

1 Estimating spatially distributed soil water content at small watershed
2 scales based on decomposition of temporal anomaly and time stability
3 analysis

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11 **Abstract**

12 Soil water content (SWC) is crucial to rainfall-runoff response at the watershed scale.
13 A model was used to decompose the spatiotemporal SWC into a time-stable pattern
14 (i.e, temporal mean), a space-invariant temporal anomaly, and a space-variant
15 temporal anomaly. The space-variant temporal anomaly was further decomposed
16 using the empirical orthogonal function (EOF) for estimating spatially distributed
17 SWC. This model was compared to a previous model that decomposes the
18 spatiotemporal SWC into a spatial mean and a spatial anomaly, with the latter being
19 further decomposed using the EOF. These two models are termed temporal anomaly
20 (TA) model and spatial anomaly (SA) model, respectively. We aimed to test the
21 hypothesis that underlying (i.e., time-invariant) spatial patterns exist in the

22 space-variant temporal anomaly at the small watershed scale, and to examine the
23 advantages of the TA model over the SA model in terms of the estimation of spatially
24 distributed SWC. For this purpose, a dataset of near surface (0–0.2 m) and root zone
25 (0–1.0 m) SWC, at a small watershed scale in the Canadian prairies, was analyzed.
26 Results showed that underlying spatial patterns exist in the space-variant temporal
27 anomaly because of the permanent controls of “static” factors such as depth to the
28 CaCO₃ layer and organic carbon content. Combined with time stability analysis, the
29 TA model improved the estimation of spatially distributed SWC over the SA model,
30 especially for dry conditions. Further application of these two models demonstrated
31 that the TA model outperformed the SA model at a hillslope in the Chinese Loess
32 Plateau, but the performance of these two models in the GENCAI network (~250 km²)
33 in Italy was equivalent. The TA model can be used to construct a high-resolution
34 distribution of SWC at small watershed scales from coarse-resolution remotely sensed
35 SWC products.

36 Keywords: Soil moisture; Soil water downscaling; Empirical orthogonal function;
37 Statistical models; Time stability

38 **1. Introduction**

39 Soil water content (SWC) of surface soils exerts a major influence on a series of
40 hydrological processes such as runoff and infiltration (Famiglietti et al., 1998;
41 Vereecken et al., 2007; She et al., 2013a). Soil water content in the root zone is, in
42 many cases, linked to vegetative growth (Wang et al., 2012; Ward et al., 2012; Jia and

43 Shao, 2013). Obtaining accurate information on the spatiotemporal SWC is crucial for
44 improving hydrological prediction and soil water management (Venkatesh et al., 2011;
45 Champagne et al., 2012; She et al., 2013b; Zhao et al., 2013). While remote sensing
46 has advanced SWC measurements of surface soils (<5 cm in depth) at basin
47 (2,500–25,000 km²) and continental scales (Robinson et al., 2008), characterization of
48 spatially distributed SWC at small watershed (0.1–80 km²) scales still poses a
49 challenge. A method is needed for estimating spatially distributed SWC in the near
50 surface and root zone at watershed scales.

51 Time stability of SWC, which refers to similar spatial patterns of SWC across
52 different measurement times (Vachaud et al., 1985; Brocca et al., 2009), has been used
53 for estimating spatially distributed SWC (Starr, 2005; Perry and Niemann, 2007;
54 Blöschl et al., 2009). This method is conceptually appealing, but assumes completely
55 time-stable spatial patterns of SWC.

56 The time-stable pattern does not explain all of the spatial variances in SWC,
57 indicating the existence of time-variant components (Starr, 2005). In order to identify
58 underlying patterns of SWC that have time-variant components, the spatiotemporal
59 SWC was decomposed into a spatial mean and a spatial anomaly. The spatial anomaly
60 of the SWC was further decomposed into the sum of the product of time-invariant
61 spatial patterns (EOFs) and temporally varying, but spatially constant coefficients
62 (ECs) using the empirical orthogonal function (EOF) (Fig. 1) (Jawson and Niemann,
63 2007; Perry and Niemann, 2007, 2008; Joshi and Mohanty, 2010; Korres et al., 2010;
64 Busch et al., 2012). Spatially distributed SWC estimates based on the decomposition

65 of spatial anomaly outperformed those based on time-stable patterns (Perry and
66 Niemann, 2007).

67 Recently, the spatiotemporal SWC was also decomposed into a temporal mean and
68 a temporal anomaly (Mittelbach and Seneviratne, 2012) (Fig. 1). Previous studies
69 indicated that the contribution of the temporal anomaly to the total spatial variance
70 was notable (Mittelbach and Seneviratne, 2012; Brocca et al., 2014; Rötzer et al.,
71 2015). These studies, however, only focused on surface soils at large scales (> 250
72 km^2). Vanderlinden et al. (2012) suggested that the temporal mean may be further
73 decomposed into its spatial mean and residuals, and the temporal anomaly may be
74 further decomposed into space-invariant term (i.e., spatial mean of temporal anomaly)
75 and space-variant term (i.e., spatial residuals of temporal anomaly) (Fig. 1). Note that
76 the spatial variance in the temporal anomaly (Mittelbach and Seneviratne, 2012)
77 equals that of the space-variant term of the temporal anomaly (Vanderlinden et al.,
78 2012). The further decomposition of the temporal anomaly may be physically
79 meaningful, because the space-invariant and space-variant terms in the temporal
80 anomaly may be forced differently. However, the models of Mittelbach and
81 Seneviratne (2012) and Vanderlinden et al. (2012) have not been used for estimating
82 spatially distributed SWC. If the space-variant terms are ignored during the estimation
83 of spatially distributed SWC, their models are equivalent to that based on time-stable
84 patterns. Therefore, estimation of spatially distributed SWC may be improved by
85 incorporating the space-variant term of the temporal anomaly if underlying (i.e.,
86 time-invariant) spatial patterns exist in the temporal anomaly.

87 To our knowledge, the importance of the space-variant term of the temporal
88 anomaly and its physical meaning at small watershed scales is not well-known. Based
89 on previous studies (Perry and Niemann, 2007; Mittelbach and Seneviratne, 2012;
90 Vanderlinden et al., 2012), we assume soil water dynamics at watershed scales can be
91 decomposed into three components (Fig. 1): (1) time-stable pattern (i.e., temporal
92 mean, spatial forcing): the “static” factors such as soil and topography control the
93 pattern; (2) space-invariant temporal anomaly (temporal forcing): the “dynamic”
94 factors such as meteorological variables and vegetation change with time, and
95 therefore modify SWC in time, regardless of spatial locations; and (3) space-variant
96 temporal anomaly (interactions between spatial forcing and temporal forcing): this
97 term represents interactions between “static” and “dynamic” factors. For example,
98 SWC recharge introduced by a rainfall may be modified by topography through
99 runoff processes; SWC loss triggered by evapotranspiration may be regulated by
100 topography through solar radiation exposure.

101 The “static” factors may be persistent in the space-variant temporal anomaly, and
102 their impacts on the space-variant temporal anomaly likely change with time. Thus,
103 we hypothesize that some underlying (i.e., time-invariant) spatial patterns exist in the
104 space-variant temporal anomaly, and their impacts can be modulated by a time
105 coefficient, both of which can be obtained by the EOF method (Fig. 1). If the
106 hypothesis is true, the estimation of spatially distributed SWC utilizing the EOF
107 decomposition may outperform the one suggested by Perry and Niemann (2007). This
108 is because: (1) the spatial anomaly which was decomposed using the EOF in Perry

109 and Niemann (2007) lumped the time-stable pattern and space-variant temporal
110 anomaly together (Fig. 1); (2) the underlying spatial patterns in the spatial anomaly
111 may not fully capture both time-stable patterns and patterns in the space-variant
112 temporal anomaly due to the possible nonlinear relations between these two terms.

113 Therefore, the objectives were (1) to test the hypothesis that underlying spatial
114 patterns exist in the space-variant temporal anomaly at small watershed scales and (2)
115 to examine whether the decomposition of the space-variant temporal anomaly using
116 the EOF has any advantages over the decomposition of the spatial anomaly (Perry and
117 Niemann, 2007) for estimating spatially distributed SWC. Two steps were included in
118 the estimation of spatially distributed SWC. First, the spatial mean SWC was upscaled
119 from the SWC measurement at the most time-stable location using time stability
120 analysis. Following this, the spatially distributed SWC was downscaled from the
121 estimated spatial mean SWC. For the purpose of this study, spatiotemporal SWC
122 datasets at depths of near surface (0–0.2 m) and root zone (0–1.0 m) from a Canadian
123 prairie landscape were used. Spatiotemporal SWC of samples taken 0–0.06 m from a
124 hillslope (100 m) in the Chinese Loess Plateau and 0–0.15 m from the GENCAI
125 network (~250 km²) in Italy were also used to further demonstrate conditions under
126 which the decomposition of the spatial anomaly was beneficial to the estimation of
127 spatially distributed SWC.

128 **2. Materials and methods**

129 **2.1 Study area and data collection**

130 This study was mainly conducted in the Canadian prairie pothole region (hereafter
131 abbreviated as Canadian site) at St. Denis National Wildlife Area (52°12' N, 106°50'
132 W) with an area of 3.6 km². This area has a humid continental climate (Peel et al.,
133 2007), and had a mean annual air temperature of 1.9 °C and a mean annual
134 precipitation of 402 mm during the study period (Fig. 2). A variety of depressions,
135 knolls, and knobs result in a sequence of undulating slopes (Biswas et al., 2011). The
136 elevation varies from 554.8 to 557.5 m. The soils are dominated by clay loam textured
137 Mollisols (Soil Survey Staff, 2010) and covered by mixed grass, i.e., smooth brome
138 grass (*Bromus inermis*) and alfalfa (*Medicago sativa* L.). The near surface soil
139 porosity ranges from 38% (knolls) to 70% (depressions). Calcium carbonates (CaCO₃)
140 derived mostly from fragments of limestone rocks are common in the Canadian
141 Prairies. The CaCO₃ is dissolved by the slightly acidic rainwater moving through the
142 upper horizons and deposited to lower horizons. The heterogeneous amount of
143 infiltrated water resulted in a varying depth of CaCO₃ layer ranging from almost 0 m
144 in the knolls to 2.1 m in the depressions. A 576 m long sampling transect with 128
145 sampling locations spaced at 4.5 m intervals was established over several rounded
146 knolls and depressions. At each location, a time domain reflectometry probe was used
147 to measure SWC of the near surface soil (0–0.2 m), and a neutron probe was used to
148 collect SWC measurements at 0.2 m intervals between a depth of 0.2 and 1.0 m. The
149 SWC was measured on a volumetric basis and expressed as a percentage (%) volume
150 of water per unit soil volume. The SWC of the root zone was calculated by averaging
151 the SWC of 0–0.2, 0.2–0.4, 0.4–0.6, 0.6–0.8, and 0.8–1.0 m. Soil water content was

152 measured on 23 dates from July 17, 2007 to September 29, 2011. The SWC dataset
153 was collected in all seasons except winter, and accurately portrays the variations in
154 soil water conditions in the study area. In addition to the SWC dataset, the soil,
155 vegetative, and topographical properties were obtained at each sampling location.
156 These properties included soil particle components (clay, silt, and sand contents), bulk
157 density, soil organic carbon (SOC) content for the surface layer, A horizon depth, C
158 horizon depth, depth to the CaCO₃ layer, leaf area index, elevation, cos(aspect), slope,
159 curvature, gradient, upslope length, solar radiation, specific contributing area,
160 convergence index, wetness index, and flow connectivity. Detailed information on the
161 measurements can be found in Biswas et al. (2012). The datasets from the Canadian
162 site were used to demonstrate the following two aspects in detail: (1) different
163 components of spatiotemporal SWC and their contributing factors, and (2) the
164 advantages of the new decomposition method over the method suggested by Perry and
165 Niemann (2007) in terms of the estimation of spatially distributed SWC.

166 **To further test the applicability of the new method, we compared its performance at**
167 **two other sites, covering both the hillslope and the large watershed scale.** Along a
168 hillslope of 100 m in length in the Chinese Loess Plateau, SWC of 0–0.06 m was
169 measured 136 times from June 25, 2007 to August 30, 2008 by a Delta-T Devices
170 Theta probe (ML2x) at 51 locations (Hu et al., 2011). The hillslope was covered by
171 *Stipa bungeana* Trin. and *Medicago sativa* L. in sandy loam and silt loam soils. In the
172 GENCAI network (~250 km²) in Italy, SWC of 0–0.15 m was measured by a TDR
173 probe at 46 locations, 34 times from February to December in 2009 (Brocca et al.,

174 2012, 2013). The GENCAI area was dominated by grassland with a flat topography,
175 in silty clay soils.

176 **2.2 Statistical models for decomposing soil water content**

177 Spatiotemporal SWC at small watershed scales was decomposed into three
178 components: time-stable pattern, space-invariant temporal anomaly, and space-variant
179 temporal anomaly. This model was compared to the one that decomposed SWC into
180 spatial mean and spatial anomaly (Perry and Niemann, 2007). Both the space-variant
181 temporal anomaly and spatial anomaly were decomposed using the EOF method. The
182 two models are termed temporal anomaly (TA) model and spatial anomaly (SA)
183 model, respectively. Figure 1 displays the differences between the two models. Each
184 component will be explained in detail later. The explanation of nomenclatures is listed
185 in Table A1. Because we focus on estimating spatial distribution of SWC at any given
186 time, only spatial variances of SWC were taken into account. Therefore, the variance
187 or covariance denotes the quantity in space without specifications.

188 **2.2.1 The SA model**

189 Perry and Niemann (2007) expressed SWC at location n and time t (S_{tn}) as (Fig.
190 1):

$$191 \quad S_{tn} = S_{t\hat{n}} + Z_{tn}, \quad (1)$$

192 where $S_{t\hat{n}}$ is the spatial mean SWC at time t (temporal forcing) and Z_{tn} is the
193 spatial anomaly of SWC (lumped spatial forcing and interactions). The subscript \hat{n}
194 (\hat{t}) indicates a space (time) averaged quantity.

195 According to Perry and Niemann (2007), $S_{t\hat{n}}$ can be estimated by remote sensing,
196 water balance models, and in situ soil water measurement at a representative (or

197 time-stable) location. The in situ soil water measurement method was selected
 198 because the representative location can be easily determined with prior SWC datasets.
 199 By measuring SWC only at the most time-stable location (s) and future time t (S_{ts}),
 200 $S_{\hat{m}}$ can be estimated using (Grayson and Western, 1998):

$$201 \quad S_{\hat{m}} = \frac{S_{ts}}{1 + \delta_{ts}} \quad , \quad (2)$$

202 where the s was identified using the time stability index of mean absolute bias error
 203 (Hu et al., 2010, 2012). The δ_{ts} is the temporal mean relative difference of SWC at
 204 the s , which was calculated with prior measurements.

205 Spatial anomaly (Z_{tm}) can be reconstructed by the sum of the product of
 206 time-invariant spatial structures (EOFs) and temporally varying coefficients (ECs)
 207 using the EOF method (Perry and Niemann, 2007; Joshi and Mohanty, 2010;
 208 Vanderlinden et al., 2012). The ECs correspond to the eigenvectors of the matrix of
 209 spatial covariance of the Z_{tm} , and the EOFs are obtained by projecting the Z_{tm} onto
 210 the matrix ECs as: EOFs = Z_{tm} ECs. The number of EOF (or EC) series equals the
 211 number of sampling dates. Each EOF series corresponds to one value at each location,
 212 and each EC series has one value at each measurement time. Each EOF is chosen to
 213 be orthogonal to other EOFs, and the lower-order EOFs account for as much variance
 214 as possible. The sum of variances of all EOFs equals the sum of variances of Z_{tm}
 215 from all measurement times.

216 Usually, a substantial amount of variance can be explained by a small number of
 217 EOFs. Johnson and Wichern (2002) suggested the eigenvalue confidence limits
 218 method for selecting the number of EOFs. Once the number of significant EOFs at a

219 confidence level of 95% is selected, Z_{tm} can be estimated as the sum of the product
 220 of significant EOFs and associated ECs as:

$$221 \quad Z_{tm} = \sum \text{EOF}^{sig} \times (\text{EC}^{sig})^T, \quad (3)$$

222 where EOF^{sig} represents the significant EOFs of the Z_{tm} obtained during model
 223 development, EC^{sig} is the associated temporally varying coefficient, and the
 224 superscript T represents matrix transpose. Following Perry and Niemann (2007), the
 225 associated significant EC at time t (EC_t), is estimated by the cosine relationship
 226 between EC and S_{in} developed using prior measurements:

$$227 \quad \text{EC}_t = a + b \cos\left(\frac{2\pi}{c} S_{in} - d\right), \quad (4)$$

228 where a , b , c , and d are the fitted parameters using prior measurements and S_{in} is
 229 estimated from Eq. (2). By using the continuous function, EC_t can be estimated at
 230 any S_{in} values, which allows for the estimation of spatially distributed SWC at any
 231 soil water conditions.

232 2.2.2 The TA model

233 Mittelbach and Seneviratne (2012) decomposed the S_{in} into a time-stable pattern
 234 (i.e., temporal mean) and a temporal anomaly component (Fig. 1):

$$235 \quad S_{in} = M_{in} + A_{in}, \quad (5)$$

236 where M_{in} is the time-stable pattern (spatial forcing) controlled by “static” factors
 237 such as soil properties and topography; A_{in} refers to the temporal anomaly (lumped
 238 temporal forcing and interactions). The variance of SWC ($\sigma_n^2(S_{in})$) is the sum of
 239 variance of the M_{in} ($\sigma_n^2(M_{in})$), variance of the A_{in} ($\sigma_n^2(A_{in})$), and two times of
 240 covariance between M_{in} and A_{in} ($2\text{cov}(M_{in}, A_{in})$), which can be expressed as:

241
$$\sigma_{\hat{n}}^2(S_m) = \sigma_{\hat{n}}^2(M_{\hat{m}}) + 2\text{cov}(M_{\hat{m}}, A_m) + \sigma_{\hat{n}}^2(A_m). \quad (6)$$

242 Because the A_m in Mittelbach and Seneviratne (2012) is a lumped term, it can be
 243 further decomposed into space-invariant temporal anomaly ($A_{\hat{m}}$, i.e., temporal
 244 forcing) and space-variant temporal anomaly (R_m , i.e., interactions) (Vanderlinden et
 245 al., 2012). At a watershed scale, the $A_{\hat{m}}$ is controlled by temporally varying factors
 246 such as meteorological variables and vegetation. Positive and negative $A_{\hat{m}}$
 247 correspond to relatively wet and dry periods, respectively. The R_m refers to the
 248 redistribution of $A_{\hat{m}}$ among different locations due to the interactions between
 249 spatial forcing and temporal forcing. For example, soil and topography regulate how
 250 much rainfall enters soil and how much water runs off or runs on at a location. This,
 251 in turn, dictates vegetation growth in a water-limited environment. Therefore, S_m
 252 can also be expressed as (Fig. 1):

253
$$S_m = M_{\hat{m}} + A_{\hat{m}} + R_m. \quad (7)$$

254 The temporal trends of $A_{\hat{m}}$ in Eq. (7) and $S_{\hat{m}}$ in Eq. (1) are the same as both
 255 represent temporal forcing. Because the $A_{\hat{m}}$ is space-invariant and orthogonal to the
 256 $M_{\hat{m}}$ and R_m in a space, $\sigma_{\hat{n}}^2(S_m)$ in Eq. (6) can also be written as:

257
$$\sigma_{\hat{n}}^2(S_m) = \sigma_{\hat{n}}^2(M_{\hat{m}}) + 2\text{cov}(M_{\hat{m}}, R_m) + \sigma_{\hat{n}}^2(R_m), \quad (8)$$

258 where $\text{cov}(M_{\hat{m}}, R_m)$ is the covariance between the $M_{\hat{m}}$ and R_m , and $\sigma_{\hat{n}}^2(R_m)$ is
 259 the variance of the R_m . Apparently, $2\text{cov}(M_{\hat{m}}, R_m)$ equals $2\text{cov}(M_{\hat{m}}, A_m)$, and
 260 $\sigma_{\hat{n}}^2(R_m)$ equals $\sigma_{\hat{n}}^2(A_m)$. The percent (%) of $\sigma_{\hat{n}}^2(M_{\hat{m}})$, $2\text{cov}(M_{\hat{m}}, R_m)$, and
 261 $\sigma_{\hat{n}}^2(R_m)$ out of the $\sigma_{\hat{n}}^2(S_m)$ are calculated. The $\text{cov}(M_{\hat{m}}, R_m)$ can be negative at
 262 some conditions, for example, when the depressions correspond to greater $M_{\hat{m}}$ and

263 more negative R_{tm} values in the discharge periods. This resulted in percentage of
 264 $\sigma_{\hat{n}}^2(M_{\hat{m}})$ and $\sigma_{\hat{n}}^2(R_{\hat{m}}) > 100\%$ and percentage of $2\text{cov}(M_{\hat{m}}, R_{\hat{m}}) < 0\%$
 265 (Mittelbach and Seneviratne, 2012; Brocca et al., 2014; Rötzer et al., 2015). If R_{tm}
 266 is zero at any time or location, there are no interactions between spatial forcing and
 267 temporal forcing, $\sigma_{\hat{n}}^2(S_{\hat{m}})$ and the spatial trends of SWC are consistent over time.
 268 Therefore, R_{tm} is directly responsible for temporal change in the spatial variability
 269 of SWC.

270 If some underlying spatial patterns exist in R_{tm} , R_{tm} can be reconstructed by the
 271 sum of the product of time-invariant spatial structures (EOFs) and time-dependent
 272 coefficients (ECs) using the EOF method. Note that the number of EOF (or EC) series
 273 also equals the number of sampling dates.

274 For estimation of spatially distributed SWC, R_{tm} is estimated by the same method
 275 as Z_{tm} using Eq. (3). The $M_{\hat{m}}$ is estimated with prior measurements by:

$$276 \quad M_{\hat{m}} = \frac{1}{m} \sum_{j=1}^m S_{\hat{m}}, \quad (9)$$

277 where m is the number of previous measurement times, and $A_{\hat{m}}$ is estimated by:

$$278 \quad A_{\hat{m}} = S_{\hat{m}} - M_{\hat{m}}, \quad (10)$$

279 where $M_{\hat{m}}$ is the spatial mean of $M_{\hat{m}}$, and $S_{\hat{m}}$ is estimated from SWC
 280 measurements at the most time-stable location using Eq. (2).

281 The Pearson correlation coefficient (R) is used to explore the linear relationships
 282 between various spatial components in the two models (i.e., EOF1 of the Z_{tm} in the
 283 SA model, $M_{\hat{m}}$, and EOF1 of the R_{tm} in the TA model) and environmental factors
 284 (i.e., soil, vegetative, and topographical properties). The multiple stepwise regressions

285 are conducted to determine the percentage of variations in the spatial components
286 which the controlling factors explain.

287 **2.3 Validation and performance parameter**

288 The TA model is more complicated than the SA model. In order to evaluate the two
289 models for parsimony, AICc values are calculated (Burnham and Anderson, 2002) as:

$$290 \quad \text{AICc} = 2k + n \ln(RSS/n) + 2k(k+1)/(n-k-1), \quad (11)$$

291 where k is the number of parameters, n is the sample size, and RSS is the residual sum
292 of squares.

293 Both cross validation and split sample validation are used to estimate SWC
294 distribution with both models. For the cross validation, an iterative removal of 1 of the
295 23 dates is made for model development, and the SWC along the transect
296 corresponding to the removed date is estimated iteratively. For the split sample
297 validation, SWC from 14 dates of the first two years (from July 17, 2007 to May 27,
298 2009) is used for model development, and the SWC distribution of 9 dates in the
299 second two years (from July 21, 2009 to September 29, 2011) is estimated.

300 The Nash-Sutcliffe coefficient of efficiency (NSCE) is used to evaluate the quality
301 of estimation of spatially distributed SWC, which is expressed as:

$$302 \quad \text{NSCE} = 1 - \frac{\sigma_{\varepsilon}^2}{\sigma_{\text{measure}}^2}, \quad (12)$$

303 where $\sigma_{\text{measure}}^2$ is the variance of measured SWC, and σ_{ε}^2 is the mean squared
304 estimation error. A larger NSCE value implies a better quality of estimation. A paired
305 samples T-test is used to test whether the NSCE values between the TA model and the
306 SA model are statistically significant at $P < 0.05$.

307 Many factors may affect the relative performance of spatially distributed SWC
308 estimation between the TA model and the SA model. First, the degree of
309 outperformance of the TA model over the SA model may depend on the amount of
310 R_{tm} variance considered in the TA model. On one hand, the two models are identical
311 if variance of R_{tm} is close to zero or there are negligible interactions between the
312 spatial and temporal components (Fig. 1). On the other hand, if no underlying spatial
313 patterns exist in the R_{tm} or the underlying spatial patterns accounted for little
314 variance of the R_{tm} , the outperformance will also be very limited. Therefore, the
315 greater the variance of R_{tm} considered in the TA model, the more likely the TA
316 model can outperform the SA model. Second, the way of EOF decomposition may
317 also affect the relative performance. In the SA model, EOF decomposition is
318 performed on lumped time-stable patterns ($M_{\hat{m}}$) and space-variant temporal anomaly
319 (R_{tm}). In the TA model, however, EOF decomposition is made only on the R_{tm} . In
320 theory, the two models will be identical if the $M_{\hat{m}}$ and the first underlying spatial
321 pattern (i.e., EOF1) of the R_{tm} were perfectly correlated. If a nonlinear relationship
322 exists between them, lumping the $M_{\hat{m}}$ and R_{tm} together, as in the SA model,
323 would weaken the model performance as compared to the TA model. From this aspect,
324 the greater deviation from a linear relationship between the $M_{\hat{m}}$ and EOF1 of the
325 R_{tm} , may lead to a greater outperformance of the TA model over the SA model.
326 Finally, the performances of both models rely on the estimation accuracy of the EC_t ,
327 which depends on both goodness of fit of the cosine function (i.e., Eq. 4) and
328 estimation accuracy of the $S_{\hat{m}}$. Because the same $S_{\hat{m}}$ values are used for the two

329 models, the relative performance of the two models is related to the goodness of fit of
330 Eq. (4).

331 **3. Results**

332 **3.1 Components of SWC and their controls**

333 **3.1.1 Spatial mean (S_{in}) and spatial anomaly (Z_{tm})**

334 The values of spatial mean (S_{in}) in the SA model varied with the seasons (Fig. 3a).
335 In the spring, such as May 2, 2008 and April 20, 2009, snowmelt infiltration resulted
336 in relatively great S_{in} values. In the summer, however, even one month after large
337 rainfall events (such as on July 19, 2008 and June 21, 2009), the high
338 evapotranspiration by fast-growing vegetation resulted in small S_{in} values. The
339 values of S_{in} also varied between inter-annual meteorological conditions. In 2008,
340 there was less precipitation and higher air temperature than in 2010 (Fig. 2). As a
341 result, S_{in} was relatively smaller in 2008 than in 2010.

342 The spatial patterns of spatial anomaly (Z_{tm}) were similar to those of the original
343 SWC patterns (Fig. 3a). The values of Z_{tm} in wet periods (e.g., May 13, 2011) were
344 much greater than in dry periods (e.g., August 23, 2008) in depressions (e.g., at a
345 distance of 123 and 250 m); at other locations, however, the spatial anomaly was
346 slightly less in wet periods than in dry periods for both soil layers. Moreover, the
347 spatial anomaly in depressions during the wet periods was much greater in the near
348 surface than in the root zone.

349 When SWCs of all 23 dates were used for model development, only EOF1 was

350 statistically significant (Fig. 4a), which accounted for 84.3% (0–0.2 m) and 86.5%
 351 (0–1.0 m) of the variances in the Z_{tn} . Correlation analysis indicated that the spatial
 352 pattern of EOF1 in the Z_{tn} was identical to the time-stable patterns ($M_{\hat{tn}}$) in the TA
 353 model ($R=1.0$). The controls of EOF1 was therefore the same as those of $M_{\hat{tn}}$, and
 354 will be discussed later. The relationship between associated EC1 and $S_{\hat{tn}}$ can be
 355 fitted well by the cosine function ($R^2=0.73$ at both the near surface and root zone) (Fig.
 356 4b).

357 **3.1.2 Time-stable pattern ($M_{\hat{tn}}$), space-invariant temporal anomaly ($A_{\hat{tn}}$), and**
 358 **space-variant temporal anomaly (R_{tn})**

359 Figure 3b displays the three components in the TA model. The first component
 360 $M_{\hat{tn}}$ fluctuated along the transect, with high values in depressions and low values on
 361 knolls; the $M_{\hat{tn}}$ also had greater spatial variability in the near surface (variance
 362 $=36.7\%^2$) than in the root zone (variance $=19.5\%^2$). For both soil layers, SOC, depth to
 363 the CaCO_3 layer, sand content, and wetness index are the dominant factors of $M_{\hat{tn}}$;
 364 they together explained 74.5% (near surface) and 75.6% (root zone) of the variances
 365 in the $M_{\hat{tn}}$ (Table 1). In addition, the temporal trend of $A_{\hat{tn}}$ was the same as that of
 366 $S_{\hat{tn}}$ in the SA model (Fig. 3a) as both represent temporal forcing.

367 The R_{tn} varied among landscape positions (Fig. 3b). At a sampling distance of
 368 123 m (in a depression), R_{tn} was negative in dry periods such as August 23, 2008 and
 369 positive in wet periods such as May 13, 2011. This was true for all depressions for
 370 both the near surface and the root zone. Therefore, topographically lower positions
 371 usually corresponded to more positive R_{tn} during the wet periods and more negative

372 R_m during the dry periods. Furthermore, the absolute values of R_m were generally
373 greater in the near surface than the root zone, indicating a greater space-variant
374 temporal anomaly for shallower depths.

375 The SWC variances and associated components (Eq. 8) also varied with time (Fig.
376 5). Often, wetter conditions corresponded to greater $\sigma_{\hat{n}}^2(S_m)$, as further indicated by
377 moderate correlation between $\sigma_{\hat{n}}^2(S_m)$ and $S_{\hat{in}}$ (R^2 of 0.51 and 0.38 for the near
378 surface and the root zone, respectively). This was in agreement with others
379 (Gómez-Plaza et al., 2001; Martínez-Fernández and Ceballos, 2003; Hu et al., 2011).
380 Furthermore, there were greater $\sigma_{\hat{n}}^2(S_m)$ values at near surface than in the root zone,
381 indicating greater variability of SWC in the near surface.

382 The time-invariant $\sigma_{\hat{n}}^2(M_{\hat{in}})$ accounted for the $\sigma_{\hat{n}}^2(S_m)$ with percentages
383 ranging from 25 to 795% for the near surface and from 40 to 174% for the root zone
384 (Fig. 5). The $\sigma_{\hat{n}}^2(M_{\hat{in}})$ exceeded the $\sigma_{\hat{n}}^2(S_m)$ mainly under dry conditions, such as
385 July–October in 2008 and 2009. This excess was offset by the $\sigma_{\hat{n}}^2(R_m)$ and
386 $2\text{cov}(M_{\hat{in}}, R_m)$, with the latter accounting for the $\sigma_{\hat{n}}^2(S_m)$ negatively with mean
387 absolute percentages of 210% for the near surface and 17% for the root zone. In the
388 dry period, the absolute percentage of $2\text{cov}(M_{\hat{in}}, R_m)$ was up to 1327% for the near
389 surface and 122% for the root zone. These values are comparable to those in
390 Mittelbach and Seneviratne (2012) and Brocca et al. (2014).

391 The $\sigma_{\hat{n}}^2(R_m)$ accounted for less percentage of the $\sigma_{\hat{n}}^2(S_m)$ than other
392 components did (Fig. 5). The percentages of $\sigma_{\hat{n}}^2(R_m)$ ranged from 11 to 632%
393 (arithmetic average of 118%) for the near surface and from 6 to 48% (arithmetic

394 average of 19%) for the root zone; the percentage of $\sigma_{\hat{n}}^2(R_m)$ tended to be greater in
395 drier periods. This indicates that the space-variant temporal anomaly cannot be
396 ignored, particularly in dry conditions. Furthermore, the percentage of $\sigma_{\hat{n}}^2(R_m)$ was
397 greater in the near surface than in the root zone, confirming stronger temporal
398 dynamics of soil water at the near surface. Compared with larger scale studies
399 (Mittelbach and Seneviratne, 2012; Brocca et al., 2014), the percentage of $\sigma_{\hat{n}}^2(R_m)$
400 out of the $\sigma_{\hat{n}}^2(S_m)$ at the near surface was greater, with a mean percentage of 118%,
401 versus 9–68% in the other, larger scale studies. This indicates that interactions
402 between spatial and temporal forcing were stronger, resulting in relatively more
403 intensive temporal dynamics of soil water in our study area than at larger scales.

404 Three significant EOFs of R_m for both soil layers were identified when SWC of
405 all 23 dates were used for model development. The first three EOFs explained 61.1,
406 13.4, and 8.1% respectively, of the total R_m variance for the near surface, and 44.3,
407 20.2, and 12.4%, respectively, of the total R_m variance in the root zone. Therefore,
408 our hypothesis that underlying spatial patterns exist in the R_m was supported. Due
409 to the negligible contribution of EOF2 and EOF3 to the estimation of spatially
410 distributed SWC, only EOF1 is shown in Fig. 6a. The associated EC1 changed with
411 soil water conditions (S_m) (Fig. 6b). When SWC was close to average levels, the EC1
412 was close to 0, resulting in negligible R_m . This was in accordance with Mittelbach
413 and Seneviratne (2012) and Brocca et al. (2014), who showed that the spatial variance
414 of the temporal anomaly was the smallest when water contents were close to average
415 levels. The cosine function (Eq. 4) explained a large amount of the variances in EC1

416 for both soil layers ($R^2=0.76$ at the near surface and 0.88 in the root zone).

417 The contribution of EOF1 to the space-variant temporal anomaly can be examined
418 through the product of the EOF1 and the associated EC1. The EC1 values tended to
419 be positive during wet periods and negative during dry periods (Fig. 6b); more
420 positive EOF1 values were usually observed at locations with greater $M_{\hat{m}}$ values
421 (Figs. 3b and 6a). Therefore, the product of EOF1 and EC1 led to greater temporal
422 SWC dynamics at wetter locations of both layers in both the wet and dry periods.

423 Depth to the CaCO_3 layer and SOC had significant, positive correlations with
424 EOF1 for both soil layers (R ranging from 0.76 to 0.88; Table 1). They jointly
425 accounted for 81.6% (near surface) and 81.0% (root zone) of the variances in EOF1.
426 This implies that locations with a greater depth to the CaCO_3 layer and SOC, which
427 correspond to wetter locations such as depressions, usually have greater temporal
428 SWC dynamics during both wet and dry periods.

429 **3.2 Estimation of spatially distributed SWC**

430 When all 23 datasets were used and only EOF1 was considered, the TA model had
431 an AICc value of 4093 for the near surface and 562 for the root zone, while the
432 corresponding values for the SA model were 6370 and 3460. This indicated that even
433 when penalty to complexity was given, the TA model was better than the SA model.
434 The two models in terms of spatially distributed SWC estimation are compared below.

435 **3.2.1 The TA model**

436 The R_m terms and associated EOFs differed slightly with each validation. The
437 number of significant EOFs varied between one (accounting for 60% of the total cases)

438 and three for both soil layers. A paired samples T-test indicated that more EOFs did
439 not result in a significant increase of NSCE in the estimation of spatially distributed
440 SWC for both validation methods. This is also supported by the increasing AICc
441 values with the increasing number of parameters resulting from more EOFs (data not
442 shown). This indicates that higher-order EOFs, even if they are statistically significant,
443 are negligible for SWC prediction. Therefore, SWC distribution was estimated with
444 EOF1 only.

445 Estimated SWCs generally approximated those measured at different soil water
446 conditions during the cross validation (Fig. 7). However, on October 27, 2009, there
447 were unsatisfactory overestimates at the 100–140 and 220–225 m locations near the
448 surface (Fig. 7a). Unsatisfactory NSCE values of -4.05, -1.83, and -3.81 were
449 obtained in the near surface in only three of the 23 dates, which were all in the fall
450 (October 22, 2008, August 27, 2009, and October 27, 2009, respectively). The poor
451 performance obtained with the TA model on those dates (Fig. 8a) was a result of
452 overestimation in depressions, which is shown for example on October 27, 2009 (Fig.
453 7a). These dates also corresponded to a high percentage of $\sigma_n^2(R_m)$ to the $\sigma_n^2(S_m)$
454 (203–439%). For August 23 and September 17 in 2008, which were in dry periods,
455 the percentage of $\sigma_n^2(R_m)$ at the near surface was also high (580 and 630%).
456 Because a fair amount of $\sigma_n^2(R_m)$ was accounted for with the TA model, the TA
457 model performed satisfactorily (NSCE of 0.43 and 0.60). For the remaining 20 dates,
458 the resulting NSCE value ranged from 0.38 to 0.90 in the near surface and from 0.65
459 to 0.96 in the root zone (Fig. 8). This suggests that the TA model was generally

460 satisfactory, with better performance in the root zone than in the near surface.

461 During the split sample validation, the TA model resulted in SWC estimations with
462 NSCE values ranging from 0.61 to 0.85 near the surface and from 0.32 to 0.92 in the
463 root zone, with exception of two days (August 27, 2009 and October 27, 2009 with
464 NSCE values of -2.63 and -5.12, respectively) at 0–0.2 m (Fig. 8). This suggested that
465 the TA model performed well in estimating spatially distributed SWC patterns except
466 on August 27, 2009 and October 27, 2009 at 0–0.2 m. The estimation in the root zone
467 was also generally better than in the near surface.

468 **3.2.2 Comparison with the SA model**

469 One significant EOF of Z_m was identified for both soil layers, irrespective of the
470 validation method. The SA model with only EOF1 produced reasonable SWC
471 estimations for both validations in all dates in the root zone and in every date except
472 five dates (August 23, 2008, September 17, 2008, October 22, 2008, August 27, 2009,
473 and October 27, 2009) in the near surface (Fig. 8). Similarly, when more EOFs were
474 included, NSCE values did not increase significantly (data not shown) and
475 consequently, estimation of spatially distributed SWC was not improved. This was
476 because EOF2 and EOF3 together explained a very limited (<10%) amount of
477 variability of Z_m and thus had low predictive power in terms of variance.

478 The difference in NSCE values between the TA and SA models for both validations
479 are presented in Fig. 9. Generally, the difference decreased as $A_{\hat{m}}$ increased, and
480 then slightly increased with a further increase in $A_{\hat{m}}$. A paired samples T-test
481 indicated that the NSCE values of the TA model were significantly ($P<0.05$) greater

482 than those of the SA model for both soil layers, irrespective of validation methods.
483 This indicates that the TA model outperformed the SA model, particularly in dry
484 conditions. This was because when the soil was dry, there was a high percentage of
485 $\sigma_{\hat{n}}^2(R_m)$, and thus strong variability in the space-variant temporal anomaly.

486 **3.3 Further application at other two sites with different scales**

487 **3.3.1 A hillslope in the Chinese Loess Plateau**

488 On average, the $\sigma_{\hat{n}}^2(M_{in})$, $\sigma_{\hat{n}}^2(R_m)$, and $2\text{cov}(M_{in}, R_m)$ accounted for 53, 74
489 and -27% out of the $\sigma_{\hat{n}}^2(S_m)$, indicating that both time-stable pattern and temporal
490 anomalies were the main contributors to the $\sigma_{\hat{n}}^2(S_m)$. The EOF analysis showed that
491 only the EOF1 was statistically significant for both the R_m and Z_m , and the EOF1
492 explained 23% and 47% of the total variances of R_m and Z_m , respectively. This
493 illustrated that underlying spatial patterns exist in the R_m on the hillslope. Cross
494 validation was used to estimate the spatially distributed SWC along the hillslope. The
495 results showed that the NSCE varied from -4.25 to 0.83 (TA model) and from -4.30 to
496 0.81 (SA model), with a mean value of 0.25 and 0.19, respectively (Fig. 10a). A paired
497 samples T-test showed that the NSCE values for the TA model were significantly
498 ($P < 0.05$) greater than those for the SA model, indicating that the TA model
499 outperformed the SA model. As Fig. 10a shows, the outperformance was greater when
500 SWC deviated from intermediate conditions, especially for dry conditions, which was
501 similar to the Canadian site.

502 **3.3.2 The GENCAI network in Italy**

503 The $\sigma_{\hat{n}}^2(M_{in})$, $\sigma_{\hat{n}}^2(R_m)$, and $2\text{cov}(M_{in}, R_m)$ accounted for 38, 68, and -7% out

504 of the $\sigma_{\hat{n}}^2(S_m)$ (Brocca et al., 2014), indicating the dominant role of temporal
505 anomalies in SWC variability. The first three EOFs of the R_m explained 19, 16, and
506 8% of the total $\sigma_{\hat{n}}^2(R_m)$, and no EOFs were statistically significant, indicating that no
507 underlying spatial patterns exist in the R_m . The EOF1 of the Z_m was significant
508 and accounted for 37% of the variances in the Z_m . Although the EOF1 of the R_m
509 was not significant, it was considered in the TA model for estimating spatially
510 distributed SWC. The cross validation indicates that the NSCE varied from -0.79 to
511 0.50 (TA model) and from -0.87 to 0.56 (SA model), with mean values of 0.09 and
512 0.08, respectively (Fig. 10b). The SWC estimation based on these two models was not
513 satisfactory except for a few days. As Fig. 10b shows, the differences in NSCE values
514 between the two models were scattered around 0. A paired samples T-test showed that
515 the NSCE values between the TA model and the SA model were not significant
516 ($P < 0.05$), indicating no differences in estimating spatially distributed SWC between
517 these two models.

518 **4 Discussion**

519 **4.1 Controls of the $M_{\hat{m}}$ and R_m**

520 The R_m played an important role in the temporal change in spatial patterns of the
521 SWC. The underlying spatial patterns and physical meaning in the R_m were
522 examined in our study for the first time. Although three significant EOFs of the R_m
523 existed in some cases, only EOF1 rather than higher-order EOFs of the R_m should
524 be considered for the spatially distributed SWC estimation. Among many factors

525 influencing the EOF1 of the R_{tm} , depth to the CaCO_3 layer followed by the SOC,
526 were the most important factors. Depressions have deeper CaCO_3 layers than knolls,
527 and the shallow CaCO_3 layer on knolls limited water infiltration during rainfall or
528 snowmelt, resulting in less water recharge on knolls than in depressions. The depth to
529 CaCO_3 layer and SOC were negatively correlated with elevation ($R=-0.54$, $P<0.01$).
530 Therefore, the influence of depth to CaCO_3 layer and SOC partially reflected the role
531 of topography in driving snowmelt runoff along slopes in the spring, which
532 contributes to increasing water recharge in depressions. As already demonstrated,
533 topographically lower positions corresponded to more negative R_{tm} during the dry
534 periods. This implies that depressions lost more water during discharge. This is
535 because depressions usually corresponded to vegetation with a larger leaf area index,
536 which would result in higher evapotranspiration and more water loss during discharge
537 periods.

538 As Table 1 shows, both the depth to the CaCO_3 layer and SOC controlled the M_{in} .
539 This was because deeper CaCO_3 layers and higher SOC were observed in depressions
540 where soils were usually wetter in most of the year because of the snowmelt runoff in
541 the spring and rainfall runoff in the summer and autumn (van der Kamp et al., 2003).
542 Therefore, the roles of soil and topography were two-fold: On one hand, they were
543 highly correlated with the time-stable patterns and thus the time stability of SWC
544 (Gómez-Plaza et al., 2000; Mohanty and Skaggs, 2001; Grant et al., 2004); On the
545 other hand, soil and topography, interplaying with temporal forcing, triggered
546 local-specific soil water change and destroyed time stability of SWC. Their roles in

547 protecting time stability persisted, but their roles in destroying time stability varied
548 with time. Greater $\sigma_n^2(R_m)$ implies greater contribution of these factors in soil water
549 dynamics, resulting in less time stability of SWC.

550 **4.2 Model performance for spatially distributed SWC estimation**

551 The outperformance of the TA model for estimating spatial SWC at the Canadian
552 site and Chinese site can be partly explained by the high percentages (average of
553 19–118%) of the $\sigma_n^2(R_m)$ out of the total variance. When SWC is close to average
554 levels, R_m is also close to zero, resulting in negligible percentage of $\sigma_n^2(R_m)$. In
555 this case, the soil water patterns are stable in time, the SA model performs well, and
556 there will be little differences between these two models. As is well known, the spatial
557 patterns in soil water content are inherently time unstable. For example, when
558 evapotranspiration becomes the dominant process at the small watershed scale, more
559 water will be lost in depressions due to the denser vegetation than on knolls (Millar,
560 1971; Biswas et al., 2012), effectively diminishing the spatial patterns and increasing
561 temporal instability. In this case, the $\sigma_n^2(R_m)$ accounts for more percentage of the
562 total variance (e.g., high up to 632%) and the TA model may outperform the SA
563 model. This explained why the outperformance of the TA model was more obvious in
564 the dry conditions. For the GENCAI network in Italy, although the $\sigma_n^2(R_m)$
565 accounted for 68% of the total variance, the performance of the TA model was
566 identical to the SA model. This was because there were no underlying spatial patterns
567 in the R_m . Similarly, because the first underlying spatial pattern (i.e., EOF1)
568 explained greater percentages of the $\sigma_n^2(R_m)$ at the Canadian site (44–61%) than the

569 Chinese site (23%), the outperformance of the TA model over the SA model was more
570 obvious at the former site (Fig. 9 and 10a). Therefore, the TA model is advantageous
571 only if the percentage of $\sigma_{\hat{n}}^2(R_m)$ out of the total variance is substantial and
572 underlying spatial patterns exist in the R_m .

573 The existence of underlying spatial patterns in the R_m is related to the controlling
574 factors, which may be scale-specific. At small scales, “static” factors such as the depth
575 to the CaCO_3 layer and SOC at the Canadian site may affect not only the time-stable
576 patterns but also the R_m . The persistent influence of “static” factors on the R_m
577 resulted in significant underlying spatial patterns in the R_m . Thus, the TA model
578 outperformed the SA model at the small scales. At large scales such as the basin scale
579 or greater, time-stable patterns may be controlled by, in addition to soil and
580 topography (Mittelbach and Seneviratne, 2012), the climate gradient (Sherratt and
581 Wheater, 1984); at those scales, R_m is more likely to be controlled by the
582 meteorological anomaly (i.e., spatially random variation) (Walsh and Mostek, 1980),
583 and the effects of soil and topography may be reduced. Consequently, spatial patterns
584 in the R_m may be weakened and the TA model may have no advantages over the SA
585 model such as for the Italian site.

586 The $M_{\hat{m}}$ and the underlying spatial patterns (EOF1) in the R_m were controlled
587 by the same spatial forcing (e.g., depth to CaCO_3 layer and SOC) at the Canadian site
588 (Table 1), and they were correlated with an R^2 of 0.83 for the near surface and 0.42 for
589 the root zone. Although the relationships between $M_{\hat{m}}$ and R_m were strong, they
590 were not strictly linear, suggesting that $M_{\hat{m}}$ and R_m were affected differently by

591 these factors. Therefore, the nonlinear relationship between $M_{\hat{m}}$ and R_m partially
592 contributed to the outperformance of the TA model over the SA model.

593 The relationship between the $S_{\hat{m}}$ and EC1 was better fitted by the cosine function
594 in the TA model than the SA model (Figs. 4b and 6b), with R^2 of 0.76 versus 0.73 in
595 the near surface and 0.88 versus 0.73 in the root zone. The reduced scatter in the $S_{\hat{m}}$
596 and EC1 relationship for the TA model may also partly explain the outperformance of
597 the TA model over the SA model.

598 Therefore, the outperformance of the TA model over the SA model depends on
599 counterbalance among the variance of R_m explained in the TA model, the linear
600 correlation between the $M_{\hat{m}}$ and EOF1 of the R_m , and the goodness of fit for the
601 $S_{\hat{m}}$ and EC1 relationship. For example, the variance of EOF1 in the R_m for the
602 near surface (i.e., 264%²) was much greater than that for the root zone (i.e., 43%²).
603 However, $M_{\hat{m}}$ and underlying spatial patterns (EOF1) in the R_m in the root zone
604 deviated more from a linear relationship, and the reduced scatter in the $S_{\hat{m}}$ and EC1
605 relationship in the TA model was more obviously in the root zone than in the near
606 surface. As a result, the outperformance of the TA model was comparable between the
607 near surface and root zone at the Canadian site (Fig. 9).

608 In the real world, the relations between the $M_{\hat{m}}$ and underlying spatial patterns in
609 the R_m may rarely be perfectly linear. Therefore, when underlying spatial patterns
610 exist in the R_m and the R_m has substantial variances, the TA model is preferable
611 to the SA model for the estimation of spatially distributed SWC. On the **other hand**,
612 when underlying spatial patterns **do** not exist in the R_m or the R_m has negligible

613 variances, the SA model may be selected although these two models yield the same
614 quality of SWC estimation. This is because the TA model needs one more spatial
615 parameter (i.e., M_{in}) than the SA model.

616 Previous studies on SWC decomposition mainly focus on near surface layers
617 (Jawson and Niemann, 2007; Perry and Niemann, 2007, 2008; Joshi and Mohanty,
618 2010; Korres et al., 2010; Busch et al., 2012). This study decomposed spatiotemporal
619 SWC using the TA model for both the near surface and the root zone. The results
620 showed that the estimation of spatially distributed SWC at small watershed scales was
621 improved by the TA method that considers the R_m . The $\sigma_n^2(M_{in})$ was greater than
622 the $\sigma_n^2(R_m)$ (Fig. 5), indicating that time stability was more important than time
623 instability for SWC estimation. For the three dates in the fall (i.e., October 22, 2008,
624 August 27, 2009, and October 27, 2009), strong evapotranspiration and deep drainage
625 in depressions resulted in a much lower SWC at the near surface than in the spring.
626 This resulted in reduced time stability of SWC patterns and poor performance of both
627 models in terms of SWC evaluation (Fig. 8a). Because of the stronger time stability of
628 SWC in deeper soil layers (Biswas and Si, 2011), SWC evaluation was more accurate
629 for soil layers extending from the surface to greater depth. This is particularly
630 important because SWC data for deeper soil layers in a watershed is more difficult to
631 collect than that of surface soil.

632 **5 Conclusions**

633 The TA model was used to decompose spatiotemporal SWC into time-stable

634 patterns $M_{\hat{m}}$, space-invariant temporal anomaly $A_{\hat{m}}$, and space-variant temporal
635 anomaly R_m . This study indicated that underlying spatial patterns may exist in the
636 R_m at small scales (e.g., small watersheds and hillslope) but may not exist at large
637 scales such as the GENCAI network (~250 km²) in Italy. This was because the R_m
638 at small scales was driven by “static” factors such as depth to the CaCO₃ layer and
639 SOC at the Canadian site, while the R_m at large scales may be dominated by
640 “dynamic” factors such as meteorological anomaly. Compared to the SA model,
641 estimation of spatially distributed SWC was improved with the TA model at small
642 watershed scales. This was because the TA model considered a fair amount of spatial
643 variance in the R_m , which was ignored in the SA model. Furthermore, the improved
644 performance was observed mainly when there was less or more soil water than the
645 average level, especially in drier conditions due to the high $\sigma_n^2(R_m)$ value.

646 This study showed that outperformance of the TA model over the SA model is
647 possible when $\sigma_n^2(R_m)$ accounts for substantial variance of SWC, and significant
648 spatial patterns (or EOFs) exist in the R_m . Further application of the TA model for
649 the estimation of spatially distributed SWC at different scales and hydrological
650 backgrounds is recommended. If the TA model parameters (i.e., $M_{\hat{m}}$, EOF1 of the
651 R_m , and relationship between EC and S_{in}) are obtained from historical in-situ SWC
652 datasets, a detailed spatially distributed SWC of near surface soil at watershed scales
653 can be constructed from remotely sensed SWC. Note that both models rely on
654 in-situ SWC measurements for model parameters. Therefore, future research should
655 be conducted to estimate spatially distributed SWC in un-gauged watersheds based on

656 the estimation of the model parameters using pedotransfer functions. The codes for
657 decomposing SWC with the SA and TA models and related EOF analysis were written
658 in Matlab and are freely available from the authors upon request.

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807 **Figure captions**

808 **Figure 1.** Decomposition of spatiotemporal soil water content (SWC) in different
809 models.

810 **Figure 2.** Daily mean air temperature and precipitation during the study period.

811 **Figure 3.** Components of soil water content in (a) the SA model (spatial mean soil
812 water content $S_{\hat{m}}$ and spatial anomaly Z_{tm}) and in (b) the TA model (time-stable
813 pattern $M_{\hat{m}}$, space-invariant temporal anomaly $A_{\hat{m}}$, and space-variant temporal
814 anomaly R_{tm}) for 0–0.2 and 0–1.0 m. Also shown is the elevation.

815 **Figure 4.** (a) The EOF1 of the spatial anomaly Z_{tm} and (b) relationships of
816 associated EC1 versus spatial mean soil water content Z_{tm} fitted by the cosine
817 function (Eq. 4).

818 **Figure 5.** Spatial variances of different components in Eq. (8) expressed in %² (upper
819 panel) and as percentage (lower panel) for (a) 0–0.2 and (b) 0–1.0 m. Spatial mean
820 soil water content $S_{\hat{m}}$ on each measurement day is also shown.

821 **Figure 6.** (a) The EOF1 of the space-variant temporal anomaly R_{tm} and (b)
822 relationships of associated EC1 versus spatial mean soil water content $S_{\hat{m}}$ fitted by
823 the cosine function (Eq. 4).

824 **Figure 7.** Estimated soil water content (SWC) versus measured SWC for three dates
825 at different soil water conditions (August 23, 2008, October 27, 2009, and May 13,
826 2011 are associated with relatively dry, medium, and wet days, respectively) using the
827 TA model for (a) 0–0.2 and (b) 0–1.0 m.

828 **Figure 8.** The Nash-Sutcliffe coefficient of efficiency (NSCE) of soil water content

829 estimation using the TA and SA models for (a) 0–0.2 and (b) 0–1.0 m for both cross
830 validation (CV) and split sample validation (SV). At 0–0.2 m, three dates (October 22,
831 2008, August 27, 2009, and October 27, 2009) as indicated by green lines present
832 negative NSCE values (-4.05, -1.83, and -3.81, respectively, for the CV on the three
833 dates; -2.63 and -5.12, respectively, for the SV on the latter two dates). Spatial mean
834 soil water content $S_{\hat{m}}$ on each measurement day is also shown.

835 **Figure 9.** Nash-Sutcliffe coefficient of efficiency (NSCE) difference between the TA
836 and SA models in terms of soil water content estimation using both cross validation
837 (CV) and split sample validation (SV) as a function of space-invariant temporal
838 anomaly $A_{\hat{m}}$ for (a) 0–0.2 and (b) 0–1.0 m.

839 **Figure 10.** Nash-Sutcliffe coefficient of efficiency (NSCE) difference between the TA
840 and SA models in terms of soil water content estimation using cross validation as a
841 function of space-invariant temporal anomaly $A_{\hat{m}}$ for (a) 0–0.06 m of the Chinese
842 Loess Plateau hillslope and (b) 0–0.15 m of the GENCAI network in Italy. The NSCE
843 values for both models are also shown.

Table 1. Pearson correlation coefficients between time-stable pattern $M_{\hat{m}}$, EOF1 of space-variant temporal anomaly R_m and various properties.

	0–0.2 m		0–1.0 m	
	$M_{\hat{m}}$	EOF1	$M_{\hat{m}}$	EOF1
Sand content	-0.52**	-0.36**	-0.66**	-0.26**
Silt content	0.29**	0.14	0.40**	0.06
Clay content	0.43**	0.38**	0.51**	0.33**
Organic carbon	0.78**	0.83**	0.73**	0.76**
Wetness index	0.64**	0.59**	0.68**	0.56**
Depth to CaCO ₃ layer	0.77**	0.84**	0.65**	0.88**
A horizon depth	0.51**	0.62**	0.44**	0.65**
C horizon depth	0.66**	0.69**	0.58**	0.76**
Bulk density	-0.58**	-0.67**	-0.46**	-0.62**
Elevation	-0.24**	-0.28**	-0.24**	-0.32**
Specific contributing area	0.20*	0.24**	0.24**	0.23**
Convergence index	-0.58**	-0.56**	-0.55**	-0.58**
Curvature	-0.10	-0.08	-0.19*	-0.16
Cos(aspect)	0.05	0.04	0.08	0.05
Gradient	-0.12	-0.09	-0.21*	-0.02
Slope	-0.51**	-0.48**	-0.56**	-0.44**
Upslope length	0.19*	0.21*	0.21*	0.25**
Solar radiation	-0.07	0.03	-0.11	0.08
Flow connectivity	0.45**	0.43**	0.49**	0.49**
Leaf area index	-0.07	0.06	-0.10	-0.14
Variance explained ¹	74.5%	81.6%	75.6%	81.0%

¹percent of variance explained by the controlling factors obtained by the multiple stepwise regressions.

*Significant at $P < 0.05$; ** Significant at $P < 0.01$.

Table A1. Notations.

$M_{\hat{m}}$	spatial mean of $M_{\hat{m}}$
R_{tn}	space-variant temporal anomaly of SWC at location n and time t
$A_{\hat{m}}$	space-invariant temporal anomaly of SWC at time t
Z_{tn}	spatial anomaly of SWC at location n and time t
$S_{\hat{m}}$	spatial mean SWC at time t
$\sigma_{\hat{n}}^2$	spatial variance
A_{tn}	temporal anomaly of SWC at location n and time t
$\delta_{\hat{m}}$	temporal mean relative difference of SWC at location n
COV	spatial covariance
S_{tn}	SWC at location n and time t
$M_{\hat{m}}$	time-stable pattern of SWC
ECs	temporally-varying coefficients of R_{tn} (or Z_{tn})
EOFs	time-invariant spatial structures of R_{tn} (or Z_{tn})
NSCE	Nash-Sutcliffe coefficient of efficiency
R	Pearson correlation coefficient
SWC	soil water content

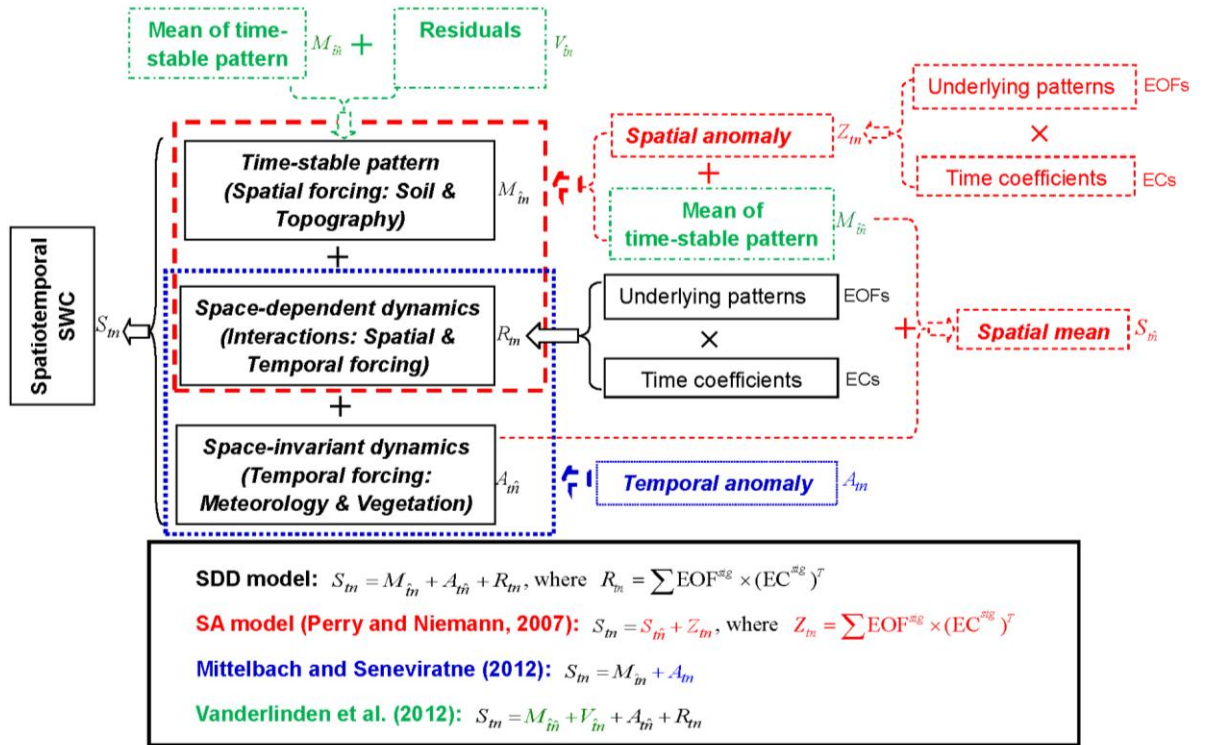


Fig. 1. Decomposition of spatiotemporal soil water content (SWC) in different models.

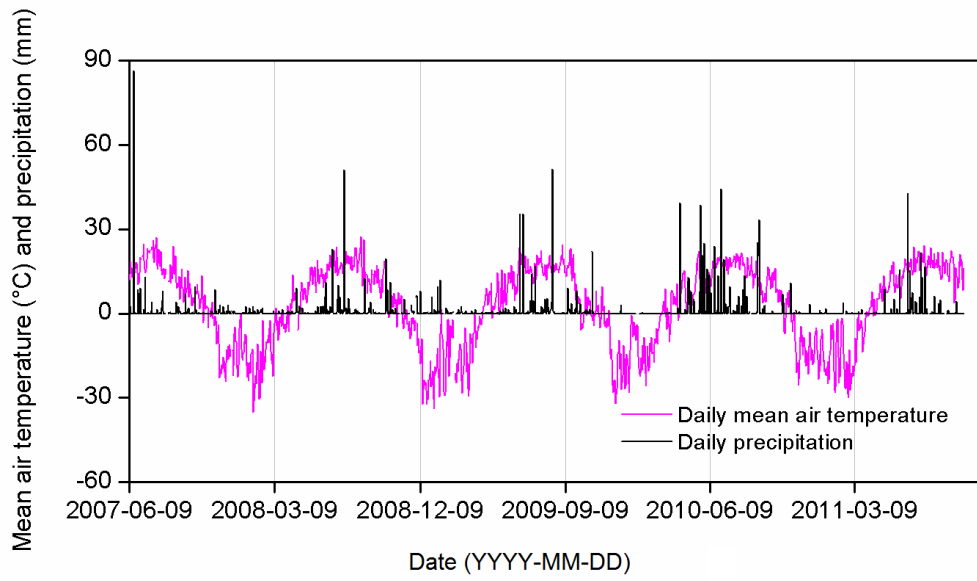


Fig. 2. Daily mean air temperature and precipitation during the study period.

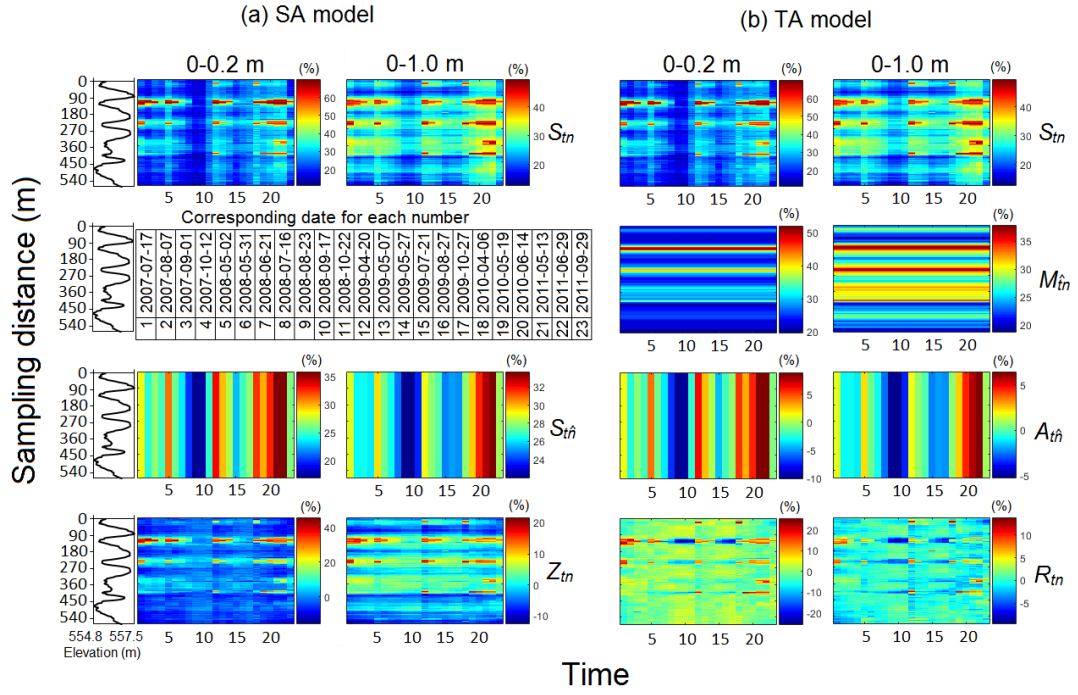


Fig. 3. Components of soil water content in (a) the SA model (spatial mean soil water content $S_{\hat{m}}$ and spatial anomaly $Z_{\hat{m}}$) and in (b) the TA model (time-stable pattern $M_{\hat{m}}$, space-invariant temporal anomaly $A_{\hat{m}}$, and space-variant temporal anomaly $R_{\hat{m}}$) for 0–0.2 and 0–1.0 m. Also shown is the elevation.

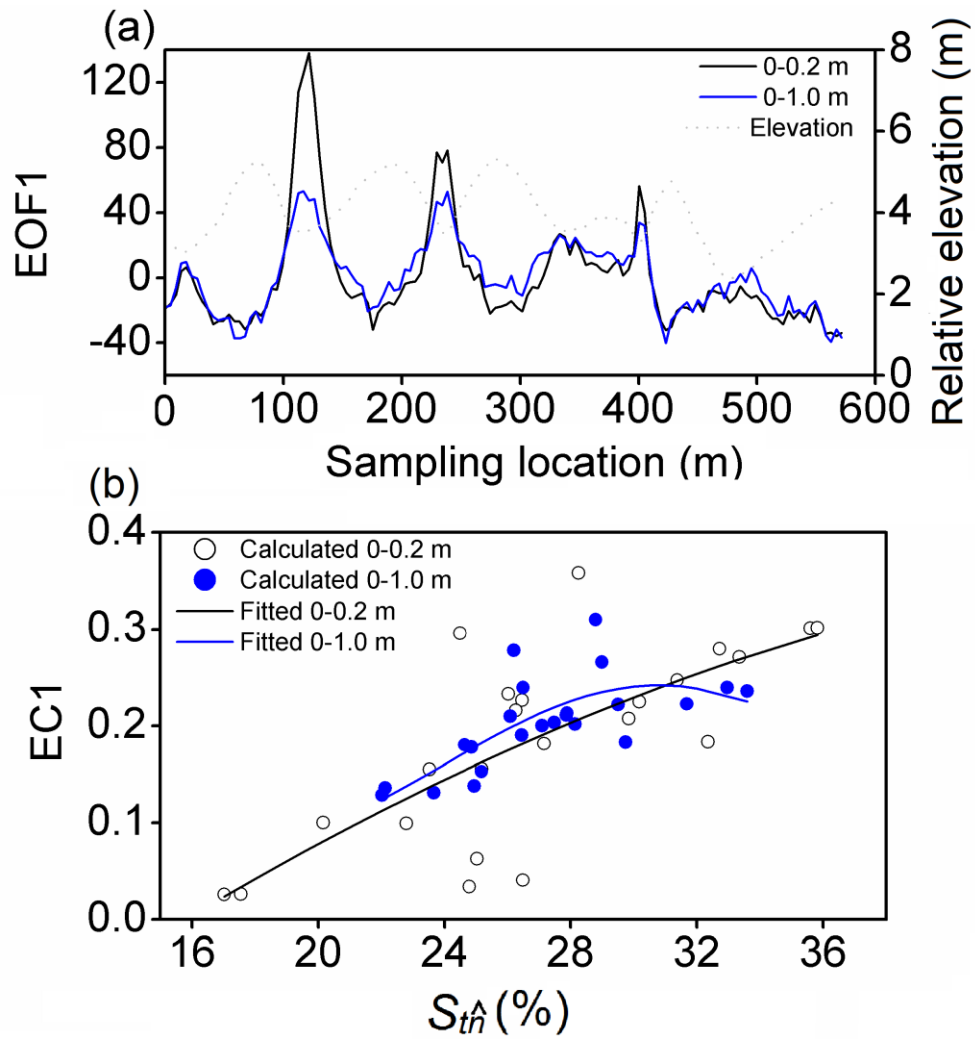


Fig. 4. (a) The EOF1 of the spatial anomaly Z_m and (b) relationships of associated EC1 versus spatial mean soil water content Z_m fitted by the cosine function (Eq. 4).

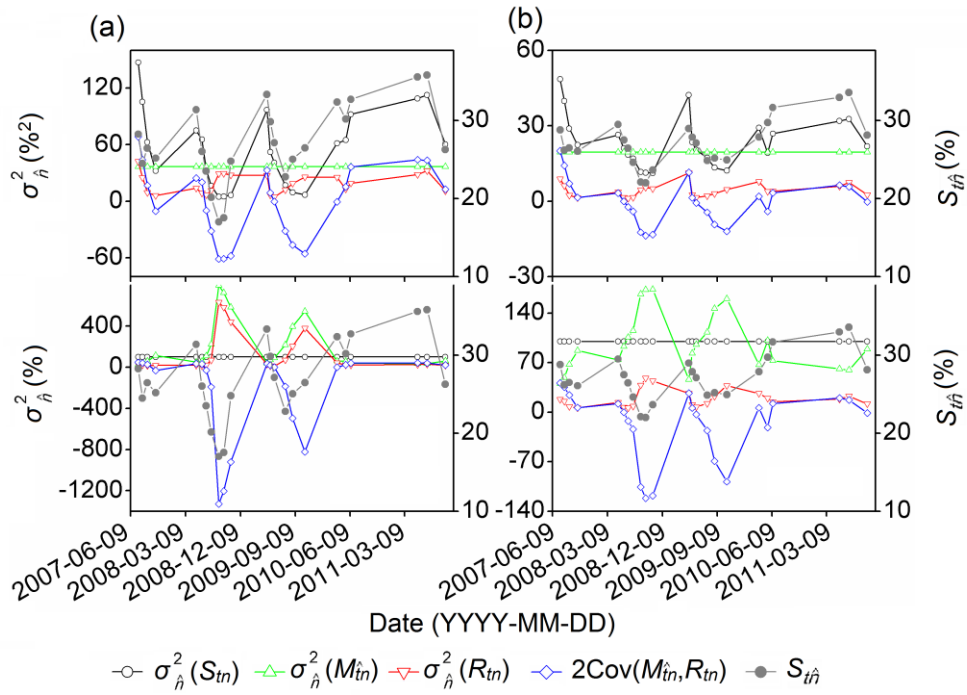


Fig. 5. Spatial variances of different components in Eq. (8) expressed in $\%^2$ (upper panel) and as percentage (lower panel) for (a) 0–0.2 and (b) 0–1.0 m. Spatial mean soil water content $S_{i\hat{h}}$ on each measurement day is also shown.

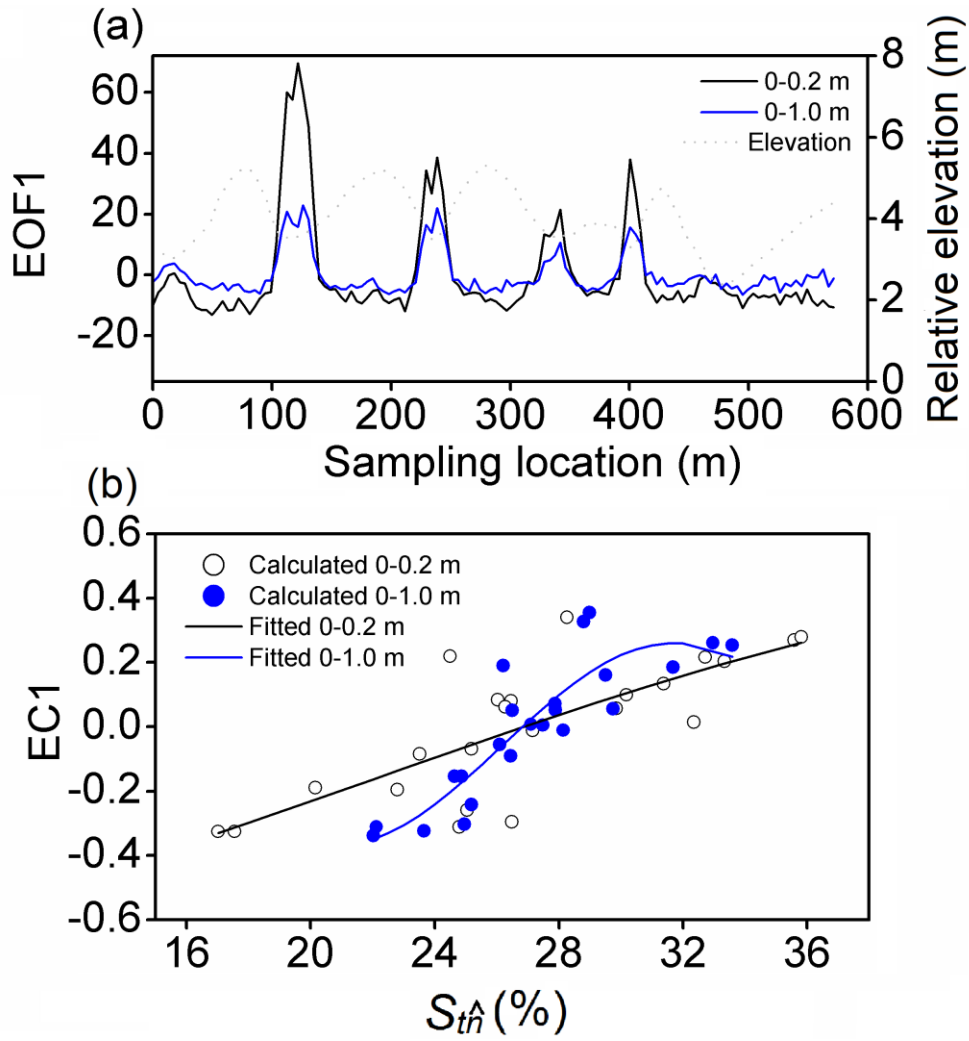


Fig. 6. (a) The EOF1 of the space-variant temporal anomaly R_{tn} and (b) relationships of associated EC1 versus spatial mean soil water content $S_{\hat{m}}$ fitted by the cosine function (Eq. 4).

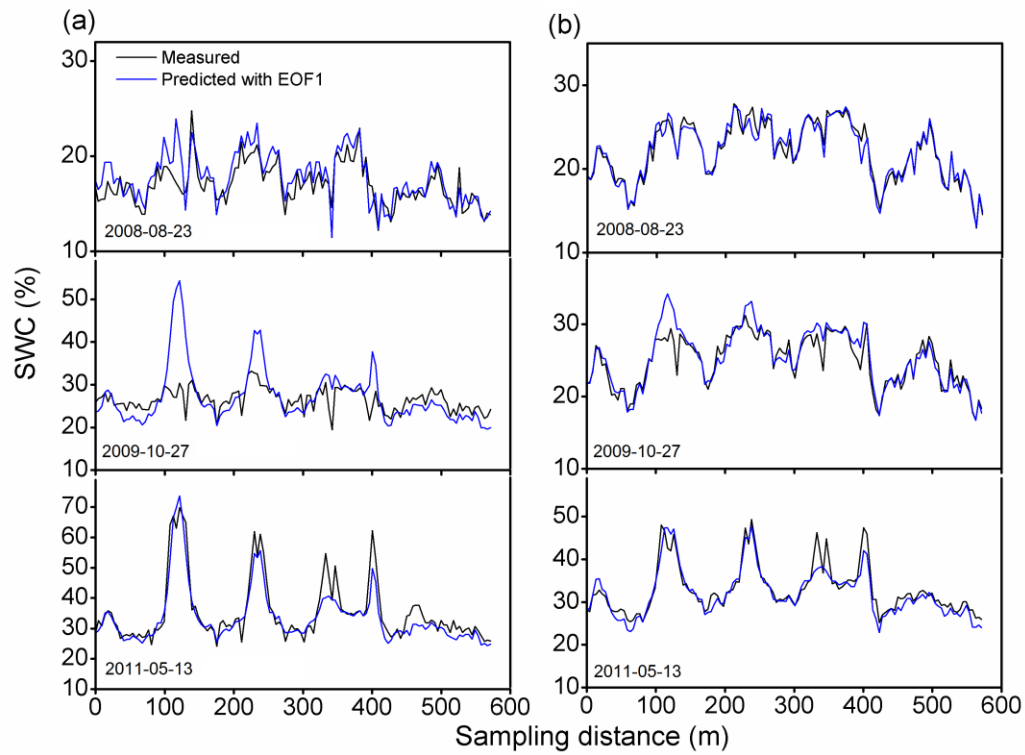


Fig. 7. Estimated soil water content (SWC) versus measured SWC for three dates at different soil water conditions (August 23, 2008, October 27, 2009, and May 13, 2011 are associated with relatively dry, medium, and wet days, respectively) using the TA model for (a) 0–0.2 and (b) 0–1.0 m.

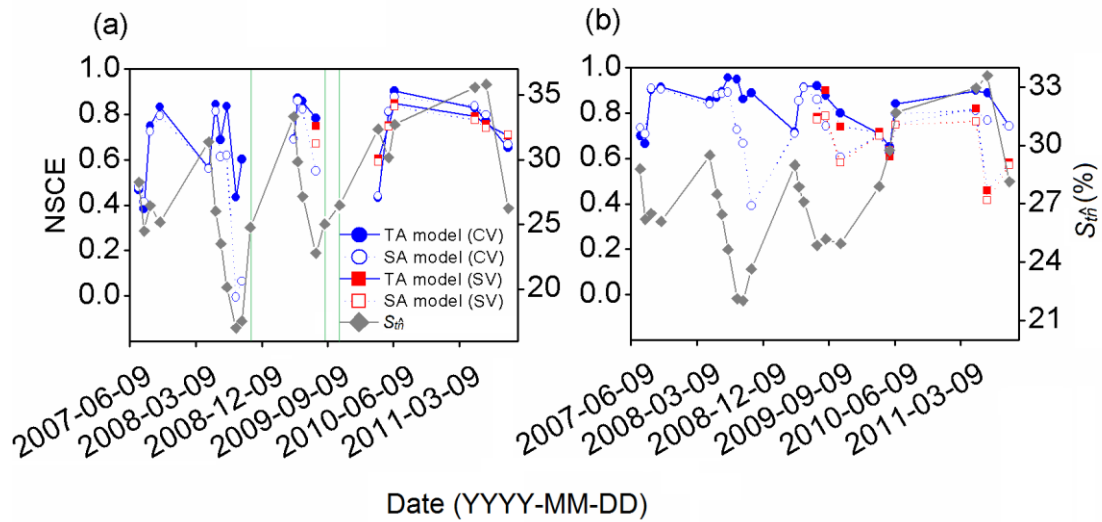


Fig. 8. The Nash-Sutcliffe coefficient of efficiency (NSCE) of soil water content estimation using the TA and SA models for (a) 0–0.2 and (b) 0–1.0 m for both cross validation (CV) and split sample validation (SV). At 0–0.2 m, three dates (October 22, 2008, August 27, 2009, and October 27, 2009) as indicated by green lines present negative NSCE values (-4.05, -1.83, and -3.81, respectively, for the CV on the three dates; -2.63 and -5.12, respectively, for the SV on the latter two dates). Spatial mean soil water content S_m on each measurement day is also shown.

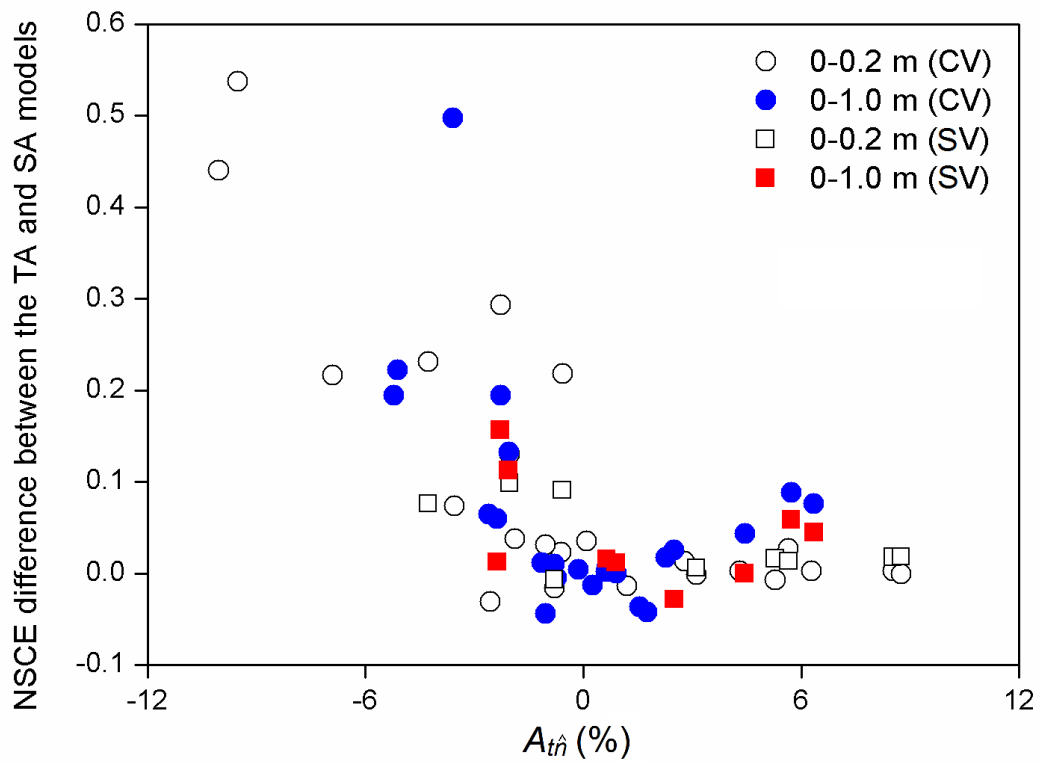


Fig. 9. Nash-Sutcliffe coefficient of efficiency (NSCE) difference between the TA and SA models in terms of soil water content estimation using both cross validation (CV) and split sample validation (SV) as a function of space-invariant temporal anomaly $A_{t\hat{n}}$ for (a) 0–0.2 and (b) 0–1.0 m.

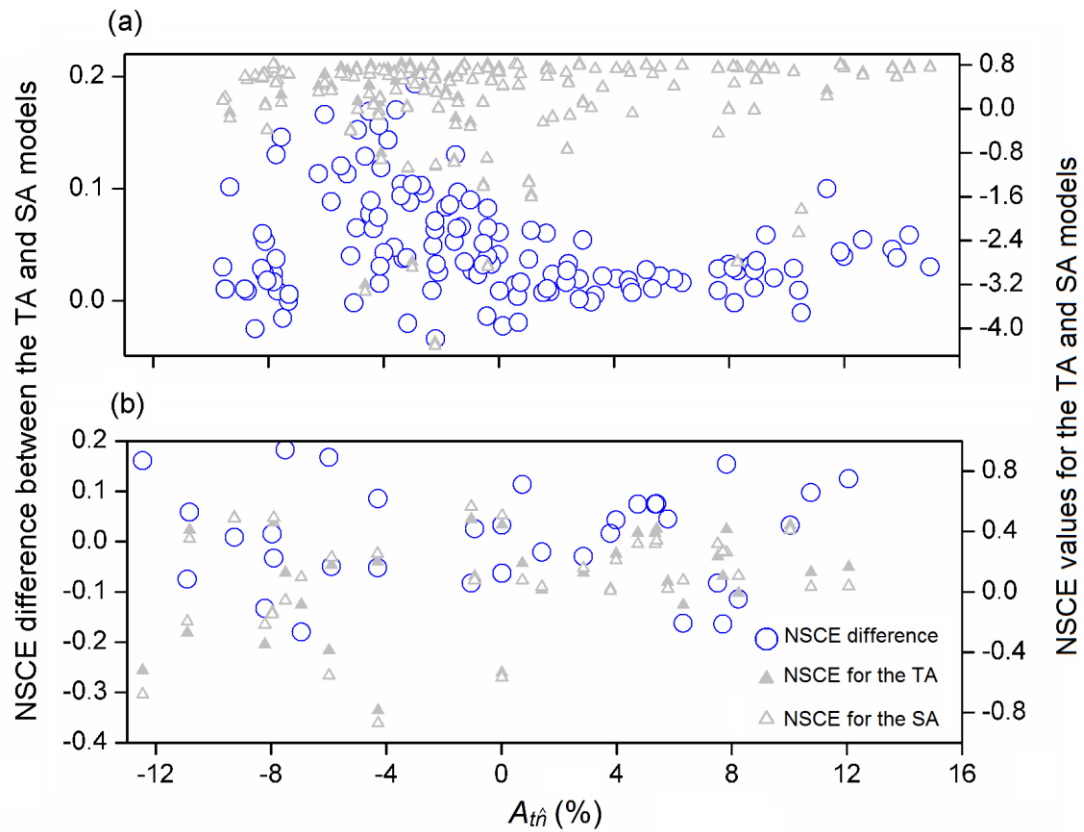


Fig. 10. Nash-Sutcliffe coefficient of efficiency (NSCE) difference between the TA and SA models in terms of soil water content estimation using cross validation as a function of space-invariant temporal anomaly $A_{t\hat{n}}$ for (a) 0–0.06 m of the Chinese Loess Plateau hillslope and (b) 0–0.15 m of the GENCAI network in Italy. The NSCE values for both models are also shown.