

On the representation of water reservoir storage and operations in large-scale hydrological models: implications on model parameterization and climate change impact assessments

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Abstract. During the past decades, the increased impact of anthropogenic interventions on river basins has prompted hydrologists to develop various approaches for representing human-water interactions in large-scale hydrological and land surface models. The simulation of water reservoir storage and operations has received particular attention, owing to the ubiquitous presence of dams. Yet, little is known about (1) the effect of the representation of water reservoirs on the parameterization of hydrological models, and, therefore, (2) the risks associated to potential flaws in the calibration process. To fill in this gap, we contribute a computational framework based on the Variable Infiltration Capacity (VIC) model and a Multi-Objective Evolutionary Algorithm, which we use to calibrate VIC's parameters. An important feature of our framework is a novel variant of VIC's routing module that allows us to simulate the storage dynamics of water reservoirs. Using the upper Mekong river basin as a case study, we calibrate two instances of VIC—with and without reservoirs. We show that both model instances have the same accuracy in reproducing daily discharges (over the period 1996–2005); a result attained by the model without reservoirs by adopting a parameterization that compensates for the absence of these infrastructures. The first implication of this flawed parameter estimation stands in a poor representation of key hydrological processes, such as surface runoff, infiltration, and baseflow. To further demonstrate the risks associated to the use of such model, we carry out a climate change impact assessment (for the period 2050–2060), for which we use precipitation and temperature data retrieved from five Global Circulation Models (GCMs) and two Representative Concentration Pathways (RCPs 4.5 and 8.5). Results show that the two model instances (with and without reservoirs) provide different projections of the minimum, maximum, and average monthly discharges. These results are consistent across both RCPs. Overall, our study reinforces the message about the correct representation of human-water interactions in large-scale hydrological models.

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20 1 Introduction

Hydrological systems consist of multiple physical, chemical, and biological processes, most of which are profoundly altered by anthropogenic interventions (Nazemi and Wheater, 2015a, b). Land cover modifications or hydraulic infrastructures, for

instance, affect both surface and sub-surface hydrological processes by redistributing water over time and space (Haddeland et al., 2006; Bierkens, 2015). Such alterations are expected to amplify in the near future, owing to the increase in water and energy consumption (Abbaspour et al., 2015). In this context, hydrological models play a key role, as they help plan the use of water resources in a sustainable way, so as to avoid adverse impacts on ecosystems and livelihoods (Bunn and Arthington, 2002; Yassin et al., 2019). A detailed and accurate representation of the anthropogenic interventions within hydrologic models is thus of paramount importance: successful water management plans must necessarily build on reliable models.

Water reservoirs are arguably one of the most common infrastructures altering hydrological processes at the catchment scale; yet, their representation in hydrological and land surface models is challenged by multiple factors. First, the vast majority of the models currently available was initially conceived to study and understand the behaviour of natural systems, so the added representation of water reservoirs entails the partial modification of the model structure. Second, the existing databases (e.g., GRanD; Lehner et al. (2011)) provide details on dam design specifications, but no information on the management aspects, such as the operating rules or flood contingency plans. Third, the installation of dams is generally combined with impoundment (or filling) strategies, which may largely differ from the steady-state operating rules and last from a few months to several years (Gao et al., 2010; Zhang et al., 2016). Although the complexity of these factors varies with the study site at hand, one might imagine that the representation of water reservoir storage and operations is particularly challenging for large-scale models, simply because of the number of dams deployed over time in large river basins. It is perhaps not surprising to observe that water reservoirs—and their corresponding operations—have not been consistently accounted for across the broad number of large-scale hydrological modelling studies available in literature.

A simple and popular approach stands in the exclusion of large impounds from the streamflow routing modules; a modelling choice that has been adopted in many regions across the globe (Maurer et al., 2002; Jayawardena and Mahanama, 2002; Akter and Babel, 2012; de Paiva et al., 2013; Leng et al., 2016). Such approach can support the investigation of various physical processes (e.g., emergence of new hydrological regimes, generation of land surface fluxes), but obviously prevents the application of the hydrological models to downstream water management problems, such as investigating the impact of regime shifts on hydropower production. Another potential issue with this approach stands in the model parameterization, which might be affected by a calibration process carried out with hydrological time series altered by anthropogenic interventions. de Paiva et al. (2013), for instance, implemented the MGB-IPH hydrologic/hydraulic model to the Amazon River basin—a region characterized by the presence of hydroelectric dams (Finer and Jenkins, 2012)—and yet obtained reliable calibration performance at multiple gauging stations. A similar example is represented by Abbaspour et al. (2015), who simulated hydrological and water quality processes for the entire European continent. Despite neglecting the presence of hydraulic infrastructures, the model yielded acceptable values for the goodness of fit statistics. One may thus wonder whether the calibration process somehow compensates for a deficiency in the model structure.

With the goal of striking a balance between an accurate representation of reservoirs and the ‘costs’ due to the modification of the model structure, several researchers have adopted an hybrid approach, in which the output of hydrologic/hydraulic models (e.g., runoff or streamflow at multiple locations) is post-processed with the aid of water management (or reservoir operation) models. The very first efforts employed data on water uses to correct the output of global models, such as WaterGAP (Alcamo

et al., 1997) or WBM (Vörösmarty et al., 1998). Using a similar concept, Hanasaki et al. (2006) accounted for 452 reservoirs in a global river routing model. More sophisticated post-processing techniques are based on optimization algorithms, which are used to design either reservoir operating rules or sequences of reservoir discharges that meet pre-defined objectives (e.g., hydropower production). Lauri et al. (2012) and Hoang et al. (2019), for example, first calibrated the distributed hydrological model VMod for the Mekong river basin, and then post-processed its output using a linear programming algorithm that designed the discharge time series for 126 dams over a given simulation scenario. Similarly, Turner et al. (2017) and Ng et al. (2017) examined the vulnerability of global hydropower production to climate changes and El Niño Southern Oscillation by correcting the discharge simulated by WaterGAP. In this case, the correction entailed designing bespoke reservoir operating rules through the use of a stochastic dynamic programming algorithm (Turner and Galelli, 2016). Other recent applications of post-processing techniques were adopted in Masaki et al. (2017); Veldkamp et al. (2018); Zhou et al. (2018).

Naturally, the most suitable approach stands in the direct representation of water storage and operations within a large-scale hydrological model (Bellin et al., 2016). This approach requires not only to modify the model structure (or to develop a new one), but also to gather information on the design specifications and operating rules of the water reservoirs. Because of these challenges, the number of large-scale hydrological modelling studies adopting such approach is limited. A first attempt was carried out by Pokhrel et al. (2012), who incorporated a water regulation module into the MATSIRO model to reproduce the dynamics of heavily regulated global river basins. More recently, Shin et al. (2019) integrated a reservoir storage dynamics and release scheme into the continental hydrological model LEAF-Hydro-Flood to simulate $\sim 1,900$ reservoirs within the contiguous United States. In both studies, the authors gave particular emphasis to the calibration of the reservoir operating scheme, and demonstrated that the hydrological model accurately represents some processes altered by human interventions, such as the reservoir-floodplain inundation.

While the relevance and needs for the description of human-water interactions in hydrological models are now well acknowledged (Nazemi and Wheater, 2015a), less is known about the risks associated to a poor representation of such interactions. For example, can the estimation of some hydrological parameters be flawed by an inaccurate representation of water reservoir storage? What are the implications for the downstream applications of a flawed model? To answer these questions, we take the upper Mekong river basin as a case study, for which we develop a computational framework based on the Variable Infiltration Capacity (VIC) model (Liang et al., 1994) and a Multi-Objective Evolutionary Algorithm (MOEA) tasked with the problem of calibrating the model. A key feature of the framework is a novel variant of VIC—named VIC-Res—that allows us to represent the reservoir storage dynamics and operating rules within the streamflow routing module. In a first experiment, we use this framework to calibrate two instances of VIC—with and without reservoirs. As we shall see, both model instances attain the same accuracy; a result obtained by the model instance without reservoirs by adopting a parameterization that compensates for the absence of these infrastructures. In turn, this leads to a poor representation of key hydrological processes, such as infiltration or baseflow. In our second experiment, we demonstrate the potential implications of these unintended consequences by applying two selected model instances (with and without reservoirs) to a climate change impact assessment, for which we obtain partially-diverging expectations on the hydrological alterations caused by global warming.

In the remainder of the manuscript, we first describe the study area (Section 2) and then proceed by illustrating the computational framework (Section 3), including the data on dams and operating rules. In Section 4, we provide a detailed description of the results obtained for the aforementioned experiments, whose implications are further discussed in Section 5.

2 Study area

5 The Mekong is a trans-boundary river that flows through China, Myanmar, Thailand, and Laos before pouring into one of the world's largest delta located in Cambodia and Vietnam. The catchment area of about 795,000 km² can be divided into two parts, namely the upper Mekong, or Lancang, and the lower Mekong basins (Figure 1a). The upper Mekong stretches in a North-to-South direction and drains an area of 167,400 km². As shown in Figure 1b, the region is characterized by a complex orography, with high mountains and deep valleys (the elevation ranges from 362 to 6,494 m). Because of these orographical conditions,
10 the spatio-temporal variability of rainfall and temperature is remarkable. The average annual precipitation across the basin ranges from 752 to 1,025 mm, 70% of which is concentrated in the monsoon season (May to November). The precipitation in the Northwestern part of the basin is sometimes lower than 250 mm/year, making it dryer than the Southeastern part, which receives an average of 1,600 mm/year (Han et al., 2019). The average annual temperature across the basin varies narrowly (from 12.3 to 14.3 °C), but the latitudinal temporal gradient is much larger—about 2.2 °C/100 km (Wang et al., 2014). Climate
15 changes are expected to modify both rainfall and temperature patterns, making the region warmer, wetter, and more susceptible to extreme weather events (Tang et al., 2015).

The favourable orography and abundant water availability have attracted massive investments in the hydropower sector (see the location of the dams in Figure 1b), with consequent impacts on the riverine ecosystems (Lauri et al., 2012; Dang et al., 2018; Hoang et al., 2019). The impact of these dams goes beyond the upper Mekong basin (Zhao et al., 2012; Han et al., 2019):
20 the analysis of historical data shows that dams have already modified many indicators of hydrological alterations in the entire basin, including the Cambodian lowlands and river delta (Hecht et al., 2018). These alterations appear to be more evident since the early 1990s, when Xi'er He 1 and Manwan dams started storing water (Cochrane et al., 2014; Lu et al., 2014; Dang et al., 2016). Overall, the upper Mekong basin offers two desirable features for investigating the effect of water reservoir storage and operations on the parameterization of hydrological models. First, the catchment is heavily regulated (Hecht et al., 2018).
25 Second, the catchment area is about 24% of the whole Mekong River basin, so this helps reduce the computational requirements of the optimization-based calibration process. The location of the gauging station (Chiang Saen) used for the calibration process is illustrated in Figure 1a. This station provides a long and reliable daily time series, which has been adopted by several studies on the Mekong basin (e.g., Lauri et al. (2012); Cochrane et al. (2014); Lauri et al. (2014); Hoang et al. (2016)). To validate the model, we use monthly discharge values at Jiuzhou station (see Figure 1a), retrieved from He et al. (2009); Wang et al. (2018);
30 Tang et al. (2019). For both stations, we used data belonging to the period 1996–2005.

The aforementioned orography and climate conditions are not particularly suitable for agricultural activities, which are indeed limited. The basin is mountainous, with mostly rocks and a shallow Quaternary alluvium (Carling, 2009; Gupta, 2009). Due to the impermeability of bedrock underneath isolated valleys, only a very small fraction of water leaks into the ground

through karst aquifer units (Lee et al., 2017). As a result, subsurface water is mostly generated in the shallow loam layer in the form of baseflow.

3 Materials and methods

The first goal of our study is to investigate the role of water reservoir storage and operations on the parameterization of large-scale hydrological models. To this purpose, we adopt the computational framework illustrated in Figure 2, which consists of VIC's rainfall-runoff and routing modules and the ε -NSGAI MOEA. In Section 3.1 we provide a detailed description of VIC's modules, including the proposed variant for representing reservoir storage dynamics. The data and experimental setup of the framework are outlined in Section 3.2 and 3.3. In Section 3.4, we describe the climate change data used for our second goal, that is, to demonstrate that different model parameterizations caused by the absence (presence) of water reservoirs can affect the results of a climate change impact assessment.

3.1 Hydrological-water resources management model

3.1.1 Variable Infiltration Capacity model

VIC is a large-scale, semi-distributed land hydrological model maintained and developed by the University of Washington (<http://www.hydro.washington.edu>). The model consists of two core components, namely a rainfall-runoff and routing module (Figure 2), which can be applied to multiple spatial scales and implemented with different temporal resolutions—daily, in our case. The rainfall-runoff module simulates the water and energy fluxes that govern the terrestrial hydrological cycle (Liang et al., 1994). To this purposes, it takes as input climate forcings (precipitation and temperature), land use and soil maps, Leaf Area Index and albedo, and a Digital Elevation Model (DEM). For each computational cell, the module uses one vegetation layer and two (or three) soil layers: the upper soil layer controls evaporation, infiltration, and runoff, while the lower layer controls the baseflow generation. These gridded variables are then used by the routing module (Lohmann et al., 1996, 1998), which simulates discharge throughout the river network using a linearized version of the Saint-Venant equations. Specifically, the module first creates the impulse response functions for each grid cell, and then simulates the flow convolution by aggregating the flow contribution from all upstream cells at each time step lagged according the response functions (ibid).

Following the approach adopted in previous works on the calibration of VIC (e.g., Dan et al. (2012); Park and Markus (2014); Xue et al. (2015)), we focus our attention on six main parameters that control the rainfall-runoff process (Table 1). These parameters are the thickness of the two soil layers (d_1 and d_2), the infiltration parameter (b), and three baseflow parameters (D_s , D_{\max} , and W_s). The parameter b characterizes the shape of the Variable Infiltration Capacity curve, and therefore influences the available infiltration capacity and quantity of runoff generated by each cell (for additional details, please refer to Ren-Jun (1992) and Todini (1996)). A higher value of b leads to a lower infiltration rate and higher surface runoff. The three parameters D_s , D_{\max} , and W_s determine the shape of the Baseflow curve (Franchini and Pacciani, 1991), which relates the soil moisture in the lower layer to the amount of baseflow. More specifically, D_{\max} is the maximum baseflow that can occur in the lower layer,

while D_s is the fraction of D_{\max} associated to the transition from linear to non-linear (rapidly increasing) baseflow generation. W_s is the fraction of the maximum soil moisture (in the lower layer) where non-linear baseflow occurs. Hence, higher values of W_s increase the water content needed for rapidly increasing baseflow. The thickness of the two soil layers affects several processes. In general, thicker layers delay the seasonal peak flow and increase the evaporation losses (since they increase the
5 water storage capacity).

3.1.2 Water reservoir storage and operations

To represent the storage dynamics of water reservoirs, we modified VIC's routing module (version 4.2) using the following steps. First, we determine the location of all dams within the basin, and directly add them to the model using a dam cell (Figure 3a-b). To avoid allocating multiple dams within the same cell, we adopt a high-spatial resolution of 0.0625 degree
10 (approximately 6.9 km). Then, we aggregate the reservoir storage in the dam cell, where we calculate the daily mass balance. From the dam cell, water is discharged using the rule curves described in the following paragraph. Since the construction of a dam is likely to create an impoundment with surface area larger than the dam cell, we proceed by estimating the maximum reservoir extent; an information used to determine the so-called reservoir cells, namely cells that are at least half-covered by
15 water (see Figure 3b). Although these cells do not contain the reservoir storage, they can affect the evaporation processes, so their number and location must be determined accurately. The flow routing in these cells follows the information provided in the flow direction map (described in Section 3.2.1). Further details about the implementation of this variant of VIC's routing module are given in Section S1. We note that a more realistic way of representing a reservoir within a hydrological model is to spread the reservoir storage over multiple upstream cells from the dam location (Shin et al., 2019). Yet, a successful
20 implementation of this method requires a detailed bathymetry of all reservoirs within the basin (an information that may not always be available) and a 2D model of the reservoir, so as to accurately calculate the water fluxes between the different reservoir cells.

As for the reservoir operations, we adopt an approach similar to that of Piman et al. (2012), which relies on rule curves conceived to maximize the hydropower production—an assumption justified by the fact that all dams within the upper Mekong are operated for hydropower supply (Räsänen et al., 2017). Determining the rule curve for a given reservoir means determining
25 the daily target water levels. For the case of hydropower production in the Mekong basin, such rule should allow to (1) drawdown the reservoir storage during the drier months (e.g., December to May) to maximize the production of electricity, (2) recharge the depleted storage during the monsoon season, and (3) avoid the risks of spilling water at the end of the monsoon season (see the illustration in Figure 3c). Rule curves are tailored to each reservoir within the basin by determining the time at which the minimum and maximum water levels are reached (May and November, in the Mekong; Piman et al. (2012)), setting
30 the value of the minimum and maximum water levels (the minimum and maximum elevation levels of each reservoir, in our case), and finally connecting these points with a piecewise linear function that gives us the daily target level for each calendar day.

As shown in Figure 3c, there are three water levels that divide the storage into four zones. These levels are the dead water (or minimum elevation) level, the target water level, and the full (or maximum elevation) level. If the water level falls below

the dead water level (Zone 1), the turbines are not operated. If the level is between the dead water and target level (Zone 2), the model first uses the information on the incoming daily inflow to solve a mass balance equation, in which the discharge from the dam is kept at zero. This is aimed to understand whether the water level is expected to go beyond the target at the end of the day. If that is the case, the model discharges through the turbines the amount of water needed to keep the level close to the target. Otherwise, the turbines are not activated. In Zone 3 (between the target and full level), the turbines are used at their maximum capacity, until the water reaches the target level. In Zone 4 (i.e., level above the maximum elevation), both turbines and spillways are used. The key advantage of the rule curves adopted here is that they do not require the calibration of any parameter. Naturally, such approach is less applicable when the information on the operating objectives is not available, or when dealing with multi-purpose water systems.

10 Overall, our model implements the following mass balance equation at each simulation time step t (and for each reservoir):

$$S_{t+1} = S_t + Q_t - E_t - R_t, \quad (1a)$$

$$0 \leq S_t \leq S_{cap}, \quad (1b)$$

$$0 \leq R_t \leq \min(S_t + Q_t - E_t, R_{max}), \quad (1c)$$

where S_t is the reservoir storage at time t , Q_t the inflow volume, E_t the evaporation loss, and R_t the water released from the reservoir. Both storage S_t and discharge R_t are constrained by the design specifications of each reservoir. Specifically, the storage cannot exceed the reservoir capacity S_{cap} (eq. (1b)), while the discharge is bounded by the water availability and capacity of the turbines R_{max} (eq. (1c)). The excess water, if any, is spilled:

$$Spill_t = \max(0, S_t + Q_t - R_{max} - E_t - S_{cap}). \quad (1d)$$

Eq. (1d) thus represents the release dynamics when the reservoir water level is in Zone 4. Zone 1, 2, and 3 are represented by the following equations:

$$R_t = \begin{cases} 0 & \text{if } S_t \leq S_d \text{ (Zone 1)} \\ 0 & \text{if } S_d \leq S_t \leq S_{ts,t_{modT}} \text{ and } S_t + Q_t - E_t \leq S_{ts,t_{modT}} \text{ (Zone 2, case 1)} \\ S_{ts,t_{modT}} - (S_t + Q_t - E_t) & \text{if } S_d \leq S_t \leq S_{ts,t_{modT}} \text{ and } S_t + Q_t - E_t > S_{ts,t_{modT}} \text{ (Zone 2, case 2)} \\ (S_t + Q_t - E_t) - S_{ts,t_{modT}} & \text{if } S_{ts,t_{modT}} \leq S_t \leq S_{cap} \text{ and } S_t + Q_t - E_t - R_{max} \leq S_{ts,t_{modT}} \text{ (Zone 3, case 1)} \\ R_{max} & \text{if } S_{ts,t_{modT}} \leq S_t \leq S_{cap} \text{ and } S_t + Q_t - E_t - R_{max} > S_{ts,t_{modT}} \text{ (Zone 3, case 2)} \end{cases} \quad (2)$$

where S_d is the storage corresponding to the dead water level, and $S_{ts,t_{modT}}$ the target storage at time t_{modT} (in our study, we use a period T of 365 days).

3.2 Data and preprocessing

3.2.1 Climate forcings and other input variables

Climate forcings are represented by precipitation and air temperature (maximum and minimum), which must be provided at a daily time step. As far as precipitation is concerned, we use the APHRODITE dataset (Asian Precipitation - Highly-Resolved Observational Data Integration Towards Evaluation), developed by the University of Tsukuba, Japan, using rain-gauge data (Yatagai et al., 2012). APHRODITE is available with a spatial resolution of 0.25 degree, and has been shown by Lauri et al. (2014) to be the most suitable precipitation dataset available for the Mekong basin. A similar observation applies to the CFSR (Climate Forecast System Reanalysis) maximum and minimum temperature dataset (Saha et al., 2014). These data are then interpolated to meet the spatial resolution of 0.0625 degrees adopted in our implementation. More specifically, we use the bilinear interpolation method, which has found successful application in some recent studies (e.g., Hoang et al. (2016); Shin et al. (2019)). We also bias correct APHRODITE dataset (using a multiplying factor of 1.26), as recommended by Lauri et al. (2014).

The monthly Leaf Area Index and albedo are derived from the Moderate Resolution Imaging Spectroradiometer (Terra MODIS) satellite images, which represent changes in canopy and snow coverage over time. (It is worth noting that snowmelt only marginally contributes to the streamflow of the Mekong River; Räsänen et al. (2016).) Land use and land cover data are obtained from the Global Land Cover Characterization (GLCC) dataset, developed by the United States Geological Survey. We choose this product because it was completed in 1993, close to the simulation period adopted in our study (1995–2005). With such choice, we make sure that the influence of land use dynamics on the model parameterization is minimized. Soil data are extracted from the Harmonized World Soil Database (HWSD), developed by the International Institute for Applied System Analysis and Food and Agriculture Organization, and last updated in 2013. Both land use and soil maps are generated with the majority resampling technique, since their original spatial resolution is 30 arcsecond (approximately 1 km). This technique assigns the most common values found from the group of involved pixels to the new cell. The resulting maps are illustrated in Figure 4a-b. The land use map shows that the upper reaches of the basin are characterized by the presence of grassland, while the lower reaches—with complex terrain and large altitudinal variations—present mixed coniferous forest ecoregions. Soil characteristics are also heterogeneous: in the central and northern part of the basin, soil is characterized by a shallow layer consisting of loam, sandy loam, and clay. At the border between China, Myanmar, and Laos (near Chiang Saen station), soil characteristics are dominated by the presence of sandy clay loam.

To estimate the flow directions, we use the Global 30 Arc-Second Elevation (GTOPO30) DEM, which has been adopted in several studies (e.g., Kite (2001); Wu et al. (2012); Li et al. (2013)). First, we mask this DEM with the shape of the upper Mekong basin. Since GTOPO30 has a spatial resolution of 30 arcsecond, we then resample the DEM to the resolution of our VIC model using the average resampling technique (Hoang et al., 2019). Finally, we manually correct the flow direction map generated by ArcGIS by comparing it to a detailed river network provided by the Mekong River Commission. Such correction is necessary, since errors are to some extent unavoidable when automatically generating a flow direction map—because overland

runoff and interflow directions depend on the relation between hillslope characteristics and adopted spatial resolution. The resulting flow direction map is illustrated in Figure 4c.

3.2.2 Dams and reservoir informations

5 Our model requires detailed information on the reservoirs, namely location, storage capacity, dam height, dead storage, turbine design discharge, and maximum and minimum elevation levels. Such information (summarized in Table 2) was retrieved by cross-checking the databases provided by the Mekong River Commission, the International Commission On Large Dams, and the Global Reservoir and Dam Database. Since data on reservoir bathymetry are not available, we modelled the storage-depth relationship with Liebe's method, which assumes that the reservoir is shaped like a top-down pyramid cut diagonally in half
10 (Liebe et al., 2005). In other words, the relation between reservoir volume (V) and depth (or level, h) is equal to $V = ah^3$, where a is a shape factor equal to V_{cap}/h_{max}^3 (V_{cap} is the live storage capacity and h_{max} the maximum water depth). This method has been adopted for regional and global studies (see Ng et al. (2017); Shin et al. (2019)).

As for the maximum reservoir extent (needed to determine the reservoir cells), the existing databases do not provide detailed information, such as the reservoir polygon, so we proceeded by analyzing remote sensed data. More specifically, we extracted
15 surface water profiles from Landsat TM and ETM+ imagery. Landsat images are raster grids with seven layers corresponding to seven bands (excluding the panchromatic band). The Normalized Difference Water Index (NDWI) was calculated using the near-infrared (NIR, Band 4) and Short-Wave infrared (SWIR, Band 5) bands: $NDWI=(NIR-SWIR)/(NIR+SWIR)$. Water bodies have NDWI values greater than 0.3 (McFeeters, 2013), so from the NDWI raster we can create a binary raster in which 1 denotes a reservoir cell (and 0 a non-reservoir cell). This process can yield an accurate estimation of the reservoir cells, since
20 Landsat images have a spatial resolution of 30 x 30 m.

When calculating the daily mass balance for each reservoir, we consider three main processes, namely inflow, evaporation, and release. Infiltration and seepage (via dam body, abutment, and foundation) are neglected. That is because of two reasons. First, the Upper Mekong basin is a mountainous region, with mostly rocks and a shallow Quaternary alluvium (see Section 2), so infiltration losses are to some extent marginal as compared to inflow, release, and evaporation. Second, the dams considered
25 in our study are built with concrete (and with rocky abutments and foundations), so seepage is indeed limited.

3.3 Experimental setup

To carry out the calibration exercise (with and without reservoirs), we couple VIC with the ϵ -NSGAI algorithm (Reed et al., 2013), which has found successful application in many water resources problems—including model calibration (ibidem). In our case, the decision variables are represented by the six parameters controlling the rainfall-runoff process in VIC (Section
30 3.1.1), and whose range of variability is reported in Table 1. As for the objective functions, we consider two goodness of fit statistics dependant upon the simulated streamflow, namely the Nash-Sutcliffe Efficiency (NSE) and Transformed Root Mean Square Error (TRMSE), which assess the model performance on high and low flows, respectively (Dawson et al., 2007). The

NSE is defined as:

$$NSE = 1 - \frac{\sum_{t=1}^n (Q_s^t - Q_o^t)^2}{\sum_{t=1}^n (Q_o^t - \overline{Q_o})^2}, \quad (3)$$

where n is the number of time steps, Q_s^t the simulated streamflow (at time t), Q_o^t the observed streamflow (at Chiang Saen station), and $\overline{Q_o}$ the mean of the observed streamflow. The TRMSE is defined as:

$$TRMSE = \sqrt{\frac{1}{n} \sum_{t=1}^n (z_{s,t} - z_{o,t})^2}, \quad (4)$$

5 where $z_{s,t}$ and $z_{o,t}$ represent the value of the simulated and observed streamflow (at time t) transformed by the expression $z = \frac{(1+Q)^\lambda - 1}{\lambda}$, ($\lambda = 0.3$). In other words, λ scales down the values of the streamflow, and TRMSE thus emphasizes the errors on the low flows. In this specific modelling problem, capturing both high and low flows is particularly important, since the riverine ecosystems are sensitive to both dry and wet conditions (Hoang et al., 2016).

Both objective functions are calculated for the period 1996–2005—after a one-year spin-up period, 1995—and scaled between 0 and 1, so we set only one value of ε (equal to 0.001). The other ε -NSGAI parameters to setup are the size of the initial population and number of function evaluations, which are equal to 10 and 250—a setting that strikes a reasonable balance between the computational requirements of the calibration exercise and the quality of the solutions. Each calibration exercise (with and without reservoirs) is solved with 20 different random seeds, so as to characterize the variability in the ε -NSGAI stochastic search process. The final set of Pareto-efficient solutions (i.e., alternative parameterizations of VIC) thus corresponds to the set of Pareto-efficient solutions identified across all 20 seeds. All experiments are carried out on an Intel (R) Xeon (R) W-2175 CPU 2.50 GHz with 128 GB RAM running Linux Ubuntu 16.04 (Xenial Xerus), using a Python implementation of various MOEAs (Platypus) that allows to parallelize the optimization experiments. For each of the 20 seeds, we used four cores, taking approximately 200 hours per core (wall-clock time).

Since six (out of eleven) dams became operational during the study period (see Table 2), the VIC simulation with reservoirs is implemented in such a way to activate the reservoirs at the right time. In this specific implementation, we do not use filling strategies different from the rule curves described in Section 3.2.2, because all six dams reach a steady-state operation within a few months (data not shown).

3.4 Climate change data

For our second experiment, we used the CMIP5 climate projections to derive climate change scenarios for the period 2050–2060. Since the data provided by the Coordinated Regional Climate Downscaling Experiment only cover one GCM for our study site (Giorgi and Gutowski Jr, 2015), we followed the approach taken by previous studies (e.g., Hoang et al. (2016, 2019)), and proceeded by using GCM projections as basis for our scenarios. As far as the GCMs are concerned, we used ACCESS1-0, CCSM4, CSIRO Mk3.6, HadGEM2-ES, and MPI-ESM-LR, whose reliability for this region has been evaluated in a few previous studies (Sillmann et al., 2013; Huang et al., 2014; Ul Hasson et al., 2016; Hoang et al., 2016). The main characteristics of the GCMs are summarized in Table 3. As for the Representative Concentration Pathways (RCPs), we chose RCPs 4.5 and

8.5. The former is a medium-to-low scenario that assumes a stabilization of radiative forcing to 4.5 W m^{-2} by 2100, while the latter is a high emission scenario based on an increase of the radiative forcing to 8.5 W m^{-2} by 2100. These two RCPs should provide a broad range of climate variability for the region—and thus exclude RCP 2.6, which is characterized by the lowest radiative forcings.

To prepare the precipitation and temperature data used by VIC, we then re-gridded and bias-corrected the GCMs outputs. The first step is necessary to overcome the limited spatial resolution of the GCMs (our VIC implementation uses a resolution of $0.0625^\circ \times 0.0625^\circ$), and is carried with the bilinear interpolation method. The bias-correction is performed with the delta method (Diaz-Nieto and Wilby, 2005; Choi et al., 2009), which has already been applied to our study site (Lauri et al., 2012). With this method, we calculate correcting factors for precipitation and temperature using the following expressions:

$$\Delta_{PRE} = \frac{\bar{P}_{\text{series},i}}{\bar{P}_{\text{ref},i}}, \quad (5)$$

$$\Delta_{TEMP} = \frac{\bar{T}_{\text{series},i} - \bar{T}_{\text{ref},i}}{\sigma_{\text{ref},i}}, \quad (6)$$

where $\bar{P}_{\text{series},i}$ and $\bar{T}_{\text{series},i}$ are the (11 year) average precipitation and temperature for month i produced by the GCM in our control period (1995–2005), $\bar{P}_{\text{ref},i}$ and $\bar{T}_{\text{ref},i}$ the (11 year) average observed precipitation and temperature for month i in the period 1995–2005, and $\sigma_{\text{ref},i}$ the standard deviation of the monthly average temperature during the same period for month i . These factors were then used to correct the future climate projections for each time series (using the same factor for all daily data in a given month).

The impact of climate change on hydrological processes are often assessed by studying changes in the flow regime, and, in particular, changes in the monthly, seasonal, and annual river discharges (Lauri et al., 2012, 2014). More recently, some studies have focussed on hydrological extremes, such as high (Q_5) and low flows (Q_{95}) (Hoang et al., 2016). Since our goal is to demonstrate that different model parameterizations caused by the absence (presence) of water reservoirs can largely impact the results of climate change assessments—and not to push forward the boundaries of climate change impact assessments—we chose a simple and established criterion, namely the annual and monthly river discharges at Chiang Saen and Jiuzhou stations.

4 Results

To discuss about the impact of water reservoirs on the parameterization of hydrological models, we first compare the results of the calibration exercise carried out with and without reservoirs, and then proceed by comparing the performance of two selected parameterizations on the climate change impact assessment.

4.1 Model parameterization

The optimization-based parameterization exercise yielded a total of 118 and 109 parameterizations (or Pareto-efficient solutions) for the VIC implementations with and without reservoirs, respectively. To prove our hypothesis that the calibration

process may somehow compensate for a deficiency in the model structure—the absence of reservoirs, in our case—we begin by analyzing the values of the goodness of fit statistics, namely NSE and TRMSE. Figure 5 reports the probability plots of NSE and TRMSE values obtained for the two model setups: results show that the calibration exercise yields a reasonable modelling accuracy, with NSE and TRMSE varying in the ranges 0.68–0.79 and 8.10–16.69. More interestingly, these results show that the NSE and TRMSE values of both model setups belong to the same range of variability and follow an almost identical distribution. In addition, all NSE and TRMSE values of the models without reservoirs fall within the 95% confidence limits calculated using the NSE and TRMSE values attained by the models with reservoirs. To corroborate this finding, we carried out a Kolmogorov-Smirnov two sample test to reject the null hypothesis that the values of NSE (and TRMSE) produced by the two model setups come from the same distribution. For both goodness of fit statistics, the hypothesis cannot be rejected (with a 5% significance level). Overall, this confirms that the accuracy of the models is not affected by the presence (absence) of the reservoirs.

How does the parameterization compensate for the absence of water reservoirs? To answer this question, we visualize both goodness of fit statistics (NSE and TRMSE) and model parameters (D_s , D_{max} , W_s , b , d_1 and d_2) in a parallel-coordinate plot (Figure 6). These eight variables are shown in eight parallel axes, so each line connecting the axes represents a parameterization (i.e., a solution of the optimization problem) along with the corresponding value of the goodness of fit statistics (i.e., the objectives). Blue and red lines denote solutions obtained with and without reservoirs, respectively. First of all, one can notice that while NSE and TRMSE spread over the same ranges (results discussed in the previous paragraph), the presence/absence of reservoirs consistently yields different parameterizations. Let's analyze them. The value of b —characterizing the shape of the Variable Infiltration Capacity curve—belongs to two distinct ranges (0.319–0.495 and 0.002–0.195) for the model implementation with and without reservoirs, respectively, indicating that the model without reservoirs has higher infiltration and lower surface runoff than the model with reservoir (recall that a higher value of b leads to a lower infiltration rate and higher surface runoff; Section 3.1.1). A similar observation applies to the parameters D_s , D_{max} , and W_s , which determine the shape of the Baseflow curve. In this case, the model without reservoirs has higher values of D_{max} (i.e., maximum baseflow) and lower values of D_s and W_s (i.e., fraction of D_{max} where rapidly increasing baseflow begins, and fraction of the maximum soil moisture in the lower layer where rapidly increasing baseflow occurs), suggesting that the absence of reservoirs leads to model parameterizations that favour the generation of baseflow in the lower layer. Finally, we can note that d_1 (the thickness of the first layer) in the models without reservoirs tends to be larger, indicating that these model instances increase the water storage capacity of the top layer. The only parameter that does not appear to depend on the absence (or presence) of water reservoirs is d_2 , the thickness of the second soil layer. This result is corroborated by a global sensitivity analysis, which shows that d_2 is indeed the parameter with the least influence on the model output (Figure S2). Overall, it appears that the calibration process compensates for the absence of water reservoirs by determining values of the soil parameters that can somehow 'mimic' the alterations caused by water reservoirs, namely an increase in the evaporation and delay in the peak flows—obtained by increasing infiltration, baseflow, and soil water storage capacity.

To further understand the unintended consequences of the absence of water reservoirs, we select two model parameterizations (with and without reservoirs) characterized by the same performance over the period 1996–2005. The values of NSE, TRMSE,

and model parameters are illustrated in Figure 7a, while the simulated daily discharges produced by both models are compared in the scatter plot of Figure 7b. In Figure 8, we contrast the average values of simulated baseflow and runoff during the dry (December–April) and wet (May–November) seasons of the period 1996–2005. Unsurprisingly, results show that during the dry season the model without reservoirs generates more baseflow and runoff than the model with reservoirs (left four panels of Figure 8): during the dry months, hydropower reservoirs release part of the water stored during the monsoon (recall the rule curves described in Section 3.1.2); a process simulated by the model without reservoirs by increasing both baseflow and runoff—and, therefore, the discharge at the catchment outlet. During the wet season, we find an opposite trend: in these months, hydropower reservoirs tend to store part of the water (thus reducing the discharge at the catchment outlet), so the model without reservoirs slightly decreases the discharge by reducing baseflow and runoff (right four panels of Figure 8). We also note that the difference between the two models is clearer during the dry season, when a larger amount of the water volumes is controlled by the hydropower reservoirs. The effect of such flawed representation of baseflow and runoff is further demonstrated by validating the simulated discharge at Jiuzhou station. Figure 9 shows a macroscopic difference between the models calibrated with and without reservoir. In particular we note that the model calibrated without reservoirs largely overestimates the dry season flow and slightly underestimates the wet season one; a result confirmed by the values of NSE (equal to 0.82 and 0.79 for the model with and without reservoirs) and TRMSE (equal to 21.48 and 28.95). One may also suspect that these unintended consequences could further propagate in downstream applications of the models, such as a climate change impact assessment.

4.2 Climate change impact assessment

To begin the climate change impact assessment, we compare the data produced by the GCMs over the reference and future period (1996–2005 and 2050–2060). In general, the total annual precipitation in the Lancang basin is projected to increase under almost all climate change scenarios—only the CSIRO MK3-RCP 8.5 scenario projects a -3.12% decrease in the total annual precipitation. Yet, we observe a large spatial variability in the total annual rainfall within each scenario (see Figure S3). For example, in ACCESS-RCP 4.5, rainfall changes vary between -2% in the central part of the basin to more than +10% in the southern part. All scenarios (but for CSIRO MK3-RCP 8.5) tend to share a similar spatial pattern, in which the lower part of the basin exhibits an increase in the projected precipitation. As for the temperature, we observe an increase in both minimum and maximum temperature across all scenarios (see Figure S4), with higher warming for the RCP 8.5. Also in this case, we can note some variability across the GCMs as well as the spatial domain. As discussed in Hoang et al. (2016), these precipitation and temperature scenarios represent an improvement with respect to the CMIP3 ones, which shown a broader variability. However, there still are some non-negligible differences across the scenarios that are likely to cause different projections of the annual and monthly river discharges.

The expected climate change impacts on the annual river discharge at Chiang Saen are synthesized in Table 4, where we report the relative changes in discharge with respect to the period 1996–2005. Interestingly, it appears that the projections are robust with respect to the representation of the water reservoirs. Indeed, the model with and without reservoirs yield comparable ensemble means and ranges for the two RCPs. Specifically, we find that the annual discharge is predicted to increase in the vast majority of the scenarios, in response to the increase in precipitation described above. Such similarity between the projections

is arguably attributable to the calibration process, which generates models producing similar aggregate performance measures at Chiang Saen station.

What is perhaps more interesting is a comparison between the monthly discharges at Chiang Saen predicted by the models with and without reservoirs. While both models produce similar ensemble ranges (see Figure 10a-d), a closer analysis of the data reveals a non-negligible difference in the minimum, maximum, and average monthly discharges (across the GCM scenarios) produced by the two models (Figure 10e-f). In particular, the model with reservoirs predicts higher discharges in the July–September period and lower discharges in October and November. Note that such difference is consistent across both RCPs. Since both models share the same rainfall and temperature scenarios, the only cause for this stark difference can stand in the unintended consequences of the parameterization process. As explained in Section 4.1, the model without reservoirs shows two ‘artefacts’ that help compensate for the absence of the hydropower reservoirs: first, it increases both baseflow and runoff during the dry season (to account for the water discharged to sustain hydropower production in the dry months); second, it decreases baseflow and runoff (to account for part of the water stored by the dams during the wet months). The latter artefacts is responsible for the macroscopic change in the hydrograph described above. In the wetter conditions depicted by the GCM-RCP scenarios, the hydropower reservoirs of the Lancang basin receive larger inflows, part of which is directly spilled into the downstream reaches (data not shown). This is an unprecedented situation for the model without reservoirs, which cannot simulate an increase in the use of the spillways. In fact, this model tends to reproduce the dynamics learned during the calibration process, that is, storing part of the water (in the lower soil layer) during the monsoon season and slowly discharging it in the following months.

Naturally, the difference between the monthly discharges predicted by the two models becomes even more apparent when we consider Jiuzhou station, which was not used in the calibration process. As depicted in Figure 11, the model without reservoirs consistently yields higher discharges in the pre-monsoon season and lower discharges in the monsoon season. Note that, in some months, the difference between the average monthly discharges produced by the two models causes an uncertainty larger than the one surrounding the downscaled climate projections. For instance, the average monthly discharge in March (under both RCPs) predicted by two models is about 500 and 750 m³/s, that is, a 50% difference.

5 Discussion and Conclusions

This work contributes to the existing literature on large-scale hydrological modelling by studying the effect of water reservoir storage and operations on the parameterization of process-based models. To this purpose, we developed a computational framework consisting of VIC and the Multi-Objective Evolutionary Algorithm ε -NSGAI, which we used to calibrate the model parameters through a simulation-optimization process. Our framework also includes a novel variant of VIC that simulates both storage dynamics and operations of water reservoirs. Using the Lancang river basin as a case study, we calibrated two implementations of VIC, with and without reservoirs. Inline with previous studies (e.g., de Paiva et al. (2013); Abbaspour et al. (2015)), we found that the model without reservoirs attains a reasonable modelling accuracy. In fact, we found that the calibration process of both model implementations yields de facto the same values of the goodness of fit statistics (NSE and

TRMSE), suggesting that the model parameterization helps compensate for a structural error, namely the absence of the water reservoirs. More specifically, this effect is achieved by determining the values of six soil parameters (D_s , D_{max} , W_s , b , d_1 and d_2) that let this model implementation emulate the presence of water reservoirs.

5 The first implication of a flawed parameter estimation stands in a poor representation of key hydrological processes, such as surface runoff, infiltration, and baseflow. In our case, we found that, during the dry months, the models calibrated without water reservoirs generate a higher amount of baseflow and runoff than the models with reservoirs. This is an artefact needed to reproduce the higher discharges of hydropower dams that sustain the production of hydro-electricity in the dry season. Vice versa, baseflow and runoff are reduced during the wet months, so as to account for the decrease in peak flows caused by the fact that dams store part of the water for the following dry season. A poor parameter estimation is also likely to affect several downstream applications of a hydrological model. In our second experiment we exemplify this concept through a climate change impact assessment, in which we contrasted the annual and monthly discharges projected by two selected models (with and without reservoirs). Both models show a similar trend in the flow regime—i.e., increased monthly discharges during the monsoon season, caused by the projected increase in precipitation—a results found in previous studies (Lauri et al., 2012; Hoang et al., 2016, 2019). Yet, one cannot neglect the different nuances of the flow regime alterations predicted by the two models. In particular, the model with reservoirs presents higher discharges at the peak of the monsoon season than the model without reservoirs. These nuances may impact some of the conclusions of a climate change impact assessment as well as other model-based studies depending on a reliable estimation of the flow regime.

Like any hydrological modelling study, also this work builds on a few modelling assumptions that should be properly discussed. First, our model calibration focuses solely on six main parameters controlling the rainfall-runoff process, and assumes that they are homogeneously distributed across the basin. As explained in Section 3.1.1, the choice of these parameters is rather established in the literature (Dan et al., 2012; Park and Markus, 2014; Xue et al., 2015); yet, it is reasonable to expect that the use of more parameters could further improve the model accuracy. As for the use of homogeneously-distributed parameters, our modelling choice is justified by the fact that the use of heterogeneously-distributed parameters would largely impact the computational requirements of the calibration process. We also note that there are no reasons to believe that the use of more (or spatially-distributed) parameters would deeply alter the main findings of this work. Second, the large spatial domain—and associated soil water retention capacity—might be a factor controlling the capability of the calibration process to compensate for the absence of water reservoirs. In other words, such capability might be dependant on the relation between soil water retention capacity and total storage volume of the reservoirs. In a small basin regulated by a large dam, a modified representation of runoff, infiltration, and baseflow may not be sufficient to compensate fully for a poor representation of reservoir storage and operations. Third, we focussed our attention on water reservoirs, which are indeed the infrastructures affecting the flow regime in the Lancang. In the lower Mekong basin (not considered in our spatial domain), the flow regime has been modified not only by hydropower reservoirs, but also by withdrawals for irrigation supply (Hoang et al., 2019). Looking forward, It would thus be interesting to extend the spatial domain of our model and study how these withdrawals could affect its parameterization.

35 As the pervasiveness of water resources management in earth system models expands, so too does the need for a deeper understanding of the mechanisms regulating the calibration process. The explicit representation of water reservoirs—and other

infrastructure—is indeed likely to result in more realistic soil parameters; an hypothesis whose verification depends on the availability of observations about soil physical properties for large spatial domains. In turn, this highlights the importance of studies aimed to infer such properties from remotely sensed images (Chang and Islam, 2000; Chabrilat et al., 2019). A related
5 topic that may also deserve future research is the robustness of these models with respect to changes in the operations or physical characteristics of dams. Variability in water and energy demand is a key driver for multiple management and planning interventions (e.g., modifications of the operating rules, construction on new storage), so it is paramount to know the extent to which models can still capture key hydrological processes once these modifications are in place.

Overall, the findings of this study reinforce the message that water infrastructures—and their operational settings—play a
10 key role on the reliability of a hydrological modelling exercise, like the quality of the hydro-meteorological data, the model structure, or the calibration process (Francés et al., 2007; Madsen, 2000). These findings gain further prominence if one considers the expected increase in hydropower development in several regions of the world (Zarfl et al., 2015).

Author contributions. TDD and SG conceptualized the paper and its scope. Data collection, model implementation, and experiments were carried out by TDD, with inputs from AFMKC and SG. All authors contributed to the manuscript preparation.

15 *Code and data availability.* Precipitation and air temperature data were retrieved from APHRODITE and CFSR datasets, available at <http://www.chikyu.ac.jp/precip/english/> and <https://climatedataguide.ucar.edu/climate-data/climate-forecast-system-reanalysis-cfsr>. Land use and land cover data were obtained from the GLCC dataset (<https://www.usgs.gov/centers/eros/science/>), while the soil data were extracted from the HWSO database (<http://www.fao.org/soils-portal/soil-survey/soil-maps-and-databases/harmonized-world-soil-database-v12/en/>). The Terra MODIS satellite images (used to calculate the monthly Leaf Area Index and albedo) are available at <https://modis.gsfc.nasa.gov>. The
20 Landsat TM and ETM+ imagery are available at <https://earth.esa.int/web/sppa/mission-performance/esa-3rd-party-missions/landsat-1-7/tm-etm/sensor-description>. The global Digital Elevation Model (GTOPO30) is available at <http://www.temis.nl/data/gtopo30.html>. The GCMs projections were retrieved from <https://esgf-node.llnl.gov/projects/esgf-llnl/>. All these data are publicly available. The daily discharge data at Chiang Saen and the design specifications of all dams were obtained by the authors from the Mekong River Commission and the International Commission On Large Dams, so they cannot be shared without their consent. Additional data about the dams were retrieved
25 from the Global Reservoir and Dam Database, available at <http://globaldamwatch.org/grand/>. The variant of VIC used in this study—named VIC-Res—is available at <https://github.com/thanhiwer/VICRes>.

Competing interests. The authors declare that they do not have individual or collective conflicts of interests.

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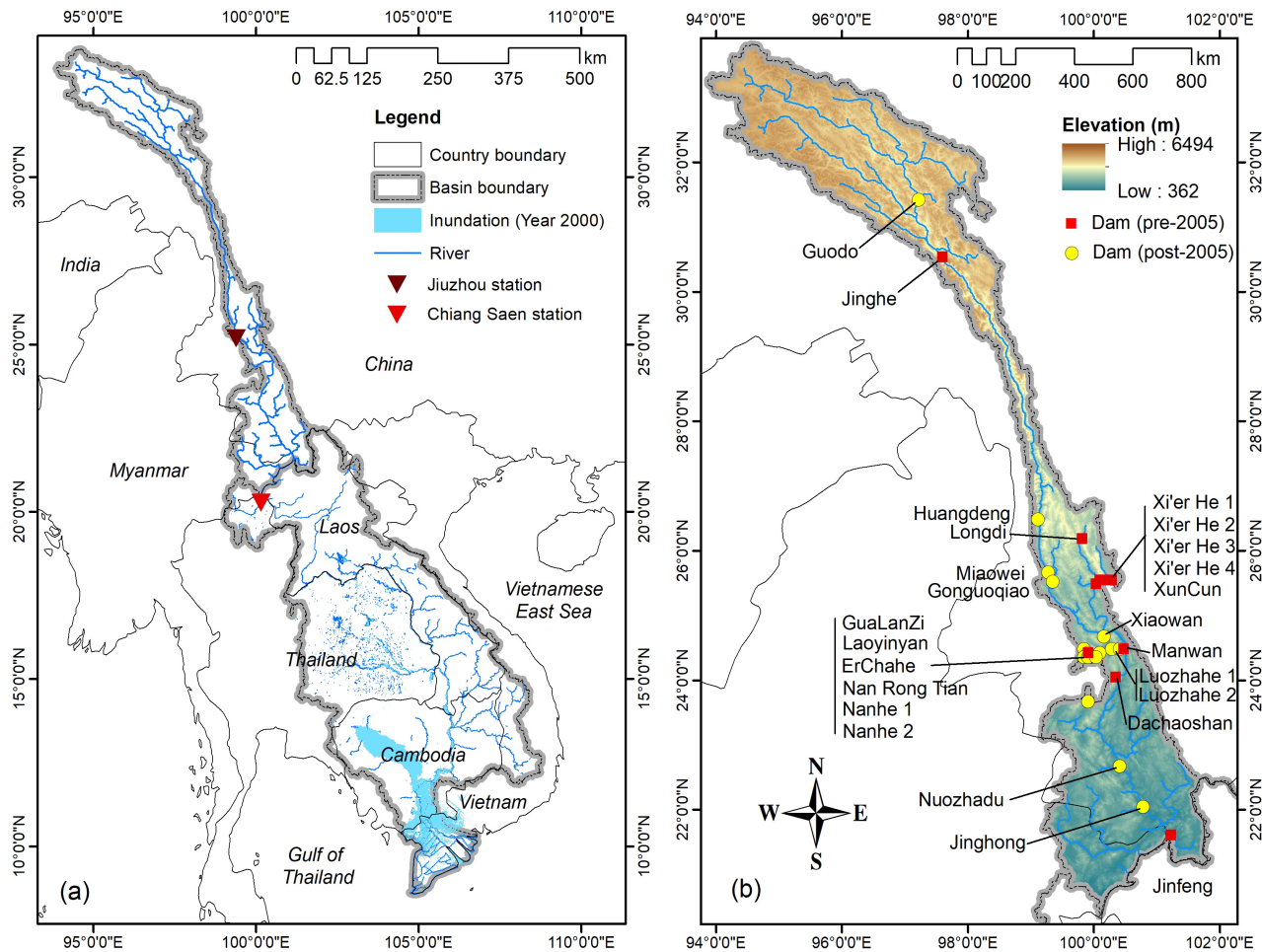


Figure 1. Mekong river basin (a); and elevation map and location of the hydropower dams in the upper Mekong basin (b). The red squares denote dams built before 2005 (and therefore included in our study), while the yellow circles indicate dams built after 2005.

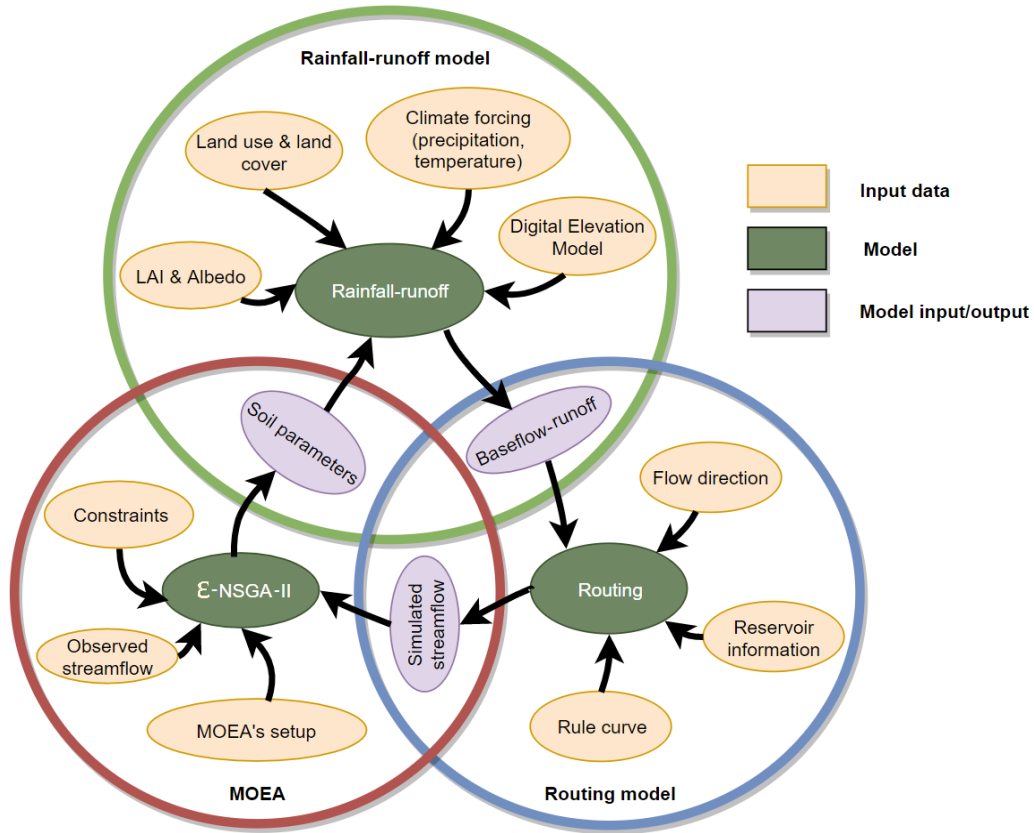


Figure 2. Computational framework adopted in the first part of this study. The framework consists of VIC's rainfall-runoff and routing modules and the MOEA ϵ -NSGAII. The output of the rainfall-runoff module (i.e., gridded baseflow and runoff) is used by the routing module, which simulates the streamflow at multiple locations within the upper Mekong basin. The simulated streamflow is then used to calculate goodness of fit statistics, whose value is optimized with ϵ -NSGAII by calibrating the parameters of the rainfall-runoff module. In other words, these parameters and goodness of fit statistics represent the decision variables and objective functions used by ϵ -NSGAII.

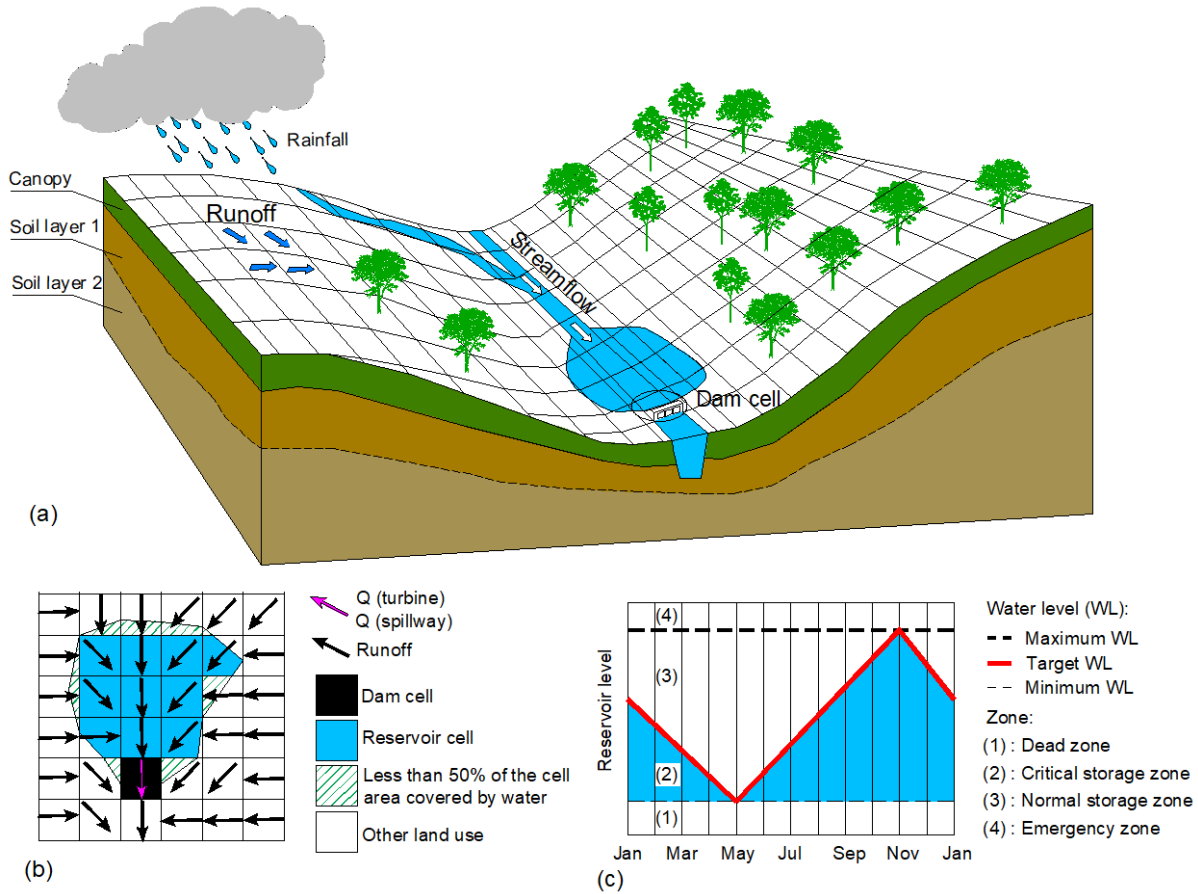


Figure 3. Graphical representation of VIC's spatial domain (adapted from <http://www.hydro.washington.edu>) (a), including the selection of dam cell (black), reservoir cells (blue), and cells with other land use (white and white with green lines). The black and pink arrows indicate the direction of the flow routing and discharge from the reservoir (b). Seasonal rule curve (c).

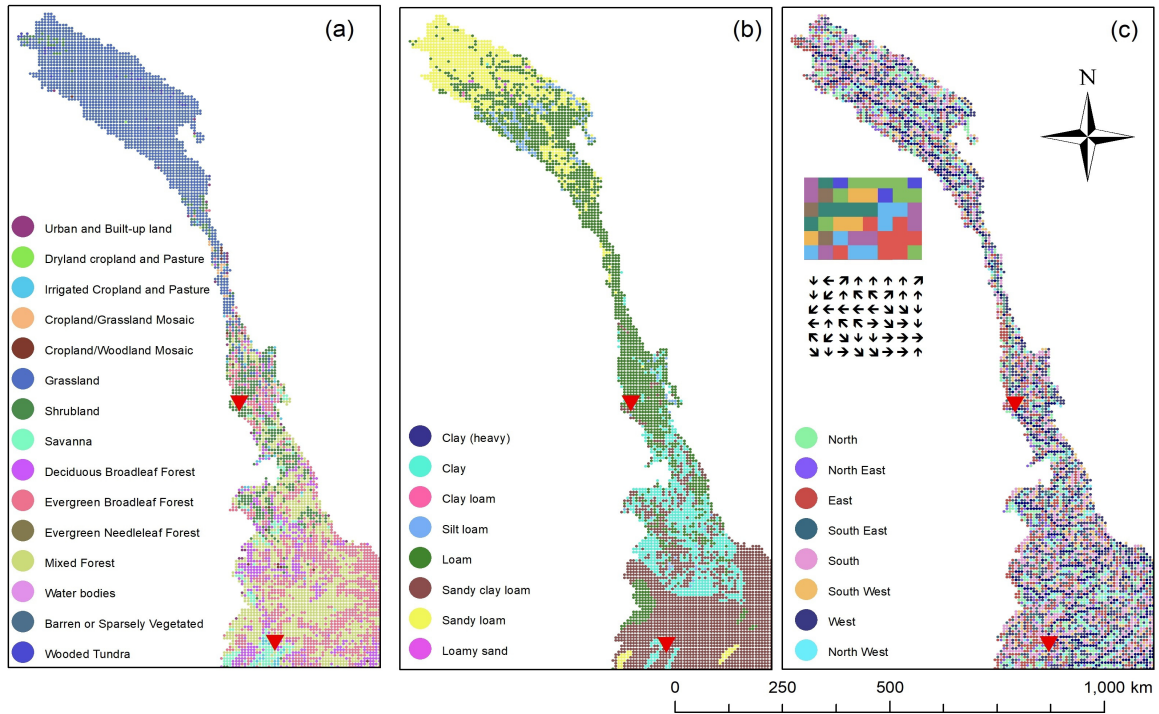


Figure 4. Land use map derived from the Global Land Cover Characterization dataset (a); soil map (for the top layer) retrieved from the Harmonized World Soil Database (b); flow direction map (c). The red triangles denote the position of the Chiang Saen and Jiuzhou gauging stations.

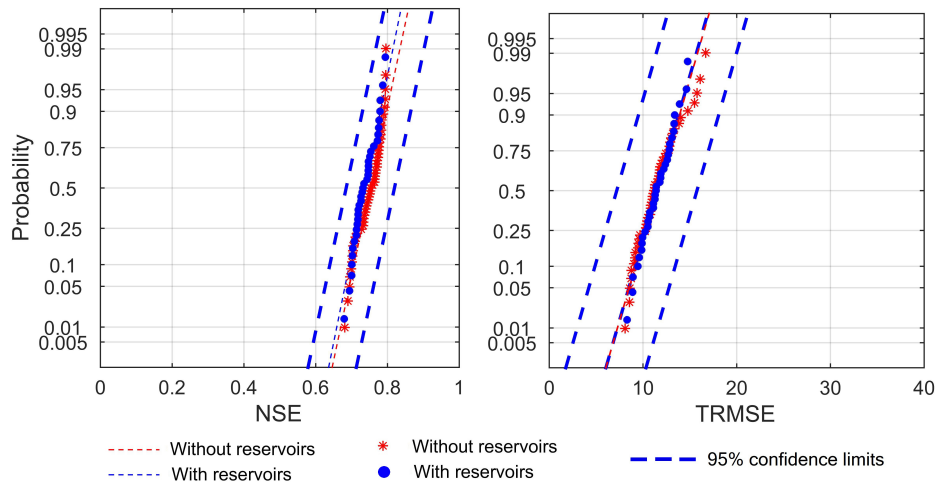


Figure 5. Probability plots for the NSE (left) and TRMSE (right) obtained in the model calibration process. The blue circles and red stars specify the results obtained by the models with and without reservoirs, respectively. The dashed blue and red lines represent the theoretical distributions. In both plots, we also report the 95% confidence limits for the models calibrated with reservoirs.

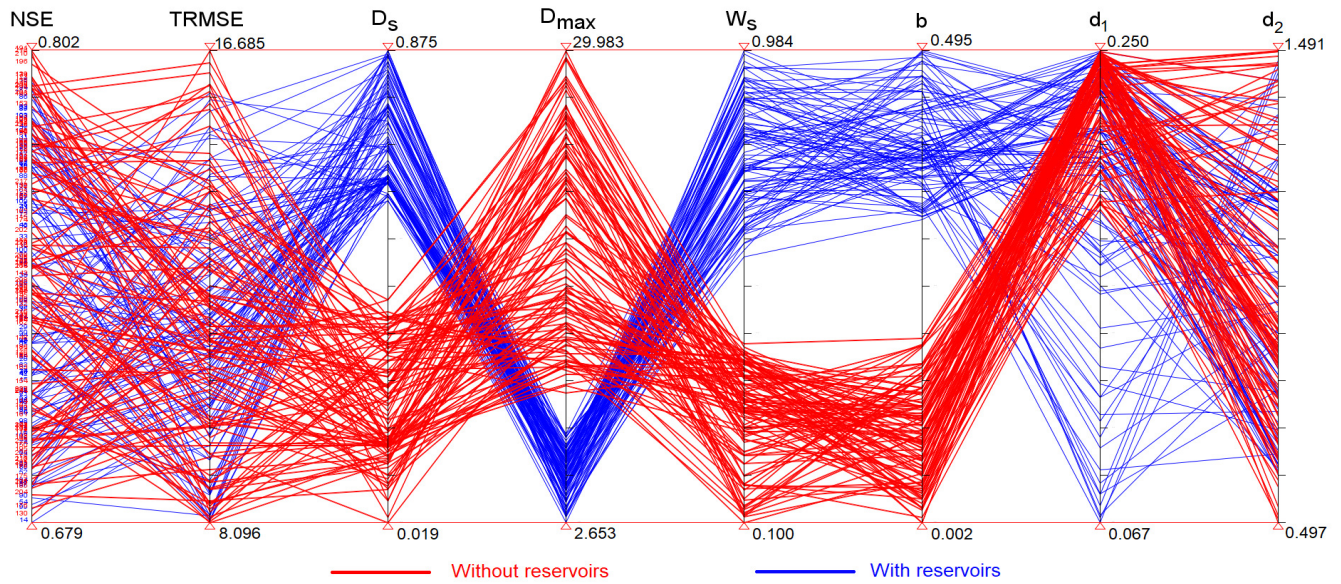


Figure 6. Parallel coordinate plot illustrating the values of the goodness of fit statistics (NSE and TRMSE) and model parameters (D_s , D_{max} , W_s , b , d_1 and d_2) obtained through the optimization-based parameterization exercise. Each line connecting the axes represents a parameterization, along with the corresponding model performance. Blue and red lines denote parameterizations obtained with and without reservoirs.

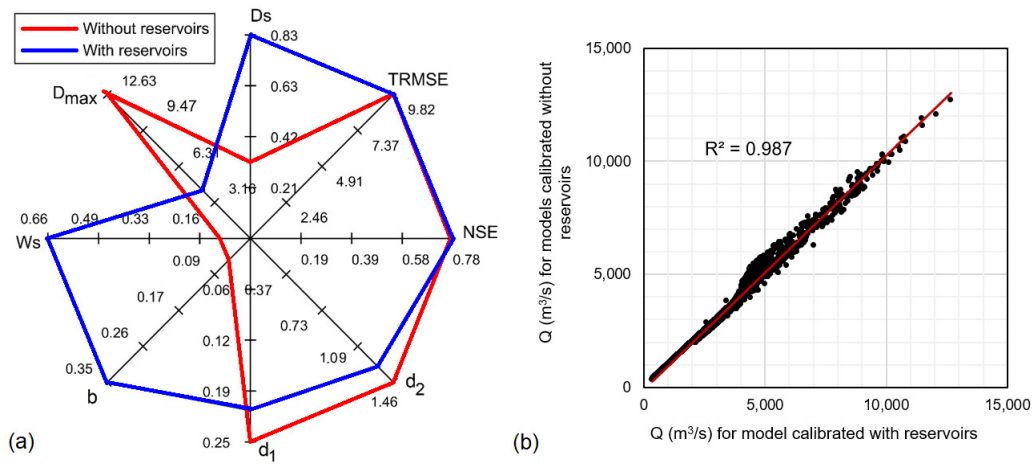


Figure 7. Radar chart illustrating the values of Nash-Sutcliffe Efficiency (NSE), Transformed Root Mean Square Error (TRMSE), and model parameters (D_s , D_{max} , W_s , b , d_1 and d_2) of the two selected models (a); scatter plot comparing the daily discharges at Chiang Sean station simulated by the two models over the period 1996–2005 (b).

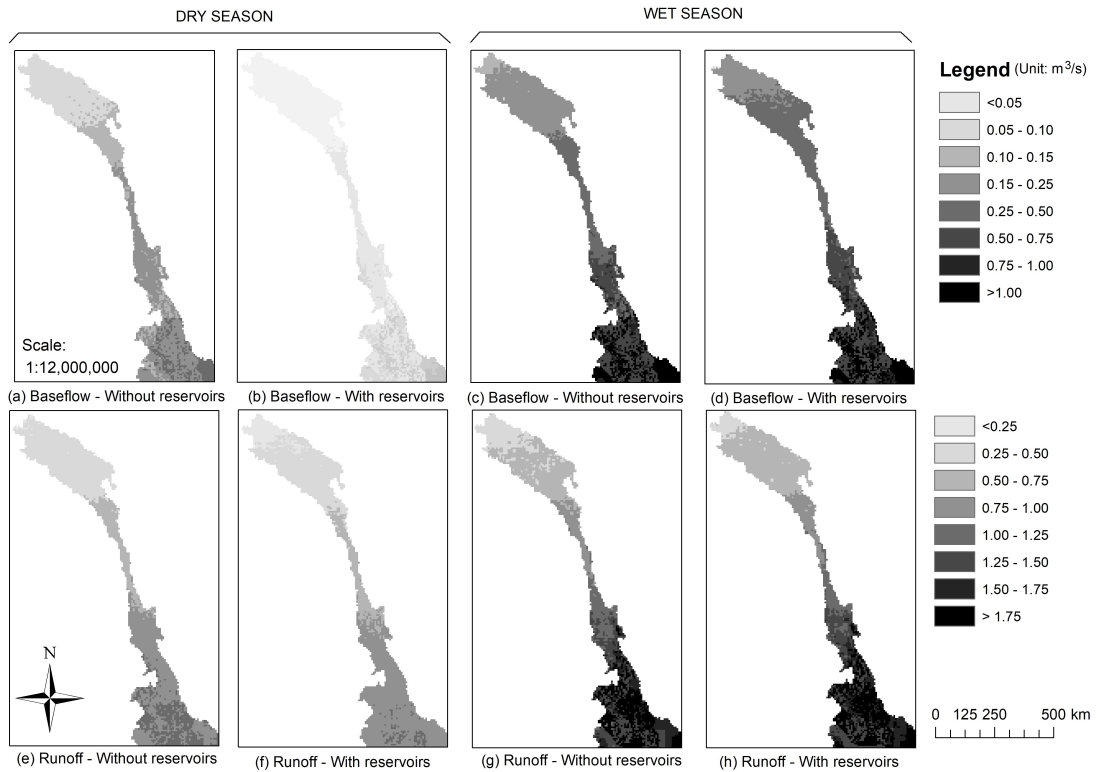


Figure 8. Average values of simulated baseflow (top panels) and runoff (bottom panels) simulated by the selected models (with and without reservoirs) during the dry (December–April) and wet (May–November) seasons of the period 1996–2005.

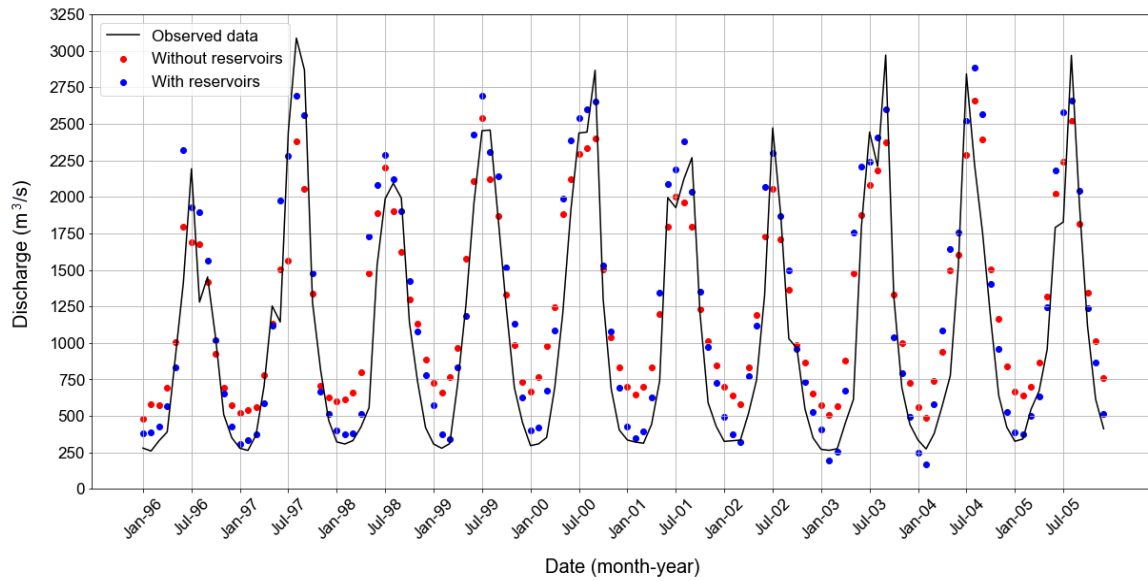


Figure 9. Comparison between observed and simulated monthly discharges at Jiuzhou station over the period 1996–2005. Simulated data are produced by the two selected models with and without reservoirs (blue and red dots, respectively).

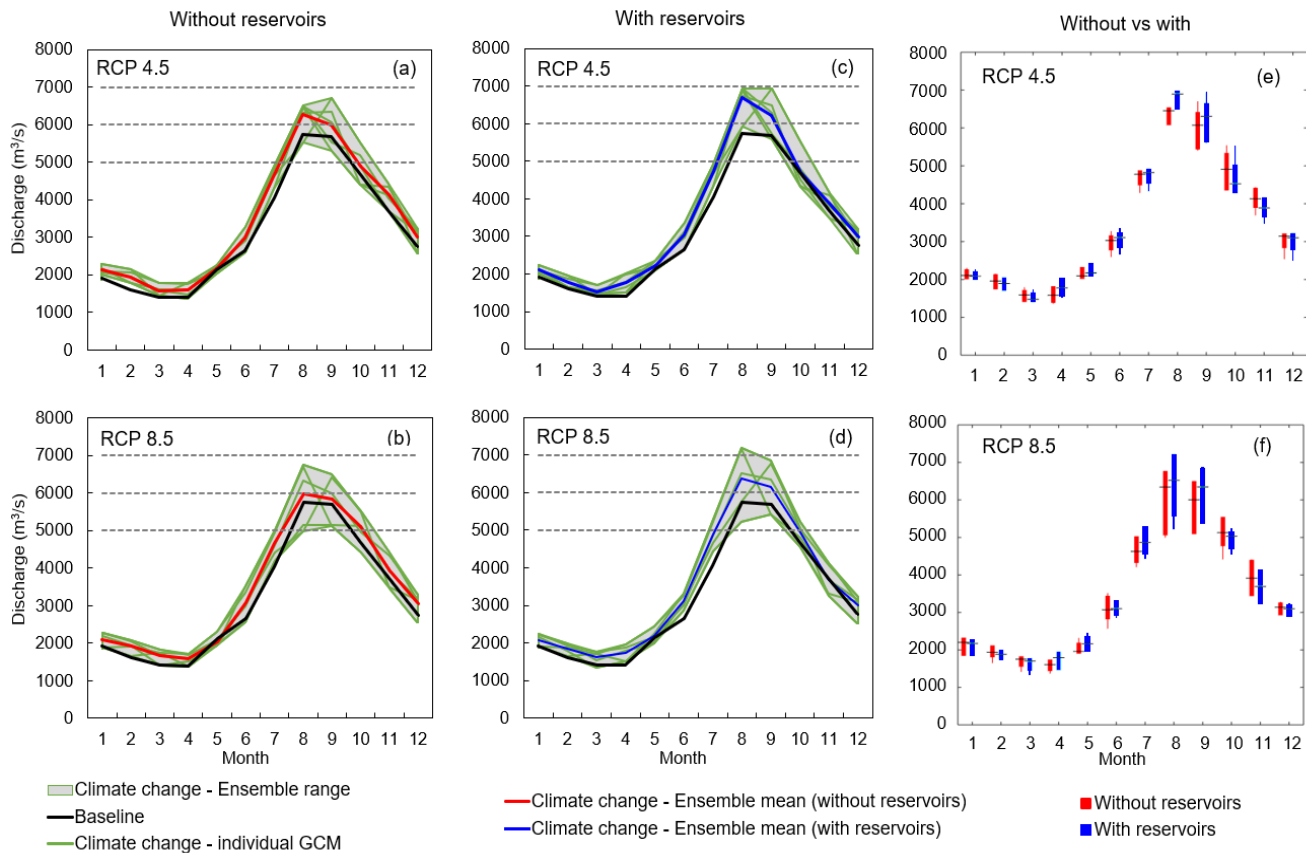


Figure 10. Projected monthly discharges at Chiang Saen under five GCMs and two RCPs for the two selected models calibrated without and with reservoirs (a-d). Box plots highlighting the variability in monthly discharges predicted by the two models under RCP 4.5 (e) and RCP 8.5 (f).

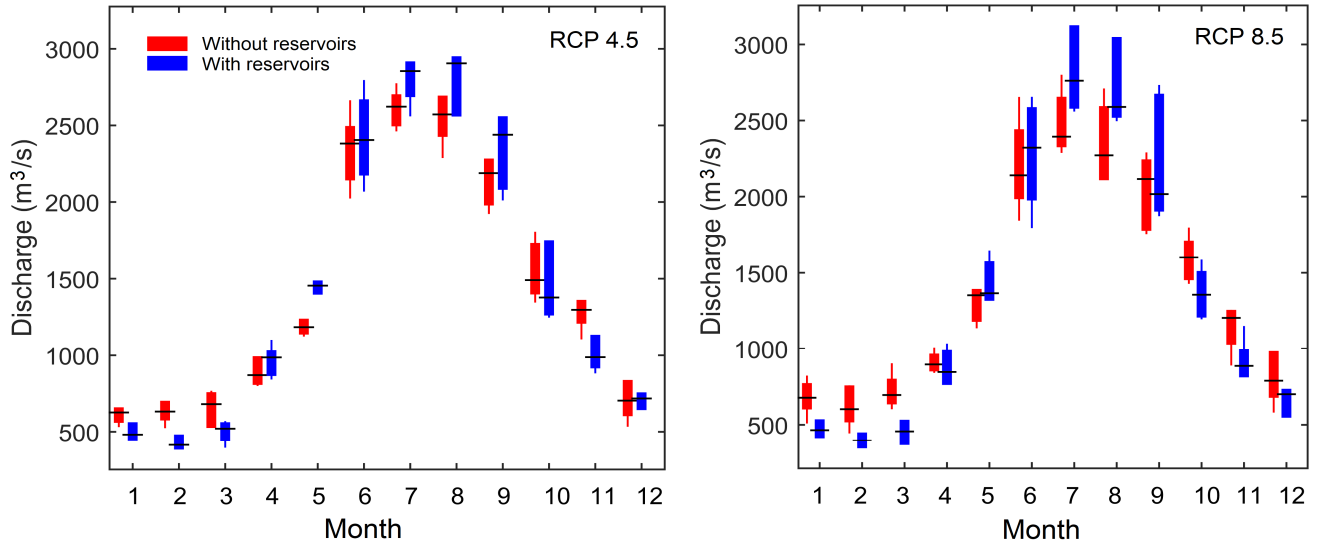


Figure 11. Variability in monthly discharges at Jiuzhou station predicted by the two selected models (with and without reservoirs) under RCP 4.5 (left) and RCP 8.5 (right).

Table 1. Main parameters controlling the rainfall-runoff process in VIC. The third column contains the range of each parameter value considered during the calibration process. Note that these are the same ranges typically adopted for the implementation of VIC to large basins (cfr., Dan et al. (2012); Xue et al. (2015); Wi et al. (2017)).

Name	Unit	Feasible range	Description
d_1	m	[0.05, 0.25]	Thickness of the upper soil layer
d_2	m	[0.3, 1.5]	Thickness of the lower soil layer
b	-	(0, 0.9]	Variable Infiltration Capacity curve parameter
D_{\max}	mm/day	(0, 30]	Maximum baseflow
D_s	-	(0, 1)	Fraction of D_{\max} where non-linear baseflow begins
W_s	-	(0, 1)	Fraction of maximum soil moisture where non-linear baseflow occurs

Table 2. Design specifications of the dams implemented in our VIC model (simulation period 1995–2005). The term Year denotes the time at which each reservoir became operational.

No.	Name	Year	Long. (°E)	Lat. (°N)	Height (m)	Storage (Mm ³)	Design discharge (m ³ /s)	Inst. cap. (MW)
1	Xi'er He 4	1971	100.066	20.000	20	14	283	50
2	Xi'er He 1	1989	100.202	30.000	30	1,501	60	105
3	Xi'er He 2	1987	100.131	25.562	37.25	0.2	168	50
4	Xi'er He 3	1988	100.108	20.700	20.70	0.09	304	50
5	Manwan	1992	100.446	24.625	136	257	1,700	1,670
6	Longdi	1997	99.724	26.221	95	13.30	12.34	10
7	Laoyinyan	1997	99.818	24.469	4.31	10.92	9.3	16
8	XunCun	1999	99.993	25.422	67	73.74	146	78
9	Jinfeng	1998	101.225	21.592	45	19.48	45	16
10	Dachaoshan	2003	100.370	24.025	115	367	2,109	1,350
11	Jinhe	2004	97.333	34.000	34	4.27	222	60

Table 3. CMIP5 GCMs used for the climate change impact assessment.

GCM	Spatial resolution (long × lat)	Control baseline	Developer
ACCESS1-0	1.875° × 1.25°	1850–2006	Commonwealth Scientific and Industrial Research Organization, Australia
CCSM4	1.25° × 0.94°	1850–2005	National Center for Atmospheric Research, USA
CSIRO Mk3.6	1.875° × 1.875°	1850–2005	Commonwealth Scientific and Industrial Research Organization and the Queensland Climate Change Centre of Excellence, Australia
HadGEM2 ES	1.875° × 1.24°	1861–2010	Met Office, UK
MPI-ESM-LR	1.875° × 1.875°	1850–2005	Max Planck Institute for Meteorology, Germany

Table 4. Relative changes in annual river discharges at the Chiang Saen station for the future period (2050–2060) relative to the reference one (1996–2005). The lowest and highest changes are presented with the corresponding scenarios. The results reported in the first and second rows were produced by the selected models without and with reservoirs.

Scenario	RCP 4.5		RCP 8.5	
	Ensemble mean (%)	Range (%)	Ensemble mean (%)	Range (%)
Without reservoirs	+13.62	+6.36 to +23.66	+13.92	-0.67 to +28.89
		CSIRO– ACCESS		CSIRO– ACCESS
With reservoirs	+13.56	+6.28 to +23.56	+13.83	-0.63 to +28.68
		CSIRO– ACCESS		CSIRO– ACCESS