping factor and \underline{k} the exponential damping factor then revealed a new equation to predict

calculate the drag coefficient had been revealed. However, Zhang et al. (2021) overlooked the relation between $\underline{k'}$ and $\underline{C_D}$ by Kobayashi et al. (1993) and only used the relation between $\underline{\alpha'}$ and $\underline{C_D}$ by Dean (1979). In this article, using the well documented relation between the damping factor $\underline{\alpha'}$ and the drag coefficient $\underline{C_D}$ by Dalrymple et al. (1984) as well as the mentioned relation by Kobayashi et al. (1993), This article will compare these two traditional approaches had been compared from another perspective and the second connection between $\underline{\alpha'}$ and $\underline{k'}$ had been revealed.

Then Hence, there are two relations between the damping factor following Dean (1979) and the exponential damping factor following Kobayashi et al. (1993) from two perspectives, and they were had been analyzed by 99 cases from collected data and experimental observations experiments in this study. Additionally, in normal tidal conditions and the initial stage of storm surge, vegetation in wetlands can be emerged while by storm surge, vegetation is submerged or near-submerged. Existing methods for the drag coefficient had been compared to calculate the drag coefficient had been compared considering these emergence conditions. Finally, relations between C_D and hydraulic parameters, for instance, the Reynolds number (R_E) , the Keuglan-Carpenter number (KC), and the Ursell number (UT), had been studied.

2 Theoretical foundations

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Typically, the drag coefficient C_D is determined from the perspective of wave energy dissipation, represented by the decay of wave height. Dean (1979) proposed one of the first models for wave attenuation by vegetation in which wave height throughout the vegetated area can be expressed as a reciprocal function:

$$K_X = H(X)/H_0 = 1/(1 + \alpha'X),$$
 (1)

where K_X (-) is the relative wave height at a distance X (m) through the vegetation field from the beginning of vegetation, H(X) (m) is the local wave height, H_0 (m) is the incident wave height, and α' (m⁻¹) is the damping factor.

Based on empirical estimates of fluid drag forces acting on vertical, rigid cylinders, Dean (1979) found that:

$$\alpha' = C_D dN H_0 / 6\pi h, \tag{2}$$

where d (m) is the diameter of the circular vegetation cylinder, h (m) is the water depth, and N (stems m⁻²) is the average number of stems per unit area.

Then Dalrymple et al. (1984) formulated an algebraic dissipation equation practicing linear theory and conservation of wave energy where α' can be expressed as:

$$\alpha' = \frac{4}{9\pi} C_D N d_v k_w H_0 \frac{\sinh^3 k_w l_s + 3 \sinh k_w l_s}{\sinh k_w h (\sinh 2k_w h + 2k_w h)},\tag{3}$$

where d_v (m) is the vegetated area per unit height of plant normal to wave direction, k_w (rad m⁻¹) is the wave number, and l_s (m) is the submerged stem height.

On the other hand, Kobayashi et al. (1993) published that the local wave height decays exponentially through submerged artificial kelp:

$$K_X = H(X)/H_0 = \exp\left(-k'X\right),\tag{4}$$

where k' (m⁻¹) is the exponential damping factor. Based on linear wave theory and the conservation equation of energy, k' wais expressed as (Kobayashi et al.,1993):

$$k' \cong \frac{1}{9\pi} C_D N d_v k_w H_0 \frac{\sinh 3k_w l_s + 9 \sinh k_w l_s}{\sinh k_w h \left(\sinh 2k_w h + 2k_w h \right)},\tag{5}$$

<u>If we compare</u> these relations between the (exponential) damping factor and the drag coefficient (Eqs. (3) and (5)),

105 a relation between the damping factor α' and the exponential damping factor k' can be derived:

$$\alpha'/k' \cong 1,$$
 (6)

Recently, Zhang et al. (2021) presented a relation between α' and k' looking at these featured functions (Eqs. (1) and (4)) directly, based on Taylor expansion. This method firstly scaled the distance X-of Eqs. (1) and (4):

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$$H/H_0 = 1/(1 + \alpha'X) = 1/(1 + \alpha x) = F(x),$$
 (7)

and

$$H/H_0 = \exp(-kX) = \exp(-kx) = G(x),$$
 (8)

where α (= $\alpha'L$) (-) is the scaled damping factor, L (m) is the length of vegetated area, x (= X/L) (-) is the scaled distance through the vegetation field, k (= k'L) (-) is the scaled exponential damping factor, and F(x) and G(x) represent functions.

Then by using the Taylor expansion, when the scaled distance x equals half, the following equations had been derived:

$$F(x) = \frac{2}{\alpha+2} - \frac{4\alpha}{(\alpha+2)^2} (x - 1/2) + \frac{8\alpha^2}{(\alpha+2)^3} (x - 1/2)^2 - \frac{16\alpha^3}{(\alpha+2)^4} (x - 1/2)^3 + R_1(x), \tag{9}$$

and

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$$G(x) = \frac{1}{e^{k/2}} - \frac{k}{e^{k/2}} (x - 1/2) + \frac{k^2}{2e^{k/2}} (x - 1/2)^2 - \frac{k^3}{6e^{k/2}} (x - 1/2)^3 + R_2(x), \tag{10}$$

where $R_1(x)$ and $R_2(x)$ are the residual terms. The relative magnitude of each term in Eqs. (9) and (10) hads been analyzed by Zhang et al. (2021), and it has had revealed that the first two terms on the right side of these equations are relatively large compared to other termsplayed the most significant role. Hence, considering only these two terms in Eqs. (9) and (10), the proportionality between the two first terms $\frac{2}{\alpha+2} / \frac{1}{e^{k/2}} \equiv \frac{4\alpha}{(\alpha+2)^2} (x-1/2) / \frac{k}{e^{k/2}} (x-1/2)$ yields two equations, which results in:

$$\alpha/k = 2/(2-k),\tag{11}$$

125 which equals:

$$\alpha'/k' = 2/(2 - k'L),$$
 (12)

Equations (6) and (12) have built a bridges between the exponential function and reciprocal function, verifying that these two <u>functions</u> are reliable and capable to describe the wave height attenuation by vegetation satisfactorily. The rule of the attenuation is then limited by two functions, which can increase the reliability of the calibration. Besides, the exponential damping factor can be obtained easily based on local wave height, therefore, calculating α' in the well documented Eq. (3) on the basis of the calibrated k' is much easier than calibrating α' directly, which needs professional numerical tools.

However, application of Eq. (6) in Eq. (12) results in $k'L \cong 0$, which is not appropriate when there is vegetation in the wetlands. Hence, it is worth further studying the relation between these two damping factors to help us better understanding the drag coefficient and wave attenuation by vegetation.

In addition, we had studiedy the relation between C_D and three relevant hydraulic parameters, which are also frequently used to model C_D , including: 1) the Reynolds number, $Re = u_{max} d_v / v$, where $v = 1.011 \times 10^{-6} \text{ m}^2 \text{ s}^{-1}$ is the kinematic viscosity of water and $u_{max} = 2\pi H_0 / 2T \tanh k_w h$ is the maximum horizontal wave velocity from linear wave theory, where T (s) is the wave period; 2) the Keulegan-Carpenter number, $KC = u_{max} T / d_v$, representing oscillatory flow around cylinders; and 3) the Ursell number, $Ur = \lambda^2 H_0 / h^3$, characterizing the balance between wave steepness and the relative water depth, where λ (m) is the wave length. Researchers had reported several formulas between C_D and Re. For instance, Wu et al. (2011) obtained the following empirical equation:

$$\underline{C_d} = 3.83 \times 10^{-6} \pm (5683/Re)^{1.17} \tag{13}$$

Besides, He et al. (2019) revealed that

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$$\underline{C_d} = 18.025 \exp\left(-0.043KC\right) \tag{14}$$

Hence, $\underline{\mathbf{T}}_{\underline{\mathbf{t}}}$ the following $\underline{\mathbf{two}}$ formulas are most possible solutions is used to study the non-linear relation between C_D and these parameters:

$$C_{\underline{D}\underline{d}} = a \exp(-bX) \tag{1315}$$

$$\underline{C}_D \equiv a + (b/\overline{X})^c \tag{16}$$

where \overline{X} could be R_e , KC or Ur; a,b,c-and b are factors. Values of these factors can be obtained by the regression of C_D by calibrated $\underline{\alpha}$ or \underline{k} and these parameters, and in this way, C_D becomes predictable under different operation conditions. We had obtained the values of the factors and the corresponding adjusted R-square as in Section 5.4 by both equations, and it is hard to tell the difference between these results from Eqs. (13) and (14). The former is at last chosen because it contains less factors and is simpler than the latter.

3 Experimental setup and instrumentations

The experiments were conducted in a wave flume in Guangdong key laboratory of hydrodynamic research at Guangdong research institute of water resources and hydropower, China. The wave flume is 80.0 m long, 1.8 m wide, and 2.6 m deep (schematized in Fig. 1a, unit: m). The wave was generated by a wave generator at one end and absorbed at the opposite end.

The start of the vegetated area was located 52.7 m from the wave generator. The uniform <u>vegetation eanopies werewas</u> constructed by putting mimic plants (Fig. 1b) in holes drilled in the bottom. These two heights of mimic plants (l_s) were 0.3 and 0.5 m and d_v of the mimics was 0.057 m considering average diameters of the stem and leaves while the height ratio of them <u>is-was</u> about 0.5 (Fig. 1b). The <u>three horizontal lengths of the eanopies-vegetated area</u> (L) were 4 m, 5 m, and 6 m, and two mimic stem densities (N) were 25 and 50 stems m⁻² (<u>marked as N1 and N2</u>, see Figs. 1c and 1d). These two water levels of the flume were 0.8 and 1.0 m so the corresponding water <u>depths</u> of the floodplain (h) were 0.3 m and 0.5 m.

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The original wave heights (H_{ori}) of each designed regular wave were was calibrated at 30 m from the wavemaker before these tests. In this study, seven wave gages (G1 to G7) were used to measure the wave height time series, which were placed 1 m apart from each other from the beginning of the vegetated area (Fig. 1a) and we used the measurement at G1 was used as the incident wave height (H_0) (Wu and Cox, 2015).

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Control tests were carried out with no mimic plants to reduce the influence of flume bed and sidewalls. As <u>listed</u> in Table 1, sixteen operating modes were conducted including various conditions. Data of each test were <u>collected during more</u> than 200 s and each case was repeated for three times.

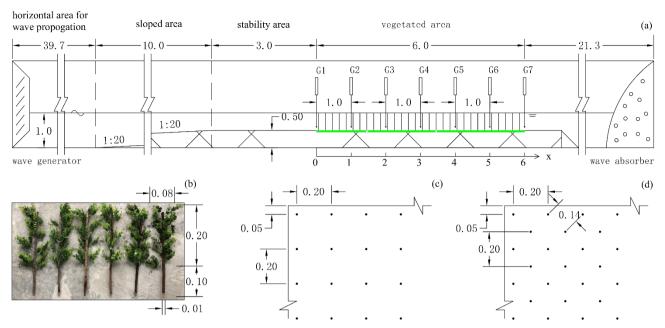


Figure 1: Experimental setup. (a) Schematic of the wave flume and instrument deployment, when the water depth of the floodplain level was 0.51.0 m and mimic plants height was 0.5 m; (b) mimic plants with a height of 0.3 m; (c) and (d) top view of the mimic plant canopy with density of 25 and 50 stems m².

Table 1: Hydrodynamic conditions with regular waves

Cases	h [m]/ H_{ori} [m]	k_w [-]	wave period (T) [s]	<i>L</i> [m]	N [stems m ⁻²]	l_s [m]
1	0.3/0.12	2.24	1.00	4	25	0.3
2	0.3/0.12	2.24	1.00	5	25	0.3
3	0.3/0.12	2.24	1.00	6	25	0.3
4	0.3/0.12	2.24	1.00	4	25	0.5
5	0.3/0.12	2.24	1.00	5	25	0.5
6	0.3/0.12	2.24	1.00	6	25	0.5
7	0.3/0.12	2.24	1.00	4	50	0.5
8	0.3/0.12	2.24	1.00	5	50	0.5
9	0.3/0.15	2.04	1.10	4	50	0.5
10	0.3/0.15	2.04	1.10	5	50	0.5
11	0.5/0.15	1.79	1.12	4	25	0.3
12	0.5/0.15	1.79	1.12	5	25	0.3
13	0.5/0.15	1.79	1.12	6	25	0.3
14	0.5/0.15	1.79	1.12	4	25	0.5

Cases	h [m]/ $H_{\rm ori}$ [m]	k_w [-]	wave period (T) [s]	<i>L</i> [m]	N [stems m ⁻²]	l_s [m]
15	0.5/0.15	1.79	1.12	5	25	0.5
16	0.5/0.15	1.79	1.12	6	25	0.5

185 4 Data collection

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Besides experiments in this study, observations in published literatures had been collected from Hu et al. (2014), Wu et al. (2011), and Wu and Cox (2015, 2016) as Zhang et al. (2021) presented. The summarized experimental setup is shown in Table 2. Overall, different operation conditions had been conducted by the researches. These researchers in previous studies had shown the values of C_D and local wave height along the vegetated area.

Hu et al. (2014) conducted laboratory experiments in a wave flume, with a 6 m long vegetation mimic canopy. The mimics were stiff wooden rods with a height of 0.36 m and a diameter of 0.01 m. Three mimic stem densities (62, 139 and 556 stems m⁻², represented by VD1, VD2 and VD3) were constructed and control tests with no stems were measured. Also, two water depths (0.25 and 0.50 m) were used to study the emerged and submerged conditions.

Wu et al. (2011) reported a series of experiments in laboratory with a 3.66 m long vegetation field. The rigid vegetation mimicked by 9.5 mm diameter birch dowels were studied by two stem densities (350 and 623 stems m⁻²) and two stem heights (0.63 and 0.48 m).

The laboratory experiments by Wu and Cox (2015) were conducted in a wave flume with a water depth of 12 cm and the 1.8 m long vegetated area was modeled by plastic strips, 5 mm wide by 1 mm thick. The length of the strips was 14 cm and the density was 2 100 stems m⁻²:

Wu and Cox (2016) also conducted experiments in a small scale wave flume, and the vegetated field is 90-cm-long by uniform stand of emergent vegetation with a stem height of 0.14 m and width of 5 mm. The stem density was 1618 stems m⁻², and the water depth was 0.1 m.

Table 2: Experimental conditions from references

Reference	Type of plant	Plant height/m	Plant diameter/ m	Plant density/ stem m ⁻²	Incident wave height/m	Length of vegetation/	Depth of water/m
<u>Hu et al.</u> (2014)	Stiff wooden rods	0.36	0.01	62/139/556 (VD1/VD2/VD3)	0.032~0.202	<u>6</u>	0.25/0.5

<u>Wu et al.</u> (2011)	Birch dowels	0.48/0.63	0.009 4	350/623	0.083/0.084/ 0.085	3.66	0.5
<u>Wu and Cox</u> (2015)	Plastic strips	0.14	0.005	<u>2 100</u>	0.014~0.042	1.8	0.12
<u>Wu and Cox</u> (2016)	Plastic strips	0.14	0.005	<u>1 618</u>	0.015~0.034	<u>0.9</u>	0.12

5 Results and discussion

210 5.1 Reduction of wave height

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Wave height along the vegetated area is a significant index for wave attenuation by vegetation. The calibrated reductions of wave height by three equations demonstrating two examples (Cases 13 and 16) were are shown in Fig. 2. It is clear that Eqs. (47) and (48) were reliable relations between the scaled distance and the relative wave height. Also, Eq. (1) with calculated α -value according to Eq. (11) is appliable to fit the observations, hence Eq. (11) is useful. Additionally, with the calibrated k value from Eq. (8), we calculated the value of α according to Eq. (11). Applying the calculated α in Eq. (7), the calculated relative wave height, which was named by Eq. (11) in Fig. 2, was appliable to fit the measurements, which suggested that Eq. (11) is valid. Results also showed that the larger the value of the scaled damping factors α and the scaled exponential damping factor α , the stronger the wave attenuates.

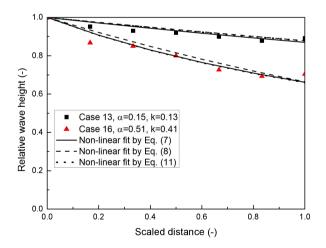


Figure 2: Measured and predicted wave attenuation. Square and trigon symbols indicated measurements of Cases 13 and 16; solid, dashed and dotted lines represented the curves fitted by Dean (1979) (Eq. (17)), Kobayashi et al. (1993) (Eq. (48)), and Eq. (11).

5.2. Relation between α and k

The relation between calibrated values of α and k by 99 cases from this study and collected data was-is shown in Fig. 3. In the study of Wu et al. (2011), Hu et al. (2014) and this research, both submerged and emerged cases were had been conducted, and in the study of Wu and Cox (2015, 2016) the vegetation eanopies—were emerged. The emerged and submerged eanopies—cases had beenwere separated for studying the influence of the emergent condition (emerged or submerged). The results Figure 3 showed that there is an obvious relation between α and k for all cases. However, Eq. (6), which has beenwas obtained by comparing these relations between the (exponential) damping factor and the drag coefficient by Dalrymple et al. (1984) and Kobayashi et al. (1993), worked well only when values of α and k were smaller than around 0.4. Equation (12), on the other hand, seemed a possible solution for the relation of these two factors, and the relation between α and k did-is not strongly affected by the emergent condition while-even though these values were are indeed relatively small when the vegetation was-is submerged (0.04< α <0.56) than when it was-is emerged (0.12< α <1.43). Notably, the analytical solution of Kobayashi et al. (1993), i.e., Eq. (5), was obtained and conducted using deeply submerged artificial kelp, and $H(X)^3 \cong H_0H(X)^2$ was assumed which can only be valid when wave height reduces slightly through submerged vegetated areas and the exponential damping factor is are-small. This is why Eq. (6) can only be profitable for submerged vegetation.

Equation (12) also revealed that $\alpha - k = \frac{k^2}{(2 - k)} > 0$ since k is smaller than 2 (Fig. 3). When the vegetation is deeply submerged, the calibrated k close to zero and α is larger than but approximate to k (Eq. (6)); when the vegetation becomes emerged, α and α become relatively large and the difference between them enlarges, which can be seen in Figs. 2 and 3. That is to say, Fig. 3 shows that Eq. (12) works well and it includes Eq. (6) to some extent.

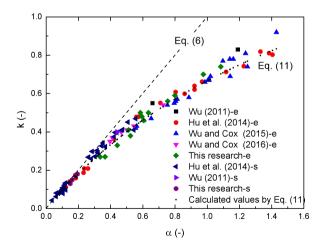


Figure 3: Comparison of calibrated α and k. Different symbols indicated cases from different researches and emergent conditions. For emerged and submerged cases, "-e" and "-s" were added after the references as the legend shown. The dashed and dotted lines indicated calculation by Eqs. (6) and (11), respectively.

5.3 Predict Calculate C_D by different methods

5.3.1 Predict Calculate C_D by Dean (1979)

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Several studies Attention has been paid attention to study the emergent condition of the vegetation recently. This condition (eg., by l_c) has had been included in Eq. (3) by Dalrymple et al. (1984) while it has had not been considered in Eq. (2) by Dean (1979). In this part, the calibrated values of the drag coefficient by Eqs. (2) and (3), both considering Both methods by Dean (1979) and Dalrymple et al. (1984) consider wave height decaying by the reciprocal function, were compared. Figure 4 in which the damping factor can be obtained by fitting the local wave height by Eq. (7). In this case, the value of the drag coefficient can be calculated using Eq. (2) or Eq. (3), and the comparison of results by these two equations is shown in Fig. 4. The result showed shows that these 99 cases obviously can be divided into two categories and they could can be fitted by linear lines. The Both the values of the adjusted R-square of the linear fit of emerged category and submerged category were are 0.970 and 0.973, respectively, which means the results by these two equations are comparable. However, while the slope of the former was is about twice as large as the latter, so the emergent condition. Hence, it is necessary to be considered when calculating distinguish submerged from emerged cases when study the drag coefficient in wave attenuation by vegetation. by Eq. (2). Furthermore Additionally, the linear fit of the submerged category was is close to the 1:1 line which means both equations are reliable and applicable for this category, while one of them is not suitable for emerged category considering the slope of the linear line. Since Eq. (3) had paid attention to the emergent condition, it is then regarded as a more satisfactory solution to calculate the drag coefficient for different conditions, while which meant that both Eqs. (2) and (3) can be the solution in submerged cases but for emerged cases Eq. (2) can lead to larger values, of the calibrated C_{D} .

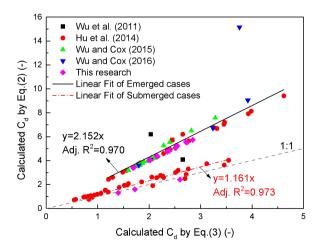


Figure 4: Comparison of the ealibrated calculated values of C_D by Eqs. (3) and (2). Different symbols indicated cases from different researches. The solid and dashed dot lines indicated linear fit of emerged and submerged categories.

5.3.2 Predict Calculate C_D by Kobayashi et al. (1993)

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Equation (5) by Kobayashi et al. (1993) also considered the emergent condition and it was obtained by using local wave height decaying exponentially. Hence, in this part, the comparison of ealibrated the values of the drag coefficient by Eqs. (3) 270 and (5) were was studied to learn the influence of different decaying functions and the result was is shown in Fig. 5. The value of C_D by Kobayashi et al. (1993) was obtained by calculating C_D using Eq. (5) on the base of the calibrated exponential damping factor by fitting the local wave height using Eq. (8). Figure 5 reveals that \underline{C}_D by Eq. (5) is always smaller than \underline{C}_D by Eq. (3). Also, The result also revealed that cases can be divided into emerged and submerged two categories. For submerged cases, the drag coefficient by Eq. (5) is close to but slightly smaller than that by Eq. (3), with a slope of 0.96 in 275 Fig. 5; for emerged cased, the former is more smaller than the latter when the drag coefficient is larger. This is consistent to the conclusion in Section 5.2 since C_0 has positive correlation with α and k and the emergent condition has smaller effect on the calibrated $C_{\rm p}$ by Eq. (5) than Eq. (2). These slopes of the linear fit lines of emerged category and submerged category in Fig. 5 were 0.77 and 0.96 while the values were 2.15 and 1.16 in Fig. 4. Additionally, the linear fit line was close to the 1:1 line for submerged category hence. In a word, for calculating the drag coefficient in wave attenuation by submerged 280 vegetation, both Eqs. (3) and (5) can be the solution. This is consistent with the result in the last Section. However, for emerged cases, Eq. (5) can lead to smaller values of the calibrated C_D .

Additionally, although the regression of data should not be linear since $k/\alpha = (2-k)/2 < 1$ is not a constant, if we obtain C_D by calibrating the exponential function for emerged cases, we have a rapid assessment that the value will be approximate 77% of the needed value. Moreover, the result reveals that $k'/\alpha' \approx 0.77$. Combining Eq. (12), k'L = k approximates to 0.46, then $K_X \approx 0.63$ at the end of the vegetation according to Eqs. (4) and (8). It means that the reduction rate $(=1-K_X)$ of the wave height for the emerged cases is about 37%. Furthermore, if we apply $k \approx 0.46$ in Eq. (12), α is about 0.53 then $K_X \approx 0.65$ according to Eqs. (1) and (7). Values of K_X which were close by α and α can be used to assess the wave attenuation by emerged vegetation very preliminary.

Of course, several parameters can affect the drag effect. In this case, certain cases should be considered instead of to use the result from a regression by all the cases with different operating conditions, then the slope of the comparison between the calculated C_D by Eqs. (3) and (5) will be different so the calculated relative wave height will be different.

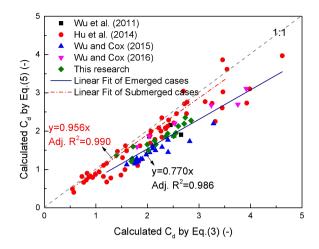


Figure 5: Comparison of the ealibrated calculated values of C_D by Eqs. (3) and (5). Details are the same as Fig. 4.

5.3.3 Predict Calculate C_D by a new method

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The new method obtained obtains the sealed-damping factor α' by using the calibrated k' based on measured wave height and Eq. (12), so and calculated the drag coefficient C_D can be calculated by Eq. (3). The Eq. (12)-based method used the rule that the local wave height decaying exponentially and the classic relation between the damping factor and C_D by Dalrymple et al. (1984). The comparison of the ealibrated calculated values of C_D by Eq. (3) and the new method is shown in Fig. 6. The result showed shows that there was is a strong linear relationship among the ealibrated calculated values in 99 cases from different researches. The slope of the linear fit iswas about unit and the adjusted R-square equalled equals 0.99. The result was is inspiring and showed shows that the new method can lead to comparable results to the method by Dalrymple et al. (1984) for the drag coefficient. It is revealed that Eq. (12) is satisfactory and can be a bridge between the damping factor and the exponential damping factor and there is no need to consider the emergent condition. Based on the results in Figs. 5 and 6, the exponential damping factor k' can be used to calculate C_D while it needs to be converted to α' based on Eq. (12) instead of to be used directly in Eq. (5) for emerged cases; while for submerged cases, it can be a solution to calculate C_D directly.

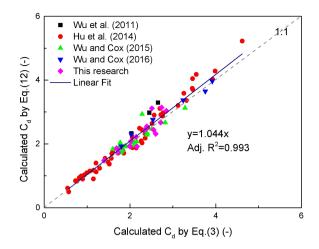


Figure 6: Comparison of the ealibrated calculated values of C_D by Eq. (3) and the new method. Different symbols indicated cases from different researches. The solid line indicated linear fit of all cases.

5.4. Relate C_D to R_e , KC, and Ur

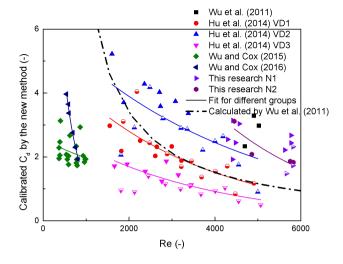
5.4.1. Relate C_D to R_e

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Relating the calculated $\underline{C_D}$ by calibration method to $\underline{R_e}$, \underline{KC} , or \underline{Ur} is a common method to predict $\underline{C_D}$. The relation between R_e and the calibrated C_D by the new method and the nonlinear fit by Eq. (1315) were are shown in Fig. 7. In the study by Hu et al. (2014) and this research, cases were grouped by different densities were separated. These two trigons in the lower left corner of cases from Hu et al. (2014) were considered outliers in these analyses. Results showed that the tendencies of the relations were noticeable for different groups of cases as the legend specified. The values of R_e ranged from 370 to 38000 and the solid line following different groups of symbols can basically fit, and this might due to the fact that Wu and Cox (2015, 2016) used irregular wave so the calculated Reynolds numbers were small. Results revealed reveals that separating cases from different densities was-is necessary for studying this relation while the effect of the emergent condition was-can be ignorable. Equation (153) was utilized to study the this relation between R_e and C_D and the outcomes of the factors from nonlinear fit between R_e and C_D by the new method and Eq. (3) were are shown in Table 23. Results showed that values for a certain factor (a or b) based on the new method and Eq. (3) were are close to each other especially for cases from Hu et al. (2014), supporting that the new method is comparable to Dalrymple et al. (1984). Moreover, values of factors can be quite different in various groups in Table 3 hence laboratory setup could play an important role on the relation between the drag coefficient and the Reynolds number. Hence, this relation is not universal for different cases. For example, the calculated line by Eq. (13) published by Wu et al. (2011) was not very suitable for other groups of measurements. Hence, for engineering applications, case study is ies are needed for certain issues.



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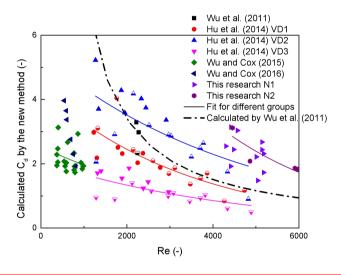


Figure 7: Relation between R_e and the calibrated C_D by the new method. Different symbols indicated cases from different researches, and partially and fully solid symbols denote submerged and emerged cases, respectively. The solid lines following groups of the symbols indicated nonlinear fit of groups by Eq. (1315).

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Table 23: Outcome of the factors in Eq. (1315) between R_e and C_D by the new method and Eq. (3).

References		The new metho	od		Equation (3)		
References	а	b	Adj. R ²	а	b	Adj. R ²	
Hu et al. (2014) VD1	<u>4.4</u> 5.2	2.9×10 ⁻⁴ 3.1×10 ⁻⁴	<u>0.65</u> 0.64	<u>4.0</u> 4.6	$2.5 \times 10^{-4} 2.7 \times 10^{-4}$	<u>0.70</u> 0.67	
Hu et al. (2014) VD2	<u>5.4</u> 6.2	2.1×10 ⁻⁴ 2.3×10 ⁻⁴	<u>0.44</u> 0.44	<u>4.9</u> 5.5	2.0×10 ⁻⁴ 2.2×10 ⁻⁴	<u>0.45</u> 0.44	

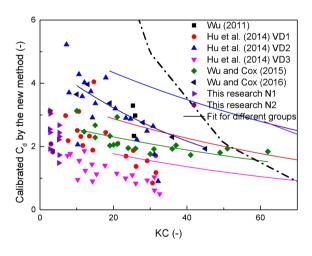
Hu et al. (2014) VD3	<u>2.2</u> 3.1	$2.1 \times 10^{-4} 3.1 \times 10^{-4}$	<u>0.47</u> 0.73	<u>2.1</u> 3.3	$2.4 \times 10^{-4} 3.3 \times 10^{-4}$	<u>0.44</u> 0.69
Wu and Cox (2015)	<u>2.5</u> 2.5	2.6×10^{-4} 2.6×10^{-4}	<u>0.04</u> 0.04	<u>3.0</u> 3.0	5.3×10^{-4} 5.4×10^{-4}	<u>0.32</u> 0.32
Wu and Cox (2016)	16.8	2.6×10^{-3}	0.99	<i>‡</i>	<i>‡</i>	<i>‡</i>
This research N2	<u>11.9</u> 14.7	3.2×10^{-4} 3.7×10^{-4}	<u>0.65</u> 0.69	<u>7.2</u> 8.3	2.5×10^{-4} 2.8×10^{-4}	<u>0.87</u> 0.90

5.4.2. Relate C_D to KC

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The relation between KC and the calibrated C_D by the new method iswas shown in Fig. 8. The values of KC ranged from 9 to 130 and the range is much smaller than that of R_e in Fig. 7. Similarly, Eqs. (13) was utilized to study the relation between KC and C_D and outcomes of the factors were are shown in Table 34. Results showed that these fit lines were are closer to each other than that in Fig. 7. The adjusted R-square values in Table 3-4 were are overall larger than the corresponding numbers in Table 23. In addition, values for a certain factor based on these two methods were closer than the results in Table 3. From these studied cases, the Keulegan-Carpenter number could can be a satisfactory better parameter for to describe describing the drag coefficient than R_e . Besides, for predicting C_D by KC, factors in Eq. (15) can be different for different densities of vegetation and operation conditions, but the emergent condition will not affect the result. In addition, values for a certain factor based on these two methods were closer than the results in Table 2, revealing that the new method performed well since the method by Dalrymple et al. (1984) is well-recognized.



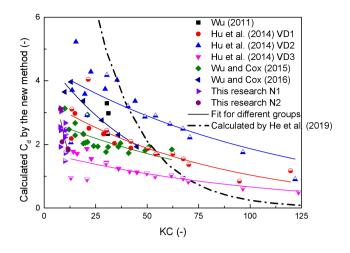


Figure 8: Relation between KC and the ealibrated calculated C_D by the new method. Details are the same as Fig. 7.

Table $\frac{34}{2}$: Outcome of the factors in Eq. ($\frac{1315}{2}$) between KC and C_D by the new method and Eq. (3).

D.f		The new method				Equation (3)		
References	a	b	Adj. R ²	а	b	Adj. R ²		
Hu et al. (2014) VD1	<u>3.4</u> 3.7	1.21.2×10 ⁻²	<u>0.66</u> 0.67	<u>3.2</u> 3.4	1.0×10^{-2} 1.1×10^{-2}	<u>0.76</u> 0.76		
Hu et al. (2014) VD2	<u>4.5</u> 5.4	8.8×10^{-2} 1.1×10^{-2}	<u>0.51</u> 0.76	<u>4.1</u> 4.8	$8.2 \times 10^{-3} 1.0 \times 10^{-2}$	<u>0.52</u> 0.76		
Hu et al. (2014) VD3	<u>1.8</u> 2.3	$1.0 \times 10^{-2} 1.3 \times 10^{-2}$	<u>0.58</u> 0.94	<u>1.8</u> 2.4	$1.0 \times 10^{-2} 1.5 \times 10^{-2}$	<u>0.54</u> 0.90		
Wu and Cox (2015)	<u>2.8</u> 2.8	$1.0 \times 10^{-2} 1.0 \times 10^{-2}$	<u>0.44</u> 0.44	<u>3.1</u> 3.0	$1.5 \times 10^{-2} 1.3 \times 10^{-2}$	<u>0.65</u> 0.65		
Wu and Cox (2016)	<u>4.8</u> 4.8	$2.0 \times 10^{-2} 2.0 \times 10^{-2}$	<u>0.94</u> 0.94	<u>5.0</u> 5.0	$2.4 \times 10^{-2} 2.4 \times 10^{-2}$	<u>0.96</u> 0.96		
This research N2	<u>7.2</u> 8.0	$1.2 \times 10^{-1} 1.7 \times 10^{-2}$	<u>0.54</u> 0.56	<u>5.0</u> 5.4	9.4×10 ⁻² 1.4×10 ⁻²	0.800.82		

5.4.3. Relate C_D to Ur

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The relation between C_D and the Ursell number Ur has had also been studied (Fig. 9). The values of Ur ranged from 1 to 68. However, the nonlinear fit by Eqs. (1315) was unsatisfactory for all groups since the relation of these data were is not so strong. Results showed that comparatively comparing to R_e and KC, Ur was is not a well-performed parameter for studying the drag coefficient in wave attenuation by vegetation.

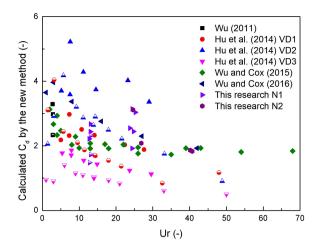


Figure 9: Relation between Ur and the ealibrated calculated C_D by the new method. Details are the same as Fig. 7.

6. Discussion and conclusions

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Wave attenuation by vegetation in wetlands is a large-scale nature-based solution providing a myriad of services for human beings. For understanding wave attenuation, two main traditional calibration approaches to the drag effect acting on the vegetation were had been established, based on local wave height decaying by a reciprocal function or exponential function. By combining tThese two reliable calibration methods by Dean (1979) and Kobayashi et al. (1993) can be combined from two perspectives: one by combining these featured functions directly (Eqs. (1) and (4)), and another by these relations between the (exponential) damping factor and the drag coefficient (Eqs. (3) and (5)). So, two relations between the damping factor α' and the exponential damping factor k' were had been derived (Eqs. (6) and (12)). Then, the relation between α' and k' and the drag coefficient in wave attenuation were analyzed by 99 laboratory experiments. Furthermore, the relations between C_D and important hydraulic parameters (Re, KC, and Ur) was analysed were analyzed to make C_D predictable under certain conditions.

The results showed that the reduction of wave height can be <u>well</u> described by both reciprocal and exponential functions. For submerged vegetation, which reduces wave height relatively slightly, the damping factor approximately <u>equals equalled</u> the exponential damping factor and Eq. (6) <u>may bewas</u> applied. However, Eq. (12) <u>wasappeared</u> applicable no matter how submerged the vegetation <u>iswas</u>, which is <u>really</u> a satisfactory result. These two equations build a bridge between the two traditional wave height decaying models. <u>Besides, for For submerged vegetationed eanopy, values of CD calculated by Eq.</u> (2) by Dean (1979) and Eq. (5) by Kobayashi et al. (1993) were consistent with the well-recognized Eq. (3) by Dalrymple et al. (1984). However, when the vegetation was emerged, Eqs. (2) and (5) were not in line with Eq. (3). On the other hand, the

predicted <u>calcuated</u> C_D values by the new method by Zhang et al. (2021) in combination with Eq. (3) were almost the same as <u>the results from those derived with</u> the method of Dalrymple et al. (1984). Additionally, it <u>is</u> appeared that KC performed best to predict C_D , better than Re and Ur, although the <u>results can be quite factors were</u> different in different groups of laboratory observations. Therefore, further studies are needed in a variety of laboratory experiments.

Building a bridge between the two reliable methods by Dean (1979) and Kobayashi et al. (1993) is helpful. Firstly, it is promising that In this way, the reduction of wave height is limited by two functions so experimental outliers can be distinguished. Also, emergent conditions and densities are very significant aspects to study the drag coefficient by vegetation. Besides, based on local wave height, the exponential damping factor k' can be obtained easily by MS Excel, while the damping factor α' needs professional numerical tools. Therefore, calculating α' by the calibrated k' is much easier than ealibrating α' directly by the well documented Eq. (3) which is the advantage of the new method in this study. This method for the drag coefficient has had been validated by a great amount of data under different laboratory conditions, however, the interaction between the vegetation and flow filed—field is complicated and laboratory errors may affect the result so verification and/or calibration are needed further for predicting the drag coefficient.

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