



## Abstract

Climate is often defined in terms of discrete classes. Here I use bivariate colour mapping to show that the global distribution of Köppen-Geiger climate classes can largely be reproduced by combining the simple means of two key states of the climate system (i.e., air temperature and relative humidity). This allows for a classification that is not only continuous in space, but can be applied at and transferred between timescales ranging from minutes to decades.

## 1 Introduction

According to a popular phrase, we are told that “climate is what you expect, weather is what you get”. Ideally, one would therefore rigorously define climate based on expected (i.e., mean) values of climate variables  $X_i$  only:

$$\text{Climate type} = f(E[X_1], E[X_2], \dots). \quad (1)$$

Such a definition can be applied at any temporal (and spatial) scale ranging from minutes (provided  $X_i$  is a continuous variable) to decades and could link short-term climate realizations and extremes to average conditions in that region or elsewhere. Here, I will explore the potential of such classification.

Current classification systems are often scale-invariant and explicitly define their resolution in time and space (i.e., through a limited number of classes). The widely used Köppen-Geiger system, for instance, has a pre-defined number of classes and utilizes information on long-term averages on both yearly and monthly timescales. As a result, the Köppen-Geiger system accounts for effects of seasonality but variations on other timescales that are relevant to climate and ecosystem functioning are ignored (e.g., diurnal temperature range, decadal variations, El Niño). Discrete climate classes imply that changes in the distribution of climate zones can only be detected along climate

**HESSD**

8, 5733–5742, 2011

## Continuous climate classification

A. J. Teuling

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



class edges (for examples see Kim et al., 2008; Rubel and Kottek, 2010). In addition, the Köppen-Geiger system mixes statistics of a continuous atmospheric state (air temperature) and a discontinuous flux field with stochastic properties (precipitation). And while the Köppen-classification has been derived manually to predict vegetation patterns rather than climate itself, it does not make optimal use of the information contained in the meteorological observations (Cannon, 2011).

## 2 Towards spatial continuity

Considering these disadvantages, it is clear that the earth system and climate sciences community could benefit from a spatially continuous and conceptually more consistent classification of climate. It is also clear that any climate classification should at least contain measures of temperature ( $T$ ) and water availability. Rather than the amount of water that falls during intermittent rain events (as in the Köppen classification) or that is stored in the soil (as in the Thornthwaite classification), I use screen-level relative humidity (RH) as a robust and well-defined measure of water availability in the environment:

$$\text{Climate type} = f(E[T], E[\text{RH}]). \quad (2)$$

Note that  $T$  and RH are defined for any time interval. For my analysis I use gridded observations (10 min spatial resolution) for the period 1961–1990 compiled by the Climate Research Unit (e.g. New et al., 2002; Mitchell and Jones, 2005).

Indeed, RH separates grid cells with classes that have similar average temperature but different rainfall characteristics, such as BWh, BSh, As/Aw and Am/Af (Fig. 1). Similarly, the different C, D, and E classes show a preference for a particular subspace. Note that the dependency on RH is indirect since the link between the amount of rain during discrete rain events and the yearly average RH depends also on the re-evaporation of rainwater into the atmosphere.

## Continuous climate classification

A. J. Teuling

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



---

**Continuous climate classification**A. J. Teuling

---

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

While conceptually straightforward, visualization of such classification requires both  $T$  and RH to be plotted simultaneously. This can be achieved by a technique called bivariate colour mapping, in which every colour on the map corresponds not to a single value of a variable as in conventional colour mapping, but rather to a unique combination of two variables. Bivariate colour mapping can be an effective method to display how fields of two different variables co-vary in space. Examples of the application of bivariate colour maps to earth system sciences can be found in Albani et al. (2006), Teuling et al. (2009), and Miralles et al. (2011). For more information on bivariate colour mapping and construction of colour legends I refer to Teuling et al. (2011).

Figure 2a shows the current distribution of climate according to the Köppen-Geiger classification as derived by Kottek et al. (2006). The colour for each climate class is selected based on its mean position in the  $T$ , RH-space (Fig. 1). In this way, the global patterns can be directly compared to a map in which distribution of mean temperature and relative humidity have been plotted using bivariate colour mapping with a limited number of colours (Fig. 2b). The number of colours ( $4 \times 4$ ) has been chosen such that upon visual inspection the class boundaries roughly align with those in Fig. 2a. However, no optimization has been performed, the classes are equally-spaced in the  $T$  and RH space, and the resulting number of classes is different from the number in the Köppen-Geiger classification.

### 3 Linking weather and climate

In spite of these limitations, the resulting maps are surprisingly similar, indicating that in addition to temperature, the yearly average rainfall as well as its seasonal distribution are reflected in the average relative humidity. Not only are the boundaries along wet-dry and warm-cold transitions well captured, even complex gradients, such as the combination of a north-south temperature gradient with a east-west humidity gradient in North-America, are captured. Differences occur over the Tibetan plateau, where the low humidity is not reflected in the Köppen-Geiger map. Thus, by combining average

temperature and relative humidity, the same global climate patterns emerge as those obtained by the much more complex Köppen-Geiger classification. It should be noted, however, that these maps cannot readily be compared in a quantitative manner since this would require the difference between two colours (with 3 degrees of freedom) to be expressed in a single number. An evaluation in the  $T, RH$ -space is provided by Fig. 1.

An important advantage of the bivariate map (Fig. 2b) over the Köppen-Geiger classification (Fig. 2a), is that it can be directly transformed into a spatially continuous map (Fig. 3c) and can be calculated at any temporal resolution. This allows for mapping and evaluation of trends and small climate gradients that would otherwise fall within the boundaries of discrete climate classes, and also allows direct comparison of weather conditions at a daily timescale with climate averages.

Next, I illustrate how colour can be used to visually link near-surface atmospheric conditions at different timescales. Figure 3 shows the distribution of long-term observations of daily average  $T$  and RH at two European stations with contrasting climate: De Bilt (The Netherlands, Cfb climate) and Madrid (Spain, Csa climate). The individual days are plotted using the same colours as in Fig. 1. By doing so, the weather on one particular day (as characterized by the color that combines its  $T$  and RH) can be directly linked to average climate conditions in those regions in Fig. 2c that have the same colour. Alternatively, it could be linked to a bivariate colour map showing the expected values of  $T$  and RH for that particular day.

It can be seen that on a daily timescale, weather conditions can vary over a range of  $T$  and RH that cover the average conditions for most climate classes (see Fig. 1). During warm and dry summer conditions, air masses over The Netherlands often originate from the Sahara, and the orange colours indicate temperature and relative humidity typical for BWh climates. During cold extremes in winter, air masses typically have arctic origin and the light-blue colours indicate that these conditions correspond to average conditions for a Dfc climate. Also note that seasonality induces preferred summer and winter states in the bivariate distribution of  $T$  and RH.

## Continuous climate classification

A. J. Teuling

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



In the example of Madrid, the distribution differs in shape and orientation, and the preferred states are even more pronounced. Whereas winter conditions do not differ strongly from those in De Bilt, average summer conditions are typical for the BWh climate with summers being dry and warm. Thus, by looking at climate over multiple timescales, a more complete picture of a local climate is obtained.

## 4 Conclusions

In summary, by linking combinations of two spatially and temporally continuous fields (air temperature and relative humidity) to unique colours, a straightforward and easy-to-understand approximation of the distribution of global climate zones can be obtained. An important advantage of this method is that the continuous nature of the variables result in temporal means that are well-defined and meaningful at any time resolution. The proposed method can thus be used to bridge the gap between the weather that you get on any particular day, and the climate you expect at that location, or at any place on Earth.

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## Continuous climate classification

A. J. Teuling

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



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# HESSD

8, 5733–5742, 2011

## Continuous climate classification

A. J. Teuling

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

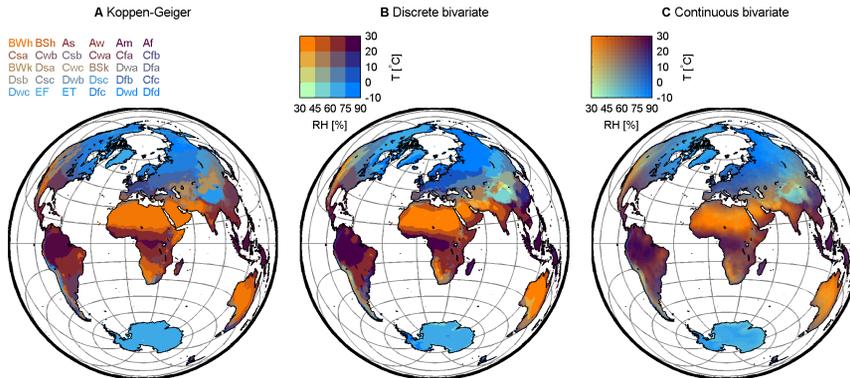
Interactive Discussion





## Continuous climate classification

A. J. Teuling



**Fig. 2.** Global distribution of climate zones. **(A):** Köppen-Geiger classification. Colouring is taken from Figure 1. Data are taken from Kottek et al. (2006). **(B):** Discrete ( $4 \times 4$ ) bivariate classification of climate based on expected values of  $T$  and RH. **(C):** (Near-)continuous ( $16 \times 16$ ) bivariate classification. Note the correspondence between **(A)** and **(B)**.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

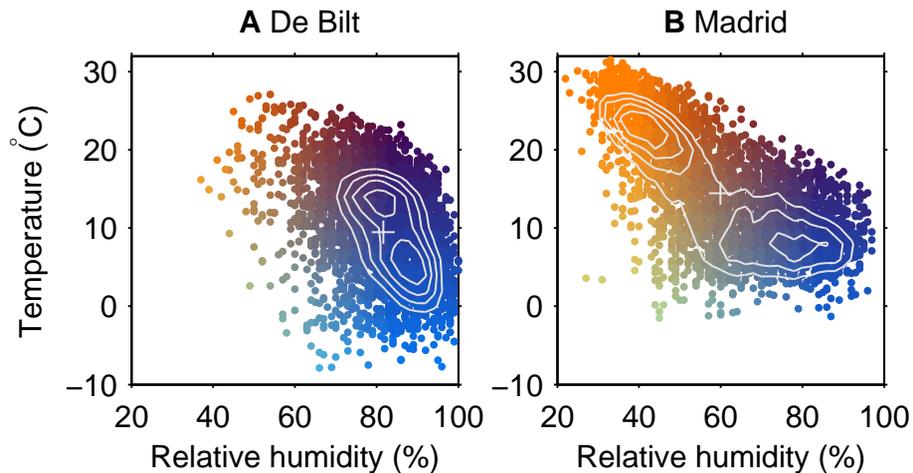
Printer-friendly Version

Interactive Discussion



**Continuous climate  
classification**

A. J. Teuling



**Fig. 3.** Daily average temperature and relative humidity over the period 2001–2010 at De Bilt **(A)** and Madrid **(B)**. Contour lines indicate the shape of the density maxima for the complete climate record. Crosses indicate mean values of RH and  $T$ . Observations are taken from the European Climate Assessment and Dataset (ecad.knmi.nl).

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[I◀](#)[▶I](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)