

Response to reviewer 1

The interactive modules for simulating water abstraction etc. with the PCR-GLOBWB model are described in greater detail, but these did not be used in this study. Thus the model description should focus on the considered process.

R1: We agree with reviewer and the model description will be modified to be more concise in the revised manuscript.

The model parameterisation with respect to the soil hydraulic properties needs to be better described.

R2: More description of the soil properties will be added to the revised manuscript (please also see R40).

I suggest adding some plots showing the special distribution of simulated TWS for the different DA scenarios.

R3: An illustration of the spatial distribution of both DA scenarios will be shown in Fig. 11. The following discussion will also be added in the revised manuscript **lines 644 – 653**:

“It is also worth discussing the impact of GRACE DA on the spatial pattern of the water storage estimates. To demonstrate this, the update term (ΔA in Eq. (7)) of October 2002 from EnKF 1D and 3D cases is shown in Fig. 11. Only TWSV, SMSV, and GWSV are presented, since other components (snow, surface water, and interception) are small. As discussed above, EnKF 3D shows smaller update in all components. Due to a greater amplitude of GRACE-derived TWSV over northern and southern parts of the region (see Fig. 4), the update is mostly seen there. Almost all update is limited to the soil moisture layer. Higher precipitation is generally observed over the southern part, which leads to higher groundwater recharge (and GWSV) over that region. As such, a GWSV update is clearly seen over the southern part of the region.”

In the DA scheme only TWS is considered. It is no clear, how “added” or “subtracted” water was distributed by DA to the different model storages (e.g. SM, GW, snow).

R4: As only TWSV is available from GRACE, TWSV is only used in the discussion in Sect. 6.1. However, the discussion of GRACE DA impact on individual stores are given Sect. 6.2 of the revised manuscript.

Compared to the model results the variations in GRACE determined TWS are much more pronounced. Possible reasons should be discussed in greater (e.g. influence of the pattern restauration procedure).

R5: This discussion will be added to the revised manuscript **lines 509 – 515**:

“It is seen that GRACE-derived TWSV has a greater annual amplitude compared to the model estimated TWSV. This can likely be attributed to the poor quality of the model parameter calibration and the accuracy of the meteorological input data over the data-sparse regions. In the absence of observations, model parameters are difficult to determine and only the best available knowledge (or guess) is generally used, leading to inaccurate model state estimates. Updating the water storage estimates using GRACE DA showed a clear improvement in this case.”

It is unclear if at all or how groundwater abstraction was considered in the modelling. If this was considered, why was the groundwater abstraction not considered in the DA (e.g. by updating the groundwater abstraction parameter)?

R6: In this study, the state vector only contains the water storage. Groundwater abstraction is one of PCR-GLOBWB's model parameters, and it is not included in the state vector. Therefore, the groundwater abstraction is not updated or separately estimated in this study, but it is treated. Please also see R45 for more detail.

Title: The term “semi-arid” is not correct (see below)

R7: The “semi-arid” term is used based on Zhu et al. (2015). Please see also R10.

At times TWS variations are simply termed “TWS”. This is somewhat confusing. The terms “TWS variations” or short “TWSV” should be always used.

R8: TWS variation will be changed to TWSV in the revised manuscript. Similarly, soil moisture storage variation and groundwater storage variation will be abbreviated as SMSV and GWSV.

L45: The groundwater well data should integrate of smaller areas than the catchment area of the streamflow data. Therefore, I am not convinced that this is a problem of spatial resolution.

R9: Reviewer statement is correct over a sufficiently large river basin. As GRACE spatial resolution is ~250 km or larger, the TWSV signal of the smaller basin can be easily interfered by the neighbouring basin. This is known as a leakage effect and such an effect is seen over the Hexi Corridor. Therefore, the limited spatial resolution of GRACE plays a very important role on the state estimates there.

L57-59: According to the Köppen climate classification this region belongs to “cold desert climate” (BWk).

R10: The “semi-arid” term is used based on Zhu et al. (2015); however, we also realize that much of the region has a cold desert climate, and this can be found in the submitted manuscript (line 152):

“Located next to the Gobi Desert, most parts of the region have a cold desert climate, …”

For clarity, we will include the references of both climate classifications (Zhu et al. (2015) and Peel et al. (2007)) in section 2 of the revised manuscript.

L67-68: This depends largely on the measured variable. For instance, streamwater discharge data provides integrated information for large catchment areas.

R11: We agree with reviewer. In the revised manuscript lines 68 – 70, this sentence will be written as follows:

“While streamflow gauges provide integrated information for large catchment areas, point observations of hydrometeorological variables and even groundwater levels can be very local in scope.”

L81: In addition, hydrological models typically suffer from inadequate process representations (model structure errors).

R12: The suggested statement will be added to the introduction section of the revised manuscript lines 85 – 86.

L98: “jump” of what?

R13: “jump” will be extended to “jump of the water storage estimates” in the revised manuscript line 101.

L115: What is the size of the area?

R14: The size of the individual basin varies between 41,600 and 157,000 km². This can be found in lines 149 - 151 of the submitted manuscript:

“Shiyang River Basin (41,600 km2), the Heihe River Basin (143,000 km2), the Shule River Basin (157,000 km2), and a Desert Region (152,445 km2)”

L115-118: How do you know (e.g. the watershed area of the Rhine river is much smaller than the Hexi Corridor area)? Can you provide the SNR values for these different areas?

R15: The size of the individual basin of the Hexi Corridor is smaller than the mentioned basins, Mississippi (3,202,230 km2), Rhine (185,000 km2), Mackenzie (1,743,058 km2). The SNR values of the Hexi Corridor is approximately 2.5, compared to Mississippi (SNR \approx 11), Rhine (SNR \approx 17), Mackenzie (SNR \approx 20).

L122: What is the difference between “surface water” and “inundated water”?

R16: The “surface water” in PCR-GLOBWB consists of river/channels, as well as lake and reservoir storages, while the term “inundated water” is conceptualized for the inundated water above the paddy field during the growing season. The terms are clearly described in PCR-GLOBWB literature (see e.g. Wada et al., 2014).

L128-129: In which way are the results validated against remote sensing?

R17: The validation is qualitatively analysed in terms of the correlation coefficient, Nash-Sutcliff coefficient, Root-Mean-Square different (RMSD). The statement will be added to the revised manuscript lines 131 – 133.

L147: The term “basin” is not appropriate.

R18: The term “basin” will be changed to “region” in the revised manuscript line 145.

L181: “distributed hydrological model”

R19: The term “global hydrological model” will be changed to “global distributed hydrological model” in the revised manuscript line 179.

L184-185: Also indicate the temporal resolution of the model.

R20: The statement “... and temporal resolution of 1 day” will be added to the revised manuscript lines 183 – 184.

L185-193: It is unclear, how or if at all these interactive modules for simulating water abstraction etc. have been used in this study. Clearly it was not the focus of this study. Thus I suggest removing this section incl. Appendix A.

R21: The section, including Appendix A, will be removed from the manuscript.

L197: Delete “an”

R22: “an” will be removed from the manuscript.

L208: Change “states” into “water storages”

R23: The term “states” will be changed to “water storage components” in the revised manuscript line 198.

L219: This is rather a conceptual model.

R24: Reviewer is correct, like many numerical models, it is conceptual in nature.

L230: Explain “complete to the degree and order 60”

R25: The Earth gravity field is generally presented using a set of spherical harmonic coefficients (SHC) to a certain degree and order. The GRACE CSR product is provided the gravity model up to SHC degree and order 60. Therefore, we compute the TWS variation using the SHC complete to the maximum degree and order 60 in this study.

L259: Does this increment correspond to the monthly change in TWS?

R26: The increment is not necessarily (or linearly) corresponding to the filtered TWS change. The increment rather reflects the missing signal that was caused by the filter applied. In other words, the spatial pattern of the restored TWS change (after signal restoration process applied) is not necessarily similar to the filtered TWS change (see Fig. 4a compared to Fig. 4f).

L261: Is this the general uncertainty of GRACE?

R27: Based on the previous GRACE literature (Wahr et al., 2006; Klees et al., 2008; Dahle et al., 2014), GRACE uncertainty averaged-globally is approximately 2 cm.

L263-264: By looking at Fig. 4 this procedure seems to have mainly intensified the already existing pattern. To which extent are the temporal variations in TWS estimates influenced by this procedure?

R28: The signal is generally damped after the filter is used, results in <4 cm of the TWSV amplitude (please see Fig. 4a). The signal restoration process is used to restore the mitigated signal that was caused by the filter applied. The process restores the signal back for each iteration and the TWSV amplitude becomes ~7 cm after 6 iterations (see Fig. 4f). The spatial pattern between Fig. 4a and Fig. 4f is also different (see the contour lines). As the signal restoration process acts differently (e.g., number of iteration) for different month, the temporal variations in TWSV estimates are also influenced by this procedure. Extensive discussion of the signal restoration process can be found in the given reference (e.g., Tangdamrongsub et al., 2016).

L287-289: It is well-known that global precipitation products show considerable uncertainties, which is also indicated by the low NS values. Since in-situ data is available, I suggest to correct the TRMM data product using the approach suggested by Condom et al. (2011).

R29: We agree with reviewer that correcting TRMM using the method proposed by Condom et al. (2011) is a good idea. However, since the in situ data over the Hexi Corridor is very sparse and does not cover all model grid cells, further analysis is needed to investigate the impact of the method on the spatial distribution. Particularly, the impact on higher frequency (daily) of the precipitation data used in this study (compared to monthly of Condom et al. (2001)). Also, there might be a chance of introducing artefacts into the TRMM data in the grid cells if no in situ data is available. Therefore, we do not apply any correction to TRMM data, and use the standard error the product provided to represent the data uncertainty.

L298: Actual or potential ET?

R30: “evapotranspiration” will be changed to “potential evapotranspiration” in the revised manuscript line 287.

L327-329: Actually, more appropriate data is available from other gauging stations in the Hexi Corridor for this study (see e.g. Zhang et al., 2015, 2016).

R31: We thank for reviewer’s information. However, we only had an access to limited ground observations by the time this study is conducted. More ground observations will be considered in future work.

L307-322: Because of this conversion method any comparison of groundwater storage changes from in-situ and GRACE observations will not be independent. This needs to be discussed in some detail. In addition, in the procedure described in Tangdamrongsub et al. (2015) two parameter were used instead of one. Please comment on this difference.

R32: Due to the fact that the estimated scale factor values are in line with the specific yield from the field observations (please also see R33), the bias of the estimated parameter from our approach can be considered small over the Shiyang River Basin. However, we understand reviewer's concern, and therefore one additional paragraph will be added to the conclusion section lines 809 – 815 as follows:

“The conversion approach between the groundwater head measurement and groundwater storage is proven feasible over the Shiyang River Basin. The approach delivers comparable ranges of scale factor estimates to the specific yield estimated from the field observation. However, it is noted here that the results of the conducted validation might be over-optimistic, since the well data processed with the adopted conversion procedure are not fully independent of assimilated GRACE data. The specific yield from the field observation must be used when available.”

Additionally, the difference between 1 and 2 parameters are only the bias (first parameter, “a” parameter in Tangdamrongsub et al. (2015)) becomes very small (~1e-14) when the TWS variation and head variation are considered. Therefore, Eq. (1,2) of Tangdamrongsub et al. (2015) and Eq. (2,3) in the submitted manuscript provide the same result. However, for consistency, we restore the bias term in the revised manuscript as

$$\Delta GWS_{(GRACE-\Delta SM)} + e = b + f \cdot \Delta h \quad (2)$$

$$\Delta GWS_{in situ} = \hat{b} + \hat{f} \cdot \Delta h \quad (3)$$

L317-318: Please provide a figure with the data and the regression.

R33: The figure of the regression analysis is shown below (Fig. R1). To reduce the redundancy, we do not include Fig. R1 in the manuscript, but instead we will include a discussion of the parameter estimation in the revised manuscript lines 658 – 667 as follows:

“Yang et al. (2001) showed that the specific yield values obtained from the field measurements over the Shiyang River Basin was between 0.01 and 0.3. Although, the measurement was not conducted at the well stations used in this study, the values obtained can be used as a guidance of the specific yield of the Shiyang River Basin. In this study, the head measurements were converted to storage unit with the approach described in Sect. 4.3.1. The bias term in Eq. (3) was found to be very close to zero, as the variation (mean removed) was used in the regression analysis. The estimated scale factor was 0.23, 0.04, 0.24, 0.25, and 0.32 at W1 – W5, respectively, which was in line with the values obtained from the field measurement.”

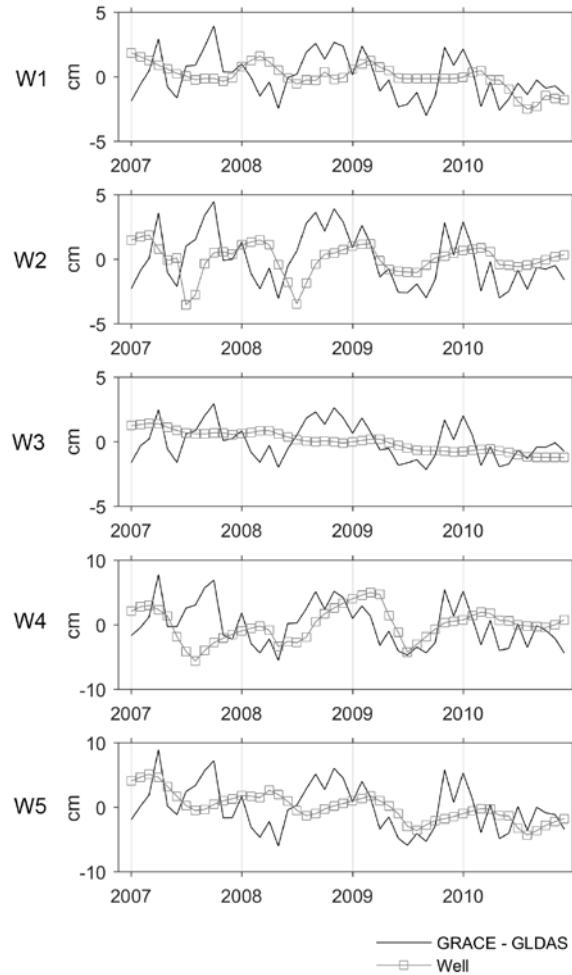


Figure R1. Regression analysis between GRACE-GLDAS and adjusted well measurements in 5 different locations.

L320: Why are you using an averaged f value to calculate the groundwater storage for each well? I would have thought that the variations in parameter f should represent local variations in storage parameters of the aquifers. Please explain the reasoning behind this procedure.

R34: The parameter is individually estimated and used for each well location. No average parameter is used. For clarity, we will extend the statement in lines 313 – 314 as follows:

“... and Δ GWS(GRACE- Δ SM) at each individual location, a bias (b), a scale factor (f) ...”

L451: Please explain how you selected these parameters (e.g. did you use a sensitivity test?).

R35: We selected these parameters based on several previous PCR-GLOBWB studies (e.g. Sutanudjaja et al., 2011, 2014), showing that these selected parameters are indeed the sensitive ones to model simulation results. For clarity, the reference will be added to the revised manuscript.

L526-527: Change into Figure 10

R36: “Fig. 9” will be changed to “Figure 10” in the revised manuscript.

L545: “on” instead of “of”

R37: “of” will be changed to “on” in the revised manuscript.

L549-550: Please provide information on the origin of these parameter values.

R38: The origin of the parameter values is given in Sutanudjaja et al. (2011, 2014), and the reference will be given in the revised manuscript.

Further information related to the origin of parameter values were provided in Appendix A of the submitted manuscript. However, they are removed based on reviewer suggestion (see R21).

The model parameters of PCR-GLOBWB are derived from several globally available datasets that are listed as follows. The Global Land Cover Characteristics Data Base Version 2.0 (GLCC 2.0, http://edc2.usgs.gov/glcc/globe_int.php) and FAO soil maps (1995) were used in order to parameterize the land cover and upper sub-surface properties. For mapping aquifers and estimating the groundwater recession coefficient, the GLobal HYdrogeology MaPS (GLHYMPS) global maps of permeability and porosity (Gleeson et al., 2014), as well as available global digital elevation models (e.g. HydroSHEDS, Lehner et al., 2008) were used. For further explanation about the PCR-GLOBWB model parameterization, the reader is referred to the technical reports (e.g. van Beek and Bierkens, 2009; van Beek, 2008); and other relevant publications (e.g. Sutanudjaja et al., 2011, 2014).

L543: How do you know that the groundwater store of the Desert Region is small.

R39: We realized that the statement is misleading and we change our statement in lines 552 – 553 as “ ...the small amplitude of the groundwater variation of this region ...”. Small GWSV over the Desert Region is presented in Fig. 10k.

L553-554: Please explain in greater detail, why higher values of K_sat and lower values of J have led to a smaller amount of water addition.

R40: We realize that the interpretation the amount of water storage in terms of K_sat and J might be misleading as they do not have a linear relationship. Instead, soil water storage capacity (SC, see Table 1) and forcing data have greater impact on the water storage estimate. Note that greater SC value leads to greater amount of water stored in soil layer, and consequently lesser water percolate to the groundwater store. Therefore, we remove the statement related to K_sat and J, and change the analysis to:

“The impact of GRACE DA on different stores was influenced by both the model parameters and the forcing data. The 4 basins have similar soil water storage capacities (see Table 3), which indicates that the basins can store similar amounts of soil water and generate similar amounts of groundwater recharge under the same rainfall conditions. However, the 4 basins received different amounts of rainfall, which resulted in different SMSV and GWSV estimates. For example, the Shiyang River Basin received the greatest amount of rainfall (~ twice of Heihe River Basin), which led to the greatest amount of the SMSV estimate (~1 cm annual amplitude). Such a large amount was also sufficient to percolate into the groundwater layer, resulting in GWSV of ~0.7 cm (see Fig. 10i and Table 2). In contrast, the Desert Region received approximately 3 times less rainfall, which led to a somewhat smaller amount of SMSV (~0.7 cm annual amplitude) and a much smaller amount of GWSV, ~0.2 cm (see Fig. 10g, k).

The above paragraph will be added to the revised manuscript lines 557 – 571.

L599-600: I wonder whether the better agreement with the GRACE DA results is due to (or at least partly due to) the scaling procedure of the piezometer data. Please add a discussion on this.

R41: Due to the fact that the estimated scale factor values are in line with the specific yield from the field observations (please also see R33), the bias of the estimated parameter from our approach can be considered small over the Shiyang River Basin. However, we understand reviewer's concern, and therefore add one additional paragraph into the conclusion of the revised manuscript lines 809 – 815 as follows:

“The conversion approach between the groundwater head measurement and groundwater storage is proven feasible over the Shiyang River Basin. The scale factor estimates produced with this approach are consistent with the specific yield estimated from the field observations. However, it is noted here that the results of the conducted validation might be over-optimistic, since the well data processed with the adopted conversion procedure are not fully independent of the assimilated GRACE data. The specific yield from the field observation must be used when available.”

L642: Clearly, predictions for G2 were improved to a lesser degree.

R42: We agree with reviewer. For clarity, the statement will be changed to “A lesser improvement was observed at G2”, lines 713 in the revised manuscript.

L647-648: These are very low amounts of precipitation, indicating very local precipitation events. It would be interesting to see the spatial distribution of these rainfall events and the resulting modelled soil moisture distribution.

R43: The maps of rainfall and SM storage estimates of the discussed events (September 2007, 2008) are shown below (Fig. R2). However, this is beyond the scope of this study, and therefore Fig. R2 is not presented in the manuscript.

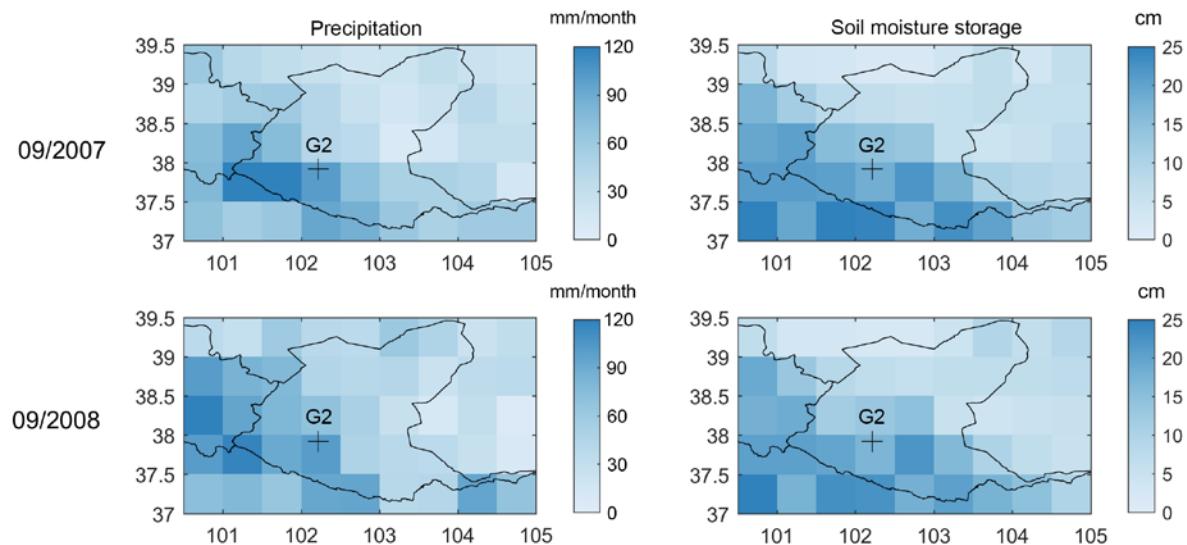


Figure R2. Monthly total precipitation (left) and SM storage estimates of September 2007 and 2008. Stream gauge location G2 is also shown.

L676-678: Why should the SM storage of the Desert Region decrease although precipitation shows an increasing trend? Please discuss.

R44: The discussion will be added to the revised manuscript lines 749 – 755 as follows:

“In the Desert Region, in contrast to other basins, the minor decreasing TWS trend of -0.1 cm/yr was dominated by loss of SM storage. This was likely caused by inaccurate model parameter calibration over the Desert Region (i.e., too large SC value). Separation of the TWS into groundwater and soil moisture store was likely incorrect. As such, the annual

signal in GWS is much less than in SM there. Therefore, GRACE update was mostly attributed to the SM component, so that a groundwater-pumping signature (Jiao et al., 2015) was seen in the SM instead of the GWS layer.”

Further discussion of this (and related) issue is also included in the conclusion, lines 792 - 793:

“It should be emphasized that GRACE does not fix a technical problem of the hydrological model, but it rather provides information which is not available otherwise.”

L712-714: Until now, there was no indication that groundwater abstraction was considered in the modelling. Please add a description. Why was the groundwater abstraction not considered in the DA?

R45: In this study, the state vector only contains the water storage. As the groundwater abstraction is a parameter of PCR-GLOBWB, it is not included in the state vector. Therefore, the groundwater abstraction is not separately estimated in this study. However, the information of groundwater abstraction is contained in GRACE observation. Once GRACE DA is applied, such information is propagated into the state vector, particularly the groundwater layer. This is clearly seen in the negative trend of updated groundwater estimates. This discussion will be included in the conclusion of the revised manuscript lines 792 – 797 as follows.

“It should be emphasized that GRACE does not fix a technical problem of the hydrological model, but rather it provides information, which is not available otherwise. Note that, in principle, the model may predict any long-term behaviour of water storage, but that information should be brought in "by hand" (e.g., via the groundwater abstraction parameter). As soon as that information is not available, reliable long-term predictions on the basis of hydrological modelling alone are conceptually impossible.”

L734-735: See comment above. Would it be possible to update the groundwater abstraction parameter?

R46: Yes, it is possible to update the model parameter together with the state vector. We will consider reviewer's suggestion in the future work.

L744: Please provide quantitative information on groundwater abstraction.

R47: As the groundwater abstraction is not estimated by our GRACE DA approach, we do not quantify the amount of groundwater abstraction in this study. The groundwater abstraction can be quantified when the parameter is estimated together with the state vector.

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Response to reviewer 2

Different GRACE gravity field models are available, CSR (this study, p6, l227ff), GFZ, JPL, CNES/GRGS (Sakumura et al 2014). Why was CSR selected and how are the differences between the different GRACE processing models for the study region. I understand that the focus of the article is on the added value of the DA, however it would be interesting to see whether GRACE is actually providing added value based on the variability in GRACE processing models.

R1: Comparing to GFZ, JPL, and CNES/GRGS, the CSR product is the only product that provides the error variance covariance matrix of the spherical harmonic coefficients. Therefore, it is selected in this study. Note here that the variance covariance matrix is the only information that reflects the true GRACE error. As this information is not available from GFZ, JPL, and CNES/GRGS, they are not considered in this study. We agree with reviewer that it would be interesting to see whether GRACE is consistently improving the water storage estimates based on different products used. The comparison can be conducted as soon as the error information from other data centre is released.

Groundwater head data can be quite complex depending on the well depth and the aquifer being pumped. So far the authors only use head data without information about the aquifer systems. Different aquifer systems also result in individual specific yields. This needs to be addressed. based on a quick literature search hydrogeologic studies (e.g. Ma et al. 2005) are available for the region. Please, do provide information on whether the wells access the same aquifer. Further, groundwater heads were converted to units of storage using a scale factor (p.8, l301ff) as specific yield data were not available. Ma et al. 2005 (and probably more papers as well) provide aquifer properties for the Shiyang basin. Given that the wells are in the same aquifer system, please, show how your units of storage compare to literature values for the region.

R2: We thank reviewer 2 for this valuable information. Unfortunately, the data we used does not come with the aquifer information, so we cannot guarantee whether the well accesses the same aquifer as in Ma et al. (2005). As such, the specific yield is computed based on the best hydrological knowledge (model) and observation. The estimated values are between 0.04 and 0.3, which is in line with the specific yield values Yang et al. (2001) determined from the pumping tests, 0.01 – 0.3. Therefore, our estimate value can be considered sufficiently accurate for the head conversion. For clarity, we add the additional statement to the revised manuscript **lines 658 – 667**:

“Yang et al. (2001) showed that the specific yield values obtained from the field measurements over the Shiyang River Basin was between 0.01 and 0.3. Although the measurements were not collected at the well stations used in this study, the values obtained can be used as a guidance of the specific yield of the Shiyang River Basin. In this study, the head measurements were converted to storage unit with the approach described in Sect. 4.3.1. The bias term in Eq. (3) was found to be very close to zero, as the variation (mean removed) was used in the regression analysis. The estimated scale factor was 0.23, 0.04, 0.24, 0.25, and 0.32 at W1 – W5, respectively, which is in line with the values obtained from the field measurement.”

Regarding the precipitation errors the RMS of TRMM was used (p12, l440). As the authors also compared TRMM to station data, was that error included as well?

R3: As the error of other precipitation products are not available, no error is included in the analysis of Sect. 4.2 to avoid the inconsistency of the comparison.

The abstract is a bit too extensive, please, shorten.

R4: The abstract will be shortened in the revised manuscript.

p2, l57-59. Provide reference

R5: References (Gong et al., 2004; Zhu et al., 2015; Cui and Shao, 2005) will be given in the revised manuscript **line 59 and 61**.

Fig. 1. Include all symbols in the figure caption (crosses). Since color is used, the river networks could also be added (1b).

R6: The symbol will be added to Fig. 1 caption of the revised manuscript **lines 1130 – 1131** as “ ...the locations of considered groundwater wells (x) and river stream gauges (+).” The river network will also be added to Fig. 1b.

p6, l208/209. Please, explain ‘the sum of different states’. What are e.g. ‘4 interception’ states?

R7: TWS variation is computed from the sum of 27 different water storage components (layers), which are 8 soil moisture layers, 2 groundwater layers, 4 interception layers, 8 snow layers, 4 inundated top water layers, and 1 surface water layer. For clarity, we revise the statement in the revised manuscript **lines 197 – 199** to:

“... the total water storage (TWS) is computed as the sum of 27 different water storage components: 8 soil moisture layers, 2 groundwater layers, 4 interception layers, 8 snow layers, 4 inundated top water layers, and 1 surface water layer.”.

p9, l331ff. What exactly was done with the NDVI values? Was the growing season length determined as the period above and below 0.2? If it was only used for visualization in Fig. 14, the section can be shortened to a couple of lines.

R8: NDVI and GWS variation were analysed together to determine if the growing season was being extended beyond the limited rainy period through groundwater extraction for irrigation. The reviewer is correct in that the growing season length is determined as the period above ~0.2. In the revised manuscript, we remove a few statements in Sect. 4.4.3 to make the section more concise.

Fig. 14a. Is the GW head relative to amsl? What is the depth to the surface?

R9: Yes, the measurement is relative to the mean sea level. For clarity, we will add an additional statement to the revised manuscript **line 295**:

“... form of piezometric heads (relative to the mean sea level), ...”

The depth from the surface is not available from the data provider, and therefore we cannot provide the value here.

References

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Response to reviewer 3

l. 368 and matrix D in Eq. (7): Burgers et al. (1998) showed that it is necessary to consider the observations as random variable, i.e. that not only an ensemble of predicted model states but also an ensemble of observations has to be considered when calculating the update of each model ensemble member. Perturbations for the observations can be drawn from the error covariance matrix R. Otherwise, the error statistics of the updated model ensemble are underestimated (i.e. not correctly treated). In a correct implementation, matrix D does not contain N identical columns as described in l. 368. This should be fixed or at least discussed by the authors.

R1: We implemented the EnKF as outlined by Evensen (2003). In our formulation, D contains the perturbed observations, i.e. each column is a replicate of the observation but perturbed with $\sim N(0, R)$. This was not articulated well in the previous version of the manuscript. The text will be corrected to make this clearer in the revised manuscript **lines 364 – 367** as follows:

“the GRACE observation vector is stored in the matrix $D_{\{m \times N\}}$, in which each column is a replicate of the observation but perturbed with random noise $\sim N(0, R)$. The analysis equation can be expressed as (Evensen, 2003): “

In addition, it is not possible to draw random errors from the full error covariance matrix of GRACE TWS changes on a 0.5x0.5 degree grid, since the matrix has a rank deficiency. This is a critical issue and should be addressed by the authors as well.

R2: In our study, the error variance-covariance matrix associated with the post-processed GRACE data was used. We did not use the original error matrix since it did not represent the filtered GRACE signal used in our study. In our covariance computation (described in Sect. 5.2.2), the localization function with correlation length similar to the Gaussian smoothing used was applied. Although the main objective of the covariance localization is to reduce the spurious correlation at long distance caused by the limited realization number, the localization also affects the correlation at short distance, and a strong correlation at a short distance becomes slightly weaker. As a result, the error variance-covariance matrix derived based on our method has a full rank. Applying localization also improved the condition number of the covariance matrix, e.g., from $\sim 10^{14}$ to $\sim 10^2$ found in our study. Similar to Eicker et al. (2014), the matrix rank and condition number were determined using Matlab functions rank and cond, respectively. We thank reviewer for the advice. The clarification regarding rank deficiency will be included in the revised manuscript **lines 433 – 436**.

l. 507-508: The standard deviations of the EnKF results are however underestimated, since the observation vector was not treated as a random variable in Eq. (7). Therefore, the error statistics of the updated model states are not correct. This should be fixed or at least discussed.

R3: Please see R1

l. 588-589: This might change after correctly estimating the updated model ensemble spread by generating perturbations for the observations (revising Eq. (7)).

R4: Please see R1

Eq. (8): Since both error covariance matrices (from the model and the observations) have a rank-defect due to (1) the fact that usually the number of model states is much larger than the number of model ensemble members and (2) GRACE cannot actually resolve TWS changes on a 0.5×0.5 degree grid, the inverse in Eq. (8) does not exist. This should be pointed out and a reference to sections 5.2.1 and 5.2.2 might be provided that describe how the authors deal with this issue.

R5: Please see R2

l. 251: GRACE observations are highly correlated on such a fine spatial resolution (similar to the above comment). Did the authors investigate this? Was this the reason to use a maximum correlation length for the observation error covariance matrix?

R6: Reviewer is correct. In our covariance computation (described in Sect. 5.2.2), the localization function with correlation length similar to the Gaussian smoothing used was applied. The localization helps to improve the matrix stability and we investigated this by checking the rank and condition number of the matrix as explained in R2.

l. 414-415: If I understand it correctly, the error correlation length is set to 250 km and TWS changes outside of this radius are assumed to not be correlated to the center grid cell. Is this reasonable? It would be helpful to investigate the correlations of points with longer distances to verify this choice. Does the "local" error covariance matrix have a full rank?

R7: As the observation error variance-covariance matrix is derived based on the application of 250 km filter radius, the correlation error at distance beyond 250 km (correlation length) does not have a crucial impact on the result. In the submitted manuscript, we demonstrate the error characteristic in Fig. 8b. From the figure, the correlation reduces significantly beyond the correlation length. Additionally, the error variance-covariance matrix derived based on our method has a full rank.

Fig. 7: In the main text (l. 414-415), it is explained that a correlation length of 250 km is used (approx. four to five 0.5×0.5 degree ($\sim 50 \text{ km} \times 50 \text{ km}$ at the equator) grid cells in each direction from the center grid cell). In Fig. 7, it is shown that only the neighboring grid cells are considered. Please clarify.

R8: Reviewer is correct. We realized that the figure caption was not explained clearly. To clarify this, we add an additional description in the figure caption lines 1158 – 1160 as follows:

“The graphic demonstrates the case of 1 pixel (0.5 degree) correlation distance. The boundary stretches farther for larger correlation distance.”

l. 419: Since the neighboring 0.5×0.5 degree grid cells are highly correlated, it is not reasonable - based on the GRACE error characteristics - to apply the EnKF without spatial error correlations on such a fine scale. A statement would be helpful to the reader.

R9: We thank reviewer for the recommendation, the statement will be added to the revised manuscript lines 399 – 400 as follows:

“Spatial correlations of model errors and observation errors were also taken into account in view of the fact that the latter are highly correlated at neighbouring $0.5^\circ \times 0.5^\circ$ grid cells.”

l. 726-727: But: The authors do not use the full error covariance matrix as directly calculated from the observations. Instead a maximum correlation length of 250 km is

assumed, and thus a part of the information within the full error covariance matrix is neglected. Therefore, the statement might be misleading.

R10: We thank for reviewer comment. To clarify this, we will modify the statement in the revised manuscript lines 830 – 832 as follows:

“...this is a reasonable price to pay as deriving the error variance-covariance matrix from the full (and only full) error covariance matrix noticeably improves the results of GRACE data assimilation.”

l. 90-91: That seems to be incorrect. Zaitchik et al. (2008) used an ensemble Kalman smoother (EnKS) approach to partition the monthly update increment (based on comparing monthly means of modeled and observed TWS changes) equally to each day of the month. GRACE TWS changes are only assimilated once per month and not every 10 days.

R11: We thank for reviewer comment. The statement will be corrected in the revised manuscript lines 197 – 199 as follows:

“...using a monthly observation value and distributing the update as daily increments (Zaitchik et al., 2008; Forman et al., 2012; Girotto et al. 2016).”

l. 95: This work adapts the method as proposed in Zaitchik et al. (2008) to a snow-dominated basin.

R12: Please see R11.

l. 98: Please also consider the disadvantage of computational costs: The method has some computational drawback since the model has to be evaluated twice over the same month.

R13: We thank for reviewer suggestion. The additional sentence will be added in the revised manuscript lines 102 – 103 as follows:

“The only price to pay is the additional computational cost of running the model twice for the same month.”

l. 106: In Forman et al. (2013), the authors did not use correlated errors for the data assimilation. They investigated for which spatial resolution errors of GRACE TWS changes might be considered as uncorrelated. According to these investigations, they assumed white noise for (sub-)basin averaged TWS changes from GRACE.

R14: We agree with reviewer. Forman et al. (2013) will be removed in this context to avoid the confusion.

l. 89-95: In this work, the authors performed an analysis of introducing the update increments completely at the beginning of a month, the end of a month or equally distributed over all days of a month. This is worth to be mentioned along with the other citations.

R15: We thank for reviewer suggestion. Girotto et al. (2016) will be cited in the revised manuscript.

l. 39-40 and l. 106-108: A first analysis of assessing the effect of considering or neglecting spatial error correlations of GRACE TWS changes was performed in Schumacher et al. (2016) in form of a synthetic experiment, for which one of the authors of this HESSD manuscript was the editor and should therefore be very familiar with the work. It seems that the paper is methodologically the closest related to the analysis presented here and,

therefore, should be cited and discussed. Findings should be compared to the findings in the published paper.

R16: At the time this study was conducted, Schumacher et al. (2016) was not published, therefore we conducted the analysis independently based on our method (proposed in this HESSD paper). However, we thank reviewer for the recommendation, and Schumacher et al. (2016) will be cited in the revised manuscript.

l. 577: This was also seen and discussed in Schumacher et al. (2016). The authors should compare their results with the findings in this paper, since the objective of both papers is to understand the effect of considering spatial error correlations of GRACE TWS changes on hydrological data assimilation results.

R17: We thank for reviewer suggestion. The suggestion will be considered in the revised manuscript.

l. 715-718: The authors should add something like "in agreement with the recommendation in Schumacher et al. (2016)."

R18: We thank for reviewer suggestion. The statement will be given in the revised manuscript lines 823 – 824.

l. 719-724: The findings in the HESSD manuscript allow for a clearer conclusion on improvements when error correlations of GRACE TWS changes are taken into account. What might be the reason for this? Differences in the study set up? Localization of model / observation error covariance matrices?

R19: The improvement is mainly due to a better representation of GRACE information in the EnKF. Ignoring error correlations in the DA led to an over-fit of the results to the observations, which led to less accurate state estimates. These explanation will be presented in the revised manuscript lines 824 – 828 as follows:

“We explain this finding by the fact that GRACE errors at the neighbouring $0.5^\circ \times 0.5^\circ$ grid cells are highly correlated. As such, the simultaneous consideration of GRACE data at multiple neighbouring cells does not reduce data noise, as it would be the case if noise were white. In other words, the white-noise assumption may severely overestimate the information content of GRACE data.”

l. 729: A reference to Schumacher et al. (2016) would strengthen this statement, since the HESSD manuscript is not the only study that concludes a benefit / more realistic GRACE data assimilation approach if implementing GRACE error correlations.

R20: We thank for reviewer for the suggestion, Schumacher et al. (2016) will be cited in the relevant context.

l. 752-753: Schumacher et al. (2016) should be added to the list of references.

R21: Schumacher et al. (2016) will be added to the list of references.

l. 755: Alternative methods have been investigated in Schumacher et al. (2016), namely a square root analysis scheme (SQRA) and the singular evolutive interpolated Kalman filter (SEIK). Especially the application of the SEIK filter showed promising results. A citation would support the authors expectation that alternative methods, e.g. the particle filter, would improve the data assimilation performance.

R22: We thank the review for the suggestion. We will consider this in the revision.

l. 583: "truth", i.e. to the independent measurements of individual water compartments. These measurements are also subject to uncertainties and not "true" values.

R23: To avoid the confusion, the statement will be changed to "Validating against the in situ groundwater and streamflow data will quantitatively reveal the performance of each approach". This is given in lines 630 – 631 of the revised manuscript.

l. 756: "true" -> better "full" (true is difficult since often unknown / poorly known)

R24: "true" will be changed to "realistic".

1 **Improving estimates of water resources in a semi-arid region by assimilating GRACE
2 data into the PCR-GLOBWB hydrological model**

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21 **Abstract**

22 An accurate estimation of water resources dynamics is crucial for proper management of both
23 agriculture and the local ecology, particularly in semi-arid regions. Imperfections in model
24 physics, uncertainties in model land parameters and meteorological data, as well as the human
25 impact on land changes often limit the accuracy of hydrological models in estimating water
26 storages. To mitigate this problem, this study investigated the assimilation of Terrestrial
27 Water Storage Variation (TWSV) estimates derived from the Gravity Recovery And Climate
28 Experiment (GRACE) data using an Ensemble Kalman Filter (EnKF) approach. The region
29 considered was the Hexi Corridor in Northern China. The hydrological model used for the
30 analysis was PCR-GLOBWB, driven by satellite-based forcing data from April 2002 to
31 December 2010. The impact of the GRACE Data Assimilation (DA) scheme was evaluated in
32 terms of the TWSV, as well as the variation of individual hydrological storage estimates. The
33 capability of GRACE DA to adjust the storage level was apparent not only for the entire
34 TWSV but also for the groundwater component. In this study, spatially-correlated errors in
35 GRACE data were taken into account, utilizing the full error variance-covariance matrices
36 provided as a part of the GRACE data product. The benefits of this approach were
37 demonstrated by comparing the EnKF results obtained with and without taking into account
38 error correlations. The results were validated against in situ groundwater data from 5 well
39 sites. On average, the experiments showed that GRACE DA improved the accuracy of
40 groundwater storage estimates by as much as 25%. The inclusion of error correlations
41 provided an equal or greater improvement in the estimates. In contrast, a validation against in
42 situ streamflow data from two river gauges showed no significant benefits of GRACE DA.

43 This is likely due to the limited spatial and temporal resolution of GRACE observations.
44 Finally, results of the GRACE DA study were used to assess the status of water resources
45 over the Hexi Corridor over the considered 9-year time interval. A really-averaged values
46 revealed that TWS, soil moisture, and groundwater storages over the region decreased with an
47 average rate of approximately 0.2, 0.1, and 0.1 cm/yr in terms of equivalent water heights,
48 respectively. A particularly rapid decline in TWS (approximately -0.4 cm/yr) was seen over
49 the Shiyang River Basin located in the southeaster part of Hexi Corridor. The reduction
50 mostly occurred in the groundwater layer. An investigation of the relationship between water
51 resources and agricultural activities suggested that groundwater consumption required to
52 maintain crop yield in the growing season for this specific basin was likely the cause of the
53 groundwater depletion.

54

55 1. Introduction

56 The focus of this study is the Hexi Corridor. It is a semi-arid region located between the
57 Gansu province of China and Mongolia (Fig. 1). A semi-arid region can be broadly classified
58 as an area on the boundary of a larger desert, receiving just enough annual precipitation (300
59 mm or less) to sustain a limited amount of agriculture (Gong et al., 2004; Zhu et al., 2015).
60 Inefficient use of the limited amount of surface water can often lead to overuse of
61 groundwater resources and salinization of the soil (Cui and Shao, 2005). This can result in
62 desertification, which not only reduces the amount of production but also may have long-term
63 effects on the local ecology. All of this holds true for the Hexi Corridor (Wang et al., 2003).

64 Improving the water resources management of semi-arid regions requires accurate knowledge
65 of the hydrological processes involved. For small areas, this can be partially obtained through
66 a network of in-situ measurement systems, such as meteorological stations, river gauges,
67 groundwater wells, evaporation trays, etc. (Dahlgren & Possling, 2007; Huo et al., 2007;
68 Kang et al., 2004; Ma et al., 2005; Du et al., 2014). While streamflow gauges provide
69 integrated information for large catchment areas, point observations of hydrometeorological
70 variables and even groundwater levels can be very local in scope. A sensor at a point several
71 kilometres away may record significantly different values. For large scales ($> 10,000 \text{ km}^2$),
72 such techniques are unlikely capable of delivering accurate results.

73 Two options for estimating the large-scale Terrestrial Water Storage Variation (TWSV) of a
74 particular region are using observations from the Gravity Recovery And Climate Experiment
75 satellite mission (GRACE, Tapley et al., 2004) or utilizing a regional or global hydrological
76 model. A number of prior studies have reported on the potential of GRACE in the estimation
77 of snow water equivalent (Niu et al., 2007), groundwater (Döll et al., 2014), and
78 evapotranspiration (Long et al., 2014) in terms of temporal and spatial variability. However,
79 GRACE only provides the total column of the water storage at a monthly time scale and large
80 spatial scales ($> 300 \text{ km}$). It is not possible to identify the contribution of separate
81 hydrological components to the TWSV from GRACE data alone. On the other hand, a
82 hydrological model can be used to estimate the individual storage components at very high
83 spatial and temporal scales. The major drawback of the model approach is mainly the

84 significant uncertainties influenced by the quality of the model parameter calibration and the
85 accuracy of the meteorological input data. In addition, hydrological models may suffer from
86 inadequate process representations (model structure errors).

87 Data Assimilation (DA) can be employed to combine the strengths of GRACE and
88 hydrological models while mitigating their respective weaknesses. A number of studies have
89 shown that GRACE DA can be used to improve the estimation of groundwater and
90 streamflow (Zaitchik et al., 2008; Tangdamrongsub et al., 2015), snow water equivalent
91 (Forman et al., 2012; Su et al., 2012), and as well as for evaluation of drought events
92 (Houborg et al., 2012; Li et al., 2012). Different temporal and spatial resolution of GRACE
93 observations and hydrological models require proper design of the DA scheme. Several DA
94 schemes have been developed to distribute GRACE observations into the model, which
95 include using 5-day interpolated observations and updating the model every 5 days
96 (Tangdamrongsub et al., 2015); using a monthly observation value and applying the model
97 update only at the end of the month (Eicker et al., 2014); using a monthly value and
98 distributing the update as a daily increments (Zaitchik et al., 2008; Forman et al., 2012;
99 Girotto et al. 2016). Although all DA schemes are acceptable, the scheme proposed by
100 Forman et al. (2012) is advantageous because it does not require an interpolation of the
101 observations and can reduce the spurious jump of the water storage estimates caused by
102 applying the update at the end of the month only. The only price to pay is the additional
103 computational cost of running the model twice for the same month. A scheme similar to
104 (Forman et al., 2012) is used in this study. Spatial disaggregation is also needed to reconcile
105 the difference in horizontal resolution between the observations and the model. Recent studies
106 by Eicker et al. (2014) and Schumacher et al. (2016) suggested including the GRACE
107 variance-covariance error information in the spatial disaggregation step. Both studies
108 proposed using 500-km GRACE spatial resolution to mitigate the ill-posedness of the error
109 covariance matrices in the spatial domain. In line with Eicker et al. (2014) and Schumacher et
110 al. (2016), the assimilation scheme in this study accounts for spatially correlated errors by
111 using full error variance-covariance matrices of GRACE data. This study will show that
112 considering the GRACE error correlations leads to an improvement of the state estimates.
113 Particularly, the Signal-to-Noise Ratio (SNR) of the TWSV is much lower than in the river
114 basins considered in the previous studies, e.g., Mississippi (Zaitchik et al., 2008), Rhine
115 (Tangdamrongsub et al., 2015), and Mackenzie (Forman et al., 2012).

116 Approximately 9 years of GRACE data – between April 2002 and December 2010 – are
117 considered in this study. GRACE observations are assimilated into the PCRaster Global
118 Water Balance (PCR-GLOBWB; Van Beek et al., 2011; Sutanudjaja et al., 2014; Wada et al.,
119 2014) hydrological model over the Hexi Corridor. TWS is computed from PCR-GLOBWB as
120 the sum of all the hydrological components (soil moisture, groundwater, surface water,
121 inundated water, interception, and snow). The previous studies showed very good agreement
122 of PCR-GLOBWB based estimates with GRACE observations in several river basins (Wada
123 et al., 2014; Tangdamrongsub et al., 2016). However, the performance of PCR-GLOBWB has
124 not yet been evaluated over the Hexi Corridor. In addition, to date the model has not been
125 incorporated into any GRACE DA scheme, making this study the first attempt to do so.

126 Investigating the added value of GRACE DA in the Hexi Corridor is the main objective of
127 this study.

128 First of all, the impact of GRACE DA and the effect of taking correlations in GRACE errors
129 into account are assessed. Both the total terrestrial water storage and the individual
130 hydrological storage compartments are considered.

131 Next, the results of the GRACE DA are validated with independent in-situ data. The
132 agreement is analysed in terms of the correlation coefficient, Nash-Sutcliff coefficient, and
133 Root-Mean-Square difference (RMSD). The groundwater storage variation (GWSV) and
134 streamflow estimates after GRACE DA are validated with the well and river stream gauge
135 measurements, respectively.

136 Finally, results from this GRACE DA study are used to assess the status of water resources
137 over the Hexi Corridor. The connections between the water storage (including groundwater
138 consumption) and agriculture in the area are also presented and discussed. At that stage, we
139 use precipitation data from the Tropical Rainfall Measuring Mission (TRMM; Huffman et al.,
140 2007) and the Moderate Resolution Imaging Spectroradiometer (MODIS) derived Normalized
141 Difference Vegetation Index (NDVI; Huete et al., 2002).

142

143 2. Study region

144 The Hexi Corridor is a long and narrow area between the Qilian Mountain range and southern
145 Mongolia (Fig. 1a). The region's elevation ranges from 5,200 m in the southern upstream area
146 (Qilian Mountains) to 900 m in the northern downstream zone (Inner Mongolia) (Fig. 1b).

147 The region is comprised of four typical inland arid and semi-arid regions (Zhu et al., 2015):
148 the Shiyang River Basin ($41,600 \text{ km}^2$), the Heihe River Basin ($143,000 \text{ km}^2$), the Shule River
149 Basin ($157,000 \text{ km}^2$), and a Desert Region ($152,445 \text{ km}^2$) (Geng and Wardlaw, 2013; Zhu et
150 al., 2015). Located next to the Gobi Desert, most parts of the region have a cold desert climate
151 (Peel et al., 2007), where precipitation is relatively low to sustain vegetation or crops.

152 Approximately 60 to 80 % of the annual rainfall is concentrated during the timeframe from
153 June to September. The inland rivers mainly originate from the Qilian Mountains and
154 disappear after entering the midstream/downstream plains and oases. As such, the southern
155 part of the region is more favourable for agriculture.

156 The four basins have distinct characteristics. First, the smallest river basin, Shiyang, has 8
157 main river streams, including the Xida and Xiying Rivers (Fig. 1c). The annual rainfall and
158 the mean temperature are approximately 250 mm and 5 °C (Fig. 2a, b), respectively. The
159 Shiyang River Basin is considered the wettest basin compared to the others, with relatively
160 high mean total renewable annual water resources of approximately 1.66 billion m^3 (Zheng et
161 al., 2013). However, a highly developed economy and population growth in the past decade
162 have resulted in a severe water resources overexploitation problem (Zheng et al., 2013). The
163 Heihe River Basin has a semi-arid climate and the mean daily temperature of ~6 °C (Fig. 2d).
164 The average annual rainfall is ~150 mm (Fig. 2c) with high heterogeneity both in temporal

165 and spatial distribution. The mean total annual available water resources are estimated at 3.7
166 billion m³ (Hu, 2015). Similar to the Shiyang River Basin, increased water exploitation,
167 increasing population, and changing climate have aggravated the damage to the downstream
168 ecology. The Shule River Basin has an arid climate, the mean temperature there is around 4
169 °C (Fig. 2f), and the average annual rainfall is only approximately 98 mm (Fig. 2e).
170 Compared to the Shiyang River Basin, the Shule River Basin is approximately four times as
171 large in terms of surface area, but has similar mean total annual water resources, ~1.6 billion
172 m³ (Hu, 2015). The district irrigation areas are mainly located in the middle of the Shule
173 River Basin. Agricultural water consumption accounts for more than 80% of the total water
174 use. Finally, the Desert Region has an extreme continental desert climate with an average
175 temperature of 8 °C, and the annual rainfall of ~130 mm. Extensive groundwater abstraction
176 was also observed over the region (Jiao et al., 2015).

177

178 3. Hydrology model

179 The [global distributed hydrological model](#) PCR-GLOBWB (van Beek et al., 2011;
180 Sutanudjaja et al., 2016) simulates spatial and temporal continuous fields of fluxes and
181 storages in various water storage components (soil moisture, groundwater, surface water,
182 inundated water, interception, and snow). The model version used here (Sutanudjaja et al.,
183 2016) has a spatial resolution of 30 arc minutes (approximately 50 km at the equator), [and a](#)
184 [temporal resolution of 1 day](#). Figure 3 illustrates the structure of PCR-GLOBWB model. The
185 model includes 2 soil layers (SM_{upp}, SM_{low}), an underlying hydrologically active and
186 replenishable groundwater (GWS_{active}) layer, a non-renewable groundwater (GWS_{fossil}) layer,
187 as well as interception, surface water, and snow stores. The non-renewable groundwater is
188 available for abstraction to satisfy water demands once the overlying hydrologically active
189 groundwater storage is depleted. For soil, snow, inundated top water, and interception stores,
190 an individual grid cell is divided into sub-grids associated with different types of topography,
191 vegetation phenology, and soil properties, as well as land cover types. Specifically, there are 4
192 types of land covers defined: short natural vegetation, tall natural vegetation, irrigated non-
193 paddy field, and irrigated paddy field. Soil components include the upper layer (SM_{upp}, 0 – 30
194 cm) and the lower layer (SM_{low}, 30 – 150 cm). The snow component includes snow water
195 equivalent (SWE), as well as snow free water (SFW) representing the storage of melted snow.
196 The water stored in the stream channels and lakes is also included in the TWS estimate. Based
197 on the structure of PCR-GLOBWB, the total water storage (TWS) is computed as [the sum of](#)
198 [27 different water storage components: 8 soil moisture layers, 2 groundwater layers, 4](#)
199 [interception layers, 8 snow layers, 4 inundated top water layers, and 1 surface water layer.](#)

200 For each grid cell and for each daily time step, the model determines the water balance in two
201 vertically stacked soil layers and the groundwater store. The model also computes the vertical
202 water exchanges between the soil layers and between the inundated top water layer and the
203 atmosphere, i.e. rainfall and snowmelt, percolation and capillary rise, as well as evaporation
204 and transpiration fluxes. The active groundwater store underlies the soil, is fed by net
205 groundwater recharge, discharges to baseflow as a linear reservoir, and is exempt from the

206 direct influence of evaporation and transpiration fluxes. However, capillary rise from the
 207 active groundwater store can occur depending on the simulated groundwater storage, the soil
 208 moisture deficit, and the unsaturated hydraulic conductivity. Fluxes are simulated according
 209 to the different land cover types. The model includes a physically-based scheme for
 210 infiltration and runoff, resulting in the direct runoff, interflow, as well as groundwater
 211 baseflow and recharge. River discharge is calculated by accumulating and routing the specific
 212 runoff along the drainage network. For further details, including model parameterization, the
 213 reader is referred to the technical reports and other relevant publications (van Beek and
 214 Bierkens, 2009; van Beek, 2008; Sutanudjaja et al., 2011, 2014).

215

216 4. Data and data processing

217 4.1 GRACE data

218 The GRACE gravity product release 5 (RL05), generated by the University of Texas at
 219 Austin's Center [for](#) Space Research (CSR, Bettadpur, 2012), was used as input. The product
 220 consists of monthly sets of spherical harmonic coefficients (SHC) complete to degree and
 221 order 60. On this basis, TWSVs were obtained for the study period between April 2002 and
 222 December 2010. The GRACE data were further processed in this study as follows:

- 223 • SHCs of degree 1 provided by Swenson et al. (2008) were restored, and all 5
 224 coefficients of degree 2 were replaced by the values estimated from satellite laser
 225 ranging (Cheng and Tapley, 2004).
- 226 • SHC variations were computed by removing the long-term mean (computed between
 227 April 2002 and December 2010) from each monthly solution.
- 228 • A destriping filter (Swenson and Wahr, 2006) was applied to the SHC variations. The
 229 filter used a 5th degree polynomial (Savitsky-Golay) over a 5-point window to remove
 230 the correlations; orders below 8 remained unchanged.
- 231 • An additional 250-km radius Gaussian smoothing (Jekeli, 1981) was applied to SHC
 232 variations to suppress high-frequency noise, and the TWS variations ($\Delta\sigma$ [m]) were
 233 then computed using (Wahr et al 1998)

$$234 \Delta\sigma(\theta, \phi) = \sum_{l=1}^{60} \sum_{m=-l}^l W_l \frac{s_l}{\frac{a_e(2l+1)}{3(1+k_l)} \frac{\rho_e}{\rho_w}} \Delta\bar{C}_{lm} \hat{Y}_{lm}(\theta, \phi), \quad (1)$$

235

236 where θ, ϕ are co-latitude and longitude in spherical coordinates, $\Delta\bar{C}_{lm}$ is the SHC
 237 variations of degree l and order m , \hat{Y}_{lm} is the normalized surface spherical harmonic,
 238 W_l is the Gaussian smoothing function, S_l is a scaling factor used to convert
 239 dimensionless coefficients to TWS in terms of Equivalent Water Heights (EWH), a_e
 240 is the semi-major axis of the reference ellipsoid, k_l is the load love number of degree
 241 l , ρ_e and ρ_w are the average density of the Earth and water, respectively. In this study,
 242 the TWS variations were computed at every 0.5°x0.5° grid cell. This cell size was
 243 selected through trial and error as a balance between performance and resolution.

243 In general, filters suppress not only noise but also the genuine TWSV signal, and are a well-
244 known source of signal leakage. To address this, a signal restoration method (Chen et al.,
245 2014; Tangdamrongsub et al., 2016) was employed. The method iteratively determined the
246 possible signal reduction caused by the [Gaussian](#) filter applied and added it back to the
247 filtered signals. The errors of the procedure grew with the number of iterations, requiring a
248 proper selection of the convergence criterion. In this study, the criterion was chosen
249 empirically: the signal restoration process was iteratively repeated until the increment in every
250 grid cell inside the Hexi Corridor became smaller than 0.5 cm. This value is 2-3 times smaller
251 than the GRACE uncertainty (Wahr et al., 2006; Klees et al., 2008; Dahle et al., 2014). Figure
252 4 demonstrates the signal restoration for October 2002. The convergence criterion was met
253 after approximately 6 iterations. The signal over the mountain range and Inner Mongolia
254 became apparent after the signal restoration was applied (see Fig. 4f).

255 **4.2 Forcing data**

256 The forcing data required by PCR-GLOBWB are precipitation, air temperature, and potential
257 evapotranspiration. Tangdamrongsub et al. (2015) showed that the use of high-quality
258 precipitation data [might](#) lead to better estimates of hydrological fluxes (e.g., TWSV and
259 streamflow). In principle, local precipitation and surface temperature measurements could be
260 obtained from the China Daily Ground Climate Dataset provided by the China Meteorological
261 Data Sharing Service System (<http://cdc.cma.gov.cn/home.do>). A total of 23 weather stations
262 were found over the Hexi Corridor (see Fig. 1b). However, the measurements were spatially
263 sparse and did not cover the entire region. Therefore, the global precipitation data were used
264 to achieve a better spatial coverage. Four global precipitation products were considered for
265 inclusion:

- 266 • The European Centre for Medium-range Weather Forecasts (ERA-Interim, spatial
267 resolution: $0.75^\circ \times 0.75^\circ$; Dee et al., 2011)
- 268 • The Tropical Rainfall Measuring Mission (TRMM 3B42, spatial resolution: 0.25°
269 $\times 0.25^\circ$; Huffman et al., 2007; Kummerow et al., 1998)
- 270 • The Climate Research Unit dataset (CRU, spatial resolution: $0.5^\circ \times 0.5^\circ$; Mitchell and
271 Jones, 2005; van Beek, 2008)
- 272 • The Princeton's Global Meteorological Forcing Dataset (Princeton, spatial resolution:
273 $0.5^\circ \times 0.5^\circ$; Sheffield et al., 2005)

274 To select the best product, the global precipitation values were [first](#) interpolated to the
275 weather station locations and then the correlation coefficient, Nash-Sutcliffe (NS) coefficient,
276 and RMSD between the interpolated and observed ground data were calculated. The mean
277 values of the statistical estimates are shown in Fig. 5a. Overall, TRMM provided the best data
278 quality, with the highest correlation (~0.85) and NS coefficients (~0.46), and an RMSD
279 approximately 2–3 mm lower than other products. The high spatial resolution of TRMM is
280 probably the reason for its better performance. Therefore, this product was chosen as the
281 precipitation input. The low NS coefficient in all 4 cases suggests that the coarse spatial
282 resolution of the global precipitation datasets prevents them from capturing all the local
283 precipitation events.

284 A similar procedure was used to compare the air temperature data from ERA-Interim, CRU,
285 and Princeton. The statistical estimates are shown in Fig. 5b. Although the results from all
286 products were very similar, CRU provided the highest data quality in terms of correlation and
287 RMSD values, and therefore, it was used as the temperature input. As far as potential
288 evapotranspiration is concerned, few data are available for this region, so the data from (van
289 Beek, 2008) were used.

290 **4.3 Validation data**

291 **4.3.1 Groundwater**

292 Monthly groundwater well measurements at 5 locations (Fig. 1c) were obtained from the
293 ground network maintained by the Shiyang River Basin Management Bureau, and Institute of
294 Water Resources and Hydropower of Gansu Province. The in situ data were provided in the
295 form of piezometric heads (relative to the mean sea level), which needed to be converted to
296 units of storage. For such a task, several parameters, e.g., storage coefficient and specific
297 yield are required, but they are not available over the Hexi Corridor. To solve that problem, a
298 scale factor computed using the information from GRACE and soil moisture (SM) from the
299 Global Land Data Assimilation System (GLDAS, Rodell et al., 2004) was used for the
300 conversion using the approach outlined by Tangdamrongsub et al. (2015). As discussed in
301 Tangdamrongsub et al. (2015), it is ideally preferred to use the in-situ soil moisture data to
302 represent the SM term, but they are not available at the well locations. The soil moisture
303 estimated from remote sensing was also not appropriate due to the limitation of the
304 penetration depth. The use of SM from PCR-GLOBWB is avoided to reduce the bias when
305 compared the adjusted well measurements to the final DA result. Therefore, the GLDAS
306 derived SM was used.

307 The adjustment procedure was as follows. First, GLDAS-based soil moisture storage
308 variations (SMSV) were removed from GRACE-derived TWSV. Four variants of GLDAS
309 model (NOAH, CLM, MOSAIC, and VIC; see Rodell et al., 2004) were considered and the
310 average SMSV value was calculated. Taking into account that SMSV and groundwater
311 storage variations (GWSV) are the major contributions to TWS variations, this resulted in
312 GWSV (GWSV_(GRACE-SMSV)). Then, by conducting a regression analysis between the monthly
313 time-series of piezometric head variation (Δh) and $\Delta GWS_{(GRACE-SMSV)}$ at each individual
314 location, a bias (b) and a scale factor (f) were estimated using the following linear
315 relationship:

316
$$\Delta GWS_{(GRACE-SMSV)} + e = b + f \cdot \Delta h, \quad (2)$$

317 where e indicates the observation error. Finally, the estimated bias (\hat{b}) and scale factor (\hat{f})
318 were used to convert the in situ head measurements into groundwater storage variation
319 (GWSV_{in situ}) as:

320
$$GWSV_{in situ} = \hat{b} + \hat{f} \cdot \Delta h. \quad (3)$$

321

322 **4.3.2 Streamflow**

323 Monthly river gauge data were obtained from the same data centre as the groundwater
324 measurements. Due to the coarse spatial resolution of PCR-GLOBWB, it models only the
325 main river streams. Therefore, the gauge measurements of small river streams, as well as the
326 gauge measurements that contained many data gaps (i.e., more than 24 months), were
327 excluded. As a result, the measurements from only 2 gauges – at Xida and Xiying Rivers (see
328 Fig. 1c) – were used in this study.

329 **4.4.3 Normalized Difference Vegetation Index (NDVI)**

330 NDVI (Carlson and Ripley, 1997) is an indicator of vegetation health or “greenness”. In this
331 study, NDVI and GWS were analysed to determine if the growing season was being extended
332 beyond the limited rainy period through groundwater extraction for irrigation. NDVI was
333 computed from the MODIS 8-day, 500-m spatial resolution surface reflectance product
334 (Vermote et al., 2011) based on data from Aqua satellite (MYD09A1 product). Based on the
335 location of the in situ groundwater measurements, the MODIS tiles h25v05 and h26v05 were
336 selected. First, the data were quality controlled to exclude pixels with cloud cover. The 8-day
337 NDVI was then computed as (Huete et al., 2002)

338
$$NDVI = \frac{\rho_{NIR} - \rho_R}{\rho_{NIR} + \rho_R}, \quad (4)$$

339 where ρ_{NIR} and ρ_R are the observed surface reflectances in the near-infrared and red portions
340 of the electromagnetic spectrum, respectively. The monthly-averaged NDVI was then
341 computed based on the derived 8-day NDVI values.

342

343 **5. Methodology and implementation**

344 **5.1 Ensemble Kalman Filter (EnKF)**

345 The Ensemble Kalman Filter (EnKF; Evensen, 2003) is used to assimilate GRACE derived
346 TWSV into the PCR-GLOBWB model. The EnKF works in two steps, a forecast step and
347 analysis (update) step. The forecast step involves propagating the states forward in time using
348 the model (PCR-GLOBWB). Identical to how the EnKF is implemented by Forman et al.
349 (2012), the state vector (ψ in this study) is an $nm \times 1$ vector, where $n = 27$ is the number of
350 TWS-related states from PCR-GLOBWB (see Sect. 3), and m is the number of model grid
351 cells. The model estimates are related to the GRACE observations by

352
$$\mathbf{d} = \mathbf{H}\psi + \boldsymbol{\epsilon}; \boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, \mathbf{R}), \quad (5)$$

353 where \mathbf{d} is an $m \times 1$ vector containing the GRACE observations for the month of interest, and
354 \mathbf{H} is a measurement operator which relates the PCR-GLOBWB state ψ to the observation
355 vector \mathbf{d} . Notice that the number of observations is equal to the number of grid cells because
356 the GRACE-based estimates are obtained for all the grid cells of the PCR-GLOBWB model
357 (see Sect. 4.1). The uncertainties in the observations are given in the random error $\boldsymbol{\epsilon}$, which is

358 assumed to have zero mean and covariance matrix $\mathbf{R}_{m \times m}$. As the sum of all state elements at
 359 a given cell is equal to TWSV, the \mathbf{H} matrix is defined as:

$$360 \quad \mathbf{H} = \left[\begin{pmatrix} (1 1 1 \dots 1)_{1 \times n} & 0 & \dots & 0 \\ 0 & (1 1 1 \dots 1)_{1 \times n} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & (1 1 1 \dots 1)_{1 \times n} \end{pmatrix} \right]_{m \times nm}. \quad (6)$$

361 Let the ensemble of the states be stored in a matrix $\mathbf{A}_{nm \times N} = (\boldsymbol{\psi}_1, \boldsymbol{\psi}_2, \boldsymbol{\psi}_3, \dots, \boldsymbol{\psi}_N)$, where N
 362 is the number of ensemble members. Then, the ensemble perturbation matrix is defined as
 363 $\mathbf{A}' = \mathbf{A} - \bar{\mathbf{A}}$, where the matrix $\bar{\mathbf{A}}$ is of the same size as \mathbf{A} and filled in with the mean values
 364 computed from all ensemble members. Similarly, the GRACE observation vector is stored in
 365 the matrix $\mathbf{D}_{m \times N} = (\mathbf{d}_1, \mathbf{d}_2, \mathbf{d}_3, \dots, \mathbf{d}_N)$, in which each column is a replicate of the
 366 observation but perturbed with random noise $\sim \mathcal{N}(\mathbf{0}, \mathbf{R})$. The analysis equation can be
 367 expressed as (Evensen, 2003)

$$368 \quad \mathbf{A}^a = \mathbf{A} + \Delta \mathbf{A} = \mathbf{A} + \mathbf{K}(\mathbf{D} - \mathbf{H}\mathbf{A}) \quad (7)$$

369 with

$$370 \quad \mathbf{K} = \mathbf{P}_e \mathbf{H}^T (\mathbf{H} \mathbf{P}_e \mathbf{H}^T + \mathbf{R})^{-1}, \quad (8)$$

371 where $\mathbf{A}^a_{nm \times N}$ is the updated model state, $\Delta \mathbf{A}_{nm \times N}$ is the update from Kalman filter, and
 372 $\mathbf{K}_{nm \times m}$ is the Kalman gain matrix. The model error covariance matrix $(\mathbf{P}_e)_{nm \times nm}$ is
 373 computed as

$$374 \quad \mathbf{P}_e = \mathbf{A}'(\mathbf{A}')^T / (N - 1). \quad (9)$$

375 The matrix \mathbf{R} is the error variance-covariance matrix of GRACE data in the spatial domain, its
 376 computation is discussed in Sect. 5.2.2.

377 In the initialization phase, which was needed to obtain the initial states, the model was spun
 378 up between 1 January 2000 and 31 December 2000 as a hot start. This time interval was
 379 sufficient to reach the dynamic equilibrium. The initial state $\boldsymbol{\psi}$ for 31 December 2000
 380 obtained this way was perturbed to yield $N = 100$ ensemble members $\boldsymbol{\psi}_i, i = 1, 2, 3, \dots, N$.
 381 The N ensemble runs between 1 January 2001 and 31 March 2002 were then conducted
 382 independently based on the perturbed initial states. This resulted in an ensemble spread of the
 383 estimated states. The model was then propagated in time between 1 April 2002 and 31
 384 December 2010 without assimilating any observation. This case is referred to hereafter as the
 385 Ensemble Open Loop (EnOL). For the EnKF, the model was also propagated beginning from
 386 1 April 2002, but the observations (when available) were assimilated.

387 The processing diagram is shown in Fig. 6, and follows the methodology introduced by
 388 Forman et al. (2012). The state is first propagated in time from the first to the last day of the
 389 month without applying DA, and the monthly averaged states are calculated from the daily
 390 values. When the GRACE observation for that month is available, the DA routine is activated
 391 (otherwise, the model continues propagating to the next month without applying DA). The

392 DA routine [computes the monthly averaged](#) update $\Delta\mathbf{A}$ of the TWS-related states, [cf.](#) Eq. (7).
 393 The daily increment (DINC) of the update is then computed by dividing the monthly averaged
 394 update by the total numbers of days in that month ($\text{numday}_{\text{month}}$). The model propagation is
 395 then restarted (second run), using the last day of the previous month ($\text{month}-1$, $\text{numday}_{\text{month}-1}$)
 396 as the initial state. In this second run, the DINC is added to the [current](#) states every day up to
 397 the last day of the month. The DA scheme is repeated [for each month up](#) to the end of the
 398 study period.

399 Spatial correlations of model [errors](#) and observation errors were also taken into account [in](#)
 400 [view of the fact that the latter are highly correlated at neighbouring \$0.5^\circ \times 0.5^\circ\$ grid cells](#). De
 401 Lannoy et al. (2009) proposed a so-called 3D-Fm (3-dimentional fine scale with multiple
 402 observation) approach, which is called EnKF 3D in this paper. The approach only considers
 403 the spatial correlations between the neighbouring grid cells. In this study, the neighbouring
 404 grid cells were assumed to be the ones inside the Gaussian smoothing radius applied, i.e., 250
 405 km. This reduced the computational cost, as only a small subset of cells pairs was considered
 406 instead of all cells pairs. That approach was applied not only to observation errors, but also to
 407 model errors in TWSV and TWS-related components in this study. The EnKF 3D scheme is
 408 illustrated in Fig. 7. For a particular grid cell (centre grid cell), all TWS-related components
 409 of the neighbouring grid cells and the centre grid cell are used to form the state ($\mathbf{A}^s_{np \times N}$) and
 410 observation ($\mathbf{D}^s_{p \times N}$) matrices, where p is the number of the considered grid cells. The matrix
 411 notation with superscript s (e.g., \mathbf{A}^s) is only used to emphasize the cell-dependent version, and
 412 it can be substituted into the original matrix notation (e.g., \mathbf{A}) in Eqs. (5–9). It is emphasized
 413 here that EnKF 3D involves only p grid cells instead of all m grid cells. As such, the
 414 measurement operator, model error covariance matrix, and observation error covariance
 415 matrix become $\mathbf{H}^s_{p \times np}$, $(\mathbf{P}_e^s)_{np \times np}$, and $\mathbf{R}^s_{p \times p}$, respectively. The EnKF was then applied and
 416 the states of the centre grid cell (only) were updated. The procedure was repeated through all
 417 grid cells. To investigate the impact of including spatial correlations of errors, the EnKF 1D
 418 was also considered. The EnKF 1D scheme is similar to EnKF 3D, but the spatial correlations
 419 are omitted (i.e., the off-diagonal elements of the covariance matrices \mathbf{P}_e^s and \mathbf{R}^s are set to
 420 zero).

421 Furthermore, sampling errors caused by finite ensemble size might lead to spurious
 422 correlations in the estimated model error covariance matrices (Hamill et al., 2001). To reduce
 423 such an effect, a distance-dependent localization function is applied to \mathbf{P}_e^s (pair-wise). In this
 424 study, the Gaussian function ($c(\alpha)$) (Jekeli, 1981) was used [for that](#):

$$425 \quad c(\alpha_{j_1, j_2}) = \frac{e^{-b[1-\cos(\alpha_{j_1, j_2}/a_e)]}}{1-e^{-2b}} \quad (10)$$

$$426 \quad \text{with } b = \frac{\ln(2)}{1-\cos(L/a_e)}, \quad (11)$$

427 where α_{j_1, j_2} is the distance on the Earth's surface between two grid cells (j_1 and j_2), and L is
 428 the correlation distance. The variogram analysis was used to derive the TWSV correlation
 429 distance (L) of PCR-GLOBWB, assuming that it is similar to the correlation distance of
 430 model errors. It was found to be approximately equal to 110 km over the Hexi Corridor. For

431 GRACE observations, to ensure that the spurious error correlations at distances greater than
432 the Gaussian smoothing distance, 250 km, are insignificant, the localization applied to \mathbf{R}^s was
433 based on $L = 250$ km. The localization also makes the correlations at short distances slightly
434 weaker. As a result, the condition number of the error covariance matrix is increased. In this
435 study, for instance, the condition number increased from $\sim 10^{14}$ to $\sim 10^2$. Thus, this matrix had
436 a full rank after localization (see Sect. 5.2.2 for a further discussion).

437

438 **5.2 Errors of PCR-GLOBWB model and errors in GRACE observations**

439 **5.2.1 Model errors**

440 The two primary sources of considered errors in the PCR-GLOBWB model are the
441 meteorological forcing data and the model parameters. For forcing data, the precipitation
442 uncertainties were quantified as the RMS error provided by the TRMM product (Huffman,
443 1997). The uncertainties of temperature and potential evapotranspiration were not provided as
444 parts of the corresponding products, and therefore errors of 2°C, and 30% of the nominal
445 potential evapotranspiration value were assumed, respectively. The error levels were chosen
446 through trial-and-error, mainly to allow the ensemble to grow between updates. The
447 precipitation and potential evapotranspiration were perturbed with additive lognormal noise
448 while the temperature was perturbed with additive Gaussian noise. The forcing data
449 uncertainties were assumed to be spatially correlated, which was accounted for using an
450 exponential decay function. Based on a variogram analysis, the correlation distances of
451 precipitation, temperature and potential evapotranspiration were found to be approximately
452 150 km, 450 km, and 450 km, respectively.

453 As far as model parameters are concerned, a total of 15 TWS-related parameters (see Table 1,
454 Sutanudjaja et al., 2011, 2014) were perturbed using additive Gaussian noise without spatial
455 correlations. The standard deviation of the perturbations of the parameters was set to 20% of
456 the range of the nominal values.

457 **5.2.2 GRACE observation errors**

458 Spatial correlations of GRACE observation errors were also taken into account in the DA
459 scheme. The uncertainties in the GRACE-derived TWSV over the Hexi Corridor were
460 computed using the monthly calibrated error variance-covariance matrix of the SHCs (Σ)
461 provided by the CSR. Recalling the replacement of the low degree SHCs (see Sect. 4.1), the
462 error (co-)variances of SHCs degree 2 were not provided by Cheng and Tapley (2004), and
463 therefore the values obtained from the CSR were used. As for SHCs of degree 1, the error (co-
464) variances were not available from (Swenson et al., 2008) either and were set to zero. Note
465 that Σ only reflects the error of the original GRACE data, i.e. before the GRACE processing
466 described in Sect. 4.1 was applied. To obtain the error variance-covariance matrix associated
467 with the post-processed GRACE data, an ensemble of SHC noise realizations \mathbf{Q}^c was first
468 generated based on Σ as follows:

469 $\mathbf{Q}^c = (\Sigma)^{\frac{1}{2}} \mathbf{Q}^w,$ (12)

470 where $\mathbf{Q}^w = (q_1^w, q_2^w, q_3^w, \dots, q_N^w)$ contains a set of white noise realizations and has the
 471 dimension of $s \times N$, where $s = 1891$ is the number of SHCs, and $N = 100$ is the number of
 472 realizations. The matrix $\mathbf{Q}^c = (q_1^c, q_2^c, q_3^c, \dots, q_N^c)$ has the same dimension as \mathbf{Q}^w and contains
 473 an ensemble of correlated noise realizations in SHCs. Then, each noise realization (i.e.,
 474 column of \mathbf{Q}^c) was post-processed in the same way as the GRACE data (Sect. 4.1), which
 475 resulted in $\widehat{\mathbf{Q}}^c = (\widehat{q}_1^c, \widehat{q}_2^c, \widehat{q}_3^c, \dots, \widehat{q}_N^c)$. The post-processing included applying the destriping and
 476 Gaussian smoothing filters, as well as the signal restoration using the same number of
 477 iterations as was used in the GRACE data post-processing. The error variance-covariance
 478 matrix $\widehat{\Sigma}$ associated with the SHCs after post-processing was then computed as

479 $\widehat{\Sigma} = [\widehat{\mathbf{Q}}^c (\widehat{\mathbf{Q}}^c)^T] / (N - 1).$ (13)

480 Recalling Eq. (1), the TWSV over the Hexi Corridor can be computed as

481 $\Delta\sigma = \mathbf{Y}\mathbf{S}\mathbf{x},$ (14)

482 where $\Delta\sigma$ is the vector composed of the computed TWSV at grid cells, \mathbf{Y} is the matrix of
 483 spherical harmonic synthesis (cf. Eq. (1)), \mathbf{S} is the matrix containing the scaling factors S_l , and
 484 \mathbf{x} is the vector composed of the dimensionless SHC variations after GRACE data post-
 485 processing described in Sect. 4.1. Then, the error covariance matrix \mathbf{R} of the GRACE-based
 486 TWSV over the Hexi Corridor was computed with the error propagation law as

487 $\mathbf{R} = \mathbf{Y}\mathbf{S}\widehat{\Sigma}(\mathbf{Y}\mathbf{S})^T.$ (15)

488 Some statistics of GRACE TWSV errors over the Hexi Corridor are shown in Fig. 8. The
 489 error standard deviation in Oct. 2002 varied with location (Fig. 8a), whereas the error
 490 correlation showed a distance-decay pattern in all directions (Fig. 8b). The areally-averaged
 491 standard deviations over 4 basins stayed in most of the months at a similar level of
 492 approximately 1 cm (Fig. 8c). The large uncertainty in September 2004 was likely caused by
 493 the near-repeat orbit of GRACE satellites during that month.

494

495 **6. Results and discussion**

496 The structure of this section is as follows. First, the impact of assimilation using EnKF 3D on
 497 the TWSV is considered in Sect. 6.1. Then, the impact of the EnKF 3D on the estimates of the
 498 individual stores is investigated in Sect. 6.2. The [results](#) of the EnKF 1D and EnKF 3D
 499 schemes are compared in Sect. 6.3 in terms of TWSV and the individual stores. [Furthermore,](#)
 500 [the obtained results are validated against independent data in Sect. 6.4.](#) Finally, in Sect. 6.5-
 501 [6.6](#), the assimilation results are used together with ancillary remote sensing data to study
 502 water resources in the Hexi Corridor.

503

504 **6.1 Impact of GRACE DA**

505 To demonstrate the impact of DA, Fig. 9 shows the daily TWSV estimates over the Shiyang
506 River Basin between 1 April 2002 and 31 December 2003. Several features associated with
507 the EnKF can be observed. Firstly, when a GRACE observation is available, the EnKF moves
508 the estimated TWSV towards it. As a result, the estimated TWSV lies between the EnOL
509 estimate and the GRACE observation most of the time. It is seen that GRACE-derived TWSV
510 has a greater annual amplitude compared to the model estimated TWSV. This can likely be
511 attributed to the poor quality of the model parameter calibration and the accuracy of the
512 meteorological input data over the data-sparse regions. In the absence of observations, model
513 parameters are difficult to determine and only the best available knowledge (or guess) is
514 generally used, leading to inaccurate model state estimates. Updating the water storage
515 estimates using GRACE DA showed a clear improvement in this case. Secondly, the standard
516 deviation across the EnKF ensemble of TWSV values is smaller than that of the EnOL and
517 smaller than the GRACE observation error. Thirdly, at the first month (April 2002) the
518 TWSV estimates of the EnOL and EnKF were similar at the forecast step (as the initial states
519 were the same, see point (a) in Fig. 9), but became different when the daily increment was
520 applied to the EnKF. Finally, discontinuities in the time-series before the update were
521 observed at the end of the month e.g., in November and December 2002 (point (b) and (c)),
522 and February 2003 (point (d)). Applying the daily increment (see Sect. 5.3) served as a
523 smoother, and these stepwise changes were reduced.

524 Similar features were also seen in the EnKF 1D TWSV estimates (not shown).

525

526 **6.2 Impact of GRACE DA on individual stores**

527 The monthly-averaged values of the TWSV and individual stores in each of the 4 basins are
528 presented in Fig. 10. Overall, TWSV estimates over the Hexi Corridor mostly reflect SMSV
529 and GWSV components, while snow water storage variation (SNSV) and surface water
530 storage variation (SFWV) are minor contributors, constituting less than 5% in most basins.
531 Clear seasonal variations in TWSV were seen in all basins for GRACE, EnOL and GRACE
532 DA (both EnKF 1D and EnKF 3D) time-series (Fig. 10 a,b,c,d). As observed in Fig. 10, the
533 GRACE DA estimated TWSVs are generally between the GRACE observations and the
534 EnOL estimates. As a result of assimilating GRACE data, both the EnKF 1D and EnKF 3D
535 added water to all basins between 2002 and 2005 and reduced it from the basins between
536 2006 and 2010. This is also seen in the time-series of SMSV (Fig. 12 e,f,g,h) and GWSV
537 (Fig. 12 I,j,k,l). Additionally, the annual amplitudes and phases of GRACE DA estimated
538 TWSV were also found mostly in between the values computed from the GRACE
539 observations and the EnOL results (see Table 2). In particular, the GRACE-DA estimated
540 TWSV's phase was always closer to the GRACE observation. The phase shifts of
541 approximately 1 month were seen in both GRACE DA estimated TWS and GRACE
542 observations compared to the EnOL results. Similar phase differences of approximately 1
543 month were also observed in SMSV and GWSV components.

544 Differences in the long-term trends were also detected between the TWSV estimates from the
545 model alone (EnOL) and the GRACE DA. The GRACE DA results showed decreasing
546 TWSV trends similarly to the GRACE data, while the EnOL showed increasing trends (Fig.
547 10 a,b,c,d, see also Table 7). This change in TWSV trend was clearly a result of assimilating
548 GRACE observations. The negative trends were also observed after DA in the GWSV
549 component in most basins (Fig. 10 i,j,l). This indicates the potential of GRACE DA in
550 adjusting GWSV. In this way, one can reveal continued groundwater consumption to support
551 local agricultural activities (Li et al., 2013). Unlike over other basins, the negative trend of
552 GWSV estimates was not clearly present over the Desert Region (Fig.10k). This could be due
553 to the small amplitude of the groundwater variation of this region (see also below), and most
554 of the update took place in the SM component. As a result, a relatively large negative trend
555 was seen in SMSV rather than GWSV after GRACE DA (see also Table 7). Further
556 discussions on the trends are given in Sect. 6.4.

557 The impact of GRACE DA on different stores was influenced by both the model parameters
558 and the forcing data. The 4 basins have similar soil water storage capacities (see Table 3),
559 which indicates that the basins can store similar amounts of soil water and generate similar
560 amounts of groundwater recharge under the same rainfall conditions. However, the 4 basins
561 received different amounts of rainfall, which resulted in different SMSV and GWSV
562 estimates. For example, the Shiyang River Basin received the greatest amount of rainfall (~
563 twice of Heihe River Basin), which led to the greatest amount of the SMSV estimate (~1 cm
564 annual amplitude). Such a large amount was also sufficient to percolate into the groundwater
565 layer, resulting in GWSV of ~0.7 cm (see Fig. 10i and Table 2). In contrast, the Desert
566 Region received approximately 3 times less rainfall, which led to a somewhat smaller amount
567 of SMSV (~0.7 cm annual amplitude) and a much smaller amount of GWSV, ~0.2 cm (see
568 Fig. 10g, k). As the uncertainty of the water storage variation is associated with the signal
569 amplitude, the greater (smaller) water storage variation leads to greater (smaller) uncertainty,
570 resulting in greater (smaller) update from GRACE DA. As such, a greater update (in
571 particular, in GWSV) is seen over the Shiyang River Basin, as compared to other basins.

572 Snow estimates (SWE plus SFW) were very small (less than 0.2 cm) over the Hexi Corridor
573 and therefore were only slightly updated by GRACE DA. Note that the large variability in the
574 amount of snow seen as the sharp peaks (e.g., in January 2008) was caused by the
575 precipitation and temperature variability. In January 2008, the precipitation records were 159
576 % higher than the January average value while the temperature was 2 – 3°C lower. Such a
577 condition resulted in a large amount of snow. Finally, GRACE DA influences the surface
578 water, but the amplitude is still lower than that of the GRACE uncertainties. Validation of the
579 surface water estimates in terms of river streamflow is given in Sect. 6.4.2.

580

581 **6.3 Impact of taking spatial correlations of errors into account**

582 The impact of accounting for the error correlations was clearly seen in the TWSV estimates
583 (Fig. 10 a,b,c,d). When the error correlations were ignored (EnKF 1D), the TWSV estimate
584 received a larger update from GRACE, particularly between 2002 and 2005. Hence, the

625 estimate was drawn significantly closer to the observation. The presence of error correlations
626 effectively reduces the amount of information in the GRACE data, since spatial averaging of
627 such data mitigates noise to a much less extent than averaging of data with uncorrelated
628 errors. Therefore, the impact of GRACE data in the EnKF 3D case is reduced. As such, the
629 EnKF 3D estimated TWSV was always between the EnOL and EnKF 1D results. |Validating
630 against the in situ groundwater and streamflow data will quantitatively reveal the performance
631 of each approach (Sect. 6.4).

632 Taking error correlations into account also has a clear impact on the SMSV and GWSV
633 components. For SMSV, similarly to TWSV, the EnKF 1D yielded a larger update between
634 2002 and 2005 compared to the EnKF 3D (Fig. 10 e,f,g,h). The difference between EnKF 1D
635 and 3D results became smaller after 2005. This can be attributed to the fact that the ensemble
636 spread in the soil moisture component becomes smaller after several years of updates. After
637 2005, the ensemble spread of SMS was lower than the GRACE uncertainty, and therefore
638 taking the error correlations into account did not have a significant impact on the SMS
639 estimates. For GWS, the impact of taking error correlations into account was even clearer,
640 especially in terms of the long-term trend (Fig. 10, i,j,k,l). With the exception of the Desert
641 Region, the EnKF 1D showed a steeper decreasing trend in all basins. For snow and surface
642 water, the impact of considering error correlations was not significant due to the fact that the
643 stores are small, as compared to SMS and GWS.

644 It is also worth discussing the impact of GRACE DA on the spatial pattern of the water
645 storage estimates. To demonstrate this, the update term (ΔA in Eq. (7)) of October 2002 from
646 EnKF 1D and 3D cases is shown in Fig. 11. Only TWSV, SMSV, and GWSV are presented,
647 since other components (snow, surface water, and interception) are small. As discussed above,
648 EnKF 3D shows smaller update in all components. Due to a greater amplitude of GRACE-
649 derived TWSV over northern and southern parts of the region (see Fig. 4), the update is
650 mostly seen there. Almost all update is limited to the soil moisture layer. Higher precipitation
651 is generally observed over the southern part, which leads to higher groundwater recharge (and
652 GWSV) over that region. As such, a GWSV update is clearly seen over the southern part of
653 the region.

654

655 **6.4 Validation against independent data**

656 **6.4.1 Validation of groundwater estimates against well data**

657 The GWSs estimated from GRACE DA were validated against the well measurements at 5
658 locations shown in Fig. 1c. Yang et al. (2001) showed that the specific yield values obtained
659 from the field measurements over the Shiyang River Basin was between 0.01 and 0.3.
660 Although the measurements were not collected at the well stations used in this study, the
661 values obtained can be used as a guidance of the specific yield of the Shiyang River Basin. In
662 this study, the head measurements were converted to storage unit with the approach described
663 in Sect. 4.3.1. The bias term in Eq. (3) was found to be very close to zero, as the variation
664 (mean removed) was used in the regression analysis. The estimated scale factor was 0.23,

666 0.04, 0.24, 0.25, and 0.32 at W1 – W5, respectively, which is in line with the values obtained
667 from the field measurement.

668 The GWSV estimate at each well location is shown in Fig. 12. Compared to the EnOL results,
669 GRACE DA results were visually closer to the well measurements at all 5 locations. The
670 EnKF 1D and EnKF 3D showed a noticeable difference at each location. The updated GWSV
671 estimates were evaluated in terms of the correlation coefficient, RMSD, and long-term trend
672 (Table 4, 5). Overall, the EnOL resulted in relatively poor correlation coefficients at most
673 stations (except station W1), with the average value of only 0.06. Clear improvements were
674 seen after GRACE DA was applied. The average correlation coefficient increased to
675 approximately 0.6 – 0.7. Although the EnKF 1D introduced a greater update than the EnKF
676 3D, it only showed higher correlation coefficients at stations W1 and W3. Applying the EnKF
677 3D led to correlation coefficients greater than 0.45 in all stations, and on average it improved
678 the correlation coefficient by approximately 0.1 over EnKF 1D. In terms of RMSD, applying
679 GRACE DA reduced the difference by approximately 15 – 25% compared to the EnOL.
680 Compared to EnKF 1D, the EnKF 3D significantly improved the RMSD in most stations. The
681 EnKF 1D only performed better than EnKF 3D at station W1, where it reduced the RMSD by
682 approximately 16 % compared to 8% reduction by the EnKF 3D. The noticeably low GWSV
683 observed by the well data at station W2 in the summers of 2007 and 2008 (Fig. 12b) was
684 probably caused by significant groundwater abstraction. These local features could not be
685 reproduced by the model and GRACE observations due to a limited spatial resolution. As a
686 result, neither of the EnKF algorithms could improve the GWSV estimates at the W2 location
687 during those periods.

688 The long-term trend estimated between 2007 and 2010 was also used to evaluate the impact of
689 GRACE DA and the effect of taking the error correlations into account (Table 5). The EnOL
690 trend estimates were considered poor as they showed the largest RMSD respected to the in
691 situ data. In fact, they were the least consistent with the in situ estimates at each individual
692 station. Similar to the results in terms of correlation coefficient and RMSD (see Table 4), the
693 EnKF 3D led to the largest improvement in the trend estimates (RMSD=0.54 compared to
694 0.93 after EnKF 1D). However, while the EnKF 3D showed closer long-term trends to the in
695 situ measurements at stations W2, W4, W5, the EnKF 1D produced better estimates at station
696 W1 and W3.

697 Thus, both EnKF 1D and 3D led to the improvement of the GWSV estimates in terms of all
698 metrics. In terms of the average results and at the majority of well locations, the EnKF 3D
699 provided more improvement than the EnKF 1D.

700

701 **6.4.2 Validation of streamflow estimates against river gauge data**

702 The streamflow estimates were validated against the river gauge measurements at locations
703 G1 and G2 (Fig 1c). Results are shown in Figure 13 and Table 6. Only modest improvements
704 in the streamflow estimates were observed in terms of the correlation coefficient, NS
705 coefficient, and RMSD. This behaviour is similar to what was observed previously for the

706 Rhine River Basin, when a different hydrology model and input data were used
707 (Tangdamrongsub et al., 2015). Figure 13 shows that taking error correlations into account
708 had little impact, i.e. similar streamflow estimates were seen for EnKF 1D and 3D results. At
709 location G1 (Fig. 13a), GRACE DA added more water to the stream channel between 2002
710 and 2006 and reduced it between 2008 and 2010. This behaviour is consistent with the TWSV
711 estimates discussed in Sect. 6.2. GRACE DA increased the correlation coefficient from 0.82
712 to 0.84, increased the NS coefficient from 0.65 to 0.69, and reduced the RMSD by
713 approximately 5 % (Table 6). A lesser improvement was observed at G2.

714 Comparing to the gauge measurements, both the EnOL and GRACE DA overestimated the
715 streamflow in September 2007 and September 2008 at G2. The sudden surge in the estimated
716 streamflow resulted ed from heavy rainfall recorded by precipitation data while the soil was,
717 according to the model, already saturated (Fig. 14). For example, in September 2007, the
718 second highest amount of SM storage in the record (~19.5 cm) was obtained when the third
719 largest amount of rainfall (~90 mm/month) was observed. Similarly, in September 2008, large
720 SM storage (~20 cm) and the heaviest rainfall (~100 mm/day) forced PCR-GLOBWB to
721 generate a large amount of streamflow. In both cases, the modelled streamflow significantly
722 exceeded the actual one observed at G2. Inaccurate precipitation data and model calibration
723 likely led to these discrepancies. GRACE DA was unable to reduce these spurious peaks due
724 to the limited spatial (~250 km) and temporal (1 month) resolution of GRACE data.

725

726 **6.5 Declining water storages in the Hexi Corridor**

727 The water resources situation over the Hexi Corridor was assessed using long-term trends
728 estimated from the 9-year EnKF 3D results. This DA variant is primarily discussed here as it
729 provided better agreement with well observations than the EnKF 1D (see Sect. 6.4.1). For
730 completeness, however, the values estimated from GRACE, EnOL, EnKF 1D, and
731 precipitation are also provided. The trends in the TWSV, SMSV and GWSV for the 4 basins,
732 as well as the areally-averaged values for the entire Hexi Corridor, are given in Table 7. The
733 average EnKF 3D trends are all negative: approximately -0.2, -0.1, and -0.1 cm/yr for
734 TWSV, SMSV, and GWSV, respectively. This reduction in the water storages is observed
735 despite the increased amount of rainfall, which shows a positive trend of about 0.4
736 (mm/month)/yr. The water storage reductions can likely be attributed to the extraction of
737 groundwater to meet irrigation demands. In Sect. 6.6, it will be shown that groundwater
738 extractions are essential for that purpose in the Hexi Corridor.

739 Focusing on individual river basins provides additional insight into the water storage issue, as
740 the influence of the large desert area is removed. The water storage losses in the individual
741 basins outside the desert are even more pronounced, particularly in the Shiyang River Basin.
742 This basin had the greatest TWS loss (approximately 0.4 cm/yr), which was entirely caused
743 by the reduction of GWS. This can be explained by groundwater abstraction to meet the
744 irrigation demand in the region. The Heihe and Shule River Basins also experienced a TWS
745 loss of ~0.2 cm/yr, which came from a reduction of both soil moisture and groundwater
746 storages. Again, the negative GWS trend was likely caused by significant pumping of

747 groundwater to maintain crop production. This is consistent with the extreme water stress
748 over the Heihe River basin between 2001 and 2010, which was documented in Table 11.7 of
749 the study by Chen et al. (2014). In the Desert Region, in contrast to other basins, the minor
750 decreasing TWS trend of -0.1 cm/yr was dominated by loss of SM storage. This was likely
751 caused by inaccurate model parameter calibration over the Desert Region (i.e., too large SC
752 value). Separation of the TWS into groundwater and soil moisture store was likely incorrect.
753 As such, the annual signal in GWS is much less than in SM there. Therefore, GRACE update
754 was mostly attributed to the SM component, so that a groundwater-pumping signature (Jiao et
755 al., 2015) was seen in the SM instead of the GWS layer.

756

757 **6.6 Connection to agriculture activity**

758 Figure 15 shows the monthly averaged groundwater head measurements at wells W1 to W5 in
759 the Shiyang River Basin (Fig. 1c). Monthly averaged precipitation and NDVI values are
760 shown as well. Since extracted water can be used to support agriculture not only at the well
761 location but also in the nearby area, precipitation and NDVI are reported as the average values
762 within a circular area of the 10-km radius. These data will be used to ascertain if groundwater
763 extractions to support agriculture might be the source of the negative GWS trends observed in
764 Fig. 12 and Table 6. From Fig. 14, it is noticed that the growing period is approximately
765 between May and October, where the amount of rainfall is higher than 15 mm/month and the
766 NDVI is typically greater than 0.2. By observing well measurements, precipitation, and NDVI
767 together, some groundwater extraction signatures can be explained by the extension of the
768 growing period over the dry season. For example, at station W1, the groundwater in 2010 was
769 lower than the average, showing a gradual decrease in summer (Fig. 15a). One may attribute
770 this to the shortage of rainfall in July and August 2010, which was lower than the average
771 (Fig. 15b). However, the NDVI value was higher than the average during summer 2010 (Fig.
772 15c), which implies that water from other sources than precipitation was probably used to
773 maintain the growing period. This additional water was likely extracted from the ground, and
774 such an activity led to a decreased groundwater table during summer 2010. A similar
775 explanation can be applied to station W2, where low groundwater head, low rainfall, and high
776 NDVI were observed in summer 2007 and summer 2008 (Fig. 15 d,e,f). At station W3, the
777 behaviour is similar to station W1: the extension of the growing period was observed in
778 summer 2010, where the GWS and precipitation were lower than the average, while NDVI
779 was significantly higher (Fig. 15 g,h,i). Groundwater pumping signatures were not present at
780 stations W4 and W5.

781

782 **7. Conclusions**

783 This study was focused on the estimation of water resources dynamics in the Hexi Corridor by
784 assimilating GRACE-derived TWSV into the PCR-GLOWBW hydrological model. Validating
785 against well data showed that DA led to noticeable improvement in the state estimates in
786 terms of correlation, RMSD, and long-term trend. Furthermore, GRACE DA estimates

787 revealed the reduction of water storages between 2002 and 2010. The Shiyang River Basin –
788 the southeaster part of the Hexi Corridor area – suffered the most from the water loss, which
789 was likely caused by the overuse of the groundwater for irrigation. Due to inaccurate
790 groundwater abstraction information, PCR-GLOBWB alone could not properly capture the
791 downward trend of water storages. This highlights the value of the GRACE DA in this
792 situation. It should be emphasized that GRACE does not fix a technical problem of the
793 hydrological model, but rather it provides information, which is not available otherwise. Note
794 that, in principle, the model may predict any long-term behaviour of water storage, but that
795 information should be brought in "by hand" (e.g., via the groundwater abstraction parameter).
796 As soon as that information is not available, reliable long-term predictions on the basis of
797 hydrological modelling alone are conceptually impossible. GRACE DA acts as a provider of a
798 missing puzzle piece here. Of course, the performance of GRACE DA needs to be further
799 investigated in other geographical locations and with different hydrological models to confirm
800 its benefits.

801 A substantial decrease in the water storage in the Hexi Corridor between 2002 and 2010,
802 particularly over the Shiyang River Basin, took place in spite of the increased precipitation.
803 The amount of water from rainfall was likely insufficient to support irrigation water
804 requirements. Irrigation water demands increased significantly to maintain the crop
805 production and, as a result, the region was under extreme water stress. Water consumption
806 from all available sources was essential for bridging the deficit, including a sizeable amount
807 of groundwater extraction. This study illustrates how ground observations and remote sensing
808 data may reveal the connection between groundwater pumping and agricultural activity.

809 The conversion approach between the groundwater head measurement and groundwater
810 storage is proven feasible over the Shiyang River Basin. The scale factor estimates produced
811 with this approach are consistent with the specific yield estimated from the field observations.
812 However, it is noted here that the results of the conducted validation might be over-optimistic,
813 since the well data processed with the adopted conversion procedure are not fully independent
814 of the assimilated GRACE data. The specific yield from the field observation must be used
815 when available.

816 Furthermore, we demonstrate how the error covariance matrix R of GRACE-derived TWSV
817 can be obtained from the error covariance matrix of GRACE SHCs (which is currently
818 provided together with the SHCs themselves). This study shows that it is necessary to use the
819 R matrix in order to properly take into account the error correlations in the DA scheme. To
820 come to that conclusion, we considered 2 variants of the error variance-covariance matrix in
821 the data assimilation: excluding and including error correlations. Validating against well data
822 showed that ignoring error correlations in DA tended to over-fit results to the observations,
823 and in many cases led to less accurate state estimates. This finding is in agreement with the
824 recommendation in Schumacher et al. (2016). We explain this finding by the fact that
825 GRACE errors at the neighbouring 0.5°x0.5° grid cells are highly correlated. As such, the
826 simultaneous consideration of GRACE data at multiple neighbouring cells does not reduce
827 data noise, as it would be the case if noise were white. In other words, the white-noise
828 assumption may severely overestimate the information content of GRACE data. We recognize

829 that the derivation of GRACE-derived TWSV error variance-covariance matrices is very
830 computationally demanding. Still, we believe that this is a reasonable price to pay as deriving
831 the error variance-covariance matrix from the full (and only full) error covariance matrix
832 noticeably improves the results of GRACE data assimilation.

833 To further improve the DA performance, an extended or an alternative DA framework can be
834 considered. One of the points of attention is only a minor improvement in streamflow
835 estimates, which is caused by an insufficient temporal and spatial resolution of GRACE data.
836 A promising way to go is to improve the runoff scheme at a conceptual level, e.g., by
837 extending GRACE DA with a simultaneous parameter calibration. To that end, the state
838 vector should be extended to also include selected model parameters (Eicker et al., 2014;
839 Wanders et al., 2014). This allows for the adjustment of the storage size and might lead to a
840 more accurate estimate of model states, including streamflow (Wanders et al., 2014).
841 Alternative ensemble-based DA approaches, such as particle filters (Weerts and El Serafy,
842 2006), can also be considered. Particle filters estimate a sample from the realistic posteriori
843 distribution, which is not necessarily Gaussian, like in the EnKF. The approach has been
844 shown very effective for the parameter calibration (Dong et al., 2015).

845 Finally, the usage of improved gravity solutions to be available after the launch of the
846 GRACE Follow-on mission (Flechtner et al., 2014) will probably further increase the
847 accuracy of the GRACE DA estimates.

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1096 **Table 1.** PCR-GLOWB model parameters related to the TWS estimate. Parameters are
 1097 functions of spatial coordinates, except DDF which is a constant.

Parameter	Description	unit
$K_{sat,up}$	Saturated hydraulic conductivity of the upper soil storage	m/day
$K_{sat,low}$	Saturated hydraulic conductivity of the lower soil storage	m/day
SC_{up}	Storage capacity of the upper soil	m
SC_{low}	Storage capacity of the lower soil	m
$f_g^{min}, f_f^{min}, f_p^{min}, f_{np}^{min}$	Minimum soil depth fraction of grassland (g), forest (f), paddy irrigation (p), non-paddy irrigation (np)	-
$f_g^{max}, f_f^{max}, f_p^{max}, f_{np}^{max}$	Maximum soil depth fraction of grassland (g), forest (f), paddy irrigation (p), non-paddy irrigation (np)	-
J	Groundwater recession coefficient	1/day
DDF	Degree-day factor in the snow pack	°Cm/day
KC^{min}	Minimum crop coefficient	-

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1099 **Table 2.** TWSV, SMSV and GWSV estimated annual amplitude (A, cm) and phase (P, cm)
 1100 month) in 4 different basins computed between April 2002 and December 2010. Areally
 1101 averaged values for the entire Hexi Corridor are also given.

		Shiyan	Heihe	Desert	Shule	Areally-average
TWSV	GRACE	A 2.05 ± 0.31 P 6.97 ± 0.29	1.49 ± 0.21 6.80 ± 0.27	1.79 ± 0.23 6.49 ± 0.24	1.21 ± 0.27 8.61 ± 0.42	1.43 ± 0.18 7.05 ± 0.24
	EnOL	A 1.35 ± 0.16 P 6.35 ± 0.23	0.90 ± 0.07 5.61 ± 0.14	0.66 ± 0.07 5.80 ± 0.19	0.37 ± 0.06 5.40 ± 0.31	0.70 ± 0.06 5.74 ± 0.16
	EnKF 1D	A 1.61 ± 0.16 P 6.96 ± 0.19	0.87 ± 0.10 6.80 ± 0.22	1.05 ± 0.11 6.47 ± 0.19	0.40 ± 0.11 8.35 ± 0.51	0.80 ± 0.09 6.92 ± 0.23
	EnKF 3D	A 1.49 ± 0.13 P 6.42 ± 0.17	0.80 ± 0.08 6.12 ± 0.19	0.72 ± 0.07 6.40 ± 0.20	0.26 ± 0.09 8.48 ± 1.02	0.72 ± 0.07 6.44 ± 0.22
SMSV	EnOL	A 1.03 ± 0.11 P 5.77 ± 0.20	0.70 ± 0.06 5.60 ± 0.16	0.62 ± 0.07 5.82 ± 0.21	0.31 ± 0.05 5.03 ± 0.32	0.59 ± 0.06 5.62 ± 0.18
	EnKF 1D	A 0.88 ± 0.09 P 6.55 ± 0.21	0.75 ± 0.09 7.01 ± 0.22	0.99 ± 0.11 7.08 ± 0.21	0.36 ± 0.10 8.47 ± 0.54	0.67 ± 0.08 7.26 ± 0.24
	EnKF 3D	A 1.30 ± 0.10 P 5.59 ± 0.15	0.66 ± 0.07 6.25 ± 0.20	0.71 ± 0.08 6.44 ± 0.20	0.12 ± 0.08 8.19 ± 0.37	0.55 ± 0.07 6.32 ± 0.22
GWSV	EnOL	A 0.50 ± 0.08 P 7.84 ± 0.29	0.19 ± 0.03 7.13 ± 0.26	0.02 ± 0.004 5.43 ± 0.34	0.09 ± 0.01 6.91 ± 0.29	0.12 ± 0.01 7.22 ± 0.21
	EnKF 1D	A 0.65 ± 0.05 P 8.69 ± 0.16	0.12 ± 0.03 7.82 ± 0.40	0.01 ± 0.01 7.91 ± 1.90	0.05 ± 0.01 8.49 ± 0.29	0.10 ± 0.01 8.32 ± 0.25
	EnKF 3D	A 0.70 ± 0.06 P 8.52 ± 0.16	0.11 ± 0.02 7.50 ± 0.31	0.02 ± 0.01 7.76 ± 1.00	0.05 ± 0.01 8.66 ± 1.33	0.10 ± 0.01 8.26 ± 0.23

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1103 **Table 3.** Averaged values and standard deviations of precipitation and model parameters for 4
 1104 different basins.

	Shiyan	Heihe	Desert	Shule
Precipitation (mm/month)	21 ± 12	13 ± 12	11 ± 2	8 ± 6
SC_{up} (m)	0.08 ± 0.02	0.09 ± 0.02	0.09 ± 0.01	0.08 ± 0.01
SC_{low} (m)	0.33 ± 0.08	0.37 ± 0.07	0.35 ± 0.04	0.33 ± 0.08

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1107 **Table 4.** Statistical values of the GWSV computed from the in situ well measurement and
 1108 GRACE DA estimates between January 2007 and December 2010. The average values are
 1109 computed by averaging the estimated statistical values from all well locations.

		W1	W2	W3	W4	W5	Average value
Correlation coefficient [-]	EnOL	0.74	0.17	-0.04	-0.05	-0.53	0.06
	EnKF 1D	0.84	0.32	0.90	0.45	0.64	0.63
	EnKF 3D	0.82	0.49	0.85	0.51	0.83	0.70
RMS difference [cm]	EnOL	0.69	1.67	0.77	3.34	3.81	2.06
	EnKF 1D	0.58	1.63	0.40	2.56	2.58	1.55
	EnKF 3D	0.63	1.43	0.38	2.24	1.27	1.19

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1111 **Table 5.** Long-term trends and standard deviations of the in situ data and the DA estimates.
 1112 The RMS difference (RMSD) between the in situ data and the DA trend estimates are also
 1113 provided.

	W1	W2	W3	W4	W5	RMSD
In situ	-0.49 ± 0.03	0.01 ± 0.06	-0.60 ± 0.004	0.56 ± 0.12	-1.40 ± 0.03	0
EnOL	-0.57 ± 0.01	-0.64 ± 0.002	-0.01 ± 0.01	-1.69 ± 0.01	1.29 ± 0.02	1.62
EnKF 1D	-0.52 ± 0.02	-0.58 ± 0.04	-0.74 ± 0.02	-1.33 ± 0.08	-1.99 ± 0.13	0.93
EnKF 3D	-0.83 ± 0.02	-0.51 ± 0.03	-0.38 ± 0.01	-0.44 ± 0.08	-1.18 ± 0.06	0.54

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1115 **Table 6.** Statistical values of the streamflow computed from the river stream gauge
 1116 measurement and GRACE DA estimates between April 2002 and December 2010. The
 1117 average values are calculated by averaging the estimated statistical values from both gauge
 1118 locations.

		G1	G2	Average value
Correlation coefficient [-]	EnOL	0.82	0.76	0.79
	EnKF 1D	0.84	0.77	0.81
	EnKF 3D	0.84	0.78	0.81
NS coefficient [-]	EnOL	0.65	0.56	0.61
	EnKF 1D	0.69	0.57	0.63
	EnKF 3D	0.69	0.57	0.63
RMS difference [cm]	EnOL	5.49	3.09	4.29
	EnKF 1D	5.18	3.08	4.14
	EnKF 3D	5.23	3.04	4.14

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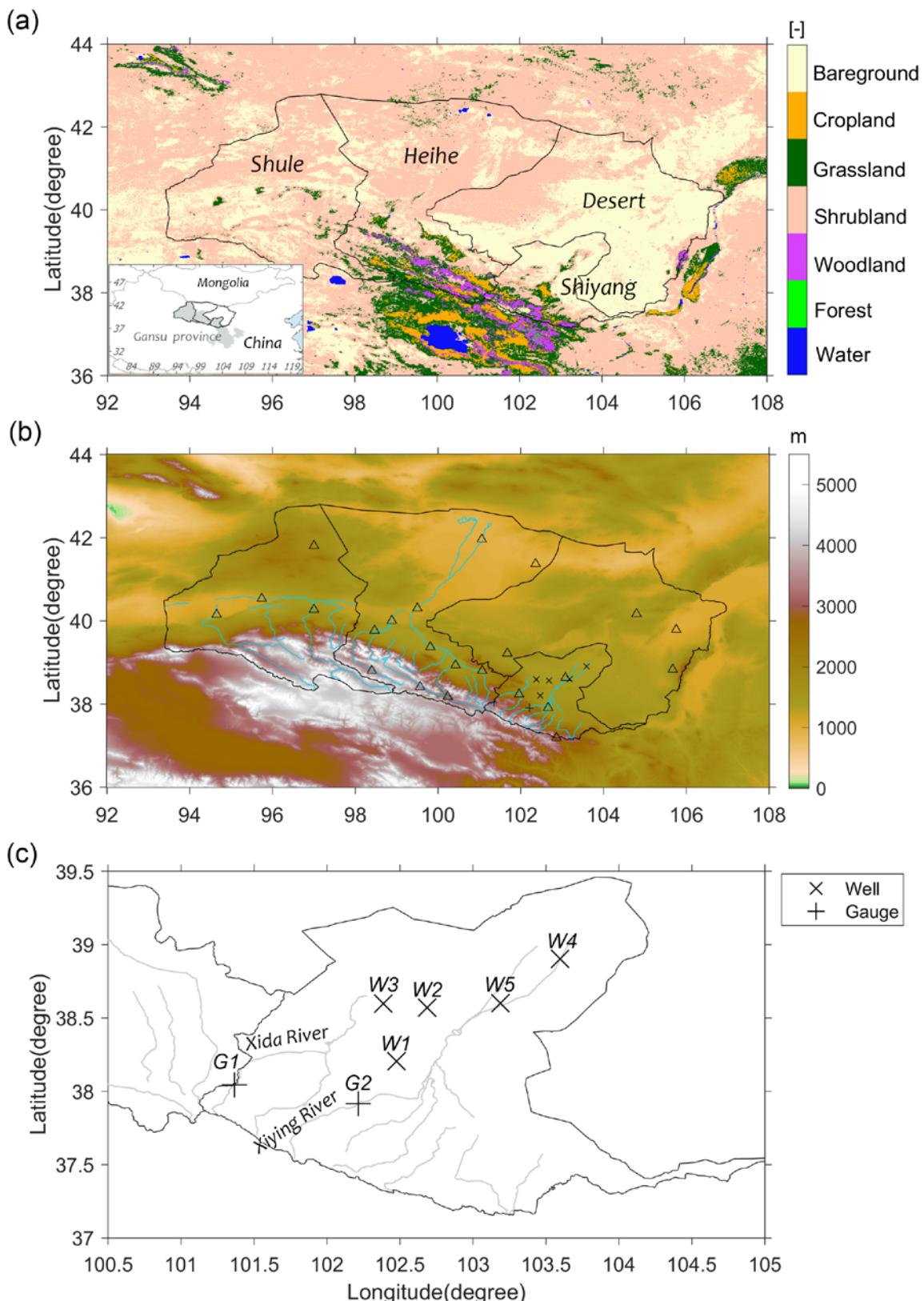
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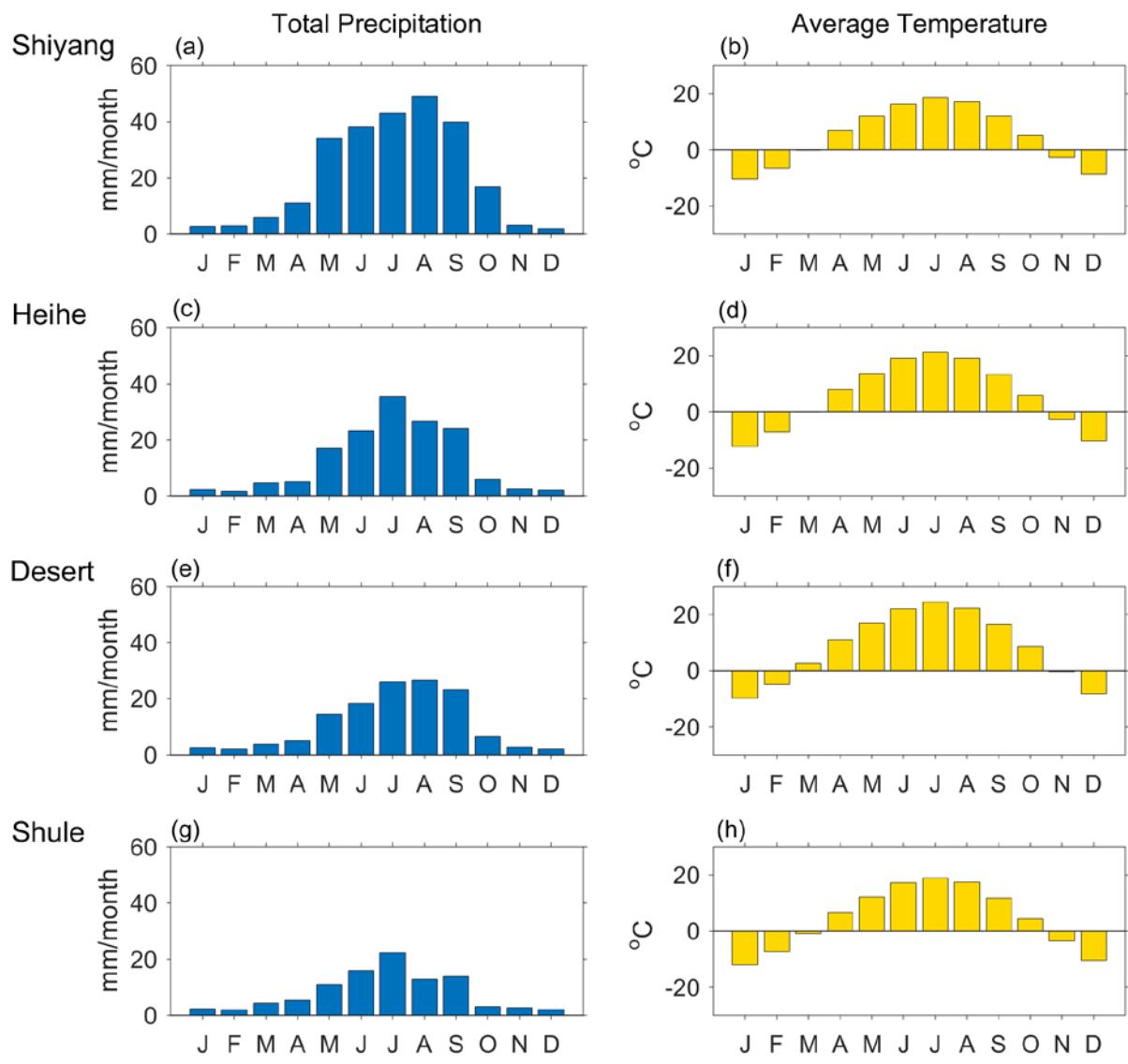
1122 **Table 7.** TWSV, SMSV, GWSV, and precipitation estimated long-term trends in 4 different
 1123 basins computed between April 2002 and December 2010. Areally averaged values for the
 1124 entire Hexi Corridor are also given.

		Shiyang	Heihe	Desert	Shule	Areally-average
TWSV (cm/yr)	GRACE	-0.73 ± 0.04	-0.64 ± 0.03	-0.72 ± 0.03	-0.34 ± 0.04	-0.59 ± 0.03
	EnOL	0.30 ± 0.15	0.24 ± 0.09	0.20 ± 0.04	0.18 ± 0.06	0.22 ± 0.07
	EnKF 1D	-0.72 ± 0.08	-0.41 ± 0.04	-0.33 ± 0.05	-0.34 ± 0.04	-0.39 ± 0.07
	EnKF 3D	-0.36 ± 0.02	-0.21 ± 0.02	-0.11 ± 0.03	-0.25 ± 0.03	-0.20 ± 0.03
SMSV (cm/yr)	EnOL	0.38 ± 0.05	0.21 ± 0.02	0.17 ± 0.03	0.14 ± 0.02	0.19 ± 0.02
	EnKF 1D	-0.11 ± 0.03	-0.20 ± 0.01	-0.29 ± 0.04	-0.22 ± 0.04	-0.23 ± 0.03
	EnKF 3D	0.10 ± 0.03	-0.12 ± 0.01	-0.12 ± 0.02	-0.14 ± 0.01	-0.11 ± 0.004
GWSV (cm/yr)	EnOL	-0.08 ± 0.12	0.03 ± 0.07	0.02 ± 0.007	0.04 ± 0.02	0.02 ± 0.04
	EnKF 1D	-0.61 ± 0.01	-0.16 ± 0.004	-0.01 ± 0.005	-0.12 ± 0.02	-0.16 ± 0.02
	EnKF 3D	-0.39 ± 0.01	-0.09 ± 0.003	0.01 ± 0.004	-0.11 ± 0.001	-0.11 ± 0.002
Precipitation ((cm/month)/yr)		0.04 ± 0.01	0.04 ± 0.01	0.05 ± 0.01	0.02 ± 0.01	0.04 ± 0.01

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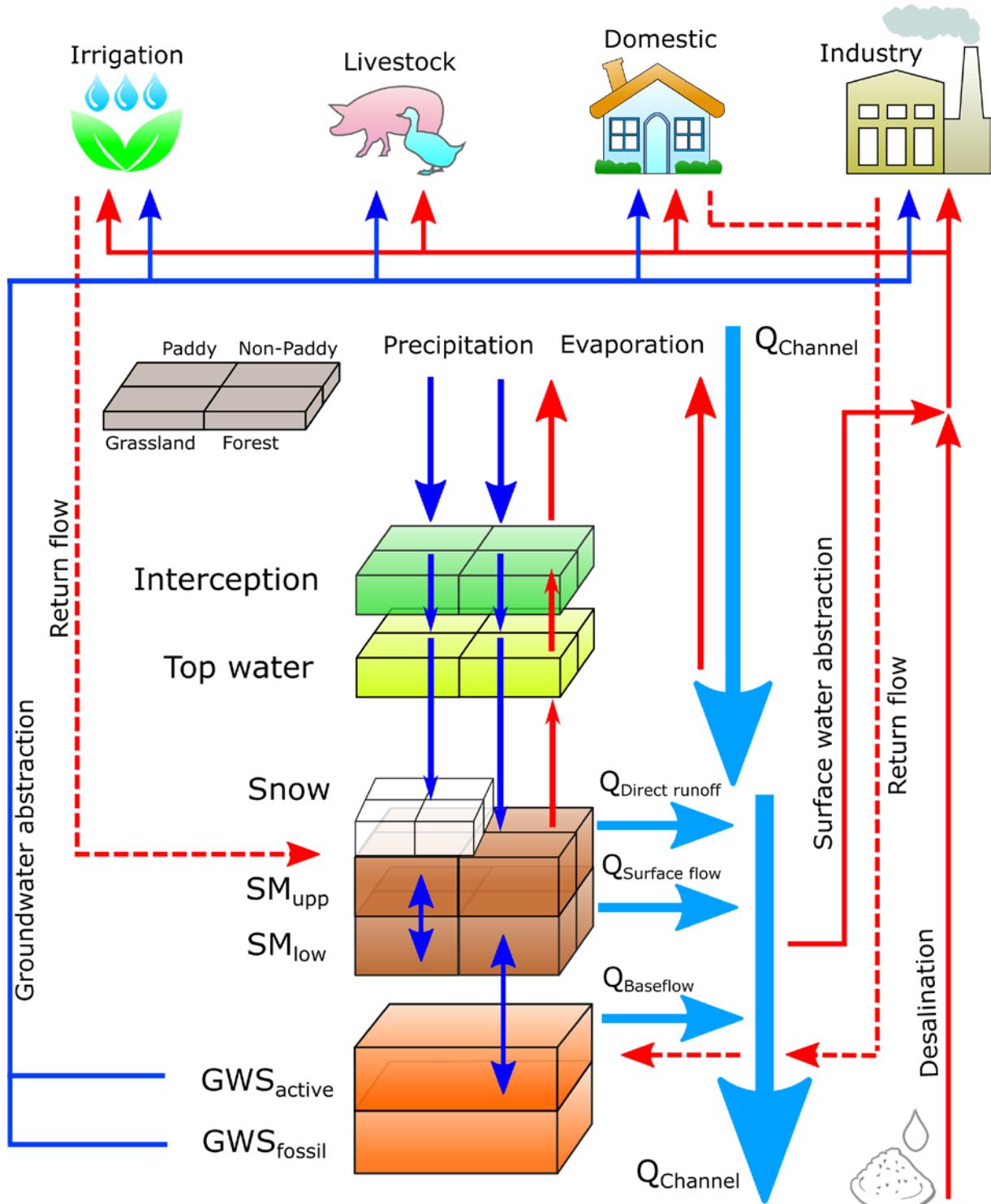
1127 **Figure 1.** Geography of the Hexi Corridor. (a) Land cover and division into individual regions
 1128 (Shiyang River Basin, Heihe River Basin, Shule River Basin, and a Desert), (b) Topography
 1129 and locations of the local meteorological stations (triangles), (c) Zoom-in on the Shiyang
 1130 River Basin, showing the locations of considered groundwater wells (x) and river stream
 1131 gauges (+).



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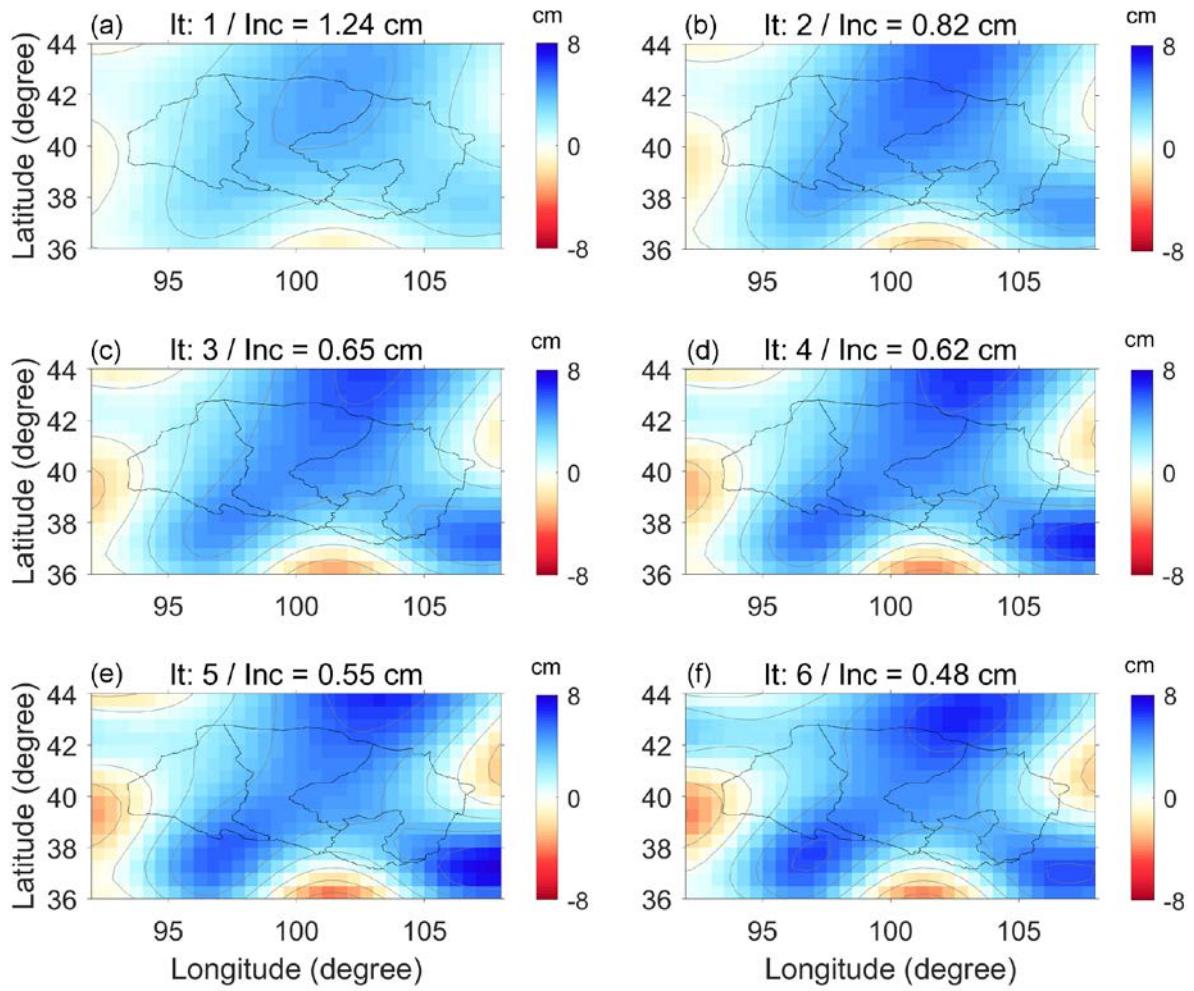
1133 **Figure 2.** Monthly total precipitation and averaged temperature over 4 regions of the Hexi
1134 Corridor.

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1137 **Figure 3.** The structure of PCR-GLOBWB hydrological model.



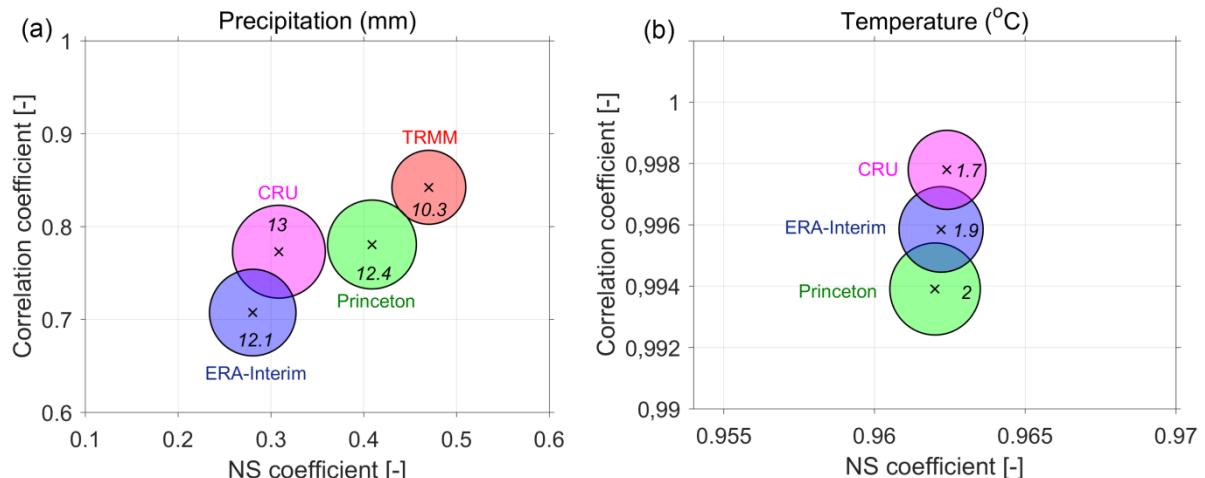
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1139 **Figure 4.** GRACE-derived TWS variation of October 2002. The signal restoration was
 1140 applied to restore the signal mitigated by the applied Gaussian filter. After each iteration (It),
 1141 the increment in each cell was computed. The procedure was stopped after six iterations,
 1142 when the maximum increment (Inc) was lower than 0.5 cm (f).

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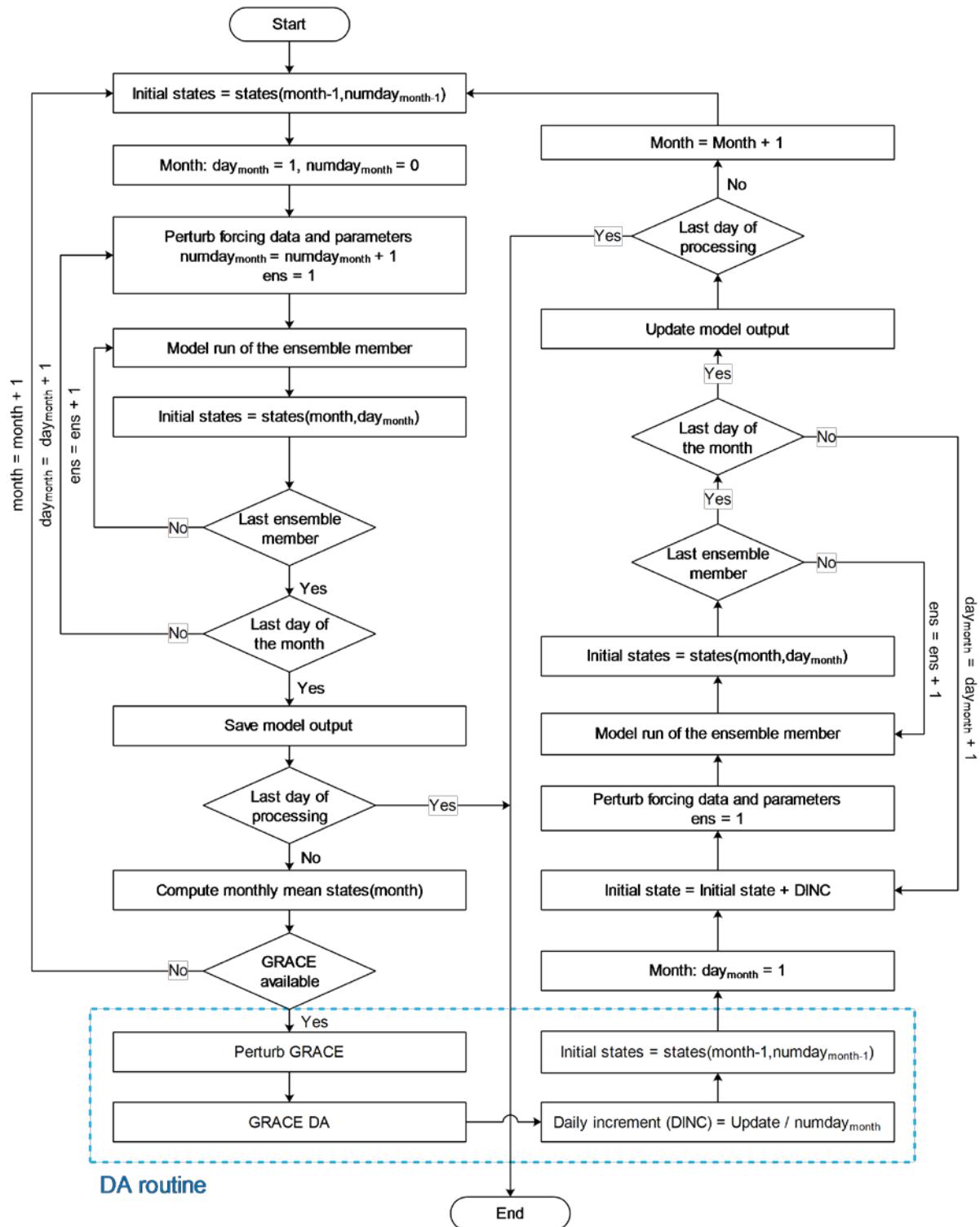
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1147 **Figure 5.** The correlation coefficient, NS coefficient, and RMS difference computed between
1148 the local and different global forcing data. The RMS difference is shown as the radius of the
1149 circle (also explicitly provided as the number).

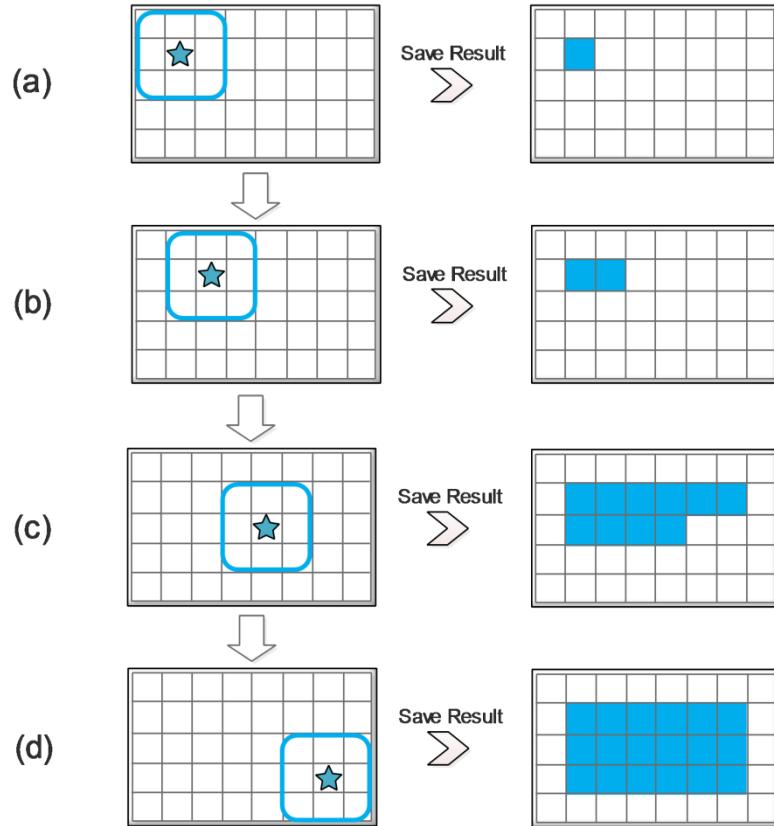
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1152 **Figure 6.** DA diagram representing the disaggregation of monthly averaged TWS from
 1153 GRACE into the daily PCR-GLOBWB state estimates.

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1156 **Figure 7.** Demonstration of EnKF 3D scheme, accounting for the spatially-correlated errors.
 1157 For a centre grid cell, the state and observation matrices contain all TWS-related components
 1158 of the neighbouring grid cells and the centre grid cell (left). The graphic demonstrates the case
 1159 of one pixel (0.5 degree) correlation distance. The boundary stretches farther for larger
 1160 correlation distance. The covariance matrices \mathbf{P}_e and \mathbf{R} are computed based on the data from
 1161 these grid cells. Then, the EnKF is applied and the states of the centre grid cell are updated
 1162 (right). The procedure is repeated through all grid cells.

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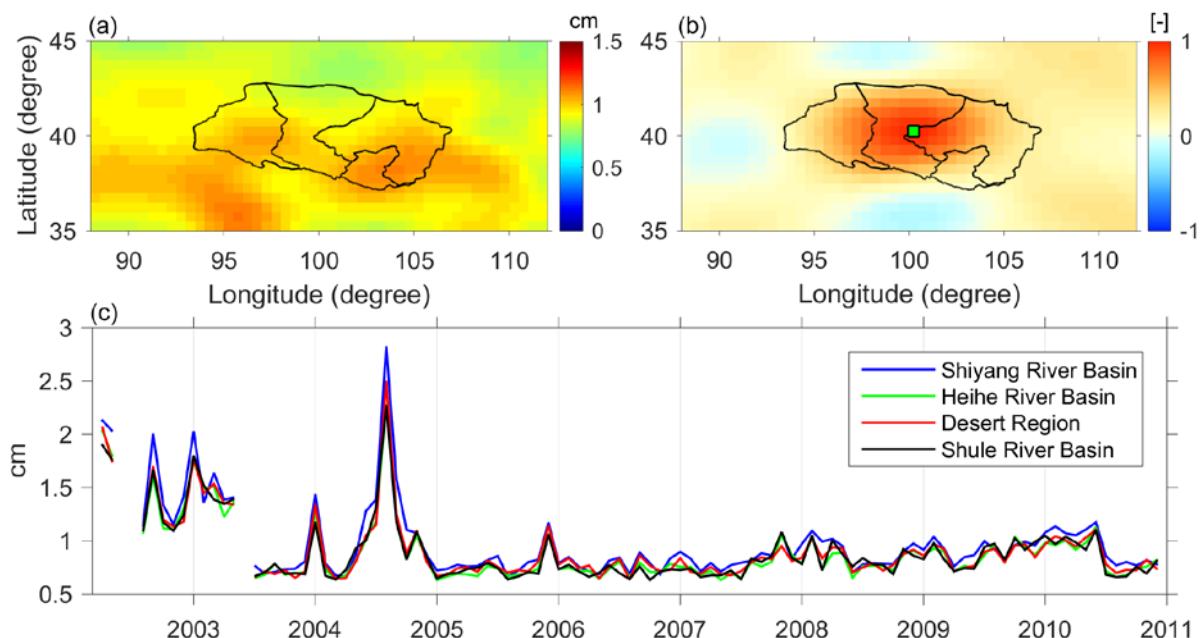
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1175 **Figure 8.** Some statistics of errors in GRACE-derived TWS variation over the Hexi Corridor.
1176 The standard deviation (a) and the correlation coefficient with respect to the green point (b)
1177 for a sample month, October 2002, are shown in the top. The time-series of averaged standard
1178 deviation computed over four different basins are shown in the bottom plot (c).

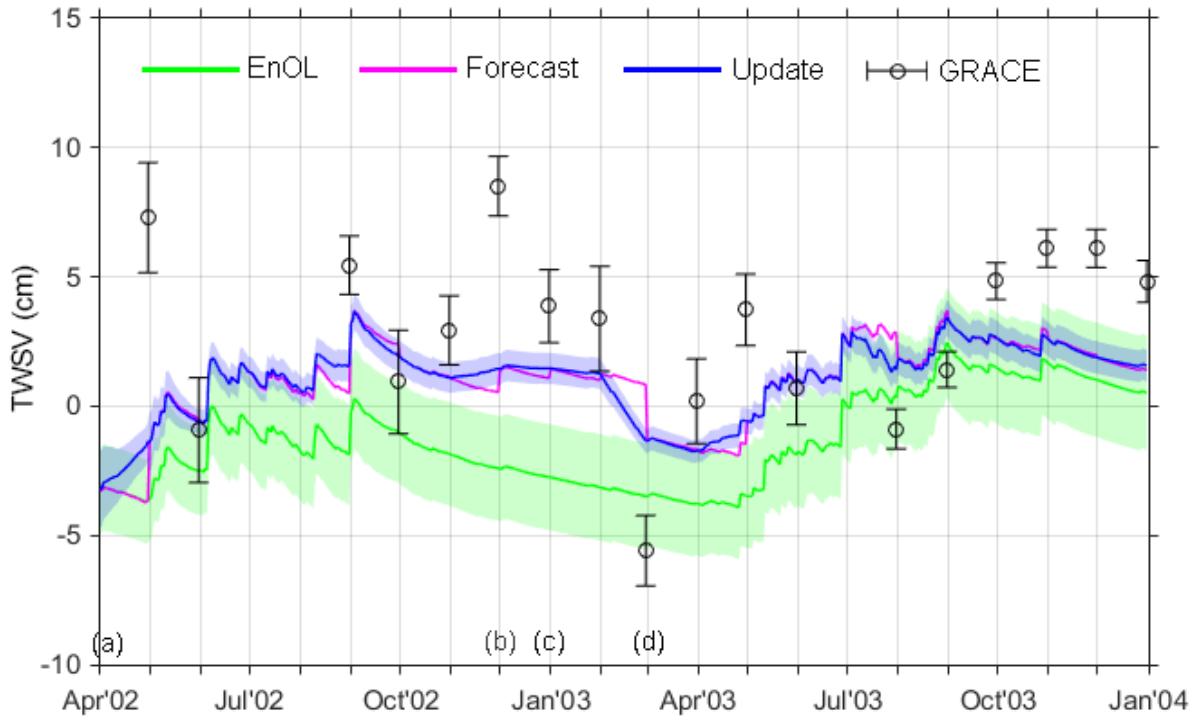
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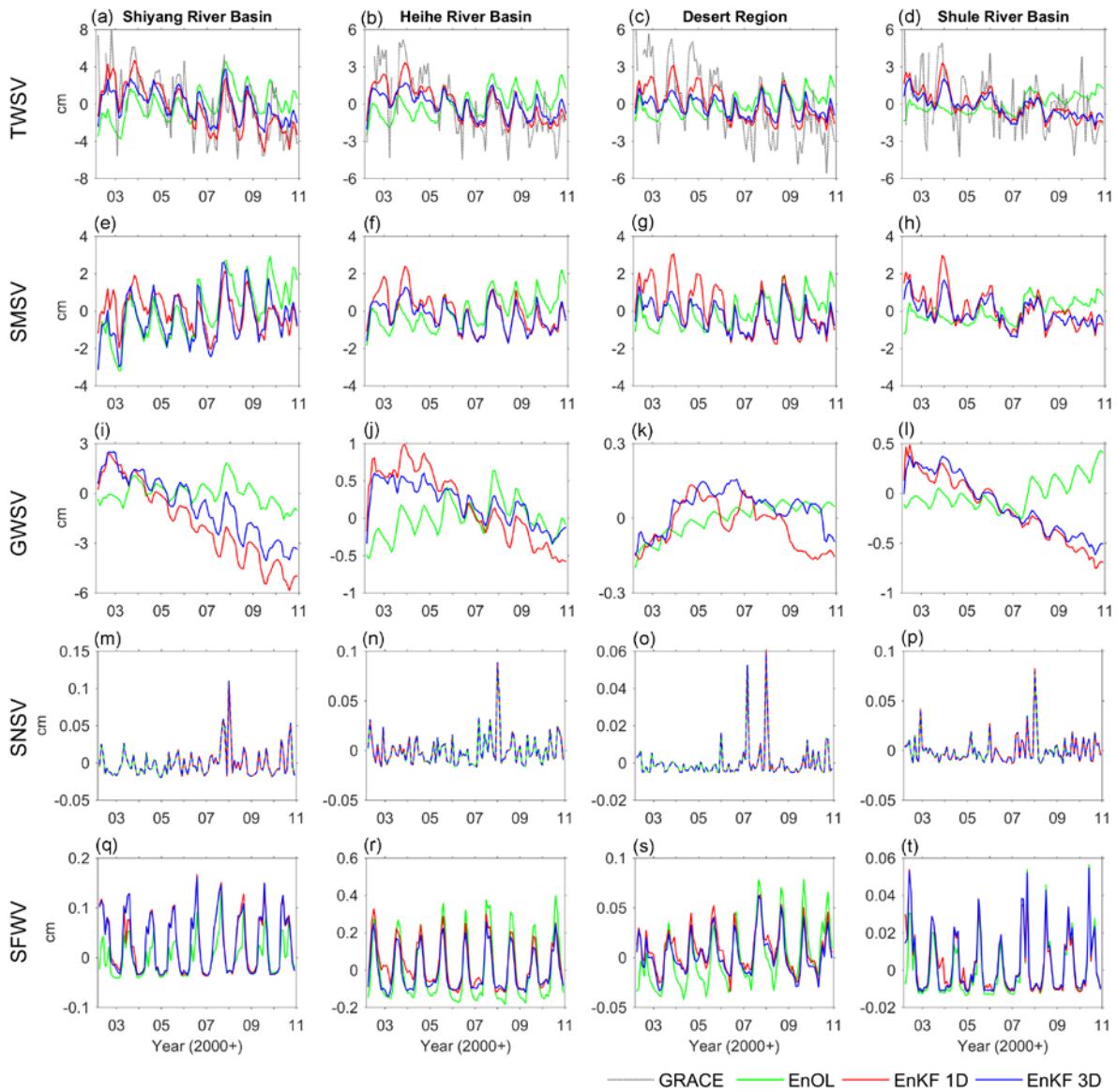
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1185 **Figure 9.** Daily TWS variations estimated between 1 April 2002 and 31 December 2003,
 1186 averaged over Shiyang River Basin. The mean value of the ensemble is given as the solid line,
 1187 and the standard deviation is shown as the shaded envelope. The TWS estimates from model
 1188 only (EnOL), GRACE DA forecast (EnKF before the update), GRACE DA update (EnKF
 1189 after update), and GRACE observations are shown. The x-axis labels represent the first day of
 1190 the month. Some features of the DA scheme regarding the identical TWS estimate seen at the
 1191 beginning of the update (point a) and the observed spurious jumps (point b,c,d) are also
 1192 shown.

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1194

1195 **Figure 10.** Monthly TWSV, SMSV, GWSV, snow water storage variation (SNSV), and
 1196 surface water storage variation (SFWV) estimated between April 2002 and December 2010
 1197 from the EnOL, EnKF 1D, EnKF 3D, and GRACE observations over 4 basins.

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1200 TWSV
SMSV
GWSV

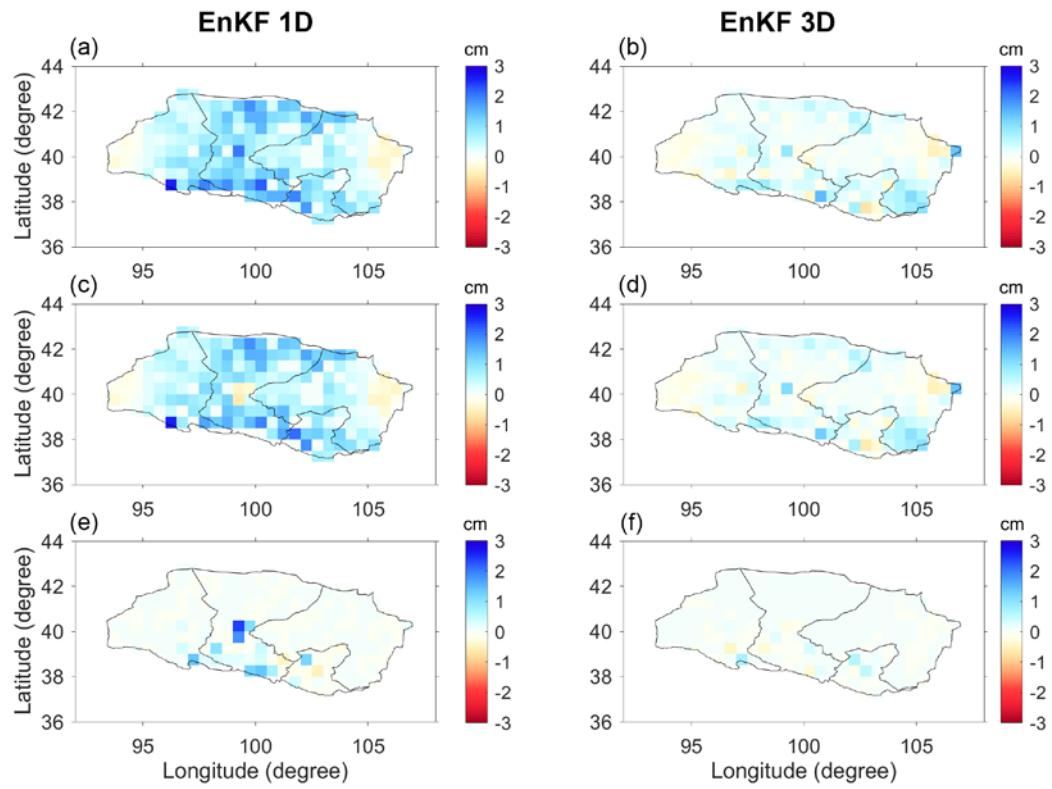
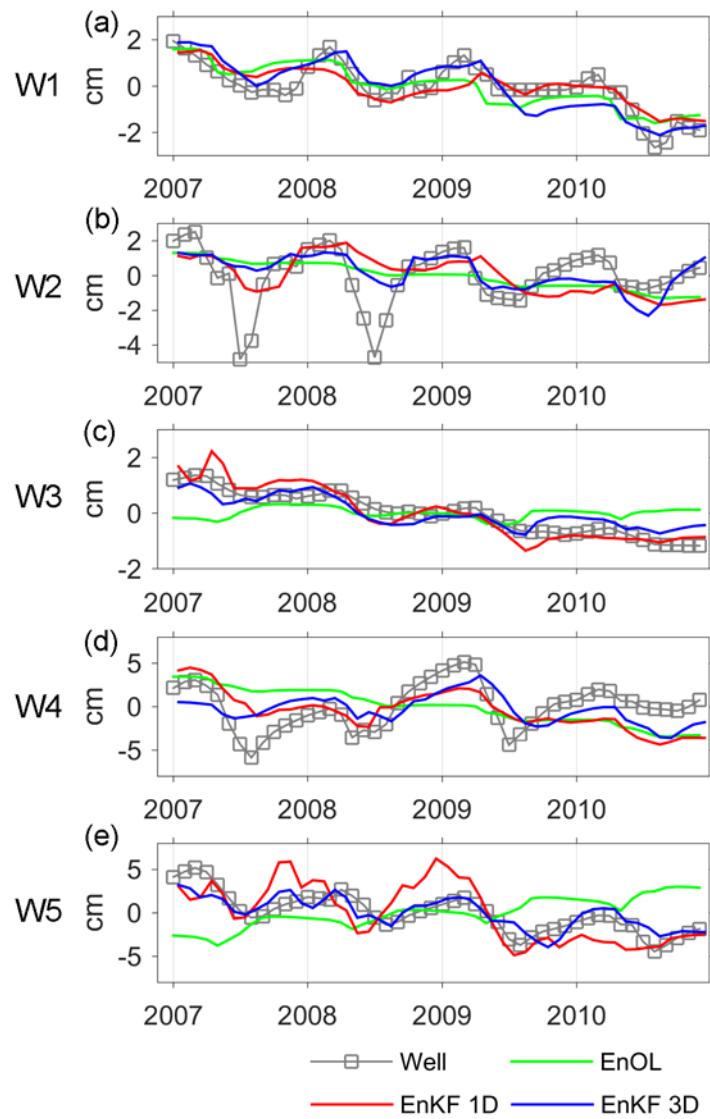
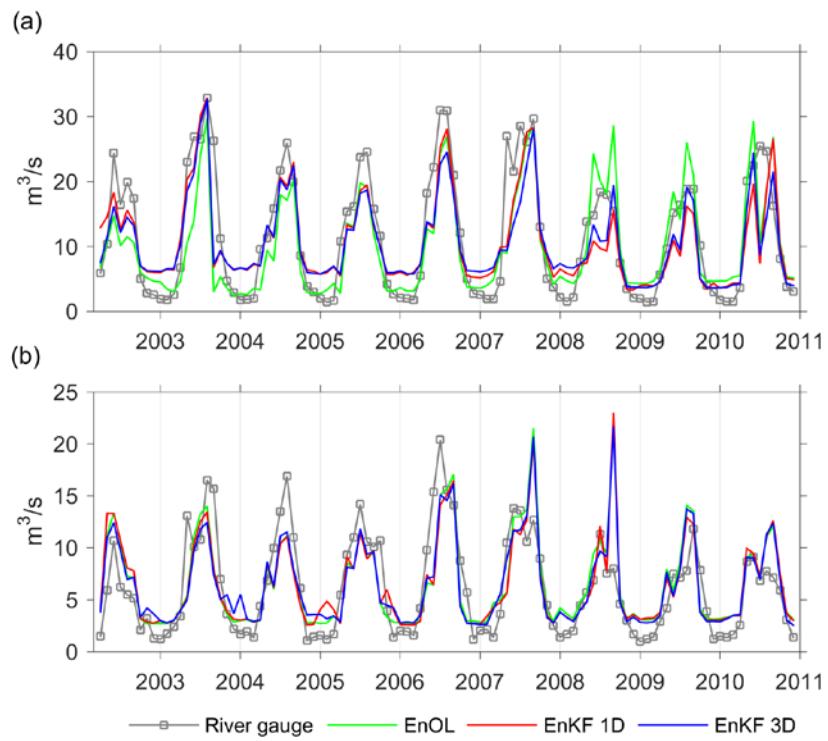


Figure 11. TWSV, SMSV, and GWSV updates of October 2002 without the correlation error applied (EnKF 1D) and with the correlation error applied (EnKF 3D).



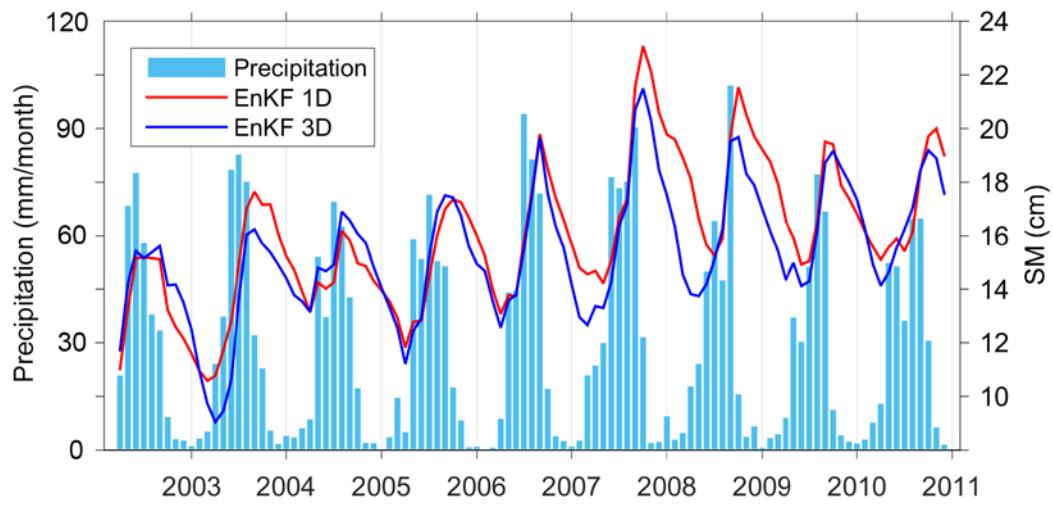
1201

1202 **Figure 12.** Monthly GWS variation estimates from the in situ well measurements, as well as
 1203 EnOL, EnKF 1D, and EnKF 3D results, between January 2007 and December 2010 at 5
 1204 groundwell locations. The chosen period is based on the availability of the well data.



1205
1206 **Figure 13.** Monthly streamflow estimates from the in situ river gauge measurements, as well
1207 as EnOL, EnKF 1D, and EnKF 3D results, between April 2002 and December 2010 at 2 river
1208 gauge locations, G1 (a) and G2 (b).

1209

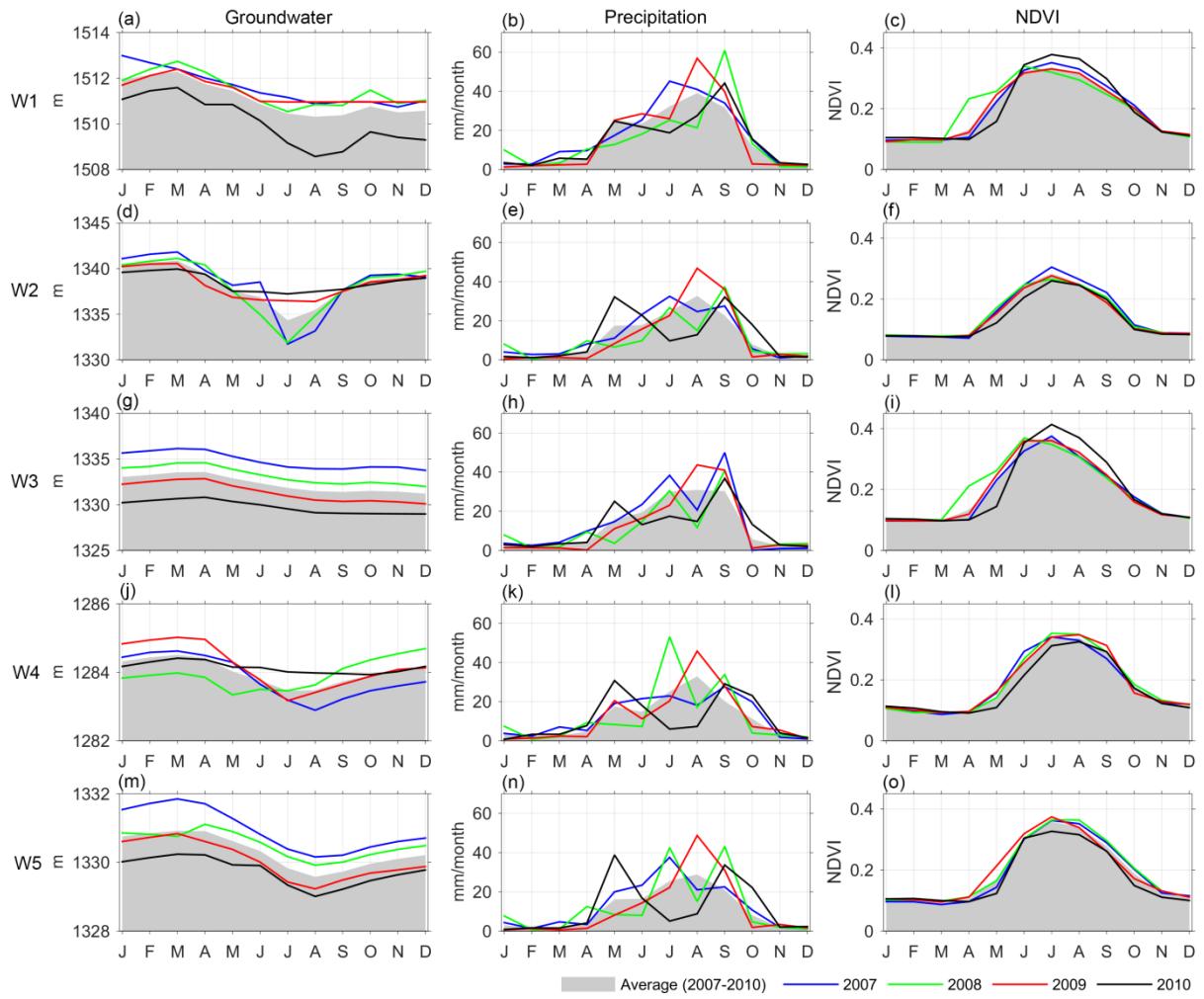


1210
1211 **Figure 14.** Monthly total precipitation (mm/month) and SM storage estimates (cm) from
1212 EnKF 1D and EnKF 3D results at river gauge G2 location.

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1216

1217 **Figure 15.** The monthly averaged groundwater head measurement (left)
1218 (middle) and NDVI (right) for **five** groundwater well locations. Precipitation
1219 and NDVI data are reported as the average values within the circular areas of the 10-km radius.
1220 The long-term average values between January 2007 and December 2010 are shown in the grey shed,
1221 and the values in 2007, 2008, 2009, and 2010 are shown as blue, green, red, and black lines,
1222 respectively. The period is chosen based on the availability of the well data.

1223