



# Spatial characterization of long-term hydrological change in the Arkavathy watershed adjacent to Bangalore, India

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**Abstract.** The complexity and heterogeneity of human water use over large spatial areas and decadal timescales can impede the understanding of hydrologic change, particularly in regions with sparse monitoring of the water cycle. In the Arkavathy watershed in south India, surface water inflows to major reservoirs decreased over a 40 year period during which urbanization, groundwater depletion, modification of the river network, and changes in agricultural practices also occurred. These multiple, co-varying drivers along with limited hydrological monitoring make attribution of the causes of water scarcity in the basin challenging, and limit the effectiveness of policy responses. We develop a novel, spatially distributed dataset to understand hydrologic change by characterizing trends in surface water area in nearly 1700 rainwater harvesting and irrigation structures known as tanks. Using an automated classification approach with subpixel unmixing, we classified water surface area in Landsat images from 1973 to 2010. The classification results compared well with a reference dataset of water surface area of tanks ( $R^2 = 0.95$ ). We modeled water surface area of 42 clusters of tanks in a multiple regression on simple hydrological covariates and time, and found distinguishable trends in water surface area in different regions of the watershed. Agricultural areas with considerable groundwater irrigation exhibited the strongest drying. Urban land use was associated with intra-urban drying, likely due to tank encroachment, and downstream periurban wetting, likely due to increased urban effluents. Disaggregating the watershed-scale hydrological response via remote sensing of surface water bodies over multiple decades yielded a spatially resolved characterization of hydrological change in an otherwise poorly monitored watershed. This approach presents an opportunity for understanding hydrological change in heavily managed watersheds where surface water bodies integrate upstream runoff and can be delineated using satellite imagery.

## 1 Introduction

Human water consumption is straining water resources worldwide (Vogel et al., 2015; Gleick, 2014; Wada et al., 2012; Lall et al., 2008), with developing nations particularly vulnerable to water scarcity (Vörösmarty et al., 2010). The causes of water scarcity are complex (Srinivasan et al., 2012) and in south India have been associated with urbanization (Srinivasan et al., 2013), groundwater depletion (Reddy, 2005), degradation of rainwater harvesting structures (Gunnell and Krishnamurthy, 2003), and interstate water disputes (Anand, 2004). Effective management of water scarcity in this region is impeded by lack of adequate



data to quantify and understand how human activities affect hydrology (Batchelor et al., 2003; Lele et al., 2013; Srinivasan et al., 2014).

Data scarcity is a common challenge in hydrology and has been extensively explored through the lens of “predictions in ungauged basins” (PUB) over the past two decades (Bonell et al., 2006; Hrachowitz et al., 2013). The methodologies developed through the PUB initiative focused strongly on near-“natural” basins, where proxies for flow behavior (whether climatic, geographic or geomorphic) could be used to form a space in which to extrapolate flows observed in gauged basins to those in the ungauged site (Blöschl, 2013). Extending these techniques to heavily managed catchments presents numerous challenges, including the identification of suitable proxies to define the effects of human intervention and non-stationarity of the water cycle (Thompson et al., 2013). Given the complexity of these managed systems, hydrological reconstruction can help identify the predominant processes that relate human water use and management with the hydrological response.

In south India, the presence of widely distributed surface rainwater harvesting structures known as tanks (Van Meter et al., 2014) creates an opportunity to employ remote sensing to enable such a reconstruction. The tanks are large enough to be detected from satellite images, and their direct connection to surface flow in the channel network means that they can be used as a proxy for surface flow generation. Because tanks integrate surface flow over the upstream catchment area, *in situ* measurements of tank water storage have been successfully used to calibrate and validate hydrological models in Andhra Pradesh (Perrin et al., 2012) and Tamil Nadu (Van Meter et al., 2016). Other studies in south India (Mialhe et al., 2008), the USA (Halabisky et al., 2016), Africa (Meigh, 1995; Liebe et al., 2005; Sawunyama et al., 2006; Liebe et al., 2009; Gardelle et al., 2010) and South America (Rodrigues et al., 2012) have used surface water bodies as aggregators of streamflow and indicators of hydrological change.

We employ remote sensing of tanks to reconstruct the history of hydrological change over four decades in the Arkavathy watershed near Bangalore, India, where the landscape has been intensively modified by humans for centuries. Concern about water scarcity in the Arkavathy watershed has grown with the loss of historical monsoon-season flow and reduced inflows to the TG Halli reservoir, which was the primary water supply reservoir for Bangalore between the 1930s and 1970s. These inflows have declined by nearly 80% since the late 1970s, a time period that also included groundwater depletion and loss of surface storage in tanks despite stationary precipitation (Srinivasan et al., 2015). Understanding of the change in water resources within the watershed is largely limited to local stakeholders (Lele et al., 2013) as records of streamflow are insufficient to describe the scope and heterogeneity of hydrological change in the watershed.

Agriculture in south India was historically sustained by a series of reservoirs known collectively as the “cascading irrigation tank system”, and nearly 1700 tanks have been constructed in the Arkavathy watershed. Tanks typically consist of a long, shallow dam bund constructed across a river to harvest surface runoff during the monsoon and supply irrigation water during the dry season. The bund impedes streamflow until the tank fills, overflows, and “cascades” into downstream tanks. Although the dam bunds remain in place, village-level water managers report that the tanks rarely fill up and overflow in large portions of the Arkavathy (ATREE et al., 2015), similar to other watersheds in south India (Janakarajan, 1993b; Gunnell and Krishnamurthy, 2003; Kumar et al., 2016).



Groundwater irrigation grew in popularity in India in the 1960s (Briscoe and Malik, 2006), supplanting tank irrigation in south India in the following decades (Janakarajan, 1993a), and is now the dominant source of irrigation water in the Arkavathy watershed. Increased water demand in the Arkavathy has been driven by a number of factors including intensification of agriculture, replacement of traditional crops with *Eucalyptus* plantations, and population growth and urbanization around the periphery of Bangalore, the road network, and other urban hubs. Additionally, thousands of in-stream check dams have been constructed in an attempt to augment groundwater recharge. These rapid changes occurring across 4000 km<sup>2</sup> of watershed area pose a challenge to understanding and managing emerging water scarcity issues.

Hydrological changes in the Arkavathy watershed should be apparent in historical satellite imagery, as the period of reported hydrological change in the Arkavathy (from the late 1970s onwards) co-incides with the start of Landsat image collection by Landsat satellites in 1972. We develop an automated approach for estimating surface water area in tanks in the Arkavathy watershed using Landsat imagery and apply this approach to reconstruct a timeseries of water extent in tanks from 1973 to 2010. We use this dataset to identify temporal trends in water extent, hypothesizing that such trends would be indicative of long-term hydrological changes induced by human activity. We conclude by comparing the temporal trends of streamflow with land use as a first attempt to identify competing influences of different land use practices on water resources throughout the Arkavathy watershed.

## 2 Methods

### 2.1 Study site

The Arkavathy watershed is located in the southeastern Indian state of Karnataka, west of the city of Bangalore (Fig. 1). It has a monsoonal climate, with the rainy season lasting from June to November, relatively stable daily maximum temperature of 27°C, and mean annual rainfall of 830 mm. Temperature peaks near the end of dry season in April around 34°C before pre-monsoon rainfall arrives sporadically in April and May. The river is gauged at TG Halli reservoir and upstream of Harobele reservoir (Fig. 1b).

The watershed contains a mix of urban, natural and agricultural land use. Agricultural land can be divided into rainfed grain crops, irrigated vegetable crops, *Eucalyptus* plantations, and other irrigated tree plantations (e.g., areca nut). Most present-day irrigation water in the Arkavathy is sourced from a deep, fractured rock aquifer. Irrigation from tanks is now significant in only a few locations, especially downstream of Bangalore, which imports water from the regional Cauvery river and returns some urban wastewater to the Arkavathy. Although many tanks are no longer in use, the tank structures remain intact and continue to capture surface water flows.

### 2.2 Remote-sensing images and supplementary data

Tracking water storage in the tanks at monthly or higher temporal resolution would be desirable, but is precluded because remotely sensed images from the monsoon season often contain large areas of cloud cover. This analysis therefore focuses



on post monsoon images from the months of December and January. The highly seasonal monsoonal climate in south India means that end-of-monsoon tank water storage can be attributed primarily to the magnitude of streamflow filling the tank during monsoon season, allowing tank water storage to be used as a proxy for cumulative streamflow, minus any evaporation, drainage or extraction losses. Although these losses do occur, they can be accounted for during subsequent trend analysis.

- 5 We selected 45 Landsat images, including 18 acceptable post-monsoon images from 1973 to 2010 for analyzing long-term hydrological trends (see Supplementary Material, Fig. S1 and Table S1 for dates). The 2014 Landsat imagery was used for remote-sensing validation and dry-season analysis, but was not included in the 1973–2010 study period. Most images were downloaded from Earth Explorer (earthexplorer.usgs.gov), except for images unavailable from USGS, which were purchased from the National Remote Sensing Centre (NRSC, nrsc.gov.in). An image from the Land Imagery Scan Sensor (LISS-IV)
- 10 were also purchased from NRSC and used for accuracy assessment. A shapefile of tank boundaries was obtained from the Karnataka State Remote Sensing Application Centre (KSRSAC) to aid in classification of water bodies. Other supplementary datasets were obtained from NASA Reverb (reverb.echo.nasa.gov) and Karnataka State Natural Disaster Monitoring Centre (KSNDMC) as listed in Table 1.

Dataset	Date	Resolution	Source
Landsat images	1973–2010 & 2014	30 m	USGS & NRSC
LISS IV image	2014	5 m	NRSC
Land use map	2001	-	KSRSAC
Tank boundaries	-	-	KSRSAC
Aster DEM	-	30 m	NASA Reverb
Daily Precipitation	1972–2010	0.69/100km <sup>2</sup>	KSNDMC

**Table 1.** Data sources.

- NRSC images were manually georeferenced using reference points from the higher-resolution LISS image, with root mean squared error (RMSE) less than 0.5 pixels in all images. All Landsat images were cropped to the extent of the Arkavathy watershed and converted to top-of-atmosphere (TOA) reflectance (Chander et al., 2009), which was used for training and classification of all images. Landsat 7 ETM+ scenes acquired after May 31, 2003 contained gaps due to a failure of the Scan Line Corrector (SLC) (Scaramuzza et al., 2005). Although gap-filling techniques for the SLC error generally use successive images to fill missing pixels (e.g., Chen et al., 2011), we used a single-image gap-filling approach because of the inherent
- 20 temporal variability of tank water extent. We used pixels along the edge of the gap to fill missing pixels similar to Catts et al. (1985) but instead of interpolation, which would cause spectral homogenization in missing pixels, we repeated edge pixels towards the center of the gaps using successive grayscale dilation.

- We used cloud-free images where possible, but in some years the only viable post-monsoon image contained some cloud cover. Cloud shadows were particularly troublesome because the spectral reflectance of land in a cloud shadow was often
- 25 similar to that of water. We applied the *fmask* algorithm (Zhu and Woodcock, 2012) to identify clouds and cloud shadows, making minor modifications to improve the method for the Bangalore region as follows: (i) we included the filters from the



automatic cloud cover assessment algorithm (ACCA, Irish, 2000) when determining the potential cloud pixels, which reduced false positives for clouds in urban areas, and (ii) we removed clouds whose height (determined with *fmask*) was an outlier, which was possible because the topography was relatively flat and the selected images contained only cumulus clouds which exhibit relatively consistent base height at the lifting condensation level (Craven et al., 2002). Outliers were determined as clouds with a height less than  $H_{25} - 1.5(H_{75} - H_{25})$  or greater than  $H_{75} + 1.5(H_{75} - H_{25})$  where  $H_{25}$  and  $H_{75}$  are the first and third quartiles of cloud height and  $H_{75} - H_{25}$  is the interquartile range. This procedure helped prevent erroneous classification of cold, white land pixels as clouds and limited the potential for erroneous classification of water bodies as shadows.

### 2.3 Classification method

The tank water classification method relied on separating pixels containing water from pixels containing land in a spatial region defined by the mapped tank boundaries. Water stored in tanks in the Arkavathy watershed varied from clear (with low reflectance in all Landsat reflectance bands) to turbid (more reflective in the visible (Moore, 1980) and NIR bands (Whitlock et al., 1981)). Turbid water exhibited its highest reflectance in the red band due to the red soils in the Arkavathy watershed (Novo et al., 1989) (see Figure 2).

Land cover surrounding wetted areas of tanks included vegetation, bare soil, and built-up urban land. We grouped these classes into a single land class, which was characterized by high reflectance in the NIR band and lower reflectance in visible bands (McFeeters, 1996). These characteristics primarily distinguish land from water in the Arkavathy, which has low reflectance in the NIR band and either low reflectance in the green band (clear water) or high reflectance in the red band (turbid water).

We developed an automated classification algorithm that distinguished areas of clear water and turbid water in each pixel from land, allowing rapid and consistent classification approach across images and Landsat sensors. We used a two-stage approach for estimating water extent in tanks. First, pixels having definitive spectral properties of water were identified and classified as “apparent” water pixels. Second, spectral unmixing was used to estimate the water fraction in all pixels within 60 m of any apparent water pixels. A conceptual representation of this algorithm is provided in Figure 3, and the steps described below are cross referenced to the numbered panels in the figure.

The only user input to the classification algorithm for each scene was to select a reservoir containing clear water with which to train the image (Fig. 3, step 1). The Normalized Difference Water Index by McFeeters (1996),  $NDWI = (green - NIR) / (green + NIR)$ , reveals a clear distinction between land and water pixels. In each image, we divided pixels within the training reservoir (or a rectangular window of pixels around the training reservoir if the reservoir was mostly full) into water or land classes using Otsu’s method (Otsu, 1979), which clusters grayscale pixels into two classes by minimizing the within-class variance. The water and land pixels at the training reservoir were used to calculate the spectral means of land pixels and clear water pixels (step 2). The minimum NDWI of water pixels at the training reservoir (step 3a) was used as a threshold to create a mask of apparent clear water for the entire scene (step 3b) which was then dilated using a 5x5 square kernel (a 3x3 kernel for MSS scenes). All pixels within the dilated mask were transformed to a single component,  $\hat{x}$ , parallel to the transect between the spectral means of clear water and land in the 2-dimensional space of NIR and green reflectance (step 3c). Pixels falling



between the  $\hat{x}$  means of clear water and land were assigned a clear water fraction. Clear water fraction was set to 1 in pixels at or below the clear water  $\hat{x}$  mean, and linearly decreased to 0 for pixels at or above the land  $\hat{x}$  mean.

A similar procedure of masking, dilating, and unmixing was performed for turbid water, with minor changes. The criteria for apparent turbid water pixels were determined from land pixels near the training reservoir as the 98th percentile of red reflectance and the 98th percentile of NDWI (step 4a), provided that red reflectance was greater than NIR reflectance. Pixels meeting these criteria were included in the turbid water mask and dilated to include the surrounding area (step 4b). Spectral unmixing was conducted similarly to clear water, except the component for unmixing,  $\hat{y}$ , was taken along the transect between the spectral means of turbid water and land in the NIR-red space (step 4c). Finally, the water area in each pixel was taken as the higher value of clear water area and turbid water area (step 5). Tank water extent was calculated as the sum of water area of all pixels within two pixels of the mapped tank boundary (step 6).

We did not estimate the area of water in any tank that was flagged for the following quality concern criteria: (i) spatial overlap or adjacency of dry tank boundary or wetted tank area with clouds or cloud shadows, (ii) spatial overlap of greater than 25% of dry or wet tank area with missing pixels due to the SLC error in Landsat 7 images, or (iii) greater than 25% spatial overlap of dry or wet tank area with the edge of the scene from MSS images (step 7). In each of these cases, the tank area was recorded as “NA”.

Remote sensing and spatial processing were scripted in R (R Core Team, 2016) using the raster (Hijmans, 2015), rgeos (Bivand and Rundel, 2016), sp (Pebesma and Bivand, 2005), and rgdal (Bivand et al., 2016) packages, as well as ggplot (Wickham, 2009) for plotting. Watershed delineation and extraction of the cascading tank network were completed in GRASS GIS (GRASS Development Team, 2016).

## 2.4 Validation of classification method

To validate the classification results, we used a 5 m resolution LISS IV satellite image from 26 February 2014 to compare with a classified Landsat image from 27 February 2014. The LISS IV image was classified in ENVI software (Harris Geospatial Solutions Inc.) using support vector machine (SVM) classification with four land classes and four water classes. After classification, the water classes were merged into a single water class and resampled to the resolution of Landsat so that the resulting grayscale classification contained a water fraction in the range [0,1] for each pixel.

We compared the Landsat results with the results from the reference (LISS) classification at the pixel scale and tank scale, ignoring tanks in which there were obvious differences due to the incongruous image capture dates (e.g., cloud cover). At the pixel level, a traditional confusion matrix is inappropriate for continuous classification data (Congalton and Green, 2009). Thus, we evaluated the error (Landsat water fraction minus reference water fraction) in all pixels within tanks by binning the pixel error into categories representing under-classified (-1 to -0.2), correct (-0.2 to 0.2) and over-classified (0.2 to 1). We further separated pixels into groups by binning the producer (reference) water fraction and user (Landsat) water fraction. We calculated producer's and user's accuracy for each water fraction bin to form both a producer error matrix and consumer error matrix (see Sect. 3.1).





## 2.5 Statistical model for long-term hydrological change

We used a statistical modeling approach to identify long-term trends in water extent in tanks that could not be explained by readily available hydrological covariates (e.g., precipitation). We account for the effect of such explanatory variables in the model and posit that the remaining temporal trend in surface water extent indicates long-term hydrological changes induced by human activity. In the model, we exclude reservoirs, which are more likely to release water to users or downstream, and complicate the relationship between streamflow and reservoir water storage.

Because the timeseries for individual tanks were relatively short and contained many dry tanks, the dependent variable in the model was a spatially aggregated measure of water area in all tanks within a “tank cluster”. We divided the watershed into 8 subwatersheds, which were further subdivided into hydrologically-connected tank clusters. Each cluster contained at least 15 tanks having non-zero water extent in at least 4 post-monsoon images. Tank clusters within each subwatershed were assumed to function as hydrologically similar units, with the only difference being the temporal trend in water extent over time.

Some tanks were constructed during the study period and were manually identified by examining the classification results of the largest 10 tanks in each cluster and verified using topographical maps from the 1970s. For these “new” tanks, we removed the tank (set the water extent to NA) in all scenes prior to the construction of the tank, unless there was a downstream tank within the same cluster, in which case the original classification (no water) was retained.

In an exploratory analysis we found that total surface water extent across the whole Arkavathy watershed was most strongly related to precipitation metrics computed from September 1, the approximate onset of the northeast monsoon, to the date of Landsat image acquisition. We anticipated that tank storage would respond to total seasonal precipitation, but also to the quantity of precipitation delivered in large events, which are more prone to generating runoff. The model thus incorporated total precipitation depth ( $P_{total}$ ) and the average depth ( $P_{extreme}$ ) of large storms ( $>10$  mm/day) as explanatory variables.

For each post-monsoon Landsat scene, we calculated these metrics at up to 62 rain gauges reporting daily rainfall, omitting gauges in which the period of record excluded the monsoon year for the Landsat image. We spatially interpolated the rainfall metrics throughout the entire watershed using the inverse distance squared method, and calculated the spatial average for each tank cluster.

We exclusively used images that were taken early in the dry season (December or January), but we anticipated that there would be a relationship between the time that the image was taken and the wetted tank area, due to evaporative and drainage losses of water from the tanks. We incorporated a linear loss term ( $L$ ) using dry season days as a covariate in the model, approximated as the number of days after December 1. To check the suitability of this assumption, we classified an additional 27 dry season Landsat images, and estimated the rate of decline of tank cluster water extent for each year with at least two dry season images via linear regression. The nonparametric Mann–Kendall test was used to determine if there had been a change in dry season water losses over time, and showed that in only two subwatersheds, the Hesaraghatta and TG Halli, the trends were significantly different from zero (i.e., the 95% bootstrap confidence intervals of the Mann–Kendall statistic excluded zero). Presumably the trend in these two subwatersheds relates to the shift from tank irrigation to groundwater irrigation during the study period.



To understand the effects of carryover storage in tanks between years we developed a timeseries of tank water extent throughout the dry season of 2014 (chosen largely for image availability through the dry season). We confirmed that at the start of the 2014 monsoon, half of the tank clusters contained  $\leq 25\%$  of 2013 post-monsoon storage. More than 75% of tank clusters contained  $\leq 50\%$  of 2013 post-monsoon storage. Tank clusters with the highest carryover storage were found in urban  
 5 subwatersheds or hilly sub watersheds at the southern part of the Arkavathy watershed.

We used a multivariate regression with interactions between continuous covariates and categorical variables (e.g., see Jaccard et al., 1990; Cohen et al., 2003) to estimate temporal trends in the different regions throughout the Arkavathy watershed. The covariates total precipitation, extreme precipitation, and tank water loss were modeled as fixed effects which interact with the subcatchments. In other words, the response of the stored water area to these variables was allowed to vary for each  
 10 subcatchment, but was assumed to be consistent for the tank clusters within the subcatchment. The model can be written as the following:

$$A_{ij} = C_0 + C_{1,k}P_{total,ij} + C_{2,k}P_{extreme,ij} + C_{3,k}L_i + B_{1,j}Year_i + e_{ij} \quad (1)$$

The subscripts refer to the Landsat scene ( $i$ ), tank clusters ( $j$ ), and subcatchments ( $k$ ). Other than the intercept ( $C_0$ ), the fixed effects differ for each subcatchment ( $C_{1,k}$ ,  $C_{2,k}$ , and  $C_{3,k}$ ) or tank cluster ( $B_{1,j}$ ). The errors for each observation are included  
 15 as  $e_{ij}$ . The dependent variable ( $A_{ij}$ ) is the normalized cluster area, where the cluster water extent of the scene is divided by the total maximum water extent of all tanks that were not removed from the scene. As a quality control measure, this area was set to NA for a given cluster and scene if more than 30% of the total tank area in the cluster was removed, either in classification (due to clouds or missing Landsat pixels) or in the assessment of tanks constructed during the study period. All covariates were centered before input into the model. The primary result of interest is the value of the time trend for each cluster,  $B_{1,j}$ , which  
 20 we use to infer hydrological change throughout the watershed.

### 3 Results

#### 3.1 Accuracy assessment

The Landsat classification performed best for pixels that were fully dry or wet, when compared with the reference (LISS) classification in producer and consumer error matrices (Figure 4a). Producer accuracy was 84% for wet pixels and 99% for  
 25 dry pixels, and because of the high number of dry pixels the overall accuracy was 98%. Pixels containing a mix of water and land (20–80% water) had lower producer accuracy (41–82%). Because these pixels lie at the boundary of the wetted tank area, classification error would be sensitive to geo-registration error in one or both of the images. Error could also arise from our specification that water pixels must lie within 60 m of clearly identifiable water bodies, or the assumptions made during spectral unmixing. Although the classification scheme accounted for only two classes, the spectral properties of the land class varied  
 30 among dry soil, wet soil, sparse vegetation, and irrigated agriculture. Classification of water was complicated by vegetation in tanks, varying degrees of turbidity, and algae blooms in tanks with considerable wastewater inflow. Overall, the classification





errors were unbiased and the histogram of classification errors (excluding pixels with zero error) was approximately normally distributed (Figure 4b).

The Landsat classification agreed well with the reference classification at the tank scale, and accuracy improved with increasing tank size. A regression of Landsat extent versus reference extent (Figure 5) for tanks less than 25 hectares (27.8 pixels) had a slope of 0.98 and coefficient of determination ( $R^2$ ) of 0.95. When all tanks and reservoirs were included, the regression line had a slope of 1.02 and coefficient of determination of 0.99. Over 99% of dry tanks were correctly classified as dry, but error was considerably large for small tanks with non-zero water extent less than 2.5 ha (2.8 pixels), due to false positives in the reference classification as well as errors the Landsat classification. For tanks between 2.5 and 10 ha the classification performed considerably better. The mean absolute error increased as the extent of the water body increased, but mean percent error decreased with water body size.

Although the time-trends in most tanks have not been reported as ground data, trends in water storage over time are widely known for some of the major reservoirs. We confirmed that the remote sensing analysis qualitatively reproduced trends for these reservoirs (Figure 6). The TG Halli and Hesaraghatta reservoirs declined from a peak storage in the 1970s to much lower contemporary storage. Large increases in water extent were observed in Manchanabele reservoir, which was constructed in 1993, and Harobebe reservoir which was constructed in 2004. We excluded Byramangala reservoir, which receives wastewater effluent from Bangalore and where the observed water extent was not reliable because it was strongly influenced by the size of algae blooms.

### 3.2 Long-term trends in surface water

The multivariate analysis yielded negative and positive values of  $B_{1,j}$  (Table S2) revealing drying and wetting in different parts of the Arkavathy watershed, with statistically significant trends in 13 tank clusters (Figure 7). In the three subwatersheds upstream of TG Halli reservoir, most tank clusters showed a drying trend. Tanks within Bangalore generally exhibited drying trends, and tanks at the city periphery and immediately downstream were wetting. Other regions of the watershed exhibited mixed results in the percent change in water extent, but none of the trends were statistically significant.

The model explained nearly 70% of the variation in tank cluster water extent ( $R^2=0.68$ ). The effects (slopes) of both precipitation covariates were significant (the 95% confidence interval of the slope of the temporal trend excluded zero) in nearly all subwatersheds, and the effect of dry-season water loss was significant in the two northernmost subwatersheds.

## 4 Discussion

### 4.1 Long-term hydrological changes

Our analysis confirms that tank water extent at the end of the monsoon season can be primarily attributed to the storage of monsoon season streamflow. Because tanks in the Arkavathy watershed rarely overflow today and there is little carry-over storage year to year, the volume of water in tanks provides an integrated measure of hydrological processes from the previous



wet season. The spatial scales of tank clusters are comparable with that of land use, and we can make associations between the observed hydrological change and human drivers of change.

We hypothesized that the divergent trends in stored water extent through space could be attributed (at least in part) to differences in the dominant land uses in the tank catchments. All the tank clusters with a large decreasing trend contain a high percentage of agriculture (Figure 8). Mann–Kendall analysis confirms that an increase in agricultural land use fraction is significantly related to a decrease in tank water storage over time across the tank clusters. Conversely, increasing the proportion natural lands increased the tank water storage over time, and the relationship between urban land use and tank water trends was indiscriminate.

These associations offer insights into the potential drivers of hydrological change. Agricultural regions in the northern part of the watershed are associated with heavy groundwater use, expansion of plantation agriculture, and watershed development programs intended to increase groundwater recharge (Srinivasan et al., 2015). These trends in land use and water management are consistent with reductions in runoff generation due to depleted subsurface stores, and reductions in channel flow due to network fragmentation by check dams and rainwater harvesting landscape features such as field bunds.

The changes within and downstream of urban areas are likely to be mixed, consistent with our failure to find a meaningful relationship between changing tank water extent and urban areas. Tanks may be encroached upon as residential areas expand and additional wastewater can lead to expansion of algae blooms covering the water surface, both of which can appear as "drying" of the tank. Urbanization can also have a "wetting" effect on tanks, due to increases in impervious surfaces or even the fallowing of agricultural land in anticipation of urbanization. There is also a non-local effect in that increased urban water use produces increased urban effluent, which is discharged to the surface channel network and may contribute to increases in tank water storage downstream. For instance, increased wastewater from Bangalore has led to additional inflows to Byramangala reservoir and more irrigated agriculture directly downstream.

The observed increases in surface water storage in areas with more natural land cover in the southern part of the watershed were unexpected, and we make two initial observations. First, the temporal trend was not significant in any of the individual tank clusters, and the association between natural land and hydrological change may not be as strong as those associated with agriculture and upstream urbanization. Second, a number of tanks were constructed in this region during the study period, indicating that there were previously unused water resources that were then captured. Given that we observe changes in water infrastructure, there may have been important dynamics associated with land use change that we miss by focusing on land use from a single date.

## 4.2 Assessing the classification and model uncertainty

The classification of small tanks in the Arkavathy watershed poses challenges associated with harmonization of different Landsat sensors and the variability in the spectral properties of "wet" tanks due to variations in water quality and vegetation extent. Given these requirements, the automated algorithm performs well. The classification tends to overestimate the amount of water in dry pixels and underestimate the amount of water in wet and mixed pixels. Because our classification scheme is



designed to avoid bias between images taken with different Landsat sensors, we likely sacrifice some precision with sensors from Landsat missions 5–8.

Errors at the pixel and tank scales are likely unavoidable given the spectral heterogeneity of both land and water pixels. In particular, tanks containing water of variable turbidity, excessive vegetation, or algae blooms are prone to classification errors.

5 Because pixel-scale errors are unbiased, accuracy at the tank scale improves as tank size increases. Error is further mitigated by grouping tanks into clusters in the statistical model. Alternative classification methods incorporating additional land cover classes (e.g., Halabisky et al., 2016; Mialhe et al., 2008) could be used to further reduce classification error, but would require additional methods development to automate classification and perform spectral unmixing consistently across Landsat sensors.

10 The uncertainty of the classification ( $R^2=0.99$  when all water bodies are included) is small compared with the uncertainty of the statistical model ( $R^2=0.68$ ). Although the results of our statistical model imply a non-trivial amount of unexplained variation, Gardelle et al. (2010) reported similar performance ( $R^2=0.78$ ) for a model relating precipitation and water extent in a single lake, and noted that the correlation was valid only for a nine-year subset of the five-decade study period. The sources of uncertainty include the complex hydrological processes that relate precipitation, streamflow, and tank water storage, as well as the nonlinear and heterogeneous relationship between water extent and water storage. The results of our analysis are reasonable  
 15 given the simplicity of the model and the complexity and heterogeneity of the watershed hydrological response.

## 5 Conclusions

The Arkavathy watershed embodies many of the water security challenges confronting southern India. With data limitations hampering the characterization of changing water supplies in the basin, remote sensing tools provide insights into the history and spatial pattern of change in water availability. We were able to take advantage of a pre-existing "sensing network" provided  
 20 by the irrigation tank system throughout the Arkavathy watershed. The high number of tanks in this watershed allowed for a comparison of hydrological change with land use at spatial scales appropriate for a first-order analysis.

The analysis reveals that changes in surface water resources are not spatially homogeneous, but vary in their magnitude and sign among different regions of the basin. These differences appear to be associated with differing patterns of land use across the basin. Further investigation could explore the effects of *changing* land use over time and, for example, agricultural water  
 25 management practices on the watershed-scale outcomes.

Surface networks of rainwater harvesting structures are employed in seasonal climates worldwide, whether in cascading tank systems in southern India and Sri Lanka, or hillslope farm dams in Australia (Callow and Smettem, 2009; Roohi and Webb, 2012), North-East Brazil (Lima Neto et al., 2011; Malveira et al., 2012; de Araújo and Medeiros, 2013; de Toledo et al., 2014), South Africa (Hughes and Mantel, 2010), the US Great Plains (Womack et al., 2012) and China (Xiankun, 2014; Xu et al.,  
 30 2013). Capitalizing on these networks as proxy indicators of rainfall and streamflow variation, as in the Arkavathy, could prove a valuable approach to circumventing problems of data scarcity and characterizing changing hydrological conditions.



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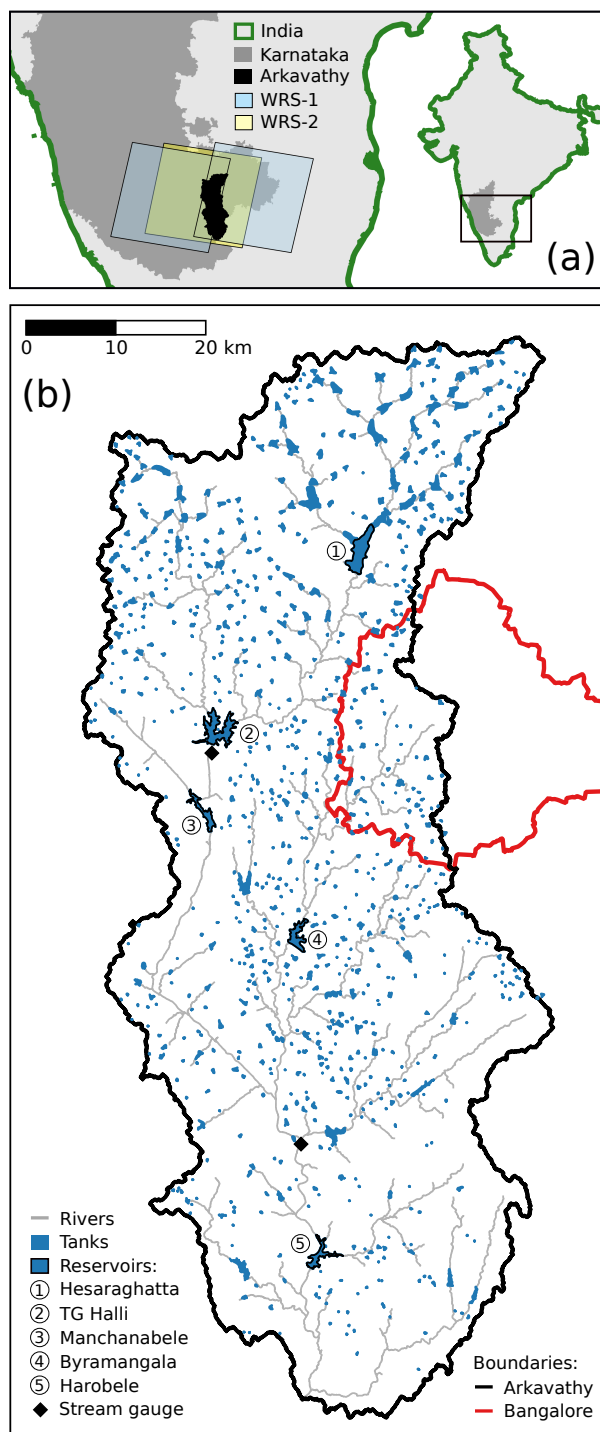
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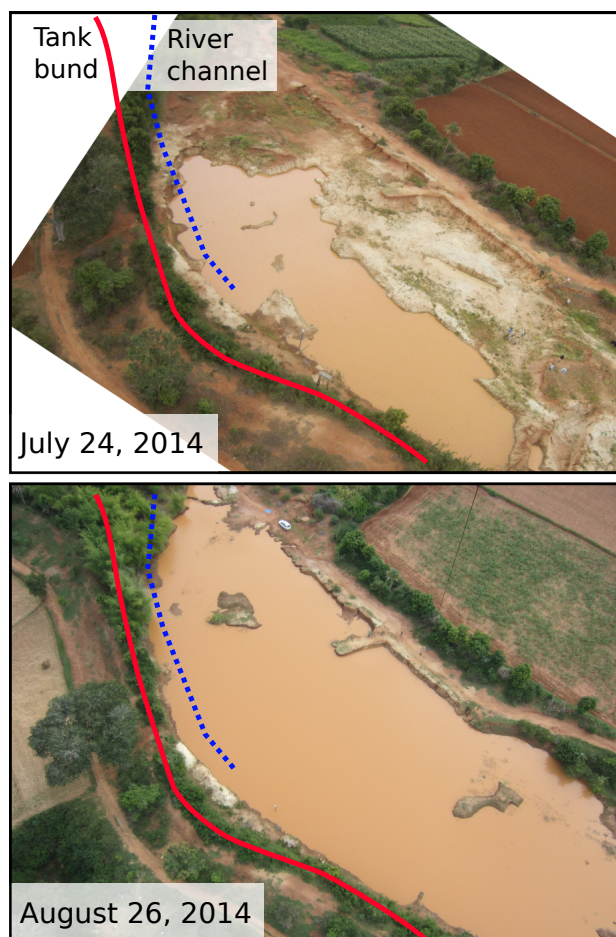
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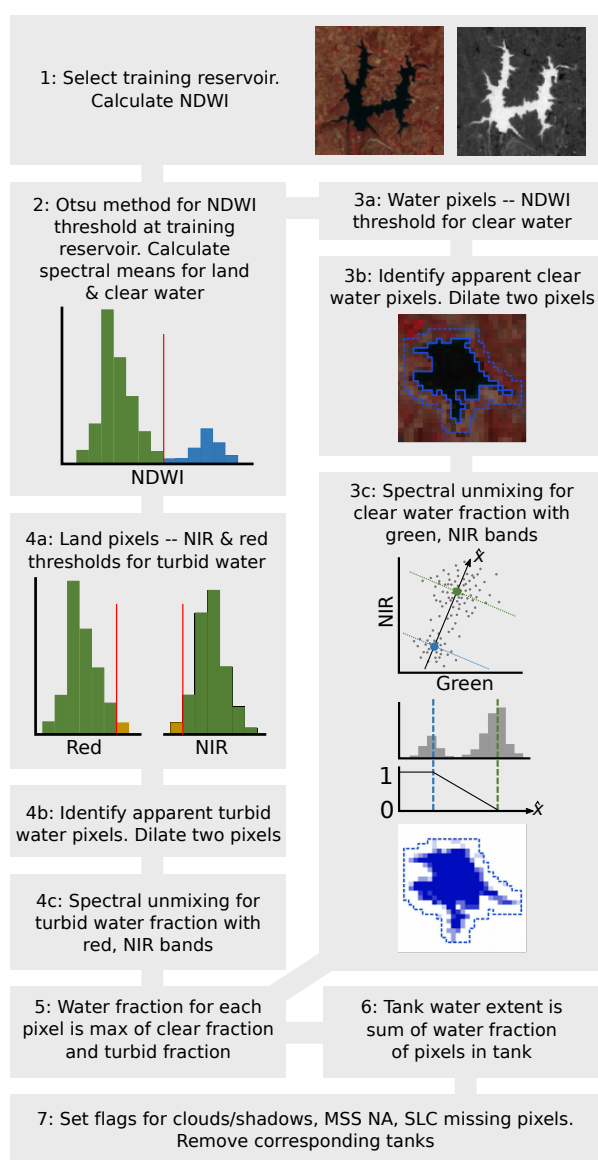
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**Figure 1.** Site map. (a) Location of the Arkavathy watershed within the state of Karnataka, India, and scene boundaries for Landsat 1–3 (WRS-1) and Landsat 4–8 (WRS-2). (b) Map of the watershed including tanks, reservoirs, river network, and municipal boundary of Bangalore. Lower-order streams and a number of small, generally dry tanks are excluded.

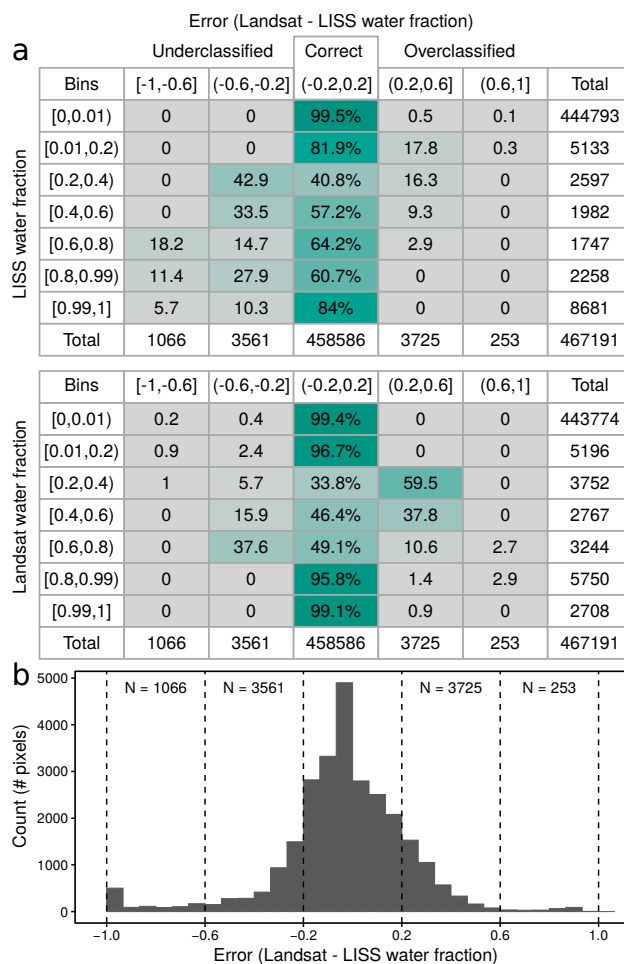


**Figure 2.** Aerial photos of a small tank containing turbid water in the Arkavathy watershed before and after runoff events in August 2014. The tank receives water from the channel and directly from adjacent agricultural plots, and water extent increases with storage.

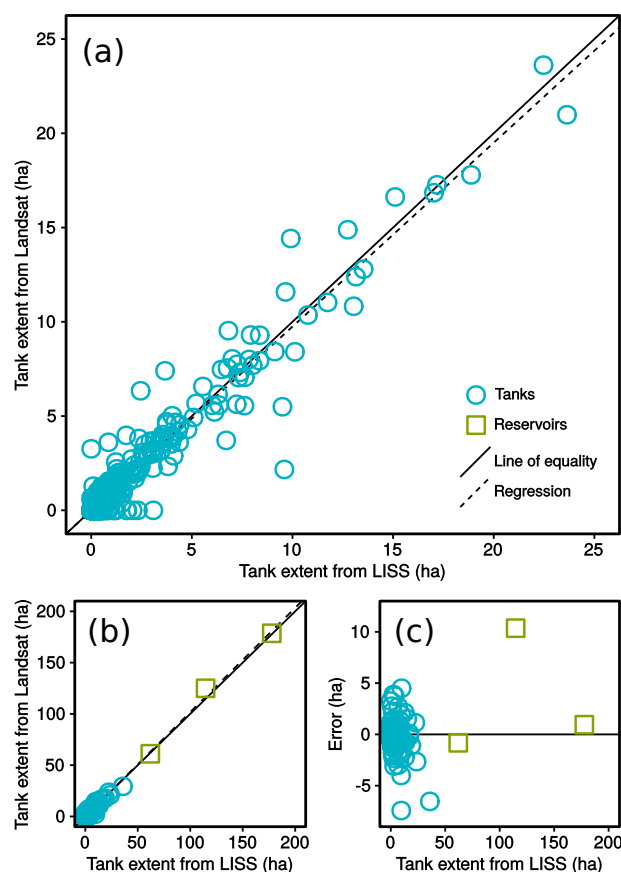


**Figure 3.** Flowchart of classification method. In Steps 3 and 4, clear water fraction and turbid water fraction are each calculated for all pixels in the image before they are combined into water fraction in Step 5. Color images are from Landsat, with red, green, and blue in the image corresponding to NIR, Red, and Green bands from Landsat TM.

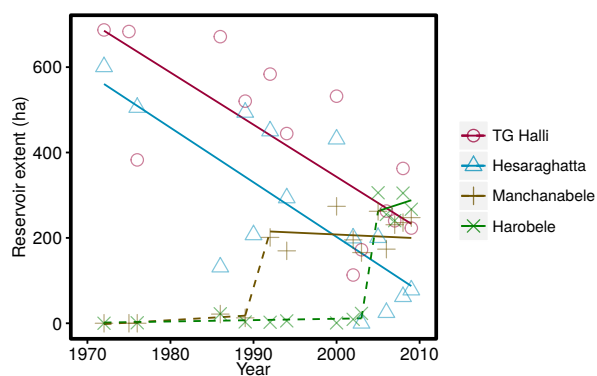




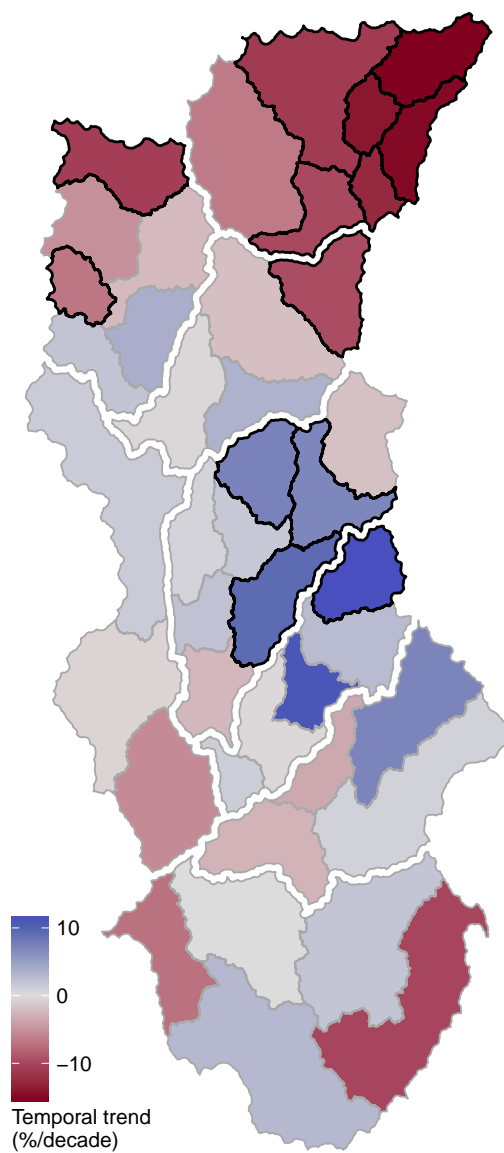
**Figure 4.** (a) Pixel-level producer and consumer accuracy tables, given by percent of pixels within a given error bin. Pixels are grouped into rows by the producer or consumer water fraction and then binned into columns by the error (Landsat - LISS water fraction). The center column shows the percentage of pixels that were correctly classified, with error between -0.2 and 0.2. (b) Histogram of non-zero classification errors (excluding pixels where the error was zero).



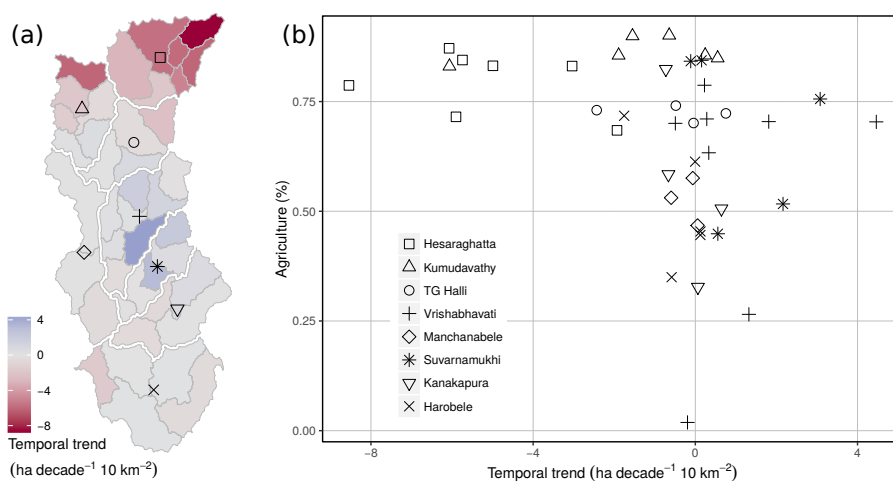
**Figure 5.** Comparison of Landsat and reference (LISS) classification from February 2014 images. (a) Water extent in tanks less than 25 ha. (b) Water extent in all tanks and reservoirs. (c) Error in the Landsat classification for tanks and reservoirs. Relative error decreases with increasing tank size. Only three of the five reservoirs are included because the LISS image excluded the Harobele reservoir and there was considerable change in an algae bloom in the Byramangala reservoir in the time between the acquisition of the LISS and Landsat images.



**Figure 6.** Water extent in reservoirs with best fit trend lines. TG Halli and Hesaraghatta reservoirs decreased over time. Manchanabele reservoir was constructed in 1993, and Harobebe Reservoir was constructed in 2004.



**Figure 7.** Relative trends in cluster water extent, 1973–2010, given as a percent change per decade relative to the maximum extent of each cluster. White space indicates subwatershed boundaries, and black lines indicate statistical significance of the cluster trend.



**Figure 8.** (a) Map of absolute trends in cluster water extent and (b) Agricultural land use percentage versus absolute trend in water extent for each cluster, with symbols corresponding to the subwatershed. Agriculture is associated with decreasing water extent.