

1 Coupling a groundwater model with a land surface model to 2 improve water and energy cycle simulation

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12 **Abstract**

13 Water and energy cycles interact, making these two processes closely related. Land surface models
14 (LSMs) can describe the water and energy cycles on the land surface, but their description of the
15 subsurface water processes is oversimplified, and lateral groundwater flow is ignored. Groundwater
16 models (GWMs) describe the dynamic movement of the subsurface water well, but they cannot depict the
17 physical mechanisms of the evapotranspiration (ET) process in detail. In this study, a coupled model of
18 groundwater flow with a simple biosphere (GWSiB) is developed based on the full coupling of a typical
19 land surface model (SiB2) and a three-dimensional variably saturated groundwater model (AquiferFlow).
20 In this coupled model, the infiltration, ET and energy transfer are simulated by SiB2 using the soil
21 moisture results from the groundwater flow model. The infiltration and ET results are applied iteratively to
22 drive the groundwater flow model. After the coupled model is built, a sensitivity test is first performed, and

1 the effect of the groundwater depth and the hydraulic conductivity parameters on the ET are analyzed. The
2 coupled model is then validated using measurements from two stations located in shallow and deep
3 groundwater depth zones. Finally, the coupled model is applied to data from the middle reach of the Heihe River
4 basin in the northwest of China to test the regional simulation capabilities of the model.

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1 Introduction

Water movement and energy transfer in the soil-atmosphere-vegetation continuum are the main processes on the land surface, and the two processes strongly interact. Land surface models (LSMs) are often used to model these physical processes. However, almost all LSMs are one-dimensional vertical models because the initial aim of these models was to provide a land surface condition for atmospheric models, such as general circulation models (GCMs) and regional climate models. Therefore, these models generally cannot simulate subsurface lateral water movement. However, many studies have indicated that lateral water movement can significantly affect land surface water and energy processes (Holt et al., 2006; Maxwell et al., 2007; Kollet and Maxwell, 2008; Maxwell et al., 2011; Soylyu et al., 2011).

Many groundwater models (GWMs), such as the MODFLOW-HYDRUS (Twarakavi et al., 2008) and ParFlow (Kollet and Maxwell, 2006) models, are based on hydrodynamic mechanisms. These models describe the physical mechanism of the three-dimensional subsurface water movement in both saturated and unsaturated zones and include water balance processes, but they usually do not explicitly describe the physical mechanism of evapotranspiration (ET) processes. ET is an integration process that includes water, energy and biological processes. The latter two processes are usually not included in GWMs. In MODFLOW (McDonald and Harbaugh, 1988), for example, ET is calculated using a linear empirical function of the groundwater table (GWT). Although this approach makes the groundwater modeling system self-closing, it oversimplifies the ET simulation, leading to simulation error.

Based on this comparison of the two types of models, coupling LSMs and GWMs could eliminate their separate disadvantages and make the simulation of water movement in the Earth's surface more accurate on mechanism. In recent years, many studies have been conducted on the coupling of GWMs with LSMs. Gutowski et al. (2002) developed the Coupled Land-Atmosphere Simulation Program (CLASP) to

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1 study the coupled aquifer, land surface and atmospheric hydrological cycle. This model considered the
2 groundwater as a reservoir. York et al. (2002) improved this model in CLASP II by integrating the soil
3 vegetation zone into the USGS groundwater flow model, MODFLOW. Liang et al. (2003) developed a
4 one-dimensional dynamic groundwater parameterization and implemented it in a three-layer variable
5 infiltration capacity (VIC-3L) model to simulate surface and groundwater interaction dynamics for LSMs.
6 Gedney and Cox (2003) coupled the Hadley Centre Atmospheric Climate Model (HadAM3) with the Met
7 Office Surface Exchange Scheme (MOSES), in which the local water table depth was used to estimate the
8 saturated fraction of the soil layers and to improve the runoff and global wetland area simulation. Tian et al.
9 (2006) implemented a subsurface runoff scheme with a variable water table in Community Land Model 2
10 (CLM2). Yeh and Eltahir (2005) incorporated a lumped unconfined aquifer model into the Land Surface
11 Transfer Scheme (LSX) to address the deficiency of the simplified representation of subsurface
12 hydrological processes in current land surface parameterization schemes. In the model, groundwater was
13 modeled as a nonlinear reservoir that received the recharge from the overlying soils and discharged the
14 runoff into streams. Niu et al. (2007) developed a simple groundwater model (SIMGM) by representing
15 groundwater recharge and discharge processes, which were added as a single integration element below the
16 soil of the CLM3 land surface model. Fan et al. (2007) coupled a simple two-dimensional groundwater
17 flow model with the VIC model to estimate the equilibrium water table, which is the result of long-term
18 climatic and geologic effects. Maxwell and Miller (2005) coupled the Common Land Model with a
19 variably saturated GWM (ParFlow) to create a single-column model to improve the groundwater
20 representation in land surface schemes. Kollet and Maxwell (2008) then improved this model and
21 developed an integrated, distributed watershed model based on the coupling of ParFlow and the Common
22 Land Model (PF.CLM). Yuan et al. (2008) coupled a groundwater model with the Biosphere-Atmosphere

1 Transfer Scheme (BATS) and the RegCM3 regional climate model to investigate the local and remote
2 effects of water table dynamics on the regional climate. Maxwell et al. (2011) coupled ParFlow with the
3 Noah LSM, which is a land surface module of the Weather Research and Forecasting (WRF) model, to
4 study the impact of groundwater on weather. These studies have shown that groundwater flow and land
5 surface processes are closely related and that coupled models can simulate complex processes more
6 realistically than uncoupled models.

7 The GWMs used in these coupled models can be classified into two categories: empirical, lumped
8 GWMs (Liang et al., 2003; Gedney and Cox, 2003; Yeh and Eltahir, 2005; Niu et al., 2007) and physically
9 based distributed GWMs (York et al., 2002; Maxwell et al., 2011; Kollet and Maxwell, 2008; Gutowski et
10 al., 2002; Fan et al., 2007). Of the two categories, the lumped GWMs require less data and are more
11 efficient, but they can only provide a groundwater impact factor for the LSMs and cannot truly describe
12 groundwater flow. Although distributed dynamic GWMs increase the complexity of the simulation, they
13 have the advantage that the groundwater flow mechanism is included in the coupled model. Consequently,
14 effects such as the interaction between the groundwater dynamics and the land-surface energy and water
15 processes can be described in the coupled model. Additionally, the water balance can be maintained when a
16 groundwater model is used instead of the groundwater level in the simulation.

17 In this paper, a coupled model of groundwater flow with a simple biosphere (GWSiB) is developed by
18 coupling a three-dimensional variably saturated dynamic GWM (AquiferFlow) (Wang, 2007; Wang et al.,
19 2010) with a typical land surface model, the Simple Biosphere Model version 2 (SiB2) (Sellers et al.,
20 1996b). In this coupled-model system, the coupling mode of physically based distributed GWMs is used in
21 the GWSiB model, and the land surface parameterization scheme and the GWM used are different from
22 other studies. Furthermore, flexible temporal and spatial coupling schemes are used to increase the

1 applicability of the model.

2 The paper is arranged as follows. In Section 2, the models to be coupled are briefly introduced, and
3 the coupling method used in the GWSiB model is described in detail. In Section 3, a sensitivity analysis of
4 the model is performed, and the model is validated using data measured from two sites. The model is then
5 tested in a regional simulation of the middle reach of the Heihe River basin in northwestern China in
6 Section 4. The discussion and conclusions are presented in Section 5.

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7 **2 Model development**

8 The critical aspect of the coupling of the GWM and the LSM is the soil moisture movement in the
9 vadose zone, which is simulated in both models. If the vadose zone water movement in the two models can
10 be linked and integrated, a water cycle process can be completely simulated. In our study, a GWM called
11 AquiferFlow that can simulate water movement in saturated and unsaturated zones (Wang, 2007; Wang et
12 al., 2010) and an LSM model, SiB2, which is used to simulate the water and energy movement above the
13 ground surface and the soil moisture movement in up to three layers of the subsurface, were chosen as the
14 two models to be coupled. The two models are coupled by replacing the three-layer soil moisture
15 simulation in the SiB2 code by the unsaturated zone water movement simulation of AquiferFlow. The
16 principle of these two models and their coupling scheme are presented in detail in the following.

17 **2.1 AquiferFlow**

18 AquiferFlow (Wang, 2007; Wang et al., 2010) is a typical numerical GWM in which rectangular grid
19 cells are used to divide the simulation domain and the finite difference method (FDM) is used to solve
20 groundwater movement equations in saturated and unsaturated zones. The main feature of AquiferFlow is
21 that the conceptual model is similar to traditional saturated GWMs, but the Richards equation is fully
22 incorporated to handle unsaturated flow, as follows:

$$\frac{\partial}{\partial x} \left(K_{xx} K_r \frac{\partial H}{\partial x} \right) + \frac{\partial}{\partial y} \left(K_{yy} K_r \frac{\partial H}{\partial y} \right) + \frac{\partial}{\partial z} \left(K_{zz} K_r \frac{\partial H}{\partial z} \right) + \varepsilon = S_s \frac{\partial H}{\partial t} \quad (1)$$

where x , y and z are coordinates (m) in which z is oriented positively upward, H is the hydraulic head (m)
 $H = Z + \psi$, where ψ is the water suction potential of the unsaturated soil (m), and Z is the relative
 high hydraulic head according to the the z -coordinate (m); K_{xx} , K_{yy} and K_{zz} are the saturated
 hydraulic conductivity (m s^{-1}) in the x , y and z directions, respectively; K_r is the relative hydraulic
 conductivity, defined as the unsaturated conductivity divided by the saturated conductivity; S_s is the
 extended specific storage and can be used in the saturated and unsaturated zones (m^{-1}); ε is the source
 and sink term (s^{-1}); and t is the time (s). Compared with the traditional governing equation for saturated
 groundwater, Equation (1) introduces new parameters, namely, the relative hydraulic conductivity (K_r)
 and the extension of the specific storage (S_s) for the calculation of the water movement in an unsaturated
 zone. The relative hydraulic conductivity is a function of the pressure head. In AquiferFlow, Gardner and
 Fireman's method (1958) is used to relate K_r to the soil moisture potential ψ :

$$K_r = \exp[-C_k(\psi - \psi_s)], \quad \psi < \psi_s; \quad K_r = 1, \quad \psi \geq \psi_s \quad (2)$$

where C_k is the attenuation coefficient of permeability (m^{-1}), and ψ_s is the saturation moisture potential
 (m). The specific storage is defined using different forms in the saturated ($\psi \geq \psi_s$) and unsaturated
 ($\psi < \psi_s$) conditions. The specific storage depends on the compressibility of the porous media and the
 water in the saturated zone and is a function of the soil volumetric water content (θ) ($\text{m}^3 \text{m}^{-3}$) and the soil
 moisture potential (ψ) in the unsaturated zone.

$$S_s = C_s(\psi) = -\frac{d\theta}{d\psi}, \quad \psi < \psi_s \quad (3a)$$

$$S_s = \rho_w g(\alpha + \phi\beta), \quad \psi \geq \psi_s \quad (3b)$$

where C_s is the specific moisture capacity (m^{-1}), ρ_w is the water density (kg m^{-3}), α is the

1 coefficient of soil compressibility ($\text{m s}^2 \text{kg}^{-1}$), β is the coefficient of groundwater compressibility (m s^2
2 kg^{-1}), ϕ is the porosity, and g is the gravitational acceleration (m s^{-2}).

3 The relationship between the soil moisture potential ψ and the moisture content θ in the aquifer
4 media is described by the suction curve, $\theta(\psi)$. In AquiferFlow, the suction curve can be created using the
5 commonly used van Genuchten (1980) equation or a simple exponential equation such as

$$6 \quad S_e = \frac{\theta - \theta_r}{\phi - \theta_r} = \exp[-C_w(\psi - \psi_s)], \quad \psi < \psi_s; \quad S_e = 1, \quad \psi \geq \psi_s \quad (4)$$

7 where S_e is the effective saturation, θ_r is the residual saturation, and C_w is the attenuation coefficient
8 of the soil moisture (m^{-1}), which is an empirical parameter.

9 The equations of AquiferFlow are based on the principles of groundwater dynamics; consequently,
10 AquiferFlow can describe water movement not only in the saturated zone but also in the unsaturated zone
11 (Wang et al., 2010). However, the ET simulation in AquiferFlow, as in most existing GWMs, is treated as a
12 sink term for the groundwater system, and the ET calculation depends only on the soil moisture of the top
13 soil layer and the potential ET of the location. The ET simulation in AquiferFlow is empirical and is unable
14 to represent a complex physical process. In summary, the governing equations of GWMs are derived from
15 water conservation and do not include the simulation of energy and biological processes. The water
16 phase-change process of evaporation and the vegetation root-uptake process of transpiration are usually
17 simplified in the parameterization scheme of GWMs. Therefore, a model that can simulate the energy cycle
18 and the biological processes, such as an LSM, need to be coupled with the GWM to overcome this
19 weakness.

20 **2.2 SiB2**

21 The simple biosphere model (SiB) (Sellers et al., 1986) is a typical land surface model that can be

1 used to calculate the transfer of energy, mass, and momentum between the atmosphere and the vegetated
2 surface of the Earth. Sellers et al. (1996b) produced a new version of the model, SiB2, by improving the
3 hydrological sub-model, increasing the canopy photosynthesis-conductance model and introducing
4 snowmelt process simulation into the SiB model. Since the release of SiB, the model has been verified and
5 applied in many case studies (Vidale and Stockli, 2005; Sen et al., 2000; Sellers et al., 1989; Gao et al.,
6 2004; Colello et al., 1998; Baker et al., 2003; Li and Koike, 2003). The study results show that the model
7 can provide an adequate description of the energy and water processes above the ground surface.

8 The model structure of SiB2 is divided into five layers in the vertical direction. One vegetation layer
9 and one ground layer lie above the ground surface. The three layers below the ground surface represent the
10 surface soil layer, the root layer, and the deep soil layer; the characteristics of these layers are determined
11 according to the soil properties of a study area. Ground vegetation is classified into nine types to represent
12 various global vegetation conditions. The main inputs of the model include meteorological data, soil data,
13 and the morphological, physiological, and biophysical parameters of the vegetation. To explain the model
14 coupling, we only provide a detailed description of the soil moisture movement and evaporation processes;
15 descriptions of the other processes can be found in the relevant literature (Sellers et al., 1989; Sellers et al.,
16 1996b; Sellers et al., 1986; Sellers et al., 1996a).

17 In the SiB2 model, precipitation reaches the ground surface after the canopy interception, and some
18 water infiltrates to the subsurface, limited by the local soil infiltration capacity. If the residual precipitation
19 still exceeds the groundwater storage capacity, runoff is generated. This process can be expressed as

$$20 \quad R_0 = P_g - Q_1 - E_{gi} \quad (5)$$

21 where R_0 is the runoff (m s^{-1}), P_g is the precipitation reaching the ground surface (m s^{-1}), Q_1 is the
22 infiltrated water from the ground surface to the first soil layer (m s^{-1}), and E_{gi} is the evaporation from the

1 water intercepted by the ground surface (m s^{-1}).

2 As the water infiltrates into the soil, the water balance in the three soil layers is defined as

$$3 \frac{\partial W_1}{\partial t} = [Q_1 - Q_{12} - E_{gs}/\rho_w] / \theta_s D_1 \quad (6a)$$

$$4 \frac{\partial W_2}{\partial t} = [Q_{12} - Q_{23} - E_{ct}/\rho_w] / \theta_s D_2 \quad (6b)$$

$$5 \frac{\partial W_3}{\partial t} = [Q_{23} - Q_3] / \theta_s D_3 \quad (6c)$$

6 where W_i is the wetness in the i -th layer, $W_i = \theta_i / \theta_s$, θ_i is the volumetric soil moisture content in the

7 i -th layer, and θ_s is the volumetric soil moisture content for the saturation condition; E_{gs} is the

8 evaporation from the surface soil layer (m s^{-1}); E_{ct} is the vegetation canopy transpiration (m s^{-1});

9 $Q_{i,i+1}$ is the water exchange between the i and $i+1$ layers (m s^{-1}); Q_3 is the base flow that drains out from

10 the bottom of the soil (m s^{-1}); and D_i is the thickness of the i -th layer (m).

11 The moisture movement between the soil layers is described by the Richards equation, and the

12 unsaturated zone hydraulic conductivity K (m s^{-1}) and the soil moisture potential ψ (m) are calculated

13 using the scheme of Clapp and Hornberger (1978), which is a function of the soil wetness (W).

$$14 K = K_s W_i^{(2B+3)} \quad (7)$$

$$15 \psi = \psi_s W_i^{-B} \quad (8)$$

16 where K_s is the saturated hydraulic conductivity (m s^{-1}), ψ_s is the saturation moisture potential (m),

17 and B is an empirical parameter. K_s , ψ_s and B are dependent on the soil characteristics and can be

18 obtained from the empirical equations, which are defined as a function of the soil texture (Yang et al., 2005;

19 Cosby et al., 1984).

20 The ET processes in the SiB2 model consist of four parts: vegetation canopy transpiration (E_{ct}),

21 evaporation from the interception of the canopy (E_{ci}), evaporation from the interception of the ground

1 (E_{gi}) and evaporation from the surface soil layer (E_{gs}). The formulas using in the calculation of the ET
 2 are similar with the electrical analog form, the ET, defined as the latent heat flux, is equal to the vapor
 3 pressure difference divided by the resistances between the different simulation points. The formulas are as
 4 follows:

$$5 \quad \lambda E_{ci} = \left[\frac{e^*(T) - e_a}{1/g_c + 2r_b} \right] \frac{\rho c_p}{\gamma} (1 - W_c) \quad (9a)$$

$$6 \quad \lambda E_{ci} = \left[\frac{e^*(T) - e_a}{r_b} \right] \frac{\rho c_p}{\gamma} W_c \quad (9b)$$

$$7 \quad \lambda E_{gi} = \left[\frac{e^*(T) - e_a}{r_d} \right] \frac{\rho c_p}{\gamma} W_g \quad (9c)$$

$$8 \quad \lambda E_{gs} = \left[\frac{h_{soil} e^*(T) - e_a}{r_{soil} + r_d} \right] \frac{\rho c_p}{\gamma} (1 - W_g) \quad (9d)$$

9 where λ is the latent heat of vaporization (J kg^{-1}); λE is the latent heat deduced from the ET (W m^{-2});
 10 $e^*(T)$ is the saturated vapor pressure at temperature T (Pa); e_a is the canopy air space vapor pressure
 11 (Pa); ρ is the density of air (kg m^{-3}); c_p is the specific heat of air ($\text{J kg}^{-1} \text{K}^{-1}$); γ is the psychrometric
 12 constant (Pa K^{-1}); W_c is the fractional wetted area of the canopy; W_g is the fractional wetted area of the
 13 ground surface; g_c is the canopy conductance (m s^{-1}), a parameter associated with the biological
 14 processes and the vegetation growth environment (e.g., the water potential of the root zone and the
 15 temperature); r_b is the bulk canopy boundary layer resistance (s m^{-1}), which is a function of the wind
 16 speed, the temperature, the canopy structure and other factors and is considered an energy-related
 17 parameter; r_d is the aerodynamic resistance between the ground and the canopy air space (s m^{-1}) and is
 18 related to the wind speed, the ground surface roughness, and other factors; h_{soil} is the relative humidity of
 19 the soil pore space; and r_{soil} is the soil surface resistance (s m^{-1}), representing the impact of the soil on
 20 the water vapor diffusion.

1 It can be seen from the above description that the ET simulation in the SiB2 model is based on a
2 physical mechanism in which the impacts of the water, energy and biological processes are all considered.
3 However, in the SiB2 model, the description of the water movement in the subsurface is relatively simple,
4 and the soil water movement is limited to a shallow unsaturated zone; the GWT and lateral flows are not
5 considered in the model. These simplifications in the water cycle will eventually cause errors in the energy
6 cycle calculation and the biological process simulation. Coupling the LSM and the GWM provides a good
7 approach to improving the accuracy of the simulated model.

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8 **2.3 Coupled model approach**

9 As described above, the SiB2 and AquiferFlow models have strengths and weaknesses. Coupling the
10 two models can overcome their weaknesses and more accurately simulate the water and energy cycles. In
11 the study presented here, the two models were tightly coupled from the model codes, and a new model,
12 named GWSiB, was developed. We will introduce the coupling mechanism in the following section.

13 In the coupled model, SiB2 simulates the energy balance, the vegetation root water uptake and the
14 hydrologic processes above the ground surface, and AquiferFlow simulates water movement in the
15 subsurface, including the saturated and unsaturated zones. Specifically, the SiB2 model is used to calculate
16 the precipitation infiltration (Q_1), the moisture evaporation (E_{gs}) and the transpiration (E_{ct}) based on the
17 energy balance and the mass balance. The calculated results are used as the sinks and sources (\mathcal{E}) and are
18 input into AquiferFlow to calculate the groundwater potential (ψ). The obtained water potential is then
19 used to calculate the groundwater movement in the model grids. The new groundwater condition obtained
20 is transferred back to SiB2 to complete the calculation cycle in one time step. A flowchart of the coupling
21 procedure is illustrated in Fig. 1.

22 The coupling of the two models includes spatial and temporal coupling. First, we discuss coupling the

1 two models in space. The SiB2 model, a vertical one-dimensional model, must be extended horizontally to
2 match AquiferFlow, a three-dimensional model. In our study, the mesh of the coupled model uses the
3 AquiferFlow scheme in the horizontal dimensions, which means that on every topmost cell of the
4 AquiferFlow grid, a SiB2 simulation is built. In the vertical space, AquiferFlow has a more flexible layer
5 structure than SiB2; consequently, the three subsurface layers in SiB2 are preserved, and the three top
6 layers in AquiferFlow are set to be consistent with them. The infiltration and the soil evaporation are linked
7 with the top layer of AquiferFlow, and the root zone uptake is linked with the second layer.

8 Although the surface runoff (R_0) and the base flow (Q_3) are calculated on a vertical column in SiB2,
9 the surface water convergence between cells is not taken into account in the coupled model. This
10 simplification will not cause a significant deviation when the model is used in the middle or lower reaches
11 of an arid or semi-arid basin because there are almost no flow confluence processes in these regions.

12 However, if the model is used in the upper reach of a basin, the errors cannot be ignored. Wang et al. (2009)
13 handled this problem by coupling SiB2 with a geomorphology-based hydrological model (GBHM). In our
14 study, the model validation and test were performed in the middle reach of the Heihe River basin where the
15 surface runoff is not the key hydrological process; consequently, the coupled model can be used here.

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16 We now discuss how to handle the temporal discretization of the coupled models. LSMs usually use a
17 time step of one hour or less because the energy and mass variables simulated by the LSM, such as the soil
18 surface temperature, vary rapidly and vary significantly from day to night. However, the groundwater head
19 and flow vary more slowly; therefore, the time intervals used in GWMs are usually one day or longer.
20 LSMs are more sensitive to the time resolution than GWMs and generally cannot accept time intervals
21 greater than one hour. If the time step in an LSM is one day, the temporal fluctuations that occur in hours
22 will smooth out, generating significant calculation errors and even making the simulation meaningless. A

1 shorter time interval will not significantly affect the simulation accuracy of GWMs but will significantly
2 reduce their computational efficiency.

3 Considering the time steps used in the two models, two alternative time coupling schemes are
4 implemented in the coupled model. One scheme is to use the AquiferFlow time step (which is the same as
5 that used in SiB2), which is set to be either one hour or 30 minutes. The second scheme is to adopt a time
6 step of one day in AquiferFlow, which is the time step normally used in the GWMs, while using a time
7 step of one hour in SiB2. The fluxes that are accumulated over one day in SiB2 are then exchanged with
8 AquiferFlow. The first scheme has a higher precision but requires more computation; it is thus suitable for
9 theoretical analysis or small-scale simulation. The second scheme greatly improves the computational
10 efficiency and achieves acceptable calculation accuracy. This scheme is more suitable for large area
11 simulation.

12 Both AquiferFlow and SiB2 use Richards equation as their control equations for soil water movement,
13 but they adopt different parameterization schemes to describe the relationship between the unsaturated
14 hydraulic conductivity (K) and the soil moisture potential (ψ). The Gardner and Fireman method (1958)
15 is used in AquiferFlow, and the Clapp and Hornberger (1978) scheme is used in SiB2. The different
16 schemes would make a huge difference in the calculation of Richards equation. Because the different
17 parameter schemes can strongly affect the calculation results of Richards equation, a discontinuity would
18 be created in the soil moisture at the two model communication times, especially when using the second
19 scheme, in which the water accumulation is exchanged between the GWM and the LSM. To solve this
20 problem, the Clapp and Hornberger (1978) soil moisture scheme used in SiB2 is introduced into the
21 AquiferFlow model framework. In AquiferFlow, the relative permeability (K_r) and the effective
22 saturation (S_e) are the two key parameters for soil moisture movement and content. These two parameters

1 are defined as fractions in AquiferFlow and are used to control the moisture movement in the unsaturated
2 zone by adjusting the saturated hydraulic conductivity (K_s) and the saturated soil water content (θ_s),
3 which is approximately equal to the porosity (ϕ). The parameters used in Clapp and Hornberger's (1978)
4 soil moisture scheme are also based on the saturated moisture potential (ψ_s) and the saturated hydraulic
5 conductivity (K_s); these equations can thus be transformed to the AquiferFlow framework as

$$6 \quad S_e = W = \left(\frac{\psi_s}{\psi} \right)^{\frac{1}{B}} \quad (10)$$

$$7 \quad K_r = \left(\frac{\psi_s}{\psi} \right)^{\frac{2B+3}{B}} \quad (11)$$

8 Replacing the K_r and S_e parameters of the AquiferFlow model by Equations (10) and (11) makes
9 the vadose zone parameters of AquiferFlow consistent with SiB2 and reduces the soil moisture
10 discontinuities in the model at the time of coupling.

11 After the GWSiB model is built, a sensitivity test about the key parameters of the model is performed,
12 and the model validation is conducted base on the measured data of two observation stations. The model is
13 then applied to the middle reach of the Heihe River basin to test the applicability of the model on the
14 regional scale. The following sections will describe the model validation in detail.

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15 **3 Model validation**

16 Many processes, such as the water cycle, the energy cycle, and biochemical processes, are integrated
17 into the GWSiB model. Because the ET is determined by the combined effects of these processes, the
18 validation of the simulated ET can assess whether these processes are adequately simulated. In this paper,
19 ET is used to validate the GWSiB model. The main feature of the GWSiB model is that the
20 three-dimensional groundwater movement is added to the land surface model. This makes it possible to
21 simulate the impact of the saturated groundwater level and the lateral groundwater flow on the land surface

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1 processes. To analyze the relationship between the groundwater and the ET, a sensitivity test is performed
2 prior to the model validation.

3 **3.1 Sensitivity test**

4 A synthetic domain is used to perform the sensitivity analysis of the GWSiB model. In this domain,
5 there are two rivers separated by 200 m, with a platform located between the two rivers. The altitude of the
6 platform is 1500 m, and its soil textures are homogeneous and isotropic. The rivers can recharge the
7 groundwater of the platform through lateral flow, so the river levels are generally representative of the
8 groundwater level in the area. The synthetic domain is divided into an array of uniform vertical columns
9 extending 3 columns wide parallel to the rivers and 10 columns long between the rivers; each column is 5
10 m wide and 20 m long (Fig. 2). In the vertical direction, the soil is divided into four layers representing the
11 surface soil layer, the root layer, the deep soil layer and the phreatic aquifer layer, at 0.02 m, 0.48 m, 1.5 m,
12 and 50 m, respectively. Consequently, the simulated domain forms a 120-element grid (10×3×4).

13 The model structure allows the groundwater level in the model to be easily controlled by directly
14 changing the water level of the two rivers. The model structure can also incorporate the characteristics of
15 the lateral groundwater flow.

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16 The forcing data used was measured at the Linze grassland station (LZG) of the Heihe River basin at
17 17:00 local time on August 12, 2008; these data represent typical moderate-radiation atmospheric
18 conditions in this arid region. The forcing data are maintained constant throughout the simulation period in
19 the sensitivity test.

20 The land cover of the simulated area is assumed to be grassland. The vegetation parameters used are
21 the default parameters for the “short vegetation / C4 grassland” vegetation type, which is one of the nine
22 types of vegetation derived from Sellers et al. (1996a) that are defined in SiB2. The leaf area index (LAI)

1 used to represent vegetation growth is kept at a constant value of 2 during the simulation period.

2 In the model, the two rivers are defined as fixed head boundaries. The other groundwater boundaries
3 are defined using the no-flow condition. The river levels, the soil texture and the groundwater hydraulic
4 parameters are specified according to the sensitivity tests described in detail in the following.

5 The first time-coupling scheme described in section 2.3 is used in the sensitivity test, and the time
6 step is set to one hour. The simulation period is 1488 hours.

7 Using the model, the impact of the groundwater depth on the ET is first analyzed. Five groundwater
8 depths, 1.5 m, 3.0 m, 5.0 m, 8.0 m, and 10.0 m (corresponding to river levels of 1498.5 m, 1497.0 m,
9 1495.0 m, 1492.0 m, and 1480.0 m, respectively), are simulated. In this experiment, the soil texture is set
10 to 30% clay, 30% silt, and 40% sand. The results from the cell located in the center of the platform are
11 used for the analysis. The analysis results are shown in Fig. 3.

12 The results show that the ET decreases as the groundwater depth increases. There is a difference of up
13 to 80% in the ET between the 10 m and 1.5 m groundwater depths in this experiment. This is because a
14 lower groundwater level reduces the water supply from the saturated groundwater to the surface and the
15 root soil layer by capillary action, and the reduction in the surface water limits ET. The simulated ET also
16 decreases continuously with time, except in the case of the 1.5 m groundwater depth. We believe this is due
17 to the velocity of groundwater flow, which includes the velocity of the lateral flow and the vertical flow.
18 When the water lost in ET is greater than the water gained through groundwater recharge, the soil
19 gradually dries, and ET decreases. However, there is a sufficient water supply in the case of the 1.5 m
20 groundwater depth, so ET does not significantly decline during the simulation period.

21 This analysis shows that the groundwater flow can significantly affect ET. In the GWSiB model, the
22 flow characteristics of the groundwater are determined by the soil texture and calculated using an empirical

1 formula (Yang et al., 2005). Consequently, in the second experiment, the effect of different soil textures on
2 the ET is analyzed. Three soil texture types, including sand-based soil (clay: 20%, silt: 20%, sand: 60%),
3 silt-based soil (clay: 20%, silt: 60%, sand: 20%), and clay-based soil (clay: 60%, silt: 20%, sand: 20%), are
4 used in this experiment. The relevant parameters defined by Clapp and Hornberger (1978) are $K_s=0.66$
5 m/day, $\Phi_s=0.12$ m, and $B=6.09$ for sand-based soil; $K_s=0.16$ m/day, $\Phi_s=0.41$ m, and $B=6.09$ for silt-based
6 soil; and $K_s=0.16$ m/day, $\Phi_s=0.41$ m, and $B=12.45$ for clay-based soil. In this experiment, the groundwater
7 level is set to 3 m. The results are shown in Fig. 4.

8 Fig. 4 shows that the hydraulic characteristics of the groundwater have a significant effect on ET. The
9 slope of the decrease in ET of the sand-based soil is less than the other soil types. This is because the
10 sand-based soil has a higher hydraulic conductivity than the other soil types, and the water in the soil that
11 is lost by ET can be recovered quickly. In contrast, the clay-based and silt-based soils have greater
12 capillary action (i.e., these soil types have a higher saturation moisture potential). These soil types can
13 provide more water to the ET process early in the simulation, but as the soil moisture decreases, the water
14 in the soil cannot be quickly replenished, and the rate of ET decreases rapidly.

15 **3.2 Model validation**

16 Based on the sensitivity analysis model, the GWSiB is validated at the Linze grassland station (LZG)
17 and the National Observatory on Climatology at Zhangye (ZYNOC), which represent shallow and deep
18 groundwater conditions, respectively. The measured data from the two stations, including atmospheric
19 driving data, vegetation data, soil textures and groundwater levels, are input to the model as the true value.
20 The vegetation parameters are calibrated for each station before the model validation is performed. The
21 detailed process is as follows.

1 (1) Validation of the model for the Linze grassland station (LZG)

2 The LZG is located in the middle reach of the Heihe River basin in the northwest of China. The
 3 longitude is 100.07, and the latitude is 39.25. The land cover in the LZG is mainly wetland, grassland and
 4 salinized meadow. An automatic meteorological station (AMS) built by the Watershed Allied Telemetry
 5 Experimental Research (WATER) project (Li et al.,2009) in the LZG was used for observations from
 6 October 1, 2007 to October 27, 2008. The AMS provides all the necessary atmospheric forcing data for our
 7 modeling study. Although there is no direct measurement of the latent heat at the LZG station, it can be
 8 obtained from the sensible heat by the energy balance equation:

$$9 \quad LE = R_n - H - G \quad (12)$$

10 where LE is the latent heat (W m^{-2}); L is the heat of vaporization (J kg^{-1}); E is the ET (m); R_n is the
 11 net radiation (W m^{-2}), equal to the difference of the downward radiation and the upward radiation, which
 12 can be obtained from the atmospheric forcing data; and H is the sensible heat. In the WATER
 13 experiment, a large-aperture scintillometer (LAS) flux system was used from May 19, 2008 to August 27,
 14 2008 to obtain the sensible heat data for the model. G is the ground heat flux (W m^{-2}) and is assumed to
 15 be proportional to the net radiation (Su, 2002):

$$16 \quad G = R_n \cdot [\Gamma_c + (1 - f_c) \cdot (\Gamma_s - \Gamma_c)] \quad (13)$$

17 where $\Gamma_c = 0.05$ for a full vegetation canopy, $\Gamma_s = 0.315$ for bare soil, and f_c is the fractional canopy
 18 coverage, which is set to 0.81 based on observations in the LZG. The latent heat of the LZG is calculated
 19 according to a variety of observational data and the energy balance equation; the ET is then deduced based
 20 on the latent heat.

21 The soil texture and groundwater depth data come from observations in the LZG. The soil is
 22 composed of 13.4% clay, 31.6% sand and 55% silt. The groundwater depth varies between 1.2 m and 1.9

1 m during the simulation period. The vegetation type used in the LZG model is “C3 grassland,” and the
2 parameters from Sellers et al. (1996a) for this vegetation type are calibrated according to the ET measured
3 in the LZG from August 20 to August 30, 2008. The parameters used in the model are listed in Table 1. In
4 the GWSiB model, the leaf area index (LAI) has often been used to characterize the vegetation growth
5 process. The LAI data for the LZG were obtained from MODIS global LAI and FPAR products
6 (MCD15A3) with a 4-day time resolution and a 1-km spatial resolution. These data were revised according
7 to observation and interpolated to the 1-hour time resolution used in the model. The LAI varies from 2.1 to
8 3.4 during the simulation period.

9 The same model structure as in the sensitivity test is used in the model validation, including the same
10 spatial structure and the same time step. The data described above are used as the input to the GWSiB
11 model to simulate the energy and water cycles of the LZG from May 19, 2008 to August 27, 2008. In the
12 simulation, the data from May 19 to July 1 are used for the calibration of the model parameters, and the
13 data from July 1 to August 27 are used to validate the model of the LZG. For comparison, the SiB2 model
14 is executed using the same conditions. The simulation results are shown in Fig. 5.

15 The simulation results show that the GWSiB simulation agrees well with the observed ET trends and
16 magnitudes. However, the SiB2 simulation significantly underestimates the ET in the LZG. These findings
17 can also be observed in the scatter plot (Fig. 6), which shows the relationship between the observed data
18 and the results of the two models. The simulated results from the SiB2 model are far below the 1:1
19 regression line. This underestimation is confirmed by the statistical analysis. The mean value of the
20 observed ET is 3.93 mm per day during the simulation period, and the mean value from the GWSiB model
21 is 3.98 mm per day; the mean relative error (MRE) between them is 1.4%. However, the mean value from
22 the SiB2 model is 0.76 mm per day, and the MRE is 80.7%.

1 The GWSiB model can provide a more realistic simulation than the SiB2 model because the
2 movement of the groundwater is taken into account in the GWSiB model but not in the SiB2 model. The
3 lateral flow of groundwater causes groundwater accumulation in the shallow-water region and raises the
4 groundwater level. The saturated groundwater supplies water to the soil near the ground surface by
5 capillary action, leading to greater ET at the land surface in the LZG. Compared with the GWSiB model,
6 the SiB2 model is a vertical one-dimensional model that cannot model the process of groundwater recharge
7 by lateral water movement; consequently, the soil water moisture of the land surface is underestimated, and
8 the lower soil moisture reduces the ET observed in the SiB2 model.

9 **(2) Validation of the model for the National Observatory on Climatology at Zhangye**

10 The National Observatory on Climatology at Zhangye is one of China's national climatology stations.
11 The station is located in the middle reach of the Heihe River basin at a longitude of 100.28 and a latitude
12 of 39.08. The ZYNOC has a Gobi landscape. Comprehensive atmospheric and heat flux data are measured
13 in the ZYNOC that can support the validation of the model for the ZYNOC. ET data in the form of the
14 latent heat were obtained from June 28, 2008 to August 22, 2008. Some of these data were removed
15 because the data quality was poor, and only 41 days of latent heat observations are used for the model
16 validation.

17 Of the 9 vegetation types defined in the SiB2 model, the "broadleaf shrubs with bare soil" type is
18 chosen as the closest to the actual conditions of the ZYNOC. The parameters from Sellers et al. (1996a) for
19 this vegetation type are calibrated according to the ET measurements. The typical soil textures of the
20 ZYNOC obtained from field measurements are 23% clay, 30% sand and 47% silt. The groundwater level
21 data come from a well approximately 2 km from ZYNOC. The variation of the groundwater depth is not
22 significant during the simulation period; the depth varies from 25.4 m to 26.2 m. The groundwater levels

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1 are used as fixed-head boundary conditions in the model. The LAI data are obtained from the MODIS
2 products (MCD15A3), in a manner similar to the validation of the LZG, using the measurements from the
3 ZYNOC. The LAI of the ZYNOC increases from 0.1 to 0.4 during the simulation period.

4 The setup of the model for the ZYNOC validation is the same as that used for the LZG validation.
5 The simulation period is from June 28, 2008 to August 22, 2008. The ET data from June 28 to July 21 are
6 used to calibrate the vegetation parameters of the model. The parameters that are held constant throughout
7 the simulation period are listed in Table 1. The remainder of the simulation period is used to validate the
8 model. The ET processes are simulated in the SiB2 model using the same conditions, except that the
9 groundwater level is not considered in the SiB2 model. The simulation results from the two models are
10 shown in Fig. 7 and Fig. 8.

11 Fig. 7 and Fig. 8 show that the two models produce similar results for the ZYNOC. Both models
12 provide a good simulation of the magnitude and the variation of the ET process, and there is no significant
13 difference between the results from the two models. The mean value of the observed ET is 0.72 mm per
14 day during the simulated period, and the mean value from the GWSiB model is 0.74 mm per day; the MRE
15 between the observation and the simulation is 3.0%. The mean value from the SiB2 model is 0.69 mm per
16 day, and the MRE is 4.7%.

17 We believe that the groundwater level and the lateral flow of the groundwater have a small effect on
18 the energy and water cycles on the land surface because the groundwater is deep (approximately 26 m
19 below groundsurface). In the thick vadose zone, water movement occurs primarily in the vertical
20 dimension. Both the SiB2 and the GWSiB models can simulate this process adequately, and they provide
21 similar and realistic results. The GWSiB and SiB2 results nevertheless show some minor differences; e.g.,
22 the variations in the simulated ET are greater in the SiB2 model than in the GWSiB model, and the SiB2

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1 model tends to produce larger or smaller extreme values. We believe that the difference in the results can
2 be attributed to the difference in the two model structures.

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3 **4 Regional test of the model**

4
5 The validation of the GWSiB model in the shallow groundwater site (LZG) and the deep groundwater
6 site (ZYNOG) demonstrate the adequacy of the model. However, the water cycle can usually only be
7 understood comprehensively on a regional scale. Because the GWSiB model is fundamentally a
8 three-dimensional model, it has the ability to simulate regional water and energy cycles. In the following,
9 the GWSiB is applied in the middle reach of the Heihe River basin to test the simulation capabilities of the
10 model in the region.

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11 **4.1 Study area**

12 The middle reach of the Heihe River basin is an arid inland river basin located in northwestern China.
13 In this basin, an integral groundwater cell, which is hydrogeologically described as the Zhangye Basin, is
14 selected as the study area. The latitude of the study area ranges from 38.7°N to 39.8°N, the longitude
15 ranges from 98.5°E to 102°E, and the total area is approximately 12,825 km² (Fig. 9). Irrigated agriculture,
16 grassland/steppe, wetland, and Gobi are the main types of land cover in the study area. Some numerical
17 groundwater simulation studies have been performed of this area, such as studies by Wen et al. (2007) and
18 Su (2005), who used the FEFLOW model to simulate the groundwater movement in the area and forecast
19 the groundwater trends. Hu et al. (2007) developed a three-dimensional GWM and used it to study the
20 groundwater interaction with rivers and springs in the area. Ding et al. (2009) developed a
21 two-dimensional numerical model to simulate the groundwater dynamics of the area. Zhou et al. (2011)
22 built a GWM of the area to quantify the effects of land use and anthropogenic activities on the groundwater

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1 system. These groundwater modeling studies provide excellent references for this study.

2 **4.2 Model settings**

3 The study area is uniformly discretized into 79 rows and 32 columns horizontally, and each numerical
4 cell has dimensions of 3 km×3 km. In the vertical direction, the soil below the ground surface is divided
5 into 6 layers. The upper three layers correspond to the soil layers of the SiB2 model and represent the
6 surface soil, the soil root, and the deeper soil layers. The thickness of these soil layers is set to 0.02 m, 0.48
7 m, and 1.5 m, respectively, according to the average conditions of the soils in the middle reach of the
8 Heihe River basin. The lower three layers are used to describe the hydrogeologic structure in the study area,
9 representing the unconfined aquifer, the aquitard and the confined aquifer. The thicknesses of the lower
10 three layers are determined by the interpretation of the logging data obtained from 108 boreholes in the
11 region, as proposed by Zhou et al. (1990). The study area contains a total of 15,168 (79×32×6) cells, as
12 shown in Fig. 9.

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13 The topography of the study area is determined from 90-m resolution digital elevation model (DEM)
14 data obtained from the Shuttle Radar Topography Mission (SRTM) and upscaled to 3-km resolution.

15 The initial GWT distribution in the study area is obtained by the interpolation of GWT measurements
16 conducted in December 2003 from 36 observation wells in the study area. Any GWT positions not
17 available from the measurements are determined from the relevant literature (Zhou et al., 2011; Wen et al.,
18 2007; Su, 2005; Hu et al., 2007). The initial GWT data show that the main direction of the groundwater
19 flow of the middle reach of the Heihe River basin is from south to north and is roughly consistent with the
20 river flow direction. The GWT is lower in the north of the study area, where the groundwater discharges to
21 the river. The boundary conditions and the saturated hydraulic conductivity of the model were initially
22 assigned values according to previous study results from the Heihe River basin (Zhou et al., 2011; Wen et

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1 al., 2007; Su, 2005; Hu et al., 2007; Ding et al., 2009). Later, these parameters were optimized through
2 trial-and-error calculations using GWT data obtained in January 2008. Ultimately, the boundary conditions
3 of the model are set as fixed-flow conditions: the southern boundary has $1.62 \times 10^8 \text{ m}^3$ water inflow every
4 year, the northern boundary has $0.37 \times 10^8 \text{ m}^3$ /a water inflow, and the western and eastern boundaries have
5 a total of $0.08 \times 10^8 \text{ m}^3$ /a water inflow. These water inflows were allocated to each of the active cells of the
6 boundary grid in the model. The saturated hydraulic conductivity (K_s) field in the study area was divided
7 into 24 sub-regions, with values ranging from 0.5 m d^{-1} to 20 m d^{-1} . The distribution of the specific storage
8 (S_s) was represented by 10 sub-regions, with values ranging from 0.003 m^{-1} to 0.17 m^{-1} . The water
9 potential parameters of the unsaturated zone were determined according to the soil texture. The parameter
10 values for the soil characteristics used in this study were obtained through the analysis of the Chinese
11 dataset of the multi-layer soil-particle size distribution, which has a 1-km resolution (Shangguan et al.,
12 2011).

13 The atmospheric data used in the model, including the incident solar radiation, incident longwave
14 radiation, wind speed, air pressure, vapor pressure, air temperature, and precipitation, are taken from the
15 Global Land Data Assimilation System (GLDAS) project (Rodell et al., 2004). The spatial resolution of the
16 original data is 25 km, and the temporal resolution is 3 hours. The data are interpolated to a spatial
17 resolution of 3 km and a temporal resolution of 1 hour to fit the resolution of the coupled model. The
18 temporal interpolations of the data were performed using a statistical method provided by the Global Soil
19 Wetness Project 2 (GSWP2) (for the precipitation data) and the cubic spline method (Dai et al., 2003) (for
20 other data). The high-resolution meteorological interpolation model MicroMet (Liston and Elder, 2006) is
21 used in the spatial interpolation of the data. These data are used in all of the model cells except those cells
22 where an AMS is located. In those cells, the interpolated atmospheric data are replaced by the measured

1 data.

2 The land cover data used in the model are derived from the Multi-source Integrated Chinese Land
3 Cover (MICL Cover) data (Ran et al., 2012). The International Geosphere-Biosphere Programme (IGBP)
4 land cover classification system is used in the MICL Cover data, and the land surface is classified into 17
5 types. In this study, the 17 types are grouped into nine types corresponding to the vegetation classifications
6 of the SiB2 model (Sellers et al., 1996b). The parameters of each vegetation type defined by Sellers et al.
7 (1996a) are calibrated according to the measured ET data from this study.

8 There is a considerable amount of irrigated farmland in the study area, and the energy and water
9 cycles are affected by the irrigation. In this model, the irrigation is modeled by sink terms added to the
10 groundwater system on the grid cells at which the vegetation type of cells is defined as “agricultural.” The
11 irrigation data used in the model come from the local administrative department of agriculture.

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12 The time-dependent vegetation parameters used in the coupled model were obtained from satellite
13 data. The level-4 combined (Terra and Aqua) MODIS global LAI and FPAR products (MCD15A3), which
14 are provided every 4 days at a resolution of 1 km, are linearly interpolated to a temporal scale of 1 hour
15 and are resampled to a spatial resolution of 3 km for the coupled model.

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16 Because of the scope of the study area and the quantity of cells, the computational effort required in
17 the simulation is considerable. Therefore, the second time-coupling scheme is used in the case study; i.e.,
18 an hourly time step is used in the SiB2 model and a daily time step is used in AquiferFlow. At the start of

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19 each simulated day, the two models exchange fluxes.

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20 Because the groundwater flow equation is highly nonlinear, the convergence of the groundwater model
21 needs careful adjustment of the solver. In this study, the model convergence was implemented through the
22 adjustment of the relaxation factor, the number of iterations, and the convergence criterium, which were

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1 set to 1.3, 10000, and 0.001 m, respectively.

2 The initial conditions of the model, such as the soil moisture, surface temperature, canopy
3 temperature and other variables, are determined according to the general conditions in the middle reach of
4 the Heihe River basin in winter. The initial conditions are specified in the coupled model for January 1,
5 2004. The model is run for four years as a spin-up from January 1, 2004 to January 1, 2008 to ensure that
6 the model is initially in equilibrium. The simulated values at the end of the spin-up period (January 1, 2008)
7 are treated as the initial conditions of the simulation period for the coupled model.

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8 **4.3 Analysis of the model results**

9 Using the GWSiB model of the middle reach of the Heihe River basin, the energy budget and the
10 water movements in this region were simulated from January 1 to December 31, 2008. We analyzed the
11 results of the model to test the model on the regional scale. First, the simulated GWT data from December
12 20, 2008 are compared with the measured GWT data for the same day obtained from the interpolation of
13 the data from the 36 observation wells. The results are shown in Fig. 10.

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14 The simulation results and the measurements agree well (Fig. 10) except on the west side of the study
15 area, where the groundwater depth is greater than 100 m and there are few groundwater observation wells.
16 The initial GWT data for these regions are taken from the existing literature (Wen et al., 2007; Su, 2005),
17 and the measured data for these regions are extrapolated from the 36 observation wells. We believe the
18 uncertainty of the GWT data for these areas is the main reason for the simulation errors. Additionally, in
19 the upper section of the Heihe River, the simulated GWT results are higher than the measured GWT data
20 (e.g., at the 1450 m GWT) in Fig. 10. This is because the upper section of the Heihe River is considered to
21 be the region of surface water recharge to the groundwater in the coupled model. The significant water
22 infiltration in this region and the partial GWT increase are simulated in the model, but this change is not

1 caught in the measurements because there are few observed wells in this region to provide data for the
2 GWT interpolation. In general, the GWSiB simulation produces a good model of the groundwater
3 conditions of the middle reach of the Heihe River basin, and the GWSiB model can provide a continuous
4 and time-varying depiction of the impact of the groundwater on the land surface energy and water cycles.

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5 The regional ET is analyzed next. In this test, the GWSiB model is used to calculate the hourly ET for
6 the study area in 2008. Because there is no way to directly measure the regional ET, we compare the
7 GWSiB simulation results with ET data obtained by remote sensing. Li et al. (2011) calculated ET from
8 the NOAA/AVHRR satellite data of the Heihe River basin, and obtained a regional ET with a 1-km
9 resolution at 15:00 local time on August 2, 2008. The regional ET simulated by GWSiB for the same time
10 is compared with these data in Fig. 11.

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11 The results of the model simulation and the remote sensing calculation have a very similar spatial
12 distribution, and both show the ET distribution characteristics of the middle reach of the Heihe River basin.

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13 In this region, the banks of the Heihe River and the irrigated area have greater ET because the river
14 recharges the groundwater through lateral flow and raises the groundwater levels of the banks while the
15 irrigation increases the soil moisture of the irrigated area. The average ET in the study area determined
16 from the model simulation is 0.24 mm, and the value calculated from the remote sensing data is 0.31 mm.
17 There is a 23% MRE between the two values. However, some details are not consistent between the two
18 results. The main reason for the inconsistency, besides the error caused by the remote sensing terms, is the
19 model uncertainties, including uncertainty in the meteorological driving data, the land cover data, the soil
20 texture data, the groundwater data, and the grid structure of the model.

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21 On the whole, the GWSiB model can simulate regional energy and water cycles, although there are
22 some errors. In this test, the GWSiB model achieves an acceptable regional ET simulation of the middle

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reach of the Heihe River basin both in terms of absolute values as spatial distribution.

5 Discussion and conclusions

LSMs can describe the land surface energy and water cycles well, but the water movement in the subsurface is oversimplified, and the movement of saturated groundwater is ignored. Conversely, GWMs can describe the dynamic movement of subsurface water, but they cannot simulate the physical mechanisms of ET, which is an important component of the water cycle because this process involves the energy cycle and the biological processes. Coupling the two types of models can effectively overcome their respective shortcomings, and by linking the energy and water cycles together, these processes can be simulated more comprehensively and potentially more accurately.

In this study, a three-dimensional dynamic groundwater model, AquiferFlow, and a typical land surface model, SiB2, are fully coupled. In the coupling scheme, infiltration, evaporation and transpiration, which are simulated by the SiB2 model, are used as inputs to the AquiferFlow model, and the soil moisture values calculated by AquiferFlow are used in SiB2. In the sensitivity analysis of the coupled model, the effects of the groundwater level and the hydraulic parameters of the groundwater on the energy and water cycles are analyzed. The excellent performance of the GWSiB model in the LZG and ZYNOC validation studies demonstrates that the coupled model has the proper structure. Additionally, the case study of the middle reach of the Heihe River basin demonstrates the ability of the GWSiB model to simulate regional-scale dynamics.

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There are many factors that can affect the accuracy of the simulation of the ET in a region, such as the meteorological driving data, the groundwater conditions determined by the groundwater hydraulic parameters and boundary conditions, the vegetation type and parameters, the dynamic variation of the vegetation, the soil texture, and the resolution of the model grid. In the simulation of the middle reach of

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1 the Heihe River basin, after we adjust the hydraulic conductivities of the groundwater by the trial-and-error
2 method, calibrate the vegetation parameters according to in situ observations, and select the appropriate
3 land cover and soil texture databases, we achieve good simulation results, as demonstrated by the
4 comparison with the remote sensing data. However, the regional simulation using the model is directly
5 affected by the input data in addition to the physical structure of the model. We believe that the model
6 errors will be gradually reduced as the accuracy of the regional data improves.

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7 In our study, the ET is used as the validation variable because the ET is the key variable in the energy
8 and water cycles, and it provides an integrated measure of the accuracy of the simulation of the energy
9 cycle, the water movement and vegetation photosynthesis. However, the GWSiB model is not limited to
10 the calculation of ET. The GWSiB model can describe the energy and water processes as a system, and the
11 model can be widely used in the study of earth science.

12 From our study, the following four conclusions can be obtained.

13 (1) The groundwater depth can significantly affect the ET on the land surface; the ET increases
14 as the groundwater depth decreases. Additionally, the groundwater hydraulic parameters and
15 the soil structure can affect ET through the vertical and lateral movement of the groundwater.

16 (2) In a shallow groundwater depth zone, the GWSiB model, which incorporates the
17 groundwater movement, simulates the ET process on the land surface more accurately than
18 the SiB2 model, in which the groundwater movement is not simulated. The ET will be
19 underestimated if the groundwater movement is ignored in this region.

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20 (3) The interaction of the groundwater and the land surface processes is weak in zones of large
21 depth to groundwater, and the subsurface water movement is dominated by vertical
22 movement under these conditions. The GWSiB model produces results similar to the SiB2

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1 model, and each of the models can simulate the ET process in this region well.

2 (4) The GWSiB model can simulate regional energy and water cycles. The GWSiB simulation
3 accurately models the middle reach of the Heihe River basin. The accuracy depends not only
4 on the correctness of the model structure but is also directly affected by the model data.

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5 In summary, the coupling of the groundwater and land surface models allows the land surface and
6 subsurface processes to be simulated as a system, and the coupled model can depict the interaction of the
7 groundwater and the energy and water movement on the land surface. This improves the simulation of the
8 energy and water cycles.

9 Although a coupled model is developed in this paper, there are many energy and water processes that
10 are not considered in our model, such as surface water processes, water resource allocation, and soil
11 freezing and thawing processes. Additionally, the validation of the GWSiB model is limited by the
12 shortage of available data. Further validation and improvement of the coupled model will be the primary
13 thrust of future studies.

14

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4 System." The data used in the paper were obtained from the Watershed Allied Telemetry
5 Experimental Research project (<http://westdc.westgis.ac.cn/water/>).

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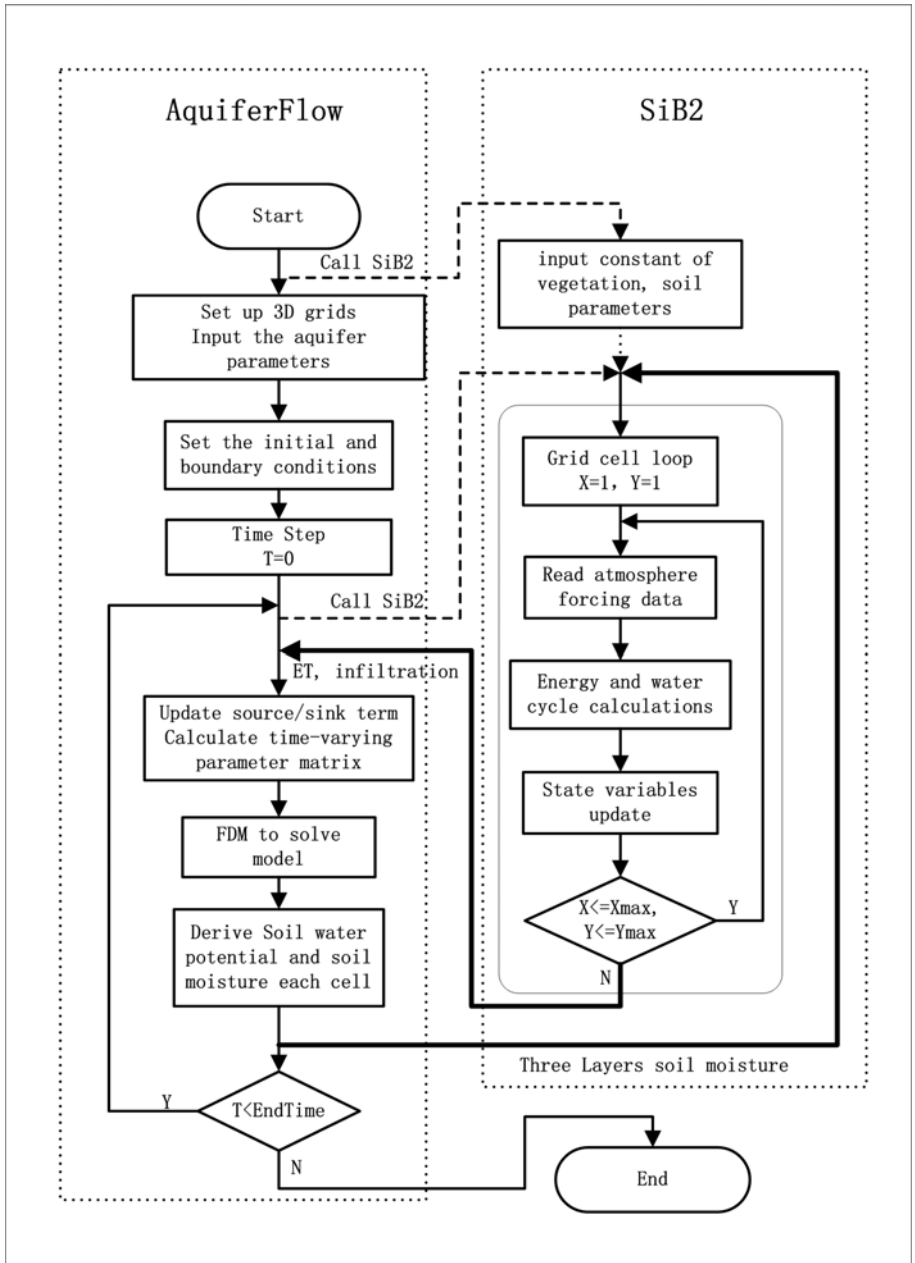
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1 Table 1. The vegetation parameters for each station

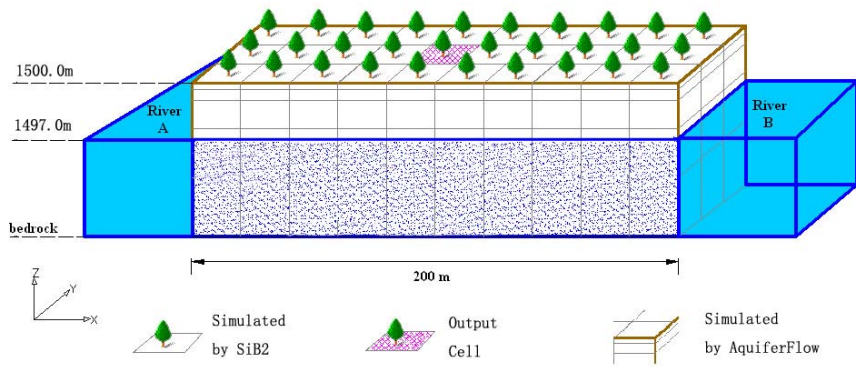
Station name	SiB2 vegetation classification	Land cover	Canopy top height (m)	Canopy base height (m)	Leaf reflectance, visible, live	Leaf reflectance, near IR, live	High temperature stress factor, photosynthesis	Low temperature stress factor, photosynthesis
LZG	Short vegetation/ C4 grassland	0.81	0.3	0.03	0.105	0.58	310	280
ZYNOC	Broadleaf shrub and bare soil	0.01	0.2	0.03	0.1	0.45	313	283

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2 Fig. 1. The coupling between SiB2 and AquiferFlow in GWSiB. The bold solid lines with
 3 arrows indicate the direction of the transmission of variables, and the dashed lines with arrows
 4 indicate function calls.



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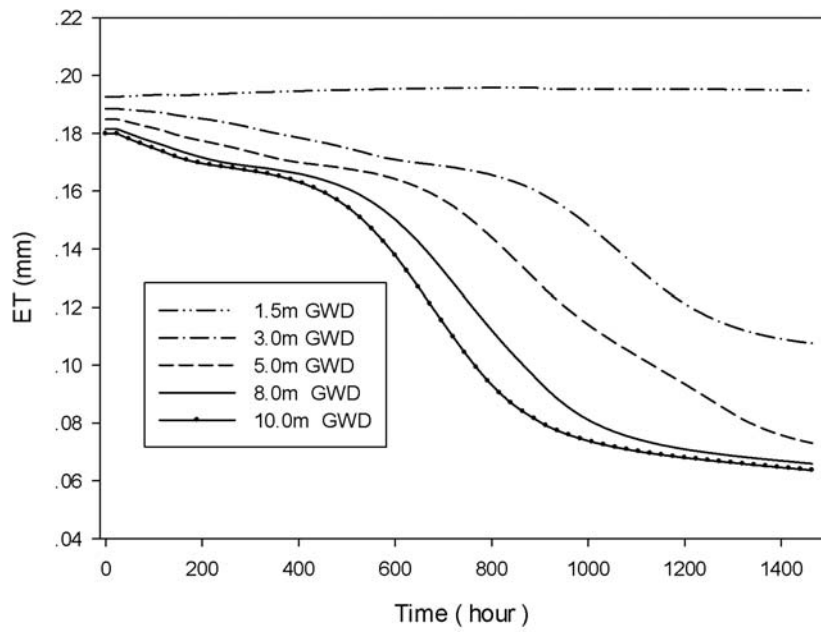
3 Fig. 2. The synthetic model structure used in the sensitivity analysis of the GWSiB. The results

4 from the output cell located in the center of the platform are used for the analysis.

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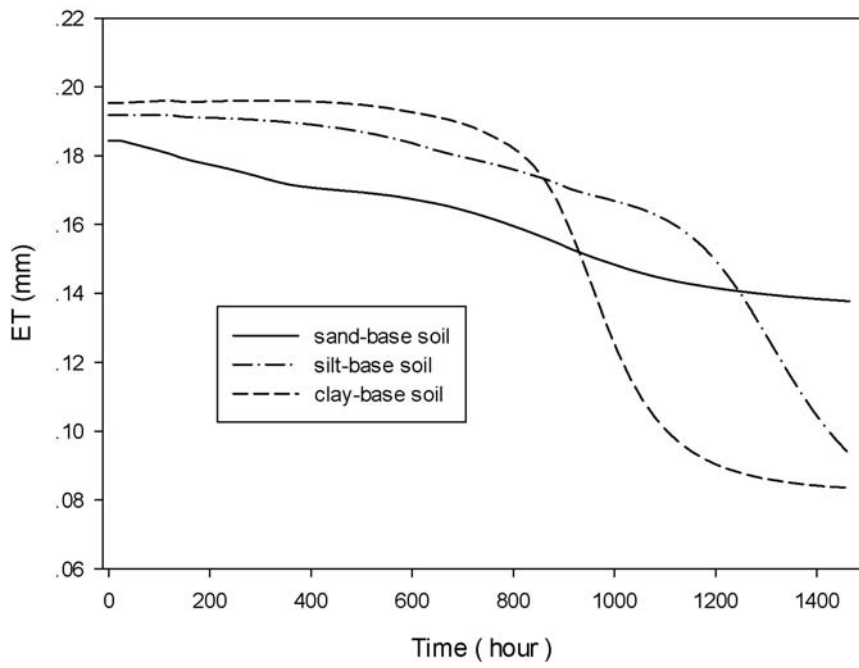


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3 Fig. 3. Simulated ET results at different groundwater depth (GWD) conditions.

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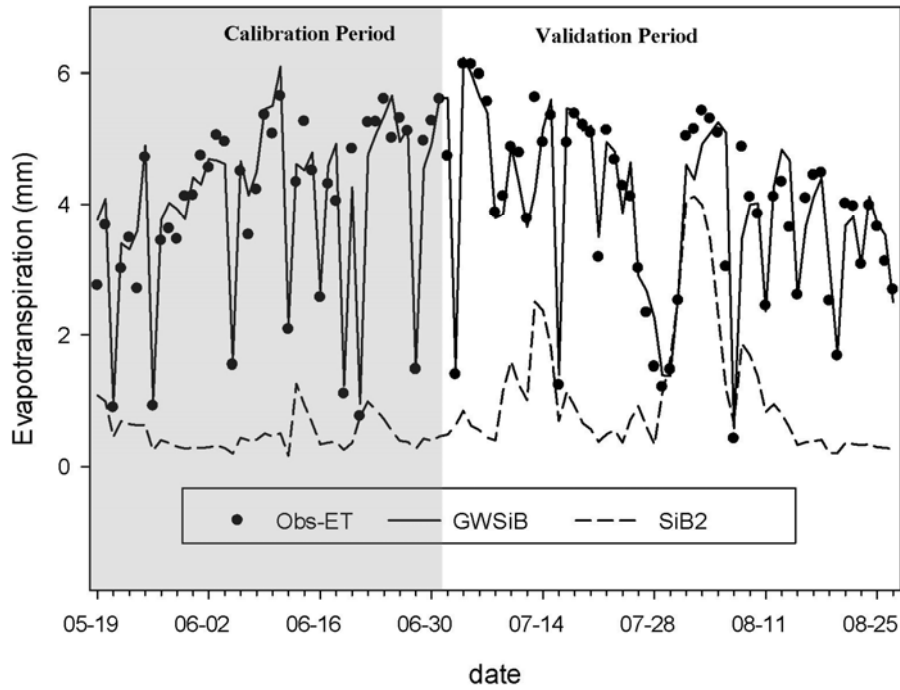
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3 Fig. 4. Simulated ET results at different soil texture conditions.

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3 Fig. 5. The measured evapotranspiration, the GWSiB-simulated evapotranspiration, and the

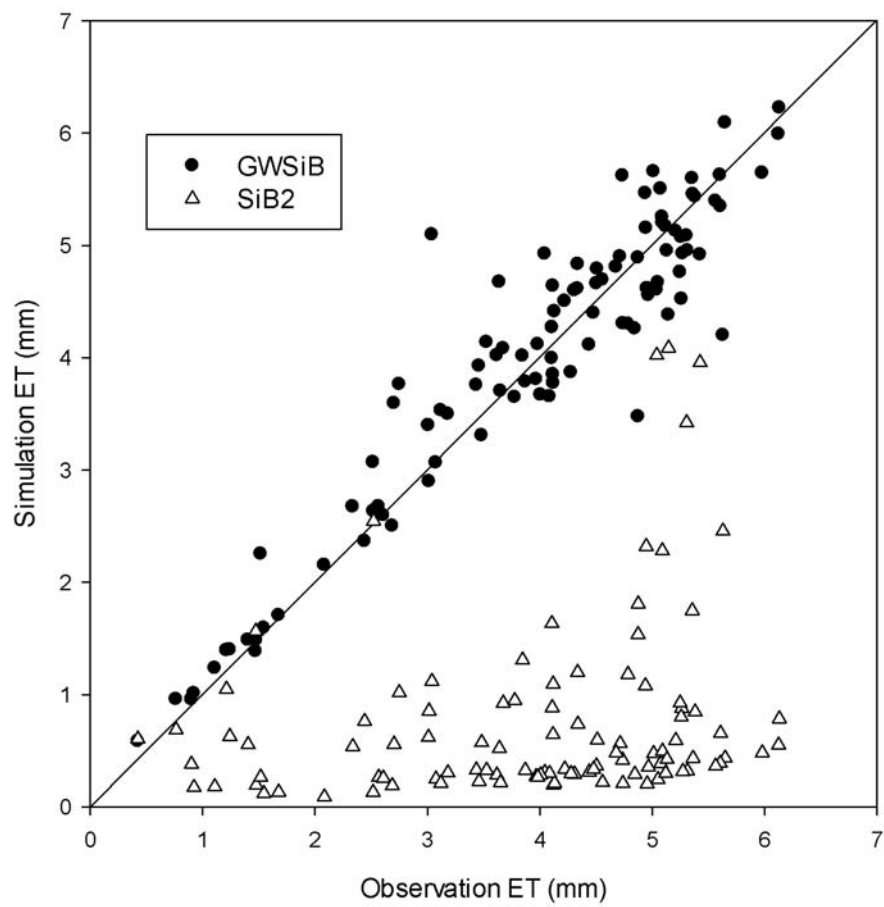
4 SiB2-simulated evapotranspiration for the Linze grassland station from May 19, 2008 to August

5 27, 2008. The data in the shadowed part of the graph are used for the model parameter calibration,

6 while the other data are used for the model validation.

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2 Fig. 6. A scatter plot comparing the GWSiB-simulated and the SiB2-simulated evapotranspiration

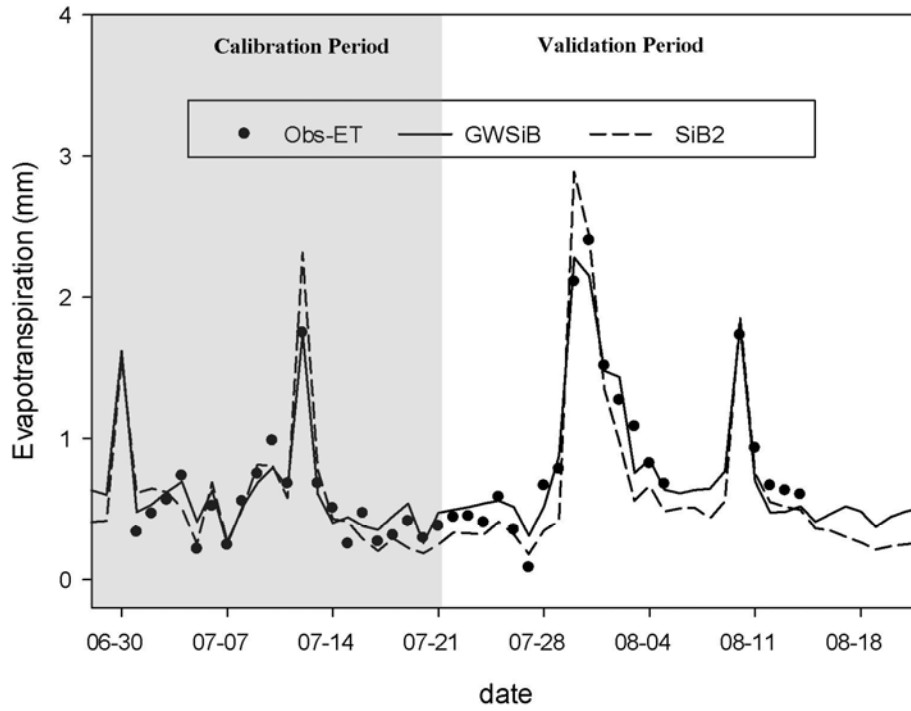
3 with the measured evapotranspiration in the Linze grassland station.

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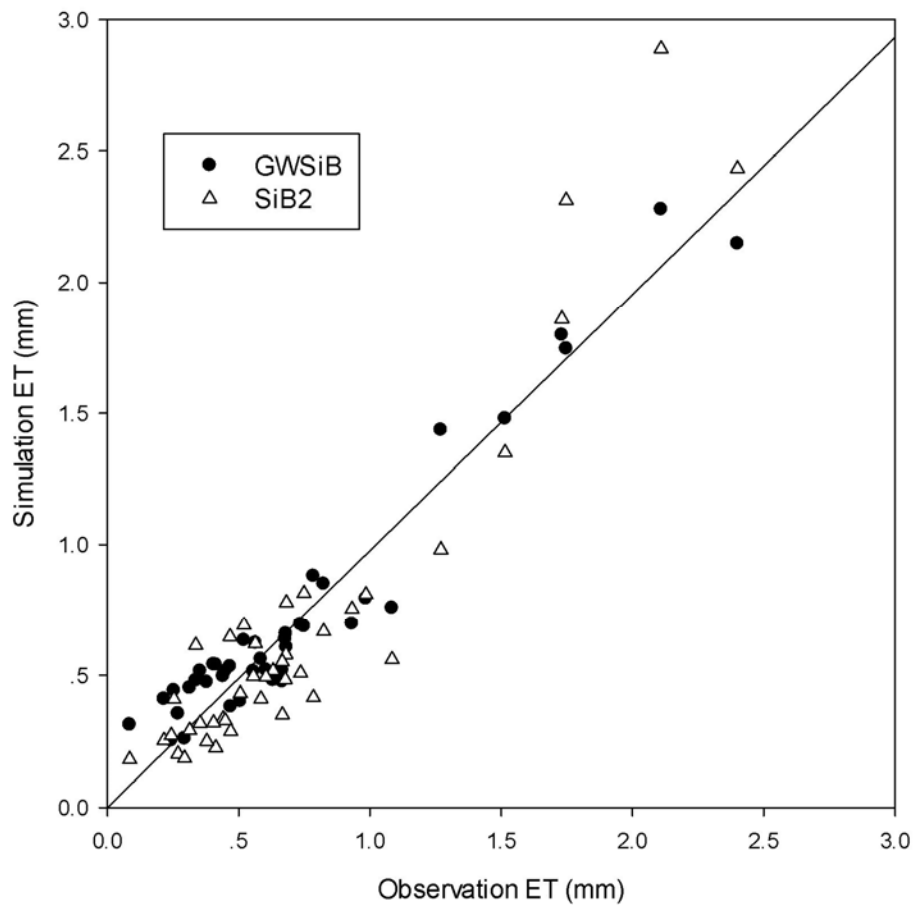
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3 Fig. 7. The measured evapotranspiration, the GWSiB-simulated evapotranspiration, and the
4 SiB2-simulated evapotranspiration for the National Observatory on Climatology station at
5 Zhangye from June 28, 2008 to August 22, 2008. The data in the shadowed part of the graph are
6 used for the model parameter calibration, while the other data are used for the model validation.

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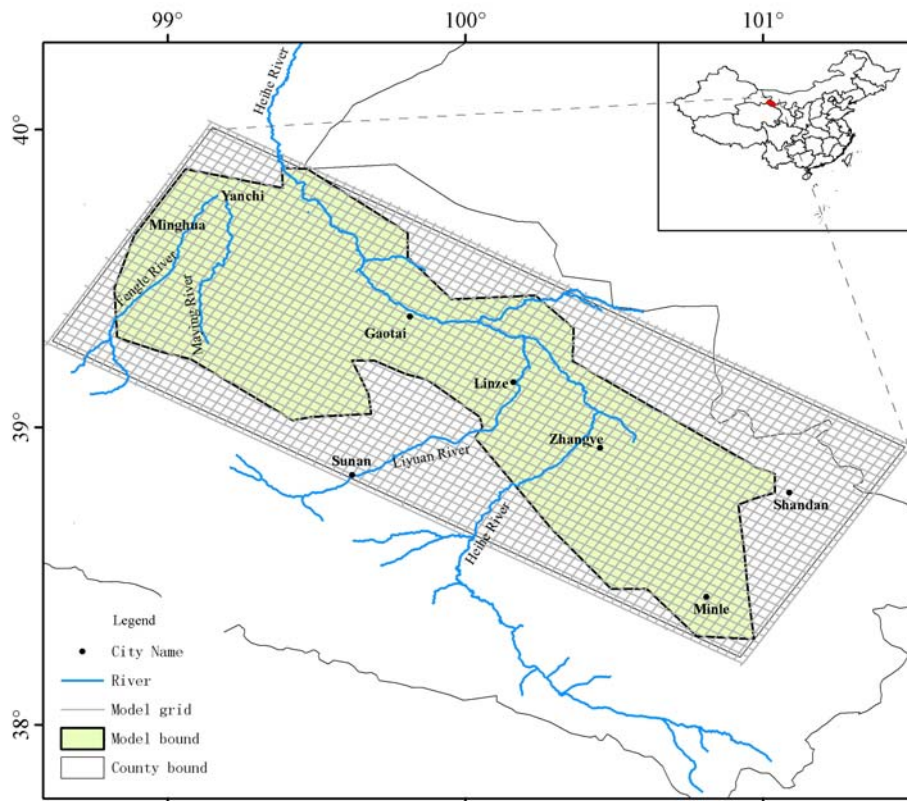


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2 Fig. 8. A scatter plot comparing the GWSiB-simulated and the SiB2-simulated evapotranspiration

3 with the measured evapotranspiration in the National Observatory on Climatology station at

4 Zhangye.

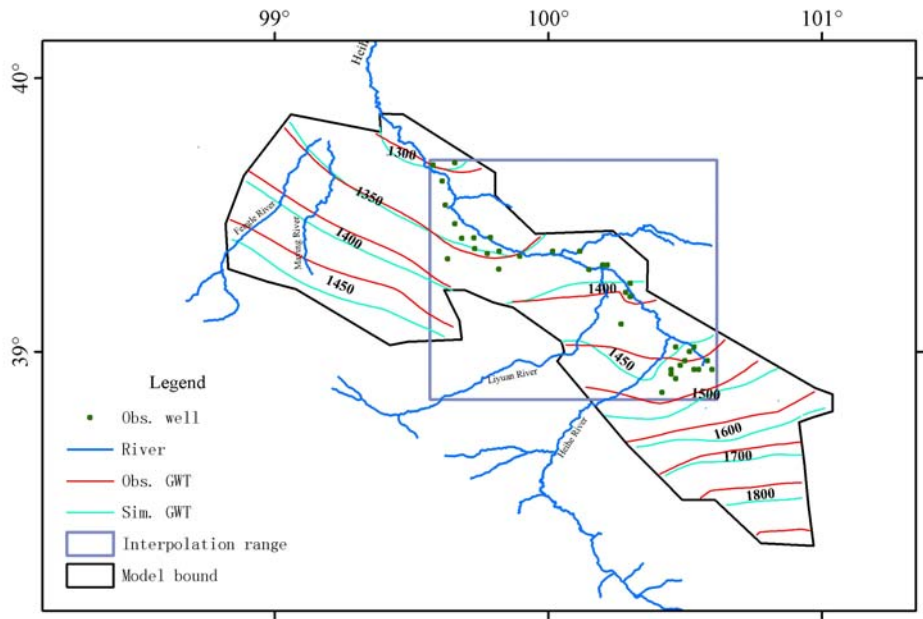


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Fig. 9. The location of the study area in the middle reach of the Heihe River basin and the model grid structure.

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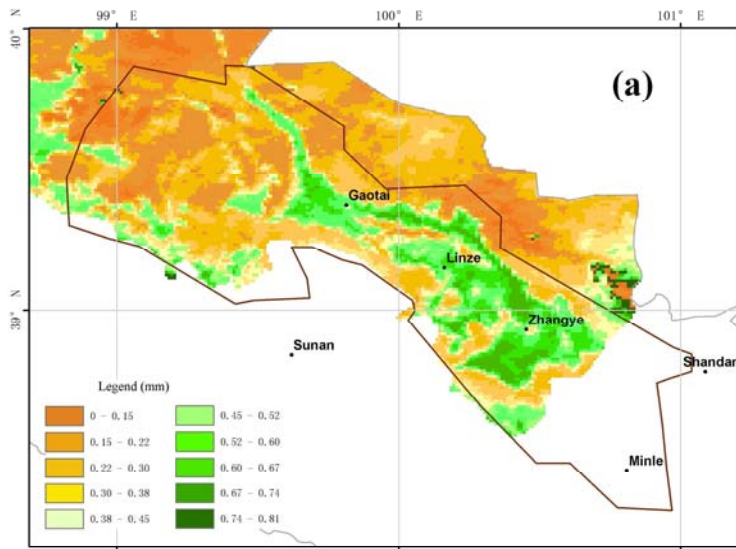


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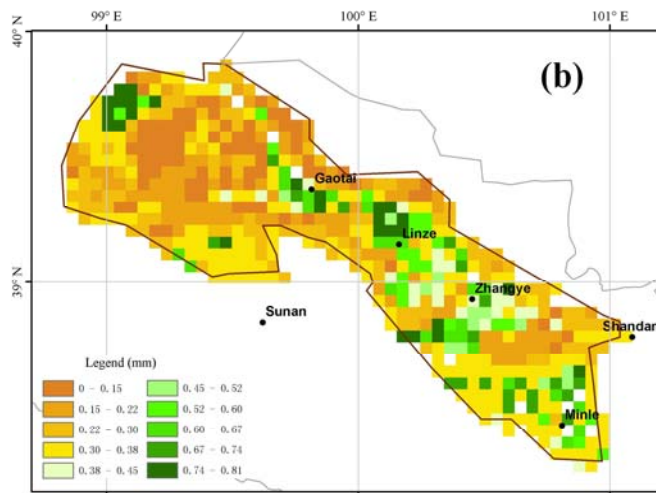
3 Fig. 10. The observed and simulated groundwater table (GWT) of the study area in December
 4 2008. The observed GWT within the scope of the 36 wells (the interpolation range) is obtained by
 5 interpolation; the rest of the GWT in the study area is obtained by extrapolation.

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3 Fig. 11. Evapotranspiration calculated by remote sensing (a) and simulated by the GWSiB model

4 (b) in the middle reach of the Heihe River basin for August 8, 2008. The map (a) is derived from

5 Li et al. (2011).

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