

1 **The skill of seasonal ensemble low flow forecasts in the Moselle River for three**
2 **different hydrological models**

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9 **Abstract**

10 This paper investigates the skill of 90 day low flow forecasts using two conceptual hydrological
11 models and one data-driven model based on Artificial Neural Networks (ANNs) for the Moselle
12 River. The three models, i.e. HBV, GR4J and ANN-Ensemble (ANN-E), all use forecasted
13 meteorological inputs (Precipitation P and potential evapotranspiration PET), whereby we
14 employ ensemble seasonal meteorological forecasts. We compared low flow forecasts for five
15 different cases of seasonal meteorological forcing: (1) ensemble P and PET forecasts; (2)
16 ensemble P forecasts and observed climate mean PET; (3) observed climate mean P and
17 ensemble PET forecasts; (4) observed climate mean P and PET and (5) zero P and ensemble PET
18 forecasts as input for the models. The ensemble P and PET forecasts, each consisting of 40
19 members, reveal the forecast ranges due to the model inputs. The five cases are compared for a
20 lead time of 90 days based on model output ranges, whereas the models are compared based on
21 their skill of low flow forecasts for varying lead times up to 90 days. Before forecasting, the
22 hydrological models are calibrated and validated for a period of 30 and 20 years respectively. The
23 smallest difference between calibration and validation performance is found for HBV, whereas

24 the largest difference is found for ANN-E. From the results, it appears that all models are prone
25 to over-predict runoff during low flow periods using ensemble seasonal meteorological forcing.
26 The largest range for 90 day low flow forecasts is found for the GR4J model when using
27 ensemble seasonal meteorological forecasts as input. GR4J, HBV and ANN-E under-predicted 90
28 day ahead low flows in the very dry year 2003 without precipitation data. The results of the
29 comparison of forecast skills with varying lead times show that GR4J is less skilful than ANN-E
30 and HBV. Overall, the uncertainty from ensemble P forecasts has a larger effect on seasonal low
31 flow forecasts than the uncertainty from ensemble PET forecasts and initial model conditions.

32

33 **Key words:** Moselle River, GR4J, HBV, ANN, low flows, ensemble seasonal meteorological
34 forecasts

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38 1 INTRODUCTION

39 Rivers in Western Europe usually experience low flows in late summer and high flows in winter.
40 These two extreme discharge phenomena can lead to serious problems. For example, high flow
41 events are quick and can put human life at risk, whereas streamflow droughts (i.e. low flows)
42 develop slowly and can affect a large area. Consequently, the economic loss during low flow
43 periods can be much bigger than during floods (Pushpalatha et al., 2011;Shukla et al., 2012). In
44 the River Rhine, severe problems for freshwater supply, water quality, power production and
45 river navigation were experienced during the dry summers of 1976, 1985 and 2003. Therefore,
46 forecasting seasonal low flows (Towler et al., 2013;Coley and Waylen, 2006;Li et al., 2008) and
47 understanding low flow indicators (Vidal et al., 2010;Fundel et al., 2013;Demirel et al.,
48 2013a;Wang et al., 2011;Saadat et al., 2013;Nicolle et al., 2013) have both societal and scientific
49 value. The seasonal forecast of water flows is therefore listed as one of the priority topics in EU's
50 Horizon 2020 research program (EU, 2013). Further, there is an increasing interest to incorporate
51 seasonal flow forecasts in decision support systems for river navigation and power plant
52 operation during low flow periods. We are interested in forecasting low flows with a lead time of
53 90 days, and in presenting the effect of ensemble meteorological forecasts for three hydrological
54 models.

55 Generally, two approaches are used in seasonal hydrological forecasting. The first one is a
56 statistical approach, making use of data-driven models based on relationships between river
57 discharge and hydroclimatological indicators (Wang et al., 2011;Van Ogtrop et al., 2011;Förster
58 et al., 2014). The second one is a dynamic approach running a hydrological model with
59 forecasted climate input.

60 The first approach is often preferred in regions where significant correlations between river
61 discharge and climatic indicators exist, such as sea surface temperature anomalies (Chowdhury
62 and Sharma, 2009), AMO – Atlantic Multi-decadal Oscillation (Ganguli and Reddy,
63 2013;Giuntoli et al., 2013), PDO – Pacific Decadal Oscillation (Soukup et al., 2009) and warm
64 and cold phases of the ENSO – El Nino Southern Oscillation - index (Chiew et al., 2003;Kalra et
65 al., 2013;Tootle and Piechota, 2004). Kahya and Dracup (1993) identified the lagged response of
66 regional streamflow to the warm phase of ENSO in the south-eastern United States. In the Rhine
67 basin, no teleconnections have been found between climatic indices, e.g. NAO and ENSO, and
68 river discharges (Rutten et al., 2008;Bierkens and van Beek, 2009). However, Demirel et al.
69 (2013a) found significant correlations between hydrological low flow indicators and observed
70 low flows. They also identified appropriate lags and temporal resolutions of low flow indicators
71 (e.g. precipitation, potential evapotranspiration, groundwater storage, lake levels and snow
72 storage) to build data-driven models.

73 The second approach is the dynamic seasonal forecasting approach which has long been explored
74 (Wang et al., 2011;Van Dijk et al., 2013;Gobena and Gan, 2010;Fundel et al., 2013;Shukla et al.,
75 2013;Pokhrel et al., 2013) and has led to the development of the current ensemble streamflow
76 prediction system (ESP) used by different national climate services like the National Weather
77 Service in the United States. The seasonal hydrologic prediction systems are most popular in
78 regions with a high risk of extreme discharge situations like hydrological droughts (Robertson et
79 al., 2013;Madadgar and Moradkhani, 2013). Well-known examples are the NOAA Climate
80 Prediction Centre's seasonal drought forecasting system (available at
81 <http://www.cpc.ncep.noaa.gov>), the University of Washington's Surface Water Monitoring
82 system (Wood and Lettenmaier, 2006), Princeton University's drought forecast system (available
83 at <http://hydrology.princeton.edu/forecast>) and University of Utrecht's global monthly

84 hydrological forecast system (Yossef et al., 2012). These models provide indications about the
85 hydrologic conditions and their evolution across the modelled domain using available weather
86 ensemble inputs (Gobena and Gan, 2010;Yossef et al., 2012). Moreover, Dutra et al. (2014)
87 showed that global seasonal forecasts of meteorological drought onset are feasible and skilful
88 using the standardized precipitation index (SPI) and two data sets as initial conditions.

89 Many studies have investigated the seasonal predictability of low flows in different rivers such as
90 the Thames and different other rivers in the UK (Bell et al., 2013;Wedgbrow et al.,
91 2002;Wedgbrow et al., 2005), the Shihmen and Tsengwen Rivers in Taiwan (Kuo et al., 2010),
92 the River Jhelum in Pakistan (Archer and Fowler, 2008), more than 200 rivers in France (Sauquet
93 et al., 2008;Giuntoli et al., 2013), five semi-arid areas in South Western Queensland, Australia
94 (Van Ogtrop et al., 2011), five rivers including Limpopo basin and the Blue Nile in Africa (Dutra
95 et al., 2013;Winsemius et al., 2014), the Bogotá River in Colombia (Felipe and Nelson, 2009),
96 the Ohio in the eastern US (Wood et al., 2002;Luo et al., 2007;Li et al., 2009), the North Platte in
97 Colorado, US (Soukup et al., 2009), large rivers in the US (Schubert et al., 2007;Shukla and
98 Lettenmaier, 2011) and the Thur River in the north-eastern part of Switzerland (Fundel et al.,
99 2013). The common result of the above mentioned studies is that the skill of the seasonal
100 forecasts made with global and regional hydrological models is reasonable for lead times of 1-3
101 months (Shukla and Lettenmaier, 2011;Wood et al., 2002) and these forecasting systems are all
102 prone to large uncertainties as their forecast skills mainly depend on the knowledge of initial
103 hydrologic conditions and weather information during the forecast period (Shukla et al.,
104 2012;Yossef et al., 2013;Li et al., 2009;Doblas-Reyes et al., 2009). In a recent study, Yossef et al.
105 (2013) used a global monthly hydrological model to analyse the relative contributions of initial
106 conditions and meteorological forcing to the skill of seasonal streamflow forecasts. They
107 included 78 stations in large basins in the world including the River Rhine for forecasts with lead

108 times up to 6 months. They found that improvements in seasonal hydrological forecasts in the
109 Rhine depend on better meteorological forecasts, which underlines the importance of
110 meteorological forcing quality particularly for forecasts beyond lead times of 1-2 months.

111 Most of the previous River Rhine studies use only one hydrological model, e.g. PREVAH
112 (Fundel et al., 2013) or PCR-GLOBWB (Yossef et al., 2013), to assess the value of ensemble
113 meteorological forcing, whereas in this study, we compare three hydrological models with
114 different structures varying from data-driven to conceptual models. The two objectives of this
115 study are to contrast data-driven and conceptual modelling approaches and to assess the effect of
116 ensemble seasonal forecasted precipitation and potential evapotranspiration on low flow forecast
117 quality and skill scores. By comparing three models with different model structures we address
118 the issue of model structure uncertainty, whereas the latter objective reflects the benefit of
119 ensemble seasonal forecasts. Moreover, the effect of initial model conditions is partly addressed
120 using climate mean data in one of the cases.

121 The analysis complements recent efforts to analyse the effects of ensemble weather forecasts on
122 low flow forecasts with a lead time of 10 days using two conceptual models (Demirel et al.,
123 2013b), by studying the effects of seasonal ensemble weather forecasts on 90 day low flow
124 forecasts using not only conceptual models but also data-driven models.

125 The outline of the paper is as follows. The study area and data are presented in section 2. Section
126 3 describes the model structures, their calibration and validation set-ups and the methods
127 employed to estimate the different attributes of the forecast quality. The results are presented in
128 section 4 and discussed in section 5, and the conclusions are summarised in section 6.

129

130 2 STUDY AREA AND DATA

131 2.1 Study area

132 The study area is the Moselle River basin, the largest sub-basin of the Rhine River basin. The
133 Moselle River has a length of 545 km. The river basin has a surface area of approximately 27,262
134 km². The altitude in the basin varies from 59 to 1326 m, with a mean altitude of 340 m (Demirel
135 et al., 2013a). There are 26 subbasins with surface areas varying from 102 to 3353 km².
136 Approximately 410 mm (~130 m³s⁻¹) discharge is annually generated in the Moselle basin
137 (Demirel et al., 2013b). The outlet discharge at Cochem varies from 14 m³s⁻¹ in dry summers to
138 a maximum of 4000 m³s⁻¹ during winter floods.

139 The Moselle River has been heavily regulated by dams, power plants, weirs and locks. There are
140 around 12 hydropower plants between Koblenz and Trier producing energy since the 1960s
141 (Bormann, 2010). Moreover, there are 12 locks only on the German part of the river (Bormann et
142 al., 2011).

143

144 2.2 Data

145 2.2.1 Observed data

146 Observed daily data on precipitation (P), potential evapotranspiration (PET) and the mean
147 altitudes (h) of the 26 sub-basins have been provided by the German Federal Institute of
148 Hydrology (BfG) in Koblenz, Germany (**Table 1**). PET is estimated using the Penman-Wendling
149 equation (ATV-DVWK, 2002) and both variables have been spatially averaged by BfG over 26
150 Moselle sub-basins using areal weights. Observed data from 12 meteorological stations in the
151 Moselle basin (as part of 49 stations over the Rhine basin), mainly provided by the CHR, the

152 DWD, Météo France, are used to estimate the basin averaged input data (Görgen et al., 2010).
153 Observed daily discharge (Q) data at Cochem (station #6336050) are provided by the Global
154 Runoff Data Centre (GRDC), Koblenz. The daily observed data (P, PET and Q) are available for
155 the period 1951-2006.

156

157 **Table 1** Overview of observed data used
158

Variable	Name	Number of stations/sub-basins	Period	Annual Range (mm)	Time step (days)	Spatial resolution	Source
Q	Discharge	1	1951-2006	163-550	1	Point	GRDC
P	Precipitation	26	1951-2006	570-1174	1	Basin average	BfG
PET	Potential evapotranspiration	26	1951-2006	512-685	1	Basin average	BfG
h	Mean altitude	26	-	-	-	Basin average	BfG

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162 2.2.2 Ensemble seasonal meteorological forecast data

163 The ensemble seasonal meteorological forecast data, comprising 40 members, are obtained from
 164 the European Centre for Medium-Range Weather Forecasts (ECMWF) seasonal forecasting
 165 archive and retrieval system, i.e. MARS system 3 (ECMWF, 2012). This dataset contains regular
 166 0.25 x 0.25 degree latitude-longitude grids and each ensemble member is computed for a lead
 167 time of 184 days using perturbed initial conditions and model physics (**Table 2**). We estimated
 168 the PET forecasts using the Penman-Wendling equation requiring forecasted surface solar
 169 radiation and temperature at 2 meter above the surface, and the altitude of the sub-basin (ATV-
 170 DVWK, 2002). The PET estimation is consistent with the observed PET estimation carried out
 171 by BfG (ATV-DVWK, 2002). The grid-based P and PET ensemble forecast data are firstly
 172 interpolated over 26 Moselle sub-basins using areal weights. These sub-basin averaged data are
 173 then aggregated to the Moselle basin level.

174
 175 **Table 2** Overview of ensemble seasonal meteorological forecast data
 176

Data	Spatial resolution	Ensemble size	Period	Time step (days)	Lead time (days)
Forecasted P	0.25 x 0.25 degree	39 + 1 control	2002-2005	1	1-90
Forecasted PET	0.25 x 0.25 degree	39 + 1 control	2002-2005	1	1-90

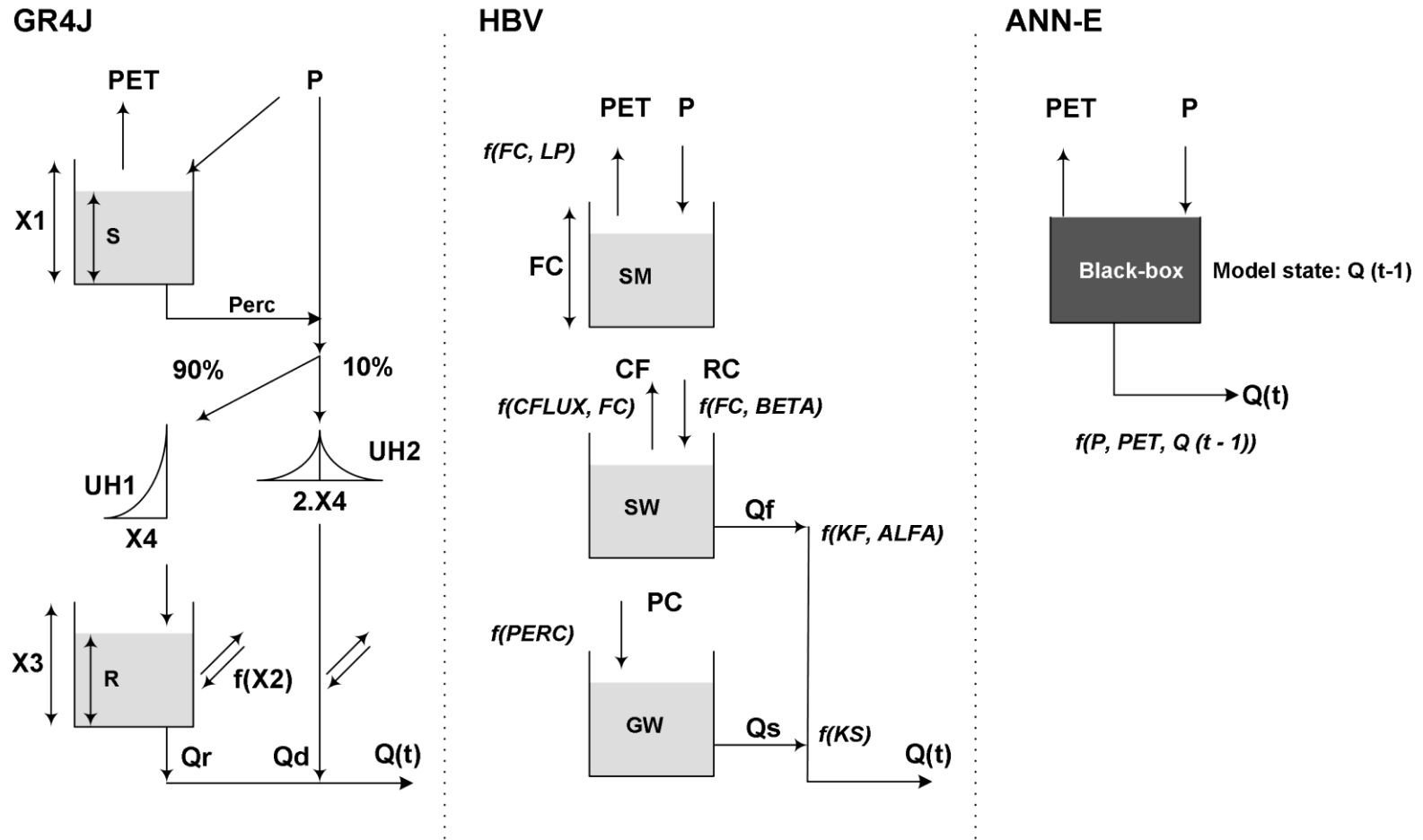
177
 178
 179

180 **3 METHODOLOGY**

181 **3.1 *Overview of model structures and forecast scheme***

182 The three hydrological models (GR4J, HBV and ANN-E) are briefly described in sections 3.1.1-
183 3.1.3. Figure 1 shows the simplified model structures. The calibration and validation of the
184 models is described in section 3.1.4. Five cases with different combinations of ensemble
185 meteorological forecast input and climate mean input are introduced in section 3.1.5. **We provide**
186 **a detailed description for each parameter of the three models in section 4.1.**

187



188

189 Figure 1 Schematisation of the three models. PET is potential evapotranspiration, P is precipitation and Q is discharge and t is the time
 190 (day).

191

192

193 3.1.1 GR4J

194 The GR4J model (Génie Rural à 4 paramètres Journalier) is used as it has a parsimonious
195 structure with **only four parameters**. The model has been tested over hundreds of basins
196 worldwide, with a broad range of climatic conditions from tropical to temperate and semi-arid
197 basins (Perrin et al., 2003). GR4J is a conceptual model and the required model inputs are daily
198 time series of P and PET (**Table 3**). All four parameters (Figure 1a) are used to calibrate the
199 model. The upper and lower limits of the parameters are selected based on previous works (Perrin
200 et al., 2003;Pushpalatha et al., 2011;Tian et al., 2014).

201 3.1.2 HBV

202 The HBV conceptual model (Hydrologiska Byråns Vattenbalansavdelning) was developed by the
203 Swedish Meteorological and Hydrological Institute (SMHI) in the early 1970's (Lindström et al.,
204 1997). The HBV model consists of four subroutines: a precipitation and snow accumulation and
205 melt routine, a soil moisture accounting routine and two runoff generation routines. The required
206 input data are daily P and PET. The snow routine and daily temperature data are not used in this
207 study as the Moselle basin is a rain-fed basin. Eight parameters (see Figure 1b) in the HBV model
208 are calibrated (Engeland et al., 2010;Van den Tillaart et al., 2013;Tian et al., 2014). **The eight**
209 **parameters are selected for calibration and the parameter ranges are selected based on previous**
210 **works (Booij, 2005;Eberle, 2005;Tian et al., 2014).**

211 3.1.3 ANN-E

212 An Artificial Neural Network (ANN) is a data-driven model inspired by functional units
 213 (neurons) of the human brain (Elshorbagy et al., 2010). A neural network is a universal
 214 approximator capable of learning the patterns and relation between outputs and inputs from
 215 historical data and applying it for extrapolation (Govindaraju and Rao, 2000). A three-layer feed-
 216 forward neural network (FNNs) is the most widely preferred model architecture for prediction
 217 and forecasting of hydrological variables (Adamowski et al., 2012; Shamseldin, 1997; Kalra et al.,
 218 2013). Each of these three layers has an important role in processing the information. The first
 219 layer receives the inputs and multiplies them with a weight (adds a bias if necessary) before
 220 delivering them to each of the hidden neurons in the next layer (Gaume and Gosset, 1999). The
 221 weights determine the strength of the connections. The number of nodes in this layer corresponds
 222 to the number of inputs. The second layer, the hidden layer, consists of an activation function
 223 (also known as transfer function) which non-linearly maps the input data to output target values.
 224 In other words, this layer is the learning element of the network which simulates the relationship
 225 between inputs and outputs of the model. The third layer, the output layer, gathers the processed
 226 data from the hidden layer and delivers the final output of the network.

227 A hidden neuron is the processing element with n inputs ($x_1, x_2, x_3, \dots, x_n$), and one output y using
 228 Eq (1).

$$y = f(x_1, x_2, x_3, \dots, x_n) = \text{logsig} \left[\left(\sum_{i=1}^n x_i w_i \right) + b \right] \quad (1)$$

229 where w_i are the weights, b is the bias, and *logsig* is the logarithmic sigmoid activation function.
 230 We tested the *tansig* and *logsig* activation functions and the latter was selected for this study as it
 231 gave better results for low flows. ANN model structures are determined based on the forecast

232 objective. In this study, we used a conceptual type ANN model structure: ANN-Ensemble (ANN-
 233 E) which requires daily P, PET and historical Q as input. Observed discharge on the forecast
 234 issue day is used to update the model states (**Table 3**). In other words, the ANN-E model receives
 235 $Q_{obs}(t)$ as input on the time step t when the forecast is issued, and then receives the streamflow
 236 forecast of the previous time step as input for lead times larger than 1 day. Further, forecasted Q
 237 for time step $t+j$ is used as input to forecast Q at $t+j+1$.
 238 This is a one day memory which also exists in the conceptual models, i.e. GR4J and HBV (Figure
 239 1). The ANN-E is assumed to be comparable with the conceptual models with similar model
 240 structures. The determination of the optimal number of hidden neurons in the second layer is an
 241 important issue in the development of ANN models. Three common approaches are ad hoc (also
 242 known as trial and error), global and stepwise (Kasiviswanathan et al., 2013). We used a global
 243 approach (i.e. Genetic Algorithm) to avoid local minima (De Vos and Rientjes, 2008) and tested
 244 the performance of the networks with one, two and three hidden neurons corresponding to a
 245 number of parameters (i.e. number of weights and biases) of 6, 11 and 16 respectively. Based on
 246 the parsimonious principle, testing ANNs only up to three hidden neurons is assumed to be
 247 enough as the number of parameters increases exponentially for every additional hidden neuron.
 248

249 **Table 3** Model descriptions. PET is potential evapotranspiration, P is precipitation and Q is
 250 discharge.
 251

Model Type		Input	Temporal resolution of input	Lag between forecast issue day and final day of temporal averaging (days)	Model time step	Model lead time (days)
Conceptual	Data-driven	P: Ensemble PET: Ensemble Q: State update	Daily P Daily PET	P: 0 PET: 0 Q: 1	Daily	1 to 90
GR4J						

HBV	P: Ensemble PET: Ensemble Q: State update	Daily P Daily PET	P: 0 PET: 0 Q: 1	Daily	1 to 90
ANN-E	P: Ensemble PET: Ensemble Q: State update	Daily P Daily PET Daily Q	P: 0 PET: 0 Q: 1	Daily	1 to 90

252

253 3.1.4 Calibration and validation of models

254 A global optimisation method, i.e. Genetic Algorithm (GA) (De Vos and Rientjes, 2008), and
 255 historical Moselle low flows for the period from 1971-2001 are used to calibrate the models used
 256 in this study. The 30-year calibration period is carefully selected as the first low flow forecast is
 257 issued on 01/01/2002. The first three years are used as warm-up period for the hydrological
 258 model. For all GA simulations, we use 100 as population size, 5 as reproduction elite count size,
 259 0.7 as cross over fraction, 2000 as maximum number of iterations and 5000 as the maximum
 260 number of function evaluations based on the studies by De Vos and Rientjes (2008) and
 261 Kasiviswanathan et al. (2013). The evolution starts from the population of 100 randomly
 262 generated individuals. The population in each iteration is called a generation and the fitness of
 263 every individual in the population is evaluated using the objective function. The best 70 percent
 264 of the population (indicated as cross over fraction) survives in the process of 2000 iterations.

265 The validation period spans from 1951-1970. The definition of low flows, i.e. discharges below
 266 the Q75 threshold of $\sim 113 \text{ m}^3\text{s}^{-1}$, is based on previous work by Demirel et al. (2013a). Prior
 267 parameter ranges and deterministic equations used for dynamic model state updates of the
 268 conceptual models based on observed discharges on the forecast issue day are based on the study
 269 by Demirel et al. (2013b). In this study, we use a hybrid Mean Absolute Error (MAE) based on

270 only low flows (MAE_{low}) and inverse discharge values ($MAE_{inverse}$) as objective function (see
 271 Eq.(4)).

$$\text{Mean Absolute Error}_{low} : \frac{1}{m} \sum_{j=1}^m |Q_{sim}(j) - Q_{obs}(j)| \quad (2)$$

272 where Q_{obs} and Q_{sim} are the observed and simulated values for the j -th observed low flow day
 273 (i.e. $Q_{obs} < Q_{75}$) and m is the total number of low flow days.

274

$$\text{Mean Absolute Error}_{inverse} : \frac{1}{n} \sum_{i=1}^n \left| \frac{1}{Q_{sim}(i) + \epsilon} - \frac{1}{Q_{obs}(i) + \epsilon} \right| \quad (3)$$

275 where n is the total number of days (i.e. $m < n$), and ϵ is 1% of the mean observed discharge to
 276 avoid infinity during zero discharge days (see Pushpalatha et al.,(2012)). The hybrid Mean
 277 Absolute Error is defined as

$$MAE_{hybrid} = MAE_{low} + MAE_{inverse} \quad (4)$$

278
 279 The MAE_{low} and $MAE_{inverse}$ were not normalised to calculate MAE_{hybrid} metric. It should be
 280 noted that we didn't fully neglect the high and intermediate flows using $MAE_{inverse}$, whereas
 281 only low flow periods are considered in MAE_{low} . This is one of the advantages of using the
 282 MAE_{hybrid} metric and also avoids redundancy.

283

284 3.1.5 Model storage update procedure for HBV and GR4J models

285 The storages in the two conceptual models are updated based on the observed discharge on the
 286 forecast issue day. In our previous study (Demirel et al., 2013c), we derived empirical relations
 287 between the simulated discharge and the fast runoff for each model to divide the observed
 288 discharge between the fast and slow runoff components (Eq. (5) and (6)).

$$k_{GR4J} = \frac{Qd}{Qr + Qd} \quad (5)$$

$$k_{HBV} = \frac{Qf}{Qf + Qs} \quad (6)$$

289 The Qf and Qs in the HBV model, and Qr and Qd in the GR4J model are estimated using the
 290 fractions above and the observed discharge value on the forecast issue day. The routing storage
 291 (R) in the GR4J model is updated for a given value of the $X3$ parameter using Eq.(7). Moreover,
 292 the surface water (SW) and groundwater (GW) storages in the HBV model are updated for given
 293 values of KF , $ALFA$ and KS parameters using Eq. (8) and (9).

$$Qr = R \left\{ 1 - \left[1 + \left(\frac{R}{X3} \right)^4 \right]^{-1/4} \right\} \quad (7)$$

$$SW = \left(\frac{Qf}{KF} \right)^{\left(\frac{1}{1+ALFA} \right)} \quad (8)$$

$$GW = \frac{Qs}{KS} \quad (9)$$

294 The remaining two storages S (in GR4J) and SM (in HBV) are updated using the calibrated model
 295 run until the forecast issue day (i.e. top-down approach).

296

297

298 **3.1.6 Case description**

299 In this study, three hydrological models are used for the seasonal forecasts. Five ensemble
 300 meteorological forecast input cases for ANN-E, GR4J and HBV models are compared: (1)
 301 ensemble P and PET forecasts (2) ensemble P forecasts and observed climate mean PET (3)
 302 observed climate mean P and ensemble PET forecasts (4) observed climate mean P and PET (5)
 303 zero P and ensemble PET forecasts (**Table 4**). P and PET forecasts are joint forecasts in our
 304 modelling practice. For example, if the first ensemble member is called from P then the first
 305 member from PET is also called to force the hydrological model.

306 Cases 1-4 are the different possible combinations of ensemble and climate mean meteorological
 307 forcing. Case 5 is analysed to determine to which extent the precipitation forecast in a very dry
 308 year (2003) is important for seasonal low flow forecasts. It should be noted that all available
 309 historical data (1951-2006) were used to estimate the climate mean. For example the climate
 310 mean for January 1st is estimated by the average of 55 January 1st values in the available period
 311 (1951-2006).

312 **Table 4** Details of the five input cases

313

Case	Precipitation (P)	The number of ensemble members (P)	Potential evapotranspiration (PET)	The number of ensemble members (PET)
1	Ensemble forecast	40	Ensemble forecast	40
2	Ensemble forecast	40	Climate mean	1
3	Climate mean	1	Ensemble forecast	40
4	Climate mean	1	Climate mean	1
5	Zero	0	Ensemble forecast	40

314

315

316 3.2 Forecast Skill Scores

317 Three probabilistic forecast skill scores (Brier Skill Score, reliability diagram, hit and false alarm
 318 rates) and one deterministic forecast skill score (Mean Forecast Score) are used to analyse the
 319 results of low flow forecasts with lead times of 1-90 days. Forecasts for each day in the test
 320 period (2002-2005) are used to estimate these scores. The Mean Forecast Score focusing on low
 321 flows is introduced in this study, whereas the other three scores have been often used in
 322 meteorology (WMO, 2012) and flood hydrology (Velázquez et al., 2010; Renner et al.,
 323 2009; Thirel et al., 2008). For the three models, i.e. GR4J, HBV and ANN-E, the forecast
 324 probability for each forecast day is estimated as the ratio of the number of ensemble members
 325 non-exceeding the preselected thresholds (here Q75) and the total number of ensemble members
 326 (i.e. 40 members) for that forecast day.

327 3.2.1 Brier Skill Score (BSS)

328 The Brier Skill Score (BSS) (Wilks, 1995) is often used in hydrology to evaluate the quality of
 329 probabilistic forecasts (Devineni et al., 2008; Hartmann et al., 2002; Jaun and Ahrens,
 330 2009; Roulin, 2007; Towler et al., 2013).

$$\text{Brier Skill Score: } 1 - \frac{BS_{forecast}}{BS_{climatology}} \quad (10)$$

331 where the $BS_{forecast}$ is the Brier Score (BS) for the forecast, defined as:

$$\text{Brier Score: } \frac{1}{n} \sum_{t=1}^n (F_t - O_t)^2 \quad (11)$$

332 where F_t refers to the forecast probability, O_t refers to the observed probability ($O_t=1$ if the
 333 observed flow is below the low flow threshold, 0 otherwise), and n is the sample size.

334 $BS_{climatology}$ is the BS for the climatology, which is also calculated from Eq. (11) for every year

335 using climatological probabilities. BSS values range from minus infinity to 1 (perfect forecast).
336 Negative values indicate that the forecast is less accurate than the climatology and positive values
337 indicate more skill compared to the climatology.

338 **3.2.2 Reliability Diagram**

339 The reliability diagram is used to evaluate the performance of probabilistic forecasts of selected
340 events, i.e. low flows. A reliability diagram represents the observed relative frequency as a
341 function of forecasted probability and the 1:1 diagonal shows the perfect reliability line
342 (Velázquez et al., 2010;Olsson and Lindström, 2008). This comparison is important as reliability
343 is one of the three properties of a hydrological forecast (WMO, 2012). A reliability diagram
344 shows the portion of observed data inside preselected forecast intervals.

345 In this study, exceedence probabilities of 50%, 75%, 85%, 95%, and 99% are chosen as
346 thresholds to categorize the discharges from mean flows to extreme low flows. The forecasted
347 probabilities are then divided into bins of probability categories; here, five bins (categories) are
348 chosen 0-20%, 20%-40%, 40%-60%, 60%-80% and 80%-100%. The observed frequency for
349 each day is chosen to be 1 if the observed discharge is below the low flow threshold, or 0, if not.

350 **3.2.3 Hit and False Alarm Rates**

351 We used hit and false alarm rates to assess the effect of ensembles on low flow forecasts for
352 varying lead times. The hit and false alarm rates indicate respectively the proportion of events for
353 which a correct warning was issued, and the proportion of non events for which a false warning
354 was issued by the forecast model. These two simple rates can be easily calculated from
355 contingency tables (**Table 5**) using Eq. (12) and (13). These scores are often used for evaluating
356 flood forecasts (Martina et al., 2006), however, they can also be used to estimate the utility of low

357 flow forecasts as they indicate the models' ability to correctly forecast the occurrence or non-
 358 occurrence of preselected events (i.e. Q_{75} low flows). There are four cases in a contingency table
 359 as shown in **Table 5**.

360
 361 **Table 5** Contingency table for the assessment of low-flow events based on the Q_{75}
 362

	Observed	Not observed
Forecasted	<i>hit</i> : the event forecasted to occur and did occur	<i>false alarm</i> : event forecasted to occur, but did not occur
Not forecasted	<i>miss</i> : the event forecasted not to occur, but did occur	<i>correct negative</i> : event forecasted not to occur and did not occur

363
 364

$$hit\ rate = \frac{hits}{(hits + misses)} \quad (12)$$

$$false\ alarm\ rate = \frac{false\ alarms}{(correct\ negatives + false\ alarms)} \quad (13)$$

365 3.2.4 Mean Forecast Score (MFS)

366 The Mean Forecast Score (MFS) is a new skill score which can be derived from either
 367 probabilistic or deterministic forecasts. The probabilities are calculated for the days when low
 368 flow occurred. In this study we used a deterministic approach for calculating the observed
 369 frequency for all three models. For all three models, ensembles are used for estimating forecast
 370 probabilities. The score is calculated as below only for deterministic observed low flows.

371
 372

$$\text{Mean Forecast Score} : \frac{1}{m} \sum_{j=1}^m F_j \quad (14)$$

373 where F_j is the forecast probability for the j -th observed low flow day (i.e. $O_j \leq Q_{75}$) and m is the
374 total number of low flow days. The probability of a deterministic forecast can be 0 or 1, whereas
375 it varies from 0 to 1 for ensemble members. For instance, if 23 of the 40 ensemble forecast
376 members indicate low flows for the j -th low flow day then $F_j = 23/40$. It should be noted that this
377 score is not limited to low flows as it has a flexible forecast probability definition which can be
378 adapted to any type of discharges. MFS values range from zero to 1 (perfect forecast).

379

380 **4 RESULTS**381 **4.1 Calibration and validation**

382 **Table 6** shows the parameter ranges and the best performing parameter sets of the three models.
 383 The GR4J and HBV models have both well-defined model structures; therefore, their calibration
 384 was more straightforward than the calibration of the ANN models. Calibration of the ANN-E
 385 model was done in two steps. First, the number of hidden neurons was determined by testing the
 386 performance of the ANN-E model with one, two and three hidden neurons.

387

388 **Table 6** Parameter ranges and calibrated values of the pre-selected three models

Parameter	Unit	Range	Calibrated value	Description
GR4J model				
X1	[mm]	10-2000	461.4	Capacity of the production store
X2	[mm]	-8 to +6	-0.3	Groundwater exchange coefficient
X3	[mm]	10-500	80.8	One day ahead capacity of the routing store
X4	[d]	0-4	2.2	Time base of the unit hydrograph
HBV model				
FC	[mm]	200-800	285.1	Maximum soil moisture capacity
LP	[-]	0.1-1	0.7	Soil moisture threshold for reduction of evapotranspiration
BETA	[-]	1-6	2.2	Shape coefficient
CFLUX	[mm/d]	0.1-1	1.0	Maximum capillary flow from upper response box to soil moisture zone
ALFA	[-]	0.1-3	0.4	Measure for non-linearity of low flow in quick runoff reservoir
KF	[d ⁻¹]	0.005-0.5	0.01	Recession coefficient for quick flow reservoir
KS	[d ⁻¹]	0.0005-0.5	0.01	Recession coefficient for base flow reservoir
PERC	[mm/d]	0.3-7	0.6	Maximum flow from upper to lower response box
ANN-E model				
W1	[-]	-10 to +10	-2.3	Weight of connection between 1 st input node (P) and hidden neuron
W2	[-]	-10 to +10	0.03	Weight of connection between 2 nd input node (PET) and hidden neuron
W3	[-]	-10 to +10	-0.02	Weight of connection between 3 rd input node ($Q(t-1)$) and hidden neuron
W4	[-]	-10 to +10	3.7	Weight of connection between hidden neuron and output node
B1	[-]	-10 to +10	0.02	Bias value in hidden layer

B2	[-]	-10 to +10	1.1	Bias value in output layer
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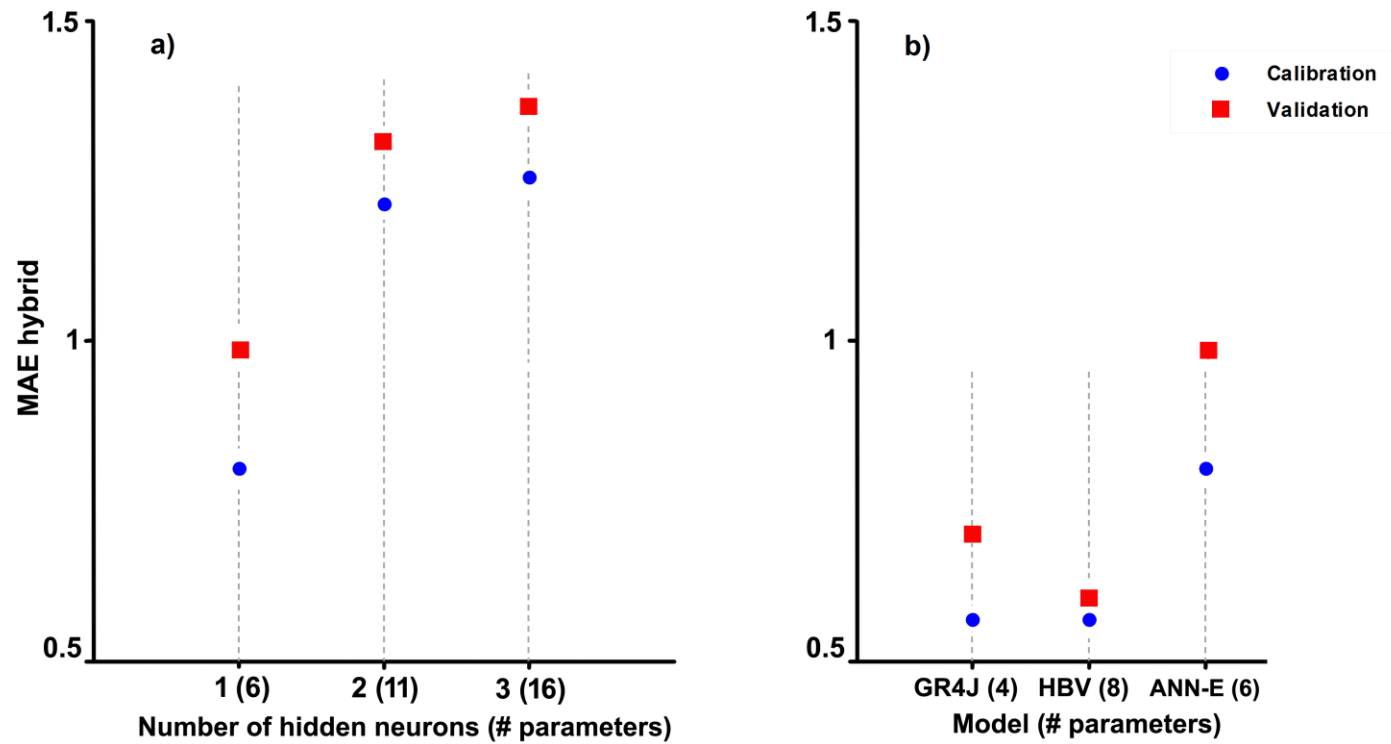
389
390 Second, daily P, PET and Q are used as three inputs for the tested ANN-E model with one, two
391 and three hidden neurons due to the fact that these inputs are comparable with the inputs of the
392 GR4J and HBV models. Figure 2a shows that the performance of the ANN-E model does not
393 improve with additional hidden neurons. Based on the performance in the validation period, one
394 hidden neuron is selected. GR4J and HBV are also calibrated. The results of the three models
395 used in this study are presented in Figure 2b.

396 The performances of GR4J and HBV are similar in the calibration period, whereas HBV
397 performs better in the validation period (Figure 2b). This is not surprising, since HBV has a more
398 sophisticated model structure than GR4J.

399
400 It should be noted that the effect of anthropogenic activities (e.g. flood preventive regulations and
401 urbanisation) on the alteration of flow magnitude and dynamics is not obvious as we found weak
402 positive trends in all P, PET and Q series ($p < 0.025$ for the three variables using Man Kendall
403 method) which might be caused by climatic changes. However, the effect of uncertainties due to
404 the anthropogenic activities on the three low flow models is minimal as the models are
405 successfully calibrated for the study area. Other studies reported that the trends in flood stages in
406 Moselle River were not significant (Bormann et al., 2011).

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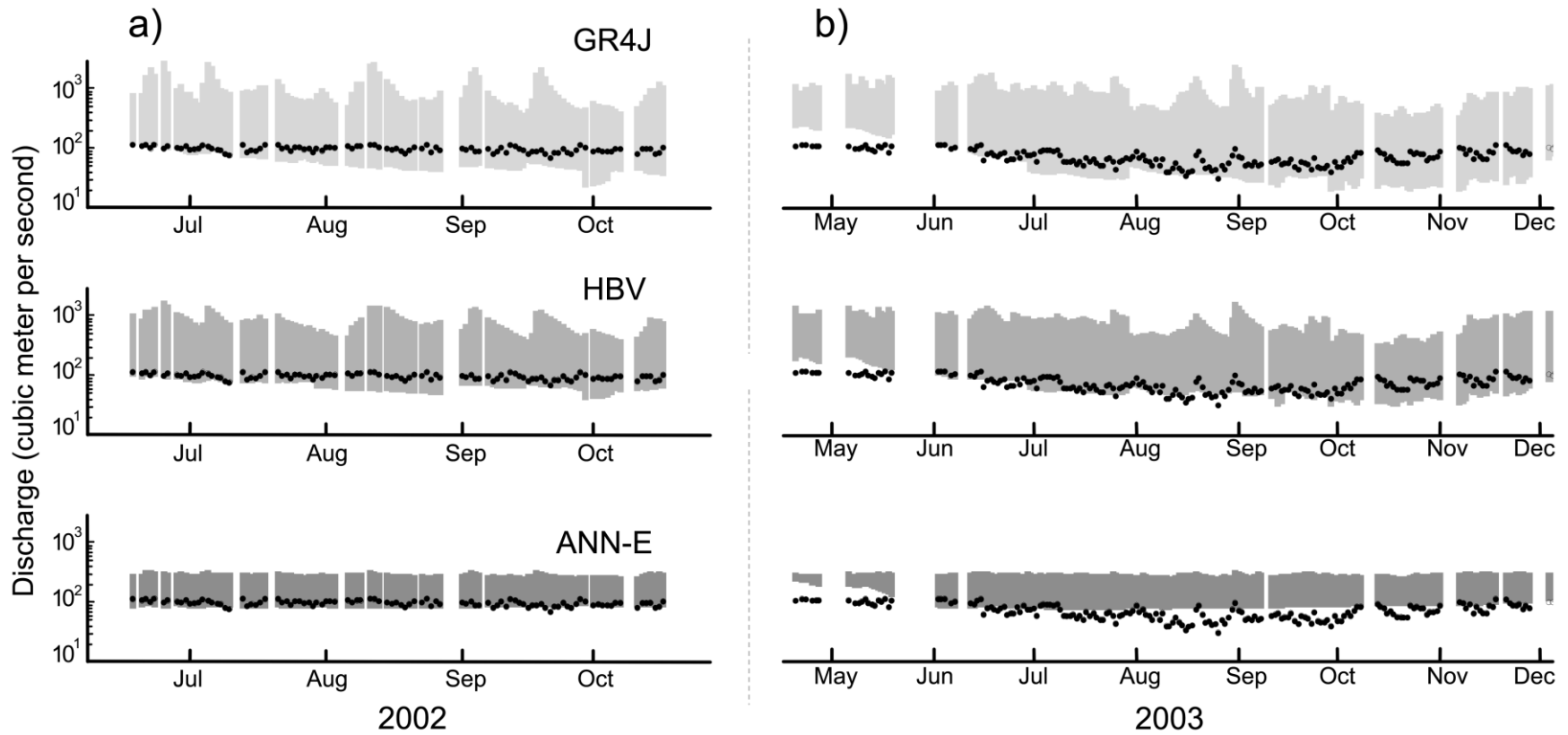
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Figure 2 Calibration and validation results of **a)** the ANN-E model with one, two and three hidden neurons and **b)** the three models used in this study. The same calibration (1971-2001) and validation (1951-1970) periods are used for both plots.

416 **4.2 *Effect of ensembles on low flow forecasts for 90 day lead time***

417 The effect of ensemble P and PET on GR4J, HBV and ANN-E is presented as a range bounded
418 by the lowest and highest forecast values in Figure 3a and b. The two years, i.e. 2002 and 2003,
419 are carefully selected as they represent a relatively wet year and a very dry year respectively.
420 Figure 3a shows that there are significant differences between the three model results. The 90 day
421 ahead low flows in 2002 are mostly over-predicted by the ANN-E model, whereas GR4J and
422 HBV over-predict low flows observed after August. The over-prediction of low flows is more
423 pronounced for GR4J than for the other three models. The over-prediction of low flows by ANN-
424 E is mostly at the same level. This less sensitive behaviour of ANN-E to the forecasted ensemble
425 inputs shows the effect of the logarithmic sigmoid transfer function on the results. Due to the
426 nature of this algorithm, input is rescaled to a small interval [0, 1] and the gradient of the sigmoid
427 function at large values approximates zero (Wang et al., 2006). Further, ANN-E is also not
428 sensitive to the initial model conditions updated on every forecast issue day. The less pronounced
429 over-prediction of low flows by HBV compared to GR4J may indicate that the slow responding
430 groundwater storage in HBV is less sensitive to different forecasted ensemble P and PET inputs
431 (Demirel et al., 2013b).

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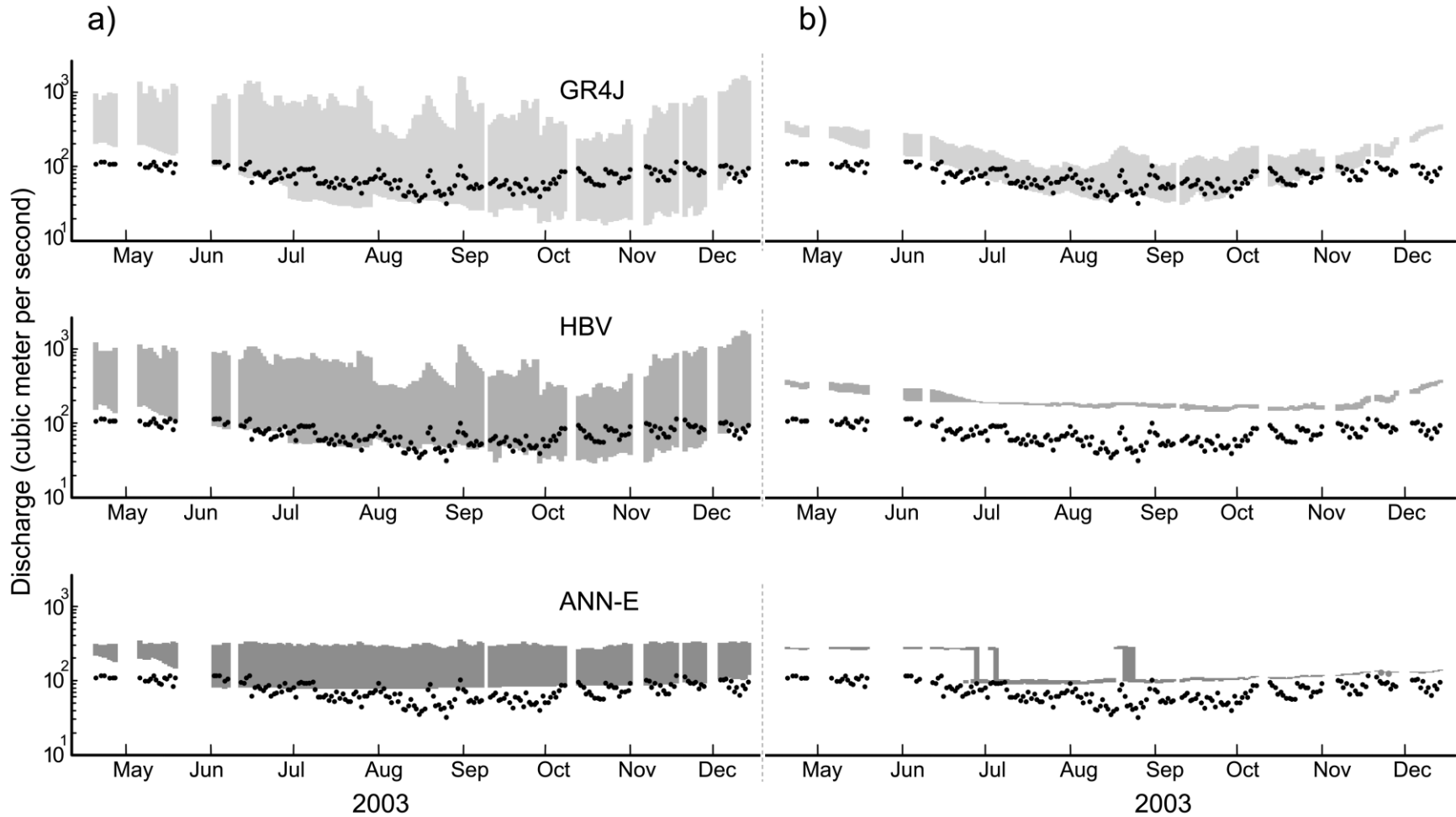
435 Figure 3 Range (shown as grey shade) of low flow forecasts in **a)** 2002 (the wettest year of the test period with 101 low flow days) **b)**
 436 2003 (the driest year of the test period with 192 low flow days) for a lead time of 90 days using ensemble P and PET as input for
 437 GR4J, HBV and ANN-E models (case 1 – 2002 and 2003). The gaps in the figures indicate non-low flow days (i.e. censored).

438
439 The results for 2003 are slightly different than those for 2002. As can be seen from Figure 3b the
440 number of low flow days has increased in the dry year, i.e. 2003, and the low flows between
441 August and November are not captured by any of the 40-ensemble forecasts using ANN-E. The
442 most striking result in Figure 3b is that the low flows observed in the period between April and
443 May are not captured by any of the three models, i.e. GR4J, HBV and ANN-E. The poor
444 performance of the models during the spring period can be explained by the high precipitation
445 amount in this period. The poor simulation of high flows in the preceding winter months can have
446 an effect on the forecasts too. The 90 day low flows between October and November are better
447 forecasted by GR4J and HBV than the ANN-E model. The two hydrological models used in this
448 study have well defined surface and ground water components. Therefore, they react to the
449 weather inputs in a physically meaningful way. However, in black box models, the step functions
450 (transfer functions or activation functions) may affect the model behaviour. The ANN model will
451 then react to a certain range of inputs based on the objective function. This feature of ANN is the
452 main reason for the erratic behaviour in Figure 4b and the small (and uniform) uncertainty range
453 in the figures (e.g. Figure 3).

454
455 For the purpose of determining to which extent ensemble P and PET inputs and different initial
456 conditions affect 90 day low flow forecasts, we run the models with different input combinations
457 such as ensemble P or PET and climate mean P or PET and zero precipitation. Figure 4a shows
458 the forecasts using ensemble P and climate mean PET as input for three models. The picture is
459 very similar to Figure 3b as most of the observed low flows fall within the constructed forecast
460 range by GR4J and HBV. The forecasts issued by GR4J are better than those issued by the other
461 two models. However, the range of forecasts using GR4J is larger than for the other models

462 showing the sensitivity of the model for different precipitation inputs. It is obvious that most of
463 the range in all forecasts is caused by uncertainties originating from ensemble precipitation input.

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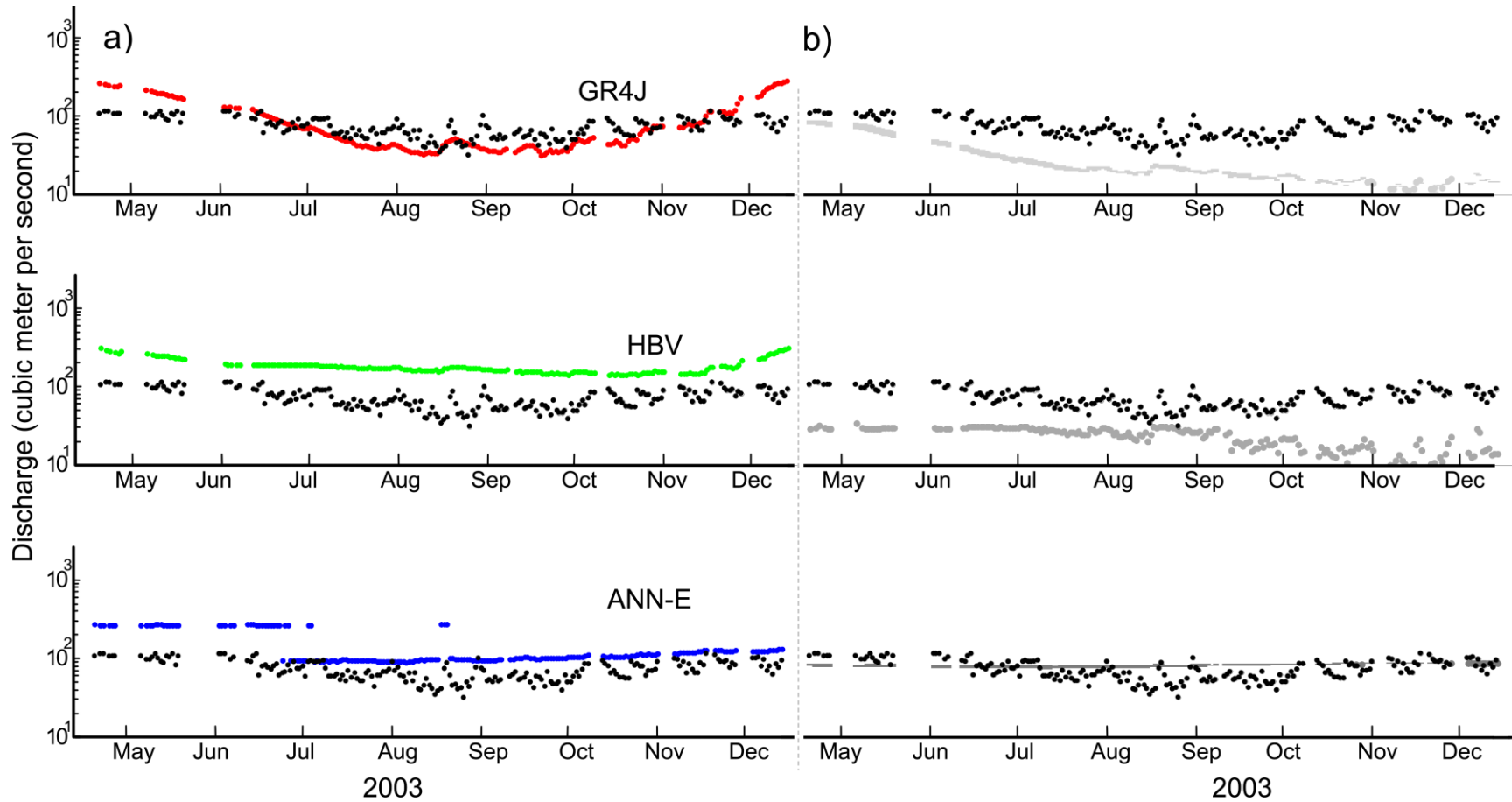
468

Figure 4 Range (shown as grey shade) of low flow forecasts in 2003 for a lead time of 90 days using **a)** ensemble P and climate mean PET (case 2) **b)** climate mean P and ensemble PET as input for GR4J, HBV and ANN-E models (case 3). The gaps in the figures indicate non-low flow days (i.e. censored).

469
470 Figure 4b shows the forecasts using climate mean P and ensemble PET as input for three models,
471 i.e. GR4J, HBV and ANN-E. Interestingly, only GR4J could capture the 90 day low flows
472 between July and November using climate mean P and ensemble PET showing the ability of the
473 model to handle the excessive rainfall. None of the low flows were captured by HBV, whereas
474 very few low flow events were captured by ANN-E (Figure 4b). The precipitation information is
475 crucial for the conceptual models to forecast low flows for a lead time of 90 days. The narrow
476 uncertainty band indicates that the effect of the PET ensemble on the forecasts is less pronounced
477 as compared to the effect of the P ensemble.

478 Figure 5a shows the forecasts using climate mean P and PET as input for three models. The
479 results are presented by point values without a range since only one deterministic forecast is
480 issued. There are significant differences in the results of the three models. For instance, all 90 day
481 ahead low flows in 2003 are over-predicted by HBV, whereas the over-prediction of low flows is
482 less pronounced for ANN-E. It is remarkable that GR4J can forecast a very dry year accurately
483 using the climate mean. The low values of the calibrated maximum soil moisture capacity and
484 percolation parameters of HBV (*FC* and *PERC*) can be the main reason for over-prediction of all
485 low flows as the interactions of parameters with climate mean P input can result in higher model
486 outputs.

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Figure 5 Low flow forecasts in 2003 for a lead time of 90 days using **a)** both climate mean P and PET (case 4) and **b)** zero P and ensemble PET (case 5) as input for GR4J, HBV and ANN-E models. The gaps in the figures indicate non-low flow days (i.e. censored).

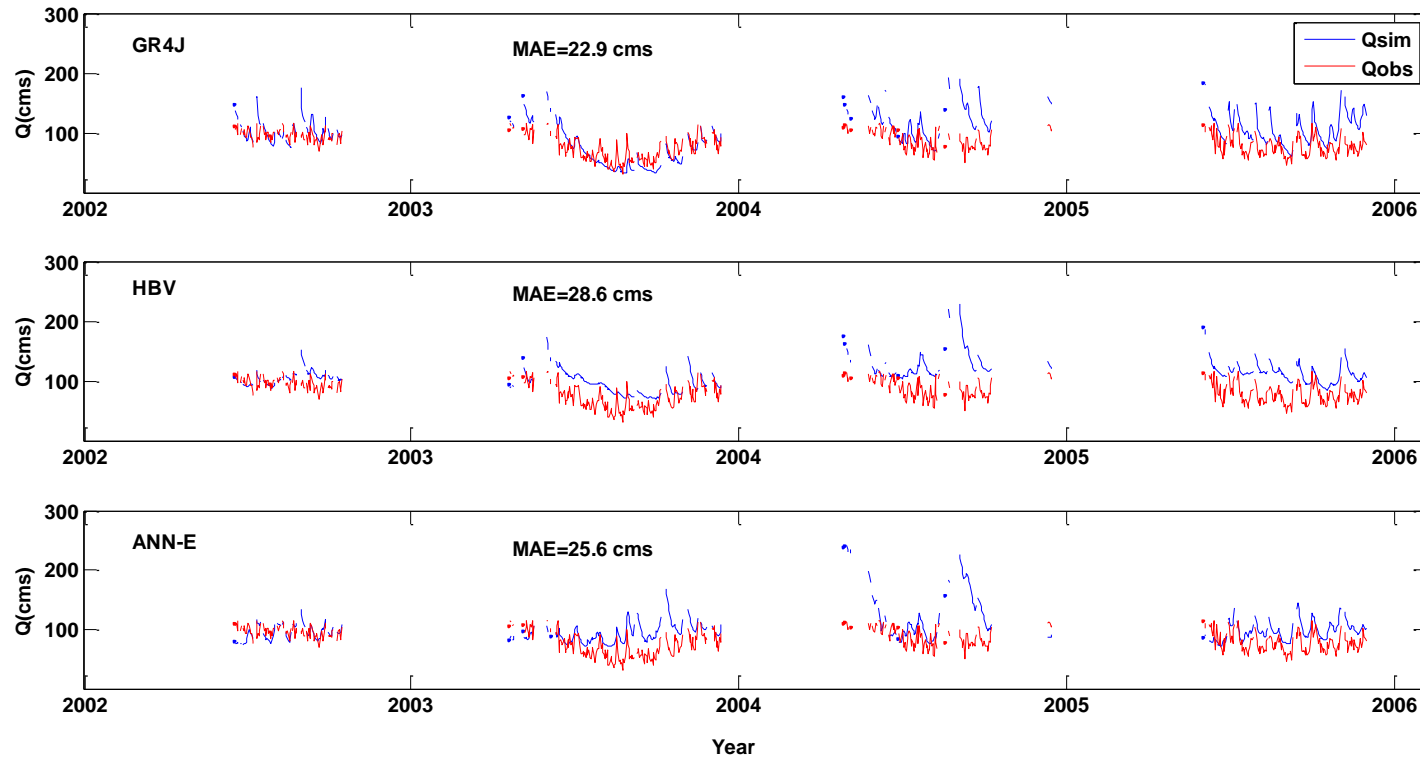
494
495 We also assessed the seasonal forecasts using zero P and ensemble PET as inputs for three
496 models (Figure 5b). Not surprisingly, both GR4J and HBV under-predicted most of the low flows
497 when they are run without precipitation input. The results of the case 5 confirm that the P input is
498 very crucial for improving low flow forecasts although obviously less precipitation is usually
499 observed in a low flow period compared to other periods.

500 Figure 6 shows the performance of the three models in the test period using perfect P and PET
501 forecasts as input. This is an idealistic case showing that GR4J model performs better than the
502 other two models. It is interesting to note that ANN-E model does not produce constant
503 predictions as in the previous figures showing the ability of this black box model to perform
504 comparable to the conceptual models when configured and trained properly.

505

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508

509 Figure 6 Benchmark reference forecasts using the three models (GR4J, HBV and ANN-E) using observed P and PET (i.e. perfect
510 forecasts)

511

512
 513 We also show the minimum and maximum prediction errors for each case in **Table 7**. There are
 514 large differences in case 1 and 2 as compared to the other cases. It is also obvious that the
 515 uncertainty range is larger in case 1 than in case 2 for the conceptual models. This is also what
 516 we see in Figure 3 and Figure 4 above.

517

518 **Table 7** Minimum and maximum prediction errors for low flow forecasts for a lead time of 90
 519 days during the test period 2002-2005

520

Model	Minimum , Median and Maximum MAE (m ³ /s)				
	Case 1	Case 2	Case 3	Case 4	Case 5
HBV	[23 101 785]	[23 72 600]	[108 119 135]	[105 105 105]	[57 57 57]
GR4J	[33 122 906]	[36 75 646]	[46 61 111]	[44 44 44]	[55 58 59]
ANN-E	[17 94 227]	[18 72 221]	[65 73 80]	[65 65 65]	[16 16 17]

521

522 *4.3 Effect of ensembles on low flow forecast skill scores*

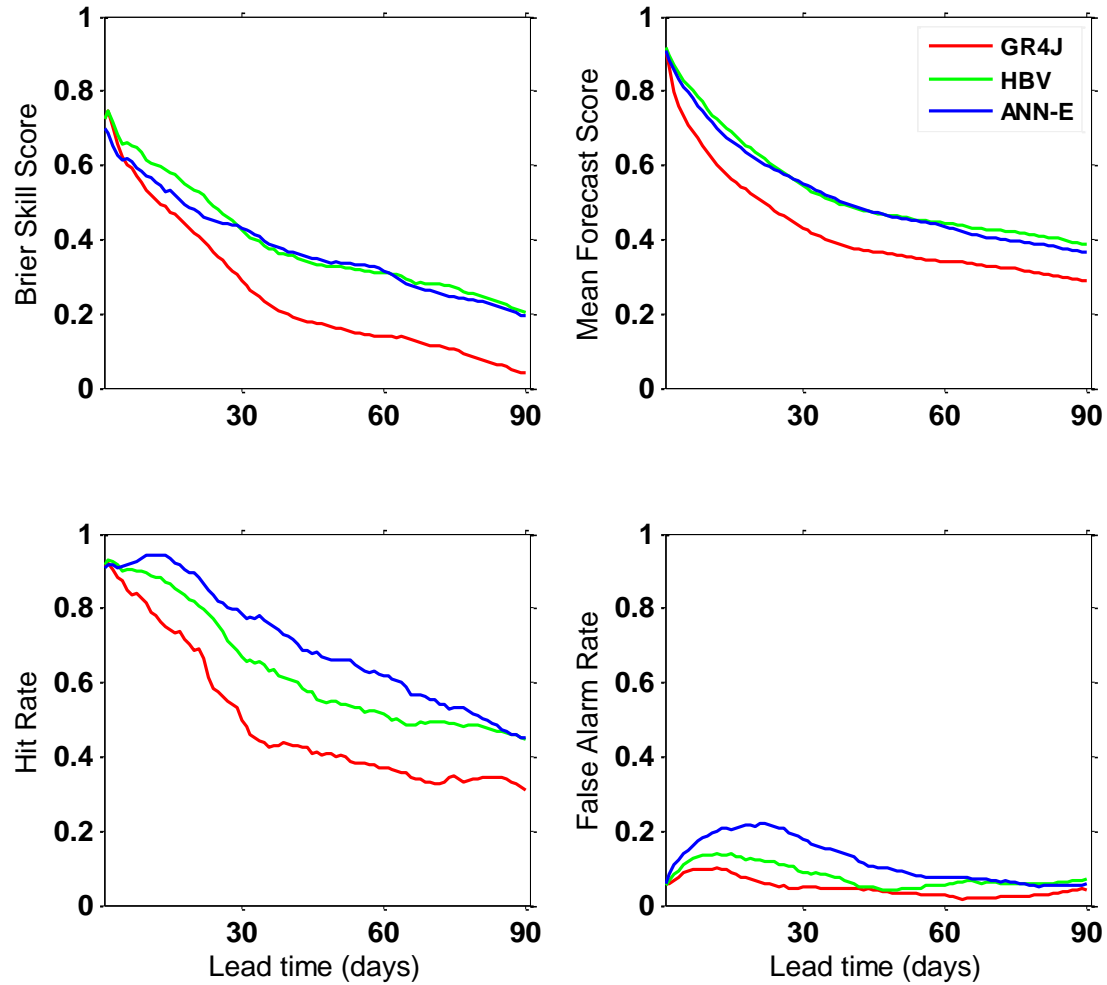
523 Figure 7 compares the three models and the effect of ensemble P and PET on the skill of
 524 probabilistic low flow forecasts with varying lead times. In this figure, four different skill scores
 525 are used to present the results of probabilistic low flow forecasts issued by GR4J, HBV and
 526 ANN-E. From an operational point of view, the main purpose of investigating the effect of
 527 ensembles and model initial conditions on ensemble low flow forecasts with varying lead times is
 528 to improve the forecast skills (e.g. hit rate, reliability, BSS and MFS) and to reduce false alarms
 529 and misses. From Figure 7 we can clearly see that the results of GR4J show the lowest BSS, MFS
 530 and hit rate. The false alarm rate of forecasts using GR4J is also the lowest compared to those
 531 using other models. The decrease in false alarm rates after a lead time of 20 days shows the
 532 importance of initial condition uncertainty for short lead time forecasts. The limit is around 20
 533 days for ANN-E and shorter for the other two models. When the forecast is issued on day (t), the
 534 model states are updated using the observed discharge on that day (t). For GR4J and HBV we

535 used the deterministic state update procedure described in section 3.1.5. However, the models
536 probably spin-up after some days and improve the results for false alarm rate are improved. For
537 longer lead times the error is better handled by the models. We further analysed the forecasted
538 meteorological forcing data (P and PET) to see if there is any difference between the short lead
539 time (~20 days) and long lead time (e.g. 90 days). This is done for three different lead times for
540 each model when the false alarm rate was highest (i.e. 12, 15 and 21 days based on the false
541 alarm rates of GR4J, HBV and ANN-E respectively.). We compared the boxplots from these
542 problematic lead times with the 90 day lead time (not shown here but available in the review
543 reports). It is interesting to note that the ranges for P and PET are larger at 90 day lead time as
544 compared to shorter lead times. However, the observed P and PET values (i.e. perfect forecasts)
545 are covered by the large ranges resulting in higher hit rates (i.e. lower false alarm rates). In other
546 words, for short lead times, 12, 15 and 21 days in particular, the ranges for P and PET are smaller
547 than those for the 90 day lead time but the observed P and PET values are usually missed causing
548 higher false alarm rates in the results.

549 It appears from the results that ANN-E and HBV show a comparable skill in forecasting low
550 flows up to a lead time of 90 days.

551

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555 Figure 7 Skill scores for forecasting low flows at different lead times for three different hydrological models for the test period 2002-
 556 2005. Note that all forecasts (including high and low flow time steps) are used to estimate these skill scores.

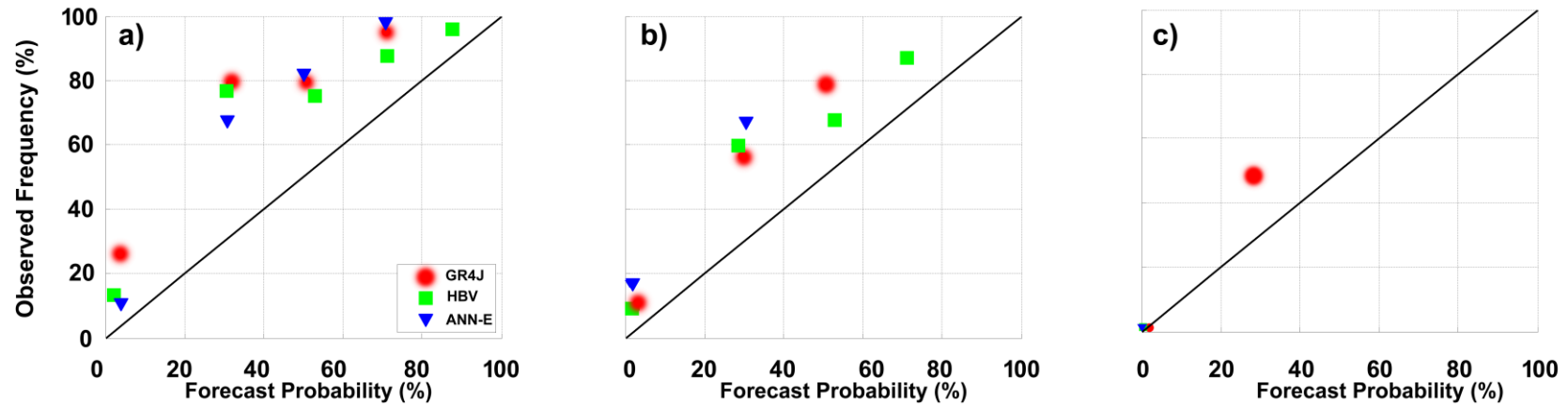
557
558 Figure 8 compares the reliability of probabilistic 90 day low flows forecasts below different
559 thresholds (i.e. Q75, Q90 and Q95) using ensemble P and PET as input for three models. The
560 figure shows that the Q75 and Q90 low flow forecasts issued by the HBV model are more
561 reliable compared to the other models. Moreover, all three models under-predict most of the
562 forecast intervals. It appears from Figure 8c that very critical low flows (i.e. Q99) are under-
563 predicted by the GR4J model.

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570 Figure 8 Reliability diagram for different low flow forecasts **a)** Low flows below Q75 threshold (584 observed events in the test period
 571 2002-2005) **b)** Low flows below Q90 threshold (250 observed events) **c)** Low flows below Q99 threshold (20 observed events). The
 572 forecasts are issued for a lead time of 90 days for the test period 2002-2005 using ensemble P and PET as input for GR4J, HBV and
 573 ANN-E models.

574

575

576 **5 DISCUSSION**

577 To compare data-driven and conceptual modelling approaches and to evaluate the effects of
578 seasonal meteorological forecasts on low flow forecasts, 40-member ensembles of ECMWF
579 seasonal meteorological forecasts were used as input for three low flow forecast models.

580 These models were calibrated using a hybrid low flow objective function. Although combining
581 two metrics offered a selective evaluation of low flows, we have noted an important caveat using
582 the second component of the hybrid metric as it is less sensitive as compared to the first part of
583 the hybrid metric resulting in higher (optimistic) values for most cases. The different units had no
584 effect on our calibration results as the ultimate calibration target value is zero (i.e. unit
585 independent). Other studies also combined different metrics with different units (Nash Sutcliffe,
586 RMSE, R^2 and NumSC, i.e. the number of sign changes in the errors) into one objective function
587 (Hamlet et al., 2013). However, the modellers should carefully use the hybrid function introduced
588 in this study, in particular when comparing different model results. Plotting the two parts of this
589 hybrid function as a Pareto front can lead to a more clear picture than simply summing the two
590 metrics.

591 In this study, different input combinations were compared to distinguish between the effects of
592 ensemble P and PET and model initial conditions on 90 day low flow forecasts. The models
593 could reasonably forecast low flows when ensemble P was introduced into the models. This result
594 is in line with that of Shukla and Lettenmaier (2011) who found that seasonal meteorological
595 forecasts have a greater influence than initial model conditions on the seasonal hydrological
596 forecast skills. Moreover, our analyses show that the better forecast performance for longer lead
597 times is an obvious artefact since the higher hit rates are the result of a more uncertain (larger
598 range) forecasts. The probabilistic skill scores focuses on the forecasts, the uncertainty in the

599 meteorological forcing data should be carefully scrutinized using different quantitative screening
600 methods e.g. box plots.

601 Two other related studies also showed that the effect of a large spread in ensemble seasonal
602 meteorological forecasts is larger than the effect of initial conditions on hydrological forecasts
603 with lead times longer than 1-2 months (Li et al., 2009;Yossef et al., 2013). The encouraging
604 results of low flow forecasts using ensemble seasonal precipitation forecasts for the hydrological
605 models confirm the utility of seasonal meteorological forcing for low flow forecasts. Shukla et al.
606 (2012) also found useful forecast skills for both runoff and soil moisture forecasting at seasonal
607 lead times using the medium range weather forecasts.

608 In this study, we also assessed the effects of ensemble P and PET on the skill scores of low flow
609 forecasts with varying lead times up to 90 days. In general, the four skill scores show similar
610 results. Not surprisingly, all models under-predicted low flows without precipitation information
611 (zero P). The most evident two patterns in these scores are that first, the forecast skill drops
612 sharply until a lead time of 30 days and second, the skill of probabilistic low flow forecasts
613 issued by GR4J is the lowest, whereas the skill of forecasts issued by ANN-E is the highest
614 compared to the other two models. Further, our study showed that data-driven models can be
615 good alternatives to conceptual models for issuing seasonal low flow forecasts (e.g. Figure 6).

616 The two hydrological models used in this study have well defined surface and ground water
617 components. Therefore, they react to the weather inputs in a physically meaningful way.
618 However, in black box models, the step functions (transfer functions or activation functions) may
619 limit model sensitivity after the training. The ANN model will then react to a certain range of
620 inputs based on the objective function. This feature of an ANN is the main reason for the small
621 (and uniform) uncertainty range in the figures. The over prediction of the models is closely
622 related to the over prediction of the P by the ensembles. Low flows are usually over predicted by

623 the models for the entire period. However, there are under-predictions of low flows for some days
624 in November-December as well. Before June, none of the low flows are captured by the ensemble
625 members. The best performing period is the fall and the worst performing period is the spring
626 period for the models. The poor performance of the models during the spring period can be
627 explained by the high precipitation amount in this period. Since the first part of the objective
628 function used in this study solely focuses on low flows, the high flow period is less important in
629 the calibration. The low flows occurring in the spring period are, therefore, missed in the
630 forecasts. The simulation of snow cover during winter and snow melt during the spring can both
631 have effects on the forecasts too.

632

633 **6 CONCLUSIONS**

634 Three hydrological models have been compared regarding their performance in the calibration,
635 validation and forecast periods, and the effect of seasonal meteorological forecasts on the skill of
636 low flow forecasts has been assessed for varying lead times. The comparison of three different
637 models help us to contrast data-driven and conceptual models in low flow forecasts, whereas
638 running the models with different input combinations, e.g. climate mean precipitation and
639 ensemble potential evapotranspiration, help us to identify which input source led to the largest
640 range in the forecasts. A new hybrid low flow objective function, comprising the mean absolute
641 error of low flows and the mean absolute error of inverse discharges, is used for comparing low
642 flow simulations, whereas the skill of the probabilistic seasonal low flow forecasts has been
643 evaluated based on the ensemble forecast range, Brier Skill Score, reliability, hit/false alarm rates
644 and Mean Forecast Score. The latter skill score (MFS) focusing on low flows is firstly introduced
645 in this study. In general our results showed that;

- 646 • Based on the results of the calibration and validation, one hidden neuron in ANN was
647 found to be enough for seasonal forecasts as additional hidden neurons did not increase
648 the simulation performance. The difference between calibration and validation
649 performances was smallest for the HBV model, i.e. the most sophisticated model used in
650 this study.
- 651 • Based on the results of the comparison of different model inputs for two years (i.e. 2002
652 and 2003), the largest range for 90 day low flow forecasts is found for the GR4J model
653 when using ensemble seasonal meteorological forecasts as input. Moreover, the
654 uncertainty arising from ensemble precipitation has a larger effect on seasonal low flow
655 forecasts than the effects of ensemble potential evapotranspiration. All models are prone

656 to over-predict low flows using ensemble seasonal meteorological forecasts. However, the
657 precipitation forecasts in the forecast period are crucial for improving the low flow
658 forecasts. As expected, all three models, i.e. GR4J, HBV and ANN-E under-predicted 90
659 day ahead low flows in 2003 without rainfall data.

660 • Based on the results of the comparison of forecast skills with varying lead times, the false
661 alarm rate of GR4J is the lowest indicating the ability of the model of forecasting non-
662 occurrence of low flow days. The low flow forecasts issued by HBV are more reliable
663 compared to the other models. The hit rate of ANN-E is higher than that of the two
664 conceptual models used in this study. Overall, the ANN-E and HBV models are the best
665 performing two of the three models using ensemble P and PET.

666

667 Further work should examine the effect of model parameters and initial conditions on the
668 seasonal low flow forecasts as the values of the maximum soil moisture and percolation related
669 parameters of conceptual models can result in over- or under-prediction of low flows. The
670 uncertainty increases in seasonal meteorological forecasts can lead to better skill scores as an
671 artefact of large ranges in input. Therefore, the quality of the model inputs should be assessed in
672 addition to the model outputs. The identified glitches in the second part of the hybrid objective
673 function can be eliminated by plotting the two parts on two axes rather than simply summing the
674 two metrics. It is noteworthy to mention that the data-driven model developed in this study, i.e.
675 ANN-E, can be applied to other large river basins elsewhere in the world. Surprisingly, ANN-E
676 and HBV showed a similar skill for seasonal forecasts, where a priori we expected that the two
677 conceptual models, GR4J and HBV, would show similar results up to a lead time of 90 days.

678

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695

696

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