

1 **Model Representation of the Coupling between**  
2 **Evapotranspiration and Soil Water Content at Different Depths**

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10 **Abstract.** Soil water content ( $\theta$ ) influences the climate system by controlling [the](#) fraction of incoming solar and  
11 longwave energy that is converted into evapotranspiration (ET). Therefore, investigating the coupling strength  
12 between  $\theta$  and ET is important for the study of land surface/atmosphere interactions. Physical models are commonly  
13 tasked with representing the coupling between  $\theta$  and ET; however, few studies have evaluated the accuracy of model-  
14 based estimates of  $\theta$ /ET coupling (especially at multiple soil depths). To address this issue, we use in-situ AmeriFlux  
15 observations to evaluate  $\theta$ /ET coupling strength estimates acquired from multiple land surface models (LSMs) and an  
16 ET retrieval algorithm – the Global Land Evaporation Amsterdam Model (GLEAM). For maximum robustness,  
17 coupling strength is represented using the sampled normalized mutual information (NMI) between  $\theta$  estimates  
18 acquired at various vertical depths and surface evaporation flux expressed as a fraction of potential evapotranspiration  
19 (fPET, the ratio of ET to potential ET). Results indicate that LSMs and GLEAM are generally in agreement with  
20 AmeriFlux measurements in that surface soil water content ( $\theta_s$ ) contains slightly more NMI with fPET than vertically  
21 integrated soil water content ( $\theta_v$ ). Overall, LSMs and GLEAM adequately capture variations in NMI between fPET  
22 and  $\theta$  estimates acquired at various vertical depths. However, GLEAM significantly overestimates the NMI between  
23  $\theta$  and ET and the relative contribution of  $\theta_s$  to total ET. This bias appears attributable to differences in GLEAM’s ET  
24 estimation scheme relative to the other two LSMs considered here (i.e., the Noah model with multi-parameterization  
25 options and the Catchment Land Surface Model). These results provide insight into improved LSM model structure  
26 and parameter optimization for land surface-atmosphere coupling analyses.

27 **Keywords.** Land surface/atmosphere interaction, soil water content, evapotranspiration

## 28 **1 Introduction**

29 Soil water content ( $\theta$ ) modulates water and energy feedbacks between the land surface and the lower atmosphere by  
30 determining the fraction of incoming solar energy that is converted [into](#) evapotranspiration (ET) (Seneviratne et al.,  
31 2010, 2013). In water-limited regimes,  $\theta$  exhibits a dominant control on ET, and therefore exerts significant terrestrial  
32 control on the earth’s water and energy cycles. Accurately representing  $\theta$ /ET coupling in land surface models (LSMs)  
33 is therefore expected to improve our ability to project the future frequency of extreme climates (Seneviratne et al.,  
34 2013).

35 A key question is how the constraint of  $\theta$  on ET and [sensible heat \(H\)<sub>s</sub>](#) varies as  $\theta$  is vertically integrated over deeper  
36 vertical soil depths. Given the tendency for the time scales of  $\theta$  dynamics to vary strongly with depth, the degree to  
37 which the ET is coupled with vertical variations in  $\theta$  determines the temporal scale at which  $\theta$  variations are propagated  
38 into the lower atmosphere. Therefore, in order to represent  $\theta$ /ET coupling, and thus land/atmosphere interactions in  
39 general, LSMs must accurately capture the relationship between vertically varying  $\theta$  values and ET. Unfortunately,  
40 their ability to do so remains an open question.

41 Recently, land surface/atmosphere coupling strength has been investigated by sampling mutual information proxies  
42 (e.g., correlation coefficient or other coupling indices) between time series of  $\theta$  and ET observations (or air temperature

43 proxies for ET). Results suggest that, even when confined to very limited vertical support (e.g., within the top 5 cm  
44 of the soil column), surface  $\theta$  estimates retain significant information for describing overall  $\theta$  control on local climate  
45 (Ford and Quiring, 2014b; Qiu et al., 2014; Dong and Crow, 2018; Dong and Crow, 2019). These findings are in  
46 contrast with the common perception that ET is constrained only by  $\theta$  values within deeper soil layers (Hirschi et al.,  
47 2014). Hence, it is necessary to examine whether LSMs can realistically reflect observed variations of  $\theta$ /ET coupling  
48 strength within the vertical soil profile.

49 Previous studies examining the  $\theta$ /ET relationship have generally been based on Pearson product-moment correlation  
50 (Basara and Crawford, 2002; Ford et al., 2014a), which captures only the strength of a linear relationship between two  
51 variables. However, the coupling between  $\theta$  and ET is generally nonlinear. Therefore, non-parametric mutual  
52 information measures are generally more appropriate. Nearing et al. (2018) used information theory metrics (transfer  
53 entropy, in particular) to measure the strength of direct couplings between different surface variables, including soil  
54 water content, and surface energy fluxes at short timescales in several LSMs. They found that the LSMs are generally  
55 biased as compared with strengths of couplings in observation data, and that these biases differ across different study  
56 sites. However, they did not look specifically at the effect of vertical water content profiles or of subsurface soil water  
57 content on partitioning surface energy fluxes.

58 Here we apply the information theory-based methodology of Qiu et al. (2016) to examine the relationship between  
59 the vertical support of  $\theta$  estimates and their mutual information (MI) with respect to ET. Our approach is based on  
60 analyzing the MI content between ET and  $\theta$  time series - acquired from both LSMs, ET retrieval algorithm - the  
61 Global Land Evaporation Amsterdam Model (GLEAM) and AmeriFlux in-situ observations. MI values are then  
62 normalized by entropy in the corresponding ET time series to remove the effect of inter-site variations to generate  
63 estimates of Normalized Mutual Information (NMI) between  $\theta$  and ET. Both surface (roughly 0–10 cm) soil water  
64 content ( $\theta_s$ ) and vertically integrated (0–40 cm) soil water content ( $\theta_v$ ) are considered to capture the impact of depth  
65 on NMI results. AmeriFlux-based NMI results are then compared with analogous NMI results obtained from LSM-  
66 based and GLEAM-based  $\theta$  and ET time series.

## 67 **2 Data and Methods**

68 The AmeriFlux network provides temporally continuous measurements of  $\theta$ , surface energy fluxes and related  
69 environmental variables for sites located in a variety of North American ecosystem types, e.g., forests, grasslands,  
70 croplands, shrublands and savannas (Boden, et al., 2013). To minimize sampling errors, AmeriFlux sites lacking a  
71 complete 3-year summer months (June, July and August) daily time series between the years of 2003 and 2015 (i.e.,  
72  $3 \times 92 = 276$  daily observations in total) of  $\theta_s$ ,  $\theta_v$  and latent heat flux (LE) are excluded here - resulting in the 34  
73 remaining eligible AmeriFlux sites listed in Table 1. These sites cover a variety of climate zones within the contiguous  
74 United States (CONUS). Table 1 gives background information on these 34 sites including local land cover  
75 information. Hydro-climatic conditions in each site are characterized using the aridity index (AI) - calculated using  
76 CRU (Climate Research Unit, v4.02) monthly precipitation and potential evaporation (PET) datasets.

77 As described above,  $\theta$ /ET coupling assessments made using AmeriFlux observations are compared with those using  
78 state-of-the-art LSMs including the Noah model with multi-parameterization options (NOAHMP) and Catchment  
79 Land Surface Model (CLSM). In addition,  $\theta$  and ET retrievals provided by the Global Land Evaporation Amsterdam  
80 Model (GLEAM) are also considered. See below for details on all three approaches. To avoid any spurious correlations  
81 between  $\theta$  and ET due to seasonality, all NMI analyses are performed on  $\theta$  and ET time series anomalies acquired  
82 during the period 2003–2015. The  $\theta$  and ET anomalies are calculated by removing the seasonal cycle – defined as 31-  
83 day window averages centered on each day-of-year sampled across all years of the 2003–2015 historical data record  
84 – from the raw  $\theta$  and ET time series data. The analysis is limited to the CONUS during summer months (June, July  
85 and August) when  $\theta$ /ET coupling is expected to be maximized.

86

Table 1 Attributes of selected AmeriFlux sites

AmeriFlux sites	Land cover	Elevation [m]	Top- layer depth [cm]	Bottom- layer depth [cm]
ARM SGP Main	Cropland	314	10 <sup>a</sup>	20 <sup>b</sup>
ARM USDA UNL OSU Woodward Switchgrass 1	Grassland	611	10	30
Audubon Research Ranch	Grassland	1469	10	20
Bondville	Cropland	219	10 <sup>c</sup>	20
Brookings	Grassland	510	10	20
Chimney Park	Evergreen needleleaf forest	2750	0-15	15-45
Duke Forest Hardwoods	Deciduous broadleaf forest	168	10	25
Duke Forest Open Field	Grassland	168	10	25
Fermi Agricultural	Cropland	225	2.5	10
Fermi Prairie	Grassland	226	2.5	10
Flagstaff Managed Forest	Evergreen needleleaf forest	2160	2	10
Flagstaff Unmanaged Forest	Woody savannas	2180	2	10
Flagstaff Wildfire	Grassland	2270	2	10
Fort Peck	Grassland	634	5 <sup>d</sup>	20
Freeman Ranch Woodland	Woody savannas	232	10	20
Glacier Lakes Ecosystem Experiments Site	Evergreen needleleaf forest	3190	5	10
Howland Forest Main	Mixed forest	60	NA	NA
Lucky Hills Shrubland	Open shrubland	1372	5	15
Marys River Fir Site	Evergreen needleleaf forest	263	10	20
Metolius Intermediate Pine	Evergreen needleleaf forest	1253	0-30	NA
Missouri Ozark	Deciduous broadleaf forest	219	10	100
Nebraska SandHills Dry Valley	Grassland	1081	10	25
Quebec Boreal Cutover Site	Evergreen needleleaf forest	400	5	20
Quebec Mature Boreal Forest Site	Evergreen needleleaf forest	400	5	10
Santa Rita Creosote	Open shrubland	991	2.5	12.5
Santa Rita Mesquite	Woody savannas	1116	2.5-5	5-10
Sherman Island	Grassland	-5	10	20

Sylvania Wilderness	Mixed forest	540	5	10
Tonzi Ranch	Woody savannas	169	0	20
University of Michigan Biological Station	Deciduous broadleaf forest	234	0-30	NA
Vaira Ranch	Grassland	129	0	10
Walker Branch	Deciduous broadleaf forest	343	5	10
Willow Creek	Deciduous broadleaf forest	515	5	10
Wind River Field Station	Evergreen needleleaf forest	371	30 <sup>e</sup>	50 <sup>f</sup>

87

88 <sup>a</sup> Was 5 cm prior to 4/13/2005

89 <sup>b</sup> Was 25 cm prior to 4/13/2005

90 <sup>c</sup> Was 5 cm prior to 1/1/2006

91 <sup>d</sup> Was 10 cm (2003-2008)

92 <sup>e</sup> Was 0-30 cm prior to 2007

93 <sup>f</sup> Unavailable prior to 2007

## 94 2.1 Ground-based AmeriFlux measurements

95 The Level 2 (L2) AmeriFlux LE and ~~sensible heat~~ ( $H$ ) flux observations are based on high-frequency (typically > 10  
96 Hz) eddy covariance measurements processed into half-hourly averages by individual AmeriFlux investigators. LE  
97 and  $\theta$  observations at a half-hour time step and without gap-filling procedures are collected from the AmeriFlux Site  
98 and Data Exploration System (see <http://ameriflux.ornl.gov/>). The LE and  $\theta$  observations are further aggregated into  
99 daily (0 to 24 UTC) values, and daily LE is converted into daily ET using the latent heat of vaporization. Daily ET  
100 values based on less than 30% half-hourly coverage (i.e., < 15 half-hourly observations per day) are considered not  
101 representative at a daily time scale and therefore excluded.

102 Soil water content measurements are generally available at two discrete depths that vary between the AmeriFlux sites  
103 (Table 1). Here, the top (i.e., closest to the surface) soil water content observation is always used to represent surface  
104 soil water content ( $\theta_s$ ). Since the depth of this top-layer measurement varies between 0 and 15 cm (see Table 1), we  
105 consider the surface-layer measurement  $\theta_s$  to be roughly representative of 0–10 cm (vertically integrated)  $\theta$ .

106 Given variations in the depth of the lower AmeriFlux  $\theta$  observations (see Table 1), we applied a variety of approaches  
107 for estimating vertically integrated soil water content ( $\theta_v$ ). Our first approach, hereinafter referred to as Case I, is  
108 based on the application of an exponential filter (Wagner et al., 1999; Albergel et al., 2008) to extrapolate  $\theta_s$  to a  
109 consistent 40-cm bottom layer depth. Therefore, only  $\theta_s$  is used to derive  $\theta_v$  and the bottom-layer (or second layer)  
110 AmeriFlux  $\theta$  measurement is neglected in this case. The application of the exponential filter requires a single time-  
111 scale parameter  $T$ . Since  $\theta$  measurements from United States Department of Agriculture’s Soil Climate Analysis  
112 Network (SCAN) are taken at fixed soil depth, we utilized this dataset to determine the most appropriate parameter  $T$   
113 at AmeriFlux sites. Following Qiu et al. (2014), first, we estimated the optimal parameter  $T$  ( $T_{opt}$ ) for the extrapolation  
114 of  $\theta$  measurements from 10 cm to 40 cm depth and established a global relationship between  $T_{opt}$  and site-based  
115 NDVI (MOD13Q1 v006, 250m, 16-day) ( $T_{opt} = 2.098 \times \exp(-1.895 \times (\text{NDVI} + 0.6271)) + 2.766$ ). Then, this global

116 relationship (Goodness of Fit  $R^2$ : 0.85) is applied to AmeriFlux sites to extrapolate 0–10 cm  $\theta_s$  times series into 0–40  
 117 cm  $\theta_v$ .

118 Previous research has suggested that such a filtering approach does not significantly squander ET information present  
 119 in actual measurements of  $\theta_v$  (Qiu et al., 2014; Qiu et al., 2016). Nevertheless, since the quality of  $\theta_v$  estimates is  
 120 important in our analysis, we also calculated two additional cases where 0–40 cm  $\theta_v$  is estimated using: 1) the bottom-  
 121 layer soil water content measurement acquired at each AmeriFlux site (hereinafter, Case II) and 2) linear interpolation  
 122 of  $\theta_s$  and the bottom-layer AmeriFlux soil water content measurement (hereinafter, Case III). The sensitivity of key  
 123 results to these various cases is discussed below.

## 124 2.2 LSM-based and GLEAM-based simulations

125 Simulations ~~is are~~ acquired from NOAAHMP (Niu et al., 2011) and CLSM (Koster et al., 2000) LSMs embedded within  
 126 the NASA Land Information System (LIS, Kumar et al., 2006) and the GLEAM ET retrieval algorithm (Miralles et  
 127 al., 2011). Both NOAAHMP and CLSM are set-up to simulate 0.125°  $\theta$  profiles at a 15-minute time step using North  
 128 America Land Data Assimilation System, Phase 2 (NLDAS-2) forcing data. A 10-year model spin-up period (1992 to  
 129 2002) is applied for NOAAHMP and CLSM.

130 NOAAHMP numerically solves the one-dimensional Richards equation within four soil layers of thicknesses of ~~10, 30,~~  
 131 ~~60, and 100~~-10, 11-30, 31-60, 61-100 cm. Major parameterization options relevant to  $\theta$  simulation include options  
 132 for canopy stomatal resistance parameterization and schemes controlling the effect of  $\theta$  on the vegetation stress factor  
 133  $\beta$ . Here we employed the Ball-Berry-type stomatal resistance scheme and Noah-type soil water content factor  
 134 controlling the  $\beta$  factor. The specific expressions are as follows:

$$135 \quad \beta = \sum_{i=1}^{N_{\text{root}}} \frac{\Delta z_i}{z_{\text{root}}} \min \left( 1.0, \frac{\theta_i - \theta_{\text{wilt}}}{\theta_{\text{ref}} - \theta_{\text{wilt}}} \right) \quad (1)$$

136 where  $\theta_{\text{wilt}}$  and  $\theta_{\text{ref}}$  are respectively soil water content at wilting point ( $\text{m}^3 \text{m}^{-3}$ ) and reference soil water content ( $\text{m}^3$   
 137  $\text{m}^{-3}$ ), which is set as field capacity during parameterization.  $\theta_i$  and  $\Delta z_i$  are soil water content ( $\text{m}^3 \text{m}^{-3}$ ) and soil depth  
 138 (cm) at  $i$ th layer,  $N_{\text{root}}$  and  $z_{\text{root}}$  are total number of soil layers with roots and total depth (cm) of root zone, respectively.

139 Following the Ball-Berry stomatal resistance scheme, the  $\theta$ -controlled  $\beta$  factor and other multiplicative factors  
 140 including temperature, foliage nitrogen simultaneously determine the maximum carboxylation rate  $V_{\text{max}}$  as follows:

$$141 \quad V_{\text{max}} = V_{\text{max}25} \alpha_{\text{vmax}}^{\frac{T_v - 25}{10}} f(N) f(T_v) \beta \quad (2)$$

142 where  $V_{\text{max}25}$  is maximum carboxylation rate at 25 °C ( $\mu\text{mol CO}_2 \text{m}^{-2} \text{s}^{-1}$ );  $\alpha_{\text{vmax}}$  is a parameter sensitive to vegetation  
 143 canopy surface temperature  $T_v$ ;  $f(N)$  is a factor representing foliage nitrogen and  $f(T_v)$  is a function that mimics thermal  
 144 breakdown of metabolic processes. Based on  $V_{\text{max}}$ , photosynthesis rates per unit LAI including carboxylase-limited  
 145 (Rubisco limited, denoted by  $A_c$ ) type and export-limited (for C3 plants, denoted by  $A_s$ ) type are calculated

146 respectively. The minimum of  $A_c$ ,  $A_s$  and light-limited photosynthesis rate determines stomatal resistance  $r_s$ , and  
 147 consequently affects ET over vegetated areas. For the complete NOAHMP configuration, please see Table S1 in the  
 148 supplementary material.

149 CLSM simulates the 0–2 and 0–100 cm soil water content and evaporative stress as a function of simulated  $\theta$  and  
 150 environmental variables. ET is then estimated based on the estimated evaporative stress and land-atmosphere humidity  
 151 gradients. Energy and water flux estimates are iterated with soil state estimates (e.g.,  $\theta$  and soil temperature) to ensure  
 152 closure of surface energy and water balances. For a detailed explanation of CLSM physics, please refer to Koster et  
 153 al. (2000).

154 GLEAM is a set of algorithms dedicated to the estimation of terrestrial ET and root-zone  $\theta$  from satellite data. In this  
 155 study, the latest version of this model (v3.2a) is employed. In GLEAM, the configuration of soil layers varies as a  
 156 function of the land-cover type. Soil stratification is based on three soil layers for tall vegetation (0–10, 10–100, and  
 157 100–250 cm), two layers for low vegetation (0–10, 10–100 cm) and only one layer for bare soil (0–10 cm) (Martens  
 158 et al., 2017).

159 The cover-dependent PET ( $\text{mm day}^{-1}$ ) of GLEAM is calculated using the Priestley and Taylor (1972) equation based  
 160 on observed air temperature and net radiation. Following this, estimates of PET are converted into actual transpiration  
 161 or bare soil evaporation (depending on the land-cover type, ET ( $\text{mm day}^{-1}$ )), using a cover-dependent, multiplicative  
 162 stress factor  $S$  (–), which is calculated as a function of microwave vegetation optical depth (VOD) and root-zone  $\theta$   
 163 (Miralles et al., 2011). The related expressions are as follows:

$$164 \quad \text{ET} = \text{PET} \times S + E_i \quad (3)$$

$$165 \quad S = \sqrt{\frac{\text{VOD}}{\text{VOD}_{\max}}} \left( 1 - \left( \frac{\theta_c - \theta_\omega}{\theta_c - \theta_{\text{wilt}}} \right)^2 \right) \quad (4)$$

166 where  $E_i$  is rainfall interception (mm);  $S$  essentially represents the fPET (see Sect. 2.3) estimated by GLEAM;  $\theta_c$  ( $\text{m}^3$   
 167  $\text{m}^{-3}$ ) is the critical soil water content and  $\theta_\omega$  ( $\text{m}^3 \text{m}^{-3}$ ) is the soil water content of the wettest layer, assuming that plants  
 168 withdraw water from the layer that is most accessible. Based on Eq. (4), GLEAM  $S$  (or fPET) tends to become more  
 169 sensitive to  $\theta$  in areas of low VOD seasonality (i.e., low differences between VOD and  $\text{VOD}_{\max}$ ). As for bare soil  
 170 conditions,  $S$  is linearly related to surface soil water content ( $\theta_1$ ):

$$171 \quad S = 1 - \frac{\theta_c - \theta_1}{\theta_c - \theta_{\text{wilt}}}. \quad (5)$$

172 To resolve variations in the vertical discretization of  $\theta$  applied by each model, we linearly interpolated NOAHMP,  
 173 CLSM and GLEAM outputs into daily 0–10 and 0–40 cm soil water content values using depth-weighted averaging.

174 **2.3 Variable indicating soil water content and surface flux coupling**

175 Soil water content – ET coupling can be diagnosed using a variety of different variables derived from ET, e.g. the  
176 fraction of PET (fPET, the ratio of ET and PET) or the evaporative fraction (EF, the ratio of LE and the sum of LE  
177 and sensible heat). Since ET is strongly tied to net radiation (Rn) (Koster et al., 2009), both fPET and EF are  
178 advantageous in that they normalize ET by removing the impact of non-soil water content influences on ET (e.g., net  
179 radiation, wind speed and soil heat flux (G)). However, since sensible heat flux is not provided in the GLEAM dataset,  
180 we are restricted here to using fPET.

181 It should be noted that the applied meteorological forcing data for NOAHMP and CLSM are somewhat different from  
182 those used for GLEAM. Therefore, to minimize the impact of this difference, NOAHMP and CLSM fPET are  
183 computed from North American Regional Reanalysis (NARR) using the modified Penman scheme of Mahrt and Ek  
184 (1984) while GLEAM fPET is calculated using its own internal PET estimates. To examine the impact of PET source  
185 on results, AmeriFlux fPET calculations are duplicated using both GLEAM- and NARR-based PET values.

186 **2.4 Information measures**

187 Mutual information (MI) (Cover and Thomas, 1991) is a nonparametric measure of correlation between two random  
188 variables. MI and the related Shannon-type entropy (SE, Shannon, 1948) are calculated as follows. Entropy about a  
189 random variable  $\zeta$  is a measure of uncertainty according to its distribution  $p_\zeta$  and is estimated as the expected amount  
190 of information from  $p_\zeta$  sample:

191 
$$SE(p_\zeta) = E_\zeta[-\ln(p_\zeta(\zeta))]. \quad (6)$$

192 Likewise, MI between  $\zeta$  and another variable  $\psi$  can be thought of as the expected amount of information about variable  
193  $\zeta$  contained in a realization of  $\psi$  and is measured by the expected Kullback-Leibler (KL) divergence (Kullback and  
194 Leibler, 1951) between the conditional and marginal distributions over  $\zeta$ :

195 
$$MI(\zeta; \psi) = E_\psi[D(p_{\zeta|\psi} \| p_\zeta)]. \quad (7)$$

196 In this context, the generic random variables  $\zeta$  and  $\psi$  represent fPET and  $\theta$  (soil water content) respectively. The  
197 observation space of the target random variable fPET is discretized using a fixed bin width. As bin width decreases,  
198 entropy increases but mutual information asymptotes to a constant value. On the other hand, increased bin width  
199 requires more sample size, which cannot always be satisfied. The trick is choosing a bin width where the NMI values  
200 stabilize with sample size. After a careful sensitivity analysis, we choose a fixed bin width of 0.25 [-] for fPET and  
201 make sure that each AmeriFlux site ~~have had~~ enough samples to accurately estimate the NMI, and change of this  
202 constant bin width from 0.1–0.5 [-] will not significantly alter our conclusions. Following Nearing et al. (2016), a bin  
203 width of 0.01 m<sup>3</sup> m<sup>-3</sup> (1% volumetric water content) for  $\theta$  is applied. Integrations required for MI calculation in Eq.  
204 (7) are then approximated as summations over the empirical probability distribution function bins (Paninski, 2003).



205 By definition, the MI between two variables represents the amount of entropy (uncertainty) in either of the two  
206 variables that can be reduced by knowing the other. Therefore, the MI normalized by the entropy of the AmeriFlux-  
207 based fPET measurements represents the fraction of uncertainty in fPET that is resolvable given knowledge of the soil  
208 water content state (Nearing et al., 2013). Unlike Pearson’s correlation coefficient, MI is insensitive to the impact of  
209 nonlinear variable transformations. Therefore, it is well suited to describe the strength of the (potentially non-linear)  
210 relationship between  $\theta$  and fPET.

211 Here, we applied this approach to calculate the MI content between soil water content representing different vertical  
212 depths (as reflected by  $\theta_s$  and  $\theta_v$ ) and fPET at each AmeriFlux site. All estimated site-specific MI are normalized by  
213 the entropy of the corresponding AmeriFlux-based fPET measurements to remove the effect of inter-site entropy  
214 variations on the magnitude of NMI differences. The resulting normalized MI calculations between both  $\theta_s$  and  $\theta_v$   
215 and fPET are denoted as  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$  respectively.

216 The underestimation of observed  $\theta/\text{ET}$  coupling via the impact of mutually-independent  $\theta$  and ET errors in AmeriFlux  
217 observations (Crow et al. 2015) is minimized by focusing on the ratio between  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$ .  
218 Therefore, relative comparisons between  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$  are based on examining the size of their  
219 mutual ratio  $\text{NMI}(\theta_s, \text{fPET})/\text{NMI}(\theta_v, \text{fPET})$ . To quantify the standard error of NMI differences between various soil  
220 water content products, we applied a nonparametric, 500-member bootstrapping approach and calculated pooled  
221 average of sampling errors across all sites assuming spatially independent sampling error.

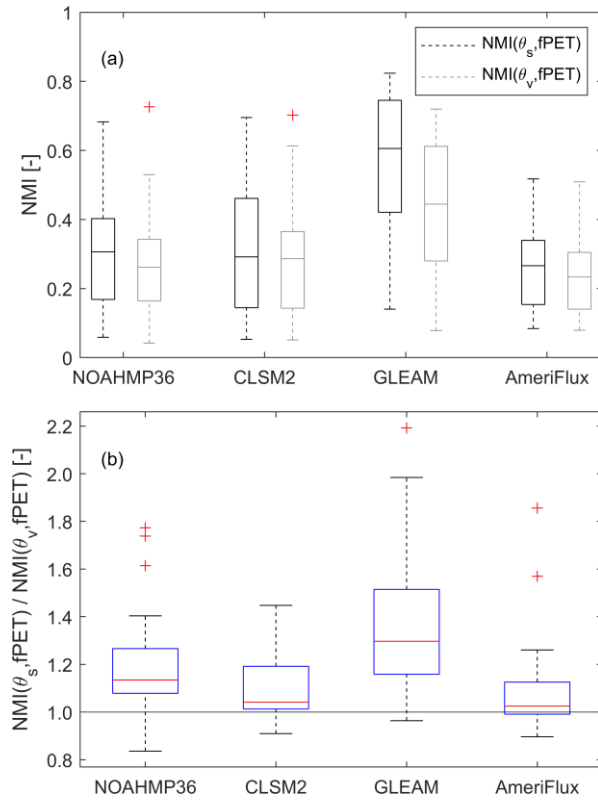
222 Finally, we also examined the impact of potential nonlinearity in the  $\theta/\text{ET}$  relationship by comparing non-parametric  
223 NMI results with comparable inferences based on a conventional Pearson’s correlation calculation. The correlation-  
224 based coupling strength between  $\theta_s$  and fPET is denoted as  $R(\theta_s, \text{fPET})$  and between  $\theta_v$  and fPET as  $R(\theta_v, \text{fPET})$ .

## 225 3 Results

### 226 3.1 Comparison of $\text{NMI}(\theta_s, \text{fPET})$ and $\text{NMI}(\theta_v, \text{fPET})$

227 Figure 1 contains boxplots of modelled and observed  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$ , i.e., the relative magnitude  
228 of fPET information contained in surface soil water content and vertically-integrated (0–40 cm) soil water content  
229 estimated from case I, sampled across all the AmeriFlux locations listed in Table 1. According to the AmeriFlux  
230 ground measurements, median values of  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$  (across all sites) are near 0.3 [-]. This  
231 suggests that approximately 30% of the uncertainty (i.e., entropy at this particular bin width of 0.25 [-]) in fPET can  
232 be eliminated given knowledge of either surface or vertically integrated soil water content state. This is consistent  
233 with earlier results in Qiu et al., (2016) who used similar metrics to evaluate  $\theta/\text{EF}$  (evaporative fraction) coupling  
234 strength. The sampled medians of  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$  estimated by the NOAAHMP and CLSM models  
235 are similar to these (observation-based) AmeriFlux values. With the single exception that the CLSM predicts much  
236 larger site-to-site variation in  $\text{NMI}(\theta_s, \text{fPET})$ .

237 In contrast,  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  values sampled from GLEAM  $\theta$  and fPET estimates are biased  
 238 highshow positive biases (with median  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  values of about 0.5 and 0.4 [-] for  $NMI(\theta_s,$   
 239  $fPET)$  and  $NMI(\theta_v, fPET)$ , respectively) with respect to all other estimates.



240  
 241 Fig.1 The  $\theta/ET$  coupling strengths for summertime anomaly time series acquired from various LSMs, GLEAM and AmeriFlux  
 242 measurements: (a)  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  individually and (b)  $NMI(\theta_s, fPET)$  normalized by  $NMI(\theta_v, fPET)$ .

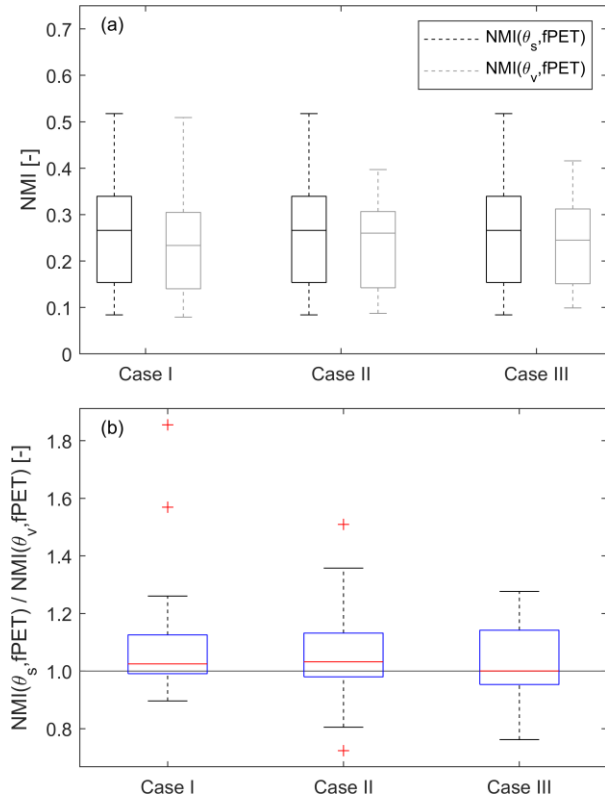
243 Using the 34 AmeriFlux site-located samples pixels for paired  $t$ -test, both Both LSMs and GLEAM overall exhibit  
 244 significantly (at  $p=0.05$  level) confidence, using the 34 AmeriFlux site-located samples pixels for pair  $t$ -test  
 245 higher  $NMI(\theta_s, fPET)$  compared to  $NMI(\theta_v, fPET)$  – implying the surface soil water content observations contain  
 246 more fPET information than vertically-integrated soil water content observations. However, the observed difference  
 247 between  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  is less discernible in AmeriFlux measurements (Fig. 1(a)).

248 Here, AmeriFlux observations are used as a baseline for LSM and GLEAM evaluation. However, it should be stressed  
 249 that random observation errors in  $\theta$  and fPET will introduce a low bias into AmeriFlux-based estimates of both  $NMI(\theta_s,$   
 250  $fPET)$  and  $NMI(\theta_v, fPET)$  (Crow et al., 2015) and thus their difference as well. To address this concern, Fig. 1(b)

251 plots the ratio of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$ , which effectively normalizes (and therefore minimizes) the  
252 impact of random observation errors. As discussed above, these ratio results illustrate the general tendency for  $NMI(\theta_s,$   
253  $fPET) \gg$  to exceed  $NMI(\theta_v, fPET)$ . They also highlight the tendency for GLEAM to overvalue  $\theta_s$  (relative to  $\theta_v$ ) when  
254 estimating  $fPET$ . A second approach for reducing the random error of  $\theta$  and  $fPET$  measurement errors is the Triple  
255 Collocation (TC)-based correction applied in Crow et al. (2015). However, this approach is currently restricted to  
256 linear correlation and cannot be applied to estimate NMI. Future work will examine extending the information-based  
257 TC approach of Nearing et al. (2017) to the examination of NMI.

### 258 3.2 Sensitivity of AmeriFlux-based $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$

259 As mentioned in Sect. 2.1, an important concern is the impact of interpolation errors used to estimate 0–40 cm  $\theta_v$  from  
260 AmeriFlux  $\theta_s$  observations acquired at non-uniform depths. To ensure that different methods for calculating  
261 AmeriFlux  $\theta_v$  values do not affect the main conclusion of this study, we configured three cases for  $\theta_v$  calculation, and  
262 compared their  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  results in Fig. 2. Case I reflects the baseline use of the exponential  
263 filter described in Sect. 2.1. However, slight changes to AmeriFlux results are noted if alternative approaches are used.  
264 Specifically, AmeriFlux-based  $NMI(\theta_v, fPET)$  increases and closes the gap with  $NMI(\theta_s, fPET)$  if the bottom-layer  
265 soil water content measurements are instead directly used as  $\theta_v$  (Case II) or if 0–40 cm  $\theta_v$  is based on the linear  
266 interpolation of the two AmeriFlux  $\theta$  observations (Case III), the impact of this modest sensitivity on key results is  
267 discussed below.



268

269 Fig.2 The  $\theta$ /ET coupling strengths for summertime anomaly time series from AmeriFlux measurements using three different  $\theta_v$   
 270 calculation methods: (a)  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  individually and (b)  $NMI(\theta_s, fPET)$  divided by  $NMI(\theta_v, fPET)$  for  
 271 multiple  $\theta_v$  cases. Case I is based on the application of an exponential filter to extrapolate 0–10 cm  $\theta_s$  to a consistent 0–40 cm  
 272 bottom layer depth, while Cases II and III refer to the direct use of only the bottom layer measurement and a linear interpolation of  
 273 both the top and bottom layer, respectively, to calculate  $\theta_v$  (see Sect. 2.1 for details on each case).

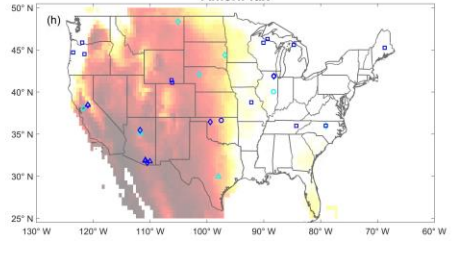
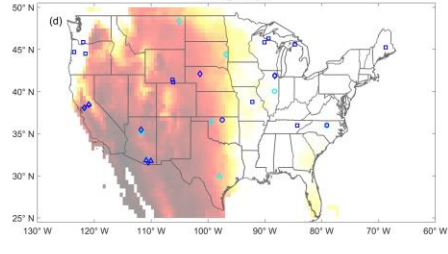
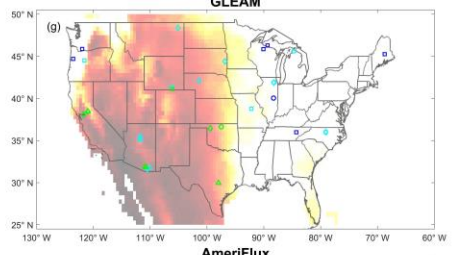
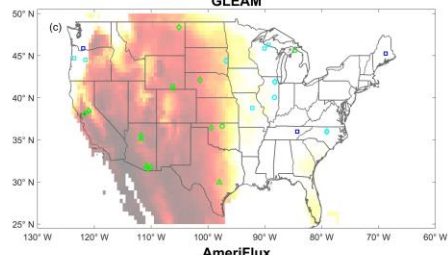
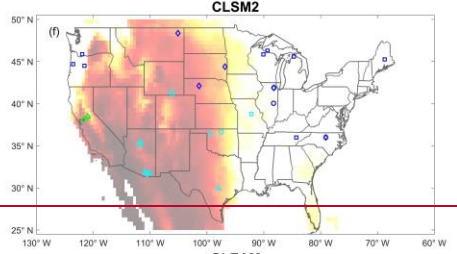
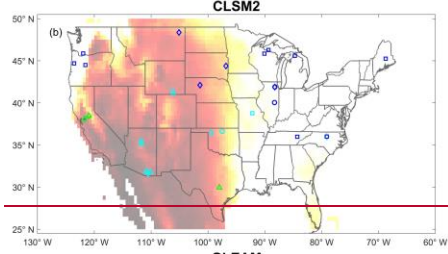
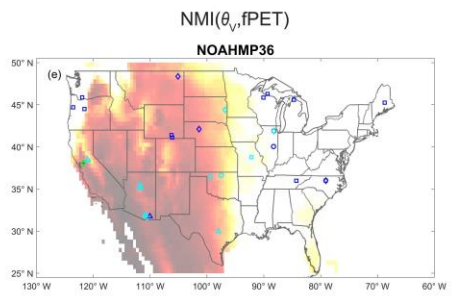
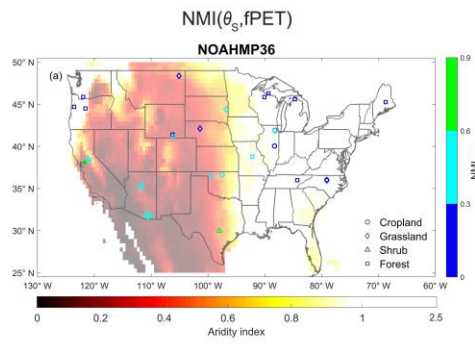
274 In addition, switching from GLEAM- to NARR-based PET when calculating fPET for AmeriFlux-based  $NMI(\theta_s,$   
 275 fPET) and  $NMI(\theta_v, fPET)$  does not qualitatively change results and produces only a very slight (~6%) increase in the  
 276 median  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio.

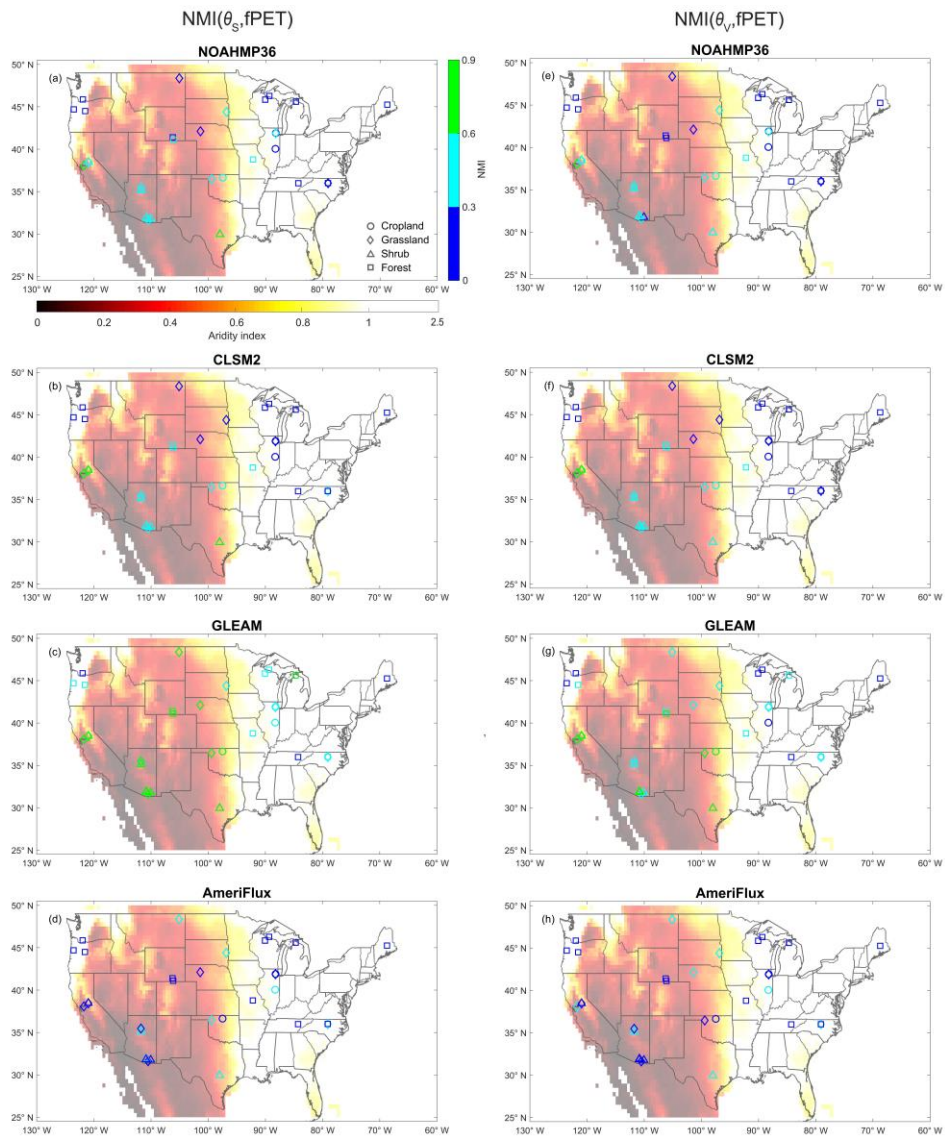
### 277 3.3 Spatial distribution of $NMI(\theta_s, fPET)$ and $NMI(\theta_v, fPET)$

278 Figure 3 plots the spatial distribution of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  results for each of the individual 34  
 279 AmeriFlux sites listed in Table 1. The climatic regime is represented by AI (aridity index) values plotted as the  
 280 background color in Fig. 3. It can be seen in Fig. 3 that  $NMI(\theta_s, fPET)$  estimates from LSMs and GLEAM are spatially  
 281 related to hydro-climatic conditions, as NOAAHMP and CLSM predict that  $\theta_s$  is moderately coupled with fPET (i.e.,  
 282  $NMI(\theta_s, fPET)$  of 0.3–0.5 [-]) in the arid southwestern US ( $AI < 0.2$ ) and only loosely coupled with fPET in the

283 relatively humid eastern US. A similar decreasing trend of  $NMI(\theta_s, fPET)$  from the southwestern to eastern US is also  
284 captured by GLEAM. However, as noted above, GLEAM generally overestimates  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$   
285 compared to NOAHMP, CLSM and AmeriFlux. In contrast, a relatively weaker spatial pattern emerges in AmeriFlux-  
286 based  $NMI(\theta_s, fPET)$  results. In addition, spatial patterns for  $NMI(\theta_s, fPET)$  are less defined than for  $NMI(\theta_v, fPET)$   
287 in all four datasets.

288 Scatterplots in Fig. 4 summarize the spatial relationship between LSM- and GLEAM-based  $NMI(\theta_s, fPET)$  and  
289  $NMI(\theta_v, fPET)$  results versus AmeriFlux observations across different land use types. While observed levels of  
290 correlation in Fig. 4 are relatively modest, there is a significant level ( $p < 0.05$ ) of spatial correspondence between  
291 LSMs modelled and observed NMI results only over forest sites – motivating the need to better understand processes  
292 responsible for spatial variations in NMI results. In addition, stratifying  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio results  
293 according to vegetation type (Fig. A1) confirms that  $NMI(\theta_s, fPET)$  slightly exceeds  $NMI(\theta_v, fPET)$  across all  
294 vegetation types (and thus all rooting depths characterizing each vegetation type). This suggests that our analysis is  
295 not severely affected by variations in the depth of  $\theta$  measurements. For further discussion on the impact of land cover  
296 on NMI results, please see Appendix A.





298

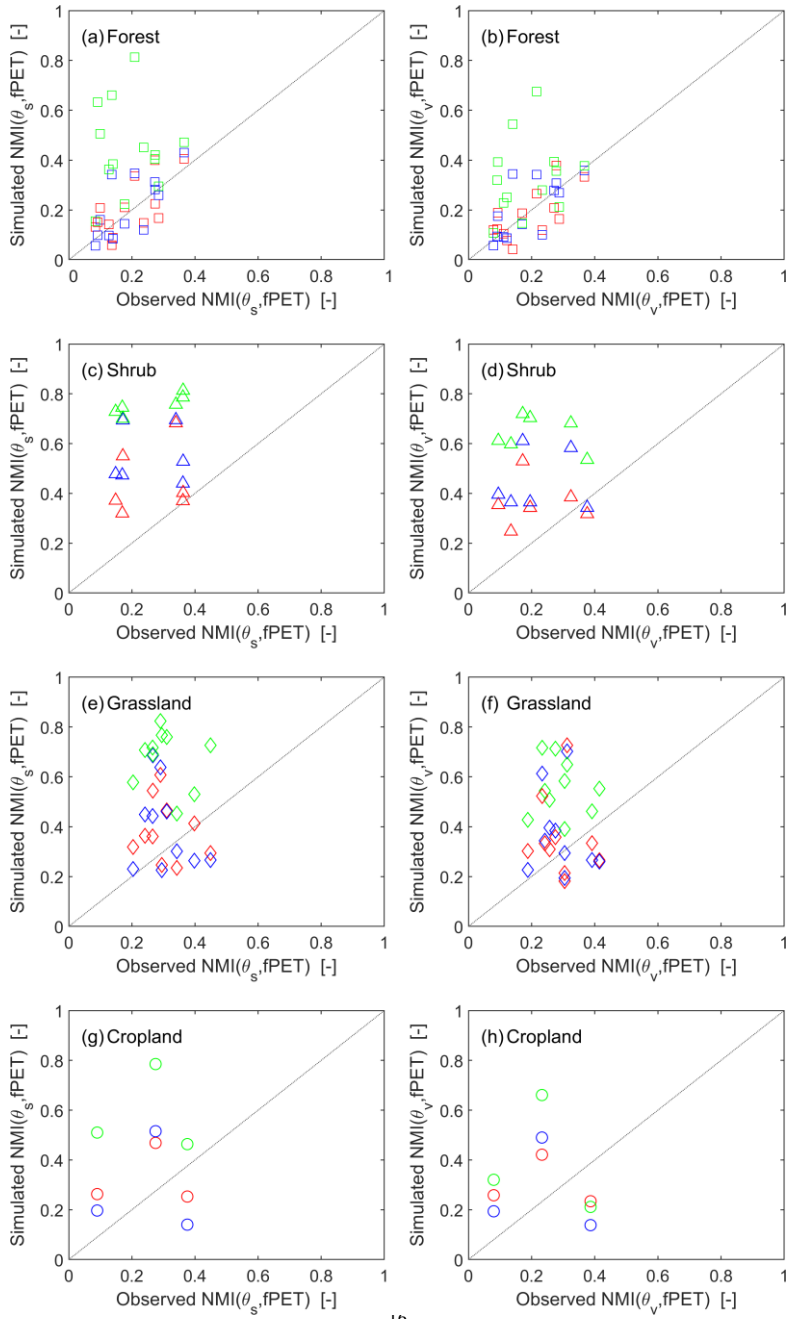
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Fig. 3  $NMI(\theta_s, fPET)$  (left column) and  $NMI(\theta_v, fPET)$  (right column) estimates at AmeriFlux sites for: (a) NOAHMP, (b) CLSM, (c) GLEAM and (d) AmeriFlux. Marker color reflects NMI magnitudes and symbol type reflects local land cover type at each site. Background color shading reflects aridity index (AI) values.

302



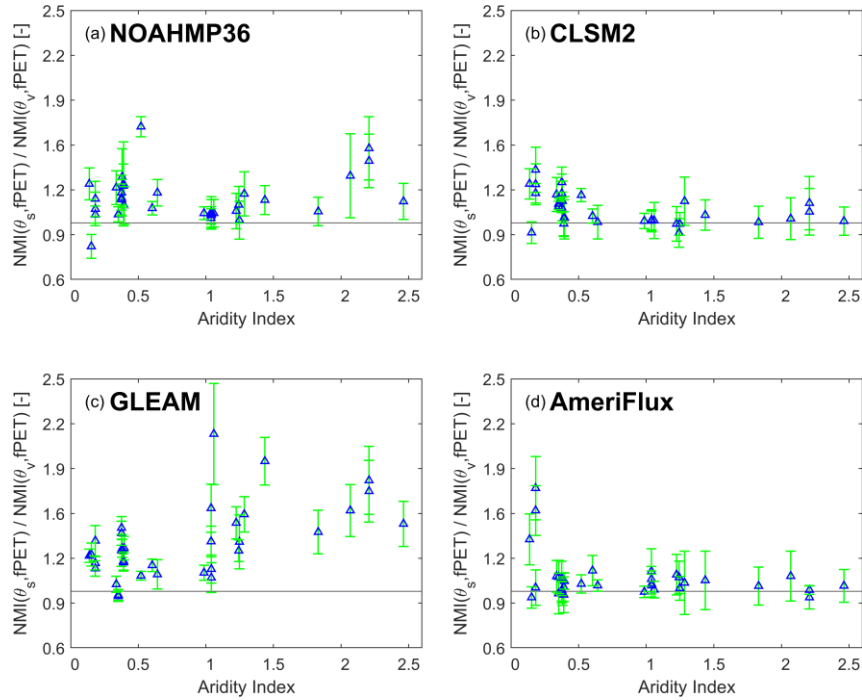


304 Fig. 4 Scatterplot of LSM-based and GLEAM-based (a)  $NMI(\theta_s, fPET)$  and (b)  $NMI(\theta_v, fPET)$  results versus AmeriFlux  
305 observations. Red symbols represent simulations from NOAHMP36; blue symbols represent simulations from CLSM2 and green  
306 symbols represent GLEAM retrievals.

### 307 **3.4 Sensitivity of $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$ ratio to climatic conditions**

308 Figure 5 further summarizes the  $NMI(\theta_s, fPET) / NMI(\theta_v, fPET)$  ratio as a function of AI for all four products  
309 (NOAHMP, CLSM, GLEAM and AmeriFlux). Error bars represent the standard deviation of sampling errors  
310 calculated from a 500-member bootstrapping analysis. With increasing AI, there is a significant decreasing trend in  
311 both  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  for all three simulations, with a goodness-of-fit above 0.5 (figure not shown).  
312 For all cases, the  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratios are consistently greater than unity under all climatic conditions.  
313 However, the estimated  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratios from all three simulations (NOAHMP, CLSM and  
314 GLEAM) exhibit quite different trends with respect to AI. The  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio for CLSM  
315 decreases with increasing AI, with a moderate goodness-of-fit value of 0.28, while GLEAM estimates of  $NMI(\theta_s,$   
316  $fPET)/NMI(\theta_v, fPET)$  shows an opposite increasing trend with increasing AI. Conversely, there is relatively lower  
317 sensitivity of the  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio to AI captured in the AmeriFlux measurements.

318 Connecting these findings to spatial distribution of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  (Fig. 3) confirms that the  
319 relative magnitudes of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  for both LSMs and GLEAM are spatially related to hydro-  
320 climatic regimes. In contrast, this link is weaker in the AmeriFlux measurements which, except for a small fraction of  
321 very low AI sites, do not appear to vary as a function of AI. These conclusions are not qualitatively impacted by  
322 looking at  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  differences, as opposed to their ratio as in Fig. 5, or by looking at  $R(\theta_s,$   
323  $fPET)$  and  $R(\theta_v, fPET)$  instead of NMI.



324  
 325 Fig. 5 For a) NOAHMP, (b) CLSM, (c) GLEAM and (d) AmeriFlux estimates, the ratio of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  as  
 326 a function of AI across all AmeriFlux sites.

327 **4 Discussion and conclusion**

328 Since transpiration dominates the global ET (Jasechko et al., 2013), deep-layer soil water content ( $\theta_v$ ) is generally  
 329 considered to contain more ET information than that of surface soil water content ( $\theta_s$ ) – given plant transpiration is  
 330 balanced by root water uptake from deeper soils (Seneviratne et al., 2010). However, this assumption is rarely tested  
 331 using models and/or observations. Here, we apply normalized mutual information (NMI) to examine how the vertical  
 332 support of a soil water content product affects its relationship with concurrent surface ET.

333 Specifically, using AmeriFlux ground observations, we examine whether (NMI-based) estimates of LSMs and  
 334 GLEAM  $\theta_s$  versus ET and  $\theta_v$  versus ET coupling strength accurately reflect observations acquired at a range of  
 335 AmeriFlux sites. In general, compared to the baseline case of exponential filter extrapolated 40-cm bottom layer  $\theta_v$ ,  
 336 LSMs and GLEAM agree with AmeriFlux observations in that the overall fPET information contained in  $\theta_s$  is slightly  
 337 higher than that of  $\theta_v$  (Fig. 1). However, the sensitivity analysis showed this difference between  $NMI(\theta_s, fPET)$  and  
 338  $NMI(\theta_v, fPET)$  diminishes when using different methods for calculating  $\theta_v$  using AmeriFlux observations (Fig. 2).  
 339 As a result, this result should be viewed with caution.

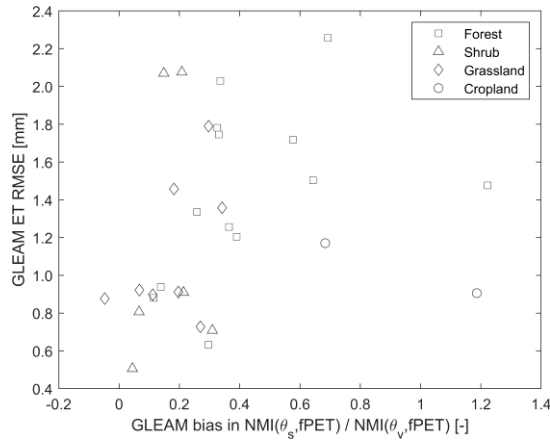
340 While NOAHMP and CLSM derived  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$  results are generally consistent with the  
341 AmeriFlux observations, GLEAM overestimates  $\text{NMI}(\theta_s, \text{fPET})$ ,  $\text{NMI}(\theta_v, \text{fPET})$ , and the ratio  $\text{NMI}(\theta_s,$   
342  $\text{fPET})/\text{NMI}(\theta_v, \text{fPET})$  relative to observations. Although both LSMs and GLEAM are based on the same classical  
343 two-section (soil water content-limited and energy-limited) ET regimes framework (Sect. 2.2), they differ in two  
344 fundamental aspects. First, the evaporative stress factor  $S$  is represented as a more direct and strong function of soil  
345 water content in GLEAM - see Eqs. (4) and (5) - which leads to the overestimation of  $\theta$ /ET coupling strength. This is  
346 consistent with our results that GLEAM generally overestimates  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$  consistently  
347 across all land covers, compared to AmeriFlux-based estimates. On the other hand, NOAHMP and CLSM approximate  
348 ET in the manner of biophysical models, and expresses biophysical control on ET through the stomatal resistance  $r_s$ ,  
349 which is a function of multiple limiting factors including  $\theta$ . Therefore, the more complex ET scheme employed by  
350 NOAHMP and CLSM would seem to mitigate the overestimation of  $\text{NMI}(\theta_s, \text{fPET})$  and  $\text{NMI}(\theta_v, \text{fPET})$ , as other  
351 relevant factors besides  $\theta$  (such as temperature, foliage nitrogen) are also considered in determining maximum  
352 carboxylation rate  $V_{\max}$  and stomatal resistance  $r_s$  - and consequently more realistic actual ET.

353 Second, the stress factor  $\beta$  in both LSMs considers the cumulative effects of  $\theta$  conditions along different layers (Eq.  
354 (1)), while the corresponding factor  $S$  in GLEAM only uses the wettest soil layer condition, which is top layer at most  
355 sites. This likely explains the overestimation of the  $\text{NMI}(\theta_s, \text{fPET})/\text{NMI}(\theta_v, \text{fPET})$  ratio by GLEAM.

356 Nevertheless, we would like to stress that all approaches considered in our paper contain (at their core) a parameterized  
357 relationship between  $\theta$  and ET. While the implications of mis-parameterizing this relationship are arguably more  
358 severe for a land surface model, we'd argue that the issue remain relevant for any approach (such as GLEAM) that  
359 utilizes a water balance (and/or data assimilation system) approach to estimate  $\theta$  and, in turn, uses  $\theta$  to constrain ET.  
360 Regardless of the complexity that a given approaches employs, failing to accurately describe the relationship between  
361 ET and (large number of potential) environmental constraints should eventually degrade the robustness of the model,  
362 ~~no matter the model, whether it~~ is employed as a retrospective, diagnostic or predictive manner. To examine this issue  
363 directly, Fig. 6 plots the relationship between GLEAMs bias in  $\text{NMI}(\theta_s, \text{fPET})/\text{NMI}(\theta_v, \text{fPET})$  ratio versus the RMSE  
364 of daily GLEAM ET simulations for a range of AmeriFlux sites. There is a positive correlation between the two  
365 quantities - which suggests that GLEAM overestimation of  $\theta$ /ET coupling during the summer may undermine the  
366 accuracy of its daily ET retrievals. It should be noted that GLEAM simultaneously overestimates both  $\text{NMI}(\theta_s, \text{fPET})$   
367 and  $\text{NMI}(\theta_v, \text{fPET})$ ; however, the impact of this mis-parameterization impact on GLEAM ET accuracy is most  
368 obvious when plotted against the ratio  $\text{NMI}(\theta_s, \text{fPET})/\text{NMI}(\theta_v, \text{fPET})$ .

**Commented [JQ1]:** We found the editor's comments to be very useful. Many thanks!

However, we disagree on the movement of Fig. 6 to the Results section. The rationale for presenting Fig. 6 will only become clear to the readers AFTER they read text presented in the first couple paragraphs of the Discussion section. Therefore, while we agree that placing a figure in the Discussion section is somewhat unusual, moving it to the Results section would disrupt the logical flow of the manuscript (by presenting results out of logical order). Therefore, it is our strong preference to keep it in the Discussion section.



369  
 370 Fig. 6 Daily ET error in GLEAM as a function of GLEAM bias in  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio across 34 AmeriFlux sites.

371 Although the median values of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$  predicted by NOAHMP and CLSM are general in  
 372 line with AmeriFlux observations, they are more spatially related to hydro-climatic conditions (as summarized by AI)  
 373 than their counter parts acquired from AmeriFlux measurements. Seen from the plot of  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$   
 374 ratio as a function of AI (Fig. 5), the modelled and observed median of  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio ~~median~~  
 375 decreases with increasing AI, and the decreasing trend is particularly clear when AI is lower than 1.0 [-]. In contrast,  
 376 there is relatively lower sensitivity to aridity exhibited in the AmeriFlux measurements.

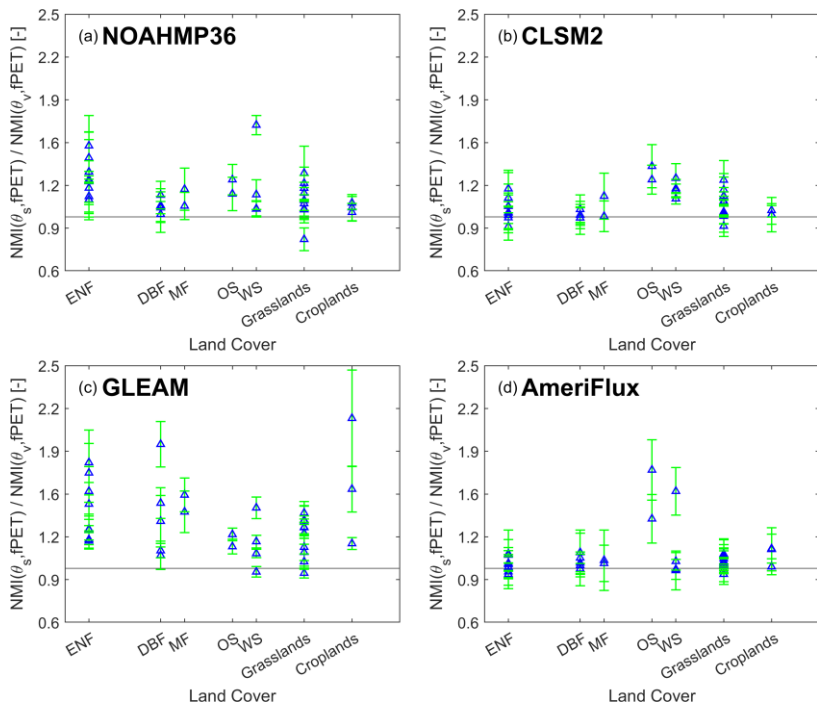
377 These results provide several key insights into future land-atmosphere coupling analysis and LSM as well as ET  
 378 algorithm development. First, all the datasets – both model-based and ground-observed – indicates that  $\theta_s$  contain at  
 379 least as much ET information as  $\theta_v$ . Hence, remote-sensing land surface soil water content datasets are suitable, and  
 380 should be considered, for analyzing the general interaction between land and atmosphere, e.g., soil water content – air  
 381 temperature coupling (Dong and Crow, 2019) and the interplay of soil water content and precipitation (Yin et al.,  
 382 2014). Additionally, future generations of GLEAM may consider more sophisticated evaporation stress functions,  
 383 which may improve its accuracy in representing soil’s control on local ET. This may, in turn, improve the accuracy  
 384 of GLEAM ET product. Finally, our results demonstrate that modeled  $\theta/ET$  is more sensitive to hydro-climates than  
 385 the observed relationship. Modifying the model structures to reduce such sensitivity might be necessary for accurately  
 386 representing the interaction of land surface and atmosphere across different climate zones. This may lead to more  
 387 realistic projections of future drought-induced heatwaves, when coupled with general circulation models.

388 **Data availability**

389 Ground-based soil water content and surface flux data are available from <http://ameriflux.ornl.gov/>. GLEAM dataset is  
390 available from <https://www.gleam.eu/>. LSMs simulations of NOAHMP and CLSM used in this study are available by  
391 contacting the authors.

392 **Appendix A**

393 We performed additional sensitivity analysis to explicitly demonstrate the effect of different vegetation land cover types  
394 and consequently different rooting depths ( $\theta$ , measurement depths) on the  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  ratio, and  
395 plotted these results in Fig. A1. The figure confirms that consistent with AmeriFlux, both LSMs and GLEAM predict  
396 that  $NMI(\theta_s, fPET)$  is slightly higher than  $NMI(\theta_v, fPET)$  over most vegetation types, and GLEAM overestimates  
397  $NMI(\theta_s, fPET)/NMI(\theta_v, fPET)$  for most vegetation types.



398  
399 Fig. A1 For a) NOAHMP, (b) CLSM, (c) GLEAM and (d) AmeriFlux estimates, the ratio of  $NMI(\theta_s, fPET)$  and  $NMI(\theta_v, fPET)$   
400 as a function of vegetation types across all AmeriFlux sites. 'ENF', 'DBF', 'MF', 'OS' and 'WS' represent evergreen needleleaf forests,  
401 deciduous broadleaf forests, mixed forests, open shrubland, and woody savannas, respectively.

402 **Author contributions**

403 Jianxiu Qiu and Wade T. Crow conceptualized the study. Jianzhi Dong helped preparing the LSMs simulation. Grey S.  
404 Nearing assisted in the mutual information analysis. Jianxiu Qiu carried out the analysis and wrote the first draft  
405 manuscript, and Wade T. Crow refined the work. All authors contributed to the analysis, interpretation and writing.

406 **Competing interests**

407 The authors declare that they have no conflict of interest.

408 **Acknowledgments**

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