

1 Lidar-based approaches for estimating solar insolation in heavily forested streams

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11 Abstract

12 Methods to quantify solar insolation in riparian landscapes are needed due to the importance of stream
13 temperature to aquatic biota. We have tested three lidar predictors using two approaches developed
14 for other applications of estimating solar insolation from airborne lidar using field data collected in a
15 heavily forested narrow stream in western Oregon, USA. We show that a raster methodology based on
16 the light penetration index (LPI) and a synthetic hemispherical photograph approach both accurately
17 predict solar insolation, explaining more than 73% of the variability observed in pyranometers placed in
18 the stream channel. We apply the LPI based model to predict solar insolation for an entire riparian
19 system, and demonstrate that no field-based calibration is necessary to produce unbiased prediction of
20 solar insolation using airborne lidar alone.

21 A. Introduction

22

23 Accurately quantifying solar insolation, defined as the amount of solar radiation incident on a specific
24 point on the Earth's surface for a given period of time, is important to many fields of study such as solar
25 energy, glacier dynamics, and climate modeling. In this study, we focus on the importance of solar
26 insolation for ecological applications. In forested ecosystems, trees interact with solar radiation through
27 shading, and thus solar insolation at fine spatial scales in these systems can vary widely. Understanding
28 the heterogeneous patterns of insolation below tree canopies has been important for numerous
29 applications, such as understanding the importance of sunflecks for understory photosynthesis, gaining
30 insight into the patterns of seedling regeneration in dense forests (Nicotra et al., 1999), and explaining
31 patterns of snowmelt (Hock, 2003) and soil moisture (Breshears et al., 1997).

32 The relationship between stream temperature and solar insolation is of particular interest in this study,
33 as high amounts of solar energy irradiating a stream can cause adverse ecological effects due to directly
34 increasing the temperature of the streams. . In northwestern North America, a large amount of research
35 has focused on the relationship between forest practices, stream temperature, and the corresponding
36 effect on river salmonid fishes (Holtby, 1988;Leinenbach et al., 2013;Moore et al., 2005a;Moore et al.,
37 2005b). Direct measurement of stream temperature with in-stream thermographs can be used to
38 quantify thermal diversity (Torgersen et al., 2012;Torgersen et al., 2007), but ground-based
39 measurements are time consuming, expensive, and impractical for large areas. In addition, stream
40 temperature measurements can only show the effect of forest management practices if taken before
41 and after trees are removed. In order to predict the potential effect of forest management practices on
42 stream temperature, models are often employed to estimate the amount of solar insolation irradiating
43 streams using remotely sensed data (Forney et al. 2013).

44 Several different methods have been utilized for measuring or predicting solar insolation on the ground.
45 Pyranometers are the most direct method for measuring insolation, capturing the solar radiation flux
46 density above a hemisphere as an electrical signal and cataloguing those signals in a datalogger (Kerr et
47 al., 1967). Once calibrated, these signals give a measure of the total direct and diffuse solar radiation
48 irradiating a point for a given period of time (Bode et al., 2014;Forney et al., 2013;Musselman et al.,
49 2015). While pyranometers give direct measurement of solar insolation for a defined period of time,
50 hemipshperical photographs allow indirect estimation of solar insolation for any point in time (Bode et
51 al., 2014;Breshears et al., 1997;Rich et al., 1994). Plotting the path of the sun in the area of sky captured
52 by the hemispherical photograph allows for calculation of direct solar radiation through identified
53 canopy gaps, while gap fraction across the entire hemisphere allows for calculation of diffuse radiation.
54 Analysis of hemispherical photographs requires assumptions of extra-terrestrial solar radiation and sky
55 conditions in order to produce solar insolation estimates. Understory light conditions can also be
56 modeled by creating a three-dimensional reconstruction of a forest from field-based biophysical
57 measurements (Ameztegui et al., 2012) or terrestrial laser scanning (Ni-Meister et al., 2008). Ground-
58 based measurements are limited by the time and cost required to collect data, and thus solar insolation
59 can only be calculated for relatively small spatial extents.

60 Airborne and satellite remote sensing methods provide a means for estimating solar insolation over
61 large spatial extents. Satellite-based methods utilizing passive remote sensing data can provide coarse-
62 scale estimates of solar radiation absorbed by tree canopies through radiative transfer models based on
63 spectral indices (Field et al., 1995;Asrar et al., 1992), but these methods are not suitable for fine-scale
64 application such as modeling stream temperature. Airborne lidar is the preferred method for
65 characterizing three-dimensional structure of forest canopies, and thus is also used to assess the
66 shading effect of those canopies. Below we discuss three different approaches that have been used in
67 previous studies to quantify solar insolation at ground level using aerial lidar.

68 *Raster Approaches*

69 Lidar data can be used to create raster datasets by selecting various attributes of lidar points within a
70 defined spatial neighborhood around a raster cell. One of the most common raster products for
71 assessing canopy structure is the light penetration index (LPI), the ratio of ground first return points
72 (typically less than 2 m in elevation above ground) to the total number of lidar first return points within
73 a given raster cell. This ratio has been shown to be useful for characterizing light extinction in canopies
74 according to the Beer-Lambert law (Richardson et al., 2009) and thus has been explored as a predictor of
75 understory light conditions (Musselman et al., 2013; Alexander et al., 2013; Bode et al., 2014). Solar
76 radiation calculators in GIS software can also be used to compute solar insolation on a lidar-derived
77 digital elevation model (DEM). Bode et al. (2014) combined a r.sun solar insolation model for the GRASS
78 GIS software based on a DEM with LPI to produce estimates of ground level solar insolation that showed
79 high accuracy compared to pyranometer-collected field data in a mixed forest in Northern California,
80 USA.

81 *Lidar Point Reprojection*

82 Lidar point returns can be reprojected from the X,Y,Z Cartesian coordinate system in which they are
83 most often delivered by a vendor into a spherical coordinate system which centers the point cloud
84 around a specific location on the ground. This reprojection allows for a circular graph of the lidar point
85 returns to be created around a point at ground level. Alexander et al. (2013) created a canopy closure
86 metric from these projected point graphs based on gap fraction, and found that this metric was
87 correlated to Ellenburg indicator values (which relate plants to their ecological niche along an
88 environmental gradient) of understory light availability. Moeser et al. (2014) created synthetic
89 hemispherical photographs from reprojected lidar returns, and solar irradiance at ground level was
90 calculated using traditional hemispherical photograph analysis software. The processed synthetic

91 hemispherical photographs showed good correlation to pyranometer measured solar irradiance at three
92 field sites in eastern Switzerland.

93 *Point Cloud Approaches*

94 Because lidar point clouds are typically represented in a three-dimensional Cartesian coordinate system,
95 it is possible to model the sun's position in relation to that three-dimensional space. The number of
96 lidar returns that are reflected from a defined volume between the direction of the sun and the ground
97 can then be calculated. These methods are computationally intensive, but have shown promise for
98 providing the most direct measure of understory light availability. Lee et al. (2008) calculated the
99 number of points within a conical field of view directed at the sun's location and created a model to
100 relate this to ceptometer measurements of photosynthetically active understory solar radiation at
101 specific times and locations in a pine forest in northern Florida, USA. This method is limited by its
102 reliance on raw lidar point counts specific to the actual and relative point densities within their lidar
103 acquisition. Raw point counts are affected by both changes in flight characteristics between missions,
104 and the patterns of flight line overlap within a mission. A different point cloud approach involves a linear
105 tracing of the sun's rays along their path to the ground, and Martens et al. (2000) demonstrated how a
106 ray-tracing algorithm could be used to characterize understory light conditions in a computer simulated
107 forest. Peng et al. (2014) combined a lidar-based ray tracing algorithm with field-collected canopy base
108 heights to produce an estimate of understory solar insolation based on the Beer-Lambert law that
109 compared well to field-collected pyranometer data but is limited in practical application because of its
110 reliance on field- measured data in its model. Musselman et al. (2013) used a ray-tracing algorithm to
111 produce highly detailed estimates of direct beam solar transmittance in 5-minute increments by
112 voxelizing the lidar data and summing the number of voxels that a ray intercepted between the point of

113 origin and the sun. The algorithm relied on site specific pyranometer measurements to calibrate and
114 adjust the beam transmittance, and therefore we were restricted from testing this method in this study.
115 Our objectives were to test the accuracy and precision of established methods of quantifying solar
116 insolation from aerial lidar within areas of narrow, heavily forested streams. We utilized two raster
117 approaches and one lidar point reprojection approach, three methodologies that had not been
118 previously applied and tested using high quality field data collected in heavily forested streams. We
119 evaluated the three methodologies using simple linear regressions that compared lidar derived metrics
120 to field-based pyranometer measurements of solar insolation and hemispherical photograph-based
121 measures of shade in Western Oregon, USA. Further, we sought to apply this method to quantify solar
122 insolation throughout a small headwater stream network.

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124 B. Methods

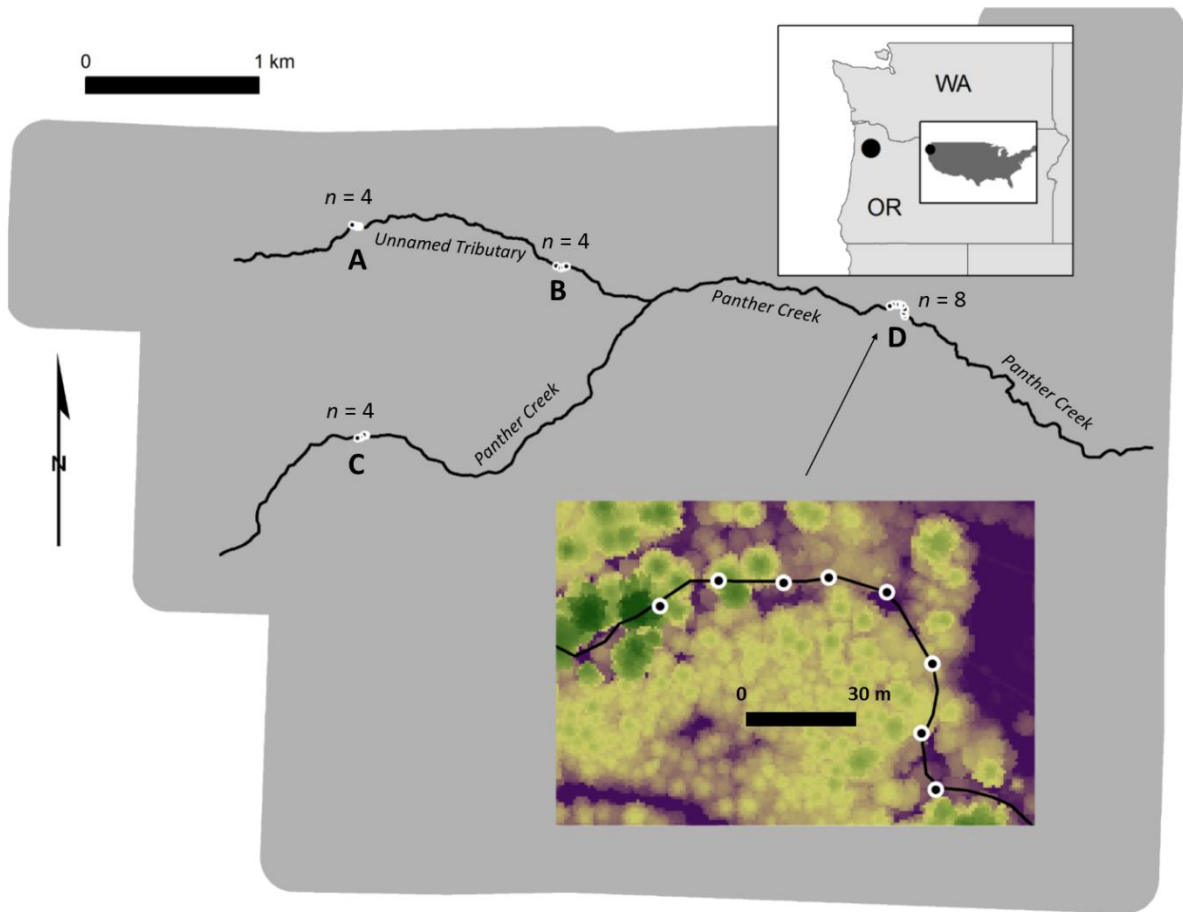
125 *Study Site*

126 All field locations were located within the wetted channel of Panther Creek and a tributary (Figure 1) in
127 narrow streams (1-6 m in width) located in the east side of the Coast Range of Oregon, USA within a
128 larger research area in which lidar has been used to quantify forest canopy structure (Flewelling and
129 McFadden, 2011). All field sites were within a mature Douglas-fir (*Pseudotsuga menziesii*) forest, with
130 other dominant trees including red alder (*Alnus rubra*), Western red-cedar (*Thuja plicata*), and Western
131 hemlock (*Tsuga heterophylla*). The elevation profile and description of the stream can be found in
132 (Richardson and Moskal, 2014). The center of the channel was manually digitized as a polyline in ArcGIS
133 using a combination of aerial imagery and the vendor-provided lidar DEM.

134 Four transects were installed in late June 2015 using a Leica Builder Total Station and georeferenced
135 using a Javad Maxor GPS unit. The locations of the transects can be seen in Figure 1, with the 19 point
136 locations used for capturing field data denoted by black dots surrounded by white circles (A contains 3
137 points, B and C contain 4 points, and D contains 8 points). Transect locations were chosen manually in
138 order to maximize variability in forest shade while allowing for safe access by the field crew. Each point
139 location was located within the stream channel and marked by driving rebar into the substrate until only
140 1 m was exposed above the water surface. Point locations were approximately 15 m apart within a
141 transect in order to allow data from multiple point locations to be collected by a single datalogger.

142 Two datasets were collected at each point location during the last two weeks of June in 2015. A
143 hemispherical photograph was collected using a Nikon CoolPix 4500 digital camera leveled on a tripod 1
144 m above the ground under uniform sky condition (Figure 2) utilizing a method to find the optimum light
145 exposure (Zhang et al., 2005). Each hemispherical photograph was analyzed using the Gap Light Analyzer
146 (GLA) program (Frazer et al., 1999) in order to produce estimates of percent transmittance for diffuse
147 and direct sunlight. An Apogee Instruments SP-110 self-powered silicon-cell pyranometer, leveled and
148 mounted to the rebar pole at 1 m height (Figure 3) was used to collect a full day's solar output at each
149 point location using the datalogger. The raw voltage values collected by the datalogger were calibrated
150 to solar irradiance using the closest publicly available meteorological data. All pyranometer datasets
151 were collected on cloudless days, except for transect A, and pyranometer data from transect A was not
152 used in this study. The calibrated pyranometer data from a point location from transect D is shown in
153 Figure 4. Note that the silicon-cell photodiodes, such as the SP-110 can, produce erroneous readings
154 under conifer canopies. A black body thermopile pyranometer would have been more appropriate for

155 this study but was not available to the authors.



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158 *Figure 1: Study area in northwestern Oregon (USA). The grey polygon is the extent of the 2015 lidar*
159 *acquisition. The black circles surrounded by white circles represent the 19 point locations. The letters A,*
160 *B, C, and D denote the four transects. The inset shows transect D and the background raster in the inset*
161 *is the lidar derived canopy height model with green representing tall trees and purple representing the*
162 *lowest heights. The direction of flow is from west to east.*

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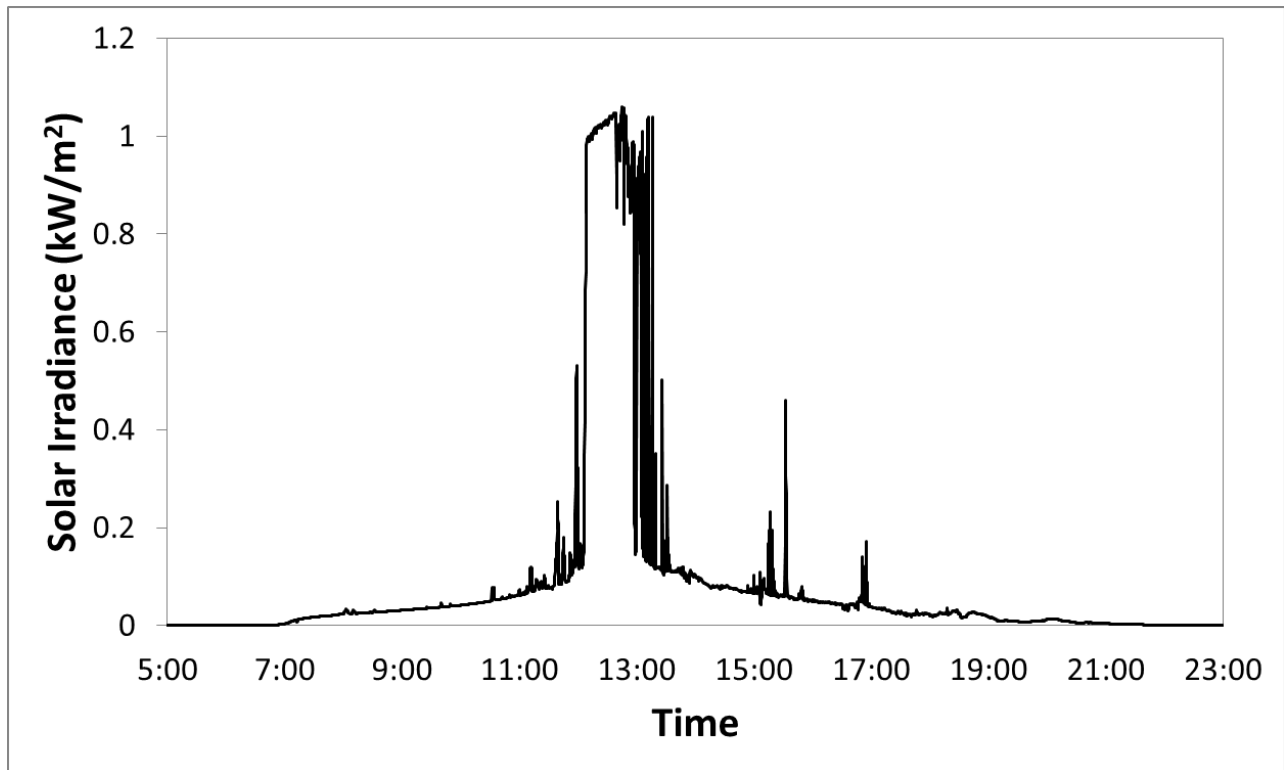
165 *Figure 2: Example of hemispherical photograph acquisition at a plot location in transect D.*



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167 *Figure 3: Example of pyranometer installation at transect D (note that pyranometer is mounted on south*

168 *side of pole at a height of 1 m).*



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Figure 4: Daily pyranometer output from sunset to sundown for a plot in Transect D

172 *Lidar Data and Analysis*

173 Airborne discrete-return lidar was acquired in June of 2015 according to the specifications described in
 174 Table 1. The vendor provided processed discrete lidar point returns as well as a lidar DEM and highest
 175 hit model at a pixel resolution of 1 m. The highest hit model was subtracted from the DEM to create a
 176 canopy height model (CHM) describing the vegetation height normalized to the ground surface. In
 177 addition, Fusion (McGaughey, 2009) was used to subtract the elevations of the raw lidar points from
 178 the ground elevation in the DEM to produce a normalized point cloud dataset (NPCD). Note that the
 179 perspective of the lidar analyses is in reference to ground height while the field data were collected at 1
 180 m above the ground. While this is a small difference, it could be a source of error in comparisons,
 181 especially at low solar angles.

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Table 1: Lidar Data Specifications

Acquisition Date	June 18, 2015
Sensor	Leica ALS80
Survey Altitude	1,400 m
Pulse Rate	394.8 kHz
Field of View	30 degrees
Mean Pulse Density	25.35 pulses/m ²
Overlap	100% with 65% sidelap
Relative Accuracy	4 cm
Vertical Accuracy	5 cm

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185 LPI was computed as:

186 $LPI = (R_g/R_t)$

187 *LPI* was computed in ArcGIS using a circular buffer with radius 10 m around each field point location

188 mirroring the radius used in Richardson et al. (2009) . *LPI* was also computed using a shifted square

189 buffer modified from the method of Bode et al. (2014) where the buffer side length (*s*) was calculated

190 based on:

191 $s = \frac{h}{\tan \theta}$

192 Where h is equal to the modal tree height across all our plots (34 m), and ϑ is equal to the maximum
193 lidar scan angle subtracted from 90° (75°), resulting in a buffer side length of 9.12 m. The square buffer
194 was shifted south to account for the seasonal solar angle in the northern hemisphere according to:

$$195 \text{ shift} = \left(\frac{s}{1 + \cos \sigma} \right) - s$$

196 Where σ is equivalent to the solar angle at noon on the date of interest. A solar angle of 68° was used
197 in this study, resulting in a southern shift of 3.42 m. The buffer tool, zonal statistics tool, and move
198 command were used to achieve the shift in ArcGIS. We also computed topographically influenced solar
199 radiation using the lidar DEM and the solar radiation function in ArcGIS, but found that there was no
200 significant difference across the plot locations and thus did not use these results in subsequent analysis.

201 Synthetic hemiphotos were created in Matlab using the method of Moeser et al. (2014) and analyzed for
202 diffuse and direct light transmittance in GLA. All statistical analyses were performed in R (version 3.4).

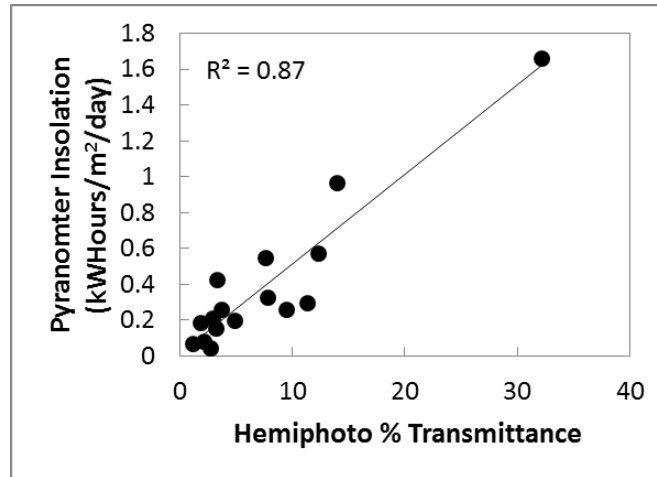
203 Longitudinal profiles of stream shading were created in ArcGIS in 1-m increments based on the
204 intersections of the stream polyline centerline with the raster output of modeled solar insolation.

205 C. Results and Discussion

206 *Comparison between Pyranometers and Hemispherical Photographs*

207 Figure 5 shows the correlation between field-collected pyranometer data and processed hemispherical
208 photographs, with data from transect A removed. These data are highly correlated ($r^2 = 0.87$), but these
209 data are also not equally distributed across a range of solar insolation. Many more plot locations were at
210 low levels of solar insolation than in areas of relatively low shade. This is very typical of the heavily
211 forested streams in northwestern North America. Note that none of our plot locations contained
212 transmittance greater than 40%.

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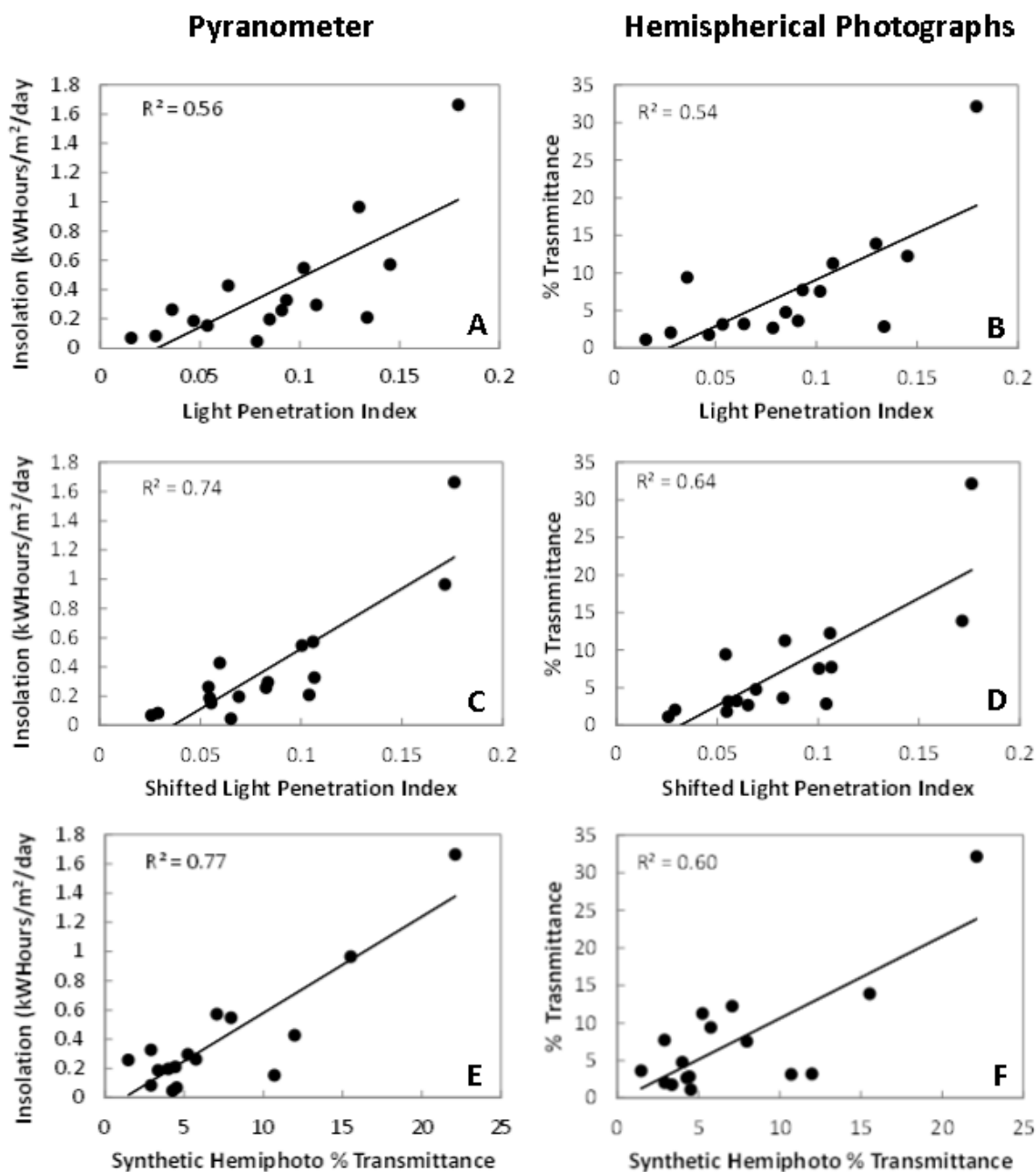
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215 *Figure 5: Comparison between pyranometer-measured solar insolation and daily diffuse and direct radiation*
 216 *canopy transmittance calculated from hemispherical photographs.*

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218 *Linear Regressions*

219 Pyranometer-based solar insolation and hemispherical photograph percent diffuse and direct radiation
 220 transmittance calculated at all point locations except transect A were compared to a three lidar
 221 predictors using simple linear regression. These results are shown in Figure 6. The LPI calculated using a
 222 10 m circle centered on the point location explained about 55% of the variability in both response
 223 variables, but the prediction accuracy improved when LPI was calculated using the shifted square buffer.
 224 Shifted LPI explained 74% of the variability in solar insolation and 64% of the variability in percent
 225 transmittance. Synthetic hemispherical photographs explained 77% of the variability in solar insolation
 226 and 60% of the variability in percent transmittance. Figure 6 shows comparisons between transects B, C,
 227 and D to make interpretation easier, but Table 2 shows the results of linear regressions between
 228 predicted variables and hemispherical photograph transmittance for all plot locations resulting in small
 229 reductions in the amount of variability explained. Table 3 gives parameters of slope and intercept
 230 resulting from the simple linear regression.



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233 *Figure 6: Simple linear regressions between lidar predictor variables and field measured pyranometer solar*

234 *insolation*

235 *(A, C, E) and hemispherical photograph % transmittance (B, D, F) omitting data from transect A*

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Table 2: Coefficients of determination for the simple linear regression between predictor variables and hemispherical photograph transmittance using three additional point locations from transect A

Predictor Variable	Coefficient of Determination (r^2)
Light Penetration Index	0.54
Shifted Light Penetration Index	0.54
Synthetic Hemispherical Photograph % Transmittance	0.45

256 *Table 3: Parameters from simple linear regressions. Note that all regressions are significant ($p < 0.05$). Data from*
 257 *transect A are excluded.*

258

Response Variable	Predictor Variable	Slope	Intercept
Hemispherical Photograph % Transmittance	Light Penetration Index	124.09	-3.29
	Shifted Light Penetration Index	142.2	-4.49
	Synthetic Hemispherical photograph % Transmittance	1.01	-0.32
Pyranometer Insolation	Light Penetration Index	6.73	-0.19
	Shifted Light Penetration Index	8.23	-0.30
	Synthetic Hemispherical Photograph % Transmittance	0.07	-0.08

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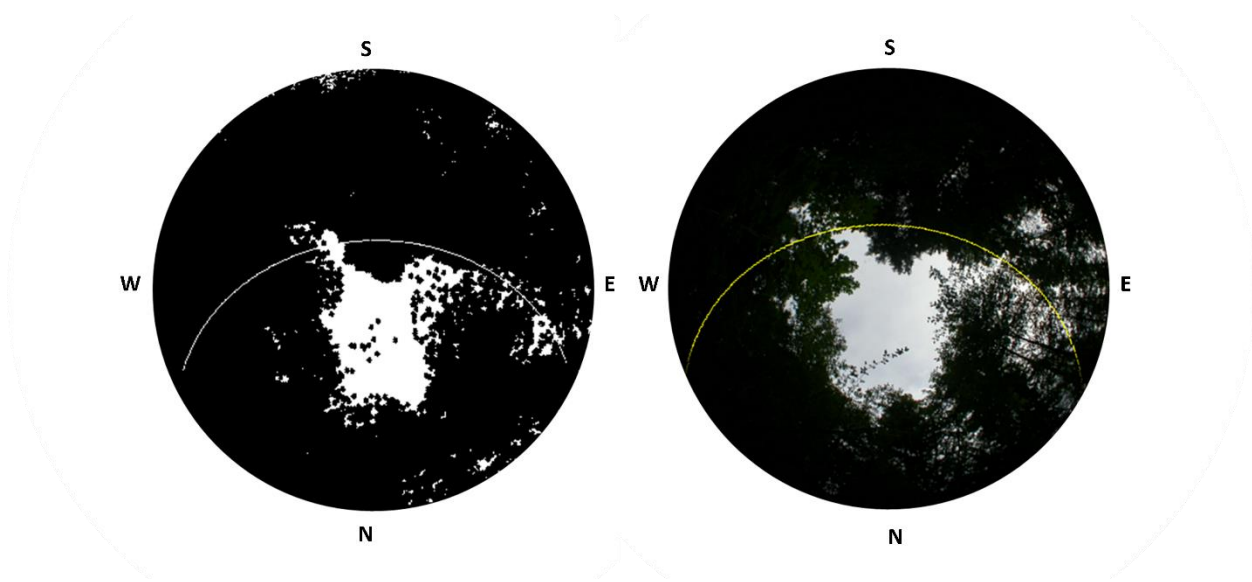
261 While both the raster-based shifted LPI approach and the lidar point reprojection synthetic
 262 hemispherical photograph approach explained more than 60 % of the variability in the field data, the
 263 limited range of solar insolation conditions at the point locations in our study may limit some of the
 264 conclusions that can be drawn. Excluding transect A, 14 of the 16 point locations received less than 0.8

265 kWhours/m²/day, leading to the other two point locations to exert a large degree of leverage on the
266 results. Note that these two point locations received less than 35% of the maximum solar insolation. The
267 three points in transect A all received less than 0.8 kWhours/m²/day and their inclusion in Table 2 did
268 not improve coefficients of determination, suggesting that all methods are not as effective at predicting
269 field measured values in areas of high canopy cover. The constraints of the study design requiring point
270 locations to be located in the stream made it impossible to achieve a greater range in solar insolation. It
271 is reasonable to expect that including more point locations receiving larger amounts of insolation would
272 have led to improved accuracy and greater coefficients of determination, as previous studies have
273 shown that accuracy increases as canopy cover decreases (Moeser et al., 2014; Musselman et al.,
274 2013; Richardson and Moskal, 2014).

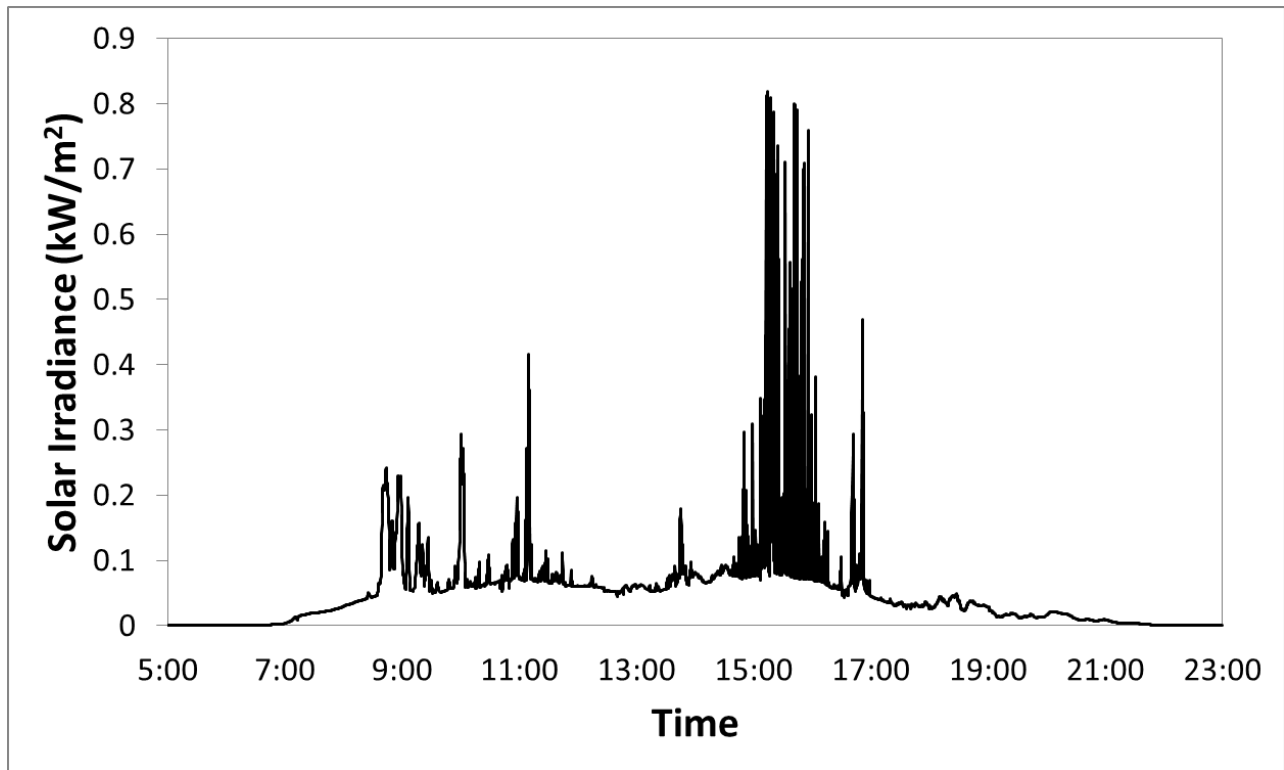
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276 One explanation of the decrease in variability at high canopy cover in regressions E and F shown in
277 Figure is demonstrated in Figure 7. Here, a synthetic hemispherical photograph from transect D is
278 compared to a field-captured hemispherical photograph with the GLA modeled sunpath superimposed.
279 This sunpath is critical for determining the quantity of direct light, but very small differences in the
280 center location of the two images can produce large differences in the modeled direct light. The sunpath
281 passes through a modeled canopy gap near solar noon on the synthetic hemispherical photograph,
282 while it intersects only canopy and misses the gap on the field-collected hemispherical photograph. Very
283 small registration errors can cause differences in transmittance at low light levels, and we suggest that
284 these errors are likely to cause the errors observed in the regressions. The daily pyranometer output for
285 the same point location is shown in Figure 8 to further aid comparison. The pyranometer is only briefly
286 exposed to full sunlight, highlighting the contribution of small gaps in the canopy.

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288 Understory vegetation is another likely cause of observed errors, as airborne lidar is inherently limited in
289 its ability to fully sample multi-layered canopies (Richardson and Moskal, 2011). We noticed several
290 points with differences between lidar predictors and field data that contained understory vegetation in
291 close proximity to the field instruments. The ideal scenario would be for the lidar scan angles to
292 precisely match the range of potential solar angles at each plot location, but this is currently impractical,
293 leading to an incomplete sample of the canopy light environment which contributes to the observed
294 errors.



295
296 *Figure 7: Sunpath superimposed on a synthetic hemispherical photograph (left) and a field acquired hemispherical*
297 *photograph (right) at a point location in Transect D. The letters represent the four cardinal directions.*



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Figure 8: Daily pyranometer output from sunset to sundown for the same plot as Figure 7.

300

301 *Modeled Solar Insolation*

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303 The correlations between lidar predictors and field data were strongest in Figure 6 C and Figure 6 E , and

304 these lidar predictors are both appropriate to use as the basis for estimating solar insolation across the

305 study area. Implementation of shifted *LPI* was the simplest and least time-intensive method, and we

306 chose to model solar radiation by multiplying shifted *LPI* by the maximum above canopy solar insolation

307 for June 20, 2015 and then computing a non-intercept linear regression (Figure 9). Removing the

308 intercept from the model lowered the coefficient of determination but provided a model that did not

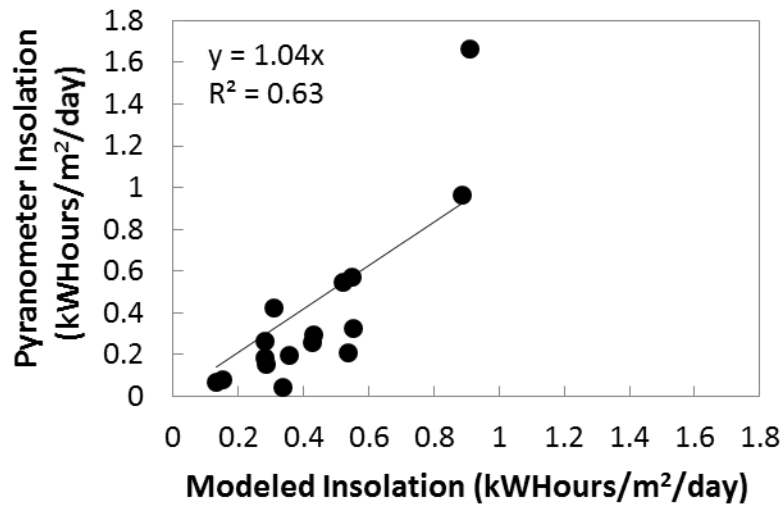
309 estimate negative values of solar insolation. Figure 10 shows the model applied across the study area.

310 The graphs show the pattern of solar insolation across the two reaches in the study, highlighting the

311 utility of these methods for predicting solar insolation in heavily forested streams across wide spatial

312 extents. Figure 11 shows the relative frequency of binned solar insolation values, highlighting the
313 dominance of heavily shaded areas (note that a dammed reservoir, point D on the map, contributes the
314 majority of the points in full sun).

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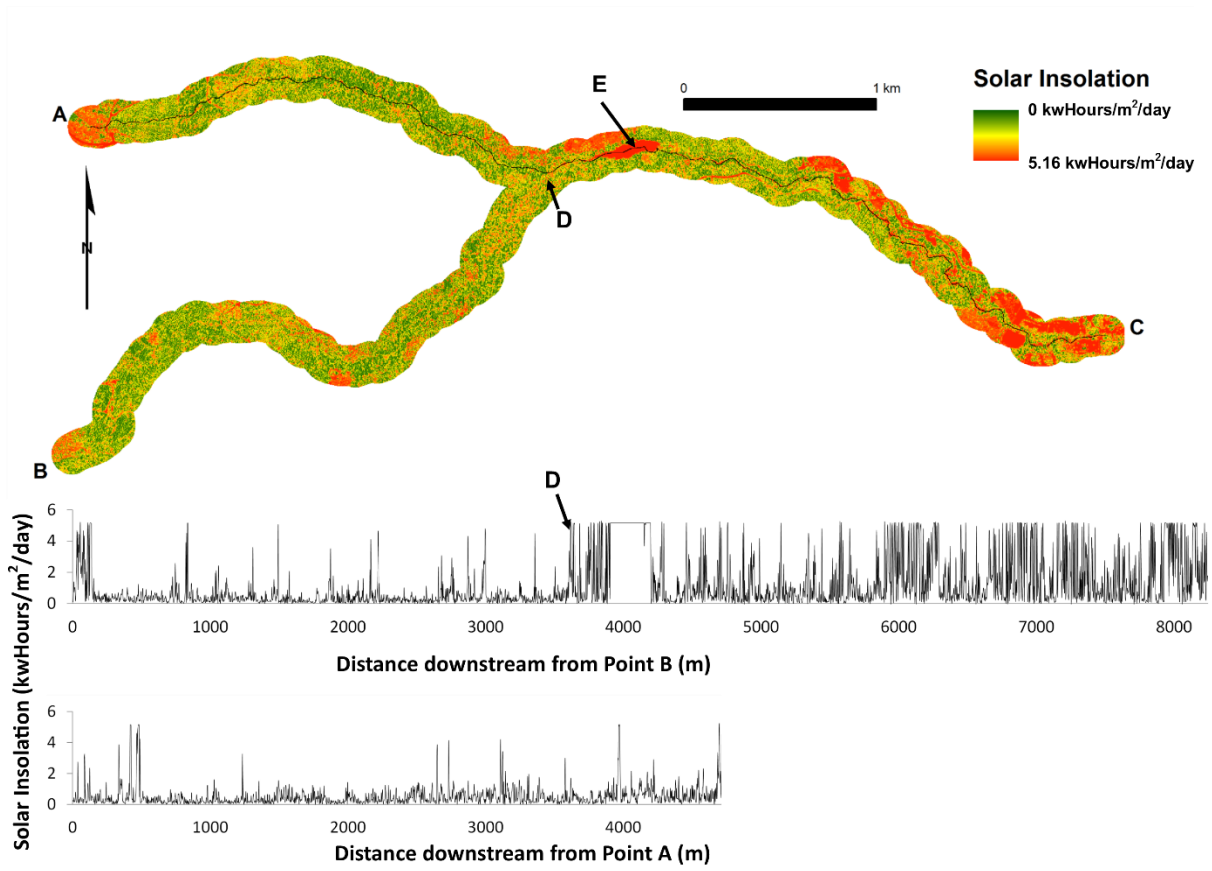
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317 *Figure 9: Model used for generation of landscape scale solar insolation estimates*

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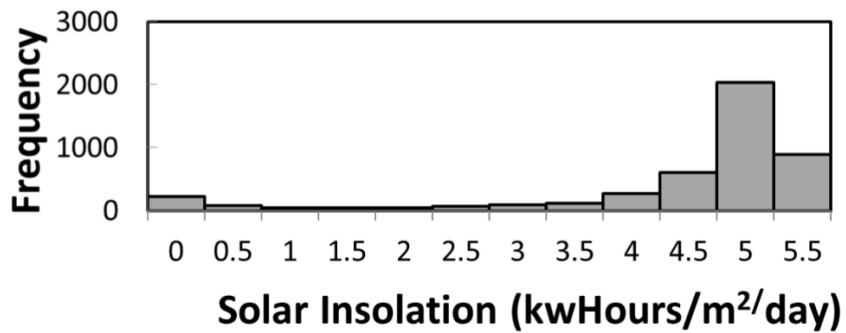


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323 *Figure 10: Map of model derived solar insolation for Panther Creek (top) and graph of model derived*
 324 *solar insolation for reach A-C (middle) and reach B-D (bottom). Point E is a dammed reservoir. Note the*
 325 *direction of flow is toward point C*

326



327

328 *Figure 11: Histogram of solar insolation pixel values along reach A-C from Figure 9*

329

330 The relatively unbiased results shown in Figure 9 show that field calibration is not required to produce
331 accurate estimates of solar insolation. However, information is still needed on local above-canopy
332 meteorological conditions, which can either be modeled from known solar outputs or collected from a
333 nearby meteorological station. Little bias was observed in comparisons between synthetic
334 hemispherical photograph transmittance and field-based hemispherical photograph transmittance
335 (Table 3). Therefore, both approaches tested in this study should not require field calibration.

336

337 D. Conclusions

338 We tested two approaches for estimating solar insolation from airborne lidar using field data collected
339 in a heavily forested narrow stream, showing that an LPI-based raster approach and a synthetic
340 hemispherical photograph approach can predict solar insolation and light transmittance. These results
341 should be interpreted with the caveat that our point locations contained few areas with high insolation.
342 We showed that the LPI-based model can be applied across the landscape, and we demonstrated that
343 no field-based calibration was necessary to produce unbiased prediction of solar insolation.

344 This study lays the groundwork for additional research on remote sensing methods for quantifying light
345 conditions in riparian areas over heavily forested streams. One method that we were unable to test is
346 ray-tracing and future research should continue to develop this approach. Second, research should focus
347 on exploring the limit of matching ground-based measurements to lidar-predicted solar insolation.
348 Lastly, the limitation of aerial lidar to quantify understory light conditions in multi-layered canopies
349 should be explored in more detail to better understand when and if airborne sensors are inappropriate
350 for these particular applications. In these circumstances, other sensors such as terrestrial lidar or

351 ground-based digital photographs utilizing structure from motion may provide additional useful
352 information.

353 E. Data availability

354 The GPS data, pyranometer data, processed hemispherical photograph data, spreadsheets used for data
355 analysis, and access to the LiDAR data can be found at <https://doi.org/10.17632/vwmwxw4hcj7.1>

356 F. Acknowledgements

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358 photographs and to Keith Musselman for advising on the applicability of ray-tracing methods. Guang
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360 field data collection. This work was supported by the Precision Forestry Cooperative, the Bureau of Land
361 Management, and the U.S. Geological Survey. Any use of trade, product or firm names is for descriptive
362 purposes only and does not imply endorsement by the U.S. government.

363 G. References

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