



Downscaling future precipitation extremes to urban hydrology scales

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Downscaling future precipitation extremes to urban hydrology scales using a spatio-temporal Neyman–Scott weather generator

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et al., 2008) and the RCM HIRHAM (version 5, Christensen et al., 2006), which are both driven by the GCM ECHAM5 (Roeckner et al., 2003) and are part on the ENSEMBLES project (van der Linden and Mitchell, 2009). Both have a spatial resolution of 25 km and a temporal output resolution of 1 h. These were the two ENSEMBLES runs we had available at true 1 h resolution. The more generally available data series with only daily maximum 1 h intensity are not sufficient for the employed downscaling procedure. The four other simulations used in this study are run with the RCM HIRHAM driven by the GCM EC-EARTH (Hazeleger et al., 2012) and the RCM WRF (Skamarock et al., 2005) driven by the GCM NorESM (Bentsen et al., 2013). The four simulations use the RCP 4.5 and RCP 8.5 scenarios (van Vuuren et al., 2011), see Table 2. The resolution of these simulations is 8 km and 1 h (Mayer et al., 2015). The simulations were carried out as part of the research project RiskChange (www.riskchange.dhigroup.com). The SRES A1B and RCP 4.5 scenarios are considered comparable moderate forcing scenarios whereas the RCP 8.5 scenario is a very strong forcing scenario.

As in Gregersen et al. (2013), climate change is considered uniform for all land cells over Denmark; this results in 87 considered grid cells for the ENSEMBLES simulations and 648 for the RiskChange simulations.

2.3 Weather generator

The RainSim WG describes the spatio-temporal rain field as discs of rain (rain cells) with uniform rain intensity that temporarily occur and overlap in space and time to produce output that realistically describe the statistical properties of precipitation. As the calibration data set consists of point observations, the time series from the simulations are not grid cell averages but strictly comparable to what a gauge would have measured if present in a grid point. Seven parameters describe the WG (Burton et al., 2008, 2010):

- λ^{-1} , the mean waiting time between storm origins (in h)
- β^{-1} , the mean waiting time for rain cell origins after storm origin (in h)

- η^{-1} , the mean duration of rain cells (in h)
- ρ , the spatial density of rainfall cell centres (cells per km²)
- ξ^{-1} , the mean intensity of the rain cells (in mm h⁻¹)
- γ^{-1} , the mean radius of the rain cells (in km)
- Φ , the non-homogeneous intensity scaling field describing how the mean monthly rainfall intensity varies in space within the model area (–)

A uniform Poisson process governed by λ describes the storm occurrences. For each storm a random number of rain cells are produced, which occur at independent time intervals after the storm origin and where the time intervals follow an exponential distribution with parameter β . A uniform spatial Poisson process governed by ρ describes the density of the rain cells in space. The cell radii are randomly drawn from an exponential distribution described by γ , and the duration and intensity of each rain cell is independent and follows an exponential distribution with parameters η and ξ , respectively. The rain intensity at a given point is therefore the sum of all overlapping rain cell intensities at a given time (Burton et al., 2008, 2010).

The non-homogeneous intensity scaling field, Φ , is a proxy for the spatial variation of mean monthly precipitation and is used for relative scaling of the precipitation in space; for this study it is interpolated from the CGD data set using inverse distance weighting. Regional modelling of short-duration extreme precipitation for Denmark using the SVK data set has shown that the only significant parameter that can explain the geographical variation of point extremes statistically is the corresponding mean annual precipitation (Madsen et al., 2002, 2009). Thus, taking Φ as the only spatially varying parameter in the WG, and as such the only parameter describing spatial differences within the WG, is considered to be an acceptable approximation. The actual spatial variation of mean monthly precipitation calculated from the CGD data set is considerable (see Fig. 3), even though the model area is small in size and relatively flat. Especially in June and

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July there is a clear North–South gradient with 75–80 mm month⁻¹ in the North of the area and 55–60 mm month⁻¹ in the South.

3 Methodology

3.1 Fitting of the weather generator

RainSim is fitted to daily and hourly statistics for each calendar month from the observed time series (SVK) to best reproduce features at both hourly and daily levels, as described by Burton et al. (2008, 2010). A custom weighing scheme is used to support the features of rainfall that are important in the context of the present study. RainSim uses the Shuffled Complex Evolution fitting algorithm in combination with an objective function that normalises the fitting statistics (to avoid bias) for optimisation; furthermore, the algorithm is run thrice to avoid sub-optima (Burton et al., 2008). The statistics used for fitting the WG are:

- the mean daily precipitation intensity from the individual gauges (24 h mean);
- the variance of the intensity of the daily and hourly observations from the individual gauges (1 and 24 h variance);
- the skewness of the intensity of the daily and hourly observations from the individual gauges (1 and 24 h skewness);
- the probability of dry days and of dry hours based on the observations from the individual gauges and with thresholds of 1.0 and 0.1 mm respectively as suggested by Burton et al. (2008);
- the lag-1 auto-correlation of the hourly precipitation intensity calculated from the observations at the individual gauges;

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- the cross-correlation between observations of hourly precipitation intensity at the individual gauges.

The chosen weighing scheme (see Table 3) favours the higher order moment statistics variance and skewness over the mean as the extreme characteristics of the simulated precipitation is prioritised. Furthermore, the cross-correlation and auto-correlation are given high weights to ensure a realistic representation of the spatio-temporal extent of the simulated precipitation. The different observation time series are furthermore weighted relative to each other according to the effective length of the time series to give more weight to longer time series. This is done to increase the data basis for cross-correlation analysis, utilising that a great deal of the short time series are from recent years and thus overlap in time, see Fig. 2.

The standard fitting bounds suggested by Burton et al. (2008) are applied in the fitting procedure to ensure that the WG is fitted with values that are considered realistic by the model developers for a North European climate.

3.2 Evaluation of simulated time series

For evaluation of all realisations of the WG the 60 grid cells closest to the observational gauges are extracted and evaluated point-wise with respect to all the fitting statistics as recommended by Burton et al. (2008). Furthermore, the WG is refitted to the simulated data sets to evaluate if the realisation is representative and results in model parameters that are comparable to the parameters estimated from the SVK observational data set.

Ten realisations of the WG, named WG1 to WG10, are used in this study.

3.3 Perturbation of the weather generator with climate change signals

The fitted WG is perturbed with climate change signals by application of climate change factors, $\alpha_{i,j,k}$'s, to the key statistics, $Y_{i,j,k}^{\text{Present}}$'s, calculated from the SVK data set and used to fit the original WG for the present climate. In this manner new key statistics are

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3.4.3 Unconditional spatial correlation of extremes

The unconditional spatial correlation, ρ , between the intensities of extreme events that are considered concurrent at different sites A and B is estimated. The methodology follows Mikkelsen et al. (1996) with the i th extreme intensity Z_{Ai} measured at site A being concurrent with the j th extreme event Z_{Bj} measured at site B if Eq. (6) is fulfilled. In this framework the precipitation process is considered to generate random occurrences of precipitation that are treated as correlated random variables, Z_A and Z_B , and two events are considered concurrent if they are overlapping in time or at most separated by a lag time Δt , which is introduced to account for the travel time of rain storms between sites.

$$\{Z_{Ai}, Z_{Bj}\} : \left[t_{si} - \frac{\Delta t}{2}, t_{ei} + \frac{\Delta t}{2} \right]_A \cap \left[t_{sj} - \frac{\Delta t}{2}, t_{ej} + \frac{\Delta t}{2} \right]_B \neq \emptyset \quad (6)$$

Here, t_s is the start times of the events and t_e is the end time of events. A lag time of $\Delta t = 11 \text{ h}$ + the duration of the event is adopted in accordance with Gregersen et al. (2013). The introduction of this lag time, in combination with lack of knowledge of the movement direction of precipitation, implies that an individual event at one site can be correlated to more than one event at another site.

The unconditional covariance is then estimated by also accounting for non-concurrent extreme events at the two sites as:

$$\text{cov}\{Z_A, Z_B\} = \text{cov}\{E\{Z_A|U\}, E\{Z_B|U\}\} + E\{\text{cov}\{Z_A, Z_B|U\}\} \quad (7)$$

with U being a boolean operator taking the value of $U = 1$ if events are concurrent and $U = 0$ otherwise. Finally, the unconditional correlation is obtained by division of Eq. (7) with the sample SDs of the two sites (Mikkelsen et al., 1996):

$$\rho_{AB} = \frac{\text{cov}\{Z_A, Z_B\}}{\sqrt{\text{var}\{Z_A\}\text{var}\{Z_B\}}} \quad (8)$$

The unconditional correlation values are grouped together in bins where the distance between the points considered are approximately the same, and an exponential model is fitted to describe the unconditional correlation's dependence on distance between sites using the e-folding distance measure as proposed by Gregersen et al. (2013).

4 Results and discussion

4.1 Fitting the weather generator

The WG converges to an optimum fit for the SVK and CGD data for all calendar months, resulting in a WG that is able to simulate realistic rainfall fields all year round. The parameter estimates (cf. Sect. 2.3) for the model fitted to SVK data, the parameter estimates for the model refitted to the 10 realisations of the WG (WG1 – WG10) and the used boundary values are given in Fig. 4. All parameters vary over the course of the year, some more smoothly than others. Note that the β parameter (the parameter controlling the arrival time of cells after a storm origin) is constrained at its prescribed minimum value for four months (February, September, October and December). However, rain events can easily last for several days at these times of the year in Denmark, and this fitting artefact is therefore considered to have limited influence on those features of rainfall, which are of interest for this study. Figure 4 shows that all the refitted values are different and especially the β parameter does not always seem to follow the same structural pattern as for the SVK data set. As β^{-1} controls the arrival time of cells after storm origin it will be heavily dependent on the actual realisation of weather from the WG and this is not considered to be important for the realised extreme events. The ξ parameter seems to be slightly biased in the same direction for all WGs. ξ^{-1} controls the mean intensity of the rain cells and the difference in fit suggests that the rain in the WG data sets are slightly more intense during summer than what is seen in the SVK data set. Generally, the WG data sets however represent the SVK data set well.

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50 and 10 year events the WG data sets result in comparable extreme intensity values for all considered durations.

Figure 8 shows that the seasonal distribution of these extreme events is captured very well by the considered grids from the simulated WG data sets for all considered event durations. The χ^2 tests furthermore confirm that there are no significant differences between distributions for the WG and the SVK data sets for all event durations.

Figure 9 shows the unconditional spatial correlation for the SVK and for the selected WG grid points calculated according to Eq. (8) and grouped in selected bins. Table 4 furthermore compares the e-folding distances based on the fitted exponential models with a set of values calculated from RCM data representing a slightly larger area, taken from Gregersen et al. (2013).

Gregersen et al. (2013) show, using data from the whole of Denmark (range 0–350 km), that the spatial correlation pattern is not the same when considering output from climate models compared to SVK data as the climate model output maintains too long spatial correlation lengths at scales below approximately 150 km and 12 h (see Table 4). Both Fig. 9 and Table 4 indicate that the WG better reproduces the spatial correlation pattern of the SVK data within the spatial range (0–60 km) covered by the observations included in this study. The e-folding distances computed in this study for the SVK data set are somewhat lower than the ones calculated by Gregersen et al. (2013). This is a consequence of inclusion of fewer gauges and, most importantly, that the time series in the SVK data set for this study have been aggregated into hourly time series prior to the smoothing and POT analysis. Gregersen et al. (2013) conducted the smoothing and POT analysis directly on the original time series that have a one-minute resolution. The WG data sets represent the space-time features of precipitation of crucial importance for urban hydrology applications much better than the climate model output; the WG data set is considered realistic at this small-scale spatio-temporal resolution.

Overall, the results show that the WG is able to realistically simulate extreme precipitation statistics down to the hourly scale at a 2×2 km spatial resolution.

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4.3 Perturbation of the weather generator with climate change signals from RCMs

As the different realisations of the WG produce similar weather, only one 30 years re-
alisation is used for perturbation with climate change signals from each of the RCMs.
Furthermore, all grid cells are used for both present and future evaluations as no com-
parisons are made to the observational data.

For each RCM run and each statistic the climate change factors, $\alpha_{i,j,k}$'s, are calcu-
lated. They are primarily above 1 for the moment derived statistics (Fig. 10a–e) but
the different RCM runs appear different. For the 24 h mean (Fig. 10a) the $\alpha_{i,j,k}$'s are
mostly above 1 with all RCM runs showing some months with values below 1 in an
unsystematic pattern. For both the 24 and 1 h variances (Fig. 10b and d) the number of
RCM runs and months that show a decrease is very limited and in general the variance
will increase for all seasons. The HIRHAM RCP 8.5 simulation differs from the other
RCM runs with very high $\alpha_{i,j,k}$'s for the summer months. The 24 and 1 h skewness
(Fig. 10c and e) show more clear seasonality than the mean and variance with higher
 $\alpha_{i,j,k}$'s from May to September for all RCM runs clearly indicating a shift in the distri-
bution of precipitation intensities towards more extremes. Again the HIRHAM RCP 8.5
run stands out with very high $\alpha_{i,j,k}$'s for the 1 h skewness for most of the year. This
means that the extreme precipitation intensities are expected to be higher during sum-
mer and especially the sub-daily extremes for the HIRHAM RCP 8.5 perturbation could
have very high intensities as a combination of a large increase in both variance and
skewness will result in many severe precipitation events with a high mean intensity.

For the lag-1 h auto-correlation (Fig. 10h) the $\alpha_{i,j,k}$ are mostly below 1 indicating
more variations from one hour to the next and thus a possibility of more abrupt changes
in the rainfall at the hourly level. For the probability of dry days and dry hours (Fig. 10f
and g) the pattern is less clear. The RCM simulations show some variation around 1
(approximately between 0.7 and 1.7) but do not agree with respect to season of these
changes or their relative magnitude. This suggests that future rainfall will follow the

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same overall patterns as today but as all RCM runs have months with $\alpha_{i,j,k}$ below 1 there will also be more severe periods since the precipitation is concentrated on fewer days and hours. For instance, the peaks for the WRF RCP 8.5 perturbation in August for both probability of dry days and hours (Fig. 10f and g) in combination with the increases in variance and skewness (Fig. 10b–e) are expected to result in very severe extremes as the increased rainfall amount is expected to occur on fewer days. All in all, the $\alpha_{i,j,k}$'s indicate that for all RCM runs there will be more rainfall on average and it will be more variable resulting in more (and more severe) extremes events. This is in accordance with general findings from studies based on direct output from RCMs (Christensen and Christensen, 2007; Sunyer et al., 2014b).

4.4 Changes in climate changed extremes from the weather generator

Calculating the climate change factors, CF's (Eq. 4), from the perturbed and original WG using the T -year event estimates calculated with Eq. (3) shows that despite the differences observed in the $\alpha_{i,j,k}$ for the input statistics (Fig. 10), the perturbation schemes based on RCM simulations modelling comparable climate change (HIRHAM SRES A1B, RACMO SRES A1B, HIRHAM RCP 4.5 and WRF RCP 4.5) result in similar changes to extremes after downscaling with the WG (Fig. 11). Clearly, and as expected from the results in Fig. 10, the HIRHAM RCP 8.5 perturbed WG results in a much more severe change in extreme precipitation than the other perturbation schemes for both 10 and 100 year return periods. It is interesting that the WG perturbed with HIRHAM SRES A1B results in a rather stable CF in the range 1.35–1.55 with seemingly little dependence on return period and event duration, The WGs perturbed with RACMO SRES A1B, HIRHAM RCP 4.5 and WRF RCP 4.5 show similar CF values that are higher for 100 year extremes than for 10 year extremes but still not depend significantly on the event duration.

Both the HIRHAM RCP 8.5 and WRF RCP 8.5 perturbed WGs yield CF values that depend on the event duration with higher CF for short duration precipitation extremes. This indicates that this high-end scenario is changing the climate more drastically than

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animation of extreme precipitation events generated directly as output from the 25 km resolution RCM HIRHAM SRES A1B, the 8 km resolution RCM HIRHAM RCP 4.5 and the 2 km WG evaluated in this study. From these it is clear that the small-scale variability is much more pronounced for the WG output than for the output of the RCMs, but also that the WG output lacks rainfall movement. At the hourly scale this is not a problem for a catchment of the size presented in the Online Resource (same as shown in Fig. 1).

Only few apparent effects are observed with respect to choice of RCM, GCM and RCM spatial resolution and it is not possible to detect any systematic patterns. The WG seems to produce robust results with respect to change in extreme precipitation due to climate change that are similar for similar climate forcing scenarios.

5 Conclusions

Precipitation time series based on high-resolution gauge measurements are presently used as input to design and analysis of urban water infrastructure, and time series representing future climates are needed in the future. Current RCMs operating at 25 and even 8 km spatial scales however yield too spatially correlated output that poorly represents the fine-scale precipitation features relevant for urban hydrology. The study indicate that statistical downscaling of precipitation output from RCMs using a stochastic weather generator (WG) is therefore a better solution.

This study demonstrates that the chosen Spatio-Temporal Neuman–Scott Rectangular Pulses weather generator (WG) fitted to a dense network of 60 rain gauges in a 40 by 60 km region simulates realistic extreme precipitation of relevance to urban hydrology. Output is generated at the 1 h temporal scale at a 2 km spatial grid, which is finer than what previous studies using this WG have focused on. Even though urban hydrology literature claims that rain data are ideally needed at a time scale of minutes, the hourly scale chosen here can still be of much use when assessing climate change impacts in urban hydrology as it is much finer than what regional climate models can currently provide.

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The WG generally reproduces statistics of the observations such as mean, variance and skewness of the rainfall intensity distribution well at both the hourly and daily levels. It also produces realistic levels of lag-1 auto-correlation, cross-correlation between output at different grid points and probabilities of dry days and hours. Evaluating the WG from an urban hydrological engineering perspective yields the following conclusions:

- The extreme events of the simulated time series show realistic levels of intensity as well as a reasonable spatial variability for the full 60 × 40 km model area. Thus, the WG handles the large data set of spatially distributed observational input in a robust manner.
- The seasonal distribution of the extremes are not significantly different in the generated WG data sets compared to the observed SVK data set, implying that the applied procedure of individual monthly model fits results in a realistic seasonal behaviour of the WG.
- The spatial extent of the extreme events in the WG data set, as evidenced by the unconditional spatial correlation of extremes, is close to that of the observational SVK data set with e-folding distances in the same order of magnitude. This is much better than what is observed for Regional Climate Model (RCM) output at 25 and 8 km grid scale in previous studies.

This indicates that the WG is a good way to downscale spatio-temporal precipitation output from RCMs to relevant urban scales and that the simulated output can be used directly as input to urban hydrological models.

Output from six different RCM runs representing average to high emission scenarios are used to perturb the WG for different possible future climate scenarios. Two have a 25 by 25 km spatial resolution and four have a very high 8 by 8 km spatial resolution, and all RCM data sets are available at hourly temporal resolution. A clear increase in the magnitude of extreme precipitation is observed for all climate change perturbations of the WG.

This study highlights that different RCMs run with the same greenhouse gas emission scenario can result in different precipitation output and hence different CFs for perturbation of the WG. Despite these observed differences, downscaling with the WG results in similar extreme precipitation behaviour for similar emission scenarios.

Most perturbed WGs confirm that there is a more severe climate change signal for extreme events. The two WGs perturbed by the RCP 8.5 scenario show a more severe climate change signal for short-duration events. However, this finding is not shared by the other emission scenarios, suggesting that extreme precipitation at T -year event level is not scalable between emission scenarios. The spatial correlation structure of the WG output is slightly altered by the perturbation indicating a built-in correlation between intensity and spatial extent and suggesting that precipitation extremes in a future climate may have larger spatial extent than extremes in the present climate.

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[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)**Table 1.** Main characteristics of the two observational data sets used in this study.

	Type of data	Spatial data resolution	Temporal data resolution	Period
SVK	Point observations	60 stations	Minute data	1979–2012
CGD	Gridded data	10 km grid	Daily data	1989–2010

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Table 2. Regional Climate Model (RCM) runs from which precipitation output is used to calculate perturbations schemes for the WG used in this study. All have a temporal resolution of 1 h.

Name	RCM	GCM	Spatial resolution	Present period	Future period
HIRHAM SRES A1B	HIRHAM 5	ECHAM 5	25 km	1980–2009	2070–2099
RACMO SRES A1B	RACMO 2.1	ECHAM 5	25 km	1980–2009	2070–2099
HIRHAM rcp 4.5	HIRHAM 5	EC-EARTH	8 km	1981–2010	2071–2100
HIRHAM rcp 8.5	HIRHAM 5	EC-EARTH	8 km	1981–2010	2071–2100
WRF rcp 4.5	WRF 3	NorESM	8 km	1981–2010	2071–2100
WRF rcp 8.5	WRF 3	NorESM	8 km	1981–2010	2071–2100

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[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)**Table 3.** The relative weights used in the fitting procedure.

Statistic	Relative weight
24 h mean	1
24 h variance	3
24 h skewness	6
1 h variance	3
1 h skewness	6
1 h auto-correlation	6
1 h Cross-correlation	6*
Probability of dry day	1
Probability of dry hour	1

* All the cross-correlations of a gauge have equal weights that sum up to the value shown.

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Table 4. e-folding distances for the SVK and WG maximum averaged intensities of extremes for 1, 6, 12 and 24 h duration, based on the fitted exponential models (cf. Fig. 8) as well as for a regional climate model (HIRHAM/ECHAM) from the study by Gregersen et al. (2013) for comparison.

e-folding distance [km]	1 h	6 h	12 h	24 h
SVK	3.5	5.5	7.3	8.
WGs	7.1–9.9	9.1–14	9.5–16	10–28
HIRHAM/ECHAM*	56	48	48	54

* Values from Gregersen et al. (2013).

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Table 5. e-folding distances for all aggregation periods for all WG output.

e-folding distance [km]	Aggregation period			
	1 h	6 h	12 h	24 h
WG – Present Climate	3.9	5.0	4.9	5.0
WG – HIRHAM SRES A1B	5.2	7.4	7.7	8.1
WG – RACMO SRES A1B	7.3	9.7	9.1	8.4
WG – HIRHAM rcp 4.5	5.2	8.4	8.7	8.8
WG – HIRHAM rcp 8.5	4.6	7.7	9.3	9.0
WG – WRF rcp 4.5	5.1	9.1	9.3	11.5
WG – WRF rcp 8.5	4.9	9.4	9.9	10.2

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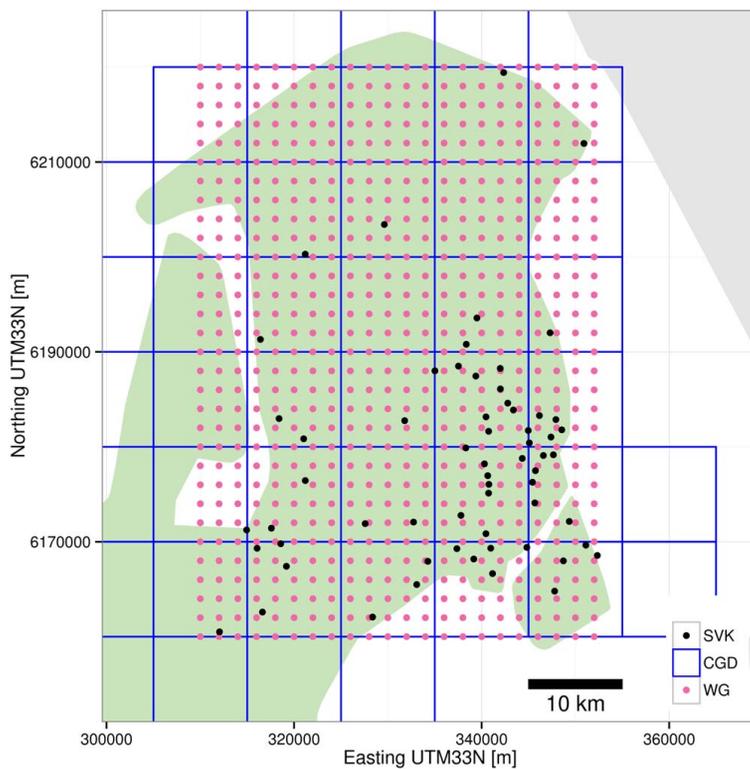


Figure 1. Locations of the rain gauges (SVK), the gridded data set (CGD) and extent of the modelled grid (WG) in the North-Eastern part of Zealand (Denmark) including Copenhagen in the South-Eastern part of the map where the concentration of SVK gauges is highest.

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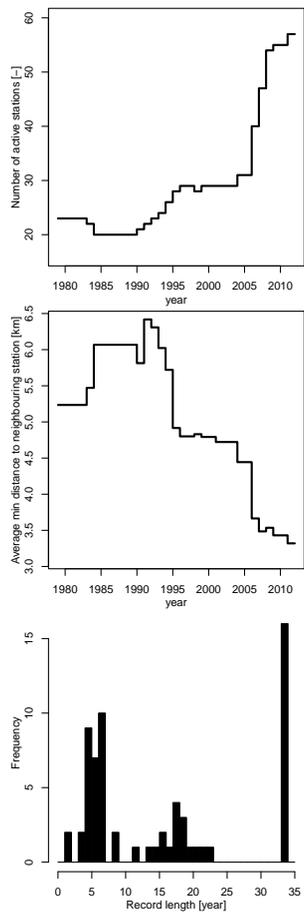


Figure 2. Temporal development in (top) the number of stations in the SVK data set and (middle) the average distance between closest neighbouring stations, and (bottom) the distribution of record lengths.

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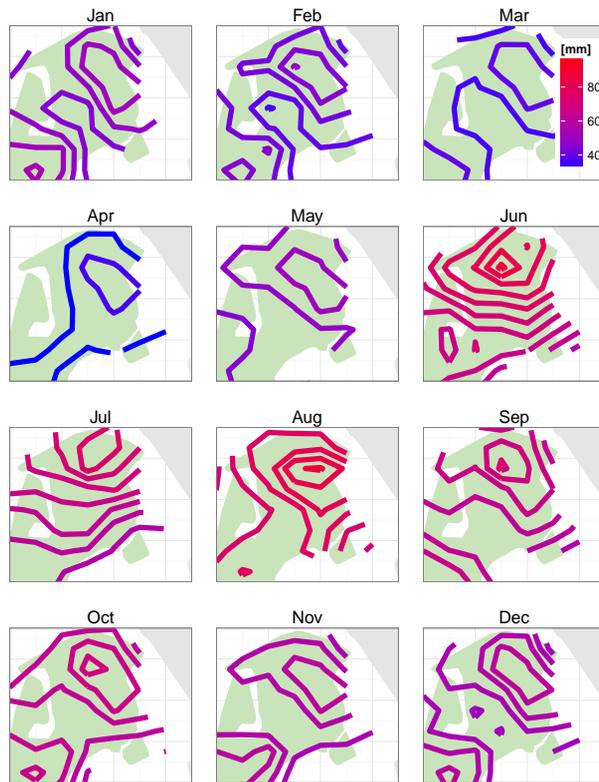


Figure 3. Spatial variation of the mean monthly precipitation calculated from the CGD data set for the model area.

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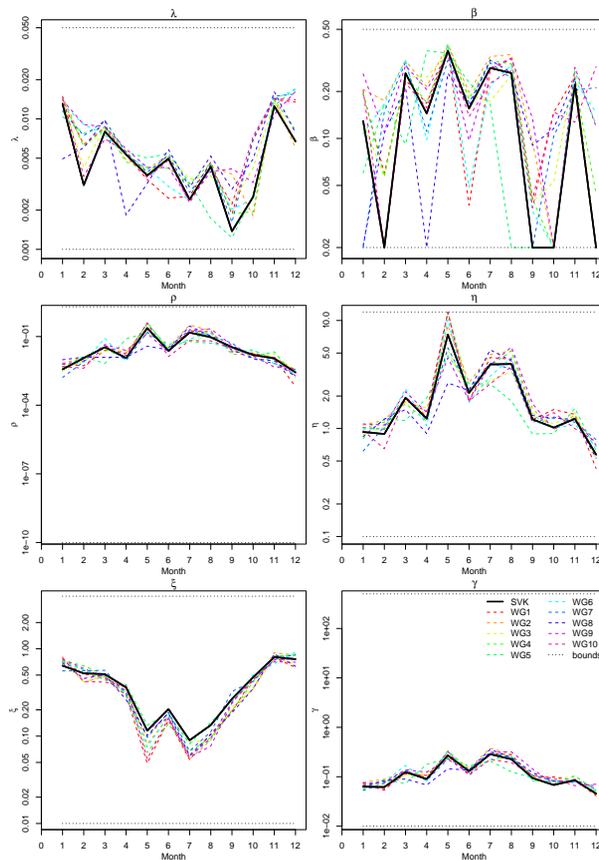


Figure 4. Monthly variation of the model parameters estimated from the SVK data set and from the simulated 10 WG data sets. Upper and lower fitting bounds are shown in light grey.

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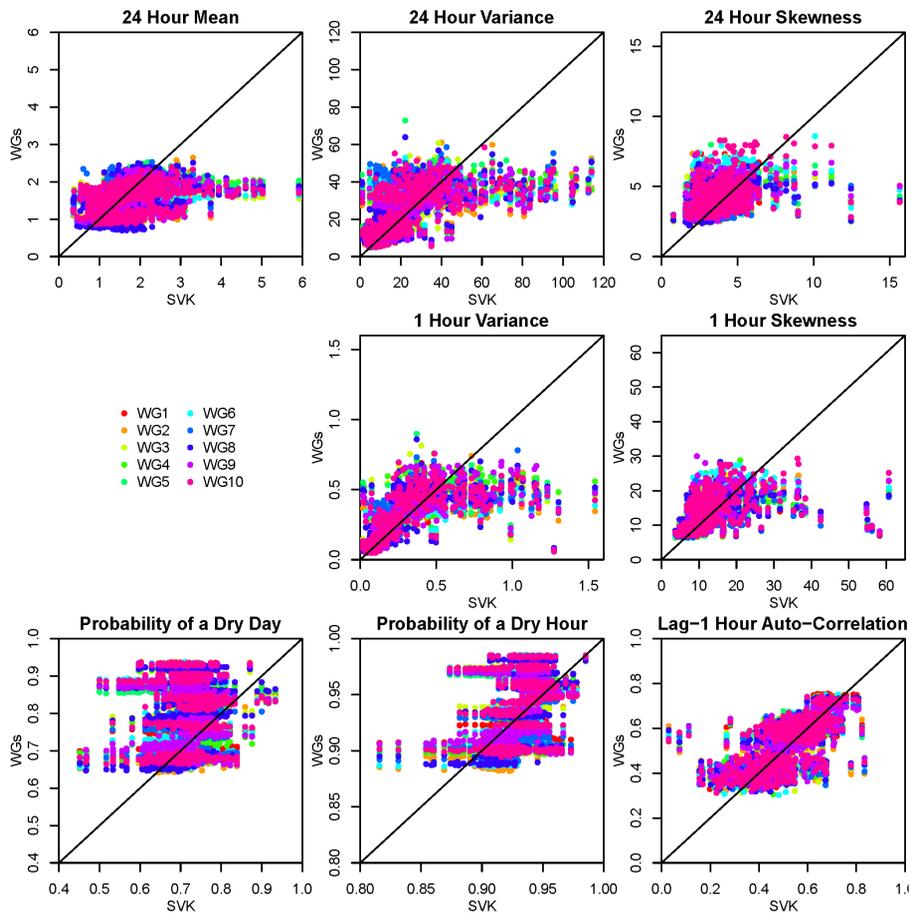


Figure 5. Fitting statistics calculated from the SVK data set (observations) and WG (simulated) data set.

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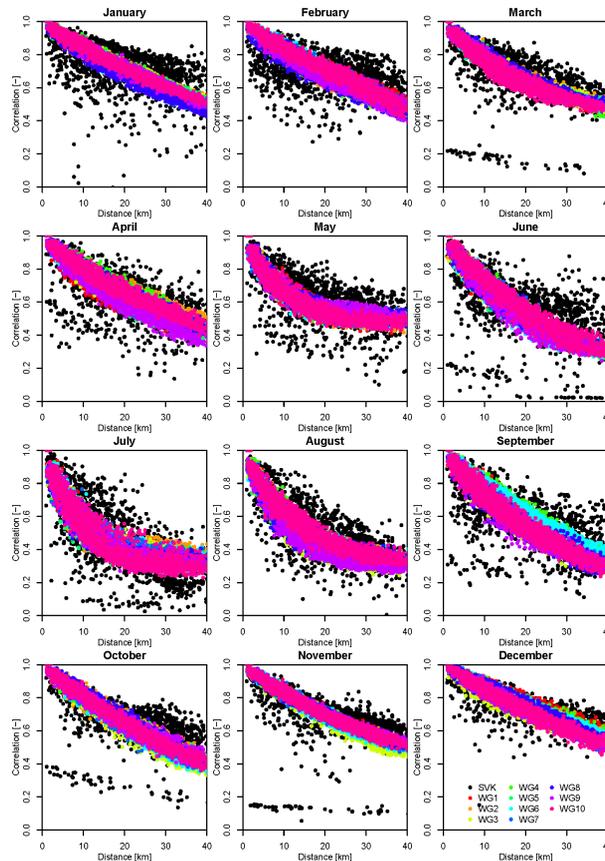


Figure 6. Variation of cross-correlation of the 1 h intensity with distance between pairs of gauges in the SVK data set (black dots) and grid points in the WG data set (coloured dots).

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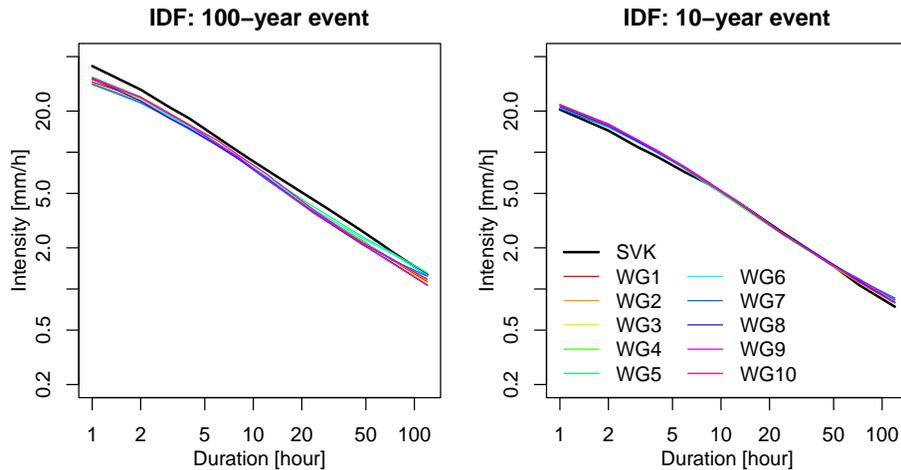


Figure 7. Mean intensity-duration-frequency curves for 100 and 10 year return periods calculated from the SVK data set and for all 10 WG realisations.

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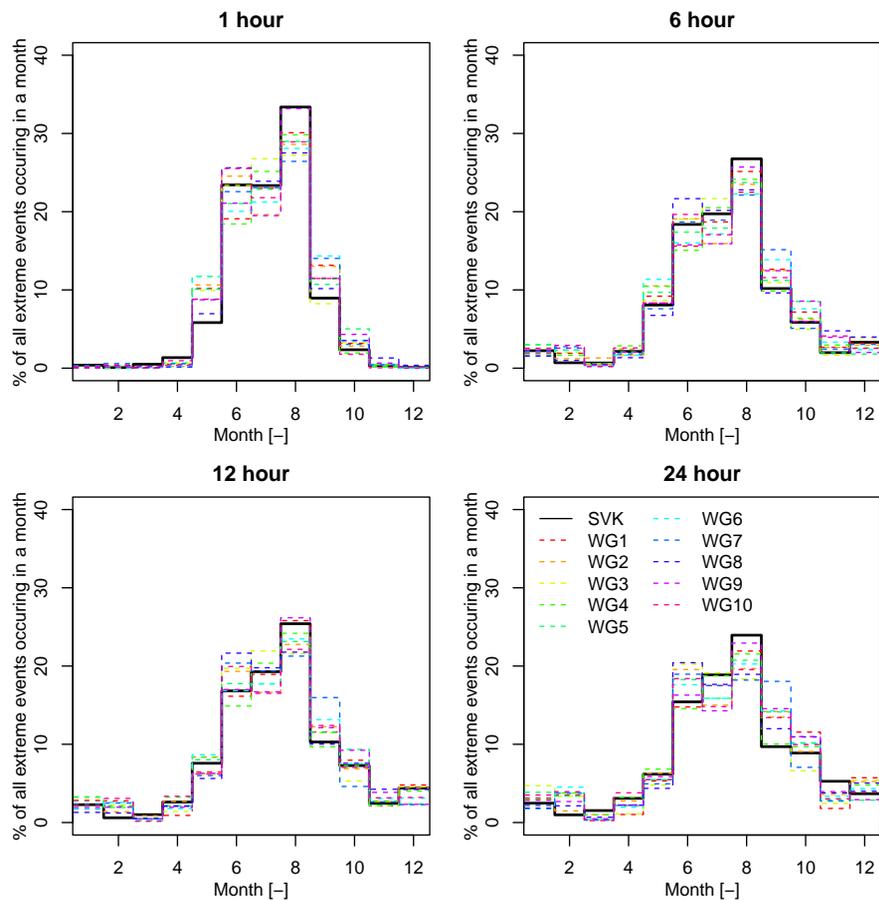


Figure 8. Monthly variation for 1, 6, 12 and 24 h durations of the frequency of extreme events in the SVK and WG data sets.

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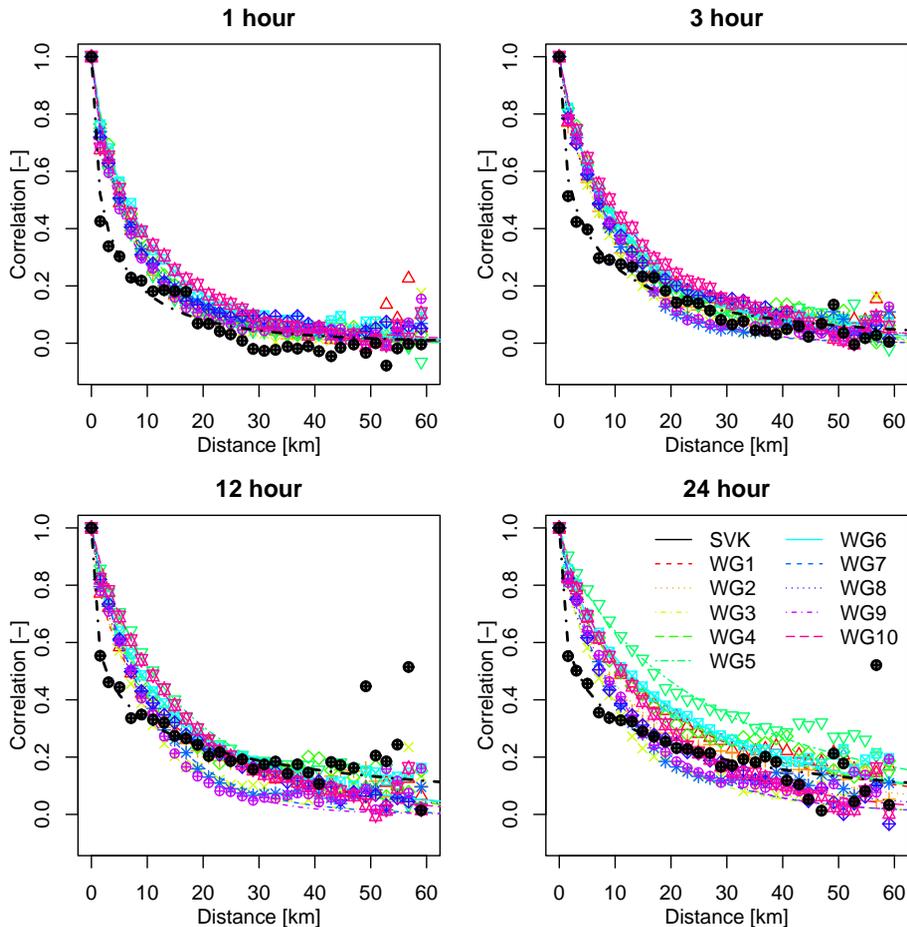


Figure 9. Unconditional spatial correlation for the SVK and WG data sets, calculated from maximum averaged intensities of extreme events for 1, 6, 12 and 24 h duration. Fitted exponential models that highlight overall tendencies are shown.

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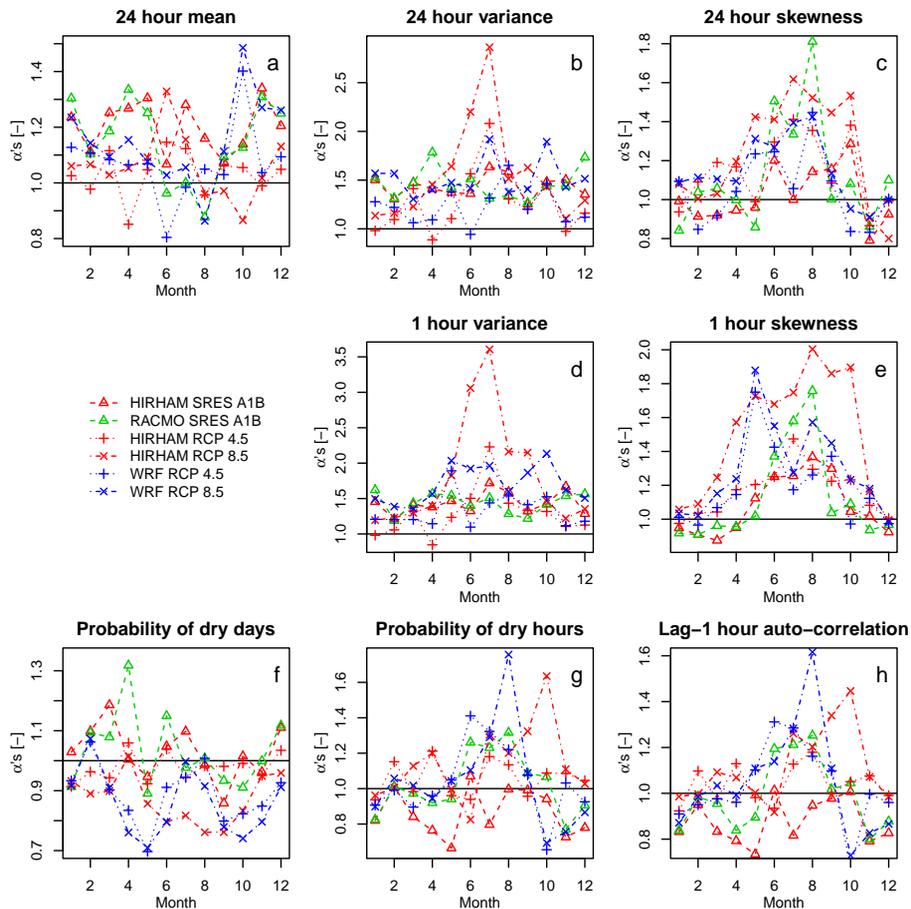


Figure 10. Climate factors, α 's, calculated on a monthly basis for each statistic and each RCM. Each set of α 's from an RCM act as a perturbation scheme for the WG.

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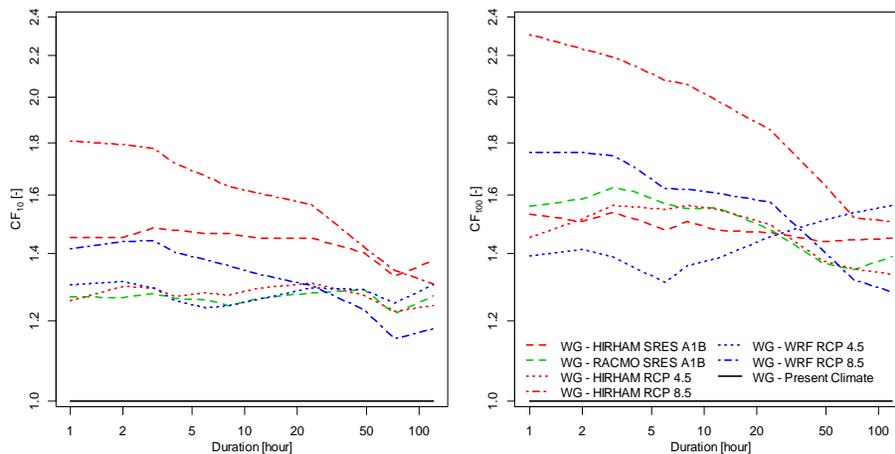


Figure 11. Climate change factors for different return periods for the different perturbed WG runs. $T = 10$ years (left) and $T = 100$ years (right).

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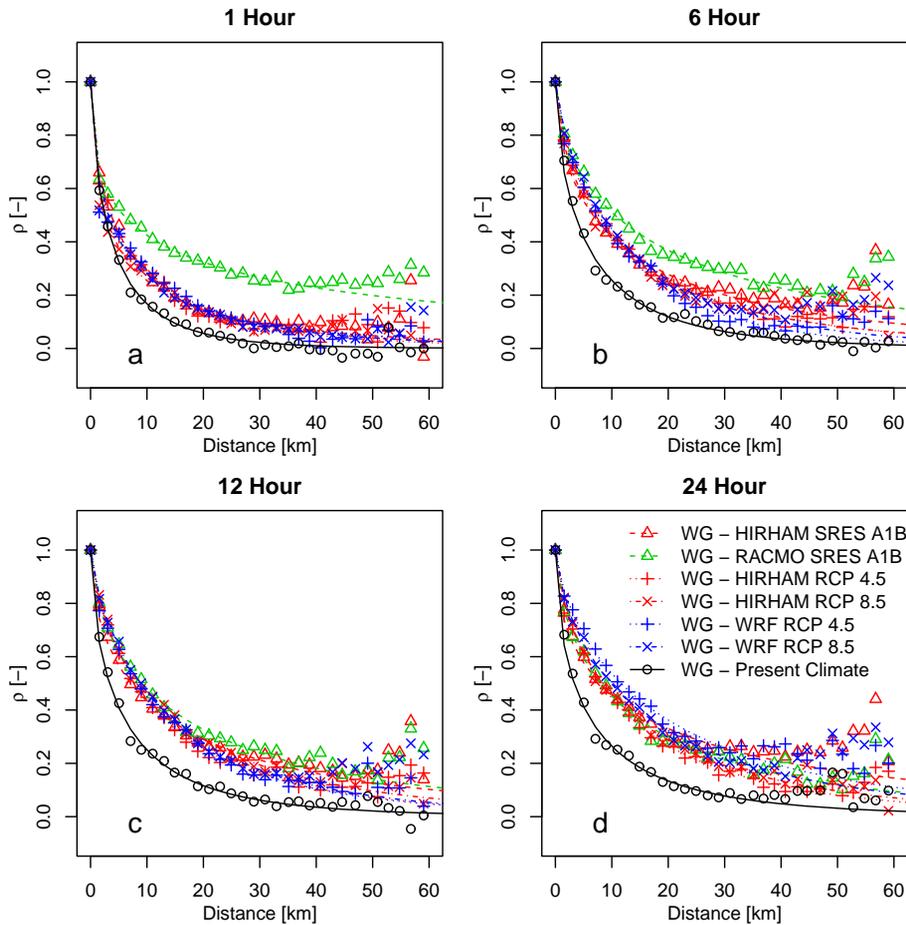


Figure 12. The unconditional spatial correlation of all T -year events for perturbed WG output for event durations of 1, 6, 12 and 24 h.