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Estimating Interception from Near-Surface Soil Moisture Response

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Abstract

Interception is the storage and subsequent evaporation of rainfall by above-ground structures, including canopy and groundcover vegetation and surface litter. Accurately quantifying interception is critical for understanding how ecosystems partition incoming precipitation, but it is difficult and costly to measure, leading most studies to rely on modeled interception estimates. Moreover, forest interception estimates typically focus only on canopy storage, despite the potential for substantial interception by groundcover vegetation and surface litter. In this study, we developed an approach to quantify “total” interception (i.e., including forest canopy, understory, and surface litter layers) using measurements of shallow soil moisture dynamics during rainfall events. Across 34 pine and mixed forest stands in Florida (USA), we used soil moisture and precipitation (P) data to estimate interception storage capacity (β_s), a parameter required to estimate total annual interception (I_a) relative to P . Estimated values for β_s (mean $\beta_s = 0.30$ cm; $0.01 \leq \beta_s \leq 0.62$ cm) and I_a/P (mean $I_a/P = 0.14$; $0.06 \leq I_a/P \leq 0.21$) were broadly consistent with reported literature values for these ecosystems and were significantly predicted by forest structural attributes (leaf area index and percent groundcover), as well as other site variables (e.g., water table depth). The best-fit model was dominated by LAI and explained nearly 80% of observed β_s variation. These results suggest that whole-forest interception can be estimated using near-surface soil moisture time series, though additional direct comparisons would further support this assertion. Additionally, variability in interception across a single forest type underscores the need for expanded empirical measurement. Potential cost savings and logistical advantages of this method relative to conventional, labor-intensive interception measurements may improve empirical estimation of this critical water budget element.

Introduction

47
48 Rainfall interception (I) is the fraction of incident rainfall stored by above-ground
49 ecosystem structures (i.e., vegetation and litter layers) and subsequently returned to the
50 atmosphere via evaporation (E), never reaching the soil surface and thus never directly
51 supporting transpiration (T) [Savenije, 2004]. Interception depends on climate and vegetation
52 characteristics and can be as high as 50% of gross rainfall [Gerrits *et al.*, 2007; 2010; Calder,
53 1990]. Despite being critical for accurate water budget enumeration [David *et al.*, 2006],
54 interception is often disregarded or lumped with evapotranspiration (ET) in hydrological models
55 [Savenije, 2004]. Recent work suggests interception uncertainty constrains efforts to partition ET
56 into T and E , impairing representation of water use and yield in terrestrial ecosystems [Wei *et al.*,
57 2017].

58 When interception is explicitly considered, it is typically empirically estimated or
59 modeled solely for the tree canopy. For example, direct measurements are often obtained from
60 differences between total rainfall and water that passes through the canopy to elevated above-
61 ground collectors (throughfall) plus water that runs down tree trunks (stemflow) during natural
62 [e.g., Bryant *et al.*, 2005, Ghimire *et al.*, 2012, 2016] or simulated [e.g., Guevara-Escobar *et al.*,
63 2007; Putuhena and Cordery, 1996] rainfall events. This method yields the rainfall fraction held
64 by and subsequently evaporated from the canopy but ignores interception by understory
65 vegetation and litter. Alternatively, numerous empirical [e.g., Merriam, 1960], process-based
66 [e.g., Rutter *et al.*, 1971, 1975; Gash, 1979, 1995, Liu, 1998], and stochastic [Calder, 1986]
67 models are available for estimating interception. As with direct measurements, most model
68 applications consider only canopy storage despite groundcover (both understory vegetation and
69 litter layers) interception that can exceed canopy values in some settings [Gerrits and Savenije,

70 2011; *Putuhena and Cordery*, 1996]. As such, it seems likely that conventional measures and
71 typical model applications underestimate actual (i.e., “total”) interception.

72 New field approaches are needed to improve quantification of total interception and
73 refine the calibration and application of available models. A detailed review of available
74 interception models [*Muzylo et al.*, 2009] stresses the need for direct interception measurements
75 across forest types and hydroclimatic regions, but meeting this need will require substantial
76 methodological advances. Throughfall measurements yield direct and site-specific interception
77 estimates [e.g., *Ghimire et al.*, 2017; *Bryant et al.*, 2005], but they are difficult and costly to
78 implement even at the stand scale because of high spatial and temporal variability in vegetation
79 structure [*Zimmerman et al.*, 2010; *Zimmerman and Zimmerman*, 2014]. Moreover,
80 comprehensive measurements also require enumeration of spatially heterogeneous stemflow, as
81 well as interception storage by the understory and litter layers, greatly exacerbating sampling
82 complexity and cost [*Lundberg et al.*, 1997]. Empirical techniques that estimate total interception,
83 integrate across local spatial and temporal variation, and minimize field installation complexity
84 are clearly desirable.

85 Here we present a novel approach for estimating total (i.e., canopy, understory and litter)
86 interception using continuously logged, near-surface soil moisture. Prior to runoff generation,
87 infiltration is equivalent to rainfall minus total interception, and the response of near-surface soil
88 moisture during and directly following rain events can be used to inform interception parameters
89 and thus interception. Since soil moisture is relatively easy and economical to measure
90 continuously for extended periods, successful inference of interception from soil moisture time
91 series may greatly expand the temporal and spatial domains of empirical interception
92 measurements. As a proof-of-concept, we tested this simple interception estimation method in 34

93 forest plots spanning a wide range of conditions (e.g., tree density, composition, groundcover,
94 understory management, age, and hydrogeologic setting) across Florida (USA).

95

96

Methods

97 Estimating Interception Storage Capacity from Soil Moisture Data

98 During every rainfall event, a portion of the total precipitation (P) is temporarily stored in
99 the forest canopy and groundcover (hereafter referring to both live understory vegetation and
100 forest floor litter). We assume that infiltration (and thus any increase in soil moisture) begins
101 only after total interception storage, defined as the sum of canopy and groundcover storage, is
102 full. We further assume this stored water subsequently evaporates to meet atmospheric demand.
103 Calculating dynamic interception storage requires first determining the total storage capacity
104 (β_s), which is comprised of the storage capacities for the forest canopy (β_c) and groundcover (β_g)
105 (Fig. 1a).

106 To estimate β_s , we consider a population of individual rainfall events of varying depth
107 over a forest for which high frequency (i.e., 4 hr⁻¹) soil-moisture measurements are available
108 from near the soil surface. To ensure that canopy and groundcover layers are dry, and thus
109 interception storage is zero prior to rainfall onset (i.e., antecedent interception storage capacity =
110 β_s), we further filter the rainfall data to only include the events that are separated by at least 72
111 hours. Volumetric soil water content (θ) at the sensor changes only after rainfall fills β_s ,
112 evaporative demands since rainfall onset are met, and there is sufficient infiltration for the
113 wetting-front to arrive at the sensor. Rainfall events large enough to induce a soil moisture
114 change ($\Delta\theta$) are evident as a rainfall threshold in the relationship between P and $\Delta\theta$. An example
115 time series of P and θ (Fig. 1b) yields a P versus $\Delta\theta$ relationship (Fig. 1c) with clear threshold

116 behavior. There are multiple equations whose functional forms allow for extraction of this
 117 threshold; here we express this relationship as:

$$118 \quad P = \frac{a}{(1+b \cdot \exp(-c \cdot \Delta\theta))} \quad (1)$$

119 where P is the total rainfall event depth, $\Delta\theta$ is the corresponding soil moisture change, and a , b ,
 120 and c are fitted parameters. Figure 2 illustrates this relationship and model fitting for observed
 121 $\Delta\theta$ data from six plots at one of our study sites described below. The y-intercept of Eq. 1 (i.e.,
 122 where $\Delta\theta$ departs from zero) is given by:

$$123 \quad P_s = \frac{a}{(1+b)} \quad (2)$$

124 where P_s represents the total rainfall required to saturate β_s , meet evaporative demands between
 125 storm onset and observed $\Delta\theta$, and supply any infiltration required to induce soil moisture
 126 response once β_s has been saturated. This equality can be expressed as:

$$127 \quad P_s = \beta_s + \int_0^T E dt + \int_t^T f dt = \beta_s + \int_0^t E dt + \int_t^T E dt + \int_t^T f dt \quad (3)$$

128 where T is the total time from rainfall onset until observed change in θ (i.e., the wetting front
 129 arrival), t is the time when β_s is satisfied, and E and f are the evaporation and infiltration rates,
 130 respectively. To connect this empirical observation to existing analytical frameworks [g., *Gash*
 131 1979], we adopt the term P_G , defined as the rainfall depth needed to saturate β_s and supply
 132 evaporative losses between rainfall onset (time = 0) and β_s saturation (time = t):

$$133 \quad P_G = \beta_s + \int_0^t E dt \quad (4)$$

134 Solving for β_s in Eq. 3 and substituting into Eq. 4 yields:

$$135 \quad P_G = P_s - \int_t^T E dt - \int_t^T f dt \quad (5)$$

136 Equation 5 may be simplified by assuming that average infiltration and evaporation rates apply
 137 during the relatively short period between t and T , such that:

138 $P_G = P_s - \bar{f}(T - t) - \bar{E}(T - t)$ (6)

139 where \bar{f} is the average soil infiltration rate and \bar{E} is the average rate of evaporation from the
 140 forest surface (i.e., canopy, groundcover, and soil) during the time from t to T [see *Gash*, 1979].

141 The storage capacity β_s can now be calculated following *Gash* [1979] as:

142
$$\beta_s = -\frac{\bar{E}}{\bar{P}} \frac{P_G}{\ln(1-\frac{\bar{E}}{\bar{P}})} = -\frac{\bar{E}}{\bar{P}} \frac{[P_s-(T-t)(\bar{f}+\bar{E})]}{\ln(1-\frac{\bar{E}}{\bar{P}})}$$
 (7)

143 where \bar{P} is the average rainfall rate and all other variables are as previously defined. In Eq. 5, \bar{E}
 144 is usually estimated using the Penman-Monteith equation [*Monteith*, 1965], setting canopy
 145 resistance to zero (e.g., *Ghimire et al.*, 2017).

146 A key challenge in applying Eq. 5, and thus for the overall approach, is quantifying
 147 infiltration, since the time, t , when β_s is satisfied is unknown. Moreover, the infiltration rate
 148 embedded in P_s is controlled by \bar{P} and initial soil moisture content (θ_i). It is worth noting that
 149 shallower sensor depth placement would likely eliminate the need for this step (see Discussion).
 150 However, to overcome this limitation in our study (where our soil moisture sensor was 15 cm
 151 below the ground surface), we used the 1-D unsaturated flow model HYDRUS-1D [*Simunek et*
 152 *al.*, 1995] to simulate the required time for the wetting front to arrive (T_w) at the sensor under
 153 bare soil conditions across many combinations of \bar{P} and θ_i . As such, T_w represents the time
 154 required for a soil moisture pulse to reach the sensor once infiltration begins (i.e., after β_s has
 155 been filled), which is $T - t$ in Eq. 7. For each simulation, T_w (signaled by the first change in θ at
 156 sensor depth) was recorded and used to develop a statistical model of T_w as a function of \bar{P} and θ_i .
 157 We used plot-specific soil moisture retention parameters from Florida Soil Characterization
 158 Retrieval System (<https://soils.ifas.ufl.edu/flsoils/>) to develop these curves for our sites, but
 159 simulations can be applied for any soil with known or estimated parameters.

160 Simulations revealed that T_w at a specific depth declined exponentially with increasing θ_i :

$$161 \quad T_w = ae^{-b\theta_i} \quad (8)$$

162 where a and b are fitting parameters. Moreover, the parameters a and b in Eq. (6) are well fitted
163 by a power function of \bar{P} :

$$164 \quad a = a_1\bar{P}^{a_2}, b = b_1\bar{P}^{b_2} \quad (9)$$

165 where a_1 and b_1 are fitting parameters. These relationships are illustrated in Fig. 3 for a loamy
166 sand across a range of \bar{P} and θ_i at 15 cm depth. The relationship between θ_i and T_w is very strong
167 for small to moderate \bar{P} (< 3.0 cm/hr). At higher values of \bar{P} , T_w is smaller than the 15-minute
168 sampling resolution, and these events were excluded from our analysis (see below).

169 Assuming that \bar{f} equals \bar{P} over the initial infiltration period from t to T (robust for most
170 soils, see below), Eq. 7 can be modified to:

$$171 \quad \beta_s = \frac{-\bar{E}}{\bar{P}} \left[\frac{P_s - T_w(\bar{P} + \bar{E})}{\ln\left(1 - \frac{\bar{E}}{\bar{P}}\right)} \right] \quad (10)$$

172 This approach assumes no surface runoff or lateral soil-water flow near the top of the soil profile
173 from time t to T . Except for very fine soils under extremely high \bar{P} , this assumption generally
174 holds during early storm phases, before ponding occurs [Mein and Larsen, 1973]. However,
175 where strong layering occurs near the surface, lateral flow above the sensor (i.e., at capillary
176 barriers or differential conductivity layers; Blume *et al.*, 2009) may occur, and wetting front
177 simulations described above would need to account for layered soil structure to avoid potential
178 overestimation of interception. Lateral flow within the duff layer during high-intensity
179 precipitation events as observed by Blume *et al.* (2008) would be more difficult to correct for,
180 though we note that since our goal is to determine β_s , extreme storms can be omitted from the
181 analysis when implementing Eqs. 1-10, without compromising β_s estimates. Similarly, not
182 accounting for the presence of preferential flow (e.g., finger flow, funnel flow, or macropore

183 flow; *Orozco-Lopez et al.*, 2018) in wetting front calculations could lead to underestimation of
 184 interception, though application in coarser texture soils (as evaluated here) likely minimize this
 185 challenge. More generally, these limitations can be minimized by placing the soil moisture
 186 sensor close to the soil surface (e.g., within 5 cm). Finally, we note that values of β_s from Eq. 10
 187 represent combined interception from canopy and groundcover, but the method does not allow
 188 for disaggregation of these two components.

189 **Calculating Interception**

190 Interception storage and subsequent evaporation (sometimes referred to as interception
 191 loss) for a given rain event are driven by both antecedent rain (which fills storage) and
 192 evaporation (which depletes it). Instantaneous available storage ranges from zero (saturated) to
 193 the maximum capacity (i.e., β_s which occurs when the storage is empty). While discrete, event-
 194 based interception models [*Gash*, 1979, 1995; *Liu*, 1998] have been widely applied to estimate
 195 interception, continuous models more accurately represent time-varying dynamics in interception
 196 storage and losses. We adopted the continuous, physically based interception modeling
 197 framework of *Liu* [1998, 2001]:

$$198 \quad I = \beta_s(D_0 - D) + \int_0^t (1 - D)E dt \quad (11)$$

199 where I is interception, D_0 is the forest dryness index at the beginning of the time step t , D is the
 200 forest dryness index at time the end of t , and E is the evaporation rate from wetted surfaces. The
 201 dryness index at each time-step is calculated as:

$$202 \quad D = 1 - \frac{C}{\beta_s} \quad (12)$$

203 where C is “adherent storage” (i.e., water that does not drip to the ground) and is given by:

$$204 \quad C = \beta_s \left(1 - D_0 \exp \left(\frac{-(1-\tau)P}{\beta_s} \right) \right) \quad (13)$$

205 where τ is the free throughfall coefficient. Because our formulation of β_s in Eq. 10 incorporates
206 both canopy and groundcover components (i.e., negligible true throughfall), we approximated τ
207 in Eq. 13 as zero. Between rainfall events, water in interception storage evaporates to meet
208 atmospheric demand, until the dryness index, D reaches unity [Liu 1997]. The rate of
209 evaporation from wetted surfaces between rainfall events (E_s) is:

$$210 \quad E_s = E(1 - D)\exp\left(\frac{E}{\beta_s}\right) \quad (14)$$

211 A numerical version of Eq. 11 to calculate interception at each time step, t , is expressed as:

$$212 \quad I = \beta_s(D_{t-1} - D_t) + \frac{1}{2}[E_{t-1}(1 - D_{t-1}) + E_t(1 - D_t)] \quad (15)$$

213 Eq. 15 quantifies continuous and cumulative interception using precipitation and other climate
214 data (for E) along with β_s derived from soil moisture measurements and corresponding
215 meteorological data.

216 **Study Area and Data Collection**

217 As part of a multi-year study quantifying forest water use under varying silvicultural
218 management, we instrumented six sites across Florida, each with six 2-ha plots spanning a wide
219 range of forest structural characteristics. Data from two of the plots at one site were not used here
220 due to consistent surface water inundation, yielding a total of 34 experimental forest plots. Sites
221 varied in hydroclimatic forcing (annual precipitation range: 131 to 154 cm/yr and potential ET
222 range: 127 to 158 cm/yr) and hydrogeologic setting (shallow vs. deep groundwater table).
223 Experimental plots within sites varied in tree species, age, density, leaf area index (LAI),
224 groundcover vegetation density (%GC), soil type, and management history (Table 1). Each site
225 contained a recent clear-cut plot, a mature pine plantation plot, and a restored longleaf pine
226 (*Pinus palustris*) plot; the three remaining plots at each site included stands of slash pine (*Pinus*
227 *elliottii*), sand pine (*Pinus clausa*), or loblolly pine (*Pinus taeda*) subjected to varying

228 silvicultural treatments (understory management, canopy thinning, prescribed burning) and
229 hardwood encroachment. The scope of the overall project (34 plots spanning 6 sites across
230 Florida) and the emphasis on measuring variation in forest ET and water yield precluded
231 conventional measurements of interception (e.g., throughfall and stemflow collectors). Because
232 model estimates of interception were considered sufficient for water yield predictions across
233 sites, the analyses presented here represent a proposal for additional insights about interception
234 that can be gleaned from time series of soil moisture rather than a meticulous comparison of
235 methods. We assessed results from this new method using comparisons with numerous previous
236 interception studies in pine stands in the southeastern US and elsewhere, and by testing for the
237 expected associations between estimated interception and stand structure (e.g., LAI and
238 groundcover).

239 Within each plot, three sets of TDR sensors (CS655, Campbell Scientific, Logan, UT,
240 USA) were installed to measure soil moisture at multiple soil depths (Fig. 1a). Only data from
241 the top-most sensor (15 cm below the ground surface) were used in this study. Soil-moisture
242 sensors were located to capture representative variation in stand geometry and structure (i.e.,
243 within and between tree rows) to capture variation in surface soil moisture response to rainfall
244 events. While this spatial layout was intended to characterize the range of plot-scale forest
245 canopy and groundcover heterogeneity, the three measurements locations were within a 10-m
246 radius and thus represent localized (sub-plot) interception estimates. Within each clear-cut plot at
247 each site, meteorological data (rainfall, air temperature, relative humidity, solar insolation, wind
248 speed and direction) were measured using a weather station (GRSW100, Campbell Scientific,
249 Logan, UT; Fig. 4c) every 3 seconds and used to calculate hourly E by setting the canopy
250 resistance to zero [*Ghimire et al.*, 2017; *Gash*, 1995; *Monteith*, 1965]. Growing season forest

251 canopy LAI ($\text{m}^2 \text{m}^{-2}$) and groundcover (%) were measured at every 5-m node within a 50 m x 50
252 m grid surrounding soil moisture measurement banks. LAI was measured at a height of 1 m
253 using a LI-COR LAI-2200 plant canopy analyzer, and %GC was measured using a 1 m^2 quadrat.

254 To estimate β_s , mean $\Delta\theta$ values from the three surface sensors were calculated for all
255 rainfall events separated by at least 72 hours. Storm separation was necessary to ensure the
256 canopy and groundcover surfaces were mostly dry (and thus antecedent storage capacity = β_s) at
257 the onset of each included rainfall event. Rainfall events were binned into discrete classes by
258 depth and plotted against mean $\Delta\theta$ to empirically estimate P_s (e.g., Fig. 2). For each rainfall bin,
259 mean θ_i , \bar{P} and \bar{E} were also calculated to use in Eq. 10, which was then applied to calculate β_s .
260 Subsequently, we developed generalized linear models (GLMs) using forest canopy structure
261 (site-mean LAI), mean groundcover (% GC), hydrogeologic setting (shallow vs. deep
262 groundwater table), and site as potential predictors, along with their interactions, to statistically
263 assess predictors of β_s estimates. Because models differed in fitted parameter number, the best
264 model was selected using the Akaike Information Criteria (AIC; *Akaike*, 1974). Finally, we
265 calculated cumulative annual interception (I_a) and its proportion of total precipitation (I_a/P) for
266 each study plot using the mean β_s for each plot (across the 3 sensor banks), climate data from
267 2014 to 2016, and Eq. 15. Differences in I_a/P across sites and among plots within sites were
268 assessed using ANOVAs. All analyses were performed using R [*R Core Team*, 2017].

269

270

Results

271 Total Storage Capacity (β_s)

272 The exponential function used to describe the P - $\Delta\theta$ relationship (Eq. 1) showed strong
273 agreement with observations at all sites and plots (overall $R^2 = 0.80$; $0.47 \leq R^2 \leq 0.97$; Table 1)

274 as illustrated for a single site in Fig. 2. This consistency across plots and sites suggests that Eq. 1
275 is capable of adequately describing observed P - $\Delta\theta$ relationships, enabling estimates of β_s across
276 diverse hydroclimatic settings and forest structural variation. Estimates of β_s ranged from 0.01 to
277 0.62 cm, with a mean of 0.30 cm (Table 1). Plot-scale LAI was moderately correlated with plot-
278 mean β_s , describing roughly 32% of observed variation across plots (Fig. 4a). This relatively
279 weak association may arise because LAI measurements only characterize canopy cover, while β_s
280 combines canopy and groundcover storage. The best GLM of β_s (Fig. 4b) used %GC and an
281 interaction term between site and LAI ($R^2 = 0.84$ and $AIC = 253.7$, Table 2). The best GLM
282 without site used LAI and hydrogeologic setting (shallow vs. deep water table) but had reduced
283 performance ($R^2 = 0.55$ and $AIC = 338.3$; Table 2). All models excluding LAI as a predictor
284 performed poorly, so we report model comparisons only for those including LAI.

285 **Annual Interception (I_a)**

286 Despite having similar rainfall regimes (mean annual precipitation ranging from 131 to
287 154 cm yr⁻¹ across sites), mean annual interception (I_a) differed significantly both across sites
288 (one-way ANOVA $p < 0.001$) and among plots within sites (one-way ANOVA $p < 0.001$).
289 Estimates of I_a/P across all plots and sites ranged from 6 to 21% of annual rainfall (Table 1) and
290 were moderately, but significantly, correlated with mean LAI, explaining approximately 30% of
291 variation in I_a/P (Fig. 5a). Correlations among I_a/P and LAI were stronger for individual sites
292 than the global relationship ($0.51 \leq R^2 \leq 0.84$), except for site EF, where I_a was small and similar
293 across plots regardless of LAI (Fig. 5b; Table 1). This suggests that additional site-level
294 differences (e.g., hydroclimate, soils, geology) play a role in driving I_a , as expected following
295 from their effects on β_s described above.

296

Discussion

297 When combined with local rainfall data, near-surface soil moisture dynamics inherently
298 contain information about rainfall interception by above-ground structures. Using soil moisture
299 data, we developed and tested an analytical approach for estimating total interception storage
300 capacity (β_s) that includes canopy, understory, and groundcover vegetation, as well as any litter
301 on the forest floor. The range of β_s given by our analysis (mean $\beta_s = 0.30$ cm; $0.01 \leq \beta_s \leq 0.62$
302 cm) is close to, but generally higher than previously reported canopy-only storage capacity
303 values for similar pine forests (e.g., 0.17 to 0.20 cm for mature southeastern USA pine forests;
304 *Bryant et al.* 2005). Moreover, our estimates of β_s and annual interception corresponded to
305 expected forest structure controls (e.g., LAI and ground cover) on interception, further
306 supporting the feasibility of the soil moisture-based approach. However, we emphasize that a
307 more robust validation of the method using co-located and contemporaneous measurement using
308 standard techniques is warranted. Below we summarize the assumptions and methodological
309 considerations that affect the potential utility and limitation of the method.

310 An important distinction between our method and previous interception measurement
311 approaches is that the soil moisture-based method estimates composite rainfall interception of
312 not only the canopy, but also of the groundcover vegetation and forest floor litter. Rainfall
313 storage and subsequent evaporation from groundcover vegetation and litter layers can be as high,
314 or higher than, canopy storage in many forest landscapes [*Putuhena and Cordery*, 1996; *Gerrits*
315 *et al.*, 2010]. For example, *Li et al.* [2017] found that the storage capacity of a pine forest floor in
316 China was between 0.3 and 0.5 cm, while maximum canopy storage was < 0.1 cm. *Putuhena and*
317 *Cordery* [1996] also estimated storage capacity of pine forest litter to be approximately 0.3 cm
318 based on direct field measurements. *Gerrits et al.* [2007] found forest floor interception to be

319 34% of measured precipitation in a beech forest, while other studies have shown that interception
320 by litter can range from 8 to 18% of total rainfall [*Gerrits et al.*, 2010; *Tsiko et al.*, 2012; *Miller*
321 *et al.*, 1990; *Pathak et al.*, 1985; *Kelliher et al.*, 1992]. A recent study using leaf wetness
322 observations [*Acharya et al.*, 2017] found the storage capacity of eastern redcedar (*Juniperus*
323 *virginiana*) forest litter to range from 0.12 to as high as 1.12 cm, with forest litter intercepting
324 approximately 8% of gross rainfall over a six-month period. Given the composite nature of forest
325 interception storage and the range of storage capacities reported in these studies, the values we
326 report appear to be plausible and consistent with the expected differences between canopy-only
327 and total interception storage.

328 Interception varies spatially and temporally and is driven by both β_s and climatic
329 variation (i.e., P and E). Our approach represents storage dynamics by combining empirically
330 derived β_s estimates with climatic data using a previously developed continuous interception
331 model [*Liu* 1998, 2001]. Cumulative I_a estimates in this study ranged considerably (i.e., from 6%
332 to 21% of annual rainfall) across the 34 plots, which were characterized by variation in canopy
333 structure ($0.12 < \text{LAI} < 3.70$) and groundcover ($7.9 < \%GC < 86.2$). In comparison, interception
334 by pine forests reported in the literature (all of which report either canopy-only or groundcover-
335 only values, but not their composite) range from 12 to 49% of incoming rainfall [*Bryant et al.*,
336 2005; *Llorens et al.*, 1997; *Kelliher and Whitehead*, 1992; *Crockford and Richardson*, 1990].
337 Notably, most of the variation in this range is driven by climate rather than forest structure, with
338 the highest I_a values from more arid regions [e.g., *Llorens et al.* 1997]. Future work could also
339 consider seasonally disaggregated measurements to explore intra-annual variation in canopy
340 structure and litter composition [*Van Stan et al.* 2017].

341 Broad agreement between our results and literature I_a values again supports the potential
342 utility of our method for estimating this difficult-to-measure component of the water budget,
343 though additional direct comparisons would further support this assertion. Additionally, the
344 magnitude and heterogeneity of our I_a estimates across a single forest type (southeastern US
345 pine) underscores the urgent need for empirical measurements of interception that incorporate
346 information on both canopy and groundcover storage in order to develop accurate water budgets.
347 This conclusion is further bolstered by the persistent importance of site-level statistical effects in
348 predicting β_s (and therefore I_a), even after accounting for forest structural attributes, which
349 suggests there are influential edaphic or structural attributes that we are not currently adequately
350 assessing. For example, while estimated I_a in clear-cut plots was generally smaller than plots
351 with a developed canopy, as expected, one exception was at EF where the clear-cut plot
352 exhibited the highest I_a of the six EF plots (8.4%, Table 1). However, differences among all EF
353 plots were very small (I_a ranged only from 7.9 to 8.4 % of annual rainfall), a rate consistent with
354 or even lower than other clear cuts across the study. This site is extremely well drained with
355 nutrient-poor sandy soils and differs from other sites in that it has dense litter dominated by
356 mosses, highlighting the need for additional local measurements to better understand how forest
357 structure controls observed interception.

358 There are several important methodological considerations and assumptions inherent to
359 estimating interception using near-surface soil moisture data. First is the depth at which soil
360 moisture is measured. Ideally, θ would be measured a few centimeters into the soil profile,
361 eliminating the need to account for infiltration when calculating P_G in Eqs. (4-6) and thereby
362 alleviating concerns about lateral and preferential flow. Soil moisture data used here were
363 leveraged from a study of forest water yield, with sensor deployment depths selected to

364 efficiently integrate soil moisture patterns through the vadose zone. The extra step of modeling
365 infiltration likely increases uncertainty in β_s given field-scale heterogeneity in soil properties and
366 potential lateral and preferential flow. Specifically, lateral flow would delay wetting-front
367 arrival, leading to overestimation of interception, while preferential flow would do the opposite.
368 Despite these caveats, infiltration in our system was extremely well-described using wetting
369 front simulations of arrival time based on initial soil moisture and rainfall. As such, while we
370 advocate for shallower sensor installation and direct comparison to standard methods in future
371 efforts, the results presented here given the available sensor depth seem tenable for this and other
372 similar data sets.

373 Another methodological consideration is that, in contrast to the original Gash (1979)
374 formulation, Eq. 5 does not explicitly include throughfall. While throughfall has been a critical
375 consideration for rainfall partitioning by the forest canopy, our approach considers total
376 interception by aboveground forest structures (canopy, groundcover, and litter). A portion of
377 canopy throughfall is captured by non-canopy storage and thus intercepted. Constraining this
378 fraction is not possible with the data available, and indeed our soil moisture response reflects the
379 “throughfall” passing the canopy, understory and litter. Similarly, estimation of β_s using Eqs. 1-7
380 cannot directly account for stemflow, which can be an important component of rainfall
381 partitioning in forests [e.g., *Bryant et al.*, 2005]. We used the mean soil moisture response across
382 three sensor locations (close to a tree, away from the tree but below the canopy, and within inter-
383 canopy rows), which lessens the impact of this assumption on our estimates of β_s . Finally, Eqs.
384 (3-10) assume the same evaporation rate, E , for intercepted water from the canopy and from the
385 understory. Evaporation rates may vary substantially between the canopy, understory, and forest
386 floor [*Gerrits et al.*, 2007, 2010], especially in more energy-limited environments. Future work

387 should consider differential evaporation rates within each interception storage, particularly since
388 the inclusion of litter as a component potentially accentuates these contrasts in E .

389 Among the many challenges of measuring interception is the spatial heterogeneity of
390 canopy and ground cover layers, with associated heterogeneity in interception rates.
391 Consequently, researchers have suggested that 25 funnel collectors per hectare (or more) are
392 necessary to maintain mean relative error below 10% for long-term monitoring, with as many as
393 200 collectors needed for similar error rates during event sampling [Zimmerman *et al.*, 2010;
394 Zimmerman and Zimmerman, 2014]. Spatial averaging using larger trough collectors obviates
395 some of this sampling effort, yielding guidance of 5 trough collectors per hectare [Zimmerman
396 and Zimmerman, 2014], but still misses stemflow and groundcover variation. While the spatial
397 integration extent of troughs versus soil moisture sensors remains unknown, the three soil
398 moisture sensors we deployed per plot (with sensor locations selected to span stand spatial
399 heterogeneity) seem likely to capture similar spatial extents. Moreover, the strong
400 correspondence between our measurements and literature reported values for the magnitude of
401 interception storage as well as the forest structure controls (i.e., LAI and ground cover) on that
402 storage volume underscores that soil moisture measurements, at least in this setting, integrate key
403 quantitative aspects of the interception process.

404 If soil moisture measurements were subject to the same fine-grained spatial heterogeneity
405 as funnel-type collectors, it seems highly unlikely that our results would comport with literature
406 expectations as closely as they do. One plausible explanation for the consistency of our results is
407 that soil moisture averages across extant spatial heterogeneity in canopy processes, allowing soil
408 moisture measurements to provide comparable spatial integration to throughfall troughs, without
409 the considerable maintenance of litter accumulation associated with those troughs. This finding

410 is concordant with results from Metzger et al. (2017), who found correspondence between
411 throughfall and soil moisture changes across storm events of different sizes, leading these
412 authors to conclude that “net precipitation” can be intuited using soil water dynamics. Additional
413 soil moisture measurements would undoubtedly improve the accuracy of field estimates, and
414 indeed we recommend that more direct methodological comparisons are needed. However, our
415 results support the general applicability of the soil moisture-based approach for developing forest
416 interception estimates across a wide range of hydroclimatic and forest structural settings.

417

418 **Conclusions**

419 Rainfall interception by forests is a dynamic process that is strongly influenced by
420 rainfall patterns (e.g., frequency, intensity), along with various forest structural attributes such as
421 interception storage capacity (β_s) [Gerrits et al., 2010]. In this work, we coupled estimation of a
422 total (or “whole-forest”) β_s parameter with a continuous water balance model [Liu, 1997, 2001;
423 Rutter et al., 1975], providing an integrative approach for quantifying time-varying and
424 cumulative interception. We propose that soil moisture-based estimates of β_s have the potential
425 to more easily and appropriately represent combined forest interception relative to existing time-
426 and labor-intensive field methods that fail to account for groundcover and litter interception.
427 However, we emphasize that further experimental work is needed to validate this promising
428 approach. Soil moisture can be measured relatively inexpensively and easily using continuous
429 logging sensors that require little field maintenance, facilitating application of the presented
430 approach across large spatial and temporal extents and reducing the time and resources that are
431 needed for other empirical measures [e.g., Lundberg et al., 1997]. Finally, while our comparisons
432 with other empirical measures of forest canopy interception should be treated cautiously, this

433 approach yields values that are broadly consistent with the literature, and provide an estimate of
434 combined canopy and groundcover storage capacity that has the potential to improve the
435 accuracy of water balances models at scales from the soil column to watershed.

436

437

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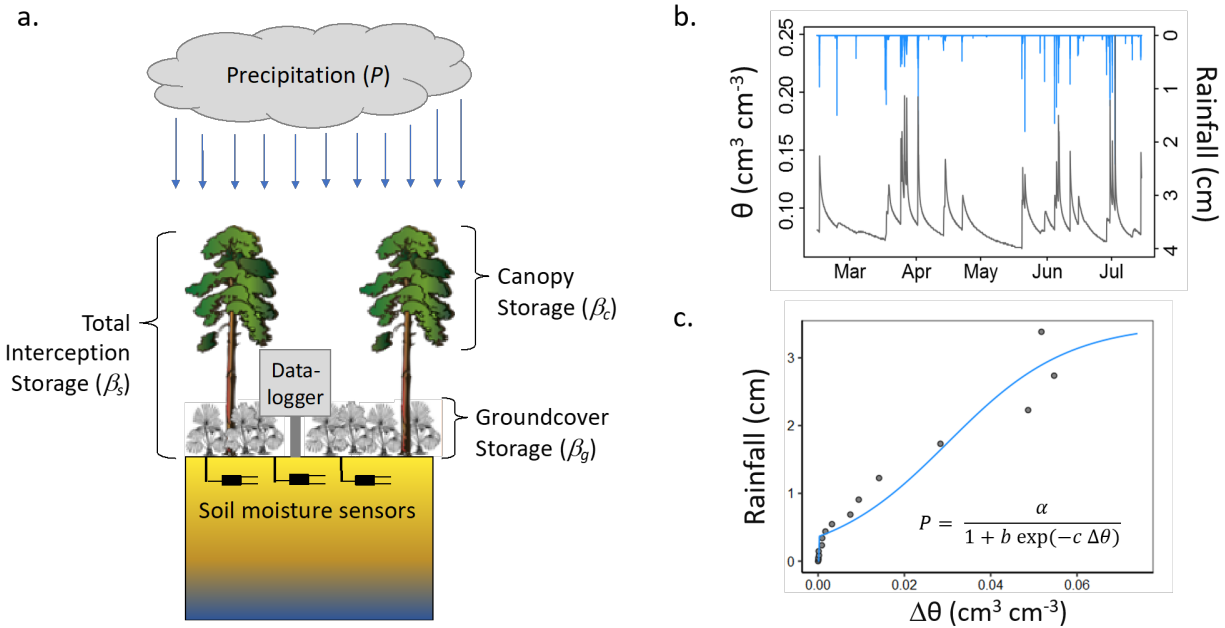
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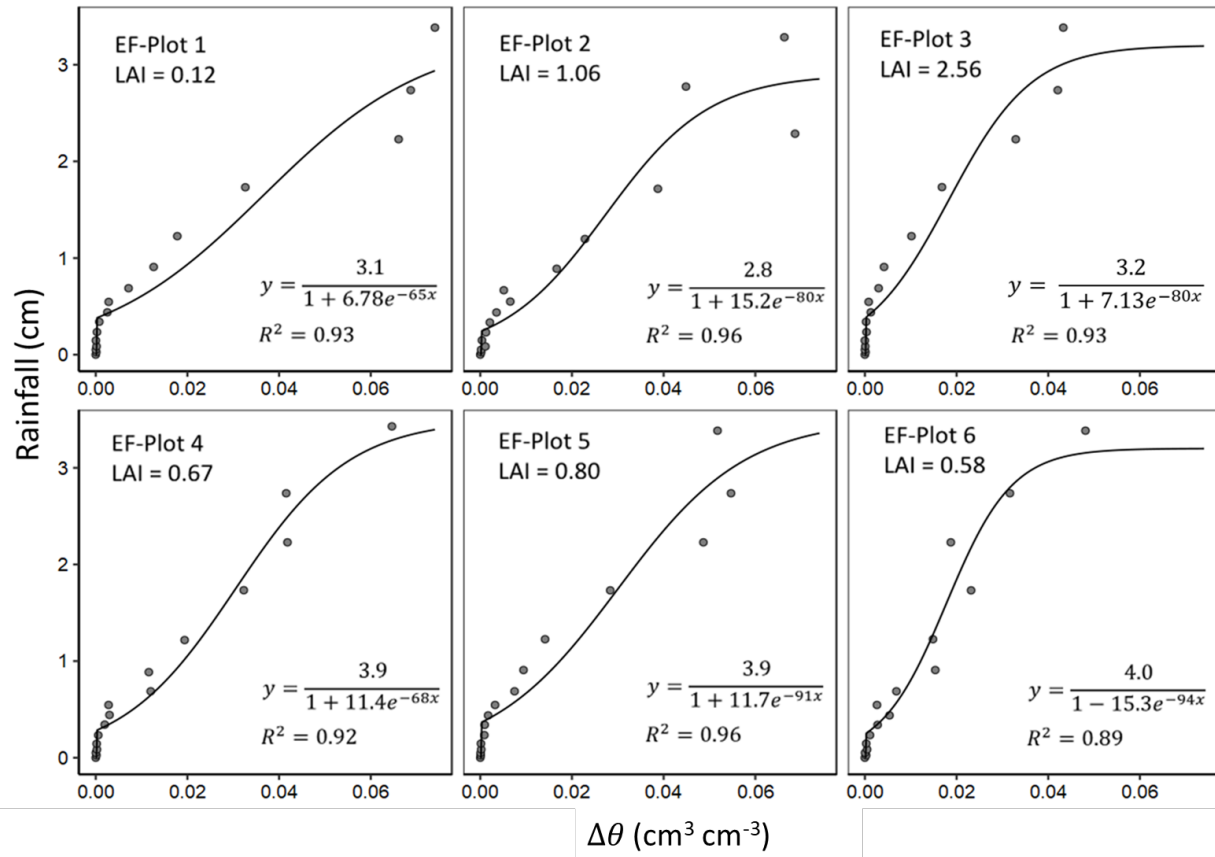
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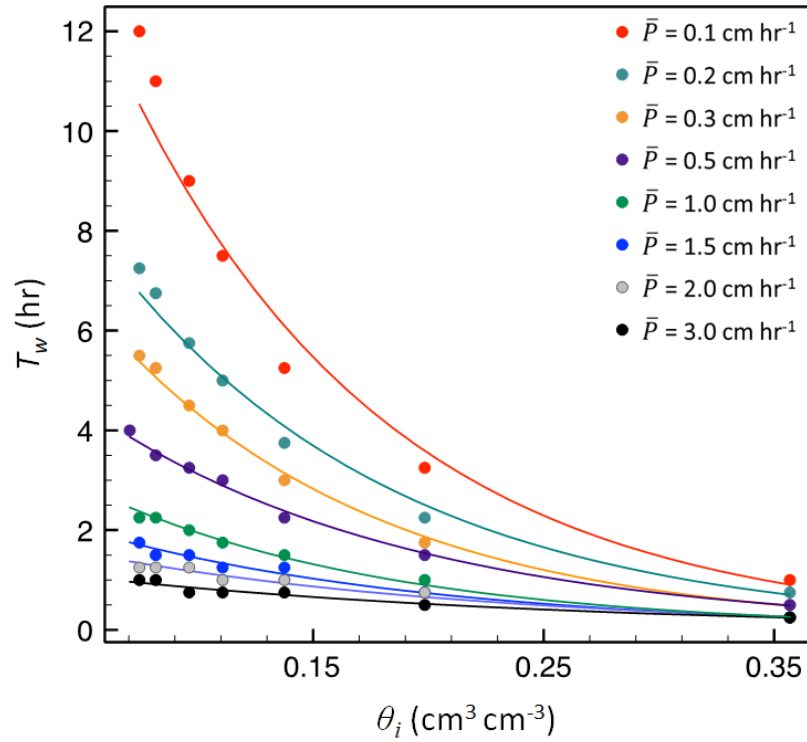
561
 562 Figure 1. (a) Schematic illustration of experimental setup and interception water storages, where
 563 total interception storage (β_s) is the sum of canopy storage (β_c) and groundcover (understory and
 564 litter) storage (β_g). (b) Example time series of rainfall (blue lines) and corresponding near-
 565 surface soil moisture content (θ , black line; observed at 15 cm in this study). (c) Resultant
 566 relationship between rainfall and change in soil moisture $\Delta\theta$ during rainfall, along with fitted
 567 model to extract the y-intercept (i.e., P_s).



568

569 Figure 2: Binned rainfall depths vs change in soil moisture content ($\Delta\theta$) for six plots at one of the
 570 study sites used in the study (Econfina; EF). The y-intercept of the fitted relationships were used
 571 to derive P_s in Eq. 2. Note different y-axis scale for EF-Plot 3.

572

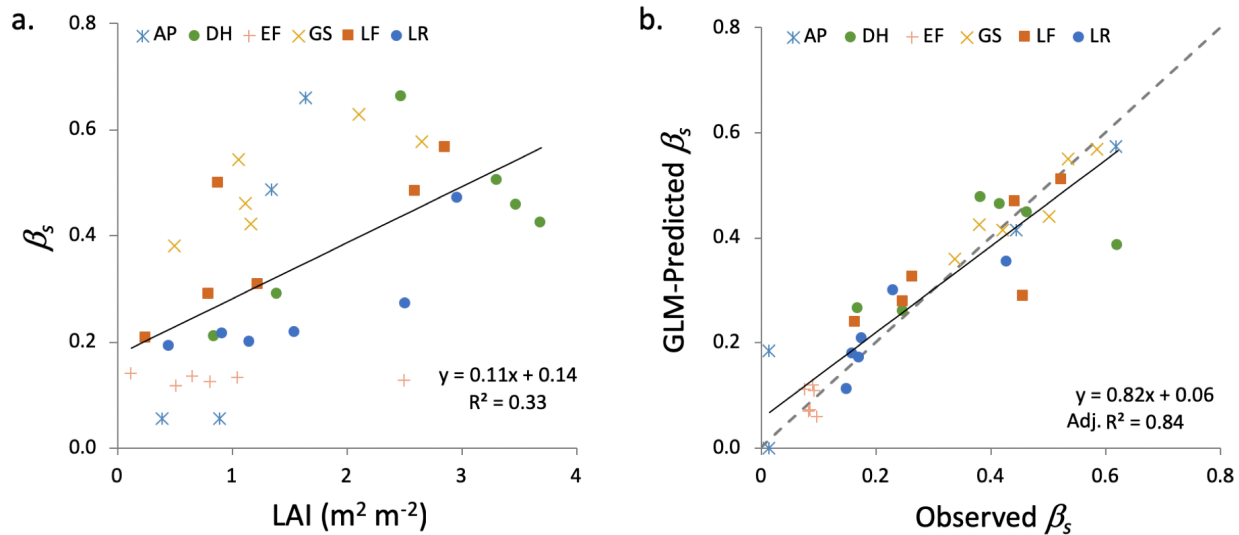


573

574 Figure 3: Initial soil moisture content (θ_i) versus time of wetting front arrival (T_w) at 15 cm depth

575 for a loamy sand soil. Dots are simulated results from HYDUS-1D simulation, and lines are the

576 exponential model given in Eq. 8, fitted for each rainfall rate, \bar{P} .



577

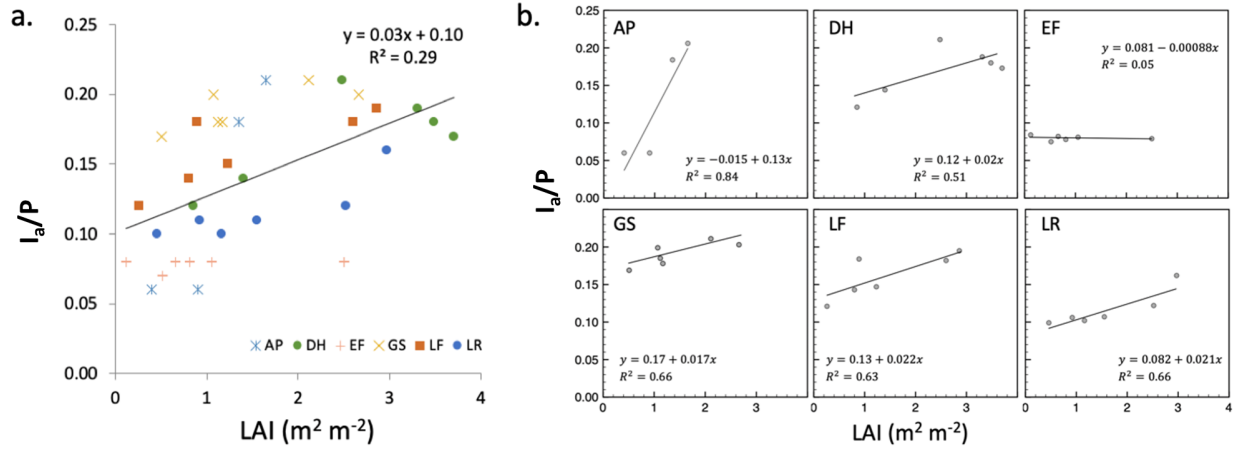
578 Figure 4. (a) Interception storage capacity (β_s) versus leaf area index (LAI) for all sites and plots.

579 (b) Modeled versus observed β_s using the best GLM, which included % groundcover vegetation

580 and an interaction term between site and LAI. The dashed line is the 1:1 line.

581

582



583

584

585 Figure 5. (a) Annual proportion of rainfall that is intercepted (I_a/P) intercepted versus LAI for all

586 sites and plots. (b) Site-specific I_a/P versus LAI relationships. The relationship is generally

587 strong except for the EF site, where the overall storage capacity is small across all values of LAI.

588

589 Table 1. Summary of storage capacity (β_s) and annual interception losses (I_a) for all sites and
 590 plots, along with plot characteristics (mean annual precipitation, P ; leaf area index, LAI; percent
 591 groundcover, %GC; and species). Note that the AP site only had four plots with the data required
 592 for the analysis.

Site	Plot	LAI	%GC	Species	β_s (cm)	R^2 ($\Delta\theta$ - P)	P (cm)	I_a/P
AP	2	1.65	47.6	SF Slash	0.620	0.31	145.0	0.206
AP	3	0.90	62.8	SF Slash	0.014	0.78	145.0	0.06
AP	4	1.35	49.1	SF Slash	0.445	0.67	145.0	0.184
AP	6	0.40	73.4	Longleaf	0.014	0.57	145.0	0.06
DH	1	0.85	86.2	Loblolly	0.170	0.90	131.5	0.121
DH	2	2.48	51.2	Slash	0.621	0.68	131.5	0.211
DH	3	1.40	39.2	Slash	0.249	0.49	131.5	0.144
DH	4	3.31	35.8	Slash	0.464	0.71	131.5	0.188
DH	5	3.70	27.1	Loblolly	0.383	0.69	131.5	0.173
DH	6	3.48	32.9	Slash	0.418	0.40	131.5	0.18
EF	1	0.12	13.6	Clearcut	0.099	0.93	153.8	0.084
EF	2	1.05	56.9	Slash	0.092	0.96	153.8	0.081
EF	3	2.50	11.8	Sand	0.086	0.93	153.8	0.079
EF	4	0.66	50.9	Slash	0.094	0.92	153.8	0.082
EF	5	0.81	17.9	Sand	0.085	0.96	153.8	0.078
EF	6	0.52	52.0	Longleaf	0.076	0.89	153.8	0.075
GS	1	1.07	67.9	Clearcut	0.502	0.84	132.4	0.199
GS	2	2.66	7.9	Slash	0.535	0.88	132.4	0.203
GS	3	2.11	71.5	Slash	0.587	0.82	132.4	0.211
GS	4	1.12	42.4	Slash	0.421	0.90	132.4	0.185
GS	5	1.17	45.6	Slash	0.382	0.76	132.4	0.178
GS	6	0.51	55.2	Longleaf	0.339	0.78	132.4	0.169
LF	1	0.26	43.5	None	0.166	0.85	136.3	0.121
LF	2	2.86	23.1	Slash	0.525	0.64	136.3	0.195
LF	3	1.23	24.9	Slash	0.266	0.72	136.3	0.147
LF	4	0.80	25.7	Slash	0.248	0.64	136.3	0.143
LF	5	2.60	12.3	Slash	0.443	0.63	136.3	0.182
LF	6	0.89	25.9	Longleaf	0.458	0.69	136.3	0.184
LR	1	0.46	34.0	Clearcut	0.151	0.96	144.5	0.099
LR	2	2.97	38.1	Slash	0.429	0.84	144.5	0.162
LR	3	0.92	47.0	Slash	0.173	0.95	144.5	0.106
LR	4	2.52	26.7	Slash	0.232	0.92	144.5	0.122
LR	5	1.55	28.1	Slash	0.177	0.96	144.5	0.107
LR	6	1.16	35.5	Longleaf	0.160	0.96	144.5	0.102

593

594 Table 2. Summary of generalized linear model (GLM) results for interception storage capacity
 595 (β_s). LAI is leaf area index, GC is groundcover, and WT is water table (shallow vs. deep). The
 596 best model (by AIC) is shown in bold.

Model #	Variable(s)	AIC	R ²
1	LAI	378.1	0.32
2	LAI + site	318.5	0.66
3	LAI * site	255.9	0.83
4	LAI * site + GC	253.1	0.84
5	LAI + WT	338.3	0.55
6	LAI * WT	339.8	0.55
7	LAI * WT + GC	341.8	0.55
8	LAI + WT + GC	340.3	0.55

597