

## Response to comments from the Referee 2:

### Report #1

#### Anonymous Referee #2

**In my previous comments on the manuscript I mainly remarked on the lack of explanations in the manuscript and the lack of documentation in the MATLAB code. I am satisfied with the changes made by the authors to the manuscript during the revision. The technical note is substantially easier to read now, and I recommend publication. The changes made to the MATLAB script and documentation are also very helpful for an improved understanding.**

R: We are very thankful to the Referee's useful remarks, which greatly helped to improve our Technical Note. We followed his/her final suggestions throughout the document.

**In the following are a few minor details that need improvement in the manuscript before publication:**

**Section 2: “Let C, represents the set of sources” – should be “let C represent the set of sources” instead.**

R: This has been corrected to “let C represent the set of sources”

**“where  $f_A, f_B, f_C$  and  $f_D$  represent the contribution fraction of sources A, B, C and D respectively to the mixture M and Eq. (1) has solution for  $f_A, f_B, f_C, f_D > 0$ , they take the following form” – this sentence should be split in two, otherwise it is unclear and grammatically incorrect.**

R: We have edited the paragraph to clarify this point. It now reads: “[...] and  $z$  to the set of A, M and C. Furthermore,  $f_A, f_B, f_C$  and  $f_D$  represent the contribution fraction of sources A, B, C and D respectively to the mixture M.

If the system is composed of Eq. (1)

$$\begin{cases} \bar{\delta}_A f_A + \bar{\delta}_B f_B + \bar{\delta}_C f_C + \bar{\delta}_D f_D = \bar{\delta}_M \\ \bar{\lambda}_A f_A + \bar{\lambda}_B f_B + \bar{\lambda}_C f_C + \bar{\lambda}_D f_D = \bar{\lambda}_M \\ \bar{\phi}_A f_A + \bar{\phi}_B f_B + \bar{\phi}_C f_C + \bar{\phi}_D f_D = \bar{\phi}_M \\ f_A + f_B + f_C + f_D = 1 \end{cases} \quad \text{Eq.(1)}$$

and has solution<sup>1</sup> for  $f_A, f_B, f_C, f_D > 0$ , the contribution fractions take the following form:

**4 “our methodology developed” – should be “our methodology was developed”**

R: This has been corrected to “Our methodology was developed”.

**Response to comments from the Referee 1:**

**Report #2**

**Anonymous Referee #1**

**Major comment:**

**- I understand the decision of the authors to present this work in the format of a technical note. Yet, their statements along the manuscript should be aligned to the proposed method and the presented analyses only. Thus, even when I agree that their methods is very valuable for the proposed purpose, a formal evaluation of the robustness of the method in comparison to other methodologies is not presented. In the new version of the manuscript the authors claim the robustness of their method based on the analysis of the effect of different data inputs on the resulting source uncertainties (P.10 , L.172-174). However, this analysis does not provide more information than the sensitivity of the estimated uncertainties to input data with different conditions. Thus, I strongly suggest the authors to avoid any misleading conclusion about the supposed robustness of their method throughout the manuscript, particularly in section 4 and P.2, L.53.**

We acknowledge the Referee's comment, which helped us to follow a more precise line. In fact, in this Technical Note, no comparative analysis with other methodologies has been performed and therefore we have carefully reviewed the entire document, to avoid the misinterpretation of the word robust. Besides, we focus on a better description of the methodological development and application examples.

**Minor comments:**

**P.1,L.12-13: This sentence is still difficult to understand. Do you mean “However, the source contributions may be uncertain and to date only Bayesian approaches to estimate the uncertainty of two and three sources exist.” Or something along those lines. Revise sentence for clarity.**

R: We have edited the phrase to clarify this point. It now reads: “[...] the source contributions may be uncertain and apart from Bayesian approaches, to date there are only solid methods to estimate such uncertainties for two and three sources”.

**P1,L13: replace “expand this methods developing an” by “introduce an alternative”.**

R: This has been modified for “introduce an alternative”.

**P1,L16: delete “particularly”.**

R: The word “particularly” has been deleted.

**P1,L18: delete “were used”**

R: The words “were used” have been deleted.

**P2,L30-31: Avoid double parenthesis.**

R: Done

**P2,L33: “tracer mass balance”**

R: The word “tracer” has been included.

**P2,L34: sources and dynamics of what? Specify for clarity.**

R: We have edited the phrase to clarify this point. It now reads: “[...] mixing models based on tracer mass balance equations are widely-applied to identify the dominant sources of a mixture and their contribution dynamics”.

**P2,L39: “mixing space”**

R: The word “mixing” has been included.

**P2,L47: “and their individual uncertainty”**

R: This has been modified for “and their individual uncertainty”.

**P2,L53: replace “a novel and robust” by “an alternative”**

R: This has been corrected to “an alternative”.

**P2,L54: perhaps good to give examples of what sources and mixture refer to. For instance “end members or sources (e.g., precipitation, soil water, snowmelt) to a mixture (e.g., streamflow)”**

R: We have included this suggestion.

**P2,L55-60: These 2 long sentences could be split at least into 4-5 shorter ones to make it easier to read. Also, I think that mentioning the “application of a final equation” is not the best way to mention that the methodology has already been applied without a formal description of the method. Please re-phrase for clarity.**

R: We have split the sentences and reworded the paragraph for clarity. It now reads:

“We illustrate this application using a multi-tracer data set from Correa et al. (2019b), in a three-dimensional space defined by a Principal Component Analysis. In Correa et al. (2019b), the authors calculated the uncertainties but without disclosing any details in the calculation and methodology used. The main objective of this Technical Note is therefore to explicitly describe the mathematical development that allows the calculation of partial derivatives, degrees of freedom and confidence interval limits for each source fraction contribution. Moreover, to provide the code and several examples for their calculation and reproducibility”.

**P2,L58: Noting was mentioned about the method in the rest of the introduction, so this sentence comes as a complete surprise. I suggest mentioning something about the proposed Taylor series approximation around P1,L54 so here you relate it directly to “the calculation of partial derivatives, degrees of freedom and confidence interval limits”.**

R: We have reworded the paragraphs for clarity. It now reads:

Around P1,L54 “[...] we propose an alternative methodology based on the first-order Taylor series approximation to estimate the uncertainty [...]”.

Around P1,L58 “[...] allows the calculation of partial derivatives, degrees of freedom and confidence interval limits for each source fraction contribution [...]”.

**P3,L62-70: It would be helpful to specify if each of the variables correspond to vectors and matrices and what is the specific data related to these variables.**

R: We have included what data are necessary for the analysis related to the sources and the mixture and indicated that further details are presented in section 3.2. The way to use the data (as matrix) in the script is detailed in section 3.3, where the practical exercises are applied.

The paragraph now reads:

“The data required for this analysis are the median and standard deviations ( $\sigma$ ) of each of the sources (A, B, C and D) and the mixture M, projected and expressed in the coordinates of the three-dimensional PCA space. In addition, the sample size (n) of each source is required. Details of the application are presented in section 3.2.”

**P3,L69-70: unclear, please split into 2 sentences for clarity. Also, I do not see the need to use a footnote. Foot note 1 could easily be included in this short paragraph.**

R: We have edited the paragraph to clarify this point. It now reads: “[...] and  $z$  to the set of A, M and C. Furthermore,  $f_A, f_B, f_C$  and  $f_D$  represent the contribution fraction of sources A, B, C and D respectively to the mixture M.

If the system is composed of Eq. (1)

$$\begin{cases} \bar{\delta}_A f_A + \bar{\delta}_B f_B + \bar{\delta}_C f_C + \bar{\delta}_D f_D = \bar{\delta}_M \\ \bar{\lambda}_A f_A + \bar{\lambda}_B f_B + \bar{\lambda}_C f_C + \bar{\lambda}_D f_D = \bar{\lambda}_M \\ \bar{\phi}_A f_A + \bar{\phi}_B f_B + \bar{\phi}_C f_C + \bar{\phi}_D f_D = \bar{\phi}_M \\ f_A + f_B + f_C + f_D = 1 \end{cases} \quad \text{Eq.(1)}$$

and has solution<sup>1</sup> for  $f_A, f_B, f_C, f_D > 0$ , the contribution fractions take the following form:

However, we preferred to keep the footnote to avoid including a new equation and further complicating this section.

**P5,L76: add symbol of variance**

R: The symbol of variance ( $\sigma^2$ ) has been included.

**P5,L76: define cA**

The definition of “cA” has been included. It now reads: “[...] where  $c_A$  is a scale constant that relates  $f_{Ay_x}$  with the respective derivative. It means that  $f_A$  with respect to  $y_x$  can be a scalar multiple of the derivative value.

**P5,Eq. 11: define n**

R: It was previously defined in the line 73

**P6,L85: crossreference Eq6**

R: We have cross-referenced, however the correct equation is Eq.(10).

**P7,L99: the IUSS reference is the general classification of soils, not the proportions of each of them at your study site as stated. Suggest deleting this reference and use one specific for the study area.**

R: We have updated the reference to: (Quichimbo et al., 2012)

**P7,L107-108: suggest moving these results from the cited references to L.115, so it is clear what the end members of the system are and easier to relate them to the rest of this section.**

R: We have updated this section as suggested. It now reads: “[...] data from waters sources RF, AN, HS and SW, were projected into a three-dimensional space (Correa et al., 2019b) and presented in Figure 1 and Table 1”.

**P7,L120-124 & P8,L125: This is basically a repetition of the methods section. Why not simply mention that A,B,C, and D now are represented by end member RF,AN,HS, and SW in the corresponding equations to shorten the text?**

R: We agree, we have eliminated this redundant paragraph and highlighted the correspondence between the end-members used in the example and the terminology in the equations.

**P8,L125: Suggest to keep using the same notation than in the methods across the whole manuscript (i.e., A,B,C,D instead of EM1,E2,EM3,EM4). After all, that is the same notation used in tables 1-4. However, whatever your decision, everything needs to be consistent, i.e., correct in tables 5-8.**

R: Yes, we agree, we have maintained consistency using A,B,C and D throughout the document.

**P8,L127-128: “U1, U2 and U3 represent the principal components PC1,PC2 AND PC3, respectively”**

R: This section has been updated. It now reads: “[...] U1, U2 and U3 represent the principal components PC1,PC2 AND PC3, respectively”

**P9,L129: “... procedure was applied to all...”**

R: This has been modified for “A similar procedure was applied to all end-members”.

**P9,L140-155: perhaps would be best to include this description using an additional section to the paper eg.: 3. Sensitivity of source uncertainty to input data. Then, a subsection with the same suggested name could be added to section 3. Application to describe the results of this analysis. For now, this part appears as a surprise to the reader.**

R: We greatly appreciate this comment, we agree that the creation of a new section (3.3) will facilitate the readability of the document.

**P9,L143-144: delete, repeated in the next sentence.**

R: The paragraph has been deleted.

**P9,L145: report how the 50% of data in set 1 was selected.**

R: The data set was divided in chronological order of sample collection, the samples gathered in the first half of the monitoring period (50%) were considered for example 1 and the remainder (50%) for example 2.

The reason was reported, and it now reads: “The first example considers 50% of the samples (collected in the first half of the monitoring period) from each source”.

**P9,L148: the second “example”**

R: The word “example” has been included.

**P9,L160-162: rewrite sentence for clarity.**

R: We have edited the paragraph to clarify this point. It now reads: “These variations were reflected in the widening (1% to 12%) of uncertainty bands for all existing cases (Table 7) in comparison with those calculated from the original data set (Table 5)”.

**P10,L172: delete “been” and consider my major comment with regards to the “robustness” of the method.**

R: The word “example” has been deleted and your major comment fully considered.

**P10,L79: “... a larger number of source contributions (>3) and the...”**

R: This has been modified for “a larger number of source contributions (>3) and the”.

**Tables 5-8: to keep consistency throughout the manuscript I suggest you use the notation A,B,C,D instead of the EMx notation.**

R: Yes, we agree, we have maintained consistency using A,B,C and D throughout the document.

# Technical note: Uncertainty in multi-source partitioning using large tracer data sets

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## 10 Abstract

The availability of large tracer data sets opened up the opportunity to investigate multiple source contributions to a mixture. However, the source contributions may be uncertain and apart from Bayesian approaches, to date there are only solid methods to estimate such uncertainties ~~to estimate such source uncertainty only exist sound methods~~ for two and three sources. We introduce an alternative ~~expand these methods developing an~~ uncertainty estimation method for four sources based on multiple tracers as input data. Taylor series approximation is used to solve the set of linear mass balance equations. We illustrate the method to compute individual uncertainties in the calculation of source contributions to a mixture, ~~particularly~~ with an example from hydrology, ~~where using~~ a 14-tracer set from water sources and streamflow from a tropical, high-elevation catchment ~~were used~~. Moreover, this method has the potential to be generalized to any number of tracers across a range of disciplines.

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## 1. Introduction

Tracer applications have dramatically increased over recent years across a wide range of disciplines (West et al., 2010). Applications in hydrology (Hooper, 2003; James and Roulet, 2006; Kirchner and Neal, 2013), ecology (Phillips and Gregg, 2003; Semmens et al., 2009b), anthropology (Ehleringer et al., 2008), conservation biology (Bicknell et al., 2014), nutrition (Magaña-Gallegos et al., 2018), environmental and ecosystem science (Bartov et al., 2013; Granek et al., 2009), and erosion and sediment transportation (Davies et al., 2018) have been the most prominent. Such a widespread use of tracers was mainly facilitated by the availability of analytical techniques that provide high sensitive, rapid multi-element analysis at lower cost (Falkner et al., 1995). For example, the use of inductively coupled plasma mass spectrometry (ICP-MS) as one of the leading analytical techniques for elemental analysis (Helaluddin et al., 2016), led to the availability and use of large tracers sets (elements) in hydrological studies (Barthold et al., 2017; Belli et al., 2017; Correa et al., 2017; Kirchner and Neal, 2013; Mimba et al., 2017). Trace elements together with water stable isotopes (Cavity Ringdown Laser Absorption Spectroscopy paved the way: (Berman et al., 2009; Lis et al., 2008)) as well as physical-chemical water parameters (e.g. electrical conductivity and pH) are now often used to improve understanding of hydro-geochemical cycles, flow pathways and runoff generation in hydrology. Furthermore, mixing models based on tracer mass balance equations are widely-applied to identify the dominant sources of a mixture and their- contribution dynamics. dynamics-as components-of-a-mixture.

In hydrological mixing models the composition of the stream is assumed to be an integrated mixture of signatures of different sources (Christophersen et al., 1990). The proportional contributions of  $n+1$  sources to the stream can be uniquely determined using  $n$  different tracers (Christophersen & Hooper, 1992). Bayesian methods have been developed to identify multiple ( $> 3$ ) sources and compute their contributions to a mixture in a two-dimensional mixing space (Parnell et al., 2010; Stock et al., 2018). In this case a unique solution is not feasible and a higher uncertainty is attributed to the model (Phillips and Gregg, 2001, 2003). On the other hand, End Member Mixing Analysis (EMMA) (Hooper, 2003) was developed to use multiple tracers as input, and therefore, allows for a multi-dimensional space that potentially increases the number of identifiable sources (Barthold et al., 2011; Inamdar et al., 2013; Liu et al., 2004). Additionally, the use of multiple tracers can avoid bias and subjectivity in the input information. Therefore, EMMA provides a robust and complete conceptualization of catchment functioning and source interactions during runoff generation (Iwasaki et al., 2015). However, despite its benefits, the EMMA approach lacks a formal methodology to assess the uncertainty of multiple end-members (Delsman et al., 2013) and ~~to assess their~~ individual uncertainties in the calculation of source contributions to a stream.

To our knowledge, the uncertainty estimation of source contributions to streams is based on Gaussian error propagation (Genereux, 1998) and was so far only calculated using one or two tracers simultaneously (MixSIAR: Parnell et al., 2010; Phillips & Gregg, 2001; Semmens, Moore, et al., 2009). Alternatively, when the number of sources is higher, the uncertainty is usually based on the sum of analytical errors, elevation effects and the spatial variability of end-member concentrations (Uhlenbrook and Hoeg, 2003). Hence, we propose an alternative novel and robust methodology based on the first-order Taylor series approximation to estimate the uncertainty of individual end-member or sources (e.g., precipitation, soil water, groundwater) to a mixture (e.g., streamflow). ~~(source) contributions to streams (mixture) based on a multi-tracer set in a three-dimensional space defined by a Principal Component Analysis.~~

60 We illustrate this application using a multi-tracer data set from Correa et al. (2019b), in a three-dimensional space  
defined by a Principal Component Analysis (PCA). In Correa et al. (2019b), ~~where~~ the authors calculated the  
 uncertainties ~~only based on the application of a final equation but~~ without disclosing any details in the calculation  
 and methodology used. ~~The main objective of this Technical Note is therefore~~ The main objective of this Technical  
Note is therefore to explicitly describe the mathematical development ~~in all detail~~ that allows the calculation of  
 65 partial derivatives, degrees of freedom and confidence interval limits for each source fraction contribution. ~~as well~~  
~~as to~~ Moreover, to provide the code and several examples ~~data~~ for their calculation and reproducibility.

## 2. Uncertainty estimation method development

In this section, the uncertainty estimation method presented in Phillips and Gregg, (2001) is expanded for four  
 source contributions to the mixture.

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Let  $\mathcal{C}_s$  represents the set of sources: A, B, C and D, and mixture M,  $\mathcal{C} = \{A, B, C, D, M\}$ . In the following equations,  
 $x \in \mathcal{C}$ ,  $y \in \{\bar{\delta}, \bar{\lambda}, \bar{\phi}\}$  and  $z \in \{A, M, C\}$ .  $x$ ,  $y$  and  $z$  are variables that belong to the sets:  $x$  to the set of A, B, C, D and  
 mixture M,  $y$  to the set of medians of every projected source and mixture in each principal component  $\bar{\delta}, \bar{\lambda}, \bar{\phi}$   
 respectively of the used sub index and  $z$  to the set of A, M and C. Furthermore, where  $f_A, f_B, f_C$  and  $f_D$  represent  
 75 the contribution fraction of sources A, B, C and D respectively to the mixture M.

The data required for this analysis are the median and standard deviations ( $\sigma$ ) of each of the sources (A, B, C and  
D) and the mixture M, projected and expressed in the coordinates of the three-dimensional PCA space. In addition,  
the sample size ( $n$ ) of each source is required. Details of the application are presented in section 3.2.

80 If the system is composed of Eq. (1)

$$\begin{cases} \bar{\delta}_A f_A + \bar{\delta}_B f_B + \bar{\delta}_C f_C + \bar{\delta}_D f_D = \bar{\delta}_M \\ \bar{\lambda}_A f_A + \bar{\lambda}_B f_B + \bar{\lambda}_C f_C + \bar{\lambda}_D f_D = \bar{\lambda}_M \\ \bar{\phi}_A f_A + \bar{\phi}_B f_B + \bar{\phi}_C f_C + \bar{\phi}_D f_D = \bar{\phi}_M \\ f_A + f_B + f_C + f_D = 1 \end{cases} \quad \text{Eq.(1)}$$

~~where  $f_A, f_B, f_C$  and  $f_D$  represent the contribution fraction of sources A, B, C and D respectively to the mixture M~~  
 and ~~Eq. (1)~~ has solution<sup>1</sup> for  $f_A, f_B, f_C, f_D > 0$ , the contribution fractions ~~they~~ take the following form:

<sup>1</sup> The system has a solution if the vector of mixture M is on the polyhedron generated by the vectors of sources A, B, C, D such that  $\sum_x f_x = 1$ .

$$\begin{aligned}
f_A &= \frac{(\Phi_M - \Delta_M)(\Lambda_C - \Delta_C) - (\Lambda_M - \Delta_M)(\Phi_C - \Delta_C)}{(\Phi_A - \Delta_A)(\Lambda_C - \Delta_C) - (\Lambda_A - \Delta_A)(\Phi_C - \Delta_C)} = \frac{Num}{Den} \\
f_C &= \frac{(\Delta_M - \Lambda_M) - (\Delta_A - \Lambda_A)f_A}{(\Delta_C - \Lambda_C)} \\
f_B &= \Delta_M - (\Delta_C f_C + \Delta_A f_A) \\
f_D &= 1 - (f_C + f_B + f_A)
\end{aligned} \tag{Eq.2}$$

where

$$\Delta_x = \frac{\bar{\delta}_x - \bar{\delta}_D}{\bar{\delta}_B - \bar{\delta}_D}, \Lambda_x = \frac{\bar{\lambda}_x - \bar{\lambda}_D}{\bar{\lambda}_B - \bar{\lambda}_D}, \Phi_x = \frac{\bar{\phi}_x - \bar{\phi}_D}{\bar{\phi}_B - \bar{\phi}_D}. \tag{Eq.3}$$

The partial derivatives of Eq. (2) are given by:

$$\begin{aligned}
\frac{\partial f_A}{\partial y_x} &= \frac{1}{Den^2} \left[ (\Lambda_C - \Delta_C) \left( \frac{\partial \Phi_M}{\partial y_x} - \frac{\partial \Delta_M}{\partial y_x} \right) + (\Phi_M - \Delta_M) \left( \frac{\partial \Lambda_C}{\partial y_x} - \frac{\partial \Delta_C}{\partial y_x} \right) \right. \\
&\quad \left. - (\Phi_C - \Delta_C) \left( \frac{\partial \Lambda_M}{\partial y_x} - \frac{\partial \Delta_M}{\partial y_x} \right) - (\Lambda_M - \Delta_M) \left( \frac{\partial \Phi_C}{\partial y_x} - \frac{\partial \Delta_C}{\partial y_x} \right) \right] Den \\
&\quad - \left[ (\Lambda_C - \Delta_C) \left( \frac{\partial \Phi_A}{\partial y_x} - \frac{\partial \Delta_A}{\partial y_x} \right) + (\Phi_A - \Delta_A) \left( \frac{\partial \Lambda_C}{\partial y_x} - \frac{\partial \Delta_C}{\partial y_x} \right) \right. \\
&\quad \left. - (\Phi_C - \Delta_C) \left( \frac{\partial \Lambda_A}{\partial y_x} - \frac{\partial \Delta_A}{\partial y_x} \right) - (\Lambda_A - \Delta_A) \left( \frac{\partial \Phi_C}{\partial y_x} - \frac{\partial \Delta_C}{\partial y_x} \right) \right] Num \Big] \\
\frac{\partial f_C}{\partial y_x} &= \frac{1}{(\Delta_C - \Lambda_C)^2} \left[ \left( \frac{\partial \Delta_M}{\partial y_x} - \frac{\partial \Lambda_M}{\partial y_x} \right) - \left( \frac{\partial \Delta_A}{\partial y_x} - \frac{\partial \Lambda_A}{\partial y_x} \right) f_A - (\Delta_A - \Lambda_A) \frac{\partial f_A}{\partial y_x} \right] (\Delta_C - \Lambda_C) \\
&\quad - \left( \frac{\partial \Delta_C}{\partial y_x} - \frac{\partial \Lambda_C}{\partial y_x} \right) [(\Delta_M - \Lambda_M) - (\Delta_A - \Lambda_A) f_A], \\
\frac{\partial f_B}{\partial y_x} &= \frac{\partial \Delta_M}{\partial y_x} - \frac{\partial \Delta_C}{\partial y_x} f_C - \Delta_C \frac{\partial f_C}{\partial y_x} - \frac{\partial \Delta_A}{\partial y_x} f_A - \Delta_A \frac{\partial f_A}{\partial y_x}, \\
\frac{\partial f_D}{\partial y_x} &= -\frac{\partial f_C}{\partial y_x} - \frac{\partial f_B}{\partial y_x} - \frac{\partial f_A}{\partial y_x}
\end{aligned} \tag{Eq.4}$$

85 It is trivial that

$$\frac{\partial \Delta_z}{\partial w_x} = 0, w \in \{\bar{\lambda}, \bar{\phi}\}; \frac{\partial \Lambda_z}{\partial w_x} = 0, w \in \{\bar{\delta}, \bar{\phi}\}; \frac{\partial \Phi_z}{\partial w_x} = 0, w \in \{\bar{\delta}, \bar{\lambda}\}. \tag{Eq.5}$$

where

$$\frac{\partial \Delta_z}{\partial \bar{\delta}_x} = (\bar{\delta}_B - \bar{\delta}_D)^{-1} \begin{cases} 1 & z \in \{A, C, M\} \text{ and } x = z \\ -\Delta_z & z \neq B \text{ and } x = B \\ \Delta_z - 1 & z \neq D \text{ and } x = D \\ 0 & \text{otherwise} \end{cases}, \tag{Eq.6}$$

$$\frac{\partial \Lambda_z}{\partial \bar{\lambda}_x} = (\bar{\lambda}_B - \bar{\lambda}_D)^{-1} \begin{cases} 1 & z \in \{A, C, M\} \text{ and } x = z \\ -\Lambda_z & z \neq B \text{ and } x = B \\ \Lambda_z - 1 & z \neq D \text{ and } x = D \\ 0 & \text{otherwise} \end{cases} \quad \text{and} \quad \text{Eq.(7)}$$

$$\frac{\partial \Phi_z}{\partial \bar{\phi}_x} = (\bar{\phi}_B - \bar{\phi}_D)^{-1} \begin{cases} 1 & z \in \{A, C, M\} \text{ and } x = z \\ -\Phi_z & z \neq B \text{ and } x = B \\ \Phi_z - 1 & z \neq D \text{ and } x = D \\ 0 & \text{otherwise} \end{cases} \quad \text{Eq.(8)}$$

For example, for  $f_A$  we have

$$\begin{aligned} \frac{\partial f_A}{\partial \bar{\delta}_x} &= \frac{1}{Den^2} \left[ \left[ \frac{\partial \Delta_M}{\partial \bar{\delta}_x} (\Phi_C - \Lambda_C) - \frac{\partial \Delta_C}{\partial \bar{\delta}_x} (\Phi_M - \Lambda_M) \right] Den \right. \\ &\quad \left. - \left[ \frac{\partial \Delta_A}{\partial \bar{\delta}_x} (\Phi_C - \Lambda_C) - \frac{\partial \Delta_C}{\partial \bar{\delta}_x} (\Phi_A - \Lambda_A) \right] Num \right]. \\ \frac{\partial f_A}{\partial \bar{\lambda}_x} &= \frac{1}{Den^2} \left[ \frac{\partial \Lambda_C}{\partial \bar{\lambda}_x} (\Phi_M - \Delta_M) - \frac{\partial \Lambda_M}{\partial \bar{\lambda}_x} (\Phi_C - \Delta_C) \right] Den \\ &\quad - \left[ \frac{\partial \Lambda_C}{\partial \bar{\lambda}_x} (\Phi_A - \Delta_A) - \frac{\partial \Lambda_A}{\partial \bar{\lambda}_x} (\Phi_C - \Delta_C) \right] Num. \\ \frac{\partial f_A}{\partial \bar{\phi}_x} &= \frac{1}{Den^2} \left[ \left[ \frac{\partial \Phi_M}{\partial \bar{\phi}_x} (\Lambda_C - \Delta_C) - \frac{\partial \Phi_C}{\partial \bar{\phi}_x} (\Lambda_M - \Delta_M) \right] Den \right. \\ &\quad \left. - \left[ \frac{\partial \Phi_A}{\partial \bar{\phi}_x} (\Lambda_C - \Delta_C) - \frac{\partial \Phi_C}{\partial \bar{\phi}_x} (\Lambda_A - \Delta_A) \right] Num \right]. \end{aligned} \quad \text{Eq.(9)}$$

Using Eq. (9), the first-order Taylor series approximation (Taylor, 1982) for the variance  $(\sigma^2)$  of  $f_A$  evaluated at the mean can be calculated by:

$$\sigma_{f_A}^2 = \sum_x \left( \frac{\partial f_A}{\partial \bar{\delta}_x} \right)^2 \sigma_{\bar{\delta}_x}^2 + \sum_x \left( \frac{\partial f_A}{\partial \bar{\lambda}_x} \right)^2 \sigma_{\bar{\lambda}_x}^2 + \sum_x \left( \frac{\partial f_A}{\partial \bar{\phi}_x} \right)^2 \sigma_{\bar{\phi}_x}^2 = \sum_y \sum_x \left( \frac{\partial f_A}{\partial y_x} \right)^2 \sigma_{y_x}^2. \quad \text{Eq.(10)}$$

90 To calculate  $\gamma_A$  (the Satterthwaite (1946) approximation for the degrees of freedom), we define  $f_{Ay_x} = c_A \left( \frac{\partial f_A}{\partial y_x} \right)^2$  where  $c_A$  is a scale constant that relates  $f_{Ay_x}$  with the respective derivative. It means that  $f_A$  with respect to  $y_x$  can be a scalar multiple of the derivative value.-

In this case, we get:

$$\gamma_A = \frac{(\sum_y \sum_x f_{Ay_x} \sigma_{y_x}^2)^2}{\sum_y \sum_x \frac{(f_{Ay_x} \sigma_{y_x}^2)^2}{n_{y_x} - 1}} \quad \text{Eq.(11)}$$

Note that whatever the value of  $c_A$  is, Eq. (11) leads to:

$$\gamma_A = \frac{\left( \sum_y \sum_x \left( \frac{\partial f_A}{\partial y_x} \right)^2 \sigma_{y_x}^2 \right)^2}{\sum_y \sum_x \frac{\left( \left( \frac{\partial f_A}{\partial y_x} \right)^2 \sigma_{y_x}^2 \right)^2}{n_{y_x} - 1}}$$

95 and if we set  $f_{Ay_x}^* = \left( \frac{\partial f_A}{\partial y_x} \right)^2$  then the numerator of the last equation can be replaced by  $(\sigma_{f_A}^2)^2$ . In other words, we can use Eq. (10) and the derivatives [Eq. \(9\)](#) to estimate the value of  $\gamma_A$  resulting in  $f_{Ay_x} = c_A f_{Ay_x}^*$ . Of course, it is required that  $c_A$  is constant w.r.t.  $y_x$ . Then,

$$\gamma_A = \frac{(\sigma_{f_A}^2)^2}{\sum_y \sum_x \frac{\left( \left( \frac{\partial f_A}{\partial y_x} \right)^2 \sigma_{y_x}^2 \right)^2}{n_{y_x} - 1}} \quad \text{Eq.(12)}$$

Let  $w \in \mathcal{C} \setminus \{A\}$ . The first-order Taylor series approximation for the variance of  $f_w$ , can be calculated by (as above [Eq.10](#)):

$$\sigma_{f_w}^2 = \sum_x \left( \frac{\partial f_w}{\partial \delta_x} \right)^2 \sigma_{\delta_x}^2 + \sum_x \left( \frac{\partial f_w}{\partial \lambda_x} \right)^2 \sigma_{\lambda_x}^2 + \sum_x \left( \frac{\partial f_w}{\partial \phi_x} \right)^2 \sigma_{\phi_x}^2 = \sum_y \sum_x \left( \frac{\partial f_w}{\partial y_x} \right)^2 \sigma_{y_x}^2. \quad \text{Eq.(13)}$$

100 If we construct  $\gamma_w$  as  $\gamma_A$ , we get:

$$\gamma_w = \frac{\left( \sum_y \sum_x f_{wy_x}^* \sigma_{y_x}^2 \right)^2}{\sum_y \sum_x \frac{(f_{wy_x}^* \sigma_{y_x}^2)^2}{n_{y_x} - 1}}$$

where  $f_{wy_x} = c_w f_{wy_x}^*$  and  $f_{wy_x}^* = \left( \frac{\partial f_w}{\partial y_x} \right)^2$  with  $c_w$  constant w.r.t.  $y_x$ , then we finally get:

$$\gamma_w = \frac{(\sigma_{f_w}^2)^2}{\sum_y \sum_x \frac{\left( \left( \frac{\partial f_w}{\partial y_x} \right)^2 \sigma_{y_x}^2 \right)^2}{n_{y_x} - 1}} \quad \text{Eq.(14)}$$

The upper and lower confidence interval limits for each end-member fraction can be calculated using partial derivatives and the 95% confidence intervals constructed as:

$$f_w \pm t_{0.05, \gamma_w} \sigma_{f_w} \quad \text{Eq.(15)}$$

105 Where  $t_{0.05, \gamma}$  is the Student's t for  $\alpha=0.05$  (two-tailed) (Walpole et al., 2017) and  $\gamma$  degrees of freedom related with  $\sigma_{f_w}$ .

### 3. Application

#### 3.1. Study site and data

This methodology was tested using data from a high elevation (3,500 - 3,900 m a.s.l.) tropical catchment (7.53 km<sup>2</sup>) located in southern Ecuador (3°4'38"S, 79°15'30"O). The mean annual precipitation for this study site is 1,300 mm (Padrón et al., 2015), the mean annual discharge is 860 mm yr<sup>-1</sup>. The catchment is of a volcanic origin and dominated by volcanic Histosol (24%) and Andosol (72%) soils ~~-(Quichimbo et al., 2012)(IUSS Working Group WRB, 2015)~~, both with high percentage of organic matter content (450 and 310 g kg, respectively) (Quichimbo et al., 2012) and large water-holding capacities (Buytaert et al., 2006). Histosols are primarily located at the valleys and covered by cushion plants, while Andosol soils are predominated on the hillslopes under a cover of tussock grass. Nearly-saturated conditions of the riparian zone are observed year-round, and a spring is located in the north-western part of the catchment. Streamwater samples from 5 nested streams were collected weekly from March 2013 to April 2014 (n=257) and at a higher frequency during experimental campaigns. Additionally, bi-weekly water samples from 4 potential end-members: rainfall (RF), soil water from Andosols (AN) and Histosols (HS) and spring water (SW) (n ~ 30, for each end-member) were collected. ~~The above mentioned waters sources (RF, AN, HS and SW), were previously identified as end members (Correa et al., 2017, 2019b) (Table 1).~~ A multi-tracer (14 tracers) data set of conservative tracers was obtained from each water sample (Na, Mg, Al, Si, K, Ca, Rb, Sr, Ba, Ce, V, Y, Nd) at the Institute for Landscape Ecology and Resource Management of the Justus Liebig University using an ICP-MS (Agilent 7500ce, Agilent Technologies) and the electrical conductivity (EC) was measured in situ. More detailed information on the study site and data set can be found in Correa et al., (2017, 2019b).

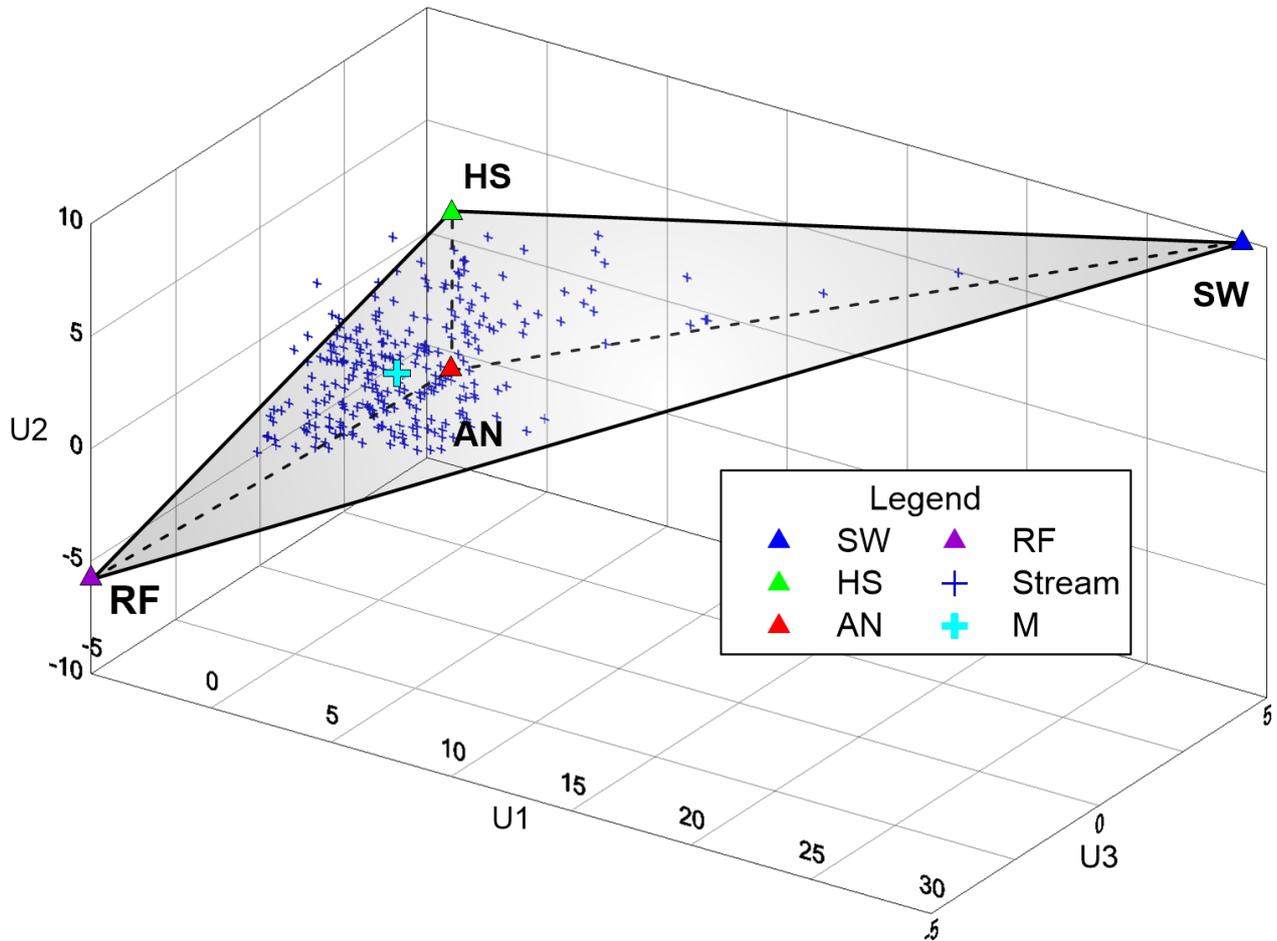
#### 3.2. Uncertainty estimation of water source contributions

Using the classic EMMA approach (Christophersen and Hooper, 1992), ~~end members (source) and stream (mixture) data from end-members SW, HS, AN, RF and stream M,~~ were projected into a three-dimensional space (Correa et al., 2019b) ~~and visualized presented~~ in Figure 1. The resulting median and standard deviation of end-members and stream coordinates are shown in Table 1. Furthermore, Figure 2 shows the distribution of projected samples from individual end-members in the PCA coordinates.

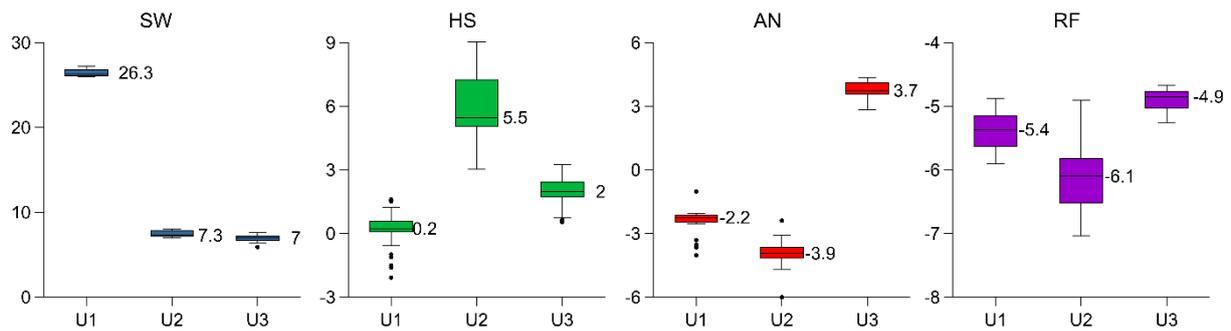
The uncertainty range of each of the four end-member contributions to the stream was determined using the above developed Eq. 15 based on the first-order Taylor series approximation ~~from~~ Eq. 14 (MatLab code in (Correa et al., 2019a)). ~~The upper limit was computed as . The variance for each end member fraction was calculated (as recommended by Phillips and Gregg (2001)) as  $f_w + t_{0.05,\gamma} \sigma_{f_w}$  and lower limit as  $f_w - t_{0.05,\gamma} \sigma_{f_w}$ . Th The  $t_{0.05,\gamma}$  depicts the Student's t for  $\alpha=0.05$  (two-tailed) and  $\gamma$  degrees of freedom. The  $\gamma$  degrees of freedom represents the Satterthwaite (1946) approximation for the related degrees of freedom with  $\sigma_{FEM1}$  and can be calculated as follows:~~

$$r_{EM1} = \frac{(\sigma_{f_{EM1}}^2)^2}{\sum_y \sum_x \frac{\left( \frac{\partial f_{EM1}}{\partial y_x} \right)^2 \sigma_{y_x}^2}{n_{y_x} - 1}} \quad \text{Eq.(16)}$$

140 ~~Note that~~ Note that the set of sources: A, B, C and D used for the development of the equations are represented here by SW, HS, AN and RF in this specific order. Eq. (16) is an adaptation of Eq. (14) for this particular end-member configuration with  $x = EM1, EM2, EM3, EM4$  and  $M$ ,  $y = \bar{\delta}, \bar{\lambda}$  and  $\bar{\phi}$ ,  $n =$  number of samples. The  $\bar{\delta}, \bar{\lambda}$  and  $\bar{\phi}$  represent the median of the projected water samples from end members and stream in the principal components U1, U2 and U3, respectively (U1, U2 and U3 represent the principal components PC1, PC2 and PC3, respectively U1 represents the principal components PC1, U2 PC2 and U3 and PC3). The  $f_{EM1-w}$  gives  $w$  the proportion of  $EM1-w$  in  $M$  and  $\sigma_{f_{EM1-w}}^2$ , the variances of the  $EM1-w$ . A similar This procedure ~~should be used for~~ was applied to all end-members. The resulting uncertainty estimates for each source end-member are shown in Table 5.



150 Figure 1. Three-dimensional mixing space generated using stream data, where the median of end-members are projected. U1 represents 59.6% of the variance, U2 19.7%, and U3 7.4% (From PCA); RF, rainfall; AN, Andosols; HS, Histosols; SW, spring water; M, median of stream data (mixture)



155 **Figure 2. Boxplots of end-members projected in the three-dimensional mixing space for the study period 2013–2014, the Y-axis represents the coordinates of the mixing space and the X-axis the principal components U1, U2 and U3 (the central bar in the box represents the median; notches represent the 95% confidence intervals; whiskers 1.5 times the interquartile range and circles represent outliers). SW, spring water; HS, Histosol; AN, Andosol; RF, rainfall.**

### 3.3. Sensitivity of water sources uncertainty to input data

160 From the above-mentioned data set, we have generated 6 examples to assess the sensitivity of the uncertainty calculation to the source sample size, the artificial inclusion of outliers (upper and lower extremes) and the increased standard deviations of the source datasets.

~~The first example considers 50% of the samples from each source. The median, standard deviation and sample size are input data (Table 2) to calculate the uncertainty ranges (Table 6).~~

- The first example considers 50% of the samples (collected in the first half of the monitoring period) from each source. The median, standard deviation and sample size are input data (Table 2) to calculate the uncertainty bands (Table 6).
- The second example considers the remaining 50% of samples and was similarly executed (Table 2).
- In the third example, outliers were artificially included at the upper positive end of data sets for each source at each coordinate, respectively. The outliers consisted of twice the maximum positive value of the observed data (Table 3).
- Using the same criteria, the negative extremes were included in the fourth example (Table 3).
- Sources affected by dispersed data clouds were taken into account by an increase in the standard deviation. We considered two cases, the first, in the example five, increasing three times the value of the standard deviation of the initial data set (Table 4) and finally, increasing the standard deviation five times for the sixth example (Table 4).

175 The results of this analysis are presented in Tables 6-8. In examples 1 and 2 the sample size reduction from 24 to 12 and 13 samples respectively (Table 6), had a minimal effect (less than 3%) on the calculation of the uncertainty ranges compared to the original complete set (Table 1). The fractions of source contributions did not experience changes. The inclusion of outliers affected the values of the medians at levels of the second decimal (Table 3) in relation to the median of the initial data (Table 2). However, the standard deviations increased in a range of 1.2 to 2.5 times the original value for AN and HS, and more for RF (2.5 to 10.5) and drastically for SW (4 to 20 times

wider). ~~“These variations were reflected in the widening (1% to 12%) of uncertainty bands for all existing cases (Table 7) in comparison with those calculated from the original data set (Table 5) These variations were reflected in the results of the calculation of uncertainties where the limits were extended for all existing cases from 1% to 12% (Table 6) in relation to Table 5.~~ Furthermore, the widening of the standard deviations to three and five times their initial values resulted in an increase in the range of uncertainty between 2% and 22% for the first case and between 5% and 37% for the second case. For the latter, the minimum limit of the uncertainty range was reached in all the reported cases. The large number of samples used in these exercises were reflected in high degrees of freedom.

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#### 4. Summary and remarks

Our methodology was developed to calculate the contribution of sources to the mixture and its associated uncertainty (based on multiple tracer sets) ~~has been shown~~ to be effective in real application cases. The ~~robustness-application~~ of the method ~~is reflected in the fact~~ that the calculations of the uncertainty ranges of multiple source contributions to a mixture do not experience significant changes with sample size reduction or inclusion of outliers. Rather, it shows marginally different results by incorporating standard deviations from widely dispersed data.

The methodology, based on Phillips and Gregg, (2001) combined with EMMA applications (Hooper, 2003) presents high potential for use as an alternative method to the simple sum of analytical errors (Uhlenbrook and Hoeg, 2003) or the Bayesian approach (Parnell et al., 2010; Stock et al., 2018). We provide a tool to close the gap in studies of mixing processes, when a larger number of source contributions (>3) and related uncertainty estimates are needed for a more complete conceptualization~~We provide a tool to help the community that has reported that a greater number of sources contribution and (common 2 or 3) the related uncertainty is needed for a more complete conceptualization of the mixing processes~~ (Iwasaki et al., 2015).

The MatLab code provided and the illustrative examples facilitate the understanding of the methodology and promote future scientific applications. We are confident that the use of this methodology will help the scientific community that is increasingly using large tracer sets in its research to obtain results supported by a sound uncertainty analysis~~robust results~~.

#### 5. Code and data availability

A MatLab code to calculate the fractions of end-members contribution to the mixture and their associated uncertainties is freely available in <https://zenodo.org/record/2649201>. As well as input data (used in this study) as an example for the code run and an instruction note.

#### 6. Author contribution

AC and CB conceptualized the methodology. AC was responsible for the data collection and analysis. DO AC programmed and evaluated the MatLab code with collected data. AC wrote the manuscript with contributions from all co-authors.

#### 7. Competing interests

The authors declare that they have no conflict of interest

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**Table 1. Median and standard deviation (std.dev.) of end-members and stream projected in three-dimensional space for the study period 2013–2014.**

End-member		Coordinates*			Naming
		U1	U2	U3	in equations
SW (n = 25)	median	26,25	7,29	7,00	A
	std.dev.	0,46	0,36	0,39	
HS (n = 33)	median	0,23	5,48	1,97	B
	std.dev.	0,85	1,29	0,69	
AN (n = 37)	median	-2,24	-3,93	3,71	C
	std.dev.	0,55	0,58	0,45	
RF (n = 36)	median	-5,38	-6,10	-4,84	D
	std.dev.	0,27	0,56	0,15	
Stream (n = 257)	median	-0,61	-1,04	0,94	M
	std.dev.	2,06	1,10	0,66	

\* Coordinates of end-members and stream (mixture) medians in three-dimensional space (U1, U2 and U3). n represents the sample size.

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**Table 2. Median and standard deviation (std.dev.) of end-members and stream projected in three-dimensional considering 50% of the data sets**

Naming in equations		1) End member	Coordinates*			2) End member	Coordinates*		
			U1	U2	U3		U1	U2	U3
A	median	SW	26.18	7.29	6.66	SW	26.28	7.29	7.1
	std.dev.	(n = 12)	0.34	0.39	0.48	(n = 13)	0.51	0.36	0.21
B	median	HS	0.23	5.41	1.87	HS	0.28	5.9	2.26
	std.dev.	(n = 17)	0.74	1.19	0.52	(n = 17)	0.96	1.33	0.74
C	median	AN	-2.37	-3.93	3.69	AN	-2.2	-3.94	3.89
	std.dev.	(n = 19)	0.59	0.4	0.49	(n = 19)	0.46	0.73	0.41
D	median	RF	-5.37	-6.26	-4.78	RF	-5.35	-5.99	-5.01
	std.dev.	(n = 18)	0.26	0.58	0.07	(n = 18)	0.28	0.53	0.15
M	median	Stream	-0.61	-1.04	0.94	Stream	-0.61	-1.04	0.94
	std.dev.	(n = 257)	2,06	1,10	0,66	(n = 257)	2,06	1,10	0,66

The example 1) considers the initial 50% and 2) the remaining 50% of the sample sets.\* Coordinates of end-members and stream (mixture) medians in three-dimensional space (U1, U2 and U3). n represents the sample size.

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**Table 3. Median and standard deviation (std.dev.) of end-members and stream projected in three-dimensional including artificial outliers**

Naming in equations		3) End member	Coordinates*			4) End member	Coordinates*		
			U1	U2	U3		U1	U2	U3
A	median	SW	26.25	7.3	7.02	SW	26.21	7.29	6.95
	std.dev.	(n = 26)	5.51	1.73	1.68	(n = 26)	10.28	2.87	2.54
B	median	HS	0.27	5.47	1.98	HS	0.23	5.45	1.97
	std.dev.	(n = 34)	0.99	2.45	1.03	(n = 34)	1.12	1.99	0.8
C	median	AN	-2.24	-3.92	3.79	AN	-2.26	-3.95	3.74
	std.dev.	(n = 38)	0.78	1.17	0.92	(n = 38)	1.07	1.43	1.15
D	median	RF	-5.36	-6.08	-4.84	RF	-5.37	-6.11	-4.86
	std.dev.	(n = 37)	1.7	1.89	1.58	(n = 37)	1.09	1.42	0.94
M	median	Stream	-0,61	-1,04	0,94	Stream	-0,61	-1,04	0,94
	std.dev.	(n = 257)	2,06	1,10	0,66	(n = 257)	2,06	1,10	0,66

470 The example 3) considers outliers included at the positive extreme of the dataset of each source and 4) outliers included at the negative extreme.\* Coordinates of end-members and stream (mixture) medians in three-dimensional space (U1, U2 and U3). n represents the sample size.

**Table 4. Median and enlarged standard deviation (std.dev.) of end-members and stream projected in three-dimensional**

Naming in equations		5) End member	Coordinates*			6) End member	Coordinates*		
			U1	U2	U3		U1	U2	U3
A	median	SW	26,25	7,29	7,00	SW	26,25	7,29	7,00
	std.dev.	(n = 25)	1.39	1.07	1.19	(n = 25)	2.32	1.78	1.99
B	median	HS	0,23	5,48	1,97	HS	0,23	5,48	1,97
	std.dev.	(n = 33)	2.56	3.87	2.06	(n = 33)	4.27	6.45	3.43
C	median	AN	-2,24	-3,93	3,71	AN	-2,24	-3,93	3,71
	std.dev.	(n = 37)	1.65	1.73	1.34	(n = 37)	2.75	2.88	2.24
D	median	RF	-5,38	-6,10	-4,84	RF	-5,38	-6,10	-4,84
	std.dev.	(n = 36)	0.8	1.69	0.46	(n = 36)	1.34	2.81	0.77
M	median	Stream	-0,61	-1,04	0,94	Stream	-0,61	-1,04	0,94
	std.dev.	(n = 257)	2,06	1,10	0,66	(n = 257)	2,06	1,10	0,66

475 The example 5) considers 3-times the standard deviation of the original data set and 6) 5-times the standard deviation of the original data set.\* Coordinates of end-members and stream (mixture) medians in three-dimensional space (U1, U2 and U3). n represents the sample size.

480 **Table 5. Uncertainty of individual end-member contributions to the stream and Satterthwaite (1946) approximation for the degrees of freedom calculated for the study period 2013–2014**

<u>Naming in equations</u> <u>End-member</u>	<u>AEM1</u>	<u>BEM2</u>	<u>CEM3</u>	<u>DEM4</u>
	SW	HS	AN	RF
Fraction of end-members contribution	0.06	0.3	0.35	0.29
Upper 95% confidence limit	0.21	0.57	0.58	0.46
Lower 95% confidence limit	0.00	0.03	0.12	0.12
Degrees of freedom	291	536	749	628

**Table 6. Uncertainty of individual end-member contributions to the stream and Satterthwaite (1946) approximation for the degrees of freedom computed considering 50% of the data sets**

<u>Naming in equations -</u> <u>End-member -</u>	1)	<u>AEM1</u>	<u>BEM2</u>	<u>CEM3</u>	<u>DEM4</u>	2)	<u>AEM1</u>	<u>BEM2</u>	<u>CEM3</u>	<u>DEM4</u>
		SW	HS	AN	RF		SW	HS	AN	RF
Fraction of end-members contribution		0.06	0.3	0.35	0.28		0.06	0.28	0.35	0.3
Upper 95% confidence limit		0.21	0.57	0.58	0.45		0.21	0.55	0.58	0.46
Lower 95% confidence limit		0.00	0.03	0.12	0.11		0.00	0.02	0.12	0.14
Degrees of freedom		289	493	676	589		288	491	679	537

485 The example 1) was computed considering the initial 50% and 2) the remaining 50% of the sample sets.

**Table 7. Uncertainty of individual end-member contributions to the stream and Satterthwaite (1946) approximation for the degrees of freedom computed after including artificial outliers**

<u>Naming in equations -</u> <u>End-member -</u>	3)	<u>AEM1</u>	<u>BEM2</u>	<u>CEM3</u>	<u>DEM4</u>	4)	<u>AEM1</u>	<u>BEM2</u>	<u>CEM3</u>	<u>DEM4</u>
		SW	HS	AN	RF		SW	HS	AN	RF
Fraction of end-members contribution		0.06	0.3	0.35	0.29		0.06	0.3	0.35	0.29
Upper 95% confidence limit		0.22	0.62	0.64	0.5		0.22	0.61	0.63	0.49
Lower 95% confidence limit		0.00	0.00	0.06	0.08		0.00	0.00	0.07	0.08
Degrees of freedom		350	448	640	529		353	554	757	621

The example 3) was computed after including outliers at the positive extreme of the dataset and 4) including outliers at the negative extreme.

490 **Table 8. Uncertainty of individual end-member contributions to the stream and Satterthwaite (1946) approximation for the degrees of freedom computed with enlarged standard deviations**

<u>Naming in equations -</u> <u>End-member -</u>	5)	<u>EM1A</u>	<u>EM2B</u>	<u>EM3C</u>	<u>EM4D</u>	6)	<u>AEM1</u>	<u>BEM2</u>	<u>CEM3</u>	<u>DEM4</u>
		SW	HS	AN	RF		SW	HS	AN	RF
Fraction of end-members contribution		0.06	0.3	0.35	0.29		0.06	0.3	0.35	0.29
Upper 95% confidence limit		0.23	0.68	0.69	0.52		0.26	0.83	0.83	0.61
Lower 95% confidence limit		0.00	0.00	0.01	0.05		0.00	0.00	0.00	0.00
Degrees of freedom		372	225	362	312		335	122	211	172

The example 5) was computed considering 3-times the standard deviation of the original data set and 6) 5-times the standard deviation of the original data set.