



Water balance with
cosmic-ray soil
moisture data

A. P. Schreiner-
McGraw et al.

This discussion paper is/has been under review for the journal Hydrology and Earth System Sciences (HESS). Please refer to the corresponding final paper in HESS if available.

Closing the water balance with cosmic-ray soil moisture measurements and assessing their spatial variability within two semiarid watersheds

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Received: 21 May 2015 – Accepted: 22 May 2015 – Published: 10 June 2015

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Published by Copernicus Publications on behalf of the European Geosciences Union.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Abstract

Soil moisture dynamics reflect the complex interactions of meteorological conditions with soil, vegetation and terrain properties. In this study, intermediate scale soil moisture estimates from the cosmic-ray sensing (CRS) method are evaluated for two semi-arid ecosystems in the southwestern United States: a mesquite savanna at the Santa Rita Experimental Range (SRER) and a mixed shrubland at the Jornada Experimental Range (JER). Evaluations of the CRS method are performed for small watersheds instrumented with a distributed sensor network consisting of soil moisture sensor profiles, an eddy covariance tower and runoff flumes used to close the water balance. We found an excellent agreement between the CRS method and the distributed sensor network (RMSE of 0.009 and 0.013 m³ m⁻³ at SRER and JER) at the hourly time scale over the 19-month study period, primarily due to the inclusion of 5 cm observations of shallow soil moisture. Good agreement was obtained in soil moisture changes estimated from the CRS and watershed water balance methods (RMSE = 0.001 and 0.038 m³ m⁻³ at SRER and JER), with deviations due to bypassing of the CRS measurement depth during large rainfall events. This limitation, however, was used to show that drier-than-average conditions at SRER promoted plant water uptake from deeper layers, while the wetter-than-average period at JER resulted in leakage towards deeper soils. Using the distributed sensor network, we quantified the spatial variability of soil moisture in the CRS footprint and the relation between evapotranspiration and soil moisture, in both cases finding similar predictive relations at both sites that are applicable to other semiarid ecosystems in the southwestern US. Furthermore, soil moisture spatial variability was related to evapotranspiration in a manner consistent with analytical relations derived using the CRS method, opening up new possibilities for understanding land-atmosphere interactions.

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)



[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



1 Introduction

Soil moisture is a key land surface variable that governs important processes such as the rainfall-runoff transformation, the partitioning of latent and sensible heat fluxes and the spatial distribution of vegetation in semiarid regions (e.g., Entekhabi, 1995; Eltahir, 1998; Vivoni, 2012). Semiarid watersheds with heterogeneous vegetation in the south-western United States (Gibbens and Beck, 1987; Browning et al., 2014) exhibit variations in soil moisture that challenge our ability to quantify land-atmosphere interactions and their role in hydrological processes (Dugas et al., 1996; Small and Kurc, 2003; Scott et al., 2006; Gutiérrez-Jurado et al., 2013; Pierini et al., 2014). Moreover, accurate measurements of soil moisture over scales relevant to land-atmosphere interactions in watersheds are difficult to obtain. Traditionally, soil moisture is measured continuously at single locations using techniques such as time domain reflectometry and then aggregated in space using a number of methods (Topp et al., 1980; Western et al., 2002; Vivoni et al., 2008b). Soil moisture is also estimated using satellite-based techniques, such as passive microwave sensors, but spatial resolutions are typically coarse and overpass times infrequent (e.g., Kustas et al., 1998; Moran et al., 2000; Narayan and Lakshmi, 2008), as compared to the spatiotemporal variability of soil moisture in semiarid watersheds.

One approach to address the scale gap in soil moisture estimation is through the use of cosmic-ray sensing (CRS) measurements (Zreda et al., 2008, 2012) that provide soil moisture with a measurement footprint of several hectares (Desilets et al., 2010). Developments of the CRS method have focused on understanding the processes affecting the measurement technique, for example, the effects of vegetation growth (Franz et al., 2013a; Coopersmith et al., 2014), atmospheric water vapor (Rosolem et al., 2013), soil wetting and drying (Franz et al., 2012a) and horizontal heterogeneity (Franz et al., 2013b). To date, the validation of the CRS method has been performed using single site measurements, aggregations of different measurement locations and particle transport models (Desilets et al., 2010; Franz et al., 2013b; Zhu et al., 2015). At the watershed

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



scale, however, the CRS method can also be validated based upon the application of the water balance equation, as performed for the eddy covariance (EC) technique often used to measure surface turbulent fluxes (Scott, 2010; Templeton et al., 2014). In small watersheds of comparable size to the CRS measurement footprint, the water balance can be expressed as:

$$z_m \frac{\Delta \theta}{\Delta t} = P - ET - Q - L, \quad (1)$$

where θ is volumetric soil moisture, P is precipitation, ET is evapotranspiration, Q is streamflow, and L is leakage, with all of the terms expressed as spatially-averaged quantities and valid over the effective soil measurement depth (z_m). Closing the water balance, or the estimation of each term of Eq. (1), would be a novel way for comparing the CRS method to independent observations valid at a commensurate spatial and temporal scale. Nevertheless, the application of Eq. (1) can be fraught with issues related to measurement limitations and representativeness or when spatially-averaged quantities are difficult to obtain in heterogeneous watersheds.

Soil moisture measurements at the intermediate scales provided by the CRS method do not capture the spatial variability within the measurement footprint (Zreda et al., 2008). As a result, distributed sensor networks consisting of different locations in a watershed are essential for establishing how the spatially-averaged properties are obtained (e.g., Franz et al., 2012b). Capturing the soil moisture spatial variability within a measurement footprint is also important for improving the representation of land-atmosphere interactions and hydrologic processes in models (Famiglietti and Wood, 1994; Bindlish et al., 2009; Mascaro and Vivoni, 2012). Based on prior studies using distributed sensor networks, the spatial variability of soil moisture is expected to increase with wetter spatially-averaged conditions in the range of values observed in semiarid areas (Famiglietti et al., 1999; Lawrence and Hornberger, 2007; Fernández and Ceballos, 2003; Vivoni et al., 2008b; Mascaro et al., 2011), as heterogeneities related to vegetation, terrain position and soil properties progressively lead to larger

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

and bare soil. Table 1 presents the vegetation and geomorphological properties for the site watersheds obtained from 1-m digital elevation models (DEMs) and 1 m vegetation maps (Fig. 2). Pierini et al. (2014) and Templeton et al. (2014) describe the image acquisition and processing methods employed to derive these products at SRER and JER, respectively.

2.2 Distributed sensor networks at the small watershed scale

Long-term watershed monitoring at the SRER and JER sites consisted of rainfall and runoff observations at Watersheds 7 and 8 (SRER, 1.25 ha) and the Tromble Weir (JER, 4.67 ha). Pierini et al. (2014) and Templeton et al. (2014) describe recent monitoring efforts using a network of rainfall, runoff, soil moisture and temperature observations as well as radiation and energy balance measurements at EC towers, commencing in 2011 and 2010 at SRER and JER. This brief description of the distributed sensor networks is focused on the spatially-averaged measurements used for comparisons to the CRS method. Precipitation (P) was measured using multiple tipping-bucket rain gauges (TE525MM, Texas Electronics) to construct a 30 min resolution spatial average based on Thiessen polygons within the watershed boundaries. At the watershed outlets, streamflow (Q) was estimated at Santa Rita supercritical runoff flumes (Smith et al., 1981) using a pressure transducer (CS450, Campbell Scientific Inc.) and an in situ linear calibration to obtain 30 min resolution observations. Evapotranspiration (ET) was obtained at 30 min resolution using the EC technique that employs a three-dimensional sonic anemometer (CSAT3, Campbell Scientific Inc.) and an open path infrared gas analyzer (LI-7500, LI-COR Inc.) installed at 7 min height on each tower. Flux corrections for the EC measurements followed Scott et al. (2004) and were verified using an energy balance closure approach reported in Table 2 for the study period. Energy balance closure at both sites is within the reported values across a range of other locations where the ratio of $\Sigma(\lambda E + H) / \Sigma(R_n - G)$ has an average value of 0.8 (Wilson et al., 2002; Scott, 2010). To summarize these observations, Fig. 3 shows the spatially-averaged P , Q and ET (mm h^{-1}), each aggregated to hourly resolution, at each study site during 1 March

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



2013 to 30 September 2014, along with seasonal precipitation amounts. While the results compare favorably to previous measurements (Turnbull et al., 2013; Pierini et al., 2014; Templeton et al., 2014), it should be noted that ET and Q data are assumed to represent the spatially-averaged watershed conditions, despite the small mismatch between the watershed boundaries and EC footprints (Fig. 2) and the summation of Q in the two watersheds at SRER.

Distributed soil moisture measurements were obtained using soil dielectric probes (Hydra Probe, Stevens Water) organized as profiles (sensors placed at 5, 15 and 30 cm depths) in each study site as: (1) at SRER, we installed three transects of 5 profiles each located under different vegetation classes (mesquite, grass, prickly pear and bare soil), and (2) at JER, we established three transects of 5 profiles each installed along different hillslopes (north-, south- and west-facing), as shown in Fig. 1. As described in Campbell (1990), individual sensors measure the impedance of an electric signal through a 40.3 cm^3 soil volume (5.7 cm in length and 3.0 cm in diameter) to determine the volumetric soil moisture (θ) in $\text{m}^3 \text{ m}^{-3}$ and soil temperature in $^\circ\text{C}$ as 30 min averaged values. A “loam” calibration equation was used in the conversion to θ (Seyfried et al., 2005) and corrected using relations established through gravimetric soil sampling at each study site (a power law relation at SRER with $R^2 = 0.99$ and a linear relation at JER with $R^2 = 0.97$), following Pierini (2013). Spatial averaging of the sensor profiles within the watersheds aggregated to an hourly resolution was performed using a specific weighting scheme for each site based on the main controls on the soil moisture distribution depending on watershed characteristics: (1) at SRER, we utilized the percentage area of each vegetation class (Table 1) and the associated sensor locations within each type (Pierini et al., 2014), and (2) at JER, we accounted for the aspect and elevation at the sensor locations and used these to extrapolate to other locations with similar characteristics based on the 1-m DEM (Templeton et al., 2014).

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



2.3 Cosmic-ray soil moisture sensing method

The CRS method relates soil moisture to the density of fast or moderated neutrons (Zreda et al., 2008) measured above the soil surface. A cosmic-ray neutron sensor (CRS-1000/B, Hydroinnova LLC) was installed in each watershed in January 2013 to record neutron counts at hourly intervals. We selected the study period (1 March 2013 to 30 September 2014) to coincide with the availability of data from the distributed sensor networks. While the theory of using neutrons for soil moisture measurements has a long history (e.g., Gardner and Kirkham, 1952), recent developments in the measurement of neutrons generated from cosmic rays has increased the horizontal scale, reduced the need for manual sampling and led to a non-invasive approach. Zreda et al. (2008) and Desilets and Zreda (2013) describe the horizontal scale as having a radius of ~ 300 m at sea level and a vertical aggregation scale ranging from 12 to 76 cm depending on soil wetness. Since the travel speed of fast neutrons is > 10 km s⁻¹, neutron mixing occurs instantaneous in the air above the soil surface (Glasstone and Edlund, 1952), providing a well-mixed region that can be sampled with a single detector.

Using a particle transport model, Desilets et al. (2010) found a theoretical relationship between the neutron count rate at a detector and soil moisture for homogeneous SiO₂ sand:

$$\theta(N) = \frac{0.0808}{\left(\frac{N}{N_0}\right) - 0.372} - 0.115, \quad (2)$$

where θ (m³ m⁻³) is volumetric soil moisture, N is the neutron count rate (counts h⁻¹) normalized to the atmospheric pressure and solar activity level, and N_0 (counts h⁻¹) is the count rate over a dry soil under the same reference conditions. The corrections applied to the neutron count rate are detailed in Desilets and Zreda (2003) and Zreda et al. (2012) and are applied automatically in the COSMOS website (<http://cosmos.hwr.arizona.edu/>). Additionally, since neutron counts are affected by all sources of hydrogen in the support volume, we apply a correction (C_{WV}) for atmospheric water vapor that

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



(Anderson, 2013), with temporal changes occurring in the amount of overlap with the watersheds and CRS footprints. Nevertheless, the vegetation distributions sampled in the CRS, EC and watershed areas (Fig. 2) are nearly the same (Vivoni et al., 2014), such that CRS and EC measurements are considered representative of the watershed conditions. In contrast to the fixed horizontal scale, the CRS method measures a time-varying vertical scale that depends on the soil water content. Franz et al. (2012b) used a particle transport model to determine that the CRS measurement depth, z^* , varied with soil moisture as:

$$z^*(\theta) = \frac{5.8}{\rho_{bd}\tau + \theta + 0.0829}, \quad (4)$$

where ρ_{bd} is dry bulk density of the soil (1.535 g cm^{-3} at SRER and 1.300 g cm^{-3} at JER) and τ is the weight fraction of lattice water in the mineral grains and bound water, established at 0.02 g/g at each site given the weathered soils (Franz et al., 2012b). To account for this temporal variation, the distributed sensor profiles representing different soil layers (0–10, 10–20, and 20–40 cm in depth) were weighted based on z^* at each hourly time step according to:

$$wt(z) = a \left(1 - \left(\frac{z}{z^*} \right)^b \right) \text{ for } 0 \leq wt \leq z^*, \quad (5)$$

where $wt(z)$ is the weight at depth z , a is a constant defined to integrate the profile to unity ($a = 1 / \left(z^* - \left(z^{*b+1} / [z^{*b}(b+1)] \right) \right)$) and b controls the shape of the weighting function. For simplicity, we assumed a value of $b = 1$ leading to a linear relationship (Franz et al., 2012b).

2.4 CRS and distributed sensor network analyses methods

We compared hourly soil moisture observations obtained from the CRS method (θ_{CRS}) to estimates from the distributed sensor network (θ_{SN}) that have been averaged in

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



and soil below z^* . L is positive when there is leakage to deeper soil layers and negative when deeper water is being drawn to support plant transpiration.

2.5 Soil moisture variability and its link to evapotranspiration

The spatial variability within the CRS footprint was assessed using the distributed sensor network by constructing relations between the spatial standard deviation (σ) and coefficient of variation ($CV = \sigma / \langle \theta \rangle$) with the mean soil moisture state ($\langle \theta \rangle$), obtained either from the CRS method (θ_{CRS}) or distributed sensor network (θ_{SN}). Based on the methods proposed by Famiglietti et al. (2008), we fitted the following empirical functions to the observations at each site:

$$\sigma = k_1 \langle \theta \rangle e^{-k_2 \langle \theta \rangle} \quad (7)$$

and

$$CV = k_1 e^{-k_2 \langle \theta \rangle}, \quad (8)$$

where k_1 and k_2 are regression parameters, and compared these to prior studies in the region (e.g., Vivoni et al., 2008b; Mascaro and Vivoni, 2012; Stillman et al., 2014). Soil moisture at single locations is typically linked to evapotranspiration in hydrologic models (e.g., Chen et al., 1996; Ivanov et al., 2004) and empirical studies (e.g., Small and Kurc, 2003; Vivoni et al., 2008a) using relations such as $ET = f(\theta)$. For example, a commonly used approach is based on a piecewise linear relation between daily ET and θ (Rodríguez-Iturbe and Porporato, 2004):

$$ET(\theta) = \begin{cases} 0 & 0 < \theta \leq \theta_h \\ E_w \frac{\theta - \theta_h}{\theta_w - \theta_h} & \theta_h < \theta \leq \theta_w \\ E_w + (ET_{\max} - E_w) \frac{\theta - \theta_h}{\theta^* - \theta_h} & \theta_w < \theta \leq \theta^* \\ ET_{\max} & \theta^* < \theta \leq \varphi \end{cases}, \quad (9)$$

5355

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



dry less quickly during some rainfall events (i.e., overestimate soil moisture during recession limbs), possibly due to landscape features such as nearby channels (Fig. 1) that remain wetter than areas measured by the distributed sensor network. Overall, however, there is an excellent match between θ_{CRS} and θ_{SN} in terms of capturing the occurrence and magnitude of soil moisture peaks across the different seasons, thus reducing some issues noted by Franz et al. (2012b) with respect to a purported over-sensitivity of θ_{CRS} for small rainfall events (< 5 mm). We attribute this improvement primarily to including a 5 cm sensor in each profile that tracks the important soil moisture dynamics occurring in the shallow surface layer within semiarid ecosystems.

To complement this, Fig. 5 compares θ_{CRS} and θ_{SN} as a scatterplot along with the sample size (N) and the Standard Error of Estimates (SEE) which quantify the deviations from the 1 : 1 line. Table 3 provides the full set of statistical metrics for the comparison of θ_{CRS} versus θ_{SN} at the two study sites. The correspondence between both methods is excellent, with low RMSE and SEE, a high CC, and a Bias close to 1. These values are comparable to previous validation efforts where the RMSE was found to be $0.011 \text{ m}^3 \text{ m}^{-3}$ (Franz et al., 2012b) and less than $0.03 \text{ m}^3 \text{ m}^{-3}$ (Bogena et al., 2013; Coopersmith et al., 2014; Zhu et al., 2015). The comparison across the sites is also illustrative. Despite the more arid climate at JER (Table 1), the study period consisted of higher precipitation (247 mm) and higher soil moisture values during the summer ($0.085 \text{ m}^3 \text{ m}^{-3}$), as compared to SRER (170 mm, $0.065 \text{ m}^3 \text{ m}^{-3}$), indicating a more active North American monsoon in the Chihuahuan Desert. In contrast, the fall-winter period is generally drier at JER (21 mm, $0.039 \text{ m}^3 \text{ m}^{-3}$), as compared to SRER (99 mm, $0.057 \text{ m}^3 \text{ m}^{-3}$), where high P and low ET in the winter promoted infiltration beyond the CRS measurement depth, as observed at a 1-m sensor profile at SRER (not shown). These two effects are observed as larger range of soil moisture values in Fig. 5 for JER. It is also worth noting that θ_{CRS} has a larger dynamic range for dry conditions (i.e., θ_{CRS} values can reach zero, whereas θ_{SN} does not), indicating that the method overcomes the measurement limitations discussed by Vereecken et al. (2014). Based on these comparisons, the CRS method is found to be a reliable approach for mea-

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



overall ET, consistent with higher extractions from the CRS measurement depth due to the mesquite trees, extensive grass cover and higher soil evaporation.

We explore whether a daily relationship exists between the absolute (σ) and relative (CV) spatial variability of soil moisture and evapotranspiration in Fig. 11. Daily observations and bin-averages with standard deviations are derived entirely from the distributed sensor network and EC measurements. Given the relations linking σ and ET with the mean soil moisture (Figs. 9 and 10), the ET- σ relations exhibit an increase in ET with higher σ at both sites, though this is clearer at JER due to the wider range of θ_{SN} . This indicates that high absolute variability of soil moisture is associated with larger ET, likely due to the growth of wet patches supporting progressively more evapotranspiration. In contrast, the ET-CV relations exhibit a weaker negative trend such that a higher relative variability implies a lower ET. This occurs due to the role of the mean soil moisture state such that dry conditions have a relatively high CV (Fig. 9) and support a low ET (Fig. 10). Observations are compared to the analytical relations obtained by combining Eq. (9) with Eqs. (7) and (8) using θ_{CRS} as the spatially-averaged value for ET- σ and ET-CV, respectively (solid lines). While the analytical relations approximate the data fairly well, it is clear that the ET_{max} limit (horizontal lines) does not represent the growth of ET with higher σ and lower CV. Nevertheless, the analytical functions are a promising application of the CRS method that can yield valuable information for understanding land-atmosphere interactions, under the assumption the σ - θ and ET- θ relations have been established (e.g., Tables 5 and 6).

4 Summary and conclusions

In this study, we utilized distributed sensor networks to examine the cosmic-ray sensing (CRS) soil moisture method at the small watershed scale in two semiarid ecosystems of the southwestern US (Pierini et al., 2014; Templeton et al., 2014). To our knowledge, this is the first study to compare CRS measurements to two complementary approaches for obtaining spatially-averaged soil moisture at a commensurate scale:

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



consumed during the summer season by active plants. These novel inferences within the two ecosystems relied heavily on the application of the CRS method and its limited measurement depth to discriminate between shallow and deeper vadose zone processes as well as on the direct measurement of the water balance components, in particular evapotranspiration from the eddy covariance technique. It is important to keep in mind, however, that the ability to resolve watershed-scale hydrologic processes, such as the interaction between shallow and deep soil layers attributed to plant water uptake and leakage, depends to a large degree on the accuracy and representativeness of the distributed sensor network measurements and how their horizontal and vertical scales overlap with the CRS measurement footprint. We expect these limitations to be especially critical in semiarid ecosystems with high spatial heterogeneity induced by vegetation and bare soil patches.

The collocation of a distributed sensor network within the CRS measurement footprint allowed us to examine important process-based relations often incorporated into hydrologic models or remote sensing analyses (e.g., Famiglietti and Wood, 1994; Famiglietti et al., 2008). The spatial variability of soil moisture is linked to the spatially-averaged conditions through predictable relations that do not vary significantly across the study sites. For higher mean soil moisture, we observed a near linear increase in spatial variability followed by an asymptotic behavior attributed to the seasonally-wet conditions during the North American monsoon. Based on these relations (k_1 and k_2), the spatial variability within a CRS measurement footprint can be approximated for other semiarid ecosystems in the region. In addition, combining fixed and mobile CRS methods can establish landscape scale (10^2 to 10^3 km²) soil moisture monitoring networks at grid sizes (~ 1 km²) comparable to land surface modeling (Franz et al. 2015). Similarly, intermediate scale soil moisture sensing can be linked effectively to daily evapotranspiration and used to obtain soil and vegetation parameters (E_w , ET_{max} , θ_h , θ_w , and θ^*) tailored to each ecosystem. In term of the ET- θ relation, the CRS method has the potential to significantly improve land-atmosphere interaction studies through the commensurate scale achieved to the EC technique. Furthermore, we found

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



that analytical relations linking soil moisture spatial variability with evapotranspiration exhibit similar characteristics to the observed datasets. As the spatial variability in soil moisture grows in the two semiarid ecosystems there is a concomitant increase in evapotranspiration. While this suggests that wet patches in a drier background sustain higher atmospheric losses, further investigations are needed to disentangle the individual roles of soil evaporation and plant water uptake on setting both the soil moisture spatial variability and the resulting evapotranspiration averaged in its measurement footprint.

Acknowledgements. We thank Mitch P. McClaran and Mark Heitlinger from the University of Arizona for help at the Santa Rita Experimental Range and John Anderson, Al Rango and other staff members at the USDA-ARS Jornada Experimental Range for their assistance. We thank funding from the US Army Research Office (Grant 56059-EV-PCS) and the Jornada Long-Term Ecological Research project (National Science Foundation Grant DEB-1235828). We also thank Nicole A. Pierini and Cody A. Anderson for help with field activities.

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Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



- Glasstone, S. and M. C. Edlund: Elements of Nuclear Reactor Theory, Van Nostrand, New York, 416 pp., 1952.
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- 30

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



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Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



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Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Table 1. Watershed and precipitation characteristics at the SRER and JER sites. Precipitation values are long-term averages (1923–2014 at SRER and 1915–2006 at JER) for annual and seasonal quantities, defined as fall (October–December), winter (January–March), spring (April–June) and summer (July–September).

Characteristic (unit)	Value	SRER	JER
Watershed area (m ²)		12 535	46734
Elevation (m)	mean	1166.6	1458.3
	max	1171.1	1467.5
	min	1160.9	1450.5
Slope (degree)	mean	3.2	3.9
	max	19.2	45
	min	2.1	0
Drainage density (1/m)		0.04	0.03
Major vegetation type (%)	shrubs	32 %	27 %
	cacti	6 %	1 %
	grasses	37 %	6 %
	bare soil	25 %	66 %
Precipitation (mm)	annual	364	251
	fall	72	54
	winter	69	31
	spring	26	32
	summer	197	134

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Table 2. Energy balance closure at SRER and JER using 30 min net radiation (R_n), ground (G), latent (λE) and sensible (H) heat fluxes. The parameters m and b are the slope and intercept in the relation $\lambda E + H = m(R_n - G) + b$, while the ratio of the sum of ($\lambda E + H$) to the sum of ($R_n - G$) is a measure of how much available energy is accounted for in the turbulent fluxes.

Site	$\lambda E + H = m(R_n - G) + b$		$\frac{\sum \lambda E + H}{\sum R_n - G}$
	m	b	
SRER	0.72	17	0.85
JER	0.72	9.9	0.82

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Table 3. Statistical comparisons of CRS method with distributed sensor network and water balance estimates based on the Standard Error of Estimates, $SEE = \sqrt{\frac{\sum(\theta_{SN} - \theta_{CRS})^2}{N}}$, Root Mean Square Error, $RMSE = \sqrt{\frac{\sum(\theta'_{CRS} - \theta_{CRS})^2}{N}}$ where θ'_{CRS} is the predicted value of θ_{CRS} based on the best fit line with θ_{SN} , Bias, $B = \frac{\overline{\theta_{CRS}}}{\overline{\theta_{SN}}}$ and Correlation Coefficient, $CC = \frac{\sum_{i=1}^N (\theta_{CRS,i} - \overline{\theta_{CRS}})(\theta_{SN,i} - \overline{\theta_{SN}})}{\left[\sum_{i=1}^N (\theta_{CRS,i} - \overline{\theta_{CRS}})^2\right]^{0.5} \left[\sum_{i=1}^N (\theta_{SN,i} - \overline{\theta_{SN}})^2\right]^{0.5}}$ where $\overline{\theta_{CRS}}$ and $\overline{\theta_{SN}}$ represent the mean soil moisture for each measurement method and N is the number of samples. Values in parentheses for JER indicate metrics when large rainfall events are excluded.

Metric (unit)	SRER	JER
θ_{CRS} versus θ_{SN}		
RMSE ($m^3 m^{-3}$)	0.009	0.013
CC	0.949	0.946
B	1.117	1.019
SEE ($m^3 m^{-3}$)	0.012	0.013
$\Delta\theta_{CRS}$ versus $\Delta\theta_{WB}$		
RMSE ($m^3 m^{-3}$)	0.001	0.038 (0.019)
CC	0.954	0.945 (0.946)
B	1.167	0.702 (0.903)
SEE ($m^3 m^{-3}$)	0.020	0.049 (0.020)

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

[Title Page](#)

[Abstract](#)

[Introduction](#)

[Conclusions](#)

[References](#)

[Tables](#)

[Figures](#)

[⏪](#)

[⏩](#)

[◀](#)

[▶](#)

[Back](#)

[Close](#)

[Full Screen / Esc](#)

[Printer-friendly Version](#)

[Interactive Discussion](#)



Table 4. Total water flux estimates from daily CRS soil water balance method (f_{CRS}) and daily sensor measurements during study period at the SRER and JER sites. P is from rain gauge measurements in both cases. L in CRS is computed as $O - ET$ where ET is from EC method, while L in sensor estimates is calculated from solving the water balance.

Water flux	SRER	JER
CRS estimates		
Precipitation (P , mm)	464	533
Infiltration (I , mm)	357	477
Outflow (O , mm)	391	482
Leakage (L , mm)	−56	193
Outflow ratio (O / P)	0.84	0.90
Runoff ratio (Q / P)	0.23	0.11
Sensor estimates		
Precipitation (P , mm)	464	533
Storage change ($\Delta\theta$, mm)	−13	26
Outflow (O , mm)	437	506
Leakage (L , mm)	−10	217
Evapotranspiration (ET, mm)	447	289
Evaporation ratio (ET / P)	0.96	0.54
Outflow ratio (O / P)	0.94	0.95
Streamflow (Q , mm)	64	5
Runoff ratio (Q / P)	0.14	0.01

HESSD

12, 5343–5388, 2015

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Table 5. Regression parameters for the relations of the spatial variability of soil moisture (σ and CV) and $\langle \theta \rangle$ at the SRER and JER sites along with the RMSE of the regressions.

Relation	SRER			JER		
	k_1	k_2	RMSE	k_1	k_2	RMSE
$\sigma - \theta_{\text{SN}}$	0.75	4.23	$0.007 \text{ m}^3 \text{ m}^{-3}$	0.74	2.75	$0.005 \text{ m}^3 \text{ m}^{-3}$
$\sigma - \theta_{\text{CRS}}$	0.57	1.80	$0.007 \text{ m}^3 \text{ m}^{-3}$	0.65	1.81	$0.007 \text{ m}^3 \text{ m}^{-3}$
CV - θ_{SN}	0.78	5.40	0.145	0.72	2.48	0.067
CV - θ_{CRS}	0.87	6.36	0.020	0.72	2.24	0.071

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

Table 6. Regression parameters for the relations of evapotranspiration and soil moisture (θ_{SN} and θ_{CRS}) at the SRER and JER sites along with the RMSE of the regressions. $\theta_{\text{h}} = 0$ in all cases.

Site	Relation	ET_{max} (mm d ⁻¹)	E_{w} (mm d ⁻¹)	θ_{w} (m ³ m ⁻³)	θ^* (m ³ m ⁻³)	RMSE (mm d ⁻¹)
SRER	ET- θ_{SN}	2.61	0.41	0.03	0.07	1.15
	ET- θ_{CRS}	2.40	0.36	0.02	0.08	0.55
JER	ET- θ_{SN}	2.16	0.18	0.03	0.12	0.34
	ET- θ_{CRS}	2.17	0.21	0.03	0.13	0.34

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)

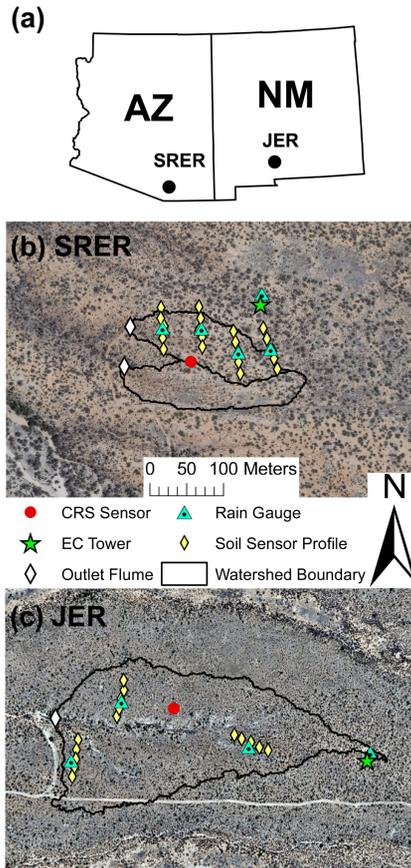



Figure 1. (a) Location of the study sites in Arizona and New Mexico. Watershed representations and sensor locations at (b) SRER and (c) JER, shown at the same scale.

Water balance with cosmic-ray soil moisture data

A. P. Schreiner-McGraw et al.

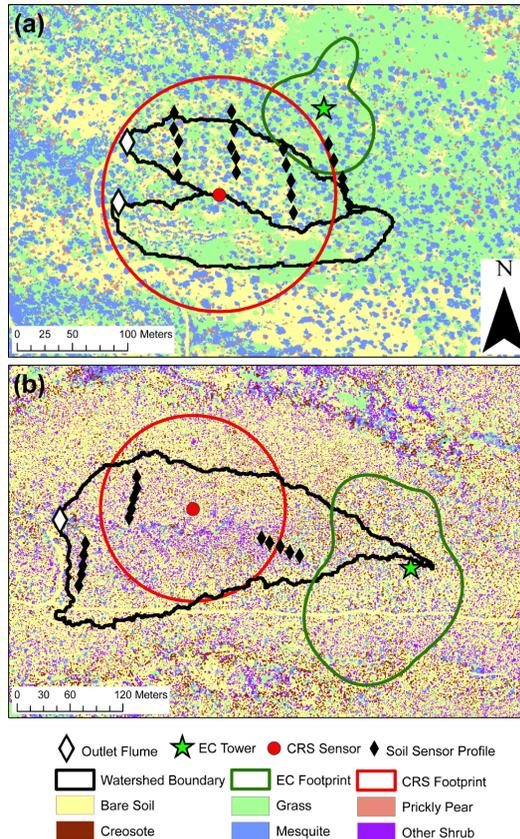


Figure 2. Vegetation classification for **(a)** SRER and **(b)** JER derived from aerial image analyses along with sensor locations and the 50 % contributing areas of the CRS and EC footprints.

[Title Page](#)
[Abstract](#) [Introduction](#)
[Conclusions](#) [References](#)
[Tables](#) [Figures](#)
[◀](#) [▶](#)
[◀](#) [▶](#)
[Back](#) [Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)



Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

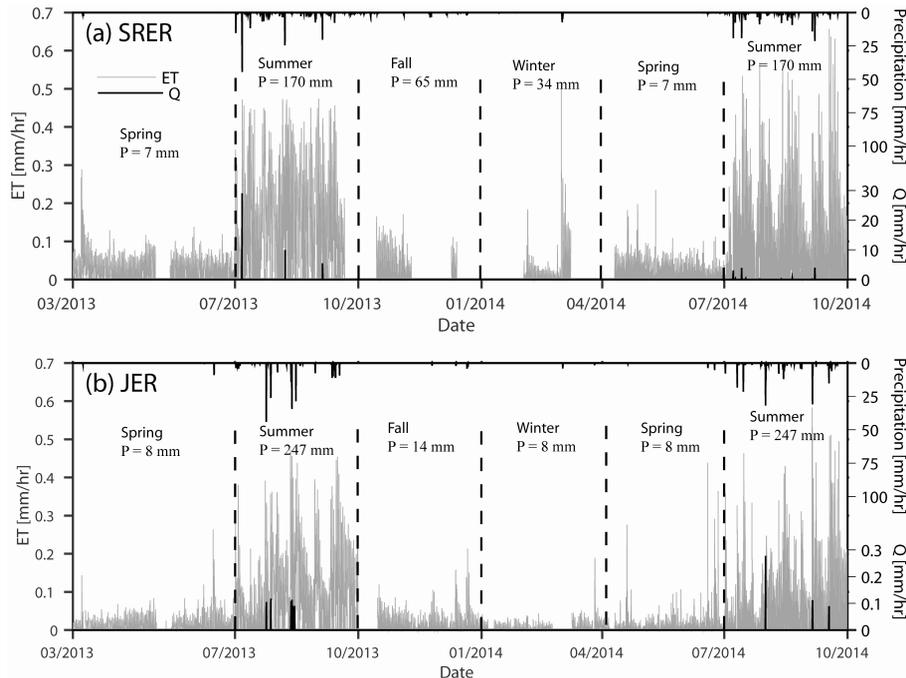


Figure 3. Hourly precipitation, streamflow and evapotranspiration at the (a) SRER and (b) JER sites during the study period (March 2013 to September 2014). Gaps in ET data indicate periods of EC tower malfunction due to equipment failures, data collection problems or vandalism. Vertical dashed lines indicate the seasonal definitions and their corresponding total precipitation.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

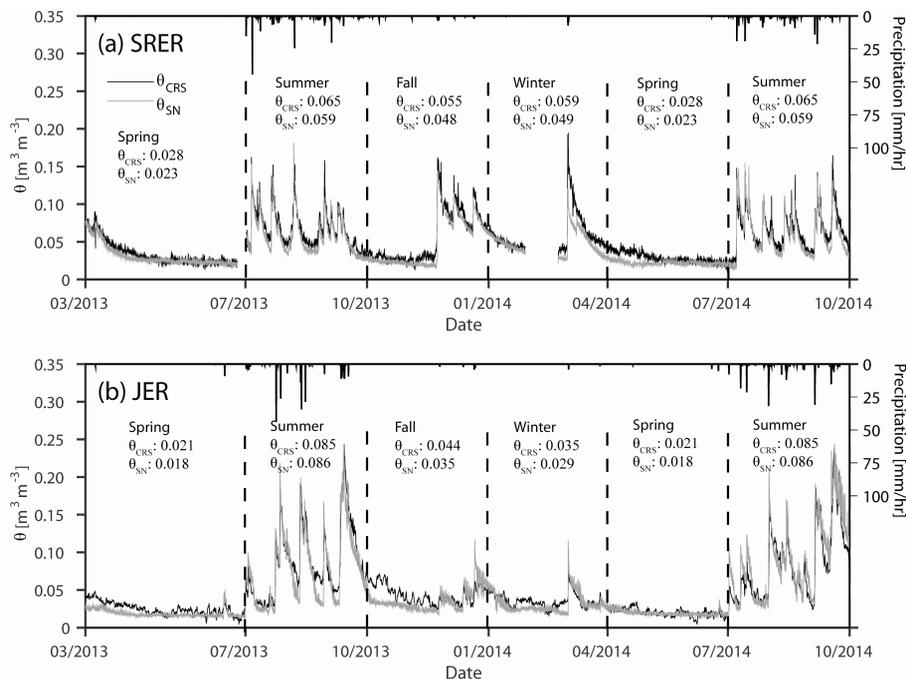


Figure 4. Comparison of the spatially-averaged, hourly soil moisture ($\text{m}^3 \text{m}^{-3}$) from CRS method (θ_{CRS} , black lines) and distributed sensor network (θ_{SN} , gray lines) at **(a)** SRER and **(b)** JER, along with spatially-averaged, hourly precipitation during 1 March 2013 to 30 September 2014. Vertical dashed lines indicate the seasonal definitions and their corresponding seasonally-averaged θ_{CRS} and θ_{SN} in $\text{m}^3 \text{m}^{-3}$.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

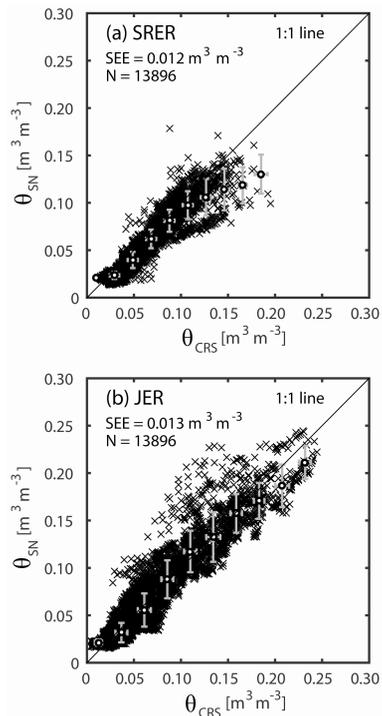


Figure 5. Scatterplots of the spatially-averaged, hourly soil moisture ($\text{m}^3 \text{m}^{-3}$) from CRS method (θ_{CRS}) and distributed sensor network (θ_{SN}) at **(a)** SRER and **(b)** JER. The SEE and the number of hourly samples (N) are shown for each site. Bin averages and ± 1 standard deviation are shown (circles and error bars) for bin widths of $0.025 \text{ m}^3 \text{m}^{-3}$ for each estimate.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[⏴](#)
[⏵](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

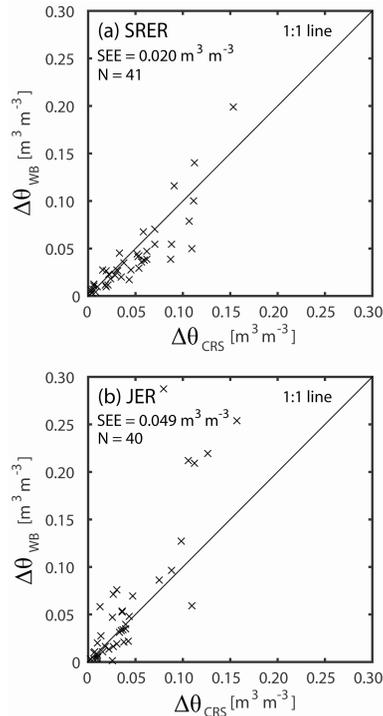


Figure 6. Scatterplots of the spatially-averaged change in soil moisture ($\text{m}^3 \text{m}^{-3}$) derived from CRS method ($\Delta\theta_{\text{CRS}}$) and the application of the water balance ($\Delta\theta_{\text{WB}}$) at (a) SRER and (b) JER. The SEE and the number of event samples (N) are shown for each site.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

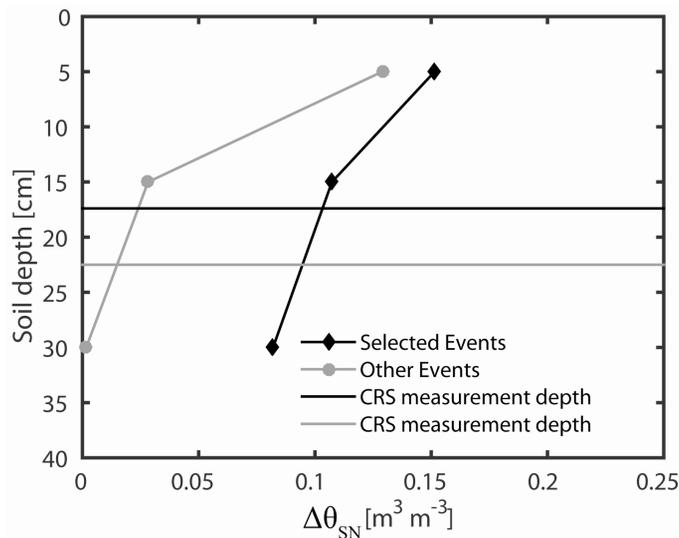


Figure 7. Change in soil moisture ($\Delta\theta_{SN}$) at depths of 5, 15 and 30 cm at the JER for the five large events (“Selected Events”) and the remaining (“Other Events”) cases. Horizontal lines are the CRS measurement depths averaged over the corresponding cases (black is Selected Events, gray is Other Events).

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

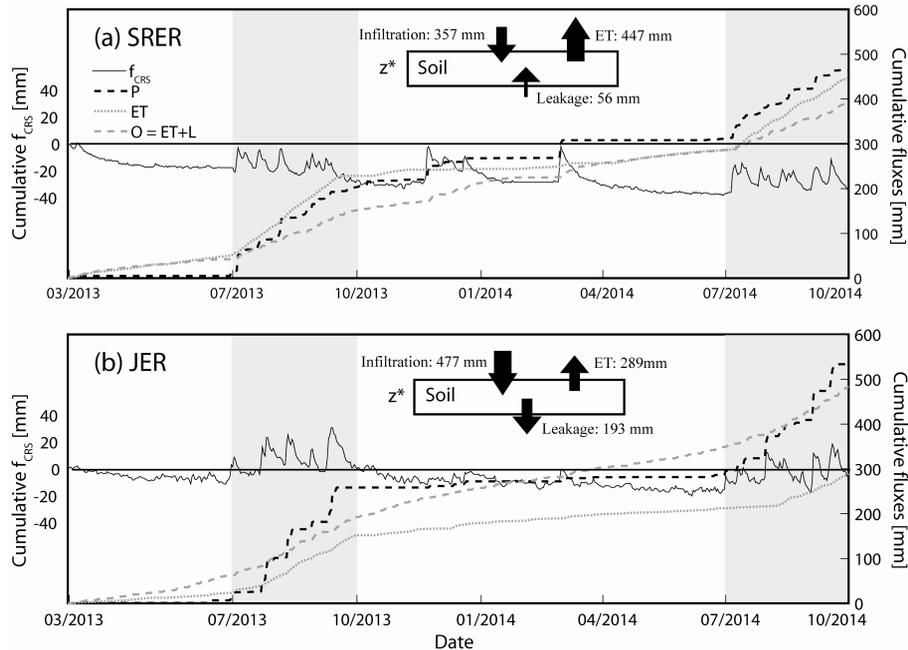


Figure 8. Comparison of cumulative f_{CRS} and measured water balance fluxes (P and ET) during study period. CRS estimates of infiltration (I), outflow (O) and leakage (L) are either depicted as cumulative fluxes ($O = ET + L$) or as total amounts during the study period (I and L) as arrows in the soil water balance box of depth z^* . Shaded regions indicate the summer seasons (July–September). The horizontal line represents $f_{\text{CRS}} = 0$.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)

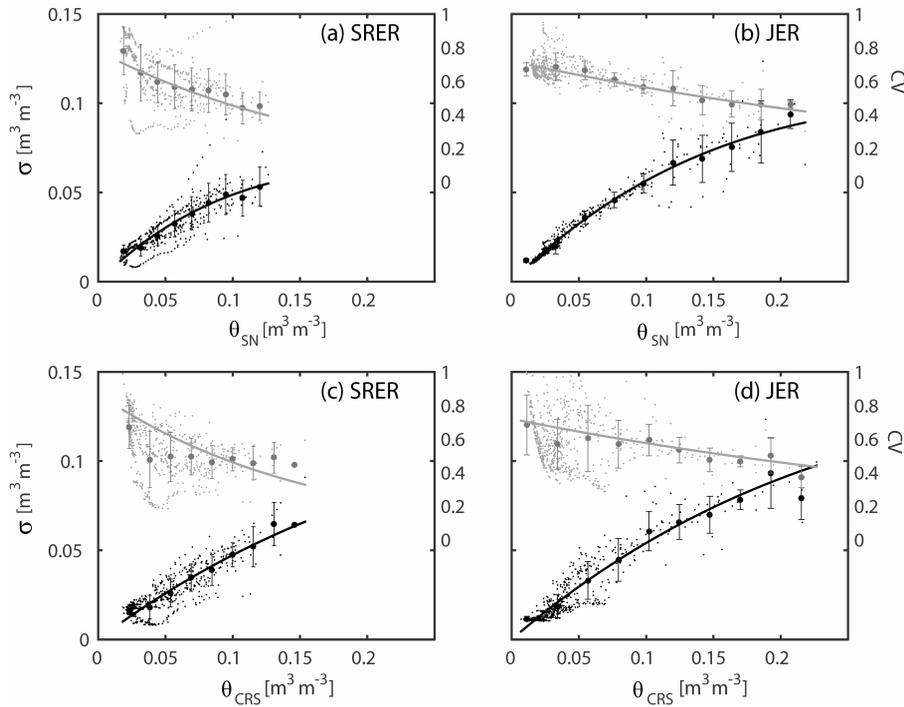


Figure 9. Soil moisture spatial variability as a function of the spatially-averaged distributed sensor network (θ_{SN} , top) and the CRS method (θ_{CRS} , bottom) for **(a, c)** SRER and **(b, d)** JER. Black symbols represent the standard deviation (σ) and gray symbols depict the coefficient of variation (CV). Bin averages and ± 1 standard deviation are shown (circles and error bars) for bin widths of $0.015 \text{ m}^3 \text{ m}^{-3}$ at SRER and $0.025 \text{ m}^3 \text{ m}^{-3}$ at JER. Regressions for the relations of σ and CV with $\langle \theta \rangle$ are valid for the entire dataset.

**Water balance with
cosmic-ray soil
moisture data**

A. P. Schreiner-
McGraw et al.

Title Page

Abstract Introduction

Conclusions References

Tables Figures

⏪ ⏩

◀ ▶

Back Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

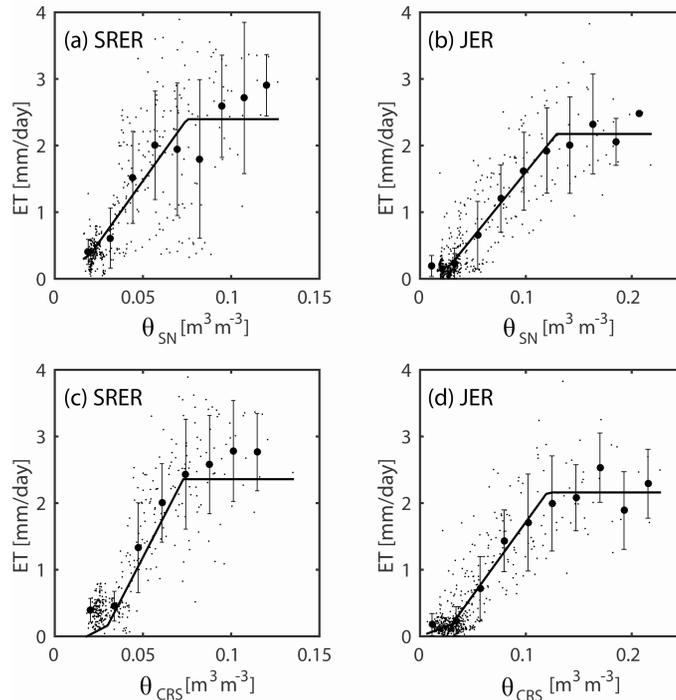


Figure 10. Evapotranspiration relation with the spatially-averaged distributed sensor network (θ_{SN} , top) and the CRS method (θ_{CRS} , bottom) for **(a, c)** SRER and **(b, d)** JER. Bin averages and ± 1 standard deviation are shown (circles and error bars) for bin widths of $0.015 m^3 m^{-3}$ at SRER and $0.025 m^3 m^{-3}$ at JER. Regressions for the relations of ET with $\langle \theta \rangle$ are valid for the entire dataset.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Water balance with cosmic-ray soil moisture data

A. P. Schreiner-
McGraw et al.

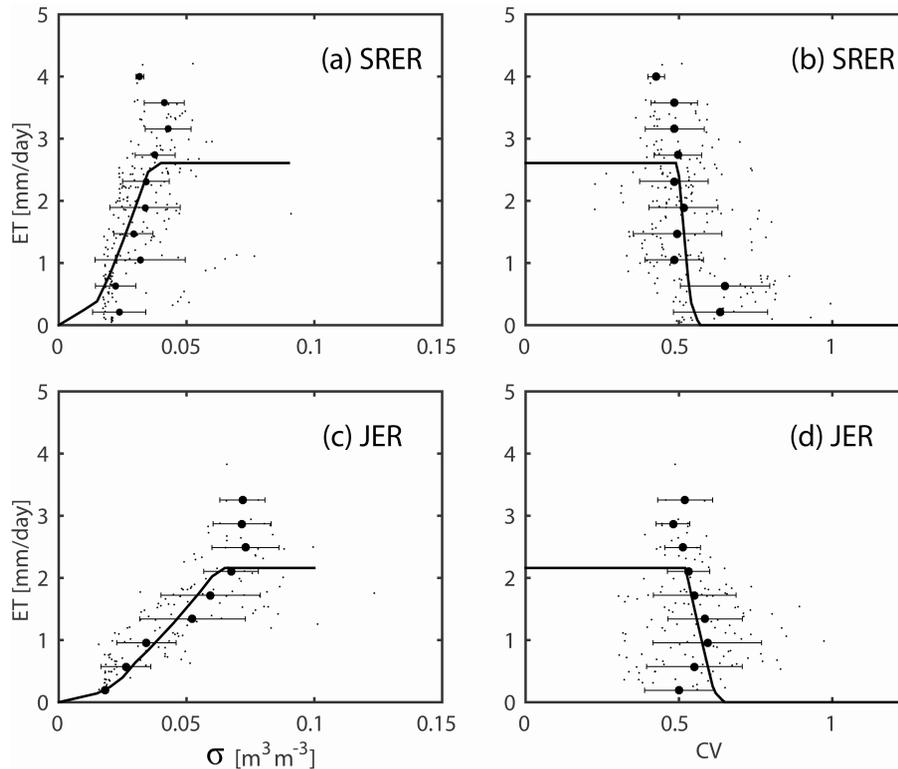


Figure 11. Evapotranspiration relation with the soil moisture standard deviation (σ , left) and the coefficient of variation (CV, right) for **(a, b)** SRER and **(c, d)** JER. Bin averages and ± 1 standard deviation are shown (circles and error bars) for bin widths of 0.33 mm d^{-1} . Solid lines represent predicted analytical relationships (not regressions).

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[⏪](#)
[⏩](#)
[◀](#)
[▶](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)
