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Satellite-driven downscaling of global reanalysis precipitation products for hydrological applications

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Abstract

Deriving flood hazard maps for ungauged basins typically requires simulating a long record of annual maximum discharges. To improve this approach, precipitation from global reanalysis systems must be downscaled to a spatial and temporal resolution applicable for flood modeling. This study evaluates such downscaling and error correc-

- ⁵ applicable for flood modeling. This study evaluates such downscaling and error correction approaches for improving hydrologic applications using a combination of NASA's Global Land Data Assimilation System (GLDAS) precipitation dataset and a higher resolution multi-satellite precipitation product (TRMM). The study focuses on 437 floodinducing storm events that occurred over a period of ten years (2002–2011) in the
- ¹⁰ Susquehanna River basin located in the northeast US. A validation strategy was devised for assessing error metrics in rainfall and simulated runoff as function of basin area, storm severity and season. The WSR-88D gauge-adjusted radar-rainfall (stage IV) product was used as the reference rainfall dataset, while runoff simulations forced with the stage IV precipitation dataset were considered as the runoff reference. Re-
- ¹⁵ sults show that the generated rainfall ensembles from the downscaled reanalysis products encapsulate the reference rainfall. The statistical analysis, including frequency and quantile plots plus mean relative error and root mean square error statistics, demonstrated improvements in the precipitation and runoff simulation error statistics of the satellite-driven downscaled reanalysis dataset compared to the original reanalysis pre-
- cipitation product. Results vary by season and less by basin scale. In the fall season specifically, the downscaled product has three times lower mean relative error than the original product; this ratio increases to four times for the simulated runoff values. The proposed downscaling scheme is modular in design and can be applied on gridded satellite and reanalysis dataset.





1 Introduction

Flooding is one of the costliest natural hazards, occurring repeatedly around the globe (Sampson et al., 2014; Hagen and Lu, 2011 among the others). Flood vulnerability analysis provides essential information to support decisions for policy and prepared-

- ness against catastrophic flood consequences and for quantifying risk for coping with this hazard (Sampson et al., 2014). However, flood frequency maps are not available for most regions around the world (Hagen and Lu, 2011) due to limited economic resources to support long-term observations; this results in lack of knowledge and data (e.g., ground based rain gauge measurements). Developing global scale flood maps
 (Porter and Demeritt, 2012) is of increasing interest in the scientific community with great applicability in the (re)insurance industry. Global gridded precipitation datasets from satellites and reanalysis datasets derived from data assimilation systems are two main sources for deriving global flood hazard maps (Cloke et al., 2013; Kappes et al.,
- 2012).
 ¹⁵ Global reanalysis products can provide long-term precipitation datasets for frequency analyses of hydrologic extremes (e.g., floods, droughts). Widely used reanalysis products include the JRA-25 (Onogi et al., 2005), ERA-40 (Bosilovich et al., 2008; Uppala et al., 2005), ERA-Interim (Dee et al., 2011), GLDAS (Rodell et al., 2004), and GDAS (Kalnay et al., 1996). These reanalysis products are available at coarse spatial resolution (100 to 250 km²) and suffer from model biases (Gottschalck et al., 2005; Peña-Arancibia et al., 2013). On the other hand, satellite-based rainfall
- products are associated with relatively higher spatial resolutions (10–25 km²) and improved accuracy, but significantly shorter temporal coverage. The most widely used high resolution, near-global, multi-sensor precipitation products include the 8 km/half-
- ²⁵ hourly National Oceanic and Atmospheric Administration CMORPH dataset (Joyce et al., 2004), the 25 km/3 hourly US Naval Research Laboratory NRLBLD (Turk and Miller, 2005), the 4 km 15 min⁻¹ National Environmental Satellite, Data, and Information Service Hydro-estimator (Scofield and Kuligowski, 2003), the 10 km 1 h⁻¹ Japan



Aerospace Exploration Agency GSMaP (Ushio and Kachi, 2009; Kubota et al., 2007), the $25 \text{ km} 3 \text{ h}^{-1}$ Center for Hydrometeorology and Remote Sensing, University of California-Irvine PERSIANN (Sorooshian et al., 2000), and the $25 \text{ km} 3 \text{ h}^{-1}$ NASA TRMM3B42 (Huffman et al., 2007). Depending on the algorithm and the purpose of the product, each dataset utilizes various combinations of information from microwave (MW) and geostationary infrared (IR) sensors.

Characterizing the uncertainty in existing global gridded precipitation products is vital for the purpose of hydrological applications. Syed et al. (2004) have shown that rainfall is responsible for nearly 70–80% of the variability in the land surface hydrol-

- ogy. Therefore, precipitation uncertainty would critically affect the predicted variability in hydrologic simulations. Several validation studies have investigated uncertainties related to satellite rainfall remote sensing over diverse geographic and hydro-climatic regimes (Adler et al., 2001; AghaKouchak et al., 2009; Brown, 2006; Dinku et al., 2007; Ebert et al., 2007; Krajewski et al., 2000; McCollum et al., 2002; Seyyedi et al.,
- ¹⁵ 2014; Stampoulis et al., 2013; Su et al., 2008; Tang et al., 2010). These studies have shown that the precision of satellite rainfall products depends on precipitation type (e.g., deep convection vs. shallow convection), as well as terrain and climatological factors (AghaKouchak et al., 2011; Demaria et al., 2011; Turk and Miller, 2005; Seyyedi et al., 2014). Gottschalck et al. (2005) evaluated precipitation products from global models,
- satellite and radar data against ground based gauge measurements over CONUS for a period of 14 months. They demonstrated that some of the reanalysis precipitation products (ECMWF, GEOS and GDAS) can generally perform better than satellite precipitation datasets (TRMM3B42RT and PERSIANN). Peña-Arancibia et al. (2013) assessed daily detection and accuracy metrics for reanalysis and satellite precipitation
- datasets against gauge data. They argued that no product could demonstrate superior performance relative to the other, e.g., the ERA-Interim is better at Southern and Northern Australia, JRA-25 performs better in South and East Asia, while TRMM3B42 and CMORPH are better during monsoon periods. Therefore, combined use of different





datasets (including satellite and reanalysis) is expected to perform better than any single product, especially for hydrological applications.

Substantial efforts have been devoted to assessing the feasibility of utilizing global-scale precipitation datasets derived from satellite or models on land surface hydrological modeling (Behrangi et al., 2011; Beighley et al., 2011; Hong et al., 2007, 2006; Hossain and Anagnostou, 2004, 2005; Nijssen and Lettenmaier, 2004; Su et al., 2008; Bitew and Gebremichael, 2011). Some of these studies have highlighted the effect of product resolution (Gourley et al., 2011) and catchment size (Vergara et al., 2013) on the precipitation error propagation in hydrological simulations. Seyyedi et al. (2014)
have recently utilized gridded precipitation datasets from TRMM3B42V7 (25 km, 3 h) and GLDAS reanalysis (100 km, 3h) to conduct a more in depth assessment of the effect of resolution and data type (satellite vs. reanalysis product) on streamflow simulations at sub-daily scale. The study was based on a multi-year (2002–2011) and

- multi-scale approach considering 1006 sub-basins (36–71 000 km²) of the Susquehanna River basin in the northeast US. They demonstrated that statistical scores in both rainfall and runoff simulations improve with increasing basin size. However, the satellite dataset (TRMM3B42V7) was shown to perform significantly better than the reanalysis (GLDAS) in the simulated runoff values. The mean relative error in runoff simulations based on GLDAS was up to seven times higher than that of TRMM3B42V7,
- which was attributed to the product resolution and associated underestimation of heavy precipitation. Results from that study suggest the use of downscaling and error correction for the GLDAS reanalysis precipitation dataset before implementing it for runoff simulations. Bastola and Misra (2014) have also evaluated two reanalysis precipitation datasets (ERA-40 and NCEP-R2) for hydrologic simulations over 28 small to midsize
- ²⁵ basins in southeastern US. Their results demonstrated that ER-40 tends to underestimate while NCEP-R2 tends to overestimate relative to the reference data. They also concluded that downscaling the reanalysis precipitation products would significantly increase their performance in terms of runoff simulations.





The critical role of high resolution gridded rainfall datasets for hydrological simulations has led to the development of several rainfall disaggregation algorithms (Brussolo et al., 2008; Ferraris et al., 2003; Fowler et al., 2007; Frei et al., 2006; Maraun et al., 2010; Ning et al., 2011; Park, 2013; Rahman et al., 2009; Ramírez et al., 2006; Tao

- and Barros, 2010, among others). The main assumption for some recently developed downscaling methods for satellite based products is the relationship between spatial variability of rainfall and environmental factors such as topography and land surface conditions. Immerzeel et al. (2009) improved average annual TRMM3B43 from 25 km to 1 km grid resolution by establishing an exponential relationship between TRMM3B43
- and Normalized Difference Vegetation Index (NDVI). Jia et al. (2011) developed a statistical downscaling scheme based on the relationship between rainfall, terrain elevation and NDVI. They disaggregated TRMM3B43 from 25 km to 1 km grid resolution by forming a multiple linear regression model between parameters. The final products of both aforementioned methods are mean annual rainfall values. Duethmann
- et al. (2013) downscaled ERA-40 with a horizontal resolution of 100 km to 12 km grid size using RCM Weather Research and Forecasting Model (WRF) over central Asia for hydrological modeling. The downscaled data exhibited significant modeling improvement. Haas and Born (2011) introduced a two-step probabilistic downscaling method for disaggregating ERA-Interim using ground based gauge data over a complex ter-
- rain in Southeastern Morocco. The technique is a combination of CDF transformation based on probability mapping and a multi linear regression model to extrapolate observation data to a high resolution grid using DEM data. The resulting downscaled high resolution precipitation data substantially outperformed the original ERA-Interim data. Although downscaling is a widely studied topic, no studies have implemented satel-
- lite precipitation datasets for downscaling reanalysis precipitation datasets. Moreover, most downscaling schemes for reanalysis datasets are in the context of regional climate focusing on producing consistent statistics for downscaled precipitation values and corresponding generated runoff. This work examines the value of satellite data for improving the applicability of reanalysis precipitation datasets in flood simulations and





flood frequency analysis. The reason for using satellite datasets is that a great deal of effort has been devoted to improving the accuracy and resolution of satellite retrievals, which is paired with the recent advent of satellite missions on precipitation (Hou et al., 2013). Moreover, satellite products are globally available, which leads to a globally consistent downscaling scheme for reanalysis products that can be particularly useful over areas lacking long-term ground based observations.

This study is motivated by the challenges of precipitation applications due to the nonlinear error propagation from rainfall to hydrological simulations and the vital need for high resolution and long-term gridded rainfall data for deriving flood frequency statistics

- and corresponding flood hazards maps. Specifically, we examine the hydrologic impact of using the higher resolution and accuracy quasi-global satellite precipitation product from TRMM3B42V7 to derive finer scale and error-corrected precipitation maps from the GLDAS reanalysis product. The methodology developed for the satellite-driven error correction and downscaling of GLDAS rainfall data is based on a stochastic error
- ¹⁵ model, which was originally developed for modeling the satellite retrieval uncertainty and its error propagation in hydrological applications (Hossain and Anagnostou, 2004; Maggioni et al., 2012, 2013). The methodology is independent of ground based measurements, which makes it applicable over data poor areas of the globe. Since GLDAS and other reanalysis datasets are available over a relatively long period of time (35–
- ²⁰ 50 years), developing a proper methodology for downscaling and improving the accuracy of these products could lead to a global gridded precipitation data source suitable for global-scale water resources assessment and flood frequency studies.

This paper is organized into six sections. After the introduction, the study area and datasets are described, including the model used for hydrological simulations. The third

section introduces the downscaling and error correction scheme, including the experiment setup and parameter calibration. The fourth section presents the error analysis methodology. The fifth section describes the results of the error analysis in rainfall and simulated runoff values. The conclusions section discusses the main findings of this research and provides recommendations for future studies.





2 Study area, datasets and models

The study area is the Susquehanna River Basin (39 to 43° N and 75 to 79° W, Fig. 1) which is the largest basin in the eastern US. The highest peak (949 m a.s.l.) is in the northwestern corner and the lowest point (22 m b.s.l. – below sea level) is in the southeastern corner with a general elevation gradient from north to southeast. The total area of the Susquehanna River Basin is 71 000 km² of which 76% is in Pennsylvania, 23% in New York, and 1% in Maryland. The Susquehanna River Basin is subject to major floods occurring once every 14 years with an average annual flood

damage on the order of USD 150 million dollars (Susquehanna River Basin Commission, http://www.srbc.net/). Cumulating the drainage areas along the river network at the outlet of each individual catchment provides 373 unique watersheds with drainage areas ranging from 315 to 71 000 km². The identified sub-basins were divided into five basin size categories (see Table 1) to study the effect of basin scale on the precipitation and runoff simulation error.

The study focuses on 437 flood-inducing rainfall events that occurred between 2002 and 2011. To investigate the effect of seasonality, the events were grouped by season. The number of events per season is reported in Table 2. Sixty percent of the events in each season were used for the downscaling model calibration, and the remaining 40 % were kept for determining error statistics (results presented in this study). Figure 2

- shows the cumulative probabilities (CDF) of the events randomly selected for inclusion in the calibration and validation datasets per season. The figure indicates that the probability distributions of calibration and validation rainfall rates are very close to each other, which indicates that the calibration and validation periods have similar statistical properties in terms of rainfall rates. It is noted that the study is based on time-series of
- catchment average precipitation values from each dataset. Catchment average stands for the weighted average of all the dataset's pixel values contained within a catchment's boundary, where the weights are based on the fraction of the catchment covered by each pixel.





2.1 Stage IV radar data

The radar based NCEP stage IV precipitation data (Lopez, 2011) are utilized as high accuracy, reference observation data in this study. The data are originally on a 4km × 4km grid and in polar-stereographic projection. Stage IV combines estimates of precipitation from a network of 150 Doppler NEXRAD (Next Generation Weather Radar) with approximately 5500 hourly rain gauge measurements over the CONUS (Continental US). NEXRAD is technically similar to the Weather Surveillance Radar-1988 Doppler (WSR-88D). The data benefit from the 12 CONUS RFCs (River Forecast Centers) manual quality-control (QC).

10 2.2 TRMM3B42V7

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TRMM3B42V7 is a combined microwave-infrared precipitation product (Huffman et al., 2007) with 25 km spatial resolution and 3 h temporal resolution representing the latest version at the time of this study. The TRMM3B42V7 blending algorithm uses passive microwave (PMW) from TRMMs' Microwave Imager (TMI) as well as low earth orbit (LEO) measurements from the Special Sensor Microwave/Imager (SSM/I) on the Defense Meteorological Satellite Program (DMSP) satellites, Advanced Microwave Scanning Radiometer-Earth Observing System (AMSR) on Aqua, the Advanced Microwave Sounding Unit-B (AMSU-B) on the National Oceanic and Atmospheric Administration (NOAA) satellite series, Microwave Humidity Sounders (MHS) on later NOAA-series

- satellites, and the European Operational Meteorological (MetOp) satellite (Kidd et al., 2011). The TRMM3B42V7 combination scheme is based on the Goddard profiling (GPROF) algorithm (Kidd et al., 2011; Kummerow et al., 2001, 1996; Olson et al., 1999; Wang et al., 2009; Gopalan et al., 2010) for rainfall estimation from PMW imagers (TMI, SSM/I, and AMSR). The PMW calibrated infrared (IR) precipitation products (Janowiak)
- et al., 2001) from Geosynchronous Earth Orbit (GEO) satellites are used to fill in the PMW gaps. Specifically, the algorithm takes the value of the PMW-calibrated IR precipitation products when the PMW is not available in a 3 hourly time step. The algorithm





uses monthly ground precipitation gauge data extending between 50° N to 50° S for bias removal and calibration.

2.3 GLDAS

The reanalysis precipitation dataset is from GLDAS and has 100 km spatial and
 ⁵ 3 hourly temporal resolution. The reasons for selecting GLDAS are its global coverage, relatively high temporal resolution and long data record (since 1979). The data are "observation based", coming from a combination of reanalysis data from the Global Data Assimilation System (GDAS) from the National Center for Environmental Prediction (NCEP), NOAA Climate Prediction Center's CMAP (CPC Merged Analysis of Pre ¹⁰ cipitation) precipitation (Xie and Arkin, 1997), and radiation datasets from Air Force's AGRicultural METeorological modeling system (AGRMET) (Rodell et al., 2004). GDAS assimilates global meteorological observations. CMAP is merged satellite based IR and MW observations with rain gauge analysis. AGRMET radiation fields are satellite observation based. GLDAS therefore represents merged, spatially and temporally interpolated fields of GDAS, CMAP, and AGREMET fields.

2.4 Hydrologic model simulations

The Hillslope River Routing (HRR) (Beighley et al., 2009, 2011) is the modeling framework used in this study. HRR integrates a water balance model for the vertical fluxes and a routing model for the horizontal fluxes of the surface and subsurface runoff and streamflow. For each model unit, the landscape is approximated as an open book with two planes draining laterally to a main channel. Water and energy balance is used to simulate the vertical fluxes and storages of water in and through the soil layers on each plane. Flow routing is then performed using variants of the kinematic wave method for both the surface and subsurface runoff from hillslopes, and diffusion wave methodolo²⁵ gies (i.e., Muskingum Cunge) for channels.





Seyyedi et al. (2014) provided details about the model implementation in the Susquehanna River Basin and reported model specifications, parameter calibration and performance results. In addition to the base model parameters (e.g., vertical hydraulic conductivity, suction head, and soil depth), three parameters were calibrated in Seyyedi 5 et al. (2014) based on soil and land cover data: horizontal conductivity, Kh, for the subsurface routing, overland flow roughness, N, for surface routing, and Manning's roughness, n, for channel routing. These parameters are scale dependent in that they capture both the hydraulic features (river reach and hillslope lengths) defined for a given model unit as well as all sub-model unit features not represented at the defined model scale (e.g., all tributaries not explicitly represented in the defined river network). The 10 calibration was performed by systematically adjusting the three parameters (Kh, N, n) to achieve zero mean error (ME, $m^3 s^{-1}$) for the annual maximum peak discharges at nine streamflow gauging stations shown in Fig. 1. As reported in Seyvedi et al. (2014), model performance after calibration includes zero mean error for the entire basin, while mean relative errors for individual gauges ranged between -16 to 23%, and errors for

¹⁵ mean relative errors for individual gauges ranged between –16 to 23 %, and errors for individual events ranged between –62 to 224 %. The largest error is from the gauge draining one of the smallest basin areas (1155 km²) during 2011 Tropical Storm Lee, which caused significant flooding especially in the northern Susquehanna River Basin. Overall, 86 % of the errors are within ±50 %, and approximately half are within ±25 %.

20 3 Error correction and downscaling scheme

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The stochastic space–time error model of Hossain and Anagnostou (2006), originally developed for satellite rainfall error modeling (hereafter named SREM2D), was devised in this study to disaggregate and error correct GLDAS precipitation datasets using reference data from the TRMM3B42V7 satellite precipitation product. Specifically, SREM2D was applied on the coarse (100 km) grid resolution GLDAS precipitation fields at 25 km grid resolution. Figure 3 illustrates the framework for the stochastic downscaling



and error correction. First SREM2D parameters are determined for each season using TRMM3B42V7 and GLDAS data from the calibration datasets of each season. Then SREM2D was applied to the GLDAS data during the validation period and evaluated against the reference Stage IV gauge adjusted radar-rainfall fields. Details about the 5 SREM2D model are provided in Hossain and Anagnostou (2006), while below we de-

scribe the model calibration results for the different seasons.

SREM2D parameters calibrated in this study are: (1) probability of rain detection (POD) (see Fig. 4e), (2) mean of the log-transformed multiplicative error, where error is the multiplicative factor "e = Rsensor/Rreference", this parameter is represented in

- 2-D spatial fields for each season on Fig. 4a-d, (3) mean value of missed rain rate, 10 (4) probability of no-rain detection (POD no rain), (5) correlation length for the retrieval error (CLret), (6) correlation length for the successful delineation of rain (CLrain det), and (7) correlation length for the successful delineation of no rain (CLno rain det). The calculated values for parameters 3 to 7 are presented in Table 3 for the selected ¹⁵ calibration events in each season.

In terms of spatial patterns, the correlation lengths of rain detection, no-rain detection and downscaled rain for all seasons are less than 83 km. The lower correlation length indicates lower dependence between variables in space. Regarding the random error, the range of standard deviation of logarithmic multiplicative errors is between 1.2 (fall)

and 1.65 (winter). The values represent higher magnitude of variability of error between 20 reference and sensor data in winter relative to the other seasons. The POD_{no-rain} takes its maximum value during the summer season (0.98) while it drops to 0.85 for the winter season. The maximum mean rain rate of non-detected values is 0.82 for the summer: the corresponding value is 0.39 for the winter. Summer events are associated with higher rain rates, which results in higher non-detected rain rates from GLDAS. 25

The mean of the log-transformed multiplicative error for each season is presented in 2-D spatial fields (Fig. 4a-d). The negative mean logarithmic error indicates that the GLDAS is underestimating relative to the TRMM3B42V7. As we see in Fig. 4a-d, the GLDAS is underestimating almost everywhere and for all seasons. The magnitude





of underestimation in the summer is relatively higher than in the other seasons. The probability of rain detection is presented as a function of GLDAS rain rate (Fig. 4e). The summer events exhibit the lowest values whereas fall and spring have higher POD values.

Figure 5 presents the accumulated values based on all validation events for the different precipitation products and the 20 member SREM2D-generated ensembles of GLDAS downscaled precipitation, depicted by the shadow area on the plot. GLDAS rainfall significantly underestimates the other two precipitation datasets, especially in spring, fall and winter seasons, while the SREM2D-generated ensemble envelops encapsulate well the TRMM3B42V7 and, in most cases, the ground based reference accumulated rainfall. This indicates that the disaggregated GLDAS precipitation data are in agreement with the TRMM3B42V7 and the corresponding ground based radar rainfall data.

4 Error analysis methodology

- The error analysis devised in this study, aimed to demonstrate the degree of improvement due to downscaling, consists of three main hydrologic components (Fig. 6): reference simulation, observation simulation and downscaled and error corrected simulation. Reference simulation is based on generating runoff values through forcing HRR with the reference radar rainfall data. Observation simulation stands for forcing HRR
 with GLDAS or TRMM3B42V7 at the product resolution. Downscaled and error corrected simulation refers to forcing HRR with the ensemble mean of the SREM2D-
- downscaled GLDAS precipitation fields. There are two error analysis steps associated with the three main components: the rainfall error analysis and simulated surface runoff error analysis. Each error analysis component consists of three statistical met-
- ²⁵ rics: quantile-quantile (Q-Q) plots, mean scale quantile relative error (QRE), and the quantile root mean square of error relative to the mean of reference (QRMSE).





The Q-Q plots are used to compare basin-average quantile rainfall and runoff values from the various data sources (GLDAS at 100 km, TRMM3B42 at 25 km, mean GLDAS downscaling ensemble at 25 km) against the reference data source (radar at 4 km). The QRE is defined as the ratio of the sum of differences between reference and sensor values (precipitation or runoff) to the sum of reference values determined over the subbasins for each quantile range:

$$QRE = \frac{\sum_{i=1}^{n} \left(\left(P_{Sensor}^{s} \mid t_{j} \le P_{ref}^{s} < t_{j+1} \right) - \left(P_{ref}^{s} \mid t_{j} \le P_{ref}^{s} < t_{j+1} \right) \right)}{\sum_{i=1}^{n} \left(P_{ref}^{s} \mid t_{j} \le P_{ref}^{s} < t_{j+1} \right)}$$
(1)

where $P_{\text{Sensor}}^{\text{s}}$ is the sensor "basin averaged" precipitation/runoff value, $P_{\text{ref}}^{\text{s}}$ is the reference "basin averaged" precipitation/runoff value over the sub-basin, *t* is the threshold value which is based on the reference data quantiles, *j* is the quantile index, and *n* is total number of value in a particular scale and quantile range. The perfect value for this metric is zero, which means there is no difference between reference and the sensor values. Negative QRE value means the sensor is underestimating and the positive value means overestimating.

QRMSE is the root mean square of the differences between reference and sensor; it is normalized to the mean of reference values.

$$QRMSE = \frac{\sqrt[2]{\frac{1}{n}\sum_{j=1}^{n} \left(\left(P_{Sensor}^{s} \mid t_{j} \le P_{ref}^{s} < t_{j+1} \right) - \left(P_{ref}^{s} \mid t_{j} \le P_{ref}^{s} < t_{j+1} \right) \right)^{2}}{\text{mean } \left(P_{ref}^{s} \mid t_{j} \le P_{ref}^{s} < t_{j+1} \right)}$$

where $P_{\text{Sensor}}^{\text{s}}$ is the sensor "basin averaged" precipitation/runoff value, $P_{\text{ref}}^{\text{s}}$ is the reference "basin averaged" precipitation/runoff value over the sub-basin, *t* is the threshold value which is based on the reference data quantiles, *j* is the quantile index, and *n* is total number of value in a particular scale and quantile range. QRMSE quantifies the spread between sensor and reference data points.



(2)

To determine dependence of the error metrics on storm severity, QRE and QRMSE statistics are categorized in two groups according to the quantile values of rainfall and runoff, namely, values between 75th and 90th percentile and greater than the 90th percentile that represent moderate and extreme events, respectively. To investigate the ⁵ effect of seasonality and basin scale statistics, Q-Q plots are presented for the four seasons and different basin scales.

5 Results

5.1 Rainfall error analysis

As mentioned above, the rainfall error analysis is divided into two categories: frequency distribution and quantitative statistics. The frequency distribution uses the quantile quantile (Q-Q) plots, and the quantitative statistics include the QRE, and QRMSE error metrics. These are discussed next.

5.1.1 Frequency distribution

To assess the correspondence between sensor and reference rainfall data, we plotted the quantile values from TRMM3B42V7, GLDAS and downscaled ensemble-mean GLDAS (sensor) against the corresponding quantile values of the reference radar rainfall (Fig. 7). In each Q-Q plot the x-axis represents sensor values and the y-axis represents radar values in mm h⁻¹. We show significant changes in the Q-Q plots for the different basin scales (small to large) and seasons.

²⁰ GLDAS show a systematic underestimation at all seasons and basin scales. The underestimation is most severe at the smallest basin scales (top panels). During the summer convective rainfall season, the underestimation reduces significantly for medium to large basin scales, and it turns to slight overestimation for the small quantile values (< 1 mm h⁻¹). On the other hand, the GLDAS downscaled ensemble-mean data





exhibit much better agreement with the reference radar rainfall data. The best agreement is observed during the fall and summer seasons, while good agreement is also depicted during the spring season. The winter season exhibits a strong underestimation (overestimation) of the low (high) quantile values. Overall, the downscaled GLDAS precipitation dataset exhibits similar performance to the TRMM3B42V7 product in the fall, summer and spring seasons, while in the winter, the downscaled GLDAS shows stronger underestimation than TRMM3B42V7 for the low quantile values.

5.1.2 Quantitative statistics

The seasonal variation of the mean relative error and relative root mean square error statistics vs. basin scale for GLDAS, TRMM3B42V7, and the downscaled ensemblemean GLDAS are presented in Figs. 8 and 9, respectively. These statistics are based on precipitation values that exceed the 90th percentile. The main point to note is that no datasets show significant changes with basin scale. In spring the GLDAS is significantly underestimating while TRMM3B42V7 is almost unbiased, while the down-

- scaled GLDAS is slightly overestimating for all basin size categories. In summer all datasets are underestimating. The magnitude of underestimation in GLDAS is significantly higher than that of TRMM3B42V7 or the downscaled ensemble-mean GLDAS. In fall, GLDAS is significantly underestimating while the downscaled ensemble-mean GLDAS is almost unbiased, in contrast to the TRMM3B42V7, which is slightly over-
- estimating. In winter, GLDAS is underestimating while TRMM3B42V7 and downscaled ensemble-mean GLDAS are overestimating. The magnitude of overestimation in the downscaled ensemble-mean GLDAS is lower than the underestimation in GLDAS. For the random component of precipitation error (relative RMSE), the three precipitation datasets are performing similarly, with scores very close in the summer and fall sea-
- sons (scores ranging between 0.9 and 1.05). Overall, GLDAS exhibits lower relative RMSE values than the other two precipitation datasets, with this difference becoming more significant (range between 0.8 and 1.4) during winter and spring seasons.





5.2 Simulated runoff error analysis

Time series of the simulated runoff for the entire basin derived from forcing the HRR model with GLDAS (observation simulation), TRMM3B42V7 (product simulation), downscaled ensemble-mean GLDAS (downscaled and error corrected simulation), and

- radar-rainfall data (reference simulation) for the validation data sample of each season are presented in Fig. 10. As shown in the time series plot, GLDAS is systematically underestimating runoff relative to the other datasets, and particularly during the major hurricane events in the fall. The downscaled ensemble-mean GLDAS performs significantly better and is shown to be able to capture the events and the overall flow patterns.
- In the case of the high flow fall events (associated with two hurricanes), the downscaled ensemble-mean GLDAS simulated runoff seems to be between TRMM3B42V7 and reference data. Below we discuss quantile-quantile (Q-Q) plots and QRE, and QRMSE error metrics for the runoff simulations.

5.2.1 Frequency distribution

- The quantile-quantile (Q-Q) plots of the simulated runoff values from the three datasets (i.e., TRMM3B42V7, GLDAS, and downscaled ensemble-mean GLDAS) against the reference simulations are presented in Fig. 11. Similar to Fig. 7, GLDAS exhibits a strong underestimation of runoff at all seasons and basin scales. The underestimation is shown to the more significant in the fall, spring and winter seasons, while
 it reduces significantly during the summer events. The ensemble-mean downscaled GLDAS on the other hand exhibits very good agreement with the reference values,
- particularly during fall and spring seasons. This agreement is very similar to the one exhibited for the TRMM3B42V7 dataset, indicating that downscaling makes GLDAS perform similarly as the corresponding TRMM3B42V7 dataset, which was used in the calibration of the stochastic model parameters.





5.2.2 Quantitative statistics

Figures 12 and 13 show the two error metrics (QRE and QRMSE) determined for the validation sample reference runoff simulation values exceeding the 90th percentile value for the different seasons. As shown in the QRE plots of Fig. 12, GLDAS underestimates significantly in all seasons (Fig. 12). The magnitude of underestimation is the strongest in summer and fall seasons and the lowest in spring season. Winter season underestimation reduces with increasing basin scale. The ensemble-mean downscaled GLDAS QRE values exhibit significant bias reduction in runoff simulations, particularly in the fall and winter seasons. In spring, the downscaled GLDAS exhibits
overestimation, which is still lower in absolute magnitude than the underestimation of the original GLDAS runoff simulations. The QRE values of the TRMM3B42V7 product are consistently low, showing a positive bias of < 10 %.

For the random error component, downscaling consistently improves the QRMSE statistic at all basin scales and for all seasons. The greatest reduction on QRMSE is

- in the summer and winter seasons, while spring exhibits the least effect. The satellite product (TRMM3B42V7) shows consistently lower QRMSE values than both GLDAS and downscaled GLDAS products for all basin scales and seasons. The greatest difference is in the summer and fall seasons that are associated with a more organized convective system and a less snow/mixed phase precipitation. Spring season also ex-
- hibits a slight basin scale dependence on QRMSE for the downscaled GLDAS and TRMM3B42V7 product driven runoff simulations; no significant basin scale dependence is presented for the other seasons or products.

The above findings are in contrast with the increased random error component shown in the downscaled GLDAS precipitation product (Fig. 9). To understand this as-

pect, we present in Table 4 the QRMSE ratios between runoff and precipitation (error propagation) for the two products, seasons and basin scales. The downscaled GLDAS exhibits dampening of the random error component from precipitation to runoff simulations; this dampening seems to be less dependent on basin scale and more related





to season. For example, winter and spring seasons exhibit the strongest dampening of random error (ratios around 0.5), while in the summer the ratio is around one (i.e., no change), and in the fall the ratio is around 0.8 with a slight basin scale dependence (i.e., ranging from 0.86 for basins below 1000 km² to 0.79 for basins greater than 10 000 km²). On the other hand, the original GLDAS product shows either an increase in the random error component from precipitation to runoff simulations during summer and fall seasons, or a weaker (about half) dampening, compared to the downscaled product, in winter and spring seasons. These differences in precipitation to runoff error propagation convert the slightly increased random error of the downscaled GLDAS
product in precipitation to a significantly lower random error in runoff simulations, which is consistent with our aim of improving the hydrologic use of GLDAS products in flood modeling.

6 Conclusions

The aim of the study was to evaluate a stochastic downscaling and error correction
 approach for improving the use of a global reanalysis precipitation dataset (GLDAS) in
 flood simulations. GLDAS is available over a relatively long time period (since 1979),
 which provides a good source of precipitation data for hydrological analyses and global
 flood hazard mapping. However, it has been shown in Seyyedi et al. (2014) that the resolution and biases of this product introduce significant runoff simulation errors, which
 limit its applicability for flood modeling. In this study we present a two dimensional

- stochastic error model (SREM2D) to downscale and adjust GLDAS precipitation data using as reference the higher resolution and accuracy TRMM3B42V7 satellite precipitation product. The study focused on a large basin (Susquehanna River Basin) in the northeast US subjected to 437 rainfall events over a 10 year period (2002–2011),
- which were grouped in four seasons. The hydrologic simulations were performed with the HRR model, which was calibrated using radar-rainfall and observations from nine USGS streamflow gauges.





The improvements from downscaling and adjusting the GLDAS precipitation were evaluated in terms of both rainfall and runoff simulations using frequency distributions and quantitative error metrics. The effect of basin scale and seasonality were considered in this analysis. For the precipitation error analysis, the quantile-quantile plots indicated that GLDAS is meaningfully underestimating for all seasons and all basin scales, while the satellite-driven downscaled GLDAS ensembles reduced significantly that bias, reaching a performance similar to the TRMM3B42V7 precipitation product. This was confirmed by the mean relative error statistic, where downscaled GLDAS shows substantial reduction of the strong underestimation exhibited in the original GLDAS product. The error analysis in simulated runoff values gave similar bias patterns as those in the precipitation products. The downscaled ensemble-mean GLDAS product has considerably reduced bias compared to the original GLDAS product. There is a slight basin scale effect on the evaluated statistics, with slightly better runoff re-

- sults for larger basin sizes. The random error in the simulated runoff values reduces meaningfully for the downscaled ensemble-mean GLDAS product relative to the original GLDAS. This was explained by the properties of the random error propagation from precipitation to runoff simulations, where for the original GLDAS the random error is either increasing (summer and fall seasons) or slightly decreasing (winter and spring). On the other hand, the downscaled GLDAS product showed a remarkable
- dampening (0.5–0.8) of the random error from precipitation to runoff simulations. This can be attributed to hydrologic processes (infiltration and runoff generation) that can average out the random precipitation error component of the high-resolution products (e.g., downscaled GLDAS), but make discharge errors worse for the strongly underestimated GLDAS rainfall rates within the basin.
- ²⁵ Overall, results presented in this study indicate that the proposed satellite precipitation based downscaling and error correction method has the potential to improve the hydrological use of GLDAS precipitation reanalysis datasets. The main advantage of this approach is that it uses high-resolution global precipitation products from multisensor satellite observations, which makes it flexible to implement over areas with





limited ground based measurements. Furthermore, the downscaling scheme is modular in design and can be applied to any gridded dataset.

The proposed scheme was demonstrated over northeast US, which is a data rich area. As stated in the study area section, TRMM3B42V7 technique uses regional ground based precipitation measurements from rain gauges to adjust the precipita-5 tion retrieval. Although this approach is consistently applied globally, many areas of the world do not have a gauge density as large as the US network. As argued in studies reported in this paper, rain gauge adjustments in data poor areas may worsen the accuracy of TRMM3B42V7 product. Therefore, future research should evaluate this scheme

- on the basis of other satellite products that do not use rain gauge based adjustments to represent more accurately the conditions of data poor areas. Another extension of this research is to apply the SREM2D downscaling scheme on the entire (35 year) record of GLDAS precipitation data to derive multi-year downscaled GLDAS reanalysis ensembles, and use them through the hydrologic model of this study to derive flood return
- periods for the Susquehanna River Basin. Finally, extending the downscaling methodol-15 ogy to GLDAS as well as other reanalysis products, such as ERA-40 and ERA-interim, at the global scale in conjunction with multi-year (1998-2014) high-resolution precipitation products from satellite-only techniques (e.g., CMORPH, PERSIANN) would allow derivation of a high accuracy global satellite-driven water resources reanalysis inde-
- pendent from ground measurements. Such products could be used in many engineer-20 ing and scientific applications, such as flood and drought frequency analyses, design of hydraulic structures, or reservoir design and operation optimization.

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Table 1. Number of basins for each basin scale category.

Basin scales (km ²)	# of basins
315–1000	154
1000–3150	77
3150-10 000	51
10 000–31 500	53
31 500-100 000	38





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Table 2. Number of flood events selected for each season.

Events	Number of events	Percentage out of the total number of events (%)
Spring	94	21
Summer	74	17
Fall	157	36
Winter	112	26
Total	437	100



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Table 3. SREM2D parameters determined for GLDAS downscaling for the four seasons using the calibration events.

SREM2D Parameter	Spring	Summer	Fall	Winter
Mean (mu-Gaussian of log-error) PODrain Sigma (std.dev Gaussian of log-error)	Fig. 4a–d Fig. 4e 1.48	Fig. 4a–d Fig. 4e 1.35	Fig. 4a–d Fig. 4e 1.20	Fig. 4a–d Fig. 4e 1.65
Missed mean rain rate (mm h ⁻¹) POD no-rain	0.58 0.88	0.82 0.98	0.48 0.93	0.39 0.85
CLrain-downscale (km)	22	20	18	21
CLrain det (km)	43	40	48	40
CLno rain det (km)	49	15	67	83

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Table 4. The ratio of QRMSE in runoff to QRMSE in precipitation for GLDAS and ensemblemean downscaled GLDAS data.

Scale	< 1000 km ²		3150 to 10 000 km ²		$> 10000 \text{km}^2$	
	GLDAS	downscaled GLDAS	GLDAS	downscaled GLDAS	GLDAS	downscaled GLDAS
Spring	0.83	0.55	0.80	0.57	0.80	0.53
Summer	1.36	0.96	1.39	1.06	1.29	0.95
Fall	1.19	0.86	1.13	0.81	1.12	0.79
Winter	0.78	0.46	0.81	0.47	0.81	0.46





Figure 2. Cumulative probability of radar rainfall rain rates in the calibration and validation events selected for each season.







Figure 3. Stochastic downscaling framework. It consists of two main parts; the left side is indicating required SREM2D parameters and the right side shows GLDAS ensemble generating and quality assessment with the absolute reference data (Stage IV radar data).





Figure 4. SREM2D parameters, 2-D spatial mean of logarithmic error "e" for each season, (a) spring, (b) summer, (c) fall, (d) winter; probability of rain detection as function of GLDAS rain rate (e).



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Figure 5. Cumulative precipitation values of the validation events in the three seasons; the shaded area indicates the 20 ensemble members of downscaled and error corrected GLDAS data.







Figure 6. Flow diagram for the error analysis methodology.



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Figure 7. Quantile-Quantile plots between sensor (TRMM3B42V7, GLDAS and downscaled GLDAS) and radar precipitation values. Rows are indicating different basin scale categories. Columns are representing the different seasons.







Figure 8. QRE error metric determined conditional to reference precipitation values exceeding their 90th percentile. The horizontal axis indicates basin scale categories presented in Table 2. Results are presented for spring (upper left panel), summer (upper right panel), fall (lower left panel) and winter (lower right panel) seasons.







Figure 9. QRMSE error metric determined conditional to reference precipitation values exceeding their 90th percentile. The horizontal axis indicates basin scale categories presented in Table 2. Results are presented for spring (upper left panel), summer (upper right panel), fall (lower left panel) and winter (lower right panel) seasons.





Figure 10. Runoff time series driven by the different precipitation product over the basin indicated in Fig. 1 and consisting of the selected validation events of each season.







Figure 11. Quantile-Quantile plots between sensor (TRMM3B42V7, GLDAS and downscaled GLDAS) and radar rainfall-driven runoff simulations. Rows are indicating different basin scale categories. Columns are representing the different seasons.







Figure 12. QRE error metric determined conditional to reference runoff values exceeding their 90th percentile. The horizontal axis indicates basin scale categories presented in Table 2. Results are presented for spring (upper left panel), summer (upper right panel), fall (lower left panel) and winter (lower right panel) seasons.





Figure 13. QRMSE error metric determined conditional to reference runoff values exceeding their 90th percentile. The horizontal axis indicates basin scale categories presented in Table 2. Results are presented for spring (upper left panel), summer (upper right panel), fall (lower left panel) and winter (lower right panel) seasons.



