

This discussion paper is/has been under review for the journal Hydrology and Earth System Sciences (HESS). Please refer to the corresponding final paper in HESS if available.

Extended power-law scaling of air permeabilities measured on a block of tuff

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Received: 16 July 2011 – Accepted: 5 August 2011 – Published: 15 August 2011

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Published by Copernicus Publications on behalf of the European Geosciences Union.

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Abstract

We use three methods to identify power law scaling of (natural) log air permeability data collected by Tidwell and Wilson (1999) on the faces of a laboratory-scale block of Topopah Spring tuff: method of moments (M), extended power-law scaling also known as Extended Self-Similarity (ESS) and a generalized version thereof (G-ESS). All three methods focus on q th-order sample structure functions of absolute increments. Most such functions exhibit power-law scaling at best over a limited midrange of experimental separation scales, or lags, which are sometimes difficult to identify unambiguously by means of M. ESS and G-ESS extend this range in a way that renders power-law scaling easier to characterize. Most analyses of this type published to date concern time series or one-dimensional transects of spatial data associated with a unique measurement (support) scale. We consider log air permeability data having diverse support scales on the faces of a cube. Our analysis confirms the superiority of ESS and G-ESS over M in identifying the scaling exponents $\xi(q)$ of corresponding structure functions of orders q , suggesting further that ESS is more reliable than G-ESS. The exponents vary in a nonlinear fashion with q as is typical of real or apparent (Guadagnini and Neuman, 2011; Guadagnini et al., 2011) multifractals. Our estimates of the Hurst scaling coefficient increase with support scale, implying a reduction in roughness (anti-persistence) of the log permeability field with measurement volume. ESS and G-ESS ratios between scaling exponents $\xi(q)$ associated with various orders q show no distinct dependence on support volume or on two out of three Cartesian directions (there being no distinct power law scaling in the third direction). The finding by Tidwell and Wilson (1999) that log permeabilities associated with all tip sizes can be characterized by stationary variogram models, coupled with our findings that log permeability increments associated with the smallest tip size are approximately Gaussian and those associated with all tip size scales show nonlinear (multifractal) variations in $\xi(q)$ with q , are consistent with a view of these data as a sample from a truncated version (tfBm) of self-affine fractional Brownian motion (fBm). Since in theory the scaling exponents, $\xi(q)$, of tfBm vary

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linearly with q we conclude, in accord with Neuman (2010a, b, 2011), that nonlinear scaling in our case is not an indication of multifractality but an artifact of sampling from tfBm. This allows us to explain theoretically how power law scaling is extended by ESS. It further allows us to identify the functional form and estimate all parameters of the corresponding tfBm based on sample structure functions of first and second orders. Our estimate of lower cutoff is consistent with a theoretical support scale of the data.

1 Introduction

The literature indicates (Neuman and Di Federico, 2003) that hydrogeologic variables exhibit isotropic and directional dependencies on scales of measurement (data support), observation (extent of phenomena such as a dispersing plume), sampling window (domain of investigation), spatial correlation (structural coherence), and spatial resolution (descriptive detail). Attempts to explain such scale dependencies have focused in part on observed and/or hypothesized power law behaviors of structure functions of variables such as hydraulic (or log hydraulic) conductivity (e.g. Painter, 1996; Liu and Molz, 1997a, b; Tennekoon et al., 2003), space-time infiltration (Meng et al., 2006), soil properties (Caniego et al., 2005; Zeleke and Si, 2006, 2007), electrical resistance, natural gamma ray and spontaneous potential (Yang et al., 2009) and sediment transport data (Ganti et al., 2009). Power law behavior means that a sample structure function

$$S_N^q(s) = \frac{1}{N(s)} \sum_{n=1}^{N(s)} |\Delta Y_n(s)|^q \quad (1)$$

of order- q (for simplicity we limit our mathematical exposition to one dimension) scales according to

$$S_N^q(s) \propto S^{\xi(q)} \quad (2)$$

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where $Y(x)$ is the variable of interest (assumed to be defined on a continuum of points x in space or time), $\Delta Y_n(s)$ is a measured increment $\Delta Y(s) = Y(x+s) - Y(x)$ of the variable over a separation distance (lag) s between two points on the x -axis, and $N(s)$ is the number of measured increments. When the scaling exponent (power) $\xi(q)$ varies linearly with q , $Y(x)$ is interpreted to form a self-affine (mono-fractal) random field and the slope H of the corresponding line is termed Hurst exponent. When the scaling exponent $\xi(q)$ is a nonlinear function of q , $Y(x)$ has traditionally been taken to form a multifractal field. A semi-empirical “universal” multifractal model due to Schertzer and Lovejoy (1987) relates $\xi(q)$ to the Hurst exponent via $H = \xi(1)$, as explained and illustrated by Seuront et al. (1999); some approximate H by $d\xi/dq$ near $q = 0$.

Neuman (2010a, 2011) has shown theoretically and Neuman (2010b) and Guadagnini et al. (2011) have demonstrated numerically that signals derived from additive processes subordinated to a truncated version (tfBm) of additive, self-affine fractional Brownian motion (fBm) scale in a manner similar to multifractals even as they differ from such multiplicative constructs in a fundamental way. Their work suggests that nonlinear variations in $\xi(q)$ with q need not represent multifractal scaling but could instead be an artifact of sampling from tfBm or fields subordinated to tfBm.

Power-law scaling is typically inferred from measured values of earth and environmental variables by the method of moments (M). This consists of calculating sample structure functions (1) for a finite sequence, q_1, q_2, \dots, q_n , of q values and for various separation lags. For each order q_i the logarithm of $S_N^{q_i}$ is related to $\log s$ by linear regression and the power $\xi(q_i)$ set equal to the slope of the regression line. Linear or near-linear variation of $\log S_N^{q_i}$ with $\log s$ is typically limited to intermediate ranges of separation scales, $s_l < s < s_u$, where s_l and s_u are theoretical or empirical lower and upper limits, respectively. Breakdown in power law scaling is attributed in the literature to noise at lags smaller than s_l and to undersampling at lags larger than s_u (Tessier et al., 1993). Yet noise-free signals subordinated to tfBm generated by Neuman (2010b) and Guadagnini et al. (2011) show power law breakdown at small and large lags even when sample sizes are large. This breakdown is caused by cutoffs which truncate the

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fields at small lags proportional to the measurement and/or resolution scale of the data, and at large lags proportional to the size of the sampling domain, regardless of noise or undersampling. Though nonlinear variation of $\xi(q)$ with q is also reproduced by the fractional Laplace model of Meerschaert et al. (2004; see Kozubowski et al., 2006, and Ganti et al., 2009), the latter does not include cutoffs and thus fails to reproduce observed breakdown in power law scaling at small and large lags.

Benzi et al. (1993a, b, 1996) discovered empirically that the range $s_l < s < s_u$ of lags over which velocities in fully developed turbulence (where Kolmogorov's dissipation scale is assumed to control s_l) scale according to Eq. (2) can be enlarged significantly, at both small and large lags, through a procedure they called Extended Self-Similarity (ESS). ESS arises from the observation that structure functions of different orders, n and m , computed for the same separation lag are related by

$$S^n(s) \propto S^m(s)^{\beta(n,m)} \quad (3)$$

where $\beta(n,m) = \xi(n)/\xi(m)$ is a ratio of scaling exponents. Benzi et al. (1996) introduced, and Nikora and Goring (2001) employed, a generalized form of ESS (G-ESS) according to which

$$G^{n,p}(s) \propto G^{n,q}(s)^{\rho(p,q,n)} \quad (4)$$

where

$$G^{n,p}(s) = \frac{S^p(s)}{S^n(s)^{p/n}} \quad G^{n,q}(s) = \frac{S^q(s)}{S^n(s)^{q/n}} \quad \rho(p,q,n) = \frac{\xi(p) - (p/n)\xi(n)}{\xi(q) - (q/n)\xi(n)} \quad (5)$$

The exponent $\rho(p,q,n)$ is a ratio between deviations of structure functions of order p and q , respectively, from linear (monofractal or self-affine) scaling. Chakraborty et al. (2010) cite the success of ESS in extending observed scaling ranges, and thus allowing more accurate empirical determinations of the functional exponent $\xi(q)$ for turbulent velocities. ESS has been reported to achieve similar results for diffusion-limited aggregates, natural images, kinetic surface roughening, fluvial turbulence, sand

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5 wave dynamics, Martian topography, river morphometry, gravel-bed mobility and atmospheric barometric pressure, low-energy cosmic rays, cosmic microwave background radiation, metal-insulator transition, irregularities in human heartbeat time series, turbulence in edge magnetized plasma of fusion devices and turbulent boundary layers of the Earth's magnetosphere (Guadagnini and Neuman, 2011). In all cases, ESS has revealed nonlinear variation of $\xi(q)$ with q . Whereas the literature has interpreted this to imply that ESS applies to multifractals, Guadagnini and Neuman have shown that Eq. (3) works equally well when applied to signals derived from additive processes subordinated to tfBm. As the latter are not multifractal, neither must be processes revealed by ESS (or any other method of analysis) to yield nonlinear variations in $\xi(q)$ with q .

10 In this paper we use three methods to identify power law scaling of log air permeability data collected by Tidwell and Wilson (1999) on the faces of a laboratory-scale cube of Topopah Spring tuff: method of moments (M) and extended power-law scaling via ESS and G-ESS. Most published analyses of extended power law scaling concern time series or one-dimensional transects of spatial data associated with a unique measurement (support) scale. We use instead data measured on diverse support scales and distributed in two or three dimensions across several faces of the cube. Our aim is to infer the scaling behavior of these data using all three methods, compare results among the methods and explore the dependence of corresponding scaling exponents on support scales and direction.

20 "In spite of several attempts to explain the success of ESS" cited by Chakraborty et al. (2010) the authors note that "the latter is still not fully understood and we do not know how much we can trust scaling exponents derived by ESS. It would be nice to have at least one instance for which ESS not only works, but does so for reasons we can rationally understand." Chakraborty et al. provide such a theoretical reason in the special context of one-dimensional Burgers equation. In contrast, they consider "the multifractal description of turbulence," with which ESS is commonly associated, to be "quite heuristic and arbitrary." We agree. After showing that our data behave in a manner consistent with those sampled from tfBm we provide in Appendix A a

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theoretical explanation of how ESS extends the power law scaling of such samples.

2 Previous analyses of experimental data

Tidwell and Wilson (1999) measured air permeabilities, k , on six faces of a block of Topopah Spring tuff (Fig. 1), extending 30 cm on each side, with the aid of a Multisupport Permeameter (MSP). Measurements were conducted at intervals of $\Delta = 0.85$ cm on a grid of 36×36 points along each face using four tip-seal sizes having inner radii $r_i = 0.15, 0.31, 0.63, 1.27$ cm and outer radii $2r_i$. As the precise nature and size of the support volume associated with each measurement is the subject of debate (Goggin et al., 1988; Molz et al., 2003; Tartakovsky et al., 2000; Neuman and Di Federico, 2003), we consider the inner radius of the tip-seal to represent a nominal measurement scale (data support) as proposed by Tidwell and Wilson (1999). We conclude from their analysis that measurements on face 6 of the block are less reliable than the rest and therefore limit our analysis below to those on faces 1–5.

Measured (natural) log permeability values, $Y = \ln k$, were found to have bi-modal frequency distributions particularly at larger tip sizes (Fig. 2 of Tidwell and Wilson, 1999). This was deemed by them to be consistent with the geologic structure of the tuff sample within which regions of high (associated with pumice fragments) and low (corresponding to solid matrix) permeability could be visually identified. Tidwell and Wilson were able to fit spherical models with nuggets to sample variograms on all faces of the cube for each tip radius. The variograms were found to be isotropic in the xy plane of Cartesian coordinates on face 1 of the cube but anisotropic in the xz and yz planes on faces 2–5, with estimated ranges in the z direction about one half of those in the x and y directions. Sill and range estimates decreased and increased, respectively, with tip seal inner radius. For additional details the reader is referred to the above authors.

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3 Identification of power low scaling

To evaluate sample structure functions for the experimental data of Tidwell and Wilson (1999) according to Eq. (1) we compute directional increments, ΔY , of $Y = \ln k$ at various separation lags (taken to be integer multiples of grid spacing, Δ , for each tip size) parallel to the x , y and z coordinates on the faces of the cube. Figure 2 depicts variations in ΔY associated with lag $s_x = 8.5$ cm along selected transects in the x direction on face 1 associated with the smallest and largest tip radii, $r_i = 0.15$ and 1.27 cm. Clearly, increasing the tip radius results in smoother and more persistent variability of the increments. Figure 3 shows frequency distributions of similar increments along all x -directional transects on multiple faces and Maximum Likelihood (ML) fits of Gaussian probability density functions (pdfs) to these distributions. Both frequency distributions are symmetric about zero with humps reflecting the bi-modal distributions of Y identified by Tidwell and Wilson. Increments corresponding to the smallest tip size appear to be closer to Gaussian than those corresponding to the largest tip size, consistent with their finding that Y becomes increasingly bimodal with tip size.

3.1 Analysis of face 1 data by method of moments

As lag increases the number $N(s)$ of incremental data along all transects of face 1 decreases from 1260 corresponding to $s_x = s_y = \Delta = 0.85$ cm to 36 corresponding to $s_x = s_y = 35 \times \Delta = 29.75$ cm. Figure 4 depicts $\log S_N^q(s_x)$ as functions of $\log s_x$ along all transects for $0.1 \leq q \leq 2.5$ at each tip size. We find it difficult to identify unambiguously a middle range of lags within which these relationships are linear, particularly in the case of relatively small tip sizes (e.g. Fig. 4a). We have done our best to do so by fitting regression lines to the data within several such ranges and adopting those that yield the highest coefficients of determination for each tip size. These ranges, identified in Fig. 4 by dashed vertical lines, are on the order of $2\Delta \leq s_x \leq 6\Delta$ or $1.7 \text{ cm} \leq s_x \leq 5.1 \text{ cm}$. The corresponding nonlinear variation of $\xi(q)$ with q for the largest tip size (based on data such as those in Fig. 4d) is depicted in Fig. 5. The solid line has slope $d\xi/dq|_{q=0} = 0.74$

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which, if taken to represent a Hurst exponent H , implies a persistent signal consistent with that depicted in Fig. 2b. Values of $\xi(q)$ in Fig. 5 start deviating from this solid line at about $q \approx 0.6$ to become asymptotically linear in q at about $q \geq 3.5$, as evidenced by the dotted line obtained through regression against these values. Results for other tip sizes and in the y direction (not reported) are qualitatively similar. Though such behavior would typically be interpreted to imply that increments of $\ln k$ are multifractal, we note that qualitatively similar scaling has been produced synthetically by Guadagnini and Neuman (2011, their Fig. 4) with a model in which Y is subordinated to tfBm, a truncated version of self-affine (monofractal) fBm.

3.2 Analysis of face 1 data by extended power law scaling

Replotting the data in Fig. 4d (corresponding to the largest tip size) as $\log S_N^q$ versus $\log S_N^{q-1}$ for $2.0 \leq q \leq 5.0$ (at intervals of 0.5) reveals much less ambiguous power law scaling over a much wider range of lags in Fig. 6. Equations of corresponding curves (regression lines on log-log scale) included in the figure are characterized by coefficients of determination, R^2 , that exceed 0.98 at all lags. Results of similar quality (not reported) have been obtained for all tip sizes and directions. The powers of the regression curves, representing $\beta(q, q-1)$ in Eq. (3), decrease asymptotically with q toward unity consistently with the asymptotic tendency of $\xi(q)$ in Fig. 5 toward linear variation with q . In Appendix A we explain this behavior theoretically for the special case of tfBm. In a manner patterned after Guadagnini and Neuman (2011) we adopt the value of $\xi(1)$ from Fig. 5 as computed by the method of moments, fit straight lines by regression to $\log S^q$ versus $\log S^p$ values corresponding to $p = q - \Delta q$ where $\Delta q = 0.1$ for $0.1 \leq q \leq 3$ and $\Delta q = 0.5$ for $3 < q \leq 5$ in ascending orders $q = 1.1, 1.2, \dots$ and descending orders $q = 0.9, 0.8, \dots$, set the slopes of these lines equal to $\xi(q)/\xi(q - \Delta q)$ according to Eq. (3), then compute $\xi(1.1), \xi(1.2), \xi(1.3), \dots$ in ascending order and $\xi(0.9), \xi(0.8), \xi(0.7), \dots$ in descending order from these ratios. Resulting values of $\xi(q)$ corresponding to the x and y directions on face 1, identified as ESS, are plotted versus q in Fig. 8.

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As $\xi(q)$ in Fig. 5 starts deviating from the solid line at approximately $q \approx 0.6$ we set $n = 0.5$ in Eq. (5) and plot in Fig. 7 $\log G^{n,q+1}(s_x)$ versus $\log G^{n,q}(s_x)$ for $q = 1.0, 1.5, 2.0, \dots, 4.0$ corresponding to the increments in Fig. 4d. Included in Fig. 7 are equations of curves fitted to these log-log relationships by linear regression and associated R^2 values. The figure reveals extended power law scaling with $R^2 \geq 0.98$ over virtually the entire range of lags. As in the earlier case of $\beta(q, q-1)$, the scaling ratios $\rho(q+1, q, n)$ diminish asymptotically toward unity as q increases. Similar behavior is observed in the case of other tip sizes. Resulting values of $\xi(q)$ corresponding to the x and y directions on face 1, computed in a manner analogous to that described in the previous paragraph and identified as G-ESS, are plotted versus q in Fig. 8.

Figure 8 juxtaposes values of $\xi(q)$ as functions of q within the range $0 \leq q \leq 5.0$, in the x and y directions of face 1, obtained for the largest tip size by the method of moments and two methods of extended power law scaling. We saw earlier that latter two methods are much less ambiguous than the first in helping one to identify and quantify power law scaling of structure functions at various orders q . As ESS requires only one reference value, $\xi(1)$, to compute $\xi(q)$ on the basis of $\beta(q, q - \Delta q)$ for any order q while G-ESS requires two such reference values, we consider the former more reliable than the latter.

Figure 9 shows that values of $\beta(q, q - \Delta q)$ and $\rho(q + \Delta q, q, n)$ are relatively insensitive to tip size and direction. The same is not true for the scaling exponent $\xi(q)$ which, as shown in Fig. 10, increases consistently with tip size. Though these results correspond to the x direction on face 1, they do not differ qualitatively from those corresponding to x and y on all five faces. This behavior translates into a consistent increase in the Hurst exponent H with tip size (from $H = 0.13$ for $r_i = 0.15$ cm to $H = 0.74$ for $r_i = 1.27$ cm), implying that averaging over larger and larger support volumes smoothes a signal and renders it more persistent.

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3.3 Analysis of multiple face data by extended power law scaling

Next we consider jointly the scaling of $Y = \ln k$ data from all five faces 1–5 of the cube along each Cartesian direction for each tip size, yielding 12 sets of three directional increments for 4 tip sizes. Figure 11 depicts log-log plots of $S_N^q(s_z)$ versus separation distance, s_z , along the z direction for $0.1 \leq q \leq 2.5$ corresponding to each tip size. In neither plot is it possible to identify an intermediate range of power law scaling, most likely due to the reduced range of the increments in this direction. We therefore omit incremental data in the z direction from further consideration in this paper. Structure functions in the x and y directions (not shown) display behaviors qualitatively similar to those noted earlier in the x direction on face 1 (Fig. 4). Figure 12 compares values of $\xi(q)$ obtained by each method on all available data with x -directional values obtained on face 1 via ESS. Whereas face 1 values in Fig. 8 show no significant difference between directions x and y , the multiface values in Fig. 12 do suggest a slight directional dependence revealed, most likely, by the relatively large size of this sample. In general, multiface values of $\xi(q)$ in Fig. 12 lie below the face 1 values in Fig. 8, reflecting the impact of sample size on the quantification of power law scaling.

As in the case of face 1, multiface values of $\beta(q, q - \Delta q)$ and $\rho(q + \Delta q, q, n)$ are seen in Fig. 13 to be relatively insensitive to tip size and direction.

We note that there is no conflict between the ability of Tidwell and Wilson (1999) to characterize Y for any tip size by means of a stationary variogram and our finding that order- q structure functions of Y exhibit power law scaling at intermediate lags with exponents that vary in a nonlinear fashion with q . Instead both, coupled with our finding that increments of Y associated with small tip sizes are approximately Gaussian, are consistent with a view of Y as a sample from tfBm (implying that Y is not multifractal). Such a sample is characterized by a truncated power variogram (Di Federico and Neuman, 1997) which is difficult to distinguish from stationary variogram models (Neuman et al., 2008) and exhibits power law scaling with exponents that are nonlinear in q at intermediate lags (Neuman, 2010a, b, 2011; Guadagnini et al., 2011). The former

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implies that Gaussian samples commonly characterized in the literature by stationary variograms may in fact represent truncated self-affine fields, the latter implies that such samples may in turn display apparent multifractality as does Y in this paper.

3.4 Model identification and parameter estimation

5 As shown by Eq. (A2) in Appendix A the q th-order structure function of tfBm is completely defined by q and the ensemble (theoretical) truncated power variogram (TPV) $\gamma^2(s; \lambda_l, \lambda_u)$. Since increments of Y associated with the smallest tip size have a near-Gaussian distribution, one should be able to estimate the parameters of this variogram by fitting such theoretical structure functions to their sample counterparts, S_N^q ,
 10 for $r_i = 0.15$ cm. As the number of data N needed to obtain stable S_N^q values increases with q , we limit our estimation of parameters to structure functions S_N^1 and S_N^2 of orders $q = 1, 2$.

Equations (A4)–(A7) in Appendix A make clear that a TPV is defined by four parameters: the Hurst exponent H , coefficient A , upper cutoff λ_u and lower cutoff λ_l . We found
 15 earlier from the slope of $\xi(q)$ at small q that, for incremental data on face 1, $H = 0.13$ in the x direction and $H = 0.09$ in the y direction while, for incremental data on multiple faces, $H = 0.08$ in the x direction and $H = 0.09$ in the y direction. All four parameters are linked by the relationship

$$A = \frac{2H\sigma^2}{(\lambda_u^{2H} - \lambda_l^{2H})} \quad (6)$$

20 where σ^2 is the sill (asymptotic plateau) of the variogram $\gamma^2(s; \lambda_l, \lambda_u)$. We expect the estimate of this sill to not differ significantly from the sample variance of the Y data.

We estimate parameters on the basis of sample variograms, $\gamma^{2*}(s; \lambda_l, \lambda_u)$, of Y data computed from sample structure functions of first and/or second order, respectively, via

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$$\gamma^{2*}(s; \lambda_l, \lambda_u) = \frac{\pi}{4} \left(S_N^1(s) \right)^2 \quad \text{and/or} \quad \gamma^{2*}(s; \lambda_l, \lambda_u) = \frac{S_N^2(s)}{2} \quad (7)$$

according to Eq. (A2). We estimate the sill, σ^2 , by averaging values of $\gamma^{2*}(s; \lambda_l, \lambda_u)$ corresponding to large lags, s , obtained from S_N^1 and/or S_N^2 in this manner. We then estimate the cutoffs (and A) through a maximum likelihood (ML) fit of $\gamma^2(s; \lambda_l, \lambda_u)$ to $\gamma^{2*}(s; \lambda_l, \lambda_u)$ where the first is a TPV model based either on Gaussian or on exponential modes as defined in Eqs. (A4)–(A7). The ML procedure consists of minimizing the log likelihood criterion (Carrera and Neuman, 1986)

$$\text{NLL} = \frac{J}{\sigma_Y^2} + n \ln \sigma_Y^2 + \ln |\mathbf{V}| + n \ln 2\pi; \quad J = \left(\hat{\gamma}^2 - \gamma^{2*} \right)^T \mathbf{V}^{-1} \left(\hat{\gamma}^2 - \gamma^{2*} \right) \quad (8)$$

with respect to λ_u and λ_l subject to Eq. (6). Here $\hat{\gamma}^2$ and γ^{2*} are vectors of n discrete $\gamma^2(s; \lambda_l, \lambda_u)$ and $\gamma^{2*}(s; \lambda_l, \lambda_u)$ values, respectively, T denotes transpose, $\mathbf{C}_Y = \sigma_Y^2 \mathbf{V}$ where \mathbf{C}_Y is the covariance matrix of errors in γ^{2*} (resulting from log permeability measurement errors), σ_Y^2 is estimated during inversion according to

$$\sigma_Y^2 = \frac{J_{\min}}{n} \quad (9)$$

where J_{\min} is the minimum of J , and \mathbf{V} is a known symmetric positive-definite matrix. For simplicity we take errors in γ^{2*} to be uncorrelated and set \mathbf{V} equal to the identity matrix.

Applying the above procedure to face 1 yields a sill of 4.48 based on S_N^1 as well as on S_N^2 of increments parallel to the x-axis, 3.64 based on S_N^1 and 3.88 on S_N^2 of increments parallel to the y-axis, the variance of the corresponding Y data being 4.06.

Applying the above procedure jointly to faces 1, 2 and 4 (where incremental data in the x direction are available, see Fig. 1) yields a sill of 3.52 based on S_N^1 and 3.77 based on S_N^2 of increments parallel to the x-axis, the corresponding variance of Y being 3.77;

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applying it to faces 1, 3 and 5 (where incremental data in the y direction are available, see Fig. 1) yields 3.52 based on S_N^1 and 3.79 on S_N^2 of increments parallel to the y-axis, the corresponding variance of Y being 3.91 while that of all Y data on faces 1–5 is 3.79. We conclude that to obtain consistent estimates of σ^2 it is best to consider jointly all data from faces 1–5 as we do below.

Due to the irregular behavior of $S_N^1(s)$ and $S_N^2(s)$ at large lags (Fig. 4a) we limit our ML estimation of cutoffs (and A) to lags in the range $\Delta \leq s \leq 13\Delta$ so that $n = 13$. Table 1 lists parameter estimates and corresponding 95% confidence intervals for TPV models consisting of Gaussian and exponential modes obtained on the basis of S_N^1 , S_N^2 and both with x- and y-directional increments. The table also lists J_{\min} , NLL, the determinant $|\mathbf{Q}|$ of the covariance matrix \mathbf{Q} of λ_u and λ_l estimation errors, and the Bayesian model discrimination criterion KIC (Kashyap, 1982)

$$\text{KIC} = \text{NLL} + M \ln\left(\frac{n}{2\pi}\right) - \ln|\mathbf{Q}| \quad (10)$$

where $M = 2$ is the number of parameters. Values of quantities obtained on the basis of S_N^1 , S_N^2 and both are seen to be mutually consistent. Though estimates of λ_u in the x direction exceed those in the y direction by about 25–30%, we hesitate to interpret this as anisotropy due to their relatively large uncertainty. Figure 14a and b compare sample x- and y-directional variogram values, respectively, based on S_N^1 , S_N^2 and S_N^1 and S_N^2 jointly with variogram models calibrated against these values.

Whereas values of NLL corresponding to TPV models based on Gaussian and exponential modes are similar, those of KIC show a preference for exponential modes. Adopting the latter while considering S_N^1 and S_N^2 jointly yields $\lambda_u = 1.65$ cm in the x direction and $\lambda_u = 1.31$ cm in the y direction with an average of 1.48 cm. These correspond to ratios $\mu = \lambda_u/L$ of upper cutoff to block size L equal to 0.055 in the x direction and 0.044 in the y direction with an average of 0.049. Corresponding estimates of the lower cutoff λ_l are 6.8×10^{-2} cm in the x direction and 1.2×10^{-1} cm in the y direction with an average of 9.4×10^{-2} cm. Adopting the suggestion of Di Federico and Neuman (1997) that $\mu = \lambda_u/L = \lambda_l/l_m$ yields support (measurement) scales $l_m = 1.24$ cm in the x direction

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and 2.69 cm in the y direction with an average of 1.88 cm. The latter is about 12 times the inner radius of the MSP. Albeit one should consider all the approximations involved in this estimate, we note that it is consistent with a definition of MPS support volume by Tartakovsky et al. (2000) as a region containing 90 % of total gas flow (see their Fig. 6).

5 Estimates of μ and l_m for all cases are listed in Table 2.

4 Conclusions

Our work leads to the following conclusions:

1. Natural log air permeability data collected by Tidwell and Wilson (1999) on the faces of a laboratory-scale block of Topopah Spring tuff, at four scales of measurement (support), exhibit power law scaling at intermediate lags in two out of three Cartesian directions. Scaling exponents vary in a nonlinear fashion with the order q of corresponding structure functions in a manner typical of multifractals.
2. Identification of this nonlinear power law scaling was greatly enhanced by a method of analysis that extend its range to virtually all lags (Guadagnini and Neuman, 2011) known as Extended Self-Similarity (ESS) and a generalized version thereof (G-ESS).
3. Most analyses of extended power law scaling published to date concern time series or one-dimensional transects of spatial data associated with a unique measurement (support) scale. We considered log air permeability data having diverse support scales and distributed in two or three dimensions across several faces of a cube.
4. Our estimates of the Hurst scaling exponent were found to increase with support scale, implying a reduction in roughness (anti-persistence) of the log permeability field with measurement volume.

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Appendix A

Analytical formulation of tfBm structure functions

Let $G(x; \lambda_l, \lambda_u)$ be truncated fractional Brownian motion (tfBm) as defined by Neuman (2010a) where x is a generic space (or time) coordinate and λ_l, λ_u are lower and upper cutoff scales, respectively. Central q th-order moments of absolute values of corresponding zero-mean increments

$$\Delta G(s; \lambda_l, \lambda_u) = G(x + s; \lambda_l, \lambda_u) - G(x; \lambda_l, \lambda_u) \quad (\text{A1})$$

are given by

$$S^q = \langle |\Delta G(s; \lambda_l, \lambda_u)|^q \rangle = \left[\sqrt{2\gamma^2(s; \lambda_l, \lambda_u)} \right]^q (q-1)!! \begin{cases} \sqrt{2/\pi} & \text{if } q \text{ is odd} \\ 1 & \text{if } q \text{ is even} \end{cases} \quad q = 1, 2, \dots, n \quad (\text{A2})$$

where s is separation scale or lag and $\gamma^2(s; \lambda_l, \lambda_u)$ is the variogram of $G(x; \lambda_l, \lambda_u)$, i.e.

$$\gamma^2(s; \lambda_l, \lambda_u) = \frac{1}{2} \langle \Delta G(s; \lambda_l, \lambda_u)^2 \rangle. \quad (\text{A3})$$

The latter is given by (Neuman, 2010a)

$$\gamma^2(s; \lambda_l, \lambda_u) = \gamma_j^2(s; \lambda_u) - \gamma_j^2(s; \lambda_l); \quad \gamma_j^2(s; \lambda_m) = \sigma^2(\lambda_m) \rho_j(s/\lambda_m) \quad (\text{A4})$$

where

$$\sigma^2(\lambda_m) = A \lambda_m^{2H} / 2H \quad (\text{A5})$$

$$\rho_1(s/\lambda_m) = \left[1 - \exp\left(-\frac{s}{\lambda_m}\right) + \left(\frac{s}{\lambda_m}\right)^{2H} \Gamma\left(1 - 2H, \frac{s}{\lambda_m}\right) \right] \quad 0 < H < 0.5 \quad (\text{A6})$$

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$$\rho_2(s/\lambda_m) = \left[1 - \exp\left(-\frac{\pi s^2}{4 \lambda_m^2}\right) + \left(\frac{\pi s^2}{4 \lambda_m^2}\right)^H \Gamma\left(1-H, \frac{\pi s^2}{4 \lambda_m^2}\right) \right] \quad 0 < H < 1 \quad (A7)$$

A is a coefficient, H is a Hurst exponent ($0 < H < 1$), $i = 1$ for tfBm with modes (defined in Neuman, 2010a) having exponential autocorrelation functions and $i = 2$ for modes having Gaussian autocorrelation functions. Figure A1 compares TPVs based on Gaussian modes with $A = 1$, $H = 0.3$, $\lambda_1 = 10$ and four values of λ_u ($= 10^4$, 10^3 , 5×10^2 , 10^2) with a power variogram (PV) $\gamma^2(s) = A_2 s^{2H}$ where $A_2 = A(\pi/4)^H \Gamma(1-H)/2H$. The slopes of the TPV and PV coincide in a midrange of lags (labeled Zone II) but not in the outlying ranges of small and large lags (labeled Zone I and III, respectively). This break in power law scaling at small and large lags is due entirely to the presence of lower and upper cutoffs, respectively, being unrelated to noise or oversampling which play no role in Fig. A1 (Neuman, 2010a). It follows that estimating H as the slope of the variogram on log-log scale is valid at intermediate lags but not at small and large lags which would lead, respectively, to over- and under-estimation of its value.

For a PV Eq. (A2) takes the form

$$S^q = \langle |\Delta G(s; \lambda_l, \lambda_u)|^q \rangle = (q-1)!! \left[\sqrt{2A_i} \right]^q s^{qH} \begin{cases} \sqrt{2/\pi} & \text{if } q \text{ is odd} \\ 1 & \text{if } q \text{ is even} \end{cases} \quad q = 1, 2, \dots, n \quad (A8)$$

rendering a log-log plot of S^q versus s linear with constant slope qH . As in the case of $q = 2$, the slopes of corresponding truncated structure functions are similar in the midrange of lags but larger and smaller, respectively, at small and large lags.

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From Eq. (A2) it follows that the ratio between structure functions of order $q+1$ and q is

$$\frac{S^{q+1}}{S^q} = \begin{cases} q\sqrt{\pi}\sqrt{\gamma^2(s;\lambda_l,\lambda_u)} & \text{if } q \text{ is odd} \\ \frac{2}{\sqrt{\pi}}\sqrt{\gamma^2(s;\lambda_l,\lambda_u)} & \text{if } q \text{ is even} \end{cases} \quad q = 1, 2, \dots, n \quad (\text{A9})$$

which is linear in q when q is odd and independent of q when q is even. Using Eq. (A2) to express $\gamma^2(s;\lambda_l,\lambda_u)$ as a function of S^q and substituting into Eq. (A9) yields, after some manipulation,

$$S^{q+1} = \begin{cases} q\sqrt{\frac{\pi}{2}} \left[\sqrt{\frac{\pi}{2}} \frac{1}{(q-1)!!} \right]^{\frac{1}{q}} [S^q]^{1+\frac{1}{q}} & \text{if } q \text{ is odd} \\ \sqrt{\frac{2}{\pi}} \left[\frac{1}{q!!} \right]^{\frac{1}{q}} [S^q]^{1+\frac{1}{q}} & \text{if } q \text{ is even} \end{cases} \quad q = 1, 2, \dots, n \quad (\text{A10})$$

This makes clear that S^{q+1} is linear in S^q on log-log scale regardless of what functional form does $\gamma^2(s;\lambda_l,\lambda_u)$ take. The slope of this line decreases asymptotically from 2 at $q = 1$ toward 1 as $q \rightarrow \infty$. Equation (A10) helps explain why ESS seems to work better than the standard method of moments in identifying and quantifying power-law scaling of earth and environmental data.

Acknowledgements. This work was supported in part through a contract between the University of Arizona and Vanderbilt University under the Consortium for Risk Evaluation with Stakeholder Participation (CRESP) III, funded by the US Department of Energy. Funding from the Politecnico di Milano (GEMINO, Progetti di ricerca 5 per mille junior) is also acknowledged. We are grateful to Vince Tidwell for sharing with us the experimental data-base.

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Table 1. Calibration results, main statistics and Model quality criteria. The 95 % confidence intervals of the parameter estimates are reported in parenthesis.

Only S_N^1 data				
	x-axis		y-axis	
Modes	Gaussian	Exponential	Gaussian	Exponential
λ_u [cm]	2.82 (1.84–4.56)	1.65 (0.21–3.10)	2.15 (1.41–2.91)	1.27 (0.55–1.98)
λ_l [cm]	6.1×10^{-4} (0– 6.5×10^{-3})	9.2×10^{-2} (0– 3.8×10^{-3})	8.9×10^{-3} (0– 4.3×10^{-2})	1.7×10^{-1} (0– 4.1×10^{-1})
A [cm $^{-2H}$]	0.64	1.41	0.88	2.01
J_{\min}	0.12	0.12	0.04	0.04
σ_y^2	9.55×10^{-3}	9.49×10^{-3}	2.88×10^{-3}	3.25×10^{-3}
NLL	–23.58	–23.65	–39.16	–37.57
$ Q $	1.24×10^{-6}	8.26×10^{-4}	4.27×10^{-6}	1.15×10^{-4}
KIC	–8.53	–15.10	–25.34	–27.05

Only S_N^2 data				
	x-axis		y-axis	
Modes	Gaussian	Exponential	Gaussian	Exponential
λ_u [cm]	2.73 (1.04–4.43)	1.64 (0.21–3.07)	2.14 (1.27–2.99)	1.26 (0.47–2.04)
λ_l [cm]	2.3×10^{-5} (0– 5.6×10^{-4})	4.8×10^{-2} (0– 2.5×10^{-1})	2.5×10^{-4} (0– 3.0×10^{-3})	8.4×10^{-2} (0– 2.8×10^{-1})
A [cm $^{-2H}$]	0.61	1.29	0.74	1.70
J_{\min}	0.10	0.10	0.03	0.04
σ_y^2	7.97×10^{-3}	7.76×10^{-3}	2.68×10^{-3}	2.91×10^{-3}
NLL	–25.93	–26.27	–40.10	–39.04
$ Q $	6.26×10^{-9}	3.59×10^{-4}	3.44×10^{-8}	8.37×10^{-5}
KIC	–5.58	–16.88	–21.46	–28.20

S_N^1 and S_N^2 data jointly				
	x-axis		y-axis	
Modes	Gaussian	Exponential	Gaussian	Exponential
λ_u [cm]	2.78 (0.96–4.61)	1.65 (0.12–3.18)	2.19 (0.71–3.66)	1.31 (0–2.61)
λ_l [cm]	1.5×10^{-4} (0– 2.4×10^{-3})	6.8×10^{-2} (0– 3.3×10^{-1})	2.0×10^{-3} (0– 2.4×10^{-2})	1.2×10^{-1} (0– 4.9×10^{-1})
A [cm $^{-2H}$]	0.62	1.35	0.80	1.78
J_{\min}	0.63	0.63	0.60	0.61
σ_y^2	2.44×10^{-2}	2.43×10^{-2}	2.30×10^{-2}	2.33×10^{-2}
NLL	–22.77	–22.91	–24.28	–23.97
$ Q $	2.12×10^{-7}	9.42×10^{-4}	8.86×10^{-6}	1.16×10^{-3}
KIC	–4.56	–13.11	–9.80	–14.37

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Table 2. Multiple faces data. Estimates of $\mu = \lambda_U/L$ and the associated support scale l_m .

Data	μ				l_m [cm]			
	x-axis		y-axis		x-axis		y-axis	
	Gauss	Exp	Gauss	Exp	Gauss	Exp	Gauss	Exp
S_N^1	0.094	0.055	0.072	0.042	0.01	1.68	0.00	4.10
S_N^2	0.091	0.055	0.061	0.042	0.00	0.87	0.02	2.01
S_N^1 and S_N^2 jointly	0.093	0.055	0.073	0.044	0.00	1.24	0.03	2.69

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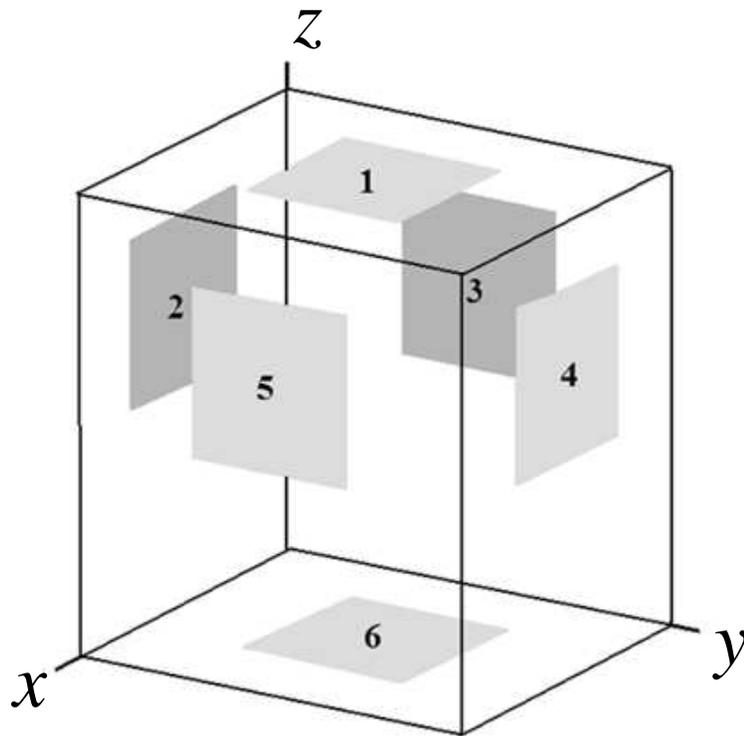


Fig. 1. Scheme of block (size: $81 \times 74 \times 63 \text{ cm}^3$) of Topopah Spring tuff sample. Faces of size $30 \times 30 \text{ cm}^2$ where MSP measurements were taken are highlighted in gray.

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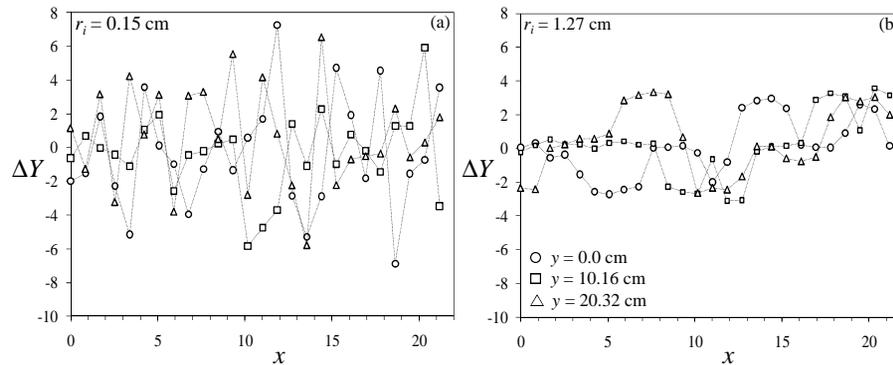


Fig. 2. Increments, ΔY ($s_x = 8.5$ cm), versus position, x , along three transects on face 1 ($y = 0, 10.16, 20.32$ cm) for **(a)** $r_i = 0.15$ cm and **(b)** $r_i = 1.27$ cm.

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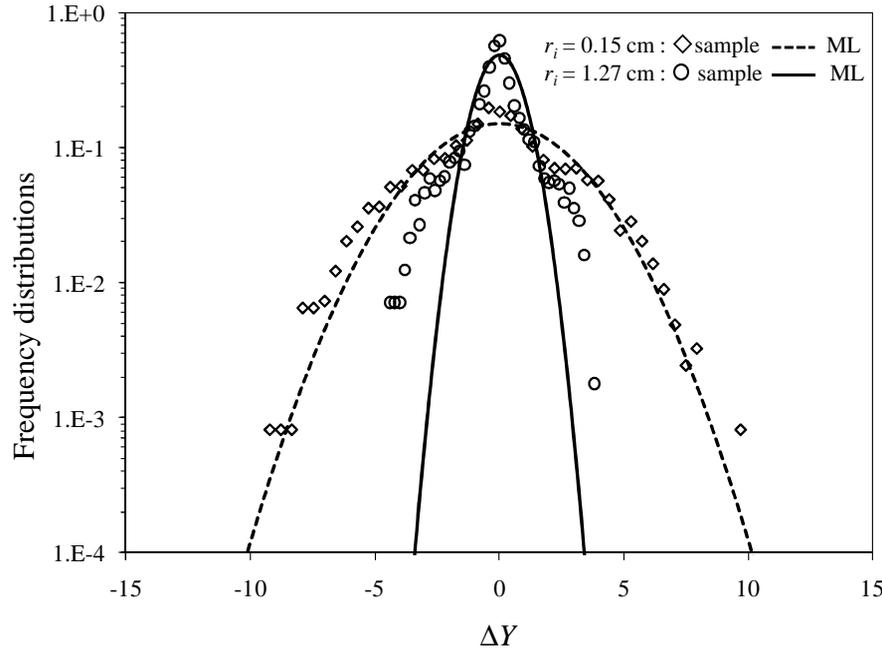


Fig. 3. Frequency distributions of ΔY ($s_x = 8.5$ cm) on multiple faces and $r_i = 0.15; 1.27$ cm (symbols). ML fits of Gaussian probability density functions are also reported (lines).

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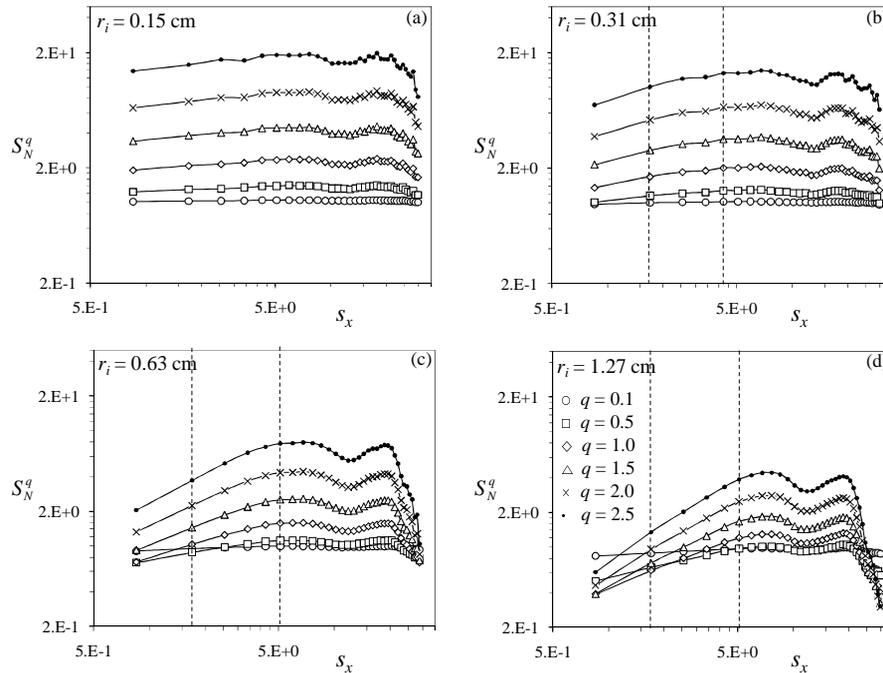


Fig. 4. Sample structure functions of absolute increments of various orders q versus lag along x direction on face 1 and **(a)** $r_i = 0.15$ cm, **(b)** $r_i = 0.31$ cm, **(c)** $r_i = 0.63$ cm, **(d)** $r_i = 1.27$ cm. Dashed vertical lines delineate ranges of lags within which power law scaling is noted.

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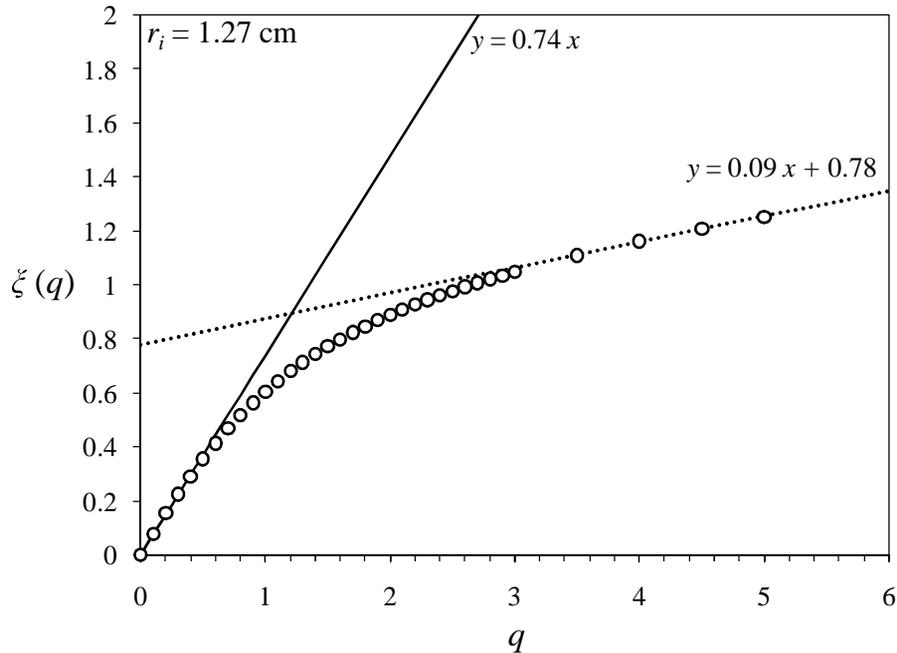


Fig. 5. $\xi(q)$ versus q evaluated for $r_i = 1.27 \text{ cm}$ on face 1 along x-axis. Continuous line has slope similar to $\xi(q)$ near $q = 0$. Dashed line has slope similar to $\xi(q)$ for $q \geq 3.5$.

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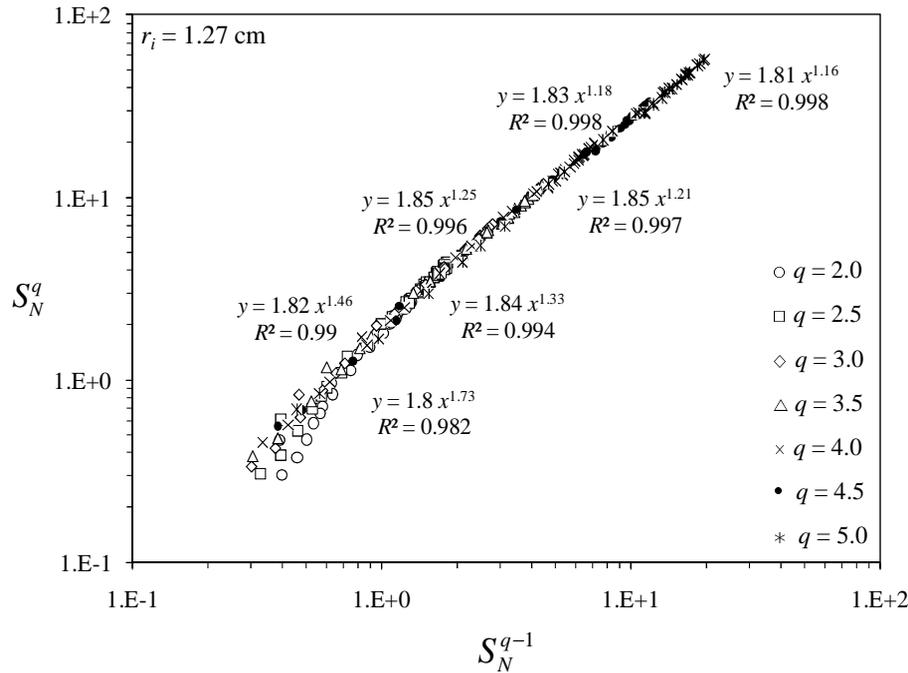


Fig. 6. S_N^q versus S_N^{q-1} for $2.0 \leq q \leq 5.0$ and $r_i = 1.27 \text{ cm}$ evaluated on face 1 along x-axis. Linear regression equations and relative regression coefficients (R^2) are also reported.

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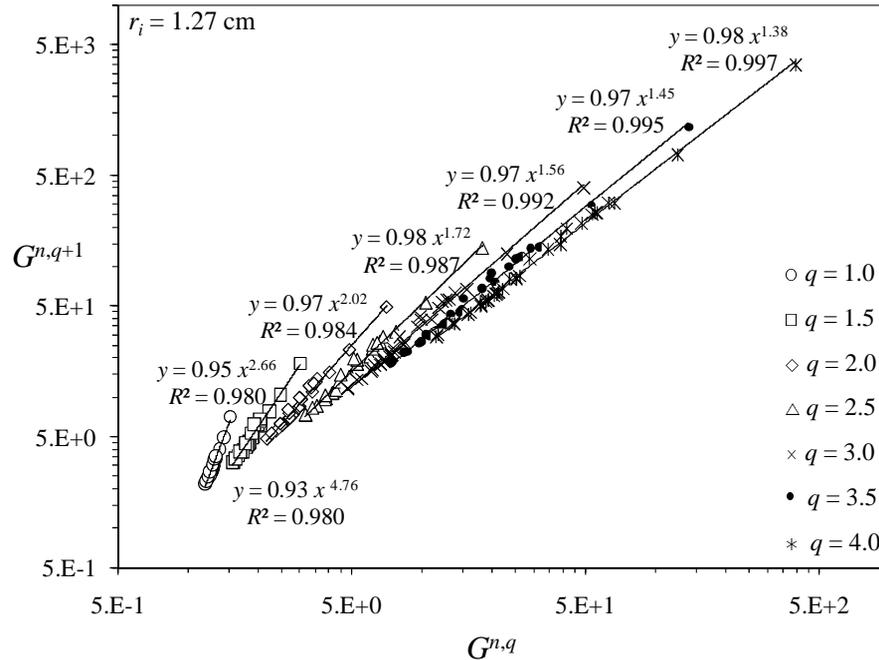


Fig. 7. $G^{n,q+1}$ versus $G^{n,q}$ for $n = 0.5, 1.0 \leq q \leq 4.0$, $r_i = 1.27$ cm evaluated on face 1 along x-axis. Linear regression equations and relative regression coefficients (R^2) are also reported.

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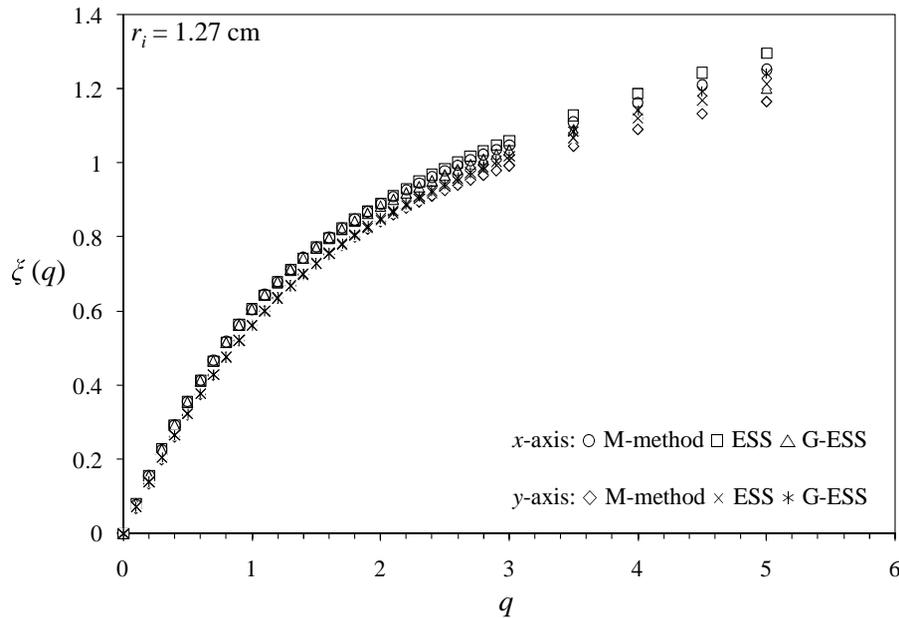


Fig. 8. $\xi(q)$ versus q evaluated for $r_i = 1.27 \text{ cm}$ on face 1 in x and y directions.

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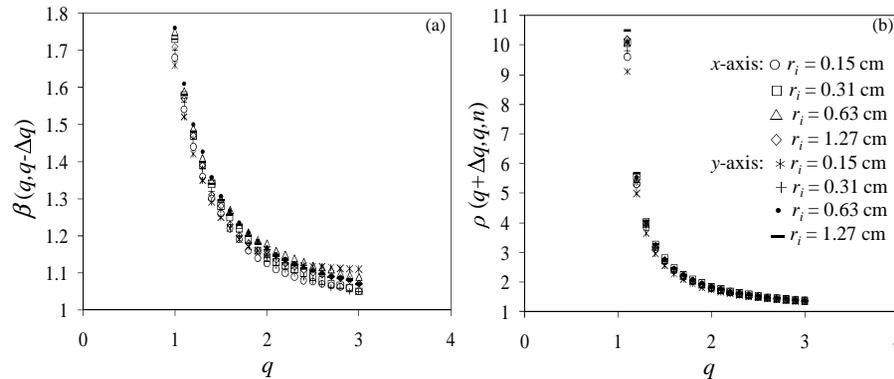


Fig. 9. (a) $\beta(q, q - \Delta q)$ and (b) $\rho(q + \Delta q, q, n = 0.5)$ versus q evaluated on face 1 in x and y directions and various r_i .

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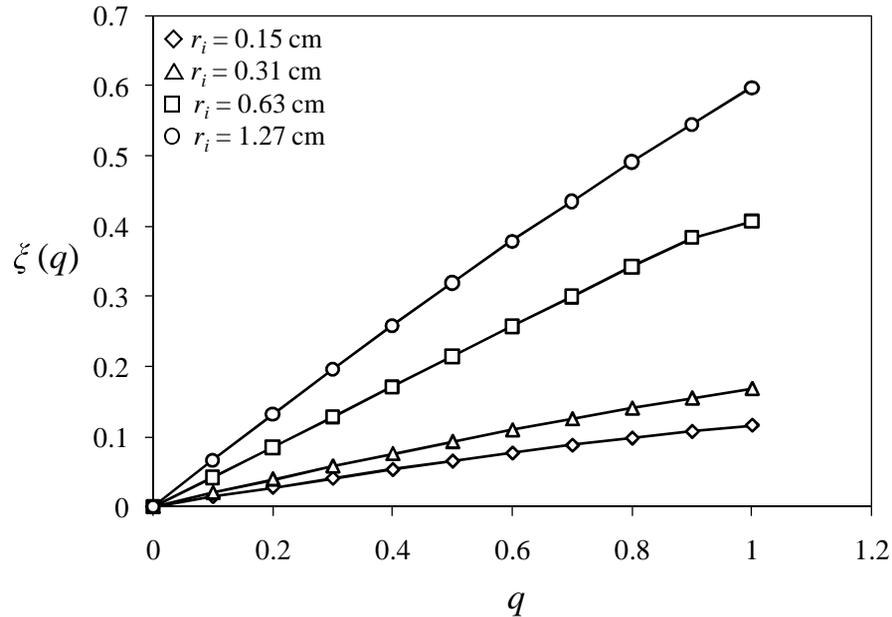


Fig. 10. ESS estimates of $\xi(q)$ versus q evaluated on face 1 in x direction and various r_i .

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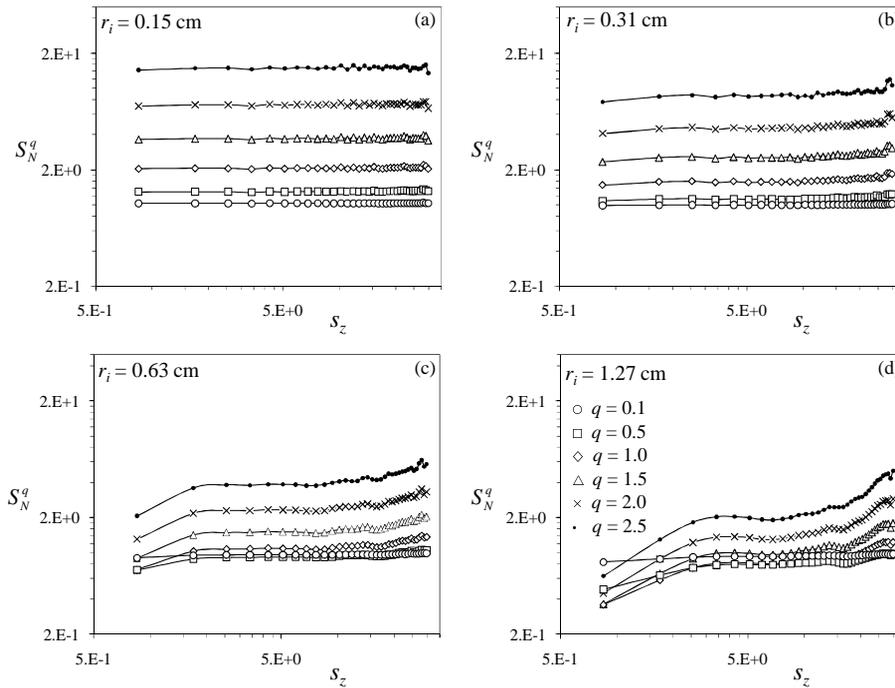


Fig. 11. Sample structure functions of absolute increments of various orders q versus lag in z direction and **(a)** $r_i = 0.15$ cm, **(b)** $r_i = 0.31$ cm, **(c)** $r_i = 0.63$ cm, **(d)** $r_i = 1.27$ cm.

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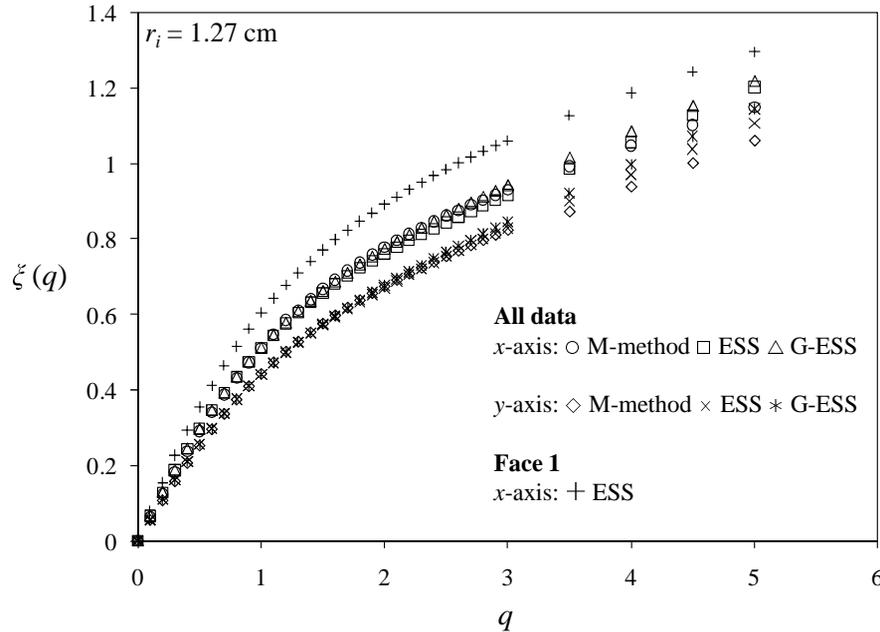


Fig. 12. $\xi(q)$ versus q evaluated for $r_i = 1.27 \text{ cm}$ using all the available data in x and y directions. ESS estimates obtained in x direction on face 1 are included for comparison.

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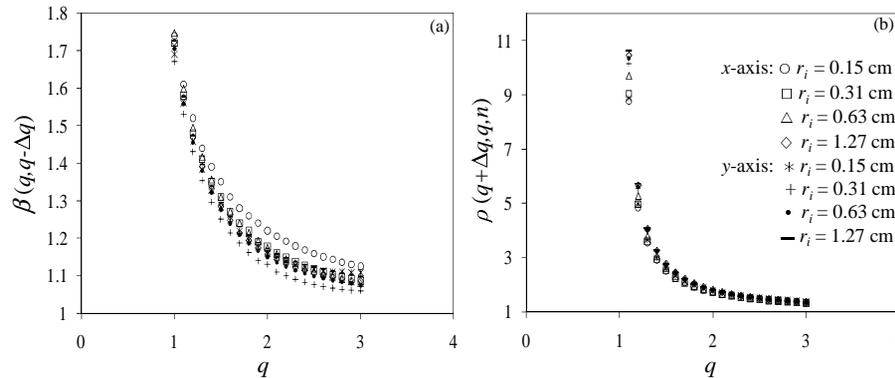


Fig. 13. (a) $\beta(q, q - \Delta q)$ and (b) $\rho(q + \Delta q, q, n = 0.5)$ versus q evaluated using all available data in x and y directions and various r_i .

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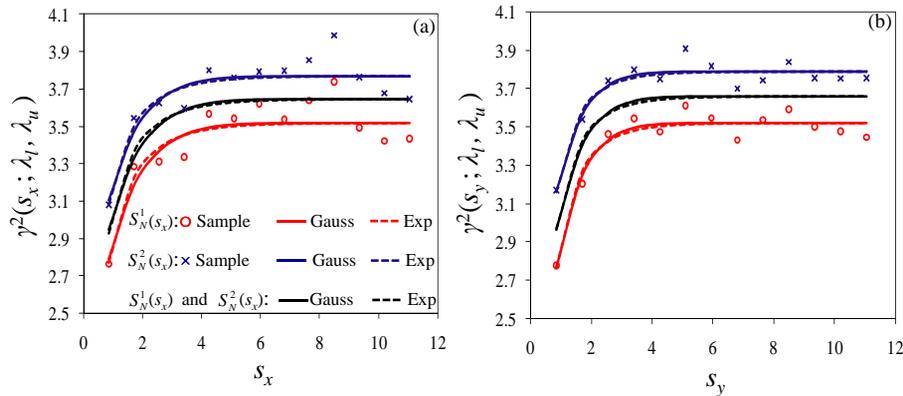


Fig. 14. Variograms obtained from multiple faces data in **(a)** x (faces 1, 2, 4) and **(b)** y (faces 1, 3, 5) directions, on the basis of S_N^1 (o) and S_N^2 (x). Estimated variograms are also reported with continuous (Gaussian modes) and dashed (exponential modes) lines. Black lines correspond to estimated variograms obtained on the basis of S_N^1 and S_N^2 jointly.

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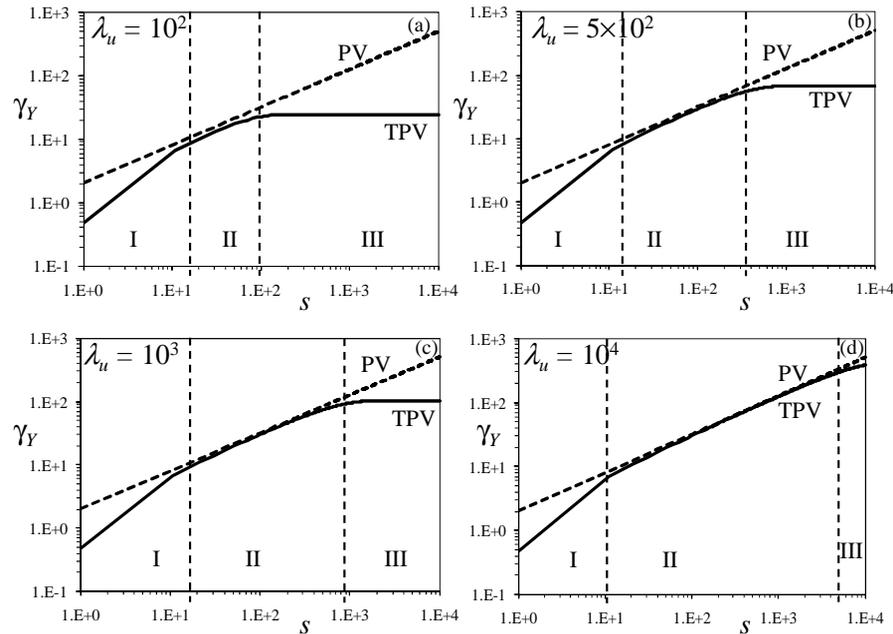


Fig. A1. Power variogram (dashed curves) and truncated power variogram (continuous curves) evaluated with $A = 1, H = 0.3, \lambda_l = 10$ and $\lambda_u =$ (a) 10^2 (b) 5×10^2 (c) 10^3 (d) 10^4 .

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