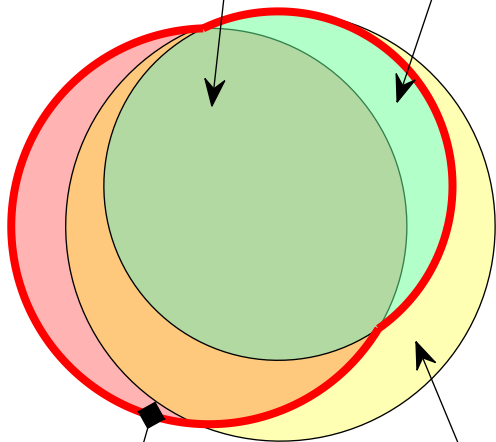









redundant info added by candidate sensor

new info added by candidate sensor



color legend

- 1  full: $H(S)$, free: $H(S|F)$
- 2  full: $H(F)$, free: $H(F|S, F_c)$
- 3  full: $H(F_c)$, free: 0
- 4  $T(S; F) - T(S; F_c)$
- 5  0, because $F_c \subset F$
- 6  $H(F_c|S)$
- 7  $T(S; F_c)$

net info collected
by current set of sensors

Non-captured information
(uncertainty left,
room for improvement)