Anonymous Referee #1

General Comments:

1.   AMSR-E downscaling: I would first suggest the authors to clarify their research goals. If providing high resolution data is not part of the goal, the authors can perform analysis at 25-km, i.e. upscale ALEXI. Downscaling MS is usually challenging. The consequences on POME are also difficult to evaluate, as pointed by the authors (page 16, line 535).

Response: One of the primary goals of the research is to provide remotely sensed soil moisture profiles at operational or near operational (1-5 km), spatial resolutions. At present the authors have a suite of hydrologic and agricultural models running over the Southeastern United States at a 4.7-km resolution to be consistent with the NWS Stage IV multi-sensor precipitation product. The NASA SPoRT project at MSFC also maintains a number of near-real-time land surface models within the NASA Land Information System (LIS) at a 3-km resolution (SPoRT LIS). So the purpose of our research was to provide soil moisture profiles at a resolution that would be consistent with our current modeling system and that can be compared to the land surface models within the SPoRT-LIS framework. We also note that the downscaling method we utilized appears to have improved the coarse resolution microwave data in a number of ways. We will revise the objectives section of the manuscript to provide further explanation of our goals in this regard (see response to detailed comment #2 below).

Required changes are reported in lines 83-85 of the revised manuscript.

2.   The proposed method can only handle cases with soil moisture is linearly increasing/decreasing with depth, if I am correct. If that is the case, the authors should discuss why the proposed method is preferable than other remote sensing based method, e.g. exponential filter (Albergel et al., 2008).

Response: We thank the referee for this comment and agree that perhaps the manuscript can be improved by further discussion on this point. While the entropy method does assume a uniform probability distribution of soil moisture initially, the final profiles are not linear in real space after the integral is performed subject to the boundary conditions and mean moisture content. We refer the referee to our previous paper on this point (Mishra et al., 2013) where a full range of profiles are shown corresponding to all possible cases that may arise in nature. Unlike other methods, the entropy approach suffers from no a priori assumptions about the nature or shape of the moisture profiles in real space. The method is a statistical approach and guarantees the minimum variance unbiased profile subject to the boundary and initial conditions specified. We consider this an improvement over other analytical methods that do presuppose a functional form of the soil moisture distribution. We refer the referee to the article by Singh, (2010) for a full explanation of the theory of entropy of moisture movement in porous media. Further, the method can easily be modified even to include non-monotonic profiles through the identification of the inflexion point based on a few well-known principles of vadose zone hydrology (Mishra et al., 2015). In addition, the proposed method is ideal for the

integration of remotely sensed data from multiple sensors which is one of the primary goals of the research. In fact, the primary objective of the project was to merge microwave (MW) and thermal infrared (TIR) soil moisture estimates into a unified profile. We will revise the manuscript to add this material.

Required changes are reported in lines 60-65 as well as 324-335 of the revised manuscript.

3.   Please add units to all the figures

Response: Thank you for pointing out this oversight.

4.   The conclusions should be presented in a more concisely.

Response: We will endeavor to condense the conclusion section by converting bullets into 3 concise paragraphs. We will then add another paragraph with condensed version of the error issues.

Detailed comments:

1.   Line 16 to 18: please add units to all the numbers being reported. I assume it is in m3/m3.

Response: Thank you for pointing out this oversight.

2.   Line 67 to 69: please revise/modify the goal here. The authors should at least mention the methodology should satisfy what applications.

Response: If we understand the comment correctly, the referee would like for us to mention the purpose, or potential uses if the developed profiles here. As the referee mentions in the first item above, perhaps this is a good place to position some of the material discussed in that item.

3.   Section 2.1: Please specify why this area is selected. It is known that AMSR-E has the poorest performances over dense vegetation areas. This means AMSR-E is usually more accurate over southwest part of the CONUS and less accurate over the eastern part of the CONUS.

Response: This is an excellent point. As mentioned previously, the authors currently participate in an extensive research program centered in the Southeastern US. The region is data rich, thus providing us with ample opportunities to test and validate the results. However, as the referee mentions, the region represents a humid subtropical climate with nearly 85% of the area represented by either forest or shrubs, making it one of the toughest regions for MW based SM estimations. As pointed out in the manuscript, the X-

band MW signal is greatly attenuated by moderate to high vegetation cover such as represented by the selected study region. Therefore, we feel that, in addition to providing added benefit to the research that we are already doing in the Southeast, the study represents an opportunity to evaluate the performance of the merged MW/TIR profiles in a challenging environment. If successful, then the study will provide greater confidence towards the robustness of the method. We believe that the results of the study do provide evidence of that robustness. This will be clarified in the revised manuscript.

Required changes are reported in lines 109-110 and 123-126 of the revised manuscript.

4.   Section 2.2.1: Please justify why LPRM based C-band AMSR-E data were not used, since it is usually considered to have a better quality?

Response: It is known that the lower frequency bands are better for surface SM detection since the higher bands suffer disproportionately from the effects of atmospheric interference, vegetation cover and radio interference (Albergel et al., 2011; Brocca et al., 2011). This study employs one of the more extensively used and validated MW based SM data sets from the AMSR-E (2002-2011) mission operating in the X-band frequency from the National Snow and Ice Data Center (NSIDC) and employs the standard NASA retrieval algorithm (Njoku et al., 2003). The NSIDC is one of two AMSR-E data sets supported by NASA with the other being the Vrije Universiteit Amsterdam - Land Parameter Retrieval Model (VUA-LPRM) data. The LPRM uses a single dual polarized channel (X- or C- band) to deduce relationships between geophysical variables such as soil moisture and vegetation characteristics and brightness temperatures (Cho et al., 2015). Several studies such as Wagner et al. (2007); Draper et al. (2011); Jackson et al. (2010); Gruhier et al. (2008) etc. have compared the two data sets and the general conclusion has been that the VUA-LPRM algorithm may be slightly superior in terms of correlation to *in-situ* data, especially at lower latitudes and sparse vegetation (Brocca et al., 2011). However, Jackson et al. (2010) found that for southeast U.S, the NASA retrieval algorithm outperformed the LPRM in terms of bias and RMSE. Furthermore, as pointed out by authors such as Njoku et al. (2005); Jackson et al. (2010) the effects of radio frequency interference (RFI) on C-band are more pronounced over countries such as United States and Japan, therefore X-band retrievals are preferred over such regions. Hence X-band based on the standard NASA (or NSIDC) data set was selected for this study. This issue will be further discussed in the revised manuscript.

Required changes are reported in lines 138-152 of the revised manuscript.

5.   Equation 6 and 7: the author can remove one of them

Response: Thank you. We will remove equations 6 and 7.

6.   The captions of figure 2 should be modified. Please specify which products are compared in the caption.

Response: We thank the referee for pointing out this oversight.

7. Line 343 and elsewhere: RMSE is the root mean square error. It can be calculated when you have a known "truth" or a very good reference. If NOAH is not assumed to be perfect, I would suggest the author to change it into RMSD, i.e. root mean square difference.

Response: We agree with the reviewer, since neither NOAH nor *in-situ* observations can be considered as a perfect reference due to their inherit errors and scale mismatch issues, we will rectify this mistake and replace RMSE with RMSD in the manuscript.

8. Line 349: provide the unit here is m3/m3, I would not say ubRMSE = 0.06 m3/m3 is small. . .

Response: We agree that RMSE/RMSD = 0.06 m^3/m^3 is little on the higher side, however the statement in question (Line 349) in quotes, "*Moreover < 97% pixels across the study area showed ubRMSE of less than 0.06 across all layers, indicating good agreement between the POME model and Noah SM estimates*". The greater than sign was wrongly put in as less than. The statement simply intent to states that the for more than 97% of pixels the ubRMSE was <u>less than</u> 0.06 m^3/m^3

Further, as pointed out by Jackson et al. (2010), the agencies such as NASA and JAXA specified an accuracy goal of errors less than 0.06 m^3/m^3 for AMSR-E retrievals. Since this study utilizes AMSR-E SM estimates, we assumed the similar accuracy standard. Although, we acknowledge some inconsistencies, such as spatial mismatch (originally AMSR-E spatial resolution is 25 km while we downscaled it to 5 km) and the specified accuracy goal was limited to surface measurements so we assumed it would be appropriate to adopt it for the rootzone as well.

9. Line 353: the author may need to define a threshold of "well" or "good". As shown in the third row of Figure 2, large fractions of correlations are below 0.4. It is hardly to be considered as "well" in my background. However, I agree that this threshold varies according to different applications.

Response: We agree that correlations below 0.4 would not be generally considered "good". In this paragraph our main point was that the better correlations (0.6 and above) were generally in the agricultural areas. We think that most people would consider such correlations "good" when dealing with remotely sensed data. Further we characterize correlations around 0.5 (0.46-0.54) as "fairly" good, a designation we think many people would agree with. While the figure does show that there are areas where the correlations are not as good, the discussion is focused on the overall correlations.

10. please add row indices.

Response: We assume that the referee is referring to the identifications on the rows (i.e., 2009. 2114, etc.). These are the SCAN station ID's and we will add that to the figure.

11. Line 476 to 477: please rephrase.

Response: We assume that the referee is referring to the sentence that begins "Figure 6 shows that …". Perhaps the objection is to the general characterization that the figure is showing the poorly defined "accuracy" of the method. If this is the case, then we apologize for the poor wording here. We will expand this section to be more specific in what we mean by accuracy according to the indices reflected in the figure.

12.   Line 478: the implementation of TC should include more information. Was the climatology removed from each dataset?

Response: In this study, we used covariance notation to compute TC error, which allows us to solve for the unscaled error variances directly. As pointed out by Gruber et al., (2016), with covariance notation, the posterior scaling of dataset is possible and is an optional process. Also, both scaled based difference notation as well as unscaled covariance notation mathematically leads to same results, therefore either method can be used. Further, the advantage of using covariance notation is that it provides an estimate of sensitivity of the dataset to soil moisture change. The sensitivity estimates allows for additional validation and inter-comparison of the datasets. We will include this information in the revised manuscript.

Required changes are reported in lines 372-389 of the revised manuscript.

13.   Line 484 and figure 7: it is not common to express TC results in R2. Please specify how this metric was derived.

Response: Thanks for pointing this out. As mentioned in response 12 above, the study uses covariance notation for TC analysis which also estimates sensitivity of the datasets represented as: $\beta_i^2 \sigma_\theta^2$, which can be used to further validate and inter-compare datasets. Recently, McColl et al., (2014) proposed to use TC analysis to estimate the correlation coefficient between datasets involved and the underlying 'true' signal as:

$$R_i^2 = \frac{\beta_i^2 \sigma_\theta^2}{\beta_i^2 \sigma_\theta^2 + \sigma_{\varepsilon_i}^2}$$

$$\beta_X^2 \sigma_\theta^2 = \frac{\sigma_{XY} \sigma_{XZ}}{\sigma_{YZ}}$$

Where X,Y,Z refers to three datasets involved in TC analysis.

14.   Line 488 to 490 is incorrect. TC estimates the total error, instead of just the random error. Please see Yilmaz and Crow 2014. This means if NLDAS is less accurate, either due to random or temporally correlated errors, it will be shown in the TC results.

Response: We agree that TC includes total error and did not mean to infer otherwise. We apologize for the confusion. The point we were making is that the root zone soil

moisture values in the NOAH LSM are the result of a deterministic equation and thus are not observations of a random variable or statistical estimates as in the POME method. For this reason, we were a little uncomfortable in making decisive statements with regard to the behavior of the NOAH data. We will rephrase this paragraph to make clear our intentions, or if the editors prefer we can remove it altogether.

15. Section 4.4.1: please refer to my general comment. If the reviewer can perform analysis at coarse scales, this section is unnecessary. This may make the manuscript cleaner.

Response: Please refer to response 1

16. Line 578 to 579: I would not consider the minimum bias is the key advantage of POME. This is because it is nearly impossible to define an absolute bias at large scales, since the reference dataset (e.g. SCAN) can also be biased.

Response: We thank the referee for this observation and agree that there is bias in the SCAN data. Here we are merely comparing the bias of the different approaches. We agree that because of scale disparities we cannot make definitive statements relative to true bias. We will revise this section accordingly to acknowledge that bias exists in all three data sets.

17. Line 585: Root zone soil moisture at large scales can have significant spatial variability, according to my experience. It can result in large errors/bias using limited point sensors to represent large scale root zone soil moisture. Hence, I'm suspecting how confidently the authors can draw this conclusion.

Response: We agree with this statement to a large extent. We are certainly aware of the uncertainties in using point data to represent larger spatial domains. In fact, this is the reason that we added the gridded NOAH soil moisture estimates as a comparison metric in addition to the point SCAN data. However, in our review of previous studies such as ours we found that it was not uncommon for other authors to use point data as we did (we cited several of these in the manuscript). To counter this, we added the gridded data sets and the TC analysis where the point data are treated as merely another estimate of the true value of the grid soil moisture. We feel that the results of all the analyses are compatible and lead to similar conclusions.

18. Line 598 to 600: please refer to my General Comment 1

Response: Please refer to response 1

Anonymous Referee #2

POME model: I would still like to have some more information about the model. It only requires surface soil moisture and soil profile mean soil moisture as input information and assumes that moisture is either monotonically increasing or decreasing. If this is not the case, an inflection point that is located in the soil layer with the highest field capacity is assumed

1.   How does the POME model consider several layers of different texture? They might exhibit rather different soil moisture contents with distinct "jumps" between layers. In addition, infiltration fronts might induce further "inflection points". I cannot really imagine how this can be estimated from surface soil moisture and mean profile water con-tent only. Will there be just one optimal soil moisture profile or might there be several (concept of equifinality).

Response: The referee makes an excellent point about the behavior of soil moisture in real world situations. First, the POME model uses effective SM to develop a profile (eq. 4, Line 280), the boundary conditions and mean are first computed in effective SM and the model is applied. Finally, the developed profile in effective SM is converted to volumetric soil moisture values based on layer soil texture. However, one assumption made here is that the mean effective SM (available from the ALEXI model) is a composite of all the layers with different textures.

Now, as to the observation made by the reviewer, profiles can certainly be very irregular due to the different characteristics of the multiple layers that make up the soil column. As discussed in the manuscript and in the earlier paper by Mishra et al., (2015), the POME method as currently formulated envisions the profile as either monotonically increasing or decreasing or as possessing a prominent inflexion point. However, the method is a statistical procedure that ensures the minimum variance unbiased profile given the input data. In short, this ensures that the profile will be the best fit possible given what we know *i.e.,* the surface and lower boundary values and the mean. As shown in multiple earlier studies (Al-Hamdan and Cruise, 2010; Mishra et al., 2015, 2013; Singh, 2010a, 2010b) the resulting profile will normally be the best fit line through irregular points of a natural profile if the input data are approximately correct. We believe that this is the best any analytical method can achieve. We will add an appendix with more description of the POME model.

2.   How is the lower boundary condition parameterized?

Response: We consider the lower boundary to potentially be a calibration parameter. There are various ways it can be estimated. For example, it could be considered a soils parameter or it can be used to link the climatology of the POME profile to a land surface model. In this study, the lower boundary was merely parameterized at 50% of available water content. As shown in past analyses (e.g., Mishra et al. (2013)) moisture content in the deeper layers is often fairly constant over the year, depending on the soil texture, and can thus can sometimes be set as the lower boundary on SM. We felt since the present study was a proof of concept in many ways, that parameterizing the lower boundary in this way was appropriate.

As the authors state correctly, both the Noah and the POME model will be affected by model errors and consequently may provide erroneous soil moisture profiles while the in situ data were measured at a much smaller measurement scale and the measurement site may not be representative for the entire pixel. Nevertheless, for a soil hydrologist, the time series shown in Figure 6 provide the most valuable information for identifying model errors and weaknesses of models and data. Unfortunately, this figure is almost not discussed within the manuscript. Observations to be addressed are e.g.

3.   Except some sites where the SCAN data show some bias (mostly towards the dry range), SCAN and NOAH data appear to agree rather well, both in absolute soil moisture content and in the amplitude of the annual dynamics whereas POME often shows a very strong dynamics (especially towards the wet range). Might this cause problem with the upper boundary condition?

Response: We agree with the referee that we did not make sufficient use of the SM series shown in Figure 5. We thought that the salient points could be made through the statistical analyses and ignored the fact that perhaps the issues could be better illuminated through the figure itself. We assume that the referee is referring in this comment primarily to stations 2027, 2053, 2078, 2037, and 2013 where the POME SM estimates show a pronounced cycling effect in the upper layer not evident in the SCAN or NOAH data. We note here that the surface SM from POME is primarily set by the boundary condition provided by the MW data and that the overall correlation among all stations in this layer was about 0.55. However, as the referee states, those particular 5 stations showed anomalies that were not in sync with either the SCAN data or the NOAH simulations. From Figure 1 and Table 1 it can be observed that all of these stations are located in agricultural or mixed crop land coverages. In addition, the stations in North Alabama and southwest Georgia are in heavily irrigated areas. Obviously, the SCAN station would not be irrigated and the NOAH model also does not include it. The ability of the microwave instrument to sense the moisture from irrigation accounts for the seasonal cycle evident in the POME profiles at those sites. In these cases, it is probable that the POME profiles are more accurate over the 5-km spatial grid than are the SCAN or NOAH data. We failed to make this point anywhere in the manuscript and we greatly appreciate the referee pointing it out to us.

Further, the other two sites are located in areas where quite a bit of surface water is present in the remotely sensed pixels. It is possible that the seasonal cycle of water levels in the area account for the behavior seen at these locations.

We will revise the manuscript to add the above discussion to Section 4.3 where Figure 5 is first raised. The later statistical analyses can then be used to support the observations raised there.

Required changes are reported in lines 511-533 of the revised manuscript.

4.   The same strong dynamics occur in the Noah model at the lower boundary condition at many sites whereas, in this layer, POME and SCAN data better correspond to each other.

Response: We completely agree and as mentioned several times throughout the manuscript, this observation provides further evidence of how the POME model tends to improve relative to the SCAN data in the deeper layers of the soil column. It is also evidence that for most of the SCAN sites, the lower boundary condition (at 50% of available water content) seems to be a reasonable assumption for the POME model.

5. In some cases, the SCAN data sometimes show strong (or strange) soil moisture dynamics in the lower part of the profile (2013, 2115) while dynamics in the upper part of the profile is much less pronounced. Please explain.

Response: We too were struck by the behavior at these two sites and conducted an extensive investigation. The SCAN site SM at these locations showed highly seasonal dynamics at the lower depths. Site 2115 is characterized mostly as sandy soil from 0-45 cm depth. These soils have a much lower water holding capacity that leads to increased infiltration to the lower depths. Having sandy soils in the upper layers in part can explain the seasonal variations at the lower depths. Similarly, at site 2013 the upper two layers (0-33 cm) are recognized as sandy loam although the lower layer at the SCAN site exhibits high clay content.

Specific comments and technical corrections:

1. L5: please correct: ALEXI
    Response: Thank you for pointing out this mistake.

2. L39: replace "and" by "that"
    Response: We appreciate the correction.

3. L43: define CONUS
    Response: Thank you. We will make this correction

4. L67-84: In my view, these two paragraphs would better fit into the methods section
    Response: We placed this material at the end of the Introduction to define the objectives of the study and to provide a brief overview of what was done. If the editors think it appropriate, we are certainly open to removing it from this section.

5. L153: typo: consistent
    Response: Thank you. We will make this correction.

6. L159: yes – please define which meteorological forcing was applied in Noah. Was the model calibrated and if yes, to which data?
    Response: A real-time version of the Land Information System (LIS) has been maintained by NASA Short-term Prediction Research and Transition Center (SPoRT) for use in experimental operations by both domestic and international operational weather forecasters (Case et al., 2016, 2008). The basis of the SPoRT-LIS is a 33-year soil moisture climatology simulation spanning 1981–2013 and extended to the present time,

forced by atmospheric analyses from the operational North American Land Data Assimilation System-Phase 2 (Xia et al., 2012). We will clarify this in the revised manuscript.

Required changes are reported in lines 185-188 of the revised manuscript.

7.   L162-165: Yes but then it must be proven that the POME-derived soil moisture profiles are correct. How will they be validated if not in a similar approach as applied in this manuscript?
Response: We appreciate this point. The POME approach has been applied under strictly controlled laboratory conditions (Al-Hamdan and Cruise, 2010; Singh, 2010a), field scale applications (Mishra et al., 2013) and compared to a detailed mathematical model of soil moisture movement (Mishra et al., 2015). In all of these instances, the method has been shown to be highly accurate (error on the order of 3%) when the input data are known accurately. In addition, entropy theory (Jaynes, 1957) indicates that the method will yield the optimal profile subject to the input data.

8.   L170: Please provide reference for the MW soil moisture depth? I think at X-band it should be even less than 2-2.5 cm
Response: Thank you for pointing out this oversight. The penetration depth of the X-band microwaves is indeed 0-2 cm.

9.   L183-185: No sentence
Response: Thank you for pointing it out, it will be replaced by "A time differential application of the ALEXI model was performed to monitor the rise in land surface temperature (LST) from morning to local noon. The early-day rise in LST is used to diagnose the partitioning of net radiation into sensible; latent and soil heat fluxes."

10.   L337: How were the POME based profiles aggregated?
Response: The initial POME profiles were generated at 5 cm layer depths. A simple unweighted (as all layers being aggregated are of equal depth) mean was used to aggregate the SM values from 5 cm layer depths to represent a layer depth consistent with Noah LSM layer depths.

11.   L424: Don't the RS measurements "see" the wet surfaces caused by irrigation?
Response: Exactly, the remotely sensed data are picking up the added water from the irrigation in this area whereas the SCAN site (which is not located in a private irrigated field) is not "seeing" this water and likewise it is not accounted for in the NOAH model. Thus, the positive bias here is not necessarily bad.

12.   L 433: please correct: Fig. 4
Response: Thanks for pointing that out. We will make the correction.

13.   L 459: How was this aggregation done?

Response: Please refer to response 10

14.   L482: Aren't the SCAN observations the "true" SM? The RS soil moisture contents are also estimates.
Response: Thank you for the comment. In triple collocation (TC) analysis the three datasets (including the point SCAN observations) are considered as three independent estimates of the true average soil moisture condition of the pixel. In this analysis there is no way to know the "true" soil moisture. Rather the error in the three datasets is computed relative to the unknown "truth" so that they can be compared to one another.

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Development of Soil Moisture Profiles Through Coupled Microwave-Thermal Infrared Observations in the Southeastern United States

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Abstract. The principle of maximum entropy (POME) can be used to develop vertical soil moisture profiles. The minimal inputs required by the POME model make it an excellent choice for remote sensing applications. Two of the major input requirements of the POME model are the surface boundary condition and profile-mean moisture content. Microwave-based soil moisture esti-

5   mates from Advanced Microwave Scanning Radiometer (AMSR-E) can supply the surface boundary condition whereas thermal infrared-based moisture estimated from the ~~Atmosphere Land Exchange Inverse (AELXI~~Atmosphereric Land EXchange Inverse (ALEXI) surface energy balance model can provide the mean moisture condition. A disaggregation approach was followed to downscale coarse resolution (∼25 km) microwave soil moisture estimates to match the finer resolution (∼5 km) ther-

10   mal data. The study was conducted over multiple years (2006-2010) in the southeastern United States. Disaggregated soil moisture estimates along with the developed profiles were compared with the Noah land surface model (Noah LSM) within the framework of NASA Land Information System (LIS), as well as *in-situ* measurements from 10 Natural Resource Conservation Services (NRCS) Soil Climate Analysis Network (SCAN) sites spatially distributed within the study region. The over-

15   all disaggregation results at the SCAN sites indicated that in most cases disaggregation improved the temporal correlations with unbiased root mean square ~~errors~~ differences in the range of 0.01-0.09 ~~in volumetric soil moisture~~m^3m^{-3}. The profile results at SCAN sites showed a mean bias of 0.03 and 0.05 ~~; unbiased RMSE~~ (m^3m^{-3}); unbiased RMSD of 0.05 and 0.06 (m^3m^{-3}); and correlation coefficient of 0.44 and 0.48 against SCAN observations and Noah LSM, respectively.

20   Correlations were generally highest in agricultural areas where values in the 0.6-0.7 range were

achieved.

1 Introduction

Although soil moisture (SM) represents a relatively small part of the overall hydrologic cycle, it is perhaps the most important part to human survival. SM is the source of water for all vegetation on
25 Earth. It also plays an important role in water and energy exchanges between the land surface and atmosphere. Hydrologically, SM is an indicator of drought or lack thereof, and antecedent moisture conditions are important determinants of runoff response to rainfall events. Thus, SM is a vital part of any terrestrial ecosystem analysis as well as land surface and climate models.

Much of the recent efforts particularly in remote sensing of SM estimation have been focused
30 on surface or near surface observations (0-5 cm); however, moisture throughout the root zone can be just as ~~prevalent~~important. The moisture within the root zone exerts a controlling influence on land-atmospheric fluxes of energy and water under vegetated condition. The actual distribution of root zone moisture is a function of vegetation canopy root density and distribution (Mishra et al., 2013). For this reason, SM at shallow depths (< 100 cm) is known to be extremely variable both as
35 functions of time (Starks et al., 2003) and depth (Scott et al., 2003).

Although several approaches have been proposed for determining SM profiles, most require either observed profile data so that a regression or inversion model can be developed (Arya and Richter, 1983; Kondratyev et al., 1977; Kostov and Jackson, 1993; Srivastava et al., 1997; Singh, 1988). ~~A~~ Another common approach is to estimate surface or total root zone moisture using remote sensing
40 and then assimilate those observations into a land surface model (LSM) to determine root zone SM distributions. The NASA Land Information System ~~(LIS)~~ [LIS, (Kumar et al., 2006)] contains a suite of land surface models and data assimilation tools for this purpose ~~and~~ that are commonly utilized as a source of SM data.

However, LSMs have their own issues (e.g., bias, ancillary data requirements, computational ex-
45 pense) so it would be advantageous if SM profiles could be deduced directly from satellite observations without the use of a LSM or the availability of *in-situ* profile data. *In-situ* SM profile data are only available generally at a few locations over the ~~CONUS~~ continental United States (CONUS) for any given period of time. In addition, a number of field campaigns over the years have produced high-density observations, but only for very short time periods over limited domains. *In-situ* data
50 suffer from the fact that they are site specific and may not be representative of wider surrounding regions. Thus, they are of limited value for modeling or operational purposes. ~~This deficiency has~~ These deficiencies have led to the increased reliance on remote sensing to retrieve SM. However, remotely sensing SM estimates alone cannot deduce the distribution of moisture within a soil column.

Due to the inherent complexities involved with the movement of SM in the column, several studies
55 have argued that SM uncertainties and complexities can be best described through the description of

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its entropy (Mays et al., 2002; Pachepsky et al., 2006; Singh, 2010). The maximization of entropy characterizes the diffusion of moisture through the soil column over a period of time. The principle of maximum entropy (POME) states that if the inferences had to be drawn from incomplete information then they should be based on the probability distribution with maximum entropy allowed by the *a-priori* information. Al-Hamdan and Cruise (2010) used the maximum entropy formulation of Jaynes (Jaynes, 1957a,b) based on the Shannon entropy (Shannon, 1948) to formulate the POME-based SM profile development algorithm. Unlike other methods, the entropy approach suffers from no *a-priori* assumptions about the nature or shape of the moisture profiles in real space. The method is a statistical approach and guarantees the minimum variance unbiased profile subject to the boundary and initial conditions specified. This could be an improvement over other analytical methods that do presuppose a functional form of the SM distribution. Singh (2010) provides a full explanation of the theory of entropy of moisture movement in porous media.

Subsequent to its introduction the POME method has been adopted and extended by several authors (e.g., Mishra et al. (2013, 2015); Pan et al. (2011); Singh (2010)). Initial studies by Al-Hamdan and Cruise (2010) and Singh (2010) compared their results against experimental data under laboratory settings. However studies by Pan et al. (2011) and Mishra et al. (2013) involved application and validation of the POME model outside laboratory environment. More recently, Mishra et al. (2015) provided extensive validation of the profiles developed using the POME approach against a U.S. Department of Agriculture Soil Climate Analysis Network (SCAN) site located in northern Alabama, as well as with a detailed mathematical model of moisture movement in the soil profile.

The objective of this study is to develop SM profiles from remotely sensed data over the southeastern U.S without the aid of observed profile data or the use of a LSM. The approach utilizes both microwave (MW) data (to supply surface estimates) and thermal infrared (TIR) estimates (for total root zone moisture) within the POME profile methodology. The POME model requires only the upper and lower boundary conditions, as well as the mean moisture content, as input. The surface and mean moisture contents can be supplied by satellite estimates, whereas the lower boundary condition ($\sim$100-200 cm) is often fairly stable and can be parameterized. This makes the POME modeling approach quite feasible when working with remotely sensed SM datasetsTherefore, the POME model is ideal for the integration of remotely sensed data from multiple sensors such as MW and TIR to develop a unified SM profile.

Within this studyThe goal of this research is to provide SM profiles at operational or near operational (1-5 km) spatial resolutions to be consistent with other fine scale hydrologic and agricultural modelling work taking place in the study region (Mishra et al., 2013; McNider et al., 2014). Consequently, before the SM profiles can be calculated, the disparity in spatial resolution between the MW and TIR data must be resolved. MW data are available at much coarser spatial resolutions (25-40 km) than are TIR data (1-10 km). The approach selected here is to downscale (or disaggregate) the coarse MW data to the resolution of the TIR data. This is accomplished via an evaporative efficiency method

proposed by Merlin et al. (2013, 2012, 2015).The spatial resolution selected is 4.7 km (∼5 km hereafter) that corresponds to the operational scale of the NWS Multisensor Stage IV precipitation

95   product (Lin and Mitchell, 2005). This facilitates the future integration of the profiles into operational land surface, hydrologic, or agricultural models that are currently operating in the region. It is quite possible that these models could be improved through assimilation of observed SM profiles, especially in regions of the world where climate information is sparse.

As stated earlier, the overall objective of the study is to determine the efficacy of SM profiles

100   developed directly from remotely sensed data only, without the use of a LSM or ancillary data. The study consists of three four parts: (a) a multiyear disaggregation of the coarse resolution MW surface SM to the 5-km spatial resolution; (b) calculation of SM profiles for each 5-km grid using the POME approach with the downscaled MW data serving as the surface boundary condition and TIR estimates providing mean SM; (c) validation of the SM profiles against a gridded LSM and

105   in-situ data; and (d) error analyses including evaluation of downscaled MW surface SM estimates against LSM and in-situ data. Two independent data sources are used for comparison and validation purposes, using ground observations from 10 available NRCS SCAN sites and gridded 3-km Noah LSM SM data aggregated to the 5-km spatial resolution.

2   Study Area and Data Sources

110   ### 2.1   Study Area

The study area for this research is the southeastern U.S consisting of four states including Alabama, Georgia, Florida and South Carolina (Fig. 1). The region is home to a significant amount of current hydrologic and agricultural research activity where accurate SM modeling is a premium (McNider et al., 2011, 2014; Mishra et al., 2013). The southeastern U.S. represents a subtropical

115   humid climate that typically has relatively hot and humid summers and precipitation that is generally evenly 100 distributed throughout the year. The mean annual precipitation is 1250-1500 mm based on the 1981-2010 period. Mean annual temperature ranges from 14^oC in Northern Alabama to nearly 24^oC in southern Florida. The region is roughly 31% forested; 54% shrubs; 12% agricultural land and rest of the area is covered by urban (1.9%), savanna (1.8%), water etc. accord-

120   ing to Moderate Resolution Infrared Spectroradiometer (MODIS) 2008 land cover data aggregated to 5-km spatial resolution. The majority of the soils (nearly 80%) at the surface are classified as sand with loamy sand and sandy loam, as determined from the Soil Information for Environmental Modeling and Ecosystem Management (Miller and White, 1998). These soils are known to have relatively low water holding capacity that can lead to great temporal variation in upper level (1-10

125   cm) SM conditions and relatively frequent short-term droughts (1-4 week period) during growing seasons in various parts of the region (McNider et al., 2014). The Although the study region is overwhelmingly represented by a forest and shrub landscape, vegetation that are known to adversely

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affect the accuracy of MW signals, the study does present an opportunity to evaluate the performance of the merged MW/TIR profiles in a challenging environment and may provide greater confidence in
130   the robustness of the system. Further, the Southeastern U.S. is one of the more data rich regions of the world (climate and soils data) providing ample opportunity for calibration as well as validation of results.

2.2   Data Sources

2.2.1   Microwave Surface SM

135   Over the past several years, much attention has been given to the use of MW sensors to measure surface SM remotely. The use of the MW band is the only remote sensing technique that is physically based as well as quantitative (Kondratyev et al., 1977; Schmugge et al., 1992). Furthermore, due to their all-weather and day/night capabilities, MW sensors are widely used globally and offer high temporal data availability. This study employs one of the more extensively used and validated
140   ~~MW-based~~ MW based SM data sets from the Advanced Microwave Scanning Radiometer (AMSR-E) mission operating in the X-band frequency from ~~2002-2011. The data were obtained from~~ the National Snow and Ice Data Center (NSIDC) and ~~were generated using the so-called "standard "~~ employs the standard NASA retrieval algorithm (Njoku et al., 2003). The NSIDC is one of two AMSR-E data sets supported by NASA with the other being the Vrije Universiteit Amsterdam - ~~an~~
145   ~~iterative multichannel inversion process to deduce surface moisture conditions through comparison~~ ~~of observed and computed brightness temperatures (Njoku et al., 2003). It is primarily impacted by~~ ~~vegetation cover and water content, as well as soil temperature and moisture (Cho et al., 2015).~~ Land Parameter Retrieval Model (VUA-LPRM) data. The LPRM uses a single dual polarized channel (X- or C- band) to deduce relationships between geophysical variables such as soil moisture and
150   vegetation characteristics and brightness temperatures (Cho et al., 2015). Several studies such as Wagner et al. (2007); Draper et al. (2011); Jackson et al. (2010); Gruhier et al. (2008) etc. have compared the two data sets and the general conclusion has been that the VUA-LPRM algorithm may be slightly superior in terms of correlation to *in-situ* data, especially at lower latitudes and sparse vegetation (Brocca et al., 2011). However, Jackson et al. (2010) found that for the southeast U.S, the NASA
155   retrieval algorithm outperformed the LPRM in terms of bias and RMSE. Furthermore, as pointed out by Njoku et al. (2005) and Jackson et al. (2010) the effects of radio frequency interference (RFI) on C-band signals are more pronounced over countries such as the United States and Japan, therefore X-band retrievals are preferred over such regions. Hence X-band based on the standard NASA (or NSIDC) data set was selected for this study. The daily Level-3 AMSR-E SM X-band product (AE-
160   Land3) (Njoku, 2004) from the ascending (1:30 pm local time) overpass was collected for this study. The ascending overpass was selected to be consistent with the ALEXI retrievals, which are forced with morning and local noon skin temperatures obtained from the Geostationary Operational En-

vironmental Satellite (GOES) Imager instrument. The Level-3 AMSR-E SM estimate is a 25-km gridded data product.

2.2.2 Thermal Infrared - ALEXI

Techniques to retrieve root-zone moisture that rely upon TIR data are inferred from surface energy fluxes typically retrieved at relatively high spatial resolutions. TIR-based evapotranspiration (ET) estimates are generally related to LST and vegetation cover fraction. Models such as the Surface Energy Balance System [SEBS: (Su, 2002)]; the Surface Energy Balance Algorithm for Land [SEBAL: (Bastiaanssen et al., 1998)]; and the Two Source Energy Balance [TSEB: (Norman et al., 1995)] exploit this relationship with varying ~~degree~~ degrees of complexities. A two-source based ~~Atmospheric Land EXcahnge Inverse (ALEXI)~~ ALEXI (Anderson et al., 1997, 2007; Hain et al., 2011) model has been implemented over the continental U.S. and used as a source of surface energy fluxes (Anderson et al., 1997; Norman et al., 2003); evapotranspiration (ET) (Anderson et al., 2011b, 2012); SM ~~(Hain et al., 2011; Mishra et al., 2013)~~(Hain et al., 2009; Mishra et al., 2013); and an Evaporative Stress Index (Anderson et al., 2011a, 2013). A continental-scale implementation of the ALEXI model was used in this study to estimate instantaneous energy fluxes. ALEXI fluxes are available at approximately 4.7 km (0.04^o) spatial resolution on a daily time-step since the year 2000 over the ~~continental U.S.~~CONUS, generated using 15-min resolution GOES 10.7 μm channel TIR data. ALEXI estimates of actual ET and SM are used in this study. A known drawback of TIR-based methods is that they are limited to cloud-free conditions.

2.2.3 *In-situ* Observations

The study area contains 25 operational U.S. Department of Agriculture SCAN (Schaefer et al., 2007) monitoring stations. In addition to meteorological observations such as precipitation, air temperature, relative humidity etc. these monitoring stations measure soil temperature and moisture content primarily at depths of 5, 10, 20, 50 and 100 cm at hourly and daily time steps. The SCAN sites use Hydra Probes (Stevens) to observe SM conditions (Schaefer et al., 2007). Most of these 25 SCAN sites are located in northern and central Alabama. Ten sites with the most ~~consiteant~~ consistent data availability and with good geographical distribution across the study area were employed for the comparison. The SM data were obtained from http://www.wcc.nrcs.usda.gov/scan/. Table 1 lists the major land cover type (at 5 km scale) along with soil ~~characteries~~ characteristics at these ten sites.

2.2.4 Noah Soil Moisture

The Noah SM product generated with the NASA LIS (Kumar et al., 2006) framework was selected as a comparison dataset. The Noah model ~~is~~ SM product used in this study is provided by the NASA Short-Term Prediction Research and Transition Center (SPoRT). The model is driven by actual meteorological ~~forcing (what forcing did you use)~~ forcings from the North American Land Data

Assimilation system-Phase 2 (NLDAS2) (Xia et al., 2012), and thus serves as a valuable comparison dataset by which to measure the MW downscaling and profile results. While Noah SM also has biases and uncertainties, the comparisons reveal regional patterns of agreement (disagreement) with

200 the remote sensing estimates. In the event that the POME profiles prove to be superior to the LSM in certain instances, this would indicate that the LSM (or other hydrologic or agricultural models) might be improved through assimilation of the remotely sensed SM profiles. The comparison assumes that errors in the Noah model are independent from the errors associated with MW and TIR based estimates. Noah SM estimates are available in four layers: 0-10; 10-40; 40-100 and 100-200

205 cm depths. It should be noted that there are inconsistencies in the surface layer depths between Noah and MW data: The surface layer in the Noah model is the top 10 cm of the soil column, while the downscaled MW represents the top ~~2-2.5~~ 0-2 cm. The Noah 3-km SM products were aggregated to 5-km to be product consistent with the downscaled MW product.

Additionally, the NLDAS2 gridded temperature forcing data (0.125^o resolution) were also utilized

210 for computing of potential ~~evapotranspiration~~ ET (PET). The NLDAS2 forcing data was available from NASA ~~Land Data Asssimilation System~~ (land data assimilation portal, https://ldas.gsfc.nasa.gov/nldas/NLDAS2forcing.php). The GTOPO30 digital elevation model (DEM) was used as source of elevation information for the study area. The GTOPO30 product was made available by the U.S. Geological Survey's EROS Data Center (https://lta.cr.usgs.gov/GTOP30). The 1-km gridded soil characteristic data for the study area

215 was available from the Soil Information for Environmental Modeling and Ecosystem Management (Miller and White, 1998).

3 Methodology

3.1 ALEXI Retrievals

3.1.1 Surface Evaporation

220 A time differential application of ~~ALEXI to monitor 10.7 μm brightness temperatures that constitute the~~ the ALEXI model was performed to monitor the rise in land surface temperature (LST) ~~rise, specifically~~ from morning to local noon~~which are~~. The early rise in LST is used to diagnose the partitioning of net radiation into sensible~~;~~, latent and soil heat fluxes. The rise in LST from morning to near-noon is known to be correlated with the moisture content of the soil: compared to a dry land

225 surface, wetter surfaces warm slowly, thus requiring more energy for evaporating surface moisture (Hain et al., 2011; Kustas et al., 2001). The soil heat conduction flux is parameterized as a function of net radiation following (Santanello and Friedl, 2003); latent heat from the canopy (transpiration) is estimated assuming a non-stressed modified Priestley-Taylor (Priestley and Taylor, 1972) approach. Finally, the soil (surface) latent heat is the residual of the canopy latent heat and latent heat of the soil

230 and canopy system ~~:~~ $LE_s = LE_{sys} - LE_c$. Here LE_s, LE_{sys} and LE_c represent the latent energy

of surface, system and canopy, respectively. Detailed model description and derivation is provided in earlier studies (Anderson et al., 2007; Hain et al., 2011). If the residual is negative [an indicator of condensation, an unlikely process during daytime (Hain et al., 2011)] then the canopy transpiration is relaxed iteratively until it reaches zero. The surface evaporation from ALEXI is used to compute the soil evaporative efficiency (SEE) function required for the disaggregation (described in section 3.2).

3.1.2   Mean Root Zone Moisture Retrieval

The ratio of actual to potential ET (f_{PET}) is functionally related to the fraction of available water (f_{AW}). Multiple relationships between the ratios of PET and available water have been proposed with varying degrees of success including linear; non-linear; piecewise linear or threshold (Hain et al., 2009). Large-scale applications prefer simpler linear functions as sensitivity to SM is constant and thus relatively less detailed soil characteristics are required (Song et al., 2000). In this study a linear relationship proposed by Wetzel and Chang (1987) is employed: $f_{PET} = 0.85 * f_{AW}$. The resulting ALEXI SM estimation is given as:

$$\theta_{ALEXI} = (\theta_{fc} - \theta_{wp})(0.85 * f_{AW}) + \theta_{wp} \tag{1}$$

Here θ_{fc} and θ_{wp} represent the field capacity and wilting point of the soil, respectively. It is argued that the SM retrieval from diagnosed evaporative fluxes is reasonable when the SM content is within the limits of wilting point and field capacity (Hain et al., 2011). ALEXI retrievals can be interpreted based on fraction of vegetation cover (f_c) as either surface moisture content (f_c <0.3); predominantly root-zone moisture (f_c >0.75) or a composite of both surface and root-zone moisture for f_c between these limits. In this study Priestly-Taylor PET was used with ALEXI actual ET to compute f_{AW}.

3.2   Surface Disaggregation

The spatial resolution of the TIR- based ALEXI SM estimates are roughly 5 x 5 km. Thus, in order to utilize them in conjunction with the AMSR-E MW data, the coarse resolution MW surface estimates must be downscaled to match the ALEXI spatial scale. A physically based, semi-empirical soil evaporative efficiency (SEE) model in combination with a first order Taylor series expansion around the coarse resolution SM is was used to map surface evaporative fluxes to SM content at finer resolutions. The SEE disaggregation approach has become very popular recently and has been employed by several investigators at varying spatial scales and locations such as: Chen et al. (2017) [r: -0.3-0.72, RMSE: 0.06-0.27]; Malbeteau et al. (2016) [r: 0.70-0.94, RMSERMSD: 0.07-0.09]; Merlin et al. (2015) [r: -0.22-0.64, RMSD:0.05-0.32]; Molero et al. (2016) [r: 0.35-0.47, ubRMSEubRMSD:0.04-0.12]. In general, the disaggregation improves agreement with *in-situ* observations in comparison with coarse-scale estimates.

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265　The disaggregation approach decouples the soil evaporation from the top few centimeters of the soil and the vegetation transpiration through ET partitioning. The disaggregation algorithm used in this study follows the concept of the DISaggregation based on Physical and Theoretical scale CHange [DISPATCH: ~~(Merlin et al., 2012, 2013, 2008)~~(Merlin et al., 2012, 2013, 2010)] model. The model accounts for aerodynamic resistance over bare soil in addition to soil parame-
270　ters such as field capacity via the SEE. Detailed DISPATCH algorithm derivation and description is presented by Merlin et al. (2012). Here we represent the prominent disaggregation equation as:

$$SM_{HR} = SM_{LR} + \frac{\partial SM_{mod}}{\partial SEE}\left[SEE_{HR} - \langle SEE_{HR}\rangle_{LR}\right] \tag{2}$$

　HR and LR refer to the high and low-resolution variables, respectively. There have been multiple linear and non-linear relationships proposed between SEE and surface SM in the past (Budyko,
275　1961; Komatsu, 2003; Lee and Pielke, 1992; Manabe, 1969; Noilhan and Planton, 1989). A recent study by Djamai et al. (2015) suggest that the non-linear model performs better in humid climatic condition. Therefore non-linear model suggested by Noilhan and Planton was used in this study to guide the DISPATCH algorithm.

3.2.1　Modified SEE Computation

280　The SEE, which can be defined as the ratio of actual to potential surface soil evaporation (Fang and Lakshmi, 2014; Merlin et al., 2010), is computed at the high resolution first, and then the SEE results are aggregated to the respective low resolution ~~25 km~~ 25-km MW scale. The studies by Merlin et al. (2010, 2012) demonstrated the use of MODIS LST, Normalized Difference Vegetation Index (NDVI) and albedo to determine surface and vegetation temperature and evaporation. The
285　SEE was defined as: $= \frac{T_{s,max}-T_{s,HR}}{T_{s,max}-T_{s,min}}$, where $T_{s,max}$ is the soil temperature at SEE = 0; $T_{s,min}$ is soil temperature at SEE = 1, and $T_{s,HR}$ represents soil temperature at the high resolution grid scale.

　However, in this study we employed the ratio of the estimated surface evaporation from ALEXI to the potential evaporation to compute SEE directly at the 5-km ALEXI resolution. As mentioned earlier, the two-source land surface representation in ALEXI separates surface evaporation and canopy
290　transpiration. The potential surface evaporation is calculated using the Hamon PET (Hamon, 1963). Hamon PET estimates are completely dependent upon atmospheric demand irrespective of soil and vegetation characteristics and can act as a proxy of potential surface evaporation (PE). This represents a subtle change in the definition of SEE from the Merlin formulation in that in our case all land cover/soil matrix combinations are weighted equally as opposed to being weighted by their assumed
295　PE value as in Merlin (approximated as function of surface temperature). Since the Southeastern U.S. is an energy limited, water rich environment (Ellenburg et al., 2016), evaporation is controlled primarily by water availability and atmospheric demand; therefore, the effects of this change are not expected to be large. Hamon PET estimates have been found to be comparable to radiation based

methods (e.g., Priestly-Taylor) to observed ET in the Southeastern U.S. at monthly or longer time scales (Lu et al., 2005), and are computed using air temperatures from the NLDAS2 forcing data subject to terrain adjustment. Terrain adjustment of coarse resolution temperature data was performed using a 30 m digital elevation map of the region and constant lapse rate of -6.5 $K.km^{-1}$ (Cosgrove, 2003).

3.3 Profile Development

A multi-year vertical SM profile was developed for each ALEXI grid cell using the POME model developed by Al-Hamdan and Cruise (2010) over the study area. The application of POME to develop a one-dimensional SM profile requires two constraints; total probability: $\int_{\Theta_L}^{\Theta_0} f(\Theta)d\Theta = 1$; and the mass balance constraint:$\int_{\Theta_L}^{\Theta_0} \Theta f(\Theta)d\Theta = \overline{\Theta}$. Here Θ is effective saturation and $\overline{\Theta}$ is the mean moisture of the soil column; whereas Θ_0 and Θ_L are the upper (surface) and lower (bottom) effective saturation. The effective SM is given as: $\frac{(\theta-\theta_{wp})}{(\theta_{fc}-\theta_{wp})}$. The second constraint serves to connect the first moment in probability space to the mean water content of the soil column in physical space. The Shannon entropy is given by (Shannon, 1948):

$$I = - \int\limits_0^\infty f(x)ln(f(x))dx \tag{3}$$

where $f(x)$ is the probability density function (pdf) of the variable. Maximizing I in Eq. (3) for the uniform pdf subject to the constraints, Chiu (1987) developed the 1-D profile of a variable decreasing monotonically from the surface down using the method of Lagrange multipliers. Al-Hamdan and Cruise (2010) applied the same technique to develop vertical SM profiles either increasing or decreasing with depth from the surface:

$$\Theta(z) = \frac{ln[exp(\lambda_2\Theta_0) \pm exp(1-\lambda_1)(\frac{z}{L})]}{\lambda_2} \tag{4}$$

The Lagrange multipliers ($\lambda's$) can be determined from application of the constraints and boundary conditions (surface effective saturation,Θ_0) and mean effective saturation value of the soil column ($\overline{\Theta}$), z is calculation depth, and L is total depth of the column. Eq. (4) is a monotonically increasing (+ sign) or decreasing (- sign) function, representing dry (increasing from the top boundary) and wet (increasing from the bottom boundary) case profiles.

Experience has shown that not all SM profiles are monotonic as given by Eq. (4). In fact, it is clear that some profiles can be parabolic in shape (i.e., demonstrate an inflection point), especially immediately subsequent to rain events (dynamic case), or due to sharp changes in soil characteristics (Al-Hamdan and Cruise, 2010; Mishra et al., 2015). ~~These~~ Such cases are identified when mass balance cannot be kept by the monotonic assumption and thus Eq. (4) has no solution. In these cases, it is assumed that the inflection point is located in the soil layer with the greatest field capacity

(Mishra et al., 2015). The POME model is then applied twice; from the surface to the inflection point, and then from the inflection point to the bottom boundary. This procedure was only required in 9% of the profiles generated in the study.

As mentioned previously, POME is a statistical approach that begins with the assumption of a uniform soil moisture distribution initially and envisions the profile as either monotonically increasing or decreasing, or possessing one prominent inflection point. The final profile will then be the optimal one subject to the given boundary and initial conditions. Of course, this is a simplification of the true behavior of soil moisture in the field; however, numerous previous studies have demonstrated that if given accurate input data, the error in the profiles will generally be less than three percent (Al-Hamdan and Cruise, 2010; Singh, 2010; Mishra et al., 2015). In the present application, the surface boundary condition is supplied by the downscaled AMSR-E estimates, the mean moisture content from the ALEXI model, and the lower boundary is parameterized as 50% of available water content. The lower boundary was selected so as to maintain the idea of a minimum of *a-priori* information available and experience has shown that the moisture content at lower depths (100-200 cm) is usually not highly variable.

3.4 Temporal Compositing

The ALEXI data are available from 2000 to present and AMSR-E from 2002-2011. For this study, the years 2006-2010 were selected for analysis as the NRCS SCAN data was most consistently available during this period (nearly 92%). The ascending AMSR-E SM estimates were available 64.5% of the days on an average for all scan site locations while ALEXI retrievals were available on only 36% of the days due to cloud cover limitations. Therefore, a three day moving window un-weighted mean was used on AMSR-E and ALEXI retrievals to develop a composite dataset that serves as gap filling and also tends to reduce day-to-day noise in satellite retrievals (Anderson et al., 2011a). Compositing of the ALEXI surface ET increased the mean data availability from 36 to nearly 63% over all scan sites and in the case of AMSR-E compositing ensured close to 100% data availability. The availability of pixels with intersection of AMSR-E and ALEXI data more than doubled from 22.5% to 58.7% for the study period over all sites.

3.5 Evaluation Metrics

The remote sensing derived SM profiles developed using the POME model were compared and validated against *in-situ* observations from 10 NRCS SCAN sites along with the gridded Noah LSM SM products over the study area. The LSM was used as a basis of comparison since the long term goal of the project is to develop RS remotely sensed SM profiles that can be assimilated into hydrologic and other land surface models. The data gaps in all three datasets restrict the possibility of time series analysis; therefore, pair-wise temporal statistical comparisons were performed using traditional matrices such as correlation coefficient (r), root mean square error (RMSEdifference (RMSD)

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and bias. It has been argued that in cases with either the model or reference dataset being biased in mean or amplitude of fluctuations, the traditional ~~RMSE~~ RMSD tends to be an overestimation of true unbiased data (Entekhabi et al., 2010). Therefore an unbiased ~~RMSE~~ RMSD in addition to traditional ~~RMSE~~ RMSD was also computed. The unbiased ~~RMSE~~ RMSD can easily be computed by removing the bias term form the definition as:

$$\underline{RMSE}ubRMSD = \underline{\sqrt{E[(\theta_{est} - \theta_{obs})^2]}}\sqrt{(RMSD^2 - Bias^2)} \tag{5}$$

$$ubRMSE = \sqrt{E[(\theta_{est} - E[\theta_{est}]) - (\theta_{obs} - E[\theta_{obs}])]^2}$$

$$ubRMSE = \sqrt{(RMSE^2 - Bias^2)}$$

~~where, E.is the expectation operator, θ_{est} and θ_{obs} are SM values estimated and observed (or reference), respectively.~~

To assess the quantitative error between three datasets against an unknown true observation, the triple collocation (TC) error estimation method was employed (Stoffelen, 1998). TC has become a very popular technique for simultaneous error analysis of three data sets since its adaptation to SM states by Scipal et al. (2008). The procedure is based on the assumption of linear relationships between the three estimates of the SM at a specific location and the unknown true value. The unknown truth is eliminated from the linear error equations through subtraction and then cross multiplied to determine the error variances of the datasets relative to each other (Gruber et al., 2016). The assumption is that the errors in the three datasets are independent and random. Multiple recent studies have used the triple collocation method for error estimation [such as Crow et al. (2015); Yilmaz et al. (2014); Su et al. (2014); McColl et al. (2014) etc.]. A detailed review of method derivations and application to SM error estimation and analysis is presented by Gruber et al. (2016). In this study, the TC errors were computed using variances and covariances of the datasets (McColl et al., 2014; Stoffelen, 1998; Su et al., 2014). The covariance based approach enables us to compute unscaled error variances directly. Further, the covariance notation also computes the sensitivity of the datasets ($\beta_i^2 \sigma_\Theta^2$) against true SM signal. Here β is the scaling parameter, i is the dataset and σ_Θ^2) is the variance of the true jointly observed SM signal. Sensitivity estimates can be used to further validate and inter-compare the datasets. Recently, McColl et al. (2014) proposed a methodology to compute the correlation coefficient between the involved datasets (referred as X,Y,Z) and underlying true SM signal as:

$$R_i^2 = \frac{\beta_i^2 \sigma_\Theta^2}{\beta_i^2 \sigma_\Theta^2 + \beta_i^2 \sigma_{\epsilon_i}^2} \tag{6}$$

Here $\sigma_{\epsilon_i}^2$ is the error variance if the dataset where $i \in$ [X,Y,Z]. The sensitivity of individual dataset is estimated as:

$$\beta_X^2 \sigma_\Theta^2 = \frac{\sigma_{XY}\sigma_{XZ}}{\sigma_{YZ}} \qquad \beta_Y^2 \sigma_\Theta^2 = \frac{\sigma_{YX}\sigma_{YZ}}{\sigma_{XZ}} \qquad \beta_Z^2 \sigma_\Theta^2 = \frac{\sigma_{ZX}\sigma_{ZY}}{\sigma_{XY}} \tag{7}$$

4 Results and Discussions

4.1 Comparison with Noah LSM

For comparing SM profiles, ~~the 5 cm layer depth~~ 0-100 cm POME based profiles ~~were aggregated at 5 cm layer depth intervals~~ were aggregated using the unweighted simple mean to the depths consistent with the Noah LSM: 0-10; 10-40; and 40-100 cm. The analysis can be approached from three perspectives: the surface values represent the MW downscaling; the bias represents the ALEXI model performance as it is providing the total SM content in the root zone; and the ~~RMSE~~ RMSD is representative of the entropy model as it measures the moisture distribution within the soil column.

Figure 2 shows the statistics of multi-year temporal SM profile comparisons between the POME and the Noah LSM for the study region. The figure shows the mean ~~RMSE and ubRMSE tends~~ RMSD and ubRMSD tend to be relatively stable with depth over the entire region, an indication of relative stability for the profile developed using the POME model. As depth increased, pixel bias ranged from 0.05-~~13~~ 0.13 m^3m^{-3} indicating that the mean SM data from the ALEXI model is positively biased compared to the Noah LSM, although the mean bias was ~~≤~~ ≥ 0.05 m^3m^{-3} for all layers. The overall ~~RMSE~~ RMSD at all layers was found to be under 0.085 in volumetric SM. Moreover ~~<~~ ¿ 97% pixels across the study area showed ~~ubRMSE~~ ubRMSD of less than 0.06 m^3m^{-3} across all layers, indicating good agreement between the POME model and the Noah SM estimates (Jackson et al., 2010). Comparing Fig. 2 with the landcover map (Fig. 1), it seems that the higher correlations (r > 0.6) occur more prominently in the agricultural dominant portions of the study area for the top two layers (0-40 cm). The overall correlations in the range of 0.46-0.54 across layer depths suggest that the temporal variabilities from remotely sensed driven POME model compared fairly well against Noah SM.

Comparison between POME and Noah SM profiles by land cover type (Fig. 3) indicate that the absolute bias tends to increase with depth in the savannah, shrub, and forest land covers while the reverse is evident for the urban, grass and crop coverages. It appears that overall bias is lowest in the savannah, forest, and agricultural land classes and since those classes (particularly forest) dominate the region, this naturally leads the relatively low overall region-wide bias shown in Fig. 2.

The ~~RMSE (and ubRMSE~~ RMSD (and ubRMSD) present an opportunity to judge the overall profile development process. It is clear from Fig. 3 that the ~~RMSE~~ RMSD improves from the surface to the middle layer and then increases again in the bottom layer in every land cover class except shrub.

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The top and bottom layer ~~RMSE~~ RMSD is being impacted by the boundary conditions placed on the

430   POME integral by the MW and the parameterized lower boundary. Clearly, the POME process tends to improve the imprecise surface boundary as depth increases until the assumed lower boundary condition is encountered and results in deterioration of the profile ~~RMSE~~ RMSD.

In terms of correlation, the mid layer (10-40 cm) has the highest correlation (overall mean r = 0.54) for all land cover types with the highest mean correlation of 0.7 for crop dominated landcover.

435   This further demonstrates the capabilities of the ALEXI model to estimate root-zone mean SM content in comparison to the Noah LSM. Incidentally, for most crops, the majority of the root mass is distributed in the top 60 cm of the soils column (Wu et al., 1999). The higher root density ensures the strong coupling of the land-plant-atmosphere system which tends to improve the accuracy of ALEXI in that zone. Increased correlations in the 10-40 cm layer indicate the ability of ALEXI to

440   mimic the temporal patterns in the root-zone consistently relative to Noah. As depth increases, the root density is reduced and thus the coupling between land and atmosphere is also reduced. This fact, along with the relatively coarse parameterization of the lower boundary on the POME profile, leads to a relative decrease in correlation at layer 3 (40-100 cm) at all land covers except for trees (forest). The cropland showed the highest correlations with the Noah profile while keeping the ~~RMSE~~ RMSD

445   and bias consistent with other land types. Agricultural areas demonstrated correlations ranging from 0.5 to 0.7 with a mean correlation of 0.62.

The overall analysis by layer depths appear to indicate that the profiles developed through the POME model using the disaggregated MW and the ALEXI derived mean SM content is in good agreement with the Noah LSM in the ~~Southeastern~~ southeastern U. S. and in very good agreement

450   in agricultural areas of the region.

4.2   Comparison with *in-situ* Observations

The comparison against Noah LSM SM estimates provided useful insights towards the performance of TIR-based SM profiles developed through the POME model. The comparisons against the LSM specifically adds to the analysis of results as a function of land cover, yet as mentioned earlier,

455   the analysis does not assume that Noah is a perfect model - it may have its own errors. Therefore multiple NRCS SCAN site *in-situ* observations are used for further validations. When comparing remotely sensed data to site specific *in-situ* observations, disparities in spatial scale and sensing depth must be considered. Although some authors prefer to remove bias due to the differing scales before comparisons are made (Brocca et al., 2011), it is also quite common to do the comparisons

460   without adjusting for scale, even when only one *in-situ* site is available (McCabe et al., 2005; Sahoo et al., 2008). In this study no bias corrections were performed.

Figure 1 shows the location of each of the sites used for validation along with the underlying land cover map. ~~Table-1~~ Table 1 summarizes the SCAN site characteristics, dominant land cover types and soil characteristics at the surface and 100 cm depth. Dominant land cover for sites 2009, 2114

and 2115 are predominantly savannas and forest type (hereafter referred as forest sites), whereas sites 2013, 2037, 2038 and 2113 are a mix of cropland either with savannas or shrubs (hereafter referred as mixed cropland sites). Only sites **2027**, **2078** and **2053** (hereafter referred as cropland sites) are predominantly cropland at the 5-km spatial resolution footprint. The crop and mixed crop sites are shown in bold in the following text. The SCAN sites monitored SM at depths of 5, 10, 20, 50 and 100 cm. The POME based profiles are developed at 5 cm layer depth increments down to 100 cm depth.

The results of the developed profiles in comparison to the SCAN site observations alone are shown in Fig. 4. First, it is evident in all the statistics except the correlation that the pattern demonstrated in the previous comparisons persists in that the statistics often tend to improve with depth with occasional deterioration when the lower boundary is encountered. Considering the performance of ALEXI initially, the bias appears reasonable in most cases where the majority of instances the absolute bias is less than 0.1 (m^3m^{-3}), but it appears to be best in the mixed cropland areas (mean absolute bias of 0.07 m^3m^{-3} across all depths) and worse in forested sites (mean absolute of 0.13 m^3m^{-3}). In fact, at seven of the ten total sites the overall bias is considerably less than the average moisture content at the SCAN site itself. At the two sites with the highest bias (2009 and **2027**), the mean moisture content from ALEXI was about twice the observations at all layers, indicating that the satellite estimates showed considerable positive bias (mean bias 0.17 and 0.13 m^3m^{-3}, respectively). Hain et al. (2011) pointed out that sensitivity of the ALEXI model decreases as moisture content nears either the wilting point or the field capacity. Both sites 2009 and **2027** had sandy soils at the SCAN site and exhibited the lowest mean moisture content of all sites. At site 2009 with sandy soil through the column, the mean SM content was 0.05 ~~cm^3cm^{-3}~~ m^3m^{-3} against the wilting point of 0.033 ~~cm^3cm^{-3}~~ m^3m^{-3} while **2027** site had sand at the surface and sandy loam (wilting point = 0.095 ~~cm^3cm^{-3}~~m^3m^{-3}) at the 100 cm depth and the mean SM content was 0.12 ~~cm^3cm^{-3}~~m^3m^{-3}. Moreover, the site 2009 is located in a forest-dominated region. Whereas for site **2027** (located in southwest Georgia), the higher bias in remotely sensed observations can be attributed to additional SM content due to irrigation. Southwest Georgia is one of the most irrigated regions of the study area. In contrast, the SCAN site observations are primarily governed by precipitation alone.

In the case of ~~RMSE~~RMSD, half the sites showed an average ~~RMSE~~ RMSD of 0.1 m^3m^{-3} or less. ~~RMSE~~ RMSD tends to be better at the mixed land use sites, while poor performances at sites 2009, 2115 and **2027** skewed the forest and cropland results respectively. As in the bias case, these sites demonstrated the highest mean ~~RMSE values (Figure-4~~RMSD values (Fig. 4). However, with the exception of these sites, the average ~~RMSE~~ RMSD was less than the SCAN average moisture content in all cases. The ~~ubRMSE~~ubRMSD, on the other hand, at all sites was better with the overall ~~ubRMSE~~ ubRMSD for all layer depths and land cover types exhibiting an average ~~ubRMSE~~ ubRMSD of 0.07 ~~. The ubRMSE~~ m^3m^{-3}. The ubRMSD tended to improve with depth for all cases (Fig. ~~5~~4) up to the depth of 50 cm, but showed a rise at the 100 cm depth as discussed previously.

Improvements in ~~ubRMSE~~ ubRMSD with depth indicate the ability of the POME model to converge and correct itself from the effects of the noisy surface boundary condition until the assumed lower boundary affected the performance in that layer.

505   The ~~correlation coefficient (r)~~ r results are interesting and do not necessarily track the other two indices. It is clear from Fig. 4 that POME tended to perform better in agricultural land use areas than in other environments. Similar to the bias results, correlation was poorest at forested locations. In all, three sites showed average correlation above 0.5 with four other sites showing a correlation above 0.4. Two sites (2009, **2113**) produced average correlations of 0.16 and 0.32 across all depths. As

510 discussed earlier, site 2009 is forested while ~~2113~~ **2113** is located near a water body (Lake Catoma). Overall, the crop sites showed the highest correlations (0.51) followed by mixed crop sites (0.42), an indication of the ability of the satellite derived surface and mean moisture content estimates to mimic wetting and drying patterns over time across depths.

    However, the correlation consistently declined with depth at most of the agriculture and mixed

515 agriculture sites. The decline most often became more pronounced after the second (or sometimes third) layer indicating that the influence of the parameterized lower boundary extends through the lower 50 cm of the profile, at least to some extent. This phenomenon was not evident in the forest areas where the SM was not as variable in the lower layers.

4.3   Intercomparison of Noah, POME with *In-situ* Observations

520 The POME profiles have been compared with Noah LSM across the study region and against *in-situ* observations at ten locations. However, as mentioned earlier, both analyses have some limitations either in terms of proxy ground truth (in case of LSM) and spatial representation (*in-situ* observations). Therefore, in this section an intercomparison between the three datasets is performed to assess the relative strength of each SM dataset. Figure 5 shows the time series of the SM state from Noah LSM,

525 SCAN observations and the POME model. Consistent with the layer depths of the Noah, the POME profile and the SCAN observations were aggregated to 0-10; 10-40; and 40-100 cm layer depths.

    The figure shows that the three data sets track each other well in some cases and that in others there are significant discrepancies. In general, with the exception of a few cases, it appears that the POME and SCAN profiles track better than the Noah simulations in the lower soil layers. In

530 particular, the Noah model shows a prominent cycling effect in the bottom layer at many sites that is not present in the other two data sets. On the other hand, the POME time series at the sites dominated by agricultural and mixed land uses (e.g., **2027, 2053, 2078, 2037, 2013**) exhibit a pronounced cyclic effect in the surface layers in addition to a positive bias compared to the Noah and the SCAN data. The sites in north Alabama (**2053** and **2078**) and in western Georgia (**2027**) are located in some

535 of the most highly irrigated regions of the study area. Therefore, the MW derived upper boundary condition for the POME model is likely to sense the irrigation activity in the region compared to the precipitation derived Noah LSM and SCAN observation located in non-irrigated areas. Further, the

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other two sites (**2037** and **2013**) are located in areas with close proximity to surface water and hence the MW surface SM estimates can be contaminated and result in the positive bias being observed at those locations. The forest dominated sites (2009, 2114 and 2115) on the other hand showed that the POME model profiles are more comparable overall to the Noah LSM than to the point sourced SCAN observations. The mixed agricultural sites (**2113** and **2038**) are located in regions hardly experiencing any irrigation activity and not impacted by surface water, and thus showed little to no bias at the surface against Noah and SCAN profiles. The time series observations suggests that the downscaled MW surface SM is able to sense irrigation activity and therefore may provide an accurate surface boundary condition to the POME model. At lower depths (40-100 cm) the POME profile seems to be in better agreement with the SCAN observations than the Noah estimates, which indicate that the parameterization of the lower boundary condition seems to be reasonable in this case, and that the POME profiles actually improve with depth in contrast to the Noah simulations.

Table-2 shows the detailed statistics of comparison between Noah LSM SM, *in-situ* observations and POME profiles at each SCAN site location. The results are further summarized across all sites in ~~Figure-6.~~ Fig. 6. The overall results show that the satellite-based and LSM SM estimates are reasonably comparable based on error statistics of ~~ubRMSE~~ ubRMSD (0.05 vs 0.04 m^3m^{-3}) and absolute bias (0.08 vs 0.07 m^3m^{-3}). For the surface layer (0-10 cm) comparisons, the Noah correlations are superior to the POME model (r = 0.75 vs 0.54), although in several cases the Noah correlations decrease vertically through the soil column to the point that the two approaches are much more comparable (Fig. 6). This case does not show the steep decline in correlation through the POME profiles as before, indicating that amalgamation of the lower layers into one 60 cm layer has dampened that effect. In terms of mean bias across layers, the POME model is superior in four cases, Noah is superior in four cases and in the other two cases (2115 and **2053**) the two models perform the same. In terms of ~~ubRMSE~~ ubRMSD, the POME is superior to Noah at three locations while at other six locations the difference is within 0.01 (~~in cm^3cm^{-3}~~ m^3m^{-3}). Overall, the average statistics across all depths and all sites, the Noah/SCAN average ~~RMSE~~ RMSD was 0.09 m^3m^{-3} in comparison to the POME ~~RMSE~~ RMSD of 0.10 m^3m^{-3} against ground based SCAN observations. The unbiased ~~RMSE~~ RMSD between Noah and SCAN was 0.04 m^3m^{-3}, and for the POME it was 0.05 in volumetric SM. Figure 6 shows that the Noah LSM tended to become less accurate compared to the SCAN observations with depth while the POME generally showed the reverse.

The three data sets can be further compared through TC analysis. TC has the advantage that the SCAN observations are treated equally with the LSM and POME as just another estimate of the true SM state. The analysis is performed for three layers to be consistent with the LSM model configuration (Fig. 7). The surface results (0-10 cm) showed that in most instances the SCAN observations are closer to the true SM compared to the Noah and POME data; however, the latter two data sets also show high coefficient of determination (R^2) values at several sites. The middle and bottom layer results appear to indicate that the Noah LSM is superior (with 5 and 9 instances

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575 of $R^2 > 0.8$, respectively), while the SCAN observations and the POME model track each other
fairly well with ~~6 and 5~~ six and five instances, respectively, of $R^2 > 0.4$ for the POME and ~~5 and 4~~
five and four such instances for SCAN observations. ~~The~~ It should be noted here that although TC
accounts for total error among the three data sets, the Noah results may be problematic in that~~the~~
~~basic assumption of TC analysis is that the errors are random and unrelated. In the case of a LSM~~
580 ~~such as Noah,~~ unlike the other two data sets, the deterministic SM equation (e.g., Richards Equation)
governs the movement of moisture through the column and some of the random errors are eliminated.
This would not affect the surface layer, which is governed by precipitation and surface evaporation.
Thus, the errors in the LSM at the deeper layers may be dampened ~~. The conclusion may be that the~~
~~LSM cannot be fairly evaluated through a purely stochastic analysis such as TC~~and thus affect the
585 results.

4.4 ~~Error Characterization~~

5 Error Characterization

The developed profile results are impacted by the boundary conditions applied to the POME as the
integral serves to transition the profile between the upper and lower boundary conditions. The upper
590 boundary is associated with the MW surface SM estimates while the lower boundary was assumed
for this study and potentially could be parameterized or used as a calibration parameter. In addition,
the mean SM estimated from ALEXI determines the total mass to be distributed. Earlier studies by
Al-Hamdan and Cruise (2010) and Mishra et al. (2015) showed that the POME model is capable
of producing profiles with significant accuracy with mean absolute errors in the range of 0.5-3.0%
595 for known input conditions. However, in this study inputs to the POME model are derived from
remotely sensed measurements, in addition to a parameterized bottom boundary condition. Hence,
profile errors may be characterized in terms of errors in input parameters.

~~Figures 8~~Figures 8(a) and (b) shows the sensitivity of the profile in terms of bias and ~~RMSE~~
RMSD to variations in the mean and surface constraints. From ~~Figure 8~~Figure 8(a) it is clear that,
600 even if the surface boundary condition is off by 50% (in effective SM), the overall profile ~~RMSE~~
RMSD and bias is less than 0.35 (in effective SM), and the maximum possible deviation in the
surface boundary results in bias and ~~RMSE~~ RMSD of 0.62 and 0.67 (in effective SM), respectively.
The sensitivity study of the mean moisture content (~~Figure 8~~Fig. 8(b)) shows that the bias and
~~RMSE~~ RMSD of the profile (in terms of effective SM) are linearly related to the deviations in the
605 assumed mean. ~~Further, Figure 8~~ Furthermore, Fig. 8 indicates that the profile is more sensitive to
errors in the mean than it is to deviations in the surface boundary condition.

5.0.1 Effect of Disaggregation of AMSR-E MW Data

Figure 8 shows that the POME profile is sensitive to the surface boundary conditions. In this study these conditions are provided by AMSR-E; therefore, it is instructive to examine the relative accuracy of the downscaled MW data. To that end, the AMSR-E surface SM before and after disaggregation is compared to both the Noah LSM and the *in-situ* SCAN data to quantify the effect of the SEE downscaling algorithm. The results from a temporal analysis between coarse and downscaled (fine) resolution MW surface SM with the Noah LSM surface is shown in ~~Figure 9~~ Fig. 9 for the study domain. The figure shows that the generally negative bias of the original AMSR-E data (overall mean = -0.08 m^3m^{-3}) when compared to the Noah LSM was transformed by the disaggregation to a positive bias in the eastern half of the study area although the overall bias remained slightly negative. The positive bias in the eastern zone was largely in the 0.04 to 0.13 m^3m^{-3} range. It is also apparent that this same area exhibited a substantial increase in correlation between the downscaled MW and Noah data. Comparing Fig. 9 to the land cover image in Fig. 1, it can be see that the increase in correlation was largely in the agricultural bands in the southwestern Georgia leading into southeastern Alabama. However, a few areas, such as extreme southwestern and east-central parts of Alabama, showed degradation in correlation on downscaling. The land cover map shows that these areas are generally forested. Overall the temporal ~~correlation (r)~~ r showed a modest increase from 0.21 to 0.25 with downscaling for the study area indicating that downscaled AMSR-E is slightly more comparable to Noah LSM surface SM. Perusal of the figure shows that the poor results in Florida and along the eastern seaboard are primarily responsible for the low correlations. It also demonstrates the fundamental property that the downscaling process will be compromised in areas where the original MW data was of exceptionally poor quality to begin with.

It is difficult to determine the impact of the disaggregated MW surface SM estimates on the profiles compared to the LSM. First, the statistics shown in Fig. 9 are for the sensing depth of the raw AMSR-E data (~~0-5~~ 0-2.5 cm) while the relatively better statistics shown in Fig. 2 are for the top layer corresponding to the Noah LSM (0-10 cm). This disparity in depth is undoubtedly affecting the results. The introduction of the mean SM from ALEXI also affects the near surface layer in the POME profile since mass balance must be maintained throughout the soil column. In any case, comparison of Fig. 2 and 9 shows that the profile statistics are considerably improved compared to the MW surface values and thus the noise in the MW data has a minimal effect when compared to the Noah LSM.

The results of the comparison with the SCAN sites are perhaps more instructive and are given in ~~Table 3~~ Table 3 below. The table shows that in terms of correlation, the disaggregated data were better related to the *in-situ* data than were the original coarse scale MW data (r = 0.53 vs r= 0.31). This result was particularly evident at the agricultural SCAN sites (r=0.64 vs r=0.42). These results were obtained at a slight cost in the bias (bias=0.07 vs bias=-0.02 ~~) and RMSE (RMSE~~ m^3m^{-3} ~~)~~ and RMSD (RMSD=0.1 vs ~~RMSE~~RMSD=0.12 m^3m^{-3}), although the difference was not as great

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in unbiased ~~RMSE~~RMSD. In the case of ~~Table 3~~Table 3, the SCAN depth is the same as the MW so comparisons are apt. In cases of relatively high bias in the MW data (e.g., sites 2009, 2114, **2053, 2078**) this error is introduced into the POME profile. Figure 8 shows that errors in the surface boundary of about 0.1 translate to bias and ~~RMSE~~ RMSD in the profile of about 0.05 (in effective SM). It appears from ~~Table 3~~ Table 3 that at the sites demonstrating the consistently higher bias and ~~RMSE~~RMSD, the error in the surface boundary could be responsible for one third to one half of that total.

5.0.2 Effect of Mean SM Inputs

The mean SM content within soil column in this study obtained from TIR based ALEXI model served as one of the two remotely sensed input parameters for the POME model. Therefore the mean SM content retrieved from the ALEXI model is compared with the Noah LSM. The results of the temporal analysis between the two datasets are shown in Fig. 10. The overall bias between the two datasets is 0.04 $m^3 m^{-3}$. The overall ~~RMSE~~ RMSD is 0.08 ~~with ubRMSE~~ $m^3 m^{-3}$ with ubRMSD of 0.04 $m^3 m^{-3}$ indicating that the mean SM content of the two datasets is similar. In terms of correlation coefficient, the root zone correlation nearly doubled (r = 0.49) compared to the surface correlations (~~Figure 9~~Fig. 9). Further, comparison of Fig. 10 with Fig. 1 reveals that, similar to the surface SM analysis, the mean SM content with the highest correlations (r ~~≥~~> 0.5) are observed mostly in agriculture-dominated areas.

Figure 8(b) shows that the translation of the error in the mean SM content to errors in the POME profile is linear, so an error of 0.04 in the ALEXI mean compared to the LSM would translate into a similar error in the computed profile. Examination of column 2 (NP) in ~~Table 2~~ Table 2 above shows that this error represents the majority of the errors in the computed POME profiles compared to the LSM. Overall, the analysis revealed that the surface SM estimates accounted for, at most, for one third to one half of the error in the SM profiles and for most cases, the mean SM and the parameterized lower boundary accounted for the majority of the error. Recent advances such as the L-band sensor aboard the SMAP mission, offers the potential for even better correlated MW data. In addition, further analysis of the lower boundary condition parameterization could improve the profiles, particularly in the lower layers. For example, Mishra et al. (2013) used POME generated profiles to update SM within a crop model using the lower boundary condition from the model itself. If sufficient ground truth data are available, calibration could be accomplished, or the lower boundary could be set as a function of soil properties in the bottom layer of the profile.

The relatively sparse (5-10 day recurrence interval) availability of the ALEXI TIR-based SM retrieval is the major weakness of the procedure and necessitated compositing of the data into three day running means. However, the issue is a function of the semi-tropical humid climate of the Southeastern U.S. Drier regions of the world would not suffer as much from this issue. Thus it is possible that the proposed method could be employed to deduce vertical SM profiles in regions of

680 the world where observed climate data are scarce or insufficient to drive ecological models. These profiles could be assimilated into the models to help correct for model bias due to the poor climate inputs.

6 Conclusions

This study evaluated the feasibility of linking downscaled MW surface SM with TIR root zone
685 estimates to develop entropy-based vertical SM profiles. The SM profiles (including surface values) were compared to *in-situ* data at the Southeastern U.S. as well as the Noah LSM within the NASA LIS. Initial results are encouraging. The SEE disaggregation method of Merlin et al. (2012), guided by high resolution TIR estimates from the ALEXI model, showed promise when compared to the *in-situ* and modeled estimates in a humid semi-tropical region of the U.S. The POME generated SM
690 profiles generally compared favorably with the SCAN site profiles and the Noah LSM. In summary:

When the Noah LSM and the POME profiles were compared to the *in-situ* data in terms of bias, the POME-generated profiles were clearly superior in at four sites, the LSM was superior at four sites and the two methods were the same at the other sites. However it must be noted that there is a scale
695 mismatch when comparing with *in-situ* observations, also biases may exist in SCAN observations as well as the models. The maximum correlation in the range of 0.4-0.65 was observed in agriculturally dominant areas. Further the highest correlations were found at the depth of 10-40 cm, coinciding with the maximum root density for crops and thus offering a better coupling between land and atmosphere. The ALEXI model was able to pick the wetting and drying trends in the root-zone
700 consistently.

Compared to *in-situ* observations, the bias and RMSE RMSD of the Noah model often tended to degrade vertically with depth while the reverse was evident in most of the POME profiles. This While acknowledging that the SCAN data contains biases and errors of their own, this characteristic of the remote sensing driven POME method seems to imply open the possibility that profiles from
705 land surface models could be improved in terms of bias and RMSE RMSD through the assimilation of the remotely sensed profiles. This conclusion is bolstered by the results of previous studies (e.g., Al-Hamdan and Cruise (2010); Singh (2010); Mishra et al. (2015)) that have found that the when the input data are well defined, the POME profiles are highly accurate throughout the soil column. TC analysis revealed that the POME and observed SCAN site observations tracked well, while the
710 LSM appeared to show less variability, possibly due to the use of the deterministic Richards Equation to model SM movement through the soil column.

Error analyses revealed that the majority of the error in the POME generated profiles was due to error in the mean SM deduced from the ALEXI retrievals and the parameterized lower boundary condition. The SEE downscaling procedure increased the correlation of the surface SM compared

715 to both the LSM and the SCAN sites, especially in agricultural areas where correlations in the range of 0.5-0.8 were achieved. In the meantime, the overall bias was reduced by a factor of 4 and the ~~RMSE~~ RMSD was only slightly increased (0.09 to 0.10 ~~).~~ $m^3 m^{-3}$). The error analysis suggested that at most the MW derived surface boundary accounted for at most one third to one half of the overall error in the POME profiles. Downscaling generally was less effective in locations where the

720 AMSR-E demonstrated positive bias and appeared to lose effectiveness as the bias increased. MW surface observations can be contaminated when a high percentage of the pixel is dominated by water, as near large streams or lakes or in the near coastal region. Dense vegetation also tends to degrade the MW results. ~~Overall, analysis revealed that the surface SM estimates accounted for, at most, for one third to one half of the error in the SM profiles and for most cases, the mean SM and the~~

725 ~~parameterized lower boundary accounted for the majority of the error. Recent advances such as the L-band sensor aboard the SMAP mission, offers the potential for even better correlated MW data. In addition, further analysis of the lower boundary condition parameterization could improve the profiles, particularly in the lower layers. For example, Mishra et al. (2013) used POME generated profiles to update SM within a crop model using the lower boundary condition from the model itself.~~

730 ~~If sufficient ground truth data are available, calibration could be accomplished, or the lower boundary could be set as a function of soil properties in the bottom layer of the profile.~~

~~The relatively sparse (5-10 day recurrence interval) availability of the ALEXI TIR-based SM retrieval is the major weakness of the procedure and necessitated compositing of the data into three day running means. However, the issue is a function of the semi-tropical humid climate of the~~

735 ~~Southeastern U.S. Drier regions of the world would not suffer as much from this issue. Thus it is possible that the proposed method could be employed to deduce vertical SM profiles in regions of the world where observed climate data are scarce or insufficient to drive ecological models. These profiles could be assimilated into the models to help correct for model bias due to the poor climate inputs.~~

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Tables

Table 1. SCAN site 5 km dominant land cover (MODIS 2008) and soil characteristics (SCAN) at surface and depth of 100 cm [S-Sand; L-Loam; C-Clay and Si-Silt]

SCAN Site	Lat/Lon	Land cover	Soil Type (SCAN)	
			Surface	100cm
2009	30.3/-84.4	Savannas/Mix Forest	S	S
2013	33.8/-83.4	Crop/Savannas	SL	C
2027	31.5/-83.5	Cropland	S	SL
2037	34.3/-79.7	Crop/Shurbland	-	-
2038	32.6/-81.2	Crop / Savannas	-	-
2053	34.9/-86.5	Cropland	SiCL	SiC
2078	34.9/-86.6	Cropland	SiCL	C
2113	34.2/-86.8	Crop/Savannas	L	SCL
2114	32.6/-88.2	Savannas	SCL	CL
2115	32.4/-85.7	Savannas	LS	SC

Table 2. Results of temporal comparisons in absolute bias(m^3m^{-3}), RMSD (m^3m^{-3}), ubRMSD (m^3m^{-3}) and correlation at 10 sites between the developed profile and Noah SM profiles against SCAN observations at 0-10; 10-40 and 40-100cm depths [NP - Noah vs POME; SP - SCAN vs POME; and NS – Noah vs SCAN]

Site	Bias			RMSD			ubRMSD			Correlation			
	NP	SP	NS	NP	SP	NS	NP	SP	NS	NP	SP	NS	
2009	0.02	0.13	0.11	0.05	0.14	0.12	0.04	0.04	0.03	0.12	0.23	0.56	
2014	0.00	-0.10	-0.10	0.06	0.13	0.11	0.06	0.07	0.03	0.54	0.50	0.85	
2015	0.01	0.15	0.14	0.07	0.16	0.14	0.07	0.06	0.00	0.50	0.54	0.72	
2027	0.09	0.19	0.10	0.10	0.20	0.11	0.06	0.07	0.05	0.64	0.49	0.70	
2053	0.05	0.03	-0.02	0.07	0.06	0.04	0.05	0.06	0.03	0.77	0.75	0.85	0-10 cm
2078	0.05	0.03	-0.02	0.09	0.09	0.05	0.07	0.08	0.05	0.73	0.69	0.72	
2113	0.00	0.02	0.03	0.06	0.08	0.06	0.06	0.08	0.05	0.41	0.51	0.86	
2037	0.06	0.08	0.02	0.09	0.10	0.04	0.07	0.06	0.03	0.40	0.63	0.72	
2038	0.02	0.02	0.16	0.06	0.06	0.04	0.05	0.05	0.04	0.34	0.37	0.62	
2013	0.04	0.07	0.23	0.07	0.09	0.04	0.05	0.05	0.03	0.59	0.67	0.88	
2009	0.06	0.18	0.12	0.08	0.19	0.13	0.05	0.03	0.05	0.21	0.17	0.37	
2014	0.02	-0.14	-0.16	0.05	0.14	0.17	0.04	0.04	0.06	0.69	0.60	0.78	
2015	0.00	0.04	0.04	0.04	0.06	0.05	0.04	0.04	0.03	0.52	0.51	0.80	
2027	0.06	0.14	0.08	0.07	0.14	0.09	0.04	0.05	0.04	0.70	0.56	0.63	
2053	0.00	0.03	0.03	0.05	0.07	0.06	0.05	0.06	0.05	0.67	0.51	0.74	10-40 cm
2078	0.01	-0.06	-0.06	0.05	0.07	0.09	0.05	0.05	0.06	0.69	0.56	0.56	
2113	0.04	0.03	-0.01	0.08	0.06	0.03	0.06	0.05	0.03	0.37	0.37	0.91	
2037	0.07	0.10	0.02	0.08	0.10	0.03	0.03	0.03	0.02	0.57	0.55	0.78	
2038	0.08	-0.01	-0.09	0.09	0.04	0.10	0.05	0.04	0.04	0.44	0.39	0.55	
2013	0.07	0.05	-0.02	0.10	0.08	0.04	0.07	0.06	0.03	0.29	0.27	0.88	
2009	0.09	0.20	0.11	0.10	0.20	0.12	0.05	0.03	0.05	0.22	0.16	0.33	
2014	0.04	-0.17	-0.21	0.08	0.17	0.22	0.07	0.02	0.07	0.65	0.59	0.68	
2015	0.00	-0.02	-0.02	0.04	0.08	0.06	0.04	0.07	0.05	0.48	0.45	0.81	
2027	0.08	0.05	-0.02	0.10	0.06	0.06	0.06	0.03	0.06	0.38	0.40	0.58	
2053	0.01	-0.04	-0.04	0.08	0.06	0.06	0.08	0.05	0.05	0.49	0.51	0.85	40-100 cm
2078	0.03	-0.08	-0.11	0.08	0.09	0.13	0.08	0.04	0.06	0.54	0.54	0.74	
2113	0.07	-0.03	-0.10	0.11	0.06	0.11	0.08	0.05	0.05	0.32	0.27	0.85	
2037	0.09	0.04	-0.04	0.10	0.05	0.06	0.04	0.03	0.03	0.52	0.45	0.68	
2038	0.13	-0.10	-0.22	0.14	0.10	0.23	0.06	0.03	0.06	0.42	0.40	0.35	
2013	0.12	0.08	-0.04	0.15	0.12	0.09	0.09	0.09	0.07	0.16	0.10	0.65	

Table 3. Statistical comparison before and after disaggregation of coarse resolution MW SM against SCAN observations [r – correlation coefficient;bias, RMSD and ubRMSD in $m^3 m^{-3}$; N – number of days data points was available; maximum possible N = 1825];*non-significant correlation using two-tailed t-test at 99% CI*

| Site	Mean SM				SCAN/MW(25km)				SCAN/MW(5k)			
	SCAN	MW (25k)	MW (5k)	N	Bias	RMSD	ubRMSD	r	Bias	RMSD	ubRMSD	r
2009	0.06	0.18	0.19	841	0.12	0.12	0.02	-0.12*	0.13	0.14	0.04	0.17
2014	0.26	0.15	0.19	1055	-0.11	0.14	0.09	0.30	-0.07	0.12	0.09	0.47
2015	0.08	0.15	0.25	1103	0.08	0.09	0.04	0.42	0.17	0.19	0.08	0.60
Mean					**0.03**	**0.12**	**0.05**	**0.22**	**0.08**	**0.15**	**0.07**	**0.42**
2027	0.08	0.13	0.29	1241	0.05	0.06	0.03	0.48	0.21	0.22	0.08	0.50
2053	0.24	0.14	0.32	1160	-0.10	0.13	0.08	0.43	0.08	0.10	0.06	0.74
2078	0.25	0.14	0.31	1080	-0.12	0.13	0.05	0.34	0.06	0.10	0.08	0.68
Mean					**-0.06**	**0.10**	**0.05**	**0.42**	**0.12**	**0.14**	**0.07**	**0.64**
2113	0.20	0.14	0.18	1014	-0.06	0.12	0.10	0.44	-0.02	0.10	0.09	0.47
2037	0.16	0.14	0.21	1157	-0.02	0.06	0.05	0.11	0.06	0.10	0.09	0.62
2038	0.14	0.16	0.16	1067	0.02	0.05	0.04	0.45	0.02	0.06	0.06	0.31
2013	0.21	0.15	0.23	1218	-0.06	0.09	0.06	0.21	0.02	0.05	0.05	0.55
Mean					**-0.03**	**0.08**	**0.06**	**0.26**	**0.02**	**0.08**	**0.07**	**0.53**
Overall Mean					**-0.02**	**0.10**	**0.06**	**0.31**	**0.07**	**0.12**	**0.07**	**0.53**

Figures
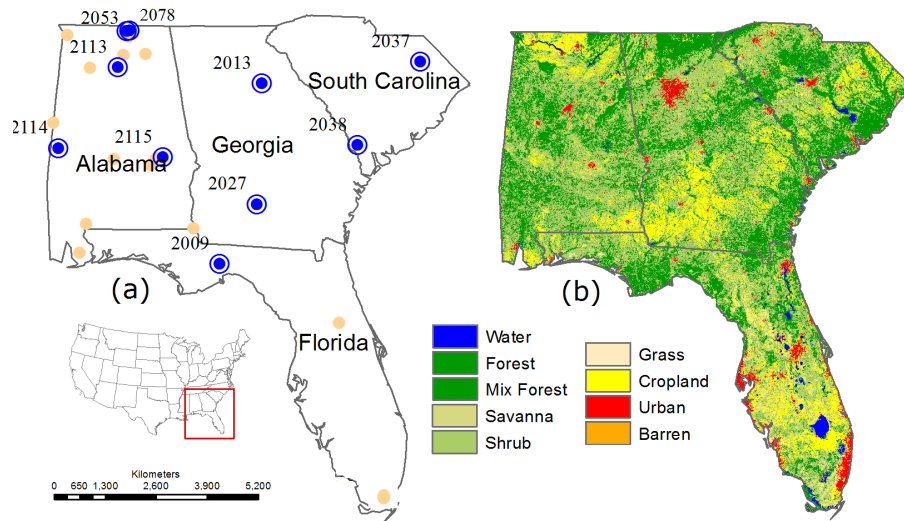
Fig. 1. (a)Overview of study area showing location of all active SCAN sites. The dark blue circles indicate sites with most consistent data availability and are being used for comparison and validation in this study.(b) The figure shows a land cover map (MODIS-2008) for the study area.
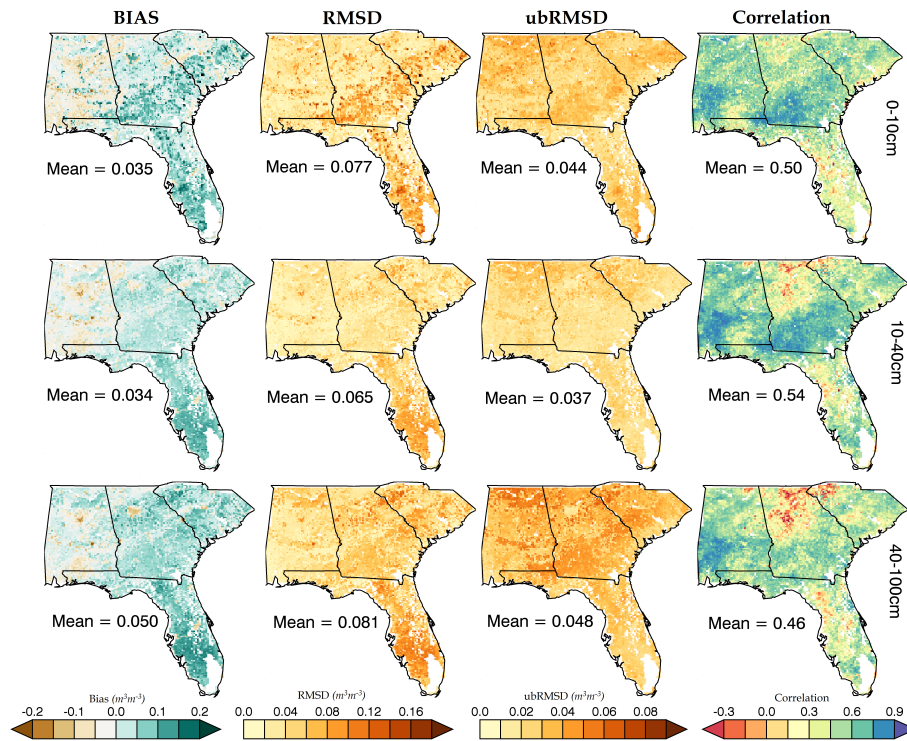

Fig. 2. Map of bias, ~~RMSE~~RMSD, ~~ubRMSE~~ubRMSD and correlation coefficient between Noah and POME SM profiles over multiple years (2006-2010) at different layer depths: top panel: 0-10 cm; middle panel: 10-40 cm and bottom panel: 40-100 cm.
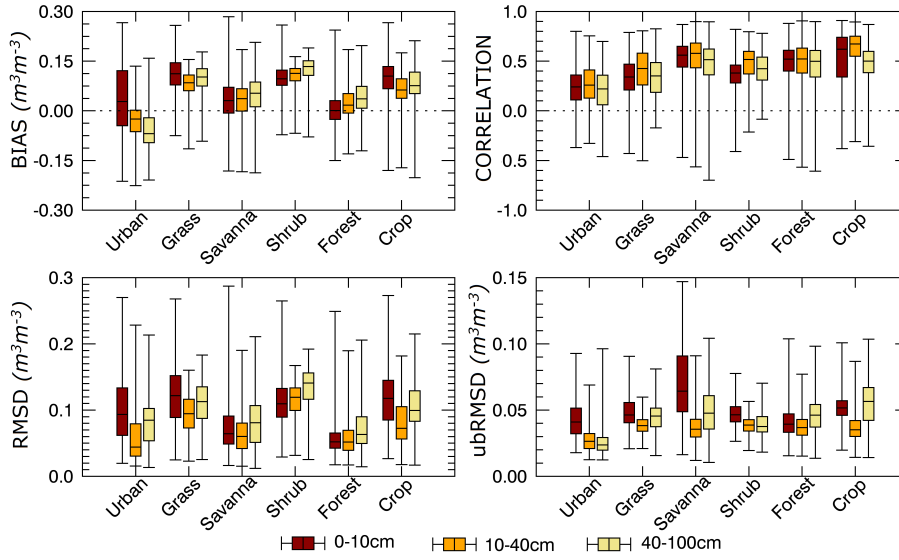
Fig. 3. Comparison of Noah and POME SM profiles at multiple layer depths by Land Cover across Southeast United States
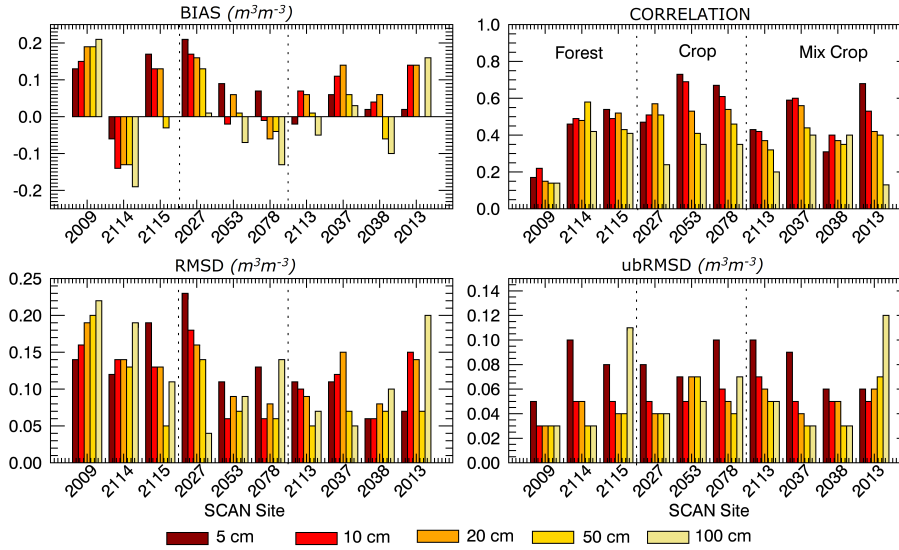

Fig. 4. Statistics at SCAN sites showing bias, Correlation, ~~RMSE~~ RMSD and ~~ubRMSE~~ ubRMSD between SCAN observations and POME SM profiles at multiple layer depths.

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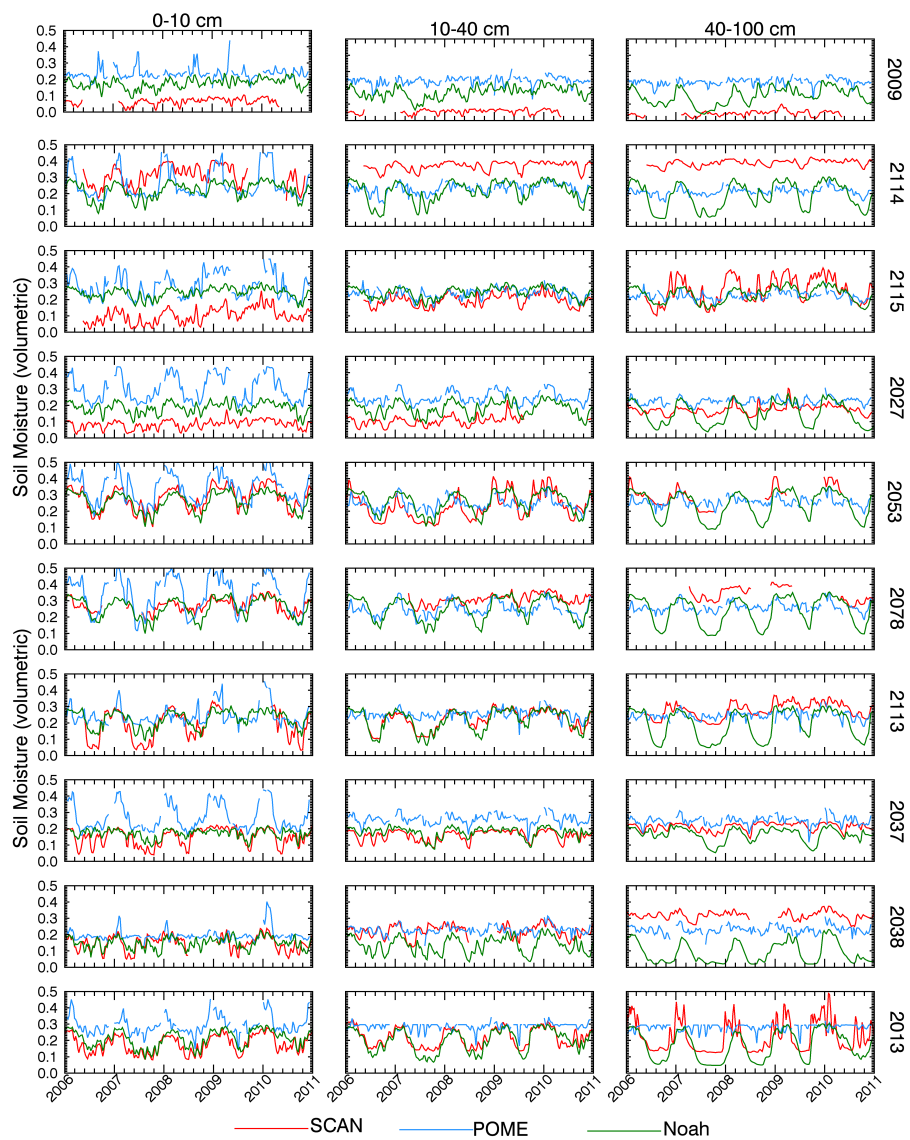
Fig. 5. Time series of soil moisture condition at 10 NRCS SCAN sites from the POME model (Blue); Noah LSM (green) and *in-situ* observations (red) at three layer depths (2006-2010)

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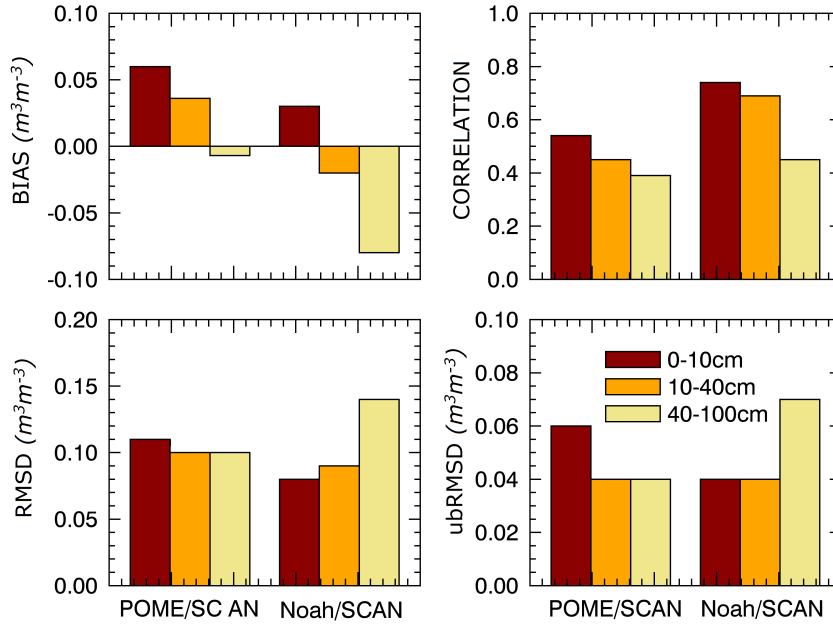
Fig. 6. POME and Noah SM profiles statistics at all SCAN sites compared against *in-situ* observations averaged across layer depths
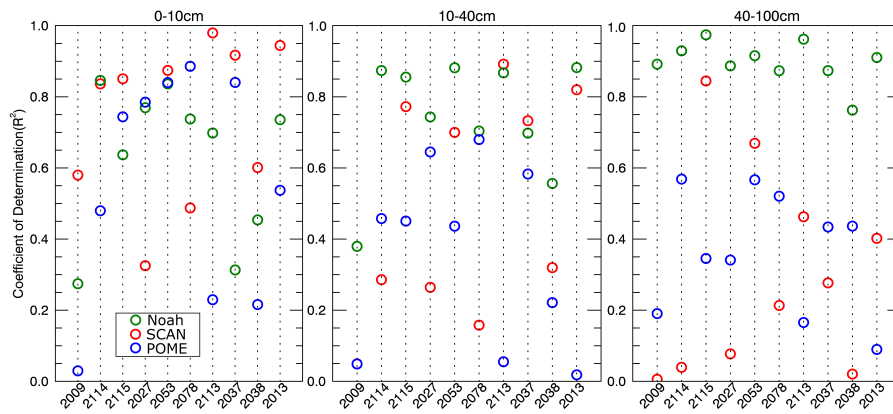

Fig. 7. Triple collocation analyses of SM profiles from Noah (green), POME (blue) and *in-situ* observations (red) at scan site locations at the depths of 0-10; 10-40 and 40-100 cm
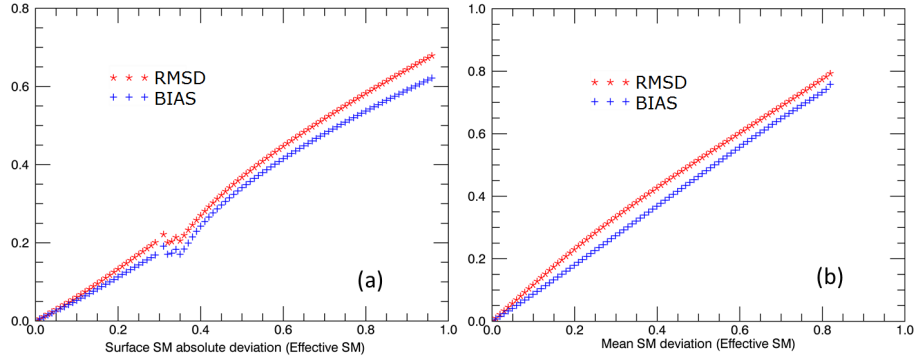
Fig. 8. POME model sensitivity to (a) boundary condition; (b) sensitivity to profile mean input towards profile Bias and ~~RMSE~~ RMSD in terms of effective SM.
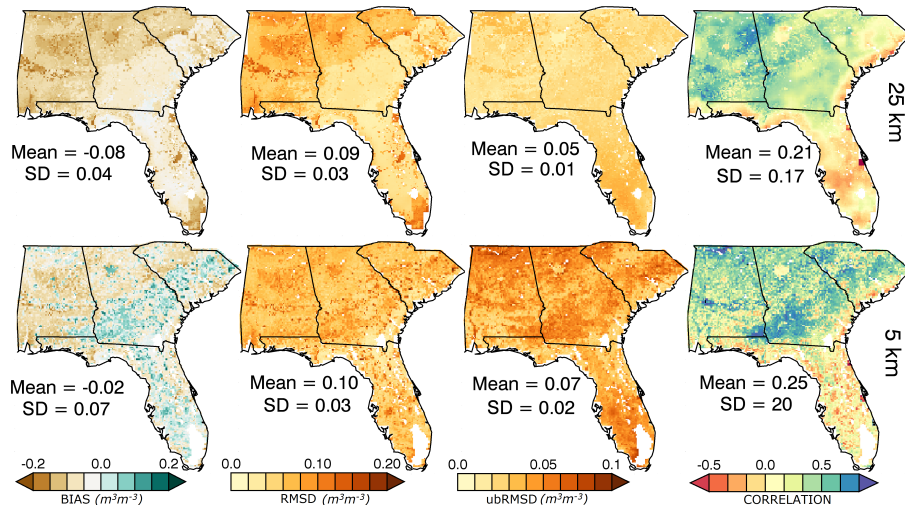
Fig. 9. Map of Southeast United States demonstrating temporal statics in bias, ~~RMSE~~RMSD, ~~ubRMSE~~ ubRMSD and correlation between coarse (top panel) and fine (bottom panel) resolution AMSR-E (MW) and Noah LSM surface SM (2006-2010)
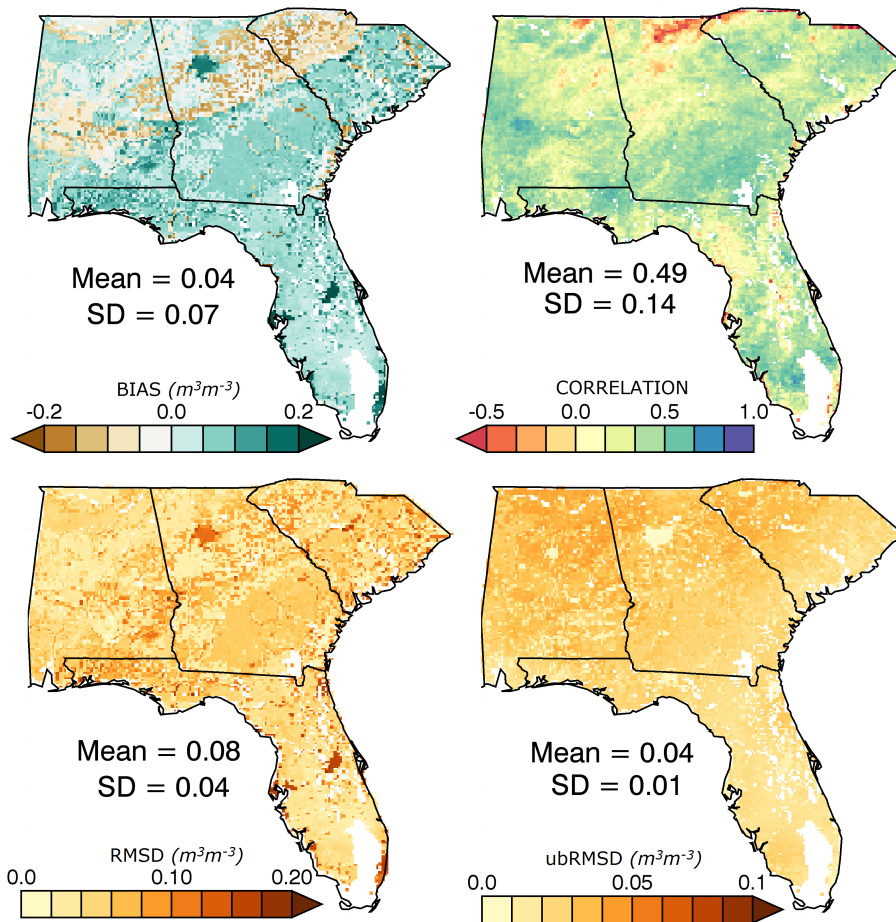
Fig. 10. Map of temporal statistics between root zone ALEXI and Noah SM (2006-2010).