

Response to Anonymous Referee #2

I appreciate the authors' work on addressing my concerns. The paper is now much improved. However, the English writing is still poor. I would suggest the senior co-authors to play some efforts to refine/smooth the writing in a revised version. The authors used the symbol ":" very often to construct rather long sentences based on unclear logics, which however is very unfriendly to the readers. Beyond that, grammar errors as well as sloppy long sentences make the texts hard to follow. Some examples are listed below, but not limited to this. Further smoothed writing by an English native speaker would be suggested.

Reply: We thank the referee for the precious and accurate corrections and suggestions. We have included most of them in the text and we tried to further improve the English making it flowing better and paying particular attention to long sentences, which were substantially cut and revised. The new changes in the manuscript are in blue text (please see the marked-up version of the manuscript attached below).

Line 10, activities;

Reply: The error was corrected.

line 13, why is the ":" used here?;

Reply: We used a colon because our work stems from the previous consideration (the fact that it is important to better understand the role of the informative content). But in order to make the paragraph shorter, we replaced ":" with ".".

line 20, "consists in"- is on the effects of; line 21, "taking into account"-based on;

Reply: We rephrased the entire sentence.

line 22, "secondly"- second/moreover;

Reply: We changed the text as suggested, thank you.

line 25, "the 'output-averaging'...data-rich regions". Please rephrase;

Reply: The sentence, that was indeed too convoluted (we thank you for pointing it out) was rephrased and divided into two periods.

line 31, ways; line 61, "result"- be obtained; line 65, "for"- of; 126, delete "reported and";

Reply: We corrected/changed the text as suggested, thank you.

line 98, delete "for generalization purposes"; line

Reply: We would keep it, it explains why we use two models instead than one.

line 130, please specify how did you calculate the stream network density, is it by the ratio between the channel area and the catchment area?

Reply: Yes, we have now specified it.

lines 135-137, please rephrase;

Reply: The sentence was rephrased.

line 141, patterns;

Reply: We corrected it, thank you.

line 143, Table 1. Catchment characteristics used in the parameter regionalisation approaches;

Reply: We prefer to keep the caption as it is because just five of these descriptors are finally used in the MS-1 and MS-OA approaches.

line 151, “consists in”- consists of; line 155, based on the sub-catchment areas; line 158, “routine”- module, same for the follows; line 170, by dividing; line 175, Table 2 describes the physical basis and the value ranges of the calibrated parameters;

Reply: We corrected/changed the text as suggested, but putting at previous line 175: “presents the parameters to be calibrated and the corresponding ranges”.

line 202, “elevation layer”- elevation band;

Reply: This is the term used in the Valery et al 2014, so we’d prefer to keep it as named by the authors.

line 207, provide inputs for the GR6J;

Reply: We corrected/changed the text as suggested, thank you.

line 208, delete “accounting”; line 209, routing procedure of the module includes two flow components; line 212, fed by;

Reply: We corrected/changed the text as suggested, thank you.

lines 214-215, please rephrase;

Reply: The sentence was changed, removing some useless detail, thank you for pointing this out.

line 216, reports briefly, for the sake of brevity; line 218, and their value ranges;

Reply: We corrected/changed the text as suggested, thank you.

line 224, using the algorithm of Dynamically Dimensioned Search;

Reply: We amended the sentence.

line 230, is r the Pearson correlation coefficient or the linear correlation coefficient? Please have a double check;

Reply: Yes, it is the Pearson product-moment correlation coefficient

line 239, demonstrated how? line 280, demonstrating how?

Reply: We corrected them with “demonstrated that”, at both lines.

Line 249, “complete”- entire;

Reply: We corrected it, thank you.

Lines 282-285, please rephrase; lines 441-442, please rephrase that;

Reply: The sentences were rephrased.

line 287, 1:n; line 322, one of the main purposes; line 364, as mentioned above; line 382, obtained by calibrating; line 406, Results show that in all the four cases; line 475, delete “the”;

Reply: We corrected/changed the text as suggested, thank you.

line 420, is reduced;

Reply: We used “dampened” instead of reduced, for replacing smoothed

line 455, performance is lower in smaller catchments is of course a clear relation;

Reply: This is not exactly what we mean: we do not see a clear relation, but we just notice that if it happens that performance is not very good, it is in general for small catchments (but most of small catchments still behave well). For this reason we replaced the sentence with “even if for some of the smaller catchments the performances were suboptimal”

lines 476-479, please rephrase; lines 529-531, please rephrase;

Reply: We rephrased them.

line 483, 43% of that have;

Reply: We used just “43% have” since we have just above cited the set to which the percentage refers.

line 525, delete “as”;

Reply: We rephrased the sentence, to clarify it.

line 531, bottom panel;

Reply: We kept the plural since we refer to all the 4 bottom panels of figure 10

line 540, as already mentioned; line 573, increases with decreasing; line 574, but are evenly distributed over the country; line 584, consists of;

Reply: We corrected/changed the text as suggested, thank you.

line 570, it is also true with respect to the variability of:

Reply: We rephrased the sentence

line 595, delete “large”;

Reply: We’d prefer to keep it.

line 608, this also holds true; line 621, reduces from; line 629, impacts; line 631, effects of data-richness and informative content on the accuracy of various methods; line 634, “extendable” - transferable; line 664, structures; line 675, “closeness” - proximity; line 708, is more noticeable; line 712, as in Austria;

Reply: We corrected/changed the text as suggested, thank you.

lines 637-640, please rephrase;

Reply: The sentence was split and rephrased.

lines 646-653, please rephrase; lines 656-662, please rephrase;

Reply: We have rephrased these paragraphs.

lines 695-698, please rephrase;

Reply: The sentence was modified.

lines 715-720, please rephrase;

Reply: The sentences were split and modified.

1 **Importance of the informative content in the study area when regionalising rainfall-runoff** 2 **model parameters: the role of nested catchments and gauging station density**

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7

8 **Abstract.**

9 The setup of a rainfall-runoff model in a river section where no streamflow measurements are available for its calibration
10 is one of the key research [activities](#) for the Prediction in Ungauged Basins (PUB): in order to do so it is possible to estimate
11 the model parameters based on the hydrometric information available in the region. The informative content of the data
12 set (i.e. which and how many gauged river stations are available) plays an essential role in the assessment of the best
13 regionalisation [method](#). [This](#) study analyses how the performances of regionalisation approaches are influenced by the
14 “information richness” of the available regional data set, [i.e. the availability of potential donors, and in particular by the](#)
15 gauging density and by the presence of nested donor catchments, that are expected to be hydrologically very similar to
16 the target section.

17 The research is carried out over a densely gauged dataset covering the Austrian country, applying two rainfall-runoff
18 models and different regionalisation approaches.

19 The regionalisation techniques are first implemented using all the gauged basins in the dataset as potential donors, and
20 then re-applied decreasing the informative content of the data set. [The effect of excluding nested basins and the status of](#)
21 [“nestedness” is identified based on the position of the closing section along the river or the percentage of shared drainage](#)
22 [area. Moreover](#), the impact of reducing station density on regionalisation performance is analysed.

23 The results show that the predictive accuracy of parameter regionalisation techniques strongly depends on the informative
24 content of the dataset of available donor catchments. [The “output-averaging” approaches, which exploit the information](#)
25 [of more than one donor basin and preserve the correlation structure of the parameter, seem to be preferable for](#)
26 [regionalisation purposes in both data-poor and data-rich regions. Moreover, the use of an optimised set of catchment](#)
27 [descriptors as similarity measure, rather than the simple geographical distance, results to be more robust to the](#)
28 [deterioration of the informative content of the set of donors.](#)

29

30 **1 Introduction**

31 In the hydrological practice, it is often needed to gain information on ungauged river sections and one of the most
32 informative [ways](#) to do so is implementing a rainfall-runoff model, when, as it is often the case, the meteorological input
33 variables are retrievable in reference to its drainage area. [In such cases, however](#), the model parameters may not be
34 obtained through a calibration procedure and it is necessary to regionalise them, exploiting the information of
35 hydrologically similar catchments in the study area.

36 Regionalisation approaches for model parameterisation can be classified into two wide categories (He et al., 2011),
37 “regression-based” and “distance-based” methods:

38 1) **Regression-based methods define** relationships between each model parameter and geomorpho-climatic catchment
39 attributes (see e.g., Seibert 1999) and apply these relationships to estimate model parameters at ungauged sites.

40 2) Distance-based methods, **instead, identify** a set of similar **donor catchments** and transfer their calibrated parameters
41 to the ungauged (“target”) catchment. This type of approaches includes:

42 2-i) “output-averaging” methods which transfer the entire set of model parameters from donor catchments, thus
43 maintaining correlation among parameters (which run the model multiple times and average the simulations),

44 2-ii) “parameter-averaging” methods which derive each target parameter independently, as a function (generally a
45 weighted average) of the calibrated **donors**. To this class (distance-based group of the parameter-averaging type)
46 **also belong** the kriging methods, where the parameters are regionalised based on their spatial correlation and
47 independently from each other (Merz and Blöschl, 2004; Parajka et al., 2005).

48 In the last two decades, hydrologic scientists from all around the world have focused on the determination of the more
49 accurate regionalisation techniques for different case studies and rainfall-runoff models (see e.g., the reviews of Merz et
50 al. 2006, He et al. 2011, Peel & Blöschl 2011, Parajka et al. 2013, Hrachowitz et al. 2013, Razavi and Coulibaly 2013).

51 Synthesis of existing studies presented in Parajka et al. (2013) has shown that different groups of regionalisation
52 approaches have similar efficiency. **Still, the regionalisation performance is related to data availability and the number of**
53 **catchments used for the analysis. So, a very important aspect for choosing the most adequate regionalisation technique is**
54 **the informative content of the study region, i.e. how many gauged stations are available for inferring the hydrological**
55 **behaviour at the target, ungauged section.** In particular, in very densely gauged areas, spatial proximity is expected to be
56 a good similarity measure, as demonstrated **by** Merz and Blöschl (2004) and Parajka et al. (2005), who tested different
57 regionalisation approaches on a dense dataset of more than 300 watersheds across Austria. **Similar results are presented**
58 **in Oudin et al. (2008), who examined spatial proximity on a set of 913 French catchments without snow impact.** But
59 different outcomes may be obtained when the gauged stations are less dense and less interconnected (that is with less
60 availability of stations along the same river). **For example,** Samuel et al. (2011) regionalised the parameters of HBV
61 model for a sparsely gauged dataset (135 watersheds on the wide area of Ontario, Canada) and found that the best approach
62 for such study area was an inverse-distance parameter-averaging **of** a pre-selected set of physically similar catchments.

63
64 The availability in the data set of gauged river stations representative of hydrological conditions similar to the ungauged
65 ones plays an essential role in the assessment of the best regionalisation method. This availability can be, in some way,
66 estimated with the station density (i.e. number of stations per km²) and with the topological relationship between
67 catchments. In particular, the presence of several nested catchments (i.e. gauged river sections on the same river) in the
68 study region can strongly influence the performance of **some regionalisation** techniques. **If** for an ungauged basin model
69 parameter sets are available for down/upstream gauged river sections, **then** donor and target watersheds share part of their
70 drainage area, and thus they may also be hydrologically very similar. **Such similarity** may lead to very good
71 regionalisation performances for a given approach, **but may not represent the accuracy that** would be obtained in different
72 conditions. Therefore, regionalisation performances obtained for datasets with a high degree of “nestedness” may be not
73 transferrable to study regions poor of nested basins.

74

75 So far, very few studies [examined](#) the impact of the presence of nested catchments on the performances of parameter
76 regionalisation techniques. Merz and Blöschl (2004), Parajka et al. (2005) and Oudin et al. (2008) tested the effect of the
77 removal of nested catchments from the available donor catchments, but only for one or two regionalisation techniques,
78 without analysing in detail the differences between different types of approaches. Additionally, the [contribution](#) of the
79 immediate downstream and/or upstream gauged stations has never been compared [to that of the other nested catchments](#)
80 [that share](#) significant portions of drainage area with the ungauged one.

81
82 [Also](#), the influence of [gauging density on the regionalisation of rainfall-runoff model parameters](#) has been little explored,
83 with two notable exceptions. Oudin et al. (2008) applied the spatial proximity and physical similarity output-averaging
84 techniques for decreasing values of station density in France and Lebecherel et al. (2016) tested the robustness of the
85 spatial proximity output-averaging approach to an increasing sparse hydrometric network on the same study region. In
86 Austria, the effect of station density has been investigated by Parajka et al. (2015), but in reference to the interpolation of
87 streamflow time-series and not to the parameterisation of rainfall-runoff models.

88
89 The purpose of the present paper is to analyse the role of the informative content of the available regional data set, that is
90 which and how many gauged catchments are available to be used as donors for the regionalisation in a target, ungauged
91 section. This will be done comparing first the impact of the presence of nested donors and then the effect of the reduction
92 of station density on the performances of different parameter regionalisation techniques for a dataset of 209 catchments
93 across Austria.

94 The tested regionalisation approaches include a set of consolidated techniques, applied to two different continuous-
95 simulation daily rainfall-runoff models, for generalisation purposes: the first is the TUW model (semi-distributed version
96 of HBV, used by Parajka et al. 2005), and the second model, never used so far for regionalisation in the Austrian region,
97 is the GR6J model implemented with the Cemaneige snow routine (Coron et al., 2017b).

98 We believe that the present analysis may provide further insights for assessing the performances and selecting the
99 parameter regionalisation approaches most suitable to a specific study region, keeping into account the impact of data
100 availability, [and](#) in particular of [gauging density](#) [and](#) of the presence of nested catchments.

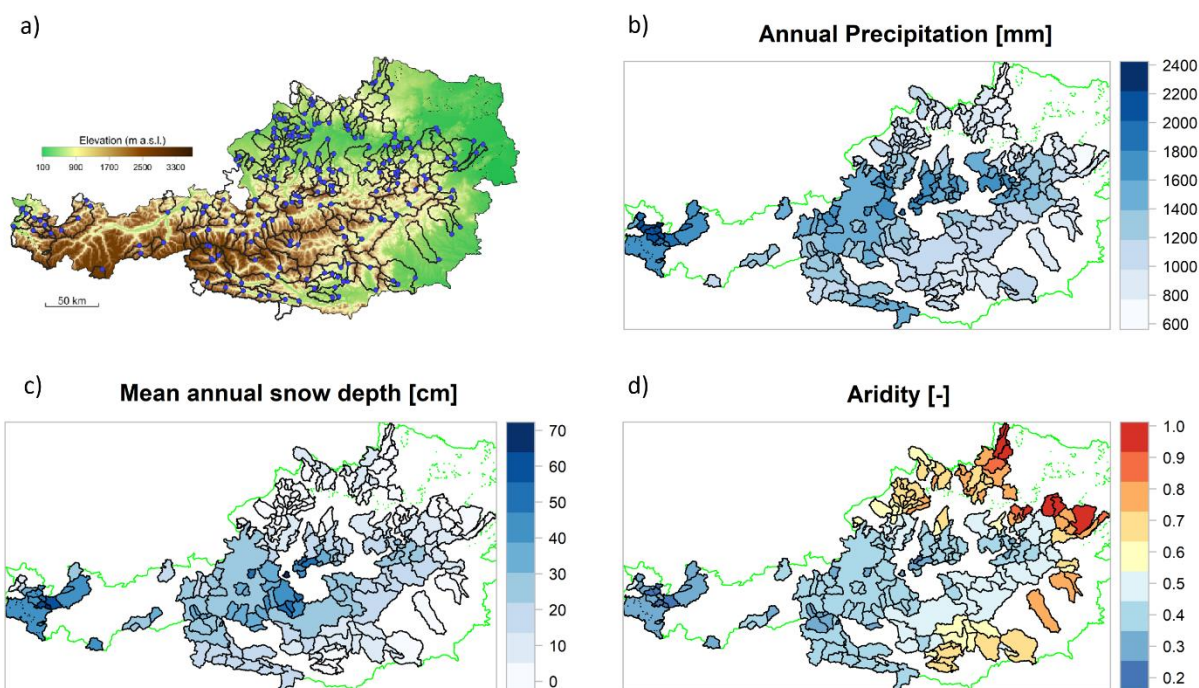
101 The paper is organised as follows: Section 2 introduces the case study and data. Section 3 first describes the rainfall-
102 runoff models, the tested regionalisation schemes and the methodology for assessing the impact of nested catchments and
103 station density. [The](#) results are presented in Section 4. Finally, Section 5 reports the discussion and conclusions.

104 **2 Study region and data**

105 The case study is composed [of](#) 209 catchments (see Figure 1, panel a) covering a large portion of Austria. Their size
106 varies considerably, mainly under 1000 km² (90% of the basins) and just [three](#) watersheds extend over more than 3000
107 km². The topography of the country varies significantly from the flat and hilly area in the north-east to the Alps in the
108 centre and the south-west, [and it is](#) particularly steep in the extreme west. The annual precipitation ranges from about 600
109 mm in the east, where the evaporation plays an important role in the water balance, to more than 2000 mm in the west,
110 mainly due to orographic lifting of north-westerly airflows at the rim of the Alps (Viglione et al., 2013). Land use is
111 mainly agricultural in the lowlands and forest in the medium elevation ranges. Alpine vegetation and rocks prevail in the
112 highest catchment (Parajka et al., 2005). The aridity index [varies](#) from 0.2 to 1, meaning that the watersheds are [mostly](#)
113 wet or weakly arid (annual evapotranspiration is never higher than precipitation).

114 Data have been provided by the Institute of Hydraulic Engineering and Water Resources Management (Vienna University
115 of Technology), which previously screened the runoff data for errors and removed all stations with significant
116 anthropogenic effects. Hydro-meteorological data include daily streamflow and daily inputs to the rainfall-runoff models
117 for the 33 years period 1976-2008: daily average precipitation, temperature and potential evapotranspiration defined for
118 200 meters elevation zones for all the study catchments. The potential evapotranspiration is estimated by a modified
119 Blaney-Criddle method (Parajka et al., 2003) using interpolated daily air temperature and grid maps of potential sunshine
120 duration (Mészáros et al., 2002).

121 To implement some of the parameter regionalisation approaches, we make use of several geo-morphoclimatic catchment
122 attributes, briefly described in Table 1. Topographic characteristics such as mean catchment elevation and mean slope are
123 derived from 1 x 1 km digital elevation model. Climatic characteristics such as mean annual precipitation, and aridity
124 index are derived from climate input time series. Figure 1 (panels b, c and d) shows the spatial pattern of mean annual
125 precipitation, snow depth and aridity index across the study area. Mean annual solar irradiance is computed through
126 GRASS GIS software (<http://grass.osgeo.org>). Stream network density was calculated from the digital river network map
127 at the 1:50000 scale for each catchment (Merz and Blöschl, 2004) as the ratio between the channel length and the
128 catchment area. FARL (flood attenuation by reservoir and lakes), boundaries of porous aquifers, areal portions of regional
129 soil types and main geological formation were the same used and described in detail in Parajka et al. (2005). Finally, Land
130 use coverage is derived from CORINE Land Cover maps updated to the year 2012 (<https://land.copernicus.eu/pan-european/corine-land-cover/clc-2012>).
131 For land cover classes, as well as for geology and soil type classes, each basin is
132 described by the portions of the total catchment area corresponding to each class. For this reason, the catchments are not
133 associated with one single attribute and Table 1 does not report the min/median/max values of such descriptors.
134



135
136 **Figure 1. Panel a) Study area; blue points refer to stream gauges and black lines to catchment boundaries. Panels b), c) and d)**
137 **Spatial patterns of some climatic catchment attributes across the study area.**

138

139

140 **Table 1. Available catchment attributes.**

Code	Unit	Min	Median	Max	Description
Elev	m a.s.l.	287	915	2964	Mean elevation
Area	km ²	14	168	6214	Drainage area
Slope	m/m	0.9	12.4	28.5	Mean slope
meanP	mm	675	1230	2310	Mean annual total precipitation
maxP	mm	35	49	84	Mean annual maximum daily precipitation
meanPET	mm	281	608	715	Mean annual total evapotranspiration
SnowF	-	0.06	0.17	0.60	Fraction of precipitation falling as snow (i.e. precipitation fallen in days below 0°)
SnowD	mm	1	14	68	Mean annual snow depth
Aridity	-	0.21	0.46	0.96	Aridity index (meanPET/meanP)
Irrad	kWh/(m ² *day)	1750	1899	2274	Mean annual solar irradiance
RiverD	m/km ²	0	830	1256	Stream network density
FARL	-	0.56	1	1	Flood attenuation index by reservoir and lakes
Corine	%	-	-	-	Portions of land use coverage
Geology	%	-	-	-	Portions of geological formations
Soils	%	-	-	-	Portions of regional soil types
Forest	-	0	0.47	0.93	Fraction of catchment covered in forest
AcqPort	-	0	0.01	0.83	Fraction of catchment with porous aquifers

141 **3 Materials and methods**

142 **3.1 Rainfall-runoff models structure and calibration**

143 Two models for simulating daily streamflow were applied in this study. This choice is made to analyse the effect of nested
 144 catchments and station density on the performance of parameter regionalisation methods for different model structures.

145 **3.1.1 TUV model**

146 The first is the TUV model, a semi-distributed version of the HBV model (Bergström 1976, Lindström et al., 1997)
 147 developed by Parajka and Viglione (2019). It consists of a snow module, a soil moisture module and a flow response and
 148 routing module. The model processes the elevation zones as autonomous entities that contribute separately to the total
 149 outlet flow. The inputs are daily air temperature, precipitation and potential evapotranspiration over the different elevation
 150 zones (Figure 2). Finally, the different outputs from the elevation zones are averaged based on the sub-catchment areas.
 151 The snow module is based on a simple degree-day concept, and it is ruled by five parameters: two threshold temperature
 152 parameters distinguishing rain and snow, T_r and T_s , a melting temperature T_m , a snow correction factor SCF and the
 153 degree-day factor DDF . The soil moisture module represents soil moisture state changes and runoff generation. It involves
 154 three parameters: the maximum soil moisture storage FC , a parameter representing the soil moisture state above which
 155 evapotranspiration is at its potential rate, LP , and a parameter β ruling the non-linear function of runoff generation. Finally,
 156 an upper and a lower soil reservoirs and a triangular transfer function compose the runoff response and routing module,
 157 involving seven additional parameters. The sum of excess rainfall and snowmelt enters the upper zone reservoir and
 158 leaves this reservoir through three paths: i) outflow from the reservoir based on a fast storage coefficient k_f ; ii) percolation
 159 to the lower zone with a constant percolation rate C_{PERC} , iii) if a threshold of the upper storage state L_{UZ} is exceeded,
 160 through an additional outlet based on a very fast storage coefficient k_o . Water leaves the lower zone based on a slow

161 storage coefficient k_2 . The outflows from both reservoirs are then routed by a triangular transfer function representing
 162 runoff routing in the streams, where the base of the transfer function, B_O , is estimated with the scaling of the outflow by
 163 the C_{ROUTE} and B_{MAX} parameters. More details about the model structure and application in R can be found in Parajka et
 164 al. (2007) and Ceola et al. (2015), respectively.

165 The model is run for all the study catchments with the semi-distributed model structure obtained by dividing them into
 166 200-meters elevation zones. While model daily inputs (precipitation, temperature and potential evapotranspiration) and
 167 model states are defined over such zones, model parameters are assumed to be the same for the entire catchment.

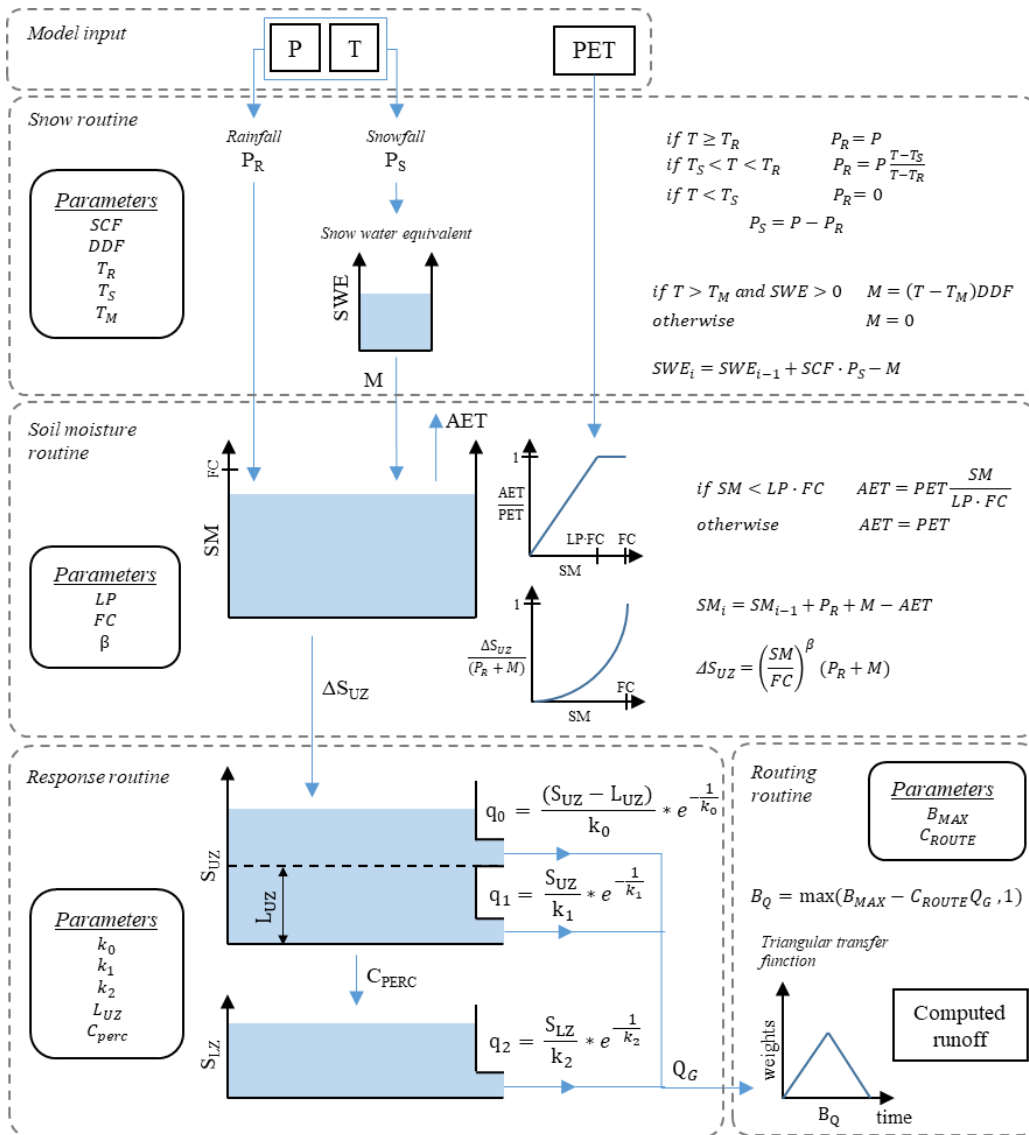
168 Following the work by Parajka et al. (2005) on the same study area, 4 out of the 15 total parameters are pre-set, and 11
 169 are calibrated: threshold temperatures T_r and T_s are fixed respectively to 2 and 0 °C, T_m to 0 °C and the maximum base
 170 of the transfer function at low flows B_{MAX} to 10 days. Table 2 presents the parameters to be calibrated and the
 171 corresponding ranges.

172

173 **Table 2. TUW model parameters and their ranges.**

Parameter	Units	Range	Description
SCF	-	0.9 - 1.5	Snow correction factor
DDF	mm/(°C*day)	0 - 5	Degree day factor
LP	-	0 - 1	Parameter related to the limit of evaporation
FC	mm	0 - 600	Field capacity, i.e., max soil moisture storage
β	-	0 - 20	Non linear parameter for runoff production
k_0	days	0 - 2	Storage coefficient for very fast response
k_1	days	2 - 30	Storage coefficient for fast response
k_2	days	30 - 250	Storage coefficient for slow response
L_{UZ}	mm	0 - 100	Threshold storage state, very fast response starts if exceeded
C_{PERC}	mm/day	0 - 8	Constant percolation rate
C_{ROUTE}	days ² /mm	0 - 50	Scaling parameter

174



175

176 **Figure 2. TUV model scheme – Lumped version.**

177

178 3.1.2 CemaNeige-GR6J model

179 The second model is the French CemaNeige-GR6J (Coron et al., 2017b). It is the combination of the CemaNeige snow
 180 accounting routine (Valéry et al., 2014) with the GR6J model (Pushpalatha et al., 2011), a daily lumped continuous
 181 rainfall-runoff model, developed at INRAE (Antony, France), by the Équipe Hydrologie des Bassins versants. The
 182 software is freely available in the *airGR* R-package (Coron et al., 2017a).

183 The inputs of the model are spatially-averaged catchment daily air temperature, precipitation and potential
 184 evapotranspiration. Catchment hypsometric curve is also required.

185 The CemaNeige snow accounting routine is based on a degree-day concept, where the thermal inertia of the snowpack is
 186 also taken into account. It involves two parameters, a snowmelt factor, θ_{G1} , and a cold-content factor, θ_{G2} . Although the
 187 module requires daily lumped inputs, for better simulating snow accumulation and melting it allows **dividing**
 188 the catchment into more elevation zones of equal area, through the use of the hypsometric curve. Inputs for each elevation
 189 zone are extracted through interpolation of the mean catchment values using precipitation and temperature gradients
 190 (Valéry et al., 2010), and not from “clipping” of the actual spatial fields like for the TUV elevation zones. The module

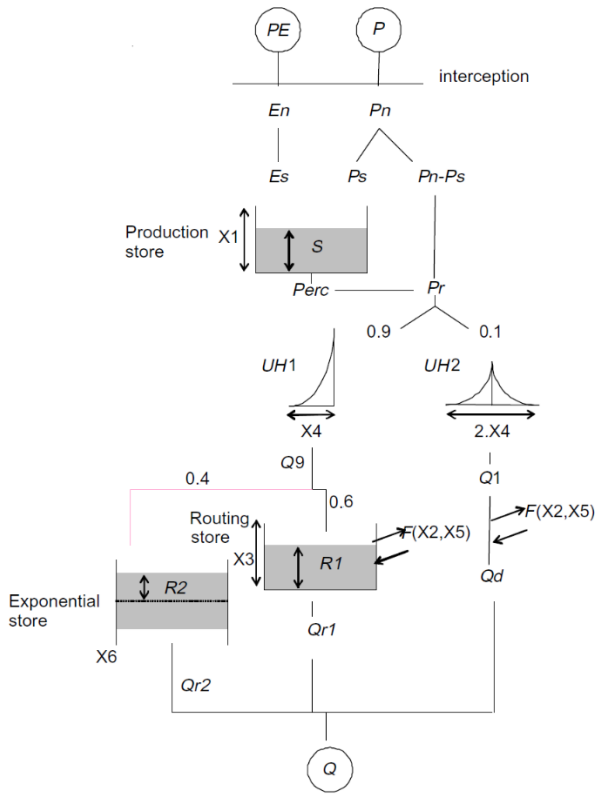
191 functions are applied with a lumped set of calibrated parameters. **Internal states are instead** allowed to vary over each
 192 elevation layer according to the different extrapolated inputs. On each elevation layer, two outputs are computed: rain
 193 and snowmelt, which are summed in order to find the total water quantity feeding the hydrological model. At every time
 194 step, the total liquid output of CemaNeige at **the** catchment scale is the average of every elevation zone outputs. Here we
 195 decide to maintain, as default, the number of elevation layers equal to five. For a detailed description of CemaNeige
 196 routines, the readers may refer to Valéry et al. (2014).

197 The total liquid output of CemaNeige module and potential evapotranspiration **provide** the inputs of the GR6J rainfall-
 198 runoff model. In the model, the water balance is controlled by a soil **moisture reservoir** and a conceptual groundwater
 199 exchange function. **The routing procedure of the module includes two flow components** routed by two unit hydrographs,
 200 a non-linear store and an exponential-store, with a total of six parameters. The structure of the model is represented in
 201 Figure 3, and a detailed description of the model routines is given in Pushpalatha et al. (2011).

202 The CemaNeige-GR6J model is fed **by** mean catchment daily precipitation, air temperature and potential
 203 evapotranspiration. All the **eight** parameters of the combined model (2 for CemaNeige, 6 for GR6J) are calibrated. Lower
 204 and upper bounds of the parameters space are kept as default (**note that the parameters are normalised in the calibration**
 205 **procedure**). Table 3 reports brief parameters description and boundaries. For the sake of **brevity**, we will refer to this
 206 model just with the acronym GR6J, even if it will always include the CemaNeige snow module.

207 **Table 3. CemaNeige-GR6J model parameters and their transformed real value ranges.**

Parameter	Units	Range	Description
θ_{G1}	mm/(°C*day)	0 - 109	Snowmelt (degree-day) factor
θ_{G2}	-	0 - 1	Cold content factor
X1	mm	0 - 21807	Non-linear production storage capacity
X2	mm/day	-1903 - 1903	Groundwater exchange coefficient
X3	mm	0 - 21807	Non-linear routing store capacity
X4	days	0 - 22	Time parameter for unit hydrographs routing
X5	-	0 - 1	Threshold parameter for water exchange with groundwater
X6	mm	0 - 21807	Exponential routing store capacity



208

209 **Figure 3. GR6J model scheme.**

210

211 3.1.3 Model calibration

212 The sets of parameters for both rainfall-runoff models are estimated for all the study catchments with an automatic model
 213 calibration procedure, using the Dynamically Dimensioned Search [algorithm \(DDS, Tolson et al. 2007\)](#).

214 The objective function to be maximised is the Kling-Gupta Efficiency (Gupta et al., 2009) between observed and
 215 simulated streamflow, defined as:

216

$$217 \quad KGE = 1 - \sqrt{(r - 1)^2 + (\alpha - 1)^2 + (\beta - 1)^2} \quad Eq. 1$$

218

219 where r is the Pearson product-moment correlation coefficient, α is the ratio between the standard deviations of the
 220 simulated and observed values and β is the ratio between the means of the simulated and observed values.

221 The 33 years of observation (1976-2008) are split into two sub-periods: the first one, from 1 November 1976 to 31 October
 222 1992, is used for model calibration, and the second one, from 1 November 1991 to 31 October 2008, for model validation.

223 Warm-up periods of one year are used in all cases. Calibration and validation performances for both models are reported
 224 in Section 4.1.

225 3.2 Regionalisation approaches

226 In order to assess the impact of the presence of nested catchments and station density on the performance of the parameter
 227 regionalisation methods, a set of consolidated approaches for the study area are implemented. Three types of techniques
 228 are tested. All belong to the distance-based group, since recent studies have demonstrated that they are generally to be

229 preferred to regression-based techniques (see e.g. Kokkonen et al. 2003, Merz and Blöschl 2004, Oudin et al. 2008, Reichl
230 et al. 2009, Bao et al. 2012, Steinschneider et al. 2015, Yang et al. 2018, Cislaghi et al. 2019).

231 3.2.1 Ordinary Kriging (KR)

232 The first is a parameter-averaging technique, based on an Ordinary Kriging approach (termed in the following KR), where
233 each model parameter is regionalised independently from each other, based on their spatial correlation. Catchment
234 position is defined by the coordinates of the catchment centroid and the Ordinary Kriging is based on an exponential
235 variogram with a nugget of 10% of the observed variance, a sill equal to the variance, and a range of 60 km both for TUW
236 and Cemaneige-GR6J model parameters.

237 3.2.2 Nearest Neighbour (1 donor, NN-1)

238 The second approach is the Nearest Neighbour method (NN-1), where the entire set of model parameters is transposed
239 from the geographically nearest donor catchment.

240 3.2.3 Most Similar (1 donor, MS-1)

241 In the third technique, termed “Most Similar” approach (MS-1), a single donor catchment is again identified, for
242 transposing the entire parameter set. Instead of choosing the catchment that is geographically the closest, the
243 “hydrologically most similar” donor is identified, based on a set of geomorphological and climatic descriptors. Five
244 descriptors are used for assessing such similarity: mean catchment elevation, long-term mean annual precipitation, stream
245 network density, land cover classes, geology classes. Such set of descriptors was selected by preliminary tests: since it is
246 not the focus of the work, the analysis for the assessment of the best catchment descriptors is reported in Appendix A.
247 The donor catchment is identified as the catchment with the smallest dissimilarity index ϕ (e.g. Burn and Boorman,
248 1993):

$$250 \quad \phi = \sum_{j=1}^5 \frac{d_j(D,U)}{\max(d_j)} \quad \text{Eq. 2}$$

251
252 which represents the sum of the differences d_j of the 5 descriptors of the donor catchment D and of the ungauged
253 catchment U , normalised by their maximum. For the attributes described by a single value (mean catchment elevation,
254 long-term mean annual precipitation and stream network density), d_j is expressed by the absolute difference between the
255 descriptors X_j^D and X_j^U of the donor and target catchments respectively (Eq. 3). For land cover and geology, whose
256 attributes X_j are the vectors containing the portions of the total catchment area $X_{j,c}$ corresponding to each class c , the
257 difference d_j is calculated as the Euclidean distance between such vectors (Eq. 4).

$$258 \quad d_j(D, U) = |X_j^D - X_j^U| \quad \text{Eq. 3}$$

$$261 \quad d_j(D, U) = \sqrt{\sum_c (X_{j,c}^D - X_{j,c}^U)^2} \quad \text{Eq. 4}$$

262

263 3.2.4 Output-averaging version of NN and MS techniques (NN-OA and MS-OA)

264 Nearest Neighbour (NN) and Most Similar (MS) approaches allow to maintain correlation among model parameters and
265 to overcome the well-known limitation of the regression approach due to interaction between them. In the regression-
266 based methods, as well as in the parameter-averaging approaches (e.g, KR technique), parameters are regionalised
267 independently from each other, possibly affecting simulation performances. On the other hand, one single donor
268 catchment (as in NN-1 and MS-1 approaches) is often not fully representative of the hydrological behaviour of the target
269 watershed. Recent studies have been demonstrating that averaging the outputs of the simulations (rather than model
270 parameters) obtained with different donor parameter sets may be preferred (see e.g., Oudin et al. 2008, Viviroli et al.
271 2009). For this reason, NN and MS techniques are also tested with an output-averaging approach (introduced by McIntyre
272 et al., 2005), in which n donor catchments are identified based on their spatial proximity (for the Nearest Neighbour
273 method) or on their similarity (for the Most Similar method) to the target. The regionalised streamflow for the ungauged
274 catchment is calculated from all the simulations $Q(d, P_i)$, obtained by running the model (fed by the meteorological input
275 of the target catchment) with each one of the n parameter sets (P_i , with i in $[1 : n]$) corresponding to each of the donor
276 catchments. Streamflow for day d , $Q(d)$, is computed as the weighted average of the simulated outputs:

$$277 \quad Q(d) = \sum_{i=1}^n w_i Q(d, P_i) \quad \text{Eq. 5}$$

278 where w_i is the weight associated with each donor catchment i , computed as a function of a measure of dissimilarity
281 between the donor and the target catchments. Such versions of the methods are here termed NN-OA and MS-OA. In the
282 NN-OA case, the dissimilarity is defined by the spatial distance D_i between the centroids of donor i and target catchments
283 (Eq. 6), while in the MS-OA method it corresponds to the dissimilarity index ϕ_i (see Eq. 2) and the corresponding weights
284 are computed accordingly to Eqs. 6 and 7, respectively.

$$285 \quad w_i = \frac{\frac{1}{D_i}}{\sum_{i=1}^n \frac{1}{D_i}} \quad \text{Eq. 6}$$

$$286 \quad w_i = \frac{\frac{1}{\phi_i}}{\sum_{i=1}^n \frac{1}{\phi_i}} \quad \text{Eq. 7}$$

290 3.2.5 Choice of the number of donor catchments for NN-OA and MS-OA

291 The choice of the number of donor catchments for output-averaging represents a central issue in the methodology.
292 Previous studies showed that the optimal number of donors is strongly related to the rainfall-runoff model and, of course,
293 to the case study. McIntyre et al. (2005) were amongst the first to apply an ensemble (output-averaging) approach and to
294 explore the use of different numbers of donors on the performance of the Probability Distribution Model (PDM, Moore,
295 1985) for a set of more than 100 UK catchments. They tested the impact of an increasing number of donors, either
296 selecting the first n catchments with the smallest dissimilarity measure or including all the donors with a value of
297 dissimilarity below a defined threshold (in the latter case, the number of donors may thus vary depending on the target-
298 donors attributes). They found that a fixed number of ten donors resulted in the best regionalisation performances. Oudin
299 et al. (2008) applied an output-averaging regionalisation for the TOPMO and GR4J models to a large French dataset of

300 almost 1000 basins, but with no weights in flow averaging, since they used an arithmetic average (thus not taking into
 301 account magnitude of donor dissimilarities). They found that the two models performed optimally with a different number
 302 of donor catchments (seven and four respectively) and the efficiency of the regionalised model decreased almost linearly
 303 when increasing the number of donors above such values. The higher is the number of donor basins included in the
 304 regionalisation process, the more dissimilar will be the donors for the target watershed, possibly leading to a deterioration
 305 of the results. The use of weights in flow averaging may indeed help to smooth this effect, giving less and less importance
 306 to the donors as their similarity decreases.

307 In the present work, the effect on regionalisation performances due to the number of donor basins is explored in detail,
 308 applying NN-OA and MS-OA for increasing number n of donor catchments, as discussed in Section 4.2.

309

310 3.3 Impact of nested catchments: which catchments should be considered (to be) nested?

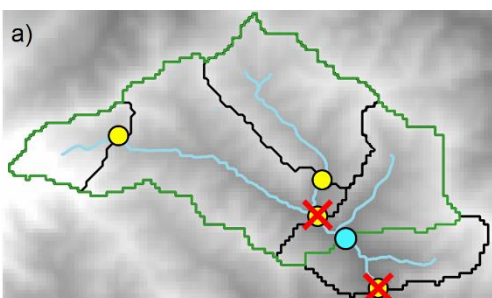
311 As already introduced, one of the main purposes of the present analysis is to quantify the impact of the presence of several
 312 nested catchments on the regionalisation techniques. In particular, since nested catchments may have a strong hydrological
 313 similarity with the ungauged one, they are expected to play an essential role in the determination of method performances.
 314 Once the performances have been evaluated using all the study catchments as potential donors, the regionalisation
 315 procedures are repeated for each target basin (assumed to be ungauged) by excluding, from the donors set, the watersheds
 316 which are considered to be nested in relation to the target section.

317 In general, two or more catchments are nested between each other if their closure sections are located on the same river,
 318 i.e. they share part of their drainage area. Since several gauged stations can be located on the same river, we propose to
 319 follow two different criteria to identify the nested basins:

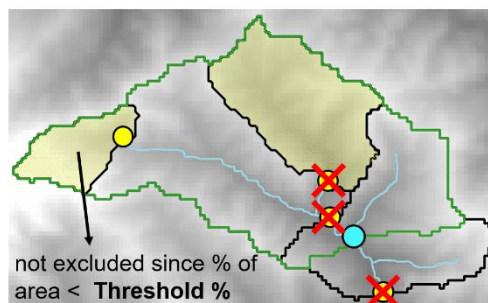
- 320 - *Criterion 1*: the gauged sections that are immediately downstream and upstream of the target section (Figure 4,
 321 panel a)).
- 322 - *Criterion 2*: all the catchments sharing a given percentage of drainage area with the ungauged one (Figure 4,
 323 panel b)).

324

Criterion 1



Criterion 2



- 325 ● ungauged catchment ● potential donor ✗ nested donor to be excluded

325

326 **Figure 4. Criteria for excluding nested catchments when regionalising model parameters.**

327

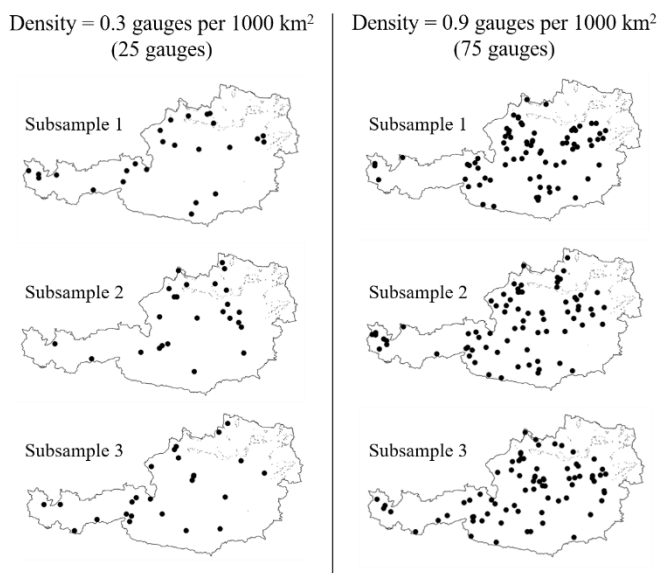
328 3.4 Impact of station density

329 Another way to evaluate the performances of regionalisation methods taking into account the richness in hydrometric
330 information of the study area is to analyse the spatial density of the potential donors.

331 It is expected that the effect of the presence of several nested watersheds in a dataset is related to the effect due to station
332 density. Because of that, the further purpose of the study is to analyse the impact of station density on regionalisation
333 accuracy. Parajka et al. (2015) tested the impact of the station density for the direct weighted interpolation of daily runoff
334 time-series with the topological-kriging (or Top-kriging) approach (see Skøien et al., 2006), and found that direct
335 interpolation is superior to hydrological model regionalisation if station density exceeds 2 stations per 1000 km². Here,
336 the same approach for analysing the density is applied to all the parameters regionalisation techniques.

337 The full station density in the dataset is about 2.4 gauges per 1000 km², estimated dividing the total number of stations
338 by the area of Austrian territory, which is approximately 84000 km². All the applied regionalisation approaches are tested
339 for decreasing station density in the catchments dataset. Seven different values of station density (ranging from 0.3 to 2.1
340 gauges per 1000 km²) are tested, which correspond to a total number of stations between 25 and 175. For each value of
341 station density, the corresponding number of gauged stations is randomly sampled (simple automatic non-supervised
342 sampling) from the original set of 209 catchments, and the regionalisation approaches are applied on this subsample
343 (catchments input dataset) in leave-one-out cross-validation. In turn, each of the catchment in the subsample is considered
344 to be ungauged, and the remaining basins are used as potential donors. This operation is repeated 100 times to consider
345 different samples of watersheds with the same density across the study area. Figure 5 shows an example of three samples
346 for two different station densities, corresponding to 25 and 100 stations in the input dataset.

347



348

349 **Figure 5. Example of three samples for two different station densities.**

350

351 3.5 Evaluation of model performances

352 As mentioned above, the rainfall-runoff models are calibrated against Kling-Gupta Efficiency (Eq. 1). In addition to KGE,
353 model performances are evaluated through Nash-Sutcliffe Efficiency (Eq. 8) as well. While KGE considers different types

354 of model errors (the error in the mean, the variability and the dynamics of runoff), NSE is a standardised version of the
 355 mean square error.

356

$$357 \quad NSE = 1 - \frac{\sum(Q_{sim} - Q_{obs})^2}{\sum(Q_{obs} - \overline{Q_{obs}})^2} \quad Eq. 8$$

358

359 where Q_{sim} is the simulated runoff, Q_{obs} is the observed runoff and $\overline{Q_{obs}}$ is the average observed runoff.
 360 The regionalisation approaches are tested through leave-one-out cross-validation for all the described analyses. The
 361 parameter sets of the donor catchments are obtained through a calibration procedure over the years 1977-1992. **In contrast,**
 362 for assessing the performances of the regionalisation methods, only the results obtained over the validation period (1992-
 363 2008) are reported. Spatiotemporal transfer of model parameters is, therefore, the most exacting task (as confirmed by
 364 the study of Patil et al. 2015) since we are using parameters obtained over different catchments (in regionalisation) and
 365 over a different observation period. On the other hand, this is exactly what would happen in a real-world forecasting
 366 application or for assessing the impact of a climate change scenario, where you have to identify the parametrisation of a
 367 model to be used for independent hydro-climatic conditions and in any possible river section in the region.

368 4 Results and discussion

369 4.1 Model performances “at-site”

370 Table 4 shows the model performances obtained by calibrating the models “at-site”, that is over the streamflow measured
 371 in each catchment during the calibration period (1977-1992) and validated over the years 1992-2008 (no regionalisation
 372 procedure is involved).

373 Both rainfall-runoff models behave well for the study area. While the median Kling-Gupta efficiencies are 0.85 for TUV
 374 and 0.88 for GR6J model in the calibration period, they deteriorate to 0.76 and 0.81 in the validation period, respectively.
 375 In the calibration period, KGE is always above 0.66 (TUV) and 0.76 (GRJ6). In contrast, the KGE is over 0.72 for both
 376 models for 75% of the basins (even if it drops below 0.3 for one and two basins, respectively for GR6J and TUV) in the
 377 validation period.

378 Looking at Nash-Sutcliffe efficiency, the difference between the two models is even more marked than for the KGE. **It is**
 379 **interesting that despite the lower number of parameters GR6J model tends to perform better than TUV.**

380

381 **Table 4. At-site performances: values of the 25% (1st quart.), 50% (med.) and 75% (3rd quart.) quantiles for Kling-Gupta**
 382 **(KGE) and Nash-Sutcliffe (NSE) efficiencies.**

		KGE [-]			NSE [-]		
		1st quart.	med.	3rd quart.	1st quart.	med.	3rd quart.
TUV	Calibration 1977 - 1992	0.82	0.85	0.90	0.65	0.72	0.80
	Validation 1992 - 2008	0.72	0.76	0.82	0.59	0.66	0.72
GR6J	Calibration 1977 - 1992	0.86	0.88	0.91	0.72	0.77	0.81
	Validation 1992 - 2008	0.75	0.81	0.84	0.67	0.74	0.79

383

384 4.2 Regionalisation performances using all catchments as potential donors

385 4.2.1 Choice of the donors for the *output-averaging* regionalisation methods

386 Before comparing performances of regionalisation methods, it is necessary to choose the optimal settings for the output-
387 averaging versions of Nearest Neighbour (NN-OA) and Most Similar (MS-OA) techniques.

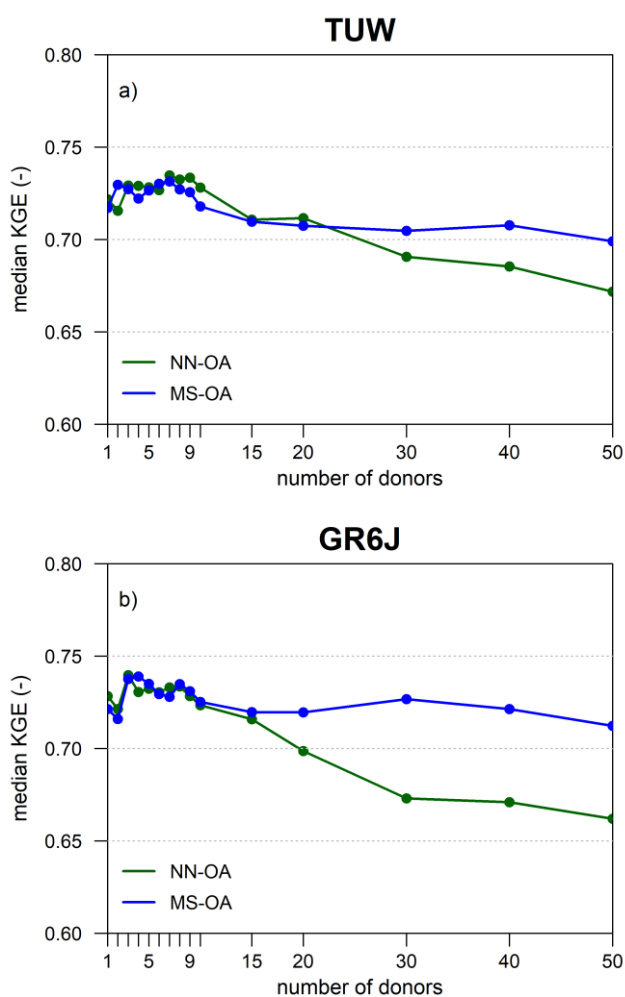
388 As introduced in the methodology Section 3.2.5, we first investigate the effect of using different numbers of donors: in
389 particular, values between 1 and 50 are tested for both regionalisation techniques.

390 Regionalisation methods are repeated through leave-one-out cross-validation for each number of donors n and the median
391 Kling-Gupta efficiency obtained for each value of n over all the 209 catchments is computed. Tests are performed for
392 calibration and validation periods, but results are reported only for the validation period.

393 Figure 6 shows the median Kling-Gupta efficiency when the changing number of donors for TUW (upper panel) and
394 GR6J (lower panel). Looking at the figures, [results show](#) that in all the four cases, the index always deteriorates when
395 more than 10 donors are chosen. On the other hand, there is not a unique optimal number of donors for the two models
396 nor for the two regionalisation techniques. The optimal number of donors identified according to the median of the KGE
397 varies between 3 and 7 depending both on the rainfall-runoff model (TUW or GRJ6) and on the regionalisation approach
398 (NN-OA or MS-OA). Since the KGE differences between 3 and 7 donors are small (around 0.02), we decided to use 3
399 donors for both regionalisation methods and both models, which is also the most parsimonious option. [The choice](#) of a
400 low number of donors is convenient also in view of the analysis to be done on decreasing density, where a large number
401 of donors would imply the use of catchments that are less and less similar to the target one.

402 It may be noted that the results by Oudin et al. (2008) highlighted a clearer pattern of model performances when increasing
403 the number of donors, with a stronger decrease in efficiency when using high numbers of donors. This result may be
404 explained by the fact that they were using a simple not-weighted average of outputs. Here instead, the influence of the
405 additional donors is gradually poorer, due to the weights implemented in the output-averaging procedure (Eq. 5). When
406 adding further donors to the approaches, the corresponding weights in the average are gradually lower according to the
407 increasing distance (for NN-OA) or dissimilarity index (for MS-OA) from the target. Thus, the impact of the less similar
408 catchments is [dampened](#), compared to what may be achieved using a not-weighted output average.

409



410

411 **Figure 6. Impact of the number of donors on output-averaging Nearest Neighbour (NN-OA) and Most Similar (MS-OA)**
 412 **regionalisation methods for TUW (panel a) and GR6J (panel b) model.**

413

414 4.2.2 Performances of the regionalisation methods

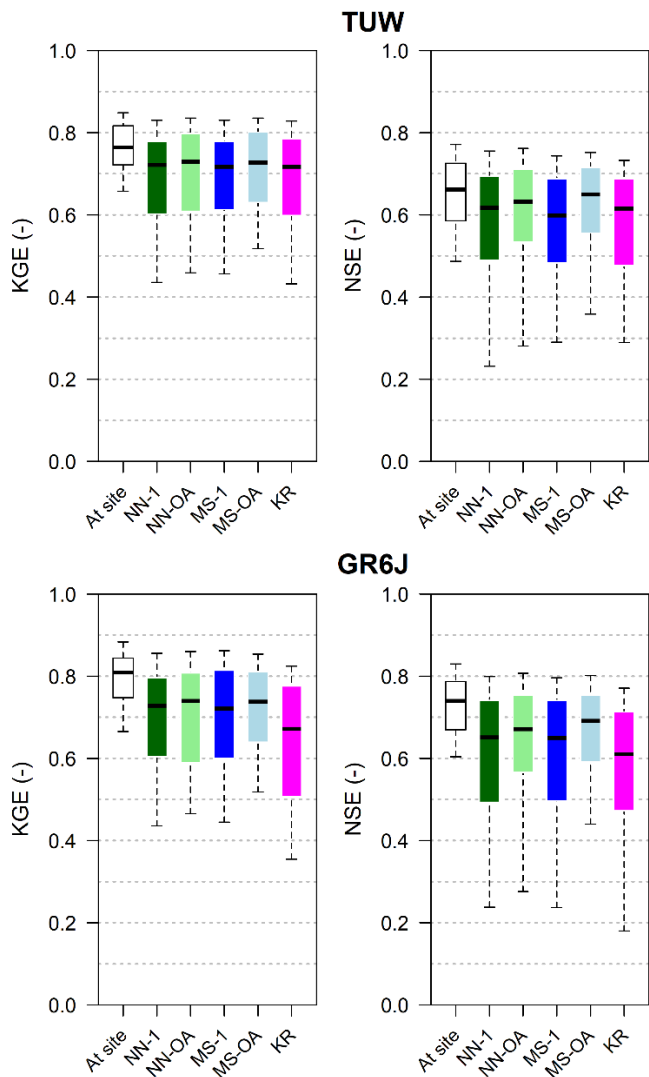
415 This section shows the performances of the regionalisation methods without excluding any candidate donor. [The above](#)
 416 [described regionalisation methods](#) are tested over all the 209 study catchments through leave-one-out cross validation,
 417 for both models. Here all the basins in the dataset are used as potential donors. [In turn](#), each basin is considered to be
 418 ungauged, and all the remaining (208) catchments are available in the donors set for testing the regionalisation approaches.
 419 Figure 7 reports Kling-Gupta and Nash-Sutcliffe efficiency boxplots for the two models when regionalising following
 420 each of the techniques.

421 For TUW (Figure 7, upper panels), all regionalisation methods provided good simulations [concerning the validation](#)
 422 [model](#) performances obtained when the models have been calibrated on the target section (at-site simulations, white
 423 boxes). [The loss in model efficiency is, overall, small](#). The Nash-Sutcliff efficiencies of KR, MS-1 and NN-1 methods
 424 are consistent with the findings of Parajka et al. (2005), who computed only the NS. [Their](#) results are very similar to the
 425 present ones, even if they worked on a greater number of Austrian catchments and calibrating the model against a different
 426 objective function.

427 For the GR6J model (Figure 7, lower panels), the efficiencies of the Nearest Neighbour (NN-1 and NN-OA) and Most
428 Similar (MS-1 and MS-OA) regionalisations are closer to those of the TUW in respect to what happened when the models
429 are calibrated at-site. In fact, with respect to the corresponding at-site calibration, the performances in the ungauged case
430 (that is when parameters are regionalised) suffer a larger deterioration for GR6J than for TUW. In addition, we notice
431 that, for GR6J model, the Ordinary Kriging has performances always poorer than all the other regionalisation methods.
432

433 For both rainfall-runoff models MS-OA tends to provide the best results and, in general, the two methods based on output
434 average (NN-OA and MS-OA), that exploit the information from more than one donor, outperform NN-1 and MS-1, in
435 particular in terms of Nash-Sutcliffe efficiency. It confirms the usefulness of regionalising based on more than one donor,
436 as indicated by previous studies (e.g. McIntyre et al. 2005, Oudin et al. 2008, Viviroli et al. 2009, Zelelew and Alfredsen
437 2014).

438
439 To verify if there is an influence of the catchment area on the results, due to the lumped structure of the model, an
440 additional analysis (not shown here for the sake of brevity), showed that despite the different drainage areas of the
441 catchments in the dataset regionalisation accuracies do not show a clear relation with the size of the watershed, even if
442 for some of the smaller catchments the performances were suboptimal. This result is consistent with previous evidence
443 from the literature (see, e.g. Parajka et al 2013).
444



445

446 **Figure 7. Original performances of the regionalisation methods for TUV (upper panels) and GR6J model (lower panels) for**
 447 **the 209 Austrian catchments in the validation period 1992-2008. Boxes extend to 25% and 75% quantiles while whiskers refer**
 448 **to 10% and 90% quantiles.**

449

450 4.3 Impact of nested donors: performance losses in regionalisation

451 4.3.1 Catchments identified as nested by the two criteria

452 As introduced in Section 3.3, two different criteria are implemented for identifying which donor catchments are
 453 considered to be nested concerning a target catchment: *Criterion 1* (Figure 4, panel a)) assumes that the only nested donors
 454 are the first downstream and the first upstream gauged sections. Following this approach, 81% of the catchments in the
 455 dataset have at least one downstream or upstream nested donor (red dots in Figure 8, panel a)).

456 Instead, *Criterion 2* (Figure 4, panel b)) excludes all the potential donors sharing a given percentage of drainage area with
 457 the target catchment. It requires the definition of a percentage threshold value of shared drainage area. A preliminary
 458 sensitivity analysis (not reported here) was performed, investigating the effect of different values between 5% and 20%
 459 for such percentage. Results show that differences in terms of regionalisation performance are not significant, and the
 460 threshold was fixed to 10%. The choice of the threshold influences the number of catchments which can be included in
 461 the study: in fact, the higher is the threshold, the lower is the number of basins classified as nested following *Criterion 2*.

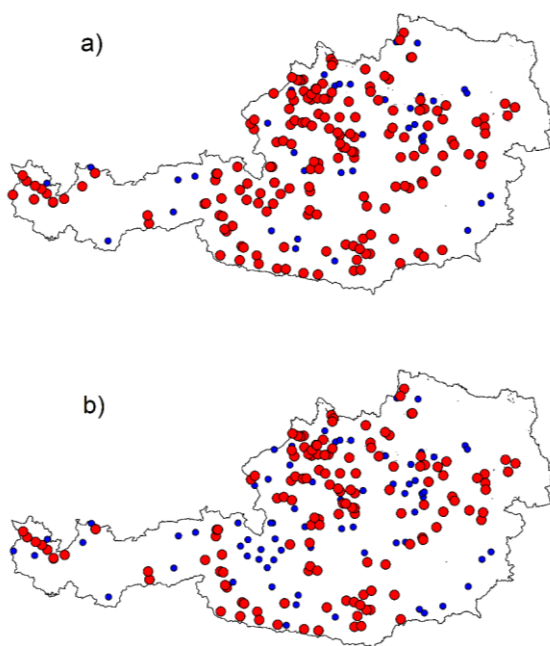
462 Using 10% as a threshold allows to include most of the watersheds in the analysis: 65% (137 catchments) of the basins
463 have at least one nested donor catchment sharing at least the 10% of its area (red dots in Figure 8, panel b)).

464 All the watersheds having potential nested donors according to the second criterion have nested gauged catchments also
465 according to the first criterion, but not vice versa. The impact of nested catchments on regionalisation performances is
466 therefore evaluated only for those 137 catchments that have at least one nested catchment according to both criteria.

467 It is important to highlight that the remaining 35% of the basins are still used as potential donor catchments. The
468 regionalisation approaches are not repeated using such basins as targets (since they have no nested donors, their
469 performance would not change and they would distort the results).

470 Among the 137 catchments considered for the analysis of the nestedness, 43% have only downstream nested donor(s),
471 28% only upstream nested donor(s), and 29% at least one upstream and one downstream nested donors.

472



473

474 **Figure 8. Panel a) Red dots (170) refer to catchments with at least one upstream or downstream nested gauged catchment**
475 **(Criterion 1). Panel b) Red dots (137) refer to catchments with at least one nested gauged catchment sharing more than 10%**
476 **of the drainage area (Criterion 2).**

477

478 4.3.2 Performance losses in regionalisation when excluding nested donors

479 The regionalisation methods are applied again in leave-one-out cross-validation, but excluding from the available donors
480 the catchments which are nested in relation to the target (ungauged) basin. This approach is done for both “nestedness
481 criteria” (down/upstream or overlapping of drainage area) and the analysis applies exclusively to the 137 catchments
482 classified as nested according to both of them (red dots in Figure 8, panel b)). The figures of this section (Figures 9 and
483 10) therefore refer to such subset.

484

485 Figure 9 compares the different performances (Kling-Gupta and Nash-Sutcliffe efficiencies in the upper and lower panels
486 respectively) obtained in regionalisation (always over the validation period), when nested catchments are available or not

487 as candidate donor basins for both TUW model (Figure 9, upper panels) and GR6J (Figure 9, lower panels). Each group
488 of boxplots refers to a different regionalisation method: within such groups, the first box indicates the performance when
489 no basins are excluded from the donor set, while the second and the third boxes report the performances due to the
490 exclusion of the nested donors following Criterion 1 or 2 respectively.

491

492 The performance deterioration is highlighted by bar plots in Figure 10, showing the mean loss in Kling-Gupta and Nash-
493 Sutcliffe efficiencies when excluding nested donors following the two criteria.

494

495 Finally, Table 5 reports the interquartile variability of Kling-Gupta and Nash-Sutcliffe efficiencies for both models and
496 all the regionalisation approaches when nested donors are excluded or not.

497

498 [The less affected](#) method is the Ordinary Kriging, especially for the TUW model. [It is because the Ordinary Kriging](#) is
499 not based on the identification of one or more “sibling” donors which may have been excluded if nested. On the other
500 hand, it should also be highlighted that such a method is the regionalisation approach that performs worst when nested
501 basins are available.

502

503 As expected, for both TUW and GR6J, NN-1 is always the most heavily affected method (dark green bars in bottom
504 panels of Figure 10). [This is likely because](#) the nearest donor is a nested one in more than 80% of the catchments for both
505 criteria and its exclusion seriously compromise the performance.

506

507 Excluding the nested catchments [also](#) has a strong impact on MS-1 (dark blue bars in bottom panels of Figure 10), even
508 if to a lesser extent than for NN-1, since for more than 60% of the catchments the most similar donor is a nested one
509 according to both criteria.

510

511 The degradation of performance moving from Criterion 1 (upstream/downstream) to Criterion 2 (overlapping drainage
512 area) highlighted in [Figure 9 demonstrates that considering as donors not only the immediate downstream or upstream](#)
513 [gauged river sections \(Criterion 1\), but also all the catchments partially sharing their drainage area with the target one](#)
514 [\(Criterion 2\), has a strong positive influence on the regionalisation performance.](#)

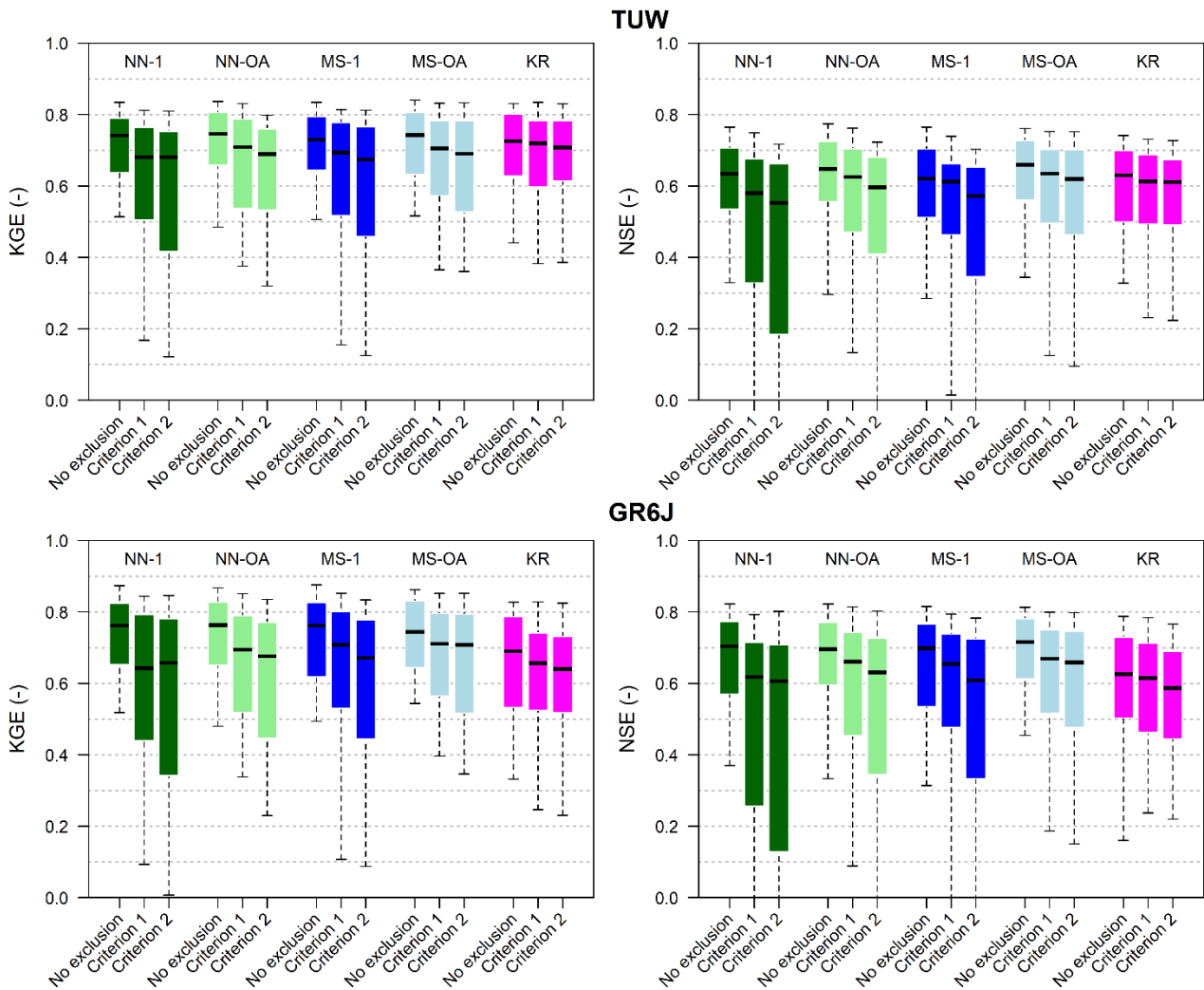
515

516 [Furthermore, the use of output-averaging for both Nearest Neighbour and Most Similar approaches \(NN-OA and MS-](#)
517 [OA\) not only outperforms the NN-1 and MS-1 when using all \(nested and non-nested\) donors \(see also Section 4.2.2\),](#)
518 [but it also improves the robustness of the methods when the nested donors are excluded.](#) The bottom panels of Figure 10
519 show that the loss in the efficiencies of NN-OA and MS-OA are always smaller than those corresponding to the single
520 donor approaches (NN-1 and MS-1), for both rainfall-runoff models and regionalisation methods. This confirms that the
521 use of output-averaging and the use of more than one donor basin is preferable for regionalisation purposes also for
522 regions that do not have so many nested catchments as the Austrian study area.

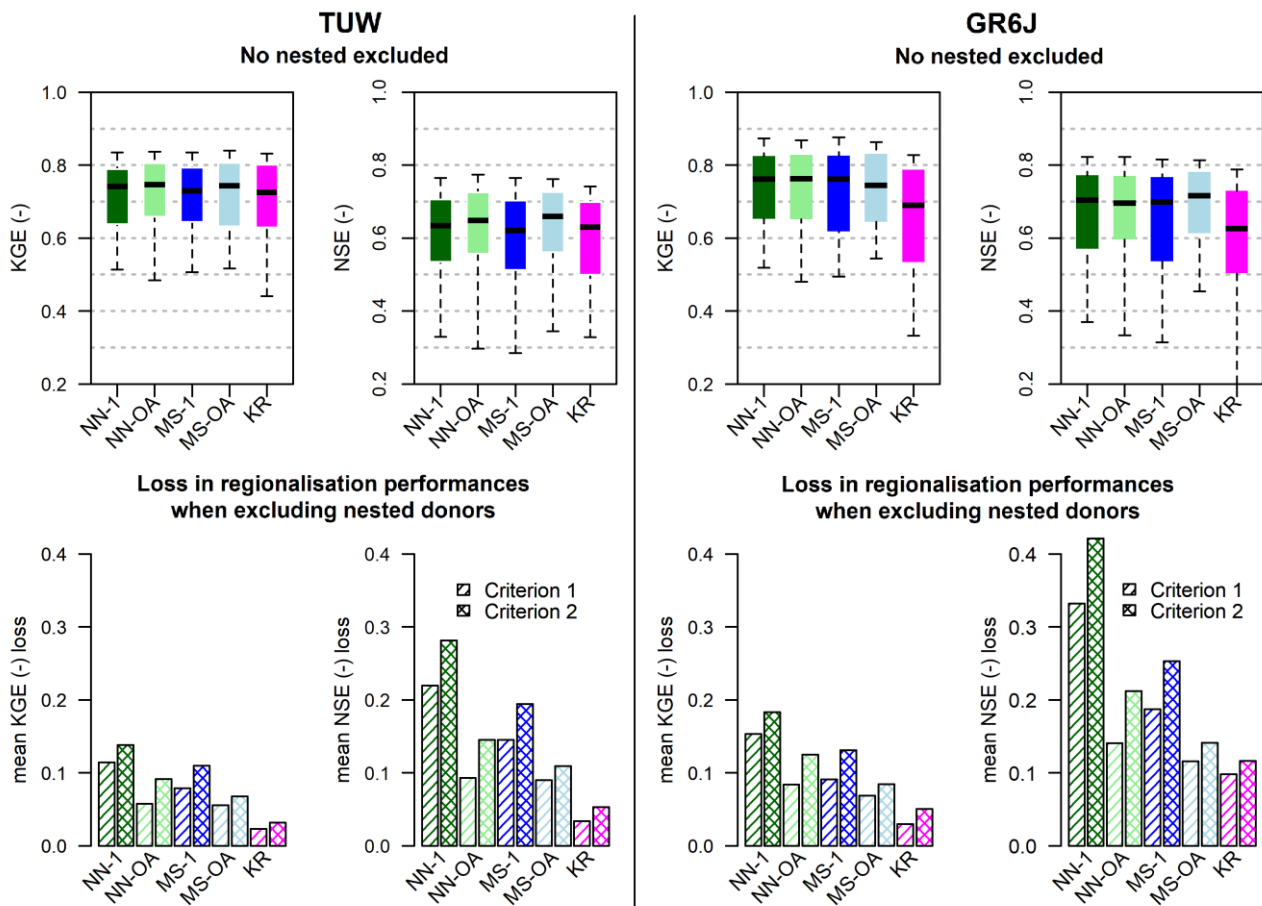
523

524 Finally, the values reported in Table 5 (as well as Figure 10) show how, especially for NSE, the losses resulting when
525 excluding nested donors from the regionalisation are higher for the GR6J model than for the TUW. [The GR6J](#) seems to
526 be slightly more affected by the presence of nested basins, except for MS-1 and MS-OA whose performances remain

527 more similar to those of TUW. It may be due to the different structure and parameter transferability of the models, which
 528 would indeed deserve a dedicated study.
 529



530
 531 **Figure 9.** Effect of the exclusion of nested catchments for the subset of 137 watersheds classified as nested: Kling-Gupta (left
 532 panels) and Nash-Sutcliffe (right panels) efficiencies when regionalising the TUW (upper panels) and GR6J (lower panels)
 533 models. “No exclusion”: all the donors are available. “Criterion 1” or “Criterion 2”: nested catchments are excluded from
 534 donor set. Box colours refer to the different methods: green is Nearest Neighbour (1 donor is dark green and three is light
 535 green), blue is Most Similar (1 donor is dark blue and three is light blue) and magenta is Ordinary Kriging. Boxes extend to
 536 25% and 75% quantiles while whiskers refer to 10% and 90% quantiles.



537

538 **Figure 10. Kling-Gupta and Nash-Sutcliffe efficiencies and mean losses in the same methods resulting when excluding the**
 539 **nested donors with Criterion 1 and 2 (bottom panels) for TUW and GR6J models.**

540

541 **Table 5. Inter-quartile values of Kling-Gupta and Nash-Sutcliffe efficiencies when regionalising TUW and GR6J models**
 542 **excluding or not excluding nested donor catchments.**

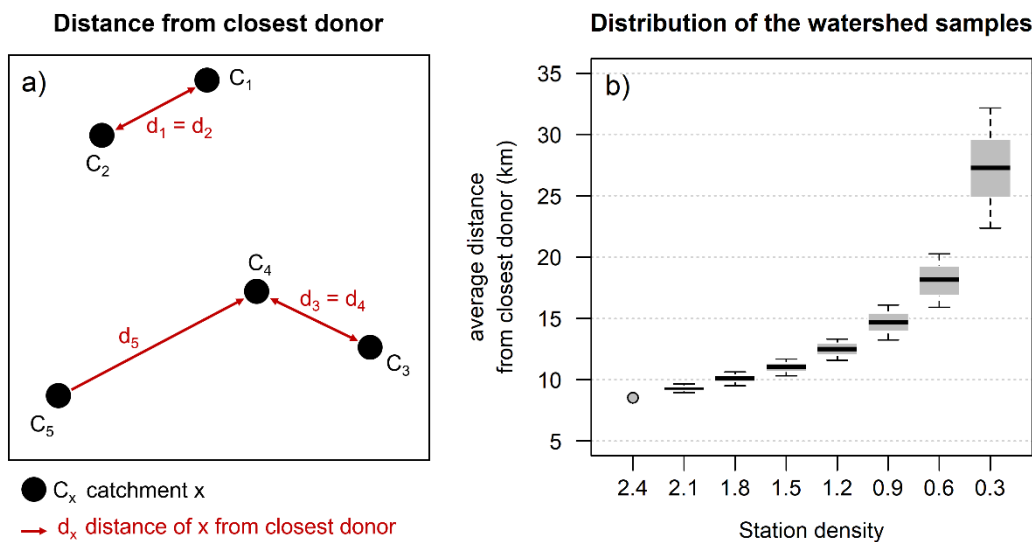
		Inter-quartile KGE [-]				
		NN-1	NN-OA	MS-1	MS-OA	KR
TUW	No nested excluded	0.64/0.79	0.66/0.81	0.64/0.79	0.63/0.81	0.63/0.80
	Criterion 1	0.50/0.76	0.54/0.79	0.52/0.78	0.57/0.78	0.60/0.78
	Criterion 2	0.42/0.75	0.53/0.76	0.46/0.77	0.53/0.78	0.61/0.78
GR6J	No nested excluded	0.65/0.82	0.65/0.83	0.62/0.83	0.64/0.83	0.53/0.79
	Criterion 1	0.44/0.79	0.52/0.79	0.53/0.80	0.56/0.80	0.52/0.74
	Criterion 2	0.34/0.78	0.45/0.77	0.44/0.78	0.52/0.79	0.52/0.73
		Inter-quartile NSE [-]				
		NN-1	NN-OA	MS-1	MS-OA	KR
TUW	No nested excluded	0.53/0.71	0.56/0.73	0.51/0.70	0.56/0.73	0.50/0.70
	Criterion 1	0.33/0.68	0.47/0.70	0.46/0.66	0.50/0.70	0.49/0.69
	Criterion 2	0.18/0.66	0.41/0.68	0.35/0.65	0.46/0.70	0.49/0.67
GR6J	No nested excluded	0.57/0.77	0.60/0.77	0.54/0.77	0.61/0.78	0.50/0.73
	Criterion 1	0.26/0.71	0.45/0.74	0.48/0.74	0.52/0.75	0.46/0.71
	Criterion 2	0.13/0.71	0.34/0.73	0.33/0.72	0.48/0.75	0.45/0.69

543 **4.4 Impact of station density: performance losses in regionalisation**

544 The last results concern the analysis of the impact of station density on regionalisation performances. As introduced in
 545 Section 3.4, for each of the seven assigned density values, the described procedure provides 100 different sets of
 546 regionalised target catchments. For a given density, each of 100 subsamples is formed by the same number of target
 547 catchments, resulting in the same number of efficiencies to be analysed.

548 First, it is important to verify that catchment samples are evenly distributed across the country: to do so we consider the
 549 distance of each catchment from its closer potential donor as shown in panel a) of Figure 11. The average of the distances
 550 (d_1, d_2, d_3, d_4, d_5) of each catchment from the closest catchment (i.e. a potential donor) in a sample can be considered as
 551 a measure of the sample spatial distribution: the higher the distance, the less dense the sample. As above said, for each
 552 density, 100 different samples are generated, so that for each density, we have 100 different values for such averages.
 553 Panel b) of Figure 11 shows the average “distance within sample” of the closest available donor catchment across the 100
 554 generated sub-sets for the different values of station density (each boxplot refers to the 100 values of average distance
 555 calculated for each sub-set). The average distance from the closest donor in the original, full density dataset (grey point
 556 in the figure) is around 8.5 km. As expected, the median target/donor distance (middle black solid line in each box)
 557 increases with decreasing density. It may be noticed that also the variability of the distance, as shown by box size and
 558 whiskers, gradually increases with the reduction of station density. Still, such increase is overall modest: even for the
 559 lowest density, it is limited to +/- 18% of the median for the 80% of the samples. The fact that, on average, the distance
 560 between a target catchment and the closest gauged catchment consistently increases with decreasing density proves that
 561 the samples with lower density do not tend to cluster/concentrate the catchments in a small region, but they are evenly
 562 distributed over the country.

563



564 **Figure 11. Panel a) Example of distance from the closest donor. Panel b) Boxplots of the average distance within a sample from**
 565 **the nearest available potential donor catchment across the 100 generated sub-sets, for different values of station density**
 566 **(gauges/1000km²). Whiskers extend to 10th and 90th percentiles. The grey point indicates the average distance from the closest**
 567 **donor in the original dataset.**

569 To analyse the results, the median regionalisation performances of each subsample are computed and presented here:
 570 thus, for each gauging density, the results consist of 100 values of median performances.

572 For the sake of brevity, only the median Kling-Gupta efficiencies over the validation periods are reported. They are shown
573 in Figure 12 for both TUW and GR6J models: each plot contains the boxplots of the median Kling-Gupta efficiencies for
574 each station density (i.e. number of gauges per 1000 km²), i.e. each boxplot presents the 100 values of median Kling-
575 Gupta efficiencies obtained applying the regionalisation approaches to the 100 subsamples generated with an assigned
576 density. The coloured point and the dotted line in the plots indicate the “original” (and maximum) median regionalisation
577 efficiency of the approaches, that is the one obtained when using all available donors (i.e. full station density,
578 corresponding to 2.4 gauges/1000 km²).

579

580 The NN-1 method (Figure 12, panels a) and f)) is the most affected by the decreasing density. In fact, when the density
581 declines, there is a higher probability that the less dense subsamples do not include the catchment that is the nearest one
582 to each target river section. And, as we have seen in the analyses on the nested donors, in the large majority of the cases,
583 the nearest catchment is a nested one. In contrast, the second best may be substantially different from the target basin.

584 Also, the output-averaging version of the Nearest Neighbour methods (Figure 12, panels b) and g)) strongly deteriorates
585 for less dense networks. In general, Nearest Neighbour methods are highly sensitive to gauging density. Geographical
586 distance results to be a good similarity measure only for densely gauged study areas (like Austria), since they firmly rely
587 on the presence of gauged catchments in the immediate surroundings that are also hydrologically very similar. If the
588 density decreases, the closest donor may be relatively far from the target, and it may therefore have little in common with
589 it.

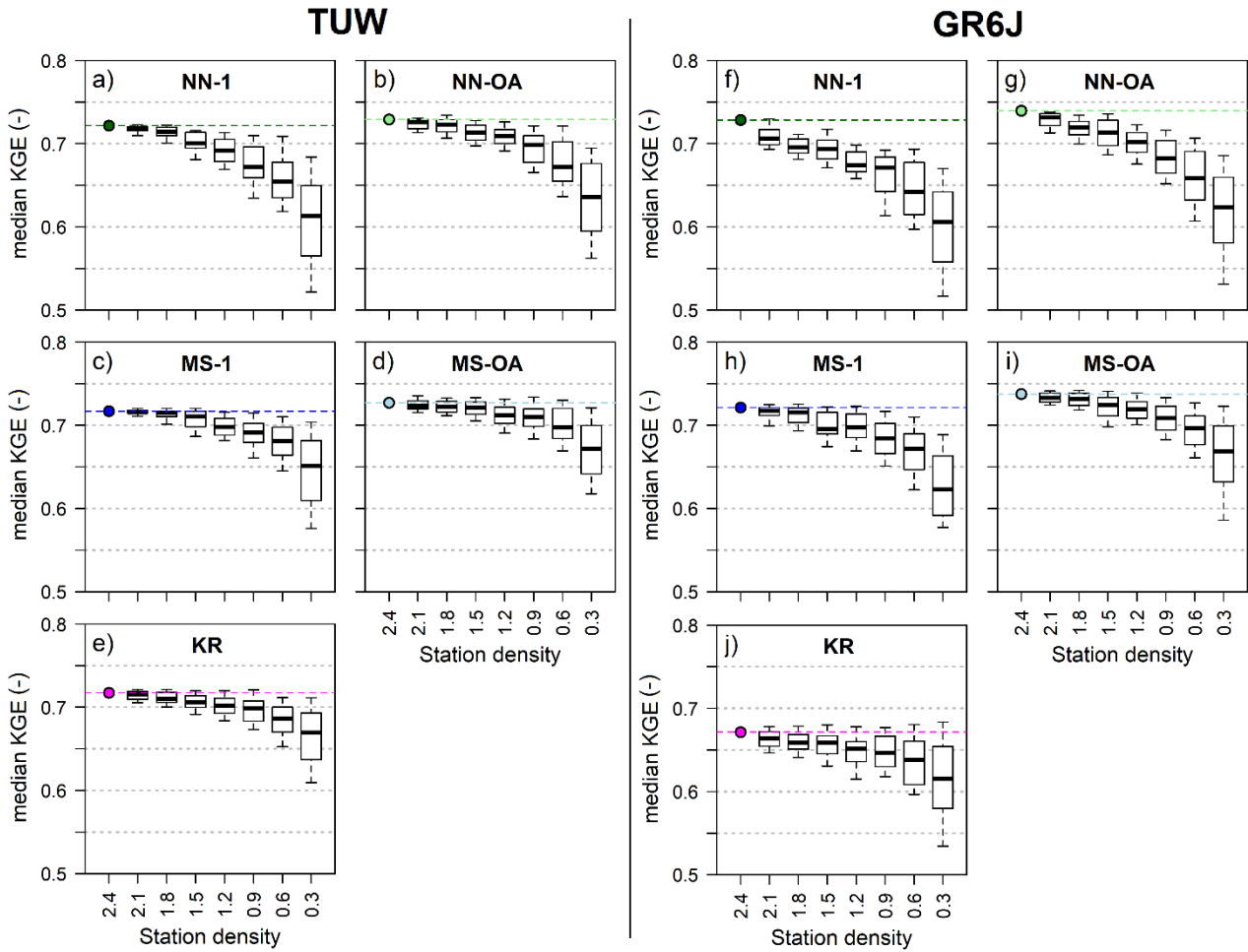
590 As far as the MS-1 (Figure 12, panels c) and h)) is concerned, its performances degrade more gracefully (except for the
591 GR6J model for the minimum density) than the NN-1 or the NN-OA. Also in this case (like for the NN-1), when the
592 density decreases it becomes less probable that the most hydrologically similar catchment (identified by MS-1 in full
593 density) is still part of the subsample. The results also indicate that there is more than one catchment in the original data
594 set that is similar enough to the target in terms of catchment attributes.

595 This also holds true for the output-averaging MS (Figure 12, panels d) and i)), which is even less affected by a reduction
596 in donors’ density and is the best-performing approach for any density (for both rainfall-runoff models).

597 We may note that, also in this analysis, analogously to what resulted for the exclusion of nested catchments, for both
598 approaches (NN and MS), the implementation of output-averaging allows to reduce the degradation in the performances
599 in comparison to the corresponding 1-donor version.

600 The impact of station density is similar to that of excluding nested catchments also for the Ordinary Kriging approach
601 (Figure 12, panels e) and j)), which deteriorates less than the other methods for decreasing values of station density. For
602 the TUW model, the Kriging regionalisation, starting from an already high KGE in full density, results in performances
603 that are inferior only to those of MS-OA when the density goes below 0.9. For the GR6J model, even if the deterioration
604 is limited since KR was poorly performing for the full density regionalisation (Figure 7), the median KGE is always worse
605 than those of all the other regionalisation approaches, for all the station densities.

606 Overall, all methods (excluding the poorly performing NN-1 and KR for the GR6J) result in relatively good performances
607 provided that the station density is at least 0.9 gauges per 1000 km². On the other hand, leaving aside the Kriging method,
608 the median KGE drops very steeply when the density reduces from 0.6 to 0.3 gauges per 1000 km².



609

610 **Figure 12. Median Kling-Gupta efficiency of the 100 sampled datasets for varying station density (number of gauges per 1000**
 611 **km²) for the TUW and GR6J models using NN-1 (panels a) and f)), NN-OA (panels b) and g)), MS-1 (panels c) and h)), MS-**
 612 **OA (panels d) and i)) and KR (panels e) and j)) regionalisation methods. The coloured point and dotted line in the plots indicate**
 613 **the original median regionalisation efficiency of the approaches when using all available donors (i.e. full station density,**
 614 **corresponding to 2.4 gauges/1000 km²).**

615 **5 Conclusions**

616 An assessment of the impacts of the presence of nested catchments and station density on the performance of parameter
 617 regionalisation techniques in a large Austrian dataset has been performed. The main motivation for this work lies in the
 618 lack of systematic studies in the literature about the effects of data-richness and informative content on the accuracy of
 619 various methods for transferring rainfall-runoff model parameters to ungauged catchments. Studies conducted on different
 620 study sets often do not lead to the same ranking of the tested approaches and the obtained results are not transferable
 621 to different study regions. This finding is indeed due to the diverse topological relationships between catchments
 622 (nestedness) in the datasets and the diverse density of the streamgauges.

623

624 The purpose of the work is to give support to the choice of the most appropriate parameter regionalisation approaches
 625 based on the available hydrometric information in the region. The study shows and quantifies how the informative content
 626 of the available gauged sections, here expressed by the presence of several nested catchments in a dataset or by the
 627 gauging density of the study region, can influence the predictive power of a certain technique.

628

629 The research has been conducted for a very densely gauged dataset covering a large portion of [Austria](#). Two rainfall-
630 runoff models for simulating daily streamflow have been calibrated for the 209 study watersheds: a semi-distributed
631 version of the HBV model (TUW model), and the lumped GR6J model coupled with the Cemaneige snow routine.

632

633 Both models perform very well when applied in the at-site mode, where the calibration and validation performances are
634 very good for both rainfall-runoff models. The selected model efficiencies are somewhat larger for the GR6J model,
635 which demonstrates to perform very well also in this Alpine dataset.

636

637 In order to assess the model performance when used in ungauged basins, the streamgauge data for every section was, in
638 turn, considered not to be available, and five regionalisation approaches were implemented for using the rainfall-runoff
639 models in the validation period. This is indeed an exacting task because we are attempting to use the model over an
640 ungauged catchment and for an observation period different from the one used for parameterising the gauged donor
641 catchments. The first regionalisation approach is an Ordinary Kriging approach (KR), which separately interpolates each
642 of the model parameter based on their spatial correlation in the study area. Two regionalisation approaches that select one
643 single donor catchment and transpose its parameter set to the target basin have also been tested: in the first (NN-1) the
644 geographically nearest catchment is selected, while in the second approach (MS-1) the single donor is the most similar
645 one in terms of a set of physiographic and climatic attributes. The latter two approaches are implemented also in the
646 output-averaging (OA) version, where the parameter sets of more than one donor are used for the simulation on the target
647 section and the model outputs are then averaged accordingly to the distance/dissimilarity between donors and target.

648 In regionalisation mode, the performances of the GR6J model deteriorates more than those of the TUW model, in
649 comparison with the “gauged”, at-site parameterisation. Reasons for this behaviour may lie in the different model
650 structures and in the different transferability of model parameters (depending also on their meaning and their relation with
651 the available catchment attributes). Such issue would deserve further attention and investigation but it would need a
652 separate ad-hoc analysis, since the comparison of the structures and physical meaning of the parameters of the two models
653 is not the specific objective of our work. For both rainfall-runoff models, the use of the output-averaging approach
654 outperforms the use of a single donor (NN-OA and MS-OA performed better than NN-1 and MS-1), confirming the
655 outcomes of other studies on the importance of exploiting the information available from more than only one donor (see
656 e.g., McIntyre et al. 2005, Oudin et al. 2008, Viviroli et al. 2009, Zelelew and Alfredsen 2014). The output-averaging
657 methods also outperform the parameter-averaging Kriging method (especially for the GR6J model), showing that it is
658 preferable transferring the entire parameter set of each donor, thus maintaining the correlation between the parameter
659 values. The results of the MS-OA are close but tend to be better than those of the NN-OA, indicating that hydrological
660 similarity is more important than geographical proximity for choosing the donors.

661 We expect that spatial proximity alone may be even less representative of hydrological similarity in a drier climate: Patil
662 et al. (2012) and Li and Zhang (2017) have shown that in dry runoff-dominated regions, nearby catchments tend to exhibit
663 less hydrological similarity than in more humid regions.

664

665 The impact of the richness of the data set (i.e. the informative content of the region) was then analysed to assess the
666 deterioration of the regionalisation approaches for decreasing availability and “worth” of the available donors, starting
667 from the influence of using nested basins as donors.

668

669 Two criteria have been proposed for identifying a basin that is nested with the target one. The first one, already used in
670 the few analysis of nestedness in the literature, classifies as nested the first upstream and the first downstream gauges on
671 the river network. The second, novel criterion, identifies as nested all the catchments that share more than a given
672 percentage (here chosen as 10%) of the drainage area with the target one. It results that the first criterion identifies a larger
673 number of nested catchments with at least one potential donor. The first criterion considers as nested also a number of
674 catchments that share less than 10% of area with the target one: this means that, in some cases, the first downstream or
675 upstream gauge may be not representative of the same drainage area and their catchments may be governed by very
676 different hydrological processes.

677

678 All the regionalisation approaches have been repeated by excluding from the donor set the catchments assumed to be
679 nested with each target basin, according to each one of the two criteria.

680 For both rainfall-runoff models and all the regionalisation approaches, when excluding all the basins that share a
681 significant portion of the same watershed (second criterion), the regionalisation procedure deteriorates more than when
682 excluding the only first up/downstream river sections: in fact, such first up/downstream catchment may, in some cases,
683 not have much in common with the target one.

684 Looking at the two rainfall-models, when excluding the nested catchments, the regionalisation performances tend to
685 deteriorates more for the GR6J than for the TUV: this seems to indicate that the TUV model may be more robust for
686 regionalisation purposes, even when nested donors are not available.

687 Comparing the different regionalisation approaches, the parameter-averaging Kriging is the method that is less impacted
688 by the exclusion of the nested donors, since it does not depend only on the choice of one or few “sibling” donors, that are
689 very often the nested ones, but it takes into account some of the donors in a given radius. This is consistent to the outcomes
690 of Merz and Blöschl (2004) and Parajka et al. (2005) who observed almost no deterioration of regionalisation
691 performances when excluding the first down and upstream nested donors using the same Ordinary Kriging approach.
692 When using, instead, a method transferring the entire parameter set from one or more donor catchments, the deterioration
693 is more noticeable. The method that experiences the worst deterioration is the NN-1, since in 80% of the cases, the nearest
694 basin is a nested one, and it is thus excluded from the potential donors. The second worst is the MS-1, that, when free to
695 choose any single potential donor in the entire region, would choose a nested one in 60% of the cases. The output-
696 averaging methods degrade less severely, showing that exploiting the information resulting from more than one donor
697 increases the robustness of the approach also in regions that do not have so many nested catchments as in Austria (where
698 the importance of nested donors in regionalising model parameters is highlighted also by Merz and Blöschl, 2004).

699

700 Finally, an assessment of the impact of station density on the regionalisation has also been implemented. The Nearest
701 Neighbour approaches (both NN-1 and NN-OA) are the methods that suffer more from the decrease in gauging density.
702 In contrast the Most Similar methods (MS-1 and MS-OA), which use as similarity measure a set of catchment descriptors,
703 are more capable of adapting to less dense datasets. In fact, in a more “sparse” monitoring network, the Most Similar
704 methods are able to find other adequate donors, that may be anywhere in the region. On the other hand, the Nearest
705 Neighbour techniques, when applied in low station density networks, risk to identify a “not so near” donor that may be
706 very different from the target one. The impact of decreasing station density on the performance of the output-averaging
707 approach based on spatial proximity (NN-OA) is in line with what observed by Lebecherel et al. (2016). The performances
708 of both the output-averaging methods, in agreement with the results obtained for similar methods by Oudin et al. (2008),
709 strongly deteriorate when the station density drops below 0.6 gauges per 1000 km².

710

711 The study confirms how the predictive accuracy of parameter regionalisation techniques strongly depends on the
712 informative content of the dataset of available donor catchments, quantifying the contribution of nested catchments and
713 station density for different approaches and rainfall-runoff models. The outcomes obtained for the Austrian data set
714 indicate that the reliability and robustness of the regionalisation of rainfall-runoff model parameters can be improved by
715 making use of output-averaging approaches, that use more than one donor basin but preserving the correlation structure
716 of the parameter set. Such approaches result to be preferable for regionalisation purposes in both data-poor and data-rich
717 regions, as demonstrated by the analyses on the degradation of the performances resulting from either removing the nested
718 donor catchments or decreasing the gauging station density.

719

720 *Code/Data availability.* The analyses have been developed within the R free software environment (R Core Team, 2018):
721 the scripts are available upon request from the first author. Discharge and precipitation station data are available at
722 <https://ehyd.gv.at/> (service provided by the Austrian ministry), while air temperature data has to be requested from the
723 Austrian meteorological service (ZAMG, Zentralanstalt für Meteorologie und Geodynamik).

724

725 *Author contribution.* ET conceived the conceptual idea; MN and ET developed the framework of the study; JP provided
726 the dataset; MN calculated land cover and irradiation attributes; MN performed all the analytic calculations and the
727 numerical simulations and prepared the graphical outputs; MN and ET analysed and interpreted the findings; JP
728 contributed to the critical interpretation of the results, sharing his deep knowledge about the dataset and the TUW model;
729 MN and ET wrote the manuscript in consultation with JP.

730

731 *Competing interests.* The authors declare that they have no conflict of interest.

732

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854

855 **Appendix A: Choice of best catchment descriptors**

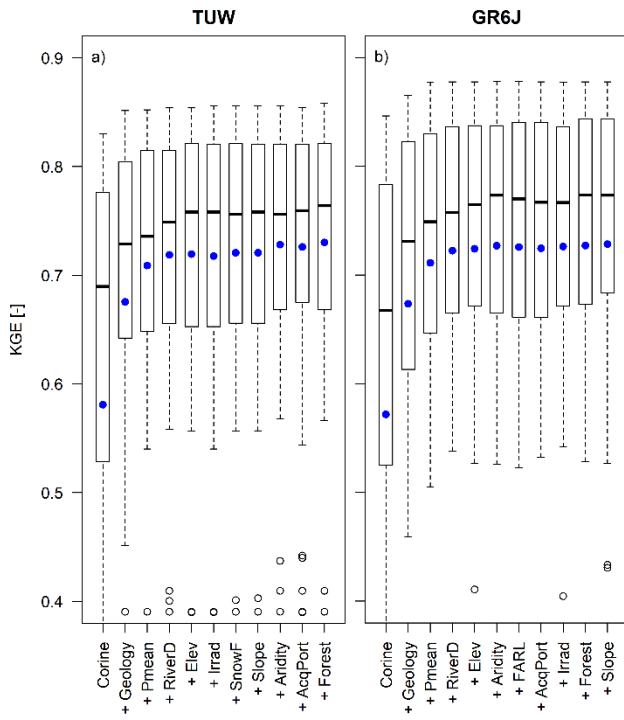
856 The implementation of the Most Similar approach requires the choice of the geo-morphologic and climatic attributes to
857 be used for selecting the donor catchment(s), i.e. to calculate the dissimilarity indices of equation 2.

858 This similarity study is part of a preliminary analysis carried out through a regionalisation experiment using the whole
859 period of available daily data (from 1976 to 2008, again with 1 year of warm-up) for calibrating the rainfall-runoff models.

860 In order to individuate the best catchment descriptors (all reported in Table 1 with a brief description), the Most Similar
861 approach with one single donor catchment (MS-1) is applied sequentially to the entire dataset in leave-one-out cross-
862 validation, using at each step an increasing number of attributes when defining the dissimilarity index ϕ . At each step,
863 the method is tested multiple times, adding one by one each of the attributes and the one which gives the best
864 regionalisation performances is selected. For greater clarity, Figure A1 (panel a) refers to TUW and panel b) to GR6J)
865 shows the boxplots of the consecutive best combinations of descriptors: at the first step, only one attribute is used, the
866 Most Similar approach is tested for all the available catchment features, and the similarity in the land cover classes
867 (Corine) gave the best efficiency. At the second step, the operation is repeated using land cover and each of the remaining
868 attributes one at a time, finding the geology classes to be the best attribute to add, and so on. The analysis stops when the
869 performances are decreasing or stop improving.

870 As can be inferred from Figure A1, both rainfall-runoff models reach good regionalisation performances when using up
871 to 5 attributes. Since the first best 5 attributes are the same for both models and from the sixth step the performances are
872 not substantially improved, we decide to choose those five descriptors to characterise catchment similarity: land use
873 classes, geological classes, mean annual precipitation, stream network density and mean elevation.

874



875

876 **Figure A1. Kling-Gupta efficiencies for TUW (panel a) and GR6J (panel b) models for the consecutive steps of the similarity**
 877 **analysis. Boxes refer to 25% and 75% quantiles, whiskers refer to 10% and 90% quantiles and the blue points to the average.**