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Information on extreme precipitation for future climate is needed to assess the changes in the frequency and intensity of flooding. The primary source of information in climate change impact studies is climate model projections. However, due to the coarse resolution and biases of these models, they cannot be directly used in hydrological models. Hence, statistical downscaling is necessary to address climate change impacts at the catchment scale.

This study compares eight statistical downscaling methods often used in climate change impact studies. Four methods are based on change factors, three are bias correction methods, and one is a perfect prognosis method. The eight methods are used to downscale precipitation output from fifteen regional climate models (RCMs) from the ENSEMBLES project for eleven catchments in Europe. The overall results point to an increase in extreme precipitation in most catchments in both winter and summer. For individual catchments, the downscaled time series tend to agree on the direction of the change but differ in the magnitude. Differences between the statistical downscaling methods vary between the catchments and depend on the season analysed. Similarly, general conclusions cannot be drawn regarding the differences between change factor and bias correction methods. The performance of the bias correction methods during the control period also depends on the catchment, but in most cases they represent an improvement compared to RCM outputs. Analysis of the variance in the ensemble of RCMs and statistical downscaling methods indicates that up to half of the total variance is derived from the statistical downscaling methods. This study illustrates the large variability in the expected changes in extreme precipitation and highlights the need of considering an ensemble of both statistical downscaling methods and climate models.

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1 Introduction

Both the frequency and intensity of extreme precipitation are expected to increase under climate change conditions in Europe (Christensen and Christensen, 2003; IPCC, 2012). Several climate studies have focused on assessing these changes (e.g. Fowler and Ekström, 2009; Frei et al., 2006; Kendon et al., 2008) and their consequences in relation to the risk of flooding (Christensen and Christensen, 2003; IPCC, 2012; Leander et al., 2008; Vansteenkiste et al., 2013). The main steps often followed in these studies comprise the selection of one or several global climate models (GCM), regional climate models (RCM) and/or statistical downscaling methods (SDM). In climate change impact studies, hydrological models are then used to estimate changes in hydrological variables.

GCMs are the most comprehensive and widely used models for simulating the response of the global climate system to changes in greenhouse gas emissions. However, their spatial resolution (approximately 150 km) is often too coarse for addressing climate change impacts at the local scale, and variables such as precipitation are often biased. RCMs are climate models that cover a specific region (e.g. Europe) and use GCMs as boundary condition. RCMs have a higher spatial resolution (approximately 25 km) than GCMs, which makes them more adequate for assessing changes at the local scale. Nonetheless, RCMs often inherit the biases from the GCMs and their spatial resolution might still be too coarse for some impact studies (Maraun et al., 2010). Hence, further statistical downscaling is often needed to obtain bias-corrected projections at the local scale (Fowler et al., 2007). Statistical downscaling is based on defining a relationship between the large scale outputs of the RCMs (or GCMs) and the local scale variables required in impact studies (Fowler et al., 2007; Wilby et al., 2004).

In recent years, a relatively large number of RCM outputs have been made available, but there is no consensus on the best way to assess their performance (Knutti et al., 2010). There are several challenges in evaluating RCMs. For example, a RCM might

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perform well for some variables in some regions but not for other variables. Moreover, even if a climate model performs well under present climate conditions it might not perform equally well under future conditions (Knutti, 2010). For these reasons, it is generally recommended to use a multi-model ensemble of RCMs (or GCMs) instead of using a single model (Knutti et al., 2010; van der Linden and Mitchell, 2009; Tebaldi and Knutti, 2007).

Similarly, a large number of SDMs have been suggested in the literature, but there is no consensus on the best SDM. Fowler et al. (2007) and Maraun et al. (2010) provide comprehensive reviews of the methods existing in the literature and their suitability for different applications. As in the case of climate models, the validation of SDMs is challenging. Only a few recent studies address this issue (e.g. Maraun et al., 2013; Räisänen and Rätty, 2013; Teutschbein and Seibert, 2012; Vrac et al., 2007).

In order to account for the uncertainties in climate change impact studies and due to the lack of consensus on the best climate model and SDM, a number of studies consider multiple climate models and SDMs. For example, Bürger et al. (2013) used eight SDMs to downscale six GCMs and three emission scenarios, Sunyer et al. (2012) used five SDMs to downscale four RCMs driven by two GCMs, and Hanel et al. (2013) used four SDMs and fifteen RCMs. In addition, some studies also consider hydrological models in the chain of uncertainties. For example, Wilby and Harris (2006) used two SDMs, four GCMs, and two emission scenarios combined with two hydrological model structures and two sets of hydrological model parameters. Lawrence and Haddeland (2011) compared two SDMs, six RCMs driven by two GCMs, and two emission scenarios and used multiple parameter sets for the hydrological impact model.

The main focus of this study is to assess the changes in extreme precipitation in eleven European catchments using a range of SDMs and RCMs. For this purpose, precipitation outputs from fifteen RCMs driven by six GCMs from the ENSEMBLES project (van der Linden and Mitchell, 2009) are downscaled using eight SDMs. Four SDMs are change factor methods, three are bias correction methods and one is a perfect prognosis method. Some previous studies have compared the results from

change factors and bias correction methods (e.g. Hanel et al., 2013; Ho et al., 2012; Räisänen and Rätty, 2013) for mean temperature and mean precipitation. Here we focus on changes in extreme precipitation.

The results presented here are based on a coordinated effort carried out as part of the COST Action FloodFreq (European Procedures for Flood Frequency Estimation, www.cost-floodfreq.eu). The outputs from this study have been used as inputs to hydrological impact modelling in order to assess the changes in extreme discharge and flood frequency in the eleven catchments (Hundechea et al., 2014).

The next section describes the case study catchments and the data used, followed by the methodology section. Section 4 presents and discusses the results, and Sect. 5 summarizes the findings and conclusions of the study.

2 Case study catchments and data

2.1 Observations

Figure 1 shows the location of the eleven catchments studied and the main properties of each catchment are summarized in Table 1. The two most northern catchments are the Norwegian catchments Nordelva at Krinsvatn (NO2) and Atna at Atnasjø (NO1), and the most southern catchment is Yermasoyia (CY) in Cyprus. The size of the catchments varies from the 6171 km² of Mulde (DE) in Germany to the 67 km² of Upper Metuje (CZ2) in the Czech Republic. Different precipitation patterns are represented in the catchments. The mean precipitation ranges between 2437 mm yr⁻¹ in NO2 to 589 mm yr⁻¹ in Nysa Kłodzka in Poland (PL). The season with more daily extreme events is summer for most of the catchments: NO1, DE, Aarhus in Denmark (DK), Merkys in Lithuania (LT), Grote Nete in Belgium (BE), and Jizera in the Czech Republic (CZ1). In NO2 and CY, winter is the season where most extremes occur, while in the Turkish catchment Omerli (TR) it is autumn.

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The observational data used is daily catchment precipitation, as the data were to be further used in catchment-based hydrological modelling in a separate work. Different methods have been used to obtain these areal precipitation time series. The catchments NO2, NO1, DK, and CZ2 use gridded data to obtain areal average daily values for the catchment, while the other catchments use station data to construct areal values.

2.2 Regional climate models

The climate model data used in this study is an ensemble of fifteen RCMs from the ENSEMBLES project (van der Linden and Mitchell, 2009). These fifteen simulations are based on eleven RCMs driven by six different GCMs. Table 2 shows the combinations of RCMs-GCMs used. The spatial resolution of all the models is 0.22° (approximately 25 km). For all the models, daily precipitation time series are available for the time period 1951–2100. In this study, we consider the time period 1961–1990 and 2071–2100 as the control and future time periods, respectively. It must be noted that six RCMs do not have data available for the year 2100. The future period used for these models is 2071–2099; this is not expected to have an influence on the results of this study. For each catchment, daily precipitation has been extracted from the 15 RCMs for the two periods using nearest neighbour interpolation to the catchment centroid. It must be noted that to simplify the calculations, the same control period is used for all the catchments. Therefore, in some catchments, the time period with observations (see Table 1) and the control period used from the RCMs do not fully overlap.

3 Methodology

3.1 Statistical downscaling methods

Eight SDMs are used to obtain downscaled RCM projections at the catchment scale. These methods are based on the idea that it is possible to define a relationship

between the RCM for the control period and the observations and then applies this to the RCM output for the future period.

A common terminology is used for describing the methods: P^{Obs} and P^{Fut} refer to the observed precipitation and the downscaled precipitation for the future period, respectively; and P^{RCMCon} and P^{RCMFut} refer to the precipitation output from the RCMs for the control and future time period, respectively. Similarly, $ECDF^{Obs}$ and $ECDF^{Fut}$ refer to the empirical cumulative distribution function (ECDF) for the observed precipitation and for the downscaled precipitation for the future while $ECDF^{RCMCon}$ and $ECDF^{RCMFut}$ refer to the ECDF estimated from the RCMs for control and future time period, respectively. The methods used here have been implemented as suggested in the literature, i.e. no harmonisation has been applied to enable, for example, a common method for accounting for seasonality or the definition of wet days. Table 3 summarizes the main advantages and disadvantages of each method.

3.1.1 Bias correction of mean

The bias correction of mean, BCM, is a simple method based on removing systematic errors in mean daily precipitation. It has been used in several hydrological applications (e.g. Hanel et al., 2013; Leander and Buishand, 2007; Leander et al., 2008). Here the method proposed by Leander and Buishand (2007) is used. This is based on the transformation:

$$P_{y,j}^{Fut} = a_j P_{y,j}^{RCMFut} \quad (1)$$

where y is the year, j is the day of the year and a_j is the transformation parameter. a_j is estimated in two steps. First, for all the years a subset of 61 days centred on day j is created for $P_{.,j}^{Obs}$ and $P_{.,j}^{RCMCon}$. Then, a_j is estimated as the mean of $P_{.,j}^{Obs}$ divided by the mean of $P_{.,j}^{RCMCon}$.

3.1.2 Bias correction of mean and variance

The bias correction of mean and variance method, BCMV, is an extension of the previous method. It corrects the RCM outputs considering systematic errors in both the mean and the variance. This method has been applied in several studies (e.g. Hanel et al., 2013; Leander and Buishand, 2007; Leander et al., 2008). The method suggested by Leander and Buishand (2007) is followed here, which is based on the transformation:

$$P_{y,j}^{\text{Fut}} = a_j \left(P_{y,j}^{\text{RCMFut}} \right)^{b_j} \quad (2)$$

where a_j is estimated as described above for BCM, and b_j is estimated by equating the coefficient of variation of $(a_j P_{y,j}^{\text{RCMCon}})^{b_j}$ and $P_{y,j}^{\text{Obs}}$. b_j is found by iteration since it is not possible to solve this equation in closed form.

3.1.3 Bias correction quantile mapping

Bias correction based on quantile mapping, BCQM, has been widely used to correct RCM outputs over Europe (e.g. Dosio and Paruolo, 2011; Gudmundsson et al., 2012; Piani et al., 2010). The non-parametric empirical quantile method suggested in Gudmundsson et al. (2012) is followed here. It is based on the concept that there exists a transformation h , such that:

$$P^{\text{Obs}} = h(P^{\text{RCMCon}}) = \text{ECDF}^{\text{Obs}-1}(\text{ECDF}^{\text{RCMCon}}(P^{\text{RCMCon}})) \quad (3)$$

First, all the probabilities in ECDF^{Obs} and $\text{ECDF}^{\text{RCMCon}}$ are estimated at a fixed interval of 0.01. Then, h is estimated as the relative difference between the two ECDFs in each interval. Interpolation between the fixed intervals is based on a monotonic tricubic spline interpolation. A threshold for the correction of the number of wet days is estimated from the empirical probability of non-zero values in P^{Obs} . All RCM values

below this threshold are set to zero. The precipitation values for the full annual daily series are corrected without subsampling by season or month, as suggested by Piani et al., 2010. The method was implemented in R using the *qmap* package (Gudmundsson, 2014).

3.1.4 Expanded downscaling

Expanded Downscaling, XDS, is a perfect prognosis technique which maps large-scale atmospheric fields to local station data. XDS was originally introduced for weather forecasting purposes, but it has been recently used in climate change studies (e.g. Bürger and Chen, 2005; Bürger et al., 2013; Dobler et al., 2012). The XDS approach is based on defining a multivariate linear regression between predictors y (multivariate fields of atmospheric variables) and predictands x (local scale variables, i.e. catchment precipitation), extended by the side condition that the local co-variability between the variables (and stations) is preserved:

$$\text{XDS} = \arg \min_Q \|xQ - y\|, \text{ subject to } Q'x'xQ = y'y, \quad (4)$$

where XDS is the least square-solution of the matrix Q which is found among those that preserve the local covariance ($Q'x'xQ = y'y$). By this approach, the estimation of extremes is supposed to be improved compared to regular linear regression models. See Bürger et al. (2009) for a detailed description of this method.

The XDS model is first trained on RCM atmospheric fields driven by the ECMWF ERA-40 reanalysis (Uppala et al., 2005) and local scale observations with at least 10 yrs of data. Then, RCM outputs for the control and future periods are used to generate time series at the local scale. Generally XDS allows for exploring a range of large scale variables as predictors. Large-scale reanalyses, however, are generally in better agreement with local observations than an RCM simulation driven by those reanalyses, simply because that the simulation likely differs from the actual weather realization which is used for XDS calibration. This has the consequence that a perfect

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prognosis approach is no longer perfect. For this study, the predictors were therefore chosen rather “conservatively”, with predictor variables being limited to large-scale total and convective precipitation. The result is a set of predictors that is, moreover, unique across all catchments. The XDS source code and documentation can be downloaded from: <http://xds.googlecode.com>.

3.1.5 Change factor of mean

The change factor of mean, CFM, is a simple method which has been widely applied in hydrological applications (Hanel et al., 2013; Prudhomme et al., 2002; Sunyer et al., 2012). It is based on applying the change in mean precipitation projected by the RCMs to the observed data. The method described in Sunyer et al. (2012) is followed here. Similarly to BCM, this method is based on the transformation:

$$P_{m,t}^{\text{Fut}} = a_m P_{m,t}^{\text{Obs}} \quad (5)$$

where m refers to the month and t to each time step in the observations; a_m is the relative change in the precipitation mean for month m . a_m is estimated as the mean of $P_{m,.}^{\text{RCMFut}}$ divided by the mean of $P_{m,.}^{\text{RCMCon}}$.

3.1.6 Change factor of mean and variance

The change factor of mean and variance, CFMV, is an extension of CFM. It has been applied in several studies (e.g. Hanel et al., 2013; Räisänen and Rätty, 2013; Sunyer et al., 2012). CFMV modifies the observed time series using the change in both the mean and variance. The method described in Sunyer et al. (2012) is followed here. Similar to BCMV, the method is based on the transformation:

$$P_{m,t}^{\text{Fut}} = a_m \left(P_{m,t}^{\text{Obs}} \right)^{b_m} \quad (6)$$

where a_m is estimated as described for CFM. b_m is estimated by equating the coefficient of variation of the time series $(a_m P_{m,t}^{\text{Obs}})^{b_m}$ and the coefficient of variation

estimated for the future period. As in BCMV, this is solved by iteration. The coefficient of variation for the future period is calculated from the relative change in the mean and variance projected by the RCMs.

3.1.7 Change factor quantile mapping

The change factor quantile mapping, CFQM, is based on using the relative change in the ECDF projected by the RCMs to modify the observed data. It has been applied in several climate change studies (e.g. Boé et al., 2007; Olsson et al., 2009).

This method uses the ECDF of wet days estimated for each month m for the observations, and the RCM output for the control and future periods. The probability intervals considered are 0.001 for quantiles lower than 0.9 and 0.0005 for higher quantiles (linear interpolation between intensities is applied to obtain the precipitation intensity for all the quantiles). Wet days are defined as days with precipitation higher than 1 mm. The perturbation of the observed time series is carried out in three steps. First, for each wet day in each month m , $ECDF_m^{Obs}$ is used to estimate the probability of the precipitation intensity. Second, the relative change in the intensity for this probability is estimated from $ECDF_m^{RCMFut}$ and $ECDF_m^{RCMCon}$. This change is then multiplied to the observed precipitation intensity to obtain the intensity for the future period. Dry days in the observations are not modified.

3.1.8 Change factor quantile perturbation

The change factor quantile perturbation, CFQP, is similar to CFQM but it also accounts for changes in the number of wet days. This method has been applied in a number of hydrological studies analysing the effects of climate change (e.g. Ntegeka et al., 2014; Taye et al., 2011; Vansteenkiste et al., 2013; Willems and Vrac, 2011). The version used here has been applied in Willems and Vrac (2011).

The observations are perturbed in a two-step way. First, the number of wet days (days with precipitation higher than 0.1 mm day^{-1}) is changed for each month. The

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relative change in the frequency of wet days is estimated from the RCM output. If the frequency increases, dry days are randomly selected and replaced by random wet day intensities from the time series. Otherwise, wet days are randomly replaced by zero precipitation. In the second step, the wet day intensities are perturbed in a similar way as in the CFQM method. The empirical probability of each intensity is first estimated. The relative change in the intensity for each probability is then calculated (linear interpolation is applied when different probabilities are obtained for the control and future period) and used to perturb the observations.

These two steps are repeated 10 times. The repetition that leads to the results closest to the mean monthly precipitation value of all the repetitions is selected. See Willems and Vrac (2011) for more details on this method and the checks done on the coefficient of variation, skewness and autocorrelation.

3.2 Extreme precipitation Index

The outputs from all the statistical downscaling methods are analysed using an extreme precipitation index (EPI). This is defined as the average change in extreme precipitation higher than a defined return period. In this study, the return period is set equal to 1 and 5 yr. EPI is estimated separately for each SDM, RCM, catchment, threshold return period, season and temporal aggregation. Four seasons are considered: winter (December to February), spring (March to May), summer (June to August), and autumn (September to November). Additionally, the index is estimated considering the whole time series, i.e. without dividing in seasons. The temporal aggregations considered are 1, 2, 5, 10, and 30 days. These are estimated using a moving average from the daily time series.

The first step in the calculation of EPI is to extract the extreme value series from the precipitation time series using a Peak Over Threshold (POT) approach. Peaks are extracted by using the 1 and 5 yr threshold return periods. For example, with a 30 yr record, the 30 and 6 most extreme events are included in the extreme series for the 1 and 5 yr threshold levels, respectively. An independence criterion based on the inter-

event time is applied to make sure that extreme values are independent, i.e. only values separated by more than Δt days are considered. Δt is set equal to the temporal aggregation, i.e. for an aggregation time of 1 day, events must be separated by more than one day. EPI is then estimated as:

$$5 \quad \text{EPI} = \frac{\overline{\text{POT}}_2}{\overline{\text{POT}}_1} \quad (7)$$

where $\overline{\text{POT}}_1$ and $\overline{\text{POT}}_2$ are the averages of the selected POT values used as reference and scenario, respectively. EPI takes the value of 1 if no change is estimated from reference to scenario and greater (less) than 1 if the average extreme precipitation is higher (lower) in the scenario time series.

10 In the results section, EPI is used to compare the changes in the downscaled time series from control to future. Additionally, three further comparisons are carried out. In total EPI is calculated for four different cases:

1. Comparison of the downscaled time series for the control and future periods.
2. Comparison of the RCM outputs for control and future periods. This allows us to compare the changes estimated from the downscaled precipitation, estimated in (i), to the changes projected by the RCMs.
3. For the four BC methods: comparison of the observations and the bias corrected RCMs for the control period. The value of the index for this comparison is a measure of the error of the BC methods in bias correcting the RCM outputs for extreme precipitation.
- 20 4. Comparison of the observations and RCM outputs for the control period. This comparison evaluates the performance of the RCMs in simulating extreme precipitation, and allows us to assess whether the error in the bias corrected time series, estimated in (iii), is smaller than in the RCMs.

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3.3 Variance decomposition

The variability in the EPI values found when comparing the downscaled time series for control and future arises mainly from three sources: GCMs, RCMs and SDMs. A variance decomposition approach is used to address the influence of each of these sources on the total variance for each catchment, return level, season and temporal aggregation. The approach described in Déqué et al. (2007, 2012) is followed here.

The total variance of EPI, V , can be split into the different contributions as:

$$V = R + G + S + RG + RS + GS + RGS \quad (8)$$

where R , G , and S are the individual parts of the variance explained by the RCMs, GCMs, and SDMs, respectively; RG , RS , and GS are the variance due to the interaction of RCM–GCM, RCM–SDM, and GCM–SDM, respectively; and RGS is the variance due to the interaction of all three sources. The part of the total variance explained by the RCMs, $V(R)$ is:

$$V(R) = R + RG + RS + RGS \quad (9)$$

The part of the total variance due to the GCMs, $V(G)$, and SDMs, $V(S)$, can be obtained in a similar way. The variances in Eqs. (8) and (9) can be estimated as:

$$R = \frac{1}{11} \sum_{i=1}^{11} \left(\overline{\text{EPI}}_{i..} - \overline{\text{EPI}}_{...} \right)^2;$$

$$RG = \frac{1}{11} \frac{1}{6} \sum_{i=1}^{11} \sum_{j=1}^6 \left(\overline{\text{EPI}}_{ij.} - \overline{\text{EPI}}_{i..} - \overline{\text{EPI}}_{.j.} + \overline{\text{EPI}}_{...} \right)^2; \quad (10)$$

$$RGS = \frac{1}{11} \frac{1}{6} \frac{1}{8} \sum_{i=1}^{11} \sum_{j=1}^6 \sum_{k=1}^8 \left(\overline{\text{EPI}}_{ijk} - \overline{\text{EPI}}_{ij.} - \overline{\text{EPI}}_{i.k} - \overline{\text{EPI}}_{.jk} + \overline{\text{EPI}}_{i..} + \overline{\text{EPI}}_{.j.} + \overline{\text{EPI}}_{..k} - \overline{\text{EPI}}_{...} \right)^2$$

show that the reconstruction approach can influence the results. From the results of the first verification, we decide to analyse the variance explained by the GCMs and RCMs separately (i.e. considering three source of variance) because, in our opinion, it adds value to separate the influence of the GCMs and RCMs. Nonetheless, we acknowledge that the results must be treated with caution due to the uncertainty added in the matrix reconstruction procedure.

4 Results and discussion

This section is divided into two main parts. The first part analyses the results of all SDMs. The second part focuses on the performance of the three BC methods and perfect prognosis method. All the results are shown for winter and summer as these are the two seasons where most of the extremes occur under present conditions. However, it should be noted that in some catchments changes in other seasons might also be important due to their influence on floods, see examples in Hundecha et al. (2014).

4.1 Statistical downscaling methods

This subsection analyses the results of the eight SDMs driven by all RCMs. A summary of the results obtained for all the catchments is first presented followed by a more detailed analysis of the differences between the SDMs for three selected catchments.

4.1.1 Summary for all catchments

Figure 2 summarizes the results of all the SDMs and RCMs for all the catchments for winter and summer for a temporal aggregation of 1 day. Additionally, it compares the results of the SDMs with the changes from control to future projected by the RCMs. For the catchment CY for some SDMs, two special situations are encountered. For the methods BCM and BCMV for both winter and summer periods, due to the few rainy days in some of the RCM simulations, some of the parameters take unrealistic values

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which lead to unrealistic values of EPI. Similarly, it is not possible to estimate the CFs used in the case of CFM, CFMV and CMQM in the summer period. The results of these methods are not included in the analysis for CY. For the other catchments no problems with the SDMs methods were encountered and all results are included in the analysis.

For winter, extreme precipitation is expected to increase in all the catchments (the median of EPI is greater than 1) except in CY. The median of EPI is similar for all catchments except for the two most northern (NO1 and NO2) and the most southern catchment (CY). The EPI values range between 1.11 and 1.2 for the 1 yr threshold, and 1.14 and 1.22 for the 5 yr threshold. For this season, a similar variability is found for all catchments, except for CY, where the variability is slightly larger than in the other catchments. For summer, the median is also greater than 1 for all the catchments except for the two most southern catchments (CY and TR). These two catchments also have a larger variability. In general, there are larger differences between and within the catchments in summer than in winter.

In most catchments, and for both threshold return levels, larger changes are expected for winter. Only in the case of NO2 are the changes obtained for summer larger than in winter. In LT, CZ2 and CZ1, larger changes are obtained for winter for the 1 yr level and for summer for the 5 yr level. In both seasons and in most catchments, larger changes and variability are obtained for the 5 yr level.

Comparing the changes obtained from the SDMs with the mean changes projected by the RCMs (see Fig. 2) there is a general tendency that slightly smaller changes are estimated from the uncorrected RCM projections. However, there are some significant differences. For example, for NO2 in winter and the 5 yr level, the uncorrected RCM projections point to a decrease of extreme precipitation but the SDMs point to an increase. The opposite situation is obtained for CY for the same season and 1 yr level. For CY in summer, there is also a rather large difference between the changes estimated from the uncorrected RCM projections and the SDMs.

Figure 2 does not differentiate between the variability due to the use of different SDMs and different RCM–GCM simulations. The variance decomposition approach is

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used to assess each of the sources of variance individually. Figure 3 shows the total variance decomposed in the variance arising from the GCMs, RCMs, SDMs and the interaction terms for all catchments for the 1 and 5 yr levels and temporal aggregation of 1 day. The results for CY for the summer are not shown because for a large number of cases EPI could not be calculated (due to the few rainy days in some of the RCM simulations), and the results for winter for CY do not include the results from BCM and BCMV

As shown in Fig. 2, the variance for the 5 yr level is higher for all catchments and seasons than is the variance for the 1 yr level. In summer, the variance tends to increase from north to south for the 5 yr level, and to some extent also for the 1 yr level. This trend is not observed in winter. The larger variance in the southern catchments and in the 5 yr level may be partially caused due to higher sampling variance (less number of extreme events). Figure 3 shows that in most cases the variance due to the RCM–GCM simulations is larger than the variance from the SDMs. However, the interaction term is in both seasons and in most catchments similar or larger than the individual sources of variance.

Figure 3 also shows the percentage explained by $V(G)$, $V(R)$, and $V(S)$, scaled to sum up to 100%. The scaling of the percentages to obtain a total of 100% is needed because some interaction terms are repeated in these three factors. As already mentioned, the percentage explained by the RCM–GCM simulations is in most cases larger than the percentage explained by the SDMs. The only exception is TR for summer and PL for winter for the 1 yr level. However, in all cases, the percentage explained by the SDMs is at least 30% of the total variance, which is considerable. Similar results are obtained for winter and summer and 1 and 5 yr levels. For both seasons and return levels, there are no clear spatial patterns in the percentages.

In all cases the percentage of the variance explained by the RCMs is larger than the percentage explained by the GCMs. For both return levels, in winter the average percentage explained by the GCMs is approximately 20% while in summer it is approximately 15%. The smaller percentage for the GCMs in the summer is due to

the larger relative influence of both the RCMs and SDMs. This is likely due to the fact that in Europe, extreme precipitation from convective storms occurs more frequently during summer, and this has a larger influence on the outputs from the RCMs and SDMs due to their higher spatial resolution.

5 The results of the variance decomposition obtained for aggregation levels larger than 1 day (not shown) point towards a smaller total variance. For this temporal aggregation, the main source of variation is also the RCM–GCMs but the percentage explained by SDMs is slightly higher than in a temporal aggregation of 1 day. The decrease in total variance and in the percentage explained by RCM–GCMs is mainly due to the
10 model outputs are more similar for larger temporal aggregations. The results from the variance decomposition highlight the need for considering both a range of SDMs and an ensemble of RCMs driven by different GCMs for assessing the uncertainty in the projection of changes in extreme precipitation.

4.1.2 Results for selected catchments

15 The previous section summarizes the main results regarding the expected changes in extreme precipitation when considering all the RCMs and SDMs. This section focuses on the differences between the statistical downscaling methods. For this purpose, three catchments have been selected: NO₂, DE, and TR (distributed north to south and with different precipitation patterns). Figure 4 shows the median, 25th, and 75th quantile of
20 EPI for each SDM for the three catchments for the 1 yr level and a temporal aggregation of 1 day.

In NO₂, for both seasons the SDMs based on BC show a lower EPI than the methods based on CFs. This could be because some RCMs under future conditions show a change in weather patterns, which causes extreme events to occur in a different
25 season than under the control period. This would have an influence on the changes in extreme precipitation obtained from the BC methods. In winter, all the CF methods point towards an increase in extreme precipitation, but some of the BC methods show

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a decrease for some RCMs. In summer, all methods point to an increase except XDS; this method leads to a small EPI and a large variability.

In DE, all the SDMs lead to similar median values except the BCMV in winter and CFM in summer. The differences between BCMV and the other two BC methods are due to some RCMs leading to very large changes when they are downscaled with BCMV, e.g. for RCA-ECHAM5, the values of EPI are 1.18 for BCM, 1.16 for BCQM and 1.63 for BCMV. This large value of EPI is most likely caused by unexpectedly large precipitation intensities obtained from the non-linear transformation in BCMV, which is one of the disadvantages of this method (see Table 3).

CFM leads to the lowest value of EPI obtained in summer. This is also the case for all the catchments considered in this study except NO2 and CY (results not shown). It indicates that mean precipitation is likely to increase less than the more extreme precipitation intensities. In addition, it illustrates that this method is not suitable for regions where the expected changes in extreme precipitation are different to the changes in mean precipitation.

In TR, the results of the SDMs vary more than in DE and NO2. For this catchment, CFM leads to the lowest EPI in both seasons, which indicates a lower increase in mean precipitation than in extreme precipitation, as in DE. In summer, all SDMs point to a decrease of extreme precipitation except BCM and BCMV, which do not show a change in extreme precipitation. These two methods show the largest variability for both winter and summer. The high variability for these two methods might be similar to the issues identified in CY, i.e. only a few rainy days in some periods in the RCM simulations.

For all catchments and both seasons, very similar results are obtained for CFQM and CFQP. This is expected since the main difference between the two methods is the treatment of wet day frequency. This is expected to have a minor impact, except for TR in summer. Similar results to those illustrated in Fig. 4 were obtained for the 5 yr level (results not shown).

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The results for the three catchments show that there is not a clear tendency in the differences between CF and BC methods. In addition, there is no evidence that methods that are based on the same statistics for the correction (e.g. BCM and CFM or BCMV and CFMV) will lead to similar results. Hence, it is not possible to generalize the results with respect to the use of SDM.

Figure 5 analyses the eight SDMs for the three catchments for two temporal aggregations: 1 and 30 days. In general, the variability in EPI in the RCM ensemble decreases for increasing temporal aggregation, except for a few cases, e.g. XDS in NO₂ and BCM for DE in summer. There is not a general indication that EPI either increases or decreases with increasing temporal aggregation.

In NO₂, EPI is larger for a temporal aggregation of 30 days for BCM, BCMV and BCQM and it is lower for the CF methods and XDS for summer. In winter, EPI for BCM, BCMV and BCQM is also slightly larger for a temporal aggregation of 30 days (in the case of BCM and BCMV, this means a smaller reduction of extreme precipitation). In DE, most methods show a lower EPI for 30 days except CFM in summer and CFM, CFMV and XDS in winter. Similarly, in TR all the methods show lower EPI for 30 days except for CFM, XDS and CFQM in summer. For all catchments, the results of the SDMs at 30 days temporal aggregation are more similar than for 1 day aggregation.

In most cases, EPI at 1 and 30 days are not considerably different and show the same signal (except in the case of TR for BCM and BCMV for both seasons and BCQM in winter). As for the 1 day aggregation, the results with temporal aggregation of 30 days do not allow general conclusions with respect to the use of the SDM.

4.2 Bias correction in the control period

The previous section focuses on the analysis of the expected changes in extreme precipitation. This section uses EPI to compare the results from the BC methods for the control period and the observations. This allows us to evaluate how well the different BC methods correct extreme precipitation from the RCMs. As in the previous section,

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season. For example, the bias corrected data for LT, BE and PL tend to overestimate extreme precipitation in winter, but underestimate this in summer. CZ1 in winter and NO2 in summer are the catchments that lead to the median closest to 1. The largest variability is found for PL in winter and TR and CY in summer.

5 The comparison of the error in the RCMs before and after bias correction shows that, in general, the error after bias correction is smaller than before bias correction. This shows that the BC methods improve the representation of extremes. However, in a few cases the error of the RCMs before bias correction is smaller than after bias correction, e.g. BE in winter and LT in summer. This is because some of the RCMs
10 result in large errors after bias correction. For example for BE with the HadRM3Q3-HadCM3Q3 model, values of 1.18 for BCM, 1.37 for BCMV, 1.24 for BCQMP, and 1.23 for XDS are obtained, while a value of 0.98 is obtained from the uncorrected data. Similar results are obtained for LT, for example with the RACMO2-ECHAM5 model, values of 0.91 for BCM, 1.19 for BCMV, 0.81 for BCQM and 0.73 for XDS are obtained,
15 while the uncorrected data gives a value of 1.05.

4.2.2 Results for selected catchments

Figure 7 shows the results of the three BC methods and XDS for NO₂, DE, and TR for the 1 yr level and 1 day temporal aggregation. The performance of each method varies depending on the season and catchment. For example, BCM overestimates extremes
20 in NO₂ in winter and TR in summer and underestimates them in NO₂ in summer and TR in winter. In DE, BCM performs equally well as BCMV. This is an example of the fact that simple BC methods can, in some cases perform similarly or better than more advanced methods. In the catchments considered in this study, there is not a clear tendency in the performance of the BC methods depending on the mean and extreme
25 precipitation regime.

In winter, the errors obtained for DE are smaller than in the other two catchments. EPI ranges from an underestimation of 4% (EPI equal to 0.96) for BCM and BCMV, to an overestimation of approximately 6% for BCQM and XDS. For this catchment and

both seasons, BCM and BCMV lead to better results than BCQM and XDS. In summer, the errors in NO₂ are smaller than in the other two catchments. For this catchment and this season, XDS is the method that leads to the smallest error and variability.

The largest errors and variability in the results are obtained for TR in both seasons. For this catchment and in the winter period, the median of all methods underestimate except XDS, while in summer BCM and BCMV overestimate extremes and the other two methods underestimate. A very large variability is obtained for BCM and BCMV in summer (the 25th and 75th percentiles range from 0.4 to 1.5).

Figure 8 shows the error of each BC method for two temporal aggregations, 1 and 30 days, for the 1 yr level. In general, the performance of the BC methods for the winter period improves for large temporal aggregation (except for XDS in TR). However, in summer this is not the case. For this season, the difference between the results for 1 and 30 day aggregations depends on the catchment and the method. In NO₂, the results for 1 day are better than for 30 days for BCQM and XDS, although the reverse is true for TR. In DE, the results for 1 day are better than for 30 days for all the methods except XDS.

As in Fig. 7, TR has the largest variability for 30 days followed by NO₂ for both seasons. The results for DE, appear to be the least dependent on the temporal aggregation. This may be the result of spatially averaging the observations from 43 stations to catchment precipitation. For such a large basin (6171 km², see Table 1), this may simultaneously lead to temporally-averaged precipitation values from the gauged nested sub-catchments. In all cases, the variability for 30 days is smaller than for 1 day, indicating that the RCMs lead to more similar results for large temporal aggregations.

5 Summary and conclusions

This study analyses the expected changes in extreme precipitation in eleven European catchments. It focuses on the variability in the changes arising from the use of different statistical downscaling methods as well as different RCM–GCM simulations. Fifteen

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RCMs driven by six GCMs are downscaled using eight statistical downscaling methods. The statistical downscaling methods rely on different assumptions and different RCM outputs. The outputs from all the statistical downscaling methods are analysed using an extreme precipitation index.

5 Extreme precipitation is expected to increase in most catchments in both winter and summer. A decrease in extreme precipitation is only expected for both winter and summer in Cyprus and for summer in Turkey. In most catchments, larger changes are expected in winter than in summer. Additionally, in all cases, higher increases and higher variability in the results are obtained for higher return levels.

10 In most catchments and for both winter and summer, the RCM–GCM projections are the main source of variability in the results when compared to the differences between SDMs, although variability due to the SDMs explains at least 30 % of the total variance in all cases. Additionally, in all cases, the RCMs represent a larger percentage of the total variability than the GCMs, especially in summer. For this season, the total variance tends to be higher for the most southern catchments.

15 In general, the eight statistical downscaling methods agree on the direction of the change but not the magnitude of the change. It is not possible to draw general conclusions regarding differences between the downscaling methods, as the differences depend on the physical geographical characteristics of the catchment and season analysed. For example, for one of the Norwegian catchments the bias correction methods lead to lower changes than the change factor methods, but this is not the case for the other catchments. The main common aspect to all catchments except NO2 and CY is that the change factor of mean method leads to the smallest value of the extreme precipitation index for summer. This indicates that this method
20 is not suitable for regions where the expected changes in extreme precipitation are different to the changes in mean precipitation. The changes obtained for different temporal aggregations also depend on the physical geographical characteristics of the catchment and season analysed, i.e. there is no general tendency for an increase or decrease in the index with increasing temporal aggregation.

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Overall, the bias correction methods improve the representation of extreme precipitation, as compared with the uncorrected RCM outputs. However, the bias corrected time series tend to underestimate extreme precipitation. The magnitude of the errors depends on the catchment and season analysed. For example, the results of the bias correction of mean are worse than the other methods for the Norwegian catchment but not for the other catchments. There is not a tendency in the performance of the bias correction methods depending on the mean and extreme precipitation regime. There is also no clear indication for an increase or decrease in the error with increasing temporal aggregation.

This study illustrates that there is a large variability in the changes estimated from different statistical downscaling methods and RCMs. It also shows that the differences between the methods and the performance of the bias correction methods depends on the catchment studied. Hence, for a specific case study, the selection of a statistical downscaling method might depend on the physical geographical characteristics of the catchment. However, we recommend the use of a set of statistical downscaling methods as well as an ensemble of climate model projections. The selection of statistical downscaling methods should include methods able to represent changes in the precipitation property studied as well as methods based on different underlying assumptions.

Appendix A: Verification of matrix reconstruction approach

A1 Comparison of results using 2 and 3 sources of variance

This verification approach assesses the influence of the matrix reconstruction procedure on the percentage of the total variance explained by climate models (influence of GCM–RCM simulations) and SDMs. For this purpose, the variance decomposition approach has been applied considering two sources of uncertainty:

SDMs and climate models (the 15 RCM–GCM simulations). In the case of two sources of variance, there is no need to reconstruct the matrix.

Table A1 shows the percentage explained by the climate models and SDMs estimated considering two and three sources of variance. The percentages for CY are not shown for summer because EPI could not be calculated for a large number of cases, and the percentages for winter do not include the results from BCM and BCMV. The percentage explained by the GCM–RCM simulations and the SDMs is similar when considering two or three sources of variances. Additionally, the conclusion on which is the most important source of variance is the same for all catchments except for DE and PL in winter. For these two catchments, the percentage explained by the GCM–RCM simulations is approximately 50 %.

A2 Comparison of reconstructed and original values

A similar verification approach as the one carried out in Déqué et al. (2007) has also been used. It consists in removing the data for one combination of RCM–GCM and using the matrix reconstruction approach to estimate its values for all SDMs. The reconstructed values are then compared with the original values and also with two other combinations of RCM–GCMs (one using the same RCM and one using the same GCM). This test is applied to two RCM–GCM simulations: RCA-ECHAM5 and HIRHAM-BCM.

The reconstructed vector for these combinations is referred to as EPI_{RG} . In the case of RCA-ECHAM5, EPI_{RG} is compared with the vectors found for: (i) the original EPI values found for RCA-ECHAM5; (ii) the combination RCA-BCM (EPI_R in Table A2); (iii) and the combination REMO-ECHAM5 (EPI_G in Table A2). In the case of HIRHAM-ARPEGE, EPI_{RG} is compared with the original values, with HIRHAM-ARPEGE (EPI_R), and RCA-BCM (EPI_G). Table A2 shows the average of the RMSE obtained for all the catchments, T-yr levels, seasons, and temporal aggregations.

Table A2 shows that in the case of RCA-ECHAM5, the difference between the reconstructed and the original values is smaller than the difference between the

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reconstructed values and the other two RCM–GCM combinations. However, in the case of HIRHAM-BCM, the difference between the reconstructed and the original values is higher than the difference between the reconstructed and the other two RCM–GCM combinations.

This results show that in some cases the reconstructed values can differ more from the original values than they differ from other models. Hence, the variances estimated in the variance decomposition approach are likely to be affected by the reconstructed values.

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Table 2. Matrix of RCM–GCM combinations considered in this study and source of the RCMs.

RCM–GCM	ECHAM5	BCM	HadCM3-Q3	HadCM3-Q16	HadCM3-Q0	ARPEGE	Institute
RM5.1						×	National Centre for Meteorological Research in France
RACMO2	×						Royal Netherlands Meteorological Institute
RCA	×	×	×				Swedish Meteorological and Hydrological Institute
REMO	×						Max Planck Institute for Meteorology
RCA3				×			Community Climate Change Consortium for Ireland
CLM						×	Swiss Federal Institute of Technology
HadRM3Q0					×		UK Met Office
HadRM3Q3			×				UK Met Office
HadRM3Q16				×			UK Met Office
HIRHAM5	×	×				×	Danish Meteorological Institute
RegCM3	×						International Centre for Theoretical Physics

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Table 3. Summary of the advantages and disadvantages of each statistical downscaling method. The name of the institution that undertook the downscaling work is included in the first column.

SD method	Advantages	Disadvantages
Bias correction of mean (T. G. Masaryk Water Research Institute, Faculty of Environmental Sciences)	Easy to apply and little computer time required. Preserves the sequences of dry/wet days from the RCMs. It accounts for different corrections in different time windows.	It only corrects the mean precipitation of the RCMs.
Bias correction of mean and variance (T. G. Masaryk Water Research Institute, Faculty of Environmental Sciences)	(same as bias correction of mean) It allows for distinct corrections between mean and variance.	The non-linear transformation may lead to unexpectedly large precipitation amounts. The autocorrelation from the RCMs is not corrected, but it is affected by the bias correction approach.
Bias correction quantile mapping (NVE)	Easy to apply and little computer time required. Preserves the sequences of dry/wet days from the RCMs. Distinction between corrections in mean and extreme precipitation. The frequency of precipitation is corrected. No theoretical distribution is assumed.	The correction of the upper tail is based on relatively few values (empirical distribution based). The same correction is applied for all the seasons. The autocorrelation from the RCMs is not corrected, but it is affected by the bias correction approach.
Expanded downscaling (U. Potsdam)	Generates realistic weather consistent with large-scale atmospheric patterns. Able to employ full range of predictor variables. It preserves co-variability between the predictands.	High demand for climate model accuracy; systematic biases can cause large errors. Requires large computation time and data preparation. No fully objective way of selecting the predictors.
Change factor of mean (DHI, DTU)	Easy to apply and little computer time required. It accounts for different changes in different months.	It only accounts for changes in mean precipitation. Does not account for changes in the length of dry/wet spells.
Change factor of mean and variance (DHI, DTU)	(same as change factor of mean) Distinction between changes in mean and variance.	Does not account for changes in the length of dry/wet spells. The autocorrelation of precipitation may be disturbed. The non-linear transformation may lead to unexpectedly large precipitation amounts.
Change factor quantile mapping (DTU)	(same as change factor of mean) Distinction between changes in mean and extreme precipitation. No theoretical distribution is assumed.	Does not account for changes in the length of dry/wet spells. The changes in the tails are based on relatively few values. The autocorrelation of precipitation may be disturbed.
Change factor quantile perturbation (KU Leuven)	(same as change factor quantile mapping) Changes in the frequency of precipitation are accounted for.	The changes in the tails are based on relatively few values. The autocorrelation of precipitation may be disturbed, although this is checked.

Table A1. Percentage of the total variance explained by the GCM–RCM simulations ($G+R$) and SDMs (S) considering 2 and 3 sources of variance. The contribution of the GCMs and RCMs is shown in brackets.

	Nr. sources	Winter		Summer	
		$G+R$	S	$G+R$	S
NO2	2	68	32	51	49
	3	69 (29+40)	31	52 (14+38)	48
NO1	2	51	49	60	40
	3	51 (13+38)	49	61 (13+48)	39
DK	2	60	40	65	35
	3	62 (22+40)	38	67 (26+41)	33
LT	2	59	41	60	40
	3	57 (20+37)	43	57 (10+47)	43
BE	2	69	31	51	49
	3	71 (30+41)	29	52 (15+37)	48
DE	2	49	51	62	38
	3	51 (18+33)	49	61 (16+45)	39
CZ2	2	54	46	61	39
	3	55 (15+41)	45	57 (14+43)	43
CZ1	2	60	40	64	36
	3	58 (24+34)	42	59 (19+40)	41
PL	2	51	49	55	45
	3	48 (21+28)	52	50 (19+30)	50
TR	2	57	43	46	54
	3	55 (19+35)	45	42 (19+23)	58
CY	2	55	45		
	3	55 (21+34)	45		

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Table A2. Average RMSE from the comparison of the reconstructed and original values and the comparison with other combinations of GCM–RCM.

RCM–GCM	Original	EPI_R	EPI_G
RCA-ECHAM5	0.47	0.60	0.61
HIRHAM-BCM	2.49	1.46	2.45

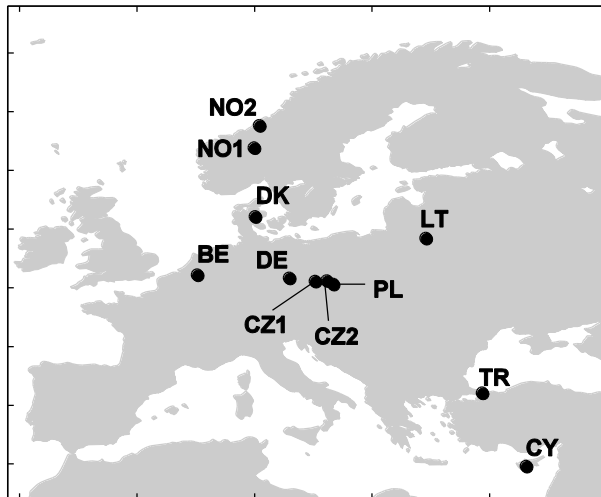


Figure 1. Location of the eleven catchments studied.

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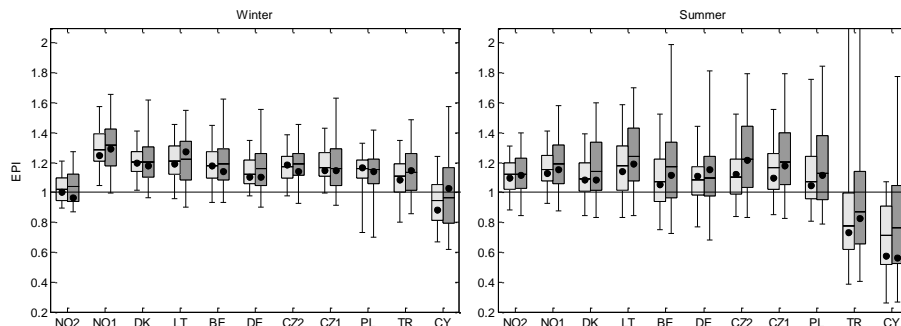


Figure 2. EPI estimated from the comparison of the downscaled time series for control and future period for 1 yr (light grey boxes) and 5 yr levels (dark grey boxes). The boxes indicate the 25th, 50th and 75th percentiles and the whiskers the 5th and 95th percentiles. The circles show the median of all the values of EPI estimated from the comparison of the RCM outputs for the control and future periods. All the results are for a temporal aggregation of 1 day.

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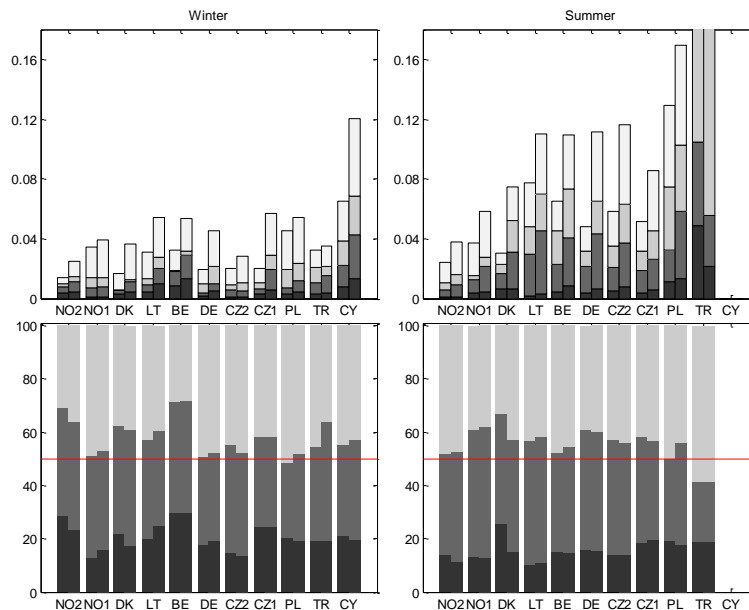


Figure 3. In the top row, total variance decomposed in variance from GCMs, RCMs, SDMs and all the interaction terms (darkest to lighter grey colours). In the bottom row, percentage of the total variance explained by GCMs, RCMs, and SDMs (darkest to lighter grey colours). All the results are shown for 1 and 5 yr levels in the left and right column of each catchment, respectively. All the results are for a temporal aggregation of 1 day.

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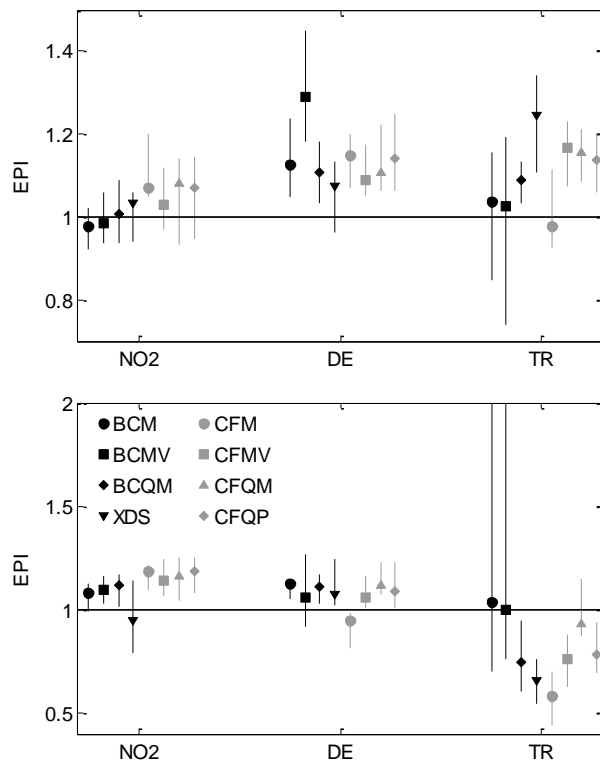


Figure 4. EPI for each SDM for NO₂, DE, and TR for winter (top) and summer (bottom). The markers indicate the median and the lines represent the range covered by the 25th and 75th percentiles. All results are for the 1 yr level and temporal aggregation of 1 day. Note the different scales used in the y axis for winter and for summer.

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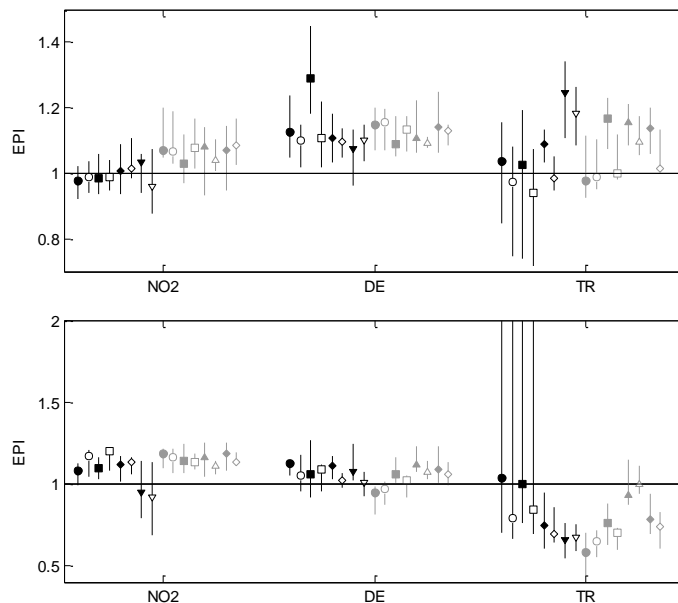


Figure 5. EPI for each SDM for NO₂, DE, and TR for winter (top) and summer (bottom). The markers indicate the median and the lines represent the range covered by the 25th and 75th percentiles. The results are shown for 1 day (filled markers) and 30 days (hollow markers) temporal aggregation. The same symbols are used for the different downscaling methods as in Fig. 4. Note the different scales used in the y axis for winter and for summer.

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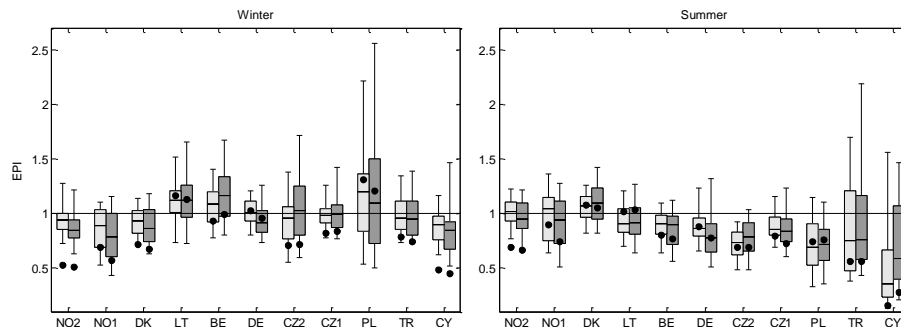


Figure 6. EPI estimated from the comparison of the observations and the downscaled time series by all BC methods for the control period for 1 yr (light grey boxes) and 5 yr levels (dark grey boxes). The boxes indicate the 25th, 50th and 75th percentiles and the whiskers the 5th and 95th percentiles. The circles show the median of all the values of EPI estimated from the comparison of the observations and the uncorrected RCM outputs for the control period. All the results are for a temporal aggregation of 1 day.

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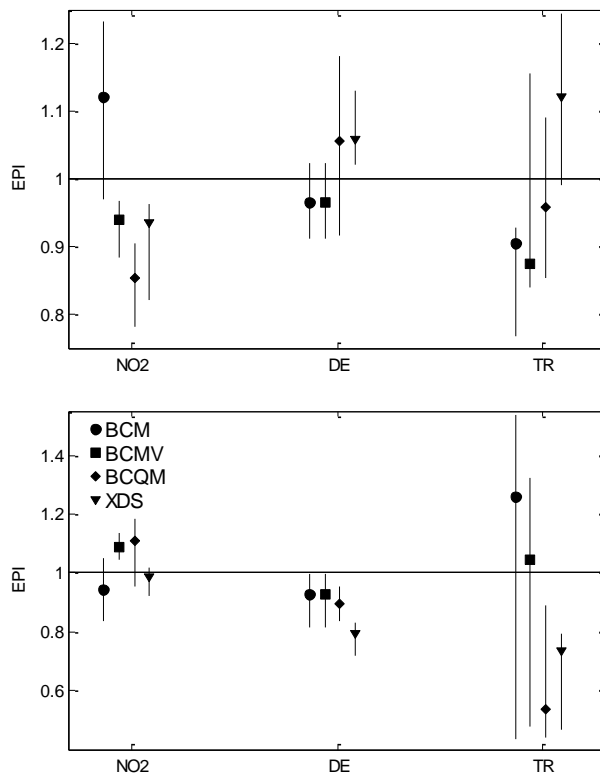


Figure 7. EPI for each BC method for NO₂, DE, and TR for winter (top) and summer (bottom). The markers indicate the median and the lines represent the range covered by the 25th and 75th percentiles. All the results are for the 1 yr level and temporal aggregation of 1 day. Note the different scales used in the y axis for winter and for summer.

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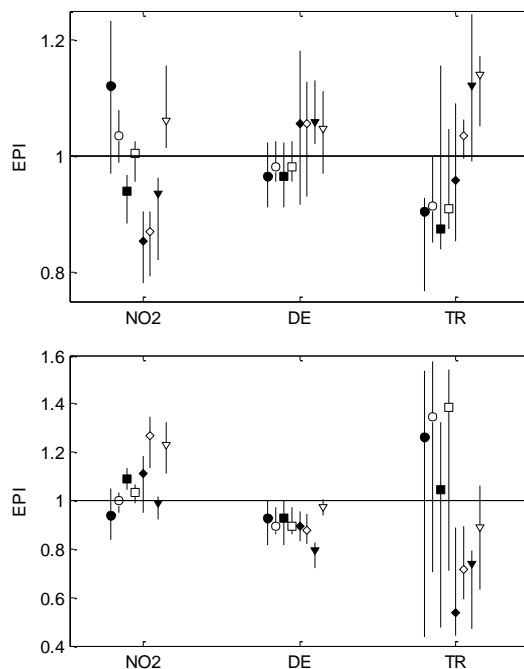


Figure 8. EPI for each BC method for NO₂, DE, and TR for winter (top) and summer (bottom). The markers indicate the median and the lines represent the range covered by the 25th and 75th percentiles. The results are shown for 1 day (filled markers) and 30 days (hollow markers) temporal aggregation. All the results are for 1 yr threshold. The same symbols are used for the different downscaling methods as in Fig. 7. Note the different scales used in the y axis for winter and for summer.

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