



1 **Technical note on long-term probe misalignment and**
2 **proposed quality control using the heat pulse method for**
3 **transpiration estimations**

4 Elisabeth K. Larsen^{1,3}, Jose Luis Palau¹, Jose Antonio Valiente¹, Esteban Chirino² and
5 Juan Bellot^{3,4}.

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7 ¹Mediterranean Centre for Environmental Studies (Foundation CEAM), Charles R. Darwin 14, Parque
8 Tecnològic, 46980 Paterna, Valencia, Spain

9 ²Faculty of Agricultural Sciences, Lay University Eloy Alfaro of Manabí, Ave. Circunvalación, Vía San
10 Mateo, Manta 130802, Ecuador

11 ³Department of Ecology, University of Alicante, Apdo. 99, E-03080 Alicante, Spain

12 ⁴IMEM Ramón Margalef, Department of Ecology, Faculty of Sciences, University of Alicante, 03080
13 Alicante, Spain

14 *Correspondence to:* Elisabeth K. Larsen (eli@ceam.es)

15 **Abstract**

16 Whole-plant transpiration is a crucial component in the hydrological cycle and a key parameter in many
17 disciplines like agriculture, forestry and ecology. Sap flow measurements are one of the most widely used
18 methods to estimate whole-plant transpiration in woody species due to its wide application range and its
19 ready automation for continuous data readings. Several different methods have been developed and
20 adjusted to different climatic conditions and wood properties. However, the scientific literature also
21 identifies several sources of error in the method that needs to be accounted for; misalignment of the
22 probes, wound to the xylem, thermal diffusivity and stem water content. This study aims to integrate
23 probe misalignment as a function of time to improve readings during long-term measurements (> 3
24 months). We conclude that even when geometrical misalignments errors are small, the introduced
25 corrections can imply an important shift in sap flow estimations. Additionally, we propose a new set of
26 statistical record to be recorded during the measurement period to use as a quality control of the heat ratio
27 readings obtained from the sensors. By using standard deviation and slope as quality indicators we
28 concluded that no general time limit can be decided for all sensors but should rather be determined from
29 individual performance over time.

30

31 **1. Introduction**

32 Plant transpiration is a key process in the hydrological cycle and in forest ecosystems it is often the largest
33 component of total evapotranspiration (Jasechko et al., 2013). Accurate estimations of transpiration are still
34 difficult to obtain, and field assessments of transpiration estimations are therefore crucial in hydrological
35 planning as well as in forestry, ecophysiological research and climate forecasting. Sap flow measurement
36 is one of the most widely used techniques to estimate whole plant transpiration in woody species because
37 it is a readily automated for continuous readings and is not limited to single leaf measurements (Forster,
38 2017). Although some sap will go to stem and leaf storage, it is estimated that 99% is lost through
39 transpiration, and sap flow measurements can therefore be used to directly estimate transpiration values



40 (Forster, 2017). In addition, sap flow sensors estimate plant transpiration rates regardless of the orographic
41 complexity and atmospheric conditions of stability or stratification, which can hinder the direct
42 measurement of transpiration flows in forest environments.

43

44 There are a range of different approaches to sap flow measurements, and methods vary between heat
45 dissipation (HD), steam heat balance (SHB), trunk segment heat balance (THB) and heat pulse velocity
46 (HPV). However, they are all based on tracing heat within the xylem (Burgess et al., 2001; Davis et al.,
47 2012; Forster, 2017). Marshall (1958) developed a theoretical method to determine sap flow from the
48 thermal diffusion and dissipation theory of heat pulses in heterogeneous material. His theory relies on
49 calculating the heat ratios measured in two parallel thermocouples aligned vertically and symmetrically
50 with respect to a line heater along the direction of the xylem. Burgess et al. (2001) developed an improved
51 HPV technique, termed the heat ratio method (HRM), based on the Marshall (1958) methodology, which
52 is sensitive to the direction of sap flow and is capable of measuring low and reverse rates (Burgess et al.,
53 2001), which is not possible using energy balance methods like eddy-covariance and which often is the
54 case for nightly values (Burgess et al., 2001; Novick et al., 2009). Burgess et al. (2001) developed two steps
55 of corrections for sap flow calculations by considering probe misalignment and wounding (caused by the
56 implementation of the sensors). By accounting for these sources of error and additionally estimating the
57 stem moisture content and radial variability, the heat ratio method (HRM) has been evaluated the heat pulse
58 velocity method (HPV) with highest accuracy, although with a tendency of underestimating transpiration
59 values (Forster, 2017).

60

61 Previous studies have suggested additional solutions for probe misalignment (Ren et al., 2017), or for
62 determining thermal diffusivity (Vandegehuchte and Steppe, 2012), and correcting for heterogeneous heat
63 capacity in wood (Becker and Edwards, 1999). However, we suggest attention should be given to check the
64 accuracy of the heat pulse ratio itself, in which the rest of the methodology is built on. In addition, we found
65 it necessary to develop a dynamic probe misalignment correction method. One way to account for changes
66 over time has been to reinstall sensors throughout the study period (Moore et al. 2010), however there is
67 little information to be found on the exact interval of which this needs to happen (Vandegehuchte and
68 Steppe, 2013), and for continuous measurements this will interrupt the dataset. The adjustment proposed
69 here, built on the calculations of Burgess et al. (2001), is necessary when monitoring transpiration
70 continuously for more than 3 months because wood properties, the heterogeneity of the xylem and plant
71 tissue growth might further misplace the sensor after its implementation (Barrett et al., 1995). Burgess et
72 al. (2001) corrected for linear probe misalignment *in situ*. This correction must be effectuated during zero
73 flow. Actual probe placement is therefore suggested to be calculated one time, usually at the end of the
74 experiment when the root system can be severed to enforce zero flow (Burgess et al., 2001). However, this
75 solution is not suitable for long term measurements, as the misplacement will change over time (Ren et al.,
76 2017), or when intrusive methods are not an option. Thus, the objective of this research is firstly, to develop
77 a statistical filtration method to ensure the quality and consistency of the measurements over time, and,
78 secondly, to implement a modified version of the probe misalignment calculation for sap flow series longer
79 than 3 months.



80 This methodological paper is structured in two parts: the first one, dealing with the statistical analysis of
81 long-term time series of heat pulse ratios to ensure the quality of data and their stability over time; the
82 second part, proposing an adaptation of the method developed by Burgess et al. (2001) to contemplate a
83 dynamic probe misalignment correction for the heat ratio method (HRM). The aim is to obtain a more
84 precise calculation of transpiration by parameterising the probe misalignment as a function of time to
85 correct for the effect of tree growth.

86

87 2. Materials and method

88

89 2.1 Field site

90 This study was carried out in the Turia river basin, Eastern Spain (39°57'45" N 1°8'31" W), in a
91 Mediterranean climate. Average annual rainfall is 475 mm, average annual maximum and minimum
92 temperature is 15.5 °C and 4.4 °C respectively. Sap flow sensors were installed in four pine trees (*Pinus*
93 *halepensis* Mill.) according to the heat ratio method (HRM, Burgess et al., 2001). Three needles, one
94 heater and two thermocouples (0.13 cm x 4 cm), were drilled into the uphill side of each tree trunk. Since
95 *P. halepensis* has a higher sap velocity average near the cambium with the velocity steady declining
96 nearer to the heartwood (Cohen et al., 2008), sensors were installed at 20 mm depth below the cambium
97 for average sap velocity rates, as estimated by Manrique-Alba (2017). A metal plate was used as guide to
98 assure a 0.6 cm spacing between the drilling holes. *P. halepensis* selected had a mean diameter of 24.5 cm
99 at breast height (150cm). Continuous measurements were obtained from April 2017 to December 2018.

100

101 2.2 Construction of the sensors

102 The thermocouples were made after Davis et al. (2012), with a type E junction of chromium and
103 constantan. The E type has a higher accuracy, stronger signal and more stability than the type K (Davis et
104 al., 2012). The wires of the thermocouples were soldered together at temperatures not surpassing 200°C
105 and placed 2 cm inside a glass tube (0.1 cm x 4 cm) and into a needle (0.13 cm x 4 cm). The heater was
106 made of a constantan wire of 20 cm coiled around a 7 cm long aluminium wire before placed inside a
107 needle of 4 cm. The wire-ends were then soldered on to an electrical cable. Another resistance of 10 ohms
108 were soldered onto the cable to get a total resistance of 20 ohms. The heater was connected to a 12 V
109 battery and delivered 7.0 W of power. All three sensors were connected to a CR800 datalogger
110 (Campbell Scientific Inc., USA).

111

112 2.3 Quality control of heat pulse ratios

113 Marshal (1958) parameterised the heat pulse velocity (V) in the HRM as a function of time following a
114 heat pulse, and the instantaneous ratio of the increase of temperature (from the temperature prior to the
115 release of the thermal pulse) at the downstream and upstream, v_1 and v_2 respectively, from a line heater:

116

$$117 \quad V = \frac{4Kt \ln\left(\frac{v_1}{v_2}\right) - (x_2^2 + y_2^2) + (x_1^2 + y_1^2)}{2t(x_1 - x_2)} \quad [1]$$



118 where K is the thermal diffusivity, t is time from the release of thermal pulse, (x_1, y_1) and (x_2, y_2) are the
119 relative positions of the thermocouples to the line heater (considering x-axis along the xylem and y-axis
120 the perpendicular direction both to the xylem and to the heater line), and v_1, v_2 represents the temperature
121 increases following the heat release, in the downstream and upstream thermocouple respectively.

122

123 If probes are installed symmetrically above and below the heater line, $x = x_1 = -x_2$ and $y_1 = -y_2$, the
124 equation 1 simplifies into a function not dependent on time:

$$125 \quad V = \phi \ln \left(\frac{v_1}{v_2} \right) \quad [2]$$

$$126 \quad \phi = \frac{K}{x}$$

127 where ϕ is, a priori, a constant only depending on the placement of the probes and on the thermal diffusivity
128 of both the xylem and the material used in sensors.

129

130 The “perfect symmetry” assumption renders that HPR remains constant with time if sap flow velocity (V),
131 thermal diffusivity (K) and probe positions (in both, x and y directions) have negligible variations during
132 the time following each heat pulse (Marshall, 1958). However, Burgess et al. (2001) describe how empirical
133 results initially differ from the ideal approach described by equation 2, although they converge
134 asymptotically at least 60 seconds after the heat pulse release and, for at least, 40 seconds more (until 100
135 seconds after the heat pulse release). A visual inspection of heat pulse velocities (V in equations 1 and 2)
136 do not necessarily give enough information to decide if measured values are a good representation of the
137 sap velocity or not. On these premises, we have built a methodology utilising a quality check of systematic
138 sap flow measurements by means of a statistical analysis performed on the instantaneous values acquired
139 between 60 and 100 seconds. Hereafter we will denote the averaged instantaneous heat pulse ratio between
140 60 and 100 seconds as HPR. Threshold values were established for the relative standard deviation (RSD)
141 and the slope of the time evolution of instantaneous heat pulse ratios.

142

143

144 2.3.1 Logging specifications

145 The proposed analysis to ensure the reliability of long time series of sap flow measurements require the
146 storage of statistics that are not usually recorded (as it is considered unnecessary). The datalogger to be
147 used must have a minimum performance of the storage capacity (memory), the processing speed of the
148 algorithm implemented (especially in the routines related to the statistical calculations to be performed). In
149 this study a CR800 (Campbell Scientific, USA) was used. A flow chart of sampling and data log (Fig. S1)
150 was specifically designed, programmed and implemented in the datalogger to enable the calculus that are
151 presented in the next sections of this paper.

152

153 The RSD is statistically defined as the standard deviation divided by the mean. Therefore, we selected RSD
154 (%) and Slope (s^{-1}) of the instantaneous ratio versus time calculated for each of the periods from 60 to 100
155 seconds and used for the quality control (Fig. 1A and B). All HPR with relative standard deviation $> 5\%$



156 and a $|\text{slope} - \text{median}(\text{slope})| < 0.003 \text{ s}^{-1}$ were removed. The 5 % threshold was chosen to ensure that 95 %
157 of the dataset was considered in the data processing. The slope median was taken from all slope values
158 obtained during the measurement period. The magnitude of this slope threshold was chosen from modelled
159 output of instantaneous ratios performed by Burgess et al. (2001), were low heat pulse velocities (5 cm h
160 ⁻¹) are shown to display a slope of 0.001. The specific threshold of 0.003 was decided upon inspection of
161 the measurements and can be modified according to the sensor.

162

163 2.4 Correction for long-term probe misplacement

164 Under the assumption of “perfect symmetry”, in periods when $V = 0 \text{ cm h}^{-1}$, the ratio of the increase of
165 temperature at the downstream and upstream from a line heater would be equal to one ($v_1 = v_2$ in equation
166 2). However, this is not always the case with field measurements due to misalignment of the probe or
167 heterogeneous wood properties (Fig. 1A). Burgess et al. (2001) showed how probe placement can be
168 estimated *in situ* with the HRM. He proposed a methodology for probe misalignment which builds on the
169 assumption that errors arising from inaccurate probe spacing can be treated one-dimensionally. His
170 approach assumed that the total effect of probe misalignment (in both axis directions), observed in the ratio
171 of the increase of temperature, can be parameterised calculating an “effective” probe misalignment in only
172 one direction (x direction, parallel to the xylem). Thus, without the assumption of “perfect symmetry”, in
173 periods when $V = 0 \text{ cm h}^{-1}$ equation 1 takes a more simplified form:

174

$$175 \quad 4Kt \ln\left(\frac{v_1}{v_2}\right) = (x_2^2 + y_2^2) - (x_1^2 + y_1^2) \quad [3]$$

176

177 Which becomes equation (4) if $y_1 = -y_2$

178

$$179 \quad 4Kt \ln\left(\frac{v_1}{v_2}\right) = x_2^2 - x_1^2 \quad [4]$$

180

181 As it is unknown if the misalignment is in x_1 or in x_2 , the calculation is repeated twice, assuming first that
182 x_1 is correct when calculating actual x_2 placement and vice versa. Two different heat pulse velocities, V_1
183 and V_2 , are then derived (using equation 1 but with the assumption $y_1 = -y_2$) for both misalignments x_1 and
184 x_2 obtained; and the final V provided as their average.

185

186 Zero sap flow conditions can either be imposed artificially by severing the root or stem (Burgess et al.,
187 2001), or assumed when atmospheric vapour pressure deficit (VPD) is close to zero, the soil is saturated,
188 usually after substantial precipitation, and values taken at predawn to avoid any biophysical driving force
189 (Forster 2017). Saturated soil is a necessary criterion due to the possibility of reverse flow at night-time. If
190 not considered, low HPR values representing reverse flows can be interpreted as zero flow. The latter
191 approach allows the parameterisation of misalignment as a function of time (equation 5), if several
192 calculations of x_1 and x_2 (equation 4) are performed. By applying equation 4 at varies times throughout the
193 measurement period, it is possible to calculate a linear regression using the estimation of Burgess et al.
194 (2001) for misalignment for each of the thermocouples:



195

196

$$x_i = m_i d + n_i \quad ; \quad i = 1, 2 \quad [5]$$

197

198 where x_i are the relative positions of the thermocouples to the line heater in cm, d is the time along the
199 measuring campaign in days, m_i is the slope of the regression for thermocouple i , and n_i is the interception
200 coefficient.

201

202 By introducing equation 5 in equation 1 and allowing the simplification assuming $y_1 = -y_2$, two equations
203 of the corrected heat pulse velocities are obtained as a function of the time in the measuring campaign
204 (equation 6).

205

206

$$V_1 = \frac{4Kt \ln\left(\frac{v_1}{v_2}\right) + (m_1 d + n_1)^2 - 0.6^2}{2t(m_1 d + n_1 + 0.6)} \quad [6]$$

207

$$V_2 = \frac{4Kt \ln\left(\frac{v_1}{v_2}\right) + 0.6^2 - (m_2 d + n_2)^2}{2t(0.6 - m_2 d - n_2)}$$

208

209 In accordance to what Burgess et al. (2001) proposes, our approach averages the two estimates obtained
210 from equation 6 to obtain a corrected heat pulse velocity.

211

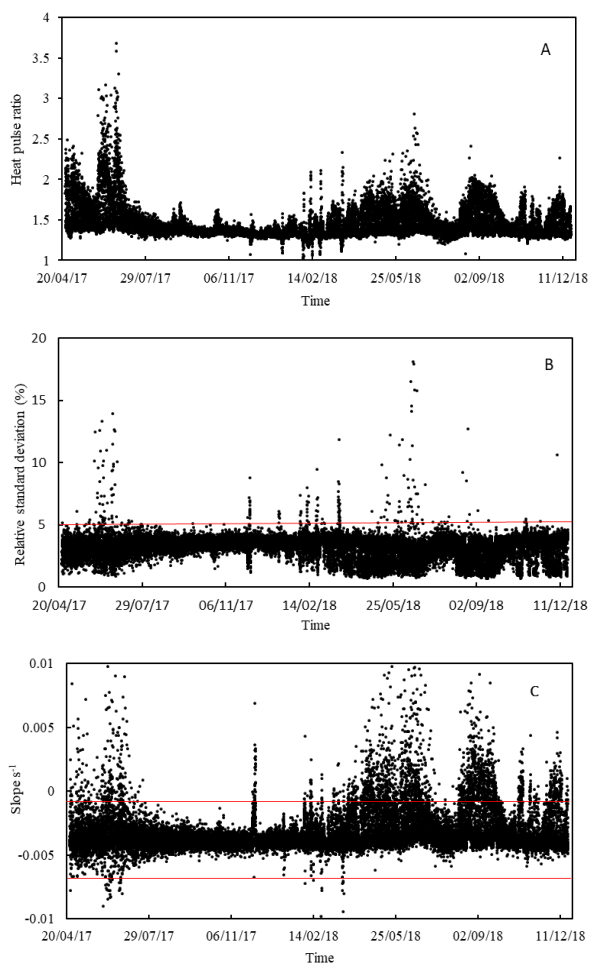
212 3 Results

213 3.1 Heat pulse ratios

214

215 The HPR obtained during the measurement period displays a clear positive shift away from the theoretical
216 ideal where the HPR would equal one at zero flow (Fig. 1A). This gives an indication of the necessity of
217 corrections, that being due to wound inflicted by the probe, misalignment, misestimation of thermal
218 diffusivity-or stem water content. However, the HPR data by itself does not give an indication of the
219 quality of each measurement, nor if it deteriorates over time. Therefore, the quality of the measurements
220 was indicated by calculating the RSD and slope for each HPR (Fig. 1B and 1C). All HPR with RSD
221 higher than 5% were eliminated. The data points eliminated corresponded to a 1 % of the total dataset.
222 Because the method is built on the theoretical assertion that the temperature in each of the thermocouples
223 is steady with time, specifically between 60 and 100 seconds after the release of a heat pulse, the slope of
224 the HPR should be close to zero. All HPR with $|\text{slope} - \text{median}(\text{slope})| < 0.003 \text{ s}^{-1}$ were eliminated,
225 which corresponded to a 12 % of the original dataset (Fig. 1C).

226



227 Figure 1. (A) Heat pulse ratios (HPR) throughout the measurement period in 30-minute intervals in tree number 1. Each
228 HPR is an average of 41 instantaneous ratios corresponding to the temperature difference in two thermocouples at 0.6
229 cm up and down stream from a heater probe. (B) Relative standard deviation (%) for each HPR in tree number 1 for
230 the whole measurement period. Red line indicates threshold used for the quality control were all HPR relative standard
231 deviation > 5% were removed from the data analysis. (C) Slope (s^{-1}) for each HPR in tree number 1 for the whole
232 measurement period. Red line indicates threshold used for the quality control for this particular sensor. HPR with
233 $|\text{slope} - \text{median}(\text{slope})| < 0.003 s^{-1}$ were removed from the data analysis.

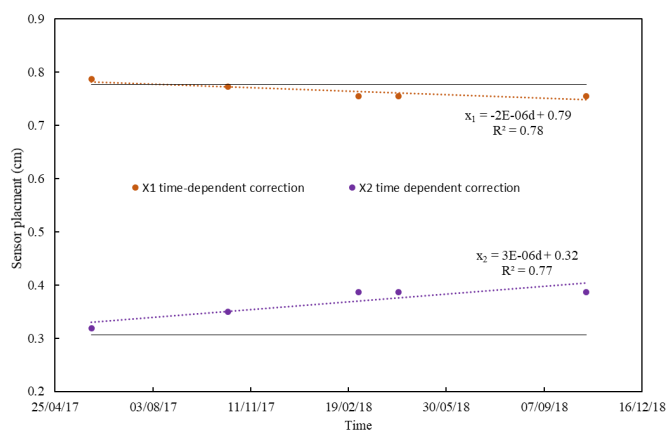
234
235

3.2 Heat pulse velocities

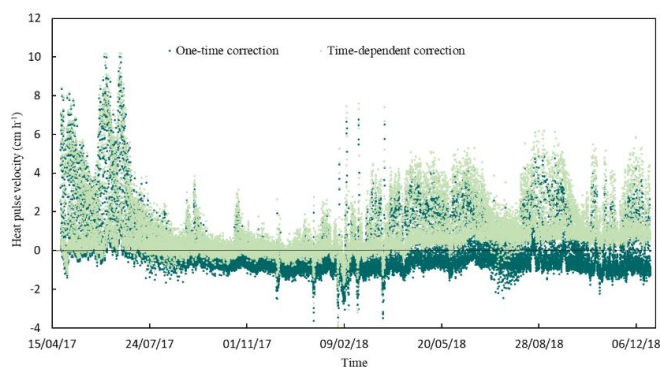
236 A linear regression was obtained from misalignment calculations for each sensor performed during zero-
237 flow conditions. Because of the dry climate, only five events fulfilled these criteria (field capacity, low
238 VPD, predawn), during the measurement period of 20 months. The outputs indicate a clear shift of
239 placement in each of the sensors over time, here denoted as x_1 and x_2 in the case of tree number 1, with a
240 greater shift in x_2 than x_1 (Fig. 2). On average, the eight sensors (two per tree) showed a shift of 0.04 cm
241 in placement after twenty months of measurement. The equation obtained from the linear regression was
242 then implemented in equation 6, and corrections to the heat pulse velocity data was done using an average



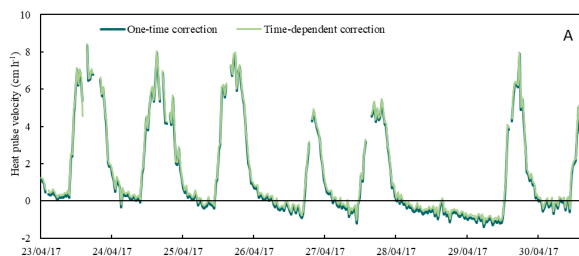
243 of V_1 and V_2 (Fig. 3,4). Outputs were compared with one-time misalignment correction calculated in the
 244 beginning of the measurement period to demonstrate the evolution of the probe misalignment. The one-
 245 time correction demonstrated a steady decline in accuracy over time (Fig. 3, 4). The difference between
 246 the two correction methods showed significance after three months of employment (Fig. 3).

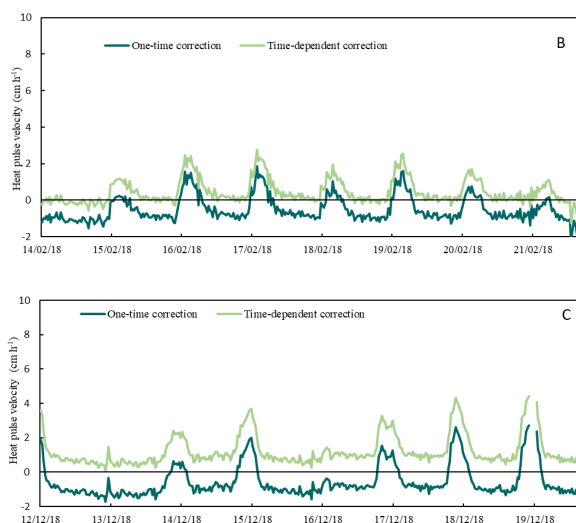


247
 248 Figure 2. Sensor misalignment positions calculated once (solid lines) compared to probe misplacement over time in
 249 (solid circles with dotted lines). Each point represents the probe misalignment position calculated during its respective
 250 zero flow event.



251
 252 Figure 3. Heat pulse velocities for tree number 1 throughout the measurement period. Dark green represents velocities
 253 with only one-time misalignment correction applied at the beginning of the campaign. Light green represents velocities
 254 with time- dependent probe misalignment corrections. Each circle represents a measurements every 30 minutes.
 255





256 Figure 4. Heat pulse velocities during one week of measurements in the beginning (A), halfway (B) and at the end
 257 (C) of the measurement period. Dark green lines represent velocities with probe misalignment corrected for once at
 258 the beginning of the experiment. Light green lines represent velocities with the time- dependent probe misalignment
 259 corrections.

260
 261 **3.3 Sap velocities**

262 Heat pulse velocities (both corrections) were converted into sap velocities according to Burgess et al.
 263 (2001). Our data demonstrated that by not correcting for changes in probe misalignment under continuous
 264 measurement for more than 3 months, the errors corresponded to an averaged difference of 0.29 cm h^{-1} in
 265 sap velocity per quartile for the four trees. At the end of the 20-months period, this corresponded to an
 266 averaged difference of 0.53 cm h^{-1} (Table 1, Fig. 5) In terms of transpiration values, this corresponded to a
 267 mean difference of $0.7 \text{ L tree}^{-1} \text{ day}^{-1}$ (sapwood area = 170 cm^2), which would correspond to a difference of
 268 $542 \text{ L ha}^{-1} \text{ day}^{-1}$ (775 tree ha^{-1}) assuming 8 hours of daylight. It is relevant to note our conversion did not
 269 consider the differences in stem moisture content, which can also affect the output values (Vandegheuchte
 270 and Steppe, 2013). The outputs obtained should be considered as relative differences as the one-time
 271 correction was applied in the beginning of the experiment.

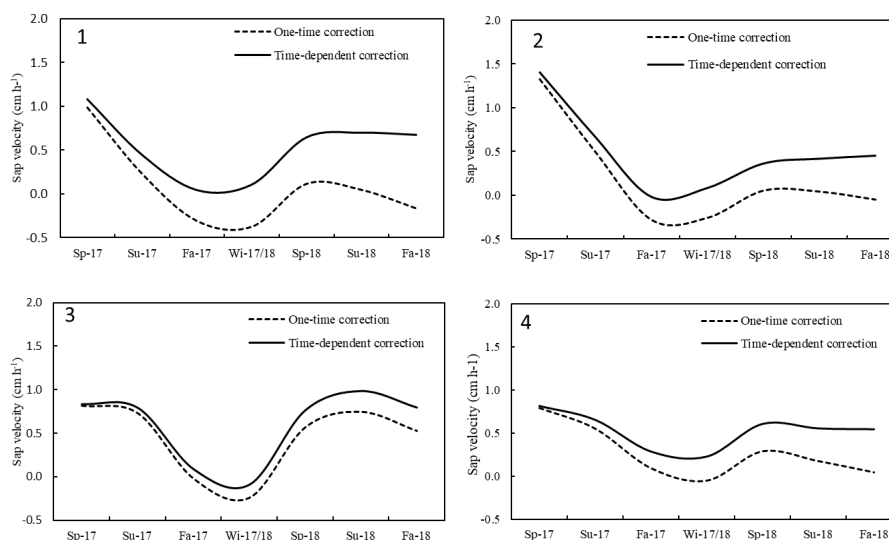
272
 273 Table 1. Seasonal averages of sap velocity for 4 different trees. All sap velocities are expressed in cm h^{-1} . Sap velocities
 274 corrected for with time-dependent misalignment calculations are compared with sap velocities corrected for once in the
 275 beginning of the measurement period. Averages were taken from daily values. Abbreviations Sp, Su, Fa, and Wi
 276 indicates Spring, Summer, Fall and Winter respectively, each with the corresponding year.

Pine number	Correction method	Sp-17	Su-17	Fa-17	Wi-17/18	Sp-18	Su-18	Fa-18
1	One-time correction	0.98	0.23	-0.31	-0.37	0.12	0.05	-0.16
	Time-dependent correction	1.08	0.44	0.04	0.10	0.64	0.70	0.67
2	One-time correction	1.33	0.49	-0.28	-0.25	0.06	0.04	-0.05
	Time-dependent correction	1.40	0.66	-0.02	0.09	0.36	0.42	0.45
	One-time correction	0.82	0.73	-0.02	-0.24	0.57	0.75	0.53



3	Time-dependent correction	0.84	0.79	0.09	-0.09	0.76	0.99	0.80
	One-time correction	0.79	0.55	0.09	-0.05	0.29	0.18	0.05
4	Time-dependent correction	0.82	0.66	0.29	0.23	0.61	0.56	0.55

277



278 Figure 5. Seasonal averages of sap velocities (cm h^{-1}) calculated using the two misalignment corrections throughout
 279 the 20-month measurement period. Dotted lines represent probe misalignment corrected for once. Solid lines represent
 280 sap velocity corrected for with the time-dependent probe misalignment method. Abbreviations Sp, Su, Fa and Wi
 281 indicates Spring, Summer, Fall and Winter respectively, each with the corresponding year. 1, 2, 3, 4 corresponds to
 282 different trees.

283

284 4 Discussion

285

286 4.1 Filtration of heat pulse ratios

287 Because the HPR is an average of instantaneous ratios it is difficult to ensure its accuracy only by visual
 288 inspection of the averaged output, and without further statistical information. We suggest RSD and slope
 289 to filter out random ratios, and to ensure the quality of the data. A clear tendency was seen of higher RSD
 290 and slope values during periods of higher flow rates when compared to the HPR data (Fig. 1A, 1B and
 291 1C), indicating more noise and less trustworthy data during higher flow rates. The HRM is known for
 292 being limited at higher rates ($> 45 \text{ cm h}^{-1}$, Forster, 2017), but our dataset showed no sap velocity values
 293 higher than 6 cm h^{-1} , and therefore was not initially considered as a limitation.

294

295 During twenty months of field measurements the thermocouples showed no visible sign of deterioration
 296 with time. However, it is still important to note that this does not consider the possible diminishing
 297 amplitude of the ratios over time, which can also lead to underestimations of actual flow (Barett et al.,



298 1995; Green et al., 2003; Forster, 2017). Therefore, this should be observed separately, comparing sap
299 flow ratios using data obtained under similar climatic conditions (Moore et al., 2010).

300

301 **4.2 Long term variation in probe placement**

302 When applying the HRM for longer than a few weeks it is relevant to quantify how ϕ in equation (2) and
303 the misalignment term in equation (4) evolve during the measuring period. The predicted variation of x_1
304 and x_2 is due to the growth of the tree and, on the other hand, periodical variations of K due to annual and
305 seasonal variations of the physiological properties of the tree (Green et al., 2003; Vandegehuchte and
306 Steppe, 2012; Ren et al., 2017). In the HRM the probe misalignment calculations can be corrected using
307 the methodology proposed here, considering that as an average, each sensor displayed a 0.04 cm
308 displacement within the tree after twenty months of measurements. The correction would also be more
309 rigorous with more assumed zero flow events which would be easier to obtain in humid environments.

310

311 By going back to the original assumption of “perfect symmetry” we investigated the original premises the
312 method is built on. Even though Burgess et al. (2001) elaborated a correction method for sensor
313 misalignment we saw that changes in sensor misplacement was detectable after each season. Therefore,
314 multiple corrections should be carried out throughout the measurement period. The proposed modified
315 method coincides with the one-time correction method (Burgess et al., 2001) for short time periods (< 3
316 months) but differs progressively over time. We found that this shift in placement is significant already
317 after 3 months, and therefore dynamically misplacement calculations should be carried out or sensors
318 should be reinstalled at this frequency.

319

320 **5 Conclusion**

321 Continuous measurements for 20 months in *Pinus halepensis* under semi-arid Mediterranean conditions
322 confirmed the theory of steady temperature difference between the sensors with time (60- 100 s) for 87
323 % of the obtained values (every 30 min over 20 months), when using 5 % relative standard deviation and
324 $|\text{slope} - \text{median}(\text{slope})| < 0.003 \text{ s}^{-1}$ as quality filter. High quality long-term measurements can be obtained
325 with sap flow sensors if proper data filtering is carried out and the time-dependent misalignment
326 technique applied. Long-term measurements can therefore be performed without reinstallation of the
327 sensors to obtain a continuous dataset, if the species allows for the sensor to be removed again after long-
328 term implementation. In conclusion, the HRM method can be used in long-term studies if probe
329 misplacement is corrected for at varies stages throughout the measurement period when exceeding 3
330 months of sampling.

331

332 **Author contributions**

333 JLP and EC conceptualized the study. EKL made the sensors with the supervision of JB. EKL
334 implemented the sensors and had the responsibility of the data processing and field site. JLP, EKL and
335 JAV all worked on the data analysis. JAV wrote the script for the datalogger and had the technical
336 responsibility. EKL and JLP prepared the manuscript with inputs from all the co-authors. JLP and JAV
337 designed the flow chart to be programmed in any data logger system.

338

339 The authors declare that they have no conflict of interest



340

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350 **References**

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