

How does initial soil moisture influence the hydrological response? A case study from southern France

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Abstract. The Cévennes-Vivarais region in southern France is prone to heavy rainfall that can lead to flash floods which are one of the most hazardous natural risks in Europe. The results of numerous studies show that besides rainfall and physical catchment characteristics the catchment's initial soil moisture also impacts the hydrological response to rain events. The aim of this paper is to analyze the relationship between catchment mean initial soil moisture $\tilde{\theta}_{ini}$ and the hydrological response that is quantified using the event-based runoff coefficient ϕ_{ev} in the two nested catchments of the Gazel (3.4 km²) and the Claduègne (43 km²). Thus, the objectives are twofold: (1) obtaining meaningful estimates of soil moisture at catchment scale from a dense network of in-situ measurements and (2) using this estimate of $\tilde{\theta}_{ini}$ to analyze its relation with ϕ_{ev} calculated for many runoff events. A sampling setup including 45 permanently installed frequency domain reflectancy probes that continuously measure soil moisture at three depths is applied. Additionally, on-alert surface measurements at ≈ 10 locations in each one of 11 plots are conducted. Thus, catchment mean soil moisture can be confidently assessed with a standard error of the mean of ≤ 1.7 vol% over a wide range of soil moisture conditions.

ϕ_{ev} is calculated from high-resolution discharge and precipitation data for several rain events with a cumulative precipitation P_{cum} ranging from less than 5 mm to more than 80 mm. Because of the high uncertainty of ϕ_{ev} associated to the hydrograph separation method, ϕ_{ev} is calculated with several methods, including graphical methods, digital filters and a tracer based method. The results indicate that the hydrological response depends on $\tilde{\theta}_{ini}$: during dry conditions ϕ_{ev} is consistently below 0.1, even for events with high and intense precipitation. Above a threshold of $\tilde{\theta}_{ini} = 34$ vol% ϕ_{ev} can reach values up to 0.99 but there is a high scatter. Some variability can be explained with a weak correlation of ϕ_{ev} with P_{cum} and rain intensity, but a considerable part of the variability remains unexplained.

30 It is concluded that threshold-based methods can be helpful to prevent overestimation of the hydrological response during dry catchment conditions. The impact of soil moisture on the hydrological response during wet catchment conditions, however, is still insufficiently understood and cannot be generalized based on the present results.

1 Introduction

The Cévennes-Vivarais region in southern France is prone to intense rainfall that can lead to the occurrence of flash floods in catchments of various scales ranging from small headwater catchments to ones of several thousand km² (Boudevillain et al., 2011; Braud et al., 2014). Flash floods are one of the most destructive natural hazards in Europe, both in terms of number of fatalities and economic damage (Gaume et al., 2009). Striking examples are the October 2015 flash flood of the Brague river that hit the French Riviera and the 2002 flash flood of the Gard river with 23 deaths and an estimated direct tangible damage of 1.2 billion Euro (Huet et al., 2003).

Despite the recognition of their high damage potential, the hydrological processes leading to the generation of flash floods are still insufficiently understood at a scale that is important for prediction and management (Gaume et al., 2009; Braud et al., 2014). One of the main problems that hinder flash flood prediction is the ignorance of the soil water retention capacity (Creutin and Borga, 2003). Other issues concern the lack of high-resolution data measured during flash flood events as well as the variety of catchment characteristics that influence their occurrence. The high degree of non-linearity in the hydrological response of catchments hinders the predictability of flash floods (Braud et al., 2014). This has motivated the installation of several measurement networks in first-order catchments especially in the USA and Australia (Slaughter et al., 2001; Renard et al., 2008; Moran et al., 2008; Baffaut et al., 2013) and - at the mesoscale and in a Mediterranean context - the FloodScale project in the Cévennes-Vivarais region (Braud et al., 2014, Nord et al., 2017).

Flash floods are usually associated with intense rainfall of > 100 mm in a few hours or long lasting rainfall (≈ 24 h) with moderate intensities (Braud et al., 2014) often generated by mesoscale convective systems and / or orographic precipitation (Marchi et al., 2010; Molinié et al., 2012; Panziera et al., 2015). However, the hydrological response to rain events varies greatly between catchments and between events. It can be quantified using the event-based runoff coefficient ϕ_{ev} , i.e. the ratio of event runoff volume to total event rainfall volume. The major drawback of this quantity is the lack of standard procedures for obtaining event runoff volumes and for defining the beginning and end of an event, which impedes comparisons between studies (Blume et al., 2007). Yet, event-based runoff coefficients of flash-flood events have been found to differ substantially, spanning nearly the full range of values from zero to one, with a high positive skewness in their frequency distribution (Merz et al., 2006; Blume et al., 2007; Norbiato et al., 2008; Merz and Blöschl, 2009; Marchi et al., 2010). They were shown to differ considerably between regions (Marchi et al., 2010), seasons (Li et al., 2012) and flood types (Merz et al., 2006), to increase with mean annual precipitation and event rainfall depth (Merz et al., 2006; Norbiato et al., 2009) and to depend on rain intensity, soil types and antecedent soil moisture conditions (Wood et al., 1990; Crow et al., 2005; Marchi et al., 2010; Hrachowitz et al., 2011; Penna et al., 2011; Li et al., 2012; Huza et al., 2014). Furthermore, a multitude of catchment characteristics also determine runoff generation and concentration, namely topography, geology, hydraulic routing and geomorphological controls (Braud et al., 2014).

Soil moisture is known to govern overland flow generation (Zehe and Sivapalan, 2008). As it controls threshold behavior, it implies qualitative changes of hydrological processes and the hydrologic system's response to rain events (Zehe and Sivapalan, 2008; Hardie et al., 2011). Initial soil moisture θ_{ini} , i.e. the soil water content at the onset of a rain event, is a crucial factor that influences the water storage capacity of the catchment as well as soil hydraulic properties and thus the hydrological response to rainfall events. It controls the soil moisture deficit, consequently, in the interplay with rainfall forcing, it determines whether soil saturation and saturation excess overland flow (Dunne and Black, 1970) occur during a rain event or not. Moreover, soil moisture controls the unsaturated hydraulic conductivity and thus the occurrence of infiltration excess overland flow (Horton, 1933). Given the high spatial and temporal variability of soil moisture and the incoherence of scale of the measurements with the catchment size, it remains challenging to obtain meaningful estimates of θ_{ini} at the catchment scale (Brocca et al., 2009a; Vereecken et al., 2014; Korres et al., 2015). There are multiple controls on soil moisture such as soil texture, topography and vegetation as well as small scale random variability (Jawson and Niemann, 2007; Garcia-Estringana et al., 2013; McMillan and Srinivasan, 2015). This problem is addressed by Vachaud et al. (1985) by introducing the concept of temporal stability, based on the finding that deviations of point measurements from the catchment mean can be persistent in time. Thus, optimum sampling locations can be identified and the number of samples required can be reduced (e.g. Brocca et al., 2009a, Huza et al., 2014).

Several studies consider the impact of initial soil moisture on the hydrological response of catchments on heavy rain events. Seasonality in the occurrence of flash floods (Gaume et al., 2009) and discharge magnitudes (Borga et al., 2007, Li et al., 2012) have been attributed to initial soil moisture conditions. Numerous modelling studies have shown the high sensitivity of the modelled runoff response to θ_{ini} and the importance of estimates of θ_{ini} at the catchment scale as initial conditions in event-based models (e.g. Castillo et al., 2003; Huang et al., 2007; LeLay and Saulnier, 2007; Berthet et al., 2009; Brocca et al., 2009b; Trambly et al., 2010, 2012; Li et al., 2012; Massari et al., 2014a,b, 2015; Grillakis et al., 2016). The dependence of catchment responses to initial soil moisture is also observed by Marchi et al. (2010) in a dataset comprising data for 25 flood events in 60 basins across Europe and on this study's site by Huza et al. (2014). This relationship is characterized by high non-linearity and threshold effects (Zehe et al., 2005; Huza et al., 2014). There is no consent on the importance of initial soil moisture during extreme events. Wood et al. (1990) conclude that catchment characteristics are important only for flood events with a low return period (up to ca. 10 y) whereas rainfall characteristics dominate those with a higher return period. On the other hand this finding is rejected in analyses of historic flash floods (Gaume et al., 2004; Borga et al., 2007; Le Lay and Saulnier, 2007) or flash flood data bases (Marchi et al., 2010) whose authors conclude that soil moisture plays an important role in the hydrological response, also under extreme conditions.

The aim of this study is to assess how soil moisture controls the hydrological response in a flash-flood prone area in southern France. The study is conducted in the two nested catchments of the Claduègne (43 km²) and Gazel (3.4 km²), Ardèche, France. Thanks to an exceptionally good data base, it is possible to obtain reliable estimates of the two catchments' initial soil moisture states for several rain events and to quantify the hydrological response with the event-based runoff coefficient. To this end, the spatio-temporal heterogeneity is assessed to obtain reliable estimates for mean initial soil moisture at the catchment scale as

well as its uncertainty. Other studies results suggest a dependence of ϕ_{ev} on initial soil moisture (e.g. Merz et al., 2006; Blume et al., 2007; Merz and Blöschl, 2009; Norbiato et al., 2009). However, most of these studies use indirect information such as remote sensing data, antecedent precipitation indices, initial baseflow, continuous soil moisture accounting models or the ratio of actual evaporation to precipitation. These approaches offer many advantages, such as the global availability of remote sensing data and the easier acquisition of this data (e.g. Brocca et al., 2009c). Numerous studies found good agreement of soil moisture data obtained from in-situ measurements and remote sensing (e.g. Brocca et al., 2009c, 2013, Huza et al., 2014) Nonetheless, case studies are important to confirm the results obtained with indirect data as well as the results from modelling exercises and to thoroughly understand the hydrologic functioning of local sites. At this studies site the impact of θ_{ini} on ϕ_{ev} was already considered by Huza et al. (2014). However, these authors used soil moisture data obtained from ASCAT satellite data which is fitted to in-situ measurements of topsoil moisture that were conducted on grasslands only. They considered five rain events only, so this relation could not be quantified unambiguously. Thus, this study's novelty is to analyze the relation between ϕ_{ev} and θ_{ini} when both are obtained from a comprehensive, high resolution data set allowing the assessment of the uncertainty of the two variables. Relying solely on in-situ data, we aim to (i) obtain a meaningful estimate of catchment scale soil moisture and its uncertainty and (ii) answer the research question how does soil moisture at the event onset affect the hydrological response?

2 Methods

2.1 Study site

For this study two nested sub-catchments of the Ardèche river in the Cévennes-Vivarais region of southern France are considered: the catchments of the intermittent Gazel stream and the perennial Claduègne river with an area of 3.4 and 43 km² respectively (Fig. 1).

Both catchments can be clearly divided into two distinct geologies: the northern part is constituted by the Coiron basaltic plateau that is bounded by a steep cliff of basaltic columns in the south, whereas the southern part of both catchments is a landscape of piedmont hills underlain by sedimentary limestone lithology (Nord et al., 2017). The basaltic plateau covers 51 % of the Claduègne catchment whereas its fraction of the Gazel catchment is only 23 %. Thus, the northern part is dominated by silty and stony soils on pebble deposit of basaltic component, while the soils in the southern part are predominantly rendzinas or other clay-stony soils, cultivated soils of loam and clay-loam and in the south of the Claduègne catchment lithosols and regosols (Nord et al., 2017). The terrain is hilly, and has a mean slope of about 20 %. The area is characterized by extensive agriculture and natural vegetation. Hence, the main land use / land cover types are grasslands, pastures, vineyards, forests and Mediterranean open woodlands. The vineyards are predominantly found on the finer textured soils in the southern part of the Claduègne catchment while the other land use types are found throughout the catchments. The average annual precipitation at Le Pradel at the outlet of the Gazel catchment is 1030 mm (Huza et al. (2014), original data: daily rain gauge data for 1958–2000 from Météo-France). For further details see Nord et al. (2017).

2.2 Data availability

As part of the HyMex (Hydrological Cycle in the Mediterranean Experiment, Ducrocq et al. (2014)) and FloodScale (Braud et al., 2014) projects and the Cévennes-Vivarais Mediterranean Hydrometeorological Observatory (OHM-CV, Boudevillain et al. (2011)), the area is exceptionally well monitored, thus high-resolution spatio-temporal data on rainfall, discharge and soil moisture is available. The data used for this study was published in Nord et al. (2017) and the link to download the data can be found at the publishers website: <https://www.earth-syst-sci-data.net/9/221/2017/essd-9-221-2017-assets.html>.

Soil moisture θ : two different sets of soil moisture data are available: continuous measurements and on-alert measurements. Soil moisture is continuously measured with 45 fixed soil moisture probes at nine plots (two vineyards, one fallow, six grasslands) within the Claduègne catchment since June 2013. Six of the plots are located in the piedmont hills and three on the basaltic plateau (Fig. 1). Concerning topography, most of the sensors are located on hillslopes which is the dominant topographic zone according to Savenije (2010) in the catchment. Only two plots are located in the riparian area and are potentially connected to the stream during rain events. At each plot, five frequency domain reflectometry (FDR) probes (Decagon 10HS soil moisture sensors) are installed at different depths: 10 cm ($n = 2$), 20–25 cm ($n = 2$) and in the subsoil (33–50 cm, $n = 1$). The temporal resolution is 15–20 min (Nord et al., 2017). The sensors in the vineyards were installed between two vine plants in a row which is a compromise between feasibility and representativeness of soil moisture in the vineyards which is heterogeneous due to transpiration. The accuracy and the range of the probe as provided by the manufacturer are ± 3 vol% and 0–57 vol%. The data is available from June 2013 – November 2014 in the dataset doi: 10.17178/OHMCV.SMO.CLA.13-14.1 presented in Nord et al. (2017).

In addition, following forecasts of heavy rain events on-alert measurements of soil moisture in 0–5 cm depth were conducted at 11 plots within the Gazel catchment with a hand-held FDR soil moisture sensor (Delta-T SM200). The accuracy and the range of the probe are ± 3 vol% and 0–50 vol%. The plots comprised four vineyards, five grasslands, one fallow and one cultivated field. All of these sites are located on hillslopes. The sampling sites were selected for reasons of accessibility, congruence with other measurements conducted during the FloodScale project and representativeness of the catchments' landscapes. All on-alert measurements were conducted in about 1 h at ≈ 10 randomly chosen measurement points within each plot. The distance between the measurement points was at least 1 m to ensure spatial independence (Huza et al., 2014). In the vineyards the measurements were conducted in between the rows of vine plants because this is where surface runoff started (visual inspection). On-alert measurements were done before and after 11 heavy rain events during the special observation periods of the HyMex Project in autumn (September–December) of the period 2012–2015. The dataset is found in the supplementary material of this article (S1).

Precipitation P : rainfall data was obtained from the HPiconet rain gauge network at a resolution of 1 min. The network consists of 19 tipping bucket rainfall gauges with a sampling surface of 1000 cm² and a resolution of 0.2 mm out of which 12 are located in the Claduègne catchment or its close vicinity (Nord et al. (2017), DOI: 10.17178/OHMCV.RTS.AUZ.10-14.1 Fig. 1).

Discharge Q : water level is continuously measured at the outlets of the two catchments with water level gauges at 2 min resolution (Gazel) and 10 min resolution (Claduègne) respectively (Nord et al., 2017). The water level is converted to discharge with a stage-discharge relationship established using the BaRatin framework (LeCoz et al., 2014) that also gives the uncertainty of the rating curve that is quantified as the 90 % confidence interval of discharge. The rating curve is based on numerous discharge measurements performed in 2012–2014 (Nord et al., 2017).

Additional data: spatial data used for this study include a digital elevation model with a resolution of 5 m (DOI: 10.6096/MISTRALS-HyMeX.1389) and the Ardèche soil data base by the French National Institute for Agricultural Research, Bureau de Recherches Géologiques et Minières and the French Department of Agriculture (DOI: 10.6096/MISTRALS-HyMeX.1385, Nord et al., 2017). Furthermore, a 0.5 m resolution land use map of the Claduègne catchment based on quickbird satellite images is available (DOI: 10.14768/mistrals-hymex.1381, Andrieu, 2015). Data on soil properties such as porosity, texture and saturated hydraulic conductivity was obtained during a measurement campaign in 2012 by Braud and Vandervaere (2015; DOI: 10.6096/MISTRALS-HyMeX.1321). Electrical conductivity (EC) of stream flow is continuously measured at the outlets of both catchments and measurements of EC of overland flow from two runoff and erosion plots in a vineyard in the south of the Gazel catchment are available (Cea et al., 2015).

15 2.3 Precipitation data processing

The catchment mean hyetographs for both catchments are calculated from the HPiconet rain gauge data with the method of Thiessen polygons. Rain events are separated by using a threshold of 12 h without precipitation being recorded at any rain gauge. The onset of an event was defined as the first time rain occurred after a dry period of at least 12 h, the end as the last time with rain being recorded by at least one rain gauge before the next dry period. The threshold of 12 h provides a good compromise between having a high number of events and excluding two separate events that are not independent from each other. Averaged catchment rainfall is then summed over the whole period of the rain event to calculate cumulative event precipitation P_{cum} . Furthermore, mean rain intensity I_{μ} over the whole event as well as maximum rain intensity I_{max} at 2, 10, 20, 30 and 60 minutes are calculated using the averaged catchment rainfall.

2.4 Soil moisture analysis

25 From both data sets (continuous and on-alert measurements) plot and catchment mean values are calculated for the initial and final state of each rain event. From the continuous data, mean values are calculated for all three depths and the profile mean value is calculated.

$\theta(x_{i,j}, t_{ev})$ refers to a spatially and temporally discrete on-alert soil moisture measurement, with the subscript i denoting the index of the n_i (usually ten) measurements within the plot, j denoting the plot and ev the event and the state (initial or final).

30 Mean soil moisture was calculated at the plot scale ($\bar{\theta}_j(t_{ev})$), for each land use class ($\bar{\theta}_{lu}(t_{ev})$) and at the catchment scale ($\bar{\bar{\theta}}_{ev}$). See Table 1 for the formulas. Plot means and catchment means obtained from the continuously measured data are

computed for all three layers l . Here, the plot mean is obtained by averaging not only the probes installed at the same depth and the same location, but also all measurements in a dry period of two hours before the onset or after the end of the rain event in order to diminish noise. The catchment mean averaged over the three layers $\bar{\theta}_{ev}$, i.e. considering the topmost 60 cm, is calculated from the continuously measured data (Eq. 4, Table 1). Finally, for all events the soil moisture storage change ΔS [mm/ev] in the upper 60 cm is computed from the difference between initial and final soil moisture (Eq. 5, Table 1).

It is assessed whether significant differences between the four land use classes exist by performing a visual inspection of boxplots or histograms and Student t-tests. Moreover, standard deviations σ as measures of spatial variability are calculated at the plot scale (σ_j^{inner} , Eq. 6, Table 1) and at the catchment scale (σ_{cat}^{inter} , Eq. 7, Table 1). Furthermore, σ is calculated between plots of the same land use ($\sigma_{lu}^{inter}(t_{ev})$, Eq. 8, Table 1) and between land use classes ($\sigma^{betw}(t_{ev})$, Eq. 9, Table 1).

As an estimate of the uncertainty of the calculated plot and catchment mean values, the standard error of the plot mean SEM_j^{inner} and the one of the catchment mean SEM_{cat}^{inter} are calculated. It should be noted that SEM_{cat}^{inter} is calculated from the on-alert measurements in the topsoil as well as from the continuous measurements over the soil profile, SEM_j^{inner} only from the on-alert measurements. The SEM is used as a measure of the confidence that the sample mean corresponds to the universal mean; it increases with the standard deviation and decreases with the number of sampling points.

Moreover, it is assessed whether temporal stability, i.e. consistency of soil moisture patterns at the catchment scale at different times of measuring (Vachaud et al., 1985), as reported by Huza et al. (2014) for six grassland plots in the Gazel catchment, is also found in the present on-alert data set: the relative spatial difference $\delta_{j,ev}$ of each plot corresponds to the relative difference between the plot mean and the catchment mean (Eq. 1); its temporal mean $\bar{\delta}_j$ is calculated with Eq. (2):

$$\delta_{j,ev} = \frac{\bar{\theta}_j(t_{ev}) - \bar{\theta}_{ev}}{\bar{\theta}_{ev}} \quad (1)$$

$$\bar{\delta}_j = \frac{1}{n_{ev}} \sum_{ev=1}^{n_{ev}} \delta_{j,ev} \quad (2)$$

The plot with the smallest $\delta_{j,ev}$ is the one that agrees best with the catchment mean on a given time of measurement. The temporal variability of the spatial difference σ_{δ_j} serves as an auxiliary variable to assess whether this behavior is stable in time:

$$\sigma_{\delta_j} = \sqrt{\frac{1}{n_{ev} - 1} \sum_{ev=1}^{n_{ev}} (\delta_{j,ev} - \bar{\delta}_j)^2} \quad (3)$$

2.5 Hydrological response

2.5.1 Event based runoff coefficients

In order to quantify the hydrological response of the catchment to different rainfall events, the dimensionless event-based runoff coefficient ϕ_{ev} is calculated for all events:

$$\phi_{ev} = \frac{Q_{ev,cum}}{P_{cum}} \quad (4)$$

To obtain cumulative event discharge $Q_{ev,cum}$, the time series of stream discharge Q_{tot} has to be separated into baseflow Q_b and event flow Q_{ev} . Q_{ev} is defined here to be the fast responding part of discharge that occurs during or directly after the rain event. It usually encompasses surface runoff or overland flow and fast subsurface flow. Q_b on the other hand is the slow responding part of discharge that lasts long after the rain event and feeds the stream between rain events. To obtain $Q_{ev,cum}$, Q_{ev} is summed up over the whole period of the event. The onset of a discharge event is defined as the first increase of discharge in response to a rain event. Defining the end of event discharge is more complicated and depends on the hydrograph separation method (Blume et al., 2007). Usually, the end of event flow is defined as the moment when Q_b equals Q_{tot} , but for some events the onset of a second event impedes this procedure which causes errors. Taking into consideration that there is no standard method for hydrograph separation and that results obtained with different methods can differ substantially (Blume et al., 2007), seven different hydrograph separation techniques are applied and compared (Sect. 2.5.2). The uncertainty of Q_{tot} associated with the stage-discharge relation can be important especially for high-flow conditions. This was taken into account by calculating ϕ_{ev} with the upper and the lower limit of the 90 % confidence interval of discharge obtained with the BaRatin framework.

2.5.2 Hydrograph separation

Straight line method. The straight line method (SL) is a simple, graphical method where baseflow during the event is interpolated by connecting the point in the event hydrograph at which discharge first increases as a response to the rain event with the first point on the falling limb of the hydrograph with the same discharge value. As this condition is often never met, the end of event flow is often determined by the onset of the next event or discharge below a threshold.

Constant-k method. The CK-method proposed by Blume et al. (2007) is based on the assumption that baseflow recession behaves similar to the outflow of a linear storage. Thus, baseflow at time step t can be described as exponential recession with the recession parameter k and initial flow Q_0 :

$$Q_b(t) = Q_0 e^{-k t} \quad (5)$$

k is calculated at each time step by differentiating eq. 5 and division by $Q_b(t)$:

$$k = - \frac{dQ}{dt} \frac{1}{Q_b(t)} \quad (6)$$

Event flow is assumed to terminate at time step t_e which is defined as the end of event runoff, once k becomes approximately constant. Baseflow is assumed to be equal to the discharge before the onset of event flow up to t_e when it equals Q_{tot} .

Electrical conductivity method. Hydrograph separation is also conducted based on electrical conductivity (EC) which serves as a natural tracer (Miller et al., 2014; Pellerin et al., 2008). The method relies on the assumption that stream flow Q_{tot} with electrical conductivity EC_{tot} is a mixture of subsurface flow Q_{sb} and surface flow Q_s , which have significantly different EC signals EC_{sb} and EC_s (Nakamura, 1971):

$$Q_{tot} = Q_{sb} + Q_s \quad (7)$$

$$Q_{tot} \cdot EC_{tot} = Q_{sb} \cdot EC_{sb} + Q_s \cdot EC_s \quad (8)$$

Thus, with given values for EC_{sb} (interpolated EC between values before the onset and after the end of event discharge) and EC_s (measured in overland flow collected at the outlet of four erosion plots representative of the signature of the rainfall flowing at the surface of soils developed on sedimentary rocks), a time series of Q_{sb} can be calculated. As no EC_s values were available for overland flow occurring on soils developed on basalts, covering half of the Claduègne catchment, the method could only be applied to the Gazel catchment, where the proportion of basaltic geology to total catchment surface is much smaller.

It should be noted that this method considers only the surficial part of event flow and is not able to separate the fast responding subsurficial flow occurring in the unsaturated zone. Thus, event flow is likely to be underestimated, especially in conditions when the latter plays an important role.

Recursive digital filter. The RDF method proposed by Lyne and Hollick (1979) uses a low-pass filter to separate high-frequency event flow signals from low frequency baseflow signals:

$$f(t) = a f(t-1) + \frac{1+a}{2} (Q_{tot}(t) - Q_{tot}(t-1)) \quad (9)$$

where $f(t)$ is filtered event flow at time t , a is a filter parameter that is usually in the range of $0.00 < a < 0.95$ (Nathan and McMahon, 1990) and $Q_{tot}(t)$ is original stream flow at time t . The data is passed to the filter several times, forwards and backwards. Recommendations for the number of passes vary depending on the temporal resolution of the discharge series (Ladson et al., 2013). The method is implemented in the R function `BaseflowSeparation` of the package `EcoHydRoLology` (Archibald, 2014).

Hysep filters (HS1 – HS3). Three further filtering approaches are implemented in the United States Geological Survey's (USGS) HySep program (Sloto and Crouse, 1996). It is based on finding minima in the discharge time series. The minima are determined either within fixed (HS1) or sliding (HS2) intervals or with a local minima algorithm (HS3). The interval width is adjusted according to Gonzales et al. (2009). It is applied using the R code of the USGS (2015).

3 Results

3.1 Spatial and temporal variability of soil moisture

The variability of soil moisture at the plot scale, determined from the on-alert measurements in the topsoil, is very high: the median range between the highest and the lowest measurement in one plot is 7.8 vol% but maximum values can get up to > 30 vol%. The mean of the inner-plot standard deviation $\sigma_j^{\text{inner}}(t_{\text{ev}})$ is 2.7 vol%. Values range from 1–8 vol% with no significant difference between the land-use classes. There is no significant correlation between plot means and standard deviations (Fig. 2a). The inner-plot standard deviation in the deeper layers, determined with the continuously measuring probes, cannot be confidently assessed because of the low number of probes installed in each plot at the same depth. However, the difference of two sensors installed at the same depth indicate, that the variability is in the order of the one derived from the on-alert measurements (Table 2).

The mean $SEM_j^{\text{inner}}(t_{\text{ev}})$ is 0.8 vol% with only three out of 228 data sets exceeding 2.0 vol%. Thus, the confidence that the population plot mean lies within the sample mean $\bar{\theta}_j(t_{\text{ev}}) \pm 2.0$ vol% is very high. This accuracy was achieved with about ten measurements per plot. The variability at catchment scale is also high (Table 2), the catchment mean can be confidently assessed nonetheless. The mean of the standard error of the Claduègne catchment $SEM_{\text{cat}}^{\text{inter}}$ is 1.5 vol%, the maximum is 1.7 vol%. The mean $SEM_{\text{cat}}^{\text{inter}}$ of the Gazel catchment is 1.3 vol%, the maximum is 1.7 vol%.

Both the on-alert and the continuous measurements were analyzed for differences between the land use classes. In the present study site the plot means of grasslands, vineyards and a fallow are not significantly different from each other (Student t test, significance level $\alpha = 0.05$). Only in the cultivated field mean soil moisture is significantly and systematically different from the one in the grasslands. A comparison of the variability between the four land use classes expressed as $\sigma^{\text{betw}}(t_{\text{ev}})$ to the one within land use classes $\sigma_{\text{lu}}^{\text{inter}}(t_{\text{ev}})$ or within plots $\sigma_j^{\text{inner}}(t_{\text{ev}})$ also reveals that it is smaller than both other standard deviations (Table 2). The initial and final soil moisture profile of the first major event in 2013 (ev. 27) shows, nonetheless, that there are differences in the profile shape and in the wetting behavior between grasslands and vineyard (Fig. 2c and 2d). While the grasslands have a nearly homogenous profile before the rain event, the vineyards have a much more pronounced vertical soil moisture profile with higher values in the deeper layers. In response to the rain event, the profile of the grasslands shifts towards higher soil moisture, with similar differences in each depth. In the vineyards, mainly the moisture in the topmost layer increases, whereas soil moisture in the subsoil hardly changes.

Figure 3 shows the relative spatial difference $\delta_{j,\text{ev}}$ of all plots for all on-alert measurements conducted from 2012 to 2015. It can be seen that temporal stability is found to some degree. The mean values of some plots are (nearly) consistently below the catchment mean (v4, v3, g5, f1, c1), others above (g4, g3, g1). This is also the case if deviations were related to the land use mean instead of the catchment mean (see e.g. the noticeable difference between grasslands g2 and g5 on the one hand and g1, g3 and g4 on the other hand). However, there are also plots with above average soil moisture for a certain period of time and below average soil moisture during other periods, indicated by a change in signs of $\delta_{j,\text{ev}}$ between events (v1, v2, g2). The plots with the lowest mean spatial difference $\bar{\delta}_j$ are v1, v2 and c1 (3, 4 and 8 % respectively). The one with the lowest temporal variability of the relative spatial difference ($\sigma_{\delta_j} = 5$ %) is the cultivated field c1.

Figure 4 shows the evolution of soil moisture in 10, 25 and 40 cm depth in autumn 2013. Due to several large rain events in July and August 2013 (not shown here), soil moisture at the beginning of the season is already relatively high. In the topsoil, however, soil moisture is much lower at the beginning of the season (Fig. 5). After the first major rain events, it remains constantly above 30 vol% at 10 cm depth and above 36 vol% in the deeper layers, with maximum values of around 42 vol% reached after major rain events. This value is not exceeded, even after rain events that occur during wet initial conditions. Temporal variability of soil moisture varies considerably between wet and dry conditions. Soil moisture in all continuously sampled depths increases rapidly as a response to rain events (Fig. 4). Differences between initial and final state in the topsoil can be even larger (Fig. 5). The rapid response is evident from the small lag between the peak of rainfall and the peak of soil moisture (usually less than two hours for all soil layers).

10 3.2 Event-based runoff coefficients

The event-based runoff coefficients ϕ_{ev} calculated for the Gazel catchment with seven hydrograph separation methods for 54 events range from 0 to 0.99 with large differences between the methods and a high positive skewness (Fig. 6a). In the Claduègne catchment, ϕ_{ev} was only calculated with the recursive digital filter method RDF and the HySep filter methods, but values still range from 0 to 0.97. The electric conductivity and constant-K methods result in the lowest values for ϕ_{ev} while the 3 HySep filters yield considerably larger values than all other methods. Except of the HySep filter methods, the other four methods correlate well with each other (Fig. 6b). The HySep filters correlate very well with each other ($R^2 \geq 0.96$ for all three pairs; not shown here), but to a lesser degree with the other methods (Fig. 6b). For the following sections, values of ϕ_{ev} determined with the RDF method are used for reasons explained in the discussion (Sect. 4.4).

The uncertainty of ϕ_{ev} associated with the stage-discharge relation is shown in Fig. 7 as black vertical error bars. In both catchments this uncertainty is very small for events with low ϕ_{ev} while it can get up to 0.28 (difference between ϕ_{ev} calculated with the 5 % and the 95 % confidence interval of discharge) for event 40 which is the one with the highest ϕ_{ev} and highest discharge in both catchments (Table 3 and Table 4). The uncertainty due to different ϕ_{ev} obtained by different hydrograph separation methods is visualized as gray vertical error bars in Fig. 7. It can be very high for any event regardless of the ϕ_{ev} and is often due to the discordance of the HySep methods with the other methods. The mean standard deviation of ϕ_{ev} calculated with different hydrograph separation methods is 0.03, when the HySep methods are excluded it decreases to 0.02. However, these measures are biased by the important positive skewness of the distribution of ϕ_{ev} .

Factors that are suggested to influence ϕ_{ev} include rainfall depth and rain intensity. Figure 7 shows the correlation of the meteorological forcing quantified as cumulative catchment rainfall depth P_{cum} , mean rain intensity I_{μ} , and maximum 20 min rain intensity $I_{max,20}$ with ϕ_{ev} . In the present data set there is a weak correlation between ϕ_{ev} and P_{cum} , I_{μ} and $I_{max,20}$ (Fig. 7). The correlations of ϕ_{ev} with maximum rain intensity calculated at 2, 10, 30 and 60 min time steps were worse than the one at 20 min. None of these variables can, therefore, explain more than 30 % of the variability of ϕ_{ev} . Figure 7 shows that events with similar rainfall characteristics (events 30 and 40, similar intensity) can have very different ϕ_{ev} . Additionally, similar ϕ_{ev} are

obtained for events with very different rainfall characteristics (events 22 and 39). These striking differences in catchment behavior can partly be attributed to differences in initial soil moisture as shown in the following section.

3.3 Soil moisture's impact on runoff generation

The hydrological responses concerning the temporal dynamics of soil moisture and discharge in reaction to rain events of the two catchments vary greatly. In Table 3 and Table 4 the characteristics of all rain events in autumn 2013 that generate event flow at the river gauges of the Gazel and / or Claduègne are given. The hyetographs, hydrographs and time series of catchment mean soil moisture of four of these events with very different behavior are exemplarily shown in Fig. 8: event 27 and event 30 occur at the beginning of the season when soil moisture is still relatively low. Rainfall leads to a considerable increase in soil moisture in all three layers and to a storage change ΔS in the 50 topmost cm of the soil profile that constitutes a notable share of cumulative precipitation. For event 30 on-alert surface soil moisture measurements show a sharp increase from 10.2 vol% before to 25.7 vol% after the event (Fig. 5). The runoff coefficients ϕ_{ev} of both events are very low. The within-event temporal dynamic of rainfall, soil moisture and runoff during event 27 is also noteworthy: the discharge peak does not follow the rainfall peak, which is closely followed by the steepest increase in soil moisture, but the second rainfall pulse that occurs when soil moisture is considerably higher than at the beginning of the event. As a response to this much smaller rainfall impulse, soil moisture rises only slightly. This behavior is also observed during event 40 where the first rainfall impulse leads to a sharp increase in soil moisture and only a small discharge peak, while the second rainfall pulse generates a substantial discharge peak and only a slight increase in soil moisture. Event 40 and event 53 both occur during wet initial soil moisture conditions, but event 53 has a much smaller ϕ_{ev} than event 40. During these two events also an inversion of the vertical soil moisture profile, i.e. temporally higher soil moisture at the topsoil than in deeper layers, can be observed approximately at the time of peak discharge. This inversion is an indicator of Hortonian overland flow. Overland flow was indeed observed during event 40 in vast areas in the north of the Claduègne catchment (Supplimentary material S2).

The large range of ϕ_{ev} of events with high $\tilde{\theta}_{ini}$ can also be seen in Fig. 9. While the three events with low $\tilde{\theta}_{ini}$ consistently have very low ϕ_{ev} , above a threshold of approximately 34 vol%, ϕ_{ev} can have a value anywhere between zero and one. An examination of Fig. 9 shows that both high $\tilde{\theta}_{ini}$ and high P_{cum} are necessary but not sufficient criteria for high ϕ_{ev} and that the relation between $\tilde{\theta}_{ini}$ and ϕ_{ev} is characterized by strong non-linearity and threshold effects. This is observed in both catchments and the threshold value is very similar for the Gazel and the Claduègne catchment. Further analysis of the relation between $\tilde{\theta}_{ini}$ and ϕ_{ev} for events with high P_{cum} and high $\tilde{\theta}_{ini}$ is limited because of the low number of events fulfilling these criteria and the uncertainty of both $\tilde{\theta}_{ini}$ and ϕ_{ev} .

Consideration of single events shows, that $\tilde{\theta}_{ini}$ can partly explain the high scatter in Fig. 7. The contrary behavior of events 30 and 40 can be explained by different initial soil moisture conditions. It can also be hypothesized that the high ϕ_{ev} of event 22 despite low P_{cum} , I_{μ} and $I_{max,20}$ is due to high initial soil moisture. For this event, that started on November 26th, 2012, only on-alert soil moisture is available and initial topsoil moisture is relatively high at 23.5 vol%. The event occurred late in the season

(26 November 2012, Fig. 5) two weeks after a heavy rain event with $P_{\text{cum}} = 72.5$ mm. Event 39 which has a similar ϕ_{ev} but higher P_{cum} , I_{μ} and $I_{\text{max},20}$, however also occurred during high initial moisture conditions which indicates that the relation between ϕ_{ev} , $\tilde{\theta}_{\text{ini}}$ and rainfall characteristics cannot easily be generalized.

4 Discussion

5 4.1 Soil moisture estimation at the catchment scale

The sampling design applied in this project proved to be efficient to assess spatial variability of soil moisture across scales, as well as to document temporal dynamics. The on-alert measurements of soil moisture allow a good estimate of the plot mean with a low mean SEM_j^{inner} of 0.8 vol% as well as an accurate estimate of the inner-plot variability, quantified as $\sigma_j^{\text{inner}}(t_{\text{ev}})$ during wet and dry conditions. On the other hand, the continuous soil moisture measurements cover a larger extent of the two studied catchments and different depths in the soil profile. Due to the higher variability at the catchment scale, the mean $SEM_{\text{cat}}^{\text{inter}}$ is somewhat higher (1.5 vol%). The values obtained for SEM_j^{inner} and $SEM_{\text{cat}}^{\text{inter}}$ show that at an accepted uncertainty of the mean of ± 2 vol%, the number of 10 measurements per plot is sufficient. This is consistent with the results of Zucco et al. (2014) who found a maximum number of 11 or 20 required samples at the plot scale and catchment scale respectively and the ones of Molina et al. (2014) who concluded that plot mean soil moisture in a Mediterranean mountain area was well represented with 9 probes. The review by Vereecken et al. (2014) shows that there is a wide range of estimates for these numbers and that they are site specific. The continuous measurements reveal the temporal evolution of soil moisture over the season and within events. The only drawback is the lack of continuous soil moisture estimates in the topsoil. The sampling at the plot scale and in nested catchments is considered to be a good approach to assess heterogeneity across scales and to cope with the change of scale problem (Braud et al., 2014).

20 In this study the inter-plot variability within one land use class $\sigma_{\text{lu}}^{\text{inter}}(t_{\text{ev}})$ usually exceeds the inner-plot variability $\sigma_j^{\text{inner}}(t_{\text{ev}})$. This is not consistent with findings of Huza et al. (2014) which may be due to different sampling strategies: whereas Huza et al. (2014) conducted measurements along 50 m transects, for this study random locations were sampled within one field in an area of ≈ 20 by 20 m. At scales larger than 10 m, they found a spatial structure revealed by a higher semi-variance at distances of more than 10 m in at least one of their transects.

25 The results of this study indicate differences between grasslands and vineyards in the vertical soil profile and in the response of the profile to rain events. These differences are most likely due to differences in soil texture, as vineyards are usually found on soils with higher clay content than the ones of the other land use types. However, there are no significant and systematic differences between the plot means of different land use classes. Thus, land use cannot be used as additional information to improve spatially distributed soil moisture estimation in the study site.

30 The cultivated field c1 shows a remarkable temporal stability of the difference of this plot's mean soil moisture and the catchment mean $\delta_{j,\text{ev}}$. This suggests that if the catchment mean has to be approximated by measurements in just one field, this

one is the best choice (Vachaud et al., 1985; Vanderlinden et al., 2012). Other fields show, however, that $\delta_{j,ev}$ is not consistent in time. The observation that several sites change the sign of $\delta_{j,ev}$ between measurements was also made at the plot scale on a grassland, a field cultivated with wheat and an olive grove by Vachaud et al. (1985) and at the catchment scale on grasslands by Huza et al. (2014). Here, notably the vineyards v1 and v2 are considerably wetter than the catchment mean throughout the autumn seasons of 2012 and 2013, dryer in 2014 and again wetter in 2015. Possible reasons include changes in cultivation. Especially tillage practices play an important role in the vineyards (not shown here). Therefore, conclusions based on this finding should be considered carefully. Moreover, the choice of the plot which best represents the catchment mean should include the temporal variability of $\delta_{j,ev}$ and should not be solely based on the minimal mean difference $\overline{\delta_j}$ which is in this case the one of v1 and v2.

10 4.2 Quantification of the hydrological response

The available precipitation and discharge data at a high spatio-temporal resolution is a major asset that is necessary to understand the hydrological processes at small scales and during short time spans that lead to flash flood generation (Nord et al., 2017). It allows to calculate the event-based runoff coefficient ϕ_{ev} and to estimate its uncertainty. The main sources of its uncertainty comprise that of the stage discharge relation which is especially important for events with high discharge and which was assessed with the BaRatin framework, the uncertainty associated to the choice of the method used for hydrograph separation and the uncertainty of the catchment mean precipitation. The latter source of uncertainty is not considered in this study. It stems from the rainfall measurements with tipping buckets and the interpolation between the rain gauges. Tipping buckets are known to underestimate precipitation at high intensities (Marsalek, 1981; Molini et al., 2005), thus, including radar data could improve the estimation of catchment mean rainfall even in relatively well gauged catchments such as the ones of the Gazel and Claduègne (e.g. Creutin and Borga, 2003; Delrieu et al., 2014; Abon et al., 2015).

In this study, the uncertainty associated to the hydrograph separation method exceeds that of the stage-discharge relation. The high range and positive skewness of event-based runoff coefficients is consistent with other study's results (Merz et al., 2006; Blume et al., 2007; Merz and Blöschl, 2009; Norbiato et al., 2009; Marchi et al., 2010). The dependence of ϕ_{ev} on rain characteristics suggested by other authors (Merz et al., 2006; Norbiato et al., 2009) was not entirely confirmed in this study as none of the rain characteristics examined here (P_{cum} , I_{μ} , $I_{max,20}$) could explain more than 30 % of the variability in ϕ_{ev} .

Each of the hydrograph separation methods used here has advantages and disadvantages. The method based on electric conductivity (EC) has a physically based foundation as it distinguishes components with different EC and represents subsurface flow dynamics. This method could not be applied to both catchments because values for surface flow EC_s were only available from Le Pradel in the south of the Gazel catchment and it is assumed that EC_s on the basaltic plateau differs considerably while this geology accounts for a large part of the Claduègne catchment. Furthermore, it is not possible to conduct a three component hydrograph decomposition with the available data, so unlike with the other methods, the fast reacting subsurface flow is considered to be baseflow. Thus, event discharge is underestimated.

Unlike the other methods, the Constant-k (CK) method offers a physical explanation for the end of event flow. The method builds on the assumption of baseflow behaving like the slow responding outflow of a linear reservoir. For the discharge data of the Gazel, this method could not always be applied because of the low discharge that results in “steps” in the data and high noise so the threshold for defining that k is constant as proposed by Blume et al. (2007) was never reached. An adjusted
5 threshold yielded reasonable results for some but not all events.

The straight line method was rejected because it does not consider baseflow dynamics and the end of event flow has to be determined arbitrarily. The filter methods have the advantage of being easy to apply to all data sets without further data treatment or demand of additional data but these methods are very sensitive to parameters such as the interval width (HySep filters) or the number of passes (RDF). The HySep filters were discarded because of the disagreement with the other methods.
10 Thus, the RDF method was used for all further analyses because it correlates well with the EC and CK methods and can easily be applied to all events and both catchments. The number of passes had to be calibrated as suggested by Ladson et al. (2013) in a manner that ϕ_{ev} is below 1 for all cases and that it is slightly higher than the value obtained with the EC method in order to compensate for the underestimation of event discharge. Nonetheless, underestimation of event discharge is still a source of uncertainty.

15 4.3 The impact of initial soil moisture on the hydrological response

The relation between ϕ_{ev} and $\tilde{\theta}_{ini}$ is not as clear as one might have expected from other studies results. Moreover, both variables are still subject to large uncertainties. Catchment mean initial soil moisture $\tilde{\theta}_{ini}$ below a threshold of 34 vol% inhibits high ϕ_{ev} . However, only three of the events considered here occur during such dry conditions, so further measurements would be useful to corroborate this finding. Threshold effects in the relation of ϕ_{ev} and $\tilde{\theta}_{ini}$ are also observed by other authors (e.g. McMillan
20 et al., 2014; Hrachowitz et al., 2011). In the Mediterranean context, the thresholds obtained by Huza et al. (2014) in the Gazel catchment and Braud et al. (2014) in the Valescure catchment (22 and 25 vol% respectively) are lower than the one obtained here. The threshold at 45 vol% observed by Penna et al. (2011) in a 1.9 km² headwater catchment in the Italian Dolomites on the other hand is higher than the one obtained here. McMillan et al. (2014) show that thresholds in different subcatchments of a 50 km² catchment in New Zealand are highly variable: They range between 27 and 58 vol% and are more or less pronounced
25 in different subcatchments. These differences might be due to different soil and land use features, climate and different sampling designs. The values for $\tilde{\theta}_{ini}$ that Huza et al. (2014) used are obtained from satellite data, while this study uses in situ data from several land use classes. Moreover, a profile mean is considered here, while Huza et al. (2014) used only values of topsoil moisture. Furthermore, different methods were applied for hydrograph separation. Huza et al. (2014) used a method similar to the HySep 3 filter, which yielded different results than the other methods applied for this study.

30 The high range of ϕ_{ev} obtained at high $\tilde{\theta}_{ini}$ also agrees with findings of Huza et al. (2014). It indicates that the hydrological response is influenced by other factors as well. The parameters describing the impact of meteorological forcing (P_{cum} , I_{μ} and $I_{max,20}$) neither explain that variability. When only events with high cumulative precipitation are considered, the range is still

very high. Results obtained in virtual experiments (Merz and Plate, 1997; Bronstert and Bárdossy, 1999; Zehe and Blöschl, 2004) showed that spatial patterns of soil moisture and threshold effects strongly impact the runoff response. The latter authors show, that especially during initial moisture conditions close to the threshold, the runoff response depends strongly on the resampling of spatially distributed soil moisture. Therefore, actual, small-scale soil moisture patterns that control connectivity of pathways but are not reflected in the catchment mean value are a possible explanation for the very diverse runoff behavior. On the other hand, Morbidelli et al. (2016) conclude that spatial heterogeneity of $\tilde{\theta}_{ini}$ does not affect the runoff response for events that are associated with floods, so more research is needed on this topic. Additionally, subsurface flow along preferential flowpaths can contribute to high ϕ_{ev} and Hortonian overland flow is not directly related to $\tilde{\theta}_{ini}$ but produces a substantial proportion of event flow.

The results of this study partly confirm the suggestions of other authors (i.e. Brocca et al., 2009b; Javelle et al., 2010; Grillakis et al., 2016) to consider estimates of initial soil moisture in flash flood warning based on the dependence of ϕ_{ev} on $\tilde{\theta}_{ini}$. This offers high potential for predictions in poorly gauged or ungauged basins given the global availability of remote sensing soil moisture data (Crow et al., 2005; Beck et al., 2009; Brocca et al., 2009c; Massari et al., 2014a,b). Threshold-based warning systems are advocated e.g. by Norbiato et al. (2008). Including a threshold value for initial soil moisture could prevent false positive flash flood warnings in cases when high precipitation is expected under dry initial catchment conditions, while above-threshold soil moisture in combination with high precipitation increases the likelihood of high runoff coefficients. This threshold seems not to be scale-dependent. However, the threshold values differ between catchments and depend to a high degree on the methodology to determine it as indicated by the different values in this study and the one by Huza et al. (2014). Furthermore, there are high data requirements to determine such thresholds and it is not known whether they can be transferred from one catchment to another, so it is not applicable for operational flash-flood warning. Moreover, the high scatter of ϕ_{ev} under high initial soil moisture conditions suggests that the relation between ϕ_{ev} and $\tilde{\theta}_{ini}$ is very complex and depends on other factors and processes that are still insufficiently understood. Thus, the impact of soil moisture on the hydrological response during wet catchment conditions cannot be generalized based on the results obtained here. Further research and instrumentation could include the installation of piezometers in the catchment to understand subsurficial flow in the catchment, using tracers other than *EC* to differentiate subsurficial stormflow as a third flow component during hydrograph separation as well as the application of multivariate regression analysis methods that systematically examine different controls on ϕ_{ev} such as meteorological forcing as well as $\tilde{\theta}_{ini}$ and their interactions.

5 Conclusions

This study aimed at assessing the influence of initial soil moisture on the hydrological response in a flash-flood prone area in southern France. To this end, two issues were addressed and exemplarily examined in the nested Gazel (3.4 km²) and Claduègne (43 km²) catchments: (1) Obtaining a meaningful estimate of soil moisture at the catchment scale and (2) Analyzing

the relation between initial soil moisture $\tilde{\theta}_{ini}$ and the hydrological response quantified as the event-based runoff coefficient ϕ_{ev} .

The main findings of this study related to the first objective are:

5 (1.1) Spatial variability of soil moisture at the plot scale and at the catchment scale is very high. There are differences between land use classes in the vertical soil moisture profile and in wetting behavior, but no significant and systematic differences in catchment mean soil moisture values between land use classes exist. Between land use standard deviation σ_{lu}^{betw} exceeds neither σ^{inter} nor σ^{inner} .

(1.2) There is one plot, c1, with remarkable temporal stability of the spatial difference between plot mean and catchment mean. Thus, this field should be opted for, if the catchment mean had to be assessed from measurements in just one plot. However, 10 none of the other plots shows this temporal stability.

The sampling design applied for this study allowed a detailed characterization of soil moisture heterogeneity across scales as well as the assessment of temporal dynamics. The catchment mean soil moisture was derived with a mean standard error of the catchment mean of 1.3 vol% or 1.5 vol% for the Gazel and Claduègne catchments respectively.

Main findings concerning the impact of initial soil moisture on the hydrological response quantified with the event-based 15 runoff coefficient ϕ_{ev} are:

(2.1) ϕ_{ev} obtained with different hydrograph separation methods can differ considerably, but results obtained with EC, CK, SL and RDF methods correlate well. The RDF method was preferred for this study because it is easy to apply and because of the good correlation with the more physically based methods EC and CK which could not be applied to all events and both catchments.

20 (2.2) There is a weak correlation between ϕ_{ev} and cumulative event precipitation P_{cum} , mean rain intensity I_{μ} and maximum 20 min rain intensity $I_{max,20}$ ($R^2 = 0.24, 0.17$ or 0.27 respectively).

(2.3) The hydrological response depends on initial soil moisture $\tilde{\theta}_{ini}$: below a threshold of 34 vol%, ϕ_{ev} remains very low, even during high precipitation events. However, there is a large scatter in ϕ_{ev} above that threshold indicating that other factors and processes also have an important impact on ϕ_{ev} . The threshold is identical for both catchments which indicates that at this 25 study's site it might be scale invariant.

(2.4) Regarding the seasonal and within event evolution of soil moisture and discharge shows that discharge peaks of two considered events did not follow the peaks in rainfall, but a second, smaller rain impulse, while the rainfall peaks lead to a considerable refilling of soil water storage.

These results indicate, that $\tilde{\theta}_{ini}$ does impact the hydrological response. For single events ϕ_{ev} can be attributed to $\tilde{\theta}_{ini}$, P_{cum} or 30 $I_{max,20}$. However, these results cannot be generalized and no systematic and unequivocal relationship between $\tilde{\theta}_{ini}$ and ϕ_{ev} was found. Even though the present data set is exceptionally detailed, there still is substantial uncertainty in the values for $\tilde{\theta}_{ini}$, P_{cum} and cumulative event flow $Q_{ev,cum}$.

The results of this study support suggestions by other authors to include estimates of initial soil moisture in flash flood warning based on the dependence of ϕ_{ev} on $\tilde{\theta}_{ini}$ by including a threshold that could prevent false positive flash flood warnings under dry initial conditions.

Further research could focus on the role of subsurface flow and on elaborating multivariate regression analysis methods..

5 Author contributions

Jean-Pierre Vandervaere and Isabella Zin conceptualized the study and Magdalena Uber carried out data analysis and its interpretation. Jean-Pierre Vandervaere, Isabelle Braud, Cédric Legoût, Gilles Molinié and Guillaume Nord were principal investigators in the FloodScale project responsible for instrumentation and criticized and provided the data used for this study. All authors contributed to data analysis and interpretation of results. Magdalena Uber prepared the manuscript with
10 contributions from all co-authors. The authors declare that they have no conflict of interest.

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Figures and Tables

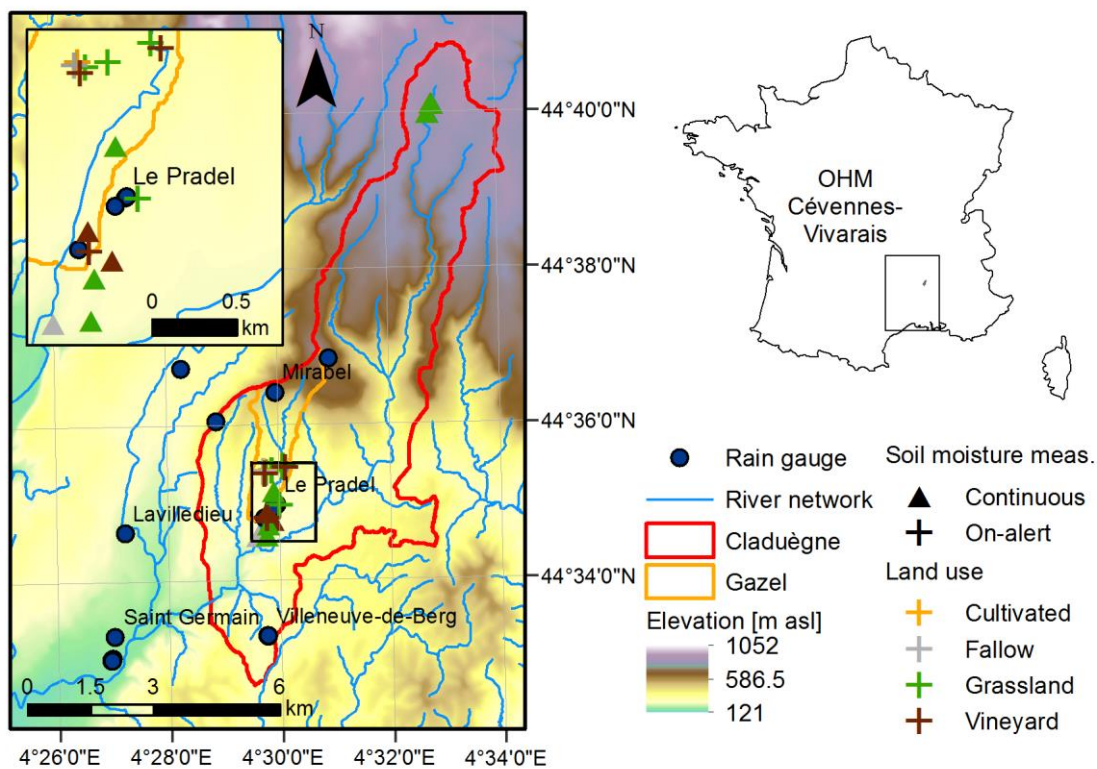


Figure 1: Location of the study site and measurement network. At every on-alert site measurements were taken at about 10
5 randomly chosen locations. At every continuous measurement sites two sensors were installed at 10 cm depth, two sensors at 20-25 cm depth and one sensor at a depth of 33-50 cm.

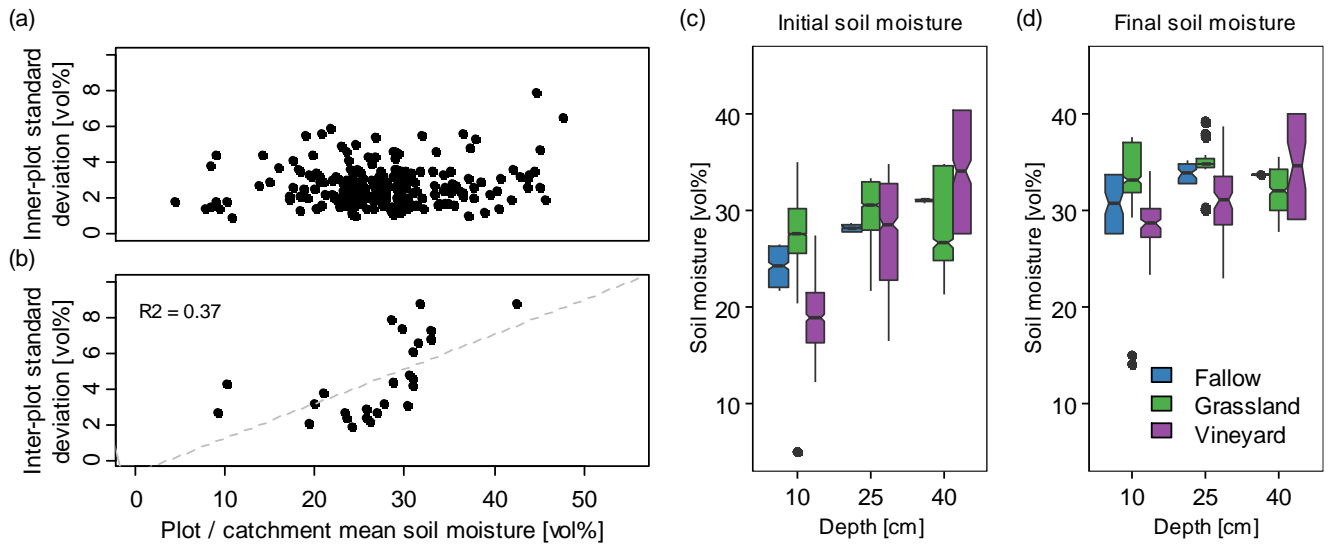


Figure 2: (a) Relationship between plot mean soil moisture $\bar{\theta}_j(t_{ev})$ and inner-plot standard deviation $\sigma_j^{inner}(t_{ev})$ as calculated with Eq. 1 and Eq. 6 in Table 1. Figure (b) shows the same at the catchment scale for catchment mean soil moisture $\bar{\theta}_{ev}$ and inter-plot standard deviation $\sigma_{cat}^{inter}(t_{ev})$ as calculated with Eq. 3 and Eq. 7 in Table 1. The right figures show initial (c) and final (d) soil moisture profile in plots of different land use during event 27 (06–09 September 2013).

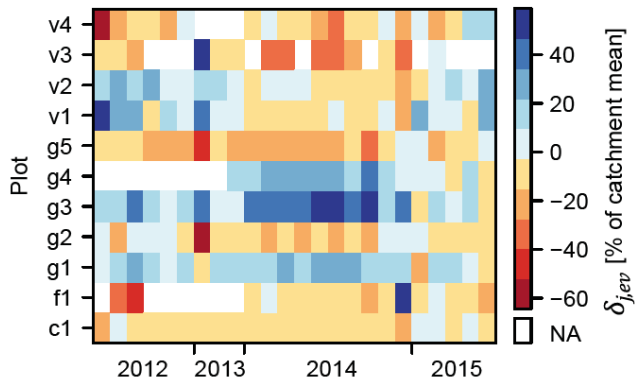


Figure 3: Temporal stability (Vachaud et al., 1985): the relative difference between the plot mean and the catchment mean $\delta_{j, ev}$ for each on-alert measurement and each plot where on-alert measurements were conducted (four vineyards v1 – v4, five grasslands g1 – g5, one fallow f1 and one cultivated field c1). Note that the time axis represents a sequence of events, no

5 equidistant

time line. Blue squares show plots with plot means that exceeded the catchment mean, red squares those with plot means below the catchment mean, white squares indicate plots that were not sampled during the respective measurement.

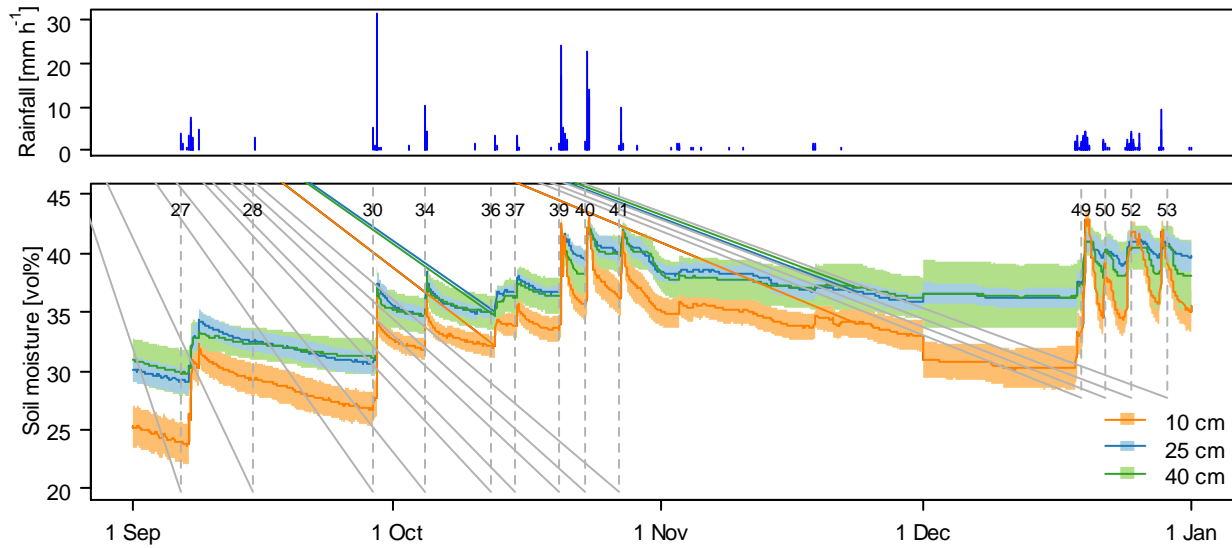


Figure 4: Rainfall and soil moisture in autumn 2013 measured in 10, 25 and 40 cm depth. The line represents the catchment mean calculated with Eq. 3 in Table 1 in the respective depth and the shaded area the mean $\pm SEM_{cat}^{inter}$. The dashed lines represent the onsets of several rain events and the labels refer to the event numbers as in Table 3 and Table 4. Note that on 27 November 2013 one of the probes stopped working which is the reason for the step in the data and the higher SEM_{cat}^{inter} .

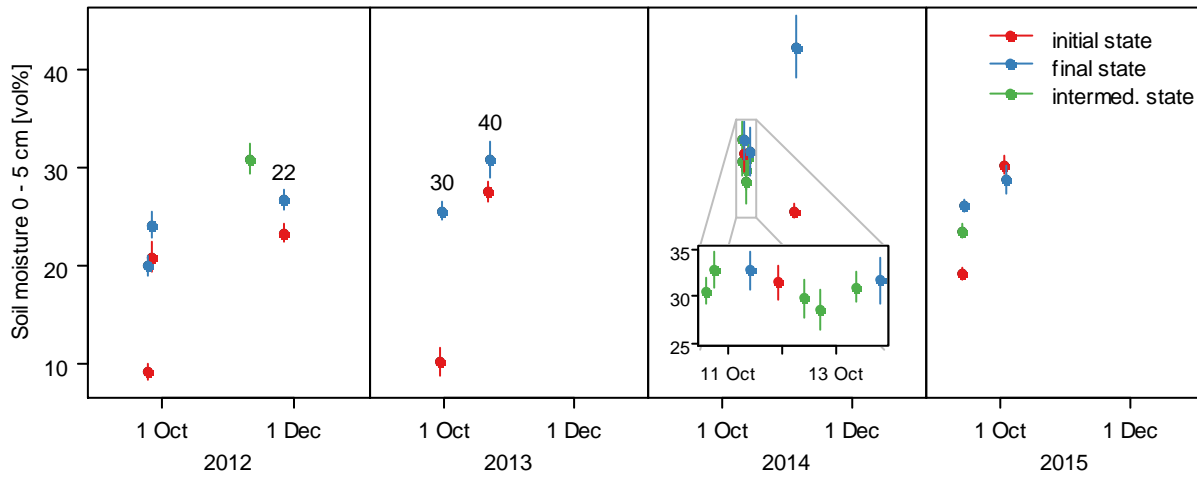


Figure 5: Soil moisture in the topsoil (0–5 cm) measured on alert basis before and after major rain events in autumn seasons in 2012–2015. The points show catchment mean values, the lines the range of the mean $\pm SEM_{cat}^{inter}$. The numbers above selected events give the event number as in Table 3 and Table 4 and as referred to in the text.

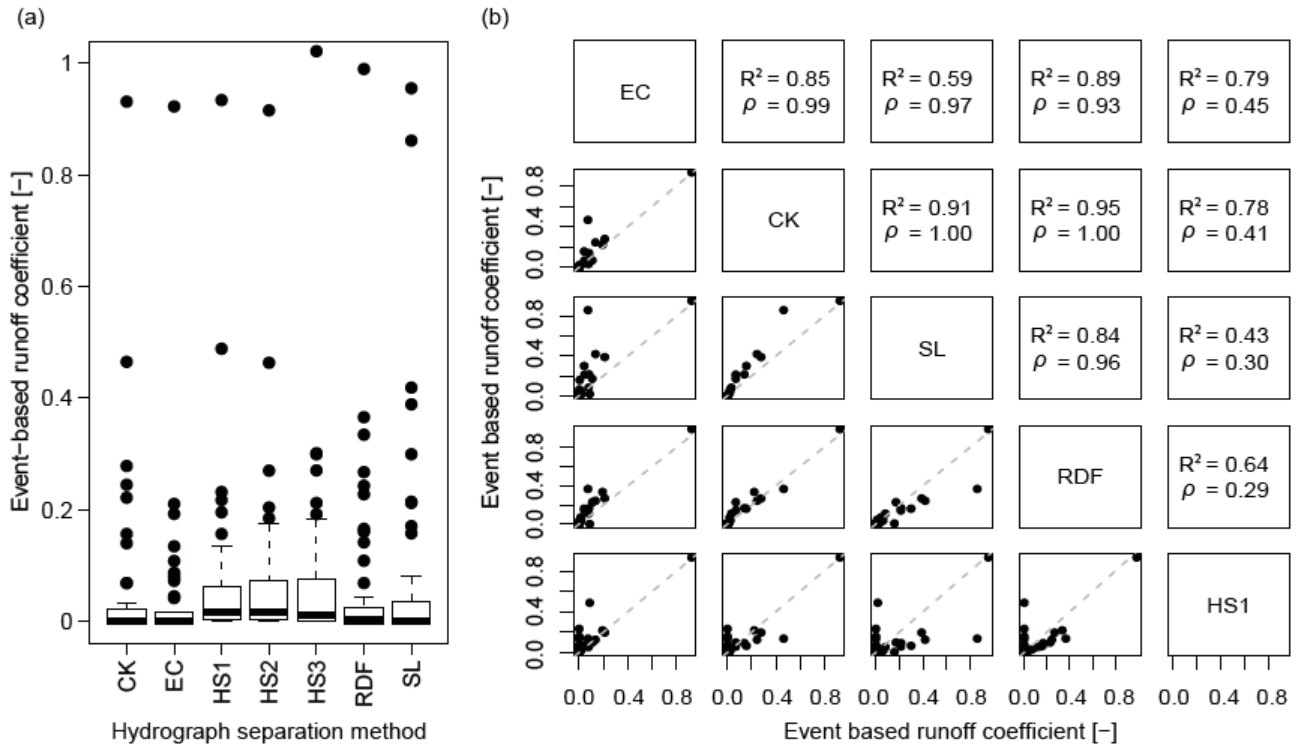


Figure 6: (a) Differences of event-based runoff coefficients ϕ_{ev} calculated for 54 rain events in the Gazel catchment in autumn 2012 and autumn 2013 derived with different methods for hydrograph separation. (b) Correlation between different methods. The upper panel gives the coefficient of determination (R^2) and Spearman's rank correlation coefficient ρ , the dashed line in the lower panel is the line of identity. The methods used for hydrograph separation are described in Sec. 2.5.2: constant-k (CK), electric conductivity (EC), Hysep filter with fixed or sliding interval (HS1–HS2), Hysep filter with local minima algorithm (HS3), recursive digital filter (RDF) and straight line (SL).

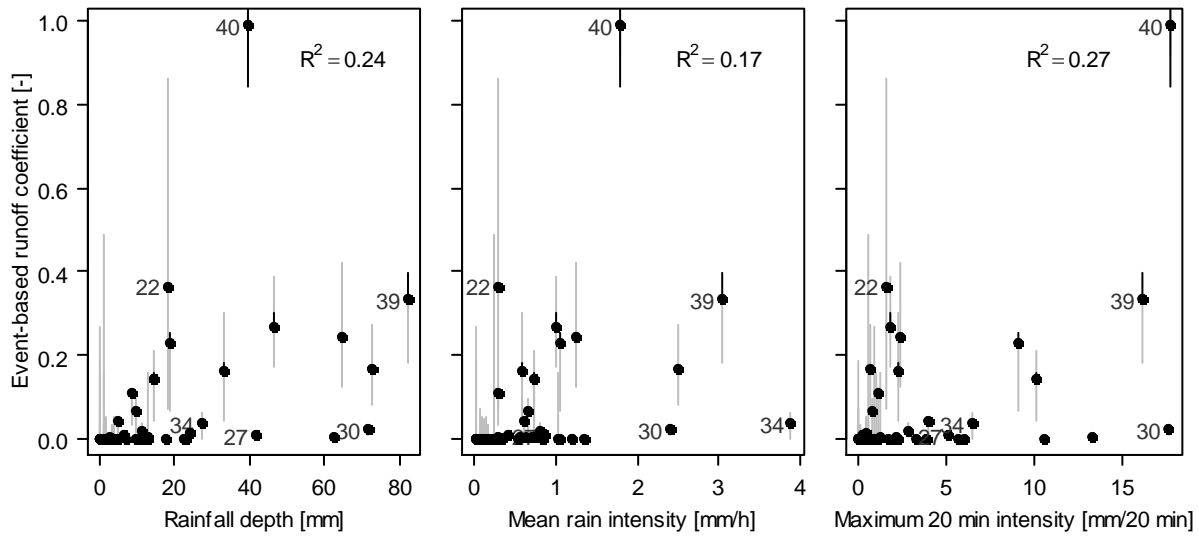


Figure 7: Correlation of three variables describing meteorological forcing with event-based runoff coefficients ϕ_{ev} of the Gazel catchment calculated with the recursive digital filter method. The lines represent the uncertainty associated to the hydrograph separation method (gray vertical lines: range of ϕ_{ev} calculated with the seven different methods) and the stage-discharge relation (black vertical lines: range between ϕ_{ev} calculated with the 5 % and the 95 % confidence interval of discharge obtained with the BaRatin framework). The point labels give the numbers of selected events as in Table 3 and Table 4 and described in the text.

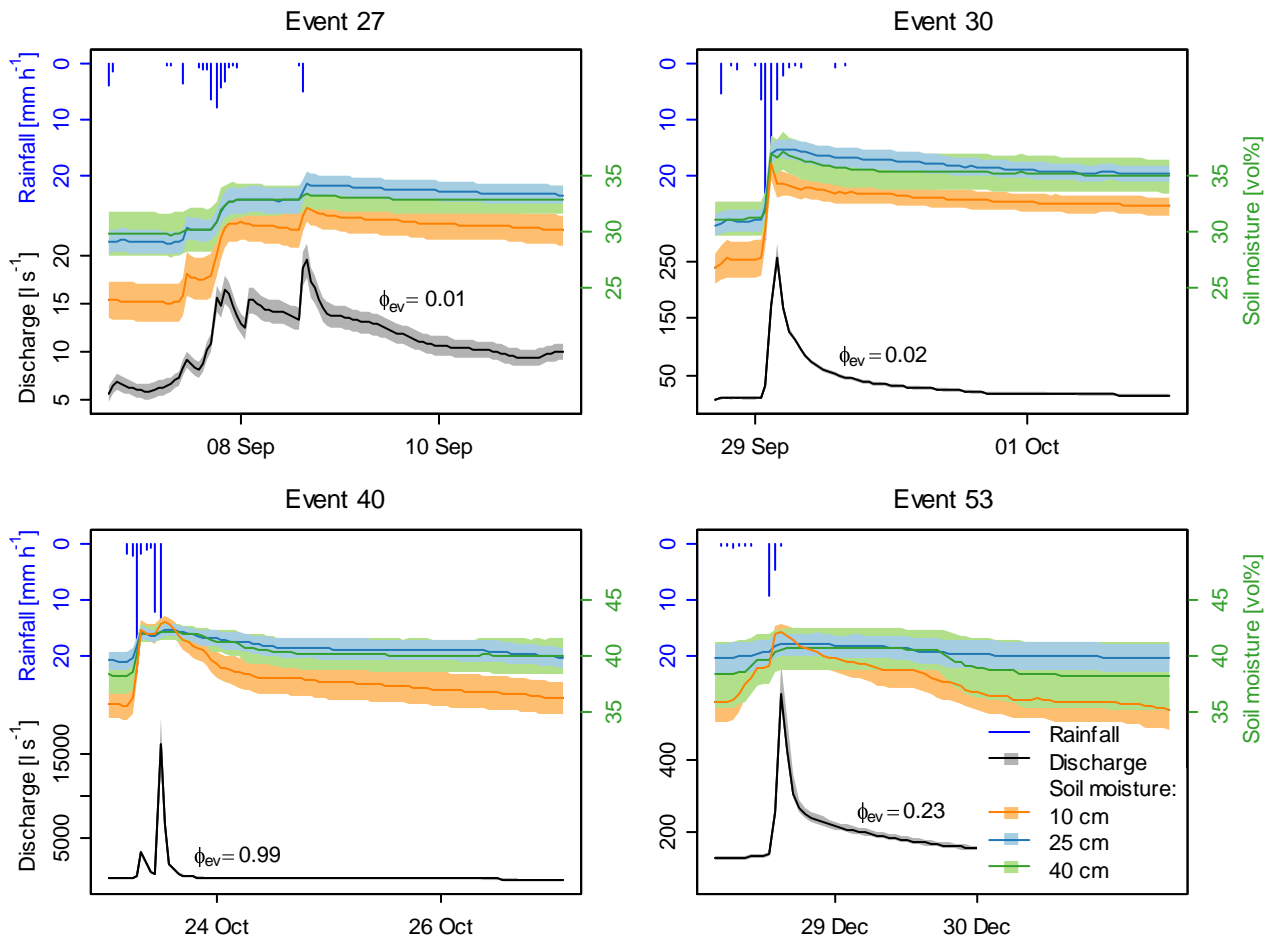


Figure 8: Hyetographs, hydrographs of total discharge and evolution of soil moisture in the Gazel catchment during four different events in 2013. The event-based runoff coefficient ϕ_{ev} is also given for all events. The representation of soil moisture gives the mean $\pm SEM_{cat}^{inter}$ in the respective depth and the one of discharge the best estimate \pm the uncertainty of the stage-

5 discharge relation.

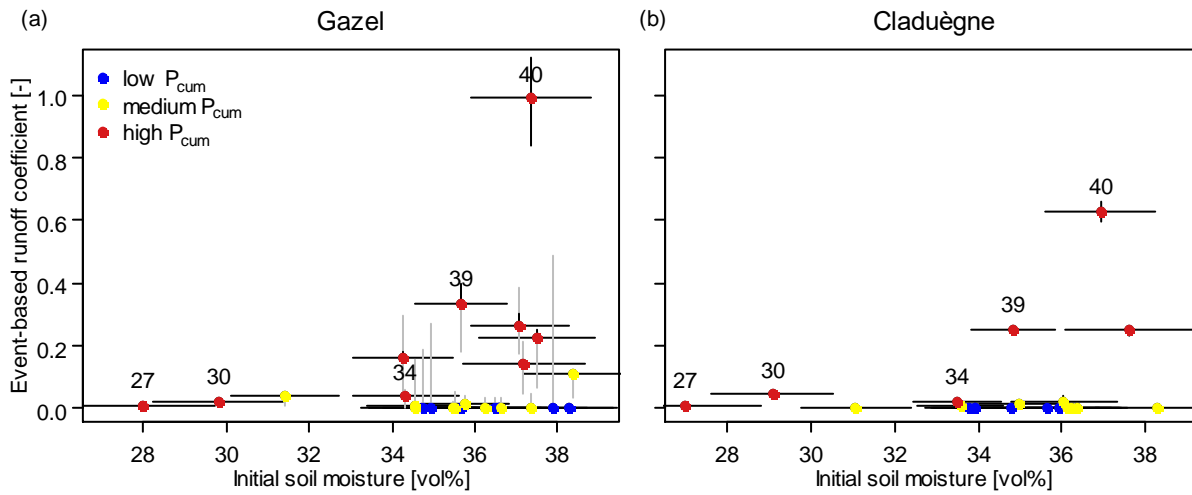


Figure 9: Relationship between initial soil moisture $\bar{\theta}_{ini}$ and event-based runoff coefficients ϕ_{ev} in the Gazel (a) and Claduègne (b) catchments. On the x-axis the point represents the profile mean initial soil moisture and the horizontal line the range of the mean $\pm SEM_{cat}^{inter}$. On the y-axis the point represents ϕ_{ev} calculated with the recursive digital filter method and the line the uncertainty as in Fig. 7. The color of the points indicates whether cumulative precipitation is low ($P_{cum} < 1.5$ mm), medium ($1.5 \text{ mm} < P_{cum} < 13$ mm) or high ($P_{cum} > 13$ mm).

Table 1: Calculated measures of averaged soil moisture and its variability at different scales. a) Thickness of layers 1-3 is assumed to be 175, 150 and 275 mm. b) only calculated for grasslands and vineyards, because the number of plots is 1 for land use classes fallow and cultivated field.

Name	Formula	Purpose and Abbreviations
Plot mean soil moisture	$\bar{\theta}_j(t_{ev}) = \frac{1}{n_i} \sum_{i=1}^{n_i} \theta(x_{i,j}, t_{ev})$	(1) Best estimate at plot scale; n_i : Number of measurements in plot j .
Land use mean soil moisture	$\bar{\theta}_{lu}(t_{ev}) = \frac{1}{n_{jlu}} \sum_{jlu=1}^{n_{jlu}} \bar{\theta}_j(t_{ev})$	(2) Best estimate for land use classes; n_{jlu} : Number of meas. in plots of land use lu ; g: grassland, v: vineyard, c: cultivated field, f: fallow
Catchment mean soil moisture	$\bar{\bar{\theta}}_{ev} = \frac{1}{n_p} \sum_{lu}^{n_{clu}} \bar{\theta}_{lu} \cdot n_{jlu}$	(3) Best estimate at catchment scale; n_p : Number of plots ($n_p = 11$); n_{clu} : Number of land use classes ($n_{clu} = 4$)
Profile mean soil moisture	$\tilde{\theta}_{ev} = \frac{\sum_{l=1}^{m_l} \bar{\bar{\theta}}_{ev,l} \cdot m_l}{\sum_{l=1}^{m_l} m_l}$	(4) Best estimate at catchment scale, integrated over the soil profile; n_l : number of layers ($n_l = 3$); m_l : thickness of layer l^a .
Soil moisture storage change	$\Delta S = \sum_{l=1}^{n_l} \frac{1}{100} \left(\bar{\bar{\theta}}_{fin,l} - \bar{\bar{\theta}}_{ini,l} \right) \cdot m_l$	(5) Soil water retention during events; $\bar{\bar{\theta}}_{fin,l}$; $\bar{\bar{\theta}}_{ini,l}$: final and initial soil moisture in layer l .
Inner plot sd	$\sigma_j^{inner}(t_{ev}) = \sqrt{\frac{1}{n_i - 1} \sum_{i=1}^{n_i} (\theta(x_{i,j}, t_{ev}) - \bar{\theta}_j(t_{ev}))^2}$	(6) Estimate of spatial variability at the plot scale.
Inter plot sd (catchment)	$\sigma_{cat.}^{inter}(t_{ev}) = \sqrt{\frac{1}{n_p - 1} \sum_{j=1}^{n_p} (\bar{\theta}_j(t_{ev}) - \bar{\bar{\theta}}(t_{ev}))^2}$	(7) Estimate of spatial variability at the catchment scale.
Inter plot sd (g/v) ^b	$\sigma_{lu}^{inter}(t_{ev}) = \sqrt{\frac{1}{n_{jlu} - 1} \sum_{jlu=1}^{n_{jlu}} (\bar{\theta}_j(t_{ev}) - \bar{\bar{\theta}}_{lu}(t_{ev}))^2};$	(8) Estimate of inter plot variability in the grasslands and vineyards.
Between land use sd	$\sigma^{betw}(t_{ev}) = \sqrt{\frac{1}{n_{clu} - 1} \sum_{lu}^{n_{clu}} (\bar{\bar{\theta}}_{lu}(t_{ev}) - \bar{\bar{\theta}}_{ev})^2}$	(9) Estimate variability between the grasslands and vineyards.

Table 2: Spatial variability of soil moisture at the plot scale (mean of all events calculated for all plots: mean $\sigma_j^{\text{inner}}(t_{\text{ev}})$, for the grassland plots: mean $\sigma_{j\text{eg}}^{\text{inner}}(t_{\text{ev}})$ and the vineyard plots: mean $\sigma_{jev}^{\text{inner}}(t_{\text{ev}})$ calculated with Eq. 6 in Table 1) and at the catchment scale (mean inter plot variability of the grassland plots: mean $\sigma_g^{\text{inter}}(t_{\text{ev}})$ and the vineyard plots mean $\sigma_v^{\text{inter}}(t_{\text{ev}})$ calculated with Eq. 8 in Table 1 as well as between land use class variability mean $\sigma^{\text{betw.}}(t_{\text{ev}})$ calculated with Eq. 7 in Table

5 1) determined at different depth with the two measuring schemes.

	Initial states				Final states			
	0-5 cm	10 cm	25 cm	40 cm	0-5 cm	10 cm	25 cm	40 cm
Mean $\sigma_j^{\text{inner}}(t_{\text{ev}})$	2.62	2.77	1.85	NA	2.91	2.71	1.88	NA
Mean $\sigma_{j\text{eg}}^{\text{inner}}(t_{\text{ev}})$	2.77	2.18	1.77	NA	2.80	2.18	1.78	NA
Mean $\sigma_{jev}^{\text{inner}}(t_{\text{ev}})$	2.49	3.15	2.24	NA	2.84	3.15	2.24	NA
Mean $\sigma_g^{\text{inter}}(t_{\text{ev}})$	3.48	4.49	2.07	4.40	3.70	4.26	2.04	4.30
Mean $\sigma_v^{\text{inter}}(t_{\text{ev}})$	2.63	2.26	5.36	6.81	2.11	2.39	5.31	6.65
Mean $\sigma^{\text{betw.}}(t_{\text{ev}})$	2.12	2.20	1.14	1.71	3.78	1.98	1.10	1.55

Table 3: Rainfall, soil moisture and discharge characteristics of selected rain events in autumn 2013 in the Gazel catchment: beginning of the rain event, cumulative precipitation (P_{cum}), maximum 20-min rain intensity ($I_{max,20}$), mean intensity (I_{μ}), initial soil moisture ($\tilde{\theta}_{ini}$), final soil moisture ($\tilde{\theta}_{fin}$), standard error of the catchment mean (SEM_{cat}^{inter}) during initial and final stage, soil storage change at depth 0 – 50 cm (ΔS), peak discharge (Q_p), cumulative total discharge ($Q_{tot,cum}$), cumulative event discharge ($Q_{ev,cum}$) and event-based runoff coefficient calculated with the recursive digital filter method (ϕ_{ev}).

Rainfall		Soil Moisture							Discharge			
Ev. #	Beg. Rain DD-MM hh:mm	P_{cum} mm	$I_{max,20}$ mm h ⁻¹	I_{μ} mm h ⁻¹	$\tilde{\theta}_{ini}$ vol%	SEM_{cat}^{inter} vol%	$\tilde{\theta}_{fin}$ vol%	SEM_{cat}^{inter} vol%	ΔS mm	Q_p l s ⁻¹	$Q_{ev,cum}$ mm	ϕ_{ev} -
27	06-09 16:06	41.59	33.30	0.85	27.99	1.73	32.69	1.07	28.17	25	0.34	0.01
28	15-09 00:23	4.82	24.00	0.60	31.40	1.31	31.34	1.38	0.00	14	0.20	0.04
30	28-09 17:09	71.73	59.70	2.39	29.80	1.57	35.20	1.45	32.43	324	1.73	0.02
34	04-10 15:39	27.20	25.50	3.89	34.33	1.29	36.43	1.25	12.62	58	1.03	0.04
36	12-10 05:12	12.86	4.50	0.71	34.55	1.15	35.91	1.02	8.12	18	0.07	0.01
37	15-10 03:46	11.29	9.00	0.81	35.76	1.07	36.54	1.07	4.72	23	0.21	0.02
39	20-10 02:41	82.20	53.40	3.04	35.65	1.10	38.12	1.41	14.83	8660	27.49	0.33
40	23-10 01:01	39.31	60.00	1.79	37.34	1.44	38.40	1.54	6.33	30096	38.91	0.99
41	27-10 03:37	14.64	37.20	0.73	37.17	1.46	38.09	1.52	5.54	361	2.07	0.14
49	18-12 06:52	33.09	8.70	0.57	34.26	1.20	37.90	1.32	21.82	402	5.30	0.16
50	21-12 03:11	8.73	4.20	0.27	38.39	1.23	37.78	1.12	0.00	175	0.95	0.11
52	24-12 01:15	46.33	7.50	0.99	37.09	1.17	39.83	1.08	16.46	1047	12.38	0.27
53	28-12 04:51	18.70	32.70	1.04	37.52	1.40	39.25	1.04	10.41	654	4.25	0.23

Table 4: Rainfall, soil moisture and discharge characteristics of selected rain events in autumn 2013 in the Claduègne catchment, abbreviations as in Table 3.

Rainfall		Soil Moisture							Discharge			
Ev. #	Beg. Rain DD-MM hh:mm	P_{cum} mm	$I_{max,20}$ mm h ⁻¹	I_{μ} mm h ⁻¹	$\tilde{\theta}_{ini}$ vol%	$SEM_{cat.}^{inter}$ vol%	$\tilde{\theta}_{fin}$ vol%	$SEM_{cat.}^{inter}$ vol%	ΔS mm	Q_p m ³ s ⁻¹	$Q_{ev,cum}$ mm	ϕ_{ev} -
27	06-09 15:41	43.26	33.3	0.88	27.00	1.38	32.62	1.16	29.05	0.19	0.38	0.01
28	15-09 00:23	3.61	26.7	0.45	31.09	1.32	31.00	1.32	0.00	NA	NA	NA
30	28-09 17:04	77.71	63	2.59	29.09	1.49	34.49	1.24	29.93	16.39	3.16	0.04
34	04-10 15:33	28.09	27	4.01	33.48	1.53	35.46	1.44	11.39	0.59	0.66	0.02
36	12-10 05:12	12.81	4.5	0.71	33.58	1.53	35.20	1.46	8.42	0.13	0.10	0.01
37	15-10 03:46	11.51	9	0.82	34.98	1.55	35.67	1.52	4.34	0.16	0.19	0.02
39	20-10 02:41	83.67	53.4	3.10	34.83	1.63	37.54	1.51	15.33	54.64	20.82	0.25
40	23-10 01:01	51.01	60	2.32	36.92	1.69	38.75	1.60	11.37	60.76	36.37	0.93
41	27-10 03:37	22.06	52.5	1.10	37.62	1.67	38.47	1.64	4.40	12.08	5.44	0.37
49	18-12 06:52	67.91	8.7	1.17	34.40	1.61	38.22	1.44	21.59	NA	NA	NA
50	21-12 03:11	10.98	4.2	0.34	38.70	1.61	38.40	1.63	0.00	NA	NA	NA
52	24-12 01:15	51.24	7.5	1.09	37.70	1.68	40.29	1.58	14.30	NA	NA	NA
53	28-12 04:51	19.65	32.7	1.09	38.09	1.66	39.68	1.60	9.56	NA	NA	NA