1	A Comprehensive Quasi-3D Model for Regional-Scale Unsaturated-
2	Saturated Water Flow
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22 Abstract: For computationally efficient modeling of unsaturated-saturated flow in 23 regional scales, the Quasi three-dimensional (3-D) scheme that considering one-24 dimensional (1-D) soil water flow and 3-D groundwater flow is an alternative method. 25 However, it is still practically challenging for regional-scale problems due to the high 26 non-linear and intensive input data needed for soil water modeling and the reliability of 27 the coupling scheme. This study developed a new Quasi-3D model coupled the 1-D soil 28 water balance model UBMOD with the 3-D hydrodynamic model MODFLOW. A new 29 implementation method of the iterative scheme was developed, in which the vertical 30 net recharge and unsaturated zone depth were used as the exchange information. A 31 modeling framework was developed to organize the coupling scheme of the soil water 32 model and the groundwater model and to handle the pre- and the post-processing 33 information. The strength and weakness of the coupled model were evaluated by using 34 two published studies. The comparison results show that the coupled model is 35 satisfactory in terms of computational accuracy and mass balance error. The influence 36 of spatial and temporal discretization as well as the stress period on the model accuracy were discussed. Additionally, the coupled model was used to evaluate groundwater 37 38 recharge in a real-world study. The measured groundwater table and soil water content 39 were used to calibrate the model parameters, and the groundwater recharge data from a 40 two years' tracer experiment was used to evaluate the recharge estimation. The field 41 application further shows the practicability of the model. The developed model and the 42 modeling framework provide a convenient and flexible tool for evaluating unsaturated-43 saturated flow system at the regional scale.

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46 **1 Introduction**

While groundwater resource is important for the domestic, agricultural, and
industrial uses, groundwater is vulnerable due to over-exploitation, climate change, and

49	biochemical pollution (Bouwer, 2000; Sophocleous, 2005; Evans and Sadler, 2008;
50	Karandish et al., 2015; Zhang et al., 2018). For protecting or exploiting groundwater
51	resource, understanding soil water flow system is necessary as soil water is the major
52	source of groundwater recharge and destination of phreatic consumption (Yang et al.,
53	2016; Wang et al., 2017). The Richards' equation is usually used to describe the soil
54	water flow and groundwater flow. Many numerical schemes have been developed to
55	solve the three-dimensional (3-D) Richards' equation (Weill et al., 2009) in computer
56	codes, such as HYDRUS (Šimůnek et al., 2012), FEFLOW (Diersch, 2013),
57	HydroGeoSphere (Brunner and Simmons, 2012), InHM (VanderKwaak and Loague,
58	2001) and MODHMS (Tian et al., 2015). These fully 3-D models have solid theoretical
59	foundation, and have been used for regional scale unsaturated-saturated water flow
60	simulation. However, since the soil water flow is highly nonlinear in nature and
61	sensitive to atmospheric changes, soil utilizations, and human activities, the numerical
62	schemes require using fine discretization in vertical space and time for accurate
63	numerical solutions (Downer and Ogden, 2004; Varado et al., 2006). This makes the
64	numerical solutions computationally expensive, especially for large scale modeling
65	(Van Walsum and Groenendijk, 2008; Shen and Phanikumar, 2010; Yang et al., 2016;
66	Szymkiewicz et al., 2018). There are also many conceptual unsaturated-saturated water
67	flow models, e.g., SWAT (Arnold et al., 2012), INFIL 3.0 (Fill, 2008), HSPF (Duda et
68	al., 2012) and SALTMOD (Oosterbaan, 1998), which show advantages in mass balance
69	and computational cost. However, these models usually adopt many empirical

equations which result in poor performance comparing with the fully 3-D numericalmodels.

72 To address the computational challenges discussed above, a variety of 73 simplifications have been introduced for the soil water flow for regional scale problems. 74 One simplification is to treat the hydrological processes (e.g., infiltration, 75 evapotranspiration, and deep percolation) occurring in the unsaturated zone as one-76 dimensional (1-D) processes in the vertical direction. Field experiments at the regional 77 scale also show that, in the unsaturated zone, the lateral hydraulic gradient is usually 78 significantly smaller than the vertical gradient (Sherlock et al., 2002). This 1-D 79 simplification leads to the Quasi-3D scheme, which ignores the lateral flow in the 80 unsaturated zone but considers groundwater flow as a 3-D problem. The Quasi-3D 81 scheme avoids solving the 3-D Richards' equation for the unsaturated zone, and thus 82 improves computational efficiency and model stability. The Quasi-3D scheme is an 83 efficient solution for large-scale unsaturated-saturated flow modeling (Twarakavi, et al., 84 2008; Yang et al., 2016) and is popular among groundwater modelers (Havard et al., 85 1995; Harter and Hopmans, 2004; Graham and Butts, 2005; Stoppelenburg et al., 2005; Seo et al., 2007; Markstrom et al., 2008; Ranatunga et al., 2008; Kuznetsov et al., 2012; 86 Xu et al., 2012; Zhu et al., 2012; Leterme et al., 2015). However, it is still challenging 87 88 when using the Quasi-3D models for a practical regional scale problem. Two concerns 89 arise as follows.



The first concern is the unsaturated modeling method. Although the Quasi-3D

91 scheme is computationally efficient, the numerical solutions of the 1-D Richards' equation still require intensive input data, and face numerical instability and mass 92 93 balance errors under some specific situations (Zha et al., 2017). These problems limit 94 their practical application for simulating regional scale problems under complicated 95 geological and climate conditions as well as anthropogenic activities. As an alternative 96 to the numerical solutions of the 1-D Richards' equation, water balance models have 97 been used to describe soil water movements, which not only reduce the amount of input data but also improve computational efficiency and stability. The water balance models 98 99 can be coupled with groundwater models. Facchi et al. (2004) coupled a conceptual soil water movement model SVAT with MODFLOW to simulate the hydrological relevant 100 processes in the alluvial irrigated plains. Kim et al. (2008) integrated SWAT with 101 102 MODFLOW to describe the exchange between hydrologic response units in the SWAT 103 model and MODFLOW cells. The traditional water balance models however, may 104 oversimplify soil water movement, and thus cannot accurately represent certain 105 important features of soil water flow, e.g., the upward flux and soil heterogeneity. To 106 extend the application of water balance model for more complicated conditions, Mao 107 et al. (2018) developed a soil water balance model (called UBMOD model), which can simulate both upward and downward soil water movement in heterogeneous situation. 108 109 And the model can be used with a coarse discretization in space and time, all of which 110 make it suitable for the large-scale modeling.

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Another concern is the scheme when coupling saturated models with unsaturated

112	models. There are three different numerical coupling schemes categorized by Furman
113	(2008): uncoupled, iterative coupled, and fully coupled. The uncoupled scheme is
114	widely used when using soil water flow packages with MODFLOW, such as
115	LINKFLOW (Havard et al., 1995), SVAT-MODFLOW (Facchi et al., 2004), UZF1-
116	MODFLOW (Niswonger et al., 2006), HYDRUS-MODFLOW (Seo et al., 2007),
117	SWAP-MODFLOW (Xu et al., 2012). While this scheme is easy to be implemented,
118	its results may not reliable when recharge from the unsaturated zone causes substantial
119	changes of water table. Additionally, this scheme may result in the mass balance error
120	(Shen and Phanikumar, 2010; Kuznetsov et al., 2012). The fully coupled scheme is
121	mathematically and computationally rigorous, because it solves unsaturated and
122	saturated flows simultaneously with internal boundary conditions of the two flows (Zhu
123	et al., 2012). However, the fully coupled scheme is computationally expensive (Furman,
124	2008). The iterative coupled scheme offers a trade-off between model accuracy and
125	computational cost (Yakirevich et al., 1998; Liang et al., 2003). And it has been widely
126	used to couple two hydrodynamic models, both of which calculate the hydraulic head,
127	and use the hydraulic head as the exchange information (Stoppelenburg et al., 2005;
128	Kuznetsov et al., 2012). However, the soil water content is the variable calculated by
129	soil water balance models other than the hydraulic head. Therefore, the traditional
130	implementation method of the iterative scheme is inapplicability, and a specific
131	implementation method of the iterative scheme should be developed to couple the soil
132	water balance model and the hydrodynamic groundwater model.

133 In this study, a new Quasi-3D model is developed. The 1-D water balance model UBMOD developed by Mao et al. (2018) is integrated with MODFLOW (Harbaugh, 134 135 2005). A new implementation method of the iterative scheme is established for 136 numerical solutions, and the net groundwater recharge and the depth of unsaturated 137 zone (which is equal to the groundwater table depth) are chosen as the exchange 138 information. The coupled model can achieve mass balance and keep numerical stability 139 well, and it is suitable for large-scale modeling based on the characteristics of MODFLOW and UBMOD. Moreover, instead of developing a new package for 140 141 MODFLOW, a framework of organizing the modeling procedures is developed. This paper elaborates the methodology of coupling the unsaturated and saturated water flow 142 and the modeling framework in Sect. 2. Two published studies are used to test the 143 144 performance of the coupled model when handling different water flow conditions in 145 Sect. 3. A real-world application to study the regional net groundwater recharge is 146 presented in Sect. 4.

147 2 Methodology and Model Development

In the new coupled model, the unsaturated-saturated domain is partitioned into a number of sub-areas in the horizontal direction mainly according to the spatially distributed inputs (soil types, atmosphere boundary conditions, land usage types, and crop types). A 1-D soil column is used to characterize the average soil water flow in each sub-area, and UBMOD is used to simulate the 1-D soil water flow. MODFLOW is used to simulate the 3-D groundwater flow of the whole domain. It is assumed that 154 the flow in the unsaturated zone is in the vertical direction, and that there is only vertical 155 exchange flux between the unsaturated and saturated zones. It is further assumed that 156 using the vertical column can reasonably simulate the unsaturated flow in each sub-area while ignoring the horizontal heterogeneity. In this section, UBMOD is first presented, 157 158 followed by a brief introduction of MODFLOW and two peripheral tools (FloPy 159 (Bakker et al., 2016) and ArcPy (Toms, 2015)) used in the model. The procedures of 160 the new model and the modeling framework are described in Sect. 2.3, and the specific 161 implementation method of the unsaturated and saturated coupling scheme is described 162 in Sect. 2.4.

163 2.1 The Soil Water Balance Model UBMOD

164 This section describes the soil water balance model UBMOD to make this paper 165 self-contained, and more details of UBMOD are referred to Mao et al. (2018) or the 166 Appendix. The UBMOD is a water balance model based on a hybrid of numerical and 167 statistical methods. The model can effectively and efficiently simulate both downward 168 and upward soil water movement with only four physically meaning parameters, which 169 makes it suitable for practical application.

170 There are four major components to describe the soil water movement in UBMOD.

Firstly, the vertical soil column is divided into a cascade of "buckets" and each "bucket"
corresponds to a soil layer. The "buckets" will be filled to saturation from the top layer
to the bottom layer if there is infiltration, which is referred as the allocation of
infiltration water. Specifically speaking, the infiltration water first fills the top "bucket",

and then the excessive infiltration water moves downward to the next "bucket", until all the infiltration water is allocated in the "buckets". The governing equation of layer i is,

178
$$q_i = \min\left(M_i \times \left(\theta_{s,i} - \theta_i\right), I - I_{d,i-1}\right), \tag{1}$$

where *i* indicates the vertical soil layer, i = 1, ..., j; q_i is the amount of allocated water per unit area of layer *i* [L]; M_i is the thickness of layer *i* [L]; θ_i is the initial soil water content of layer *i* [L³L⁻³]; $\theta_{s,i}$ is the saturated soil water content of layer *i* [L³L⁻³]; *I* is the quantity of infiltration rate [L]; $I_{d, i-1}$ is the consumed infiltration water per unit area by all upper layers above layer *i* [L]. The infiltration rate *I* is an input data in the model, and the partitioning of rainfall between infiltration and runoff has not been considered by now.

186 Secondly, when the soil water content exceeds the field capacity, the soil water187 will move downward driven by the gravitational potential. The governing equation is,

188
$$\frac{\partial \theta}{\partial t} = -\frac{\partial K(\theta)}{\partial z},$$
 (2)

189 where *t* is the time [T]; *z* is the elevation in the vertical direction [L]. The vertical 190 coordinate is positive downward. $K(\theta)$ is the unsaturated hydraulic conductivity [LT⁻¹] 191 as a function of soil water content, which is characterized by empirical formulas 192 referred to as drainage functions. The commonly used equations can be found in Mao 193 et al. (2018) and the Appendix.

194 Thirdly, the source/sink terms are used to account for soil evaporation and crop195 transpiration. The governing equation is as follows,

196
$$\frac{\partial \theta}{\partial t} = -W, \qquad (3)$$

197 where *W* is the source/sink term $[T^{-1}]$. The Penman-Monteith formula and Beer's law 198 (also known as Ritchie-type equation) are adopted to estimate the potential soil 199 evaporation E_p and potential crop transpiration T_p . Then E_p and T_p are distributed to 200 each layer based on the evaporation cumulative distribution function and the root 201 density function. The actual soil evaporation and crop transpiration are obtained by 202 discounting E_p and T_p with the soil water stress coefficient.

Lastly, we calculate the diffusive movement driven by the matric potential. Thegoverning equation is,

205
$$\frac{\partial \theta}{\partial t} = \frac{\partial}{\partial z} \left(D(\theta) \frac{\partial \theta}{\partial z} \right), \tag{4}$$

where $D(\theta)$ is the hydraulic diffusivity [L²T⁻¹]. The finite difference method is used to 206 solve the equation. An empirical formula with four parameters (saturated hydraulic 207 conductivity K_s , saturated water content θ_s , field capacity θ_f , and residual water content 208 209 $\theta_{\rm r}$) is used to describe the hydraulic diffusivity $D(\theta)$. The heterogeneity of soils is also 210 taken into account by adding a correction item in the right side, which makes the model 211 applicable to heterogeneous situations. With the help of the diffusive term, the UBMOD 212 can consider upward soil water movement, which is ignored by most water balance 213 models. The details of $D(\theta)$ are shown in the Appendix.

The original UBMOD is a soil water balance model, which cannot consider groundwater table. For the purpose of saturated-unsaturated coupling, the model has been improved to calculate the groundwater recharge, which is expatiated in Sect. 2.4.

217 **2.2** The Brief Introduction of MODFLOW and Two Peripheral Tools

MODFLOW is a computer program that numerically solves the 3-D groundwater flow equation for a porous medium using a block-centered finite-difference method (Harbaugh, 2005). The governing equation solved by MODFLOW is,

221
$$\frac{\partial}{\partial x_i} \left(K_{ij} \frac{\partial H}{\partial x_j} \right) + W = S_s \frac{\partial H}{\partial t}, \qquad (5)$$

where i, j = 1 - 3 indicate the x, y, and z directions, respectively; K_{ij} is the saturated hydraulic conductivity $[LT^{-1}]$; H is the hydraulic head [L]; W is the volumetric flux per unit volume representing sources and/or sinks of water $[L^{3}T^{-1}]$; S_{s} is the specific storage of the porous material $[L^{-1}]$; and t is the time [T].

226 FloPy and ArcPy are the two peripheral tools used in the model development. FloPy (Bakker et al., 2016) is a Python package for creating, running, and post-227 processing MODFLOW-based models. Unlike the commonly graphical user interfaces 228 229 (GUIs) method, FloPy facilitates users to write a Python script to construct and post-230 process MODFLOW models, and it has been shown as a convenient and powerful tool 231 by Bakker et al. (2016). Geographic information system (GIS) is a helpful tool for 232 groundwater modeling by providing geospatial database and results presentation (Xu et 233 al., 2011; Lachaal et al., 2012). ArcPy is an application program interface (API) of 234 ArcGIS for Python (Toms, 2015), which provides a useful and productive way to perform geographic data analysis, data conversion, data management, and map 235 automation with Python. 236

237 2.3 The Process of Geographic Input Information

238 The procedures of the modeling framework are composed of three major parts, including the pre-processing, the coupled model, and the post-processing. The 239 preparation of geographic input information of the model shown in Fig. 1(a) is the major 240 241 component of pre-processing. The geographic information includes the domain area, 242 boundary conditions, sub-areas, digital elevation model (DEM), hydraulic conductivity 243 and porosity. The shapefile of the domain area (usually irregular in shape) is first discretized by regular boundary with both active and inactive cells. The discretized 244 domain can be joined with the shapefile of boundary condition to generate the "ibound" 245 246 array of MODFLOW as shown in Fig. 1(a), which is used to specify which cells are 247 active, inactive, or fixed head in MODFLOW. The shapefile of sub-areas is joined with the domain file, represented in subareas array with different number specified as 248 249 different sub-areas. The raster files of DEM, hydraulic conductivity and porosity are 250 further joined, and the values of these variables are listed in the arrays shown in Fig.1 251 (a). The unsaturated-saturated flow model coupling scheme will be described in next 252 section. The results presentations are accomplished by the post-processing tool, which 253 contains a series of utilities developed based on Python packages.

254

2.4 Coupling Scheme of UBMOD and MODFLOW

Figure 1(b) demonstrates the sketch map of the specific implementation method of the unsaturated and saturated coupling scheme. The unsaturated-saturated domain is partitioned into a number of sub-areas in the horizontal direction mainly according to the spatially distributed inputs (each sub-area is considered to be homogeneous in 259 horizontal). There are *l* sub-areas, *j* layers for a specific soil column shown in Fig. 1(b). Soil water flow of each sub-area is simulated by using one 1-D soil column. The 260 261 recharge at the bottom boundary calculated by UBMOD is treated as the upper 262 boundary condition of MODFLOW. The whole saturated zone is discretized into a grid 263 with cells, and there are m rows and n columns cells of the saturated zone as shown in 264 Fig. 1(b). All cells in the same sub-area receive the same recharge from soil zone 265 calculated by the representative 1-D soil column. In the vertical direction, both the 266 saturated domain and the soil columns are discretized into different layers based on 267 available data and information, and the layer discretization remain unchanged during the simulation. The lower boundary condition of the whole region is set in MODFLOW. 268 269 As the soil water movement is reduced to 1-D flow, the surrounding boundary 270 conditions for the unsaturated zone are no-flux boundary, while the surrounding 271 boundary conditions for the saturated zone are set in MODFLOW as practical. Note 272 that the saturated zone and the unsaturated zone are independent, but some layers may 273 transform between the saturated zone and the unsaturated zone, which are referred as 274 the overlap region. Fine vertical discretization of UBMOD in the overlap region is 275 needed to improve the simulation accuracy.

Since the independent variable of UBMOD is the soil water content and the independent variable of MODFLOW is the hydraulic head, this study uses the vertical net recharge and the unsaturated zone depth to couple the unsaturated zone and saturated zone. The domain shown in Fig. 1(b) is used as an example to illustrate the spatial and temporal coupling methods in the study. The vertical net recharge is represented by vector **R** with $m \times n$ elements, and the unsaturated zone depth by vector **Du** with *l* elements, as illustrated in Fig. 1(b). Scalar *R* is used to denote the specific net recharge of a soil column to the corresponding saturated sub-area, and scalar d_u denotes the depth of the soil column. Figure 2(a) shows the spatial coupling method of a soil column connected with groundwater system. The water table locates in the *j*-th layer. The net recharge *R* from soil zone is calculated by UBMOD as follows,

287 $R = q_{\rm I} + q_{\rm A} + q_{\rm S} + q_{\rm D},$ (6)

where $q_{\rm I}$, $q_{\rm A}$, $q_{\rm S}$ and $q_{\rm D}$ are the fluxes across the water table caused by allocation of the infiltration water, the advective movement driven by the gravitational potential, source/sink terms and the water diffusion driven by the matric potential per unit area, respectively [L].

292 These four terms are corresponded to the four major components in UBMOD, as 293 described in Sect. 2.1. Specifically, the infiltration water is allocated first according to 294 Eq. (1) if there is precipitation or irrigation. When there is residual infiltration water 295 across the water table in the *j*-th layer, the amount of residual infiltration is denoted as $q_{\rm I}$. Then the advective flow $q_{\rm A}$ across the water table driven by gravitational potential 296 is calculated by Eq. (2). The direction of these two terms is downward. The $q_{\rm S}$ term is 297 298 caused by evapotranspiration. When the critical depth of evapotranspiration is 299 shallower than the groundwater table depth, the groundwater can be consumed by evapotranspiration and it causes an upward $q_{\rm S}$ term. A virtual layer is needed when 300

301 calculating the diffusive movement driven by matric potential across the water table 302 based on Eq. (4). As shown in Fig. 2 (a), the virtual layer will be added under water 303 table, numbered as layer j+1. The thickness, M_{j+1} [L], of the layer is set as,

 $304 M_{i+1} = z_{i+1} - d_u, (7)$

305 where z_{j+1} is the bottom depth of layer j+1 [L]; d_u is the thickness of unsaturated zone 306 [L]. The amount of the upward flux between the virtual layer and layer j is denoted as 307 q_D . Then, the net recharge matrix **R** for the whole area is obtained and used for the 308 Recharge (RCH) package of MODFLOW.

309 The time coupling method is shown in Fig. 2(b). There are three levels of time discretization in the coupled model as follows: the stress period ΔT used in MODFLOW, 310 the calculation time step for MODFLOW Δt_s , and the calculation time step for UBMOD 311 312 $\Delta t_{\rm u}$. The stress time step (ΔT) is also used in the iterative process, and the unsaturated 313 model UBMOD and saturated model MODFLOW exchange information at the end of 314 each stress period. Δt_u is a priori value and cannot be changed during the calculation. 315 The UBMOD can give acceptable results when Δt_u is shorter than 10 d for assumed 316 cases and 1 d for a real-world case (Mao et al., 2018). Δt_s is set as the technical report 317 described by Harbaugh (2005) and can be changed during the calculation. 318 The implementation of iterative coupling scheme is shown in Fig. 2(c), which

shows the calculation period from *t* to $t+\Delta T$. At the time *t*, the saturated hydraulic head is known, marked as \mathbf{H}^{t} (*m*×*n* dimension). When the model runs from *t* to $t+\Delta T$, firstly, the initial saturated hydraulic head $\mathbf{H}^{t+\Delta T}$ at $t+\Delta T$ is set to be equal to \mathbf{H}^{t} , and then the 322 average unsaturated depth from t to $t+\Delta T$ is calculated according to $\mathbf{H}^{t+\Delta T}$, marked as 323 $\mathbf{D}\mathbf{u}^{t+\Delta T, p}$ (*l* elements). p is the iteration level. The $d_u^{t+\Delta T, p}$ for one soil column is 324 calculated as follows,

325

$$d_{u}^{t+\Delta T,p} = \overline{D} - H^{t+\Delta T} , \qquad (8)$$

where \overline{D} is the average depth from the soil surface to the impermeable layer of the controlling domain of the soil column [L]; $\overline{H^{t+\Delta T}}$ is the average thickness of controlling saturated domain of the soil column [L].

329 Secondly, the model runs UBMOD with the unsaturated time step Δt_u to obtain the 330 vertical recharge at each time step (marked as r_t) until the time comes to be $t+\Delta T$. The 331 total recharge during the stress period ΔT (from t to $t+\Delta T$) $R_{\Delta T}$ can be obtained by 332 summarizing the recharge at each unsaturated time step, as follows,

$$R_{\Delta T} = \sum_{t}^{t+\Delta T} r_t , \qquad (9)$$

334 The average recharge *R* from *t* to $t+\Delta T$ can be obtained by,

$$R = R_{\Delta T} / \Delta T . \tag{10}$$

Then the average recharge from all 1-D soil columns can be obtained, represented as $\mathbf{R}^{t+\Delta T, p}$, which is then used by the MODFLOW RCH package. Subsequently, the model runs the MODFLOW model with the saturated time step Δt_s to obtain the saturated hydraulic head until the time comes to $t+\Delta T$. The hydraulic head at the time $t+\Delta T$ is marked as $\mathbf{H}^{t+\Delta T, p}$ ($m \times n$ dimension). The convergence of the iteration is determined by using the difference of hydraulic head between the present $\mathbf{H}^{t+\Delta T, p}$ and the initial $\mathbf{H}^{t+\Delta T}$. The convergence criterion is,

343
$$if \max\left(\left|\mathbf{H}^{t+\Delta T,p}-\mathbf{H}^{t+\Delta T}\right|\right) < \varepsilon_{H}, \tag{11}$$

where ε_H is a user-specified tolerance [L]. If the criterion is met, the iteration stops, and H^{t+ $\Delta T, p$} is the convergent results at time t+ ΔT , and the model proceeds to the next stress period. Otherwise, the iteration continues to p+1 and H^{t+ $\Delta T, p$} will be used to calculate the average unsaturated depth shown in Eq. (8). The above procedures will be repeated until the convergence criterion of Eq. (11) is met.

349 **3 Model Evaluation**

350 In this section, two test cases were designed to evaluate the model accuracy and 351 the performance of the numerical coupling scheme under complicated soil and 352 boundary conditions. The simulation results were compared with numerical results obtained using HYDRUS-1D (Šimůnek et al., 2008) and SWMS2D (Šimůnek et al., 353 354 1994), and with published experimental data. For these cases, the mean absolute relative error (ARE), the root mean squared error (RMSE), the index of agreement (IA) and the 355 determination coefficient (R^2) are used to quantitatively evaluate the misfit between the 356 simulated results of the coupled model and reference values, which are calculated as, 357

358
$$ARE = \frac{1}{x} \sum_{i=1}^{x} \frac{|y_i - Y_i|}{Y_i} \times 100\%, \qquad (12)$$

359
$$RMSE = \sqrt{\frac{1}{x} \sum_{i=1}^{x} (Y_i - y_i)^2}, \qquad (13)$$

360
$$IA = 1 - \frac{\sum_{i=1}^{x} (y_i - Y_i)^2}{\sum_{i=1}^{x} \left[|y_i - \overline{y}| + |Y_i - \overline{Y}| \right]^2}, \qquad (14)$$

361
$$R^{2} = 1 - \frac{\sum_{i=1}^{x} (y_{i} - \overline{Y}_{i})^{2}}{\sum_{i=1}^{x} (Y_{i} - \overline{Y})^{2}},$$
 (15)

where the subscript *i* represents the serial number of the results; *x* represents the total number of the results; y_i is the simulated result of the coupled model and Y_i is the reference result; \overline{y} is the average simulated result and \overline{Y} is the average reference result.

366 3.1 Two Test Cases

367 3.1.1 Case 1: 1D upward flux with atmospheric condition

368 This case was to test the performance of the coupling scheme explained in Sect. 2.4. The case simulated a single field soil profile of the Hupselse Beek watershed in the 369 370 Netherlands, which was used as a demo in HYDRUS-1D technical manual (Šimůnek, 371 2008). The soil profile consists of a 0.4 m-thick upper layer and a 1.9 m-thick bottom 372 layer. The depth of the root zone is 0.3 m. The hydraulic parameters of the two soil 373 layers are presented in Table 1. The surface boundary condition involves actual 374 precipitation and potential transpiration rate as shown in Fig. 3. The groundwater level 375 was initially set at 0.55 m below the soil surface. Only one vertical soil column and one 376 MODFLOW cell were used in the coupled model. The parameters used in the coupled model are also listed in Table 1. The results from HYDRUS-1D were used as the 377 378 reference of this test case. The stress period ΔT was set as 5 d, and the MODFLOW 379 time step Δt_s and the UBMOD time step Δt_u were both set to be 1 d. The spatial discretization was 0.1 m. 380

381	To figure out the influence of the temporal and spatial discretization as well as the
382	stress period on the simulation results, scenarios with different temporal and spatial
383	resolution and the stress period of the coupled model were performed. Scenario 1 was
384	set as the same as the above case. The UBMOD time step of scenario 2 and scenario 3
385	were 0.5 d and 2 d while other inputs were the same as scenario 1. The spatial
386	discretization of scenario 4 and scenario 5 were set as 0.05 m and 0.2 m, while other
387	inputs were the same as scenario 1. The stress period of scenario 6, scenario 7 and
388	scenario 8 were set as 8 d, 10 d and 15 d while other inputs were the same as scenario
389	1. The 8 scenarios were marked as S1-S8.

390 3.1.2 Case 2: Two-dimensional (2-D) water table recharge experiment

391 This test case was used for model validation in a 2-D unsaturated-saturated flow 392 system. The purpose of the case is to discuss the performance of the model under the condition with large lateral flux in the unsaturated zone. The numerical simulation of 393 394 our model was compared with the data of a 2-D water table recharge experiment 395 conducted by Vauclin et al. (1979). The experimental data have been used to test the variably saturated flow models (Clement et al., 1994) and coupled unsaturated-396 saturated flow models (Thoms et al., 2006; Twarakavi et al., 2008; Shen and 397 398 Phanikumar, 2010; Xu et al., 2012). The 2-D domain is a rectangular sandy soil slab of $6.0 \times 2.0 \times 0.05$ m. The initial pressure head is 0.65 m at the domain bottom. At the soil 399 400 surface, a constant flux of q = 3.55 m/d is applied at the central 1.0 m, and the rest soil surface is the no flux boundary. Because of the symmetry of the flow system, only one 401

402	half of domain (right side) with the size of 3.0 m \times 2.0 m \times 0.05 was simulated. The
403	setup of the simulation is shown in Fig. 4(a). No-flow boundaries were defined on the
404	bottom and the left side, and specified hydraulic head boundary of 0.65 m was set on
405	the right side. The values of soil hydraulic parameters are listed in Table 1. The
406	simulation period is 8 h. In our coupled model, there were 30 uniform rectangular cells
407	used by MODFLOW, and there were 10 sub-areas defined to represent the unsaturated
408	zone, which were numbered from left to right. The first and last sub-areas covered 0.2
409	m and 0.4 m in the x direction respectively, and each of the rest sub-area covered 0.3 m
410	in the x direction. The first and the second sub-areas were used to define the recharge
411	boundary, while the other sub-areas were used to define the no-recharge boundary. The
412	stress period ΔT was set as 1 h, and the initial MODFLOW time step Δt_s and UBMOD
413	time steps Δt_u were set as 0.167 h. The spatial discretization of UBMOD was uniformly
414	0.1 m. The experiment was also simulated by using SWMS2D, which considered the
415	lateral flow. The mean time step of SWMS2D was set to be 0.0225 h, and 20, 200 finite
416	elements were used.

417 **3.2 Results and Discussions of Model Performance**

418 3.2.1 Computational accuracy of the coupling scheme

Figure 5 shows the comparison of the results simulated by HYDRUS-1D and the coupled model of case 1. The statistical indexes are listed in Table 2. Figure 5(a) demonstrates that the groundwater table depth calculated by the coupled model has a similar pattern to that of HYDRUS-1D. The *ARE*, *RMSE*, *IA* and R^2 values were 17.0%, 423 0.171 m, 0.976 and 0.977. The soil water contents at the depth of 1.15m over time from the two models are compared in Fig. 5(b). The ARE, RMSE, IA and R^2 were 2.2%, 0.008 424 cm³/cm³, 0.991 and 0.976. The simulated soil water content profiles at different times 425 426 are shown in Fig. 5(c)-(e) and the evaluation indexes demonstrate the satisfactory 427 performance of the model. Moreover, the net groundwater consumption at the end of 428 the simulation period was compared, which is 0.132 m calculated by the coupled model, 429 and it is the same with that from HYDRUS-1D. In general, these results indicate that the coupled model can capture the flow information under the upward flux and the 430 431 heterogeneous condition.

432 The deviations of groundwater table depth and soil water content from the coupled model and HYDRUS-1D can also be observed in Fig. 5. The deviations are caused by 433 434 the different model structures of the coupled model and HYDRUS-1D. The HYDRUS-1D solves the saturated-unsaturated flow together, and the groundwater table is 435 436 determined at the depth with the matric potential equaling to zero. The soil water 437 content of the capillary fringe above the groundwater table is almost saturated. However, 438 the UBMOD model cannot simulate the capillary fringe. And there is a parameter the field capacity used to calculate the downward movement of soil water, which is defined 439 under a free drainage condition. So, the coupled model could lead to the lower soil 440 441 water content in the capillary fringe and higher groundwater table as shown in Fig. 5. 442 And there is another parameter specific yield used in the coupled model to determine 443 the groundwater table, which also attributes to the deviation of groundwater table.

444	Figure 4(b) shows the comparison of simulated water tables at 4 different times
445	using the coupled model and SWMS2D and the observation data in case 2. The index
446	values are listed in Table 3. The coupled model matched the observation data well at
447	the simulation times of 3 h, 4 h and 8 h, with the ARE values smaller than 3%, the RMSE
448	values smaller than 0.03 m and the IA and R^2 values close to 1. The observed and
449	simulated soil water content profiles for the initial and ending times are presented in
450	Fig. 6. The statistical index values are also listed in Table 3. The simulations by the
451	coupled model agree well with the observations at the locations of $x = 0.2$ m, $x = 1.4$ m
452	and $x = 2$ m (Figs. 6(a), (d) and (e)) where the lateral water flow is negligible. The
453	calculated recharge is 3.55 m/d per unit area when the flow becomes steady, which
454	equals to the input flux. These results demonstrate the accuracy of the coupled model
455	and the reliability of the coupling scheme shown in Sect. 2.4.

456 3.2.2 Influence of the temporal and spatial discretization as well as the stress period on457 simulation results

The groundwater table depth calculated by scenarios with different temporal discretizations (S1-S3) are compared with those from HYDRUS-1D in Fig. 7(a). The statistical index values are shown in Table 2. It can be found that the water table depth calculated by different scenarios have the same variation trend. The *ARE* values of the three scenarios are smaller than 20%, and the maximum *RMSE* value is 0.171 m. The *IA* and R^2 values are larger than 0.95. The groundwater table depth calculated by scenarios with different spatial discretizations (S1, S4 and S5) are compared with those

465 from HYDRUS-1D in Fig. 7(b). The ARE values of the three scenarios are smaller than 25%. The maximum *RMSE* value is 0.215 m. The *IA* and R^2 values are larger than 0.95. 466 467 The water table depth calculated by scenarios with different stress periods (S1, S6, S7 and S8) are compared with those from HYDRUS-1D in Fig. 7(c). It should be noted 468 469 that the model collapsed at the time of 227 d when the stress period is 15 d (S8). The 470 statistical index values for S1, S6 and S7 are shown in Table 2. The ARE and RMSE 471 values of the three scenarios are very similar. Considering the water balance method and empirical formulas adopting in the coupled model, the results calculated by all the 472 473 scenarios except S8 are acceptable. These results indicate that the temporal and spatial discretization have slight influence on the modeling results. It should be noted that the 474 impact of stress period in a certain scale (<10 d in this case) has no significant impact 475 476 on the simulation results. However, a too large stress period will cause improper results.

477 3.2.3 Limitations of the coupled model

478 Although the coupled model had a sufficient computational accuracy as shown 479 above, there were limitations because of the Quasi-3D assumptions. The coupled model 480 overestimates the water table at the time of 2 h in case 2 as shown in Fig. 4(b). This is 481 caused by a significant lateral flow in the unsaturated zone during the early period due 482 to the relatively low initial soil water content condition. Therefore, a portion of the 483 infiltration water in the first and second sub-areas should move in the lateral direction, 484 instead of moving downward to the saturated zone as in the Quasi-3D model. The coupled model thus overestimates the recharge flux, and results in a higher water table 485

486	at the early period. Additionally, the simulated soil water content by the coupled model
487	has poor performance at the locations of $x = 0.6$ m and $x = 0.8$ m (Fig. 6(b) and (c)).
488	These two sub-areas are close to the recharge zone and affected by the lateral flow,
489	which is ignored in the coupled model. These phenomena are similar to the results
490	calculated by other Quasi-3D models (Xu et al., 2012; Shen and Phanikumar, 2010).
491	Therefore, the coupled model overestimates the recharge and underestimates the soil
492	water content when the lateral flow cannot be ignored. Its application should be limited
493	to cases in which the soil flow mainly occurs in the vertical direction.
494	3.2.4 Water mass balance and computational cost
495	The mass balance error of the coupled model is small with the maximum value
496	0.012% in case 1 and 0.004% in case 2, while they are 1.6% for the HYDRUS-1D
497	model and 0.133% for the SWMS2D model. The cases were run on a 6 GB RAM,
498	double 2.93 GHz intel Core (TM) 2 Duo CPU-based personal computer. The
499	computational cost of different scenarios in case 1 of the coupled model ranges from
500	49 s to 63 s as listed in Table 2. It is 1.4 s by HYDRUS-1D. The temporal and spatial
501	discretization has slight influence on computational cost, while the stress period has
502	significant influence on the computation cost. The iteration and information exchange
503	are responsible for the high computational cost. For case 2, the computational cost of
504	the coupled model and the SWMS2D model are 46 s and 95 s, respectively. The coupled
505	model has a better efficiency comparing with the complete 2D model due to its simpler
506	numerical solutions and coarse discretization in space and time. The advantage of

descreasing computational cost will be more obvious when the application scale
becomes larger. Generally speaking, the coupled model provides satisfactory mass
balance and good computational efficiency.

- 510 4 Real-World Application
- 511 4.1 Study Site and Input Data

512 The coupled model was used to calculate the regional-scale groundwater recharge 513 in a real-world case, where the shallow groundwater has significant impact on the soil 514 water movement. Figure 8(a) shows the location of the study site, the Yonglian 515 irrigation area (107°37'19" - 108°51'04" E, 40°45'57" - 41°17'58" N) in Inner Mongalia, 516 China. The irrigation area is 12 km long from north to south, and 3 km wide from east to west. The whole domain size is 29.75 km². The ground surface elevation decreases 517 518 from 1028.9 m to 1025.4 m from the southwest to the northeast. A two-year tracer 519 experiment from 2014 to 2016 was conducted to obtain the groundwater recharge (Yang, 520 2018), and the experimental locations are shown in Fig. 8(a). This irrigation area has 521 well-defined hydrogeological borders by the channel network. Since the Zaohuo Trunk 522 Canal and No. 6 Drainage Ditch are filled with water over the simulation time, the firstkind boundary condition was applied to the two segments. The non-flow boundary 523 524 condition was used for the other segments. The irrigation water of this area is diverted 525 from the Renmin Canal. This irrigation area was divided into three sub-areas according 526 to the land usage since they own significantly different upper boundary conditions, 527 which are farm land, villages and bared soil, as shown in Fig. 8(b). The crop types in

the farmland were not considered for determining the sub-areas. The surface digitalelevation model (DEM) is shown in Fig. 8(c).

530 The measured soil water content and groundwater table in the crop growing season 531 from May to October of 2004 were used to calibrate the hydraulic parameters, and the 532 tracer experiment from 2014 to 2016 was used for the groundwater recharge evaluation. 533 A uniform daily rainfall rate was applied to the whole domain. The irrigation water was 534 only applied to the farm land. As lack of the weather data in 2004, the potential 535 evapotranspiration ET_0 was calculated by the measured evaporation data from the 20 536 cm pan (ET_{20}) , multiplying by an empirical conversion coefficient. The empirical 537 coefficient is 0.55, which was recommended by Hao (2016) by comparing monthly ET_0 and ET_{20} with 8 years' data in this area. The ET_0 during 2014 to 2016 was calculated 538 539 by using the Penman-Monteith equation. The precipitation, irrigation and ET_0 are 540 shown in Fig. 9. The crop growing season is from May to October, and the rest months 541 are no-crop growing season. Based on the hydrogeological characteristics of the study 542 area provided by the Geological Department of Inner Mongolia, the top aquifer within 543 the depth of 7 m is loamy sand and loam with small hydraulic conductivity; an underlying sand aquifer with the thickness of 46 m has high permeability, and the sand 544 545 aquifer is lying on an impervious 1 m-thick clay layer. The clay layer was used as the 546 bottom of the simulation domain, and seven different geological layers were used in the 547 MODFLOW model. The first layer was set to be the top aquifer, and the second aquifer were divided into 6 layers for numerical simulation. Ten groundwater monitoring wells 548

were set in this district, and the groundwater tables were observed every 6 days. Well 1, well 2, well 3, well 5 and well 6 are located in farm land areas, well 4 and well 8 in villages, and well 7, well 9 and well 10 in bared soil areas. Additionally, there are 5 soil water content monitoring points in the farm land and 2 points in the bared soil area, as shown in Fig. 8(a). Soil water contents within 1 m depth were observed 1-3 times every month from May to October in 2004.

Five GIS files are prepared as the shapefile files of the study domain, the land usage types, the boundary conditions, and raster files of the surface DEM and initial hydraulic head. There were 150 rows and 50 columns used in the MODFLOW model. The spatial discretization of UBMOD was set to be 0.1 m. The stress period ΔT was set as 5 d, and the MODFLOW time step Δt_s and UBMOD time step Δt_u were set as 1 d.

560

4.2 Model Calibration Results

561 There are two soil types in the first layer as loamy sand and loam. The unsaturated 562 hydraulic parameters of the two soils are listed in Table 4. The hydraulic conductivity of the top aquifer in MODFLOW was set as the same as the unsaturated layer, and the 563 564 hydraulic conductivity of the bottom sand aquifer was set as 3.5 m/d during the calibration, and the specific yields of the top and bottom were set as 0.08 and 0.1, 565 respectively. Figure 10 shows the comparison of the simulated and observed water table 566 567 depth for the whole area and locations of different monitoring wells. The statistical index values are listed in Table 5. It can be found that the ARE, RMSE, IA and R^2 values 568 are 9.9%, 0.203 m, 0.869 and 0.71 for the regional average water table depth. Larger 569

570 deviations of simulated water table depth can be found for the locations of monitoring wells, with RMSE values ranging from 0.25 m-0.39 m. Figure 11 further shows the 571 572 spatial distribution of the simulated water table depth at different output times. The 573 increasing trend is obviously found in Fig. 11(a) to Fig. 11(c) in the crop growing season, 574 during which the groundwater was consumed by crop transpiration and strong soil evaporation. When the intensive autumn irrigation happened after the 160th day, the 575 576 water table depth in the farm land decreased rapidly, as shown in Fig. 11(d). These 577 results indicate that our model can reasonably simulate the water table depth trend in 578 space and time.

579 The recharge during short-term was calculated for further checking the results by comparing the results with those from reference papers. The calculated recharge in farm 580 581 land during the autumn irrigation (from Oct 16 to Oct 31) is 93.3 mm, and the coefficient of recharge from the autumn irrigation is 0.37. Zhang (2011) proposed the 582 583 coefficient of recharge from the autumn irrigation is approximately 0.3. Yang (2016) 584 proposed that the coefficient of the recharge from the autumn irrigation is between 0.36 585 and 0.4. Yu (2017) used the coefficient of recharge from autumn irrigation as 0.33 for the district. The calculated result is consistent with the previous studies. The phreatic 586 evaporation coefficient was estimated during the period from Sep 15 to Sep 30 with no 587 588 precipitation or irrigation. The quantity of the recharge from saturated zone to 589 unsaturated zone is 10.1 mm during the period in the farm land. The phreatic evaporation coefficient is 0.179, and the averaged water table depth is 1.51 m during 590

591	the period. The phreatic evaporation coefficient measured by Wang (2002) is 0.172 at
592	the depth of 1.5 m. The short-term results indicate the validity of the simulating results.
593	Figure 12 shows the comparison between the simulated and average observed soil
594	water content profiles of the farm land and bared soil at different times. The statistical
595	index values are listed in Table 5. The ARE values of the farm land at the times of 40d,
596	85d, 125d, and 166d are 15.3%-24.9%, the <i>RMSE</i> values $0.044 \text{ cm}^3/\text{cm}^3$ - $0.066 \text{ cm}^3/\text{cm}^3$,
597	the <i>IA</i> values 0.621-0.775, and the R^2 values 0.54-0.689. The corresponding values for
598	the bared soil are 10.8%-19.8%, 0.038 cm ³ /cm ³ -0.052 cm ³ /cm ³ , 0.823-0.905, 0.620-
599	0.813, respectively. The larger measured soil water content in the root zone for the farm
600	land can be observed than the simulations, while the simulated soil water content
601	profiles in the bared soil agree well with the observations, as shown in Fig. 12. The
602	reason may be that the sampling locations are at the border of fields, which leads to an
603	overestimation of the soil water content in the root zone due to smaller crop root uptake.
604	The computational cost of the real-world application is 120 s, which is efficient
605	considering the scale of the problem.

4.3 Regional Groundwater Recharge

In the tracer experiment, bromide (Br) was used as the tracer for calculating groundwater recharge. The tracer was injected at 1 m depth at two locations shown in Fig. 8(a) in October, 2014. Based on two sampling locations in October of 2015 and 2016, the downward recharge is estimated according to the movement distance of the tracer peak and the average water content from the initial position of the tracer to the 612 final position (Tan et al., 2014). The soil water content at the depth of 1 m is relatively 613 stable according to the measurements and the results of Peng (2015), which ensures the 614 reliability of the experiment. As shown in Table 6, the annual average recharge *R* is 33.8 615 mm/year, and the recharge coefficient is 0.055 during the period of 2014 - 2016.

616 The calibrated coupled model was used to estimate the groundwater recharge from 617 October 1, 2014 to September 30, 2016. Figure 13 shows the time series of simulated 618 recharge rate in the farm land, and Table 6 lists the simulation results. The simulation 619 results indicate that groundwater is recharged in the no-crop growing season and 620 consumed in the crop growing season. The two peak values of groundwater recharge in Fig. 13 are due to the autumn irrigation after harvest for washing salt out. The no-crop 621 growing season provides 92.30 mm/year groundwater recharge over a year and the 622 623 average recharge coefficient is 0.346, which indicates that the autumn irrigation in the 624 no-crop growing season provides the primary groundwater recharge in the year. In the 625 crop growth season, the recharge is negative, which means that groundwater is 626 consumed by crop transpiration and soil evaporation. As calculated by the coupled 627 model, the annual groundwater recharge is 36.21 mm/year during the period from October 1, 2014 to September 30, 2016 in the farm land, which is similar to the result 628 of the tracer experiment. The results confirm the coupled model for groundwater 629 630 recharge evaluation, which is helpful for scheduling the irrigation amount in the crop growing season under the water saving policies. 631

632 **5** Conclusions

This study developed a new Quasi-3D coupled model for the purpose of practical modeling of unsaturated-saturated flow at the regional scale. The 1-D water balance model UBMOD describing the unsaturated soil water flow was integrated with MODFLOW iteratively. A developed framework implemented the modeling procedures, and provided the pre- and post-processing tools. The model was evaluated by using both synthetic numerical examples and real-world experimental data. The major conclusions drawn from this research are as follows,

(1) The new iteration coupling scheme iteratively integrating a hydrodynamic model
with a water balance model is reliable. The vertical net recharge and the depth of
the unsaturated zone are effective to be used as the exchange information to couple
the unsaturated zone and saturated zone.

644

of the new Quasi-3D model with an acceptable calculative efficiency and well-

(2) The satisfactory results in the two testing examples demonstrate the effectiveness

- 646 maintained saturated zone and unsaturated zone mass balance.
- 647 (3) The spatial and temporal discretization has slight impact on the simulation results.
- 648 The stress period should be not too large and it also has slight impact on the 649 simulation results in a certain range.
- 650 (4) The model gives a satisfactory performance for calculating the groundwater
- 651 recharge measured from the tracer experiment. The calculated annual groundwater
- recharge is 36.21 mm/year and the recharge coefficient is 0.059 in the study area.
- (5) The coupled model should not be used for problems with substantial lateral flow in

654	the unsaturated zone because of the Quasi-3D assumptions used in the model.
655	(6) The coupled model could lead to a higher groundwater table depth since it ignores
656	the capillary fringe.
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661	
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		The parameters used by			The parameters used		The parameters used	
		HYDR	US-1D/SV	WMS2D	only by	HYDRUS-	only by	the coupled
	Depth		ne coupled model		1D/SWMS2D		model	
	(m)	θ _r (-)	$ heta_{ m s}$ (-)	<i>K</i> s (m/d)	п	α (1/m)	$ heta_{ m f}$ (-)	μ
Case 1	0-0.4	0.001	0.399	0.2975	1.3757	1.74	0.25	-
Case I	0.4-2.3	0.001	0.339	0.4534	1.6024	1.39	0.23	0.083
Case 2	0-2.0	0.001	0.3	8.4	4.1	3.3	0.15	0.15

Table 1. The hydraulic parameters of case 1 and case 2.

Note: θ_r is the residual water content (L³L⁻³); θ_s is the saturated water content (L³L⁻³); K_s is the saturated hydraulic conductivity (LT⁻¹); α (L⁻¹) and n (-) are parameters depending on the pore size distribution; θ_f is the field capacity (L³L⁻³) and μ is the specific yield (-).

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				ARE (%)	RMS	Ε	IA	R^2
Groundwat	er table d	lepth (S1)		17.0	0.171 m		0.976	0.977
Soil water of	content a	t z = 1.15 m	l	2.2	0.008 cm ³ /cm ³		0.991	0.976
Soil water of	content p	rofile at $t =$	151 d	1.3	0.007 cm	0.007 cm ³ /cm ³		0.951
Soil water of	content p	rofile at $t =$	212 d	4.3	0.015 cm	³ /cm ³	0.976	0.914
Soil water of	content p	rofile at $t =$	273 d	8.5	0.024 cm	³ /cm ³	0.919	0.811
	Scen	narios		Gro	oundwater ta	able depth	1	
NT 1	$\Delta t_{\rm s}$			ARE	RMSE	T 4	D)	Calculation
Number	(d)	Δz (m)	ΔI (d)	(%)	(m)	IA	R≟	time (s)
S1	1	0.1	5	17.0	0.171	0.976	0.977	59
S2	0.5	0.1	5	14.1	0.157	0.980	0.980	62
S 3	2	0.1	5	17.7	0.157	0.979	0.958	59
S4	1	0.05	5	20.5	0.214	0.965	0.978	63
S5	1	0.2	5	24.0	0.215	0.959	0.964	60
S6	1	0.1	8	17.7	0.181	0.964	0.977	50
S 7	1	0.1	10	17.3	0.124	0.988	0.977	49

Table 2. The statistical index values of the coupled model of case 1.

Groundwater table		t = 2 h $t = 3 h$		h	t = 4 h	t = 8 h
	SWMS2D	0.9%	1.5%	<i>(</i> 0	1.6%	1.8%
AKE (70)	Coupled model	11.6%	11.6% 2.4%		2.9%	1.6%
	SWMS2D	0.010	0.014	4	0.016	0.022
KMSE (III)	Coupled model	0.088	0.02	5	0.029	0.021
T A	SWMS2D	0.985	0.99	6	0.995	0.991
IA	Coupled model	0.562	0.98	6	0.981	0.990
D?	SWMS2D	-	0.99	7	0.996	0.993
<i>K</i> ²	Coupled model	-	0.99	9	0.999	0.996
Soil wate	r content profile	<i>x</i> =0.2 m	<i>x</i> =0.6 m	<i>x</i> =0.8 m	<i>x</i> =1.4 m	<i>x</i> =2 m
4DE (0/)	SWMS2D	5.6%	11.4%	21.0%	17.6%	6.7%
AKE (%)	Coupled model	12.3%	80.5%	52.1%	27.6%	4.1%
RMSE	SWMS2D	0.018	0.031	0.044	0.022	0.017
(cm^3/cm^3)	Coupled model	0.040	0.173	0.109	0.039	0.010
T 4	SWMS2D	0.863	0.828	0.919	0.990	0.962
IA	Coupled model	0.741	0.279	0.707	0.968	0.983
D ²	SWMS2D	0.634	0.590	0.775	0.977	0.999
R^2	Coupled model	0.766	0.666	0.758	0.944	0.959

Table 3. The statistical index values of SWMS2D and the coupled model of case 2.

	• 1				
Soil type	Location	$ heta_{ m r}$ (-)	$ heta_{ m s}$ (-)	$K_{\rm s}$ (m/d)	$ heta_{ m f}$ (-)
Loamy sand	Village, bared soil	0.065	0.41	1.061	0.21
Loam	Farm land	0.078	0.43	0.2496	0.24

Table 4. The unsaturated hydraulic parameters of the real-world application.

Water table	Regional	average	Well 2	Well 3	Well	7 We	ell 8	Well 9
depth								
ARE (%)	9.9)	19.4	13.9	19.7	13	3.5	27.9
RMSE (m)	<i>RMSE</i> (m) 0.203		0.253	0.233	0.383	0.2	241	0.366
IA	0.869		0.803	0.831	0.745	0.8	819	0.623
R^2	0.710		0.598	0.562	0.646	0.6	525	0.649
			<i>t</i> =85 d					
Soil water	<i>t</i> =4	0 d	<i>t</i> =85	d	<i>t</i> =12	25 d	<i>t</i> =1	66 d
Soil water content	t=4 Farm land	0 d Bared soil	<i>t</i> =85 Farm land	d Bared soil	t=12 Farm land	25 d Bared soil	t=1 Farm land	66 d Bared soil
Soil water content ARE (%)	t=4 Farm land 15.3	0 d Bared soil 10.8	<i>t</i> =85 Farm land 15.4	d Bared soil 19.8	t=12 Farm land 15.3	25 d Bared soil 16.2	t=1 Farm land 24.9	66 d Bared soil 14.8
Soil water content ARE (%) RMSE (cm ³ /cm ³)	t=4 Farm land 15.3 0.052	0 d Bared soil 10.8 0.038	<i>t</i> =85 Farm land 15.4 0.045	d Bared soil 19.8 0.052	<i>t</i> =12 Farm land 15.3 0.044	25 d Bared soil 16.2 0.047	t=1 Farm land 24.9 0.066	66 d Bared soil 14.8 0.038
Soil water content ARE (%) RMSE (cm ³ /cm ³) IA	t=4 Farm land 15.3 0.052 0.774	0 d Bared soil 10.8 0.038 0.904	<i>t</i> =85 Farm land 15.4 0.045 0.775	d Bared soil 19.8 0.052 0.868	t=12 Farm land 15.3 0.044 0.650	25 d Bared soil 16.2 0.047 0.823	t=1 Farm land 24.9 0.066 0.621	66 d Bared soil 14.8 0.038 0.905

869 Table 5. The statistical index values of the real-world application.

	Tracer		Coupled model	
	experiment	Crop growing season	No-crop growing season	Annual
P (mm/year)	133.55	100	33.55	133.55
I (mm/year)	477.52	244.27	233.25	477.52
R (mm/year)	33.8	-56.09	92.30	36.21
$R_{\rm c}$ (-)	0.055	-	0.346	0.059

Table 6. The recharge sources and results of the tracer experiment.

873 Note: *P* is the annual precipitation; *I* is the irrigation water; *R* is the annual recharge and R_c is the

874 recharge coefficient, $R_c = \frac{R}{(P+I)}$.

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Fig. 1. (a) The procedures of geographic input information preparation. (b) The spatial

scheme of the coupled model.



882 *Note*: z_i (i = 1, ..., j) is the vertical elevation of layer i; d_u is the thickness of unsaturated zone; M_i 883 is the thickness of layer i; R is the groundwater recharge for one cell; q_1 , q_A , q_S and q_D are the fluxes 884 across the water table caused by allocation of the infiltration water, the advective movement, 885 source/sink terms and the water diffusion per unit area, respectively; **Du** is the thickness of 886 unsaturated zone (l dimension); **R** is the vertical net recharge for region scale ($m \times n$ dimension); t is 887 the time; p is the iteration level; **H** is the saturated hydraulic head ($m \times n$ dimension); ε_H is a user-888 specified tolerance.

Fig. 2. (a) The spatial coupling scheme for one saturated cell and one unsaturated soil

890 column. (b) The temporal coupling scheme, and the relationship between the stress

891 period (ΔT) and the time steps for UBMOD (Δt_u) and MODFLOW (Δt_s). (c) The

specific implementation of the iterative coupling scheme from t to $t+\Delta T$.



Fig. 3. The values of actual precipitation and potential transpiration rates of case 1.



Fig. 4. (a) The sketch of the 2D recharge experiment of case 2. (b) The comparison of
water table between simulated results by the coupled model, SWMS2D and observation
data of case 2.



902 Fig. 5. The comparison of the results calculated by HYDRUS-1D and the coupled





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Fig. 6. Comparison of soil water content profiles between the simulations from the coupled model, SWMS2D and the observations at different locations: (a) x = 0.2 m; (b) x = 0.6 m; (c) x = 0.8 m; (d) x = 1.4 m; (e) x = 2 m.



911 Fig. 7. The influence of (a) temporal and (b) spatial discretization and (c) stress period





915 Fig. 8. (a) The geographic location of Yonglian irrigation area. (b) The land use map.

916 (c) The surface DEM.

917

Fig. 10. Comparison between simulated and observed water table depth of the real-world application.

926 Fig. 11. Spatial simulated water table depth at different output times of the real-world

927 application.

930 Fig. 12. Comparison between simulated and observed regional average soil water

Fig. 13. The recharge rate in the farm land calculated by the coupled model