1	An integrated probabilistic assessment to analyze stochasticity
2	of soil erosion in different restoration vegetation
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Stochasticity of soil erosion reflects the variability of soil hydrological response to 24 25 precipitation under complex environment. Assessing this stochasticity is important to conserve soil and water resources, however stochasticity of erosion event in restoration 26 vegetation types in water-limited environment is less investigated. In this study, we 27 constructed an event-driven framework to quantify the stochasticity of runoff and 28 sediment generation in three typical restoration vegetation types (Armeniaca sibirica 29 (T1), Spiraea pubescens (T2), and Artemisia copria (T3)) at closed runoff plot over five 30 31 rainy seasons in the Loess Plateau of China. The results indicated that, under the same rainfall condition, the average probabilities of runoff and sediment in T1 (3.8% and 32 1.6%) and T3 (5.6% and 4.4%) were lowest and highest, respectively. The Binomial 33 34 and Poisson probabilistic model were two effective ways to simulate the frequencies distribution of times of erosion events occurring in all restoration vegetation. The Bayes 35 model indicated that relative longer duration and stronger intensity rainfall events 36 37 respectively become the main probabilistic contributors of one stochastic erosion event occurring in T1 and T3. Logistic regression modeling highlighted that the higher-grade 38 rainfall intensity and canopy structure were as two most important factors to 39 respectively improve and restrain the probability of stochastic erosion generation in all 40 restoration vegetation types. Bayes, Binomial, Poisson and logistic regression models 41 constituted an integrated probabilistic assessment to systematically simulate and 42 43 evaluate soil erosion stochasticity. It may be an innovative and important complement in understanding of soil erosion from stochasticity view, and also provide an alternative 44

45	to assess the efficacy of ecological restoration on conserving soil and water resource in
46	a semi-arid environment.
47	
48	Key words: stochasticity of soil erosion, Binomial and Poisson, logistic regression
49	model, restoration vegetation,
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67 **1. Introduction**

Soil erosion is one of globe environmental problems. In the recent centuries, the erosion 68 69 rate over worldwide has been accelerating by the climate change and anthropogenic activities, causing soil deterioration and terrestrial ecosystem degradation (Jiao et al., 70 1999; Marques et al., 2008; Fu et al., 2011; Portenga and Bierman, 2011). The 71 uncertainty and intensity of soil erosion constitute the main feature of erosive 72 phenomenon. Although many studies have been concentrating on the intensity of 73 erosion under different spatiotemporal scales (Cant ón et al., 2011; Puigdef ábregas et al., 74 75 1999), the uncertainty of soil erosion generation is another challenge of researchers expecting to improve the accuracy of erosion prediction. To some extent, the 76 stochasticity of environment and spatiotemporal heterogeneity of soil loss mainly 77 78 affected the randomness of runoff production and sediment transportation in natural conditions (Kim. J et al., 2016). Meanwhile, the complex mechanism of erosion 79 generation also increased the uncertainty and variation of erosion processes (Sidorchuk, 80 81 2005, 2009). Therefore, how to effectively describe the erosive stochasticity and to reasonably assess its impacting factors is necessary and important for understating soil 82 erosion science from the perspective of randomness. 83

First, the combination of various probabilistic, conceptual and physical models have been reported as different integrated approaches to describe the stochasticity of soil erosion intensity (Table 1). As one form of erosion intensity, the runoff processes was proved as a stochastic process by different mathematic simulation models. Some studies (Moore, 2007; Janzen and McDonnell, 2015) have also simulated the stochastic

processes, and further quantified the randomness of runoff production and its 89 connectivity dynamics in hillslope and catchment scales by using different probabilistic 90 91 distribution functions and conceptual models. In these studies, the theory-driven conceptual models simplified main hydrological behaviors related to runoff production, 92 highlighting the stochastic effects of infiltration and precipitation on runoff processes. 93 Based on above precondition, the data-driven probabilistic models further simulated the 94 stochastic runoff production by mapping or calibrating the difference between observed 95 and predicted probabilistic values. As a results, the stochastic-conceptual approaches 96 97 have formed an effective framework to model the rainfall-runoff processes (Freeze, 1980), as well as to assess flood forecasting (Yazdi et al., 2013) 98

The stochasticity of soil erosion rate which is another pattern of erosion intensity was 99 100 generally investigated by probabilistic and physical models in some studies. The theory-driven physical models in these studies (Sidorchuk, 2005) integrated 101 hydrological and mechanical mechanism of overflow and soil structure with sediment 102 103 transpiration processes, stressing the stochastic effect of physical principles on erosion rate in different spatial scales (Table 1). Especially Sidorchuk in 2005 further introduced 104 stochastic variables and parameters into probabilistic models by randomizing the 105 physical properties of overflow and soil structure. This approach developed the 106 understanding of uncertainty of sediment transpiration processes, leading the 107 randomness simulation to be better fit the reality of stochastic erosion rate (Sidorchuk, 108 109 2009). Additionally, the stochasticity of soil erosion rate also reflected the erosion risk which was assessed by the integration of theory-driven empirical model with 110

geostatistics (Jiang et al., 2012; Wang et al., 2002; Kim. J et al., 2016). Erosion risk 111 analysis generally concentrated on the uncertainty or variability of soil erosion rate in 112 catchment and regional scales. It highlighted the impact of the spatiotemporal 113 heterogeneous rainfall and other environment conditions on the stochastic erosion rate. 114 In a word, these probabilistic and physical models constituted a systematical analysis 115 framework which closely related to the principle of water balance and basic 116 hydrological assumptions. It effectively described the randomness of soil erosion rate 117 affected by complex hydrological processes (Bhunya et al., 2007). However, few 118 119 studies has been made to analyze the stochasticity of soil erosion events. Especially, there are little effort to systematically investigate how the signal of stochastic rainfall 120 is transmitted to erosion event occurring in different restoration vegetation types based 121 122 on observational data rather than on other model assumptions. In fact, this event-based investigation deriving from specific experiment results probably have more practical 123 meaning for understanding the stochastic interaction between rainfall and erosion 124 125 events.

Secondly, the probabilistic approaches have also been reported as a crucial tool to describe the stochasticity of factors affecting soil erosion rate (Table 1). The randomness of soil water content (Ridolfi et al., 2003), antecedent soil moisture (Castillo et al., 2003), infiltration rate (Wang, P and Tartakovsky 2011) and soil erodibility (Wang et al., 2001) in heterogeneous soil types were all modelled by different probability distribution functions. These stochasticity of soil hydrological characteristics related to erosion rate mainly acted as various roles on impacting the

spatiotemporal distribution of erosion rate especially generating in regional or even 133 larger spatial scales. Meanwhile, as the main driving force of soil erosion generation, 134 the uncertainty of rainfall event, to some extent, represents the environment 135 stochasticity (Andres-Domenech et al., 2010). Eagleson in 1978 applied probabilistic-136 trait models to characterize the stochasticity of rainfall event by using Poisson and 137 Gamma probability distribution functions. The stochastic rainfall distribution in 138 different spatiotemporal scales has also been applied to examine the effect of runoff and 139 sediment yield (Lopes, 1996), to calibrate the runoff-flood hydrological model 140 141 (Haberlandt and Radtke, 2014), as well as to evaluate the sewer overflow in urban catchment (Andres-Domenech et al., 2010). 142

It has been well recognized the role of spatial distribution of vegetation in controlling 143 the soil erosion rate under different spatiotemporal scales (Wischmeier and Smith, 1978; 144 Puigdefabregas, 2005). How the plants reduce soil erosion rate was also illuminated 145 and interpreted by various physical and empirical models (Liu, 2001; Mallick et al., 146 2014; Prasannakumar et al., 2011). In theory, Puigdef & bregas in 2005 proposed 147 Vegetation-Driven-Spatial-Heterogeneity (VDSH) to explain the relationship between 148 vegetation patterns and erosion fluxes, which improves the understanding of 149 hydrological function of plant on erosion processes. Moreover, Trigger-Transfer-150 Reserve-Pulse (TTRP) framework proposed by Ludwig in 2005, systematically 151 explored the responses and feedback between vegetation patches and runoff-erosion 152 during whole ecohydrological processes. Theoretically, the stochastic signals of 153 different rainfall events could also be disturbed by the hydrological function of plant, 154

which finally affects the randomness of runoff and sediment events occurring in various 155 vegetation types. However, little effort has been made to explore the effect of different 156 vegetation types on the stochasticity of corresponding soil erosion events. In particular, 157 less approaches have been used to analyze how the properties of rainfall, soil and 158 vegetation impact on the stochastic erosion events through event-based investigation 159 deriving from observational data rather than on theory-based models. Actually, logistic 160 regression modeling (LRM) probably deal with above problems. LRM evaluates the 161 causal effects of categorical variables on dependent variables, and quantifies the 162 163 probabilistic contribution of influencing factors on the randomness of responsive random events in terms of odds ratio (Hosmer et al., 2013). It could be regarded as 164 another probabilistic model to explore the probability-attribution of influencing factors. 165 166 However, little literature is available on making LRM to explore the probabilistic attributing of stochastic erosion events under complex environmental conditions. 167 In this study, we hypothesized that the uncertainty of erosive events was also an 168 169 important property of soil erosion phenomenon, and monitored erosion events generating in three typical restoration vegetation types in runoff plots scale over 170 consecutive five years' rainy seasons. We aim to (1) comprehensively describe the 171

stochasticity of runoff and sediment events in details by using probability theory, and (2) to systematically evaluate the effect of the properties of soil, plant and rainfall on the stochastic erosion events by employing LRM approach. The probabilistic description-attribution approach could constitute an integrated probabilistic assessment based on event-driven probability theory and data-drive experimental observation.

177	Meanwhile, the investigation of stochastic soil erosion events by the integrated
178	assessment may be an innovative and important complement in understanding of soil
179	erosion from stochasticity view, but also could provide an alternative to assess the
180	efficacy of ecological restoration on conserving soil and water resource in a semi-arid
181	environment.
182	
183	Table 1
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185 2. Method
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186 **2.1 Definition and classification of random events**

Each observed stochastic weather condition with different durations in field monitoring 187 188 period was defined as a random experiment. All possible outcomes of a random experiment constituted a sample space (Ω) defined as a random observational event 189 (short for O event). Two mutually exclusive random event types—random rainfall event 190 191 (short for I event) and random non-rainfall event (short for C event)-constituted the O event. Precipitation is a necessary condition of runoff generation, and the random runoff 192 production event (short for R event) is a subset of I event. Similarly, R event is also a 193 necessary condition of random sediment migration event (short for S event), which lead 194 to S event be a subset of R event. As a result, O, C, I, R, and S events constituted a 195 random events framework (OCIRS) to reflect the stochasticity of environment in which 196 soil erosion events generation. 197

198 The random event duration in OCIRS is an important property of stochastic weather

conditions. In particular, the duration property of I event was closely related to the 199 transmission of stochastic signals of rainfall into the R and S events. According to the 200 201 rainfall duration patterns in China (Wei et al., 2007), the time interval between two adjacent individual I events is set to be more than 6 hours, forming the criteria for 202 individual rainfall classification. Meanwhile, based on the observation of random 203 events over five consecutive rainy seasons, we summarized duration property of all I 204 events and further classified them into four mutually exclusive I event types. They were 205 a random extreme long rainfall event type (short for Ie event), a random general long 206 207 duration rainfall event type (short for Il event), a random spanning rainfall event type (short for Is event) whose duration spans two consecutive days, and a random within 208 rainfall event type (short for Iw event) generated in a day. Additionally, the C event can 209 210 also be divided into two types at daily scale. They are random non-rainfall event type lasting a whole day (short for Cd event), and random non-rainfall event type whose 211 duration is less than 24 hours (short for Ch event) which is interrupted by I event. 212

Table 2 indicated the physical, probabilistic properties and implications of all random event types in OCIRS. The classification process of all random event types was sketched by figure 1a, the Venn diagram of all random event types in OCIRS was showed in figure 1c. Considering the observed longest duration of Ie event approximating 72 hours, in figure 1b, we summarized a series of random event sequences in terms of different combing patterns of I and C events in every three consecutive days during the whole monitoring period.

220

- 221 Figure 1
- 222

Table 2

- 223
- 224

225 **2.2 Probabilistic description of erosion event**

226 **2.2.1 Conditional probability of erosion event**

In the sample space Ω , for any random event type *E* in OCIRS, we defined *P*(*E*) as the proportion of time that *E* occurs in terms of relative frequency:

229
$$P(E) = \lim_{n \to \infty} \frac{n(E)}{n} = p_E, \ p_E \in [0,1]$$
 (1)

Theoretically, n(E) is the number of times in *n* outcomes of observed random experiment that the event *E* occurs. According to the law of total probability (Robert et al., 2013), the probability of R event is defined as:

233
$$P(R) = P(RI) = P(R|\bigcup_{m=1}^{4} I_m) P(\bigcup_{m=1}^{4} I_m) = \sum_{m=1}^{4} P(R|I_m) P(I_m) = p_R$$
(2)

234 I_m , m=1, 2, 3 and 4 represent the Ie, II, Is, and Iw respectively, and $P(R|I_m)$ represents

conditional probability that R event occur given that m^{th} I event type has occurred.

236 Similarly, the probability of S event is defined as:

237
$$P(S) = P(SI) = P(S|\bigcup_{m=1}^{4} I_m) P(\bigcup_{m=1}^{4} I_m) = \sum_{m=1}^{4} P(S|I_m) P(I_m) = p_S$$
(3)

Equation (2) and (3) quantify the stochastic soil erosion events by using conditionalprobability.

240 **2.2.2 Probability distribution functions of erosion event**

- 241 We defined X, Y as two discrete random variables, representing two real-valued
- functions defined on the sample space (Ω). Let X, Y denote the numbers of times of R

and S events occurrence respectively, and assign the sample space Ω to another random variable Z. $X(R) = x, Y(S) = y, Z(\Omega) = z, y \le x \le z$. x, y, z are integers. The ranges of X and Y are $R_X = \{all x : x = X(R), all R \in \Omega\}$ and $R_Y = \{all y : y =$ $Y(S), all S \in \Omega\}$. The probability of x_i or y_j numbers of times of R or S events can be quantified by probability mass function (PMF) as follow:

248
$$pmf_X(x_i) = P[\{R_i: X(R_i) = x_i, x_i \in R_X\}]$$
 (4)

249
$$pmf_Y(y_j) = P[\{S_j: Y(S_j) = y_j, y_j \in R_Y\}] \text{ for } i \ge j$$
 (5)

The random variables X, Y obey the Binominal distribution with *n* independent Bernoulli experiments (Robert et al., 2013). Therefore, the PMF of X, and Y can be defined as follow:

255
$$pmf_{Xbin}(x) = P_{Xbin}(X = x) = \begin{cases} \binom{n}{x} p_R^x (1 - p_R)^{n-x} & x = 0, 1, 2, ..., n \\ 0 & elsewhere \end{cases}$$
 (6)

256
$$pmf_{Ybin}(y) = P_{ybin}(Y = y) = \begin{cases} \binom{n}{y} p_S^y (1 - p_S)^{n-y} & y = 0, 1, 2, ..., n \\ 0 & elsewhere \end{cases}$$
 (7)

where *x* and *y* indicate all possible numbers of times of R and S occurring over *n* I events. However, when the Bernoulli experiment is performed infinite independent times $(n \rightarrow \infty)$, the Binomial PMF can be transformed into Poisson PMF (proved by appendix A), and finally expressed as follow:

261
$$pmf_{Xpoi}(x) = P_{Xpoi}(X = x) = \begin{cases} \frac{\lambda_R^x e^{-\lambda_R}}{x!} & x = 0, 1, 2, ... \\ 0 & elsewhere \end{cases}$$
 (8)

262
$$pmf_{Ypoi}(y) = P_{Ypoi}(Y = y) = \begin{cases} \frac{\lambda_S^y e^{-\lambda_S}}{y!} & y = 0, 1, 2, ... \\ 0 & elsewhere \end{cases}$$
 (9)

where the parameter $\lambda_R \approx np_R$, $\lambda_S \approx np_S$. Equation (6) ~ (9) reflect two PMF models to simulate the probability distribution of R or S events.

265 **2.3 Probabilistic attribution of erosion events**

266 **2.3.1 Bayes model**

Based on the Bayes forumula theroy (Sheldon, 2014), if we want to evaluate how much the probabilistic contributions of k^{th} type of random rainfall event on one stochastic runoff or sediment event which has been generated and observed, the Bayes model can quantify the results as follow:

271
$$P(I_k|R) = \frac{P(I_kR)}{P(R)} = \frac{P(R|I_k)P(I_k)}{\sum_{m=1}^{4} P(R|I_m)P(I_m)}$$
(10)

272
$$P(I_k|S) = \frac{P(I_kS)}{P(S)} = \frac{P(S|I_k)P(I_k)}{\sum_{m=1}^4 P(S|I_m)P(I_m)}$$
(11)

In fact, the Bayes model provides an important explanation that how the priori stochastic information ($P(I_k)$) was modified by the posterior stochastic information (P(R)orP(S)). The application of Bayes model in equation (10) ~ (11) reflects the feedback of random erosion events on the stochastic rainfall events. It could also be regarded as one pattern of probabilistic attribution to assess the effect of different random rainfall events on the uncertainty of soil erosion events without considering the diversity of restoration vegetation.

280 **2.3.2 Logistic regression model**

Firstly, we constructed event-driven logistic function, and defined Y_R and Y_S as two dichotomous dependent variables. When we denoted 1 or 0 to Y_R and Y_S respectively, it

- means that a R and S event has occurred or not occurred. Given Y_R is a dichotomous
- dependent variable of R event in linear probability model to be expressed as follow:

285
$$Y_{R_i} = \alpha + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots + \beta_n x_{ni} + \xi_i = \alpha + \sum_{n=1}^n \beta_n x_{ni} + \xi_i$$
(12)

286 Then further transforming equation (12) into conditional probability of R event which

has generated in i^{th} observation time as follow:

288
$$P(Y_{R_i} = 1 | \cap_{n=1}^n x_{ni}) = P\left[\left(\alpha + \sum_{n=1}^n \beta_n x_{ni} + \xi_i\right) \ge 0\right]$$

289
$$= P\left[\xi_i < \left(\alpha + \sum_{n=1}^n \beta_n x_{ni}\right)\right]$$

$$= P\left[\xi_i \le \left(\alpha + \sum_{n=1}^{n} \beta_n x_{ni}\right)\right]$$

$$=F\left(\alpha + \sum_{n=1}^{n} \beta_n x_{ni}\right)$$
(13)

291 α, β are constants, $F(\alpha + \sum_{n=1}^{n} \beta_n x_{ni})$ is the cumulative distribution function of ξ_i 292 when $\xi_i = \alpha + \sum_{n=1}^{n} \beta_n x_{ni}$. Equation (12) and (13) quantified the stochasticity of Y_{R_i} 293 depending on the linear combination of *n* influencing factors x_n and measurement error 294 ξ under *i*th observation times of stochastic runoff generation.

Secondly, assuming the probabilistic distribution of ξ_i satisfies logistic distribution and $P(Y_{R_i} = 1 | \bigcap_{n=1}^n x_{ni}) = p_i$, then the logistic regression modeling (LRM) expression of $Y_{R_i} = 1$ is deduced as follow:

298
$$p_{i} = F\left(\alpha + \sum_{n=1}^{n} \beta_{n} x_{ni}\right) = \frac{1}{1 + e^{-(\alpha + \sum_{n=1}^{n} \beta_{n} x_{ni})}} = \frac{e^{\alpha + \sum_{n=1}^{n} \beta_{n} x_{ni}}}{1 + e^{\alpha + \sum_{n=1}^{n} \beta_{n} x_{ni}}}$$
(14)

299 Correspondingly, the LRM of $Y_{R_i} = 0$ can be express as:

300
$$P(Y_{R_i} = 0 | \cap_{n=1}^n x_{ni}) = 1 - p_i = \frac{1}{1 + e^{\alpha + \sum_{n=1}^n \beta_n x_{ni}}}$$
 (15)

301 The ratios of equation (14) to (15) is defined as odds of R event:

302
$$0dds = \frac{p_i}{1 - p_i} = \frac{\frac{e^{\alpha + \sum_{n=1}^n \beta_n x_{ni}}}{1 + e^{\alpha + \sum_{n=1}^n \beta_n x_{ni}}}}{\frac{1}{1 + e^{\alpha + \sum_{n=1}^n \beta_n x_{ni}}}} = e^{\alpha + \sum_{n=1}^n \beta_n x_{ni}}, \text{ odds } \in [0, 1]$$
(16)

In this study, the odds in equation (16) is a probabilistic attribution index to quantify how much the *n* influencing factors to affect the generation of i^{th} stochastic runoff event. Specifically, when the odds of an influencing factor is greater (less) than 1, it means that the corresponding influencing factor exerts positively (negatively) effects on theprobability of R generation.

Finally, taking the natural logarithms of the both sides of equation (16), we transform the odds of stochastic runoff event into linear equation (17) reflecting the standard expression of LRM:

311
$$ln\left[\frac{P(Y_{R_i}=1|\bigcap_{n=1}^{n} x_{ni})}{P(Y_{R_i}=0|\bigcap_{n=1}^{n} x_{ni})}\right] = ln\left(\frac{p_i}{1-p_i}\right) = \alpha + \sum_{n=1}^{n} \beta_n x_{ni}$$
(17)

LRM could be regarded as another probabilistic attribution pattern to evaluate the effect
of mutiple impacting factors—such as soil, vegetation, and rainfall—on the randomness
of soil erosion events occuring in different restoration vegetation types.

315

316 **3. Experimental design and data analysis**

317 **3.1 Study area**

The study was implemented in the Yangjuangou Catchment (36 42'N, 109 31'E, 2.02 318 km²) which is located in the typical hilly-gully region of the Loess Plateau in China 319 (Figure 2a). A semi-arid climate in this area is mainly affected by the North China 320 monsoon. Annual average precipitation reaches approximately 533 mm, and the rainy 321 season here spans from June to September (Liu et al., 2012). The Calcaric Cambisol 322 soil type (FAO-UNESCO, 1974) with weak structure and higher erodibility in the Loess 323 Plateau is vulnerable to water erosion. For these reasons, soil and water loss was one of 324 most environmental problems to seriously degrade the ecosystem in the Loess Plateau 325 326 before 1980s (Miao et al., 2010; Wang et al., 2015). After that, as a crucial soil and water resource protection project, the Grain-for-Green Project was widely implemented 327

in the Loess Plateau. A large number of steeply sloped croplands were abandoned,
restored or natural recovered by local shrub and herbaceous plants (Cao et al., 2009;
Jiao et al., 1999). In the Yangjuangou Catchment, the main restoration vegetation
distributed on hillslopes includes *Robinia. pseudoacacia Linn, Lespedeza davurica, Aspicilia fruticosa, Armeniaca sibirica, Spiraea pubescens*, and *Artemisia copria*, etc.
All the restoration vegetation was planted over 20 years ago.

334 **3.2 Design and monitoring**

In the Yangjuangou Catchment, we have had conducted a systematic long-term field experiments, including the monitoring of soil erosion (Liu et al., 2012; Zhou et al., 2016), observation of soil moisture dynamic (Wang et al., 2013; Zhou et al., 2015) and assessment of soil controlling service in this typical water-restricted environment (Fu et al., 2011).

In this study, we first monitored the soil erosion events occurring in three typical 340 restoration vegetation (Armeniaca sibirica (T1), Spiraea pubescens (T2) and Artemisia 341 342 copria (T3)) from rainy season of 2008 to 2012 (figure 2b). Each restoration vegetation type was designed in three 3 m by 10 m closed runoff-plot distributing on southwest 343 facing hillslopes with a 26.8% aspect. The boundaries of each runoff-plot were 344 perpendicularly fenced by impervious polyvinylchloride (PVC) sheet with 50 cm depth. 345 Collection troughs and storage buckets were installed at the bottom boundary to collect 346 the runoff and sediment (Zhou et al., 2016). Under natural precipitation condition, we 347 recorded the number of times of stochastic runoff and sediment events generating in 348 each runoff-plot over five rainy seasons. Meanwhile, we collected runoff and sediment, 349

and separated them after settling the collecting bottles for 24 hours, dried at 105 °C over
8 hours and weighted.

352 Secondly, we systematically monitored the hydrological properties of soil in different restoration vegetation types. In the rainy season of 2010, the dynamic of soil moisture 353 was started to be measured in the study region (Wang et al., 2013). The real-time 354 dynamic data of soil water content with interval of 10 minutes were recorded by the S-355 SMC-M005 soil moisture probes (Decagon Devices Inc., Pullman, WA), and were 356 collected by HOBO weather station logger (figure 2c). These data provided the 357 358 information about average antecedent soil moisture (short for ASM) before every rainfall events generating in the two rainy seasons from 2010 to 2012. We further 359 measured the field saturated hydraulic conductivity (short for SHC) in all vegetation 360 361 types by Model 2800 K1 Guelph Permeameter (Soilmoisture Equipment Corp., Santa Barbara, CA, USA) to determine the average infiltration capability of soil matrix (figure 362 2d). 363

Thirdly, we also investigated the morphological properties of different vegetation types in each runoff-plot for 2-3 times over different periods of rainy season. We measured the average crown width, height and the thickness of litter layer in three restoration vegetation by setting 60×60 cm quadrats in each runoff plot (Bonham, 1989) (figure 2e).

Finally, two tipping bucket rain gauges were installed outside of runoff-plot to automatically record the rainfall processes over the five rainy seasons with an accuracy of 0.2 mm precipitation. Table 3 summarized the properties of four types of random

372	rainfall event, and all the basic characteristic of soil and vegetation was showed in Table
373	4.
374	Figure 2
375	Table 3
376	Table 4
377	
378	3.3 Statistics
379	We employed nonparametric statistical tests—one-way ANOVA and post hoc LSD—to
380	determine the significant difference of soil, vegetation and erosive properties in the

three restoration vegetation types. meanwhile, the maximum likelihood estimator (MLE)

and uniformly minimum variance unbiased estimator (UMVUE) (Robert et al., 2013)

383 were explored to compare the suitability of the binomial PMF and Poisson PMF for

384 predicting the uncertainty of runoff and sediment generation over long term.

385

386 4. Results

4.1 Environmental stochasticity in different rainy seasons

The probabilistic distribution of random rainfall events (I events) and random nonrainfall events (C events) forms the environmental stochasticity which is a background of stochastic soil erosion generation. In the OCIRS, the stochastic environment at monthly and seasonal scales over five rainy seasons was described by figure 3. From the rainy season of 2008 to 2012, the probability of I event generation firstly increased with the increasing of monitoring period and then decreased in the last two rainy

394	seasons. In the rainy season of 2008, the average probability of I event was lower than
395	other four rainy seasons, with being less than 15%. However, the types of I events was
396	most complex in 2008. The random extreme long rainfall event (Ie event) only appeared
397	in this rainy season, with the probability even reaching to 2.5% On the other hand, the
398	average probability of I event was the highest in the rainy season of 2010, with being
399	larger than 18%. But, there only existed two types of I events (Iw and Is events) in this
400	rainy season. Over the five rainy seasons, the average probability of Iw (12.3%) and Ie
401	(0.8%) events generation were the highest and lowest, respectively. The average
402	probability of Is (1.7%) and Il (1.3%) events ranged between Iw and Ie. The probability
403	of Cd event was higher than Ch in each month of rainy season, with average probability
404	being 54.4% and 29.4%, respectively. Moreover, in the table 3, the difference of average
405	precipitation and duration in the four types of I events was significance. But the average
406	rainfall intensity of Iw and Is events were nearly twice that of Il and Ie events.
407	
408	Figure 3
409	
410	4.2 Stochasticity of soil erosion events
411	4.2.1 Probability of erosion events in vegetation types

The stochasticity of erosion events was quantified by the probability of runoff and sediment generation in three restoration vegetation types (T1, T2 and T3) under monthly and rainy season scales (figure 4). Over the five rainy seasons, the probability of soil erosion occurring in all vegetation types generally decreased with the increasing

416	of monitoring period, and then increased in 2012. At early period of erosion monitoring
417	(2008), the randomness of erosion events is similar, and the probability of R and S event
418	ranged from 6% to 13% and from 3% to 13% respectively. After that, from rainy season
419	of 2009 to 2011, the highest probabilities of erosion events in each vegetation type all
420	concentrated in the July and August of each season. As to runoff production, the average
421	probability of R event in T1 (3.78%) was less than that of T2 (5.60%) and T3 (5.58%)
422	under same precipitation condition. With respect to sediment yield, the average
423	probability of S event in T1 (1.65%) was also the lowest in all restoration vegetation
424	types. Especially, in the last two rainy seasons, there was no S event occurring in T1,
425	but, the average probability of S event in T2 and T3 reached to 1.83% and 3.36%
426	respectively in corresponding rainy seasons. Consequently, affected by the same
427	stochastic signal of rainfall events, T1 and T3 have the lowest and highest probability
428	of erosion event generation over the five rainy seasons respectively.
429	
430	Figure 4
431	
432	4.2.2 Probabilistic distribution of erosion events in vegetation types
433	More detailed stochastic information of erosion events in different vegetation types was
434	simulated by Binominal and Poisson mass functions (PMFs) under the monthly scales.
435	It also compared the frequencies distribution of different numbers of observed erosion
436	events with the corresponding simulated results by the two PMFs in figure 5. Firstly, as
437	to the detailed stochastic information of R events, the two PMFs generally provided a

438	better simulation to the observation in T1 than that of in T2 and T3. When comparing
439	the simulated and observed values, Binomial PMF supplied better simulation to the
440	observed numbers of time of R events with larger frequency (such as 2~4 time) than
441	that of Poisson PMF. However, Poisson PMF simulated the observed numbers of time
442	of R events with the lower frequency (such as 6~8 times) better than that of Binomial
443	PMFs. Secondly, as to the detailed stochastic information of S event, the two PMFs
444	provided better simulation to the observation in T3 than that of in T1 and T2. In
445	particular, when the number of times of S event generation reaches two in T1 and T2,
446	the corresponding simulated probability values were all nearly 2 times larger than the
447	observed frequencies, reflecting the most simulation error of the two PMFs. Moreover,
448	with the restoration vegetation types changing from T1 to T3, both of the simulated and
449	observed numbers of time of R and S events with largest probability or frequency
450	increased in consistence. In a word, comparing with the observed frequency of numbers
451	of erosion events, both PMFs indicated well-simulating effect to detail the stochasticity
452	of runoff and sediment events under monthly scale.

Figure 5

4.3 Stochastic attribution of soil erosion events

4.3.1 Effect evaluation of stochastic erosion events by Bayes model

458 The Bayes model was applied to analyze the effect of random rainfall events (including

459 Iw, Is, Il and Ie) on stochastic erosion events in different restoration vegetation types.

Specifically, Bayes model evaluated the different probabilistic contributions of four 460 types of I events on one observed erosion event which has stochastically generated in 461 462 specific vegetation type under monthly and rainy seasonal scales (figure 6). In the rainy season of 2008, the types of I events driving one stochastic erosion event was most 463 complex than other rainy seasons. In contrast, one stochastic soil erosion generation in 464 three vegetation types attributed to only Iw and Is events in the rainy season of 2010. 465 In other three rainy seasons, when one R or S event stochastically generated on T1, the 466 main contributing I event types concentrated on Is and Il events both of which have 467 468 relatively higher precipitation and longer duration, respectively. On the other hand, if one R or S event occurred in T2 or T3 randomly, the main contributing I event types 469 was Iw event which, however, have no contribution to S event occurred on T1. 470

In general, over five rainy seasons, the composition of I event driving one R event was more complex than that of driving one S event. The relative longer duration rainfall events (II and Ie) became the main probabilistic contributors of one stochastic erosion event occurring in T1, and the relative stronger intensity rainfall events (Iw and Is) mainly caused one random erosion event generating in T2 and T3.

476

477

Figure 6

478

479 4.3.2 Effect evaluation of stochastic erosion events by LRM

According to the results of significant difference analysis in table 4, we defined theproperties of soil and plant as ordinal variables, and classified them into four grades

(Table 5). Meanwhile, based on previous studies (Liu et al., 2012; Wei et al., 2007) and
rainfall properties in this study area, we further subdivided all precipitation and rainfall
intensity into four grades with different scores.

First, the intensity of positive and negative effects of single influencing factor on the 485 probability of runoff and sediment generation in all restoration vegetation types was 486 quantified in terms of odds ratio of erosion events by LRM (table 6). In the LRM, the 487 highest and lowest odd ration appeared in rainfall intensity ordinal variable (INT) and 488 average crown width ordinal variable (CRO). The increasing INT and CRO (from 489 490 middle to extreme grade) significantly increased and decreased the odds ratio of erosion events, respectively. This means that INT and CRO acts as two most important roles on 491 improving and restraining the probability of stochastic erosion generation in all 492 493 restoration vegetation types. Additionally, the increasing of antecedent soil moisture ordinal variable (ASM) and the filed saturated hydraulic conductivity ordinal variable 494 (SHC) (from middle to high grade) in the LRM, also significantly increased and 495 496 decreased the odds ratio of R and S events, respectively. However, the average thickness of litter layers ordinal variable (TLL) has not exerted significant effect on the odds ratio 497 of erosion events. Table S-1 and S-2 in supplementary information systematically 498 describe the whole processes of LRM to evaluate the effect of single factor on odds 499 ratio of erosion event. 500

501 Secondly, we further applied LRM to evaluate the interactive effects of multiple 502 influencing factors on the odds ratio of R and S events in all restoration vegetation types 503 (table 7). As to the interactive effect of two soil hydrological properties, the interaction

504	between low-grade of SHC and increasing-grade of ASM significantly raised the odds
505	ratio of erosion events. Such that the odds ratio of R and S events affected by the
506	interactive effects of low-grade of SHC and extreme-grade of ASM were respectively
507	7.02 and 1.82 times larger than that interactive effects of low-grade of SHC and low-
508	grade of ASM. Similarly, as to the effect of two vegetation properties, the interactive
509	effect of low-grade of CRO and increasing-grade of TLL would reduce the odds ratio
510	of erosion events. Such that the odds ratio of R and S events influenced by the
511	interaction between low-grade of CRO and high-grade of TLL were respectively only
512	0.12 and 0.33 times larger than that interactive effects of low-grade of CRO and low-
513	grade of TLL. Additionally, with respect to the interaction between soil and plant
514	properties, the interactive effect of low-grade of CRO and increasing-grade of ASM
515	properties also significantly raised the odds ratio of erosion events. The whole processes
516	of LRM to evaluate the interactive effect of multiple factors on odds ratio of erosion
517	event were indicated by the table S-3,4 and 5 in the supplementary information.
518	
519	Table 5
520	Table 6
521	Table 7
522	Table S-1,2,3,4,5
523	
524	

526 **5. Discussion**

527 5.1 The integrated probabilistic assessment to erosion stochasticity

528 The probabilistic attribution and description of stochastic erosion events constituted the

529 framework of integrated probabilistic assessment (IPA).

First, as to one pattern of probabilistic attribution in the IPA, Bayes model supplies a 530 supplementary view and algorithm about how to evaluate the feedback of a result which 531 had stochastically occurred on all possible reasons (Wei and Zhang, 2013). Under the 532 conditions of insufficient information about an occurred result, Bayes model can 533 534 determine which reasons have the relative greater probability to trigger the occurrence of the result through some prior information. Specific to this study, Bayes model was 535 used to evaluate the probabilistic contribution of four types of I events on one stochastic 536 537 R ($P(I_k|R)$) and S ($P(I_k|S)$) event generated in each restoration vegetation. Although there were no more specific information about a stochastic soil erosion event, the prior 538 information $(P(R|I_m), P(S|I_m), P(I_m))$ can provide assistance for us to assess the 539 540 feedback of the stochasticity of soil erosion on different random rainfall events by Bayes model. Meanwhile, $(P(I_k|R))$ and $(P(I_k|S))$ also reflect the different probability 541 threshold values of four rainfall event types triggering soil erosion. Bayes model 542 integrated with total probability theory to systematically quantify the interactive 543 relationship between the stochasticity of precipitation and soil erosion, forming a 544 relative simple and practicable risk assessment of soil erosion event occurring in 545 complex restoration vegetation conditions. 546

547 Secondly, as a pattern of probabilistic description in the IPA, Binomial and Poisson

PMFs are two crucial probabilistic functions to characterize many random hydrological 548 phenomena and to model their ecohydrological effects in natural condition (Eagleson, 549 550 1978, Rodriguez-Iturbe et al, 1999, 2001). In this study, the two PMFs were found to have good simulations of the frequency of times of soil erosion events in three 551 restoration vegetation types. However, it is necessary and meaningful for the reliability 552 and accuracy of the IPA to assume whether the two PMFs can both stably and 553 reasonably simulate the erosion stochasticity at closed-runoff-plot over longer 554 monitoring period. Therefore, based on above assumption, two important point 555 556 estimations methods-the maximum likelihood estimator (MLE) and uniformly minimum variance unbiased estimator (UMVUE) (Robert et al., 2013)-were applied 557 to evaluate the stability of erosion stochasticity estimation by means of analyzing the 558 559 unbiasedness and consistency of p_R, p_S, λ_R and λ_S . Taking parameter analysis of random runoff event for example, we defined X_i as the number of times of R event 560 occurring in some specific restoration vegetation in i^{th} rainy season (i = 1,2,3,4 and 5). 561 562 The five independent and identical (iid) random variables satisfies the same and mutually independent binomial or Poisson PMFs as follows: 563

564
$$X_1, X_2, \dots, X_5 \xrightarrow{iid} binomial(p_R) \text{ or } X_1, X_2, \dots, X_5 \xrightarrow{iid} Poisson(\lambda_R)$$
 (18)

Considering longer monitoring periods, we supposed that the numbers of corresponding I events (*n*) and rainy seasons (*i*) would approach infinity ($n, i \rightarrow \infty$), and (18) can be transformed as follow:

568
$$X_1, X_2, \dots, X_i \xrightarrow{iid} binomial(p) \text{ or } X_1, X_2, \dots, X_i \xrightarrow{iid} Poisson(\lambda)$$
 (19)

569 We take MLE and UMVUE methods to search for the best reasonable population

more comprehensive stochastic information about the randomness of R even rainy seasons. The Appendix B proved that the best estimator \hat{p} in Binomial the unbiasedness and consistency of the MLE of p . However, proved by the A C, the best estimator $\hat{\lambda}$ in Poisson PMF have more reliability as it is not unbiasedness and consistency of the MLE of λ , but also the UMVUE of M UMVUE in Poisson PMF implied that lowest variance unbiased estimator c the Poisson PMF to be more steadily and accurately stimulate the stochasticit erosion events over long-term observation than binomial PMF. Thirdly, besides having better simulation of the stochastic soil erosion events temporal scale, the Poisson PMF could also be more suitable for simula randomness of S event in the closed-design plot system than that of binomial I As the hypothesis of Boix-Fayos et al in 2006, the closed runoff-plot desig an obstruction to prevent the transportable material from entering the close more	nt over <i>i</i> PMF is ppendix only the LE. The un make y of soil at larger
rainy seasons. The Appendix B proved that the best estimator \hat{p} in Binomial the unbiasedness and consistency of the MLE of p . However, proved by the A C, the best estimator $\hat{\lambda}$ in Poisson PMF have more reliability as it is not unbiasedness and consistency of the MLE of λ , but also the UMVUE of M UMVUE in Poisson PMF implied that lowest variance unbiased estimator c the Poisson PMF to be more steadily and accurately stimulate the stochasticit erosion events over long-term observation than binomial PMF. Thirdly, besides having better simulation of the stochastic soil erosion events temporal scale, the Poisson PMF could also be more suitable for simula randomness of S event in the closed-design plot system than that of binomial I As the hypothesis of Boix-Fayos et al in 2006, the closed runoff-plot desig an obstruction to prevent the transportable material from entering the close more	PMF is ppendix only the LE. The un make y of soil at larger
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574 C, the best estimator $\hat{\lambda}$ in Poisson PMF have more reliability as it is not 575 unbiasedness and consistency of the MLE of λ , but also the UMVUE of M 576 UMVUE in Poisson PMF implied that lowest variance unbiased estimator c 577 the Poisson PMF to be more steadily and accurately stimulate the stochasticit 578 erosion events over long-term observation than binomial PMF. 579 Thirdly, besides having better simulation of the stochastic soil erosion events 580 temporal scale, the Poisson PMF could also be more suitable for simula 581 randomness of S event in the closed-design plot system than that of binomial I 582 As the hypothesis of Boix-Fayos et al in 2006, the closed runoff-plot desig 583 an obstruction to prevent the transportable material from entering the close more	Donly the LE. The In make y of soil at larger
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an obstruction to prevent the transportable material from entering the close mo	n forms
	nitoring
system, which, in particular, lead the transport-limited erosion pattern to g	radually
transform into detachment-limited pattern in the closed-plot over time (Boix-	Fayos et
al., 2007; Cammerraat, 2002). Consequently, with the extension of monitoring	; period,
this closed runoff-plot design would cause the sediment more and more dif	ficult to
588 migrate out of plot, which also reduce the probability of observed S events u	nder the
same precipitation condition. In fact, the effect of closed runoff-plot on st	ochactic
sediment event could also be successfully implied by the algorithm of Poiss	ochastic
591 Specifically, in order to satisfying the fact that $\lambda = np$ in Poisson PMF is an u	on PMF.

constant, the extension of monitoring period could lead to the numbers of times of I events (n) approach infinity, then the probability (p) of R or S events generation have to approach to zero. Above inference coincides with the assumption about the decreasing of sediment generation in closed-plot system, and further proves that Poisson PMF could be more reliable to simulate the stochastic erosion events at longer temporal scale.

598

599 5.2 The effect of influencing factors on erosion stochasticity

600 The effects of rainfall, soil and vegetation properties on erosion stochasticity in different restoration vegetation types were evaluated by LRM. It integrated stochastic rainfall 601 events with their precipitation and intensity grades, and connected the ecohydrological 602 603 functions of soil and plant with their classified hydrological and morphological features. Just as serving as previous studies (Verheyen and Hermy, 2001a, 2001b; Verheyen et 604 al., 2003 and Hermy, 2001a; 2001b; Verheyen et al., 2003), LRM in this study explored 605 606 the relative importance of morphological features disturbing on the transmission of stochastic signal of I events into R and S events in different restoration vegetation types. 607 These disturbances are closed related to the complex hydrological functions owned by 608 different morphological structures, which finally affect the whole processes of runoff 609 production and sediment yield (Bautista et al., 2007; Puigdef åbregas, 2005). 610

First, many previous field experiments and mechanism models have proved that canopy structure has capacity for intercepting intercept precipitation. This specific hydrological function could potentially prevent the rainfall from directly forming

overland flow or splashing soil surface particles (Liu, 2001; Mohammad and Adam, 614 2010; Morgan, 2001; Wang et al., 2012). The precipitation retention owned by canopy 615 616 structure was regarded as an indispensable positive factor to reduce the soil erosion rate. Meanwhile, as a crucial complement to understanding hydrological function of canopy 617 structure, the result of LRM in this study indicated that the higher-grade canopy 618 structure was a most important morphological feature to reduce the odds ratio of 619 random soil events in all restoration vegetation types. This result suggests that, the 620 larger canopy diameter would have relatively stronger capacity for disturbing the 621 622 transmission processes of stochastic signal of rainfall on the soil surface than that of other morphological properties. From the perspective of erosion stochasticity, the 623 higher-grade canopy structure could finally attribute to the lower probability of R and 624 625 S event generation. Therefore, the diversity of canopy structures in different vegetation types could act a key role on both reducing the intensity and probability of soil erosion 626 generation. 627

628 Secondly, many studies have also discovered that the denser root system distributing in soil matrix could improve the reinfiltration of the overland (Gyssels et al., 2005). 629 This reinfiltration process is an effective way to recharge soil water stores when the 630 overland flow started to occur in hillslopes, which was also an indispensable 631 contributing factor to reduce the unit area runoff production (Moreno-de las Heras et 632 al., 2009; Moreno-de las Heras et al., 2010). In this study, the potential reinfilitration 633 capacity of soil matrix could be positively affected by the saturated hydraulic soil 634 conductivity (SHC) index. Figure 7 further indicated the distribution patterns of root 635

system in three restoration vegetation types. Meanwhile, the result of LRM also implied
that the grade of SHC could negatively affect the odds ratio of stochastic erosion event,
which improved the understanding of the hydrological function of root distribution of
plant from the view of erosion randomness. It may suggest that the denser root system
could create more macropores in the subsurface to provide more probability of
reinfiltration of overland flow. This disturbance of overland flow by SHC could reduce
the probability of erosion event generation.

Thirdly, the litter layer was proved to act multiple roles on conserving the rainfall, 643 644 improving infiltration of throughfall, as well as cushioning the splashing of raindrop (Gyssels et al., 2005; Munoz-Robles et al., 2011; Geißler et al., 2012). Therefore, the 645 thicker litter layer in T2 (figure 7) probably has stronger capacity for conserving and 646 647 infiltrating throughfall, as well as inhibiting splash erosion than that of other restoration vegetation types (Woods and Balfour, 2010). Although the result of LRM indicated that 648 there was no significant correlation between the litter layer thickness (TLL) and the 649 650 odds ratio of soil erosion (table 6), the interactive effect of TLL and CRO significantly affect the odds ratio of stochastic erosion events (table 7). The interaction result implied 651 that, under the relative low-grade CRO condition, the higher-grade TLL could have 652 stronger disturbance on the transmission of stochastic signals of rainfall to improve the 653 throughfall absorption to reduce the probability of splash or sheet erosion occurrence. 654

Additionally, table 7 explored more interactive effects of the soil and plant properties on odds ratio of random runoff and sediment event. These explorations suggested that the interactions between soil and vegetation properties formed more complex hydrological functions to affect the stochastic soil erosion event during wholeecohydrological processes in semi-arid environment (Ludwig et al., 2005).

Although the hydrological-trait of vegetation acted as core roles on reducing the soil 660 erosion depending on the mechanical properties of their morphological structures (Zhu 661 et al., 2015), the LRM analysis in this study further illuminated that these hydrological-662 trait morphological structure of vegetation may also play an important role on affecting 663 the stochasticity of soil erosion. Actually, the different stochasticity of soil erosion in 664 three restoration vegetation types reflected the different extents of disturbance of 665 666 vegetation types on the transmission of stochastic signals of rainfall into soil-plant systems. Therefore, the relative smaller canopy structure, thinner litter layer, and 667 shallower root system in T3 have relatively weaker capacity to disturbing the stochastic 668 669 signal of rainfall than that of T1 and T2 with obvious hydrological-trait morphological structures (figure 7). The effect of diverse morphological structures on stochasticity of 670 soil erosion was a meaningful complement to studying on the hydrological functions of 671 672 restoration vegetation types in semi-arid environment.

Figure 7

673

674

- 675Table 6
- Table 7
- 677

678

679

680 5.3 The implication of integrated probabilistic assessment

The integrated probabilistic assessment (IPA) could be an important complement to 681 682 expand on the understanding of hydrological function existing in vegetation types. The hydrological-trait of morphological structures owned by different plants is closely 683 related to the function of vegetation-driven in affecting the intensity of erosion events. 684 The vegetation-driven-spatial-heterogeneity (VDSH) theory (Puigdef bregas, 2005) 685 could be regarded as a clear concise summary to emphasize the dominant role of 686 vegetation in restructuring soil erosion processes. It reflected the effect of spatial 687 688 distribution patterns of vegetation on their corresponding hydrological functions on controlling erosion rate in patch, stand, and even regional scales. Therefore, VDSH 689 theory has provided an innovative view to investigating the soil erosion and other 690 691 ecohydrological phenomena affected by vegetation (Sanchez and Puigdef abregas, 1994; Puigdef åbregas, 1998; Boer and Puigdef åbregas, 2005). In the study, depending 692 on the long-term experimental data and fundamental probability theories, the IPA 693 concentrated on the hydrological function of vegetation-driven in affecting the 694 randomness of erosion events rather than the erosion rate. It could enrich the 695 comprehension of hydrological function of vegetation morphological structure on soil 696 erosion phenomena, and also be effective complement for application of VDSH theory 697 on interpreting the stochastic erosion events. 698

Additionally, in our study, the IPA could also provide a new framework for practitioners to develop restoration strategies which focused on controlling the risk of erosion generation rather than only on reducing erosion rate. The framework contains three stages including construction of stochastic environment, description of randomerosion events, and evaluation of probabilistic attribution (figure 8).

704 The first stage in the framework aims to build a unified platform to describe the stochasticity of different hydrological phenomena closely related to the erosion event. 705 706 This stage generally investigates the stochastic background under which soil erosion generation, which is also an indispensable precondition for quantifying the probability 707 of R and S in stage II. The second stage is designed to construct a phased adjustment of 708 monitoring processes based on the principle of Bayes theory as well as on the parameter 709 710 analysis of Binomial and Poisson models. In this phased-adjustment monitoring, the Bayes, Binomial and Poisson models were applied on simulating the randomness of 711 erosion events in short-term, mid-term and long-term monitoring stages, respectively. 712 713 This model-driven monitoring approach could be regarded as a more reasonable method to explore the complexity of stochastic erosion events in larger temporal scales, but also 714 provide a new perspective for researchers to more effectively evaluate the stochasticity 715 716 of erosion events in stage III. The objective of stage III is to assess the probabilistic attribution of rainfall, soil and vegetation properties on erosion events generation. This 717 probabilistic attribution evaluation by LRM, could develop the restoration strategies for 718 more effectively selecting vegetation types with stronger capacity for reducing the 719 erosion risk, and finally improve the management of soil and water conservation in a 720 semi-arid environment. 721

As a result, this stochasticity-based restoration strategy was developed by a combination of experimental data with multiple probabilistic theories to deal with the

soil erosion randomness under complex stochastic environment. It is different from the 724 trait-based restoration scheme derived from the functional diversity of vegetation 725 726 community to reduce the soil erosion rate (Zhu et al., 2015; Baetas et al., 2009). Meanwhile, with the increase of monitoring duration, more stochastic information of 727 erosion events could be added into the IPA framework. This addition could finally fulfil 728 the self-renewal and self-adjustment of the IPA to improve the restoration strategy for 729 selecting more reasonable vegetation types with stronger capacity for controlling 730 erosion risk in long term. Therefore, the IPA framework containing three stages could 731 732 translate the event-driven erosion stochasticity into restoration strategies concentrating on erosion randomness, which may be a meaningful complement for restoration 733 management in a semi-arid environment. 734

- 735
- 736

Figure 8

737

738 **6.** Conclusion

In this study, we applied an integrated probabilistic assessment (IPA) to describe,
simulate and evaluate the stochasticity of soil erosion in three restoration vegetation
types in the Loess Plateau of China, and draw the following conclusions:

(1) In the IPA, the OCIRS was an innovative event-driven system to standardize thedefinition of hydrological random events, which is also a foundation for quantifying

- the stochasticity of soil erosion events under complex environment conditions.
- 745 (2) Both of binomial and Poisson PMFs in the IPA could simulate the probability

distribution of the numbers of runoff and sediment events in all restoration
vegetation types. However, Poisson PFM could more effectively simulate the
stochasticity of soil erosion at larger temporal scales.

(3) The difference of morphological structures in restoration vegetation types is the
main source of different stochasticity of soil erosion from T1 to T3 under same
rainfall condition. Larger canopy, thicker litter layer and denser root distribution
could more effectively affect the transmission of stochastic signal of rainfall into
soil erosion.

The IPA is an important complement to developing restoration strategies to improve the understanding of stochasticity of erosion generation rather than only of the intensity of erosion event. It could also be meaningful to researchers and practitioners to evaluate the efficacy of soil control practices in a semi-arid environment.

758

759 Appendix A. The transformation from binominal to Poisson PMF

760 Let $p = \frac{\lambda}{n}$, then: 761 $pmf_{Xbin}(x) = {n \choose x} p^x (1-p)^{n-x} = \frac{n!}{x!(n-x)!} \cdot \left(\frac{\lambda}{n}\right)^x \cdot \left(1-\frac{\lambda}{n}\right)^{n-x}$ 762 $= \frac{\lambda!}{x!} \cdot \frac{n(n-1)(n-2)\cdots 1}{(n-x)(n-x-1)\cdots 1} \cdot \frac{1}{n^x} \cdot \left(1-\frac{\lambda}{n}\right)^{n-x}$

763
$$= \frac{\lambda!}{x!} \cdot 1 \cdot \left(1 - \frac{1}{n}\right) \cdot \left(1 - \frac{2}{n}\right) \cdots \left(1 - \frac{x-1}{n}\right) \cdot \left(1 + \frac{-\lambda}{n}\right)^n \cdot \left(1 - \frac{\lambda}{n}\right)^{-x}$$
(A1)

In equation (A1), when $n \to \infty$, and x, λ is finite and constant, then

765
$$\lim_{n \to \infty} \left(1 - \frac{1}{n}\right) = \dots = \lim_{n \to \infty} \left(1 - \frac{x - 1}{n}\right) = \lim_{n \to \infty} \left(1 - \frac{\lambda}{n}\right)^{-x} = 1$$
(A2)

766 And

767
$$\lim_{n \to \infty} \left(1 + \frac{-\lambda}{n} \right)^n = e^{-\lambda}$$
(A3)

And according to equation (A2) and (A3), the equation (A1) can be transformed as:

769
$$\lim_{n \to \infty} \left[\frac{n!}{x! (n-x)!} \cdot \left(\frac{\lambda}{n}\right)^x \cdot \left(1 - \frac{\lambda}{n}\right)^{n-x} \right] = \frac{\lambda^x e^{-\lambda}}{x!} \quad x = 0, 1, 2, \dots$$
(A4)

770 or

771
$$pmf_{Xbin}(x) \xrightarrow{n \to \infty} \frac{\lambda^{x} e^{-\lambda}}{x!} = pmf_{Xpoi}(x)$$
 (A5)

772

773 Appendix B. Parameter estimation of *p* in Poisson PMF

774 (1) Derivatization of the MLE \hat{p}

TT5 Let the random sample $X_1, X_2, ..., X_i \xrightarrow{iid} pmf_{Xbin}(p)$ and assume the binomial distribution as:

777
$$P(X = x_i) = {\binom{m}{x_i}} p^{x_i} (1 - p)^{m - x_i}$$
(B1)

The likelihood function L(p) is joint binomial PDF with parameter p as follow:

779
$$L(p) = f_X(X_1, ..., X_n, p) = \prod_{i=1}^n \binom{m}{x_i} p^{\sum_{i=1}^n X_i} (1-p)^{(mn-\sum_{i=1}^n X_i)}$$
(B2)

780 By taking logs on both side of equation (B2):

781
$$lnL(p) = ln\left(\prod_{i=1}^{n} {m \choose x_i}\right) + \sum_{i=1}^{n} X_i ln p + \left(mn - \sum_{i=1}^{n} X_i\right) ln(1-p)$$
 (B3)

And differentiating with respect to p in lnL(P) and let the result be zero:

783
$$\frac{\partial lnL(p)}{\partial p} = \frac{\sum_{i=1}^{n} X_{i}}{p} - \frac{(mn - \sum_{i=1}^{n} X_{i})}{(1-p)} = 0$$
(B4)
784 Solution $\hat{p} = \frac{\sum_{i=1}^{n} X_{i}}{mn}$, let $m = n, \Longrightarrow \hat{p} = \frac{\overline{X}}{n}$

Therefore,
$$\hat{p} = \frac{\overline{x}}{n}$$
 is the MLE of population parameter p in binomial PMF model.
786

787 (2) Discussion of the unbiasedness and consistency of \hat{p}

788 Let $E_p(\hat{p})$ be the expectation of M.L.E \hat{p} when population parameter p is true in

random sample which is $X_1, X_2, ..., X_i \xrightarrow{iid} pmf_{Xbin}(p)$, then

790
$$E_p(\hat{p}) = E_P(\overline{X}/n) = \frac{1}{n^2} \sum_{i=1}^n E_P(X_i) = \frac{1}{n^2} n^2 p = p$$
 (B5)

791 Which proved that MLE $\hat{p} = \frac{\overline{X}}{n}$ is a unbiased estimator for p. And furthermore then

192 let $Var_p(\hat{p})$ be the variance of \hat{p} when population p is true.

793
$$Var_p(\hat{p}) = Var_p\left(\sum_{i=1}^n X_i/n^2\right) = \frac{1}{n^4} \sum_{i=1}^n Var_p(X_i) = \frac{p(1-p)}{n^2}$$
 (B6)

As the *n* approaches to infinite:

795
$$\lim_{n \to \infty} Var_p(\hat{p}) = \lim_{n \to \infty} \left(\frac{p(1-p)}{n^2} \right) = 0$$
(B7)

Final Equation (B5)~(B7) satisfied the theme of weak law of larger number, which lead the $\hat{p} = \frac{\bar{x}}{n}$ is probabilistic converge to population parameter p: $\lim_{n \to \infty} P(|\hat{p} - p| \ge \varepsilon) = 0$, for all $\varepsilon > 0$ (B8)

799 Consequently, the unbiased MLE
$$\hat{p} = \frac{\overline{X}}{n}$$
 is consistent for p

800

801 Appendix C. Parameter estimation of λ in Poisson PMF

802 (1) Derivatization of the MLE $\hat{\lambda}$

803 Let the random sample $X_1, X_2, ..., X_i \xrightarrow{iid} pmf_{Xpoi}(\lambda)$, and assume the poisson 804 distribution as:

805
$$pmf_{Xpoi}(x_i) = \frac{\lambda^{x_i} e^{-\lambda}}{x_i!}$$
 (C1)

806 The likelihood function $L(\lambda)$ is joint PDF with parameter λ as follow:

807
$$L(\lambda) = f_X(X_1, \dots, X_n, \lambda) = f(X_1, \lambda) \times \dots \times f(X_n, \lambda) = \prod_{i=1}^n \frac{\lambda^{x_i} e^{-\lambda}}{x_i!}$$
(C2)

Taking logs on $L(\lambda)$ in equation (B4) and differentiating logarithm function with respect to λ :

810
$$\frac{\partial lnL(\lambda)}{\partial \lambda} = \frac{\partial (\prod_{i=1}^{n} \frac{\lambda^{x_i} e^{-\lambda}}{x_i!})}{\partial \lambda} = -n \frac{\lambda^{\sum_{i=1}^{n} X_i}}{(x_1 x_2 \cdots x_n)!} e^{-n\lambda} + \frac{\sum_{i=1}^{n} X_i \lambda^{(-1+\sum_{i=1}^{n} X_i)}}{(x_1 x_2 \cdots x_n)!}$$
(C3)

811 Let the equation (C3) equal to zero, and has solution:

812
$$\hat{\lambda} = \frac{1}{n} \sum_{i=1}^{n} X_i = \overline{X}$$
(C4)

Therefore, $\hat{\lambda} = \overline{X}$ is the MLE of population parameter λ in Poisson PMF model. 813

814

(2) Discussion of the unbiasedness and consistency of $\hat{\lambda}$ 815

- Let $E_{\lambda}(\hat{\lambda})$ be the expectation of MLE $\hat{\lambda}$ when population parameter λ is true in 816
- random sample $X_1, X_2, ..., X_i \xrightarrow{iid} pmf_{Xpoi}(\lambda)$, then: 817

818
$$E_{\lambda}(\hat{\lambda}) = E_{\lambda}(\overline{X}) = \frac{1}{n^2} \sum_{i=1}^{n} E_{\lambda}(X_i) = \frac{1}{n} n\lambda = \lambda$$
(C5)

- which proved that MLE $\hat{\lambda} = \overline{X}$ is a unbiased estimator for λ . Meanwhile, let $Var_{\lambda}(\hat{\lambda})$ 819
- be the variance of MLE $\hat{\lambda}$ when population parameter λ is true 820

821
$$Var_{\lambda}(\hat{\lambda}) = Var_{\lambda}(\overline{X}) = Var_{\lambda}\left(\sum_{i=1}^{n} X_{i}/n^{2}\right) = \frac{1}{n^{4}}\sum_{i=1}^{n} Var_{\lambda}(X_{i}) = \frac{\lambda}{n}$$
 (C6)

And 822

823
$$\lim_{n \to \infty} Var_{\lambda}(\hat{\lambda}) = \lim_{n \to \infty} \left(\frac{\lambda}{n}\right) = 0$$
(C7)

According to the weak law of large number theme, equation (B7, B8, C1) lead that 824

unbiased MLE $\hat{\lambda} = \overline{X}$ is probabilistic converge to λ : 825

826
$$\lim_{n \to \infty} P(|\hat{\lambda} - \lambda| \ge \varepsilon) = 0, \text{ for all } \varepsilon > 0$$
(C8)

Therefore, MLE $\hat{\lambda} = \overline{X}$ is consistent for population parameter λ . 827

828

(3) Determination of UMVUE $\hat{\lambda}$ of population parameter 829

Firstly, MLE $\hat{\lambda} = \overline{X}$ is an unbiased estimator of parameter λ which is the 830 precondition of UMVUE determination. Secondly, by using Cramer-Rao lower bound 831 38 to check whether the unbiased MLE was UMVUE or not. Then we have:

833
$$lnf_X(X,\lambda) = -lnx! + xln\lambda - \lambda$$
 (C9)

834
$$\frac{\partial (lnf_X(X,\lambda))}{\partial \lambda} = \frac{x}{\lambda} - 1$$
(C10)

835 And

836
$$\frac{\partial^2 ln f_X(X,\lambda)}{\partial \lambda^2} = \frac{\partial(\frac{X}{\lambda} - 1)}{\lambda} = -\frac{x}{\lambda^2}$$
(C11)

837 Accordingly the expectation of equation (C11) when the population parameter λ is 838 true:

839
$$E_{\lambda}\left[\frac{\partial^{2} ln f_{X}(X,\lambda)}{\partial \lambda^{2}}\right] = E_{\lambda}\left(-\frac{X}{\lambda^{2}}\right) = -\frac{1}{\lambda^{2}}E_{\lambda}(X) = -\frac{\lambda}{\lambda^{2}} = -\frac{1}{\lambda}$$
(C12)

840 So the Cramer-Rao lower bound (CRLB) is

841
$$\operatorname{CRLB} = \frac{1}{-nE_{\lambda}\left[\frac{\partial^{2} lnf_{X}(X,\lambda)}{\partial\lambda^{2}}\right]} = \frac{1}{-n\cdot(-\frac{1}{\lambda})} = \frac{\lambda}{n} = \operatorname{Var}_{\lambda}(\hat{\lambda}) = \operatorname{Var}_{\lambda}(\overline{X}) \quad (C13)$$

842 Consequently, MLE $\hat{\lambda} = \overline{X}$ is UMVUE of population parameter λ .

843

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853 **Figure captions**

Figure 1 The construction of OCIRS system : (a) a flow chart to determine all random event types in OCIRS framework; (b) the different combining patterns of rainfall and non-rainfall events in three consecutive days to form ten observed random event sequences on five rainy seasons; (c) Venn diagram to reveal the relationship among all random events types in OCIRS framework.

858

Figure 2 Study area and experimental design: (a) location of the Yangjuangou Catchment; (b) three restoration vegetation types including *Armeniaca sibirica* (T1), *Spiraea pubescens* (T2), and *Artemisia copria* (T3); (c) the dynamic measurement of soil moisture and data collection to provide the information about average antecedent soil moisture; (d) the measurement of field saturated hydraulic conductivity to determine the average infiltration capability; (e): the investigation of morphological properties of restoration vegetation by setting quadrats

865

Figure 3 The probability distribution of different random rainfall event types (Iw, Is, II, and Ie)
and random non-rainfall event types (Ch and Cd) at monthly and seasonal scales from rainy season
of 2008 to 2012.

869

Figure 4 The probability distribution of random runoff and sediment events generating in three
restoration vegetation types at monthly and seasonal scales from rainy season of 2008 to 2012, the
Arabic numbers and letter "T" on the abscissa indicate the month and season respectively, the same
as follow figures

874

Figure 5 The comparison between simulation of stochasticity of runoff and sediment events by
Binomial and Poisson PMFs and the observed frequencies of numbers of times of soil erosion events
in three restoration vegetation type, Exp_B and Exp_P indicates the simulated values in Binomial
and Poisson PMF respectively, and the histogram represents the observed values.

879

Figure 6 The distribution of probabilistic contribution of four random rainfall event types on
anyone runoff or sediment event stochastically generating in three restoration vegetation types at
monthly and seasonal scales from rainy season of 2008 to 2012

883

Figure 7 Morphological properties of three restoration vegetation types including the thickness
of litter layer, the distribution of root system. The dashed lines indicates the diameter and depth of
soil samples with approximating 10 cm and 30 cm respectively.

887

Figure 8 The framework of integrated probabilistic assessment for soil erosion monitoring andrestoration strategies

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1065 Tables

1066 Table 1 The summary of main researches on the stochasticity of soil erosion rate and the stochasticity of factors to affect the soil erosion rate

^a Stochasticity	^b Approach or	^c Driven types	Main Hydrological	Main Influencing	Spatiotemporal	Reference	
(Uncertainty)	method	• •	behaviors	factors	Scale		
· · · · · · · · · · · · · · · · · · ·		Si	tochasticity of soil erosion ra	te			
Runoff	Probabilistic model	(1)Data-Mapping	Infiltration processes	Topography	Hillslope scale in	Janzen, D., and	
connectivity	Conceptual model	(2)Theory	Precipitation	Soil depth	USA	McDonnell, J 2015	
Runoff processes	Probabilistic model	(1)Simulation	Infiltration processes	Topography		Janzen, D., and	
	Conceptual model	(2)Theory	Precipitation			McDonnell, J	
						2015	
Runoff production	Probabilistic model	(1)Theory	Runoff absorption	Soil moisture	Point and basin scale	Moore, 2007	
	Conceptual model	(2)Simulation	Water storage	Evaporation Recharge			
			Infiltration capacity				
Flood prediction	Probabilistic model	(1)Simulation	Stochastic rainfall process	Parameters in rainfall-	Multiple catchment	Yazdi, J. et al.,	
and runoff	Multivariate analysis	(2)Data-Calibration		runoff model	scales in Iran	2014	
Rainfall and runoff	Probabilistic model	(1)Simulation	Soil storage	Given climate regime	Hillslope scale	Freeze, 1980	
processes	hydrological	(2)Random event		hydraulic conductivity			
	mechanism	(3)Theory		landform development			
Erosion rate	Probabilistic model	(1)Data-Calculation		Bed shear stress	Laboratory scales in	Prooijen and	
	Mechanical	(2)stochastic forcing		Critical shear stress	Netherlands	Winterwerp,	
	mechanism					2010	
Erosion rate	Physical model	(1)Theory	Simulated near-bed flow	Soil structure		Sidorchuk,	
	Probabilistic model	(2)Simulation		Oscillating flow		2005	
	Conceptual model						

Erosion risk	Empirical model	(1)Data-Mapping	Erosive precipitation	Erosive precipitation Factors in RUSLE		Jiang et al.,
	Geo-statistics				scales in China	2012
Uncertainty of soil	Empirical model	(1)Simulation	Erosive precipitation Spatiotemporal Rainfall		Annual time and	Wang et al.,
loss	Geo-statistics	(2)Data-calibration	Runoff and sediment	erosivity distribution	catchment scale in	2002
	Error analysis		<u> </u>		USA	
Uncertainty and	Empirical model	(1)Hypotheses	Total rainfall volume and	Stochastic environment		Kim et al.,
variability of		(2)Data-calculation	30-minute rainfall	conditions		2016
erosion rate			intensity	Scale effect		
		Stochastic	city of factors to affect soil er	osion rate		
Soil moisture	Probabilistic model	(1)Hypotheses,	Precipitation	Temporal patterns of	Daily time and	Ridolfi et al.,
related to soil	Physical model	(2)Simulation	Evapotranspiration	rainfall property	Hillslope scale in	2003
erosion		(3)Theory				
Antecedent soil	Probabilistic model	(1)Data-Mapping	Runoff response		Daily time and	Castillo et al.,
moisture related to	Physical model	(2)Theory	Infiltration processes		multiple catchment	2003
soil erosion					scales in Spain	
Stochastic rainfall	Probabilistic model	(1)Data-Calibration	Stochastic storm	Parameters in Peak flow	Hourly-daily time	Haberlandt and
related to flood and	Conceptual model	(2)Random event	Runoff and flood	models	and multiple	Radtke, 2014
runoff		(3)Hypothesis			catchment scales in	
					Germany	
Stochastic rainfall	Physical model	(1)Simulation	Overland/channel flow	Spatiotemporal rainfall	Seasonal and annual	Lopes, 1996
related to runoff	Empirical model	(2)Data-calibration	Erosion transport	distribution	time catchment scale	
and erosion			Precipitation		in USA	
Uncertainty of soil	Empirical model	(1)Simulation	Spatiotemporal soil		Regional scales in	Wang et al.,
erodibility	Geo-statistics	(2)Data-Mapping		types, depth and parent	USA	2001
				material		
Stochastic rainfall	Probabilistic model	(1)Data-calibration	Sewer overflows	Rainfall depth and	Seasonal and annual	Andres-

	related to runoff Conceptual model (2)Theory		duration, climate			time catchment Domenech			ch et		
		Physical model			conditions		scales in S	Spain	al., 2010		
	a: the main contents of different studies focusing on the stochasticity ((uncertainty) of soil erosion	ncertainty) of soil erosion and its influencing factors						
	b: the ma	ain statistica	al methods or different t	hysical models to be emplo	oyed to describe a	and analyz	e the stocha	sticity of s	oil erosion		
	c: the ma	ain propertie	es of analyzing framewo	ork in the different studies	and the characteristics of c	lata application of	on the eval	uation of st	ochasticity	of soil erosi	on
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1069											
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1072	Table 2	Definition a	and explanation of all ra	andom events in OCIRS							
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	symbol	Physical n	neaning of random ever	nt types	Probabilistic meaning of	random event ty	pes	Influencir	g factors a	nd implicati	on
	0	observatio	on events with time ste	ep ranging from 0 to 72	random events composi	ng the sample	space of	indicating	the ge	neral stoc	hastic
		hours, inc	luding non-rainfall and	rainfall events	OCIRS system. The prob	ability $P(0) = 2$	1	weather c	onditions o	ver rainy sea	asons
	С	non-rainfa	all events with time ste	ep ranging from 0 to 24	random events, the prob	ability of C even	nts is the	implying	the extent	of evaporat	ion or
		hours, inc	luding sunny or cloudy	weather condition at hour	ratio of numbers of C	events to O eve	ents C ⊂	potential e	evapotransj	piration in w	eather
		or day sca	les		$0,0 \le P(C) \le P(0) = 1$			condition.			
	Cd	non-rainfa	all events with time	step being 24 hours,	random events composing	g the subset of C	events,	implying	the duration	1 of evaporat	tion or
		including	observed sunny or clou	idy at day scale	$Cd \subseteq C, 0 \le P(Cd) \le P(Cd)$	C)		evapotran	spiration at	a day scale	
	Ch	non-rainfa	all events with time step	being less than 24hours,	random events composing	g the subset of C	events,	influence	l by the fre	quency of ra	ainfall
		including	observed sunny or clou	udy at hour scales which	the intersection of Ch and	l Cd is null, Ch	⊑ C, Cd ∪	events ge	eneration,	and implyin	ng the
		intercepte	d by rainfall events wit!	hin a day	$Ch = C, Cd \cap Ch = \emptyset, 0 \leq$	$\leq P(Ch) \leq P(C)$		alternation	n of sunny	and rainy in	a day
	Ι	an individ	lual rainfall event with	h different precipitation,	random events, the proba	bility of I event	is ratio of	a driven	force of so	oil erosion,	which
		intensity a	and duration ranging fro	om 0 to 72 hours, the time	numbers of I events to C	D events over ob	servation	could be i	ntercepted	by vegetatic	on and
		interval be	etween two I events is r	nore than 6 hours	$I \subset 0, I \cup C = 0, I \cap C =$	$\emptyset, 0 \le P(I) \le P$	(0) = 1	transform	ed into thro	oughfall	

Ie	an extreme longest individual rainfall event whose average	random events composing the subset of I events,	rainfall events with low intensity and		
	precipitation, intensity and duration were 96.6 mm, 0.022	$Ie \subseteq I, 0 \le P(Ie) \le P(I)$	longest duration, inclining to		
	mm/min, and 73 hours, respectively.		infiltration-excess runoff generation		
Il	a second longest individual rainfall events types whose	random events composing the subset of I events,	rainfall events with low intensity and		
	average precipitation, intensity and duration were 47.3	the intersection of II and Ie is null, $II \subseteq I$, $II \cap Ie =$	long duration, inclining to infiltration-		
	mm, 0.027 mm/min, and 30 hours, respectively.	$\emptyset, 0 \le P(II) \le P(I)$	excess runoff generation		
Is	A rainfall event type spanning two days whose average	random events composing the subset of I events,	rainfall events with strongest rainfall		
	precipitation, intensity and duration were 22.7 mm, 0.042	Is \subseteq I, Is \cap Il \cap Ie = \emptyset , $0 \le P(II) \le P(I)$	intensity in middle duration, inclining		
	mm/min, and 10 hours, respectively		to runoff and sediment generation		
Iw	a rainfall event type generating within a day whose average	random events composing the subset of I events,	rainfall events with fewest and shortest		
	precipitation, intensity and duration were 9.8 mm, 0.045	$Iw \subseteq I$, $Iw \cap Is \cap Il \cap Ie = \emptyset$, $Iw \cup Is \cup Il \cup Ie =$	precipitation and duration, which is		
	mm/min, and 5 hours, respectively. it usually generates	$I, 0 \le P(Iw) \le P(I)$	different to trigger soil erosion		
_	several times within one day.				
R	runoff event type generating on vegetation land types, it	random events responding to I events, $R \subset I, R \cap$	influenced by rainfall and vegetation		
	occurs on rainfall processes, and its duration is negligible	$C = \emptyset, 0 \le P(R) < P(I)$	properties.		
S	sediment event occurring on vegetation land types, it	random events responding to R events, $S \subset R \subset$	driven by R events, and affected by		
	occurs on runoff processes, and its duration is negligible	$I, S \cap C = \emptyset, 0 \le P(S) \le P(R) < P(I)$	rainfall and vegetation properties.		

Rainy	Rainfall	Average	Average intensity	Average duration
season	event types	precipitation (mm)	(mm/min)	(hour)
2008	Iw	16.7	0.122	2.3
	Is	19.2	0.066	4.8
	11	53.2	0.032	27.7
	Ie	96.6	0.022	73.2
2009	Iw	9.0	0.027	5.6
	Is	35.4	0.059	10.0
	11	47.9	0.032	24.9
	Ie	×	×	×
2010	Iw	9.0	0.018	8.3
	Is	7.6	0.012	10.6
	11	×	×	×
	Ie	×	×	×
2011	Iw	3.3	0.031	1.8
	Is	21.5	0.040	9.0
	11	42.5	0.020	35.4
	Ie	×	×	X
2012	Iw	10.8	0.028	6.4
	Is	30.0	0.031	16.1
	11	45.5	0.023	33.0
	Ie	×	×	×
Average	Iw	9.8	0.045	4.9
	Is	22.7	0.042	10.1
	11	47.3	0.027	30.3
	Ie	96.6	0.022	73.2

 Table 3
 Main characteristics of four types of random rainfall event over five rainy seasons

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 Table 4
 Basic properties of soil, vegetation and erosion in different restoration vegetation types

Basic properties of different	^h N	Restoration vegetation types		
vegetation types		Armeniaca	Spiraea	Artemisia
		sibirica pubescens		copria
		Type 1 (T1)	Type 2 (T2)	Type3 (T3)
Topography property				
Slope aspect	9	Southwest	Southwest	Southwest
Slope gradation (%)	9	≈26.8	≈26.8	≈26.8
Slope size for each (m)	9	3×10	3×10	3×10
Soil property				
^a DBD (g cm ⁻³)	30	1.28±0.08	1.16±0.12	1.23±0.10
Clay (%)	30	11.07±2.43	11.98±3.05	9.54±1.48
Silt (%)	30	26.11 ± 1.50	25.24±3.84	26.72±2.87
Sand (%)	30	62.82±0.94	62.78±4.51	63.74±3.24
^b Texture type		Sandy loam	Sandy loam	Sandy loam
^c SHC (cm min ⁻¹)	20	0.46±0.82(a)	2.22±0.66(b)	0.50±0.60(a)
^d SOM (%)	30	1.28±0.63(a)	0.98±0.15(b)	0.90±0.09(b)
Vegetation property				
Restoration years	9	20	20	20
Crown diameters (cm)	27	211.6±15.4(c)	80.5±4.5(b)	64.1±6.3(a)
Litter layer (cm)	30	1.2±0.3(a)	3.4±1.8(b)	1.8±0.5(a)
Height (cm)	27	256.3±11.1(c)	128.3±8.3(b)	61.8±1.1(a)
LAI	27	×	2.31	1.78
^e Ave. Coverage (%)	27	85	90	90
Rainfall/Erosion property				
Times of rainfall events			130	
Times of runoff events		30/30/30	45/45/45	45/45/45
Times of sediment events		13/13/13	19/19/19	32/32/32
^f Ave. runoff depth (cm)		0.012(a)	0.014(a)	0.083(b)
^g Ave. sediment amount (g)		5.8(a)	6.8(a)	25.7(b)

a: dry bulk density; b: texture type is determined by textural triangle method based on USDA; c: field saturated hydraulic conductivity, and all the values with same letter in each row indicates non-significant difference at α =0.05 which is the same as follow rows; d: soil organic matter; e: average coverage of three restoration vegetation types over five rainy seasons; f: average runoff depth in restoration types over rainy seasons; g: average sediment yield in restoration types over rainy seasons; h: sample number.

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 Table 5
 The definition and classification of properties of rainfall soil and plant ordinal variables

Ordinal	Physical meaning of	Standard	l of influencing factor classification		
variable	classified influencing factors	Low	Middle	High	Extreme
		(L)	(M)	(H)	(E)
PREC	classified precipitation variable of a	0~15	15~30	30~60	>60
	single random rainfall event	mm	mm	mm	mm
INT	classified intensity variable of a	0~0.025	0.025~0.05	0.05~0.1	>0.1
	single random rainfall event	mm/min	mm/min	mm/min	mm/min
ASM	classified variable of the antecedent	0~5	5~10	10~20	>20
	soil moisture	%	%	%	%
SHC	classified variable of the filed	0~1	×	>1	×
	saturated hydraulic conductivity	cm/min		cm/min	
CRO	classified variable of the average	0~60	60~80	>80	×
	crown width in vegetation types	cm	cm	cm	
TLL	classified variable of the average	$0 \sim 2$	×	>2	×
	thickness of litter layers	cm		cm	
Y _R	dichotomous dependent variable to	If $Y_R = 1$,	it means that a	a random ru	noff event
	indicate whether a random runoff	has genera	tted; If $Y_R = 0$,	it means tha	t a random
	event has generation or not	runoff eve	nt has not gen	erated	
Ys	dichotomous dependent variable to	to If $Y_s = 1$, it means that a random		sediment	
	indicate whether a random sediment	event has	generated; If	Y _s =0, it me	eans that a
	event has generation or not	random se	diment event l	has not gene	erated

1129 Table 6 Logistic regression model to analysis the single effect of rainfall, plant and soil ordinal1130 variable on the erosion events presence/absence in all restoration vegetation types

Grade	PREC	INT	ASM	SHC	CRO	TLL
levels	(Low)	(Low)	(Low)	(Low)	(Low)	(Low)
		Odds	ratio of all rai	ndom runoff	events	
Extreme	^a × ^{NS}	^b 90.91***	°2.19*	Null	Null	Null
High	\times^{NS}	32.26***	2.01*	^d 0.85*	e7.53×10-3**	$^{\rm f}\times^{\rm NS}$
Middle	\times^{NS}	2.09*	1.59*	Null	7.17×10 ⁻² **	Null
	Odds ratio of all random sediment events					
Extreme	142.85***	166.67***	15.40*	Null	Null	Null
High	16.95**	125.00***	13.79**	0.78*	6.27×10 ⁻³ **	$\times^{\rm NS}$
Middle	6.09**	34.48***	6.36*	Null	2.55×10-2**	Null

a: making the low-grade of PREC ordinal variable as reference, the odds ratio of all random runoff event in extreme-grade of PREC is not significantly larger than that of low-grade of PREC; b: making the low-grade of INT ordinal variable as reference, the odds ratio of all random runoff events in extreme-grade of INT is 90.91 times significantly larger than that of low-grade of INT, under the controlled PREC condition with P≤0.001; c: making the low-grade of ASM ordinal variable as reference, the odds ratio of all random runoff events in extreme-grade of ASM is 2.19 times significantly larger than that of low-grade of ASM, under the controlled PREC and INT condition with $P \le 0.1$; d: making the low-grade of SHC ordinal variable as reference, the odds ratio of all random runoff events in high-grade of SHC is 0.85 times significantly larger than that of low-grade of SHC, under the controlled PREC, INT and ASM condition with $P \le 0.1$; e: making the low-grade of CRO ordinal variable as reference, the odds ratio of all random runoff events in high-grade of CRO is 7.53×10^{-3} larger than that of low-grade of CRO, under the controlled PREC, INT, ASM and SHC condition with $P \le 0.01$; f: making the low-grade of TLL ordinal variable as reference, the odds ratio of all random runoff event in high-grade of TLL is not significantly larger than that of low-grade of TLL, under the controlled PREC, INT, ASM, SHC and CRO condition. (Wald test statistic is applied to test the significant of odds ratio *** $P \le 0.001$, ** $P \le 0.01$, * $P \le 0.1$, NS: not significant, \times^{NS} : the nonsignificant value cannot be estimated)

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1146 Table 7 Logistic regression model to analysis the interactive effect of rainfall, plant and soil

ordinal variables on the erosion events presence/absence in all restoration vegetation types

Grade	Reference of	Soil_ASM			Plant_TLL		
levels	grade levels	ASM	ASM	ASM	ASM	TLL	TLL
		(low)	(middle)	(high)	(extreme)	(low)	(high)
			Odds	s ratio of al	l random runo	ff events	
Soil_SHC	SHC (low)	Ref.	^a 2.23 ^{NS}	3.19 ^{NS}	7.02*	Null	Null
Plant_TLL	TLL (Low)	Ref.	2.23 ^{NS}	3.19 ^{NS}	7.02*	Null	Null
Plant_CRO	CRO (low)	Ref.	^b 64.34*	70.77*	486.43**	Ref.	°0.12***
	CRO(middle)	Ref.	$\times^{\rm NS}$	2.32 ^{NS}	22.49*	Null	Null
	CRO (high)	Ref	Null	Null	Null	Null	Null
			Odds	ratio of all	sediment runc	off events	
Soil_SHC	SHC (low)	Ref.	\times^{NS}	1.22 ^{NS}	1.82 ^{NS}	Null	Null
Plant_TLL	TLL (Low)	Ref.	$\times^{\rm NS}$	1.22 ^{NS}	1.82 ^{NS}	Null	Null
Plant_CRO	CRO (low)	Ref.	$\times^{\rm NS}$	\times^{NS}	\times^{NS}	Ref.	0.33**
	CRO(middle)	Ref.	$\times^{\rm NS}$	\times^{NS}	\times^{NS}	Null	Null
	CRO (high)	Ref	Null	Null	Null	Null	Null

a: making the interactive effect of low-grade of SHC and low-grade of ASM as reference, the odds ratio of all random runoff events affected by the interactive effect of low-grade of SHC and middle-grade of ASM is 2.23 times larger than that interactive effect of low-grade SHC and low-grade of ASM under controlled rainfall conditions; b: making the interactive effect of low-grade of CRO and low-grade of ASM as reference, the odds ratio of all random runoff events affected by the interactive effect of low-grade of CRO and low-grade of CRO and middle-grade of ASM is 64.34 times significantly larger than that interactive effect of low-grade of CRO and low-grade of ASM under controlled rainfall conditions, with P \leq 0.1; c: making the interactive effect of low-grade of CRO and low-grade of TLL as reference, the odds ratio of all random runoff events affected by the interactive effect of low-grade of CRO and high-grade of TLL is 0.12 times significantly larger than that interactive effect of low-grade of CRO and low-grade of TLL, with P \leq 0.001 (Wald test statistic is applied to test the significant of odds ratio *** P \leq 0.001, ** P \leq 0.01, * P \leq 0.1, NS: not significant, ×^{NS}: the nonsignificant value cannot be estimated)

1162 Figures



Figure 1 The construction of OCIRS system : (a) a flow chart to determine all random event types in OCIRS framework; (b) the different combining patterns of rainfall and non-rainfall events in three consecutive days to form ten observed random event sequences on five rainy seasons; (c) Venn diagram to reveal the relationship among all random events types in OCIRS framework.



Figure 2 Study area and experimental design: (a) location of the Yangjuangou Catchment; (b) three restoration vegetation types including *Armeniaca sibirica* (T1), *Spiraea pubescens* (T2), and *Artemisia copria* (T3); (c) the dynamic measurement of soil moisture and data collection to provide the information about average antecedent soil moisture; (d) the measurement of field saturated hydraulic conductivity to determine the average infiltration capability; (e): the investigation of morphological properties of restoration vegetation by setting quadrats



Figure 3 The probability distribution of different random rainfall event types (Iw, Is, II, and Ie) and random non-rainfall event types (Ch and Cd) at monthly and seasonal scales from rainy season of 2008 to 2012.



Figure 4 The probability distribution of random runoff and sediment events generating in three restoration vegetation types at monthly and seasonal scales from rainy season of 2008 to 2012, the Arabic numbers and letter "T" on the abscissa indicate the month and season respectively, the same as follow figures



Figure 5 The comparison between simulation of stochasticity of runoff and sediment events by Binomial and Poisson PMFs and the observed frequencies of numbers of times of soil erosion events in three restoration vegetation type, Exp_B and Exp_P indicates the simulated values in Binomial and Poisson PMF respectively, and the histogram represents the observed values.



Figure 6 The distribution of probabilistic contribution of four random rainfall event types on anyone runoff or sediment event stochastically generating in three restoration vegetation types at monthly and seasonal scales from rainy season of 2008 to 2012



Figure 7 Morphological properties of three restoration vegetation types including the thickness of litter layer, the distribution of root system. The dashed lines indicates the diameter and depth of soil samples with approximating 10 cm and 30 cm respectively.

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Stage I: Construction & Determination

Step 1: Constructing OCIRS system Collecting and classifying influencing factors to characterize the stochastic environment

Step 2: **Determing monitoring period** From short-term to long-term monitoring of erosion events generation.

Stage II: Observation & Simulation

Step 3: **Phased adjustment of description** *Short-term*: OCIRS-Bayes to analyze stochastic erosion events *Mid-term*: OCIRS-Binomial to analyze stochastic erosion events *Long-term*: OCIRS-Poisson to analyze stochastic erosion events

Stage III: Evaluation & Management

- Step 4: **Probabilistic attribution evaluation** LRM to determine vegetation types with stronger capacity for reducing probability of erosion generation
- Step 5: **Restoration vegetation selection** Managing to select the restoration vegetation by IPA to improve soil and water conservation

Figure 8 The framework of integrated probabilistic assessment for soil erosion monitoring and restoration strategies

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