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**A Proposed Method for Estimating Interception from Near-Surface Soil
Moisture Response**

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Abstract

Interception is the storage and subsequent evaporation of rainfall by above-ground structures, including canopy and groundcover vegetation and surface litter. Accurately quantifying interception is critical for understanding how ecosystems partition incoming precipitation, but it is difficult and costly to measure, leading most studies to rely on modeled interception estimates. Moreover, forest interception estimates typically focus only on canopy storage, despite the potential for substantial interception by groundcover vegetation and surface litter. In this study, we developed an approach to quantify “total” interception (i.e., including forest canopy, understory, and surface litter layers) using measurements of shallow soil moisture dynamics during rainfall events. Across 34 pine and mixed forest stands in Florida (USA), we used soil moisture and precipitation (P) data to estimate interception storage capacity (β_s), a parameter required to estimate total annual interception (I_a) relative to P . Estimated values for β_s (mean $\beta_s = 0.30$ cm; $0.01 \leq \beta_s \leq 0.62$ cm) and I_a/P (mean $I_a/P = 0.14$; $0.06 \leq I_a/P \leq 0.21$) were broadly consistent with reported literature values for these ecosystems and were significantly predicted by forest structural attributes (leaf area index and percent groundcover), as well as other site variables (e.g., water table depth). The best-fit model was dominated by LAI and explained nearly 80% of observed β_s variation. These results suggest that whole-forest interception can be estimated using near-surface soil moisture time series, though additional direct comparisons would further support this assertion. Additionally, variability in interception across a single forest type underscores the need for expanded empirical measurement. Potential cost savings and logistical advantages of this proposed method relative to conventional, labor-intensive interception measurements may improve empirical estimation of this critical water budget element.

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Introduction

49 Rainfall interception (I) is the fraction of incident rainfall stored by above-ground
50 ecosystem structures (i.e., vegetation and litter layers) and subsequently returned to the
51 atmosphere via evaporation (E), never reaching the soil surface and thus never directly
52 supporting transpiration (T) [Savenije, 2004]. Interception depends on climate and vegetation
53 characteristics and can be as high as 50% of gross rainfall [Gerrits *et al.*, 2007; 2010; Calder,
54 1990]. Despite being critical for accurate water budget enumeration [David *et al.*, 2006],
55 interception is often disregarded or lumped with evapotranspiration (ET) in hydrological models
56 [Savenije, 2004]. Recent work suggests interception uncertainty constrains efforts to partition ET
57 into T and E , impairing representation of water use and yield in terrestrial ecosystems [Wei *et al.*,
58 2017].

59 When interception is explicitly considered, it is typically empirically estimated or
60 modeled solely for the tree canopy. For example, direct measurements are often obtained from
61 differences between total rainfall and water that passes through the canopy to elevated above-
62 ground collectors (throughfall) plus water that runs down tree trunks (stemflow) during natural
63 [e.g., Bryant *et al.*, 2005, Ghimire *et al.*, 2012, 2016] or simulated [e.g., Guevara-Escobar *et al.*,
64 2007; Putuhena and Cordery, 1996] rainfall events. This method yields the rainfall fraction held
65 by and subsequently evaporated from the canopy but ignores interception by understory
66 vegetation and litter. Alternatively, numerous empirical [e.g., Merriam, 1960], process-based
67 [e.g., Rutter *et al.*, 1971, 1975; Gash, 1979, 1995, Liu, 1998], and stochastic [Calder, 1986]
68 models are available for estimating interception. As with direct measurements, most model
69 applications consider only canopy storage despite groundcover (both understory vegetation and
70 litter layers) interception that can exceed canopy values in some settings [Gerrits and Savenije,

71 2011; *Putuhena and Cordery*, 1996]. As such, it seems likely that conventional measures and
72 typical model applications underestimate actual (i.e., “total”) interception.

73 New field approaches are needed to improve quantification of total interception and
74 refine the calibration and application of available models. A detailed review of available
75 interception models [*Muzylo et al.*, 2009] stresses the need for direct interception measurements
76 across forest types and hydroclimatic regions, but meeting this need will require substantial
77 methodological advances. Throughfall measurements yield direct and site-specific interception
78 estimates [e.g., *Ghimire et al.*, 2017; *Bryant et al.*, 2005], but they are difficult and costly to
79 implement even at the stand scale because of high spatial and temporal variability in vegetation
80 structure [*Zimmerman et al.*, 2010; *Zimmerman and Zimmerman*, 2014]. Moreover,
81 comprehensive measurements also require enumeration of spatially heterogeneous stemflow, as
82 well as interception storage by the understory and litter layers, greatly exacerbating sampling
83 complexity and cost [*Lundberg et al.*, 1997]. Empirical techniques that estimate total interception,
84 integrate across local spatial and temporal variation, and minimize field installation complexity
85 are clearly desirable.

86 Here we present a novel approach for estimating total (i.e., canopy, understory and litter)
87 interception using continuously logged, near-surface soil moisture. Prior to runoff generation,
88 infiltration is equivalent to rainfall minus total interception, and the response of near-surface soil
89 moisture during and directly following rain events can be used to inform interception parameters
90 and thus interception. As a proof-of-concept, we tested this simple interception estimation
91 method in 34 forest plots spanning a wide range of conditions (e.g., tree density, composition,
92 groundcover, understory management, age, and hydrogeologic setting) across Florida (USA).

93

Methods

Estimating Interception Storage Capacity from Soil Moisture Data

During every rainfall event, a portion of the total precipitation (P) is temporarily stored in the forest canopy and groundcover (hereafter referring to both live understory vegetation and forest floor litter). We assume that infiltration (and thus any increase in soil moisture) begins only after total interception storage, defined as the sum of canopy and groundcover storage, is full. We further assume this stored water subsequently evaporates to meet atmospheric demand. Calculating dynamic interception storage requires first determining the total storage capacity (β_s), which is comprised of the storage capacities for the forest canopy (β_c) and groundcover (β_g) (Fig. 1a).

To estimate β_s , we consider a population of individual rainfall events of varying depth over a forest for which high frequency (i.e., 4 hr⁻¹) soil-moisture measurements are available from near the soil surface. To ensure that canopy and groundcover layers are dry, and thus interception storage is zero prior to rainfall onset (i.e., antecedent interception storage capacity = β_s), we further filter the rainfall data to only include the events that are separated by at least 72 hours. Volumetric soil water content (θ) at the sensor changes only after rainfall fills β_s , evaporative demands since rainfall onset are met, and there is sufficient infiltration for the wetting-front to arrive at the sensor. Rainfall events large enough to induce a soil moisture change ($\Delta\theta$) are evident as a rainfall threshold in the relationship between P and $\Delta\theta$. An example time series of P and θ (Fig. 1b) yields a P versus $\Delta\theta$ relationship (Fig. 1c) with clear threshold behavior. There are multiple equations whose functional forms allow for extraction of this threshold; here we express this relationship as:

$$P = \frac{a}{(1+b*exp^{-c*\Delta\theta})} \quad (1)$$

117 where P is the total rainfall event depth, $\Delta\theta$ is the corresponding soil moisture change, and a , b ,
 118 and c are fitted parameters. Figure 2 illustrates this relationship and model fitting for observed
 119 $\Delta\theta$ data from six plots at one of our study sites described below. We chose a reverse exponential
 120 function in Eq (1) to fit the observed $\Delta\theta$ - P relationship because it aligns well with observations
 121 and is physically representative of the typical infiltration behavior observed across most soil
 122 profiles (e.g., Horton 1941). While the data in Figure 2 suggest that other functional forms (e.g.,
 123 a linear equation with thresholds at $\Delta\theta = 0$ and $\Delta\theta_{max}$) could provide equivalent fidelity over the
 124 range of our observations, a constant slope would be inferior for describing the infiltration
 125 dynamics of the $\Delta\theta$ - P relationship more generally. The y-intercept of Eq. 1 (i.e., where
 126 $\Delta\theta$ departs from zero) is given by:

$$127 \quad P_s = \frac{a}{(1+b)} \quad (2)$$

128 where P_s represents the total rainfall required to saturate β_s , meet evaporative demands between
 129 storm onset and observed $\Delta\theta$, and supply any infiltration required to induce soil moisture
 130 response once β_s has been saturated. This equality can be expressed as:

$$131 \quad P_s = \beta_s + \int_0^T E dt + \int_t^T f dt = \beta_s + \int_0^t E dt + \int_t^T E dt + \int_t^T f dt \quad (3)$$

132 where T is the total time from rainfall onset until observed change in θ (i.e., the wetting front
 133 arrival), t is the time when β_s is satisfied, and E and f are the evaporation and infiltration rates,
 134 respectively. To connect this empirical observation to existing analytical frameworks [e.g., *Gash*
 135 1979], we adopt the term P_G , defined as the rainfall depth needed to saturate β_s and supply
 136 evaporative losses between rainfall onset (time = 0) and β_s saturation (time = t):

$$137 \quad P_G = \beta_s + \int_0^t E dt \quad (4)$$

138 Solving for β_s in Eq. 3 and substituting into Eq. 4 yields:

139
$$P_G = P_s - \int_t^T E dt - \int_t^T f dt \quad (5)$$

140 Equation 5 may be simplified by assuming that average infiltration and evaporation rates apply
 141 during the relatively short period between t and T , such that:

142
$$P_G = P_s - \bar{f}(T - t) - \bar{E}(T - t) \quad (6)$$

143 where \bar{f} is the average soil infiltration rate and \bar{E} is the average rate of evaporation from the
 144 forest surface (i.e., canopy, groundcover, and soil) during the time from t to T [see *Gash, 1979*].

145 The storage capacity β_s can now be calculated following *Gash [1979]* as:

146
$$\beta_s = -\frac{\bar{E}}{\bar{P}} \frac{P_G}{\ln(1-\frac{\bar{E}}{\bar{P}})} = -\frac{\bar{E} [P_s - (T-t)(\bar{f} + \bar{E})]}{\bar{P} \ln(1-\frac{\bar{E}}{\bar{P}})} \quad (7)$$

147 where \bar{P} is the average rainfall rate and all other variables are as previously defined. In Eq. 5, \bar{E}
 148 is usually estimated using the Penman-Monteith equation [*Monteith, 1965*], setting canopy
 149 resistance to zero (e.g., *Ghimire et al., 2017*).

150 A key challenge in applying Eq. 5, and thus for the overall approach, is quantifying
 151 infiltration, since the time, t , when β_s is satisfied is unknown. Moreover, the infiltration rate
 152 embedded in P_s is controlled by \bar{P} and initial soil moisture content (θ_i). It is worth noting that
 153 shallower sensor depth placement would likely eliminate the need for this step (see Discussion).
 154 However, to overcome this limitation in our study (where our soil moisture sensor was 15 cm
 155 below the ground surface), we used the 1-D unsaturated flow model HYDRUS-1D [*Simunek et*
 156 *al., 1995*] to simulate the required time for the wetting front to arrive (T_w) at the sensor under
 157 bare soil conditions across many combinations of \bar{P} and θ_i . As such, T_w represents the time
 158 required for a soil moisture pulse to reach the sensor once infiltration begins (i.e., after β_s has
 159 been filled), which is $T - t$ in Eq. 7. For each simulation, T_w (signaled by the first change in θ at
 160 sensor depth) was recorded and used to develop a statistical model of T_w as a function of \bar{P} and θ_i .

161 We used plot-specific soil moisture retention parameters from Florida Soil Characterization
 162 Retrieval System (<https://soils.ifas.ufl.edu/flsoils/>) to develop these curves for our sites, but
 163 simulations can be applied for any soil with known or estimated parameters.

164 Simulations revealed that T_w at a specific depth declined exponentially with increasing θ_i :

$$165 \quad T_w = ae^{-b\theta_i} \quad (8)$$

166 where a and b are fitting parameters. Moreover, the parameters a and b in Eq. (6) are well fitted
 167 by a power function of \bar{P} :

$$168 \quad a = a_1\bar{P}^{a_2}, b = b_1\bar{P}^{b_2} \quad (9)$$

169 where a_1 and b_1 are fitting parameters. These relationships are illustrated in Fig. 3 for a loamy
 170 sand across a range of \bar{P} and θ_i at 15 cm depth. The relationship between θ_i and T_w is very strong
 171 for small to moderate \bar{P} (< 3.0 cm/hr). At higher values of \bar{P} , T_w is smaller than the 15-minute
 172 sampling resolution, and these events were excluded from our analysis (see below).

173 Assuming that \bar{f} equals \bar{P} over the initial infiltration period from t to T (robust for most
 174 soils, see below), Eq. 7 can be modified to:

$$175 \quad \beta_s = \frac{-\bar{E}}{\bar{P}} \left[\frac{P_s - T_w(\bar{P} + \bar{E})}{\ln\left(1 - \frac{\bar{E}}{\bar{P}}\right)} \right] \quad (10)$$

176 This approach assumes no surface runoff or lateral soil-water flow near the top of the soil profile
 177 from time t to T . Except for very fine soils under extremely high \bar{P} , this assumption generally
 178 holds during early storm phases, before ponding occurs [*Mein and Larsen, 1973*]. However,
 179 where strong layering occurs near the surface, lateral flow above the sensor (i.e., at capillary
 180 barriers or differential conductivity layers; *Blume et al., 2009*) may occur, and wetting front
 181 simulations described above would need to account for layered soil structure to avoid potential
 182 overestimation of interception. Lateral flow within the duff layer during high-intensity
 183 precipitation events as observed by *Blume et al. (2008)* would be more difficult to correct for,

184 though we note that since our goal is to determine β_s , extreme storms can be omitted from the
185 analysis when implementing Eqs. 1-10, without compromising β_s estimates. Similarly, not
186 accounting for the presence of preferential flow (e.g., finger flow, funnel flow, or macropore
187 flow; *Orozco-Lopez et al.*, 2018) in wetting front calculations could lead to underestimation of
188 interception, though application in coarser texture soils (as evaluated here) likely minimize this
189 challenge. More generally, these limitations can be minimized by placing the soil moisture
190 sensor close to the soil surface (e.g., within 5 cm). Finally, we note that values of β_s from Eq. 10
191 represent combined interception from canopy and groundcover, but the method does not allow
192 for disaggregation of these two components.

193 **Calculating Interception**

194 Interception storage and subsequent evaporation (sometimes referred to as interception
195 loss) for a given rain event are driven by both antecedent rain (which fills storage) and
196 evaporation (which depletes it). Instantaneous available storage ranges from zero (saturated) to
197 the maximum capacity (i.e., β_s which occurs when the storage is empty). While discrete, event-
198 based interception models [*Gash*, 1979, 1995; *Liu*, 1998] have been widely applied to estimate
199 interception, continuous models more accurately represent time-varying dynamics in interception
200 storage and losses. We adopted the continuous, physically based interception modeling
201 framework of *Liu* [1998, 2001]:

$$202 \quad I = \beta_s(D_0 - D) + \int_0^t (1 - D)E dt \quad (11)$$

203 where I is interception, D_0 is the forest dryness index at the beginning of the time step t , D is the
204 forest dryness index at time the end of t , and E is the evaporation rate from wetted surfaces. The
205 dryness index at each time-step is calculated as:

$$206 \quad D = 1 - \frac{C}{\beta_s} \quad (12)$$

207 where C is “adherent storage” (i.e., water that does not drip to the ground) and is given by:

$$208 \quad C = \beta_s \left(1 - D_0 \exp \left(\frac{-(1-\tau)}{\beta_s} P \right) \right) \quad (13)$$

209 where τ is the free throughfall coefficient. Because our formulation of β_s in Eq. 10 incorporates
210 both canopy and groundcover components (i.e., negligible true throughfall), we approximated τ
211 in Eq. 13 as zero. Between rainfall events, water in interception storage evaporates to meet
212 atmospheric demand, until the dryness index, D reaches unity [Liu 1997]. The rate of
213 evaporation from wetted surfaces between rainfall events (E_s) is:

$$214 \quad E_s = E(1 - D) \exp \left(\frac{E}{\beta_s} \right) \quad (14)$$

215 A numerical version of Eq. 11 to calculate interception at each time step, t , is expressed as:

$$216 \quad I = \beta_s(D_{t-1} - D_t) + \frac{1}{2}[E_{t-1}(1 - D_{t-1}) + E_t(1 - D_t)] \quad (15)$$

217 Eq. 15 quantifies continuous and cumulative interception using precipitation and other climate
218 data (for E) along with β_s derived from soil moisture measurements and corresponding
219 meteorological data.

220 **Study Area and Data Collection**

221 As part of a multi-year study quantifying forest water use under varying silvicultural
222 management, we instrumented six sites across Florida, each with six 2-ha plots spanning a wide
223 range of forest structural characteristics. Data from two of the plots at one site were not used here
224 due to consistent surface water inundation, yielding a total of 34 experimental forest plots. Sites
225 varied in hydroclimatic forcing (annual precipitation range: 131 to 154 cm/yr and potential ET
226 range: 127 to 158 cm/yr) and hydrogeologic setting (shallow vs. deep groundwater table).
227 Experimental plots within sites varied in tree species, age, density, leaf area index (LAI),
228 groundcover vegetation density (%GC), soil type, and management history (Table 1). Each site

229 contained a recent clear-cut plot, a mature pine plantation plot, and a restored longleaf pine
230 (*Pinus palustris*) plot; the three remaining plots at each site included stands of slash pine (*Pinus*
231 *elliottii*), sand pine (*Pinus clausa*), or loblolly pine (*Pinus taeda*) subjected to varying
232 silvicultural treatments (understory management, canopy thinning, prescribed burning) and
233 hardwood encroachment. The scope of the overall project (34 plots spanning 6 sites across
234 Florida) and the emphasis on measuring variation in forest ET and water yield precluded
235 conventional measurements of interception (e.g., throughfall and stemflow collectors). Because
236 model estimates of interception were considered sufficient for water yield predictions across
237 sites, the analyses presented here represent a proposal for additional insights about interception
238 that can be gleaned from time series of soil moisture rather than a meticulous comparison of
239 methods. We assessed results from this new proposed method using comparisons with numerous
240 previous interception studies in pine stands in the southeastern US and elsewhere, and by testing
241 for the expected associations between estimated interception and stand structure (e.g., LAI and
242 groundcover).

243 Within each plot, three sets of TDR sensors (CS655, Campbell Scientific, Logan, UT,
244 USA) were installed to measure soil moisture at multiple soil depths (Fig. 1a). Only data from
245 the top-most sensor (15 cm below the ground surface) were used in this study. Soil-moisture
246 sensors were located to capture representative variation in stand geometry and structure (i.e.,
247 within and between tree rows) to capture variation in surface soil moisture response to rainfall
248 events. While this spatial layout was intended to characterize the range of plot-scale forest
249 canopy and groundcover heterogeneity, the three measurements locations were within a 10-m
250 radius and thus represent localized (sub-plot) interception estimates. Within each clear-cut plot at
251 each site, meteorological data (rainfall, air temperature, relative humidity, solar insolation, wind

252 speed and direction) were measured using a weather station (GRSW100, Campbell Scientific,
253 Logan, UT; Fig. 4c) every 3 seconds and used to calculate hourly E by setting the canopy
254 resistance to zero [Ghimire *et al.*, 2017; Gash, 1995; Monteith, 1965]. Growing season forest
255 canopy LAI ($m^2 m^{-2}$) and groundcover (%) were measured at every 5-m node within a 50 m x 50
256 m grid surrounding soil moisture measurement banks. LAI was measured at a height of 1 m
257 using a LI-COR LAI-2200 plant canopy analyzer, and %GC was measured using a 1 m^2 quadrat.

258 To estimate β_s , mean $\Delta\theta$ values from the three surface sensors were calculated for all
259 rainfall events separated by at least 72 hours. Storm separation was necessary to ensure the
260 canopy and groundcover surfaces were mostly dry (and thus antecedent storage capacity = β_s) at
261 the onset of each included rainfall event. Rainfall events were binned into discrete classes by
262 depth and plotted against mean $\Delta\theta$ to empirically estimate P_s (e.g., Fig. 2). For each rainfall bin,
263 mean θ_i , \bar{P} and \bar{E} were also calculated to use in Eq. 10, which was then applied to calculate β_s .
264 Subsequently, we developed generalized linear models (GLMs) using forest canopy structure
265 (site-mean LAI), mean groundcover (% GC), hydrogeologic setting (shallow vs. deep
266 groundwater table), and site as potential predictors, along with their interactions, to statistically
267 assess predictors of β_s estimates. Because models differed in fitted parameter number, the best
268 model was selected using the Akaike Information Criteria (AIC; Akaike, 1974). Finally, we
269 calculated cumulative annual interception (I_a) and its proportion of total precipitation (I_a/P) for
270 each study plot using the mean β_s for each plot (across the 3 sensor banks), climate data from
271 2014 to 2016, and Eq. 15. Differences in I_a/P across sites and among plots within sites were
272 assessed using ANOVAs. All analyses were performed using R [R Core Team, 2017].

273

274

Results

275 **Total Storage Capacity (β_s)**

276 The exponential function used to describe the $P-\Delta\theta$ relationship (Eq. 1) showed strong
277 agreement with observations at all sites and plots (overall $R_2 = 0.80$; $0.47 \leq R_2 \leq 0.97$; Table 1)
278 as illustrated for a single site in Fig. 2. This consistency across plots and sites suggests that Eq. 1
279 is capable of adequately describing observed $P-\Delta\theta$ relationships, enabling estimates of β_s across
280 diverse hydroclimatic settings and forest structural variation. Estimates of β_s ranged from 0.01 to
281 0.62 cm, with a mean of 0.30 cm (Table 1). Plot-scale LAI was moderately correlated with plot-
282 mean β_s , describing roughly 32% of observed variation across plots (Fig. 4a). This relatively
283 weak association may arise because LAI measurements only characterize canopy cover, while β_s
284 combines canopy and groundcover storage. The best GLM of β_s (Fig. 4b) used %GC and an
285 interaction term between site and LAI ($R_2 = 0.84$ and $AIC = 253.7$, Table 2). The best GLM
286 without site used LAI and hydrogeologic setting (shallow vs. deep water table) but had reduced
287 performance ($R_2 = 0.55$ and $AIC = 338.3$; Table 2). All models excluding LAI as a predictor
288 performed poorly, so we report model comparisons only for those including LAI.

289 **Annual Interception (I_a)**

290 Despite having similar rainfall regimes (mean annual precipitation ranging from 131 to
291 154 cm yr⁻¹ across sites), mean annual interception (I_a) differed significantly both across sites
292 (one-way ANOVA $p < 0.001$) and among plots within sites (one-way ANOVA $p < 0.001$).
293 Estimates of I_a/P across all plots and sites ranged from 6 to 21% of annual rainfall (Table 1) and
294 were moderately, but significantly, correlated with mean LAI, explaining approximately 30% of
295 variation in I_a/P (Fig. 5a). Correlations among I_a/P and LAI were stronger for individual sites
296 than the global relationship ($0.51 \leq R_2 \leq 0.84$), except for site EF, where I_a was small and similar
297 across plots regardless of LAI (Fig. 5b; Table 1). This suggests that additional site-level

298 differences (e.g., hydroclimate, soils, geology) play a role in driving I_a , as expected following
299 from their effects on β_s described above.

300 **Discussion**

301 When combined with local rainfall data, near-surface soil moisture dynamics inherently
302 contain information about rainfall interception by above-ground structures. Using soil moisture
303 data, we developed and tested an analytical approach for estimating total interception storage
304 capacity (β_s) that includes canopy, understory, and groundcover vegetation, as well as any litter
305 on the forest floor. The range of β_s given by our analysis (mean $\beta_s = 0.30$ cm; $0.01 \leq \beta_s \leq 0.62$
306 cm) is close to, but generally higher than previously reported canopy-only storage capacity
307 values for similar pine forests (e.g., 0.17 to 0.20 cm for mature southeastern USA pine forests;
308 *Bryant et al.* 2005). Moreover, our estimates of β_s and annual interception corresponded to
309 expected forest structure controls (e.g., LAI and ground cover) on interception, further
310 supporting the feasibility of the soil moisture-based approach. However, we emphasize that a
311 more robust validation of the method using co-located and contemporaneous measurement using
312 standard techniques is warranted. Below we summarize the assumptions and methodological
313 considerations that affect the potential utility and limitation of the method.

314 An important distinction between our proposed method and previous interception
315 measurement approaches is that the soil moisture-based method estimates composite rainfall
316 interception of not only the canopy, but also of the groundcover vegetation and forest floor litter.
317 Rainfall storage and subsequent evaporation from groundcover vegetation and litter layers can be
318 as high, or higher than, canopy storage in many forest landscapes [*Putuhen and Cordery*, 1996;
319 *Gerrits et al.*, 2010]. For example, *Li et al.* [2017] found that the storage capacity of a pine forest
320 floor in China was between 0.3 and 0.5 cm, while maximum canopy storage was < 0.1 cm.

321 *Putuhena and Cordery* [1996] also estimated storage capacity of pine forest litter to be
322 approximately 0.3 cm based on direct field measurements. *Gerrits et al.* [2007] found forest floor
323 interception to be 34% of measured precipitation in a beech forest, while other studies have
324 shown that interception by litter can range from 8 to 18% of total rainfall [*Gerrits et al.*, 2010;
325 *Tsiko et al.*, 2012; *Miller et al.*, 1990; *Pathak et al.*, 1985; *Kelliher et al.*, 1992]. A recent study
326 using leaf wetness observations [*Acharya et al.*, 2017] found the storage capacity of eastern
327 redcedar (*Juniperus virginiana*) forest litter to range from 0.12 to as high as 1.12 cm, with forest
328 litter intercepting approximately 8% of gross rainfall over a six-month period. Given the
329 composite nature of forest interception storage and the range of storage capacities reported in
330 these studies, the values we report appear to be plausible and consistent with the expected
331 differences between canopy-only and total interception storage.

332 Interception varies spatially and temporally and is driven by both β_s and climatic
333 variation (i.e., P and E). Our approach represents storage dynamics by combining empirically
334 derived β_s estimates with climatic data using a previously developed continuous interception
335 model [*Liu* 1998, 2001]. Cumulative I_a estimates in this study ranged considerably (i.e., from 6%
336 to 21% of annual rainfall) across the 34 plots, which were characterized by variation in canopy
337 structure ($0.12 < \text{LAI} < 3.70$) and groundcover ($7.9 < \% \text{GC} < 86.2$). In comparison, interception
338 by pine forests reported in the literature (all of which report either canopy-only or groundcover-
339 only values, but not their composite) range from 12 to 49% of incoming rainfall [*Bryant et al.*,
340 2005; *Llorens et al.*, 1997; *Kelliher and Whitehead*, 1992; *Crockford and Richardson*, 1990].
341 Notably, most of the variation in this range is driven by climate rather than forest structure, with
342 the highest I_a values from more arid regions [e.g., *Llorens et al.* 1997]. Future work could also

343 consider seasonally disaggregated measurements to explore intra-annual variation in canopy
344 structure and litter composition [Van Stan et al. 2017].

345 Broad agreement between our results and literature I_a values again supports the potential
346 utility of our method for estimating this difficult-to-measure component of the water budget,
347 though additional direct comparisons would further support this assertion. Additionally, the
348 magnitude and heterogeneity of our I_a estimates across a single forest type (southeastern US
349 pine) underscores the urgent need for empirical measurements of interception that incorporate
350 information on both canopy and groundcover storage in order to develop accurate water budgets.
351 This conclusion is further bolstered by the persistent importance of site-level statistical effects in
352 predicting β_s (and therefore I_a), even after accounting for forest structural attributes, which
353 suggests there are influential edaphic or structural attributes that we are not currently adequately
354 assessing. For example, while estimated I_a in clear-cut plots was generally smaller than plots
355 with a developed canopy, as expected, one exception was at EF where the clear-cut plot
356 exhibited the highest I_a of the six EF plots (8.4%, Table 1). However, differences among all EF
357 plots were very small (I_a ranged only from 7.9 to 8.4 % of annual rainfall), a rate consistent with
358 or even lower than other clear cuts across the study. This site is extremely well drained with
359 nutrient-poor sandy soils and differs from other sites in that it has dense litter dominated by
360 mosses, highlighting the need for additional local measurements to better understand how forest
361 structure controls observed interception.

362 There are several important methodological considerations and assumptions inherent to
363 estimating interception using near-surface soil moisture data. First is the depth at which soil
364 moisture is measured. Ideally, θ would be measured a few centimeters into the soil profile,
365 eliminating the need to account for infiltration when calculating P_G in Eqs. (4-6) and thereby

366 alleviating concerns about lateral and preferential flow. Soil moisture data used here were
367 leveraged from a study of forest water yield, with sensor deployment depths selected to
368 efficiently integrate soil moisture patterns through the vadose zone. The extra step of modeling
369 infiltration likely increases uncertainty in β_s given field-scale heterogeneity in soil properties and
370 potential lateral and preferential flow. Specifically, lateral flow would delay wetting-front
371 arrival, leading to overestimation of interception, while preferential flow would do the opposite.
372 Despite these caveats, infiltration in our system was extremely well-described using wetting
373 front simulations of arrival time based on initial soil moisture and rainfall. As such, while we
374 advocate for shallower sensor installation and direct comparison to standard methods in future
375 efforts, the results presented here given the available sensor depth seem tenable for this and other
376 similar data sets.

377 Another methodological consideration is that, in contrast to the original Gash (1979)
378 formulation, Eq. 5 does not explicitly include throughfall. While throughfall has been a critical
379 consideration for rainfall partitioning by the forest canopy, our approach considers total
380 interception by aboveground forest structures (canopy, groundcover, and litter). A portion of
381 canopy throughfall is captured by non-canopy storage and thus intercepted. Constraining this
382 fraction is not possible with the data available, and indeed our soil moisture response reflects the
383 “throughfall” passing the canopy, understory and litter. Similarly, estimation of β_s using Eqs. 1-7
384 cannot directly account for stemflow, which can be an important component of rainfall
385 partitioning in forests [e.g., *Bryant et al.*, 2005]. We used the mean soil moisture response across
386 three sensor locations (close to a tree, away from the tree but below the canopy, and within inter-
387 canopy rows), which lessens the impact of this assumption on our estimates of β_s . Further, Eqs.
388 (3-10) assume the same evaporation rate, E , for intercepted water from the canopy and from the

389 understory. Evaporation rates may vary substantially between the canopy, understory, and forest
390 floor [*Gerrits et al.*, 2007, 2010], especially in more energy-limited environments. Future work
391 should consider differential evaporation rates within each interception storage, particularly since
392 the inclusion of litter as a component potentially accentuates these contrasts in *E*.

393 Among the many challenges of measuring interception is the spatial heterogeneity of
394 canopy and ground cover layers, with associated heterogeneity in interception rates. Our study
395 deployed only three sensors per plot, yielding interception estimates that covaried with the
396 expected forest structure controls (i.e., LAI and ground cover) and that aligned closely with
397 literature reported values. Nonetheless, future work should assess spatial variation in soil
398 moisture responses to known heterogeneity in net precipitation (i.e., throughfall plus stemflow)
399 across forest stands (e.g., *Roth et al.*, 2007; *Wullaert et al.*, 2009; *Fathizadeh et al.*, 2014). Soil
400 moisture responses are likely driven by variation in both vegetation and soil properties [*Metzger*
401 *et al.*, 2017], indicating the need for future inquiry across systems to inform the number and
402 locations of soil moisture sensor needed for accurate interception estimates in a variety of
403 settings. Notably, the requisite sampling frequency for aboveground interception is estimated to
404 be 25 funnel collectors per hectare (or more) to maintain relative error below 10% for long-term
405 monitoring, with as many as 200 collectors needed for similar error rates during individual event
406 sampling [*Zimmerman et al.*, 2010; *Zimmerman and Zimmerman*, 2014]. Spatial averaging using
407 larger trough collectors reduces some of this sampling effort, yielding guidance of 5 trough
408 collectors per hectare for assessment of multiple precipitation events or up to 20 per hectare for
409 individual events [*Zimmerman and Zimmerman*, 2014].

410 While the comparative spatial integration extent of aboveground collectors versus soil
411 moisture sensors remains unknown, the strong correspondence between our measurements and

412 literature reported values for the magnitude of interception storage, as well as the forest structure
413 controls (i.e., LAI and ground cover) on that storage volume, underscores that soil moisture
414 measurements, at least in this setting, can integrate key quantitative aspects of the interception
415 process. One possible explanation for the consistency of our results with previous interception
416 studies using aboveground collectors is that soil moisture averages across extant spatial
417 heterogeneity in canopy processes, providing comparable spatial integration to throughfall
418 troughs. In this context, soil moisture measurements have several operational advantages over
419 trough-type collectors, including automated data logging and reduced maintenance burden (e.g.,
420 clearing litter accumulation in collectors), while also providing total interception estimates (as
421 opposed to canopy-only measures). Additional soil moisture measurements would undoubtedly
422 improve the accuracy of these estimates, and indeed we recommend that more direct
423 methodological comparisons are needed to determine the optimal number of sensors for future
424 applications. Overall, however, our results support the general applicability of this proposed soil
425 moisture-based approach for developing “whole-forest” interception estimates across a wide
426 range of hydroclimatic and forest structural settings.

427

428

Conclusions

429 Rainfall interception by forests is a dynamic process that is strongly influenced by
430 rainfall patterns (e.g., frequency, intensity), along with various forest structural attributes such as
431 interception storage capacity (β_s) [Gerrits *et al.*, 2010]. In this work, we coupled estimation of a
432 total (or “whole-forest”) β_s parameter with a continuous water balance model [Liu, 1997, 2001;
433 Rutter *et al.*, 1975], providing an integrative approach for quantifying time-varying and
434 cumulative interception. We propose that soil moisture-based estimates of β_s have the potential

435 to more easily and appropriately represent combined forest interception relative to existing time-
436 and labor-intensive field methods that fail to account for groundcover and litter interception.
437 However, we emphasize that further experimental work is needed to validate this promising
438 approach. Soil moisture can be measured relatively inexpensively and easily using continuous
439 logging sensors that require little field maintenance, facilitating application of the presented
440 approach across large spatial and temporal extents and reducing the time and resources that are
441 needed for other empirical measures [e.g., *Lundberg et al.*, 1997]. Finally, while our comparisons
442 with other empirical measures of forest canopy interception should be treated cautiously, this
443 approach yields values that are broadly consistent with the literature and provide an estimate of
444 combined canopy and groundcover storage capacity that has the potential to improve the
445 accuracy of water balances models at scales from the soil column to watershed.

446

447

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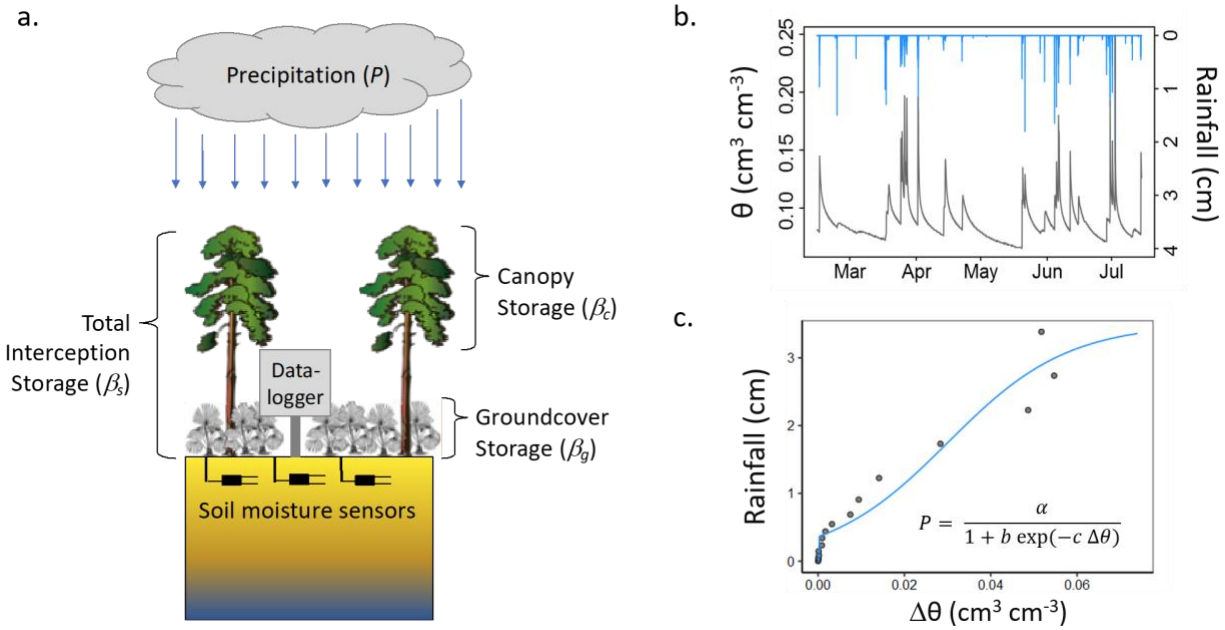
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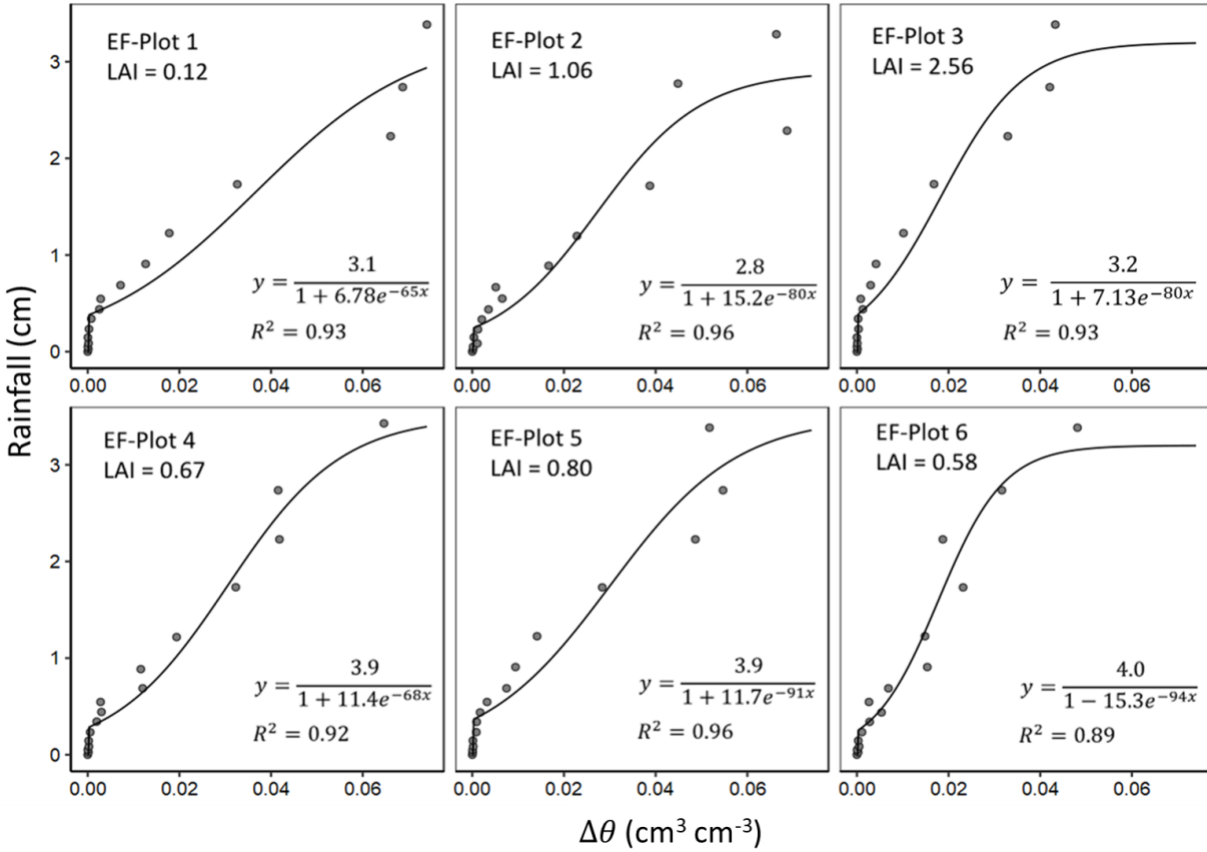
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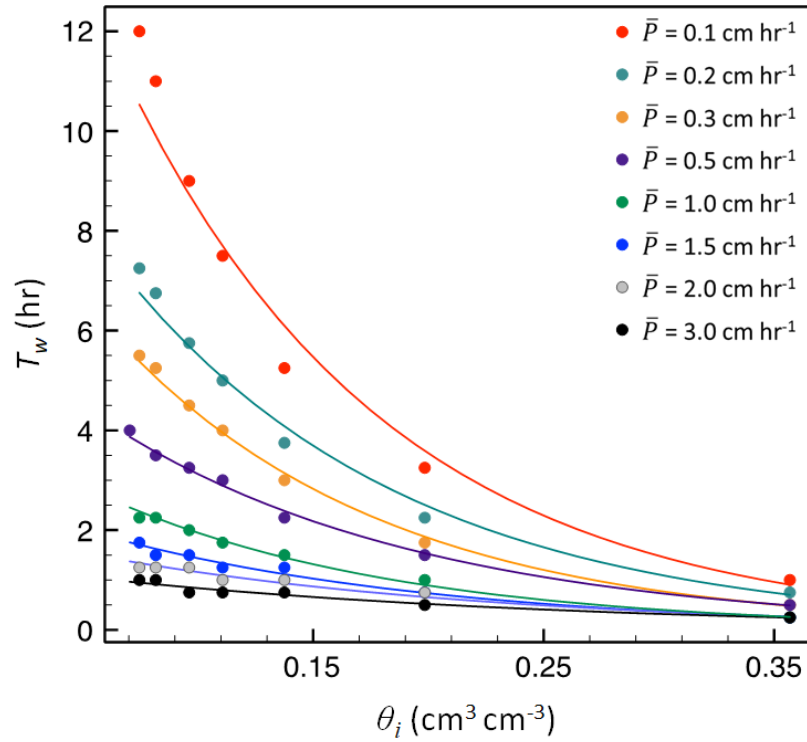
583 Figure 1. (a) Schematic illustration of experimental setup and interception water storages, where
 584 total interception storage (β_s) is the sum of canopy storage (β_c) and groundcover (understory and
 585 litter) storage (β_g). (b) Example time series of rainfall (blue lines) and corresponding near-
 586 surface soil moisture content (θ , black line; observed at 15 cm in this study). (c) Resultant
 587 relationship between rainfall and change in soil moisture $\Delta\theta$ during rainfall, along with fitted
 588 model to extract the y-intercept (i.e., P_s).



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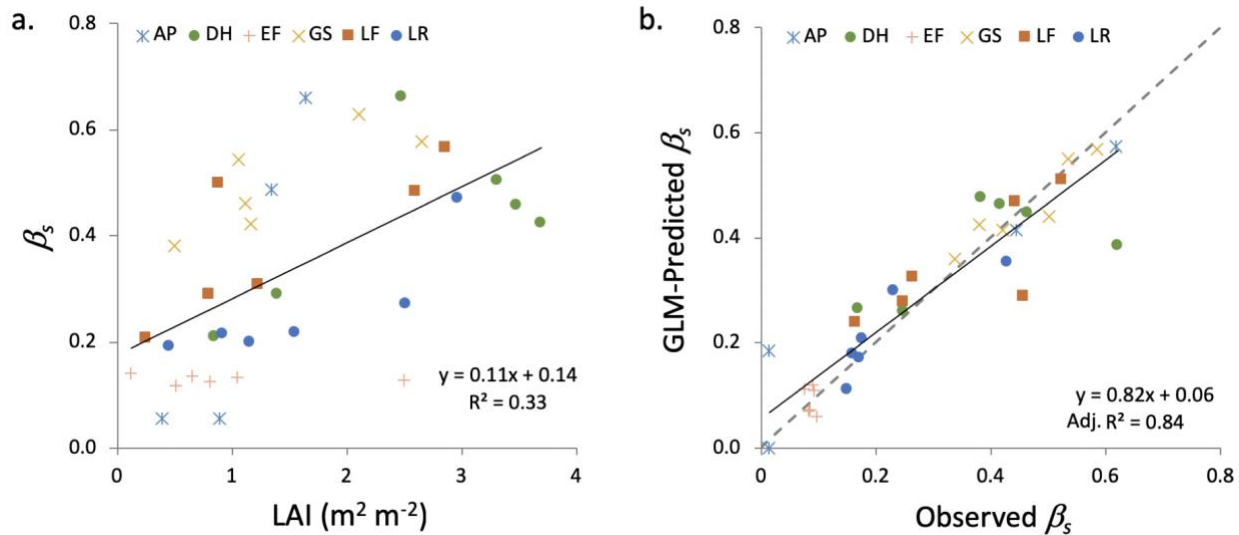
590 Figure 2: Binned rainfall depths vs change in soil moisture content ($\Delta\theta$) for six plots at one of the
 591 study sites used in the study (Econfina; EF). The y-intercept of the fitted relationships were used
 592 to derive P_s in Eq. 2. Note different y-axis scale for EF-Plot 3.

593



594

595 Figure 3: Initial soil moisture content (θ) versus time of wetting front arrival (T_w) at 15 cm depth
 596 for a loamy sand soil. Dots are simulated results from HYDUS-1D simulation, and lines are the
 597 exponential model given in Eq. 8, fitted for each rainfall rate, \bar{P} .



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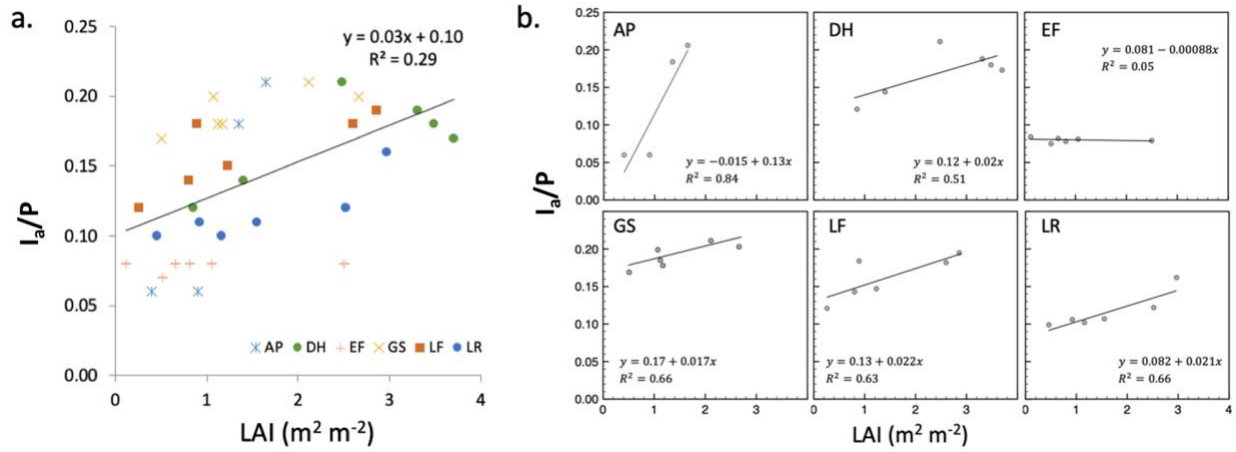
599 Figure 4. (a) Interception storage capacity (β_s) versus leaf area index (LAI) for all sites and plots.

600 (b) Modeled versus observed β_s using the best GLM, which included % groundcover vegetation

601 and an interaction term between site and LAI. The dashed line is the 1:1 line.

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606 Figure 5. (a) Annual proportion of rainfall that is intercepted (I_a/P) intercepted versus LAI for all

607 sites and plots. (b) Site-specific I_a/P versus LAI relationships. The relationship is generally

608 strong except for the EF site, where the overall storage capacity is small across all values of LAI.

609

610 Table 1. Summary of storage capacity (β_s) and annual interception losses (I_a) for all sites and
611 plots, along with plot characteristics (mean annual precipitation, P ; leaf area index, LAI; percent
612 groundcover, %GC; and species). Note that the AP site only had four plots with the data required
613 for the analysis.

Site	Plot	LAI	%GC	Species	β_s (cm)	R_2 ($\Delta\theta$ - P)	P (cm)	I_a/P
AP	2	1.65	47.6	SF Slash	0.620	0.31	145.0	0.206
AP	3	0.90	62.8	SF Slash	0.014	0.78	145.0	0.06
AP	4	1.35	49.1	SF Slash	0.445	0.67	145.0	0.184
AP	6	0.40	73.4	Longleaf	0.014	0.57	145.0	0.06
DH	1	0.85	86.2	Loblolly	0.170	0.90	131.5	0.121
DH	2	2.48	51.2	Slash	0.621	0.68	131.5	0.211
DH	3	1.40	39.2	Slash	0.249	0.49	131.5	0.144
DH	4	3.31	35.8	Slash	0.464	0.71	131.5	0.188
DH	5	3.70	27.1	Loblolly	0.383	0.69	131.5	0.173
DH	6	3.48	32.9	Slash	0.418	0.40	131.5	0.18
EF	1	0.12	13.6	Clearcut	0.099	0.93	153.8	0.084
EF	2	1.05	56.9	Slash	0.092	0.96	153.8	0.081
EF	3	2.50	11.8	Sand	0.086	0.93	153.8	0.079
EF	4	0.66	50.9	Slash	0.094	0.92	153.8	0.082
EF	5	0.81	17.9	Sand	0.085	0.96	153.8	0.078
EF	6	0.52	52.0	Longleaf	0.076	0.89	153.8	0.075
GS	1	1.07	67.9	Clearcut	0.502	0.84	132.4	0.199
GS	2	2.66	7.9	Slash	0.535	0.88	132.4	0.203
GS	3	2.11	71.5	Slash	0.587	0.82	132.4	0.211
GS	4	1.12	42.4	Slash	0.421	0.90	132.4	0.185
GS	5	1.17	45.6	Slash	0.382	0.76	132.4	0.178
GS	6	0.51	55.2	Longleaf	0.339	0.78	132.4	0.169
LF	1	0.26	43.5	None	0.166	0.85	136.3	0.121
LF	2	2.86	23.1	Slash	0.525	0.64	136.3	0.195
LF	3	1.23	24.9	Slash	0.266	0.72	136.3	0.147
LF	4	0.80	25.7	Slash	0.248	0.64	136.3	0.143
LF	5	2.60	12.3	Slash	0.443	0.63	136.3	0.182
LF	6	0.89	25.9	Longleaf	0.458	0.69	136.3	0.184
LR	1	0.46	34.0	Clearcut	0.151	0.96	144.5	0.099
LR	2	2.97	38.1	Slash	0.429	0.84	144.5	0.162
LR	3	0.92	47.0	Slash	0.173	0.95	144.5	0.106
LR	4	2.52	26.7	Slash	0.232	0.92	144.5	0.122
LR	5	1.55	28.1	Slash	0.177	0.96	144.5	0.107
LR	6	1.16	35.5	Longleaf	0.160	0.96	144.5	0.102

614

615 Table 2. Summary of generalized linear model (GLM) results for interception storage capacity
 616 (β s). LAI is leaf area index, GC is groundcover, and WT is water table (shallow vs. deep). The
 617 best model (by AIC) is shown in bold.

Model #	Variable(s)	AIC	R ₂
1	LAI	378.1	0.32
2	LAI + site	318.5	0.66
3	LAI * site	255.9	0.83
4	LAI * site + GC	253.1	0.84
5	LAI + WT	338.3	0.55
6	LAI * WT	339.8	0.55
7	LAI * WT + GC	341.8	0.55
8	LAI + WT + GC	340.3	0.55

618