Evaluating a land surface model at a water-limited site: implications for land surface contributions to droughts and heatwaves

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Abstract. Land surface models underpin coupled climate model projections of droughts and heatwaves. However, the lack of simultaneous observations of individual components of evapotranspiration, concurrent with root-zone soil moisture, has limited previous model evaluations. Here, we use a comprehensive set of observations from a water-limited site in southeastern Australia including both evapotranspiration and soil moisture to 4.5 m depth to evaluate the Community Atmosphere-Biosphere Land Exchange (CABLE) land surface model. We demonstrated that alternative process representations within CABLE had the capacity to improve simulated evapotranspiration, but not necessarily soil moisture dynamics - highlighting problems of model evaluations against water fluxes alone. Our best simulation was achieved by resolving a soil evaporation bias; a more realistic initialisation of the groundwater aquifer state; higher vertical soil resolution informed by observed soil properties; and further calibrating soil hydraulic conductivity. Despite these improvements, the role of the empirical soil moisture stress function in simulated water fluxes remained important: using a site calibrated function reduced the median level of water stress by 36 % during drought and 23 % at other times. These changes in CABLE not only improve the seasonal cycle of evapotranspiration, but also affect the latent and sensible heat fluxes during droughts and heatwaves. Alternative parameterisations led to differences of ~150 W m$^{-2}$ in the simulated latent heat flux during a heatwave, implying a strong impact of parameterisations on the capacity for evaporative cooling and feedbacks to the boundary layer (when coupled). Overall, our results highlight the opportunity to advance the capability of land surface models to capture water cycle processes, particularly during meteorological extremes, when sufficient observations of both evapotranspiration fluxes and soil moisture profiles are available.

1 Introduction

Droughts and heatwaves can have severe and long-lasting impacts on terrestrial ecosystems (Allen et al., 2015; Reichstein et al., 2013) and humans (Matthews et al., 2017; Pal and Eltahir, 2016). Global climate models are commonly used to project how anthropogenic climate change will affect the magnitude, frequency and intensity of droughts and heatwaves. Heatwaves are projected to increase in the future in response to climate change (Dosio et al., 2018; Zhao and Dai, 2017). The future of droughts is less clear: projections of an increase in future droughts are common in the literature (Ault, 2020), yet regional precipitation projections remain uncertain (Collins et al., 2013) and land surface processes relevant to drought are poorly represented in climate models (Ukkola et al., 2018a).

While there is no universal definition, drought can be classified into meteorological, agricultural, hydrological and socioeconomic drought. From a climate model perspective, drought is an anomalous lack of water at the land–atmosphere...
interface sustained over time. It begins with a reduction in precipitation (“meteorological” drought) and if this persists it can evolve into “agricultural” drought via low soil moisture or into “hydrological” drought through low streamflow or groundwater. A critical feedback exists between low soil moisture availability and heatwaves (Seneviratne et al., 2010; Teuling et al., 2010; Vogel et al., 2017). As soil moisture becomes depleted, the surface energy partitioning becomes increasingly dominated by sensible heat fluxes ($Q_s$) relative to latent heat fluxes ($Q_e$). This can lead to a positive feedback whereby the high sensible heat fluxes warm the boundary layer, which, combined with the reduced evaporation, leads to increased atmospheric demand for moisture exacerbating land desiccation (Miralles et al., 2019). A combination of drought and heatwaves lead to wide ranging impacts on the functioning of terrestrial ecosystems (Reichstein et al., 2013; Schumacher et al., 2019). For example, during the European heatwave and drought in 2003, terrestrial carbon losses of up to 0.5 Pg C were reported, corresponding to roughly four years of European terrestrial net carbon uptake (Ciais et al., 2005).

Given projections of worsening heatwaves and potentially more droughts under future climate change, the importance of land surface models (LSMs) to capture land responses and feedbacks to the atmosphere during climate extremes is becoming increasingly recognised (Mazdiyasni and AghaKouchak, 2015; Schumacher et al., 2019; Yang et al., 2019). Despite many improvements to LSMS over the past decades, LSMS have remained poor at simulating water fluxes during water-stressed periods (Egea et al., 2011; De Kauwe et al., 2017; Powell et al., 2013; Trugman et al., 2018; Ukkola et al., 2016a), which likely contributes to biases in land-atmosphere feedbacks during heatwaves (Sippel et al., 2017). LSMS commonly underestimate interanual variations in terrestrial water storage (Humphrey et al., 2018), underestimate $Q_e$ during droughts (Powell et al., 2013; Ukkola et al., 2016a) and lack “persistence” by responding too strongly to short-term precipitation variation (Tallaksen and Stahl, 2014). Poor representation of hydrological processes has been identified as a key reason for model biases. There is uncertainty around soil moisture dynamics, how soil texture information is translated to soil hydraulic properties through pedotransfer functions and how water fluxes are partitioned to different components of evapotranspiration and runoff (Clark et al., 2015; Lian et al., 2018; Van Looy et al., 2017). Various approaches have been adopted to improve LSM hydrology, such as the introduction of groundwater dynamics (Niu et al., 2007), alternative pedotransfer functions (Best et al., 2011) and subgrid-scale processes for runoff generation (Decker, 2015). By contrast, the functions used in LSMS to represent the effect of declining water availability on vegetation function are poorly constrained by data (Medlyn et al., 2016), and not consistently applied. Specifically, some models down-regulate the maximum rate of Rubisco carboxylation, whilst others reduce stomatal parameters (De Kauwe et al., 2013). Models also do not account for differences in species-level sensitivity to drought (De Kauwe et al., 2015; Klein, 2014; Zhou et al., 2014). This model gap has driven a significant investment in new theoretical approaches (Dewar et al., 2018; Sperry et al., 2017; Wolf et al., 2016).

Despite model developments, it has remained difficult to disentangle the reasons behind poor model performance due to a lack of suitable observations. Root-zone soil moisture estimates are rare and whilst satellite estimates are available, they only cover the top few centimetres or are only available at coarse spatial resolution. Meanwhile, $Q_e$ is routinely measured at the site-scale, but gridded large-scale estimates remain highly uncertain (Pan et al., 2020). As such, many past model evaluations have focused on observed $Q_h$ and $Q_e$ from eddy-covariance observations (Best et al., 2015) or near-surface soil moisture and evaporation from water balance sites (e.g. Schlosser et al., 2000). What is rare is evaluation of LSMS, designed for use in climate models, utilising observations of soil moisture extending root zone with concurrent measurements of water fluxes at high temporal frequency. In this paper, we use a novel dataset from the water-limited Eucalyptus Free-Air CO2 Enrichment (EucFACE) experiment site in southeastern Australia to evaluate the Community Atmosphere-Biosphere Land Exchange (CABLE) LSM. At this site, frequent measurements of each component of the water balance were made coincident with soil moisture observations to a depth of 4.5 m. The highly variable rainfall at this site leads to extended dry-downs, and the heatwaves in summer commonly exceed 35°C. We use this high-quality dataset to assess multiple model assumptions
commonly used across LSMs within a single model framework, evaluating both simulated fluxes and state variables at seasonal
to annual scales and across weather (heatwaves) and climate (drought) phenomena.

2. Methods and data

2.1 Site information

The EucFACE experiment is located on an ancient alluvial floodplain, 3.6 km from the Hawkesbury River in Western Sydney,
Australia (33°36′59″S, 150°44′17″E) (Gimeno et al., 2018a; Figure 1). The site has a temperate-subtropical transitional climate
with a mean annual temperature of 17.8 °C and the mean annual precipitation of 719.1 mm evenly distributed over the year.
EucFACE is a water-limited site experiencing frequent droughts and low water availability. The site is in an open woodland
with a canopy height of 18–23 m and a plant area index (including leaf and woody components) that varied between 1.3 and
2.2 m² m⁻² (mean = 1.7 m² m⁻²) over the study period. The overstorey is dominated by a single species *Eucalyptus tereticornis*
Sm. with scattered individuals of *Eucalyptus amplifolia* Naudin. The upper soil layer is a loamy sand with a sand fraction >75%;
at 30–80 cm depth, there is a higher clay content layer (15%–35% clay), and below the clay layer sand clay loam soil extends
to the depth of 300 cm. Between 300–350 cm and 450 cm depth, the soil is > 40% clay (Gimeno et al., 2016). The observed
water table is at ~ 12 m. The site is characterized as nutrient poor, especially lacking in available phosphorus (Crous et al.,
2015; Ellsworth et al., 2017). In this paper we evaluate CABLE against the averaged data from Rings 2, 3 and 6, which are
exposed to the ambient atmospheric CO₂ concentration.

2.2 Observation data

In our study, CABLE is driven by *in situ* meteorological data and observed leaf area index (LAI) from 2013 to 2019. The
photosynthetically active radiation (PAR; LI-190, LI-COR, Inc., Lincoln, NE, USA), air temperature, and relative humidity
(HUMICAP ® HMP 155, Vaisala, Vantaa, Finland) were measured every second and one-minute averages were recorded on
data loggers (CR3000, Campbell Scientific Australia, Townsville, Australia). Meteorological data were gap-filled by linear
interpolation and aggregated to 30-minute averages following Yang et al. (2020). LAI was calculated from the measurements
of above- and below-canopy PAR at each ring following Duursma et al. (2016). Since the site LAI represents the plant area
index (including both woody part and leaves), to reflect the actual leaves condition we follow Yang et al. (2020) and reduce
the LAI by a constant branch and stem cover (0.8 m² m⁻²) estimated by the lowest LAI when the canopy shed almost all leaves
during November 2013. The CO₂ concentration was measured every 5 minutes at each ring and then gap-filled and aggregated
to 30-minute averages.

To evaluate CABLE, we used measurements of transpiration (ETr) and soil evaporation (Es) and volumetric water content (θ)
at different soil depths (see below). ETr and Es come from a dataset published in Gimeno et al. (2018a). ETr estimates are derived
from tree sapflow using the heat pulse compensation technique (Gimeno et al., 2018a). Es is computed from the soil moisture
change in the top 5 cm depth monitored at two locations in each of the three ambient rings. The Es data also includes
transpiration from the dynamic (flushes and wilts) understory vegetation (Collins et al., 2018; Pathare et al., 2017). For ETn,
Gimeno et al. (2018a) excluded rainy days and days preceded by a day with > 2 mm d⁻¹ of precipitation.

We used two sets of observations for θ to evaluate CABLE’s simulated soil hydrology. The first dataset is from neutron probe
measurements monitored at two locations in each ring every 10 to 21 days (lower frequency in 2017), covering the period
January 2013 to July 2019. These data are collected at 12 different depths: 25 cm intervals from 25 to 150 cm depth, and 50
cm intervals from 150 to 450 cm depth. The second dataset is daily derived measurements from frequency-domain
reflectometers (CS650, Campbell Scientific Australia, Garbutt, Qld.) at each ring, monitoring to a depth of 25 cm and covering the period January 2013 to December 2019.

2.3 Model description

CABLE is a LSM that can be used in stand-alone mode with prescribed meteorological forcing (Haverd et al., 2013; Ukkola et al., 2016b; Yang et al., 2020), or coupled to the Australian Community Climate and Earth System Simulator (ACCESS (Bi et al., 2013; Law et al., 2017)) or the Weather and Research Forecasting (WRF) model (Decker et al., 2017; Hirsch et al., 2019b) to provide energy, water and momentum fluxes to the lower atmosphere. The standard version of CABLE has been widely evaluated (De Kauwe et al., 2015; Li et al., 2012; Lorenz et al., 2014; Ukkola et al., 2016b; Wang et al., 2011; Williams et al., 2009) and the model’s overall performance in simulating energy, water and energy fluxes is in line with other LSMs (Best et al., 2015). A detailed description of model components can be found in Kowalczyk et al. (2006) and Wang et al. (2011). The version of CABLE used here includes multiple process updates (Decker, 2015; Decker et al., 2017; Kala et al., 2015).

2.3.1 Hydrology scheme

We use the hydrology scheme from Decker (2015) that includes an improved representation of sub-surface hydrology similar to that implemented in the Community Land Model (Lawrence and Chase, 2007; Oleson et al., 2008). Saturation- and infiltration-excess runoff generation mechanisms are represented, and a dynamic groundwater component with aquifer water storage is included. CABLE uses six soil layers covering a depth to 4.6 m and allows for vertical heterogeneity in soil parameters. The scheme solves the vertical redistribution of soil water following the modified Richards equation (Decker and Zeng, 2009):

\[
\frac{\partial \theta}{\partial t} = - \frac{\partial}{\partial z} K \frac{\partial}{\partial z} (\Psi - \Psi_e) - F_{\text{soil}}
\]  

(1)

where \( \theta \) is the volumetric water content of the soil (mm\(^3\) mm\(^{-3}\)), \( K \) (mm s\(^{-1}\)) is the hydraulic conductivity, \( \Psi \) (mm) is the soil matric potential, \( \Psi_E \) (mm) is the equilibrium soil matric potential, \( z \) (mm) is soil depth and \( F_{\text{soil}} \) (mm mm\(^{-1}\) s\(^{-1}\)) is the sum of subsurface runoff and \( E_{tr} \) (Decker, 2015). A 25 m deep unconfined aquifer is simulated below the 6-layer soil column by incorporating a simple water balance model:

\[
\frac{dW_{\text{aq}}}{dt} = q_{re} - q_{aq,\text{sub}}
\]  

(2)

where \( W_{\text{aq}} \) (mm) is the mass of water in the aquifer, \( q_{aq,\text{sub}} \) (mm s\(^{-1}\)) the subsurface runoff removed from aquifer and \( q_{re} \) (mm s\(^{-1}\)) the water flux between the aquifer and the bottom soil layer, computed by the modified Darcy’s law as

\[
q_{re} = K_{aq} \frac{(\Psi_{\text{aq}} - \Psi_n) - (\Psi_{E,\text{aq}} - \Psi_{E,n})}{z_{\text{water}} - z_n}
\]  

(3)

where \( K_{aq} \) (mm s\(^{-1}\)) is the hydraulic conductivity within the aquifer, \( \Psi_{\text{aq}} \) and \( \Psi_{E,\text{aq}} \) (mm) are the soil matric potential and the equilibrium soil matric potential for the aquifer, and \( \Psi_n \) and \( \Psi_{E,n} \) (mm) are the soil matric potential and the equilibrium soil matric potential for the bottom soil layer. \( z_{\text{water}} \) and \( z_n \) (mm) are the depth of the water table and the lowest soil layer, respectively. The groundwater aquifer is assumed to sit above an impermeable layer of rock, giving a bottom boundary condition of...
Subsurface runoff \( q_{\text{sub}} \) (mm s\(^{-1}\)) is calculated from

\[
q_{\text{sub}} = \sin \frac{\overline{d_s}}{d_l} \hat{q}_{\text{sub}} e^{-\frac{z_{\text{sat}}}{P}}
\]  

where \( \overline{d_s} \) is the mean subgrid-scale slope, \( \hat{q}_{\text{sub}} \) (mm s\(^{-1}\)) is the maximum rate of subsurface drainage assumed to be achieved when the whole soil column is saturated and \( f_p \) is a tunable parameter. \( q_{\text{sub}} \) is generated within the aquifer and for each saturated soil layer below the third soil layer.

### 2.3.2 Soil evaporation \((E_s)\)

The computation of \( E_s \) (kg m\(^{-2}\) s\(^{-1}\)) considers the subgrid-scale soil moisture heterogeneity within a grid square (Decker, 2015), and is given as

\[
E_s = F_{\text{sat}} E_s^* + (1 - F_{\text{sat}}) \beta_s E_s^*
\]  

where \( F_{\text{sat}} \) is the saturated fraction of a grid cell, \( E_s^* \) (kg m\(^{-2}\) s\(^{-1}\)) is the potential evaporation without soil moisture stress, and \( \beta_s \) is an empirical soil moisture stress factor (see below) that limits evaporation as water becomes limiting in the top soil layer.

\( E_s^* \) is given by

\[
E_s^* = \frac{\rho_a (q_{\text{sat}}(T_{\text{surf}}) - q_a)}{r_g}
\]  

where \( \rho_a \) (kg m\(^{-3}\)) is the air density, \( q_{\text{sat}}(T_{\text{surf}}) \) (kg kg\(^{-1}\)) is the saturated specific humidity at the surface temperature, \( q_a \) (kg kg\(^{-1}\)) is the specific humidity of the air and \( r_g \) (s m\(^{-1}\)) is the aerodynamic resistance term.

\( \beta_s \) is computed as:

\[
\beta_s = 0.25 \left( 1 - \cos \left( \pi \frac{\theta_{\text{unsat}}}{\theta_{\text{fc}}} \right) \right)^2
\]  

where \( \theta_{\text{unsat}} \) (mm\(^3\) mm\(^{-3}\)) is the volumetric water content in the unsaturated portion of the top soil layer (top 2 cm), and \( \theta_{\text{fc}} \) (mm\(^3\) mm\(^{-3}\)) is the field capacity in the top soil layer.

### 2.3.3 Transpiration \((E_{tr})\)

CABLE’s canopy is represented using a two-leaf model, which computes photosynthesis, stomatal conductance, \( E_{tr} \) (kg m\(^{-2}\) s\(^{-1}\)) and leaf temperature separately for sunlit and shaded leaves. \( E_{tr} \) (for each sunlit/shaded leaf) is calculated following the Penman-Monteith equation:

\[
E_{tr} = \frac{D \rho_v c_p M_a D_1 (q_h + \theta_r)}{\lambda (c_p + \Delta)}
\]  

where \( \lambda \) (J kg\(^{-1}\)) is the latent heat of vapourisation, \( D_1 \) (Pa) is the vapour pressure deficit at the leaf surface, \( c_p \) (J kg\(^{-1}\) K\(^{-1}\)) is the air heat capacity, \( M_a \) (kg mol\(^{-1}\)) is the molar mass of air, \( \Delta \) (Pa K\(^{-1}\)) is the slope of the curve relating saturation vapour...
pressure to air temperature and $\gamma$ (Pa K$^{-1}$) is the psychrometric constant. $g_h$, $g_r$, and $g_w$ (mol m$^{-2}$ s$^{-1}$) are the conductances for heat, radiation and water, respectively. $R_{nt}$ (W m$^{-2}$) is the non-isothermal net radiation calculated as:

$$R_{nt} = R_a - C_pM_a(T_a - T_l)\gamma$$

where $R_a$ (W m$^{-2}$) is the net radiation under isothermal conditions and $T_a$ and $T_l$ is the air and leaf temperature (K), respectively.

$g_w$ is calculated as:

$$g_w^{-1} = g_a^{-1} + g_b^{-1} + g_s^{-1}$$

(11)

where $g_a$ (mol m$^{-2}$ s$^{-1}$) is canopy aerodynamic conductance, and $g_b$ (mol m$^{-2}$ s$^{-1}$) is leaf boundary layer conductance for free and forced convection (Kowalczyk et al., 2006). $g_s$ (mol m$^{-2}$ s$^{-1}$) is the leaf stomatal conductance following Medlyn et al. (2011):

$$g_s = g_0 + 1.6 \left(1 + \frac{\theta_l}{\theta_f}\right) \frac{A}{C_a}$$

(12)

where $A$ ($\mu$mol m$^{-2}$ s$^{-1}$) is the photosynthetic rate, $C_a$ ($\mu$mol mol$^{-1}$) is the CO$_2$ concentration at the leaf surface, $\beta$ (unitless) is the soil moisture stress factor on plants, $g_0$ (mol m$^{-2}$ s$^{-1}$) and $g_s$ (kPa$^{-0.5}$) are fitted parameters representing the residual stomatal conductance when $A = 0$ and the sensitivity of conductance to the assimilation rate, respectively. $g_0$ reflects the plant’s water use strategy and was derived for each plant functional type in CABLE (De Kauwe et al., 2015) based on a global synthesis of stomatal behaviour (Lin et al., 2015). $\beta$ is calculated as:

$$\beta = \sum_{i=1}^{n} f_{\text{root},i} \frac{\theta_i - \theta_{wi,i}}{\theta_f,i - \theta_{wi,i}}$$

(13)

where $\theta_i$, $\theta_f,i$ and $\theta_{wi,i}$ (mm$^{-1}$ mm$^{-3}$) are the soil moisture content, the field capacity and wilting point for soil layer $i$, and $f_{\text{root},i}$ is the root mass fraction of soil layer $i$.

CABLE does not have the capacity to simulate interacting water fluxes between the understorey and overstorey vegetation. Instead, it uses a “tiling” approach (fractionally weights separate simulations). As a result, comparisons between CABLE’s $E_v$ and data-derived $E_v$ during wetter periods would be expected to be an underestimate as we only consider the fluxes from the overstorey trees. To quantify the effect of the understorey transpiration on the water balance, we also ran an extra simulation for the grass understorey at this site with the same setting as $Watr$ (see below) but using CABLE default grass physiology parameters and a fixed LAI (1 m$^2$ m$^{-2}$ – site average). The estimated multi-year mean transpiration of 0.94 mm d$^{-1}$ can be regarded as an upper estimate since the simulation does not consider grass dynamics, overstorey rainfall interception, or water and energy competition between tree and grass. Not accounting for understorey transpiration will lead to an overestimate of moisture availability in the soil profile.

2.4 Experiment design

We conducted a series of model experiments based on weaknesses identified in previous LSM evaluation studies. In our experiments, we deliberately adopted a “layering” approach: sequentially resolving a key systematic model bias and then
layering additional experiments to examine how much additional benefit each experiment added to model performance. A summary of all experiments is provided in Table 1.

In all experiments, LAI and physiology parameters were prescribed based on site observations (Table S1). We tested the difference of using the CABLE default evergreen broadleaf physiology parameters (Figure S1) compared to using the site physiology (Figure 2) and found that using site parameters increases $E_v$ (due to higher $g_s$ and increased sensitivity of carbon fixation to temperature), in turn reducing $E_s$ and $\theta$.

All experiments were spun-up using an iterative process recycling all years of the meteorological forcing until the change between two iterations was $< 0.001$ m$^3$ m$^{-3}$ for soil moisture, $< 0.01$°C for soil temperature and $< 0.0001$ m$^3$ m$^{-3}$ for aquifer moisture.

2.4.1 Control experiment (Ctl)

The control simulation (Ctl) uses the default version of CABLE with 6 soil layers (but with site physiology and LAI). The soil hydraulic parameters are derived via the pedotransfer functions based on Cosby et al. (1984) using the global soil texture map from the Harmonized World Soil Database (Fischer et al., 2008). Soil parameters are the same throughout the 6-layer soil column.

2.4.2 Increasing the resistance for soil evaporation ($S_{res}$)

Previous studies suggest LSMS vary widely in their simulation of $E_s$. For example, De Kauwe et al. (2017) found that in an ensemble of 10 models, six models simulated ~2-3.5 times more $E_s$ than the other four models. LSMS also partition evapotranspiration between $E_v$ and $E_s$ with a high degree of uncertainty (Lian et al., 2018). At many sites, high springtime evapotranspiration can be linked to excessive $E_s$ rather than $E_v$ (Decker et al., 2017; Ukkola et al., 2016b) and can lead to biases in soil moisture availability later in the growing season.

We note that models have attempted to resolve this $E_s$ bias through different mechanisms, for example, via a litter layer (Haverd and Cuntz, 2010; Sakaguchi and Zeng, 2009) or by limiting $E_s$ via adding the resistances to vapour diffusion through the soil pores and the surface viscous sublayer (Decker et al., 2017; Haghighi and Or, 2015; Swenson and Lawrence, 2014). Here, we adopt a simple litter layer (Decker et al., 2017) which adds an additional surface resistance to vapour and heat fluxes but does not limit rainfall infiltration. After adding the additional resistance, $E_s^*$ is calculated as

\[
E_s^* = \frac{E_s(1 - r_{lit})}{r_{lit}}
\]

where $r_{lit}$ is the resistance (s m$^{-1}$) for diffusion via the litter layer of depth $z_l$ (m) (default value is 10 cm) given by:

\[
r_{lit} = \frac{z_l}{d}
\]

where $d$ is the diffusivity of water vapour in air (m$^2$s$^{-1}$).

2.4.3 Water table initialisation experiment ($W_{atr}$)

The parameters governing the groundwater aquifer saturation and water table depth are both highly uncertain and difficult to constrain from observations. We investigated the importance of a correct water table depth to the simulation soil moisture and
water fluxes. To better match the observed water table depth at EucFACE, we changed the aquifer $\theta_{sat}$ from the model default value (0.235 m$^3$ m$^{-3}$) to $\theta_{sat}$ set based on the observed soil texture at 4.5 m depth (0.448 m$^3$ m$^{-3}$). This has the effect of lowering the water table to ~12 m, in line with observations (Gimeno et al. 2018a).

### 2.4.4 High resolution soil experiment (Hi-Res)

Most LSMs assume that soil parameters are depth invariant through the soil profile. The number of layers typically ranges from a minimum of 2, through to 6 in CABLE and up to 20 in Community Land Model (Lawrence et al., 2019). Here, we test the impact of increasing the number of discrete soil layers, informed by observations of the varying soil texture at the EucFACE site. Recent soil maps (e.g. SoilGrids (Hengl et al., 2017)) have begun to capture vertical variations in soil texture, so it is important to test the impact in LSMs.

We performed two sub-experiments in Hi-Res:

1) the number of vertical soil layers was increased from 6 to 31 (for later maximising the utilization of soil texture observations) (**Hi-Res-1**);

2) soil parameters were allowed to vary vertically based on observed soil texture (**Hi-Res-2**).

To implement vertically varying soil parameters, the observed fractions of sand, clay and silt, soil bulk density and organic carbon fraction were taken from measurements at each ambient CO$_2$ ring and interpolated into 31 layers using the ~15 cm resolution of the observations. Soil hydraulic parameters are computed using the same pedotransfer functions as used in Ctl but allowed to vary with depth based on the vertical heterogeneity in soil properties. Since CABLE assumes the aquifer’s suction at saturation and Clapp and Hornberger parameter are identical to the bottom soil layer, adding depth-varying soil parameters in **Hi-Res-2** also changes these two parameters for the aquifer.

### 2.4.5 Soil parameter optimisation experiment (Opt)

As it is impractical to measure soil hydraulic parameters at the global scale, pedotransfer functions are used to convert widely measured soil properties into global soil hydraulic parameter datasets (Dai et al., 2013; Kishné et al., 2017). However, most of the widely-used pedotransfer functions are empirical equations derived from the limited experimental samples measured for the specific locations (Cosby et al., 1984; van Genuchten, 1980). The adaptability of these pedotransfer functions are always confined by their underrepresentation of some soil properties, such as soil aggregate stability or macroporosity (Puhlmann and von Wilpert, 2012) and can lead to a divergence in model parameters (Van Looy et al., 2017; Zhang and Schaap, 2019). As a result, parameter calibrations are common to obtain more accurate representations.

First, we used the site observations to adjust the plant wilting point ($\theta_w$) and volumetric water content at saturation ($\theta_{sat}$). With each layer as $\theta_r$ is changed, the corresponding residual water content ($\theta_{res}$) was also updated to ensure it was smaller than $\theta_r$. $\theta_{sat}$ was set to the observed maximum from the daily data measured by frequency-domain reflectometers for the top 30 cm. Due to muted variability in deeper soil layers, $\theta_{sat}$ below 30 cm was not adjusted. $\theta_r$ and $\theta_{res}$ were adjusted for each 15 cm layer in the soil column using the observed minimum (OBS$_{min}$) in each layer. When OBS$_{min}$ was below the default $\theta_{res}$, $\theta_{res}$ was set to OBS$_{min}$ and $\theta_r$ to OBS$_{min}$ + 0.0001 m$^3$ m$^{-3}$. When $\theta_{res} <$ OBS$_{min}$ < $\theta_r$ was set to OBS$_{min}$. Otherwise $\theta_{res}$ and $\theta_r$ were not adjusted.
Second, we optimised $K_{sat}$ to test whether allowing the soil column to drain faster or slower reduced model biases in the soil moisture profile. $K_{sat}$ was optimised by minimising errors between modelled and observed soil moistures over total column and in the top 0.25 m, transpiration and soil evaporation.

2.4.6 Soil water limitation on transpiration ($\beta_{hvrd}$ and $\beta_{exp}$)

LSMs use different, empirical functional forms to represent the effect of water stress on vegetation function (see Introduction). To explore the influence of different functional formulations, we compare CABLE’s default function (Equation 13) to two alternative parameterisations: 1) an alternative hypothesis that plants optimise their root water uptake to exploit resources, with the wettest soil layer determining soil water stress on plants ($\beta_{hvrd}$; Haverd et al., 2016) and 2) a site calibrated function to observations at EucFACE over the top 1.5 m ($\beta_{exp}$; Yang et al., 2020). We note that a number of studies have tested different water stress formulations (e.g. Egea et al. (2011)) but this process evaluation is often decoupled from analysis of other contributing errors (e.g. LAI and/or soil hydrology).

The $\beta_{hvrd}$ method tends to predict less water stress than the default function (Equation 13) in CABLE when the moisture is unevenly distributed within the soil column. This function takes the form:

$$\beta = \max(\alpha_i \cdot \delta_i, i = 1, n)$$

where:

$$\alpha = \left\{ \begin{array}{ll}
(\theta - \theta_w)/(\theta - \theta_u) & , (\theta - \theta_w) > 0 \\
0 & , (\theta - \theta_w) \leq 0
\end{array} \right.$$

where $\alpha_i$ is proportional to the root “shut-down” function (Lai and Katul, 2000) in the $i$th soil layer, and $\delta_i = 1$ if there are roots at the $i$th soil layer, otherwise $\delta_i = 0$. $n$ is the total number of soil layers.

In $\beta_{exp}$, $\beta$ is an exponential function calibrated to the site observations. Yang et al. (2020) fitted a non-linear relationship between $\beta$ and $\theta$, based on a fitted exponent term $q$ (Table S1) using measured soil moisture over the top 1.5 m from EucFACE:

$$\beta = \sum_{i=1}^{n} f_{\text{root}} \left( \frac{\theta - \theta_w}{\theta_u - \theta_w} \right)^q$$

2.4.7. Evaluation metrics

We used five metrics to evaluate CABLE’s performance compared to observations. Root Mean Squared Error (RMSE) and Mean Bias Error (MBE) were used to evaluate overall performance and Pearson’s correlation coefficient ($r$) the temporal variability. The absolute differences in modelled and observed 5th (P5) and 95th (P95) percentile values were used to evaluate the lower and upper tails, respectively. As the observed data have gaps, the metrics were only calculated for days for which observations were available.
3. Results

3.1 Control experiment (Ctl)

We first evaluate the Ctl simulation by comparing to the observed $E_n$, $E_s$ and soil moisture (Figure 2). Overall, CABLE simulates $E_n$ similarly to the observed ($r = 0.85$, RMSE = 0.34 mm d$^{-1}$, Table 2) but overestimates peak $E_n$, which is particularly evident in the austral summer of 2014, by 0.54 mm d$^{-1}$ on average (P95 in Table 2). However, it is worth noting that during the summer of 2014 there was an outbreak of psyllids leading to canopy defoliation (Gherlenda et al., 2016), which may explain part of the model-data mismatch (CABLE only accounts for this via a decline in LAI). Compared to $E_n$, CABLE simulates $E_s$ less well ($r = 0.65$, RMSE = 0.70 mm d$^{-1}$; Table 2, Figure 2a). Whilst the observations exclude rainy days when CABLE reaches its highest $E_n$, CABLE systematically overestimates mean and peak $E_s$ during observed days by 0.12 and 1.22 mm d$^{-1}$, respectively (MBE and P95 in Table 2). Figure 2b shows that CABLE has a significant wet bias in the top 0.25 m soil moisture and never falls to the observed values below 0.08 m$^3$ m$^{-3}$ during drier periods. Given the excessive $E_s$ (Figure 2a), the failure of the top 25 cm to dry out is surprising and suggests either a parameterisation error and/or the impact of not accounting for understory transpiration (see methods). Figure 2c shows that the wet bias in soil moisture is systematic, extending throughout the soil column (particularly between 2.5 and 4.5 m).

Taken together, the evaluation of the Ctl simulation implies that a good simulation in one evaporative flux (Figure 2a) can be achieved for the wrong physical reasons and is associated with major systematic biases in the simulation of near surface and root zone soil moisture (Figures 2b-d).

3.2 Increasing the resistance to soil evaporation experiment ($S_{res}$)

Implementing a litter layer (a proxy for additional surface resistance to $E_s$) in CABLE significantly reduces $E_s$ from 305 mm y$^{-1}$ in Ctl to 204 mm y$^{-1}$ in Sres (Figure 3a, Table 3). The simulation of peak $E_s$ is significantly improved compared to Ctl but CABLE still overestimated $E_s$ (MBE and P95 in Table 2); this is particularly evident during an observed dry period in late 2013. As a consequence of lower $E_s$ compared to Ctl, $E_n$ is markedly increased (from 341 mm y$^{-1}$ in Ctl to 402 mm y$^{-1}$ in Sres, Table 3) which implies a reduction in soil moisture stress in the profile (lower $\beta$). This degrades the simulated $E_n$ relative to the observations for all metrics, particularly from around October 2013 to March 2014 (Figure 3b). With an overall reduction in evapotranspiration, CABLE displays a considerably worse soil moisture profile (cf. Figure 3c and 2d) and a larger wet bias through most of the soil profile (cf. Figure 3d and 2e). Thus, resolving the $E_s$ bias alone, relocated the bias to other model components, where it less easily identified using commonly available measurements.

3.3 Water table (Watr) and vertical soil structure (Hi-Res) experiments

Figure 4 shows that reconciling the parameterisation of the aquifer $\theta_{sat}$ with the bottom layer $\theta_{sat}$ based on observed soil properties (Watr) leads to a marked improvement in the simulated soil moisture profile. By increasing the point of saturation and initialising the aquifer to be drier, CABLE simulates a more negative water potential in the aquifer, which promotes vertical drainage and results in a realistic water table depth in line with observations (simulated and observed ~ 12 m over 2013-2014). The wet bias in the top 3 m is markedly reduced (cf. Figure 4d and 2e); however, the model now has a clear dry bias between 3 and 4.6 m. The simulated moisture in the top 0.25 m (Figure 4b) is now also in better agreement with the observations (0.06 m$^3$ m$^{-3}$ in Watr vs 0.11 m$^3$ m$^{-3}$ in Sres, MBE in Table S2). Finally, both the bias in the simulated $E_s$ and $E_n$ is reduced by > 0.2 mm d$^{-1}$ (MBE in Table 2), particularly evident during the summer of 2014.

Increasing the number of soil layers from 6 to 31 (Hi-Res-1; Figure S2), leads to a small improvement in the simulated temporal correlation (0.78 in Watr vs 0.83 in Hi-Res-1; Table 2) of soil moisture, without notably changing the fluxes. The higher
vertical resolution in the soil enables the transition of the dry-down to be better captured, in contrast to the alternating wet and dry patterns associated with the coarse vertical resolution at depths between 0.5-3.0 m depth in War (cf. Figure S2c and 4c).

Allowing the soil parameters to vary vertically based on observed soil texture (Hi-Res-2; Figure 5) reduces the dry bias in the lower layers in War (Figure 4) but leads to a greater wet bias throughout the upper soil profile (< 3 m). The error in soil moisture has reduced in the mean, low and high extremes compared to Ctrl and Sres (MBE, P5 and P95 in Table 2). Overall, Figure 5 highlights a simulation with CABLE where the fluxes of $E_o$, $E$, and soil moisture are all in reasonable agreement with the observations (Table 3), albeit with an overestimation of peak $E_o$.

### 3.4 Soil parameter optimisation experiment (Opt)

To address the simulated wet bias in the soil moisture profile (Figure 5), we used observations to prescribe the critical soil hydraulic parameters $\theta_w$ and $\theta_{sat}$ (Figure S3) and to optimise $K_{sat}$ (Figure S4 and S5). Prescribing $\theta_w$ and $\theta_{sat}$ led to a much improved “operating range” of soil moisture in the top 0.25 cm (Figure S3b) but did not reduce the wet bias in the soil profile or solve the slow drainage after rainfall events (cf. Figure 5c and Figure 2c). Overall, these changes had a limited effect on simulated $E_o$ (344 mm y$^{-1}$ vs 327 mm y$^{-1}$ in Hi-Res-2 in Table 3) as might be expected because the profile was sufficiently wet as not to limit evapotranspiration, especially in the root zone of top 1.5 m (Figure S5d). A reduction of the simulated $E_s$ (138 mm y$^{-1}$ vs 165 mm y$^{-1}$ in Hi-Res-2; Table 3) was mainly associated with the drier shallow soil (Figure S5b). The optimised $K_{sat}$ increased drainage speed (cf. Figure 5c and Figure 3c) and lowered the overall wet biases (0.04 m$^3$ m$^{-3}$ in Opt vs 0.07 m$^3$ m$^{-3}$ in Hi-Res-2, MBE in Table 2).

### 3.5 Soil water limitation on transpiration ($\beta$-hvr$^d$ and $\beta$-exp)

Replacing CABLE’s default soil moisture stress function with an alternative hypothesis that plants maximise their root water uptake to exploit resources ($\beta$-hvr$^d$) led to a substantial increase in $E_o$ relative to experiment Opt (from 344 mm y$^{-1}$ to 403 mm y$^{-1}$, Table 3) because the function assumes that the soil water stress on plants is determined by the availability of water in the wettest soil layer. This overestimation of $E_o$ led to a small reduction in the wet soil moisture bias (cf. Figure S5d and Figure 6d).

Figure 7 shows the impact of using a site-calibrated $\beta$ function ($\beta$-exp) (Yang et al., 2020). Using this function also increased $E_o$ relative to experiment Opt (from 344 mm y$^{-1}$ to 373 mm y$^{-1}$, Table 3), degrading the simulation relative to the standard $\beta$ (Opt). In both experiments, owing to the overall simulated wet bias in the soil profile, a decreased sensitivity to soil moisture availability (either using $\beta$-hvr$^d$ or $\beta$-exp) did not improve simulated evapotranspiration.

### 3.6 Implications for Drought

Improving the simulation of $E_o$, $E$, and soil moisture in LSMs is important on the seasonal timescale, but the increasing use of models to simulate future drought highlights the value of examining how these improvements impact the expression of drought in LSMs. We focus on a period of extensive drought across southeastern Australia that begins in October 2017 and extends to the end of 2019. Due to rainfall data availability, we focus on the dry-down period between October 2017 and September 2018.

Figure 8 shows selected fluxes during the drought period over which the soil slowly dries in the observations and in the models (Figure 8a) and the shallow soil moisture is close to wilting point (e.g. Figure 6b). The Sres experiment maintains the highest soil moisture throughout the drought period and $\beta$-hvr$^d$ the lowest, with the range across all experiments exceeding 0.1 m$^3$ m$^{-3}$. These soil moisture variations lead to inconsistent behaviour in $E_o$ (Figure 8b) due to resulting differences in $\beta$ (Figure 8c). $\beta$-hvr$^d$ $E_o$ is very high despite having the driest soil moisture (Figure 8a) because it is derived from the wettest soil layer where
there is notably muted temporal variation. The differences in soil moisture, and as a result $\beta$, lead to differences in $E_{tr}$ (Figure 8b) of 20 ~ 50 mm month$^{-1}$ until autumn/winter (~April-July) when lower evaporative demand leads to more similar simulations. Through summer (~November-February), $E_{tr}$ varies markedly from around 10 mm month$^{-1}$ ($\beta$-hvrd) to 35 mm month$^{-1}$ (Ctl) (Figure 8d). The differences in $E_{tr}$ and $E_{tr}$ are mirrored by differences in $Q_h$ (Figure 8e) which varies by > 30 W m$^{-2}$ between the experiments between October 2017 and March 2018.

Integrating the simulations over the drought period highlights the differences in simulating water stress (expressed as $\beta$) between experiments. Figure 9a shows that $S_{res}$ and $\beta$-hvrd maintain a relatively high $\beta$ during drought periods (median > 0.7) while the remaining experiments are notably lower. The $\beta$-exp simulates median values of 0.63, which is notably higher than the Hi-Res-2 of 0.33 and Opt of 0.46. This difference originates from the calibrated functional form shown in Figure 9b, where the exponent in the $\beta$-exp function leads to a delay in the onset (point of inflection) of moisture stress relative to the default linear function used in CABLE. Overall, in a single model, parameterisations led to a difference of 98 % between simulated $\beta$ during drought.

3.7 Implications for Heatwaves

The link between soil moisture and heatwaves is well known (Teuling et al., 2010) and is usually examined in the context of a drying soil leading to higher $Q_h$ relative to $Q_e$ (as our simulations are uncoupled, we cannot examine the consequences of these changes on the boundary layer).

Figure 10 shows a heatwave that occurred on 19-22 January 2018, where the air temperatures exceeded 35°C for four consecutive days and exceeded 40°C on the last day (Figure 10a). The evaporative fraction during the daytime (9am - 4pm) is shown in Figure 10b and highlights a remarkable range from ~0.2 in Ctl to ~0.7 in $\beta$-hvrd, suggesting much stronger evaporative cooling in $\beta$-hvrd. An obvious diurnal variation in evaporative fraction is characterised by a progressive decline from a peak at 9 am. $Q_e$ gradually declines through the four heatwave days (Figure 10c) in all experiments. At the beginning of the heatwave (19 January) daytime $Q_e$ ranges from > 200 W m$^{-2}$ in $\beta$-hvrd and $S_{res}$ to around 100 W m$^{-2}$ in Ctl, Watr, Hi-Res-1, Hi-Res-2 and Opt. The differences in $Q_e$ are mirrored by differences in $Q_h$ (Figure 10d) with daytime fluxes varying on the heatwave days by more than 150 W m$^{-2}$.

Figures 10c and 10d also highlight a key divergence in energy partitioning due to parameterisations and the emergent interactions with soil water availability. Models that show a pronounced midday depression in $Q_e$ (e.g. Ctl, Watr and Hi-Res-2) due to increasing diurnal vapour pressure deficit ($D$) and soil moisture stress, show earlier diurnal peaks in $Q_h$ (Figure 10d).

By contrast, parameterisations that are less limited by $\beta$ (e.g. $\beta$-hvrd despite the lowest soil moisture, Figure 10a), see an emergent shift in peak in $Q_h$ to later in the afternoon. When coupled, these emergent differences due to the role of soil water availability – and importantly, how this is translated in canopy gas exchange via $\beta$ – may have implications for surface interactions with the boundary layer.

Given the importance of the role of $D$ during heat extremes, to further explore the role of high $D$ on simulated $E_{tr}$, we plotted modelled and measured transpiration as a function of binned $D$ (Figure 11). At high $D$ (> 2 kPa), simulated $E_{tr}$ is overestimated. As the mismatch between simulated $E_{tr}$ and observed occurs at both low and high $D$ (Figure 11), it implies that model improvements are unlikely to simply be relate to an alternative parameterisation of the stomatal sensitivity to $D$, but instead suggest a missing mechanism to limit canopy gas exchange with increasing $D$. The impact of this overestimation would likely have greater significance for summers with concurrent heatwaves and droughts (compound events that are common in Australia), as during heatwaves the model would overestimate $E_{tr}$ using up available soil moisture.
4. Discussion and conclusions

Land surface schemes used in climate models range in complexity and different approaches translate into contrasting predictions of the exchange of carbon, energy and water (Fisher and Koven, 2020). Perhaps critically, how strongly the land is coupled to the atmosphere also varies widely and is typically attributed to soil moisture variability (Brantley et al., 2017; Dirmeyer, 2011; Guo et al., 2006). A key component of LSMs is how soil moisture availability impacts processes internal to the land model and, in turn, how these impact fluxes of carbon and water.

In this paper we used a rich observational dataset from a water-limited site that experiences both high temperatures and pronounced periods of low rainfall, to explore a range of alternative model-based assumptions within a single model framework. We focussed on the capacity of the model to simulate both the state (soil moisture) and the fluxes (evapotranspiration and its components). We demonstrated that the default simulation (Ctl, Figure 2) was able to simulate good transpiration fluxes but for the wrong reasons: erroneously high soil evaporation with a marked wet soil moisture bias. Errors of this kind may not have been identified in previous LSM evaluations against eddy covariance data which mostly focus on $Q_e$ (Best et al., 2015).

Our results highlight a potential bias in model evaluations due to a limited capacity to assess soil moisture or the partitioning of evapotranspiration. We demonstrated that poor model behaviour could be overcome via four key steps: (i) reducing soil evaporation biases; (ii) correctly initialising the aquifer moisture content, (iii) adjusting soil parameters to match site conditions and (iv) replacing the function used to constrain transpiration as soil moisture becomes limiting. Given the critical role of drought-prone ecosystems in contributing to interannual variability in the land CO$_2$ sink size (Ahlström et al., 2015), our approach has the potential to improve the representation of these systems in models. We note that despite these improvements we still simulated a persistent wet soil moisture bias (e.g. Figure 5d). We think on balance this is unlikely to originate from not simulating a seasonal understorey transpiration as $\beta-hvrd$, which grossly overestimated overstorey transpiration and did not sufficiently dry out the profile (cf. Figure S5d and Figure 6d). Instead the soil moisture bias must relate to CABLE’s representation of sub-surface processes.

Soil evaporation

Biases in soil evaporation are commonplace in model intercomparisons (De Kauwe et al., 2017), suggesting this is a key model weakness. Errors in soil evaporation are rarely isolated in models and often contribute to errors in transpiration by limiting soil moisture availability later in the growing season (Ukkola et al., 2016b) as well as affecting the distribution of shallow versus deep soil moisture draw-down during drought. A number of approaches have been suggested to improve simulations (Haghighi and Or, 2015; Haverd and Cuntz, 2010; Lehmann et al., 2018; Or and Lehmann, 2019). Here we used a simple approach that increased resistance to surface evaporation, approximating the role of surface litter (Decker et al., 2017). At this site, this increased resistance to surface evaporation improved agreement with observations ($Sres$; Figure 3a) but did not resolve all biases. Soil evaporation was not directly measured at the site, but instead derived from the change in observed soil moisture, while ignoring days following rain (when the evaporative flux would likely be largest). As these fluxes also contain changes due to the transpiration of a seasonal grass understorey, model evaluation is complicated. As many soil evaporation schemes used in LSMs lack a physical basis (e.g. ignoring the role of soil pores), a focussed intercomparison of competing approaches against data originating from different ecosystems would be a valuable future direction.

Aquifer initialisation

Our results showed that the initialisation of the aquifer moisture store was critical to an improved simulation of the soil moisture profile. By default, CABLE equilibrates the aquifer state by assuming almost complete saturation at the start. If, as happened with the Ctl, the aquifer is initialised too wet, the simulated water table is too high and the water potential in the aquifer is
unlikely to be below the lowest soil moisture layer, impeding vertical aquifer recharge. When we initialised from a drier starting
position ($W_{at}$), the simulated soil moisture profile matched the observed better. There are a number of implications of this
result. First, it obviously implies that LSMs that incorporate groundwater schemes need to be careful about aquifer initialisation
because it strongly affects soil moisture dynamics. Second, there is no obvious solution to this initialisation and spin-up
problem because drainage into the aquifer is a slow process, and it may take hundreds of years to reach a realistic equilibrium
state. For global simulations, this suggests the need to a priori initialise the starting aquifer state and to assess against satellitebased products like GRACE (Döll et al., 2014; Niu et al., 2007) or implement off-line spin-up using meteorological forcing
consistent with the subsequent simulations. However, while spin-up with observations is attractive, when the resulting states
are taken into a coupled global model, inconsistencies are inevitable. Third, CABLE currently assumes an identical spin-up
approach for the aquifer as the soil moisture, iterating until state changes between sequences of years are smaller than some
threshold. LSMs that employ similar iteration approaches (Gilbert et al., 2017) are likely to encounter similar problems as
CABLE because the rate of drainage into the aquifer is very slow, leading to negligible changes between iterations and thus,
satisfying the criteria for equilibrium.

**Soil layers and pedotransfer functions**

LSMs typically define a fixed number of soil layers globally, anywhere up to 20 layers. Most LSMs assume constant
parameters across the entire soil profile, based on limited measurements and uncertain pedotransfer functions. We explored
the implications of these assumptions by first increasing the number of soil layers to match the number of observed layers (Hi-
Res-1; Figure S2) and then implementing soil parameters that varied vertically based on site texture (Hi-Res-2; Figure 5).
Increasing the vertical resolution had a small impact on the soil moisture and fluxes but did improve the temporal variability
in soil moisture compared to observations. The use of site soil texture better depicts the moisture distribution in the soil profile
but led to a slightly degraded soil moisture simulation. These results again highlight uncertainties in the translation of soil
texture information to soil parameters via pedotransfer functions (Van Looy et al., 2017) and the value of parameter calibration
as an alternative in site-level studies. The availability of site soil information at EucFACE further enabled the separation of
parameter uncertainties from biases in process representations and model structural errors, a highly valuable step in better
constraining LSM simulations.

**Calibration of soil hydraulic parameters**

A number of studies have used satellite-derived (passive and active microwave) estimates of soil moisture to optimise soil
hydraulic parameters in the top few soil layers (Harrison et al., 2012). Clearly these approaches are a potential way to constrain
LSMs globally given the plethora of satellite observations extending back to the 1970s. However, these approaches implicitly
assume that improving near-surface soil moisture translates to improvements over the entire soil column, an assumption not
supported by our results. Whilst the use of observation-constrained $\theta_a$ and $\theta_s$ over top 0.3 m improved the simulated dynamics
of shallow soil, it did not result in a large reduction in the bias simulated in deeper soil moisture layers (Figure S3). At this
site, the inability to significantly improve soil moisture dynamics through calibration of soil hydraulic conductivity against
observed soil moisture data likely relates to the complexity of the soil profile, which contains two clay layers at depth (30-80
cm and 300-450 cm). This vertical texture complexity meant that it was difficult to obtain unique parameter solutions that
would sufficiently improve vertical drainage, whilst simultaneously simulating moisture dynamics well (Figure S5). However,
the neutron probe measurement of soil moisture also involves the calibration of instruments and assumptions of soil
characteristics. It is possible that some of the differences between our simulation and the observations are therefore associated
with measurement errors. Overall, our sensitivity experiments demonstrated that there is likely to be an upper bound to model
improvement achievable from adjusting empirical pedotransfer functions, the water retention curve and hydraulic conductivity
functions despite the utilisation of the high-quality soil texture data at the site. As such, our study suggests that optimising soil
properties alone is not sufficient and calibration exercises should also account for vegetation information to reduce biases in sub-surface processes.

Water stress functions

Studies commonly highlight the functions used to limit photosynthesis and stomatal conductance with water stress as a key weakness among models. The lack of theory in this space (Medlyn et al., 2016) has led to models employing a range of functions encompassing different shapes and sensitivities that are not constrained by data. More recently, plant hydraulic (Christoffersen et al., 2016; Xu et al., 2016) and stomatal optimality approaches have emerged to fill the theoretical gap (Sperry et al., 2017) but are yet to be widely adopted in LSMs (but see (Eller et al., 2020; De Kauwe et al., 2020; Kennedy et al., 2019; Sabot et al., 2020)). Trugman et al. (2018) explored the role of soil moisture stress in simulated “potential” gross primary productivity (GPP) among CMIP5 models and argued that the functional form used to represent the effect of soil moisture stress was the major driver of carbon cycle uncertainty. Here we deliberately attempted to first resolve model biases through other avenues (e.g. soil evaporation, soil parameterisation), because it is likely that model biases originate from multiple sources (e.g. leaf area, soil moisture dynamics, etc.). We were subsequently able to assess the capacity to then further improve model behaviour via the functional forms used to represent water stress.

We examined three alternative water stress functions: the function used in Ctl (common among models), a function based on Haverd et al. (2016) ($\beta$-hvrd) and a calibrated $\beta$ ($\beta$-exp) for this site based on Yang et al. (2020). Haverd et al. (2016) hypothesised that plants optimise their root water uptake, only limiting function when water in the deepest accessible soil layer becomes limiting. They further argued that this behaviour did not vary among sites (and so species). De Kauwe et al. (2015) previously tested this hypothesis and demonstrated that it led to an underestimation of the effect of moisture stress, inconsistent with observations. Our results again show that this hypothesis is not supported by data and led to an overestimation of transpiration (Figure 6) and little evidence of moisture stress (Figure 9b). Integrated over the drought periods, we found that after reducing other model biases, the use of the calibrated $\beta$-exp function did reduce the simulated soil moisture stress (median $\beta = 0.63$ vs 0.33 in Hi-Res-2 and 0.46 in Opt, Fig 9). Overall, the various experiments show markedly different median $\beta$ (ranging from 0.67 to 0.99, considering all simulated years), consistent with previous evaluations that have highlighted differences in simulated $\beta$ across models (De Kauwe et al., 2017; Medlyn et al., 2016; Powell et al., 2013; Trugman et al., 2018). However, our results highlight that differences originate as much from alternative model assumptions and biases (e.g. soil evaporation, soil parameters) as the functional forms themselves.

Heatwaves

Differences between the versions of CABLE lead to a different initial soil moisture state at the beginning of a heatwave ranging from ~ 0.15 m$^3$ m$^{-3}$ ($\beta$-hvrd) to ~ 0.23 m$^3$ m$^{-3}$ ($Sres$) (Figure 10). In addition to the impact of the initial state, differences between parameterisation also affect estimates of $\beta$, leading to large divergences in evaporative cooling during a heatwave. Consequently, some versions of CABLE respond to the heatwave with a depression of $Q_d$ and a peak of $Q_w$ during the early to mid-afternoon while other simulations maintain a high $Q_d$ during the earlier parts of the day and shift the peak of $Q_w$ to later in the afternoon (Figure 10c-d). The magnitudes of $Q_d$ and $Q_w$ between simulations are also substantially different: Ctl would amplify a heatwave, warming and drying the boundary layer while $\beta$-hvrd would tend to moisten and (relatively) cool the boundary layer. Many studies have shown that the land surface can play a key role in amplifying heatwaves (Hirsch et al., 2019a; Miralles et al., 2014; Teuling et al., 2010) and LSMs exhibit systematic biases in representing this feedback (Sippel et al., 2017; Ukkola et al., 2018b). For a mega-heatwave like the 2010 European Heatwave, the contribution of local surface to sensible heat anomaly was ~ 20 W m$^{-2}$ (Schumacher et al., 2019). However, our results show the differences between parameterisations within a single LSM can result in a greater divergence than this value. Therefore, these feedbacks can be...
substantially changed through different parameterisations and, if coupled to an atmospheric model, may be large enough to change the frequency and magnitude of heatwaves within a model.

We also showed that at high $D$, our model overestimated transpiration, which would have consequences for subsequent soil moisture availability. Renchon et al. (2018) recently highlighted this point at the Cumberland Plains eddy covariance site which neighbours the EucFACE site. Yang et al. (2019) showed that the MAESPA canopy gas exchange model similarly overpredicted transpiration at high $D$, leading to an overprediction of annual transpiration by 19%. By examining leaf gas exchange data, they demonstrated that the reduction of transpiration could be attributed to non-stomatal limitation of photosynthesis at high $D$. Although non-stomatal limitation is commonly observed under low soil moisture content (e.g. Zhou et al. 2013) and implemented in a number of LSMs (De Kauwe et al., 2015), non-stomatal limitation at high $D$ has been much less commonly reported and is not, to our knowledge, implemented in any LSMs. To echo Yang et al. (2019), further data on non-stomatal limitation at high $D$ should be a priority, to determine whether this mechanism is sufficiently widespread to warrant inclusion in LSMs.

Future directions

We have shown that improving a LSM for one water flux is achievable, but improving a model to capture individual components of evapotranspiration and the associated soil moisture state is more challenging. No single step is sufficient in isolation and if observations only constrain one element of a model, biases can be transferred within a model. This can lead to a tendency to hide biases in seldom observed states because soil moisture profiles are rarely measured along with aboveground fluxes. International observational networks (e.g. FLUXNET; Baldocchi et al., 2001) rarely report $Q_E$, $Q_H$ and soil moisture through and below the root zone simultaneously, although soil moisture profiles do sometimes exist. Expanding observational networks to include soil moisture profiles could accelerate model development. The EucFACE dataset holds exceptional promise as a means of evaluating model simulations and refining new theory. It is freely available, contains observations of the complete water balance and captures responses to both droughts and heatwaves. More broadly, our results also speak for the importance of multi-variable model evaluation methods for LSMs (e.g. iLAMB; Hoffman et al., 2017).

Finally, our results imply that caution is needed in the interpretation of simulated heatwaves and droughts in coupled climate models. The feedback via the land surface is a key component and as our model experiments show, a range of alternative approaches can produce very different coupling between the land and the atmosphere if embedded in a coupled model. Despite the difficulties in acquiring datasets of the complete water balance, as a community we need to find an avenue to better assess (coupled) model predictions. Critical Zone Observatory Networks (Brantley et al., 2017) may be one means to better constrain models, but in all likelihood, targeted field campaigns that collect observations of soil moisture, eddy-covariance and the boundary layer are also needed.

Code and data availability: CABLE code is available at https://trac.nci.org.au/trac/cable/wiki after registration. Here, we use CABLE revision r7278. Scripts for plotting and processing model outputs are available at https://github.com/bibivking/Evaluate_CABLE_EucFACE.git. EucFACE observations are publicly available in Western Sydney University’s archive http://doi.org/10.4225/35/5ab9bd1e2f4fb (Gimeno et al., 2018b), and in https://doi.org/10.5281/zenodo.3610698 (Yang, 2019).

Author contributions. MGDK, MM, AJP and AMU put forward the general scientific questions, designed the model experiments, investigated the simulations and drafted the manuscript. TEG, BEM, JY and DSE endeavoured to collect, to process and to correct the EucFACE observations. All authors participated in the discussion and revision of the manuscript.
Competing interest. The authors declare that they have no conflict of interest.

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References


Figure 1. (a) Location of the experimental site in western Sydney, Australia (33°36′59″S, 150°44′17″E) shown by the red star. (b) Distribution of six rings (© Google Maps, 2020. EucFACE experiment site, 1:50. Google Maps [https://www.google.com/maps/@-33.6177915,150.7379194,356m/data=!3m1!1e3]). (c) Understorey vegetation and infrastructure inside a ring (photograph taken by M. M.). (d) Canopy structure and central tower (photograph taken by M. M.).
Figure 2. Control simulation (Ctl). (a) $E_{tr}$, $E_s$ and precipitation ($P$) between 2013 and 2015. The shaded areas represent uncertainty between three ambient rings. Both simulations and observations are smoothed with a 3-day window to aid visualisation. (b) $\theta$ in the top 0.25m from 2013 to 2019. (c) The vertical distribution of $\theta$ measured at observed dates from 2013 to 2019. (d) The vertical distribution of $\theta$ in Ctl for observed dates from 2013 to 2019. (e) $\theta$ differences between CABLE and observations (note, for (c), (d) and (e) the horizontal axis is not linear, rather it reflects periods of observations).
Figure 3. Increasing soil evaporation resistance experiment (Sres). (a) $E_s$ between 2013 and 2015. (b) $E_{tr}$ between 2013 and 2015. In panel (a) and (b) the shaded areas represent uncertainty between three ambient rings, and both simulations and observations are smoothed with a 3-day window to aid visualisation. (c) The vertical distribution of $\theta$ in Sres at observed dates from 2013 to 2019. (d) $\theta$ difference between CABLE and observations (note, for (c) and (d) the horizontal axis is not linear, rather it reflects periods of observations).
Figure 4. Water table initialisation experiment (Watr). (a) $E_r$ and $E_s$ between 2013 and 2015. The shaded areas represent uncertainty between three ambient rings. Both simulations and observations are smoothed with a 3-day window to aid visualisation. (b) $\theta$ in the top 0.25m from 2013 to 2019. (c) The vertical distribution of $\theta$ in $Watr$ at observed dates from 2013 to 2019. (d) $\theta$ difference between CABLE and observations (note, for (c) and (d) the horizontal axis is not linear, rather it reflects periods of observations).
Figure 5. High soil resolution experiment (Hi-Res-2), which uses 31 soil layers with depth-varying hydraulic parameters informed by observed soil properties. (a) $E_T$ and $E_s$ between 2013 and 2015. The shaded areas represent uncertainty between three ambient rings. Both simulations and observations are smoothed with a 3-day window to aid visualisation. (b) $\theta$ in the top 0.25 m from 2013 to 2019. (c) The vertical distribution of $\theta$ in Hi-Res-2 at observed dates from 2013 to 2019. (d) $\theta$ difference between CABLE and observations (note, for (c) and (d) the horizontal axis is not linear, rather it reflects periods of observations).
Figure 6. Haverd water stress function experiment ($\beta$-hvrd). (a) $E_T$ and $E_s$ between 2013 and 2015. The shaded areas represent uncertainty between three ambient rings. Both simulations and observations are smoothed with a 3-day window to aid visualisation. (b) $\theta$ in the top 0.25m from 2013 to 2019. (c) The vertical distribution of $\theta$ in $\beta$-hvrd at observed dates from 2013 to 2019. (d) $\theta$ difference between CABLE and observations (note, for (c) and (d) the horizontal axis is not linear, rather it reflects periods of observations).
Figure 7. Site-based water stress function experiment (β-exp). (a) $E_T$ and $E_s$ between 2013 and 2015. The shaded areas represent uncertainty between three ambient rings. Both simulations and observations are smoothed with a 3-day window to aid visualisation. (b) $θ$ in the top 0.25m from 2013 to 2019. (c) The vertical distribution of $θ$ in β-exp at observed dates from 2013 to 2019. (d) $θ$ difference between CABLE and observations (note, for (c) and (d) the horizontal axis is not linear, rather it reflects periods of observations).
Figure 8. Simulations for each experiment during the drought period (October 2017 to September 2018). (a) the root zone soil moisture over top 1.5 m ($\theta_{1.5m}$) and rainfall ($P$, bars), with blue dots showing the observed soil moisture. (b) $E_T$, (c) water stress factor ($\beta$), (d) $E_s$ and (e) sensible heat ($Q_H$). All lines are smoothed with a 30-day window.
Figure 9. (a) Box plot of simulated $\beta$ during a drought year (October 2017 - September 2018) and all simulated years (2013-2019). The dashed line is the mean value of $\beta$ in Ctl over the dry period. (b) $\beta$ variance with root zone soil moisture over the top 1.5m ($\theta_{1.5m}$) during all simulated years.
Figure 10. Simulations during an observed heatwave with relatively low soil moisture (19-22 January 2018). (a) Air temperature ($T_{air}$; in black) and soil moisture within root zone over the top 1.5m ($\theta_{1.5m}$). The black dashed line shows the 35°C threshold. (b) evaporative fraction ($EF$; calculated for day-time conditions), (c) latent heat ($Q_{E}$) and (d) sensible heat ($Q_{H}$). One day before the heatwave is also shown.
Figure 11. Modelled hourly $E_{tr}$ compared with measured hourly $E_{tr}$ over 2013. The solid line represents the 1:1 line. The dashed line is the linear fit between modelled and measured $E_{tr}$. Colours of dots indicate the range of vapour pressure deficit.
Table 1. The experiments conducted. Layers refers to the number of soil layers. Increase resistance refers to whether increasing surface resistance to soil evaporation. Soil heterogeneity indicates whether soil properties and hydraulic parameters change with depth. The adjustment of $\theta_w$, $\theta_{sat}$ and $K_{sat}$ and the method used to calculate $\beta$ are the final two columns.

<table>
<thead>
<tr>
<th>Experiment</th>
<th>Layers</th>
<th>Increase Resistance</th>
<th>Soil heterogeneity</th>
<th>Parameter adjustment</th>
<th>$\beta$</th>
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<td></td>
<td></td>
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</tr>
<tr>
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<td>Y</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Watr</td>
<td>6</td>
<td>Y</td>
<td></td>
<td></td>
<td></td>
</tr>
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<td></td>
<td></td>
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<td>Y</td>
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<tr>
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<td>Y</td>
<td>Y</td>
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<td>default</td>
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<td>Y</td>
<td>As per Opt</td>
<td>Haverd</td>
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<tr>
<td>$\beta$-exp</td>
<td>3</td>
<td>Y</td>
<td>Y</td>
<td>As per Opt</td>
<td>in situ</td>
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Table 2. Performance metrics for the different experiments. Bold numbers are the best value among these experiments.

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<tr>
<th>Simulation</th>
<th>Variable</th>
<th>$r$</th>
<th>RMSE mm or m$^3$</th>
<th>MBE mm or m$^3$</th>
<th>PS mm or m$^3$</th>
<th>P95 mm or m$^3$</th>
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<tr>
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<td>$E_w$</td>
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<td>0.19</td>
<td>0.01</td>
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Table 3. Average values from each experiment. Precipitation ($P$), total evapotranspiration ($ET$), transpiration ($E_t$), soil evaporation ($E_s$), canopy evaporation ($E_c$), total runoff ($R$) including surface and subsurface runoff, soil water drainage to aquifer ($D_r$), gross primary production ($GPP$), latent heat ($Q_E$), sensible heat ($Q_H$), and volumetric water content in the 4.6m soil column ($\theta$). 

<table>
<thead>
<tr>
<th>Simulation</th>
<th>$E_t$ (mm y$^{-1}$)</th>
<th>$E_s$ (mm y$^{-1}$)</th>
<th>$E_c$ (mm y$^{-1}$)</th>
<th>$E_r$ (mm y$^{-1}$)</th>
<th>$R$ (mm y$^{-1}$)</th>
<th>$D_r$ (mm y$^{-1}$)</th>
<th>$GPP$ (g C m$^{-2}$ y$^{-1}$)</th>
<th>$Q_E$ (W m$^{-2}$)</th>
<th>$Q_H$ (W m$^{-2}$)</th>
<th>$\theta$ (m$^3$ m$^{-3}$)</th>
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<td>657</td>
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<td>305</td>
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