1 **RESPONSES TO THE REFEREES**

2 We thank the reviewers for the comments. Below are our responses (in **blue** font) to the re-3 viewers' comments and questions (in **black** font).

4 Anonymous Referee #1

- 5 Received and published: 9 February 2016
- 6 General Comments:

7 This manuscript compares two different approaches to retrieve energy budget components 8 (including sensible and latent heat flux) at the land surface using satellite data from the Chinese 9 HJ-1B. One approach (IPUS) uses information aggregated to the 300m resolution as given by 10 the thermal channel; the second approach (TSFA) uses a temperature sharpening approach, 11 making use of a NDVI – TS relationship and downscaling 300m Ts information to the 30m scale. Authors illustrate the differences between both approaches and demonstrate within a val-12 13 idation exercise the advantages and improved prediction capacities of the latter approach. I 14 think this comparison and the results obtained are in principle worth publishing and will be of 15 use for the readership of HESS. However, before a possible publication, author need to address 16 and solve some significant concerns and questions that came up when working through the 17 manuscript.

18

19 1. One of the major deficits of the manuscript is the following: The satellite data available 20 are the 30m resolution data in the VIS/NIR spectral region and the 300m thermal information. 21 As a "standard/normal" remote sensing user, I would try to make use of this available infor-22 mation. That means in a "reference application" (as it appears to me the IPUS scheme is meant 23 to be) I would try to make use of the 30m data to derive NDVI and land use information (and 24 all the other relevant parameters such as vegetation height, vegetation cover, roughness length 25 etc., but also the simplification of individual fluxes for given LU type). Why are these param-26 eters aggregated in the IPUS approach? Why don't use the high resolution information with an 27 aggregated 300m Ts-signal. This should be compared to the TSFA approach in order to be able 28 to evaluate the effect of purely temperature sharpening. Here actually the baseline situation is 29 first worsened by aggregating information that is available in much higher resolution. In case 30 the intention of the authors was to show what can happen when also in the VIS/NIR range only 31 300m resolution data were available, then all the (300m) average land surface parameters 32 should have been derived from the aggregated reflectance information. So, I personally feel 33 here are different aspects mixed and not properly separated.

34 Response: Thank you for your valuable comments. We assume that the ET estimation errors 35 mainly come from inhomogeneity of surface landscape and variables. We aimed to reduce the uncertainties in estimated ET that caused by surface heterogeneities, and the TSFA is our final scheme. 36 37 To evaluate the ability of the TSFA method to capture surface heterogeneity and reveal the scale 38 effect, we used the IPUS method because it does not consider the effects of mixed pixels at all. 39 According to your comments, we added the TRFA (temperature resampling and flux aggregation) 40 method, which uses 30 m visible/near infrared band data with 300 m thermal infrared band data to 41 estimate ET. In this method, simple spatial resampling (300 m to 30 m) of LST was used instead of 42 spatial sharpening according to NDVI information. Comparisons between the TFSA and TRFA

1	methods can be used to evaluate the effects of temperature sharpening on estimating ET, as well as
2	the significance of separating inhomogeneity of landscape from that of surface variables (such as
3 4	LST), and that would make our logic clearer.
5	2. The title of the manuscript suggests that the focus of the paper is on evapotranspiration
6	- when looking through the manuscript and figures and tables, it seems to me that sensible heat
7	flux is dominating the content and discussion. As a result, I would suggest to either change the
8	title or put some more emphasis on ET in the presentation and discussion of results. As a result
9	of my evaluation I would suggest major revisions of the manuscript before a possible publica-
10	tion in HESS.
11	Response: Thank you for your suggestion. We revised the manuscript by placing more empha-
12 13	sis on LE with a balance analysis and discussion of H.
14	Specific Comments/Questions
15	
16 17	- In general, there are a very large number of abbreviations used in the manuscript – not all of them are intuitive and it is painful to always try and find the first position where they are
18	explained. So I would suggest generating a list of abbreviations.
19	Response: Thank you for your suggestion. A table of abbreviations and the usage of input data
20	were added in the appendix.
21	
22	- Figure and table legends are not self-explaining throughout the manuscript and need ex-
23	tension!
24	Response: The figure and table legends were revised.
25	
26	P2L14-22: While this paragraph is ok in principle, we as hydrologist all know how im-
27	portant ET – so in order to come quicker to the point it should be omitted.
28	Response: Thank you for your suggestion. We agree with your suggestion and have deleted
29	this paragraph.
30	
31	P6L17: Why choosing the 25% fractions having the lowest CV? Please explain in the
32	text!
33	Response: We have added our justification for this decision in the manuscript.
34	According to the temperature sharpening method "DisTrad" proposed by Kustas et al. (2003),
35	25% of the pure pixels with the lowest CV are selected from each class. Regarding heterogeneity,
36	lower CVs correspond with more homogeneous land surfaces. In addition, a fraction should guar-
37	antee that a sufficient number of pixels was obtained to fit a least-squares expression between
38	NDVI ₃₀₀ and T_{300} ; thus, we choose 25% of the fractions with the lowest CVs.
39	
40	P9L11: How is Ld calculated in the scheme?
41	Response: The Ld calculation method was introduced in Section 3.2.1.1. (P14L10).
42	Reference: Yu, S., Xin, X., and Liu, Q.: Estimation of clear-sky longwave downward radiation
43	from HJ-1B thermal data, Sci. China Earth Sci., 56, 829-842, 10.1007/s11430-012-4507-z, 2013.
44	

1 P12L21ff: It remains unclear how albedo is calculated 2 Response: The expression of the surface albedo computing method was modified as follows: 3 "According to the algorithm proposed by Liang et al. (2005) and Q. Liu et al. (2011), surface 4 albedo was obtained from the top of the atmosphere (TOA) reflectance by the HJ-1 satellite with a 5 lookup table based on an angular bin regression relationship. The surface albedo and bidirectional 6 reflectance distribution function (BRDF) of the HJ-1 satellite in the regression procedure were mon-7 itored by using POLDER-3/PARASOL BRDF datasets, and BRDF was used to obtain the TOA 8 reflectance using the 6S (Second Simulation of a Satellite Signal in the Solar Spectrum) radiation 9 transfer mode." 10 Reference: Liang, S., Stroeve, J., and Box, J. E.: Mapping daily snow/ice shortwave broad-11 band albedo from Moderate Resolution Imaging Spectroradiometer (MODIS): The improved di-12 rect retrieval algorithm and validation with Greenland in situ measurement, Journal of Geophysi-13 cal Research: Atmospheres, 110, D10109, 10.1029/2004JD005493, 2005. 14 Liu, Q., Qu, Y., Wang, L. Z., Liu, N. F., and Liang, S. L.: Glass-Global Land Surface Broad-15 band Albedo Product: Algorithm Theoretical Basis Document. Version, 1, 1-50, College of Global 16 Change and Earth System Science, Beijing Norman University, 2011. 17 18 P14L11: briefly describe how this is expressed/described (Ref) 19 Response: The top-of-atmosphere (TOA) brightness temperature of the HJ-1B thermal channel 20 was used as the atmospheric effective temperature. 21 As shown in Yu et al. (2013), "To investigate the relation between TOA brightness temperature 22 of the HJ-1B thermal channel and near-surface air temperature, TOA brightness temperature of HJ-23 1B is simulated using the Thermodynamic Initial Guess Retrieval (TIGR) atmospheric profile data-24 base TIGR2002 (http://ara.abct.lmd.Polytechnique.fr/index.php?page=tigr) and MODTRAN radia-25 tive transfer model; it has high correlation with near-surface air temperature." 26 27 Reference: Yu, S., Xin, X., and Liu, Q.: Estimation of clear-sky longwave downward radiation 28 from HJ-1B thermal data, Sci. China Earth Sci., 56, 829-842, 10.1007/s11430-012-4507-z, 2013. 29 30 P16L2: What reliable methods? This needs to be more specific and with references. 31 Response: The methods were added as follows: 32 "Reliable methods were used to ensure the quality of the turbulent heat flux data. Before the 33 main campaign, an intercomparison of all instruments was conducted in the Gobi Desert (Xu et al., 34 2013). After basic processing, including spike removal and corrections for density fluctuations 35 (WPL-correction), a four-step procedure (data were rejected when (1) the sensor was malfunction-36 ing, (2) precipitation occurred within 1 h before or after collection, (3) the missing ratio was greater 37 than 3% in the 30-min raw record and (4) the friction velocity was below 0.1 ms-1 at night) was 38 performed to control the quality of the EC data, and EC outputs were available every 30 min (for 39 more details see Liu et al., 2011; Xu et al., 2013)." 40 41 P17ff: In the section 4.1 surface parameter and fluxes derived are evaluated against meas-42 urements. In order to put those results into a general context I think a discussion and comparison 43 in relation to other international Remote sensing/Flux measurement campaigns should be given.

44 Response: Thank you for your comments. Introduction and discussion of the other ground

campaigns was given.
 Introduction of the study area:

The Heihe River Basin has long served as a test bed for integrated watershed studies as well as land surface or hydrological experiments. Comprehensive experiments, such as Watershed Allied Telemetry Experimental Research (WATER) (Li et al., 2009), and an international experiment - the Heihe Basin Field Experiment (HEIFE) in World Climate Research Programme (WCRP) have taken place in the Heihe River Basin. One major objective of HiWATER is to capture the strong land

8 surface heterogeneities and associated uncertainties within a watershed (Li et al., 2013).

9 Discussion:

Our surface variable retrieval methods were validated against other areas considered in remote sensing measurement campaigns. For example, the albedo algorithm was previously applied to retrieve Global Land Surface Satellite (GLASS) Products (Liang et al., 2014), the LST retrieval algorithm was validated in the Haihe River Basin in northern China (Li et al., 2011), and the soil heat flux correction algorithm was validated in the GAME-Tibet campaign (Yang and Wang, 2008). Since the surface of the Heihe River Basin is extreme heterogeneous, additional comparisons of our algorithm in other areas of research would be better.

17 References:

Hu Y Q, Gao Y X, Wang J M, Ji G L, Shen Z B, Chen L C, Chen J Y and Li S Q: Some
achievements in scientific research during HEIFE, Plateau Meteorology, (03), 2-13, 1994.

Li, H., Liu, Q., Jiang, J., Wang, H., and Sun, L.: Validation of the land surface temperature
derived from HJ-1B/IRS data with ground measurements, Geoscience and Remote Sensing Symposium (IGARSS), 2011 IEEE International, Vancouver, Canada, 293-296, 2011.

Li, X., Cheng, G. D., Liu, S. M., Xiao, Q., Ma, M. G., Jin, R., Che, T., Liu, Q. H., Wang, W.
Z., Qi, Y., Wen, J. G., Li, H. Y., Zhu, G. F., Guo, J. W., Ran, Y. H., Wang, S. G., Zhu, Z. L., Zhou,
J., Hu, X. L., and Xu, Z. W.: Heihe Watershed Allied Telemetry Experimental Research (HiWATER):
Scientific Objectives and Experimental Design, Bulletin of the American Meteorological Society,
94, 1145-1160, 10.1175/BAMS-D-12-00154.1, 2013.

Liang, S. L., Zhang, X. T., Xiao, Z. Q., Cheng, J., Liu, Q., and Zhao, X.: Global LAnd Surface
Satellite (GLASS) Products: Algorithms, Validation and Analysis, 1 ed., SpringerBriefs in Earth
Sciences, Springer International Publishing, 2014.

Yang, K., and Wang, J.: A temperature prediction-correction method for estimating surface soil
heat flux from soil temperature and moisture data, Sci. China Ser. D-Earth Sci., 51, 721-729,
10.1007/s11430-008-0036-1, 2008.

Response: We deleted this statement because it was repetitive with the sentence preceding it.

34 35

P20L9-10: This statement about errors is not very specific!

36

38

37

P22L5: How do you justify a ground heat flux of 0 for buildings?

39 Response: In our study area, 'buildings' contain residents and roads. Influenced by local cli-40 mate situation, special materials with low heat conductance are used for residential buildings to 41 maintain cool conditions during the summer and warm conditions during the winter. Thus, we jus-42 tified using a ground heat flux of 0 for buildings. According to your comments, the buildings of 43 these residents were not prevalent. Thus, we recalculated all the data, and $G = 0.4R_n$ for buildings 44 during the summer (Kato, 2005). Reference: Kato, S., and Yamaguchi, Y.: Analysis of urban heat-island effect using ASTER and
 ETM+ Data: Separation of anthropogenic heat discharge and natural heat radiation from sensible
 heat flux, Remote Sensing of Environment, 99, 44-54, http://dx.doi.org/10.1016/j.rse.2005.04.026,
 2005.

5 6

7

P23L22ff: This statement is actually a result of what is summarized under point 1 in the general conclusion.

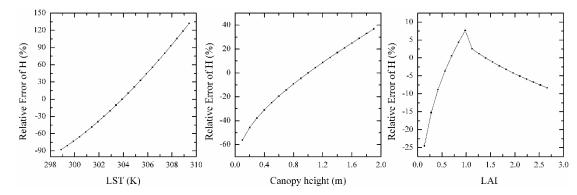
8 Response: We did not observe any relations between the statement at P23L22 and the general9 conclusion.

10

11 P24L25ff: Why do you use these specific day for calculating the sensitivities! In fig. 12 12 the x-axis shows variations in %. This makes it difficult to follow the interpretations of the 13 curves in the section.

Response: Sensitivity analysis is a general mathematic analysis procedure, and the presented input data for a specific day can indicate the influences of surface variables. We calculated the sensitivity results using large amounts of data from different phenophases, and our input data illustrated the sensitivities of our ET algorithm. To make the sensitivity analysis results universal, we drew a figure with % on the x-axis. We revised the paragraph and the x-axis in Figure 12 (Figure 13 in latest revised version) to make it easier to understand, especially for LST, because the discussed manuscript did not describe the x axis of LST variation clear, as follows:

21 "Since LE is calculated as a residual item in energy balance equations, the sensitivity of H is 22 analyzed at first. Land surface variables (including LST, LAI, canopy height, and FVC) and mete-23 orological variables (including wind speed, air temperature, air pressure and relative humidity) are 24 needed to estimate H in this paper. To locate the error source when retrieving H, a sensitivity analysis 25 was performed by adding errors at each 10% step (except LST). Fig. 13 presents the sensitivity 26 analysis results: LST = 303.9 K (ranging from 298.4~309.4 K with a step size of 0.5 K), LAI=1.4 27 (ranging 0.14~2.66 with a step size of 0.14), canopy height equals 1 m (ranging 0.1~1.9 m with a step size of 0.1 m), FVC=0.5, wind speed u=2.48 m·s⁻¹, air temperature Ta=297.9 K, air pressure = 28 29 97.2 kPa, and RH=40.29%. In addition, the land use type is maize, and the reference H is 230.2 W·m⁻²." 30



31 32

Figure 13. Sensitivity analysis of the surface variables for sensible heat flux

33

P29L5: Why do authors suddenly come up with the two source model – why didn't theyuse it initially?

36

Response: This sentence was deleted because it was not related to the objective of our study.

1	
2	P30: While the difference between Ts and Taero has been mentioned in the introduction,
3	why isn't that problem discussed here!
4	Response: Yes, we agree that the difference between Ts and Tareo should be discussed in this
5	paper. "Excess" resistance r_{ex} was added to r_a to correct the discrepancy between Ts and Tareo
6	in most remotely sensed evapotranspiration models. Thus, the error caused by the difference be-
7	tween Ts and Tareo was shifted to the parameterization scheme error of "excess" resistance, which
8	we discussed in the discussion. We revised this section as follows to clarify the discussion.
9	"In addition, to correct the discrepancy between remotely sensed radiative surface temperature
10	and aerodynamic temperature at the source of heat transport, a brief and well-performed parameter-
11	ization scheme (under uniformly flat plant surface) of "excess" resistance was used to calculate the
12	aerodynamic resistance of heat transfer (Jiao et al., 2014). Because the objects of our study are
13	mixed pixels, more parameterization methods should be compared to select the optimum method."
14	Reference: Jiao, J. J, Xin, X. Z., Yu S. S., Zhou, T. and Peng, Z. Q.: Estimation of surface en-
15	ergy balance from HJ-1 satellite data. Journal of Remote Sensing, 18(5), 1048-1058,
16	doi:10.11834/jrs.20143322, 2014
17	
18	P50: Table 13 – there is an error in the definition of the relative error (twice the same
19	expression in the difference)
20	Response: The mistake regarding the definition of relative error was corrected.
21	
22	Minor Comments:
23	
24	P3L4: Surface resistance is also needed for schemes classified under (1) because closure
25	schemes need to calculate H where ra is required as well.
26	Response: We classified these remotely sensed models to discuss their drawbacks when used
27	for heterogeneous surfaces. In addition, surface resistance is also needed for Penman-Monteith
28	equations. Thus, we do not think surface resistance needs to be classified in this paper because it
29	would disturb the flow of the manuscript and is not a focal point of our study.
30	
31	P3L20: Which models? All those listed in (1) - (5) or only those in (5)
32	Response: All those models listed in $(1) - (5)$.
33	
34	P3L24-25: I do not understand ": : : inhomogeneity is a relative concept of homogeneity:
35	: :!???
36	Response: We tried to express comparison concept of heterogeneous surface and weak hetero-
37	geneous surface and homogeneous surface. And we removed this sentence.
38	
39	P3L26: Density of what?
40	Response: The density of the vegetation variations. We revised this paragraph for clarity as
41	follows: "Surface landscape inhomogeneity can be classified using two scenarios: nonlinear vege-
42	tation density variations between sub-pixels (e.g., different types of vegetation mixed with each
43	other or with bare soil) and coarse pixels containing total different landscapes (e.g., vegetation or
44	bare soil mixed with buildings or water)."

1	
1	DAL Aff. I do not un denotor d'état contan co (statement)
2	P4L4ff: I do not understand that sentence/statement!
3	Response: We have revised this sentence as follows:
4	"However, it is difficult to develop linear operational models due to the complexity of mass
5	and heat transfer processes between the atmosphere and land surface."
6	
7	P13L18: what is $\langle d\epsilon \rangle$ in equation (15)?
8	Response: $\langle d\epsilon \rangle$ is an effective value of the cavity effect of emissivity and is the mean $d\epsilon$ of
9	all vegetation species. In this paper, $\langle d\epsilon \rangle = 0.015$. The definition of $\langle d\epsilon \rangle$ was updated in the manu-
10	script.
11	
12	P14L1: Sentence (: : : H Li et al : : :) does not make sense.
13	Response: The names of the authors were located incorrectly due to typesetting. We corrected
14	this problem as follows:
15	"A single-channel parametric model for retrieving LST based on HJ-1B/IRS TIR data devel-
16	oped by H. Li et al. (2010) was applied."
17	
18	P14L7: What is 6SLUT? Reference!
19	Response: 6SLUT is a look up table that was generated by the 6S (Second Simulation of a
20	Satellite Signal in the Solar Spectrum) radiation transfer mode (Vermote et al., 2006). The following
21	reference was added in the paper.
22	Reference: Vermote E F, Tanre D, Deuze J L, et al. Second Simulation of a Satellite Signal in
23	the Solar Spectrum-Vector. 6S User Guide Version 3, 2006.
24	
25	P28L1: Sentence (::: greatly decreased the heterogeneity) does not make sense
26	Response: We have corrected this expression as follows:
27	"The temperature sharpening algorithm in TSFA uses the NDVI at 30 m to monitor the LST at
28	30 m and is capable of decreasing the influences of the heterogeneity of the LST."
29	K. Mallick (Referee)
30	kaniska.mallick@gmail.com
31	Received and published: 15 February 2016
32	General Comments:
33	In this manuscript, the authors compared two different spatial aggregation approaches to
34	retrieve and evaluate the land surface energy balance fluxes using remote sensing data from the
35	Chinese HJ-1B. One approach (IPUS) uses information aggregated to the 300m resolution as
36	given by the thermal channel while the second approach (TSFA) uses a thermal sharpening
37	approach by utilizing NDVI – TS relationship and downscaling 300m Ts into the 30m. Authors
38	showed the differences between both approaches. Validation exercise is also performed to
39	demonstrate the advantages and improved prediction capacities of the TSFA approach. This
39 40	study is very useful to the community and worth publishing. However, the authors need to
40 41	address the following concerns before a possible publication.
41 42	accress the ronowing concerns before a possible publication.
42 43	The sentence constructions also need to be better in some part of the manuscript.
75	The sentence constructions also need to be better in some part of the manuscript.

(1) A clear hypothesis and research question is missing in the manuscript.

Response: Our basic hypothesis is that the inhomogeneity of surface landscapes and variables
in the mixed pixels would result in large ET estimation error. In this study, we aimed to reduce the
uncertainty of ET estimations caused by landscape and surface variables. We revised the introduction to clarify our hypothesis and goals.

6 7

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1

(2) Is it really necessary to aggregate the NDVI from 30 m to 300 m as described in the IPUS method? Why not using the 30 m NDVI with 300 m LST?

9 Response: Thank you for your valuable comments. Although it is important to compare the 10 TSFA method with the IPUS method, this comparison is not sufficient. We assume that ET estima-11 tion errors mainly result from the inhomogeneity of surface landscapes and variables. We aim to 12 reduce the uncertainties of ET estimations due to surface heterogeneities and use the TSFA method 13 as our final method. To evaluate the ability of the TSFA method to capture surface heterogeneity 14 and reveal the scale effect, we used the IPUS method because it does not consider the effects of 15 mixed pixels at all. According to your comments, we added the TRFA (temperature resampling and 16 flux aggregation) method, which uses 30 m visible/near infrared and 300 m thermal infrared band 17 data to estimate ET and simple spatial LST resampling (300 m to 30 m) instead of spatial sharpening 18 based on NDVI information. Comparisons of the TFSA and TRFA methods can be used to evaluate 19 the effects of temperature sharpening on estimating ET, as well as the significance of separating 20 inhomogeneity of landscape from that of surface variables (such as LST), and that would make our 21 logic clearer.

22

(3) More emphasis is given on discussing the sensible heat flux (For example Table 11,
12, 13 and 14). A balanced discussion involving both LE and H would read better and rational.
Response: We revised the manuscript by placing more emphasis on discussing the LE with a
balance analysis and discussion of H.

27

(4) Suggest including a table on different input data, their source and for what purposethey were used.

Response: Thank you for your suggestion. A table of abbreviations and the usage of input datawere added in the appendix.

32 33

34

35

(5) The table and figure captions need to be explicit.

Response: We revised the table and figure captions.

36 (6) Abstract: Some statistics need to be added in the abstract. At this moment it reads too37 general.

38 Response: We revised the abstract by adding and updating statistical results as follows:

39 "Evapotranspiration (ET) plays an important role in surface-atmosphere interactions and can 40 be monitored using remote sensing data. However, surface heterogeneity including inhomogeneity 41 of landscapes and surface variables affects the accuracy of ET estimated from satellite data signifi-42 cantly. The objective of this study is to assess and reduce the uncertainties resulted from surface 43 heterogeneity in remotely sensed ET using Chinese HJ-1B satellite data, which is of 30m spatial 44 resolution in VIS/NIR bands and 300m spatial resolution in TIR band. A temperature sharpening

and flux aggregation scheme (TSFA) was developed to obtain accurate heat fluxes from the HJ-1B 1 2 satellite data. Two methods employing different upscaling policies of surface variables and fluxes 3 were used to compare with TSFA, i.e., IPUS (input parameter upscaling) and TRFA (temperature 4 resampling and flux aggregation). Moreover, the three methods can also be regarded as representing 5 three typical schemes handling mixed pixels from the simplest to the most complex, i.e., all surface variables are at coarse resolution (300 m in this study) in IPUS and fine resolution (30 m in this 6 7 study) in TSFA, while TRFA is in the middle (both 30m and 300m variables are used). Analysis and 8 comparison between them can help us to get better understandings about spatial scale errors in re-9 mote sensing of surface heat fluxes. In situ data collected during HiWATER-MUSOEXE (Multi-10 Scale Observation Experiment on Evapotranspiration over heterogeneous land surfaces of The 11 Heihe Watershed Allied Telemetry Experimental Research) were used for the validation and analy-12 sis of the methods. ET estimated by TSFA is of best agreement with in-situ observations, the foot-13 print validation results show that the R2, MBE, and RMSE of the sensible heat flux (H) were 0.61, $0.90 \text{ W} \cdot \text{m}^{-2}$ and $50.99 \text{ W} \cdot \text{m}^{-2}$, respectively, and the corresponding terms for the latent heat flux (LE) 14 were 0.82, -20.54 W·m⁻² and 71.24 W·m⁻², respectively, and IPUS showed the largest errors in ET 15 estimation. The RMSE of LE between the TSFA and IPUS methods was 51.30 W·m⁻², and the 16 17 RMSE of LE between the TSFA and TRFA methods was 16.48 W·m⁻². Furthermore, additional 18 analysis shows that the TSFA method can capture the sub-pixel variations of land surface tempera-19 ture and integrate the effects of overlooked landscapes in mixed pixels." 20 21 (7) Page 2, line 16: Evapotranspiration is a variable, not a 'parameter' as stated by the authors. Authors should know the difference between a parameter and a variable. 22 23 Response: We agree with your opinion that evapotranspiration is a variable rather than a 'pa-24 rameter'. We have revised this phrasing throughout the manuscript. 25 26 (8) Page 2, line 16: Reference is too old. Many recent references are available. 27 Response: Thank you for this reminder. We agree that the presented references are old. This 28 paragraph was mainly introduced to highlight the importance of ET. We deleted this paragraph be-29 cause hydrologists should already understand the importance of ET. 30 31 (9) Page 2, line 22-22: This sentence does not carry anything meaningful. Please make 32 your statement clear. 33 Response: We agree with your opinion and have deleted this meaningless sentence to introduce 34 the models directly. 35 36 (10) Page 3, line 37: it should be 'landscapes' instead of 'landscape'. 37 Response: We have made this suggested correction. 38 39 (11) Page 3 (line 23 onwards to page 4): The last paragraph is quite confusing to under-40 stand. 41 Response: We have revised this paragraph. 42 (12) Page 4, L26: 'Land based parameters': : ...LAI, LST, DLR are not parameters, these 43 44 are variables. This is becoming confusing now.

1	Response: Thank you for your suggestion. We have revised our use of 'parameters' throughout
2	the manuscript.
3	
4	(13) Page 5, L10: The resolution: : :: : .: Need to be explicit on what is intended here by
5	'resolution'.
6	Response: We revised this sentence as follows:
7	"The spatial resolution of TIR images is usually not as high as the spatial resolution of visible
8	near-infrared bands (VNIR) because the energy of VNIR photons is higher than the energy of ther-
9	mal photons. Thus, the inhomogeneity of TIR images would be greater than the inhomogeneity of
10	VNIR images."
11	
12	(14) Throughout the entire manuscript, the authors are confused about 'parameter'.
13	Response: Thank you for your suggestion. We have revised our use of 'parameter' throughout
14	the manuscript.
15	
16	(15) Section 4.3.2, paragraph 3: The authors have not mentioned anything about the LE
17	statistics of the two methods.
18	Response: We revised this paragraph and emphasized the LE.
19	
20	(16) Spatial comparison of surface fluxes (as mentioned in section 4.3.2) should be done
21	at least for 2 different vegetation cover conditions.
22	Response: Thank you for your suggestion. We added comparisons of the turbulent heat fluxes
23	for the two following weak heterogeneity conditions: (1) different vegetation cover conditions and
24	(2) vegetation mixed with bare soil.
25	
26	(17) I made some edits and comments in the manuscript pdf (attached here), which the
27	authors should consider.
28	Response: The provided edits and comments were addressed in the manuscript.
29 20	Specific comments in attached adfi
30 21	Specific comments in attached pdf:
31 32	How did you assign the crop height and ancillary parameter information in the stability corrections.
32 33	Response: A widely used parameterization scheme was used for stability correction. The equa-
33 34	tions used are listed below.
35	From the Monin-Obukhov similarity theory (MOST), the aerodynamic resistance r_a can be
36	calculated as follows:
50	
37	$r_{a} = \frac{1}{ku_{*}} \left[\ln(\frac{z-d}{z_{0m}}) - \psi_{H}(\frac{z-d}{L}) \right] $ (1)
38	$u_* = ku[ln(\frac{z-d}{z_{0m}}) - \psi_M(\frac{z-d}{L})]^{-1} $ (2)
39	$L = -\rho c_{\rm p} \frac{u_*^3 \theta_{\rm v}}{\rm kgH} $ (3)
40	where $k = 0.4$ and is the von Karman's constant, u_* is the friction velocity, u is the wind speed

41 at a reference height of z above the surface, d and z_{0m} are the zero plane displacement height

and the roughness length for momentum transfer, respectively, L is the Monin-Obukhov length, g is the acceleration due to gravity and θ_v is the potential virtual temperature near the surface. In addition, ψ_M and ψ_H are stability functions, where $\psi_M = \psi_H = 0$ under neutral conditions and ψ_M and ψ_H can be parameterized as follows under unstable conditions (Paulson, 1970; Ambast et al., 2002):

$$\psi_{\rm M} = 2\ln\left[\frac{1+x}{2}\right] + \ln\left[\frac{1+x^2}{2}\right] - 2\tan^{-1}x + \frac{\pi}{2} \tag{4}$$

7

6

$$\psi_{\rm H} = 2\ln[(1+x^2)/2] \tag{5}$$

(6)

8 where $x = (1 - 16z/L)^{1/4}$. Under stable conditions, ψ_M is equal to ψ_H as follows (Webb, 1970):

 $\psi_{\rm M} = \psi_{\rm H} = -5 \cdot \frac{z-d}{L}$

10 The parameterization of the zero plane displacement height d and the roughness length z_{0m} are 11 determined as follows (Choudhury and Monteith, 1988):

12
$$d = 1.1h \ln(1 + (c_d LAI)^{1/4})$$
(7)

13
$$z_{0m} = \begin{cases} z_{0s} + 0.3h(c_d LAI)^{1/2} & 0 \le c_d LAI \le 0.2\\ 0.3h\left(1 - \frac{d}{h}\right) & 0.2 < c_d LAI \le 1.5 \end{cases}$$
(8)

where h is the canopy height and was set according to the area phenophase, classification and a priori knowledge. c_d is the mean drag coefficient and is assumed uniform within the canopy, LAI is the leaf area index, and z_{0s} is the substrate roughness length (for the bare soil surface, $z_{0s} =$ 0.01).

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30

How can you infer "The quadrangular with a relatively large bias in Fig. 9a and b is caused by DLR, i.e. it is influenced by the MOD05 water vapor."

32 Response: Bad lines appeared in the images scanned by MODIS Terra due to an instrumental 33 malfunction that occurred beginning in 2002. After preprocessing the original data by interpolation, 34 a weak quadrangular remained in the image. In addition, the MOD05 water vapor product was used 35 to calculate downward longwave radiation in this paper, which is an important and sensitive variable 36 of net radiation. We compared the results with the processed MOD05 product and observed that the 37 quadrangular overlapped well. In addition, the order of magnitude at the quadrangular was within 38 ± 5 W·m⁻², which matches the bias caused by the downward longwave radiation between IPUS and 39 TSFA.

40 We revised the expression as follows (Fig. 9 becomes Fig. 11 in the latest revised manuscript,

1 in next page):

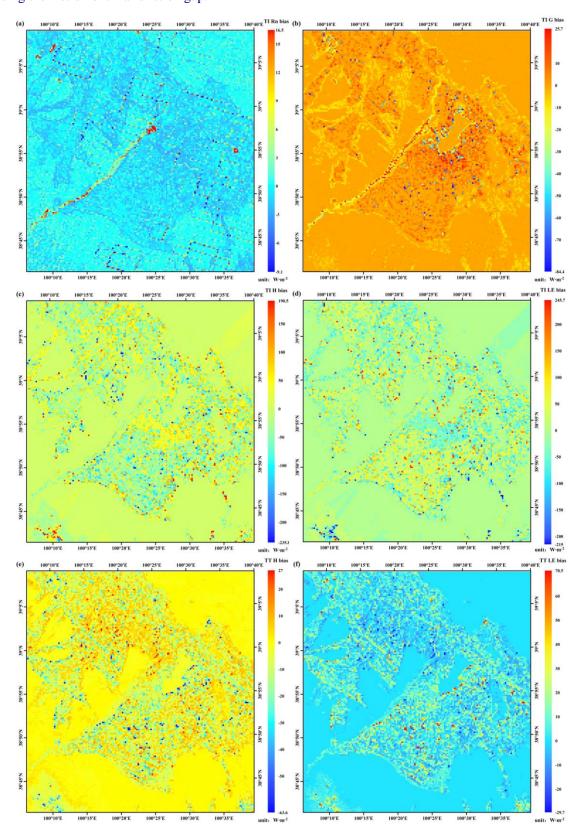


Figure 11. Maps of the bias of the energy balance components calculated using the TSFA method minus the IPUS method: (a) R_n, (b) G, (c) H, (d) LE, TSFA minus TRFA: (e) H and (f) LE.
Relevant changes

- All the changes were marked as red color in the manuscript.
 1. We have revised the abstract and introduction with hypothesis and research question stated.
 2. We revised the manuscript by placing more emphasis on discussing the LE with a balance
 analysis and discussion of H.
 3. Figure and table legends and names were revised.
 4. A table of abbreviations and the usage of input data were added in the appendix.
 5. New references were added.
- 12

Remote-sensing algorithm for surface evapotranspiration

14 considering landscape and statistical effects on mixed-pixels

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20 Abstract

21 Evapotranspiration (ET) plays an important role in surface-atmosphere interactions and can be 22 monitored using remote sensing data. However, surface heterogeneity including inhomogeneity of 23 landscapes and surface variables affects the accuracy of ET estimated from satellite data signifi-24 cantly. The objective of this study is to assess and reduce the uncertainties resulted from surface 25 heterogeneity in remotely sensed ET using Chinese HJ-1B satellite data, which is of 30m spatial 26 resolution in VIS/NIR bands and 300m spatial resolution in TIR band. A temperature sharpening 27 and flux aggregation scheme (TSFA) was developed to obtain accurate heat fluxes from the HJ-1B 28 satellite data. Two methods employing different upscaling policies of surface variables and fluxes 29 were used to compare with TSFA, i.e., IPUS (input parameter upscaling) and TRFA (temperature 30 resampling and flux aggregation). Moreover, the three methods can also be regarded as representing 31 three typical schemes handling mixed pixels from the simplest to the most complex, i.e., all surface 32 variables are at coarse resolution (300 m in this study) in IPUS and fine resolution (30 m in this 33 study) in TSFA, while TRFA is in the middle (both 30m and 300m variables are used). Analysis and 34 comparison between them can help us to get better understandings about spatial scale errors in re-35 mote sensing of surface heat fluxes. In situ data collected during HiWATER-MUSOEXE (Multi-36 Scale Observation Experiment on Evapotranspiration over heterogeneous land surfaces of The Heihe Watershed Allied Telemetry Experimental Research) were used for the validation and analy-37 38 sis of the methods. ET estimated by TSFA is of best agreement with in-situ observations, the foot-39 print validation results show that the R^2 , MBE, and RMSE of the sensible heat flux (H) were 0.61, 1 $0.90 \text{ W} \cdot \text{m}^{-2}$ and 50.99 W $\cdot \text{m}^{-2}$, respectively, and the corresponding terms for the latent heat flux (LE)

2 were 0.82, -20.54 W·m⁻² and 71.24 W·m⁻², respectively, and IPUS showed the largest errors in ET

3 estimation. The RMSE of LE between the TSFA and IPUS methods was 51.30 $W \cdot m^{-2}$, and the

4 RMSE of LE between the TSFA and TRFA methods was 16.48 W·m⁻². Furthermore, additional

5 analysis shows that the TSFA method can capture the sub-pixel variations of land surface tempera-

6 ture and integrate the effects of overlooked landscapes in mixed pixels.

- 7 Index Terms: heterogeneous surface, temperature sharpening, area weighting, energy balance, evapo-
- 8 transpiration, spatial scale, HJ-1B satellite

9 **1. Introduction**

10 Five types of methods have been developed to estimate evapotranspiration (ET) or latent heat 11 flux (LE) via remote sensing. (1) Surface energy balance models calculate LE as a residual term. 12 According to the partitioning of the sources and sinks of the Soil-Plant-Atmosphere Continuum 13 (SPAC), surface energy balance models can be classified as one-source (Bastiaanssen et al., 1998; 14 Su, 2002; Allen et al., 2007; Long and Singh, 2012a) or two-source models (Shuttleworth and Wal-15 lace, 1985; Norman et al., 1995; Xin and Liu, 2010; Zhu et al., 2013). (2) Penman-Monteith models 16 are used to calculate LE by using the Penman-Monteith equation and numerous surface resistance 17 parameterization schemes that control the diffusion of evaporation from land surfaces and transpi-18 ration from plant canopies. These two-source Penman-Monteith models separate soil evaporation 19 from plant transpiration (Cleugh et al., 2007; Mu et al., 2011; Leuning et al., 2008; Chen et al., 2013; 20 Sun et al., 2013; Mallick et al., 2015). (3) Land surface temperature-vegetation index (LST-VI) space 21 methods assign the dry and wet edges of the LST-VI feature space as minimum and maximum ET, 22 respectively. These methods interpolate the media using the Penman-Monteith or Priestley-Taylor 23 equation to calculate the LE (Jiang and Islam, 1999, 2001; Sun et al., 2011; Long and Singh, 2012b; 24 Yang and Shang, 2013; Fan et al., 2015; Zhang et al., 2005). (4) Priestley-Taylor models expand the 25 range of the Priestley-Taylor coefficient in the Priestley-Taylor equation (Jiang and Islam, 2003; Jin 26 et al., 2011) or combine the physiological force factors with the energy component of ET (Fisher et 27 al., 2008; Yao et al., 2013). (5) Additional methods include empirical/statistical methods (Wang and 28 Liang, 2008; Yebra et al., 2013) and the use of complementary based models (Venturini et al., 2008) 29 and land-process models with data assimilation schemes (Bateni and Liang, 2012; Xu et al., 2015).

All these ET estimation models are usually developed for simple and homogeneous surface conditions. When these remotely sensed models are applied to calculate the regional ET via satellite data, large spatial scale errors occur. Because heterogeneity is a natural attribute of the Earth's surface, non-linear operational model is another important issue of remotely sensed spatial scale error. However, it is difficult to develop linear operational models due to the complexity of mass and heat transfer processes between the atmosphere and land surface.

36 In previous studies, researchers have coupled high- and low-resolution satellite data and statis-37 tically quantified the inhomogeneity of mixed pixels to correct the scale error in ET estimations by 38 using temperature downscaling that converts images from a lower (coarser) to higher (finer) spatial 39 resolution using statistical-based models with regression or stochastic relationships among parameters (Kustas et al., 2003; Norman et al., 2003; Cammalleri et al., 2013; Ha et al., 2013), the correc-40 41 tion-factor method that uses sub-pixel landscapes information to regress the correction factor of 42 scale bias (Maayar and Chen, 2006) and the area-weighting method that calculates roughness length 43 and sensible heat flux based on sub-pixel landscapes (Xin et al., 2012). These correction methods mainly focus on two problems: inhomogeneity of landscapes and inhomogeneity of surface varia-bles.

3 Studies have shown that different landscapes (Blyth and Harding, 1995; Moran et al., 1997; 4 Bonan et al., 2002; McCabe and Wood, 2006) and the sub-pixel variations of surface variables, such 5 as stomatal conductance (Bin and Roni, 1994), leaf area index (Bonan et al., 1993; Maayar and 6 Chen, 2006) can cause errors in turbulent heat flux estimations. Surface variables inhomogeneity is 7 rather difficult to evaluate as the sub-pixel variation of surface variables could be large even in the 8 pure pixel. For example, generally, temperatures over the land surfaces vary strongly in space and 9 time, and it is not unusual for the LST to vary by more than 10 K over just a few centimeters of 10 distance or by more than 1 K in less than a minute over certain cover types (Z. Li et al., 2013). But 11 in mixed pixels, surface variables such as land surface temperature are set as singular to represent 12 the entire pixel area in ET estimation models.

13 The focus of this study is on the effects of surface heterogeneity when estimating ET. Accord-14 ing to the current satellites operation situation, three methods were used to analyze the uncertainty 15 produced by surface heterogeneity. Input parameter upscaling (IPUS) does not consider the surface 16 heterogeneities at all. It was designed to simulate the satellites that have identical spatial resolution 17 both in visible near-infrared (VNIR) and thermal infrared bands (TIR), such as the land surface 18 products of Moderate-Resolution Imaging Spectroradiometer (MODIS) satellites. Temperature 19 resampling and flux aggregation (TRFA) only does not consider the heterogeneity of LST, and tem-20 perature sharpening and flux aggregation (TSFA) consider all the surface heterogeneities. They 21 were designed for the majority of satellites data or products that have inconsistent spatial resolution 22 between VNIR and TIR, such as Landsat and HJ-1B satellites.

23 Surface variables in this paper mainly derived from HJ-1B satellite data were used for this 24 purpose. The Chinese HJ-1A/B satellites were launched on September 6, 2008, and were designed 25 for disaster and environmental monitoring, as well as other applications. The HJ-1B satellites are 26 equipped with two charge-coupled device (CCD) cameras and one infrared scanner (IRS) with spa-27 tial resolutions of 30 m and 300 m, respectively. Compared with high-temporal-resolution satellites, 28 such as the MODIS satellite, or high-spatial-resolution satellites, such as the Landsat 7 or 8 satellites, 29 HJ-1B has the advantage of a high spatial-temporal resolution. Since the satellites were launched, 30 the HJ-1/CCD time series data have been widely used in China to accurately classify land cover 31 (Zhong et al., 2014a) and monitor various environmental disasters (Wang et al., 2010). Land-based 32 variables, such as leaf area index (LAI), land surface temperature (LST), and downward longwave 33 radiation (L_d), have been retrieved by the HJ-1 satellites using algorithms developed by Chen et al. 34 (2010), H. Li et al. (2010, 2011) and Yu et al. (2013), respectively. These variables lay the foundation 35 for ET research.

Although the HJ-1B satellites provide CCD data with a high spatial resolution of 30 m, the spatial resolution of the thermal infrared (TIR) band is only 300 m. Thus, surface heterogeneity effects must be considered when estimating the heat flux.

39 2. Methodology

40 **2.1. Temperature-sharpening method based on statistical relationships**

Surface thermal dynamics are a driving force of ET. The spatial resolution of TIR images is
usually not as high as the spatial resolution of visible near-infrared bands (VNIR) because the energy
of VNIR photons is higher than the energy of thermal photons. Thus, the inhomogeneity of TIR

images would be greater than the inhomogeneity of VNIR images. Once the inhomogeneity of TIR images is enhanced, the uncertainty of the variables is calculated in the TIR band, and variables such as the land surface temperature become unpredictable. Therefore, we would like to derive land surface temperature data with a high spatial resolution.

5 The different spatial resolutions of TIR and VNIR images make it possible to obtain the land 6 surface temperature at the spatial resolution of the VNIR images, which is referred to as tempera-7 ture-sharpening. Kustas et al. (2003) proposed a statistical temperature-sharpening method that 8 could be applied to remotely sensed evapotranspiration models. This method assumes that the neg-9 ative correlation between the Normalized Difference Vegetation Index (NDVI) and LST is invariant. 10 The NDVI reflects vegetation growth and cover, and the LST reflects surface thermal dynamics. 11 The LST decreases with increasing vegetation cover. The resulting scatter plots form a feature space 12 that is applicable at different scales when enough pixels exist.

HJ-1B satellite images can provide vegetation and thermal information at spatial resolutions of 30 m and 300 m, respectively. However, the 300 m resolution thermal data cannot be use to discriminate the surface temperatures of small targets within pixels. This deficiency can be addressed by using the functional relationship between NDVI and LST. A flowchart of temperature sharpening is shown in Fig. 1, and the LST at the NDVI pixel resolution can be derived based on the following steps (Kustas et al., 2003):

(1) The selection of a subset of pixels from the scene where the NDVI is the most uniform at a
 pixel resolution of 300 m. Calculate the coefficient of variation (CV) by using the original NDVI
 data (NDVI₃₀) with a resolution of 30 m and sort the values from smallest to largest. The CV is
 calculated as follows:

23 $CV = \frac{STD}{mean}$

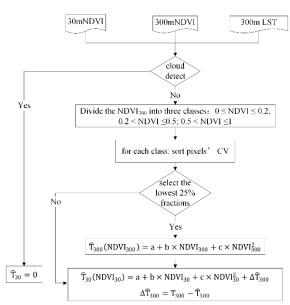
where STD and mean are the standard deviation and the average values, respectively, among the
$$10 \times 10$$
 pixels that make up each 300-m NDVI (NDVI₃₀₀) aggregated from NDVI₃₀.

26 (2) Next, the NDVI₃₀₀ is divided into several classes ($0 \le NDVI_{300} < 0.2$, $0.2 \le NDVI_{300} <$ 27 0.5 and $0.5 \le NDVI_{300}$). Lower CV values correspond with more homogeneous land surface val-28 ues, and a specific fraction should guarantee that a sufficient number of pixels is available for fitting 29 a least-squares expression between NDVI₃₀₀ and T₃₀₀. Then, the fractions (25%) of the pixels 30 having the lowest CV are selected from each class.

- 31 (3) A least-squares expression is fit between $NDVI_{300}$ and T_{300} using the selected pixels.
- 32

 $\widehat{T}_{300}(NDVI_{300}) = a + b \times NDVI_{300} + c \times NDVI_{300}^2$ (2)

(1)



1 2

5

Figure 1. Flowchart of temperature sharpening.

3 (4) For each 30-m pixel within the 300-m pixel, \hat{T}_{30} can be computed according to Eq. (2) as 4 follows:

$$\hat{T}_{30}(NDVI_{30}) = a + b \times NDVI_{30} + c \times NDVI_{30}^2 + \Delta \hat{T}_{300}$$
(3)

where $\Delta \hat{T}_{300} = T_{300} - \hat{T}_{300}$ is the deviation between the regressed temperature and the tempera-6 7 ture that was observed by the satellite at 300 m.

8 2.2. Area-weighting method based on landscape information

9 Coarse pixels are inhomogeneous because various types of land use may be included. Using a 10 dominant type to represent such a large landscape is irrational. When a sharpened temperature is obtained, the spatial details could be provided by surface variables at a high resolution, and the 11 12 inhomogeneous problem could be greatly diminished as the landscape is divided into finer pixels.

13

25

Combined with a high-resolution classification map, sub-pixel scale parameters can be applied 14 to the ET algorithm, which is more rational than using a dominate-class type because different land-15 scapes might require different ET algorithms. The surface energy flux can be averaged linearly due 16 to the conservation of energy (Kustas et al., 2003), and a simple average that calculates the arithme-17 tic mean over sub-pixels is the best choice for flux upscaling approaches (Ershadi et al., 2013b). Thus, the aggregated flux at a low resolution F(x, y) is the arithmetic mean of all of the $n \times n$ 18 19 sub-pixel fluxes that constitute the contributing flux $F(x_i, y_j)$ at coordinate (x_i, y_j) as follows:

20
$$F(x,y) = \frac{1}{n \times n} \sum_{i=1}^{n} \sum_{j=1}^{n} F(x_i, y_j)$$
 (4)

21 Because the average of the sub-pixels fluxes is equal to the area-weighted sum of each land-22 type result, the final coarse result can be derived by the area-weighted sum of each land-type result 23 within the landscape. The main steps of the area-weighting process are shown below (Xin et al., 24 2012):

(1) Geometric correction and registration of the VNIR and TIR input datasets.

26 (2) Count area ratio of different land-cover types within each pixel of a low-spatial-resolution 27 classification image.

28 (3) According to the fine-classification data, different parameterization schemes can be used in 29 the ET algorithm to calculate the sub-pixel flux, such as net radiation (R_n), soil heat flux (G) and 1 sensible heat flux (H).

2 (4) To calculate the regional flux, the flux of the large pixel is calculated by the area-weighting 3 method as follows:

4

$$\mathbf{F} = \sum_{i=1}^{n} \mathbf{w}_i \cdot \mathbf{F}_i \tag{5}$$

where w_i is the fractional area contributing flux F_i of class type i, and F is the aggregated flux 5

- 6 at the coarse resolution. The LE is computed as a residual of the surface energy balance in the TSFA 7 (Temperature Sharpening and Flux Aggregation, see Sect. 2.3) process, in which a high-spatial-
- 8 resolution image is used to reduce the mixed pixels.

9 2.3. Pixel ET algorithm

10 The surface energy balance describes the energy between the land surface and atmosphere. The 11 energy budget is commonly expressed as follows:

12

$$R_n = LE + H + G \tag{6}$$

where R_n is the net radiation, G is the soil heat flux, H is the sensible heat flux, and LE is the 13 14 latent heat flux absorbed by water vapor when it evaporates from the soil surface and transpires 15 from plants through stomata. The widely used one-source energy balance model considers the ho-16 mogeneous SPAC medium and ignores the inhomogeneity and structure. The LE can be expressed 17 as follows:

18

$$LE = \frac{\rho c_p}{\gamma} \cdot \frac{e_s - e_a}{r_a + r_s} \tag{7}$$

(8)

19 where γ is the psychometric constant; e_s and e_a are the aerodynamic saturation vapor pressure 20 and atmospheric water vapor pressure, respectively; and r_a and r_s are the water vapor transfer 21 aerodynamic resistance and surface resistance, respectively. Surface resistance includes soil re-22 sistance and canopy resistance. The surface resistance is influenced by the physiological character-23 istics of the vegetation and the water supply of roots. Thus, it is difficult to obtain surface resistance 24 by using remote sensing, and surface resistance is highly uncertain, particularly over heterogeneous 25 surfaces. To avoid error introduced by the uncertainty of the surface resistance, the LE is computed 26 as a residual of the surface energy balance equation.

27 28

36

$$R_n$$
 is the difference between incoming and outgoing radiation and is calculated as follows:

 $R_n = S_d(1 - \alpha) + \varepsilon_s L_d - \varepsilon_s \sigma T_{rad}^4$ where S_d is the downward shortwave radiation, α is the surface broadband albedo, ε_s is the 29 emissivity of the land surface, L_d is the downward atmospheric longwave radiation, $\sigma=5.67\,\times$ 30 $10^{-8}W\cdot m^{-2}\cdot K^{-4}$ is the Stefan-Boltzmann constant, and T_{rad} is the surface radiation tempera-31 32 ture.

33 G is commonly estimated by deriving empirical equations that consider surface variables, such 34 as R_n . Because the canopy exerts a significant influence on G, the fractional canopy coverage FVC 35 is used to determine the ratio of G to R_n as follows:

> $G = R_n \times [\Gamma_c + (1 - FVC) \times (\Gamma_s - \Gamma_c)]$ (9)

37 where Γ_s is 0.315 for bare soil and Γ_c is 0.05 for a full vegetation canopy (Su, 2002). H is the 38 transfer of turbulent heat between the surface and atmosphere that is driven by a temperature differ-39 ence and is controlled by resistances that depend on local atmospheric conditions and land cover 40 properties (Kalma et al., 2008). According to gradient diffusion theory,

41
$$H = \rho c_p \frac{T_{aero} - T_a}{r_a}$$
(10)

1 where ρ is the density of the air; c_p is the specific heat of the air at a constant pressure; T_{aero} is 2 the aerodynamic surface temperature obtained by extrapolating the logarithmic air-temperature pro-3 file to the roughness length for heat transport; T_a is the air temperature at a reference height; and r_a is the aerodynamic resistance, which influences the heat transfer between the source of turbulent 4 5 heat flux and the reference height. Aerodynamic resistance was calculated based on the Monin-6 Obukhov similarity theory (MOST) using a stability correction function (Paulson, 1970; Ambast et 7 al., 2002). The zero-plane displacement height, d, and roughness length, z_{0m} , were parameterized 8 by the schemes proposed by Choudhury (Choudhury and Monteith, 1988). 9 In this approach, H must be accurately estimated. However, calculating H by using Eq. (10)

is difficult. Because remote sensing cannot obtain T_{aero} , the value of T_{aero} is usually replaced by the radiative surface temperature T_{rad} , which is not always equal to T_{aero} . The difference between these terms for homogeneous and fully covered vegetation is approximately 1-2°C (Choudhury et al., 1986), or up to 10°C in sparsely vegetative areas (Kustas, 1990). The method that corrects for this discrepancy adds "excess" resistance r_{ex} to r_a . We used the brief method $r_{ex} = 4/u_*$, which

15 was proposed by Chen (1988), to calculate r_{ex} .

Fig. 2 shows a flowchart for merging ET retrieval and temperature sharpening based on HJ-1Bsatellites.

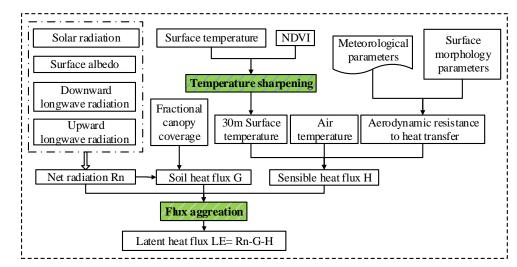
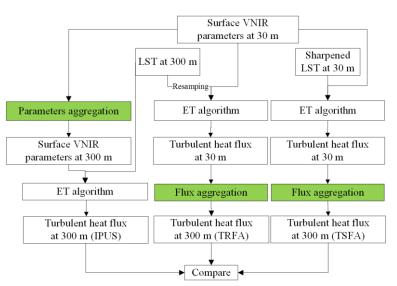




Figure 2. Flowchart of ET retrieval using the "Temperature Sharpening and Flux Aggregation" method.

20 The spatial scale effect is usually revealed by a discrepancy between different upscaling meth-21 ods: the upscaling of aggregate parameters to the large scale to calculate the heat flux and the cal-22 culation of the heat flux at the small scale before upscaling it to the large scale. In this paper, the 23 resolution of the final output result is 300 m. To evaluate the reduced heterogeneity effect of TSFA, 24 two other upscaling methods called IPUS and TRFA were used (see Fig. 3). When using IPUS, the 25 surface-parameter retrieving algorithms (see Sect. 3.2.1.1) are applied to HJ-1 CCD data. Then, the variable results are aggregated at a spatial resolution of 300 m. These 300 m outputs are used as 26 27 input parameters in the one-source energy balance model to obtain the four energy-balance compo-28 nents at 300 m. In TRFA, the LST at 300 m is resized to 30 m using nearest neighbor sampling. Then, the resampled LST and surface VNIR variables at 30 m are applied to ET algorithm. The 29 30 outputs of the four energy-balance components of the TRFA are obtained using the area-weighting 31 method shown in Sect. 2.2.



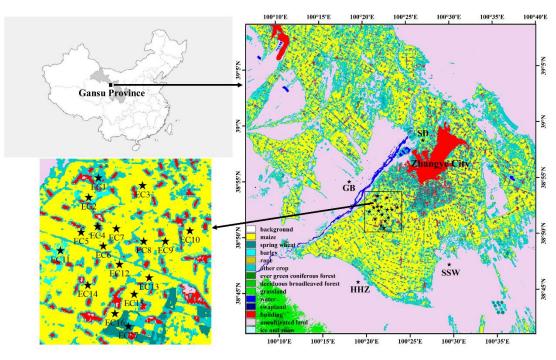
1 2

Figure 3. Flowchart of the three upscaling methods for retrieving evapotranspiration.

3 3. Study area and Dataset

4 **3.1. Study area**

5 Our study was conducted in the middle stream of the Heihe River Basin (HRB), which is lo-6 cated near the city of Zhangye in the arid region of Gansu Province in northwestern China 7 (100.11 E-100.16 E, 39.10 N-39.15 N). The middle reach of the HRB is a typical desert-oasis ag-8 riculture ecosystem dominated by maize and wheat. A large portion of the Gobi Desert and the 9 alpine vegetation of Qilian Mountain are located near the study area (see Fig. 4). The artificial oasis 10 is highly heterogeneous, which impacts the thermal-dynamic and hydraulic features. Consequently, 11 the water use efficiency and ET are variable. The Heihe River Basin has long served as a test bed for integrated watershed studies as well as land surface or hydrological experiments. Comprehen-12 13 sive experiments, such as Watershed Allied Telemetry Experimental Research (WATER) (Li et al., 14 2009), and an international experiment - the Heihe Basin Field Experiment (HEIFE) in World Cli-15 mate Research Programme (WCRP) have taken place in the Heihe River Basin. One major objective 16 of HiWATER is to capture the strong land surface heterogeneities and associated uncertainties 17 within a watershed (Li et al., 2013).



1 2

Figure 4. Study area and distribution of EC towers in HiWATER-MUSOEXE

3 **3.2. Dataset**

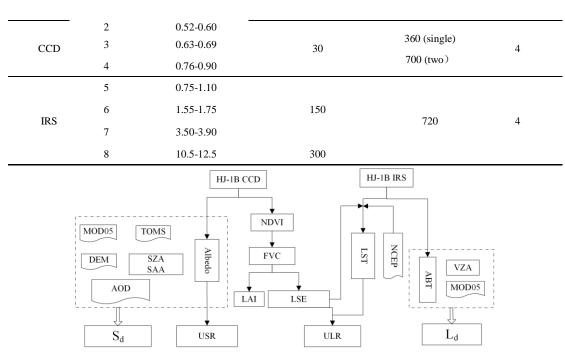
In this paper, the data are mainly derived from the HJ-1B satellite. We combined these data
with ancillary data and the in situ "Multi-Scale Observation Experiment on Evapotranspiration over
heterogeneous land surfaces of The Heihe Watershed Allied Telemetry Experimental Research"
(HiWATER-MUSOEXE) data to estimate and validate the HJ-B land surface variables and heat
fluxes.

9 3.2.1. Remote sensing data

10 3.2.1.1. HJ-1B satellite data

11 The specifications of HJ-1B are shown in Table 1. These satellites have quasi-sun-synchronous 12 orbits at an altitude of 650 km, a swath width of 700 km and a revisit period of 4 days. Together, the 13 revisit period of the satellites is 48 h. Because HJ-1 CCDs lack an onboard calibration system, 14 scholars have proposed cross-calibration methods for calibrating the CCD instruments (Zhong et al., 2014b; Zhang et al., 2013). The image quality of HJ-1A/B CCDs is stable, the performances of each 15 16 band are balanced (Zhang et al., 2013), and the radiometric performance of the HJ-1A/B CCD sen-17 sors is similar to the performances of the Landsat-5 TM, Advanced Land Imager, and ASTER sen-18 sors. The image quality of HJ-1 CCDs is very similar to the image quality of Landsat-5 TM (Jiang 19 et al., 2013). In addition, the accuracy of the TIR band's onboard calibration meets land surface 20 temperature retrieval requirements but not sea surface temperature retrieval requirements (J. Li et 21 al., 2011). China Center for Resources Satellite Data and Application (CRESDA) releases calibra-22 tion coefficients once each year on its website (http://www.cresda.com). These data are freely avail-23 able from the CRESDA website (http://218.247.138.121/DSSPlatform/index.html). 24 Table 1. Specifications of the HJ-1B main payloads

			1	1	5
_	Sensor	Band	Spectral range (µm)	Spatial resolution (m)	Swath width (km) Revisit time (days)
-		1	0.43-0.52		



1

Figure 5. Flowchart of the land surface variable retrieval. The abbreviations are defined as follows: SZA: solar zenith angle; SAA: solar azimuth angle; VZA: view zenith angle; AOD: aerosol optical depth; ABT: at-nadir brightness temperature; Sd: downward shortwave radiation; USR: upward shortwave radiation, ULR: upward longwave radiation; and Ld: downward longwave radiation.

6 We used the HJ-1B satellite data for the HRB region in 2012. Because many variable-retrieving 7 algorithms required clear-sky conditions for calculating ET, we combined data-quality information 8 with visual interpretation to select satellite images without clouds. Considering the time period of 9 the ground observations discussed in Sect. 3.2.2, we obtained data for 11 days: June 19, June 30, 10 July 8, July 27, August 2, August 15, August 22, August 29, September 2, September 13 and Sep-11 tember 14.

The HJ-1B satellite data from the HRB were pre-processed and included geometric correction, radiometric calibration, and atmosphere correction. For Eq. (1) to (10), the following surface variables are needed: downward shortwave radiation, downward longwave radiation, emissivity, albedo, fractional vegetation coverage (FVC), cloud mask data, meteorological data, LAI and LST. Fig. 5 contains a flowchart showing the retrieval of these variables.

(1) Surface albedo. According to the algorithm proposed by Liang et al. (2005) and Q. Liu et
al. (2011), surface albedo was obtained from the top of the atmosphere (TOA) reflectance by the
HJ-1 satellite with a lookup table based on an angular bin regression relationship. The surface albedo
and bidirectional reflectance distribution function (BRDF) of the HJ-1 satellite in the regression
procedure were monitored by using POLDER-3/PARASOL BRDF datasets, and BRDF was used to
obtain the TOA reflectance using the 6S (Second Simulation of a Satellite Signal in the Solar Spectrum)
radiation transfer mode.

(2) NDVI, FVC and LAI. The NDVI is the central regression of temperature sharpening and
 was used to calculate the FVC. Atmospherically corrected surface reflectance values were used to
 calculate the NDVI as follows:

27

$$NDVI = \frac{\rho_{nir} - \rho_{red}}{\rho_{nir} + \rho_{red}}$$
(11)

28 and

1

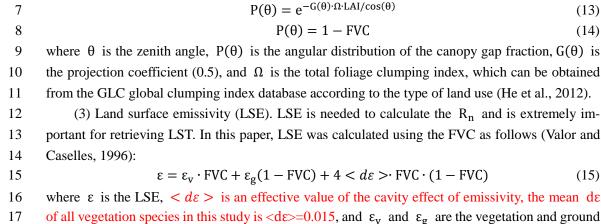
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$FVC = \frac{NDVI - NDVI_s}{NDVI_v + NDVI_s}$ (12)



LAI was determined using the following equation (Nilson, 1971):

where ρ_{nir} and ρ_{red} are the reflectances in the near-infrared and red band, respectively, and

NDVI_v and NDVI_s are the fully vegetated and bare soil NDVI values, respectively. As an im-

portant input for the parameterization of surface roughness length and aerodynamic resistance, the

18 emissivity, respectively.

(4) Land surface temperature. A single-channel parametric model for retrieving LST based on
 HJ-1B/IRS TIR data developed by H. Li et al. (2010) was applied. This model was developed from
 a parametric model based on MODTRAN4 using NCEP atmospheric profile data.

(5) Downward shortwave radiation. The algorithm proposed by L. Li et al. (2010) was applied.
MOD05, TOMS, aerosol, and solar angle data were used to estimate the direct light flux and diffuse
light flux by using a lookup table that was generated using the 6S radiation transfer mode (Vermote
et al., 2006). This method considered the influences of complex terrain, and a topographic correction
was performed by using products of the ASTER DEM.

27 (6) Downward longwave radiation (Ld). The TOA brightness temperature of the HJ-1B thermal 28 channel was used to substitute the atmospheric effective temperature. Effective atmospheric emis-29 sivity was parameterized as an empirical function of the water vapor content. These values were 30 substituted for atmospheric temperature and atmospheric emissivity to estimate the value of L_d. 31 Because this L_d retrieval method proposed by Yu et al. (2013) was only valid for clear-sky conditions, 32 cloud masking information was used to determine clear skies. When cloud contamination existed in 33 the image, the brightness temperature was relatively low, causing the L_d to be lower than that in the 34 cloudless images.

- 35 3.2.1.2. Ancillary data
- Ancillary data were used because the bands of the satellite could not invert all of the variablesneeded for retrieving ET.

(1) Atmospheric water vapor data. MODIS provides water vapor data (MOD05), including a
 1-km near-infrared product and a 5-km thermal-infrared product, every day. The 1-km near-infrared
 water vapor product was used to retrieve L_d in this study.

41 (2) Surface elevation data. We used the 30-m resolution Global Digital Elevation Model
42 (GDEM) based on ASTER, which covers 83 N–83 S, to derive S_d.

(3) Atmosphere ozone data. A Total Ozone Mapping Spectrometer (TOMS), which was carried
 on an Earth Probe (EP) satellite, was used to derive S_d. The TOMS-EP provided daily global at mosphere ozone data at a resolution of 1 °×1.25 °(Li et al., 2010b).

4 (4) Atmosphere profile data. Global reanalysis data from the National Centers for Environmen5 tal Prediction (NCEP) were used to derive LST. These data were generated globally every 6 hours
6 (0:00, 06:00, 12:00, 18:00 UTC) for every 1 °of latitude and longitude (Li et al., 2010a).

7 **3.2.2. HiWATER experiment dataset**

8 The in situ HRB observation data were provided by HiWATER. From June to September 2012,
9 HiWATER designed two nested observation matrices over 30 km×30 km and 5.5 km×5.5 km within
10 the middle stream oasis in Zhangye to focus on the heterogeneity of the scale effect in the so-called
11 HiWATER-MUSOEXE.

12 In a larger observation matrix, four eddy covariance (EC) systems and one superstation were 13 installed in the oasis-desert ecosystem. Each station was supplemented with an automatic meteor-14 ological station (AMS) to record meteorological and soil variables and monitor the spatial-temporal 15 variations of ET and its impact factors (Li et al., 2013). The station information is shown in Table 16 2, and the distribution of the stations is shown in Fig. 4. Within the artificial oasis, an observation 17 matrix composed of 17 EC towers and ordinary AMSs exists where the superstation was located. 18 The land surface was heterogeneous and dominated by maize, maize inter-cropped with spring 19 wheat, vegetables, orchards, and residential areas (Li et al., 2013). Because the EC16 and HHZ 20 stations lacked R_n and G observation data, they were excluded from this study.

21

Table 2. The in situ HiWATER-MUSOEXE station information

Station	Longitude ()	Latitude ()	Tower height (m)	Altitude (m)	Land cover
EC1	100.36E	38.89N	3.8	1552.75	vegetation
EC2	100.35E	38.89N	3.7	1559.09	maize
EC3	100.38E	38.89N	3.8	1543.05	maize
EC4	100.36E	38.88N	4.2	1561.87	building
EC5	100.35E	38.88N	3	1567.65	maize
EC6	100.36E	38.87N	4.6	1562.97	maize
EC7	100.37E	38.88N	3.8	1556.39	maize
EC8	100.38E	38.87N	3.2	1550.06	maize
EC9	100.39E	38.87N	3.9	1543.34	maize
EC10	100.40E	38.88N	4.8	1534.73	maize
EC11	100.34E	38.87N	3.5	1575.65	maize
EC12	100.37E	38.87N	3.5	1559.25	maize
EC13	100.38E	38.86N	5	1550.73	maize
EC14	100.35E	38.86N	4.6	1570.23	maize
EC15	100.37E	38.86N	4.5	1556.06	maize
EC17	100.37E	38.85N	7	1559.63	orchard
GB	100.30E	38.91N	4.6	1562	uncultivated land-Gobi
SSW	100.49E	38.79N	4.6	1594	uncultivated land-desert
SD	100.45E	38.98N	5.2	1460	swamp land

1 The ground observation data include the H and LE. Reliable methods were used to ensure the 2 quality of the turbulent heat flux data. Before the main campaign, an intercomparison of all instru-3 ments was conducted in the Gobi Desert (Xu et al., 2013). After basic processing, including spike 4 removal and corrections for density fluctuations (WPL-correction), a four-step procedure (data were 5 rejected when (1) the sensor was malfunctioning, (2) precipitation occurred within 1 h before or 6 after collection, (3) the missing ratio was greater than 3% in the 30-min raw record and (4) the 7 friction velocity was below 0.1 ms⁻¹ at night) was performed to control the quality of the EC data, 8 and EC outputs were available every 30 min (for more details see Liu et al., 2011b; Xu et al., 2013). 9 G was measured by using three soil heat plates at a depth of 6 cm at each site, and the surface G 10 was calculated using the method proposed by (Yang and Wang, 2008) based on the soil temperature 11 and moisture above the plates. Surface meteorological variables, such as wind speed, wind direction, 12 relative humidity and air pressure, were used to interpolate images using the inverse-distance 13 weighted method. Researchers can obtain these data from the websites of the Cold and Arid Regions 14 Science Data Center at LanZhou http://card.westgis.ac.cn/ or the Heihe Plan Data Management 15 Center http://www.heihedata.org/.

16 An energy imbalance is common in ground flux observations. The conserving Bowen ratio 17 (H/LE) and residual closure technique are often used to force energy balance. Computing the LE as 18 a residual variable may be a better method for energy balance closure under conditions with large 19 LEs (small or negative Bowen ratios due to strong advection) (Kustas et al., 2012). Thus, the resid-20 ual closure method was applied because the "oasis effect" was distinctly observed in the desert-21 oasis system on clear days during the summer (Liu et al., 2011).

22 4. Results and analysis

4.1. Evaluation of surface variables 23

24 To control the model input variables and analyze sources of error, the coarse-resolution land surface temperature, downward shortwave radiation, downward longwave radiation, Rn and G 25 26 were evaluated using in situ data.

27 The ground-based land surface temperature, T_s, was calculated using the Stefan-Boltzman Law from the AMS measurements of the longwave radiation fluxes (Li et al., 2014) as follows: 28

29
$$T_{s} = \left[\frac{L^{\dagger} - (1 - \varepsilon_{s}) \cdot L^{\downarrow}}{\varepsilon_{s} \cdot \sigma}\right]^{\frac{1}{4}}$$
(16)

in which L^{\uparrow} and L^{\downarrow} are in situ surface upwelling and atmospheric downwelling longwave radiation, 30 31 respectively, and ε_s is the surface broadband emissivity, which is regarded as the pixel value of the HJ-1B at the AMS. The coefficient of determination R², mean bias error (MBE) and root mean 32 33 square error (RMSE) of the LST are 0.71, -0.14 K and 3.37 K, respectively. As seen in Table 3, the 34 accuracy of EC4 is low. The main causes of the large errors are as follows: (1) because buildings 35 and soil/vegetation are distinct materials, the LSE algorithm may not be suitable for buildings and 36 (2) the EC4 foundation is non-uniform and is not suitable for validation. After removing the EC4 37 data, the R², MBE, and RMSE of the LSTs were 0.83, 0.69 K and 2.51 K, respectively. The LST 38 errors of SSW and SD were large due to large errors on particular days. For example, although it 39 was briefly cloudy above station SSW on July 27, this area was not identified as cloudy in the cloud 40 detection process. 41

Table 3. Station validation results of land surface temperature

	- 2		RMSE		- 2			
station	R ²	MBE (K)	(K)	station	R ²	MBE (K)	RMSE (K)	
EC1	0.82	0.18	1.74	EC11	0.42	1.59	2.98	
EC2	0.82	0.59	1.54	EC12	0.87	0.62	1.51	
EC3	0.69	0.38	1.90	EC13	0.83	0.44	1.48	
EC4	0.83	-9.87	10.04	EC14	0.73	1.43	2.44	
EC5	0.83	1.71	2.34	EC15	0.74	1.53	2.41	
EC6	0.61	0.30	2.44	EC17	0.78	1.20	2.32	
EC7	0.82	0.39	1.40	GB	0.69	0.12	2.33	
EC8	0.83	0.45	1.55	SSW	0.59	1.38	3.82	
EC9	0.63	2.31	3.15	SD	0.76	-3.83	4.84	
EC10	0.68	1.32	2.45					

1 The R², MBE, and RMSE values of S_d were 0.81, 13.80 W·m⁻², and 25.35 W·m⁻², respectively. 2 The station validation results are shown in Table 4. The accuracy of SSW is low. Because cloudy 3 conditions occurred briefly on July 27, few ground observations were obtained, and S_d was signif-

4 icantly overestimated. After removing these data, the R^2 , MBE, and RMSE values of S_d at SSW

5 were 0.87, 10.90 W \cdot m $^{-2}$ and 21.13 W \cdot m $^{-2}$, respectively.

6

Table 4. Station validation results of downward shortwave radiation

station	R ²	MBE (W·m ⁻²)	RMSE (W·m ⁻²)	station	R ²	MBE (W·m ⁻²)	RMSE (W·m ⁻²)
EC1	0.97	25.23	27.73	EC11	0.90	30.11	33.76
EC2	0.84	28.29	33.57	EC12	0.96	24.35	26.43
EC3	0.97	17.56	19.25	EC13	0.93	12.41	17.92
EC4	0.98	6.07	9.34	EC14	0.98	32.40	33.49
EC5	0.98	10.60	12.29	EC15	0.94	26.71	29.71
EC6	0.93	27.68	30.71	EC17	0.94	-20.25	24.54
EC7	0.89	-17.69	27.59	GB	0.89	25.34	30.63
EC8	0.83	15.63	25.50	SSW	0.63	18.51	34.93
EC9	0.96	-2.27	9.96	SD	0.98	5.70	13.82
EC10	0.94	-3.50	11.97				

The R², MBE, and RMSE of the HRB L_d were 0.73, 0.28 W·m⁻², and 21.24 W·m⁻², respectively. 7 8 As seen in Table 5, the accuracies at EC3, SD and SSW were low. The low accuracies at EC3 and 9 SD potentially resulted from (1) high humidity, which resulted in low at-nadir brightness tempera-10 tures and low retrieved L_d , or (2) instrument error, which occurred because the EC3 ground obser-11 vations were always greater than those of the other stations during the same period. Although SSW 12 was located in a desert, the ground-air temperature difference was large. The L_d retrieval may have 13 a large error because the models use surface temperature when estimating L_d to approximate or 14 substitute the near-surface temperature (Yu et al., 2013). The corrected error of our L_d retrieving algorithm resulted from the ground-air temperature difference in non-vegetated areas. The inaccu-15 16 racy of the SSW LST may influence the L_d results.

17

Table 5. Station validation results of downward longwave radiation

station	R ²	MBE	RMSE	station	D ²	MBE I	RMSE
		(W·m ⁻²)	(W·m ⁻²)		R ²	$(W \cdot m^{-2})$ (W∙m ⁻²)

EC1	0.85	4.16	17.21	EC11	0.93	-2.72	10.55
EC2	0.88	0.11	14.23	EC12	0.87	-0.84	14.80
EC3	0.91	-35.65	37.88	EC13	0.86	-7.28	15.98
EC4	0.88	3.36	16.38	EC14	0.82	4.07	16.42
EC5	0.88	-0.79	15.02	EC15	0.85	17.67	23.06
EC6	0.84	2.55	15.43	EC17	0.90	-1.11	12.87
EC7	0.75	-5.90	19.72	GB	0.88	9.50	27.82
EC8	0.80	-1.35	17.49	SSW	0.85	25.33	34.50
EC9	0.86	10.44	17.99	SD	0.85	-26.54	34.08
EC10	0.87	7.98	16.05				

1 The R², MBE, and RMSE of the HRB R_n were 0.70, -9.64 W·m⁻², and 42.77 W·m⁻², respec-2 tively. The station R_n validation results are shown in Table 6, which indicate that the accuracies of 3 EC4, EC7, EC17 and SSW were relatively low. According to the sensitivity analysis of Eq. (8), Ld and S_d are highly sensitive variables when calculating R_n , while the albedo, LSE and LST are not 4 5 as sensitive. Although LST was not a sensitive variable, the EC4's LST, MBE and RMSE reached -6 9.87 K and 10.04 K because the land cover of EC4 was maize at the 300 m resolution. However, 7 the observation tower was in a built-up area, which potentially caused errors when estimating R_n. 8 The accuracies of the EC7 S_d and L_d were low on several days, and after removing these data, 9 MBE=-43.40 W·m⁻² and the RMSE=50.50 W·m⁻². EC17 was within an orchard, and the signal that 10 was received by the sensors at EC17 were affected by the complex vertical structure of the orchard 11 ecosystem. The information on substrate plants may be ignored, leading to albedo retrieval errors. 12 Although the albedo was not a sensitive variable, a 0.03 bias can lead to an R_n error of approxi-13 mately 20 W·m⁻² when the solar incoming radiation is large. As previously mentioned, it was briefly 14 cloudy on July 27, and after removing that data, the R^2 , MBE, and RMSE values of the R_n obtained 15 at SSW were 0.72, 8.20 W·m⁻², and 37.60 W·m⁻², respectively.

16

station	R ²	MBE (W·m ⁻²)	RMSE (W·m ⁻²)	station	R ²	MBE (W·m ⁻²)	RMSE (W·m ⁻²)
EC1	0.76	-2.55	30.61	EC11	0.86	-15.13	28.05
EC2	0.79	2.52	25.24	EC12	0.90	-8.46	19.38
EC3	0.86	-35.84	42.97	EC13	0.88	-25.73	32.34
EC4	0.84	76.64	80.25	EC14	0.90	4.23	18.18
EC5	0.85	-24.41	32.34	EC15	0.84	8.33	23.01
EC6	0.82	4.35	23.44	EC17	0.89	-62.62	68.11
EC7	0.61	-58.66	67.83	GB	0.77	-10.40	38.86
EC8	0.83	-20.62	32.45	SSW	0.44	23.05	62.93
EC9	0.87	-29.60	36.27	SD	0.75	19.98	35.24
EC10	0.83	-24.35	33.51				

Table 6. Station net radiation validation results

17

The R², MBE, and RMSE of the G in the HRB were 0.57, 8.51 W·m⁻², and 29.73 W·m⁻², re-18 spectively. The station R_n validation results are shown in Table 7. For EC5, the soil temperature 19 and moisture were the same at different depths after July 19, which resulted in a surface G that was 20 equal to the G at a depth of 6 cm. The G below the surface was usually less than the G at the soil 21 surface; thus, the validation results of the G at EC5 indicate that G was overestimated. For SSW,

1 the brief cloudy period decreased the observed soil surface temperature, which decreased the calcu-

2 lated surface G. However, the remotely sensed G did not reflect this situation. In this case, the G

3 was overestimated because the R_n was overestimated. After removing the data on July 27, the R^2 ,

4 MBE, and RMSE of the G at SSW were 0.17, 19.34 W·m⁻², and 33.30 W·m⁻², respectively.

station	\mathbb{R}^2	MBE (W·m ⁻²)	RMSE (W·m ⁻²)	station	\mathbb{R}^2	MBE (W·m ⁻²)	RMSE (W·m ⁻²)
EC1	0.50	19.73	31.53	EC11	0.71	4.23	19.23
EC2	0.24	20.78	28.72	EC12	0.53	20.29	24.79
EC3	0.03	-1.15	36.28	EC13	0.91	-0.89	17.27
EC4	0.45	18.50	22.29	EC14	0.82	-1.89	18.72
EC5	0.38	41.87	60.19	EC15	0.78	6.68	15.80
EC6	0.83	-5.91	14.57	EC17	0.49	8.26	33.59
EC7	0.28	7.50	24.65	GB	0.29	-17.86	26.81
EC8	0.68	-5.73	20.15	SSW	0.01	30.41	51.87
EC9	0.61	6.83	26.96	SD	0.71	-4.79	13.71
EC10	0.41	7.68	28.67				

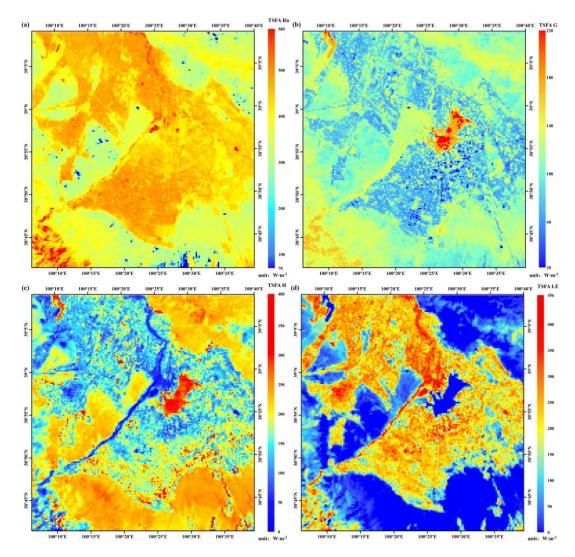
 Table 7. Station validation results of the soil heat flux

6 4.2. Validation of heat fluxes by TSFA

5

7 Fig. 6 provides the turbulent heat flux results calculated by TSFA on September 13, 2012. The 8 spatial distribution of the turbulent heat flux is obvious. The H of buildings and uncultivated land, 9 including the Gobi Desert, barren areas and other deserts, was high, in addition to the LEs of the water and agricultural areas in the oasis. The southern areas of the images show uncultivated barren 10 11 land bordering the Qilian Mountains that resulted from snowmelt and the downward movement of 12 water. In these areas, the groundwater levels are high and the soil moisture content is approximately 13 30% based on in situ measurements at a depth of 2 cm. Therefore, the LE is higher in the south than 14 in the southeast desert, although both areas were classified as uncultivated land.

Studies have shown that validation methods that consider the source area are more appropriate for evaluating ET models than traditional validation methods based on a single pixel (Jia et al., 2012; Song et al., 2012). In this study, a user-friendly tool presented by Neftel et al. (2008) and based on the Eulerian analytic flux footprint model proposed by Kormann and Meixner (2001) was used to calculate the footprints of the function parameters. The continuous footprint function was dispersed based on the relative weights of the pixels on which the source area fell.



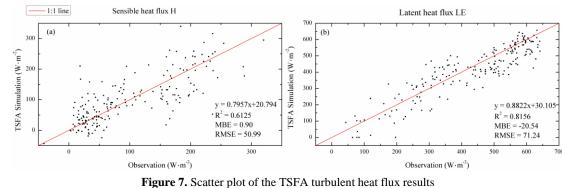
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2 Figure 6. Maps of the four energy components, (a) Rn, (b) G, (c) H and (d) LE, calculated by TSFA on September

3 13, 2012.



The footprint validation results of the TSFA turbulent heat fluxes are shown in Fig. 7 and Table
8. The R², MBE, and RMSE of the H were 0.61, 0.90 W·m⁻² and 50.99 W·m⁻², respectively, and the
corresponding terms for the LE were 0.82, -20.54 W·m⁻² and 71.24 W·m⁻², respectively. Because
the LE was calculated as a residual term, it was impacted by the R_n, surface G and H. The errors
of all of these variables may contribute to the LE, which complicates the error source of the LE and
is discussed in Sects. 4.3.2 and 4.4.
Table 8. In situ validation results of heat flux of TSFA

	TS	SFA-H(W	•m ⁻²)	TSFA-LE(W⋅m ⁻²)				
date	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE		
0619	0.39	44.73	66.38	0.69	-44.15	80.60		
0630	0.73	23.71	38.96	0.88	-63.81	77.83		
0708	0.55	32.70	58.72	0.85	-43.02	72.32		
0727	0.90	-34.34	43.59	0.92	26.74	57.60		
0803	0.80	-4.77	18.92	0.78	-4.58	47.86		
0815	0.74	-18.37	38.82	0.93	4.75	35.41		
0822	0.40	31.64	66.21	0.65	-44.44	93.81		
0829	0.79	23.01	38.36	0.79	-50.45	77.99		
0902	0.21	-45.10	74.81	0.54	24.39	69.31		
0913	0.25	-9.64	41.01	0.59	-59.36	82.77		
0914	0.31	-34.11	50.88	0.47	27.99	67.50		

As seen in Fig. 7, most of the H values are small because June, July, August and September 1 2 constitute the growing season when ET greatly cools the air. The differential temperature between 3 the land surface and air is small, leading to a low H. The points with large H values are influenced by uncultivated land. In our study area, bare soil, the Gobi Desert, and desert areas compose the 4 5 uncultivated land. The points in the scatter plot with large H values represent desert, where the H values reach approximately 300 W·m⁻². Some points in the H scatter plot are less than 0 due to 6 7 inversion from the "oasis effect" or irrigation. For example, HiWATER's soil moisture data show 8 that irrigation occurred on August 22, 2012. Irrigation is the main source of water within the oasis 9 and cools the land surface to temperatures below the air temperature. In addition, irrigation leads to 10 errors in LST retrieval because it increases the atmospheric water vapor content, as discussed in 11 Sect. 4.1. The model error is further analyzed in Sect. 4.4.

12 4.3. Comparison between TSFA, TRFA and IPUS

To verify whether the TSFA method can simulate the heterogeneities of the land surface, the TRFA and IPUS methods were compared for estimating the ET. These three methods were evaluated using (1) validation of TRFA and IPUS based on in situ measurements and (2) qualitative analysis based on the spatial distribution and scatter plots of the four energy balance components.

17 4.3.1. Validation of TRFA and IPUS heat fluxes

18 Table 9 provides the footprint in situ validation results of the H and LE calculated using the 19 IPUS and TRFA methods. The R², MBE, and RMSE of the LE between TSFA and TRFA were 0.99, 20 -7.81 W·m⁻² and 16.48 W·m⁻², respectively. And the R², MBE, and RMSE of the LE between TSFA and IPUS were 0.91, -4.10 W·m⁻² and 51.30W·m⁻², respectively. Comparing with validation results 21 22 of TSFA in Table 8, the TSFA method had a better retrieval accuracy than the TRFA method, and 23 TRFA method was better than the IPUS method on all days, because the MBE and RMSE of TSFA 24 decreased and the R^2 of TSFA increased on most days. Table 9 shows that the improvement in the 25 accuracy that resulted from temperature resampling (TRFA) when comparing with the IPUS method 26 was relatively higher than the improvement observed from temperature sharpening (TSFA) when 27 comparing with the TRFA method. Compared with the IPUS method, the TRFA results were similar 28 to the TSFA results since the sub-pixel landscapes and sub-pixel variations of most variables were 29 considered. Thus, TRFA could effectively decrease the scale error that resulted from heterogeneity

because the VNIR data of satellite were fully used. However, the performance of the TRFA method 1

2 is unstable. For example, on August 3 and August 29, the TRFA results were slightly worse than the

3 IPUS results, and the TSFA results were obviously better. This difference occurred because the dif-

- 4 ferent sub-pixel landscape temperatures were treated as equal to the values estimated at the 300-m
- 5 resolution. Thus, when the 300-m-resolution LST has large retrieving errors, the turbulent heat flux
- 6 retrieving error may be amplified by the sub-pixel landscapes. 7

	IPUS-H(W·m ⁻²)				US-LE (W	/•m⁻²)	TR	RFA-H (W	∕·m ⁻²)	TR	FA-LE (V	V •m⁻²)
date	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE
0619	0.32	48.53	71.70	0.66	-47.68	86.02	0.39	52.28	70.98	0.65	-46.71	85.93
0630	0.50	41.45	67.30	0.80	-81.75	102.33	0.69	42.64	60.85	0.86	-78.50	93.98
0708	0.34	44.17	77.45	0.63	-66.75	118.63	0.44	54.20	76.00	0.82	-63.82	89.11
0727	0.81	-33.14	50.01	0.83	25.61	74.26	0.84	-23.53	41.76	0.86	14.82	65.21
0803	0.84	-5.23	33.50	0.74	-3.98	60.49	0.80	7.76	37.51	0.76	-18.23	62.71
0815	0.64	-23.28	47.89	0.85	10.32	54.98	0.70	-14.77	39.99	0.89	0.59	45.22
0822	0.31	41.50	74.81	0.61	-53.60	102.12	0.40	40.63	69.94	0.65	-54.17	98.97
0829	0.72	27.15	44.16	0.76	-54.76	83.20	0.75	30.79	44.97	0.77	-59.43	86.22
0902	0.28	-52.44	83.25	0.51	32.89	76.48	0.21	-45.77	75.84	0.52	24.37	71.69
0913	0.08	-11.45	57.50	0.61	-57.38	81.83	0.06	-11.89	49.63	0.54	-57.78	84.58
0914	0.12	-36.52	67.38	0.28	19.46	89.30	0.03	-34.34	64.85	0.38	25.41	75.96

Table 9. In situ validation results of turbulent heat fluxes of IPUS and TRFA

8

Surface landscape inhomogeneity can be classified using two conditions: nonlinear vegetation 9 density variations between sub-pixels (e.g., different types of vegetation mixed with each other or 10 with bare soil) and coarse pixels containing different landscapes (e.g., vegetation or bare soil mixed with buildings or water). And landscapes variation always corresponding to inhomogeneity of sur-11 12 face variable. To evaluate the effects of TSFA, stations with a typical severe heterogeneous surface, 13 such as EC4, a weak heterogeneous surface, such as EC11 and a typical pixel (called "TP" hereafter) 14 at the boundary of the oasis and bare soil (sample 62, line 102 in the image of study area), and a 15 uniform surface, such as EC15, were selected to analyze the temperature sharpening results.

16 EC4 is used as an example because its land cover and sub-pixel variation of temperature were 17 complicated. Table 11 compares the turbulent heat fluxes calculated using the IPUS, TRFA and TSFA methods. Significant differences were observed between the TSFA and IPUS results and be-18 19 tween the TRFA and IPUS results due to the heterogeneity of the surface. The LE calculated using the TSFA method was more consistent with in situ measurements than the LE calculated using the 20 21 IPUS method because the MBE and RMSE decreased greatly, the R² increased, and the accuracy 22 was improved by approximately 40 W·m⁻². However, the LE calculated by using the TRFA was 23 more accurate than the LE calculated by using the TSFA, as discussed below.

24 The H calculated by using the TSFA method was more accurate than the H calculated by using 25 the TRFA and IPUS methods. The accuracy of the results from the TRFA method was relatively close to the accuracy of the results from the TSFA method because the TRFA method also considers 26 27 the effects of the heterogeneity of landscapes. In addition, the H values obtained from the TRFA 28 method were always greater than those obtained from the TSFA method. Because the TSFA turbu-29 lent heat flux results are the same as the TRFA turbulent heat flux results for buildings and water 30 bodies in our pixel ET algorithm, so the difference between TSFA and TRFA depends on the veg-31 etation and bare soil. And the 300-m-resolution LST is larger than the LST of the sub-pixels, such

1 as pixels containing vegetation or bare soil, for two reasons: (1) the coarse pixels contain buildings and result in a larger 300-m-resolution LST and (2) the LSTs were underestimated at EC4 (as shown 2 3 in Table 3), which would underestimate the value of $\Delta \hat{T}_{300}$ in Eq.(3) and, consequently, the sharp-4 ening temperature at 30 m and H. Because the LE was calculated as a residual item in the energy 5 balance equation, the errors of the other three energy balance components would accumulate in the 6 LE. At EC4, the R_n was overestimated by approximately 80 W·m⁻², but the scale effect of R_n was 7 not obvious, as discussed in Sect. 4.3.1, and the G was overestimated by approximately 20 W·m⁻². 8 These results would lead to low accuracy of the available energy and overestimate the error by 60 9 W·m⁻². As TRFA overestimates H, the underestimation of H in TSFA would result in larger overestimation of LE than TRFA. Consequently, the LE calculated by using the TSFA method is less 10 11 accurate than the LE calculated by using the TRFA method.

12

Table 10. Comparison of the turbulent heat flux results at EC4

	EC4		H(W	·m ⁻²)		$LE(W \cdot m^{-2})$					
	Date	EC IPUS TR		TRFA	TSFA	EC	IPUS	TRFA	TSFA		
	0619	150.65	105.86	154.71	142.13	278.55	402.60	344.05	357.79		
	0630	138.32	99.91	153.53	126.88	341.98	419.83	358.12	386.07		
	0708	117.04	63.47	131.79	112.16	361.16	502.60	424.85	444.01		
	0727	136.41	4.87	85.99	72.33	306.53	543.48	452.01	467.96		
	0803	68.97	36.51	111.73	74.76	389.63	498.21	414.67	454.23		
	0815	104.60	12.69	88.26	82.56	357.34	522.31	436.43	441.95		
	0822	125.34	85.93	120.68	93.18	318.08	415.15	370.76	400.99		
	0829	82.93	73.06	103.84	74.76	317.68	362.04	322.77	355.16		
	0902	162.05	93.74	144.49	132.60	280.41	375.42	315.16	326.29		
	0913	119.42	151.44	157.07	130.85	263.18	234.93	222.62	249.59		
	0914	110.02	88.24	128.37	99.33	262.33	333.82	285.04	314.91		
units: W	∕•m ⁻²										

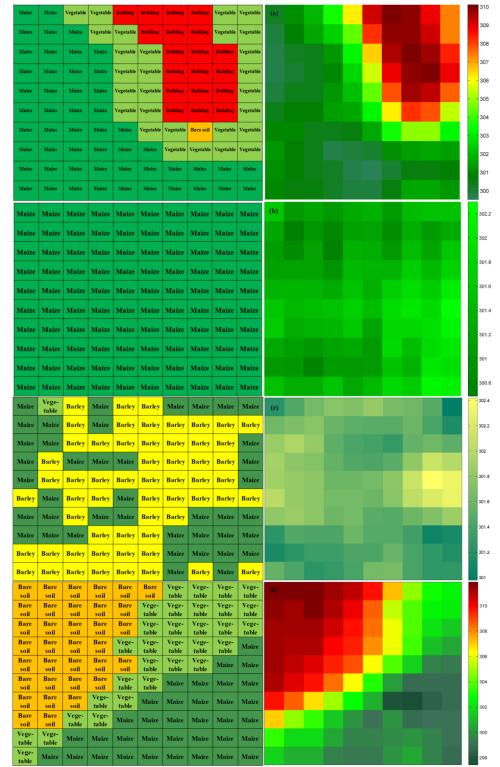
13

	IPUS			TRFA		TSFA		
\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE
0.11	-44.65	61.73	0.25	5.88	26.33	0.51	-16.93	26.54
0.49	99.21	119.55	0.56	42.69	62.40	0.60	63.92	76.78
	0.11	R ² MBE 0.11 -44.65	R ² MBE RMSE 0.11 -44.65 61.73	R ² MBE RMSE R ² 0.11 -44.65 61.73 0.25	R ² MBE RMSE R ² MBE 0.11 -44.65 61.73 0.25 5.88	R ² MBE RMSE R ² MBE RMSE 0.11 -44.65 61.73 0.25 5.88 26.33	R ² MBE RMSE R ² MBE RMSE R ² 0.11 -44.65 61.73 0.25 5.88 26.33 0.51	IPUS TRFA TSFA R ² MBE RMSE R ² MBE RMSE R ² MBE 0.11 -44.65 61.73 0.25 5.88 26.33 0.51 -16.93 0.49 99.21 119.55 0.56 42.69 62.40 0.60 63.92

14

Fig. 8 shows that the classes and temperatures of 10×10 sub-pixels at 30 m correspond to the 15 pixels with a resolution of 300 m at the EC tower. In the IPUS upscaling scheme, the 300-m pixels included buildings and maize and vegetable crops at the 30-m resolution and were identified as 16 17 maize. The canopy height gap between maize and vegetables was large during our study period, 18 resulting in the overestimation of the canopy height. For more details see the sensitivity and error 19 analysis in Sect. 4.4. However, because buildings corresponded with $H = 0.6R_n$ in this paper, ig-20 noring the contributions of buildings would result in the underestimation of H. Fig. 8(a) shows the 21 temperature-sharpening results for the EC4 pixel on August 29. The temperature achieved at a res-22 olution of 300 m was 303.49 K. Compared with the in situ measurement of 313.24 K, the tempera-23 ture at a resolution of 300 m was underestimated. Even when substituting the in situ temperature 24 into the ET model, the value of H reached 399.60 W·m⁻² and the LE became 0 W·m⁻². When substi-25 tuting the in situ temperature in the TRFA method, H was 396.49 W·m⁻² and LE was 18.7 W·m⁻², 26 indicating that the LE was underestimated and the H was overestimated with large errors. After 27 processing by temperature sharpening, the distribution of the temperature at the 30-m resolution

- 1 agreed with the classification. Temperature sharpening improved the description of heterogeneity
- 2 based on the thermodynamic-driven force of the turbulent heat flux. These results apply to the ET
- 3 model with the classification map and high-resolution variables and correspond with more accurate
- 4 sensible heat flux estimations.



5

6 Figure 8. Distribution of classes and temperatures over the extreme heterogeneous surface (a) EC4, homogeneous

The land surface of EC15 was uniform and comprised of pure pixels covered by maize. The

7 surface (b) EC15, weak heterogeneous surface (c) EC11 and (d) a typical pixel on August 29, 2012.

8

1 temperature distribution at the 30-m resolution was as homogeneous as the land cover, and the var-2 iation range of the surface temperature was small (approximately 1.6 K). Table 11 shows the in situ 3 validation results of EC15, for which the overall accuracy is not high due to the low LST retrieval 4 accuracy on July 8, which is discussed in Sect. 4.4.1. For the homogeneous surface, the gaps be-5 tween IPUS, TRFA and TSFA were not large (within 10 W·m⁻²), and the accuracy did not improve 6 (MBE and RMSE did not have obvious variations). Statistically sharpening the temperature may 7 increase the uncertainty of the model results for a homogeneous surface; however, this influence 8 could be omitted. 9 Table 11. Comparison of the turbulent heat fluxes results at EC15

		Table	in comp		ulent n	in neur nuxes results at EE15					
	EC15		Н (V	V ∙m ⁻²)			L	E (W·	m ⁻²)		
	Date	EC	TRFA	TSF	Ă	EC	IPU	JS '	TRFA	TSFA	
	0619	92.55	106.60	109.25	99.8	31 42	19.47	427.	19 4	419.99	429.98
	0630	42.37	43.99	45.51	44.6	57 55	51.73	527.	12	525.17	526.09
	0708	18.34	217.53	235.48	209.	90 62	20.95	425.	71	397.49	424.86
	0727	27.68	21.22	31.11	24.3	30 59	97.76	589.	58	579.43	586.47
	0803	2.33	33.32	-0.07	0.0	1 59	92.37	565.	20	601.33	601.33
	0815	48.81	32.31	46.28	44.6	52 55	53.74	561.	92	547.48	549.11
	0822	54.59	154.34	151.77	158.	60 47	73.68	408.	.37 4	410.80	405.07
	0829	9.80	94.97	95.01	90.9	91 47	73.54	399.	25	398.52	402.93
	0913	176.96	265.62	209.65	257.	81 30	07.72	165.	40 2	221.68	173.58
	0914	188.34	198.15	197.04	196.	60 27	74.98	275.	07 2	276.05	276.56
units:	W·m ⁻²										
-		IPUS								TSF	A
	Variable	\mathbb{R}^2	MBE	RMSE	R ²	MBE	RN	1SE	\mathbb{R}^2	MBE	RMSE
-	EC15-H	0.40	40.64	74.64	0.33	45.93	3 80).81	0.40	40.36	5 72.88
	EC15-LE	0.74	-52.11	83.48	0.71	-48.80) 82	2.51	0.74	-49.00	81.94

10

11	The weak heterogeneous land surface EC11 contained barley, maize and vegetables in a coarse
12	pixel with a fractional area of 48:41:1 and was classified as barley at the 300-m resolution. The
13	distributions of the classes and temperatures are shown in Fig. 8(c), and the pixel belongs to the first
14	conditions of heterogeneity (nonlinear vegetation density variation between sub-pixels) that are
15	classified in the introduction. Table 12 shows the in situ validation results of EC11, for which the
16	improvements in the accuracies of H and LE by temperature resampling or sharpening were not as
17	obvious as the improvements at EC4, which contained total different landscapes (the other inhomo-
18	geneous scenario in introduction).

19 Theoretically, the LE pixel values from the TSFA and TRFA methods at EC11 should be 20 smaller than the IPUS values in the energy balance system. The height of maize (range $0.3 \sim 2$ m) 21 was usually higher than the height of barley (range $0.9 \sim 1.1$ m) in the study area from June to 22 August. Taller vegetation resulted in greater surface roughness and smaller aerodynamic resistance, 23 which led to larger H values, smaller LE values, and vice versa (e.g., vegetables with a canopy 24 height of 0.2 m). When using the TSFA and TRFA methods, patch landscapes consisting of different 25 crops, such as maize and vegetables, were considered. Thus, the LE was smaller than the IPUS LE. 26 On June 19, the canopy height of maize was 0.74 m, which was lower than the canopy height of 27 barley (1 m) and indicated that the H values resulting from the TRFA and TSFA methods were less 28 than the H resulting from the IPUS method. Because our validation method considered the influence

of source area, the in situ turbulent heat flux validation results included the effects of neighboring
pixels (i.e., on August 3, the turbulent heat flux values of the pixel corresponding with the location
of EC11 was only weighted 37% in the source area).

4 The differences between the TSFA and TRFA methods was small and resulted from the LST 5 differences between the 30-m resolution temperature sharpening results and the LST retrieved at the 6 300-m resolution and were not evident at EC11. For example, on August 29, the temperature range 7 was 1.4 K, as shown in Fig. 8(c). This temperature was even less than the temperature range at EC15 8 because the observation system at EC15 was a superstation with a 40-m tall tower that may cause a 9 large shadow and a large temperature range. Hence the temperature sharpening effect is not obvious 10 after aggregating flux at the 300-m resolution under dense vegetation canopies. However, tempera-11 ture sharpening can still decrease the heterogeneity that results from thermal dynamics.

The excess errors resulted from the relatively low LST accuracy, with R^2 , MBE, and RMSE values of 0.42, 1.59 K and 2.98 K, respectively. On August 29, the temperature at a resolution of 300 m was 301.6 K, and the observed temperature of the ground was 300.20 K. The LST at the 300m resolution was slightly overestimated. When the in situ temperature was substituted into the IPUS algorithm, the value of H decreased to 16.06 W·m⁻² and the LE became 467.43 W·m⁻². When substituting the in situ temperature in the TRFA scheme, the value of H was 22.43 W·m⁻² and the LE was 461.58 W·m⁻², which were more similar to the ground observations.

19

Table 12. Comparison of the turbulent heat flux results at EC11

EC11		H(W	·m ⁻²)		$LE(W \cdot m^{-2})$					
Date	EC	IPUS	TRFA	TSFA	EC	IPUS	TRFA	TSFA		
0619	33.94	173.69	158.12	158.18	531.46	391.60	407.42	407.40		
0630	25.03	3.29	23.12	21.37	635.22	586.37	566.48	568.28		
0708	32.29	68.17	97.16	96.13	601.98	567.73	538.77	539.81		
0727	21.42	-1.17	-1.58	-3.77	587.70	618.80	619.19	621.46		
0803	7.01	24.85	20.34	19.52	614.28	575.03	585.29	586.16		
0815	38.94	12.51	15.52	16.02	567.07	584.31	581.31	580.82		
0822	69.25	73.45	83.11	84.38	516.07	483.23	473.60	472.40		
0829	29.77	48.21	60.9	60.81	473.22	427.92	415.32	415.45		
0902	193.97	154.58	197.01	197.49	306.62	361.96	319.54	319.03		
0913	288.37	168.42	176.4	177.71	160.29	216.53	208.49	207.19		
0914	240.33	268.91	256.29	256.40	199.52	156.00	168.63	168.55		

20 units: W·m⁻²

		IPUS			TRFA		TSFA		
Variable	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE
EC11-H	0.61	-1.07	61.31	0.57	-0.36	63.24	0.67	-0.21	55.50
EC11-LE	0.88	-19.83	63.16	0.89	-18.12	60.02	0.90	-21.29	58.11

Another typical pixel located at the boundary of the bare soil and the oasis with no flux measurements was used to evaluate the correction effects of landscapes and temperature sharpening. The land surface of TP contained maize, vegetables and bare soil at a fraction of 35:31:34. Table 13 shows that when neither the heterogeneity of the landscape nor the LST are considered, the relative error of LE could reach $180 \text{ W}\cdot\text{m}^{-2}$. In addition, if only the LST heterogeneity is not considered, the LE relative error could reach $48 \text{ W}\cdot\text{m}^{-2}$. This result also reveals that the influences of landscape inhomogeneity are greater than the influences of inhomogeneity on the LST in mixed pixels.

Tuble 13: Comparison of the tarbulent near nax results at 1											
		ŀ	H (W·m ⁻²)		Ι	LE (W·m ⁻²	2)				
Date	IP	US	TRFA	TSFA	IPUS	TRFA	TSFA				
0619	18	6.31	149.73	143.98	321.04	358.22	364.79				
0630	38	3.65	191.59	158.79	67.03	259.36	292.89				
0708	49	8.36	240.20	204.18	0.29	259.25	293.41				
0727	27	6.79	136.06	84.01	206.52	347.64	402.23				
0803	21	4.14	75.45	53.72	252.37	392.08	416.41				
0815	21	4.14	98.24	72.05	252.37	368.64	393.68				
0822	43	6.48	369.28	276.70	0.00	67.79	162.80				
0829	23	5.29	117.16	67.21	183.62	302.41	356.75				
0902	42	3.61	212.15	180.92	0.00	211.77	241.36				
0913	33	8.00	285.04	216.26	0.00	53.62	122.58				
0914	27	0.44	148.20	100.19	115.19	238.43	286.51				
			IPUS		TRFA						
Varia	ble	\mathbb{R}^2	MBE	RMSE	\mathbb{R}^2	MBE	RMSE				
TP-I	H	0.62	174.47	185.49	0.95	42.28	48.01				
TP-L	E	0.71	-175.91	186.63	0.97	-43.11	49.04				

Table 13. Comparison of the turbulent heat flux results at TP

units: W·m⁻²

3 4.3.2. Comparison of TRFA and IPUS methods

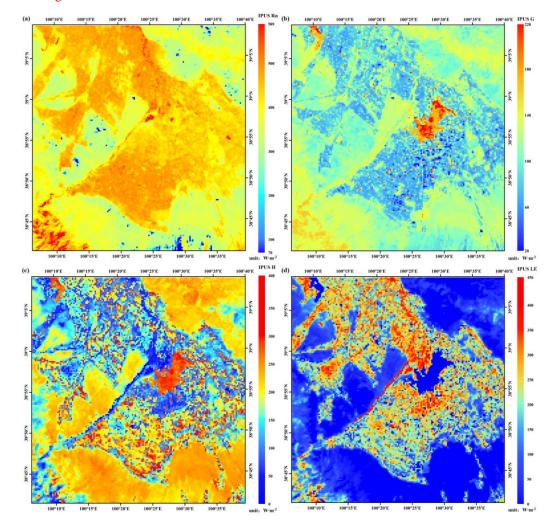
Using September 13 as an example, the spatial distributions of the four components of the
energy balance calculated by IPUS and TRFA are shown in Fig. 9 and Fig. 10, respectively. TSFA
minus IPUS and TSFA minus TRFA, which show the spatial distributions of the heterogeneity effect, are shown in Fig. 11. Scatterplots of TSFA versus IPUS and TRFA are shown in Fig. 12.

8 Comparing Fig. 6 with Fig. 9, the spatial distribution of the fluxes greatly changes, except for 9 R_n . The TSFA results are synoptically smoother than the IPUS results because the land types and 10 temperature distributions in mixed pixels that cannot be considered in IPUS appear in TSFA. For 11 example, the boundary between the oasis and uncultivated land becomes a belt of intermediate G, 12 H and LE because mixed pixels include uncultivated land and vegetation. However, mixed pixels 13 are classified as the dominant land use type in the parameterization process of IPUS. This result 14 overlooks the contributions of heat flux from complex land use types and overestimates or underes-15 timates the heat flux by approximately 50 W·m⁻². However, TSFA can integrate the effects of these 16 land areas and reveals the relative actual surface conditions. The results of this analysis vary less 17 dramatically than the results obtained using IPUS, as shown in the figures. The results are similar 18 in the oasis.

19 Based on the overviews presented in Fig. 6 and Fig. 10, the TRFA and TSFA methods are 20 similar. Because the TRFA method considers the sub-pixel landscapes that could be a significant 21 source of error in ET models, the difference between the TSFA and TRFA methods result from the 22 differences between the sharpened and retrieved LST for the sub-pixels at the 300 m resolution. In 23 addition, the bias between the TSFA and TRFA is not as obvious as the bias between the TSFA and 24 IPUS methods, as shown in Fig. 11(c)(d)(e)(f). Furthermore, Fig. 11(f) shows that the LEs calcu-25 lated by using the TSFA method for most oasis areas were slightly greater than the LEs calculated 26 by using the TRFA method, which were approximately 20 W·m⁻².

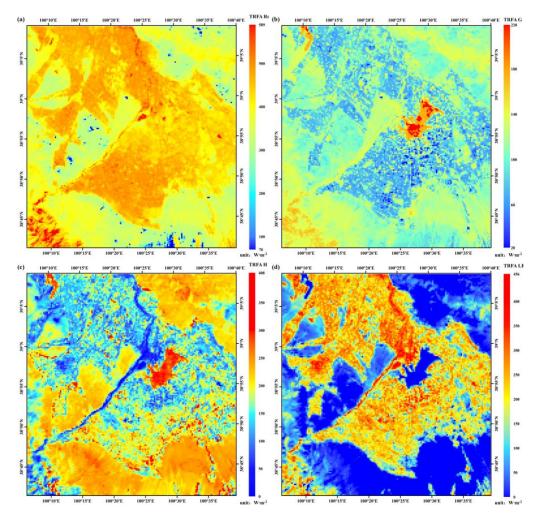
2

1 The quadrangular with a relatively unstable bias shown in Fig. 11(a) is caused by the L_d that 2 was calculated from the MOD05 water vapor product which exists quadrangular even after prepro-3 cessing the instrument malfunction gap. From Fig. 11, the differences of the four energy components 4 of the pure pixels between these three methods are within 5 W·m⁻², and the mixed pixels have dif-5 ferent ranges.



6

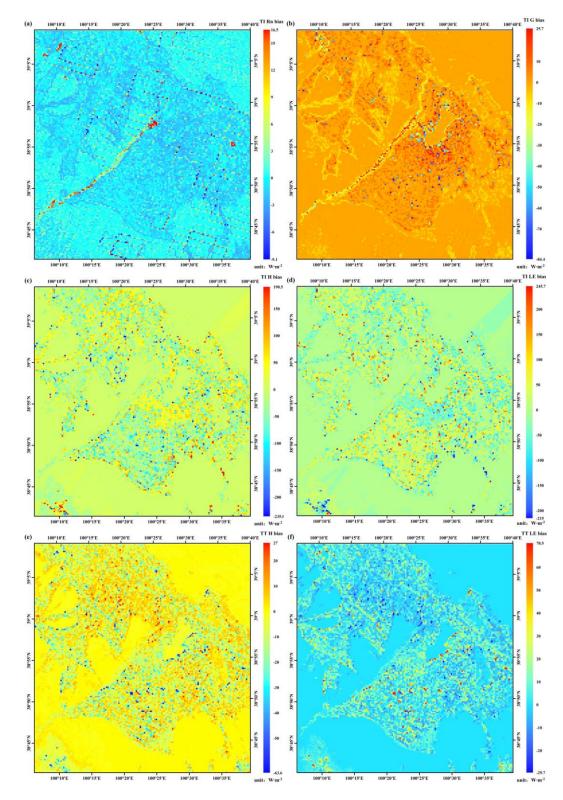
Figure 9. Maps of the four energy components, (a) R_n, (b) G, (c) H and (d) LE, calculated using the IPUS method
on September 13, 2012.



1 2

Figure 10. Maps of the four energy components, (a) R_n, (b) G, (c) H and (d) LE, calculated using the TRFA method

3 on September 13, 2012.



1

2 Figure 11. Maps of the bias of the energy balance components calculated using the TSFA method minus the IPUS

 $3 \qquad \text{method: (a)} \ R_n, (b) \ G, (c) \ H, (d) \ LE, \ TSFA \ minus \ TRFA: (e) \ H \ and (f) \ LE.$

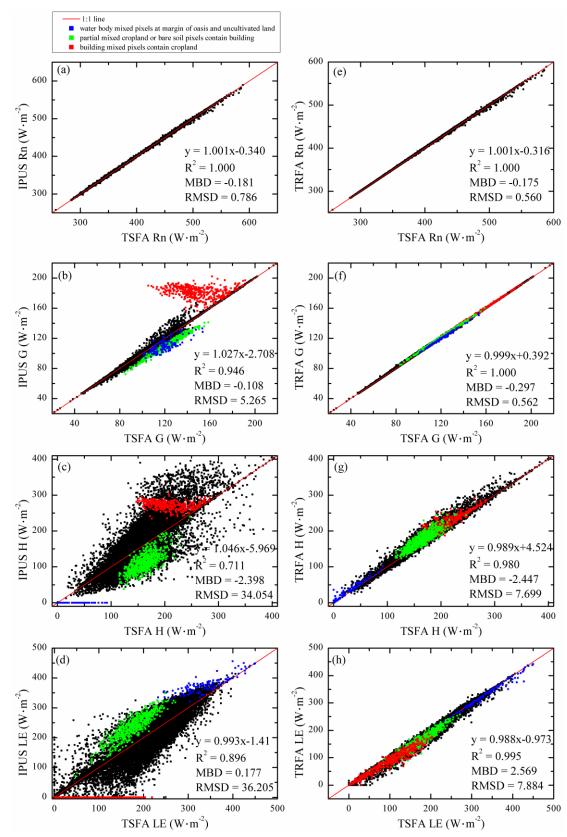




Figure 12. Scatter plots between the TSFA and IPUS results: (a) R_n, (b) G, (c) H and (d) LE; TSFA and TRFA (e)
R_n, (f) G, (g) H and (h) LE. MBD and RMSD are the mean bias deviation and root mean square deviation between
the TSFA and IPUS results, respectively.



Fig. 12 shows the scatter plots between the results from the TSFA method and the other two

1 methods for all four energy balance components in the image. Fig. 11(a)(e) shows that R_n does not 2 vary much between the three methods because the scatter is centralized around the 1:1 line. However, 3 regarding the spatial scale effect, the differences in G, H and LE calculated by using the IPUS 4 and TSFA methods are obvious: the scatter plots are dispersed at the mixed pixels, and the differ-5 ences between the TRFA and TSFA results are relatively smaller. When using the TSFA method, the 6 temperature sharpening results can be divided into results that are higher and lower than the LST 7 retrieved at 300 m. Compared with the LST retrieved at 300 m when using the TRFA method, a 8 higher LST would be counterbalanced by a lower LST when calculating H. Thus, the heterogeneous 9 effect of temperature is neutralized in this case. This observation potentially resulted from the tem-10 perature sharpening algorithms because they tend to overestimate the sub-pixel LST for cooler land-11 scapes and underestimate the sub-pixel LST for warmer areas in the image (Kustas et al., 2003).

However, LE is calculated as a residual; thus, the difference of LE resulted from the G and H. When the 300 m mixed pixels contain various types of land, they may be categorized as one type of land because of the coarse resolution of the IPUS results and because a single temperature value is used to evaluate the thermal dynamic effects when using the TRFA method. Pixels with highly different G, H and LE values are mainly distributed near the mixed pixels, as shown in Fig. 10. An explanation for these deviations is provided below.

18 The parameterization of G and H is based on the land cover type. For example, for buildings, 19 $G = 0.4R_n$ (Kato and Yamaguchi, 2005) (which is usually greater than the G of vegetation and bare 20 soil deduced from Eq.(9)) and H = 0.6R_n, and for water, G = 0.226R_n and LE = R_n - G. From 21 the land cover map shown in Fig. 4, four major classes exist in the study area, buildings with a high 22 H, uncultivated land with a relatively high H, cropland with a relatively low H, and water with 23 H = 0.

24 (1) If a pixel contains cropland and buildings and is categorized as cropland the building area 25 within the pixel is ignored when using the IPUS method. In this case, G and H are underestimated 26 and LE is overestimated. In addition, after considering the landscapes by using the TRFA method, 27 the LE is underestimated and H is overestimated because the pixels contain buildings that are still 28 reflected indistinctly by LST at 300 m because the detailed temperature heterogeneity cannot be 29 represented by the TRFA method. These points are shown in green in Fig. 11. However, if the pixel 30 is categorized as built-up, the building area within a pixel is exaggerated, which causes G and H 31 to be overestimated and LE to be underestimated when using the IPUS method. This situation is 32 similar to the points shown in green for the TRFA results and is shown by red points in Fig. 11.

(2) At the margin of the oasis and uncultivated land, the mixed pixels are divided into cropland,
the LE is overestimated, G and H are underestimated in the IPUS method, and vice versa. The
LE is also overestimated in the pixels containing water and other types of land cover (generally
bare soil in our study area). These pixels are categorized as water and are shown as blue points in
Fig. 11. Some of the blue LE points calculated by using the TSFA method are slightly smaller than
those calculated by using the TRFA method for pixels containing vegetation, and the temperature
of vegetation is lower than the temperature of water bodies at noon in our study area.

40 (3) In mixed pixels that contain various crops, such as maize and vegetables, the LE is under-41 estimated if the area of maize within the pixel is overestimated because the canopy height of the 42 maize would be taller than that of vegetables, which would result in the overestimation of H when 43 using the IPUS and TRFA methods. In addition, G depends on the FVC of the crops when using 44 the IPUS method, and is nearly the same as the values of G obtained when using the TRFA and 1 TSFA methods because it depends on R_n .

2 At the study area scale, we compared TRFA and IPUS to quantify the ability of the TSFA 3 method to simulate the heterogeneities of the land surface on September 13 (see Table 14). For pure pixels, the LE biases among the IPUS, TRFA and TSFA methods were small. In mixed pixels, the 4 5 LE bias between the TSFA and IPUS methods varied from 35.36 to 65.66 W·m⁻², and the bias be-6 tween the TSFA and TRFA methods varied from 4.41 to 22.53 W·m⁻². More class types in mixed 7 pixels correspond to larger biases. Table 15 shows the bias of the mixed pixels that contain buildings 8 and bare soil between the three methods. For mixed pixels with buildings, the IPUS and TRFA 9 methods usually underestimated the LE, with a large bias compared with the TSFA method. For 10 mixed pixels without buildings and bare soil, the bias between TRFA (or IPUS) and TSFA was 11 relatively small, which indicates that the landscape and temperature inhomogeneity are accounted 12 for by the TSFA method. The aforementioned analyses demonstrate that the TSFA method can con-13 sider the heterogeneous effects of mixed pixels.

14

19

Table 14. Comparison of the latent heat flux in pixels containing different numbers of class types

Number of class	IPUS (W·m ⁻²)			Т	Pixel		
types in pixels	R ²	MBD	RMSD	R ²	MBD	RMSD	number
1	1.00	0.21	0.21	1.00	0.05	0.61	11,398
2	0.85	-7.18	35.36	1.00	-0.35	4.41	8212
3	0.66	-2.32	52.55	0.98	-7.33	12.56	4762
4	0.49	1.88	65.66	0.96	-11.56	16.55	2824
5	0.98	-30.92	62.69	0.96	-16.90	22.53	4

15 Notes: Number of class types in mixed pixels means the number of classification types that were contained in

16 the pixels. For example, 1 represents the pure pixels, 2 represents mixed pixels containing two land use types, etc.

17 MBD and RMSD are the mean bias deviation and root mean square deviation, respectively, between the TSFA

18 results and the TRFA and IPUS results.

Turner of university in the	IPUS (W·m ⁻²)			TRFA (W⋅m ⁻²)			Pixel
Types of mixed pixels	R ²	MBD	RMSD	R ²	MBD	RMSD	number
mixed pixels contain buildings	0.58	-1.02	61.94	0.97	-9.64	14.66	4918
mixed pixels do not contain buildings	0.81	-5.49	39.21	0.99	-2.12	7.60	10,884
mixed pixels contain bare soil	0.73	-1.52	49.04	0.98	-5.96	11.86	9049
mixed pixels do not contain bare soil	0.65	-7.55	45.28	0.98	-2.46	7.83	6753

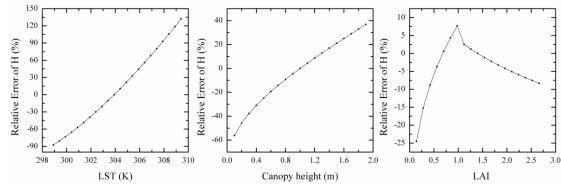
Table 15. Comparison of the latent heat fluxes of typical mixed pixels

Considering the landscapes and inhomogeneous distribution of LST, the TSFA method ensures that none of the end members (30 m pixel) are ignored or exaggerated. Thus, the distribution of LE calculated using the TSFA method is smoother and more rational than the distributions of LE calculated using the other methods. At the regional scale, the TSFA method describes the heterogeneity of the land surface more precisely. And how much the estimation accuracy can be improved is discussed in the following sections.

26 **4.4. Error analysis**

Since LE is calculated as a residual term in the energy balance equations, the sensitivity of H was analyzed at first. Land surface variables (including LST, LAI, canopy height, and FVC) and meteorological variables (including wind speed, air temperature, air pressure and relative humidity) are needed to estimate H in this paper. To locate the error source when retrieving H, a sensitivity

- analysis was performed by adding errors at each 10% step (except LST). Fig. 13 presents the sensi-1
- 2 tivity analysis results: LST = 303.9 K (ranging from 298.4~309.4 K with a step size of 0.5 K),
- 3 LAI=1.4 (ranging 0.14~2.66 with a step size of 0.14), canopy height equals 1 m (ranging 0.1~1.9 m
- 4 with a step size of 0.1 m), FVC=0.5, wind speed u=2.48 m·s⁻¹, air temperature Ta=297.9 K, air
- 5 pressure = 97.2 kPa, and RH=40.29%. In addition, the land use type is maize, and the reference H
- 6 is 230.2 W·m⁻².



7 8

Figure 13. Sensitivity analysis of the surface variables for sensible heat flux

9 The air pressure is stable over a short period and has little effect on the ET results. Although 10 "excess resistance" was calculated from the friction velocity, the meteorological data were provided 11 by ground observations; thus, the meteorological data are relatively accurate. As shown in Fig. 13, 12 LAI, canopy height and LST are sensitive variables.

13 The parameterization of the momentum roughness length indicates that LAI is sensitive to H, with decreasing sensitivity when the LAI is greater than 1. When the LAI is less than 1, the momen-14 15 tum roughness length increases as the LAI increases and the H and turbulent exchange are enhanced. 16 However, when the LAI is greater than 1, the plant canopy could be regarded as a continuum that is 17 not sensitive to H. Because our study area is dominated by agriculture and the study period was 18 from July to September, the crops in the HRB middle stream grew quickly, so the LAI was generally 19 greater than 1. Thus, LST and canopy height are the main sources of error.

20 4.4.1. The error of LST

21 As shown in Fig. 13 using monitoring data, a 1 K LST bias would result in 21% error of H, 22 about 48.3 W·m⁻². However, the sensitivity of the LST is unstable and depends on the strength of 23 the turbulence. The strength of the turbulence determines the mass and energy transport and the 24 resistance of heat transfer, which influences the sensitivity of the LST. A weaker turbulence corre-25 sponds to a weaker LST sensitivity and vice versa.

26 The influence of LST was analyzed based on the sensitivity analysis and LE results. We chose 27 homogeneous stations to analyze the LST error so that other errors could be ignored. These results 28 are shown in Table 16. The LE results obtained from the observed LST are consistent with the in 29 situ observations but have less bias. The LE was overestimated when the LST was underestimated 30 and vice versa. Because the magnitude of LE was greater than H, the relative error of LE was less 31 than the relative error of H. However, 1 K of LST bias would result in an average LE error of 30 32 W·m⁻², which is consistent with the sensitivity analysis of H shown in Fig. 13. Specifically, 1 K of 33 LST bias would result in LE biases of 8.7 W·m⁻² (in desert, SSW) to 84.4 W·m⁻² (in oasis, EC8), 34 which may prove that the sensitivity of LST is unstable. 35

Table 16. Results of the LST error analyses at the homogeneous stations

Station	Date	retrieved LST (K)	observed LST (K)	LST bias (K)	EC-LE (W·m ⁻²)	LE from retrieved LST (W·m ⁻²)	LE from observed LST (W·m ⁻²)	LE relative error (%)	H relative error (%)
EC8	0619	304.92	301.74	3.18	415.89	321.80	399.78	-22.62	68.58
EC7	0630	302.5	299.35	3.15	611.22	453.59	557.97	-25.79	886.08
EC10	0708	303.58	300.5	3.08	617.83	504.44	549.53	-18.35	390.24
EC15	0708	303.55	300.13	3.42	620.95	425.71	603.73	-31.44	450.57
EC7	0727	298.87	300.55	-1.68	577.59	643.56	566.62	11.42	-132.47
SSW	0727	307.86	316.82	-8.96	119.35	238.07	78.43	99.48	-60.36
EC2	0822	299.79	298.05	1.74	501.12	411.43	486.28	-17.90	67.20
EC8	0822	299.58	297.77	1.81	543.56	416.23	467.42	-23.42	88.59
EC10	0822	301.61	298.04	3.57	503.82	398.82	513.67	-20.84	138.61
EC15	0822	300.59	297.69	2.9	473.68	408.37	495.49	-13.79	129.60
EC8	0829	301.54	300.44	1.1	514.31	402.93	428.78	-21.66	63.91
EC15	0829	301.41	299.84	1.57	473.54	399.25	459.66	-15.69	182.34
SSW	0902	304.9	303.42	1.48	226.88	127.96	149.83	-43.60	11.36

1 Notes: "LST bias" is calculated as the retrieved LST minus the observed LST; "EC-LE" is the in situ latent heat flux;

2 "LE relative error" is the relative error between the retrieved and observed LST and is expressed as ((LE from
3 retrieved LST)-(LE from observed LST))/(LE from observed LST)×100%, "H relative error" is calculated in the
4 same way.

5 **4.4.2. The error of canopy height**

6 In this paper, canopy height was obtained from a phenophase and classification map. Thus, the 7 accuracy of the canopy height was mainly dependent on the classification accuracy and plant growth 8 state. Even within the same region, the canopy height of a crop can differ due to differences in 9 seeding times and soil attributes, such as soil moisture and fertilization.

10 The land use at EC17 was orchard. However, in our land classification map, the land use at 11 EC17 was other crops, which includes vegetables and orchards. Thus, it was difficult to set the 12 canopy height. In our study area, most of the other crops were vegetables (canopy height of 0.2 m), 13 and the height of the orchard was approximately 4 m; thus, a value of 0.2 m would overestimate the 14 LE. The LE results with incorrect canopy heights and correct orchard canopy heights at EC17 are 15 shown in Table 17. The days of large LST bias were removed, and the bias between the model and 16 ground observations decreased. The excess errors were caused by errors in the LST and other land 17 use types, such as buildings and maize in the mixed pixels.

18

 Table 17. Results of the canopy height error analyses at EC17

			•	
Data	$\mathbf{EC} \mathbf{IE} (\mathbf{W} = \mathbf{r}^2)$	LE from incorrect	LE from correct	LE relative
Date	EC-LE ($W \cdot m^{-2}$)	canopy height (W·m ⁻²)	canopy height (W·m ⁻²)	error (%)
20120815	499.62	562.06	521.83	7.71
20120822	366.27	519.01	396.54	30.88
20120902	377.96	471.68	336.52	40.16
20120914	465.38	352.78	258.07	36.70

19 Except for the error source discussed before, the following sources of error were unavoidable:

20 (1) Although the remotely sensed turbulent heat flux is instantaneous, the EC data are averaged

1 over time. Thus, the time scales do not match in the validation.

(2) The calibration coefficient of HJ-1B satellite's CCD and IRS drifts because of the aging
 instruments.

4 (3) Geometric correction causes half-pixel bias equal to or less than the deviation of the artifi-5 cially subjective interpretation.

A one-source model and simplified parameterization schemes for determining surface roughness lengths and heat transfer coefficients were used in this paper. The one-source model combines soil evaporation and plant transpiration and assumes that SPAC is a one-source continuum for calculating ET. This assumption is reasonable when the surface is densely covered by vegetation but relies on the accuracy of the difference between the LST and air temperature, as previously mentioned. When a one-source model is applied to an area covered by sparse vegetation, such a semiarid or arid areas, this assumption is irrational.

13 5. Discussion

As mentioned in the results and analysis, the TSFA method describes the surface heterogeneity more clearly than the IPUS and TRFA methods. The IPUS method aggregates the land surface parameters achieved by CCDs from 30 m to 300 m, which results in the loss of surface information and leads to the scale effect. Although the TRFA method uses VNIR information and partially decreases the heterogeneity caused by landscape and VNIR variables, it treats the pivotal variable LST as homogeneous within mixed pixels, which results in considerable error. In summary, the superiority of the TSFA method is described as follows:

(1) The temperature sharpening algorithm in TSFA uses the NDVI at 30 m to monitor the LST
at 30 m and is capable of decreasing the influences of the heterogeneity of the LST, which agrees
with previous research results (Kustas et al., 2003; Bayala and Rivas, 2014; Mukherjee et al., 2014).
As analyzed in Sect. 4.3, the ignorance of the heterogeneity of LST in mixed pixels is irrational and
causes errors when estimating ET.

(2) In the one-source energy balance model, different landscapes used different parameterization schemes. In the IPUS method, a single land cover type is assigned to a mixed pixel, which
results in a large error. However, the TSFA method is used to calculate the surface flux at 30 m and
is aggregated to 300 m using the area-weighting method, which considers all of the sub-pixel landscapes and improves the retrieval accuracy.

31 Some problems exist in the temperature sharpening algorithms. The temperature-downscaling 32 method used in this paper caused boxy anomalies in parts of the sharpened-temperature field because of the constant residual term, $\Delta \hat{T}_{300}$, in Eq. (3) within large pixels. This situation also oc-33 34 curred in the temperature sharpening algorithm proposed by Agam et al. (2007). In addition, our 35 temperature sharpening algorithm tends to overestimate the sub-pixel LST for cooler landscapes 36 and underestimate the sub-pixel LST for warmer areas (Kustas et al., 2003). This inaccurate estima-37 tion causes errors that are difficult to evaluate when estimating turbulent heat flux. For example, the 38 small turbulent heat flux bias between TSFA and TRFA was caused by the counterbalanced effect 39 as analyzed in Sect. 4.3.1. The evaluation of more temperature sharpening algorithms under heter-40 ogeneous surfaces with real datasets when applied in ET models would be helpful (Ha et al., 2011). 41 Our surface variable retrieval methods were validated against other areas considered in remote

42 sensing measurement campaigns. For example, the albedo algorithm was previously applied to re-

trieve Global Land Surface Satellite (GLASS) Products (Liang et al., 2014), the LST retrieval algorithm was validated in the Haihe River Basin in northern China (Li et al., 2011), and the soil heat
flux correction algorithm was validated in the GAME-Tibet campaign (Yang and Wang, 2008).
Since the surface of the Heihe River Basin is extreme heterogeneous, additional comparisons of our
algorithm in other areas of research would be better.

In addition, to correct the discrepancy between remotely sensed radiative surface temperature
and aerodynamic temperature at the source of heat transport, a brief and well-performed parameterization scheme (under uniformly flat plant surface) of "excess" resistance was used to calculate the
aerodynamic resistance of heat transfer (Jiao et al., 2014). Since the objects of our study are mixed
pixels, more parameterization methods should be compared to select the optimum method.

11 Because of the sensitive variables of the one-source energy balance model used in this paper, 12 the accuracy of the LST and canopy height greatly influenced the turbulent heat flux. HJ-1B IRS is 13 a single-thermal channel, the single-channel LST-retrieving algorithm may be unstable under wet 14 atmospheric conditions (water vapor contents higher than 3 g/cm^2) (H. Li et al., 2010), which may 15 create a bottleneck for ET estimations by HJ-1B. The canopy height is a priori knowledge based on 16 phenophase classifications and would influence the accuracy of the surface roughness, the length of 17 a heterogeneous surface or the seasonal transition. Multi-source remote sensing data could be used 18 to improve the accuracy of calibrations and land surface variable estimations. Active microwave 19 and LiDAR data (Colin and Faivre, 2010) could be used to obtain the canopy height, which would 20 decrease the dependence on the accuracy of the classification.

21 6. Conclusion

22 We studied the effects of surface heterogeneity in ET estimation by the IPUS, TRFA and TSFA 23 methods over heterogeneous surface based on spatial resolution characteristic of different satellites, 24 and applied them to HJ-1B satellite data based on operational satellites' instrumental characteristics. 25 Compared with the IPUS and TRFA methods, the TSFA method is more consistent with in situ 26 measurements. If ET estimating algorithm does not consider surface heterogeneity at all (i.e. IPUS), 27 it would cause significant error (i.e. 186 W·m⁻²) of heat fluxes. If ET estimating algorithm does not 28 consider heterogeneity of LST only (i.e. TRFA), it would cause non-negligible error (i.e. 49 W·m⁻²) 29 in heat fluxes calculating. The TSFA method reduces the uncertainties produced by surface land-30 scapes and LST inhomogeneity. As a sensitive variable of the ET model, canopy height is mainly 31 determined by classification, and the application of classification at a 30-m resolution can improve 32 the accuracy of the canopy height. As another sensitive variable, the sharpened surface temperature 33 at a resolution of 30 m decreases the thermodynamic uncertainty caused by land surface heteroge-34 neities. The TSFA method can capture the heterogeneities of the land surface and integrate the ef-35 fects of landscapes in mixed pixels that are neglected at coarse spatial resolutions.

HJ-1B satellite data are advantageous because of their high spatiotemporal resolution and free
 access. Because the satellites are still in operation, long-term data have promising applications for
 monitoring energy budgets.

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5 Appendix

Notation		Application (for calculating)
6S radiation	Second Simulation of a Satellite Signal in the Solar Spectrum	
transfer mode	radiation transfer mode	Albedo, S _d
α	Surface broadband albedo	S _d , R _n
ABT	At-nadir brightness temperature (K)	L_d
AMS	Automatic meteorological station	
AOD	Aerosol optical depth	S _d
BRDF	Bidirectional reflectance distribution function	α
CCD	Charge-coupled device	
CV	Coefficient of variation	Sharpened LST
EC	Eddy covariance	
FVC	Fractional vegetation coverage	LSE, G, LAI
G	Soil heat flux (W·m ⁻²)	
$G(\theta)$	G function, Foliage angle distribution	LAI
Н	Sensible heat flux (W·m ⁻²)	
HRB	The Heihe River Basin	
IPUS	Input parameter upscaling scheme	
IRS	Infrared scanner	
L _d	Downward atmospheric longwave radiation (W·m ⁻²)	R _n
LSE/E	Land surface emissivity	LST
ϵ_v/ϵ_g	The vegetation/ground emissivity	
LST/T _{rad}	Land surface temperature/Surface radiation temperature (K)	Н
MBE/MBD	Mean bias error (deviation)	
NCEP	National Centers for Environmental Prediction	LST
NDVI/NDVI ₃₀	Normalized difference vegetation index	FVC, Sharpened LST
NDVI300	300-m NDVI aggregated from NDVI	Sharpened LST
NDVI _s /NDVI _v	Normalized difference vegetation index of bare soil/fully cov- ered vegetation	FVC
$P(\theta)$	Angular distribution of the canopy gap fraction	LAI
r _a	Aerodynamic resistance (s·m ⁻¹)	Н
r _{ex}	"Excess" resistance (s·m ⁻¹)	heat transfer resistance
R _n	Net radiation (W·m ⁻²)	
RMSE/RMSD	Root mean square error (deviation)	
S _d	Downward shortwave radiation (W·m ⁻²)	R _n
SPAC	The soil-plant-atmosphere continuum	
SZA	Solar zenith angle	S _d
Ta	Air temperature (K)	Н

	Aerodynamic surface temperature obtained by extrapolating the	Н
T _{aero}	logarithmic air-temperature profile to the roughness length for	
	heat transport (K)	
TOA	Top of the atmosphere	
TOMS	Total ozone mapping spectrometer	S _d
TRFA	Temperature resampling and flux aggregation	
TSFA	Temperature sharpening and flux aggregation	
ULR	Upward longwave radiation (W·m ⁻²)	R _n
USR	Upward shortwave radiation (W·m ⁻²)	R _n
VNIR	Visible/near-infrared	
VZA/θ	View zenith angle	L _d , LAI

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