

## Response to Editor Comments

Authors' responses inserted as blue text.

As I know both reviewers personally well and consider them as very much competent to judge your work, I decided to thoroughly and carefully review your manuscript to make up my mind in an as much as possible independent manner. As your manuscript is technically demanding, this took a little while. After this effort I am fully convinced that your work is very valuable for the field of hydrology, and yet I think needs moderate revisions before it can be accepted.

Response: Thank you very much for your thoughtful handling of this manuscript and for the additional efforts and time that you invested in as an additional reviewer.

Within this process I encourage you to address the recommendations of Reviewer 2 as outlined in your response.

Response: Thanks. We have thoroughly revised the manuscript based on our prior response to Reviewer 2.

While Reviewer 1 did, although she/he recommended major revisions, did not come up with a single major point that can be addressed, I leave it to you whether you consult a selection of the literature sources he/she provided or not.

Response: We have chosen not to modify the paper after Reviewer 1's comments. As we expressed in our prior responses to Review 1, we believe this is a useful contribution to the HESS community. We are very pleased to learn that both Reviewer 2 and the Editor have seen the merits of the manuscript.

Finally, although I am not an expert in time series analysis, I wonder about the following points:

1. In spatial statistics/geostatistics it is quite common to estimate the spatial covariance in a data set which is irregularly sampled in space by means of the semi-variogram. This implies to pool data into irregularly spaced lag classes and to fit the best suited theoretical variogram function, which of course might be also a power law. It is also standard to fill gaps between the sampling locations by interpolations methods that preserve the covariance structure for instance by means of ordinary kriging or external drift kriging, which may account for a drift in the expectation values (see next comment). I wonder whether the same procedure is not applicable to irregularly sampled time series, both to estimate the autocorrelation function and to fill gaps in a manner that preserves the autocorrelation?

Response: Great comment. While we think it is beyond the scope of our current manuscript, we agree that in future efforts it is useful to develop approaches to estimate autocorrelation (in the time domain) and then use that to fill the gaps in monitoring records. This kind of research can really improve our capability to build statistical models for estimating constituent concentrations and loads for days without samples. Unfortunately, this has been only well understood for simple autocorrelation models such as the autoregressive lag-1 model (AR[1]), which is a short-term

memory model. But as we discuss in Section 1.1, water quality data generally exhibit long-term memory. Therefore, it remains a real challenge and also a critical need to “fill gaps in manner that preserves the autocorrelation” for long-memory time series.

Moreover, we want to add that since the auto-covariance is the Fourier transform of the spectrum, estimating the autocorrelation to infill the data before estimating the spectrum is really an example of 'begging the question' (in the original meaning of that idiom) in the sense of assuming a result in order to justify the conclusion.

2. The term water quality data seem a little imprecise. Do you refer to concentrations of solutes in stream flow (C) or to total loads (Q\*C) in stream flow. Only the latter reflects mass conservation, and concentration data might exhibit quite a bit of pseudo-dynamics and pseudo seasonality due to simple dilution effects and seasonality in discharge (as you pointed out). In this context there is also quite a bit of discussion in the geostatistical literature whether data sets which include an external drift (a deterministic dependence of their mean on an external variable such as air temperature and or rainfall and topographic elevation) or in your case a flow dependence of concentration shall be detrended before estimating the covariance or not. I personally think it is necessary to remove a drive to avoid mixing of deterministic and stochastic variability – and there is evidence that a variogram analysis without the removal of a trend leads to a positive bias in the range and the sill of the variogram (e.g. Zimmermann et al. 2008).

Response: Thank you for this note on “external drift.” We agree and that is why we discussed the complexities in concentration data with respect to trend, discharge, and season effects in the Introduction (see lines 139-153 in Section 1.3) and why we applied the WRTDS method to the real concentration data to remove such effects prior to the fractal scaling estimation (see Section 3.3).

3. The definition of delta t average seems inconsistent with example 2 in line 199.

Response: We double checked the definition and found the example consistent with its definition. For example 2, delta t average =  $(2+1+4+3)/4 = 2.5$  hr, which also equals to  $L/(N-1) = 10/(5-1) = 2.5$  hr.

4. Please flip the numbering of figure 1 and 2.

Response: Please note that Figure 1 appears first – below equation (8) in Section 1.2, so it is not needed to flip the two figures.

## Response to Anonymous Referee #2

Authors' responses inserted as blue text.

I find the manuscript is well-written and technically rigorous, with results that can be generalized beyond hydrologic time series. This manuscript tackles a challenging and highly relevant topic - the quantification of fractal scaling behavior for irregularly sampled data - and provides needed synthesis on the most promising methods to estimate this behavior. For these reasons, I recommend the manuscript be accepted subject to minor revisions.

Response: Thank you for these comments.

I do, however, have a number of comments that would help improve clarity of the manuscript and emphasize the more practical aspects of this work.

### Major comments:

1) Lines 127-129: It would be interesting to the reader and for understanding the important contribution of this work to detail the effects of non-normal data and persistence, seasonality, and the presence of long-term trends on the estimation of Beta.

Response: We agree this would be potentially useful to do, but it is simply beyond the scope of the paper -- new modeling experiments for each of these effects would multiply the length and complexity of the paper by large factors. We recognize this would be an important area for future research, which we explicitly put in the Section 3.3 (lines 459-464): *“such real data are typically much more complex than our simulated time series, because of (1) strong deviations from normal distributions and (2) effects of flow-dependence, seasonality, and temporal trend (Hirsch et al., 1991; Helsel and Hirsch, 2002). In this regard, future research may simulate time series with these important characteristics and evaluate the performance of various estimation approaches, perhaps following the modeling framework described herein.”*

2) Lines 264-265: It is noted that the results which demonstrate that the approach used in this manuscript to mimic the sampling irregularity performs well as compared to other simulation methods are not shown. I think these results are important to show, as this approach is what underlies the remainder of the analysis of the methods. This can be added to the supplementary material.

Response: Thank you for this suggestion. We now provide these simulation results in the supplementary material, see *Section S1*.

3) There are a large number of interpolation methods (n=11) presented here. I would argue that some of these methods are not very realistic in the context of what one would experience in terms interpolation for irregular samples. Unless the authors provide sound technical justification for each scenario, I would consider removing scenarios that would not generally be considered in standard

practices (examples are scenarios B3, B4, and select a smaller subset of LOESS smoothing parameter values). This would also streamline the results and text.

Response: The interpolation methods were selected not only on the basis of their frequency of use, but to ensure a certain degree of completeness -- we felt it would ultimately be more useful to include obvious variations of common methods than to exclude one that someone might have been considering and looked to our paper for guidance. Although methods B3-B5 seem not plausible, they have been discussed and used in the scientific literature (e.g., Blankers et al. 2010; Graham 2009). Furthermore, some R packages have been developed (e.g., “na.locf”), making these methods readily available to general users without any prior knowledge on the methods’ performance. Therefore, we think it is worthwhile to keep the results and discussion of these methods’ performance, which is a useful contribution to the topic of “missing data analysis.” Furthermore, removing one or two methods would do little to shorten or simplify the paper at this stage, so we have chosen not to so.

4) Line 412: For Monte Carlo analysis, average values of the simulated parameter of interest are computed from sample sizes of 100 or more - not 30. Was this tested in your experiments?

Response: We used 30 samples because it was quite sufficient to constrain estimates of the average in most cases. Standard error of the mean beta for most methods is much smaller than the variation between methods. Nonetheless, to follow common practice, we have adopted this suggestions to run the simulation 100 times and we have revised all relevant figures and text accordingly (including Figures 5-9 and Figures S3-S12).

Minor clarification comments:

1) Lines 3-4: Consider adding a phrase or sentence to explain why spectral slope is important to trend detection.

Response: We agree and have added the phrase “to avoid false inference on the statistical significance of trends” at the end of this sentence.

2) Line 15: Is the “modified form” being newly introduced here? Or does it already exist. Clarify.

Response: It is a published method, see method C1b in Section 3.1 where it is introduced. For clarity, we have revised “a modified form” to “a previously-published modified form.”

3) line 38-39: The fact that ACF is summable seems a non-sequitor here. It is later that the connection is made to summability and the presence of fractal behavior. Perhaps it is not necessary to comment on the summability of the ACF?

Response: Agreed. We have deleted the comment on “summability”.

4) lines 90-103: Moving this paragraph to the end of Section 1.1 would provide more immediate clarity as to the scope and value of this work.

Response: Thanks. This paragraph has been moved to the suggested location, i.e., Section 1.1.

5) Line 158: Consider the of the work “interpolating” instead of “modeling”

Response: We have decided to keep the use of “modeling.”

6) Section 2.1: Highly clever way to define sampling irregularity.

Response: Thank you.

7) line 216 (and throughout): I do not think “gappy” is a word and chuckled at its appearance. Please replace with “irregularly-spaced”.

Response: Thank you. We have replaced the word “gappy” with “irregularly-spaced” throughout the manuscript.

8) line 237: Please be more specific in how you arrived at this equation for the shape parameter.

Response: As the line states,  $\lambda = \mu^2/[\text{var}(\Delta t^*) - \mu] = (\text{mean}(\Delta t^*) - 1)^2/[\text{var}(\Delta t^*) - \text{mean}(\Delta t^*) + 1]$ . The first equality represents a well-established property for the negative binomial distribution. The second equality is achieved through the substitution of  $\mu$  by “ $\text{mean}(\Delta t^*) - 1$ ”. We think it is already clear and hence further modification is not necessary.

9) line 247 (as an example): Please add units to values provided in this section and throughout. This will help the reader follow the results and methods.

Response: Units are provided for  $\Delta t_{\text{average}}$  (days). Note that  $\lambda$  and  $\mu$  are fitted (negative binomial distribution) parameters for the *non-dimensionalized* time series ( $\Delta t^*$ ) -- see Section 2.1 -- therefore these two variables do not have units.

10) line 473: Hirsch and DeCicco (2015) is the reference to the user manual for WRTDS. The method itself is explained in Hirsch et al. (2010). I would cite the original paper.

Hirsch, R. M., Moyer, D. L. and Archfield, S. A. (2010), Weighted Regressions on Time, Discharge, and Season (WRTDS), with an Application to Chesapeake Bay River Inputs. JAWRA Journal of the American Water Resources Association, 46: 857–880. doi: 10.1111/j.1752-1688.2010.00482.x

Response: Thanks. We have corrected this citation to Hirsch et al. (2010).

### References Cited

Blankers, M., Koeter, M. W., & Schippers, G. M. (2010). Missing data approaches in eHealth research: simulation study and a tutorial for nonmathematically inclined researchers. Journal of medical Internet research, 12(5).

Graham, J. W. (2009). Missing data analysis: Making it work in the real world. Annual review of psychology, 60, 549-576.

## Response to Anonymous Referee #1

Authors' responses inserted as blue text.

The study performs a comparative evaluation of statistical methods available in the literature using as benchmark test the quantification of fractal scaling in water quality time series with irregular sampling. While lacking technical novelty, the manuscript is written in a sober, careful manner, aptly guiding the reader throughout the key arguments, methodologies and procedures, and presenting the results in a clear and concise manner.

Response: While we thank the reader for the comments about the clarity of our presentation, and for the helpful comments the reviewer has made, we disagree with the comment about the lack of technical novelty, which is repeated elsewhere below. We respond to it there.

This being said, I raise four fundamental concerns:

1) The paper is a pure statistical exercise. It would thus benefit from a physical interpretation of the methodological structure and results: namely, discussing possible physical mechanisms responsible for the statistical signatures detected in the analysis, along with their physical consistency. For instance, whether a trend is physically sustainable and realistic in terms of system energetics, what physical mechanisms sustain the power laws detected in the data, and what physically entails the fractal behaviour. Fractals and scaling are well understood in the physical sciences but the HESS readers will be happy to learn this in the hydrological context. In doing so, the authors will be able to strengthen their arguments and diffuse concerns about whether there is any realism underlying the signatures detected in the analysis.

Response: While we appreciate the value of a physical interpretation, we will not alter the manuscript in response to this comment for the following reasons:

- I. We disagree that this is a 'statistical exercise' (which we take to imply that it provides no actual illumination). As its title reflects, the manuscript focuses on the comparison of various statistical methods for quantifying fractal scaling. These methods are actually used in the literature, and we believe that it is of value to know if they actually work or not.
- II. Sections 1.1 and 1.2 in the Introduction provide background information with some reference to the physical origins, and providing many citations to literature that provides the insights the reviewer is looking for. In fact, significant sections of the foundational literature on fractals and scaling were developed within the hydrology community and later picked up more widely (the Hurst exponent is an example).
- III. The physical interpretations of fractal time series are many and varied, depending on the context. Those interpretations are already available in the literature, and our purpose is neither to add to them, nor to review them. Instead our purpose is to conduct benchmark tests to determine whether some widely used techniques for inferring fractal scaling are reliable or not.

2) Monte Carlo simulations can be structured and tuned for essentially any purpose and to yield any outcome, relying on wise choices made in the methodological setup and the generating system, based on the researchers' understanding or conception of its behaviour. If the methodological setup is entirely data-based, i.e. learn from some statistic or machine learning procedure derived from dataset records, there will always be a degree of case-specific empiricism that is not straightforwardly generalisable, unless there is a fundamental principle beneath. This again links to concern 1. Therefore, it is important to thoroughly provide a solid background to all the assumptions supporting the choices made in the methodological setup and operation.

**Response:** We believe we have provided sufficient reasoning for the assumptions adopted, but welcome comments on any specific area that is unclear or has been omitted.

3) The paper does not introduce any methodological novelty. In fact, there is a vast literature on statistics of irregularly sampled series (also known as unevenly spaced time series). Therefore, I strongly encourage the authors to look into the literature outside of hydrology, e.g. in astrophysics, neurosciences, paleoclimatology, where they will find a rich diversity of sophisticated and long-proven methods that already tackle the same problems. In doing so, the authors will necessarily tone down the false claims about novelty in new methods and frameworks, when in reality the only novelty is the application of existing methods to hydrological case studies. The key merit of the paper is essentially the comparative evaluation of well known statistical methods and their application to the hydrological sciences, namely relevant water quality issues. As such, this is a purely applied paper and should be clearly presented as such. This brings me to the fourth concern.

**Response:** We agree with the reviewer's comment that "the paper is essentially the comparative evaluation of well known statistical methods and their application to the hydrological sciences, namely relevant water quality issues." This is precisely stated in Section 1.3 where we define the scope of the work -- see the 2nd last paragraph in that section. But we stress that we never claimed that our work is about developing "new methods". Rather, it is stated clearly in several locations of the paper that this work is about the evaluation of existing statistical methods.

In addition, we disagree with the reviewer on the point that there are "a rich diversity of sophisticated and long-proven methods that already tackle the same problems". Many existing methods do not apply to irregularly sampled data and hence can not be used. Others have been widely used, but have not been rigorously tested. The Lomb-Scargle spectral method is well established, but has known weaknesses (as discussed in the paper and elsewhere, see Montanari et al. 1999). If the reviewer is aware of other works that solve the problem addressed by our work, we again encourage the reviewer to provide citations.

Regarding the novelty (or contribution) of this work, we are not aware of any other papers that perform a similar comparative analysis of these methods, let alone one that is tailored to the needs of the hydrology and earth science community. The reviewer provides no evidence or citations to back up the claim that our study is not novel. If the reviewer is aware of any other such studies we

would encourage the reviewer to provide them. One of us has been working on this problem for over 20 years, and in that time has seen no published work that is similar to ours.

Studies that review, compare and critically evaluate available methods are valuable contributions to the scientific literature. They are, in our opinion, useful checks on a proliferation of divergent methods that threatens to generate (at best) incomparable and (at worst) inaccurate observations of physical phenomena.

Our contribution in this regard is explicitly summarized in the last paragraph of the paper, which is copied below: *“Overall, these results provide new contributions in terms of better understanding and quantification of the proposed methods’ performances for estimating the strength of fractal scaling in irregularly sampled water-quality data. In addition, the work has provided an innovative and general approach for modeling sampling irregularity in water-quality records. Moreover, this work has proposed and demonstrated a generalizable framework for data simulation (with gaps) and  $\beta$  estimation, which can be readily applied toward the evaluation of other methods that are not covered in this work. More generally, the findings and approaches may also be broadly applicable to irregularly sampled data in other scientific disciplines. Last but not least, we note that accurate quantification of fractal scaling in irregular water-quality time series remains an unresolved challenge for the hydrologic community and for many other disciplines that must grapple with irregular sampling.”*

4) There are no novel hydrological insights in the paper. While the statistical messages are useful (albeit not technically novel), it would be essential to bring out a substantial advance in the understanding of the hydrological and earth systems. After all, HESS is not merely a journal of applied statistics but rather one in which there should be something to be learnt in the functioning of the hydrological system.

Response: We disagree with the reviewer that this work does not provide contributions to HESS in terms of understanding of the hydrological and earth systems. As noted in Section 1.3 “Motivations and Objectives of this Work,” the quantification of fractal scaling has important implications for detecting trends in water quality time series, but there is a large gap with respect to what methods are appropriate (or applicable) for quantifying fractal scaling in irregularly sampled water quality time series. By dealing with this issue, this work is highly relevant to the hydrological community.

#### References Cited

Montanari, A., M. S. Taqqu and V. Teverovsky, 1999. Estimating long-range dependence in the presence of periodicity: An empirical study. *Mathematical and Computer Modelling* 29:217-228, DOI: 10.1016/S0895-7177(99)00104-1.



# Evaluation of statistical methods for quantifying fractal scaling in water quality time series with irregular sampling

Qian Zhang<sup>1</sup>, Ciaran J. Harman<sup>2</sup>, James W. Kirchner<sup>3,4,5</sup>

<sup>1</sup> University of Maryland Center for Environmental Science at the US Environmental Protection Agency Chesapeake Bay Program Office, 410 Severn Avenue, Suite 112, Annapolis, MD 21403 (formerly, Department of Geography and Environmental Engineering, Johns Hopkins University, 3400 North Charles Street, Baltimore, Maryland 21218)

<sup>2</sup> Department of Environmental Health and Engineering, Johns Hopkins University, 3400 North Charles Street, Baltimore, Maryland 21218

<sup>3</sup> Department of Environmental System Sciences, ETH Zurich, Universitätsstrasse 16, CH-8092 Zurich, Switzerland

<sup>4</sup> Swiss Federal Research Institute WSL, Zürcherstrasse 111, CH-8903 Birmensdorf, Switzerland

<sup>5</sup> Department of Earth and Planetary Science, University of California, Berkeley, California 94720

Correspondence to: Qian Zhang ([qzhang@chesapeakebay.net](mailto:qzhang@chesapeakebay.net))

1 **Abstract.** River water-quality time series often exhibit fractal scaling, which here refers to  
2 autocorrelation that decays as a power law over some range of scales. Fractal scaling presents  
3 challenges to the identification of deterministic trends to avoid false inference on the statistical  
4 significance of trends, but traditional methods for estimating spectral slope ( $\beta$ ) or other  
5 equivalent scaling parameters (*e.g.*, Hurst exponent) are generally inapplicable to irregularly  
6 sampled data. Here we consider two types of estimation approaches for irregularly sampled data  
7 and evaluate their performance using synthetic time series. These time series were generated  
8 such that (1) they exhibit a wide range of prescribed fractal scaling behaviors, ranging from  
9 white noise ( $\beta = 0$ ) to Brown noise ( $\beta = 2$ ), and (2) their sampling gap intervals mimic the  
10 sampling irregularity (as quantified by both the skewness and mean of gap-interval lengths) in  
11 real water-quality data. The results suggest that none of the existing methods fully account for  
12 the effects of sampling irregularity on  $\beta$  estimation. First, the results illustrate the danger of using  
13 interpolation for gap filling when examining auto-correlation, as the interpolation methods  
14 consistently under-estimate or over-estimate  $\beta$  under a wide range of prescribed  $\beta$  values and gap  
15 distributions. Second, the long-established Lomb-Scargle spectral method also consistently

16 under-estimates  $\beta$ . A [previously-published](#) modified form, using only the lowest 5% of the  
17 frequencies for spectral slope estimation, has very poor precision, although the overall bias is  
18 small. Third, a recent wavelet-based method, coupled with an aliasing filter, generally has the  
19 smallest bias and root-mean-squared error among all methods for a wide range of prescribed  $\beta$   
20 values and gap distributions. The aliasing method, however, does not itself account for sampling  
21 irregularity, and this introduces some bias in the result. Nonetheless, the wavelet method is  
22 recommended for estimating  $\beta$  in irregular time series until improved methods are developed.  
23 Finally, all methods' performances depend strongly on the sampling irregularity, highlighting  
24 that the accuracy and precision of each method are data-specific. Accurately quantifying the  
25 strength of fractal scaling in irregular water-quality time series remains an unresolved challenge  
26 for the hydrologic community and for other disciplines that must grapple with irregular sampling.

## 27 **Key Words**

28 Fractal scaling, autocorrelation, Hurst effect, river water-quality sampling, sampling irregularity,  
29 trend analysis

## 30 **1. Introduction**

### 31 *1.1. Autocorrelations in Time Series*

32 It is well known that time series from natural systems often exhibit auto-correlation, that is,  
33 observations at each time step are correlated with observations one or more time steps in the past.  
34 This property is usually characterized by the autocorrelation function (ACF), which is defined as  
35 follows for a process  $X_t$  at lag  $k$ :

$$\gamma(k) = cov(X_t, X_{t+k}) \quad (1)$$

36 In practice, auto-correlation has been frequently modeled with classical techniques such as auto-  
37 regressive (AR) or auto-regressive moving-average (ARMA) models (Darken *et al.*, 2002; Yue  
38 *et al.*, 2002; Box *et al.*, 2008). These models assume that the underlying process has short-term  
39 memory, *i.e.*, the ACF decays exponentially with lag  $k$ , [which implies that the ACF is summable](#)  
40 (Box *et al.*, 2008).

41 Although the short-term memory assumption holds sometimes, it cannot adequately describe  
42 many time series whose ACFs decay as a power law (thus much slower than exponentially) and

43 may not reach zero even for large lags, which implies that the ACF is non-summable. This  
44 property is commonly referred to as long-term memory or fractal scaling, as opposed to short-  
45 term memory (Beran, 2010).

46 Fractal scaling has been increasingly recognized in studies of hydrological time series,  
47 particularly for the common task of trend identification. Such hydrological series include  
48 riverflow (Montanari *et al.*, 2000; Khaliq *et al.*, 2008; Khaliq *et al.*, 2009; Ehsanzadeh and  
49 Adamowski, 2010), air and sea temperature (Faticchi *et al.*, 2009; Lennartz and Bunde, 2009;  
50 Franzke, 2012b; Franzke, 2012a), conservative tracers (Kirchner *et al.*, 2000; Kirchner *et al.*,  
51 2001; Godsey *et al.*, 2010), and non-conservative chemical constituents (Kirchner and Neal,  
52 2013; Aubert *et al.*, 2014). Because for fractal scaling processes the variance of the sample mean  
53 converges to zero much slower than the rate of  $n^{-1}$  ( $n$ : sample size), the fractal scaling property  
54 must be taken into account to avoid "false positives" (Type I errors) when inferring the statistical  
55 significance of trends (Cohn and Lins, 2005; Faticchi *et al.*, 2009; Ehsanzadeh and Adamowski,  
56 2010; Franzke, 2012a). Unfortunately, as stressed by Cohn and Lins (2005), it is "surprising that  
57 nearly every assessment of trend significance in geophysical variables published during the past  
58 few decades has failed [to do so]", and a similar tendency is evident in the decade following that  
59 statement as well.

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## 60 **1.2. Overview of Approaches for Quantification of Fractal Scaling**

61 Several equivalent metrics can be used to quantify fractal scaling. Here we provide a review  
62 of the definitions of such processes and several typical modeling approaches, including both  
63 time-domain and frequency-domain techniques, with special attention to their reconciliation. For  
64 a more comprehensive review, readers are referred to Beran *et al.* (2013), Boutahar *et al.* (2007),  
65 and Witt and Malamud (2013).

66 Strictly speaking,  $X_t$  is called a stationary long-memory process if the condition

$$\lim_{k \rightarrow \infty} k^\alpha \gamma(k) = C_1 > 0 \quad (2)$$

67 where  $C_1$  is a constant, is satisfied by some  $\alpha \in (0,1)$  (Boutahar *et al.*, 2007; Beran *et al.*, 2013).

68 Equivalently,  $X_t$  is a long-memory process if, in the spectral domain, the condition

$$\lim_{\omega \rightarrow 0} |\omega|^\beta f(\omega) = C_2 > 0 \quad (3)$$

69 is satisfied by some  $\beta \in (0,1)$ , where  $C_2$  is a constant and  $f(\omega)$  is the spectral density function  
70 of  $X_t$ , which is related to ACF as follows (which is also known as the Wiener-Khinchin theorem):

$$f(\omega) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \gamma(k) e^{-ik\omega} \quad (4)$$

71 where  $\omega$  is angular frequency (Boutahar *et al.*, 2007).

72 One popular model for describing long-memory processes is the so-called fractional auto-  
 73 regressive integrated moving-average model, or ARFIMA ( $p, q, d$ ), which is an extension of  
 74 ARMA models and is defined as follows:

$$(1 - B)^d \varphi(B) X_t = \psi(B) \varepsilon_t \quad (5)$$

75 where  $\varepsilon_t$  is a series of independent, identically distributed Gaussian random numbers  $\sim (0, \sigma_\varepsilon^2)$ ,  
 76  $B$  is the backshift operator (*i.e.*,  $BX_t = X_{t-1}$ ), and functions  $\varphi(\cdot)$  and  $\psi(\cdot)$  are polynomials of order  
 77  $p$  and  $q$ , respectively. The fractional differencing parameter  $d$  is related to the parameter  $\alpha$  in Eq.  
 78 (2) as follows:

$$d = \frac{1 - \alpha}{2} \in (-0.5, 0.5) \quad (6)$$

79 (Beran *et al.*, 2013; Witt and Malamud, 2013).

80 In addition to a slowly decaying ACF, a long-memory process manifests itself in two other  
 81 equivalent fashions. One is the so-called ‘‘Hurst effect’’, which states that, on a log-log scale, the  
 82 range of variability of a process changes linearly with the length of time period under  
 83 consideration. This power-law slope is often referred to as the ‘‘Hurst exponent’’ or ‘‘Hurst  
 84 coefficient’’  $H$  (Hurst, 1951), which is related to  $d$  as follows:

$$H = d + 0.5 \quad (7)$$

85 (Beran *et al.*, 2013; Witt and Malamud, 2013). The second equivalent description of long-  
 86 memory processes, this time from a frequency-domain perspective, is ‘‘fractal scaling’’, which  
 87 describes a power-law decrease in spectral power with increasing frequency, yielding power  
 88 spectra that are linear on log-log axes (Lomb, 1976; Scargle, 1982; Kirchner, 2005).

89 Mathematically, this inverse proportionality can be expressed as:

$$f(\omega) = C_3 |\omega|^{-\beta} \quad (8)$$

90 where  $C_3$  is a constant and the scaling exponent  $\beta$  is termed the ‘‘spectral slope.’’ In particular, for  
 91 spectral slopes of zero, one, and two, the underlying processes are termed as ‘‘white’’, ‘‘pink’’ (or  
 92 ‘‘flicker’’), and ‘‘Brown’’ (or ‘‘red’’) noises, respectively (Witt and Malamud, 2013). Illustrative  
 93 examples of these three noises are shown in **Figure 1a-1c**.

94 In addition, it can be shown that the spectral density function for ARFIMA ( $p, d, q$ ) is

$$f(\omega) = \frac{\sigma_\varepsilon^2 |\psi(e^{-i\omega})|^2}{2\pi |\varphi(e^{-i\omega})|^2} |1 - e^{-i\omega}|^{-2d} \quad (9)$$

95 for  $-\pi < \omega < \pi$  (Boutahar *et al.*, 2007; Beran *et al.*, 2013). For  $|\omega| \ll 1$ , Eq. (9) can be  
 96 approximated by:

$$f(\omega) = C_4 |\omega|^{-2d} \quad (10)$$

97 with

$$C_4 = \frac{\sigma_\varepsilon^2 |\psi(1)|^2}{2\pi |\varphi(1)|^2} \quad (11)$$

98 Eq. (10) thus exhibits the asymptotic behavior required for a long-memory process given by Eq.  
 99 (3). In addition, a comparison of Eq. (10) and (8) reveals that,

$$\beta = 2d \quad (12)$$

100 Overall, these derivations indicate that these different types of scaling parameters (*i.e.*,  $\alpha$ ,  $d$ , and  
 101  $H$  and  $\beta$ ) can be used equivalently to describe the strength of fractal scaling. Specifically, their  
 102 equivalency can be summarized as follows:

$$\beta = 2d = 1 - \alpha = 2H - 1 \quad (13)$$

103 It should be noted, however, that the parameters  $d$ ,  $\alpha$ , and  $H$  are only applicable over a fixed  
 104 range of fractal scaling, which is equivalent to  $(-1, 1)$  in terms of  $\beta$ .

105 ~~Fractal scaling has been increasingly recognized in studies of hydrological time series,  
 106 particularly for the common task of trend identification. Such hydrological series include  
 107 riverflow (Montanari *et al.*, 2000; Khaliq *et al.*, 2008; Khaliq *et al.*, 2009; Ehsanzadeh and  
 108 Adamowski, 2010), air and sea temperature (Fatihi *et al.*, 2009; Lennartz and Bunde, 2009;  
 109 Franzke, 2012b; Franzke, 2012a), conservative tracers (Kirchner *et al.*, 2000; Kirchner *et al.*,  
 110 2001; Godsey *et al.*, 2010), and non conservative chemical constituents (Kirchner and Neal,  
 111 2013; Aubert *et al.*, 2014). Because for fractal scaling processes the variance of the sample mean  
 112 converges to zero much slower than the rate of  $n^{-1}$  ( $n$ : sample size), the fractal scaling property  
 113 must be taken into account to avoid "false positives" (Type I errors) when inferring the statistical  
 114 significance of trends (Cohn and Lins, 2005; Fatihi *et al.*, 2009; Ehsanzadeh and Adamowski,  
 115 2010; Franzke, 2012a). Unfortunately, as stressed by Cohn and Lins (2005), it is "surprising that  
 116 nearly every assessment of trend significance in geophysical variables published during the past  
 117 few decades has failed [to do so]", and a similar tendency is evident in the decade following that  
 118 statement as well.~~

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119 **1.3. Motivation and Objective of this Work**

120 To account for fractal scaling in trend analysis, one must be able to first quantify the strength  
121 of fractal scaling for a given time series. Numerous estimation methods have been developed for  
122 this purpose, including Hurst rescaled range analysis, Higuchi's method, Geweke and Porter-  
123 Hudak's method, Whittle's maximum likelihood estimator, detrended fluctuation analysis, and  
124 others (Taqqu *et al.*, 1995; Montanari *et al.*, 1997; Montanari *et al.*, 1999; Rea *et al.*, 2009;  
125 Stroe-Kunold *et al.*, 2009). For brevity, these methods are not elaborated here; readers are  
126 referred to Beran (2010) and Witt and Malamud (2013) for details. While these estimation  
127 methods have been extensively adopted, they are unfortunately only applicable to regular (*i.e.*,  
128 evenly spaced) data, *e.g.*, daily streamflow discharge, monthly temperature, *etc.* In practice,  
129 many types of hydrological data, including river water-quality data, are often sampled irregularly  
130 or have missing values, and hence their strengths of fractal scaling cannot be readily estimated  
131 with the above traditional estimation methods.

132 Thus, estimation of fractal scaling in irregularly sampled data is an important challenge for  
133 hydrologists and practitioners. Many data analysts may be tempted to interpolate the time series  
134 to make it regular and hence analyzable (Graham, 2009). Although technically convenient,  
135 interpolation can be problematic if it distorts the series' autocorrelation structure (Kirchner and  
136 Weil, 1998). In this regard, it is important to evaluate various types of interpolation methods  
137 using carefully designed benchmark tests and to identify the scenarios under which the  
138 interpolated data can yield reliable (or, alternatively, biased) estimates of spectral slope.

139 Moreover, quantification of fractal scaling in real-world water-quality data is subject to  
140 several common complexities. First, water-quality data are rarely normally distributed; instead,  
141 they are typically characterized by log-normal or other skewed distributions (Hirsch *et al.*, 1991;  
142 Helsel and Hirsch, 2002), with potential consequences for  $\beta$  estimation. Moreover, water-quality  
143 data also tend to exhibit long-term trends, seasonality, and flow-dependence (Hirsch *et al.*, 1991;  
144 Helsel and Hirsch, 2002), which can also affect the accuracy of  $\beta$  estimate. Thus, it may be more  
145 plausible to quantify  $\beta$  in transformed time series after accounting for the seasonal patterns and  
146 discharge-driven variations in the original time series, which is also the approach taken in this  
147 work. For the trend aspect, however, it remains a puzzle whether the data set should be de-  
148 trended before conducting  $\beta$  estimation. Such de-trending treatment can certainly affect the  
149 estimated value of  $\beta$  and hence the validity of (or confidence in) any inference made regarding

150 the statistical significance of temporal trends in the time series. This somewhat circular issue is  
151 beyond the scope of our current work -- it has been previously discussed in the context of short-  
152 term memory (Zetterqvist, 1991; Darken *et al.*, 2002; Yue *et al.*, 2002; Noguchi *et al.*, 2011;  
153 Clarke, 2013; Sang *et al.*, 2014), but it is not well understood in the context of fractal scaling (or  
154 long-term memory) and hence presents an important area for future research.

155 In the above context, the main objective of this work was to use Monte Carlo simulation to  
156 systematically evaluate and compare two broad types of approaches for estimating the strength  
157 of fractal scaling (*i.e.*, spectral slope  $\beta$ ) in irregularly sampled river water-quality time series.  
158 Specific aims of this work include the following:

- 159 (1) To examine the sampling irregularity of typical river water-quality monitoring data and  
160 to simulate time series that contain such irregularity; and
- 161 (2) To evaluate two broad types of approaches for estimating  $\beta$  in simulated irregularly  
162 sampled time series.

163 The first type of approach includes several forms of interpolation techniques for gap filling, thus  
164 making the data regular and analyzable by traditional estimation methods. The second type of  
165 approach includes the well-known Lomb-Scargle periodogram (Lomb, 1976; Scargle, 1982) and  
166 a recently developed wavelet method combined with a spectral aliasing filter (Kirchner and Neal,  
167 2013). The latter two methods can be directly applied to irregularly spaced data; here we aim to  
168 compare them with the interpolation techniques. Details of these various approaches are  
169 provided in **Section 3.1**.

170 This work was designed to make several specific contributions. First, it uses benchmark tests  
171 to quantify the performance of a wide range of methods for estimating fractal scaling in  
172 irregularly sampled water-quality data. Second, it proposes an innovative and general approach  
173 for modeling sampling irregularity in water-quality records. Third, while this work was not  
174 intended to compare all published estimation methods for fractal scaling, it does provide and  
175 demonstrate a generalizable framework for data simulation (with gaps) and  $\beta$  estimation, which  
176 can be readily applied toward the evaluation of other methods that are not covered here. Last but  
177 not least, while this work was intended to help hydrologists and practitioners understand the  
178 performance of various approaches for water-quality time series, the findings and approaches  
179 may be broadly applicable to irregularly sampled data in many other scientific disciplines.

180 The rest of the paper is organized as follows. We propose a general approach for modeling  
181 sampling irregularity in typical river water-quality data and discuss our approach for simulating  
182 irregularly sampled data (**Section 2**). We then introduce the various methods for estimating  
183 fractal scaling in irregular time series and compare their estimation performance (**Section 3**). We  
184 close with a discussion of the results and implications (**Section 4**).

## 185 **2. Quantification of Sampling Irregularity in River Water-Quality Data**

### 186 **2.1. Modeling of Sampling Irregularity**

187 River water-quality data are often sampled irregularly. In some cases, samples are taken  
188 more frequently during particular periods of interest, such as high flows or drought periods; here  
189 we will address the implications of the irregularity, but not the (intentional) bias, inherent in such  
190 a sampling strategy. In other cases, the sampling is planned with a fixed sampling interval (*e.g.*,  
191 1 day) but samples are missed (or lost, or fail quality-control checks) at some time steps during  
192 implementation. In still other cases, the sampling is intrinsically irregular because, for example,  
193 one cannot measure the chemistry of rainfall on rainless days or the chemistry of a stream that  
194 has dried up. Theoretically, any deviation from fixed-interval sampling can affect the subsequent  
195 analysis of the time series.

196 To quantify the sampling irregularity, we propose a simple and general approach that can be  
197 applied to any time series of monitoring data. Specifically, for a given time series with  $N$  points,  
198 the time intervals between adjacent samples are calculated; these intervals themselves make up a  
199 time series of  $N-1$  points that we call  $\Delta t$ . In addition, the following parameters are calculated to  
200 quantify its sampling irregularity:

- 201 •  $L$  = the length of the period of record,
- 202 •  $N$  = the number of samples in the record,
- 203 •  $\Delta t_{nominal}$  = the nominal sampling interval under regular sampling (*e.g.*,  $\Delta t_{nominal} = 1$  day  
204 for daily samples),
- 205 •  $\Delta t^* = \Delta t / \Delta t_{nominal}$ , the sample intervals non-dimensionalized by the nominal sampling  
206 interval,
- 207 •  $\Delta t_{average} = L / (N - 1)$  the average of all the entries in  $\Delta t$ .

208 The quantification is illustrated with two simple examples. The first example contains data  
209 sampled every hour from 1:00 am to 11:00 am on one day. In this case,  $L = 10$  hours,  $N = 11$



210 samples,  $\Delta t = \{1, 1, 1, 1, 1, 1, 1, 1, 1, 1\}$  hour, and  $\Delta t_{nominal} = \Delta t_{average} = 1$  hour. The second  
 211 example contains data sampled at 1:00 am, 3:00 am, 4:00 am, 8:00 am, and 11:00 am. In this  
 212 case,  $L = 10$  hours,  $N = 5$  samples,  $\Delta t = \{2, 1, 4, 3\}$  hours,  $\Delta t_{nominal} = 1$  hour, and  $\Delta t_{average} = 2.5$   
 213 hours. It is readily evident that the first case corresponds to fixed-interval (regular) sampling that  
 214 has the property of  $\Delta t_{average}/\Delta t_{nominal} = 1$  (dimensionless), whereas the second case corresponds to  
 215 irregular sampling for which  $\Delta t_{average}/\Delta t_{nominal} > 1$ .

216 The dimensionless set  $\Delta t^*$  contains essential information for determining sampling  
 217 irregularity. This set is modeled as independent, identically distributed values drawn from a  
 218 negative binomial (NB) distribution. This distribution has two dimensionless parameters, the  
 219 shape parameter ( $\lambda$ ) and the mean parameter ( $\mu$ ), which collectively represent the irregularity of  
 220 the samples. The NB distribution is a flexible distribution that provides a discrete analogue of a  
 221 gamma distribution. The geometric distribution, itself the discrete analogue of the exponential  
 222 distribution, is a special case of the NB distribution when  $\lambda = 1$ .

223 The parameters  $\mu$  and  $\lambda$  represent different aspects of sampling irregularity, as illustrated by  
 224 the examples shown in **Figure 2**. The mean parameter  $\mu$  represents the fractional increase in the  
 225 average interval between samples due to gaps:  $\mu = \text{mean}(\Delta t^*) - 1 = (\Delta t_{average} - \Delta t_{nominal})/\Delta t_{nominal}$ .  
 226 Thus the special case of  $\mu = 0$  corresponds to regular sampling (*i.e.*,  $\Delta t_{average} = \Delta t_{nominal}$ ), whereas  
 227 any larger value of  $\mu$  corresponds to irregular sampling (*i.e.*,  $\Delta t_{average} > \Delta t_{nominal}$ ) (**Figure 2c**). The  
 228 shape parameter  $\lambda$  characterizes the similarity of gaps to each other; that is, a small  $\lambda$  indicates  
 229 that the samples contain gaps of widely varying lengths, whereas a large  $\lambda$  indicates that the  
 230 samples contain many gaps of similar lengths (**Figure 2a-2b**).

231 To visually illustrate these gap distributions, representative samples of **irregulargappy** time  
 232 series are presented in **Figure 1** for the three special processes described above (**Section 1.2**), *i.e.*,  
 233 white noise, pink noise, and Brown noise. Specifically, three different gap distributions, namely,  
 234  $\text{NB}(\lambda = 1, \mu = 1)$ ,  $\text{NB}(\lambda = 1, \mu = 14)$ , and  $\text{NB}(\lambda = 0.01, \mu = 1)$ , were simulated and each was  
 235 applied to convert the three original (regular) time series (**Figure 1a-1c**) to **irregulargappy** time  
 236 series (**Figure 1d-1f**). These simulations clearly illustrate the effects of the two parameters  $\lambda$  and  
 237  $\mu$ . In particular, compared with  $\text{NB}(\lambda = 1, \mu = 1)$ ,  $\text{NB}(\lambda = 1, \mu = 14)$  shows a similar level of  
 238 sampling irregularity (same  $\lambda$ ) but a much longer average gap interval (larger  $\mu$ ). Again  
 239 compared with  $\text{NB}(\lambda = 1, \mu = 1)$ ,  $\text{NB}(\lambda = 0.01, \mu = 1)$  shows the same average interval (same  $\mu$ )

240 but a much more irregular (skewed) gap distribution that contains a few very large gaps (smaller  
241  $\lambda$ ).

## 242 **2.2. Examination of Sampling Irregularity in Real River Water-Quality Data**

243 The above modeling approach was applied to real water-quality data from two large river  
244 monitoring networks in the United States to examine sampling irregularity. One such network is  
245 the Chesapeake Bay River Input Monitoring program, which typically samples streams bi-  
246 monthly to monthly, accompanied with additional sampling during stormflows (Langland *et al.*,  
247 2012; Zhang *et al.*, 2015). These data were obtained from the U.S. Geological Survey National  
248 Water Information System (<http://doi.org/10.5066/F7P55KJN>). The other network is the Lake  
249 Erie and Ohio tributary monitoring program, which typically samples streams at a daily  
250 resolution (National Center for Water Quality Research, 2015). For each site, we determined the  
251 NB parameters to quantify sampling irregularity. The mean parameter  $\mu$  can be estimated as  
252 described above, and the shape parameter  $\lambda$  can be calculated directly from the mean and  
253 variance of  $\Delta t^*$  as follows:  $\lambda = \mu^2 / [\text{var}(\Delta t^*) - \mu] = (\text{mean}(\Delta t^*) - 1)^2 / [\text{var}(\Delta t^*) - \text{mean}(\Delta t^*) + 1]$ .  
254 Alternatively, a maximum likelihood approach can be used, which employs the “*fitdist*” function  
255 in the “*fitdistrplus*” R package (Delignette-Muller and Dutang, 2015). In general, the two  
256 approaches have produced similar results, which are summarized in **Table 1**, with two examples  
257 of fitted NB distributions shown in **Figure 3**.

258 For the Chesapeake Bay River Input Monitoring program (9 sites), total nitrogen (TN) and  
259 total phosphorus (TP) are taken as representatives of water-quality constituents. According to the  
260 maximum likelihood approach, the shape parameter  $\lambda$  varies between 0.7 and 1.2 for TN and  
261 between 0.8 and 1.1 for TP (**Table 1**). These  $\lambda$  values are around 1.0, reflecting the fact that  
262 these sites have relatively even gap distributions (*i.e.*, relatively balanced counts of large and  
263 small gaps). The mean parameter  $\mu$  varies between 9.5 and 19.6 for TN and between 13.4 and  
264 24.4 for TP in the Chesapeake monitoring network, corresponding to  $\Delta t_{\text{average}}$  of 10.5–20.6 days  
265 for TN and 14.4–25.4 days for TP, respectively. This is consistent with the fact that these sites  
266 have typically been sampled bi-monthly to monthly, along with additional sampling during  
267 stormflows (Langland *et al.*, 2012; Zhang *et al.*, 2015).

268 For the Lake Erie and Ohio tributary monitoring program (6 sites), the record of nitrate-plus-  
269 nitrite ( $\text{NO}_x$ ) and TP were examined. According to the maximum likelihood approach, the shape  
270 parameter  $\lambda$  is approximately 0.01 for both constituents (**Table 1**). These very low  $\lambda$  values occur

271 because these time series contain a few very large gaps, ranging from 35 days to 1109 days (~3  
272 years). The mean parameter  $\mu$  varies between 0.06 and 0.22, corresponding to  $\Delta t_{average}$  of 1.06  
273 and 1.22 days, respectively. This is consistent with fact that these sites have been sampled at a  
274 daily resolution with occasional missing values on some days (Zhang and Ball, 2017).

### 275 **2.3. Simulation of Time Series with Irregular Sampling**

276 To evaluate the various  $\beta$  estimation methods, our first step was to use Monte Carlo  
277 simulation to produce time series that mimic the sampling irregularity observed in real water-  
278 quality monitoring data. We began by simulating regular (gap free) time series using the  
279 fractional noise simulation method of Witt and Malamud (2013), which is based on inverse  
280 Fourier filtering of white noises. Our analysis showed this method performed reasonably well  
281 compared to other simulation methods for  $\beta$  values between 0 and 1 ([data not shown](#) see  
282 [Supporting Information S1](#)). In addition, this method can also simulate  $\beta$  values beyond this  
283 range. The noises simulated by the Witt and Malamud method, however, are band-limited to the  
284 Nyquist frequency (half of the sampling frequency) of the underlying white noise time series,  
285 whereas true fractional noises would contain spectral power at all frequencies, extending well  
286 above the Nyquist frequency for any sampling. Thus these band-limited noises will be less  
287 susceptible to spectral aliasing than true fractional noises would be; see Kirchner (2005) for  
288 detailed discussions of the aliasing issue.

289 ~~Thirty~~100 replicates of regular (gap free) time series were produced for nine prescribed  
290 spectral slopes, which vary from  $\beta = 0$  (white noise) to  $\beta = 2$  (Brownian motion or “random  
291 walk”) with an increment of 0.25 (*i.e.*, 0, 0.25, 0.5, 0.75, 1.0, 1.25, 1.5, 1.75, and 2). These  
292 regular time series each have a length ( $N$ ) of 9125, which can be interpreted as 25 years of  
293 regular daily samples (that is,  $\Delta t_{nominal} = 1$  day).

294 Each of the simulated regular time series was converted to irregular time series using gap  
295 intervals that were simulated with NB distributions. To make these gap intervals mimic those in  
296 typical river water-quality time series, representative NB parameters were chosen based on  
297 results from **Section 2.2**. Specifically,  $\mu$  was set at 1 and 14, corresponding to  $\Delta t_{average}$  of 2 days  
298 and 15 days respectively. For  $\lambda$ , we chose four values that span three orders of magnitude, *i.e.*,  
299 0.001, 0.1, 1, and 10. Note that when  $\lambda = 1$  the generated time series corresponds to a Bernoulli  
300 process. With the chosen values of  $\mu$  and  $\lambda$ , a total of eight scenarios were generated, which were

301 implemented using the “*rmbinom*” function in the “*stats*” R package (R Development Core Team,  
302 2014):

303 1)  $\mu = 1$  (i.e.,  $\Delta t_{average} / \Delta t_{nominal} = 2$ ),  $\lambda = 0.01$ ,

304 2)  $\mu = 1$ ,  $\lambda = 0.1$ ,

305 3)  $\mu = 1$ ,  $\lambda = 1$ ,

306 4)  $\mu = 1$ ,  $\lambda = 10$ ,

307 5)  $\mu = 14$  (i.e.,  $\Delta t_{average} / \Delta t_{nominal} = 15$ ),  $\lambda = 0.01$ ,

308 6)  $\mu = 14$ ,  $\lambda = 0.1$ ,

309 7)  $\mu = 14$ ,  $\lambda = 1$ ,

310 8)  $\mu = 14$ ,  $\lambda = 10$ .

311 Examples of these simulations are shown with boxplots in **Figure 2**.

### 312 **3. Evaluation of Proposed Estimation Methods for Irregular Time Series**

#### 313 **3.1. Summary of Estimation Methods**

314 For the simulated irregular time series,  $\beta$  was estimated using the aforementioned two types  
315 of approaches. The first type includes 11 different interpolation methods (designated as B1-B11  
316 below) to fill the data gaps, thus making the data regular and analyzable by traditional methods:

317 B1) Global mean: all missing values replaced with the mean of all observations;

318 B2) Global median: all missing values replaced with the median of all observations;

319 B3) Random replacement: all missing values replaced with observations randomly drawn  
320 (with replacement) from the time series;

321 B4) Next observation carried backward: each missing value replaced with the next available  
322 observation;

323 B5) Last observation carried forward: each missing value replaced with the preceding  
324 available observation;

325 B6) Average of the two nearest samples: it replaces each missing value with the mean of its  
326 next and preceding available observations;

327 B7) Lowess (locally weighted scatterplot smoothing) with a smoothing span of 1: missing  
328 values replaced using fitted values from a lowess model determined using all available  
329 observations (Cleveland, 1981);

330 B8) Lowess with a smoothing span of 0.75: same as B7 except that the smoothing span is 75%  
331 of the available data (similar distinction follows for B9-B11);  
332 B9) Lowess with a smoothing span of 50%;  
333 B10) Lowess with a smoothing span of 30%; and  
334 B11) Lowess with a smoothing span of 10%.

335 B4 and B5 were implemented using the “*na.locf*” function in the “*zoo*” R package (Zeileis and  
336 Grothendieck, 2005). B7-B11 were implemented using the “*loess*” function in the “*stats*” R  
337 package (R Development Core Team, 2014). An illustration of these interpolation methods is  
338 provided in **Figure 4**. The interpolated data, along with the original regular data (designated as  
339 A1) were analyzed using the Whittle’s maximum likelihood method for  $\beta$  estimation, which was  
340 implemented using the “*FDWhittle*” function in the “*fractal*” R package (Constantine and  
341 Percival, 2014).

342 The second type of approaches estimates  $\beta$  in the irregularly sampled data directly, using  
343 several variants of the Lomb-Scargle periodogram (designated as C1a-C1c below), and a  
344 recently developed wavelet-based method (designated as C2 below). Specifically, these  
345 approaches are:

346 C1a) Lomb-Scargle periodogram: the spectral density of the time series (with gaps) is  
347 estimated and the spectral slope is fit using all frequencies (Lomb, 1976; Scargle, 1982).  
348 This is a classic method for examining periodicity in irregularly sampled data, which is  
349 analogous to the more familiar fast Fourier transform method often used for regularly  
350 sampled data;

351 C1b) Lomb-Scargle periodogram with 5% data: same as C1a except that the fitting of the  
352 spectral slope considers only the lowest 5% frequencies (Montanari *et al.*, 1999);

353 C1c) Lomb-Scargle periodogram with “binned” data: same as C1a except that the fitting of  
354 the spectral slope is performed on binned data in three steps: (1) The entire range of  
355 frequency is divided into 100 equal-interval bins on logarithmic scale. (2) The  
356 respective medians of frequency and power spectral density are calculated for each of  
357 the 100 bins. (3) The 100 pairs of median frequency and median spectral density are  
358 used to estimate the spectral slope on a log-log scale.

359 C2) Kirchner and Neal (2013)’s wavelet method: uses a modified version of Foster’s  
360 weighted wavelet spectrum (Foster, 1996) to suppress spectral leakage from low

361 frequencies and applies an aliasing filter (Kirchner, 2005) to remove spectral aliasing  
362 artifacts at high frequencies.  
363 C1a was implemented using the “*spec.ls*” function in the “*cts*” R package (Wang, 2013). C2 was  
364 run in *C*, using codes modified from those in Kirchner and Neal (2013).

### 365 **3.2. Evaluation of Methods’ Performance**

366 Each estimation method listed above was applied to the simulated data (**Section 2.3**) to  
367 estimate  $\beta$ , which were then compared with the prescribed (“true”)  $\beta$  to quantify the performance  
368 of each method. Plots of method evaluation for all simulations are provided as **Figures S4S3-**  
369 **S10-S12 in the (Supporting Information S2)**. Close inspections of these plots reveal some  
370 general patterns of the methods’ performance. For brevity, these patterns are presented with a  
371 subset of the plots, which correspond to the cases where true  $\beta = 1$  and shape parameter  $\lambda = 0.01$ ,  
372 0.1, 1, and 10 (**Figure 5**). In general,  $\beta$  values estimated using the regular data (A1) are very  
373 close to 1.0, which indicates that the adopted fractional noise generation method and the  
374 Whittle’s maximum likelihood estimator have small combined simulation and estimation bias.  
375 This is perhaps unsurprising, since the estimator is based on the Fourier transform and the noise  
376 generator is based on an inverse Fourier transform; thus, one method is essentially just the  
377 inverse of the other. One should also note that when fractional noises are not arbitrarily band-  
378 limited at the Nyquist frequency (as they inherently are with the noise generator that is used  
379 here), spectral aliasing should lead to spectral slopes that are flatter than expected (Kirchner,  
380 2005), and thus to underestimates of LRD.

381 For the simulated irregular data, the estimation methods differ widely in their performance.  
382 Specifically, three interpolation methods (*i.e.*, B4-B6) consistently over-estimate  $\beta$ , indicating  
383 that they introduce additional correlations into the time series, reducing its short-timescale  
384 variability. In contrast, the other eight interpolation methods (*i.e.*, B1-B3 and B7-B11) generally  
385 under-estimate  $\beta$ , indicating that the interpolated points are less correlated than the original time  
386 series, thus introducing additional variability on short timescales. As expected, results from the  
387 lowess methods (B7-B11) depend strongly on the size of smoothing window, that is, more  
388 severe under-estimation of  $\beta$  is produced as the smoothing window becomes wider. In fact, when  
389 the smoothing window is 1.0 (*i.e.*, method B7), lowess performs the interpolation using all data  
390 available and thus behaves similarly to interpolations based on global means (B1) or global  
391 medians (B2), except that lowess fits a polynomial curve instead of constant values. However,

392 whenever a sampling gap is much shorter than the smoothing window, the infilled lowess value  
393 will be close to the local mean or median, and the abrupt jumps produced by these infilled values  
394 will artificially increase the variance in the time series at high frequencies, leading to an  
395 artificially reduced spectral slope  $\beta$  and correspondingly, an underestimate of  $\beta$ . This mechanism  
396 explains why lowess interpolation distorts  $\beta$  more when there are many small gaps (large  $\lambda$ ), and  
397 therefore more jumps to, and away from, the infilled values, than when there are only a few large  
398 gaps (small  $\lambda$ ).

399 Among the direct methods (*i.e.*, C1a, C1b, C1c, and C2), the Lomb-Scargle method, with  
400 original data (C1a) or binned data (C1c) tends to under-estimate  $\beta$ , though the underestimation  
401 by C1c is generally less severe. The modified Lomb-Scargle method (C1b), using only the  
402 lowest 5% of frequencies, yields estimates that are centered around 1.0. However, C1b has the  
403 highest variability (*i.e.*, least precision) in  $\beta$  estimates among all methods. Compared with all the  
404 above methods, the wavelet method (C2) has much better performance in terms of both accuracy  
405 and precision when  $\lambda$  is 1 or 10, a slightly better performance when  $\lambda$  is 0.1, but a worse  
406 performance when  $\lambda$  is 0.01.

407 The shape parameter  $\lambda$  greatly affects the performance of the estimation methods. All the  
408 interpolation methods that under-estimate  $\beta$  (*i.e.*, B1-B3 and B7-B11) perform worse as  $\lambda$   
409 increases from 0.01 to 10. This effect can be interpreted as follows: when the time series  
410 contains a large number of relatively small gaps (*e.g.*,  $\lambda = 1$  or 10), there are many jumps (which,  
411 as noted above, contain mostly high-frequency variance) between the original data and the  
412 infilled values, resulting in more severe under-estimation. In contrast, when the data contain only  
413 a small number of very large gaps (*e.g.*,  $\lambda = 0.01$  or 0.1), there are fewer of these jumps, resulting  
414 in minimal under-estimation. Similar effects of  $\lambda$  are also observed with the interpolation  
415 methods that show over-estimation (*i.e.*, B4-B6) – that is, over-estimation is more severe when  $\lambda$   
416 is larger. Similarly, the Lomb-Scargle method (C1a and C1c) performs worse (more serious  
417 underestimation) as  $\lambda$  increases. Finally, method C2 seems to perform the best when  $\lambda$  is large (1  
418 or 10), but not well when  $\lambda$  is very small (0.01), as noted above. This result highlights the  
419 sensitivity of the wavelet method to the presence of a few large gaps in the time series. For such  
420 cases, a potentially more feasible approach is to break the whole time series into several  
421 segments (each without long gaps) and then apply the wavelet method (C2) to analyze each  
422 segment separately. If this can yield more accurate estimates, then further simulation

423 experiments should be designed to systematically determine how long the gap needs to be to  
 424 invoke such an approach.

425 Next, the method evaluation is extended to all the simulated spectral slopes, that is,  $\beta = 0$ ,  
 426 0.25, 0.5, 0.75, 1.0, 1.25, 1.5, 1.75, and 2. For ease of discussion, three quantitative criteria were  
 427 proposed for evaluating performance, namely, bias (B), standard deviation (SD), and root-mean-  
 428 squared error (RMSE), as defined below:

$$B_i = \bar{\beta}_i - \beta_{true} \quad (14)$$

$$SD_i = \sqrt{\frac{1}{9929} \sum_{j=1}^{10030} (\beta_{i,j} - \bar{\beta}_i)^2} \quad (15)$$

$$RMSE_i = \sqrt{B_i^2 + SD_i^2} \quad (16)$$

429 where  $\bar{\beta}_i$  is the mean of ~~30~~100  $\beta$  values estimated by method  $i$ , and  $\beta_{true}$  is the prescribed  $\beta$  value  
 430 for simulation of the initial regular time series. In general, B and SD can be considered as the  
 431 models' systematic error and random error, respectively, and RMSE serves as an integrated  
 432 measure of both errors. For all evaluations, plots of bias and RMSE are provided in the main text.  
 433 (Plots of SD are provided as **Figure S5-S7** and **Figure S10-S12** for simulations with  $\mu = 1$  and  $\mu$   
 434 = 14, respectively.)

435 For simulations with  $\mu = 1$ , results of estimation bias and RMSE are summarized in **Figure 6**  
 436 and **Figure 7**, respectively. (More details are provided in **Figures S1S3-S4S6**.) For brevity, we  
 437 focus on three direct methods (C1a, C1b and C2) and three representative interpolation methods.  
 438 (Specifically, B1 represents B1-B3 and B7; B6 represents B4-B6, and B8 represents B8-B11.)  
 439 Overall, these six methods show mixed performances. In terms of bias (**Figure 6**), B1 (global  
 440 mean) and B8 (lowess with a smoothing span of 0.75) tend to have negative bias, particularly for  
 441 time series with (1) moderate-to-large  $\beta_{true}$  values and (2) large  $\lambda$  values (*i.e.*, less skewed gap  
 442 intervals). By contrast, B1 and B8 generally have minimal bias when (1)  $\beta_{true}$  is close to zero (*i.e.*,  
 443 when the simulated time series is close to white noise); and (2)  $\lambda$  is small (*e.g.*, 0.01), since  
 444 interpolating a few large gaps cannot significantly affect the overall correlation structure. In  
 445 addition, lowess interpolation with a larger smoothing window tends to yield more negatively  
 446 biased estimates (data not shown). The other interpolation method, B6 (mean of the two nearest  
 447 neighbors) tends to over-estimate  $\beta$ , particularly for time series with (1) small  $\beta_{true}$  values and (2)



448 large  $\lambda$  values. At large  $\beta_{true}$  values (*e.g.*, 2.0), the auto-correlation is already very strong such  
449 that taking the mean of two neighbors for gap filling does not introduce much additional  
450 correlation, as opposed to the case of small  $\beta_{true}$  values. The Lomb-Scargle methods (C1a and  
451 C1b) generally have negative bias, particularly for time series with (1) moderate-to-large  $\beta_{true}$   
452 values (for both methods) and (2) large  $\lambda$  values (for C1a), which is similar to B1 and B8.  
453 However, C1b overall shows less severe bias than C1a. Finally, the wavelet method (C2) shows  
454 generally the smallest bias among all methods. However, its performance advantage is not as  
455 great when the time series has small  $\lambda$  values (*i.e.*, very skewed gap intervals), as noted above,  
456 which may be due to the fact that the aliasing filter was designed for regular time series. In terms  
457 of SD (**Figure S5S7**), method C1b performs the worst among all methods (as noted above),  
458 method B6 and B8 perform poorly for large  $\beta_{true}$  values, and method C2 performs poorly for  $\beta_{true}$   
459 = 0. In terms of RMSE (**Figure 7**), methods B1, B8, C1a, and C1b perform well for small  $\beta_{true}$   
460 values and small  $\lambda$  values, whereas method B6 performs well for large  $\beta_{true}$  values and small  $\lambda$   
461 values. In comparison, method C2 has the smallest RMSEs among all methods, and its RMSEs  
462 are similarly small for the wide range of  $\beta_{true}$  and  $\lambda$  values. In general, the wavelet method can be  
463 considered the best among all methods.

464 For simulations with  $\mu = 14$ , results of estimation bias and RMSE are summarized in  
465 **Figure 8** and **Figure 9**, respectively. (More details are provided in **Figures S6S8-S9S11**.)  
466 Overall, these methods show mixed performances that are generally similar to the cases when  $\mu$   
467 = 1, as discussed above. These results highlight the generality of these methods' performances,  
468 which applies at least to the range of  $\mu = [1, 14]$ . In addition, all methods show generally larger  
469 RMSE for  $\mu = 14$  than  $\mu = 1$ , indicating their dependence on the mean gap interval (**Figure 9**).  
470 Perhaps the most notable difference is observed with method C2, which in this case shows  
471 positive bias for small  $\lambda$  values (0.01 and 0.1) and negative bias for large  $\lambda$  values (1 and 10)  
472 (**Figure 8f**). It nonetheless generally shows the smallest RMSEs among all the tested methods.

### 473 **3.3. Quantification of Spectral Slopes in Real Water-Quality Data**

474 In this section, the proposed estimation approaches were applied to quantify  $\beta$  in real water-  
475 quality data from the two monitoring programs presented in **Section 2.2 (Table 1)**. As noted in  
476 **Section 1.3**, such real data are typically much more complex than our simulated time series,  
477 because of (1) strong deviations from normal distributions and (2) effects of flow-dependence,  
478 seasonality, and temporal trend (Hirsch *et al.*, 1991; Helsel and Hirsch, 2002). In this regard,

479 future research may simulate time series with these important characteristics and evaluate the  
480 performance of various estimation approaches, perhaps following the modeling framework  
481 described herein. Alternatively, one may quantify  $\beta$  in transformed time series after accounting  
482 for the above aspects. In this work, we have taken the latter approach for a preliminary  
483 investigation. Specifically, we have used the published Weighted Regressions on Time,  
484 Discharge, and Season (WRTDS) method (Hirsch *et al.*, 2010) to transform the original time  
485 series. This widely accepted method estimates daily concentrations based on discretely collected  
486 concentration samples using time, season, and discharge as explanatory variables, *i.e.*,

$$\ln(C) = \beta_0 + \beta_1 t + \beta_2 \ln(Q) + \beta_3 \sin(2\pi t) + \beta_4 \cos(2\pi t) + \varepsilon \quad (17)$$

487 where  $C$  is concentration,  $Q$  is daily discharge,  $t$  is time in decimal years,  $\beta_i$  are fitted  
488 coefficients, and  $\varepsilon$  is the error term. The 2<sup>nd</sup> and 3<sup>rd</sup> terms on the right represent time and  
489 discharge effects, respectively, whereas the 4<sup>th</sup> and 5<sup>th</sup> terms collectively represent cyclical  
490 seasonal effects. For a full description of this method, see [Hirsch \*et al.\* \(2010\)](#) ~~Hirsch and De~~  
491 ~~Cicco (2015)~~. In this work, WRTDS was applied to obtain the time series of estimated daily  
492 concentration for each constituent at each site. The difference between observed concentration  
493 ( $C_{obs}$ ) and estimated concentration ( $C_{est}$ ) was calculated in logarithmic space to obtain the  
494 concentration residuals,

$$residuals = \ln(C_{obs}) - \ln(C_{est}) \quad (18)$$

495 For our data sets, histograms of concentration residuals (expressed in natural log concentration  
496 units) are shown in [Figures S14S13-S14S16 \(Supporting Information S3\)](#). Compared with the  
497 original concentration data, these model residuals are much more nearly normal and  
498 homoscedastic. Moreover, the model residuals are less susceptible to the issues of temporal,  
499 seasonal, and discharge-drive variations than the original concentrations. Therefore, the model  
500 residuals are more appropriate than the original concentrations for  $\beta$  estimation using the  
501 simulation framework adopted in this work.

502 The estimated  $\beta$  values for the concentration residuals are summarized in **Figure 10**. Clearly,  
503 the estimated  $\beta$  varies considerably with the estimation method. In addition, the estimated  $\beta$   
504 varies with site and constituent (*i.e.*, TP, TN, or NO<sub>x</sub>). Our discussion below focuses on the  
505 wavelet method (C2), because it is established above that this method performs better than the  
506 other estimation methods under a wide range of gap conditions. We emphasize that it is beyond  
507 our current scope to precisely quantify  $\beta$  in these water-quality data sets, but our simulation

508 results presented above (**Section 3.2**) can be used as references to qualitatively evaluate the  
509 reliability of C2 and/or other methods for these data sets.

510 For TN and TP concentration data at the Chesapeake River Input Monitoring sites (**Table 1**),  
511  $\mu$  varies between 9.5 and 24.4, whereas  $\lambda$  is  $\sim 1.0$ . Thus, the simulated gap scenario of NB( $\mu = 14$ ,  
512  $\lambda = 1$ ) can be used as a reasonable reference to assess methods' reliability (**Figure 8**). Based on  
513 method C2, the estimated  $\beta$  ranges between  $\beta = 0.36$  and  $\beta = 0.61$  for TN and between  $\beta = 0.30$   
514 and  $\beta = 0.58$  for TP at these sites (**Figure 10**). For such ranges, the simulation results indicate  
515 that method C2 tends to moderately under-estimate  $\beta$  under this gap scenario (**Figure 8**), and  
516 hence spectral slopes for TN and TP at these Chesapeake sites are likely slightly higher than  
517 those presented above.

518 For NO<sub>x</sub> and TP concentration data at the Lake Erie and Ohio sites (**Table 1**),  $\mu$  varies  
519 between 0.06 and 0.22, whereas  $\lambda$  is  $\sim 0.01$ . Thus, the simulated gap scenario of NB( $\mu = 1$ ,  $\lambda =$   
520 0.01) can be used as a reasonable reference to assess the methods' reliability (**Figure 6**). For  
521 such small  $\lambda$  (*i.e.*, a few gaps that are very dissimilar from others), C2 is not reliable for  $\beta$   
522 estimation, as reflected by the generally positive bias in the simulation results. By contrast,  
523 methods B1 (interpolation with global mean) and B8 (lowess with span 0.75) both perform quite  
524 well under this gap scenario (**Figure 6**). These two methods provide almost identical  $\beta$  estimates  
525 for each site-constituent combination, ranging from  $\beta = 1.0$  to  $\beta = 1.5$  for NO<sub>x</sub> and from  $\beta = 1.0$   
526 to  $\beta = 1.4$  for TP (**Figure 10**).

527 Overall, the above analysis of real water-quality data has illustrated the wide variability in  $\beta$   
528 estimates, with different choices of estimation methods yielding very different results. To our  
529 knowledge, these water-quality data have not heretofore been analyzed in this context. As  
530 illustrated above, our simulation experiments (**Section 3.2**) can be used as references to coarsely  
531 evaluate the reliability of each method under specific gap scenarios, thereby considerably  
532 narrowing the likely range of the estimated spectral slopes. Nonetheless, our results demonstrate  
533 that the analyzed water-quality time series can exhibit strong fractal scaling, particularly at the  
534 Lake Erie and Ohio tributary sites. Thus, an important implication is that researchers and  
535 analysts should be cautious when applying standard statistical methods to identify temporal  
536 trends in such water-quality data sets (Kirchner and Neal, 2013). In future work, one may  
537 consider applying Bayesian statistical analysis or other approaches to more accurately quantify  
538 the spectral slope and associated uncertainty for real water-quality data analysis. In addition, the

539 modeling framework presented herein (including both gap simulation and  $\beta$  estimation) may be  
540 extended to simulations of irregular time series that have prescribed spectral slopes and also  
541 superimposed temporal trends, which can then be used to evaluate the validity of various  
542 statistical methods for identifying trend and associated statistical significance.

#### 543 **4. Conclusions**

544 River water-quality time series often exhibit fractal scaling behavior, which presents  
545 challenges to the identification of deterministic trends. Because traditional estimation methods  
546 are generally not applicable to irregularly sampled time series, we have examined two broad  
547 types of estimation approaches and evaluated their performances against synthetic data with a  
548 wide range of prescribed  $\beta$  values and gap intervals representative of the sampling irregularity of  
549 real water-quality data.

550 The results of this work suggest several important messages. First, the results remind us of  
551 the risks in using interpolation for gap filling when examining auto-correlation, as the  
552 interpolation methods consistently under-estimate or over-estimate  $\beta$  under a wide range of  
553 prescribed  $\beta$  values and gap distributions. Second, the long-established Lomb-Scargle spectral  
554 method also consistently under-estimates  $\beta$ . Its modified form, using the 5% lowest frequencies  
555 for spectral slope estimation, has very poor precision, although the overall bias is small. Third,  
556 the wavelet method, coupled with an aliasing filter, has the smallest bias and root-mean-squared  
557 error among all methods for a wide range of prescribed  $\beta$  values and gap distributions, except for  
558 cases with small prescribed  $\beta$  values (*i.e.*, close to white noise) or small  $\lambda$  values (*i.e.*, very  
559 skewed gap distributions). Thus, the wavelet method is recommended for estimating spectral  
560 slope in irregular time series until improved methods are developed. In this regard, future  
561 research should aim to develop an aliasing filter that is more applicable to irregular time series  
562 with very skewed gap intervals. Finally, all methods' performances depend strongly on the  
563 sampling irregularity in terms of both the skewness and mean of gap-interval lengths,  
564 highlighting that the accuracy and precision of each method are data-specific.

565 Overall, these results provide new contributions in terms of better understanding and  
566 quantification of the proposed methods' performances for estimating the strength of fractal  
567 scaling in irregularly sampled water-quality data. In addition, the work has provided an  
568 innovative and general approach for modeling sampling irregularity in water-quality records.

569 Moreover, this work has proposed and demonstrated a generalizable framework for data  
570 simulation (with gaps) and  $\beta$  estimation, which can be readily applied toward the evaluation of  
571 other methods that are not covered in this work. More generally, the findings and approaches  
572 may also be broadly applicable to irregularly sampled data in other scientific disciplines. Last but  
573 not least, we note that accurate quantification of fractal scaling in irregular water-quality time  
574 series remains an unresolved challenge for the hydrologic community and for many other  
575 disciplines that must grapple with irregular sampling.

#### 576 **Data Availability**

577 River monitoring data used in this study are available through the U.S. Geological Survey  
578 National Water Information System (<http://doi.org/10.5066/F7P55KJN>) and the Heidelberg  
579 University's National Center for Water Quality Research.

#### 580 **Supporting Information**

581 Supporting information to this article is available online.

#### 582 **Competing Interests**

583 The authors declare that they have no conflict of interest.

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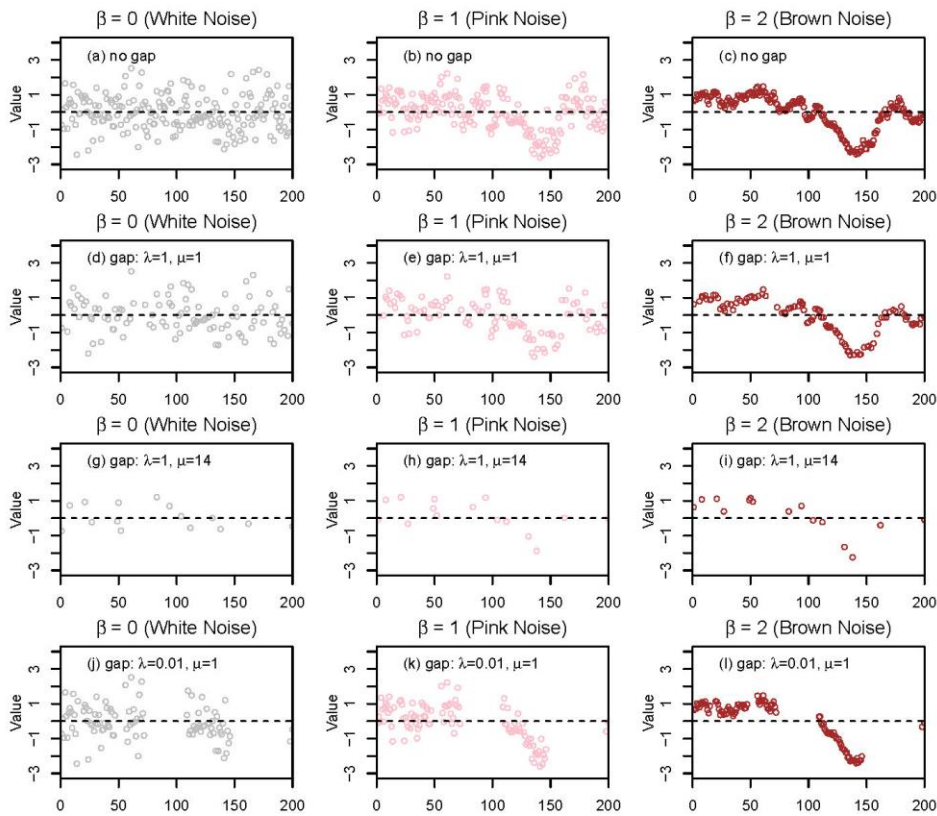
**Table 1.** Quantification of sampling irregularity for selected water-quality constituents at nine sites of the Chesapeake Bay River Input Monitoring program and six sites of the Lake Erie and Ohio tributary monitoring program. ( $\mu$ : mean parameter;  $\lambda$ : shape parameter estimated using maximum likelihood;  $\lambda'$ : shape parameter estimated using the direct approach (see **Section 2.2**).  $\Delta t_{average}$ : average gap interval;  $N$ : total number of samples.)

*I. Chesapeake Bay River Input Monitoring program*

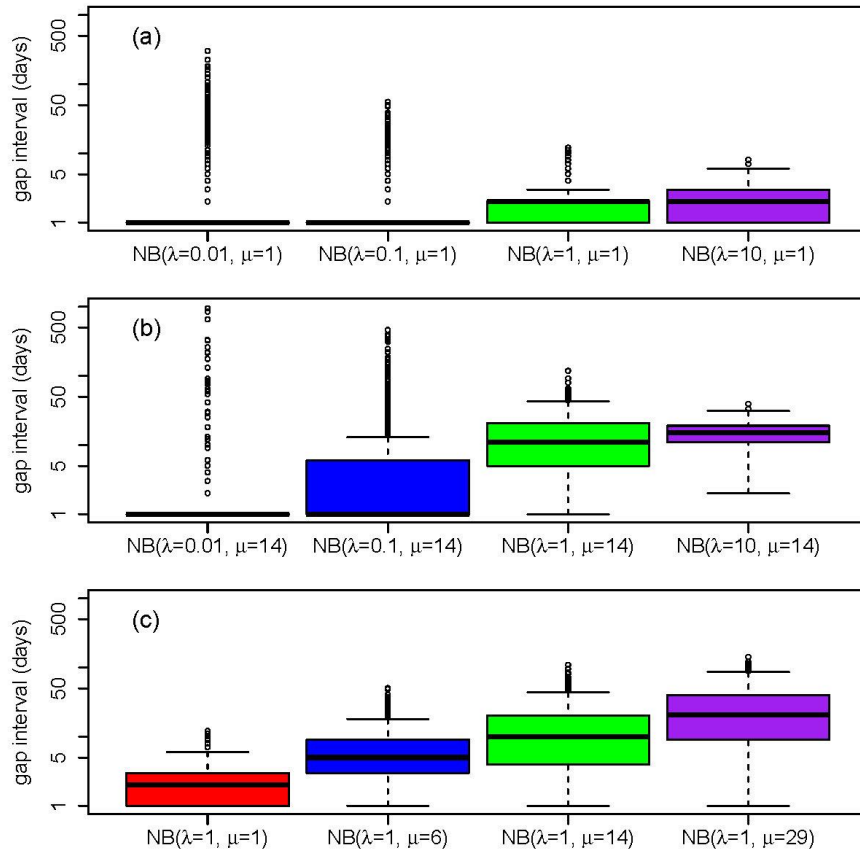
Site ID	River and station name	Drainage area (mi <sup>2</sup> )	Total nitrogen (TN)					Total phosphorus (TP)				
			$\lambda$	$\lambda'$	$\mu$	$\Delta t_{average}$ (days)	$N$	$\lambda$	$\lambda'$	$\mu$	$\Delta t_{average}$ (days)	$N$
01578310	Susquehanna River at Conowingo, MD	27,100	0.8	1.1	13.5	14.5	876	0.8	1.0	13.4	14.4	881
01646580	Potomac River at Chain Bridge, Washington D.C.	11,600	0.9	0.6	9.5	10.5	1,385	1.1	1.0	24.4	25.4	579
02035000	James River at Cartersville, VA	6,260	0.8	1.0	13.9	14.9	960	0.8	1.1	13.7	14.7	974
01668000	Rappahannock River near Fredericksburg, VA	1,600	0.8	0.6	15.6	16.6	776	0.8	0.6	15.2	16.2	796
02041650	Appomattox River at Matoaca, VA	1,340	0.8	0.8	15.1	16.1	798	0.8	0.8	14.9	15.9	810
01673000	Pamunkey River near Hanover, VA	1,071	0.8	0.9	15.1	16.1	873	0.8	1.0	14.7	15.7	894
01674500	Mattaponi River near Beulahville, VA	601	0.7	0.9	14.3	15.3	810	0.8	0.9	14.2	15.2	820
01594440	Patuxent River at Bowie, MD	348	0.9	1.1	15.3	16.3	787	0.8	0.8	14.0	15.0	861
01491000	Choptank River near Greensboro, MD	113	1.2	1.5	19.6	20.6	680	1.1	1.0	20.5	21.5	690

*II. Lake Erie and Ohio tributary monitoring program*

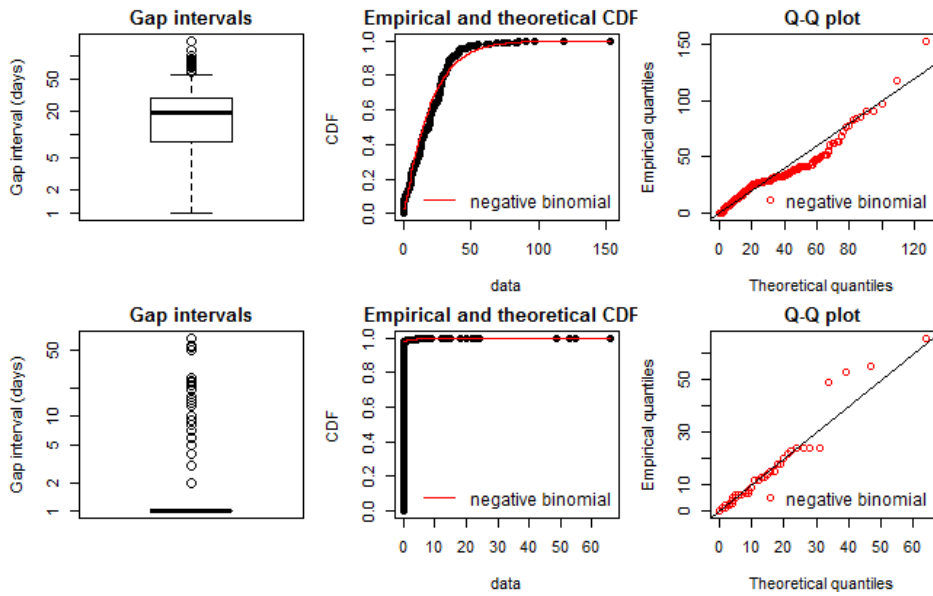
Site ID	River and station name	Drainage area (mi <sup>2</sup> )	Nitrate-plus-nitrite (NO <sub>x</sub> )					Total phosphorus (TP)				
			$\lambda$	$\lambda'$	$\mu$	$\Delta t_{average}$ (days)	$N$	$\lambda$	$\lambda'$	$\mu$	$\Delta t_{average}$ (days)	$N$
04193500	Maumee River at Waterville, OH	6,330	0.005	0.0003	0.19	1.19	9,101	0.005	0.0003	0.19	1.19	9,101
04198000	Sandusky River near Fremont, OH	1,253	0.01	0.003	0.22	1.22	9,641	0.01	0.003	0.22	1.22	9,655
04208000	Cuyahoga River at Independence, OH	708	0.007	0.006	0.13	1.13	7,421	0.007	0.006	0.13	1.13	7,426
04212100	Grand River near Painesville, OH	686	0.01	0.005	0.21	1.21	5,023	0.01	0.005	0.22	1.22	4,994
04197100	Honey Creek at Melmore, OH	149	0.007	0.005	0.06	1.06	9,914	0.007	0.005	0.06	1.06	9,914
04197170	Rock Creek at Tiffin, OH	34.6	0.007	0.008	0.06	1.06	8,422	0.007	0.008	0.06	1.06	8,440



723  
 724 **Figure 1.** Synthetic time series with 200 time steps for three representative fractal scaling  
 725 processes that correspond to white noise ( $\beta = 0$ ), pink noise ( $\beta = 1$ ), and Brown noise ( $\beta = 2$ ).  
 726 The 1<sup>st</sup> row shows the simulated time series without any gap. The three rows below show the  
 727 same time series as in the 1<sup>st</sup> row but with data gaps that were simulated using three different  
 728 negative binomial (NB) distributions, that is, 2<sup>nd</sup> row:  $\text{NB}(\lambda = 1, \mu = 1)$ ; 3<sup>rd</sup> row:  $\text{NB}(\lambda = 1, \mu =$   
 729  $14)$ ; 4<sup>th</sup> row:  $\text{NB}(\lambda = 0.01, \mu = 1)$ .



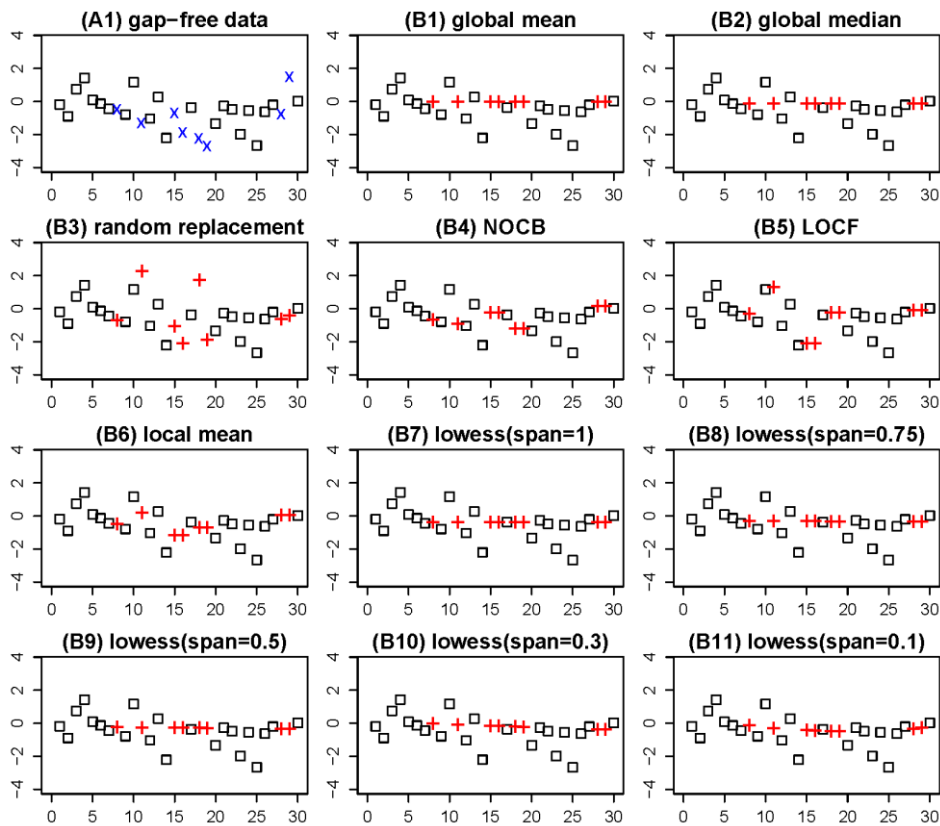
730  
 731 **Figure 2.** Examples of gap interval simulation using binomial distributions, NB (shape  $\lambda$ , mean  
 732  $\mu$ ). Simulation parameters:  $L = 9125$  days,  $\Delta t_{nominal} = 1$  day. The three panels show simulation  
 733 with fixed (a)  $\mu = 1$ , (b)  $\mu = 14$ , and (c)  $\lambda = 1$ . Note that  $\Delta t_{average}/\Delta t_{nominal} = \mu + 1$ .



734

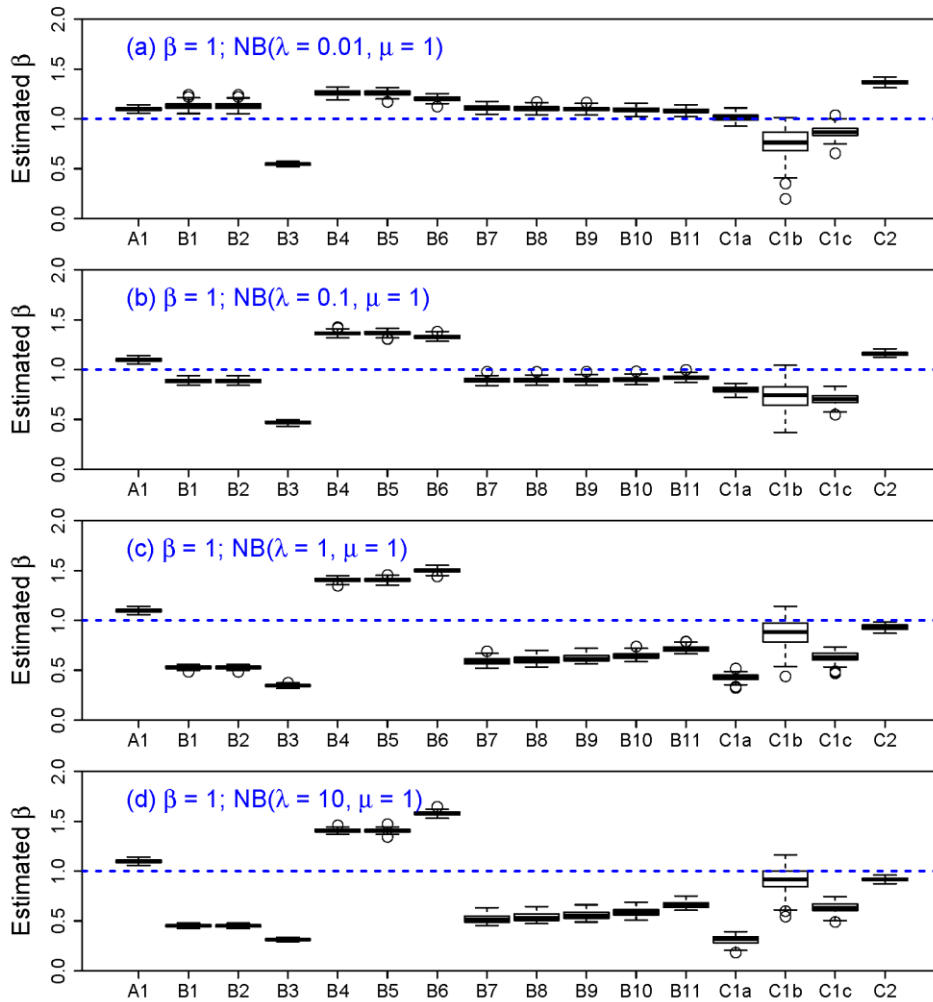
735

736 **Figure 3.** Examples of quantified sampling irregularity with negative binomial (NB)  
 737 distributions: total nitrogen in Choptank River (top) and total phosphorus in Cuyahoga River  
 738 (bottom). Theoretical CDF and quantiles are based on the fitted NB distributions. See **Table 1**  
 739 for estimated mean and shape parameters.

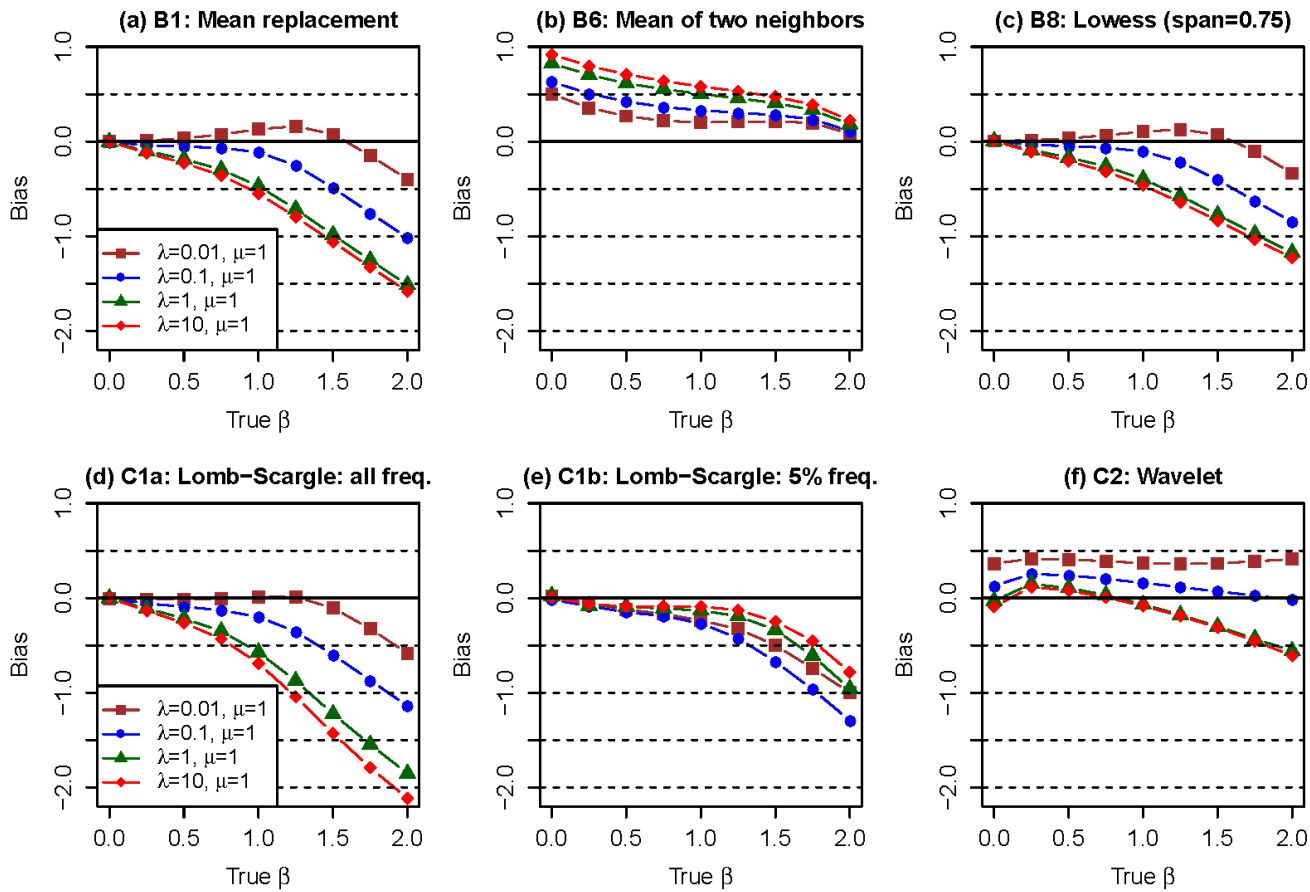


740  
 741 **Figure 4.** Illustration of the interpolation methods for gap filling. The gap-free data (A1) was  
 742 simulated with a series length of 500, with the first 30 data shown. (x: omitted data for gap filling;  
 743 +: interpolated data; NOCB: next observation carried backward; LOCF: last observation carried  
 744 forward; lowess: locally weighted scatterplot smoothing.)

Commented [QZ1]: Updated figure with 100 replicate runs



745  
746 **Figure 5.** Comparison of bias in estimated spectral slope in irregular data that are simulated with  
747 prescribed  $\beta = 1$  (30100 replicates), series length of 9125, and gap intervals simulated with (a)  
748 NB ( $\lambda = 0.01, \mu = 1$ ), (b) NB ( $\lambda = 0.1, \mu = 1$ ), (c) NB ( $\lambda = 1, \mu = 1$ ), and (d) NB ( $\lambda = 10, \mu = 1$ ).  
749 The blue dashed lines indicate the true  $\beta$  value.



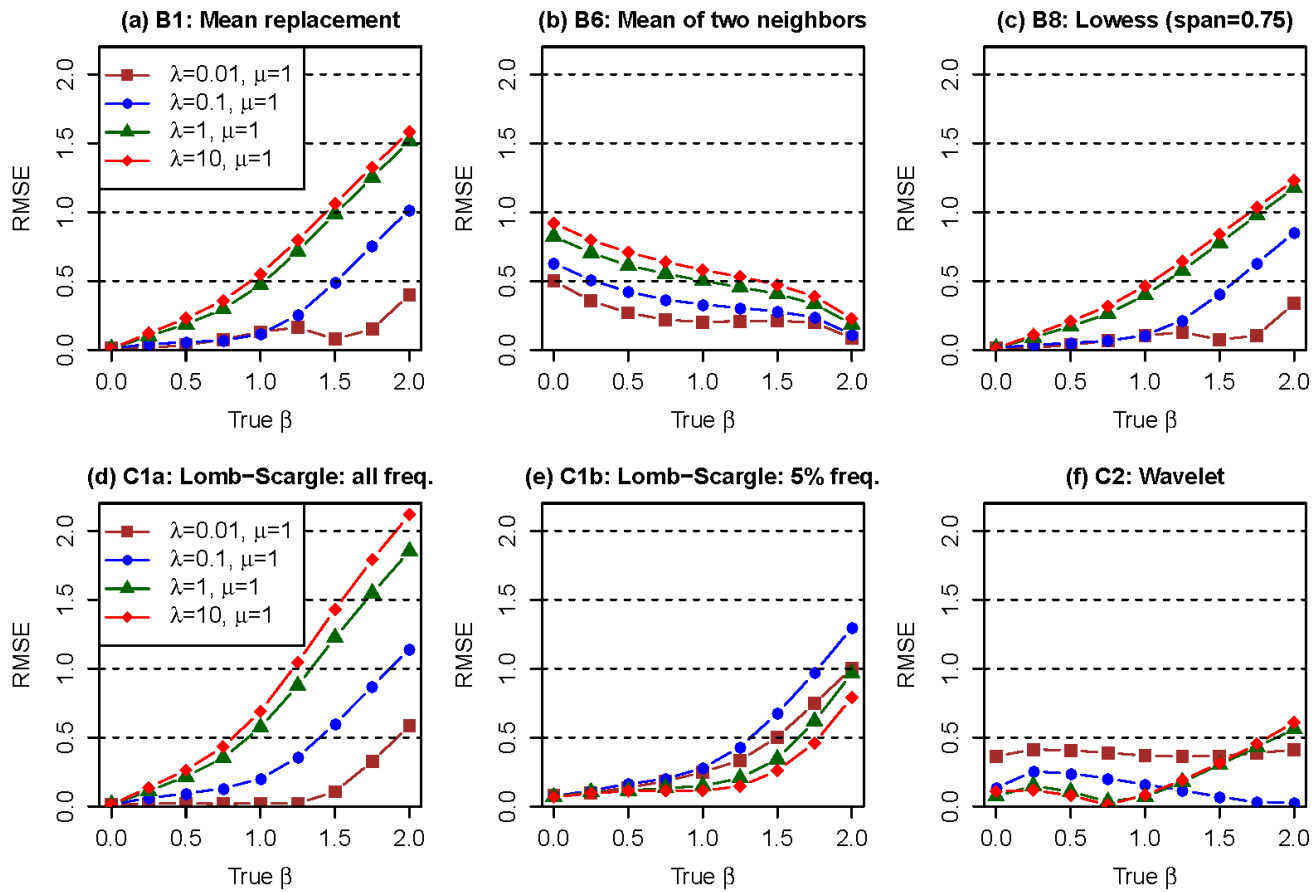
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750

751 **Figure 6.** Comparison of bias in estimated spectral slope in irregular data that are simulated with varying prescribed  $\beta$  values ([39100](#)

752 replicates), series length of 9125, and mean gap interval of 2 (*i.e.*,  $\mu = 1$ ).

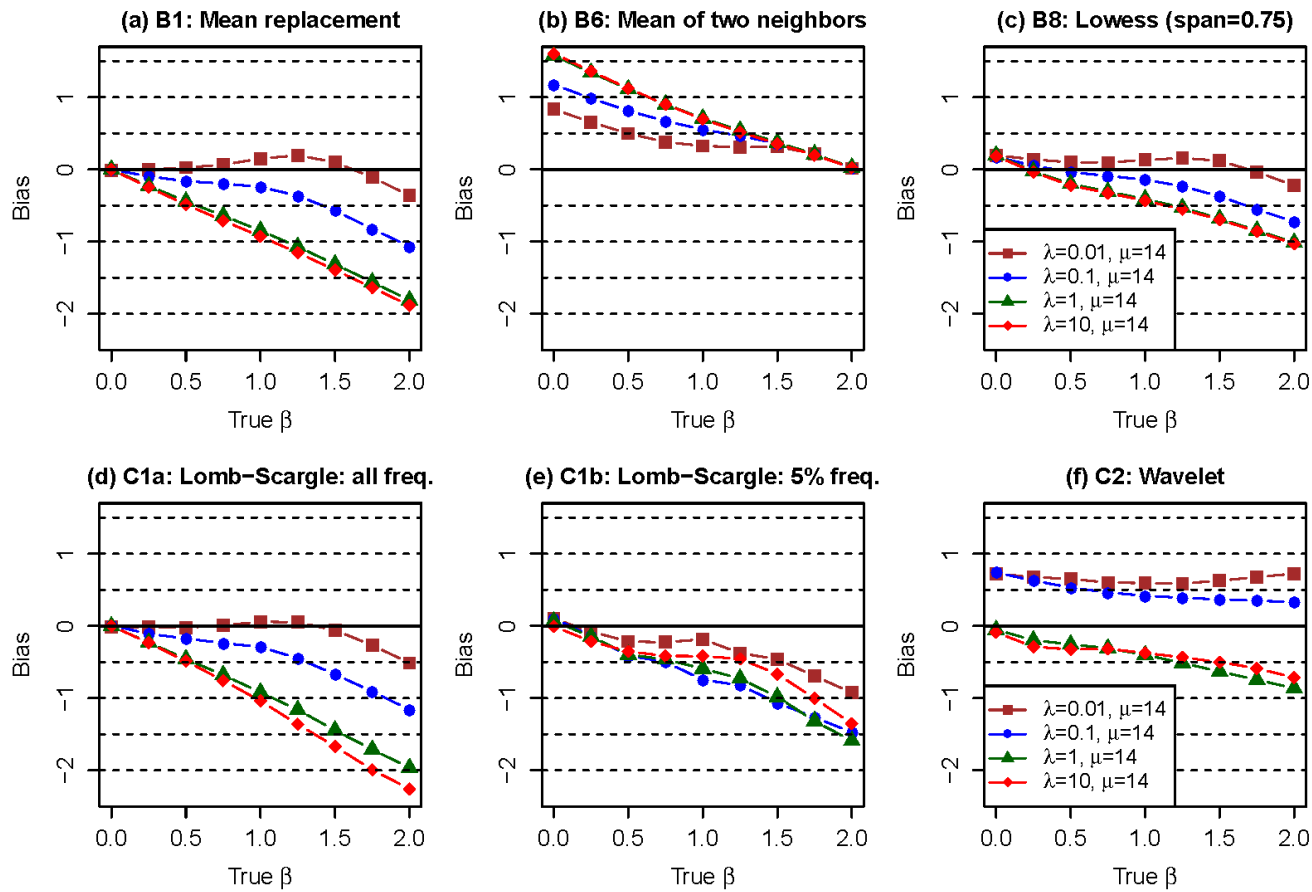




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753

754 **Figure 7.** Comparison of root-mean-squared error (RMSE) in estimated spectral slope in irregular data that are simulated with varying  
 755 prescribed  $\beta$  values (30100 replicates), series length of 9125, and mean gap interval of 2 (*i.e.*,  $\mu = 1$ ).



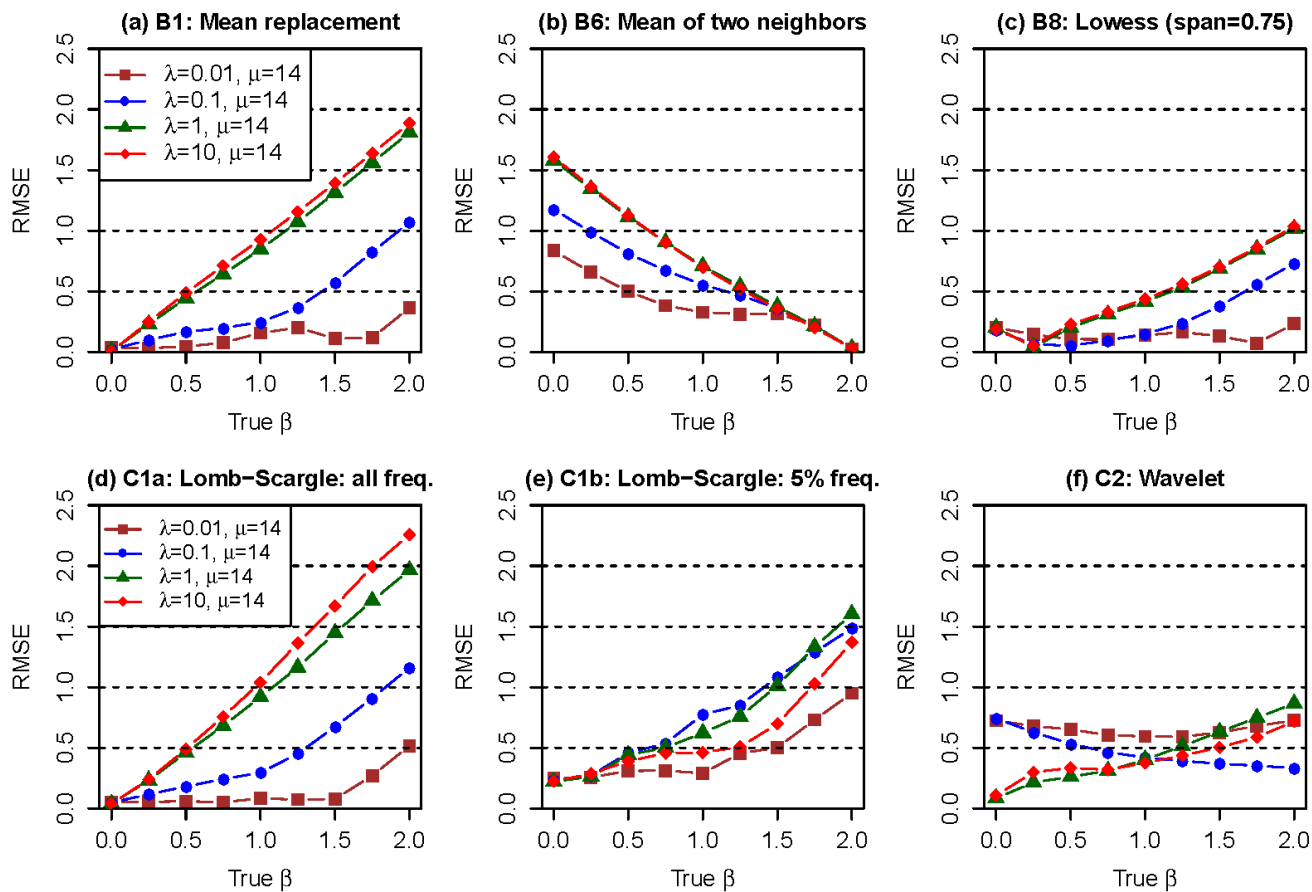
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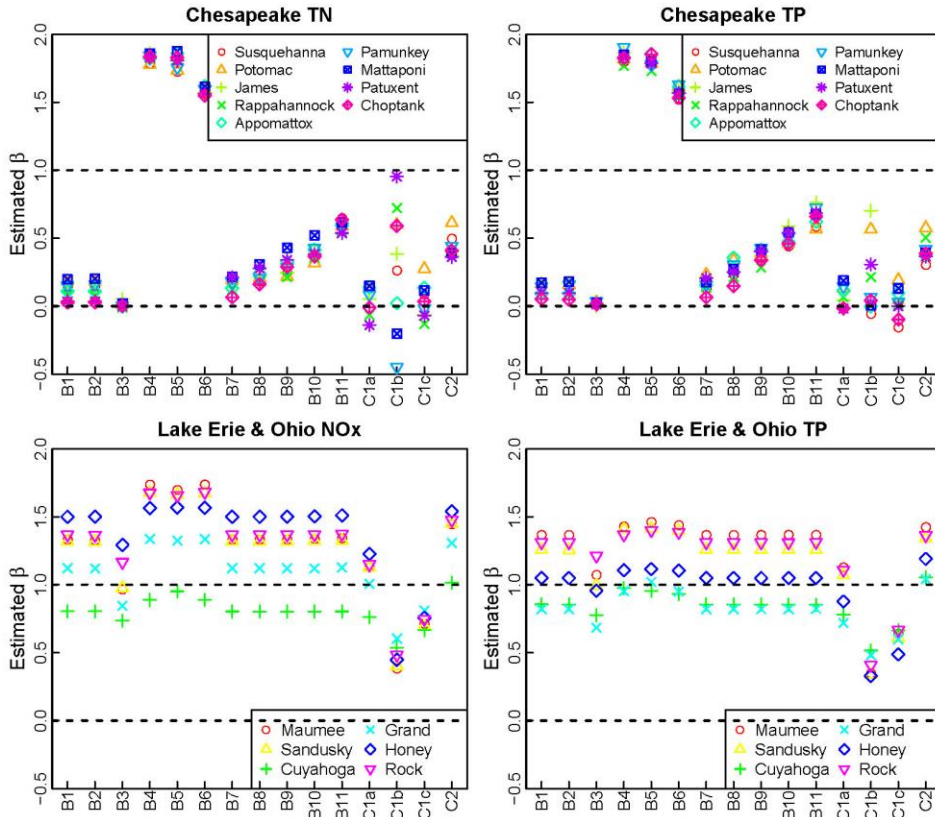
**Figure 8.** Comparison of bias in estimated spectral slope in irregular data that are simulated with varying prescribed  $\beta$  values (39100 replicates), series length of 9125, and mean gap interval of 15 (*i.e.*,  $\mu = 14$ ).



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759

760 **Figure 9.** Comparison of root-mean-squared error (RMSE) in estimated spectral slope in irregular data that are simulated with varying  
 761 prescribed  $\beta$  values (30100 replicates), series length of 9125, and mean gap interval of 15 (*i.e.*,  $\mu = 14$ ).



762  
 763 **Figure 10.** Quantification of spectral slope in real water-quality data from the two regional  
 764 monitoring networks, as estimated using the set of examined methods. All estimations were  
 765 performed on concentration residuals (in natural log concentration units) after accounting for  
 766 effects of time, discharge, and season. The two dashed lines in each panel indicate white noise ( $\beta$   
 767 = 0) and pink (flicker) noise ( $\beta = 1$ ), respectively. See **Table 1** for site and data details.