Many thanks for your insightful comments and careful examination of the manuscript. I have studied your comments carefully and tried our best to revise the manuscript. My responses are given as follows. Attached please find the revised version. Thank you and best regards.

1. [The paper describes a mathematical method to attribute a discrete change in runoff to changes in climate and catchment characteristics. The method is directly applicable to common data and yields quite similar results when compared to existing methods. However, it remains open which of these methods is more accurate because there is no data to verify.]

Response: I admitted that I have not provided data to verify the LI method. However, the method is mathematically precise but the other methods are not, so that it is more accurate than other methods.

2. [Still, there are two interesting and valuable aspects of the manuscript: a) The role of the evolution over time b) Reconciling the existing methods and their assumptions on this evolution]

Response: Many thanks for your appreciation.

3. [To consider the path of changes is an important aspect and, as the author illustrates, may thus alter the resultant sensitivity to a change. This is important, since this may allow to better assess the vulnerability of a given catchment to global change. The problem is, that there is usually not sufficient data to constrain the evolution of disturbances. ]

Response: I have added a paragraph to discuss the high data requirement associated with the LI method. See line 316-321 for details.

4. [The author uses subperiods of 7 years, where at least the meteorological data provides some constraints. However, the use of shorter periods comes at the cost of potential changes in the catchment water storage, which can then be misinterpreted as changes in catchment characteristics. Figure 6 shows that the temporal variation of the catchment property sensitivity is largest. This might actually be caused by water storage changes, rather than actual changes in the catchment properties. This aspect is not sufficiently discussed in the manuscript.]

Response: I have added a paragraph to justify my use of an aggregated time period of 7 years. See Lines 322-338 for details.

- [Although I like that the existing methods are discussed in detail, I strongly recommend that the author better visualizes these methods. An attempt is done in Figure 1, but this must be extended and linked to the other methods.]
   Response: I have revised Figure 1 as you suggested.
- 6. [Recommendation: Major Revisions. The relevance/significance of the paper must

be better highlighted. This requires major changes throughout.]

Response: Thanks for your comments. I highlighted the relevance in lines 39-43, 81-92, 94-98, 313-316, and 339-349.

7. [Further comments: Overall, the notation should be more consistent (for example indices)and streamlined]

Response: I have checked the notation throughout the manuscript.

8. [I think that some parts of the paper can be cut. Figure 2b is trivial and can be removed]

Response: A major conclusion of the manuscript is that the decomposition method is a special case of the LI method. Figure 2b lends direct support to the conclusion so that it is not trivial. I am sorry I do not cut it.

9. [It would be better to describe the decomposition method in a conceptual Figure, similar to Fig.1.]

Response: I have revised Figure 1 as you suggested.

10. [The catchments with the largest changes in n have a reference period of only 3 years. This is quite short for a reference period.]

Response: I am sorry that I directly used the data given in Zhou et al (2016). Many thanks for your careful examination, but the data of the catchment NO.10 remains in the manuscript considering the reasons below: 1) the catchment has a high aridity index of 1.5. In dry areas, the carryover of soil water storage between years is relatively small as much of the annual precipitation is evaporated and thus has little effect in altering water storage. For example, a one-year aggregated time period may be appropriate in the semi-arid Loess Plateau (Ning et al., 2017); 2) the carryover of soil water storage would result in an overestimated *E*, and in turn an overestimated *n*. The catchment NO.10 had a medium *n* value (1.7) in the reference period, much smaller than the evaluation period (4.2), so that the effect of the carryover of soil water storage should not be significant in the reference period.

11. [Figure 6: It is unclear what is shown here.]

Response: Figure 6 compares the temporal variability of the sensitivities of water yield to precipitation, potential evapotranspiration, and catchment properties. The boxplot clearly showed that the sensitivities to catchment properties had a much greater temporal variation.

12. [The motivation of the figures 7,8 and 9 is not really clear to me. Please explain or remove]

Response:

Figure 7 shows the correlation of the obtained sensitivities with P,  $E_0$ , n, and aridity index, for purpose to determine the predictors of the sensitivities.

Fig. 8 shows that the path-averaged sensitivities can be well predicted over space if having all data of P,  $E_0$ , and R.

Fig. 9 shows the prediction performance in the absence of runoff data as it frequently occurs in practices.

13. [At Line 311-312 it is argued that the timing of precipitation change is important. I did not see this aspect in the results.]

Response: This sentence is problematic. I have removed it.

Reference

- Zhou, S., B. Yu, L. Zhang, Y. Huang, M. Pan, and G. Wang (2016), A new method to partition climate and catchment effect on the mean annual runoff based on the Budyko complementary relationship. Water Resources Research, 52, 7163–7177. https://doi.org/10.1002/2016WR019046, 2016.
- Ning, T., Li, Z., and W. Liu: Vegetation dynamics and climate seasonality jointly control the interannual catchment water balance in the Loess Plateau under the Budyko framework, Hydrology and Earth System Sciences, 21, 1515-1526. https://doi.org/10.5194/hess-2016-484, 2017.

A line integral-based method to partition climate and catchment effects on
runoff
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# 14 Abstract

15 It is a common task to partition synergistic impacts of a number of drivers in environmental sciences. However, there is no mathematically precise solution to the partition. Here I presented a line integral-16 based method, which concerns about the sensitivity to the drivers throughout their evolutionary path so 17 as to ensure a precise partition. The method reveals that the partition depends on both the change 18 magnitude and pathway (timing of change), and not on the magnitude alone unless for a linear system. 19 To illustrate the method, I used the Budyko framework to partition the effects of climatic and catchment 20 conditions on the temporal change in runoff for 21 catchments from Australia and China. The method 21 reduced to the decomposition method when assumed a path along which climate change occurs first 22 followed by an abrupt change in catchment properties. The method re-defines the widely-used concept 23 of sensitivity at a point as the path-averaged sensitivity. The total differential and the complementary 24 methods simply concern about the sensitivity at the initial or/and the terminal state, so that they cannot 25 give precise results. The path-average sensitivity of water yield to climate conditions was found to be 26 stable over time. Space-wise, moreover, it can be readily predicted even in the absence of streamflow 27 observations, whereby facilitates evaluation of future climate effects on streamflow. As a 28 mathematically accurate solution, the method provides a generic tool to conduct the quantitative 29 attribution analyses. 30

31

32 Keywords: Runoff; Climate change; Human activities; Attribution analysis; Budyko

33

# 34 **1 Introduction**

It is often needed to quantify the relative roles of a few drivers to the observed changes of interest in environmental sciences. In the hydrology community, diagnosing the relative contributions of climate change and human activities to runoff is of great relevance to the researchers and managers as both climate and human activities have pose global-scale impact on hydrologic cycle and water resources (Barnett *et al.*, 2008; Xu *et al.*, 2014; Wang and Hejazi, 2001). Unfortunately, the quantitative attribution analysis of the runoff changes remains a challenge (Wang and Hejazi, 2001; Berghuijs and
 Woods, 2016; Zhang *et al.*, 2016); this is to a considerable degree due to a lack of a mathematically
 precise method to decouple synergistic and often confounding impacts of climate change and human
 activities.

44 Numerous studies have detected the long term variability in runoff and attempted to partition the 45 effects of climate change and human activities by means of various methods (Dey and Mishra, 2017). Among them are the paired-catchments method and the hydrological modeling method. The paired-46 catchment method is believed to be able to filter the effect of climatic variability and thus isolate the 47 48 runoff change induced by vegetation changes (Brown et al., 2005). However, the method is capital intensive. Particularly, it generally involves small catchments and is challenged when 49 extrapolating to large catchments (Zhang et al., 2011). The physical-based hydrological models often 50 51 suffer from limitations including high data requirement, labor-intensive calibration and validation processes, and inherent uncertainty and interdependence in parameter estimations (Binley *et al.*, 1991; 52 Wang et al., 2013; Liang et al., 2015). Interest then turns to the conceptual models over recent years, 53 54 such as the Budyko-type equations (see Section 2.1).

Within the Budyko framework, a large number of studies (Roderick and Farquhar, 2011; Zhang 55 et al., 2016) have used the total differential of runoff (i.e. dR, where R represents runoff) as a proxy for 56 the runoff change (i.e.  $\Delta R$ ) and further evaluated hydrological responses to climate change and human 57 activities (hereafter called the total differential method). However, dR is essentially a first-order 58 59 approximation of  $\Delta R$  (Fig. 1(a)). It has been shown that the approximation has caused an error of the climate impact on runoff ranging from 0 to 20 mm (or -118 to 174%) over China (Yang et al., 2014). 60 61 The total differential method directly used the partial derivatives of runoff as the sensitivities of runoff to climate and catchment conditions. Most studies applied the forward approximation of the runoff 62 change, *i.e.*, using the sensitivities at the initial state while calculation (e.g. Roderick and Farquhar, 63 2011). The elasticity method proposed by Schaake (1990) is also based on the total differential 64 expression (Sankarasubramanian et al., 2001; Zheng et al., 2009). The method uses the "elasticity" 65 concept to assess the climate sensitivity of runoff. The elasticity coefficients, however, have been 66 estimated in an empirical way and is not physically sound (Roderick and Farquhar, 2011; Liang et al., 67 2015). 68

The so-called decomposition method developed by Wang and Hejazi (2011) has also been widely used. The method assumes that climate changes drive a shift along a Budyko curve and then human interferences cause a vertical shift from the Budyko curve to another (Fig. 1(b)). Under this assumption, the method extrapolates the Budyko models calibrated using observations of the reference period, in which human impacts remain minimal, to determine the human-induced changes in runoff occurred during the evaluation period.

Recently, Zhou *et al.* (2016) established a Budyko complementary relationship for runoff and applied it to partitioning the climate and catchment effects. Superior to the total differential method, the method culminates with yielding a no-residual partition. Nevertheless, the method depends on a given weighted factor, which is determined in an empirical but not a precise way. Furthermore, Zhou *et al.* (2016) argued that the partition is not unique in the Budyko framework as the path of the climate and catchment changes cannot be uniquely identified.

A precise partition remains difficult even given a precise mathematical model. This can be 81 illustrated by using a precise hydrology model R = f(x, y), where x and y climate factors and catchment 82 characteristics respectively. We assumed that R changes by  $\Delta R$  when x changes by  $\Delta x$  and y by  $\Delta y$ , *i.e.* 83  $\Delta R = f(x + \Delta x, y + \Delta y) - f(x, y)$ . To determine the effect of x on  $\Delta R$ , *i.e.*  $\Delta R_x$ , a common practice is to 84 assume that y remains constant when x changes by  $\Delta x$ . We thus get:  $\Delta R_x = f(x + \Delta x, y) - f(x, y)$ . 85 Similarly, we can get:  $\Delta R_y = f(x, y + \Delta y) - f(x, y)$ . Although the derivation seems quite reasonable, it 86 is problematic as the sum of  $\Delta R_x$  and  $\Delta R_y$  is not equal to  $\Delta R$ . Further examination shows that a 87 variable's effect on R seems to differ depending on the changing path. For example, 88  $\Delta R_x = f(x + \Delta x, y) - f(x, y)$  and  $\Delta R_y = f(x + \Delta x, y + \Delta y) - f(x + \Delta x, y)$  if x changes first and y 89 subsequently (Note that the partition is precise with the sum of  $\Delta R_x$  and  $\Delta R_y$  equaling  $\Delta R$  now). If y 90 changes first and x subsequently, the partition then becomes:  $\Delta R_x = f(x + \Delta x, y + \Delta y) - f(x, y + \Delta y)$ 91 and  $\Delta R_y = f(x, y + \Delta y) - f(x, y)$ . In case of x and y changing simultaneously, unfortunately, 92 current literature seems not to provide a mathematically precise solution. 93

94 The aims of this work are to propose a mathematically precise method to conduct quantitative attribution to drivers. The method is based on the line integer (called the LI method hereafter) and takes 95 account of the sensitivity throughout the evolutionary path of the drivers rather than at a point as the 96 97 total differential does. In this way, the method revises the widely-used concept of sensitivity at a point as the path-averaged sensitivity. To present and evaluate the method, I decomposed the relative 98 influences of climate and catchment conditions on runoff within the Budyko framework using data from 99 21 catchments from Australia and China. I also examined the spatio-temporal variability of the path-100 averaged sensitivities of runoff to climatic and catchment conditions and assessed their spatio-temporal 101 predictability. 102

103

# 104 2 Methodology

# 105 2.1 The Budyko Framework and the MCY equation

Budyko (1974) argued that the mean annual evapotranspiration (E) is largely determined by 106 water and energy balance of a catchment. Using precipitation (P) and potential evapotranspiration ( $E_0$ ) 107 proxies for water and energy availabilities respectively, the Budyko framework 108 as relates evapotranspiration losses to the aridity index defined as the ratio of  $E_0$  over P. The Budyko 109 framework has gained wide acceptance in the hydrology community (Berghuijs and Woods, 2016; 110 Sposito, 2017). Over past decades, a number of equations have been developed to describe the 111 framework. Among them, the Mezentsev-Choudhury-Yang's equation (Mezentsev, 1955; Choudhury, 112 1999; Yang et al., 2008) (Called the MCY equation hereafter) has been widely accepted and was used 113 here: 114

115 
$$\frac{E}{P} = \frac{E_0/P}{\left(1 + (E_0/P)^n\right)^{1/n}}$$
(1)

116 where  $n \in (0, \infty)$  is an integration constant that is dimensionless, and represents catchment properties. Eq. (3) requires a relative long time scale whereby the water storage of a catchment is negligible and the 117 water balance equation reduces to be R = P - E. Here I adopted a "tuned" *n* value that can get exact 118 agreement between the calculated E by Eq. (1) and that actually encountered (= P - R). 119 120

The partial differentials of R with respect to P,  $E_0$ , and n are given as:

121 
$$\frac{\partial R}{\partial P} = R_P(P, E_0, n) = 1 - \frac{E_0^{n+1}}{(P^n + E_0^n)^{1/n}}$$
(2a)

122 
$$\frac{\partial R}{\partial E_0} = R_{E_0}(P, E_0, n) = -\frac{P^{n+1}}{(P^n + E_0^n)^{1/n}}$$
(2b)

123 
$$\frac{\partial R}{\partial n} = R_n(P, E_0, n) = \frac{-E_0 P n^{-1}}{(P^n + E_0^n)^{1/n}} \left[ \frac{\ln(P^n + E_0^n)}{n} - \frac{P^n \ln P + E_0^n \ln E_0}{P^n + E_0^n} \right]$$
(2c)

#### 2.2 The theory of the line integral-based method 124

To present the LI method, we start by considering an example of a two-variable function z = f(x, z)125 y), which has continuous partial derivatives  $\partial z / \partial x = f_x(x, y)$  and  $\partial z / \partial y = f_y(x, y)$ . Suppose that x and y 126 varies along a smooth curve L (e.g. AC in Fig. 1(c)) from the initial state  $(x_0, y_0)$  to the terminal state  $(x_N, y_0)$ 127  $y_N$ ), and z co-varies from  $z_0$  to  $z_N$ . Let  $\Delta z = z_N - z_0$ ,  $\Delta x = x_N - x_0$ , and  $\Delta y = y_N - y_0$ . Our goal is to seek 128 for a mathematical solution to quantify the effects of  $\Delta x$  and  $\Delta y$  on  $\Delta z$ , i.e.  $\Delta z_x$  and  $\Delta z_y$ .  $\Delta z_x$  and  $\Delta z_y$ 129 should be subject to the constraint  $\Delta z_x + \Delta z_y = \Delta z$ . 130

As shown in Fig. 1(c), points  $M_1(x_1, y_1), \dots, M_{N-1}(x_{N-1}, y_{N-1})$  partition L into N distinct segments. 131 Let  $\Delta x_i = x_{i+1} - x_i$ ,  $\Delta y_i = y_{i+1} - y_i$ , and  $\Delta z_i = z_{i+1} - z_i$ . For each segment,  $\Delta z_i$  can be approximated as the 132  $dz_i$ :  $\Delta z_i \approx dz_i = f_x(x_i, y_i) \Delta x_i + f_y(x_i, y_i) \Delta y_i$ . total differential We then have: 133  $\Delta z = \sum_{i=1}^{N} \Delta z_i \approx \sum_{i=1}^{N} f_x(x_i, y_i) \Delta x_i + \sum_{i=1}^{N} f_y(x_i, y_i) \Delta y_i$ . We thus obtain an approximation of  $\Delta z_x$  and  $\Delta z_y$ : 134  $\Delta z_x \approx \sum_{i=1}^N f_x(x_i, y_i) \Delta x_i$  and  $\Delta z_y \approx \sum_{i=1}^N f_y(x_i, y_i) \Delta y_i$ . Define  $\tau$  as the maximum length among the N segments. 135

The smaller the value of  $\tau$ , the closer to  $\Delta z_i$  the value of  $dz_i$ , and then the better the approximations are. 136 The approximations becomes exact in the limit  $\tau \rightarrow 0$ . Taking the limit  $\tau \rightarrow 0$  then turns sum into 137 integrals and gives a precise expression (it is an informal derivation and please see Appendix A for a 138

139 formal one): 
$$\Delta z = \lim_{\tau \to 0} \sum_{i=1}^{N} f_x(x_i, y_i) \Delta x_i + \lim_{\tau \to 0} \sum_{i=1}^{N} f_y(x_i, y_i) \Delta y_i = \int_L f_x(x, y) dx + \int_L f_y(x, y) dy$$
, where

140 
$$\int_{L} f_{x}(x, y) dx = \lim_{\tau \to 0} \sum_{i=1}^{N} f_{x}(x_{i}, y_{i}) \Delta x_{i} \text{ and } \int_{L} f_{y}(x, y) dy = \lim_{\tau \to 0} \sum_{i=1}^{N} f_{y}(x_{i}, y_{i}) \Delta y_{i} \text{ denote the line integral of } f_{x} \text{ and } f_{y}$$

along L (termed integral path) with respect to x and y, respectively.  $\int_{L} f_x(x, y) dx$  and  $\int_{L} f_y(x, y) dy$  exist 141 provided that  $f_x$  and  $f_y$  are continuous along L. We thus obtain a precise evaluation of  $\Delta z_x$  and  $\Delta z_y$ : 142

143 
$$\Delta z_x = \int_L f_x(x, y) dx \qquad (3a)$$

144 
$$\Delta z_y = \int_{I} f_y(x, y) dy.$$
 (3b)

145 Unlike the total differential method, the sum of  $\Delta z_x$  and  $\Delta z_y$  persistently equals  $\Delta z$  (Appendix B). 146 If f(x, y) is linear, then  $f_x$  and  $f_y$  are constant. Define  $C_x = f_x(x, y)$  and  $C_y = f_y(x, y)$ , we have  $\Delta z_x = C_x \Delta x$ 147 and  $\Delta z_y = C_y \Delta y$ .  $\Delta z_x$  and  $\Delta z_y$  are thus independent of *L*. If f(x, y) is non-linear, however, both  $\Delta z_x$  and  $\Delta z_y$ 148 varies with *L*, as was exemplified in Appendix C. Hence, the initial and the terminal states, together 149 with the path connecting them, determine the resultant partition unless f(x, y) is linear.

The mathematical derivation above applies to a three-variable function as well. By doing the line integrals for the MCY equation, we obtain the desired results:

152 
$$\Delta R_P = \int_L \frac{\partial R}{\partial P} dP \qquad (4a)$$

153 
$$\Delta R_{E_0} = \int_L \frac{\partial R}{\partial E_0} dE_0 \tag{4b}$$

154 
$$\Delta R_n = \int_L \frac{\partial R}{\partial n} dn \qquad (4c)$$

where  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  denotes the effects on runoff change of *P*,  $E_0$ , and *n*, respectively. The sum of  $\Delta R_P$  and  $\Delta R_{E_0}$  represents the effect of climate change, and  $\Delta R_n$  are often related to human activities although it probably includes the effects of other factors, such as climate seasonality (Roderick and Farquhar, 2011; Berghuijs and Woods, 2016). *L* denotes a three-dimensional curve along which climate and catchment changes have occurred. I approximated *L* as a union of a series of line segments.  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  were finally figured out by summing up the integrals along each of the line segments (see Section 2.3).

# 162 2.3 Using the LI method to determine $\Delta R_P$ , $\Delta R_{E_0}$ , and $\Delta R_n$ within the Budyko Framework

163 1) Determining  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  assuming a linear integral path

164 Given two consecutive periods and assumed that the catchment state has evolved from  $(P_1, E_{01}, n_1)$  to  $(P_2, E_{02}, n_2)$  along a straight line *L*. Let  $\Delta P = P_2 - P_1$ ,  $\Delta E_0 = E_{02} - E_{01}$ , and  $\Delta n = n_2 - n_1$ , then the 166 line *L* is given by parametric equations:  $P = \Delta Pt + P_1$ ,  $E_0 = \Delta E_0t + E_{01}$ ,  $n = \Delta nt + n_1$ ,  $t \in [0,1]$ . Given the 167 equations, Eq. (2) becomes a one-variable function of *t*, i.e.,  $\partial R / \partial P = R_P(t)$ ,  $\partial R / \partial E_0 = R_{E_0}(t)$ , and 168  $\partial R / \partial n = R_n(t)$ . Then,  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  can be evaluated as:

169 
$$\Delta R_P = \int_L \frac{\partial R}{\partial P} dP = \int_0^1 R_P(t) d(\Delta P t + P_1) = \Delta P \int_0^1 R_P(t) dt$$
(5a)

170 
$$\Delta R_{E_0} = \int_L \frac{\partial R}{\partial E_0} dE_0 = \int_0^1 R_{E_0}(t) d(\Delta E_0 t + E_{01}) = \Delta E_0 \int_0^1 R_{E_0}(t) dt \qquad (5b)$$

171 
$$\Delta R_n = \int_L \frac{\partial R}{\partial n} dn = \int_0^1 R_n(t) d(\Delta nt + n_1) = \Delta n \int_0^1 R_n(t) dt$$
(5c)

Unfortunately, I cannot figure out the antiderivatives of  $R_P(t)$ ,  $R_{E_0}(t)$ , and  $R_n(t)$  and have to make approximate calculations. As the discrete equivalent of integration is summation, we can approximate integration as summation. I divided the  $t \in [0,1]$  interval into 1000 subintervals of the same width, thereby setting *dt* identically equal to 0.001, and then then calculated  $R_P(t)dt$ ,  $R_{E_0}(t)dt$ , and  $R_n(t)dt$  for each subinterval. Let  $t_i = 0.001i$ ,  $i \in [0,999]$  and is integer-valued,  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  was approximated as:

178 
$$\Delta R_P \approx 0.001 \Delta P \sum_{i=0}^{999} R_P(t_i)$$
 (6a)

179 
$$\Delta R_{E_0} \approx 0.001 \Delta E_0 \sum_{i=0}^{999} R_{E_0}(t_i)$$
 (6b)

180 
$$\Delta R_n \approx 0.001 \Delta n \sum_{i=0}^{999} R_n(t_i)$$
 (6c)

181 2) Dividing the evaluation period into a number of subperiods

I first determine a change point and divide the whole observation period into the reference and evaluation periods. To determine the integral path, the evaluation period is further divided into a number of subperiods. The Budyko framework assumes a steady state condition of a catchment and therefore requires no change in soil water storage. Over a time period of 5-10 years, it is reasonable to assume that changes in soil water storage are sufficiently small (Zhang *et al.*, 2001). Here I divided the evaluation period into a number of 7-year subperiods with the exception for the last one, which varied from 7 to 13 years in length depending on the length of the evaluation period.

189 3) Determining  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  by approximating the integral path as a series of line segments

As did in Fig. 1(c), a curve can be approximated as a series of line segments. For a short period, 190 the integral path L can be considered as linear, which implies a temporally invariant change rate. For a 191 192 long period, in which the change rate usually varies over time, L can be fitted using a number of line segments. Given a reference period and an evaluation period comprising N subperiods, I assumed that 193 the catchment state evolved from  $(P_0, E_{00}, n_0), \ldots, (P_i, E_{0i}, n_i), \ldots$  to  $(P_N, E_{0N}, n_N)$ , where the subscript 194 "0" denotes the reference period, and "i" and "N" denotes the *i*th and the last subperiods of the 195 evaluation period, respectively. I used a series of line segments  $L_1, L_2, ..., L_N$  to approximate the 196 integral path L, where  $L_1$  connects  $(P_0, E_{00}, n_0)$  with  $(P_1, E_{01}, n_1)$ ,  $L_i$  connects points  $(P_{i-1}, E_{0,i-1}, n_{i-1})$  with 197  $(P_i, E_{0i}, n_i)$ , and the initial point of  $L_{i+1}$  is the terminal point of  $L_i$  and. Then  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  are 198 evaluated as the sum of the integrals along each of the line segments, which was calculated using Eq. 199 200 (6).

201 2.4 The total-differential, decomposition and complementary methods

To evaluate the LI method, I compared it with the decomposition method, the total differential method, and the complementary method. The total differential method approximated  $\Delta R$  as dR (Fig. 1(a)):

205 
$$\Delta R \approx dR = \frac{\partial R}{\partial P} \Delta P + \frac{\partial R}{\partial E_0} \Delta E_0 + \frac{\partial R}{\partial n} \Delta n = \lambda_P \Delta P + \lambda_{E_0} \Delta E_0 + \lambda_n \Delta n \tag{7}$$

where  $\lambda_P = \partial R/\partial P$ ,  $\lambda_{E_0} = \partial R/\partial E_0$ , and  $\lambda_n = \partial R/\partial n$ , representing the sensitivity coefficient of *R* with respect to *P*, *E*<sub>0</sub>, and *n*, respectively. Within the total differential method,  $\Delta R_P = \lambda_P \Delta P$ ,  $\Delta R_{E_0} = \lambda_{E_0} \Delta E_0$ , and  $\Delta R_n = \lambda_n \Delta n$ . I used the forward approximation, *i.e.* substituting the observed mean annual values of the reference period into Eq. (2), to estimate  $\lambda_P$ ,  $\lambda_{E_0}$ , and  $\lambda_n$ , as did in most studies (Roderick and Farquhar, 2011; Yang and Yang, 2011; Sun *et al.*, 2014). 211 The decomposition method (Wang and Hejazi, 2011) calculated  $\Delta R_n$  as follows:

212 
$$\Delta R_n = R_2 - R_2' = (P_2 - E_2) - (P_2 - E_2') = E_2' - E_2$$

where  $R_2$ ,  $P_2$ , and  $E_2$  represents the mean annual runoff, precipitation and evapotranspiration of the

(8)

evaluation period; and  $R_2$  and  $E_2$  represents the mean annual runoff and evapotranspiration respectively, given the climate conditions of the evaluation period and the catchment conditions of the reference period. Both  $E_2$  and  $E_2$  were calculated by Eq. (1), but using *n* values of the evaluation period and the

reference period respectively.  $L_2$  were calculated by Eq. (1), but using *n* values of the evaluation period and the

The complementary method (Zhou *et al.*, 2016) uses a linear combination of the complementary relationship for runoff to determine  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$ :

$$\Delta R = a \left[ \left( \frac{\partial R}{\partial P} \right)_{1} \Delta P + \left( \frac{\partial R}{\partial E_{0}} \right)_{1} \Delta E_{0} + P_{2} \Delta \left( \frac{\partial R}{\partial P} \right) + E_{0, 2} \Delta \left( \frac{\partial R}{\partial E_{0}} \right) \right] + (1-a) \left[ \left( \frac{\partial R}{\partial P} \right)_{2} \Delta P + \left( \frac{\partial R}{\partial E_{0}} \right)_{2} \Delta E_{0} + P_{1} \Delta \left( \frac{\partial R}{\partial P} \right) + E_{0, 1} \Delta \left( \frac{\partial R}{\partial E_{0}} \right) \right]$$
(9)

where the subscript 1 and 2 denotes the reference and the evaluation periods, respectively. *a* is a weighting factor and varies from 0 to 1. As suggested by Zhou *et al.* (2016), I set a = 0.5. Equation (9) thus gave an estimation of  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_r$  as follows:

224 
$$\Delta R_P = 0.5 \Delta P \left[ \left( \frac{\partial R}{\partial P} \right)_1 + \left( \frac{\partial R}{\partial P} \right)_2 \right]$$
(10a)

225 
$$\Delta R_{E_0} = 0.5 \Delta E_0 \left[ \left( \frac{\partial R}{\partial E_0} \right)_1 + \left( \frac{\partial R}{\partial E_0} \right)_2 \right]$$
(10b)

226 
$$\Delta R_n = 0.5\Delta \left(\frac{\partial R}{\partial P}\right) (P_1 + P_2) + 0.5\Delta \left(\frac{\partial R}{\partial E_0}\right) (E_{0,1} + E_{0,2})$$
(10c)

#### 227 2.5 Data

I collected data of runoff and climate of 21 selected catchments from previous studies (Table 1). 228 The change-point years gave in the studies was directly used to determine the reference and evaluation 229 periods for the LI method. As mentioned above, the LI method further divides the evaluation period into 230 a number of subperiods. For the sake of comparison, the last subperiod of the evaluation period was 231 used as the evaluation period for the decomposition, the total differential and the complementary 232 233 methods (It can be equally considered that all methods used the last subperiod as the evaluation period, 234 but the LI method cares about the intermediate period between the reference and the evaluation periods 235 and the others do not). Nine of the 21 catchments had a reference period comprising only one subperiod (Table 1), and the others had two to seven ones. 236

The 21 selected catchments were located in diverse climates and landscapes. Among them, 14 are from Australia and 7 from China (Table 1). The catchments spanned from tropical to subtropical and temperate and from humid to semi-humid and semi-arid regions, with mean annual rainfall varying from 506 to 1014 mm and potential evaporation from 768 to 1169 mm. The index of dryness ranges between 0.86 and 1.91. The catchment areas vary by five orders of magnitude from 1.95 to 121,972 with a median 606 km<sup>2</sup>. The key data includes annual runoff, precipitation, and potential evaporation.

The record length varied between 15 and 75 with a median of 35 years. Among the 21 catchments, the 243 changes from the reference to the evaluation period ranged between -271 and 79 mm yr<sup>-1</sup> for 244 precipitation, and -35 and 41 mm vr<sup>-1</sup> for potential evaporation (Table 2). The coeval change in the 245 parameter n of the MCY equation ranged between -0.2 to 2.53. All of the catchments experienced both 246 climate change and land cover change over the observation period. The mean annual streamflow 247 reduced for all of them, by from 0.43 to 229 with a median 38 mm yr<sup>-1</sup>. More details of data and the 248 catchments can be found in Zhang et al. (2011), Sun et al. (2014), Zhang et al. (2010), Zheng et al. 249 (2009), Jiang et al. (2015), and Gao et al. (2016). 250

251

# 252 **3 Results**

253 3.1 Comparisons with existing methods

The LI method first partitions the whole observation period into the reference and evaluation periods, then further divides the latter into a number of subperiods and evaluates the contributions to runoff from climate and catchment changes for each subperiod, and finally adds up the derived contributions. Table 3 lists all of the resultant values of  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  of the LI method, together with the three other methods.

Fig. 2(a) compares the resultant  $\Delta R_n$  of the LI method and the decomposition method. Although they are quite similar, the discrepancies between them can be up to >20 mm yr<sup>-1</sup>. The decomposition method assumes that climate change occurs first and then human interferences cause a sudden change in catchment properties (Fig. 1(b)). Such a fictitious path is identical to the broken line AB+BC in Fig. 1(c), provided that *x* represents climate factors and *y* catchment properties. As a result, the decomposition method can be considered as a special case of the LI method when adopting the broken line AB+BC in Fig. 1(c) as the integral path, as was demonstrated clearly in Fig. 2(b).

The total differentiae method is predicated on an approximate equation, *i.e.* Eq. (7). The LI 266 method reveals that the precise form of the equation is  $\Delta R = \overline{\lambda_P} \Delta P + \overline{\lambda_E} \Delta E_0 + \overline{\lambda_n} \Delta n$  (i.e. Eq. (D2) in 267 Appendix D), where  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  (Table 4) denote the path-averaged sensitivity of R to P,  $E_0$ , and n, 268 respectively. All points along the path have the same weight in determining  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$ . To determine 269 them, the total differential method utilizes only the initial state and the complementary method utilizes 270 the initial and the terminal states. Neglecting the intermediate states between the initial and the terminal 271 272 ones possibly results in a reverse trend estimation (see  $\Lambda R_{E_0}$  for Catchment NO. 1 in Table 3). Although the elasticity method exploits information contained over the entire observation period (e.g. Zheng *et al.*, 273 274 2009: Wang et al., 2013), the resultant descriptive statistics of climate elasticity may not be robust 275 (Roderick and Farguhar, 2011; Liang et al., 2015).

Superior to the total differential method, the sum of  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  always equaled to  $\Delta R$ for the LI method. Examination of the subperiods revealed that  $\partial R/\partial n$  was more temporally variable than  $\partial R/\partial P$  and  $\partial R/\partial E_0$  (discussed below). For this reason,  $\Delta R_n$  showed considerable discrepancies between the two methods but  $\Delta R_P$  as well as  $\Delta R_{E_0}$  matched well between the two methods (Fig. 3). As with the LI method, the complementary method produced  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  that exactly add up to  $\Delta R$ . Although its resultant  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  were all in good agreement with the LI method (Fig. 4), the LI method often yielded values beyond the bounds given by the complementary method (Fig. 5); this is because the initial and terminal states are not equivalent to the maximum and minimum values over the integral path.

285

# 3.2 The spatio-temporal variability of the path-averaged sensitivities

 $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  implies the average runoff change induced by a unit change in P,  $E_0$  and n, 286 respectively (Appendix D). Their spatio-temporal variability is relevant to the prediction of the runoff 287 change. To evaluate their temporal variabilities, I calculated  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  for each subperiod of the 288 evaluation period and assessed their deviation from those for the whole evaluation period. As shown in 289 Fig. 6, the deviation was rather limited for  $\overline{\lambda_P}$  (averaged 8.6%) and  $\overline{\lambda_{E_0}}$  (averaged 13%), but was 290 considerable for  $\overline{\lambda_n}$  (averaged 41%). Hence, it seems guite safe to predict the future climate effects on 291 runoff using earlier  $\overline{\lambda_P}$  and  $\overline{\lambda_{E_0}}$ , but care must be taken when using earlier  $\overline{\lambda_n}$  to predict future catchment 292 effect on runoff. 293

Different from the temporal variability,  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  all varied greatly, by up to several or 294 even ten folds, between the studied catchments (Table 4). It was found that there were good correlations 295 between  $\overline{\lambda_P}$  and P, between  $\overline{\lambda_{E_0}}$  and P, and between  $\overline{\lambda_n}$  and n (Fig. 7). Fig. 8 shows that Eq. (2) 296 reproduced  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  very well taking the long-term means of P,  $E_0$ , and n as inputs, a fact that the 297 dependent variable approached its average if setting the independent variables to be their averages. The 298 finding is of relevance to the spatial prediction of  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$ ; moreover, it would greatly facilitate 299 the prediction of future climate effect on runoff as  $\overline{\lambda_P}$  and  $\overline{\lambda_{E_0}}$  was rather stable over time as previously 300 mentioned. 301

Runoff data and in turn, the parameter n in the MCY equation, are often unavailable. It is thus 302 desirable to make predictions of  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  in the absence of the parameter *n*. I developed three 303 strategies as follows: 1) using Eq. (2) and assuming n = 2 as n is typically in a small range from 1.5 to 304 2.6 (Roderick and Farquhar, 2011); 2) using P and  $E_0$  to establish regression models; 3) using the aridity 305 index to establish regressions as it appeared to be more correlated with both  $\overline{\lambda_P}$  and  $\overline{\lambda_{E_0}}$  than P and  $E_0$ 306 (Fig. 7). As shown in Fig. 9, the three strategies have similar performance although the second one 307 seems to perform better. All of the strategies gave acceptable predictions of  $\overline{\lambda_P}$  and  $\overline{\lambda_{E_0}}$ , but rather poor 308 results for  $\overline{\lambda_n}$  as it was primarily controlled by *n* (Fig. 7). It was thus needed to seek more sophisticated 309 approaches to predict the future catchment effect on runoff in the absence of runoff observations. 310

311

### 312 4 Discussion

The LI method re-defines the widely-used concept of sensitivity at a point as the path-averaged sensitivity. The method highlights the role of the evolutionary path in determining the resultant partition. Yet, it seems that no studies have taken into account the path issue while evaluating the relative influences of drivers. Compared with the existing methods, the limit of the LI method is high data requirement for obtaining the evolutionary path. When the data are unavailable, the complementary method can be considered as an alternative. First, the complementary method offer results free of residuals; in addition, it employs both data of the reference and the evaluation periods to determine the sensitivities, thereby generally yielding values closer to the path-averaged sensitivities than the total differentiae method.

322 While using the Budyko models, a reasonable time scale is relevant to meet the assumption that changes in catchment water storage are small relative to the magnitude of fluxes of P, R and E 323 324 (Donohue et al., 2007; Roderick and Farquhar, 2011). The present study selected seven years as most studies have suggested a time period of 5-10 years (Zhang et al., 2001; Zhang et al., 2016; Wu et al., 325 2017a; Wu et al., 2017b; Li et al., 2017) or even one year (Roderick and Farguhar, 2011; Sivapalan et 326 327 al., 2011; Carmona et al., 2014; Ning et al., 2017). Nevertheless, some studies asserted that the time period should be longer than ten years (Li et al., 2016; Dey and Mishra, 2017). If this is the case, the 328 high temporal variation of  $\overline{\lambda_n}$  shown in Fig. 6 might be caused by water storage changes, rather than 329 actual changes in the catchment properties. The uncertainty should be addressed. Using the Gravity 330 Recovery and Climate Experiment (GRACE) satellite gravimetry, Zhao et al.(2011) detected the water 331 storage variations for three largest river basins of China, namely, Yellow, Yangtze, and Zhujiang. The 332 Yellow River mostly drains an arid and semiarid region (P. 450mm; R. 70 mm; E. 380mm), and the 333 Yangtze (P, 110mm; R, 550 mm; E, 550mm) and the Zhujiang river basins (P, 1400mm; R, 780 mm; E, 334 620mm) are humid. The amplitude of the water storage variations between years were 7, 37.2 and 65 335 336 mm for the three rivers respectively, one magnitude order smaller than fluxes of P, R and E. Although 337 the observations cannot be directly extrapolated to other regions, the possibility seems remote that the 338 use of a 7-year aggregated time strongly violates the assumption of the steady state condition.

339 Mathematically, the LI method is unrelated to a functional form and applies to communities other than just hydrology. For example, identifying the carbon emission budgets (an allowable 340 341 amount of anthropogenic  $CO_2$  emission consistent with a limiting warming target), is crucial for global efforts to mitigate climate change. The LI method suggested that the emission budgets depends on both 342 the emission magnitude and pathway (timing of emissions), in line with a recent study by Gasser *et al.* 343 344 (2018). Hence, an optimal pathway would bring about an elevated carbon budget unless the carbon-345 climate system behaves in a linear fashion. This study presented the LI method using time-series data, but it applies equally to the case of spatial series of data. Given a model that relates fluvial or aeolian 346 sediment load to the influencing factors (e.g. rainfall and topography), for example, the LI method can 347 be used to separate their contributions to the sediment-load change along a river or in the along-348 wind direction 349

350

#### 351 **5 Conclusions**

Based on the line integral, I found a mathematically precise solution to partition the effects of a number of independent variables on the change in the dependent variable. I then applied the method to partition the effects on runoff of climatic and catchment conditions within the Budyko framework. The method reveals that in addition to the change magnitude, the change pathways of climatic and

catchment conditions also exert control on their impacts on runoff. Instead of using the runoff 356 sensitivity at a point, the LI method uses the path-averaged sensitivity, thereby ensuring a 357 mathematically precise partition. I further examined the spatiotemporal variability of the path-averaged 358 sensitivity. Time-wise the runoff sensitivity is stable to climate but highly variable to catchment 359 properties, suggesting that it is reliable to predict future climate effects using earlier observations but 360 361 care must be taken when predicting the catchment effects. Space-wise (between catchments) the runoff sensitivity was highly variable both to climatic and catchment conditions, but it can be well depicted by 362 the long-term means of the climatic and catchment conditions. As a mathematically accurate scheme, 363 the LI method has the potential to be a generic attribution approach in the environmental sciences. 364

365

# 366 **Data availability**

The data used in this study are freely available by contacting the authors.

368

### 369 Author contribution

370 MZ designed the study, analyzing the data and wrote the manuscript.

371

# 372 Competing interests

The authors declare that they have no conflict of interest.

374

# 375 **Appendix A: Derivation of equation** $\Delta z = \int_{L} f_{x}(x, y) dx + \int_{L} f_{y}(x, y) dy$

We define that the curve *L* in Fig. 1(c) is given by a parametric equation: x = x(t), y = y(t),  $t \in [t_0, t_N]$ , then  $\Delta z = z_N - z_0 = f[x(t_N), y(t_N)] - f[x(t_0), y(t_0)]$ . Substituting the parametric equations, we get:

The right-hand side of the equation = 
$$\int_{t_0}^{t_N} f_x[x(t), y(t)] dx(t) + \int_{t_0}^{t_N} f_y[x(t), y(t)] dy(t)$$

$$380 = \int_{t_0}^{t_0} \left\{ f_x[x(t), y(t)] x'(t) + f_y[x(t), y(t)] y'(t) \right\} dt$$

Let g(t) = f[x(t), y(t)], and after using the chain rule to differentiate g with respect to t, we obtain:

(A1)

382 
$$g'(t) = \frac{\partial g}{\partial x}\frac{dx}{dt} + \frac{\partial g}{\partial y}\frac{dy}{dt} = f_x[x(t), y(t)]x'(t) + f_y[x(t), y(t)]y'(t)$$
(A2)

It shows that g'(t) is just the integrand in Eq. (A1), Eq. (A1) can then be rewritten as:

The right-hand side of the equation 
$$= \int_{t_0}^{t_N} g'(t) dt = [g(t)]_{t_0}^{t_N} = g(t_N) - g(t_0)$$
  
 $= f[x(t_N), y(t_N)] - f[x(t_0), y(t_0)] =$  The left-hand side of the equation

# 386 Appendix B: The sum of $\int_{x} f_{x}(x, y) dx$ and $\int_{y} f_{y}(x, y) dy$ is path independent

Theorem: Given an open simply-connected region *G* (i.e., no holes in *G*) and two functions *P*(*x*, *y*) and *Q*(*x*, *y*) that have continuous first-order derivatives, if and only if  $\partial P / \partial y = \partial Q / \partial x$  throughout *G*, then  $\int_{L} P(x, y) dx + \int_{L} Q(x, y) dy$  is path independent, i.e., it depends solely on the starting and ending point of *L*.

We have  $\partial f_x / \partial y = \partial^2 z / \partial x \partial y$  and  $\partial f_y / \partial x = \partial^2 z / \partial y \partial x$ . As  $\partial^2 z / \partial x \partial y = \partial^2 z / \partial y \partial x$ , we can state that  $\partial f_x / \partial y = \partial f_y / \partial x$ , meeting the above condition and proving that  $\int_L f_x(x, y) dx + \int_L f_y(x, y) dy$  is path independent. The statement was further exemplified using a fictitious example in Appendix C.

# 394 Appendix C: A fictitious example to show how the LI method works

- It is assumed that runoff (R, mm yr<sup>-1</sup>) at a site increases from 120 to 195 mm yr<sup>-1</sup> with  $\Delta R = 75$  mm yr<sup>-1</sup>; meanwhile, precipitation (P, mm yr<sup>-1</sup>) varies from 600 to 650 mm yr<sup>-1</sup> ( $\Delta P = 75$  mm yr<sup>-1</sup>) and runoff coefficient ( $C_R$ , dimensionless) from 0.2 to 0.3 ( $\Delta C_R = 0.1$ ). The goal is to partition  $\Delta R$  into the effects of precipitation ( $\Delta R_P$ ) and runoff coefficient ( $\Delta R_{C_R}$ ) provided that P and  $C_R$  are independent. We have a function  $R = PC_R$  and its partial derivatives  $\partial R / \partial P = C_R$  and  $\partial R / \partial C_R = P$ . Given a path L
- along which *P* and *C<sub>R</sub>* change and using Eq. (3), the LI method evaluates  $\Delta R_P$  and  $\Delta R_{C_R}$  as:

401 
$$\Delta R_{C_R} = \int_L \partial R / \partial C_R dC_R = \int_L P dC_R \text{ and } \Delta R_P = \int_L \partial R / \partial P dP = \int_L C_R dP \quad (C1)$$

The result differs depending on *L* but the sum of  $\Delta R_P$  and  $\Delta R_{CR}$  uniformly equals  $\Delta R$ . It will be demonstrated using Fig. 1(c), in which the *x*-axis represents  $C_R$  and the *y*-axis *P*. Point A denotes the initial state ( $C_R = 0.2$ , P = 600) and point C the terminal state ( $C_R = 0.3$ , P = 650). I calculated  $\Delta R_P$  and  $\Delta R_{CR}$  along three fictitious paths as follows:

406 1) L=AC. Line segment AC has equation  $P = 500C_R + 500, 0.2 \le C_R \le 0.3$ . Let's take  $C_R$  as the 407 parameter and write the equation in the parametric form as  $P = 500C_R + 500, C_R = C_R, 0.2 \le C_R \le 0.3$ . 408 By substituting the equation into Eq. (C1), we have:

409 
$$\Delta R_{C_R} = \int_{AC} P dC_R = \int_{0.2}^{0.3} (500C_R + 500) dC_R = 62.5$$

410 
$$\Delta R_P = \int_{AC} C_R dP = \int_{AC} C_R d(500C_R + 500) = 500 \int_{0.2}^{0.3} C_R dC_R = 12.5$$

411 2) L=AB+BC. To evaluate on the broken line, we can evaluate separately on AB and BC and then sum 412 them up. The equation for AB is  $P = 600, 0.2 \le C_R \le 0.3$ , and is  $C_R = 0.3, 600 \le P \le 650$  for BC. 413 Notes that a constant  $C_R$  or P implies that  $dC_R = 0$  or dP = 0. Eq. (C1) then becomes:

414 
$$\Delta R_{CR} = \int_{AB+BC} P dC_R = \int_{AB} P dC_R + \int_{BC} P dC_R = \int_{0.2}^{0.3} 600 dC_R + 0 = 60$$

415 
$$\Delta R_P = \int_{AB+BC} C_R dP = \int_{AB} C_R dP + \int_{BC} C_R dP = 0 + \int_{600}^{650} 0.3 dP = 15$$

416 3) L=AD+DC. The equation for AD is  $C_R = 0.2$ ,  $600 \le P \le 650$  and is P = 650,  $0.2 \le C_R \le 0.3$  for 417 DC.  $\Delta R_P$  and  $\Delta R_{C_R}$  are evaluated as:

418 
$$\Delta R_{C_R} = \int_{AD+DC} P dC_R = \int_{AD} P dC_R + \int_{DC} P dC_R = 0 + \int_{0.2}^{0.3} 650 dC_R = 65$$

419 
$$\Delta R_P = \int_{AD+DC} C_R dP = \int_{AD} C_R dP + \int_{DC} C_R dP = \int_{600}^{650} 0.2 dP + 0 = 10$$

420 As we expect, the sum of  $\Delta R_P$  and  $\Delta R_{CR}$  persistently equals  $\Delta R$  although  $\Delta R_P$  and  $\Delta R_{CR}$  varies with *L*. 421

# 422 **Appendix D: Derivation of** $\Delta R = \overline{\lambda_P} \Delta P + \overline{\lambda_E} \Delta E_0 + \overline{\lambda_n} \Delta n$

If we partition the interval  $[x_0, x_N]$  in Fig. 1(c) into *N* distinct bins of the same width  $\Delta x_i = \Delta x/N$ . Eq. (3a) can then be rewritten as:

425 
$$\Delta Z_{x} = \int_{L} f_{x}(x, y) dx = \lim_{\tau \to 0} \sum_{i=0}^{N-1} f_{x}(x_{i}, y_{i}) \Delta x_{i} = \lim_{\tau \to 0} N \Delta x_{i} \frac{\sum_{i=0}^{N-1} f_{x}(x_{i}, y_{i})}{N} = \Delta x \lim_{\tau \to 0} \frac{\sum_{i=0}^{N-1} f_{x}(x_{i}, y_{i})}{N} = \overline{\lambda_{x}} \Delta x$$

426 where  $\overline{\lambda_x} = \lim_{\tau \to 0} \frac{\sum_{i=1}^{J \to (0,r)} f_i(x_i, y_i)}{N}$ , denoting the average of  $f_x(x, y)$  along the curve *L*. Likewise, we have

427  $\Delta Z_y = \overline{\lambda_y} \Delta y$ , where  $\overline{\lambda_y}$  denotes the average of  $f_y(x, y)$  along the curve *L*. As a result, we have:

428 
$$\Delta Z = \overline{\lambda_x \Delta x} + \overline{\lambda_y \Delta y}$$
(D1)

The result can readily be extended to a function of three variables. Applying the mathematic derivation above to the MCY Equation results in a precise form of Eq. (7):

(D2)

431 
$$\Delta R = \Delta R_P + \Delta R_{E_0} + \Delta R_n = \lambda_P \Delta P + \lambda_{E_0} \Delta E_0 + \lambda_n \Delta n,$$

432 where  $\Delta R_P = \overline{\lambda_P} \Delta P$ ,  $\Delta R_{E_0} = \overline{\lambda_{E_0}} \Delta E_0$ ,  $\Delta R_n = \overline{\lambda_n} \Delta n$ , and  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  denote the arithmetic mean of  $\partial R/\partial P$ ,  $\partial R/\partial E_0$ , and  $\partial R/\partial n$  along a path of climate and catchment changes, respectively. Because  $\overline{\lambda_P} = \Delta R_P / \Delta P$ ,  $\overline{\lambda_{E_0}} = \Delta R_{E_0} / \Delta E_0$ , and  $\overline{\lambda_n} = \Delta R_n / \Delta n$ ,  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  also implies the runoff change due to a unit change in P,  $E_0$  and n, respectively.

436

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441

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Catchment	Area	D	<u>ס</u>			A T	Reference	Evaluation	The Last
No. <sup>b</sup>	$(km^2)$	R	Р	$E_0$	п	AI	Period	Period	Subperiod
1	391	218	1014	935	3.5	0.92	1933-1955	1956-2008	1998-2008
2	16.64	32.9	634	1087	3.16	1.71	1979-1984	1985-2008	1999-2008
3	559	183	787	780	2.68	0.99	1960-1978	1979-2000	1993-2000
4	606	73	729	998	3.07	1.37	1971-1995	1996-2009	2003-2009
5	760	77.9	689	997	2.66	1.45	1970-1995	1996-2009	2003-2009
6	502	57.2	730	988	3.59	1.35	1974-1995	1996-2008	1996-2008
7	673	431	1013	953	1.34	0.94	1947-1955	1956-2008	1998-2008
8	390	139	840	1021	2.61	1.22	1966-1980	1981-2005	1995-2005
9	1130	20.7	633	1077	3.79	1.7	1972-1982	1983-2007	1997-2007
10	3.2	37.5	631	954	3.49	1.51	1989-1991	1992-2009	1999-2009
11	1.95	111	767	901	3.06	1.18	1990-1992	1993-2005	1993-2005
12	89	272	963	826	2.82	0.86	1958-1965	1966-1999	1987-1999
13	243	38.5	735	1010	4.27	1.37	1989-1995	1996-2007	1996-2007
14	56.35	65.8	744	1007	3.35	1.35	1989-1995	1996-2008	1996-2008
15	14484	385	893	1022	1.11	1.14	1970-1989	1990-2000	1990-2000
16	38625	461	985	1087	1.03	1.1	1970-1989	1990-2000	1990-2000
17	59115	388	897	1161	1.02	1.29	1970-1989	1990-2000	1990-2000
18	95217	371	881	1169	1.03	1.33	1970-1989	1990-2000	1990-2000
19	121,972	171	507	768	1.17	1.52	1960-1990	1991-2000	1991-2000
20	106,500	60.5	535	905	2.25	1.69	1960-1970	1971-2009	1999-2009
21	5891	34.4	506	964	2.54	1.91	1952-1996	1997-2011	2004-2011

574 **Table 1.** Summary of the long-term hydrometeorological characteristics of the selected catchments<sup>a</sup>

<sup>a</sup>R, P, and  $E_0$  represents mean annual runoff, precipitation and potential evaporation, all in mm yr<sup>-1</sup>. n 575 (dimensionless) is the parameter representing catchment properties in the MCY equation. AI is 576 dimensionless aridity index (AI =  $E_0/P$ ). Data of Catchments 1-14 were derived from Zhang *et al.* 577 (2010). Data of Catchments 15-18 were from Sun et al. (2014). Data of Catchments 19-21 were from 578 Zheng et al. (2009), Jiang et al. (2015), and Gao et al. (2016), respectively. I used the change points 579 given in the literatures to divide the observation period into the reference and elevation periods. The LI 580 method further divides the evaluation period into a number of subperiods. The column "The Last 581 Subperiod" denotes the last one, which was used as the evaluation period for the total differential 582 method, the decomposition method and the complementary method. The bold and italic rows denote 583 that the column "Evaluation Period" is the same as the column "The Last Subperiod". 584

<sup>b</sup>Catchments 1-14 are in Ausralia and the others in China. 1: Adjungbilly CK; 2: Batalling Ck; 3:
Bombala River; 4: Crawford River; 5: Darlot Ck; 6: Eumeralla River; 7: Goobarragandra CK; 8:
Jingellic CK; 9: Mosquito CK; 10: Pine Ck; 11: Red Hill; 12: Traralgon Ck; 13: Upper Denmark River;
14: Yate Flat Ck; 15: Yangxian station, Hang River; 16: Ankang station, Hang River; 17: Baihe station,
Hang River; 18: Danjiangkou station, Hang River; 19: Headwaters of the Yellow River Basin; 20: Wei
River; 21: Yan River.

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598 **Table 2.** Comparisons of *R* (mm yr<sup>-1</sup>), *P* (mm yr<sup>-1</sup>),  $E_0$  (mm yr<sup>-1</sup>), and *n* (dimensionless) between the 599 reference and the evaluation periods<sup>a</sup>

Catchment	D	л	ת	ת	F	F			4 D	4.0	٨E	A
No.	$R_1$	$R_2$	$P_1$	$P_2$	$E_{01}$	$E_{02}$	$n_1$	$n_2$	$\Delta R$	$\Delta P$	$\Delta E_0$	$\Delta n$
1	223	216	959	1038	950	928	2.7	4.1	-7.2	79.2	-21	1.4
2	40.6	31	655	629	1087	1087	3	3.2	-9.7	-27	0	0.2
3	249	127	847	736	780	780	2.3	3.2	-122	-112	0.4	0.9
4	90.6	41.5	753	685	1002	989	2.9	3.7	-49	-67	-13	0.8
5	94.9	46.3	718	633	1000	992	2.5	3	-49	-85	-9	0.5
6	70.8	34.3	756	687	989	987	3.4	4.1	-36	-69	-2	0.6
7	575	406	1123	995	931	957	1.1	1.4	-169	-128	25	0.3
8	139	139	871	821	1043	1008	2.7	2.5	-0.4	-50	-35	0
9	24.1	19.2	659	621	1100	1067	3.7	3.8	-4.9	-37	-33	0.1
10	116	24.3	588	638	927	958	1.7	4.2	-92	50.4	31	2.5
11	297	68	986	716	884	905	2.3	3.6	-229	-271	22	1.3
12	301	265	992	956	820	828	2.7	2.8	-36	-36	7.4	0.1
13	48.5	32.6	752	725	991	1021	4.2	4.4	-16	-28	30	0.2
14	90.4	52.6	753	739	991	1015	2.9	3.7	-38	-14	24	0.8
15	435	295	948	795	1008	1047	1.1	1.2	-139	-153	38	0.1
16	520	353	1035	894	1074	1109	1	1.2	-167	-141	35	0.2
17	441	291	939	820	1149	1182	1	1.2	-151	-119	33	0.2
18	412	296	913	821	1163	1179	1	1.1	-116	-92	15	0.2
19	180	144	512	491	774	751	1.1	1.3	-36	-21	-23	0.2
20	90.2	52.1	585	520	895	908	2.1	2.3	-38	-65	13	0.2
21	37.7	24.6	521	462	954	995	2.6	2.5	-13	-59	41	0

<sup>a</sup>The subscript "1" denotes the reference period and "2" denotes the evaluation period.  $\Delta X = X_2 - X_1$  (X as a substitute for *R*, *P*, *E*<sub>0</sub>, and *n*).

Catchment LI Method			Decomposition Method	Total Differential Method			Complementary Method			
NO. <sup>a</sup>	$\Delta R_P$	$\Delta R_P  \Delta R_{E_0}  \Delta R_n$		$\Delta R_n$	$\Delta R_P$	$\Delta R_{E_0}$	$\Delta R_n$	$\Delta R_P$	$\Delta R_{E_0}$	$\Delta R_n$
1	-70.9	-8.99	-24.3	-44.6	-67	4.82	-62	-60.7	4.34	-47.3
2	-6.49	0.95	-9.74	-9.65	-7.2	1.3	-13	-6.23	1.13	-10.2
3	-89	25.9	-140	-128	-104	26.6	-483	-88	25.7	-140
4	-18.1	2.09	-35.4	-36.3	-18	2.37	-58	-14.8	1.99	-38.5
5	-27.9	1.14	-21.3	-18.6	-34	1.18	-27	-28.1	0.97	-20.9
6	-19.9	0.29	-16.7	-14.9	-24	0.36	-22	-19.9	0.29	-16.7
7	-211	-7.19	-101	-90.9	-236	-6.9	-134	-211	-6.21	-102
8	-32.2	12.3	-14.4	-12.6	-35	12.6	-15	-32.9	11.9	-13.3
9	-11.8	3.02	-9.96	-8.45	-13	0.85	-20	-8.76	0.56	-10.5
10	19.47	-5.61	-119	-96.5	0.91	-10	-291	0.56	-6.53	-99.1
11	-150	-7.46	-71.8	-60.7	-188	-9.4	-113	-144	-7.04	-78.3
12	-9.88	-3.99	-79.2	-82	-11	-0.5	-154	-10.8	-0.57	-81.6
13	-6.98	-4.36	-4.54	-4.21	-8	-5.1	-5.2	-7	-4.38	-4.51
14	-4.84	-4.42	-28.7	-27.9	-5.6	-5	-37	-4.85	-4.4	-28.6
15	-104	-8.56	-24.8	-23	-110	-9.4	-27	-103	-8.52	-25.1
16	-99.3	-7.99	-58.8	-56	-105	-8.3	-68	-99	-7.92	-59.1
17	-78.8	-6.26	-63.9	-61	-84	-6.5	-76	-78.6	-6.2	-64.2
18	-60.1	-2.79	-53.5	-52	-64	-2.9	-62	-60	-2.77	-53.6
19	-11.9	3.89	-27.6	-27	-12	3.81	-31	-11.9	3.85	-27.5
20	-27.5	-2.46	-18.5	-17	-31	-4.4	-26	-25.5	-3.47	-19.5
21	-10.4	-3.47	-2.11	-3.4	-9.9	-4.8	-4.8	-8.27	-3.86	-3.82

**Table 3.** Effects of precipitation ( $\Delta R_P$ , mm yr<sup>-1</sup>), potential evapotranspiration ( $\Delta R_{E_0}$ , mm yr<sup>-1</sup>), and catchment changes ( $\Delta R_n$ , mm yr<sup>-1</sup>) on the mean annual runoff resulting from the four methods

<sup>a</sup>The bold and italic numbers denote that the evaluation period comprises a single subperiod.

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Catchm- ent NO.	$\overline{\lambda_P}$	$\overline{\lambda_{E_0}}$	$\overline{\lambda_n}$	$\lambda_{Pf}$	$\lambda_{E \circ f}$	$\lambda_{nf}$	$\lambda_{Pb}$	$\lambda_{Eob}$	$\lambda_{nb}$
1	0.68	-0.55	-17	0.621	-0.39	-71.8	0.497	-0.32	-39.7
2	0.2	-0.08	-27.3	0.227	-0.1	-30.9	0.168	-0.07	-19.6
3	0.58	-0.36	-26.7	0.68	-0.42	-79	0.473	-0.39	-6.29
4	0.3	-0.16	-30.5	0.39	-0.2	-50.1	0.248	-0.14	-21
5	0.33	-0.14	-43.1	0.394	-0.19	-59.4	0.264	-0.12	-33.2
6	0.29	-0.16	-26.5	0.352	-0.2	-34.9	0.228	-0.12	-19.1
7	0.71	-0.32	-223	0.781	-0.33	-299	0.615	-0.26	-157
8	0.49	-0.26	-77.9	0.478	-0.27	-64.9	0.429	-0.24	-50.7
9	0.16	-0.07	-11.8	0.161	-0.07	-17.6	0.052	-0.02	-4.31
10	0.27	-0.12	-40.9	0.45	-0.16	-99.9	0.101	-0.05	-7.8
11	0.55	-0.35	-56.1	0.695	-0.44	-88.2	0.367	-0.22	-30.7
12	0.72	-0.45	-57.3	0.74	-0.53	-61.1	0.775	-0.67	-16.7
13	0.25	-0.15	-19.8	0.29	-0.17	-22.5	0.219	-0.12	-17.1
14	0.34	-0.18	-37.2	0.393	-0.21	-48.6	0.291	-0.16	-27.8
15	0.68	-0.22	-275	0.719	-0.25	-303	0.635	-0.2	-246
16	0.7	-0.23	-326	0.745	-0.24	-378	0.659	-0.21	-279
17	0.66	-0.19	-320	0.708	-0.2	-378	0.609	-0.18	-267
18	0.65	-0.19	-315	0.692	-0.19	-363	0.614	-0.18	-270
19	0.58	-0.17	-153	0.602	-0.17	-175	0.552	-0.17	-134
20	0.32	-0.12	-50.1	0.402	-0.16	-69.6	0.255	-0.1	-37.7
21	0.2	-0.06	-29.2	0.234	-0.09	-34	0.157	-0.05	-22.6

Table 4. Comparisons of the path-averaged with the point sensitivities of runoff<sup>a, b</sup> 

 $a \overline{\lambda_P}$  (mm mm<sup>-1</sup>),  $\overline{\lambda_{E_0}}$  (mm mm<sup>-1</sup>), and  $\overline{\lambda_n}$  (dimensionless) represent the path-averaged sensitivities of runoff to precipitation, potential evaporation, and catchment properties (see Appendix D). If the evaluation period comprises only one subperiod,  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  was calculated as:  $\overline{\lambda_P} = \Delta R_P / \Delta P$ ,  $\overline{\lambda_{E_0}} = \Delta R_{E_0} / \Delta E_0$ , and  $\overline{\lambda_n} = \Delta R_n / \Delta n$ . If the evaluation period comprises N > 1 subperiods, the equations become:  $\overline{\lambda_{P}} = \sum_{i=1}^{N} |\Delta R_{Pi}| / \sum_{i=1}^{N} |\Delta P_{i}|, \overline{\lambda_{E_{0}}} = -\sum_{i=1}^{N} |\Delta R_{E_{0}i}| / \sum_{i=1}^{N} |\Delta E_{0i}|, \text{ and } \overline{\lambda_{n}} = -\sum_{i=1}^{N} |\Delta R_{ni}| / \sum_{i=1}^{N} |\Delta n_{i}|, \text{ where the subscript } i \text{ denotes the } i\text{th}$ subperiod.

 ${}^{b}\lambda_{P}$ ,  $\lambda_{E_{0}}$ , and  $\lambda_{n}$  represent the point sensitivities of runoff. The subscript "f" represents a forward approximation, i.e. substituting the observed mean annual values of the reference period into Eq. (2) to calculate the sensitivities, while the subscript "b" represents a backward approximation, i.e. substituting 

the observed mean annual values of the evaluation period into Eq. (2). 

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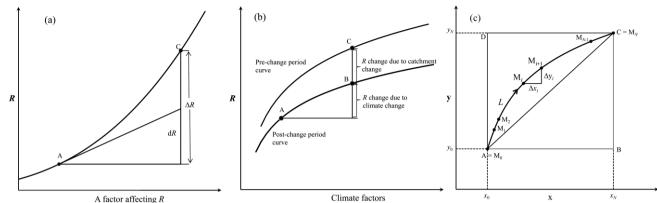
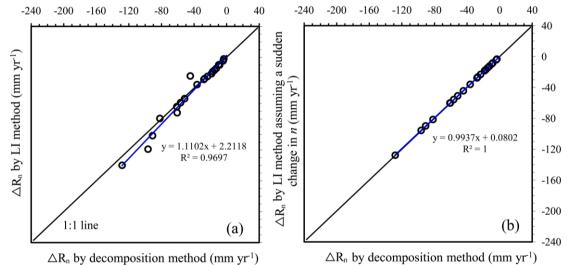
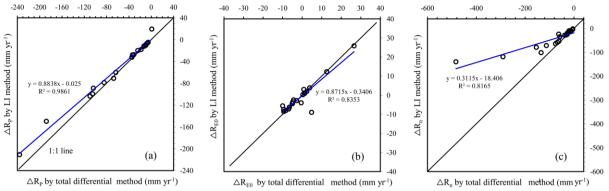


Fig. 1. A schematic plot to illustrate (a) the total differential method, (b) the decomposition method, and (c) the LI method. Pont A denotes the initial state and Point C the terminal state.



656 Fig. 2. Comparison between the LI method and the decomposition method. (a) Comparison of the 657 estimated contribution to the runoff change from catchment change  $(\Delta R_n)$ ; (b) the decomposition 658 method is equivalent to the LI method that assumes a sudden change in catchment properties following 659 climate change. In this case, the integral path of the LI method is the broken line AB+BC in Fig. 1(c) (x 660 represents climate factors and catchment properties, v i.e. n) and 661  $\Delta R_n = \int_{AB+BC} \frac{\partial R}{\partial n} dn = \int_{AB} \frac{\partial R}{\partial n} dn + \int_{BC} \frac{\partial R}{\partial n} dn = 0 + \int_{BC} \frac{\partial R}{\partial n} dn = \int_{n_1}^{n_2} f_n(P_2, E_{02}, n) dn , \text{ where the subscript}$ "1" 662 denotes the reference period and "2" denotes the last subperiod of the evaluation period. 663



**Fig. 3.** Comparison of the estimated contribution to runoff from the changes in (a) precipitation  $(\Delta R_P)$ , (b) potential evapotranspiration  $(\Delta R_{E_0})$ , and (c) catchment properties  $(\Delta R_n)$  between the LI method and the total differential method.

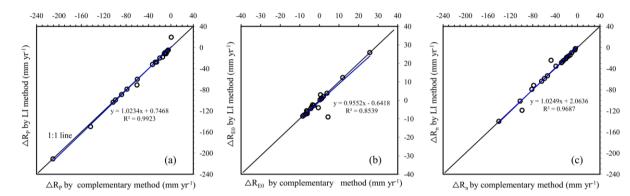
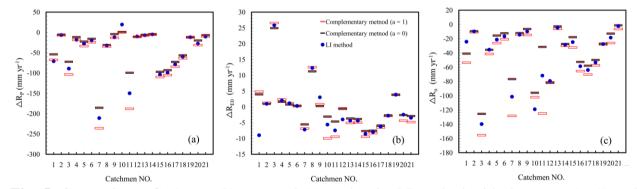


Fig. 4. Comparison of (a)  $\Delta R_P$ , (b)  $\Delta R_{E_0}$ , and (c)  $\Delta R_n$  between the LI method and the complementary method (a = 0.5).

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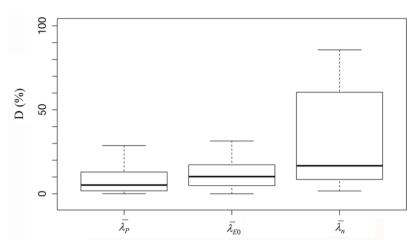
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**Fig. 5.** Comparison of (a)  $\Delta R_P$ , (b)  $\Delta R_{E_0}$ , and (c)  $\Delta R_n$  by the LI method with the upper (*a*=1) and lower (*a*=0) bounds given by the complementary method. According to Zhou *et al.* (2016), the upper and lower bounds of  $\Delta R_P$ ,  $\Delta R_{E_0}$ , and  $\Delta R_n$  are reached when *a* is 0 or 1.

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675



**Fig. 6**. Boxplots showing the temporal variability of the path-averaged sensitivities of water yield to precipitation  $(\overline{\lambda_P})$ , potential evapotranspiration  $(\overline{\lambda_{E_0}})$ , and catchment properties  $(\overline{\lambda_n})$ . *D* (%) was calculated as the relative difference between the sensitivity of the whole evaluation period and that of a subperiod. In the calculations, I excluded the catchments whose evaluation periods were not long enough to comprise two or more subperiods. Box spans the inter-quartile range (IQR) and solid lines are medians. Whiskers represent data range, excluding statistical outliers, which extend more than 1.5IQR from the box ends.

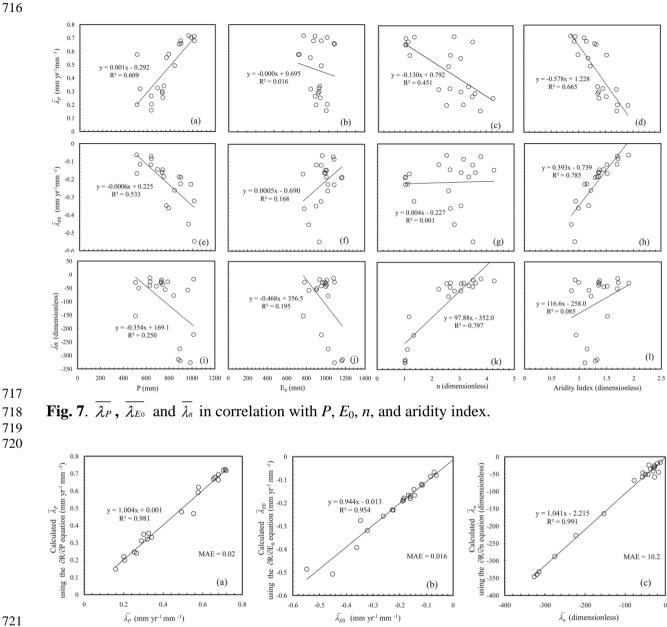


Fig. 8. Comparisons of  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  (given in Table 4) with those predicted using Eq. (2) with the long-term mean values of *P*,  $E_0$ , and *n* as inputs.  $MAE = N^{-1} \sum_{i=1}^{N} |O_i - P_i|$ , is the mean absolute error, where *O* and *P* are values that actually encountered (given in Table 4) and predicted using Eq. (2) respectively, and *N* is the number of selected catchments.

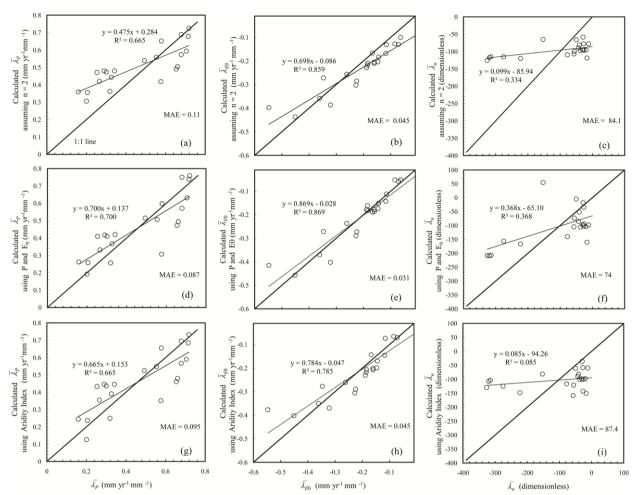


Fig. 9. Comparisons of  $\overline{\lambda_P}$ ,  $\overline{\lambda_{E_0}}$  and  $\overline{\lambda_n}$  with those predicted by the three strategies. (a)-(c) by Eq. (2) with a constant *n* (*n* = 2), (d)-(f) by the regression equations established using *P* and *E*<sub>0</sub>:  $\overline{\lambda_P} = 0.0011P - 0.0006E_0 + 0.21$  ( $R^2 = 0.7$ ),  $\overline{\lambda_{E_0}} = 0.0007P - 0.0007E_0 - 0.38$  ( $R^2 = 0.87$ ), and  $\overline{\lambda_n} = -0.302P - 0.372E_0 + 493$  ( $R^2 = 0.37$ ), and (g)-(i) by the regression equations established using only the aridity index, as shown in Fig. 7 (d), (h) and (l). *MAE* was calculated as for Fig. 8.