

1 **Scoping a Field Experiment: Error Diagnostics of TRMM Precipitation Radar Estimates in**
2 **Complex Terrain as a basis for IPHEX2014**

3 **Yajuan Duan, Anna M. Wilson and Ana P. Barros**

4 Department of Civil and Environmental Engineering, Pratt School of Engineering, Duke
5 University, Durham, NC 27708, USA.

6 *Correspondence to:* A. P. Barros (barros@duke.edu)

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1 Abstract

2 A diagnostic analysis of the space-time structure of error in Quantitative Precipitation
3 Estimates (QPE) from the Precipitation Radar (PR) on the Tropical Rainfall Measurement
4 Mission (TRMM) satellite is presented here in preparation for the Integrated Precipitation and
5 Hydrology Experiment (IPHEX) in 2014. IPHEX is the first NASA ground-validation field
6 campaign after the launch of the Global Precipitation Measurement (GPM) satellite. In
7 anticipation of GPM, a science-grade high-density raingauge network was deployed at mid to
8 high elevations in the Southern Appalachian Mountains, USA since 2007. This network allows
9 for direct comparison between ground-based measurements from raingauges and satellite-based
10 QPE (specifically, PR 2A25 Version 7 using five years of data 2008-2013). Case studies were
11 conducted to characterize the vertical profiles of reflectivity and rain rate retrievals associated
12 with large discrepancies with respect to ground measurements. The spatial and temporal
13 distribution of detection errors [false alarm (FA), missed detection (MD)] and magnitude errors
14 [underestimation (UND), overestimation (OVR)] for stratiform and convective precipitation are
15 examined in detail toward elucidating the physical basis of retrieval error.

16 The diagnostic error analysis reveals that detection errors are linked to persistent stratiform
17 light rainfall in the Southern Appalachians, which explains the high occurrence of FAs
18 throughout the year, as well as the diurnal MD maximum at midday in the cold season (fall and
19 winter), and especially in the inner region. Although UND dominates the error budget,
20 underestimation of heavy rainfall conditions accounts for less than 20% of the total consistent
21 with regional hydrometeorology. The 2A25 V7 product underestimates low level orographic
22 enhancement of rainfall associated with fog, cap clouds and cloud to cloud feeder-seeder
23 interactions over ridges, and overestimates light rainfall in the valleys by large amounts, though
24 this behavior is strongly conditioned by the coarse spatial resolution (5 km) of the topography
25 mask used to remove ground clutter effects. Precipitation associated with small-scale systems (<
26 25 km²) and isolated deep convection tends to be underestimated, which we attribute to non-
27 uniform beam-filling effects due to spatial averaging of reflectivity at the PR resolution. Mixed
28 precipitation events (i.e., cold fronts and snow showers) fall into OVR or FA categories, but
29 these are also the types of events for which observations from standard ground-based raingauge
30 networks are more likely subject to measurement uncertainty, that is raingauge underestimation
31 errors due to under-catch and precipitation phase.

32 Overall, the space-time structure of the errors shows strong links among precipitation,
33 envelope orography, landform (ridge-valley contrasts), and local hydrometeorological regime
34 that is strongly modulated by the diurnal cycle, pointing to three major error causes that are inter-
35 related: 1) representation of concurrent vertically and horizontally varying microphysics; 2) Non
36 Uniform Beam Filling (NUBF) effects and ambiguity in the detection of bright band position;
37 and 3) spatial resolution and ground clutter correction.

1 **1. Introduction**

2 Reliable quantitative measurement of rainfall distribution over mountainous regions is
3 essential for climate studies, hydrological and hazard forecasting, and the management of water
4 and ecosystem resources (Barros, 2013; Viviroli et al., 2011). Recent advances toward high
5 spatial and temporal resolution satellite-based quantitative precipitation estimation (QPE) make
6 these estimates potentially attractive for flood forecasting and other operational hydrology
7 studies (e.g. Tao and Barros, 2013 and 2014 and references therein). Numerous studies have
8 been conducted to compare satellite products against ground measurements to quantify errors
9 and to improve retrieval algorithms (Amitai et al., 2009, 2012; Barros et al., 2000; Kirstetter et
10 al., 2013; Tao and Barros, 2010; Wolff and Fisher, 2008). For long-term monitoring, raingauges
11 remain the most autonomous and affordable instruments, but large errors can be introduced in
12 extrapolating point observations to represent areal means (Prasetia et al., 2012). Considering the
13 large uncertainties due to satellite temporal sampling and volume sampling discrepancies, and
14 the challenges in accounting for atmospheric heterogeneity and landform complexity, direct
15 comparison of satellite-based precipitation estimates with ground-based point measurements
16 (e.g., raingauges) poses many challenges, especially at short time scales over small areas (< 1000
17 km; Amitai et al., 2012; Barros and Tao, 2008; Fisher, 2004; among many others).

18 In mountainous regions, terrain complexity is a key complicating factor not only because it
19 introduces spatial variability, but also because land in this region is difficult to access. This tends
20 to constrain the type, density and locations of ground-based observations, leading to sparse,
21 poorly maintained, and irregularly distributed observing networks. Furthermore, observations
22 from operational ground-based radar systems cannot be relied upon to monitor the lower
23 troposphere due to blockage and ground-clutter effects, and thus satellite-based observations
24 provide an opportunity for long-term monitoring at high spatial resolution with consistent
25 measurement quality. Studies evaluating satellite QPE consistently report widespread
26 underestimation of rainfall in mountainous regions independently of the temporal scale (Barros
27 et al., 2000; Barros and Tao, 2008; Lang and Barros, 2002; Prat and Barros, 2010a). In the
28 Southern Appalachians and the adjacent Piedmont, light rainfall ($\leq 3\text{mm/hr}$) accounts for 30-
29 50% and higher of annual freshwater input to headwater catchments (Barros, 2013; Wilson and
30 Barros, 2014), and therefore light rainfall detection and estimation, which has been a long-
31 standing challenge in remote sensing of rainfall, is critical to water cycle studies. On the other
32 hand, vertical complexity and high spatial variability of heavy rainfall and mixed precipitation
33 events associated with severe weather pose major challenges to operational weather and
34 hydrological forecasting of extreme events.

35 A diagnostic analysis of the space-time structure of error in QPE from the Precipitation
36 Radar (PR) on the Tropical Rainfall Measurement Mission (TRMM) satellite in preparation for
37 the Integrated Precipitation and Hydrology Experiment (IPHEX) in 2014 is reported here. In
38 particular, we examine the physical basis of false alarm (FA), missed detection (MD),
39 underestimation (UND) and overestimation (OVR) errors with the purpose of designing and
40 implementing a Ground-Validation Observing System that captures the range of key conditions

1 and hydrometeorological regimes linked to various types of retrieval errors, and thus can inform
2 improvements in retrieval algorithms and precipitation product development in regions of
3 complex orography.

4 IPHEX is the first ground-validation field campaign after the launch of the Global
5 Precipitation Measurement (GPM) satellite (Barros et al., 2014). The configuration of the terrain
6 and TRMM overpasses and the complex regional meteorology necessitate a comprehensive
7 assessment of the spatial and temporal structure of uncertainty conditional on observing
8 geometry and hydrometeorological regime. In anticipation of IPHEX, a science-grade high-
9 density raingauge network was deployed at mid to high elevations in the Southern Appalachian
10 Mountains, USA since 2007. This network allows for direct comparison of ground-based
11 measurements from raingauges and satellite-based QPE from the TRMM precipitation radar
12 (specifically, PR 2A25 V7), and the GPM Dual-Frequency Precipitation Radar (DPR) when
13 these become available. Specifically, raingauge measurements were compared against 5 years of
14 TRMM orbital precipitation estimates PR 2A25 collected between 2008 and 2013. The satellite-
15 based estimates were evaluated via gauge-to-pixel analysis for spatiotemporally matched gauges
16 and areal average analysis at the PR pixel scale. Case studies were conducted to characterize the
17 vertical profiles of reflectivity and rain rate associated with large uncertainty, as well as the
18 spatial distribution for typical cases of quantitative errors [underestimation (UND) and
19 overestimation (OVR)] and detection errors [false alarm (FA) and missed detection (MD)] for
20 stratiform and convective precipitation.

21 Kirstetter et al. (2013) performed a comprehensive study and reported improvements of
22 TRMM PR 2A25 V7 over version 6 (V6) across the southern conterminous US (CONUS) using
23 the National Weather Service (NWS) operational radars and raingauges as reference. Several
24 changes were implemented in the TRMM PR algorithm of V7 including the vertical profile of
25 hydrometeor characteristics, which affects the reflectivity-to-rainfall rate (Z-R) relationship and
26 attenuation correction, and the reintroduction of a correction for non-uniform beam-filling
27 (NUBF) effects (described in Kozu and Iguchi, 1999) that had been removed from V6. Because
28 there are large gaps in the NWS operational observing system in mountainous regions, we build
29 on earlier work by Prat and Barros (2010a) and overlapping V6 and V7 products (TRMM PR
30 2A25) are also compared here for the 3 years of concurrent availability in the study region
31 (2008-2011).

32 Section 2 briefly describes the TRMM PR products and the climatology of rainfall observed
33 from the raingauge network, and includes a comparison of TRMM 2A25 V7 and V6 estimates
34 with respect to reference ground measurements focusing on rainfall detectability and quantitative
35 accuracy. Section 3 is devoted to an examination of the vertical reflectivity structures of
36 underestimation (UND), overestimation (OVR), false alarm (FA) and missed detection (MD)
37 errors for stratiform and convective rainfall as defined by TRMM-based criteria with the purpose
38 of characterizing the uncertainty in each class and exploring the physical basis of associated

1 errors. Section 4 focuses on diagnosing the potential sources of errors for illustrative case
2 studies. Summary and conclusions follow in Section 5.

3 **2. Data**

4 **2.1 The GSMNP Raingauge Network**

5 A high-spatial resolution raingauge network has been installed in the Great Smoky
6 Mountains National Park (GSMNP) in the Southern Appalachians since 2007 (Prat and Barros,
7 2010b). In this study, 32 stations equipped with tipping bucket (TB) gauges operating for the
8 longest continuous period, distributed at mid to high elevations (from 1150 m to 1920 m) on
9 mountain ridges, will be used as reference “ground-truth” (Table 1, Fig. 1). The current network
10 configuration includes additional raingauges, disdrometers, MicroRain Radars (MRRs) and
11 weighing raingauges (Barros et al., 2014), but in this study we use only the TB raingauge data
12 that have several years of record length during the 2008-2013 period, thus assuring robust
13 statistics. The raingauges provide point observations of surface rainfall at different measurement
14 resolution: seven raingauges use the TB3 model (RG0XX: catchment size of 200 mm; 0.2
15 mm/tip), 13 are TB3/0.1 (RG1XX: catchment size of 282.2 mm; 0.1 mm/tip) and 12 are HS305
16 (RG3XX: catchment size of 305 mm; 1 mm/tip). Note the RG3XX data are available only from
17 2009 onward. Although higher resolution TB gauges were co-located with several RG3XX
18 gauges since their initial deployment, their record is short and thus those observations are not
19 used here. To reiterate, a note of caution is warranted with regard to the many potential errors
20 due to spatial density and geolocation distribution of the gauges, wind effects, surface wetting of
21 the gauge funnel, animal and human interference, evaporation, and splashing that may introduce
22 error in the raingauge observations independently of the measurement accuracy proper. For
23 example, for high wind speeds, the reported rain rate is typically 2-18% lower than the actual
24 value (Chen et al., 2013; Wang and Wolff, 2010). Nevertheless, the raingauge measurements
25 provide a reliable and independent reference to evaluate uncertainties and identify possible
26 biases associated with remote-sensing estimates.

27
28 Over the Southern Appalachians, most precipitation is associated with stratiform systems,
29 although isolated thunderstorms and mesoscale convective systems are dominant in the warm
30 season. Figure 1 shows a map of the study region, where the GSMNP network is a relatively
31 dense raingauge network deployed in the Pigeon River basin in the Southern Appalachians
32 spanning an area of about 1,400 km². As can be seen in Fig. 1, the RG0XX (easternmost) and
33 RG3XX (westernmost) gauges are clustered over the outer ridges, whereas the RG1XX gauges
34 are distributed in the inner mountain region. Figure 2 shows the spatial variability of average
35 daily precipitation raingauge accumulations over the period of study. Note the lack of classic
36 orographic rainfall enhancement with elevation (Fig. 2b), as well as the stronger variability for
37 the RG1XX gauges in the inner mountain region (blue colors) with higher rainfall totals at lower
38 elevations in the valleys and at ridge tops and a decrease at intermediate elevations on hill slopes.

1 The high values in the valleys reflect the contribution of seeder-feeder processes resulting from
2 the interaction of stratiform rainfall with low level clouds and thick fog banks (Wilson and
3 Barros, 2014). Complex orographic precipitation effects in the Southern Appalachian Mountains
4 and high intra-annual variability in large-scale weather conditions explain the high spatial
5 variability in the diurnal cycle of rainfall frequency from one season to another as depicted in Fig
6 3. During the summer, rainfall frequency peaks in the late afternoon (15:00 EDT to 18:00 EDT)
7 with daytime convection accounting for nearly 20% of the seasonal total and is somewhat
8 uniform in the remainder of the day with each period contributing about 10-15%; during the
9 winter, rainfall frequency reveals a strong diurnal cycle characterized by a high-amplitude
10 maximum in the early afternoon (12:00 to 15:00 EDT) and a relative minimum occurring
11 between 21:00 and 06:00 EDT. Spring and fall seasons, on the other hand, exhibit a much
12 weaker diurnal cycle, with a relative maximum occurring in the afternoon, and otherwise more or
13 less constant throughout the rest of the day.

14 **2.2 TRMM PR 2A25 Products**

15 The TRMM satellite was launched in November 1997 and operated on a non-sun-
16 synchronous orbit designed to capture precipitation structure in the tropics. On July 8, 2014
17 NASA ceased station keeping maneuvers and TRMM is currently drifting downward from its
18 operating altitude of 402 km to 335 km, expected to be reached around February 2016, at which
19 point data collection will be terminated. The Precipitation Radar (PR) was the first active
20 microwave instrument for measuring three-dimensional rainfall structure over the tropics and
21 subtropics from space (Kozu et al., 2001), and produces more reliable near surface estimates of
22 precipitation at higher spatial resolution than radiometers including in mountainous regions
23 (Barros et al., 2000; Barros and Tao, 2008; Nesbitt et al., 2000). The PR operates at 13.8 GHz
24 frequency with 250 m vertical resolution, and is thus capable of penetrating dense cloud layers to
25 detect underlying precipitation (Praselia et al., 2012). Retrieval errors such as the uncertainty of
26 the assumed drop size distribution (DSD), incorrect physical assumptions (freezing-level height,
27 hydrometeor temperatures), possible contamination by surface backscatter, the reliability and
28 physical basis of the stratiform-convective classification, attenuation and extinction of the signal
29 and NUBF effects, light rain sensitivity (minimum detectable signal), and surface clutter
30 rejection all contribute to uncertainty in PR rainfall estimates, and the respective effects are
31 corrected to varying degrees (Iguchi et al., 2009; Wolff and Fisher, 2008).

32 Specifically, a hybrid of the surface reference technique and the Hitschfeld and Bordan
33 method is applied to correct for atmospheric attenuation (Iguchi et al., 2000). The PR attenuation
34 correction is adequate in stratiform rain but is underestimated in convective rain, particularly for
35 heavy rain accumulations (Liao and Meneghini, 2009). Generally, application of the attenuation
36 correction can change the estimated rain rate by an order of magnitude in cases of heavy
37 precipitation (Bindlish and Barros, 2000; Iguchi et al., 2000; Meneghini et al., 2000). Generally,
38 the NUBF effects refer to underestimation errors in the presence of reflectivity gradients, that is,
39 subgrid-scale volume heterogeneity at the relatively coarse resolution of the PR footprint

1 (Durden et al., 1998; Nakamura, 1991). Previous studies evaluating the impact of NUBF have
2 been conducted for ocean conditions and for moderate to heavy rainfall conditions, and results
3 suggested very small errors due to NUBF for the TRMM PR, but no studies focused on subgrid-
4 scale effects in mountainous regions where there is a strong co-organization of landform and
5 precipitation along with strong space-time variability. Other sources of errors include the orbital
6 geometry of the satellite at relatively high latitude (Fisher, 2004), and local hydrometeorological
7 regimes which may present cloud and rainfall vertical structure very different from that implied
8 in the retrieval algorithm's microphysical assumptions. Intercomparison of precipitation
9 estimates from different algorithms allows examination of the specific impacts of algorithm
10 differences on QPE reliability and accuracy. For instance, the underestimation of rain rate in V6
11 (Prat and Barros, 2010a) was addressed in the V7 algorithm revisions by recalibration of the Z-R
12 relationship over land, and implementation of the NUBF correction to produce larger estimates
13 both over land and over ocean (Seto et al., 2011). Finally, sampling errors are subject to
14 sampling frequency and the spatiotemporal structure of precipitation associated with diurnal,
15 seasonal, and inter-annual variability of rainfall within a region. Even though sampling errors are
16 more randomly distributed, they can be a significant contribution to the total error (Fisher, 2004).
17 The main TRMM product used in this work is the PR 2A25 V7 product, described at
18 (http://disc.sci.gsfc.nasa.gov/precipitation/documentation/TRMM_README). V6 products are
19 used for assessing V7 algorithm improvements, specifically with regard to instantaneous
20 precipitation estimates. For this purpose, all rainfall measurements observed coincidentally by
21 TRMM overpasses and the GSMNP network from June 2008 to May 2011 are used.

22 An important challenge in the validation of satellite-derived estimations against ground
23 measurements is the resolution discrepancy of different datasets. Here, all the raingauge
24 measurements within a 2.5-km radius from the center of the PR pixel position for each PR
25 overpass within a selected time-scale are integrated into one. Nevertheless, matching the
26 observations from raingauges and TRMM PR at the nominal pixel scale (~5 km) in space and
27 time introduces uncertainties due to differences in the measurement control-volume, generally
28 referred to as representativeness error (i.e. Porcù et al., 2014), which is further aggravated due to
29 sparse spatial sampling and topographic variations: raingauges report near-surface point rainfall
30 rate while satellite estimates correspond to a cloud volume-averaged rainfall rate, which is also
31 highly dependent on the precipitation system, cloud physics and morphology, and associated
32 rainfall (e.g. Habib and Krajewski, 2002; Prat and Barros, 2010a). However, this discrepancy can
33 be alleviated by using an optimal integration time interval for gauge observations (Prat and
34 Barros 2009; Wang and Wolff, 2010) as it is done in this manuscript (see Section 2.3). Despite
35 these challenges, comparisons with ground reference gauges constitute a critical component in
36 evaluating the accuracy of the PR estimates of surface precipitation, reflectivity and rain rate.

37 **2.3 Comparison of TRMM PR 2A25 V7 versus V6**

38 **2.3.1 Rainfall Detection** - As stated earlier, the objective of the revisions implemented in the
39 TRMM PR V7 algorithm was to correct some key deficiencies identified in the V6 algorithm,

1 namely the large underestimation of rain over land relative to ground-based measurements, and
2 the relatively large dependence of rain estimates on the viewing angle (Iguchi et al., 2009). A
3 detailed summary of the major changes in the TRMM PR retrieval algorithm are summarized in
4 Iguchi et al. (2009) and Okamoto et al. (2008). Here, V6 and V7 rain rates from June 2008 to
5 May 2011 corresponding to three years of satellite overpasses over the Southern Appalachians
6 are compared. Note that V6 data are only available up to summer 2011. To evaluate the satellite
7 estimates, rain rate estimates for a given pixel are compared to the observed values at raingauges
8 located within the pixel's fingerprint (~5 km diameter). The number of raingauges varies from
9 pixel to pixel, but on average, about 2 gauges can be found in each PR field of view. To
10 determine whether there is an optimal time-scale that reconciles the nearly instantaneous (point
11 in time) satellite-based areal rainfall estimates (pixel scale) with raingauge observations (point in
12 space) with different measurement resolution (TB size), the gauge rain rates are integrated over a
13 range of time-scales (10–60 min) centered at the time of overpass and spatially averaged at the
14 PR pixel scale. To evaluate precipitation detectability (contingency tables and statistical skill
15 scores), point-to-pixel comparisons were applied to increase the sample size and avoid ambiguity
16 associated with the spatial representativeness of the gauges within the pixel. When multiple
17 gauges exist in the same pixel, the PR measurements are paired separately with different
18 raingauges. It is assumed that the PR resolution remains constant for both near-nadir and off-
19 nadir inclination angles. To avoid contamination due to the resolution deformation, the PR-RG
20 pairs were segregated into “near-nadir” (scanning inclination angles ranging from 0° to 9°) and
21 “off-nadir” (scanning inclination angles beyond 9°) comparisons. Off-nadir pairs are discarded in
22 some quantitative comparisons to exclude the angle deformation in exploring other sources of
23 error. In this section, the TRMM PR 2A25 near surface rain rate was analyzed with respect to the
24 independent ground reference rainfall data to examine the detectability performance of satellite
25 rainfall retrievals using contingency tables and statistical skill scores. The rain detection and
26 surface clutter discrimination are primarily handled by the Level 1 algorithms (e.g., 1B21 and
27 1C21 products), which have been improved over time (e.g., change of clutter routine module in
28 PR 1B21 from V6 to V7). Level 1 products are used subsequently as input to the Level 2
29 algorithm. For example, the near-surface rain rate from 2A25 is retrieved based on the
30 identification of clutter free ranges from 1C21. Therefore, the higher level product 2A25 reflects
31 the integration of Level 1 results, and can serve as a fair indicator of effective rainfall
32 detectability of TRMM.

33 The contingency matrices of PR estimates with regard to the gauge observations at 10-min
34 time-scale for all angles (a) and for near-nadir cases only (b) are presented in Table 2. Table 3
35 provides a summary of detection metrics (i.e. skill scores) based on the counts of hits (YY),
36 misses (NY), false alarms (YN) and correct rejections (NN) inferred from contingency matrices
37 at time-scales ranging from 10 to 60 min: accuracy, frequency bias (FB), probability of detection
38 (POD), false alarm ratio (FAR), probability of false detection (POFD), and threat score (TS). The
39 equations to calculate the skill scores are included as footnotes to Table 3. The results for all
40 raingauges (see Table 2a) for V7 show the percentage of correct detections (rain events detected

1 simultaneously by the TRMM PR and raingauges: ~1%) is lower than the number of false alarms
2 (events registered by the TRMM and not recorded by rain gauge: ~3%), but higher than the
3 number of missed detections (events observed by raingauges but missed by TRMM: ~0.7%). The
4 agreement in the number of rejections (when both TRMM and raingauges do not detect rain) is
5 expected. Although the specific quantitative values are different, the skill for near-nadir viewing
6 angles (Table 2b) is nearly the same as that for all cases (Table 2a). Overall, V7 exhibits slightly
7 better detection skill than V6 as indicated by the higher probability of correct detection and
8 correct rejection, and lower probability of false alarms and missed detection.

9
10 Results from the sensitivity study of the skill scores to time-scale of integration of rain gauge
11 observations centered at the time of TRMM overpasses are summarized in Table 3. TB RG3XX
12 data are excluded from this comparison considering its coarse measurement accuracy (1 mm/tip),
13 and due to the fact that the record length of concurrent V6 and V7 is too short. V6 and V7
14 exhibit similar skill in accuracy and POFD at different time scales. The FB scores, which
15 indicate whether TRMM has a tendency to underestimate (<1) or overestimate (>1) rainfall,
16 show strong sensitivity to the time-scale of integration, followed by the gauge measurement
17 sensitivity. Unbiased results are obtained at the 20 min time scale with skill scores close to
18 perfect (1). The POD scores decrease with the time-scale as expected due to the space-time
19 intermittency of rainfall, and no significant improvements were found in V7 as compared to V6.
20 FAR scores, which count how often the satellite products detect rainfall in the absence of rainfall
21 at the gauges, are slightly lower for V7. Lower scores are observed in RG1XX series in the inner
22 mountain region than in the RG0XX series on the eastern ridges, possibly because of rain gauge
23 measurement threshold (RG0XX: 0.2 mm/tip, RG1XX: 0.1 mm/tip) and location (RG0XX: outer
24 ridge, RG1XX: inner ridge). The TS values, which are sensitive to correct detection and penalize
25 for both missed detections and false alarms, are consistently higher in V7 as compared to V6, but
26 only slightly so. Overall, this analysis indicates that V7 improvements in rainfall detection in the
27 Southern Appalachians are minimal relative to V6. This result is consistent with Kirstetter et al.
28 (2013), who reported improvement in QPE but not in detection metrics for 2A25 V7 products
29 relative to V6.

30
31 **2.3.2 Quantitative Precipitation Estimation (QPE)** - To assess the accuracy of TRMM PR
32 rainfall estimates, histograms of concurrent satellite near surface rain rate (NSR) estimates and
33 gauge observations for the near-nadir cases are displayed in Fig. 4a, using the average rain gauge
34 rates at the PR pixel scale. Only non-zero data pairs are used, and thereby large amounts of non-
35 rainy days are excluded from this comparison. The overestimation of the relative frequency of
36 light rainfall (< 5mm/hr) results from QPE underestimation of heavier rainfall. Figure 4b
37 suggests that V7 NSR estimates of moderate rainfall rates are higher than estimated surface rain
38 rate (ESR) estimates. In addition, scatterplots and regression analysis were examined (not shown
39 here) for ESR and NSR against rain gauge observations with similar results to those reported by
40 Prat and Barros (2010a). Compared to V6, a smaller slope is obtained in V7 for these two

1 TRMM products, which is consistent with Seto et al. (2011) who showed that V7 rain rate
2 estimates are larger than in V6 over land and over ocean. The tendency to underestimate rain rate
3 (slope >1) has been mitigated in V7 with slopes closer to unity, thus indicating better agreement
4 with the reference ground observations. The severe underestimation of heavy rainfall rates in
5 both versions can be attributed at least in part to the lack of areal representativeness of the
6 raingauges which are point estimates in contrast with the area-averaged (5×5 km²) TRMM
7 rainfall estimates, although the point estimates of rain rate are reduced by using a time-scale of at
8 least 10 minutes centered at the satellite overpass time.

9 **3. Statistics and Physical Basis of PR 2A25 V7 Error Structure**

10 The physical basis of error structure in V7 is assessed focusing on the space-time variability
11 of error and how it relates to storm structure for underestimation (UND), overestimation (OVR),
12 false alarm (FA) and missed detection (MD) cases. This section is organized by first evaluating
13 the overall quantitative performance of TRMM precipitation estimates compared to gauge data,
14 next examining the rain type, rain rate, and the temporal distribution over a spectrum of time
15 scales (e.g., diurnal and seasonal), and finally exploring the relationship between rainfall error
16 and vertical reflectivity structure.

17 **3.1 Surface Rain Rate Classes**

18 Error analysis of TRMM estimates for 1820 PR overpasses in the Southern Appalachians
19 during 2008-2013 is presented here. The reference rainfall is computed in a similar manner to
20 that described earlier by selecting raingauges that lie within a 2.5 km radius around the center of
21 the PR pixel. A sensitivity analysis of bias was conducted on four TRMM PR 2A25 precipitation
22 products: estimated surface rain rate (ESR), near surface rain rate (NSR), 2-4 km averaged rain
23 rate, and integrated column rain rate at various time scales ranging from 10- to 60-min (not
24 shown here). Results for TRMM NSR indicate that bias is minimized at 10min time scales for
25 RG0XX & RG1XX, and 30min for RG3XX estimates (RG0XX: ~0.5, RG1XX:~0.2,
26 RG3XX:~0). Consequently, 10- and 30- min (centered at the time of overpass) rain rates from
27 RG0XX & RG1XX and RG3XX respectively will be used as reference hereafter. As seen in
28 Figure 5a, bias is lowest overall in the inner mountain region (RG1XX). Overestimation of light
29 rainfall leads to large positive bias everywhere, but is much larger on the western ridges
30 (RG3XX) than on the eastern ridges (RG0XX) or in the inner region (RG1XX) consistent with
31 the gauges' measurement resolution (Fig. 5a); for moderate and heavier rain rates (> 5 mm/hr),
32 the bias is negative, relatively small, and uniformly distributed.

33 Regression analysis (not shown here) of PR 2A25 V7 rainfall estimates (NSR and ESR)
34 versus averaged gauge data indicates that for non-null PR-gauge pairs, both estimates derived
35 from PR are in good agreement (regression slope close to one) with the ranges of rainfall
36 intensity associated with the regional hydrometeorological regimes, but the R² value is very low

1 for both estimates (NSR: 0.09, ESR: 0.08), which likely results from significant discrepancies for
2 heavy rainfall events.

3 In order to better understand the quantitative discrepancy between TRMM and RG, the
4 matched PR pixels and raingauge cluster pairs are classified into five distinct categories
5 corresponding to the relative difference (ϵ) of the 2A25 estimates with respect to raingauge
6 observations (see Fig. 5b and Table 4). The same classes are used later in the manuscript to
7 examine TRMM reflectivity profiles. In Table 4, regardless of the value of the discrepancy in the
8 rainfall rate estimates, conditions when rain was simultaneously observed by the satellite and
9 raingauges (cases I, II, III), correspond to approximately 31% of all cases, while about 50%
10 report rain for TRMM only (case IV, FA), and about 19% report rain for raingauges only (case
11 V, MD). As will be shown later in more detail (see Figure 7a), a large fraction of FAs and MDs
12 occurs at larger viewing angles ($> 8^\circ$) in which case NUBF uncertainty is expected to be higher.
13 However, the predominance of FAs raises concerns about the reliability of the algorithm in
14 mountainous regions. In order to address this question, an evaluation was conducted by
15 comparing concurrent TB and weighing raingauge observations (not shown here). The analysis
16 indicates that the TB raingauges miss detection of light rainfall events of short duration (< 30
17 min) with accumulations below their measurement sensitivity, corresponding to circumstances
18 when wind and turbulence under-catch effects can be dominant, but these circumstances are not
19 statistically meaningful. Significant discrepancies between TB and weighing raingauges occur
20 for snowfall conditions when near-surface air temperature is below 0°C , but this is still a small
21 number of events ($\sim 15\%$ of FAs) in the region of study. Thus, the problem of excessive spurious
22 detection cannot be explained by TB raingauge measurement limitations alone.

23 An overview of the organization of error categories as a function of rain type and rain rate is
24 provided in Figure 6. The rain type (derived in TRMM 2A23 as a parameter to separate
25 convective and stratiform rain) and rain rate categories follow the error classification framework
26 described in Table 4. A large fraction of UND errors (class II) is associated with “probably
27 stratiform” (rain type: 120) rainfall by the TRMM PR algorithm in the winter, but over 60%
28 correspond to heavy rainfall events (see Table 4, IIa) and most convective rainfall (200 & 210)
29 occurs during the summer. There is a relatively small number of samples overall (the UND 5-
30 year total is only 174, see Table 4). The errors tend to cluster at specific times-of-day that are
31 consistent with the regional hydrometeorology, thus enhancing our confidence on the diurnal
32 cycle and providing a physical basis for attribution. Indeed, a survey of the results shows that
33 the diurnal cycle of UND error peaks during the period 15-18 EDT (not shown here), a time of
34 day typically associated with daytime solar forcing of convective activity. The histograms of
35 TRMM and raingauge rain rate estimates for UND events (Fig. 6a, right panel) have different
36 skew with TRMM PR NSR estimates mostly below 5 mm/hr, whereas most raingauge
37 observations exceed 10 mm/hr. This indicates that UND errors cannot be corrected using linear
38 bulk adjustments such as bias correction; rather, physical insight is needed to improve retrievals.

1 Overestimation (OVR, class III) errors are mostly associated with wintertime precipitation
2 classified as “probably stratiform”. Inspection (not shown here) of the apparent annual and
3 diurnal cycles of OVR errors (note again the limited sample size on an hourly basis: 5-year total
4 OVR is 139, Table 4, III) indicates that these errors exhibit a diurnal cycle peaking in January
5 and March during daytime (9-15 EDT) consistent with the diurnal cycle of rainfall in winter
6 (Figure 3d). A good overall agreement between the histograms of raingauge and TRMM rain
7 rates (Figure 6b, right panel) for these events suggests that bias correction of OVR errors should
8 lead to immediate improvements in TRMM PR products. Figure 6c shows that FA (IV) errors are
9 also associated with “stratiform” and “probable stratiform” rainfall throughout the year and light
10 rainfall rates (< 5 mm/hr).

11 Overall, the results show that the error budget of TRMM PR NSR estimates is largely
12 controlled by ambiguity in the detection of the bright band (stratiform conditions) for
13 significantly off-nadir observations (significant NUBF effects) for light rainfall conditions in all
14 seasons, and in the wintertime generally.

15 **3.2 Space-Time Error Structure**

16 A survey of precipitation detectability skill in the TRMM PR 2A25 V7 from the point of
17 view of FA and MD errors is presented in Figure 7. The impact of observing geometry is
18 explored in Fig. 7a, focusing specifically on the interplay between complex orography, satellite
19 orbit, and the viewing angle for each pixel in the satellite’s swath. Detection skill depends on the
20 orbit and the specific trajectory of the satellite over the region. For the eastern ridges (RG0XX
21 series), a large portion of FA occurs at small angles, in particular $\sim 5^\circ$, reflecting the geometry of
22 the overpasses and the terrain underneath as the satellite approaches the Appalachians; in the
23 inner ridges (RG1XX series), more cases are observed around 8° and 11° ; for the western ridges
24 (RG3XX series), almost all cases are registered at off-nadir angles ($\geq 9^\circ$), especially around 11° .
25 Note that at larger viewing angles (RG1XX and RG3XX) the radar signal also travels through a
26 longer trajectory, and thus an extended liquid water path. Figures 7b and c display the diurnal
27 and seasonal distributions of FAs and MDs corresponding to rainfall classes IV and V (Table 3).
28 Note the strong diurnal cycle of FAs peaking at mid-day and early afternoon, especially in the
29 case of the inner region (blue color). The seasonal cycle shows that FAs in the eastern ridges and
30 western ridges are relatively uniformly distributed throughout the year, whereas they peak in the
31 summer in the inner ridges. Furthermore, the number of FAs and MDs in the inner region is very
32 high and dominates overall statistics. Close examination of the diurnal cycle reveals that most
33 FAs in the summer occur in the afternoon (12-18 EDT) corresponding to diurnal convective
34 activity, while winter cases follow the diurnal cycle of precipitation pattern peaking in the early
35 afternoon (not shown here).

36 Among all MD cases, most are classified as “no rain” and some are categorized as “other”,
37 whereas only 3 are classified as stratiform, and none are considered convective (not shown here).
38 Figures 7b and c for MDs (class V) show a strong diurnal cycle with most occurring around 12-
39 15 EDT and a seasonal trend with a large proportion occurring during the cold season, which is

1 attributed to the frequent presence of fog and low level clouds in the fall and winter seasons,
2 especially in the inner region (RG1XX). The very small count of MDs in the western ridges
3 (RG3XX) is explained in part by the coarse gauge sensitivity (1mm/tip, 30-min time-scale), and
4 because fog seldom develops over this region due to strong winds. Dense and deep fog
5 formation during the fall and winter seasons in the inner mountain region establishes conditions
6 for enhanced stratiform rainfall via seeder-feeder mechanisms at low levels (<1 km) that is
7 measured by the gauges in the inner mountain region (e.g. Wilson and Barros, 2014), but cannot
8 be detected by the TRMM PR due to the topography and automatic ground clutter correction. In
9 addition, the minimum detectable signal of TRMM PR is approximately 18 dBZ (0.4 mm/h)
10 (Heymsfield et al., 2000; Yang and Nesbitt, 2014), and thus weak radar reflectivity for light
11 rainfall can also partly explain MD statistics.

12 **3.3 TRMM PR Reflectivity Profile and Rainfall Detectability**

13 Here, we examine the relationship between rainfall detectability and the vertical reflectivity
14 structure of TRMM PR. To facilitate the comparison of various types of precipitation including
15 the distinction between convective and stratiform precipitation by TRMM-derived criteria, three
16 categories of reflectivity profiles have been identified (see Figure 8): 1) stratiform with bright
17 band (BB); 2) stratiform without bright band (BB); and 3) convective. Note that the reflectivity
18 profile is used in the rain classification algorithm, in addition to the precipitation rate estimation
19 proper.

20 For stratiform UND cases (see Figures 8a and 8b, class II), the reflectivity gradually
21 decreases with altitude and the median values between 2 km and 4 km are in the range of 20 – 30
22 dBZ approximately. Some UND cases (see the red outliers in Figure 8b, II) display high cloud
23 tops (up to 9 km), consistent with the heavy rainfall events in Figure 6a that are indicative of
24 warm rain with embedded convection. Reflectivity data below 2 km are often removed due to
25 ground clutter contamination. In Figure 8a (III), the mean reflectivity profile shows a decreasing
26 tendency with height (from 2.75 km toward the ground surface), suggesting that summertime
27 OVR errors are likely linked to light rainfall evaporating before it reaches the ground (see rain
28 type: 100 in Figure 6b). Compared to the UND (II) cases (left panels in Figure 8), the reflectivity
29 profiles for OVR cases show steeper positive gradients at lower levels, in particular below 3 km,
30 and more measurements are available below 2 km altitude in the convective cases(see Figures 8b
31 and 8c, III). The downward decreasing trend of reflectivity toward the surface is also evident in
32 the reflectivity profiles of FAs for stratiform conditions with and without bright band (see Figure
33 8a, IV), which can also be explained by raindrop evaporation during the summer (see rain type:
34 100 in Figure 6c). Compared to the UND and OVR cases in Figs. 8a and b, the FA stratiform
35 reflectivity profiles decrease more gradually with altitude at lower levels. Note the rapid
36 reflectivity increase (35-50 dBZ) below 2 km in the convective cases (IV, Figure 8c). This
37 feature will be further discussed next in the context of error diagnosis and interpretation. Overall,
38 steeper positive gradients in reflectivity are displayed in OVR cases at lower levels, while the
39 decreasing trend with height shown in UND and FA possibly indicates light rainfall evaporation

1 before reaching the ground. The high cloud tops in UND are characteristics of warm stratiform
2 rainfall with embedded convection, resulting in heavy rainfall events.

3 **4. Physical Context of Retrieval Error**

4 In this section, we focus primarily on diagnosing the potential sources of errors in the
5 retrieval algorithm by studying selected representative TRMM overpasses with substantial
6 discrepancies between 2A25 V7 NSR estimates and raingauge observations, including isolated
7 thunderstorms, mesoscale convective systems, cold fronts, hail events, and snow showers.
8 Figure 9 shows the TRMM overpass in the region of study for each of the selected cases overlaid
9 on the base reflectivity fields from the KMRX and KGSP NWS (National Weather Service)
10 radars respectively in Knoxville, TN and Greer, SC.

11 **4.1 Local Underestimation (II)**

12 Figure 10a depicts a vertical cross-section from the TRMM overpass at 15:08 EDT during a
13 tornado outbreak event (<http://earthobservatory.nasa.gov/NaturalHazards/view.php?id=77308>)
14 on 2 March 2012 as the primary squall line was moving over the region (Fig. 9a). After applying
15 the ground clutter correction, the near surface rain rate of 4.5 mm/hr at the location marked by
16 the black arrow (viewing angle 7.6°) is estimated at 2.25 km altitude. The collocated raingauge
17 (RG104, Fig. 1) is placed at a much lower elevation (~1.6 km) and records very heavy rainfall
18 intensity (60 mm/h). In the presence of low level fog and orographic clouds, this difference in
19 elevation (~ 650 m) is sufficient to explain the one order of magnitude difference in rainfall
20 intensities by seeder-feeder enhanced coalescence (Wilson and Barros, 2014). The PR
21 reflectivity profile extends up to 8 km in altitude, and there is no indication of bright band or
22 large ice-scattering aloft; nevertheless, this pixel is classified as “probably stratiform” (rain type:
23 120) based on the H method because of the weak echo. In addition to the ground-clutter filter
24 that eliminates a significant fraction of the measured reflectivity profile at lower levels, the
25 incorrect classification of shallow convection as probably stratiform is also due in part to the
26 effect of spatial averaging over the PR’s relatively coarse horizontal resolution, a smoothing
27 effect that is amplified at off-nadir viewing angles. Similar results were reported by Heymsfield
28 et al. (2000) who found that convective precipitation often falls from cells smaller than the PR
29 footprint and its average reflectivity tends to be underestimated due to the NUBF effects,
30 consequently leading to the rain-type classification being artificially biased toward the stratiform
31 type. Nevertheless, an examination of the TRMM reflectivity cross-section in Fig. 10a as well as
32 PR 4 km reflectivity fields (not shown here) clearly reveals the substantial advantage of the
33 satellite based radar in mountainous regions, where the terrain blocks the monitoring
34 effectiveness of the ground radars (see Fig. 9a).

35 Figures 10b and c display the vertical cross-section of reflectivity and rain rate of two
36 adjacent scans on 8 July 2011 15:51 EDT associated with the presence of small bands and
37 clusters of severe summer thunderstorms in the region of interest at the time of overpass (Fig.

1 9b). Two selected pixels (denoted as pixel 1 on one scan and pixel 2 on the other) observed at
2 $\sim 12.1^\circ$ angle among those corresponding to the high altitude outliers (red + signs) in Figure 8c
3 (II) are highlighted here. Note the steep increase in profile reflectivity at altitudes above 4 km
4 followed by a decrease with height that indicates the existence of a bright band; along with high
5 low-level reflectivities, the vertical structure of reflectivity suggests that over the western slopes
6 of the Appalachians high precipitation rates were produced by a stratiform system with
7 embedded convection. Although gauges RG303 (40 mm/hr) and RG311 (60 mm/hr) are very
8 close together (Fig.1), RG303 is located at a higher elevation (~ 1.5 km) on the wall of a valley
9 running nearly perpendicular to the western ridge of the Southern Appalachians, whereas RG311
10 is at lower elevation (~ 1.25 km) in the valley proper. The TRMM near surface estimate for both
11 scans is between 22-25 mm/hr. The effect of the ground clutter correction is evident in Figs. 10b
12 and 10c. In addition, note the relative location of the gauges at the boundary between two
13 columns, one with low to moderate reflectivity and one with very high reflectivity in Figs. 10b
14 and 10c. Because the clusters of shallow embedded convection are very small, averaging
15 significantly reduces the TRMM estimated rainfall and reduces spatial variability. Therefore,
16 TRMM appears to underestimate rainfall from the isolated small-scale summer convective cells,
17 consistent with previous studies demonstrating the underestimation of convection over land by
18 the TRMM PR algorithm (Iguchi et al., 2009; Rasmussen et al., 2013). Among the two rain gauge
19 observations in pixel 2, more intense rainfall is observed in the nearby valley (RG311) than on
20 the ridge (RG303), and the PR reflectivity in the valley is much higher than surrounding ridges.
21 Despite horizontal separation in addition to the elevation difference, the low level enhancement
22 of rainfall at RG311 compared to RG303 is consistent with the increased depth of the
23 precipitation column thus enhanced raindrop growth by coalescence (Prat and Barros, 2010b;
24 Wilson and Barros, 2014). In such circumstances, orographic rainfall does not increase with
25 elevation as in the canonical model. This event highlights detectability challenges over
26 mountainous regions at coarse horizontal scales (e.g., high spatial variability due to the inability
27 to resolve the complexity of the physics of orographic enhancement). The effective resolution
28 deformation at far-range viewing angles may further contribute to the large underestimation.

29 **4.2 Local Overestimation (III)**

30 At the time of the TRMM overpass on 18 August 2011 18:53 EDT, there were small
31 convective clusters and isolated thunderstorms scattered across the region (Fig. 9c). The KMRX
32 radar located in Knoxville, TN shows no activity over the Appalachians, but the KGSP radar
33 located in Greer, SC does show activity over the eastern ridges, which is consistent with the
34 shallow isolated cells detected by the TRMM PR shown in Fig. 11a. Classified as “certainly
35 convective” (the reflectivity profiles show no signal of ice scatter aloft), the retrieved near
36 surface rain rate overestimates the observed precipitation at RG005 (~ 1.52 km; 12 mm/hr) and
37 RG008 (~ 1.74 km; 18 mm/hr) by nearly 60% on average (viewing angle is 5.2°). Interestingly,
38 despite very different vertical structure including the bright band effects for the UND (II) case on
39 8 July 2011 discussed in Section 4.1, the near surface precipitation estimates derived from
40 TRMM for both cases are about the same (~ 24 mm/hr). However, the OVR(III) problem could

1 be related to the relative position of the two gauges at the edge of the isolated convective cluster
2 (Fig. 9c) as the satellite moves over the orography, in which case NUBF artifacts should lead to
3 overestimation of reflectivity over the gauges outside of the convective cluster. Indeed, the
4 TRMM PR reflectivity between 2 and 4 km is in the 40-50 dBZ range, whereas the base-
5 reflectivity from KGSP at gauge locations is in the 20-30 dBZ range.

6 Two other relevant OVR (III) cases coincided with the passage of a cold front with a leading
7 pre-frontal convection line in the Piedmont on 21 January 2012 that was captured by the TRMM
8 overpass at 12:05 EDT (Fig. 9d), and a pattern of disorganized thunderstorm activity ahead of
9 the propagation of a westerly convective system on 17 April 2012 with overpass at 15:09 EDT
10 (Fig. 9e). The winter system produced major winter snow and ice precipitation from western
11 North Carolina to New York State. In the reflectivity cross-section (Fig. 11b), the vertical
12 profiles exhibit a sharp decrease of about 16 dBZ in reflectivity between 2 km and 3 km. The
13 TRMM PR rain rate at ~2 km and the value observed at RG109 in the inner mountain region
14 (~1.5 km, Fig. 1) are 26.3 mm/h and 10.8 mm/h respectively, resulting in an overestimation of
15 140%. However, raingauge measurements are expected to exhibit significant errors (~ up to
16 60%) for frozen precipitation, and even higher for snow in the presence of strong winds. Since
17 this event produced significant snow accumulations and frozen rain, error attribution is an
18 ambiguous proposition.

19 Both ground-based radars (KMRX, KGSP) miss the deep isolated convective activity in the
20 mountains that is detected by the TRMM PR (Fig. 11c). The vertical profiles for pixel 1 and 2
21 over the locations of RG001 and RG010 on the eastern slopes of the Appalachians show large
22 reflectivity (>30 dBZ) up to 6-7 km, suggesting the presence of ice/hail aloft. Records held by
23 the State Climate Office of North Carolina (<http://www.nc-climate.ncsu.edu/lrddb/index.php>)
24 reveal multiple reports of intense hail over large areas in the Southern Appalachian Mountains at
25 the time. However, raingauge records indicate only 1.2- and 9-mm/hr compared to 25.8- and
26 36.5-mm/h from TRMM estimates for pixel 2 (RG001) and pixel 1 (RG010) respectively.
27 Again, this reflects the deficiency of tipping-bucket gauges to capture frozen precipitation, and
28 hail in particular. Conditions in the two pixels are classified as “certainly convective” because of
29 the high horizontal reflectivity gradients. The TRMM PR demonstrates good capability to detect
30 this hail-producing storm.

31 **4.3 Local False Alarms (IV)**

32 FA (IV) errors can result from NUBF effects for certain viewing angles, terrain and weather
33 configurations due to coarse resolution leading to spatial deformation in reflectivity similar to the
34 problems leading to overestimation in the August 2011 case (Fig. 11a) discussed above. Such
35 errors could result from non-precipitating ice clouds, or from light snowfall under windy
36 conditions that is missed by the raingauges. Indeed, blizzard conditions were present for the
37 TRMM overpass 24 January 2010 19:54 EDT (Fig. 9f). Note the extremely large reflectivity
38 values in the lowest levels in the cross-section on the western ridges of the Appalachians
39 displayed in Figure 12. The vertical profiles exhibit large increments of reflectivity (22 dBZ) and

1 rain rate (47 mm/h) below 4 km. The pixel identified by the black arrow is classified as
2 “certainly convective” and the retrieved near surface rain rate is ~50 mm/h at 1.75 km elevation,
3 whereas the nearest raingauge (RG302, at 1.86 km) does not register precipitation. According to
4 winter storm reports from the State Climate Office of North Carolina ([http://www.nc-](http://www.nc-climate.ncsu.edu/climate/winter_wx/database.php)
5 [climate.ncsu.edu/climate/winter_wx/database.php](http://www.nc-climate.ncsu.edu/climate/winter_wx/database.php)), snow showers developed across the
6 mountains on 12 January 2010, resulting in ice and snow accumulation in the lower valleys. The
7 substantial increase in reflectivity at lower levels in the TRMM PR profiles likely results from
8 frozen precipitation particles in cold clouds and/or the accumulated ice and snow in the valleys
9 detected by TRMM.

10 **5. Summary and Conclusions**

11 TRMM PR 2A25 QPE products were spatiotemporally matched and compared with ground
12 gauges in the Southern Appalachian Mountains over a five-year period 2008-2013, which
13 provides a statistically large sample of comparisons performed at PR-pixel resolution. The
14 quantitative comparisons yield favorable agreement of the PR with raingauge observations, with
15 clear advantage over remote ground-based operating radars, but errors can be significant
16 depending on the underlying rainfall regimes.

17 First, V7 and V6 QPEs were inter-compared in order to assess the impact of retrieval
18 algorithm changes such as reintroducing the NUBF correction, recalibration of the Z-R
19 relationship over land, and attenuation correction of the PR radar signal. Although a small
20 improvement from V6 to V7 was identified at high to moderate rainfall rates, the results do not
21 show significant differences in warm-season precipitation detection skill.

22 Based on the TRMM rain-type classification, characteristic features in the vertical structure
23 of reflectivity and retrieved rainfall profiles that can be associated with distinct error
24 characteristics under various precipitation regimes were identified. Regardless of error type, a
25 significant fraction of estimation errors occurs when rainfall is classified as “probably
26 stratiform”, which is hypothesized to result from the compounded effect of radar sensitivity and
27 NUBF that renders the PR detectability of bright band unreliable for small-scale systems,
28 especially at far-viewing angles. The statistics of FAs are highly sensitive to the measurement
29 threshold of the raingauges (TB tip size) and the phase of precipitation. Nevertheless, the errors
30 exhibit a relatively constant rate of occurrence throughout the year, a strong diurnal cycle with
31 early and mid-afternoon peaks, a large skew of the rain rates toward low values (< 5 mm/hr), and
32 the highest incidence is in the inner mountain region. This suggests that averaging at the coarse
33 resolution of the PR pixel eliminates the signature of the small-scale complex structure of
34 isolated orographic convection and localized multi-layered clouds and fog that are dominant in
35 the region, and thus explains the high number of FA counts using the point-to-pixel strategy used
36 here.

1 MDs show a strong annual cycle occurring predominantly during the cold season and into
2 the spring with very low values in the summer. The diurnal cycle indicates that MDs appear
3 linked to fog and multi-tiered low-level clouds especially in the inner mountain region, which the
4 TRMM PR products fail to detect due to the ground clutter correction. The high reflectivity
5 sensitivity threshold of the PR can also result in failure to detect weak echoes, thus missing
6 detection of light rainfall. Ground-clutter contamination is not a problem inherent to the TRMM
7 PR alone, but it is rather a general challenge for all space-based radars such as the DPR (Dual-
8 frequency Precipitation Radar) on the GPM satellite. This work took advantage of multiple
9 sources of concurrent and co-located observations to investigate in detail the conditions
10 associated with different types of error, which should be helpful to identify opportunities for
11 improving retrieval algorithms in regions of complex terrain, despite the challenges, particularly
12 at the current spatial resolution. Specifically in the case of surface contamination, special
13 precaution should be taken when strong echoes are observed near the surface, an indication of
14 surface clutter artifacts that should be excluded from rain analysis. Because of the importance of
15 persistent low-level clouds and light rainfall in mountainous regions generally, there is a critical
16 need to develop retrieval strategies that can capture the vertical structure of low-level reflectivity
17 and the associated rainfall in complex terrain. This can be accomplished for instance by
18 integrating operational satellite retrieval algorithms with simple physical models targeting local
19 processes (e.g. Prat and Barros, 2009; Wilson and Barros, 2014).

20 Albeit of low frequency, heavy precipitating events have significant hydrologic impact
21 leading to extreme floods and landslides in the region. Six representative case studies with
22 substantial discrepancies between TRMM and gauge references provide insight into the
23 characteristics of PR rainfall retrieval errors that need to be taken into consideration for
24 applications in complex terrain. The results show that TRMM tends to underestimate small-scale
25 winter storms and embedded convection in the summer, which can be attributed to the averaging
26 effects of NUBF at TRMM PR coarse horizontal resolution as well as misclassification of
27 convective systems as stratiform, especially at large incidence angle. Precipitation from warm
28 season convective systems smaller than the PR footprint is either underestimated or
29 overestimated depending on the size of the system footprint and the depth of active convection.
30 In particular, TRMM tends to underestimate rainfall from embedded convection, and
31 overestimates rainfall from isolated small-scale shallow convection when and where it is
32 detected. Cold-season mixed-phase precipitation (i.e., hail, ice falling through melting layers,
33 etc.) is associated with strong scattering signal from ice crystals and can be misclassified as
34 “certain convective”. Mixed-phase precipitation cannot be estimated by the convective Z-R
35 (reflectivity –rainfall) relationship in the algorithm, leading to the severe overestimation or false
36 alarm errors in the winter and spring seasons.

37 Diagnostic analysis focusing on the characterization of the physical basis of QPE error
38 provides a framework for error source attribution and subsequent correction or mitigation of
39 satellite retrievals generally and can be applied elsewhere. Based on the results presented here,

1 the observing strategy devised for IPHEX placed strong emphasis on documenting the spatial and
2 temporal heterogeneity of rainfall microphysics conditional on time-of-day, prevalent
3 hydrometeorological regime, and topographic and physiographic context (Barros et al., 2014).
4 Special emphasis was placed on the vertical structure of precipitation in the lower troposphere.
5 Analysis of IPHEX results is ongoing.

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1 **Table 1** – Inventory of long-term raingauges in the Pigeon River basin including the Great
 2 Smoky Mountains National Park (GSMNP) in the Southern Appalachians used in this study.

Raingauge	Latitude	Longitude	Elevation (m)	Series
RG001	35.4	-82.91	1156	RG0XX Eastern Ridge
RG002	35.43	-82.97	1731	
RG003	35.38	-82.92	1609	
RG004	35.37	-82.99	1922	
RG005	35.41	-82.96	1520	
RG008	35.38	-82.97	1737	
RG010	35.46	-82.95	1478	
RG100	35.59	-83.07	1495	RG1XX Inner Ridge
RG101	35.58	-83.09	1520	
RG102	35.56	-83.1	1635	
RG103	35.55	-83.12	1688	
RG104	35.55	-83.09	1587	
RG105	35.63	-83.04	1345	
RG106	35.43	-83.03	1210	
RG107	35.57	-82.91	1359	
RG108	35.55	-82.99	1277	
RG109	35.5	-83.04	1500	
RG110	35.55	-83.15	1563	
RG111	35.73	-82.95	1394	RG3XX Western Ridge
RG112	35.75	-82.96	1184	
RG300	35.73	-83.22	1558	
RG301	35.71	-83.26	2003	
RG302	35.72	-83.25	1860	
RG303	35.76	-83.16	1490	
RG304	35.67	-83.18	1820	
RG305	35.69	-83.13	1630	
RG306	35.75	-83.17	1536	
RG307	35.65	-83.2	1624	
RG308	35.73	-83.18	1471	
RG309	35.68	-83.15	1604	RG3XX Western Ridge
RG310	35.7	-83.12	1756	
RG311	35.77	-83.14	1036	

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1 **Table 2** – Contingency matrices for TRMM 2A25 V7 surface rain rate and 10-min raingauge
 2 rain rates for: a) all angles; and b) near-nadir cases. Counts are expressed as a percentage of the
 3 total number of observations. Values in parentheses are for V6. The 10-min time scale is
 4 centered over the time of the satellite overpass during 06/2008 – 05/2011.

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(a)	All angles (RG0XX and RG1XX)			
		Yes	No	Tot.
TRMM PR 2A25	Yes	1.18(1.12)	2.73(3)	3.91(4.12)
	No	0.74(0.71)	95.35(95.17)	96.09(95.88)
	Tot.	1.93(1.83)	98.07(98.17)	100(100)

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(b)	Near-nadir cases (RG0XX and RG1XX)			
		Yes	No	Tot.
TRMM PR 2A25	Yes	2.23(2.01)	2.83(3.12)	5.06(5.13)
	No	1.24(1.28)	93.7(93.59)	94.94(94.87)
	Tot.	3.47(3.29)	96.53(96.71)	100(100)

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1 **Table 3** – Rainfall detection metrics for TRMM 2A25 V7 (V6) compared to RG observations as
 2 a function of time scale (10-, 20-, 30-, 60-min) during 06/2008 – 05/2011. Note the definitions of
 3 the skill scores are provided below. Y indicates positive detection; N indicates no detection.

	Time window (min)												Perfect Score
	10min			20min			30min			60min			
	All	0XX	1XX	All	0XX	1XX	All	0XX	1XX	All	0XX	1XX	
Accuracy ^a	0.97 (0.96)	0.96 (0.96)	0.97 (0.97)	0.96 (0.96)	0.96 (0.96)	0.97 (0.96)	0.96 (0.96)	0.96 (0.96)	0.96 (0.96)	0.95 (0.94)	0.94 (0.94)	0.95 (0.95)	1
FB ^b	1.5 (1.65)	1.7 (1.84)	1.39 (1.55)	1.02 (1.12)	1.05 (1.12)	1.01 (1.12)	0.83 (0.89)	0.83 (0.87)	0.82 (0.91)	0.59 (0.63)	0.56 (0.59)	0.6 (0.66)	1
POD ^c	0.61 (0.61)	0.6 (0.58)	0.61 (0.62)	0.55 (0.55)	0.55 (0.54)	0.55 (0.56)	0.49 (0.49)	0.51 (0.5)	0.48 (0.49)	0.4 (0.4)	0.42 (0.4)	0.39 (0.4)	1
FAR ^d	0.59 (0.63)	0.65 (0.68)	0.56 (0.6)	0.46 (0.51)	0.47 (0.52)	0.45 (0.5)	0.41 (0.45)	0.39 (0.43)	0.42 (0.46)	0.32 (0.36)	0.26 (0.31)	0.36 (0.39)	0
POFD ^e	0.02 (0.03)	0.03 (0.03)	0.02 (0.03)	0.02 (0.02)	0.02 (0.02)	0.02 (0.02)	0.02 (0.02)	0.02 (0.02)	0.02 (0.02)	0.01 (0.02)	0.01 (0.01)	0.01 (0.02)	0
TS ^f	0.32 (0.3)	0.28 (0.26)	0.35 (0.32)	0.37 (0.35)	0.37 (0.34)	0.38 (0.36)	0.37 (0.35)	0.38 (0.36)	0.36 (0.34)	0.34 (0.33)	0.36 (0.34)	0.32 (0.32)	1

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5 ^aAccuracy = $[YY + NN] / Total$

6 ^bFrequency Bias = $FB = [YY + YN] / [YY + NY]$

7 ^cProbability of detection = $POD = YY / [YY + NY]$

8 ^dFalse alarm ratio = $FAR = YN / [YY + YN]$

9 ^eProbability of False Detection = $POFD = YN / [NN + YN]$

10 ^fThreat Score = $TS = YY / [YY + NY + YN]$

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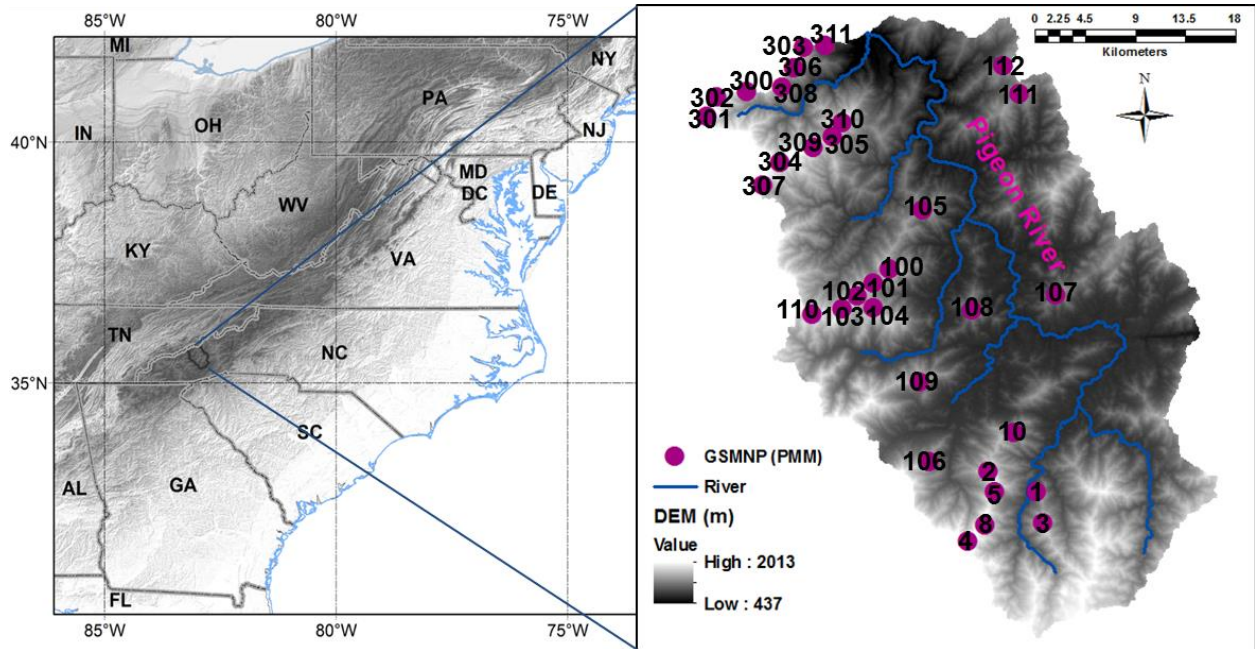
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1 **Table 4** – Classification of TRMM 2A25 reflectivity profiles as a function of the difference (ϵ)
 2 $[\text{RR_TRMM2A25} - \text{RR_RG}]/\text{RR_RG}$ that represents the relative error of the 2A25 estimates
 3 with respect to the raingauge observations. The time-scale of integration is 10-min for RG0XX
 4 and RG1XX and 30-min for RG3XX, which corresponds to the minimum error bias for the
 5 period of record. Bold values correspond to $\epsilon = 0.5$.

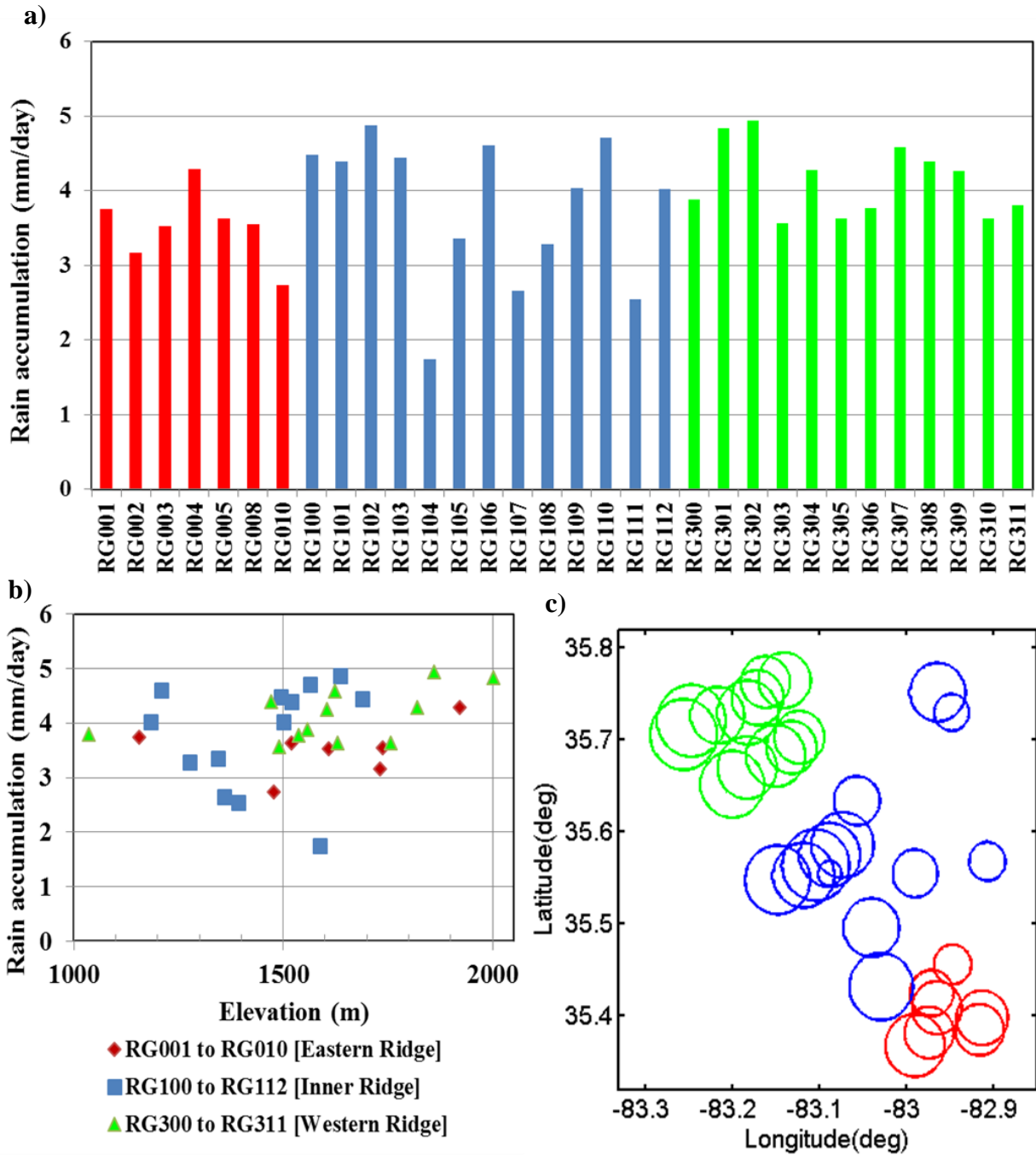
Class	Diff (ϵ) = $[\text{RR_TRMM} - \text{RR_RG}]/\text{RR_RG}$		
	$\epsilon = 0.25$	$\epsilon = 0.50$	$\epsilon = 0.75$
I : $\text{Abs}(\text{Diff}) < \epsilon$	126	237	368
II : $\text{Diff} < -\epsilon$	259	174	70
IIa : $\text{Diff} < -\epsilon$ and $\text{RR_RG} > 7\text{mm/h}$	99	76	45
III : $\text{Diff} > \epsilon$	165	139	112
IIIa : $\text{Diff} > \epsilon$ and $\text{RR_TRMM} > 7\text{mm/h}$	50	43	35
IV : $\text{RR_RG} = 0$ and $\text{RR_TRMM} \neq 0$	863	863	863
V : $\text{RR_RG} \neq 0$ and $\text{RR_TRMM} = 0$	330	330	330
Total	1743	1743	1743

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Figure 1 - Region of study including the Great Smoky Mountains National Park (GSMNP) in the Southern Appalachians. The right panel shows the Pigeon River basin where the raingauges are installed. Note RG0XX, RG1XX, and RG3XX were installed in summer 2007, 2008, and 2009 respectively. Additional raingauges and other instrumentation placed in the region are not shown here [see <http://iphex.pratt.duke.edu>].



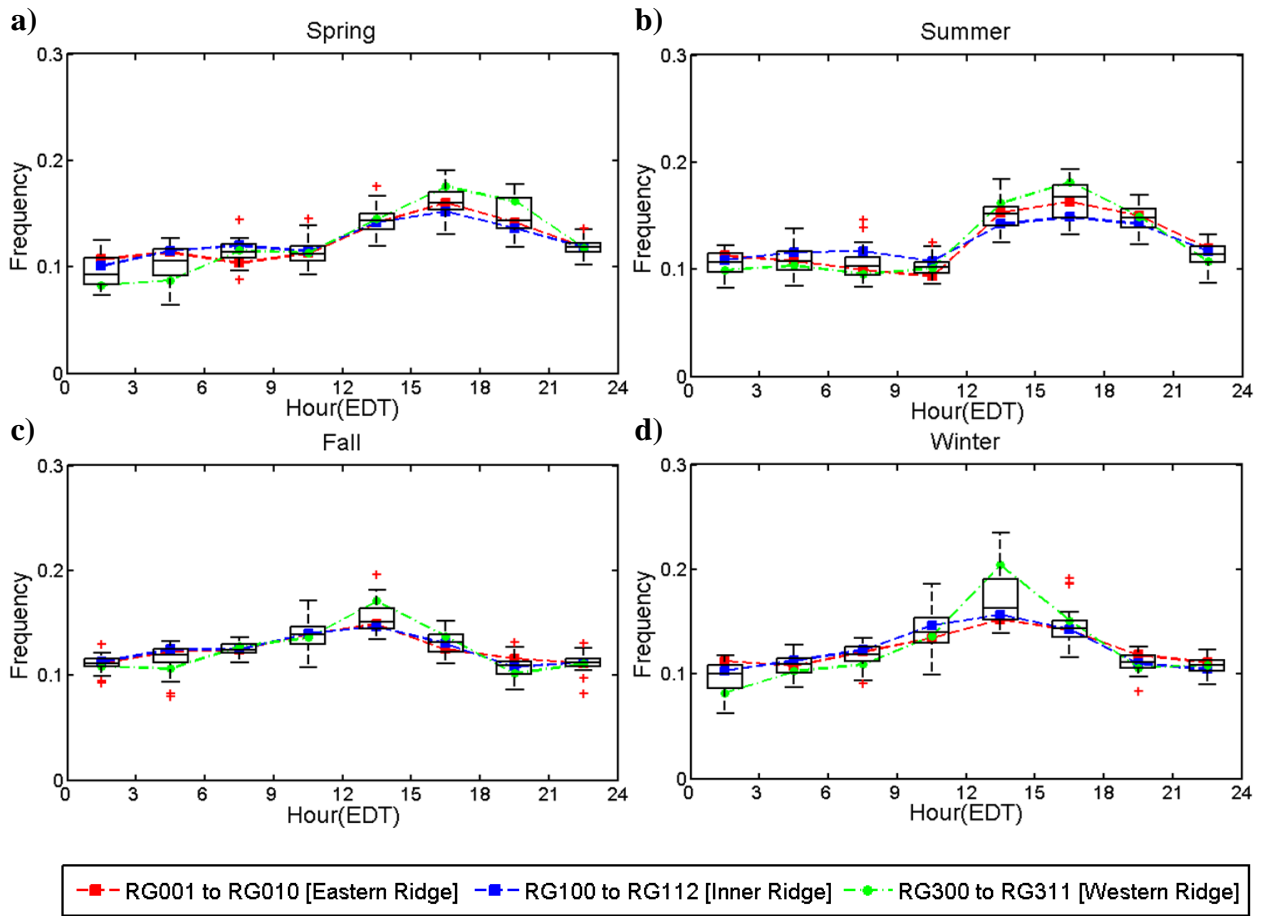
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2 **Figure 2** – a) Average rain accumulation (mm/day) for the raingauges deployed in the
 3 GSMRGN. Average rain accumulation as a function of: b) Elevation. c) Geolocation of each
 4 raingauge with circle size indicating relative magnitude of the daily rain accumulation.

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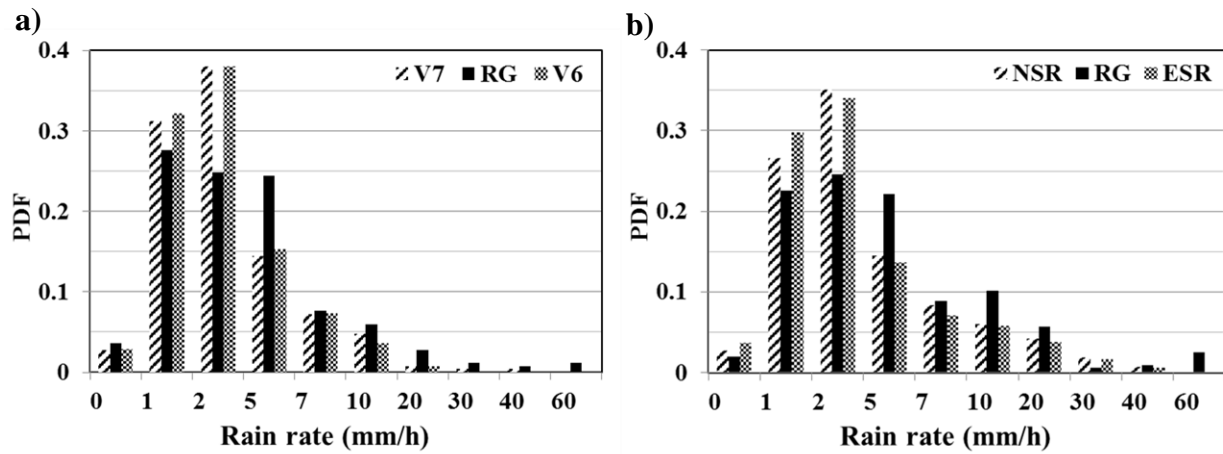
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4 **Figure 3** – Three-hourly diurnal cycle as a function of the season of the year and the raingauge
5 network location (Eastern, Inner, and Western Ridge) for: a) spring (April-May-June), b)
6 summer (July-August-September), c) fall (October-November-December), d) winter (January-
7 February-March).

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2 **Figure 4** – a) Probability distributions of rain rates for V7 and V6 comparison of **non-null**
 3 TRMM 2A25 Near Surface Rain Rate (NSR) estimates and average raingauge rain rates for
 4 **near-nadir pixels** (scanning inclination angles ranging from 0° to 9°) during the period
 5 06/01/2008-05/31/2011; b) Probability distribution of **non-null** TRMM 2A25 V7 surface rain
 6 rate products [Estimated Surface Rain Rate (ESR) and NSR] and average gauge rain rates during
 7 the period 06/01/2008-05/31/2013. Raingauge rain rates are calculated using time-scales of 10-
 8 min (RG0XX and RG1XX) and 30-min (RG3XX) corresponding to the interval centered at the
 9 time of satellite overpasses.

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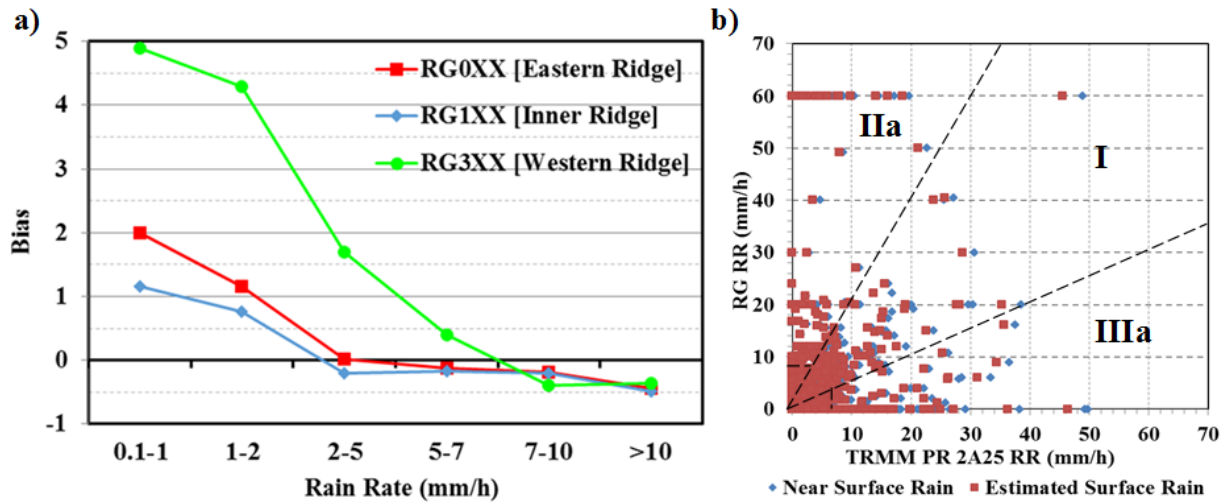
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3 **Figure 5** – a) Bias between TRMM 2A25 V7 NSR and average raingauge rain rates for different
 4 series: RG0XX, RG1XX, and RG3XX (see Table 1); b) Scatterplot for TRMM 2A25 V7 surface
 5 rain rates (NSR and ESR) and average raingauge rain rates during the period 06/01/2008-
 6 05/31/2013. Raingauges rain rates are using a 10-min (RG0XX and RG1XX) and 30-min
 7 (RG3XX) scale centered at the time of the satellite overpasses. Note raingauge measurements
 8 and TRMM profiles classification as described in Table 4 [5 primary categories (I-II-III-IV-V),
 9 and 2 subcategories (IIa-IIIa)].

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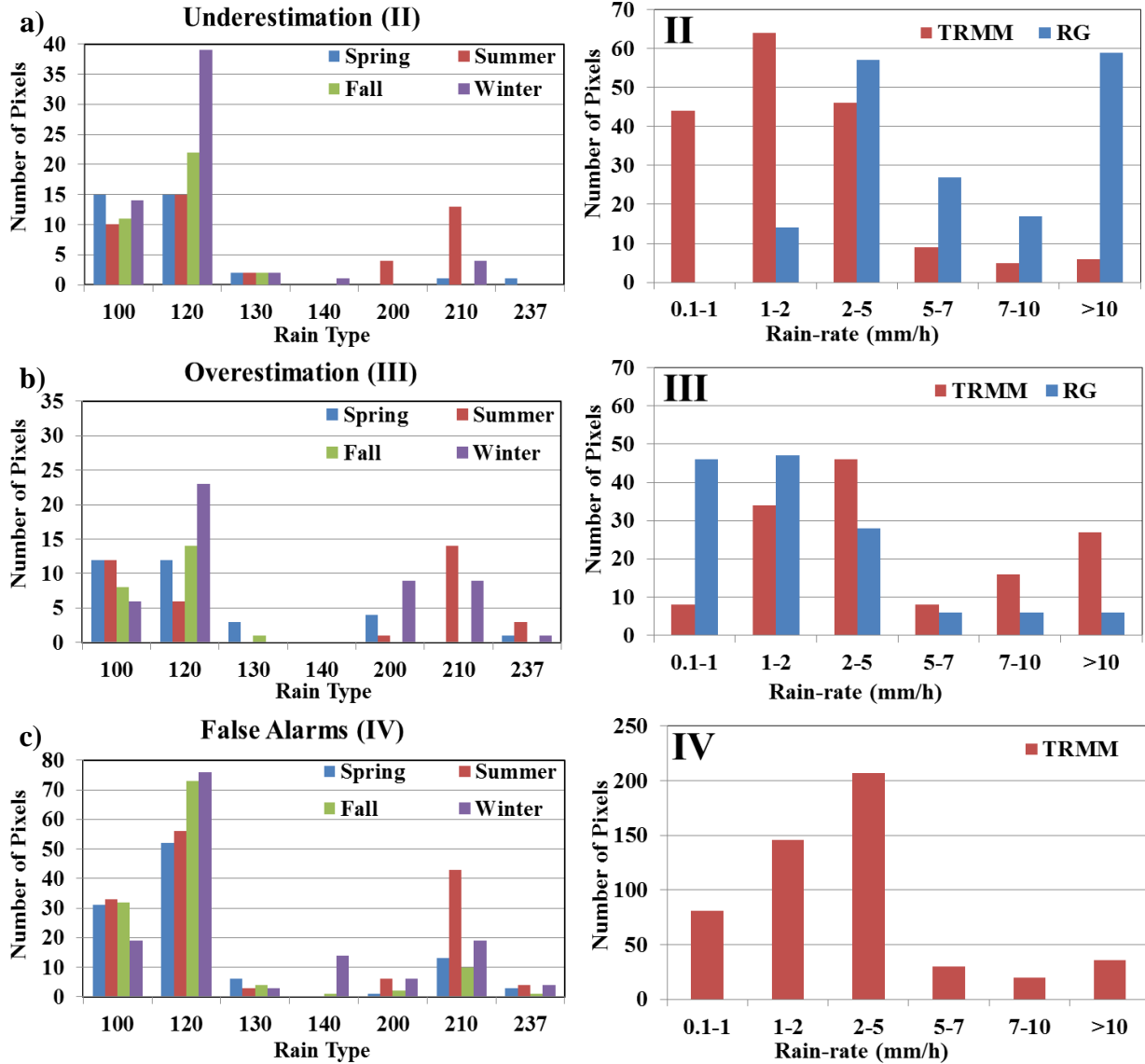
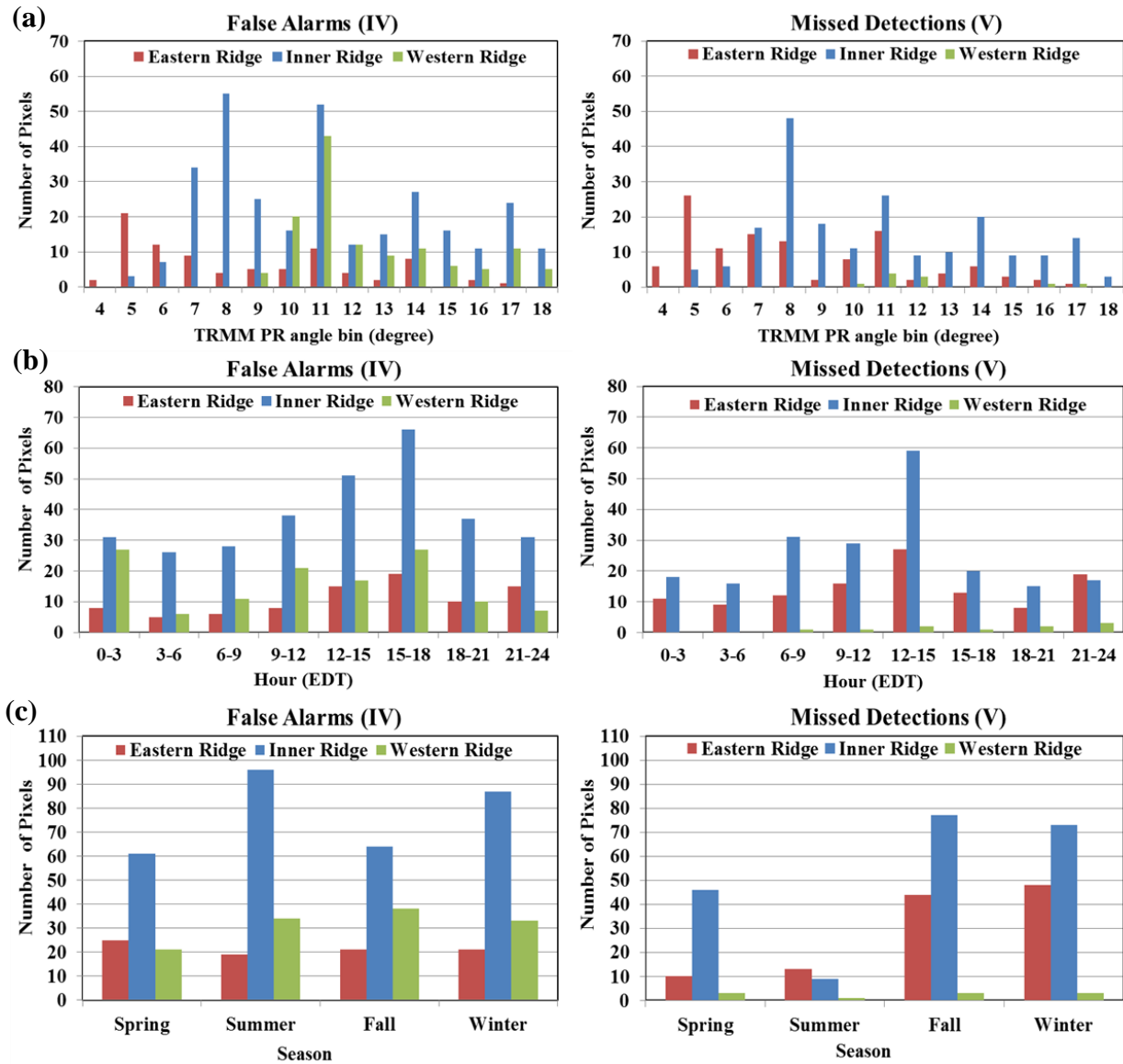
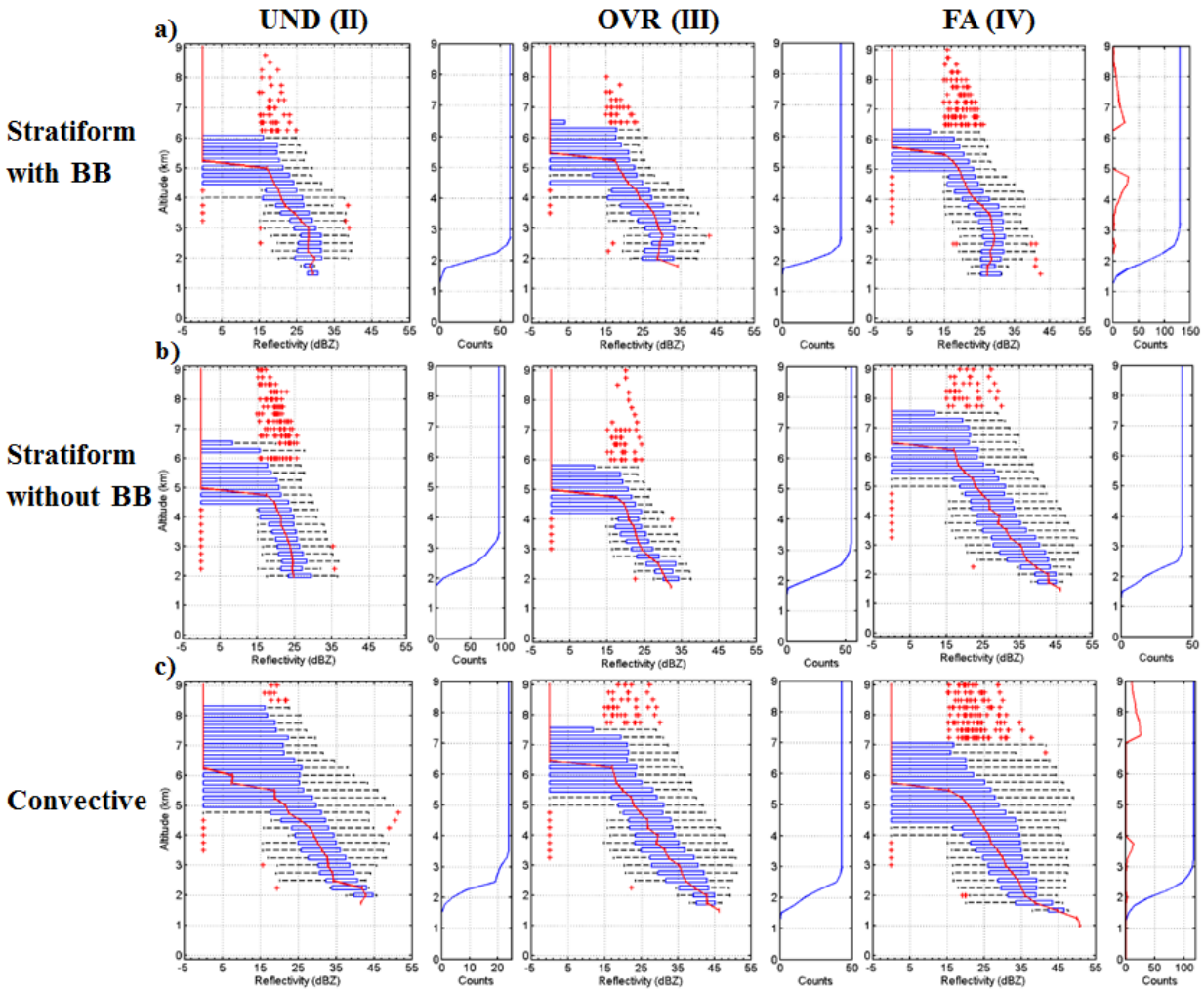


Figure 6 - Histogram of rain type (left panels) and observed RG rain rate and NSR from TRMM (right panels) distributions for the different errors: a) II (UND); b) III (OVR); and c) IV (FA). The error classification is provided in Table 4. The rain type categories correspond to the TRMM 2A23 Rain Type Flag: 100- Stratiform certain, 120- Probably stratiform, 130- Maybe stratiform, 140- Maybe stratiform or maybe transition or something else, 200 & 210- Convective certain, 237- Probably convective. (For further details please see the 2A23 documentation at http://disc.sci.gsfc.nasa.gov/precipitation/documentation/TRMM_README).



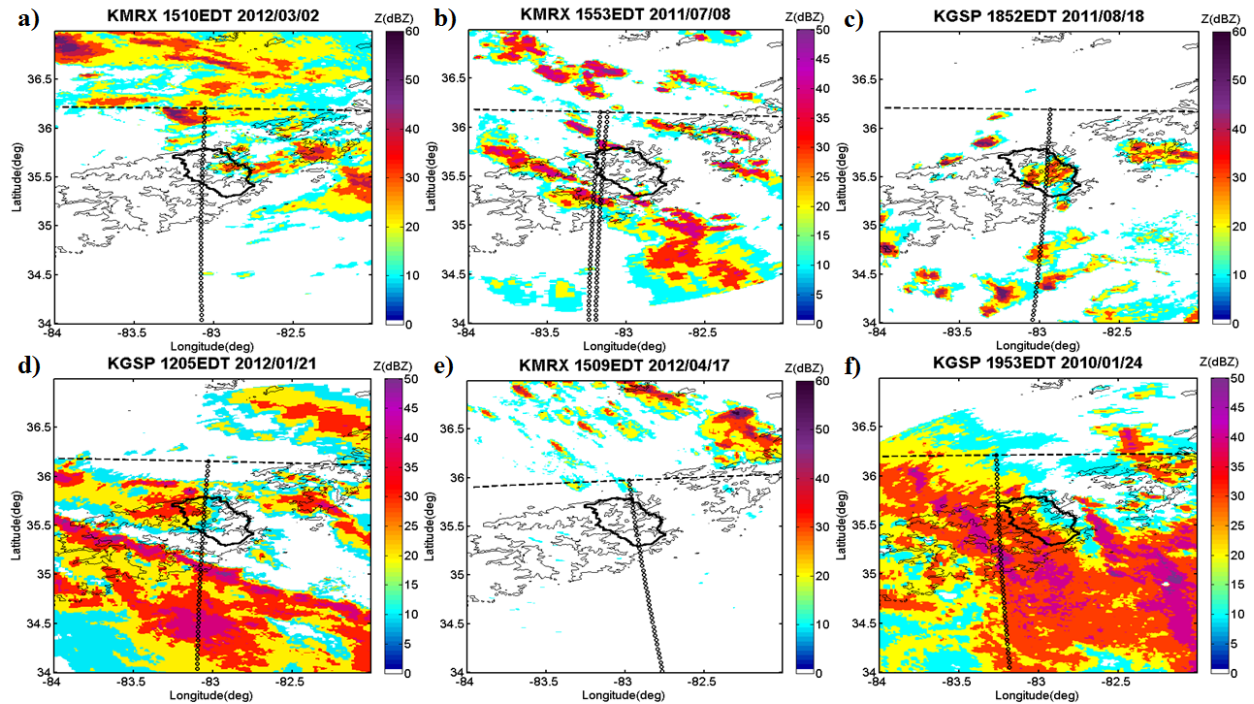
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Figure 7 - Histograms of FA (left panel) and MD (right panel) occurrences as a function of the viewing angle (a), time of the day (b) and season of the year (c). As previously, the colors correspond to raingauges aligned with the eastern (red, RG0XX), western (green, RG3XX) and inner ridges (blue, RG1XX) in the region of study (Fig.1, Table 1).



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2 **Figure 8** - TRMM 2A25 reflectivity profiles for error classes II (UND), III (OVR), and IV (FA):
3 a) Stratiform conditions with BB detected (Rain Type: 100 and 130, Fig. 6); b) Stratiform
4 conditions without BB detected (Rain Type: 120 and 140, Fig. 6); and c) Convective
5 conditions (Rain Type: 200, 210, and 237, Fig. 6). The blue box denotes the interquartile range (IQR)
6 from the lower quartile (25th) to the upper quartile (75th); the median is indicated by the red mark
7 inside the box. The red line connects the median reflectivity at all levels to yield the median
8 reflectivity profile. The two horizontal lines (“whiskers”) extending from the central box
9 represent the ± 1.5 IQR interval. Outliers (points falling out of ± 1.5 IQR) are marked as red
10 crosses. For each error class, the right panel shows the number of observations with height; the
11 red line for error class IV (FA) shows the distribution of outliers with height.

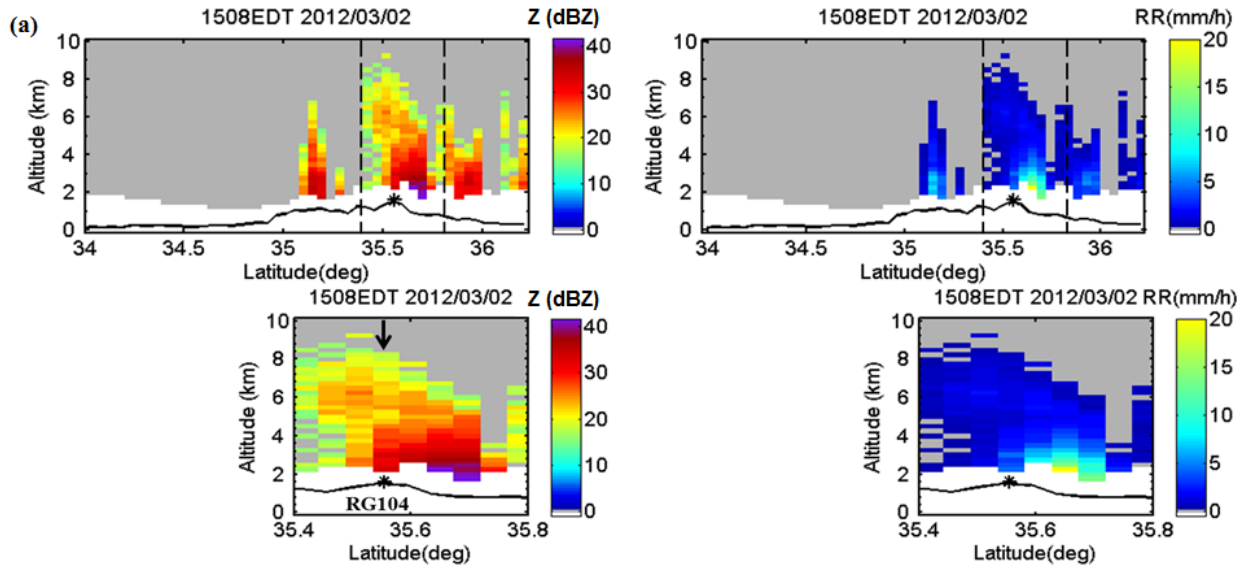
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2 **Figure 9** - Base reflectivity composites from KMRX (Knoxville, TN) and KGSP (Greer, SC)
3 National Weather Service radars corresponding to the overpass times shown in Figures 10-12
4 below. The lines of black circles show the overpass tracks corresponding to the cross-sections in
5 Figures 10-12. The dashed line delimits the northern boundary of TRMM PR swath over the
6 Southern Appalachians, and the 1,000 m terrain elevation contour line and the outline of the
7 study region (the Pigeon River basin) are marked in solid black for reference.

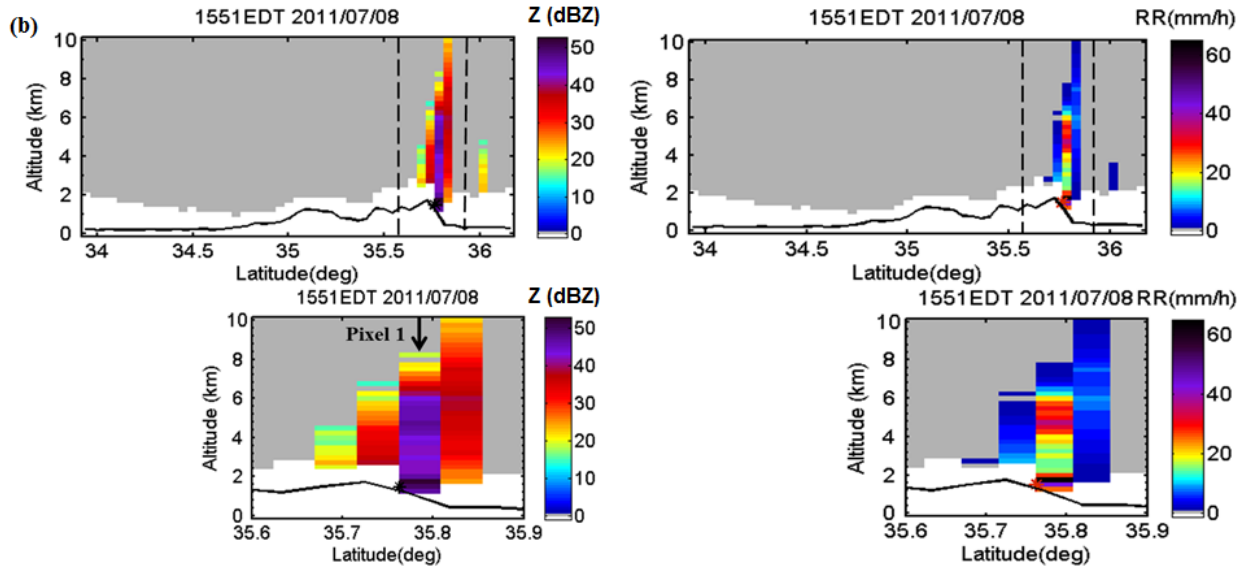
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2 **Figure 10** - Cross section of reflectivity (Z) and rain rate estimates (RR) from TRMM 2A25 for
3 three underestimation cases: a) 15:08 EDT on 2 March 2012; and for two different cross-sections
4 at 15:51 EDT on 8 July 2011 (**b, c**). The top row shows the overpass cross-section. The bottom
5 row shows the cross-section between the two dashed vertical lines in the top rows. Asterisks
6 denote the position of the raingauges as marked, and the color in the right panel is consistent
7 with the measured rain-rate. The black arrow identifies the PR profile used to make the error
8 determination. Ground clutter flags are shown in white. The black continuous line represents the
9 topography.

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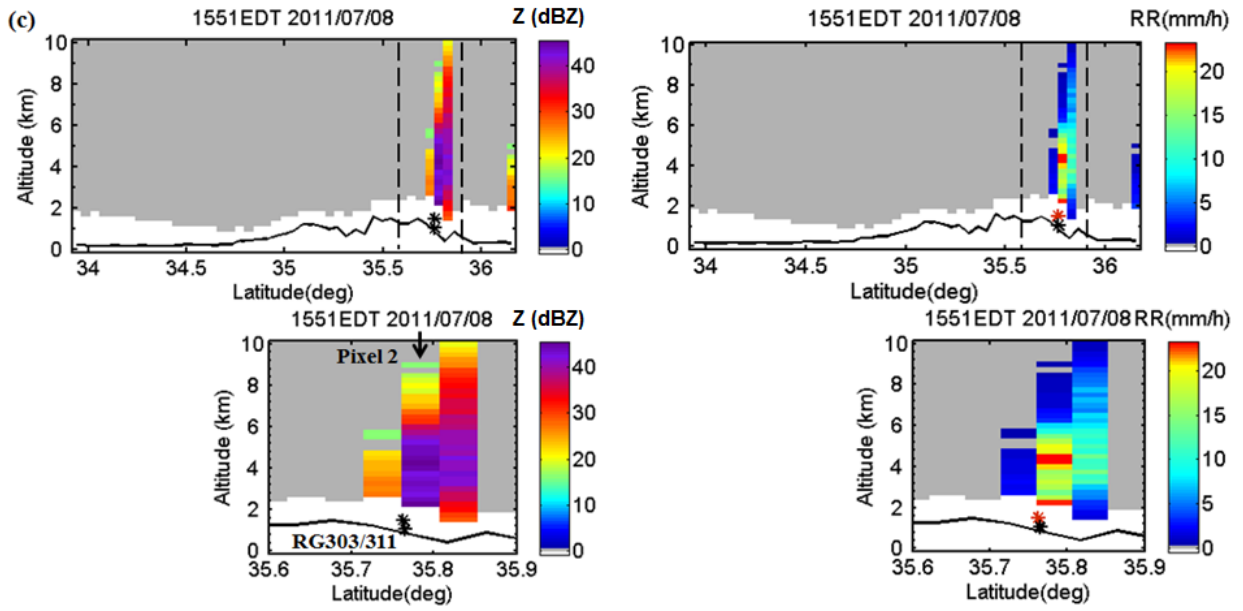
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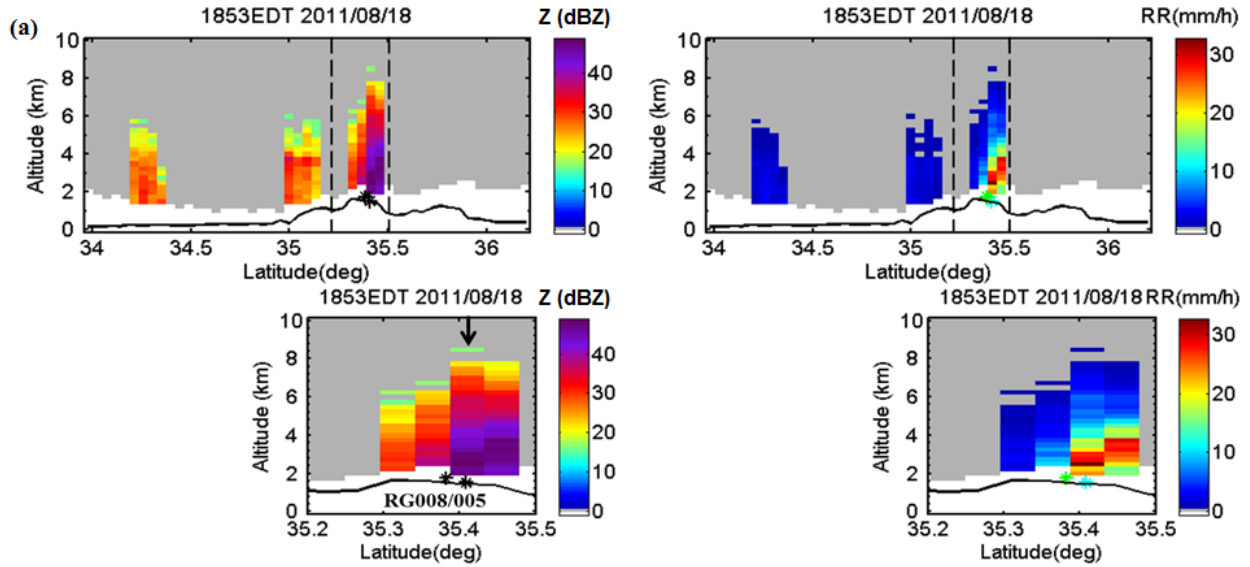
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2 **Figure 11** - Cross section of reflectivity (Z) and rain rate estimates (RR) from TRMM 2A25 for
 3 three overestimation cases, respectively: a) 18:53 EDT on 18 August 2011; b) 12:05 EDT on 21
 4 January 2012; and c) 15:09 EDT on 17 April 2012. The top row shows the overpass cross-
 5 section. The bottom row shows the cross-section between the two dashed vertical lines in the top
 6 row plots. Asterisks denote the position of the raingauges as marked, and the color in the right
 7 panel is consistent with the measured rain-rate. The black arrow identifies the PR profile
 8 corresponding to the 2A25 used to make the error determination. Ground clutter flags are shown
 9 in white. The black continuous line represents the topography.

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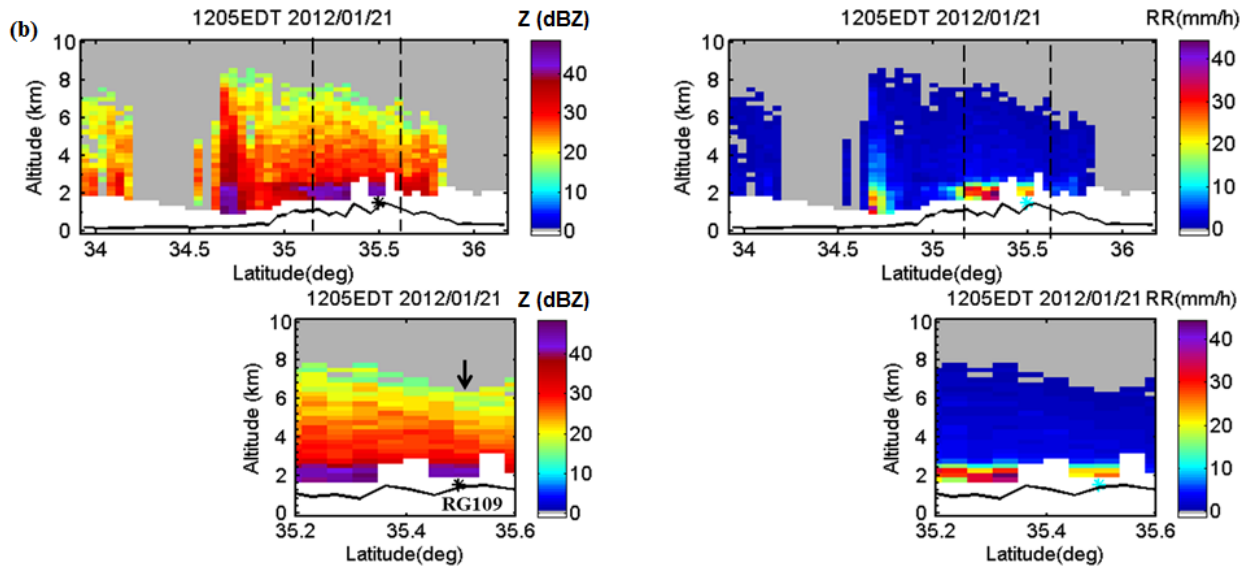
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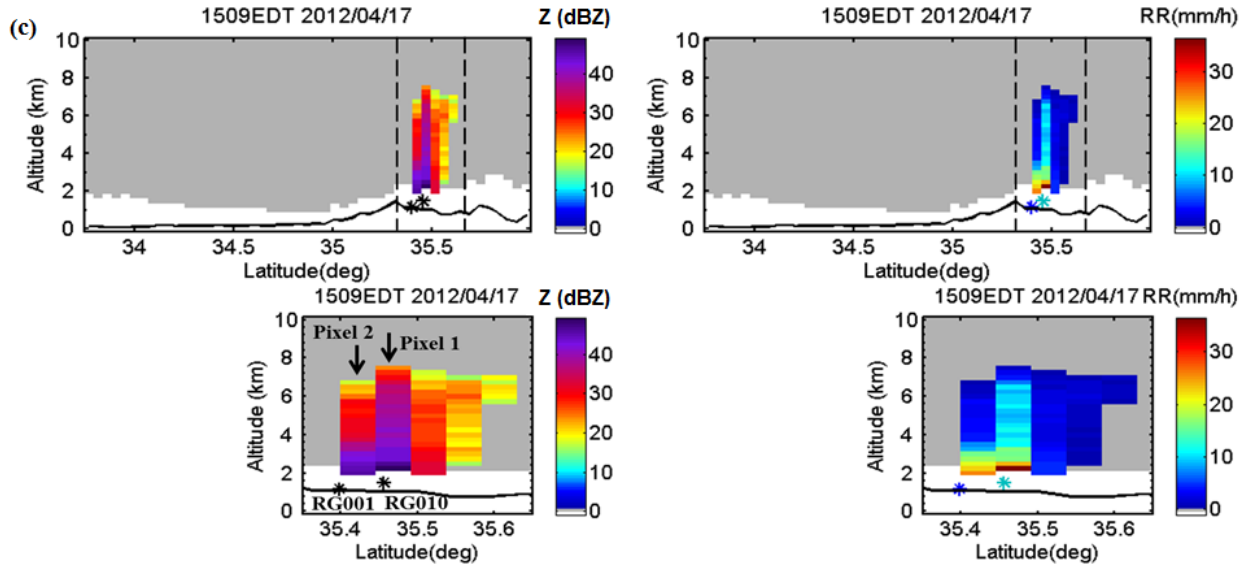
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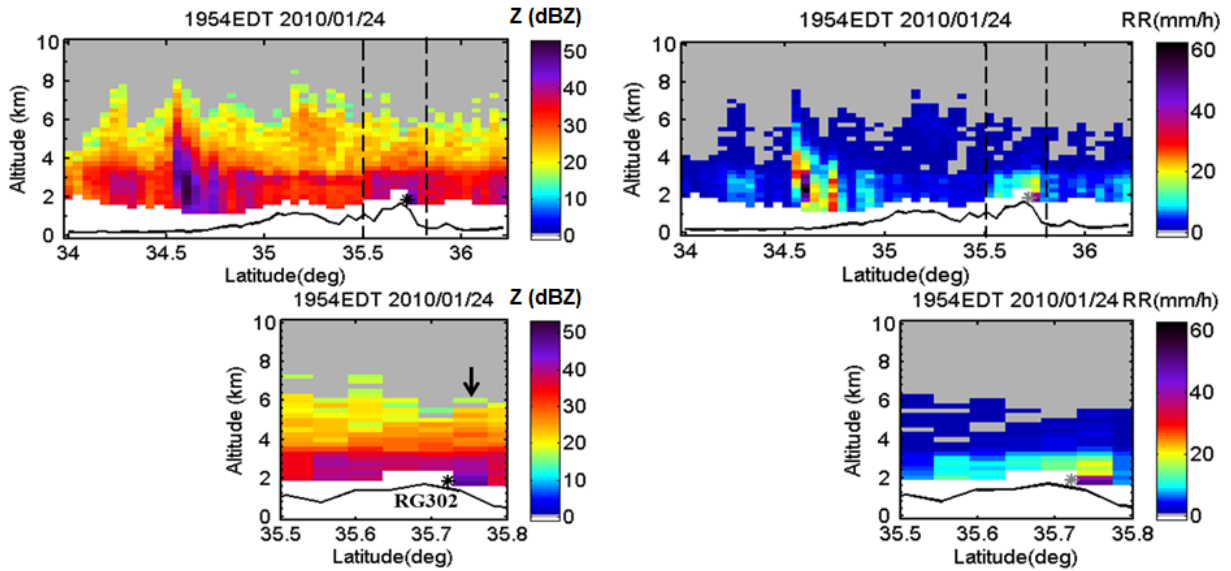
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2 **Figure 12** - Cross section of reflectivity (Z) and rain rate estimates (RR) from TRMM 2A25 for
 3 a selected case of incorrect False Alarm determination at 19:54 EDT on 24 January 2010. The
 4 top row shows an overpass cross-section. The bottom row shows the cross-section between the
 5 two dashed vertical lines in the top row plots. Asterisks denote the position of RG302, and the
 6 color in the right panel is consistent with the measured rain-rate. The black arrow identifies the
 7 PR profile used to make the error determination. Ground clutter flags are shown in white. The
 8 black continuous line represents the topography.

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