

**Measuring and  
modelling  
soil–vegetation  
feedbacks**

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# Measuring and modelling water related soil–vegetation feedbacks in a fallow plot

**N. Ursino<sup>1</sup>, G. Cassiani<sup>2</sup>, R. Deiana<sup>3</sup>, G. Vignoli<sup>4</sup>, and J. Boaga<sup>2</sup>**

<sup>1</sup>Nadia Ursino, Department ICEA, University of Padova, Padova, Italy

<sup>2</sup>Giorgio Cassiani, Jacopo Boaga Department of Geosciences, University of Padova, Padova, Italy

<sup>3</sup>Rita Deiana, Department dBC, University of Padova, Padova, Italy

<sup>4</sup>Giulio Vignoli, Department of Geoscience, HydroGeophysics Group, Aarhus University, Aarhus, Denmark

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Correspondence to: N. Ursino (nadia.ursino@unipd.it)

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## Abstract

Land fallowing is one possible response to shortage of water for irrigation. Leaving the soil unseeded implies a change of the soil functioning that has an impact on the water cycle. The development of a soil crust in the open spaces between the patterns of grass weed affects the soil properties and the field scale water balance. The objectives of this study are to test the potential of integrated non invasive geophysical methods and ground-image analysis and to quantify the effect of the soil vegetation interaction on the water balance of a fallow land at the local and plot scale.

We measured repeatedly in space and time local soil saturation and vegetation cover over two small plots located in southern Sardinia, Italy, during a controlled irrigation experiment. One plot was left unseeded and the other was cultivated. The comparative analysis of ERT maps of soil moisture evidenced a considerably different hydrologic response to irrigation of the two plots. Local measurements of soil saturation and vegetation cover were repeated in space to evidence a positive feedback between weed growth and infiltration at the fallow plot. A simple bucket model captured the different soil moisture dynamics at the two plots during the infiltration experiment and was used to estimate the impact of the soil vegetation feedback on the yearly water balance at the fallow site.

## 1 Introduction

The interaction between soil, water and vegetation begins below ground where the roots grow if enough soil moisture and nutrients are available, creating preferential infiltration flow paths and providing access to water and nutrients to the plant that will grow above ground. Vegetation type diversity, especially in arid zones may be ascribed to differences in the way of exploiting subterranean resources and differences in root system morphology (Cody, 1986; Casper and Jackson, 1997; Schenk and Jackson, 2002). Then the interaction continues above the soil surface where the shoots and the

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leaves shadow the soil and limit the evaporation while transpiration begins. Vegetation reduces the soil moisture content particularly in the hot season, but it also enhances the soil hydraulic conductivity with its root apparatus (Gish and Jury, 2004; Zimmermann et al., 2006), thus helping to replenish the subsoil water storage and creating a positive feedback system (Franz et al., 2011). When a spontaneously growing species establishes on bare land, water related soil–vegetation feedbacks are often invoked to motivate field scale soil moisture and vegetation patterns, describe patterns related to eco-hydrological processes and evaluate the associated water budget. Water-related feedbacks between the vegetation growth and the water fluxes may have a major impact on the soil moisture balance (Kefi et al., 2007), depending on climate (Baudena et al., 2009; Rietkerk et al., 2011), plant physiology and their survival strategy under water stress (Kurc and Small, 2004, 2007; Ursino, 2007, 2009).

Agricultural systems provide an opportunity to study the relevant plant–water relations and soil–vegetation feedbacks in a more controlled environment than other natural systems (Jackson et al., 2009). The interplay between soil and vegetation alters locally the hydrologic cycle and this is a main concern in areas where the water scarcity may become a limiting factor to agricultural production. In those countries where water is scarce, increasing root depth and local infiltration, and reducing evaporation of water from soil are key tasks (Marris, 2008). The interaction between soil and vegetation in rainfed agriculture is crucial to determining the partitioning of rainfall into runoff and infiltration, the connectivity of soil moisture patterns, the recharge of water bodies and ultimately solute transport that are hot topics in understanding the ecohydrological effects of human actions on landscape (Jackson et al., 2009). Repeated measurements of local soil moisture content in space and time can illuminate soil moisture paths, and clarify the nature of relevant spatial processes in catchment hydrology (Grayson and Bloeschl, 2000). Repeated measurements of soil moisture and biomass density during an irrigation experiment allowed us to detect substantially different soil moisture and vegetation paths in fallow and cultivated plots.

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Image analysis is a superior choice for detecting relative change of ground cover, since it facilitates extensive data collection, and reduces human bias by limiting human judgments (Sadler et al., 2010). Image analysis has been successfully applied to ground images, with substantially different objectives, including the classification of soil structures (Gimmi and Ursino, 2004), soil texture (Graham et al., 2005, 2010) and soil cover (Laliberte et al., 2007). The whole spectrum of light may be used to analyze the vegetation responses to external stimuli (Chaerle and Van Der Straeten, 2001). Visualization techniques to monitor plant health include fluorescence (Bushman and Lichtenthaler, 1998; Oxborough, 2004), thermal (Alchanatis et al., 2009; Meron et al., 2010), magnetic resonance and reflectance (Penuelas and Filella, 1998), but among all these techniques, reflectance imaging is the most easily and cost-effectively achievable one, and a customer grade color digital camera offers a low-cost alternative to spectroscopy. Visual Image Analysis (VIA) was used here to repeatedly detect ground cover and to relate local biomass density to soil moisture dynamics in a fallow plot sparsely covered by grass weed.

Non-invasive techniques, and particularly ground-penetrating radar (GPR) and electrical resistivity tomography (ERT) provide data at the scale and resolution necessary to understand the hydrological processes of the topsoil. The use of these techniques has been increasingly focused on their ability to measure, albeit indirectly, changes in moisture content (Binley et al., 1996; Strobbia and Cassiani, 2007; Deiana et al., 2008; Vanderborght et al., 2013) and solute concentration (Cassiani et al., 2006). Geophysical inspection was coupled here to local measurements of soil saturation to be obtained by TDR (Roth et al., 1990), in order to quantify relevant hydrological processes related to vegetation patterns.

In our study, the response of the soil–vegetation system during an irrigation experiment was captured by plot scale maps of the soil moisture variability obtained by ERT. The interest on the transient behavior of the flow field following irrigation, derives from the comparison of the hydrological response to irrigation of two adjacent plots of an agricultural site located in southern Sardinia, where infiltration, runoff and water storage

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appeared significantly different. Sardinia has a climate characterized by water deficit at most altitudes during summertime (ARPAS, 2011, 2012). One of the experimental plots was left unseeded for a year and was found barely covered by grass weed at the time of the experiment. The other one was cultivated. Cassiani et al. (2012) ascribed the different behavior of the two plots to the different interaction between soil and vegetation envisioning the possibility that feedbacks between water flow and vegetation growth could come into play. The fallow plot had a crusty appearance, and was dry at the surface, evidently as the result of evaporation from the top layer. The soil in the vegetated plot appeared much wetter at the surface likely due to the shade provided by the vegetation against direct sunlight. Unlike those of the cultivated plot, the deeper soil layers of the bare plot seemed to be wet before irrigation. New experimental data and a reinterpretation of previously published data are presented here. The hydrological response of the fallow plot is discussed with major focus on the soil vegetation interaction and the water budget. Crucial water related soil–vegetation feedbacks are often conjectured and rarely quantified by dedicated experiments. Coupling hydrological and biological databases is a promising way to test ecohydrological modelling concepts (Garre et al., 2012). Vegetation cover and soil moisture were repeatedly measured at local scale by VIA and TDR, to provide hints on the occurrence of soil vegetation feedbacks on fallow land and further discuss their relevance in terms of yearly average water balance.

## 2 Methods

### 2.1 Experimental setup

A four days monitoring following an irrigation test was performed at an agricultural experimental farm located in Sardinia, Italy, as part of the EU-FP7 CLIMB project (Ludwig et al., 2010), focused on the analysis of climate change impact on the hydrology of Mediterranean basins. The irrigation lasted for one night (approximately 8 h) with a total of 42 mm of applied artificial rainfall, on both plots.

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The experiment took place at the San Michele farm near Ussana, in the Rio Mannu Catchment (Southern Sardinia). The basin ranges in elevation from 62 to 842 m a.s.l. (meters above the sea level) with an average of 295.5 m a.s.l. The basin is mainly covered by crop fields and grass-land, while only a small percentage of its area is occupied by forests in the south-eastern part of the basin. The farm area has a gentle topography and is part of the Campidano plain. The soils in the area are brown soils, regosols and vertisols with outcrops of marls, sandstones and conglomerates. The floodplain is characterized by alluvial soils, predominantly gravelly or sandy gravelly.

The island of Sardinia has a climate characterized by a water deficit at most altitudes. In the south-eastern part of Sardinia where Ussana is located, the water deficit is maximum in summer while the soil moisture availability is at its maximum in wintertime. The hydrological regime is characterized by wet periods from October to April, where more than 90 % of the rainfall is accumulated, and very dry summers (May–September). The yearly average temperature is 16 °C. And the effective soil moisture availability ranges from 100 % of the field capacity during winter to 0–10 % in summertime (ARPAS, 2011, 2012).

The controlled irrigation experiment was undertaken in May 2010. During the period October 2009–September 2010, the cumulate rainfall at the site was 300 mm, and the temperature ranged from 10 to 30 °C.

### 2.2 Plot scale soil moisture measurements

Using three ERT lines the detailed soil moisture response of the system from the controlled irrigation was captured. Both bare and cultivated plots were irrigated with the same amount of water. Each ERT line is composed of 24 electrodes spaced 20 cm, for a total length of 4.6 m each, and an expected depth of investigation not exceeding 1 m. Two lines were left in place throughout the experiment till four days after irrigation ended in the bare plot and one was left in place in the cultivated plot. Time-lapse measurements were taken periodically, using a dipole-dipole skip 0 scheme and full acquisition of reciprocals to estimate the data error level (see e.g. Monego et al., 2010).



and “All of the existing color image segmentation approaches are, by nature, ad hoc.” (Cheng et al., 2001).

We used the IDL7.1 a programming language developed by ITT (2009) for making automated cover detection by k-means (MacQueen, 1967) and secondly to estimate the vegetation greenness on rangeland (that we use here to evaluate the goodness of the estimate of local vegetation density). Each  $i$ th image was processed in order to obtain NC complementary binary images  $M_{i,j}$  that are referred to as masks, with  $j$  ranging from 1 to the number of clusters NC that was used to parameterize the  $k$  means algorithm. The optimum number of cluster NC is site specific. A reference object of interest (e.g. a leaf) is chosen in each picture. The targeted mask  $M_{i,t}$  that contains the reference object is used to evaluate the vegetation cover  $CC = \langle M_{i,t} \rangle$  as the average ( $\langle \rangle$ ) of the mask’s pixel values. Furthermore, the vegetation greenness is evaluated as a function of the average normalized red  $r$ , green  $g$  and blue  $b$ .

Borzuchowski and Schulz (2010) revise a list of vegetation spectral indices to describe plant eco-physiological parameters. None of them can be estimated in the visible spectrum, due to its restricted range of reflectance. However, we adapted the vegetation spectral index concept to the VIA data and defined the following greenness index

$$F = \frac{\langle r \cdot M_{i,t} \rangle - \langle g \cdot M_{i,t} \rangle}{\langle r \cdot M_{i,t} \rangle + \langle g \cdot M_{i,t} \rangle} \quad (1)$$

where  $\langle r \cdot M_{i,t} \rangle$  and  $\langle g \cdot M_{i,t} \rangle$  are the average value of the normalized red and green of the non zero pixels in the targeted mask  $M_{i,t}$  (the one that contains the reference object and is used to estimate the vegetation cover). Since the vegetation cover is discontinuous but homogeneously green at the plot scale and at the time of the experiment, we expect  $F$  to be quite homogeneous, unless the targeted mask contains intermixed soil and vegetation objects and in this sense, we used  $F$  to estimate the reliability of the segmentation procedure.

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## 2.5 Water balance model

We set up a simple bucket model to address the two way interaction between plants and soil in water controlled ecosystems according to the experimental evidence provided by ERT, TDR and VIA. Even though the focus was on the fallow plot, we used the model to reproduce also the soil moisture dynamics of the adjacent cultivated plot during the irrigation experiment for comparison (Fig. 1).

Kurc and Small (2004, 2007), found that evapotranspiration is largely correlated with surface soil moisture, not to root zone soil moisture, and suggested that evaporation is dominant over transpiration within the top 15 cm of soil whereas evaporation has a minor influence on soil moisture below about 15–20 cm. This tenet represents a common assumption of many crop models where, according to a two layer approach (Mailhol et al., 1997), after small rain events a shallow upper soil layer (USL) acts as a temporary storage for water that is entirely returned to the atmosphere through soil transpiration.

Excess rainfall leaching from the USL supplies a deeper reservoir that we refer to as the deep soil layer (DSL) where roots have exclusive access to soil moisture leading to transpiration even when the upper soil layer is empty. According to our interpretation of the experimental results, the growth of the vegetation is associated to the formation of macroporosity in the USL leading to a local increase of hydraulic conductivity (soil–vegetation feedback) and leakage of excess water into the DSL even if the USL is poorly conductive (crusty). In absence of vegetation we do not expect any water flux to take place at the interface between the two layers due to the presence of the sealing crust. We identify the USL's depth with  $H_u = 100$  mm and the DSL's depth with  $H_d = 500$  mm, according to the root depth estimated by Cassiani et al. (2012), and the effective saturation of the two layers with  $S_u$  and  $S_d$  respectively (Fig. 2).

The daily water balance within the USL is expressed by the following differential equation

$$\frac{\partial \theta}{\partial t} = n \cdot \frac{\partial S_u}{\partial t} = \frac{1}{H_u} \cdot (P + I - RO - E - L_u) \quad (2)$$

where  $\theta$  is the soil moisture content,  $n = 0.4$  is the soil porosity,  $P$  is the daily precipitation,  $I$  is the irrigation, and RO is surface runoff. The evaporation  $E$  was evaluated with the dual crop coefficient approach (Allen et al., 1998),

$$E = ET_0 \cdot [K_b \cdot K_r \cdot (1 - CC)] \quad (3)$$

5 where  $ET_0$  is the reference evapotranspiration evaluated using the Penman–Monteith equation,  $K_b = 1$  is the basal crop coefficient,  $K_r$  is the evaporation reduction coefficient linearly decreasing from 1 to 0 with the USL's saturation when the soil water content is  $\theta_{WP} < \theta < 0.5 \cdot \theta_{FC}$ ; where  $\theta_{FC} = 0.28$  is the soil moisture content at field capacity and  $\theta_{WP} = 0.1$  is the soil moisture content at wilting point. Excess water percolates into the  
10 deeper soil layer leading to the leakage  $L_u$  unless the soil is completely bare.

In Eq. (3) CC is the vegetation cover that we estimated by VIA.

The daily soil moisture balance within the DSL is expressed by the following differential equation

$$\frac{\partial \theta}{\partial t} = n \frac{\partial S_d}{\partial t} = \frac{1}{H_d} \cdot (L_u - T - L_d) \quad (4)$$

15 where the transpiration  $T$  evaluated according to the dual crop coefficient approach (Allen et al., 1998) as

$$T = ET_0 \cdot [K_b \cdot K_s \cdot CC]. \quad (5)$$

The stress coefficient  $K_s$  is a linear function of the DSL's saturation between the readily available soil water in the root zone RAW and the total available soil water in the root  
20 zone TAW. According to Allen et al. (1998) we set

$$TAW = (\theta_{FC} - \theta_{WP}) \cdot H_u \quad (6)$$

and

$$RAW = \rho \cdot TAW \quad (7)$$

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with  $p = 0.3$  in the cultivated plot, and  $p = 0.7$  in the fallow plot (partially covered by grass weed). Leakage out of the control volume  $L_d$  may be reasonably neglected under water scarcity conditions (Keating et al., 2002; Zhang et al., 2001).

### 3 Results

#### 3.1 Estimate of vegetation cover by VIA

Repeated measurements in space of the vegetation cover CC were obtained by VIA. The optimum number of cluster NC was chosen in order to achieve positive and homogeneous estimates of the vegetation greenness  $F$  (Fig. 3, right panel. We observed that when  $NC = 2$  (the objects are vegetation and soil) the vegetation cover may be over-estimated with respect to the result obtained with a larger number of clusters (Fig. 3, left panel, bold circles) and if pixels belonging to the soil class are classified as vegetation,  $F$  varies significantly switching from negative to positive values, meaning that the segmentation outcome is unreliable. Further increasing the number of clusters NC from 3 to 4 May induce an error in the evaluation of the vegetation cover due to the fact that the pixels belonging to the vegetation class, result split into subclasses of slightly different color, and this results in an underestimate of the actual vegetation cover in few cases (Fig. 3 left panel, open circles). Figure 3 (right panel) shows that, when  $NC = 3$  and 4,  $F$  varies less, indicating that objects belonging to the targeted mask could be more homogeneous and belonging to the “vegetation class” as we would expect. For these reasons we set  $NC = 3$  and estimated that the vegetation cover varies from point to point ranging between 0 and 0.4. The estimate of CC obtained with different color representation (e.g. IHS, not shown here) was consistent with the results presented in this section.

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## 3.2 Observed soil moisture dynamics at the plot scale

Two perpendicular ERT lines (NA and NB) were placed in the fallow plot and measurements were taken repeatedly over time before and after the irrigation experiment. The background ERT images (collected on 19 October 2012 – see Fig. 4a) shows a profile where a very resistive soil layer, about 20 cm thick and corresponding to a visually apparent crust of dry material, overlies a much more electrically conductive subsoil. This is in sharp contrast with the ERT profile acquired on the nearby cultivated plot (Fig. 4b) where the presence of vegetation cover maintains a higher moisture content (and electrical conductivity) in the top soil, whereas vegetation depletes the moisture content of the deeper layer where the roots exerts their suction. This result indicates that in the fallow plot vegetation shadowing may be neglected, thus the upper soil layers are exposed to significant evaporation. Following a minor rainfall event (13 mm) the night of 19–20 May 2010 and the irrigation experiment the night of 21–22 May 2012 (42 mm), no major change in electrical resistivity was observed in this fallow plot, as opposed to the dramatic change observed in the nearby vegetated field (see Cassiani et al., 2012 for a thorough discussion), leading to the conclusion that the majority of the irrigated (and rainfall) water must have resulted mainly in runoff, observable (but not measured) on the dirt road separating the vegetated and fallow fields. While this conclusion essentially hold, a detailed analysis of resistivity changes based on a ratio inversion approach (see e.g. Cassiani et al., 2006) reveals the details of the subtle changes caused by irrigation to the resistivity patterns of the subsoil in the patchy plot. The results along lines NA and NB, thus coming from totally independent measurements, are perfectly consistent with each other and are shown in Fig. 5. From these figures it is apparent that (a) the natural rainfall, consisting of roughly 13 mm and occurred during the night between 19 and 20 May 2010, causes essentially no changes in the electrical resistivity profiles (see Fig. 5). We can conclude that nearly the entire precipitation must have resulted in surface runoff, with direct evaporation from local ponding in the field and along the dirt road; (b) the irrigation experiment in the night be-

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in moisture content after rainfall or irrigation. Note that the shorter sondes (32 cm) on the contrary show an increase in moisture content after irrigation, but as discussed above this resolution may not be achievable by the employed electrode system (the electrode spacing is 20 cm). If the moisture content in the top 50 cm is practically unchanged (Fig. 6), we can conclude that a resistivity change is likely to be caused by a decrease in pore water conductivity due to the infiltration of fresher irrigated water. This “new” water in turn pushes down the existing pore water and a mixture of old and new water reaches deeper zones, as apparent in Fig. 5.

Figure 7 shows a comparison between the location of the individual plants along the profiles and the time – lapse images along the ERT line NA, particularly the one relevant to the morning after the end of irrigation. There is a clear correlation between the location of major changes (especially on the right-hand side of the profile) and the plant location. Note however that this analysis is neglecting the 3-D effects that are possibly linked to the location of patchy vegetation off the individual ERT lines.

### 3.3 Feedbacks between vegetation growth and soil moisture dynamics

In order to get more evidence on the key interrelations between the spatially variable soil moisture and vegetation density, in Fig. 8 we compared the repeated measurements of vegetation cover obtained by VIA (with  $NC = 3$ ) with the corresponding measurements of the soil saturation obtained by portable TDR. After the small rainfall event the soil saturation of the upper 20 cm thick soil layer was measured by TRASE. The soil saturation appeared to be not at all correlated with the vegetation cover (Fig. 8, left panel).

In the three days following the irrigation, the soil saturation was measured using 32 cm long probes. Shortly after irrigation the vegetation cover and the soil saturation were positively correlated (Fig. 8,  $t = t_1$ ), but the correlation was very weak. Already one day after irrigation (Fig. 8,  $t = t_2$ ), the results seem to indicate that redistribution took place because the soil saturation homogenized (the slope of the fit line changes) and evapotranspiration came into play (the fit lines shift downward). This result poorly



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The model shows how, after irrigation, the soil saturation of the two plots looks similar, according to the new interpretation of the ERT data proposed in this paper. There is at least a qualitative agreement between the TDR measurements and the simulated  $S_d$  of the two plots, suggesting that local scale processes, that are typical of the fallow plot, are missed, but the average soil moisture dynamics is reasonably captured by our simple model.

We conjectured that the presence of a crust over the bare plot could limit the water flux from the USL to the DSL, but the growth of weeds created a crust discontinuity and transformed the USL in a dual porosity layer, allowing locally the deep percolation of water, in the DSL. The weed survival should be linked to this preferential local infiltration. We tried to explore the relevance of this positive feedback on the yearly water balance by running the model for the whole 2010 (the year of the infiltration experiment). We assumed the weed to be active in between Day Of the Year (DOY) 80 and DOY 274 and integrate Eqs. (2) and (4) in between DOY = 1 and DOY = 365. The initial condition is chosen in a way that  $S_u(365)$  and  $S_d(365)$  (at DOY = 365) equal the initial  $S_u(1)$  and  $S_d(1)$ .

Two different scenarios are compared in Fig. 10: CC = 0.4, and the case of completely bare soil with deep percolation impeded  $L_u = 0 \text{ mm d}^{-1}$ . In the case CC = 0 (blue and green lines) the water balance reduces to  $P = RO + E$  in the USL. The USL is saturated by each rainfall event and slowly loses water via transpiration with  $S_u = 1$  often during the winter season (blue line). Minor differences between the estimated  $S_d$  in the two case studies are visible during the dry summer period when the vegetation is water stressed (the red and the green lines coincide in between DOY 170 and DOY 280). During the summer season,  $S_u$  is higher for CC = 0.4 (black line) than for CC = 0 (blue line) due to the vegetation shadowing, whereas, during the wet season  $S_u$  is higher when CC = 0 (blue line) due to the fact that when CC = 0.4 the USL transfers water to the DSL that acts as a reservoir and the vegetation facilitates the infiltration.



The situation that was observed at the beginning of our irrigation experiment corresponds to the simulation outcome at DOY 110, for  $CC = 0.4$ , with most winter rainfall stored in the DSL and  $S_u < S_d$  before rainfall.

In summary, when  $CC = 0.4$  (black and red lines), the vegetation roots alter the structure of the USL that transfers water to the lower soil layers during the winter season where it is stored. As a consequence, the USL maintains the DSL hydrologically active, supporting the later vegetation establishment. According to previous studies conducted in Mediterranean catchments where transpiration and storm flow are out of phase (Brooks et al., 2003), two water compartments interact in the subsoil: a matrix with small pore with low matrix potential, and fast flow paths originating from the interaction between vegetation growth and soil structural change. The fine grained soil matrix is filled by heavy precipitation events (possibly occurring in autumn) or irrigation (as in our experimental setup) to be dried by the vegetation during the rainless season, thus, exchanging water with the fast flow paths through absorption.

Concerning the value of  $CC$ , we reckon that it could correspond to some threshold dictated by the scarce water availability, and  $CC$  could be different if more water was supplied to the environment (the fallow plot is not irrigated and the vegetation relies on rainfall only). By time averaging the calculated relevant water fluxes over the whole year 2010, we found that 77% of the mean annual rainfall evaporated and 23% was transpired, while deep percolation was negligible, suggesting that  $CC = 0.4$  could be the maximum achievable vegetation cover given the scarce water resources, leading to minor runoff losses. For the sake of comparison, we estimated that in the hypothetic case  $CC = 0$ , and thus  $L_u = 0$ , only 33% of the mean annual rainfall would evaporate and 67% should turn into runoff.

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## 4 Conclusions

A combined experimental and theoretical approach was used to investigate the existence and the relevance of a positive feedbacks between weed growth and infiltration on a fallow plot. The ERT data collected during an irrigation experiment (for a comprehensive description see Cassiani et al., 2012) evidenced that the infiltration flux in the fallow plot was more heterogeneous than in the cultivated plot and this fact could be dictated by the poor conductivity of the USL and by the macroporosity associated to the partial vegetation cover. Nevertheless, the fixed TDR data suggested that all the irrigation water infiltrated, and the coupled measurements of soil saturation and vegetation cover by mobile TDR and VIA did not evidence a strong correlation between these two variables. Whether the infiltration is restricted by the crusty layer and enhanced by the vegetation in the fallow plot is unclear, due to the lack of a strong experimental evidence that confirm our previous intuition (Cassiani et al., 2012).

Relevant plant–soil–water interrelations that we tried to assess by repeated local measurements over a short time scale, have been conceptualized in a modelling frame. The model captured the observed soil moisture dynamics during a 5 days irrigation experiment and was further used to investigate the impact of the positive feedback on the yearly water balance.

The results of our experimental and numerical research suggest that in the fallow plot (a) infiltration is heterogeneous and could be locally influenced by plant growth, (b) shortly after irrigation, redistribution takes place below ground where (c) roots have access to the whole active volume; (d) a positive feedback between infiltration and vegetation growth could maintain the DSL hydrologically active during the whole year; based on the model outcome, we may also state that (e) the interplay between vegetation growth and soil, that has an impact on the local hydrologic processes, affects the yearly water budget, reducing runoff and increasing the evapotranspiration, but leaving the groundwater recharge unaltered as compared to the bare soil situation.

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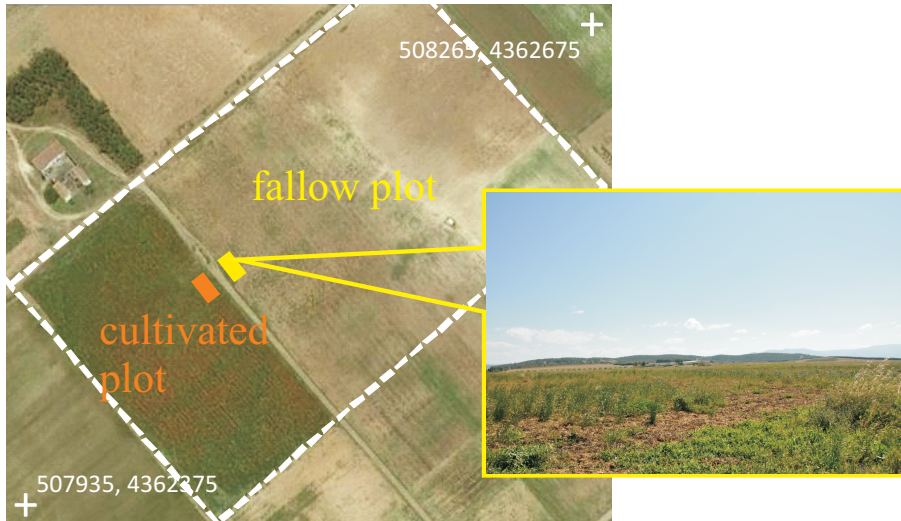
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**Fig. 1.** The experimental site.

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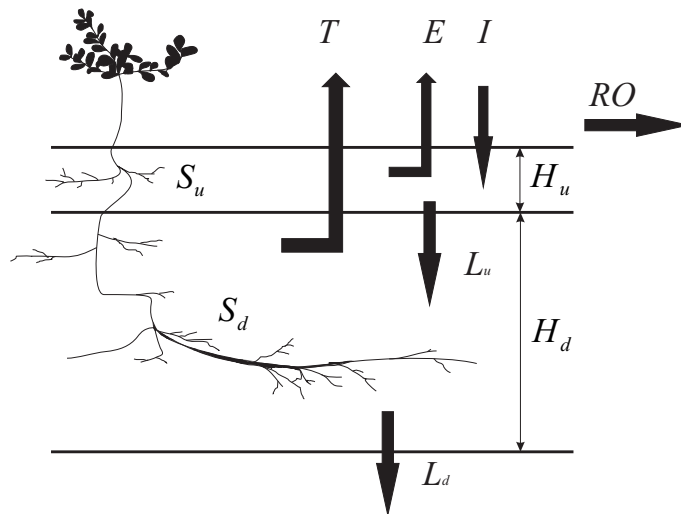
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**Fig. 2.** Scheme of the conceptual model.

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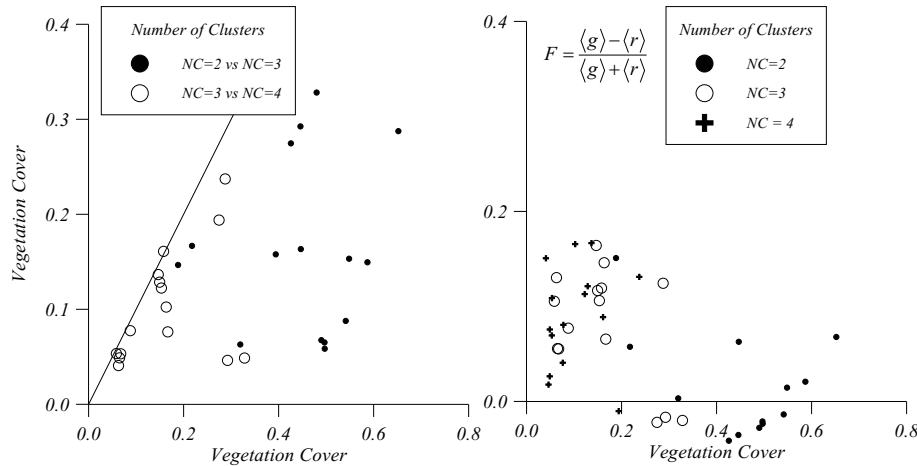
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**Fig. 3.** Vegetation cover evaluated by image analysis with different number of clusters NC (see legend) and vegetation fitness  $F$ .

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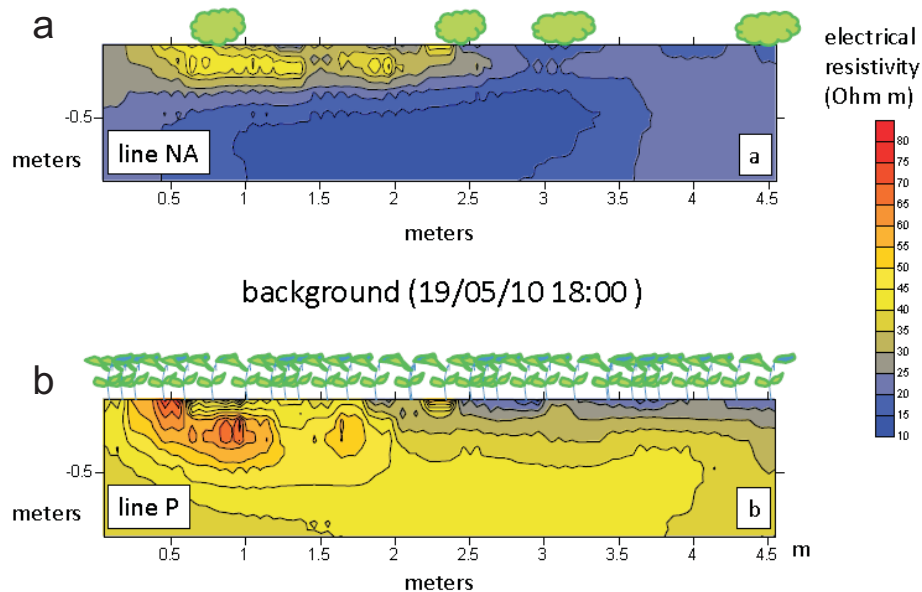
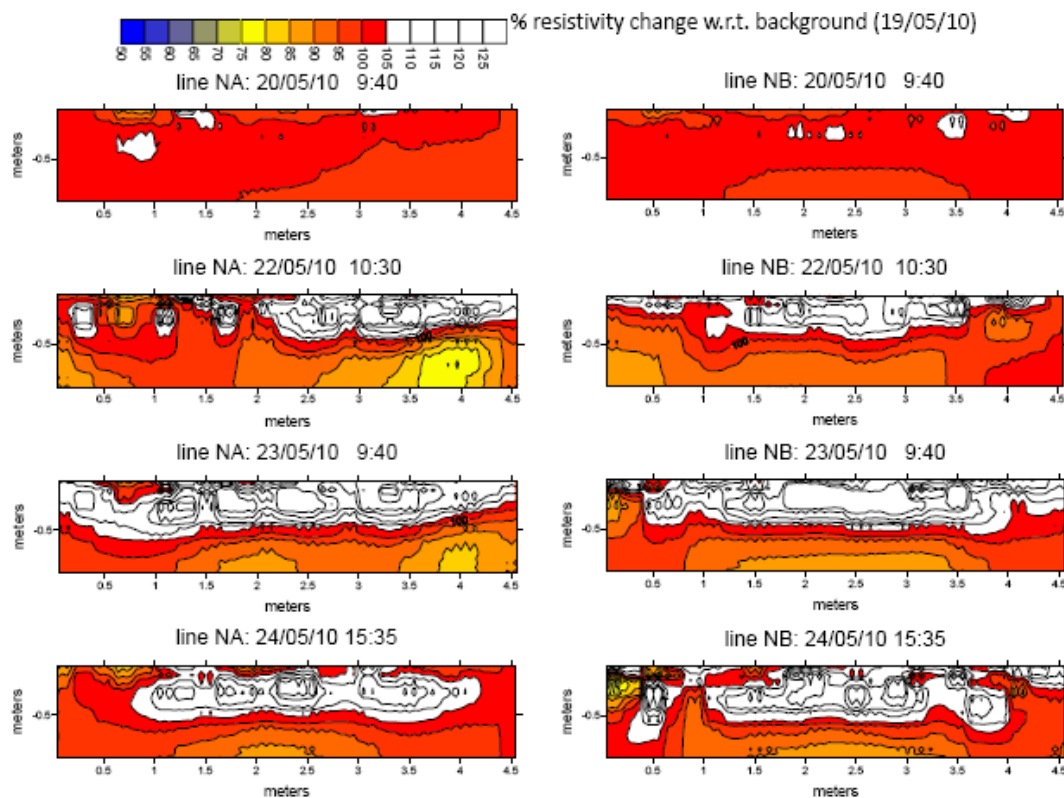


Fig. 4. Background images of the fallow (a) and of the adjacent cultivated (b).

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**Fig. 5.** ERT measurements along lines NA (left panel) and NB (right panel) in the fallow plot at different times. Top to bottom: background, after irrigation (22 May 2010 10:30 LT), one day after irrigation (23 May 2010 09:40 LT), more than two days after irrigation (24 May 2010 15:35 LT).

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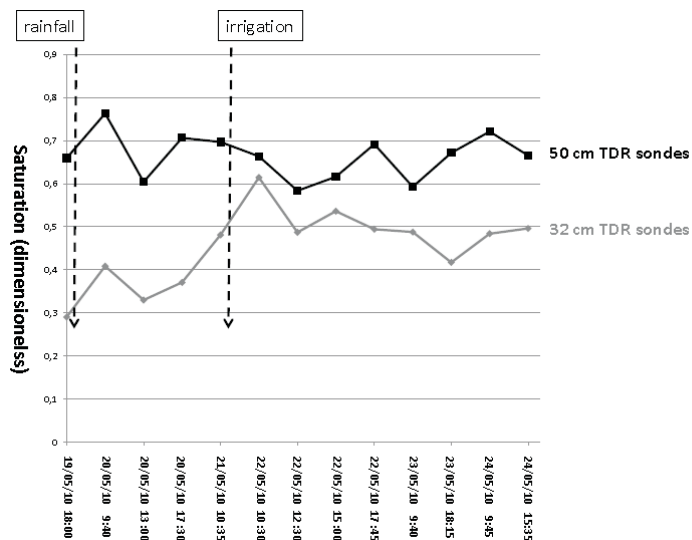
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**Fig. 6.** Soil saturation measured by fixed 50 and 32 cm deep TDR probes at different times.

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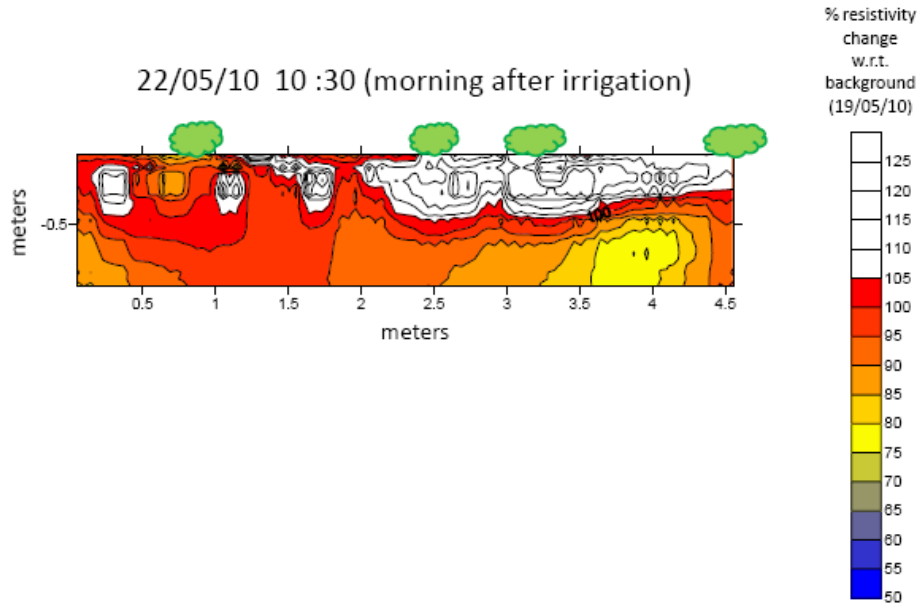


Fig. 7. Plant distribution along ERT line NA.

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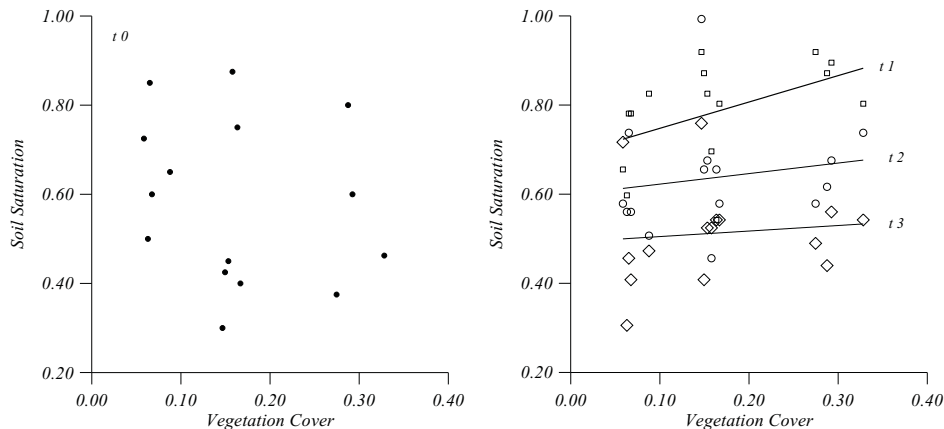
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**Fig. 8.** Left panel: vegetation cover (CC) vs. soil saturation after rainfall. Vegetation cover is evaluated by VIA, soil saturation is measured by portable TDR (rod length = 21 cm).  $t_0$ : 21 May, 10:30 LT – (bold circles). Right panel: vegetation cover vs. soil saturation at different times after irrigation. soil saturation is measured by TDR (rod length = 32 cm).  $t_1$ : 22 May, 11:30 LT (squares);  $t_2$ : 23 May, 09:30 LT (open circles);  $t_3$ : 24 May, 10:30 LT (diamonds).

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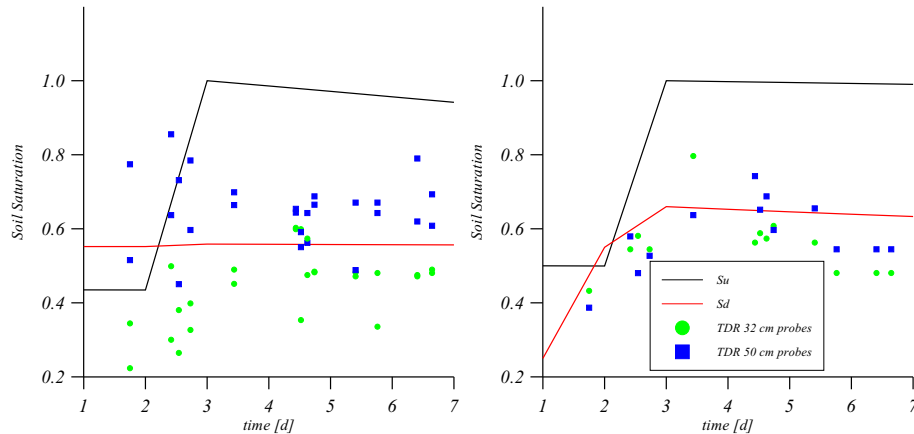
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**Fig. 9.** Soil Saturation estimated by mass balance at daily time scale, starting from 18 May 2010 (before the 13 mm rainfall event) and Soil Saturation measured by fixed TDR probes. Left panel: fallow plot. Right panel: cultivated plot.

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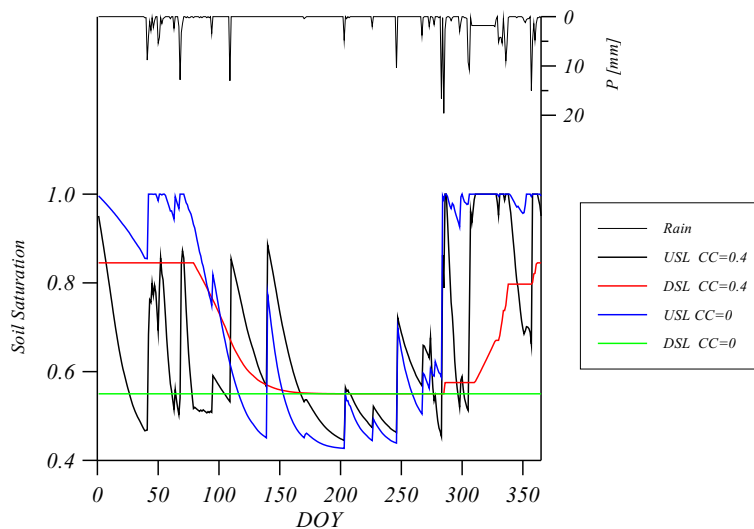
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**Fig. 10.** Model outcome for the whole year 2010: DSL's Soil Saturation  $S_d$  and USL's Soil Saturation  $S_u$  vs. time, for extreme values of the measured vegetation cover: CC = 0 and CC = 0.4.

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