



Combined measurement and modeling of the hydrological impact of hydraulic redistribution using CLM4.5 at eight AmeriFlux sites

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Abstract. Effects of hydraulic redistribution (HR) on hydrological, biogeochemical, and ecological processes have been demonstrated in the field, but the current generation of standard earth system models does not include a representation of HR. Though recent studies have examined the effect of incorporating HR into land surface models, few (if any) have done cross-site comparisons for contrasting climate regimes and multiple vegetation types via the integration of measurement and modeling. Here, we incorporated the HR scheme of Ryel et al. (2002) into the NCAR Community Land Model Version 4.5 (CLM4.5), and examined the ability of the resulting hybrid model to capture the magnitude of HR flux and/or soil moisture dynamics from which HR can be directly inferred, to assess the impact of HR on land surface water and energy budgets, and to explore how the impact may depend on climate regimes and vegetation conditions. Eight AmeriFlux sites with contrasting climate regimes and multiple vegetation types were studied, including the Wind River Crane site in Washington State, the Santa Rita Mesquite savanna site in southern Arizona, and six sites along the Southern California Climate Gradient. HR flux, evapotranspiration (ET), and soil moisture were properly simulated in the present study, even in the face of various uncertainties. Our cross-ecosystem comparison showed that the timing, magnitude, and direction (upward or downward) of HR vary across ecosystems, and incorporation of HR into CLM4.5 improved the model-measurement matches of evapotranspiration, Bowen ratio,

and soil moisture particularly during dry seasons. Our results also reveal that HR has important hydrological impact in ecosystems that have a pronounced dry season but are not overall so dry that sparse vegetation and very low soil moisture limit HR.

1 Introduction

Hydraulic redistribution (HR) is the transport of water from wetter to drier soils through plant roots (Burgess et al., 1998). Several recent reviews (Neumann and Cardon, 2012; Prieto et al., 2012; Sardans and Peñuelas, 2014) summarize results from the hundreds of empirical and modeling papers describing HR that have emerged over the last 3 decades. Monitoring of sap flow (e.g., Scott et al., 2008), soil water potential (e.g., Meinzer et al., 2004), soil moisture content (e.g., Brooks et al., 2002), and isotope (e.g., Brooks et al., 2006) all indicate that HR can occur in many ecosystems worldwide, ranging in climate from arid to wet, particularly if the system has a pronounced dry season. HR-induced transport of water can be upward (as “hydraulic lift”) from moist deep soils to dry shallow soils (Richards and Caldwell, 1987), downward (as “hydraulic descent”) usually following a precipitation event (Ryel et al., 2003), or lateral (Brooks et al., 2002).

Though effects of HR on hydrological (e.g., Scott et al., 2008), biogeochemical (e.g., Domec et al., 2012; Cardon et

al., 2013), and ecological (e.g., Hawkins et al., 2009) processes have been amply demonstrated in the field, the current generation of standard dynamic global vegetation and earth system models do not include a representation of HR (Neumann and Cardon, 2012; Warren et al., 2015). The several modeling studies at ecosystem and regional scales that do include HR do so by incorporating empirical equations describing HR (e.g., Ryel et al., 2002) into various land surface models (Lee et al., 2005, CAM2-CLM; Zheng and Wang, 2007, IBIS2 and CLM3; Baker et al., 2008, SiB3; Wang, 2011, CLM3; Li et al., 2012, CABLE; Luo et al., 2013, VIC-3L; Yan and Dickinson, 2014, CLM4.0; Tang et al., 2015, CLM4.5). For example, Li et al. (2012) modeled three evergreen broadleaf forests in tropical, subtropical, and temperate climate, and showed that the ability of CABLE to match observed evapotranspiration (ET) and soil moisture was improved by including HR and dynamic root water uptake (preferential uptake of moisture from areas of the root zone where moisture is more available, Lai and Katul, 2000). Currently, few (if any) has investigated the effects of HR on land surface water and energy cycles in a comprehensive manner by using both the monitoring and modeling methods for contrasting climate regimes and multiple vegetation types. In this study, we attempt to address this research gap based on both field measurements and numerical modeling at an ecologically broad selection of eight AmeriFlux sites characterized by contrasting climate regimes and multiple vegetation types. Of the eight sites, two have a long history of empirical research focused on HR: the US-Wrc Wind River Crane site in the Pacific Northwest (Washington State), and the US-SRM Santa Rita Mesquite savanna site in southern Arizona. The other six are new sites along the Southern California Climate Gradient (US-SCs, g, f, w, c, and d), each with a pronounced dry season, where we suspect HR may occur during dry periods.

At one of the six Southern California Climate Gradient sites (the James Reserve, US-SCf), Kitajima et al. (2013) recently used the HYDRUS-1D model and isotopic measurements of xylem water to show that trees and shrubs use deep water, probably delivered both by HR and to some extent by capillary rise, during summer drought. In the Pacific Northwest, adjacent to the Wind River Canopy Crane Research Facility (US-Wrc), stands of Douglas fir (*Pseudotsuga menziesii* (Mirb.) Franco) have been the focus of numerous papers examining the importance of HR in this overall moist but seasonally dry ecosystem. For example, Brooks et al. (2002) used sap flow and soil moisture information to show that 35 % of the total daytime water consumption from the upper 2 m soil layer was replaced by HR during July–August in 2000. Brooks et al. (2006) further reported that HR was negligible in early summer but increased to 0.17 mm d^{-1} by late August. Meinzer et al. (2004) reported that the seasonal decline of soil water potential was greatly reduced by HR. Based on monitoring of sap flow of *Prosopis velutina* Woot (velvet mesquite) and soil moisture, both hydraulic lift and

hydraulic descent were found at or near the Santa Rita Arizona savanna (US-SRM) site (Hultine et al., 2004; Scott et al., 2008).

The objectives of this study are to investigate the impact of HR on land surface water and energy budgets based on both observational data and numerical modeling, and to explore how the impact may depend on climate regimes and vegetation conditions. Observed soil moisture at the six Southern California Climate Gradient sites was corrected for temperature first, and then HR signal was checked using the wavelet method. The modeling investigation is done through incorporating the HR scheme of Ryel et al. (2002) into the NCAR Community Land Model Version 4.5 (CLM4.5). To apply the hybrid model to the eight AmeriFlux sites, we first examined the performance of the hybrid model in capturing the magnitude of HR flux and/or soil moisture diel fluctuation, from which a reasonable HR flux magnitude can be directly inferred; we then analyzed the role of HR in the water and energy cycles. The sensitivity of the modeled HR to parameters and the uncertainty in the modeling were also investigated in the present study.

2 Materials and methods

2.1 Study sites

The sites in this study were chosen based on several criteria. Concurrent meteorological forcing data, soil moisture data throughout the soil profile, and ET data for a continuous period of several years had to be available. The sites cover a range of annual rainfall amounts and vegetation types, and have a seasonally dry climate – a good indicator of ecosystems where HR may occur (Neumann and Cardon, 2013). Two of the eight sites (US-SRM and US-Wrc) were specifically chosen because they have a strong record of hydraulic redistribution research. In contrast, the six Southern California Climate Gradient sites were chosen because it was not yet known whether HR occurred at them, and modeling results could be compared to new empirical data. Table 1 presents location, elevation, climate, vegetation type, annual precipitation, average temperature, and years for which we have atmospheric forcing data, for each of the eight AmeriFlux sites. Further details about these eight sites can be found on the AmeriFlux website (<http://ameriflux.lbl.gov/sites/site-search/>). All sites except Santa Rita Mesquite have a Mediterranean climate (rainy winters, dry summers); Santa Rita Mesquite (US-SRM) is a semi-arid site with a dominant summer rainy season. Precipitation varies from ~ 2200 (US-Wrc) to ~ 100 mm (US-SCw) per year. Average temperature ranges from 8.7 (US-Wrc) to 23.8°C (Sonoran Desert US-SCd). Vegetation ranges from needleleaf and broadleaf forest to chaparral, grassland, and desert perennials and annuals.

Table 1. Study site information.

Site	Location	Elevation (m)	Climate	Vegetation	Annual precipitation	Average temperature (°C)	Atmospheric forcing data (mm)
Wind River Crane (US-Wrc)	45.8205° N, 121.9519° W, WA	371	Mediterranean (Csb)	Douglas fir/western hemlock	2223 ^{1*}	8.7 ^{1*}	1999–2012
Santa Rita Mesquite (US-SRM)	31.8214° N, 110.8661° W, AZ	1116	Cold semi-arid (BSk)	Mesquite tree, grass	3772 ^{2*}	19.6 ^{3*}	2004–2012
Southern California Climate Gradient – Coastal Sage (US-SCs)	33.7342° N, 117.6961° W, CA	475	Mediterranean (Csa)	Coastal sage	288 ^{4*}	16.2 ^{4*}	2007–2012
Grassland (US-SCg)	33.7364° N, 117.6947° W, CA	470	Mediterranean (Csa)	Grass	281 ^{4*}	16.6 ^{4*}	2007–2012
Oak Pine Forest (US-SCf)	33.8080° N, 116.7717° W, CA	1710	Mediterranean (Csa)	Oak/pine forest	526 ^{4*}	13.3 ^{4*}	2007–2012
Pinyon Juniper Woodland (US-SCw)	33.6047° N, 116.4527° W, CA	1280	Mediterranean (Csa)	Pinyon, juniper	100 ^{4*}	16.5 ^{4*}	2007–2012
Desert Chaparral (US-SCc)	33.6094° N, 116.4505° W, CA	1300	Mediterranean (Csa)	Desert shrubland	153 ^{4*}	16.3 ^{4*}	2007–2012
Sonoran Desert (US-SCd)	33.6518° N, 116.3725° W, CA	275	Mediterranean (Csa)	Desert perennials and annuals	123 ^{5*}	23.8 ^{5*}	2007–2011

Notes: 1*: 1978–1998, statistic is based on a NOAA station located 5 km north of the US-Wrc tower. 2*: 1937–2007, from Scott et al. (2009). 3*: 2004–2012. 4*: 2007–2012. 5*: 2007–2011.

Table 2. Sources of data for model inputs.

Site	Atmospheric forcing data	Land coverage	LAI	Canopy height	Soil texture	Soil organic matter
US-Wrc	AmeriFlux tower data	Google Earth map; Table 2 in Shaw et al. (2004) (overstory trees: 24 %; vine maple: 36 %; salal and oregon grape: 40 %)	Shaw et al. (2004); AmeriFlux biological data file	Table 3 in Shaw et al. (2004) (mean overstory tree height: 19.2 m)	Fig. 4 in Warren et al. (2005). Sandy loam, with loamy sand at some depths.	Table 1 in Shaw et al. (2004); AmeriFlux biological data file
US-SRM	AmeriFlux tower data	Dr. Russell Scott from USDA-ARS (bare ground: 40 %; mesquite canopy: 35 %; grass: 25 %)	Dr. Russell Scott from USDA-ARS	Potts et al. (2008) (Tree height: 0.25–5 m)	AmeriFlux biological data file. Mixed sandy loam and loamy sand.	AmeriFlux biological data file
US-SCs	UCI Goulden Lab	Estimation based on site picture (bare ground: 10 %; coastal sage: 90 %)	NCAR database	NCAR database	UCI Goulden Lab Shallow sand, deep loamy sand	NCAR database
US-SCg	UCI Goulden Lab	Estimation based on site picture (bare ground: 10 %; grass: 90 %)	NCAR database	NCAR database	UCI Goulden Lab Shallow sand, deep loamy sand	NCAR database
US-SCf	UCI Goulden Lab	Table 3 in Anderson and Goulden (2011) (Doak)	Table 2 in Fellows and Goulden (2013)	NCAR database	UCI Goulden Lab Sandy loam, with loamy sand at some depths	NCAR database
US-SCw	UCI Goulden Lab	Table 3 in Anderson and Goulden (2011) (Oshrub)	NCAR database	NCAR database	UCI Goulden Lab Estimated as sand (sand: 90 %; clay: 7.5 %)	NCAR database
US-SCc	UCI Goulden Lab	Google Earth map (bare ground: 78 %; chaparral: 22 %)	UCI Goulden Lab	NCAR database	UCI Goulden Lab Estimated as sand (sand: 90 %; clay: 7.5 %)	NCAR database
US-SCd	UCI Goulden Lab	Table 3 in Anderson and Goulden (2011) (LowDes)	NCAR database	NCAR database	UCI Goulden Lab Estimated as sand (sand: 99 %; clay: 0.5 %)	NCAR database

2.2 CLM4.5 parameterization

The NCAR Community Land Model Version 4.5 (CLM4.5) (Oleson et al., 2013) is used in this study to simulate the energy fluxes and hydrological processes at the eight AmeriFlux sites. Surface heterogeneity in CLM is represented using a nested hierarchy of grid cells, land units, snow/soil columns, and plant functional types (PFTs). Different PFTs differ in physiological, structural, and biogeochemical parameters. Within each vegetated land unit, multiple columns can exist, and multiple PFTs can share a column; vegetation state variables, surface mass, and energy fluxes are solved at the PFT level, and soil parameters and processes are solved at the column level. Surface fluxes at the grid cell level (e.g., ET) are the area-weighted average across different components (PFTs, columns, and land units). The plant growth and carbon/nitrogen cycles were not simulated in this study. Instead, LAIs for each PFT were prescribed based on observa-

tional data. At each study site, the simulations were implemented for the footprint of eddy flux tower. Table 2 presents the sources of data used as model input, for atmospheric forcing and surface properties including coverage of different plant functional types (PFTs), LAI, canopy height, soil texture, and soil organic matter content. At each site, atmospheric forcing data used to drive CLM4.5 are taken from the corresponding AmeriFlux tower. Surface properties in the model are set to reflect the AmeriFlux site conditions when such information is available and were drawn by interpolation from corresponding gridded data sets in the NCAR database (Oleson et al., 2013, and notes in the Supplement Sect. S1) in the absence of site-specific data. There are 10 active soil layers in CLM, and a maximum depth of 3.8 m is used in this study (Table 3). The PFT-level root fraction r_i in

each soil layer is

$$r_i = \begin{cases} 0.5 \cdot [\exp(-r_a z_{i-1}) + \exp(-r_b z_{i-1}) - \exp(-r_a z_i) + \exp(-r_b z_i)] & \text{for } 1 \leq i < 10 \\ 0.5 \cdot [\exp(-r_a z_{i-1}) + \exp(-r_b z_{i-1})] & \text{for } i = 10, \end{cases} \quad (1)$$

where z_i is the depth at the bottom of soil layer i , and z_0 is 0. The PFT-dependent root distribution parameters r_a and r_b are adopted from Zeng (2001). From Eq. (1), r_i decreases exponentially with depth. In the present study, roots did not have access to groundwater through the simulation periods at all sites except US-Wrc where groundwater could rise into the 10th soil layer during the wet season. However, the groundwater level was below the 10th soil layers during dry season when HR occurred at the US-Wrc site as shown in Sect. 3.1.2.

Within CLM4.5, the Clapp and Hornberger B parameter (the exponent in the soil water retention curve that varies substantially with soil texture) strongly influences simulated soil moisture. We used available sources of soil texture information for the eight sites (Table 2) to set the range of appropriate B for each site and depth (Table 3), following Clapp and Hornberger's (1978) ranges of B for different soil types. Within each range, however, we tuned the values for B with depth to get a good match between modeled and measured soil moisture.

The atmospheric forcing data at the US-Wrc and US-SRM sites include incident longwave radiation, incident solar radiation, precipitation, surface pressure, relative humidity, surface air temperature, and wind speed. Because incident longwave radiation and surface pressure data were not available at the six southern California sites, CLM4.5 assumes standard atmospheric pressure and calculates the incident longwave radiation based on air temperature, surface pressure, and relative humidity (Idso, 1981). Gap-filled atmospheric forcing data are at 30 min resolution, and the time step for model simulations is also 30 min. Time frames for which atmospheric forcing data are available for each site are shown in Table 1.

2.3 HR model parameterization

To quantify HR, we incorporated the HR scheme of Ryel et al. (2002) into CLM4.5. Many HR modeling studies used this HR scheme (e.g., Zheng and Wang, 2007; Wang, 2011; Li et al., 2012) or its variations (e.g., Lee et al., 2005; Yu and D'Odorico, 2015). HR-induced soil water flux $q_{HR}(i, j)$ (cm h^{-1}) between a receiving soil layer i and a giving soil layer j is quantified as

$$q_{HR}(i, j) = -C_{RT} \cdot \Delta\phi_m \cdot c_j \frac{F_{root}(i) \cdot F_{root}(j)}{1 - F_{root}(j)} \cdot D. \quad (2)$$

By summing all giving and receiving layer pairs within the soil column, total q_{HR} can be calculated. C_{RT} is the maximum radial soil–root conductance of the entire active root system for water ($\text{cm MPa}^{-1} \text{h}^{-1}$); $\Delta\phi_m$ is the water potential difference between two soil layers (MPa); $F_{root}(i)$ is root

fraction in soil layer i (weighted average of PFT-level root fractions; Zeng, 2001); and D is a switching factor set to 1.0 during night and 0.0 during the day since during daytime the transpiration-induced gradient of water potential within a plant continuum dictates a transport of water from roots to leaves. The factor reducing soil–root conductance for water in the giving layer c_j is

$$c_j = \frac{1}{1 + \left(\frac{\phi_j}{\phi_{50}}\right)^b}. \quad (3)$$

In Eq. (3), ϕ_j is soil water potential in layer j (MPa), ϕ_{50} is the soil water potential where soil–root conductance is reduced by 50 % (MPa), and b is an empirical constant. Values for b (3.22) and ϕ_{50} (−1 MPa) were taken from Ryel et al. (2002) due to lack of site-specific parameters, and we tested the model sensitivity to the parameters C_{RT} , b , and ϕ_{50} at each site. Rather than tuning C_{RT} as Ryel et al. (2002) did to match modeled HR (calculated in Eq. 2) to measured HR (from soil sensor data) after a saturating rain, we based the tuning of C_{RT} on comparison of modeled and measured magnitude and dynamics of water content in upper soil layers (0–30 cm) at an hourly scale during dry periods. At the three drier southern California sites (US-SCw, US-SCc, and US-SCd), C_{RT} was further adjusted to relatively small values (0.05–0.1) to limit the hydraulic descent in order to reduce the model bias for soil water potential during dry periods. If $C_{RT} > 0.1$, the modeled soil water potential would be always higher than −1 MPa during dry periods, which is not realistic for such dry sites. Specific values of the parameters in the HR scheme of Ryel et al. (2002) used for the eight study sites are shown in Table 4.

2.4 Combined model

Two multi-year simulations were carried out at each of the eight study sites. “Without HR” used the default land surface model CLM4.5; “with HR” (CLM4.5+HR) used the version of the model including Ryel's representation of HR. To distinguish the influences of the Clapp and Hornberger B and HR on the soil moisture modeling, the tuning of the parameter B was done in the wet season (with high soil moisture) when the HR influence is negligible at the US-Wrc and southern California sites. Therefore, the B values do not depend on whether the tuning was done with CLM4.5 or with CLM4.5+HR. At the SRM site, HR is mainly in the form of hydraulic descent during rainfall events (as shown later in the “Results” section), we tuned B during dry periods when hydraulic descent was minimum to make the minimum value of the modeled soil moisture from CLM4.5 be close to the observation for surface soil layers. The B values for soil layers deeper than 83 cm were not tuned and used the default value generated by CLM at the US-SRM site. Therefore, at each site, “without HR” and “with HR” simulations used identical B values tuned for that site. We then examined whether for

Table 3. Clapp and Hornberger B used in this study.

Layers	Depth at layer interface (m)	US-Wrc		US-SRM		US-SCs		US-SCg		US-SCf		US-SCw		US-SCc		US-SCd	
		B	Soil texture ^{1*}	B	Soil texture ^{1*}	B	Soil texture ^{1*}	B	Soil texture ^{1*}	B	Soil texture ^{1*}	B	Soil texture ^{2*}	B	Soil texture ^{2*}	B	Soil texture ^{2*}
1	0.0175	3.96	SL	3.15	LS	5.07	S	4.46	S	3.15	SL	4.09	S	4.09	S	2.27	S
2	0.0451	4.31	SL	3.15	LS	5.09	S	4.49	S	3.26	SL	4.09	S	4.09	S	2.27	S
3	0.0906	4.46	SL	3.15	LS	5.13	S	4.53	S	3.39	SL	4.10	S	4.10	S	2.27	S
4	0.1655	4.52	SL	3.16	LS	5.30	LS	4.65	S	3.18	SL	4.11	S	4.11	S	2.27	S
5	0.2891	4.39	SL	3.41	LS	4.83	LS	4.27	LS	3.34	SL	4.11	S	4.11	S	2.27	S
6	0.4929	4.31	SL	3.66	LS	4.63	LS	4.19	LS	3.27	SL	4.11	S	4.11	S	2.27	S
7	0.8289	4.00	SL	3.91	LS	3.94	LS	4.33	LS	3.27	LS	4.11	S	4.11	S	2.27	S
8	1.3828	5.85	LS	4.41	LS	3.51	LS	4.08	LS	3.30	SL	4.11	S	4.11	S	2.27	S
9	2.2961	6.65	SL	4.40	LS	3.15	LS	3.90	LS	3.50	SL	4.10	S	4.10	S	2.27	S
10	3.8019	6.65	SL	4.40	LS	3.15	LS	3.90	LS	3.50	SL	4.10	S	4.10	S	2.27	S

Note: ^{1*}-derived from soil sample data in former studies; ^{2*}-estimated by UCI Goulden Lab. “S” represents sand, “LS” loamy sand, and “SL” sandy loam. B values for sand, loamy sand, and sandy loam were 2.27–5.83, 2.91–5.85, and 3.15–6.65 in Clapp and Hornberger (1978), respectively.

Table 4. Parameters used in the HR scheme of Ryel et al. (2002) for the study sites. “ C_{RT} ” is the maximum radial soil–root conductance of the entire active root system for water, “ φ_{50} ” is the soil water potential where conductance is reduced by 50 %, and “ b ” is an empirical constant.

Site	C_{RT} (cm MPa ⁻¹ h ⁻¹)	b	φ_{50} (MPa)
US-Wrc	0.1	3.22	-1.0
US-SRM	1.0	3.22	-1.0
US-SCs	1.0	3.22	-1.0
US-SCg	0.25	3.22	-1.0
US-SCf	1.0	3.22	-1.0
US-SCw	0.1	3.22	-1.0
US-SCc	0.05	3.22	-1.0
US-SCd	0.05	3.22	-1.0

these eight ecologically diverse sites, CLM4.5 with and/or without HR were able to reproduce basic patterns observed at the sites in ET, soil moisture with depth, and Bowen ratio.

2.5 Field observations

ET, sensible heat flux, and soil moisture data at the US-SRM and US-Wrc sites were obtained from AmeriFlux databases. Data for these variables at the six Southern California Climate Gradient sites were collected by the Goulden lab (<http://www.ess.uci.edu/~california/>). Observed soil moisture was available for multiple soil layers with the maximum depth of 200 cm and 100 cm at the US-Wrc and US-SRM sites, respectively. Soil moisture data at southern California sites were processed as described in the notes in the Supplement Sect. S2. Briefly, each southern California site had four CS-616 water content reflectometers (three reflectometers at US-SCd), each sensing 0–30 cm depth. All southern California sites except US-SCd also had five CS-229 thermal dissipation probes sensing water potential at five depths (to 200 cm). Data from both soil moisture sensor types at the southern California sites were used more cautiously. Though sensor output suggesting nighttime increases in soil moisture fol-

lowed by daytime decreases is often used in the literature as a signature of HR, we only recognized such oscillations from the 0–30 cm CS-616 or CS-229 probes as signatures of HR if they were clearly stronger than a putative temperature-induced oscillation in surrounding portions of the signal trace (e.g., Fig. S1a in the Supplement, larger oscillations beginning around day 180 in the 5 cm trace) and if wavelet transform analysis of the CS-229 probe data corroborated the existence of HR (see Sect. S2 and Fig. S1b, c in the Supplement).

3 Results

3.1 Soil moisture observations and simulations

Observed soil moisture (grey lines) and CLM4.5 model simulations with (blue lines) and without (red lines) HR are plotted in Fig. 1 at daily timescale for selected years, for the top 0–30 cm soil layer and also at multiple depths where such data are available. As noted above, CS-229 thermal dissipation probes were installed from 0 to 200 cm depth at five of the six California sites, but are known only to provide reliable information down to approximately -2.5 MPa; sensor output thus flatlined for lower water potentials during drought. We therefore chose only to include 0–30 cm CS-616 probe data in Fig. 1, with panels ordered from west (US-SCs, Coastal Sage) to east (US-SCd, Sonoran Desert) down the panels. However, modeled output by depth increment at the five instrumented US-SC southern California sites is plotted in Figs. S2–S6 in the Supplement along with temperature-corrected data from the CS-229 probes.

Modeled soil moisture content generally follows the magnitude and dynamics in observational data (Fig. 1), except at depth at US-Wrc. At that site, we set B – the only parameter in the soil water retention curve in the models – based on the soil texture information from the biological data file at the US-Wrc AmeriFlux ftp website <ftp://cdiac.ornl.gov/pub/ameriflux/data/Level1/> (sandy loam and loamy sand) with the maximum value being 6.65 (Table 3). However, Shaw

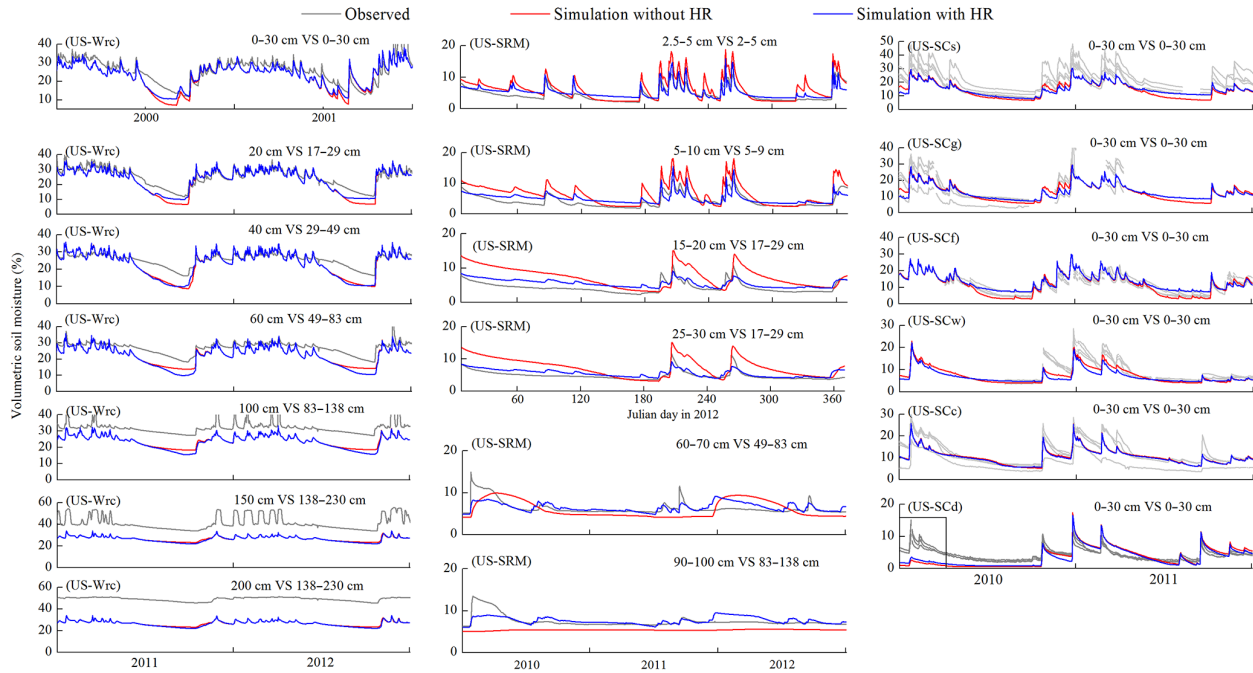


Figure 1. Observed and simulated soil moisture over selected years. Labels at the upper right corner of each soil moisture panel show the depths of observed and simulated soil moisture. For example, “20 cm VS 17–29 cm” means the observation depth of soil moisture is 20 cm and the simulated results at depths of 17–29 cm were compared with this observation. Within panels for southern California sites (US-SCs, US-SCg, US-SCf, US-SCw, US-SCc, and US-SCd), the four grey lines are data from the four CS-616 soil moisture sensors at 0–30 cm depth. Results were shown for the last year only (2012) for the top 30 cm depths at US-SRM site for clarity. The rectangular box indicated period with incomplete precipitation record.

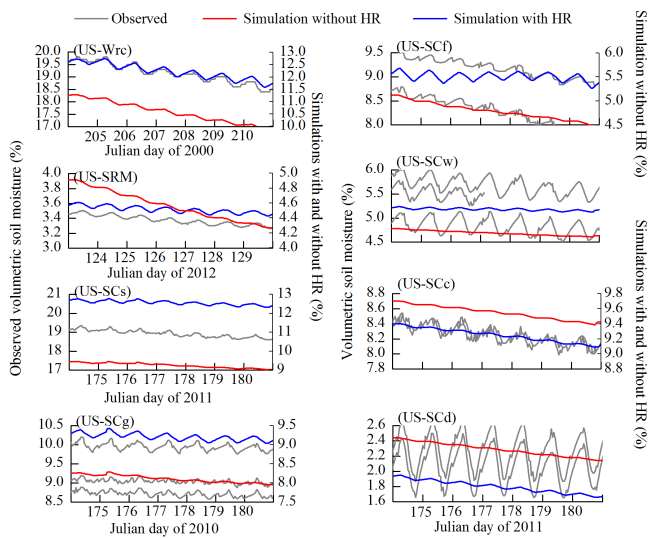


Figure 2. Observed and simulated soil moisture for depth of 0–30 cm during dry periods.

et al. (2004) (and <http://ameriflux.ornl.gov/fullsiteinfo.php?sid=98>) report that in some locations soil at depth can approach silt to clay loam for which the range of B is 8.5 ± 3.4 (clay loam, Clapp and Hornberger, 1978). Using a higher B

value in the simulations would have reduced the difference between the simulated and observed soil moisture at depth at the US-Wrc site.

At US-SRM (Fig. 1), modeled soil moisture at depth (≥ 49 cm) was more dynamic in CLM4.5+HR (blue line) than in CLM4.5 (red line). The dynamism is also clearly seen in the observed soil moisture data (grey lines) in both the 60–70 and 90–100 cm depths at this site. In CLM4.5+HR, this dynamism is caused by downward HR (hydraulic descent) when root systems redistribute the infiltrated rainwater from shallow to deep soils faster than it could be delivered by percolation alone (Ryel et al., 2003). In Figs. S2–S6, similar measured dynamism at depth is also detected by CS-229 probes for large rain events at the five instrumented Southern California Climate Gradient sites.

As discussed in Sect. S2 in the Supplement, using wavelet analysis of site measurement data, we found clear evidence of upward HR at the most moist southern California site US-SCf (Oak Pine Forest), and spotty evidence at US-SCw (Pinyon Juniper Woodland) and US-SCc (Desert Chaparral) sites (Fig. S1 in the Supplement). We did not find clear phase-based evidence of upward HR at US-SCg (Grassland) or US-SCs (Coastal Sage) sites, and temperature oscillations at the US-SCd (Sonoran Desert) site were very large, precluding easy identification of periods of upward HR. Still,

the CLM4.5+HR results suggested that HR could occur at the southern California sites given the rooting distribution of plants and the seasonal drought, but its hydrological effect on landscape-level eddy flux was predicted to be far lower (than wetter sites such as US-Wrc) where plant biomass was small (e.g., US-SCd). This combination of factors (drought, rooting depth, density of vegetation) influenced the simulated magnitude of soil moisture fluctuations, and we plot them with the sensor data in Fig. 2 and Fig. S7 in the Supplement. The noticeable discrepancy between modeled and measured rainy season soil moisture at the US-SCd site (indicated with rectangular box in Fig. 1) are most likely caused by the incomplete precipitation record (Sect. S3 in the Supplement).

Overall, Fig. 1 and the corresponding root mean squared error (RMSE) illustrate clear improvement of the match between modeled and observed soil moisture at the US-SRM site by incorporating HR into CLM4.5 (Table 5, Fig. S8 in the Supplement). At the southern California sites, the match is improved at the US-SCs, g, and f sites during dry periods (Table 5, Fig. S8 in the Supplement); inclusion of HR makes little difference at the US-SCw, c, and d sites (Table 5, Fig. S8 in the Supplement). Improvement of simulated soil moisture at shallow layers (e.g., 0–30 cm, 17–29 cm) was observed at the US-Wrc site during dry periods by incorporating HR (Table 5, Fig. S8 in the Supplement), but at depth, the modeling challenges associated with the Clapp and Hornberger (1978) *B* factor (described above) precluded detection of any change in RMSE with inclusion of HR in CLM4.5. The reduced model performance in soil moisture modeling at depth by including HR at site like US-Wrc is not a negligible challenge in HR modeling.

3.1.1 HR flux simulations

To evaluate the simulation of the HR flux, the modeling results were compared to both direct measurement of HR flux itself and measurement of soil moisture dynamics from which HR flux could be inferred. These include (a) observed downward sap flow at the US-SRM site, (b) observed diel fluctuations of soil moisture for depth of 0–30 cm during dry periods at all eight sites, (c) the vertical change of the magnitude in the observed diel fluctuations of soil moisture at the US-Wrc and US-SRM sites, and (d) the seasonal pattern of HR's influences on soil moisture at the US-Wrc site.

At the US-SRM site, Scott et al. (2008) monitored sap flow and estimated hydraulic descent during days 31–109 in 2004 to be 12–38 mm H₂O d⁻¹ at ecosystem scale; the CLM4.5+HR estimate for the same period was 35 mm H₂O d⁻¹, within the scope provided by Scott et al. (2008). CLM4.5+HR could largely capture the amplitude of the HR-induced diel fluctuations of soil moisture for depth of 0–30 cm at US-Wrc, US-SRM, US-SCs, US-SCg, and US-SCf sites during drought (Fig. 2; Fig. S7 in the Supplement). The simulated amplitude of diel fluctuation during the dry periods decreased from shallower to deeper layers at all eight

sites. For example, the simulated amplitude decreased from 0.002 at depth of 2–5 cm to essentially 0 at depth of 17–29 cm at the US-SRM site, and the decrease of amplitude with depth is quantitatively consistent with observations at the US-Wrc and US-SRM sites (results shown in Fig. S9 in the Supplement). At the US-Wrc site, the maximum depth at which the HR-induced soil moisture increases is identifiable during dry seasons (mainly limited to the upper 60 cm), and the seasonal pattern of HR's influences on soil moisture could also be correctly reproduced by the CLM4.5+HR (as shown in detail in Sects. 3.1.2 and 4.1). As discussed in Sect. 2.3, we used soil water potential to roughly control the magnitude of HR at the three drier southern California sites, where the diel fluctuation of soil moisture was clearly influenced by temperature. These comparisons indicate that the HR flux is properly simulated in the present study.

3.1.2 Soil moisture simulations with and without HR

Differences between CLM4.5 and CLM4.5+HR in modeled volumetric soil moisture are plotted in Fig. 3 and Fig. S10 for all sites. Inclusion of HR in CLM4.5 increased summertime soil moisture by several percentage points (above the zero line) in the six southern California US-SC sites (0–30 cm depths), US-Wrc, and US-SRM (0–49 cm depths) sites (Fig. 3). In the US-Wrc model profile, these periods of increased shallow soil moisture clearly coincide with those of decreased soil moisture at depth (49–380 cm depth), consistent with hydraulic lift. In the US-SRM (Fig. 3) and southern California US-SC site model profiles (Fig. S10 in the Supplement), the patterns of soil moisture with depth are more complex, with central layers being sources or sinks of water depending on time of year and year itself. During rainy winter seasons at the six southern California US-SC sites, CLM4.5+HR produced periods of reduced soil moisture in shallow 0–30 cm layers in all years at US-SCs (Coastal Sage) and US-SCg (Grassland) sites, consistent with hydraulic descent (Fig. 3). Similar patterns are most clear only during the wettest winter in 2011 for US-SCd (Sonoran Desert), SCc (Desert Chaparral), SCw (Pinyon Juniper), and SCf (Oak Pine) sites.

Pulling together averaged model output from all years, for 0–250 cm depths at each site, Fig. 4 illustrates the complex patterns in the change in volumetric soil water content driven by inclusion of the HR scheme of Ryel et al. (2002) in the CLM4.5 modeling framework, over the annual cycle. Blue indicates an increase of (up to 0.06) volumetric soil moisture in the CLM4.5+HR vs. the CLM4.5 model output. Yellow indicates a decrease of (up to 0.06) volumetric soil moisture in the CLM4.5+HR vs. CLM4.5 model output. Here the contours are generated from soil moisture increases or decreases in each CLM4.5-defined layer node, and the node depths increase exponentially downward. Because soil moisture differences result from the cumulative effect of HR, the timing of maximum differences in soil moisture lags behind the tim-

Table 5. Root mean square error (RMSE) comparing field observations with modeled output from CLM4.5 or CLM4.5+HR.

Site	Bowen ratio (multi-year, dry period)		Evapotranspiration (multi-year, dry period)		Soil moisture* (multi-year, dry period)		Soil moisture (middle/deep layers) (multi-year, dry period)				
	CLM4.5	CLM4.5 + HR	CLM4.5	CLM4.5 + HR	CLM4.5	CLM4.5 + HR	CLM4.5	CLM4.5 + HR			
US-Wrc	1.36	>**	0.74	0.77	>	0.69	7.09	>	5.92	60 cm: 6.11 100 cm: 8.81 150 cm: 11.56 200 cm: 22.67	60 cm: 7.67 100 cm: 9.86 150 cm: 11.95 200 cm: 23.08
US-SRM	13.30	>	6.84	0.53	>	0.35	2.35	>	1.15	60 cm: 1.36 90 cm: 1.56	60 cm: 0.39 90 cm: 0.47
US-SCs	6.36	>	4.71	0.47	>	0.42	4.65	>	3.85	–	–
US-SCg	2.72	>	1.80	0.53	>	0.54	2.67	>	2.46	–	–
US-SCf	3.35	>	1.09	1.14	>	0.82	2.67	>	2.45	–	–
US-SCw	6.04	>	3.02	0.40	>	0.37	2.30	>	2.36	–	–
US-SCc	5.25	>	5.27	0.42	>	0.44	2.38	>	2.29	–	–
US-SCd	6.02	>	6.05	0.28	>	0.30	1.67	>	1.51	–	–
Site	Bowen ratio (multi-year, dry & wet)		Evapotranspiration (multi-year, dry & wet)		Soil moisture (0–30 cm) (multi-year, dry & wet)		Soil moisture (middle/deep layers) (multi-year, dry & wet)				
US-Wrc	CLM4.5	CLM4.5 + HR	CLM4.5	CLM4.5 + HR	CLM4.5	CLM4.5 + HR	CLM4.5	CLM4.5 + HR			
	2.87	2.94	0.74	0.71	8.39	>	8.01	60 cm: 5.35 100 cm: 8.59 150 cm: 14.45 200 cm: 22.15	<	60 cm: 6.17 100 cm: 9.17 150 cm: 14.65 200 cm: 22.40	
US-SRM	9.13	>	4.11	0.51	>	0.29	1.00	0.88	90 cm: 1.79 60 cm: 2.23	<	60 cm: 1.15 90 cm: 1.12
US-SCs	5.02	>	4.36	0.49	>	0.47	7.18	7.34	–	–	
US-SCg	2.01	>	1.29	0.58	>	0.61	4.85	5.36	–	–	
US-SCf	2.70	>	0.89	0.94	>	0.70	3.02	2.79	–	–	
US-SCw	5.33	>	2.85	0.38	>	0.36	3.51	3.87	–	–	
US-SCc	3.80	>	3.98	0.41	>	0.42	3.60	3.59	–	–	
US-SCd	4.44	>	4.31	0.27	>	0.28	2.43	2.19	–	–	

* Southern California observed soil moisture data were calculated from the average of four (or three, for US-SCd) soil moisture probes.
 ** Differences between CLM4.5 and CLM4.5+HR larger than 0.2 (for Bowen ratio and soil moisture) and 0.05 (for ET) are indicated with ">" or "<". Smaller RMSE indicates improved model fit to data.

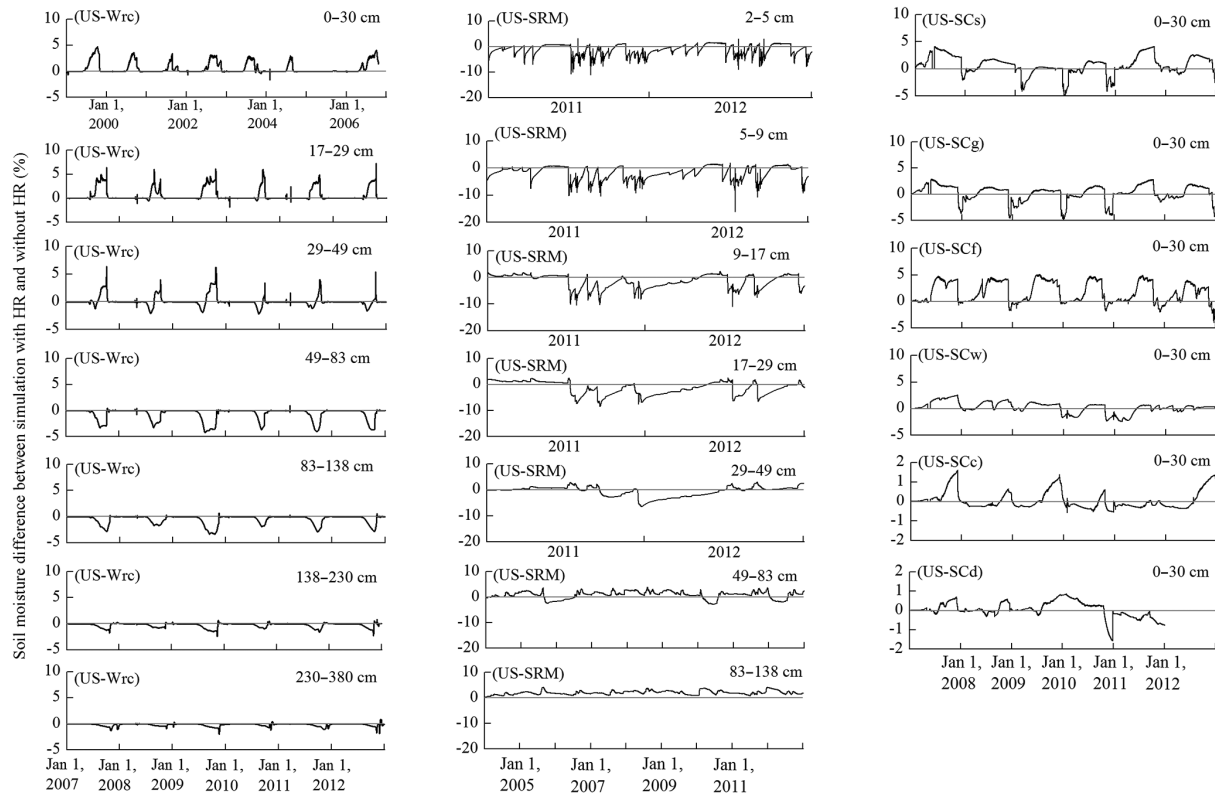


Figure 3. Soil moisture difference between simulations with HR and without HR at each site. Labels at the upper right corner of each panel show the depths of simulated soil moisture.

Table 6. Modeled contribution of HR to ET during dry periods for all simulation years (mean ± SD, columns 3–6).

Site	Dry period (month day ⁻¹)	HL* (mm H ₂ O d ⁻¹)	ET _{without HR} (mm H ₂ O d ⁻¹)	ET _{with HR} (mm H ₂ O d ⁻¹)	HR-induced ET increase (ET _{with HR} – ET _{without HR} ; mm H ₂ O d ⁻¹)	$\frac{HL}{ET_{with HR}}$	Contribution of HR to ET ($\frac{ET_{with HR} - ET_{without HR}}{ET_{with HR}}$; %)
US-Wrc	06/01–09/30	0.60 ± 0.44	1.61 ± 0.82	1.90 ± 0.77	0.29 ± 0.35	0.32	15
US-SRM	05/01–06/30	0.19 ± 0.10	0.34 ± 0.45	0.52 ± 0.39	0.18 ± 0.20	0.37	34
US-SCs	04/01–09/30	0.41 ± 0.18	0.63 ± 0.50	0.89 ± 0.48	0.26 ± 0.17	0.46	29
US-SCg	04/01–09/30	0.48 ± 0.13	0.59 ± 0.46	0.94 ± 0.38	0.35 ± 0.19	0.51	37
US-SCf	04/01–09/30	0.71 ± 0.26	0.85 ± 0.50	1.32 ± 0.47	0.47 ± 0.33	0.53	35
US-SCw	04/01–09/30	0.22 ± 0.07	0.34 ± 0.31	0.47 ± 0.31	0.13 ± 0.10	0.46	29
US-SCc	04/01–09/30	0.10 ± 0.07	0.39 ± 0.42	0.45 ± 0.43	0.06 ± 0.07	0.21	13
US-SCd	04/01–09/30	0.14 ± 0.08	0.34 ± 0.38	0.44 ± 0.36	0.10 ± 0.08	0.31	22

* HL represents hydraulic lift (upward HR).

ing of strongest HR, and the time derivative of the soil moisture difference conceptually reflects the magnitude of HR (Fig. 4 vs. Fig. 5). As shown clearly in Fig. 4, at all sites simulated, the magnitude of soil moisture differences increases with time rather abruptly (indicating HR in action) and decreases with time rather gradually (as soil moisture diffusion takes its course). At the wettest US-Wrc site, modeled upward HR (hydraulic lift) is mainly concentrated during the dry season July–September (~ days 180–270), followed by a short period of weak downward HR (hydraulic descent) during October. Effects of HR on modeled soil water con-

tent persist for a longer time during the year at the other seven sites. At the US-SRM site, hydraulic lift was weak but evident in May and June (just before the North American monsoon season July–September); hydraulic descent could be found throughout the rest of the year, and would reach its maximum during the monsoon season. Among the six southern California sites, a gradient in the vertical and temporal effect of HR on modeled soil moisture was clear. The strongest upward HR occurred at the most moist (but still seasonally dry) US-SCf (Oak Pine) site with deciduous oak trees, followed by US-SCg (Grassland) and US-SCs (Coastal Sage),

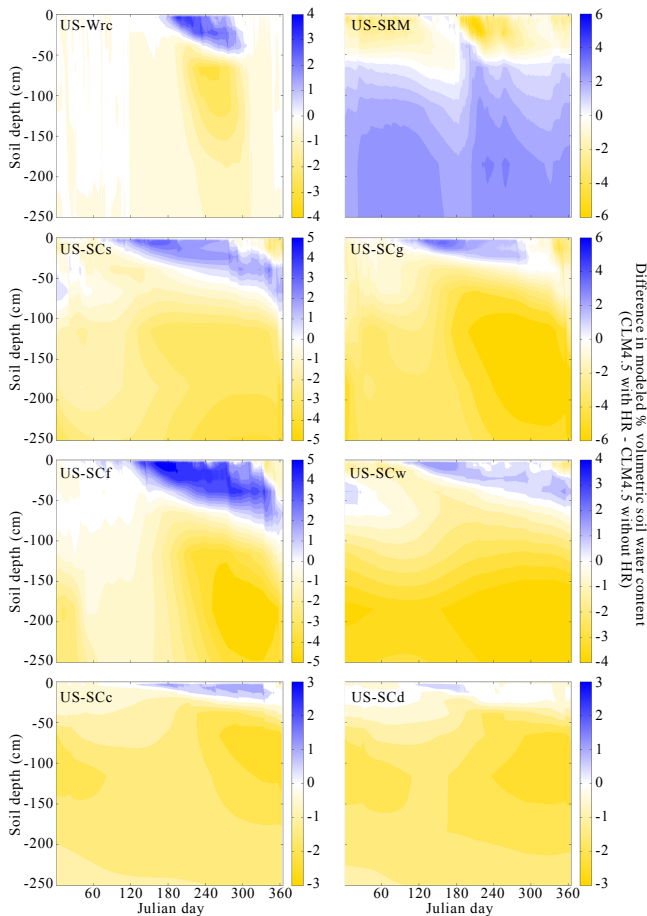


Figure 4. Modeled HR-induced change in volumetric soil moisture at the eight study sites. Results shown here are the averaged values for Julian days over the entire simulation period.

and US-SCw (Pinyon Juniper); at the much drier US-SCc (Desert Chaparral) and US-SCd (Sonoran Desert) sites with sparse vegetation, the temporal spread and depth range of HR influence were far more limited. Still, hydraulic descent occurred during at least a small portion of December (between days 330 and 365) at all southern California US-SC sites. However, despite the small amount of moisture redistributed through HR at the desert sites, HR-induced soil moisture differences of large magnitude persist throughout the year in deeper layers, due to the lack of strong precipitating events to facilitate hydraulic descent and the low hydraulic conductivity in deep soils.

Table 6 shows the average modeled hydraulic lift (in $\text{mm H}_2\text{O d}^{-1}$) during dry periods for all simulation years, for all sites; highest values were found at the two forested sites with highest annual precipitation (0.71 and $0.60 \text{ mm H}_2\text{O d}^{-1}$ for US-SCf and US-Wrc sites, respectively). Modeled hydraulic lift is comparatively small at the US-SRM ($0.19 \text{ mm H}_2\text{O d}^{-1}$) and the three drier south-

ern California sites (US-SCw, US-SCc, and US-SCd: 0.10 – $0.22 \text{ mm H}_2\text{O d}^{-1}$).

3.2 Evapotranspiration observations and simulations

Figure 6 documents the model performance in simulating ET at the daily timescale, at all eight study sites, over multiple years. Figure 6 shows that CLM4.5+HR can simulate ET well at the US-Wrc and US-SRM sites, but tends to underestimate ET during the high ET periods at the six southern California sites. An increase in modeled ET associated with HR during drought can be identified (to various degrees) at all eight sites. Figure 6 and the corresponding RMSE (Table 5) illustrate that including HR leads to improvement in ET simulation at the US-SRM and US-SCf sites during dry periods and year round, and also improvement at the US-SCs and US-Wrc sites during dry periods. At other sites, the corresponding ET simulations from CLM4.5+HR and CLM4.5 are very similar.

Figure 7 shows the average diel cycles of ET and its components during dry and wet periods for all simulation years, at the eight sites (see the notes in the Supplement Sect. S4). From Fig. 7, CLM4.5+HR tended to underestimate the ET peak around noon at the US-Wrc, US-SRM, US-SCf, and US-SCw sites, but reproduced observations fairly well at the US-SCc and US-SCd sites. Under most circumstances, the simulated ET peaks in CLM4.5+HR are closer to observations than those in CLM4.5. HR-induced increase in simulated midday transpiration and subsequent increase of ET can be identified during the dry periods at all eight sites, though it is very weak at US-SCc and US-SCd. Compared to dry periods, HR-induced changes in simulated ET were relatively limited during wet periods at all eight study sites. At the US-SRM site, a decrease of ground evaporation and increase of transpiration were both evident during wet periods, caused by significant hydraulic descent at this site (Figs. 1, 5). The soil water in shallow layers that would otherwise be evaporated was redistributed to deep layers during and after rain events in the monsoon season (July–September), and was eventually consumed by plants during subsequent transpiration.

Table 6 shows the HR-induced increase in ET ($\text{mm H}_2\text{O d}^{-1}$), estimated as the difference in ET between simulations with and without HR. The contribution of HR to ET (unit: %) refers to this difference normalized by the ET from CLM4.5+HR. The HR-induced ET increase is largest at the US-SCf site ($0.47 \text{ mm H}_2\text{O d}^{-1}$), and corresponding ET increase is comparatively small at the US-SRM site ($0.18 \text{ mm H}_2\text{O d}^{-1}$) and the three drier southern California sites (US-SCw, US-SCc, and US-SCd: 0.06 – $0.13 \text{ mm H}_2\text{O d}^{-1}$) (Table 6).

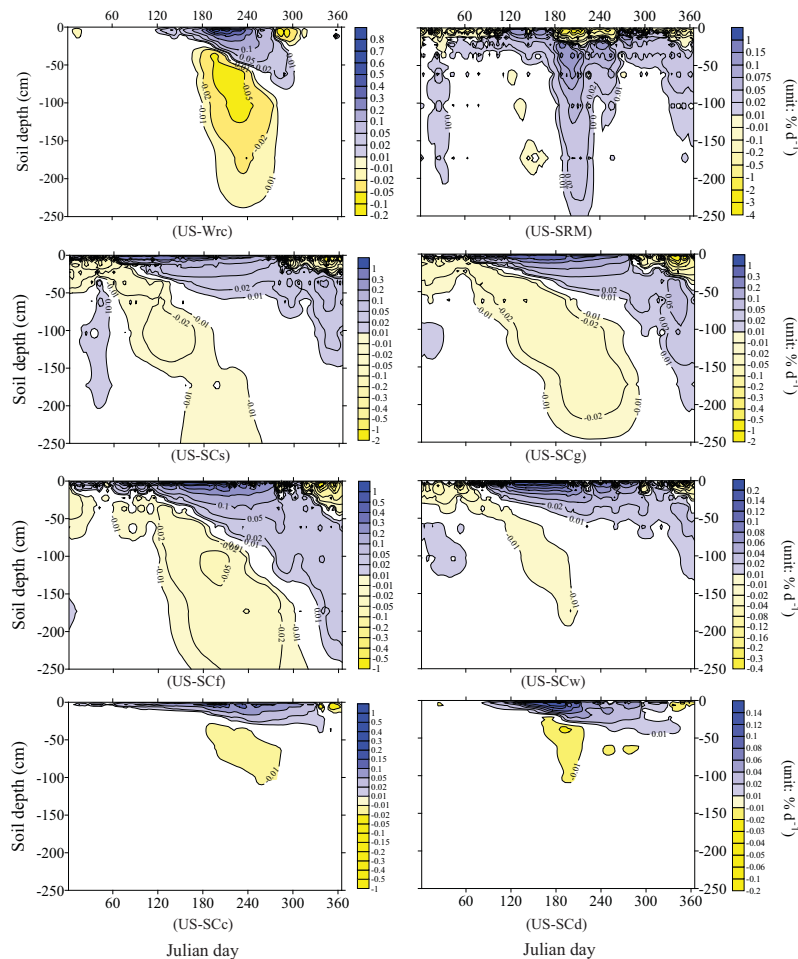


Figure 5. Modeled HR flux, as represented by the amount of soil moisture given or received per day, at the eight study sites. Results shown here are the averaged values for Julian days over the entire simulation period.

3.3 HR-induced Bowen ratio change

The partitioning of surface energy between latent and sensible heat fluxes, often characterized using the Bowen ratio (the ratio of sensible heat to latent heat flux), drives the dynamics of boundary layer growth and subsequently the triggering mechanisms of convective precipitation (Siqueira et al., 2009). The influence of HR on Bowen ratio is therefore important for understanding the broader impact of HR beyond the land surface. Including HR improves the model performance in reproducing the Bowen ratio (Fig. 8, Table 5), especially during dry periods, at all sites except the two driest southern California sites (US-SCc and US-SCd). This indicates that the ET or soil moisture comparison alone does not capture the full benefit of including HR in the model. Instead, HR's impact on ET and soil moisture influences surface temperature and therefore sensible heat flux. The Bowen ratio synthesizes these effects of HR. The better agreement between model and observation in Bowen ratio than in ET may be related to the challenge of the eddy covariance flux

measurement. Since ET (latent heat flux) and sensible heat flux are both derived from the same eddy covariance measurement, potential errors in quantifying the eddy covariance (which are not uncommon as reflected by the energy closure challenge facing many flux tower measurements) are likely to have a much smaller impact on the Bowen ratio estimate than on the magnitude of latent heat flux or sensible heat flux alone.

Combining the modeling results for daily ET into Fig. 9, a larger pattern emerges from the cross-site comparison. Each site is color-coded differently, and HR-induced increases in ET are plotted against shallow soil moisture (0–30 cm, also commonly measured at other field sites). At low soil moisture, the driest southern California gradient sites have little water to redistribute and very sparse vegetation to carry out HR. At high soil moisture, little driving gradient exists to support HR. By including all sites in Fig. 9, it is clear that maximal HR-induced increases in ET primarily occur at sites (and during seasons) with mid-range soil moisture.

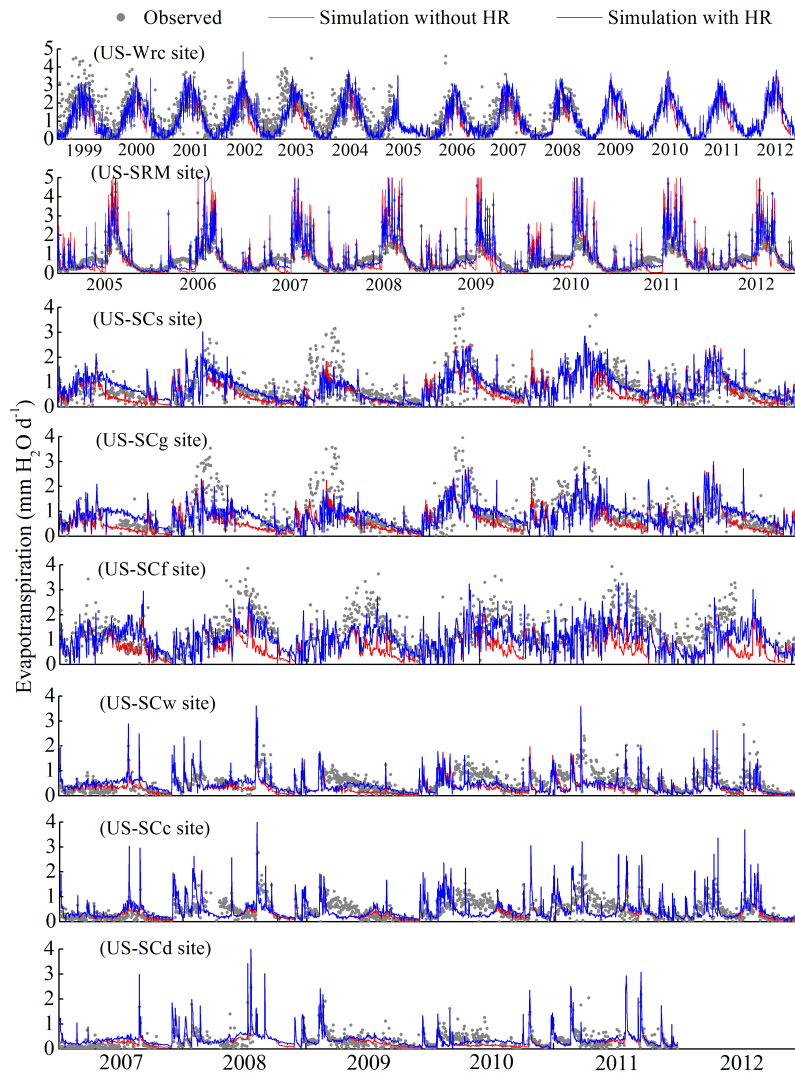


Figure 6. Observed and simulated daily ET at the eight study sites.

3.4 Sensitivity to HR model parameters

The sensitivity of modeled hydraulic lift, hydraulic descent, and contribution of HR to ET (defined in Table 6) to parameters C_{RT} , φ_{50} , and b in the HR scheme of Rye et al. (2002) was tested for four sites (US-Wrc, US-SRM, US-SCs and US-SCw). Both hydraulic lift and hydraulic descent were nearly insensitive to variation in b (ranging from 0.22 to 4.22) (Figs. S11, S12). Variation of approximately one order of magnitude in C_{RT} (from 0.1 to 1.5 cm MPa⁻¹ h⁻¹) and φ_{50} (from -0.5 to -4.0 MPa) resulted in less than a doubling of the magnitude of hydraulic lift, even during the periods with high HR flux (Fig. S11 in the Supplement). However, hydraulic descent was notably more sensitive; increasing C_{RT} from 0.1 to 1.5 cm MPa⁻¹ h⁻¹ resulted in nearly an order of magnitude increase in maximum hydraulic descent at US-Wrc (from ~ 0.1 to ~ 1 mm d⁻¹), and a tripling of hydraulic

descent at the other sites (Fig. S12 in the Supplement). A change in φ_{50} from -4.0 to -0.5 MPa led to at most a tripling of hydraulic descent at all sites. Similarly, the modeled contribution of HR to ET was sensitive to C_{RT} and φ_{50} and insensitive to b (Fig. 10).

4 Discussion

The cross-ecosystem comparisons demonstrate that the timing, magnitude, and direction (upward or downward) of HR vary across ecosystems (Figs. 1, 5), and incorporation of HR into CLM4.5 improved model-measurement match particularly during dry seasons (Table 5). The hydrological impact of HR is substantial in ecosystems that have a pronounced dry season but are not overall so dry that sparse vegetation and very low soil moisture limit HR (Figs. 5, 7, 8). The lack of HR representation in the current generation of land sur-

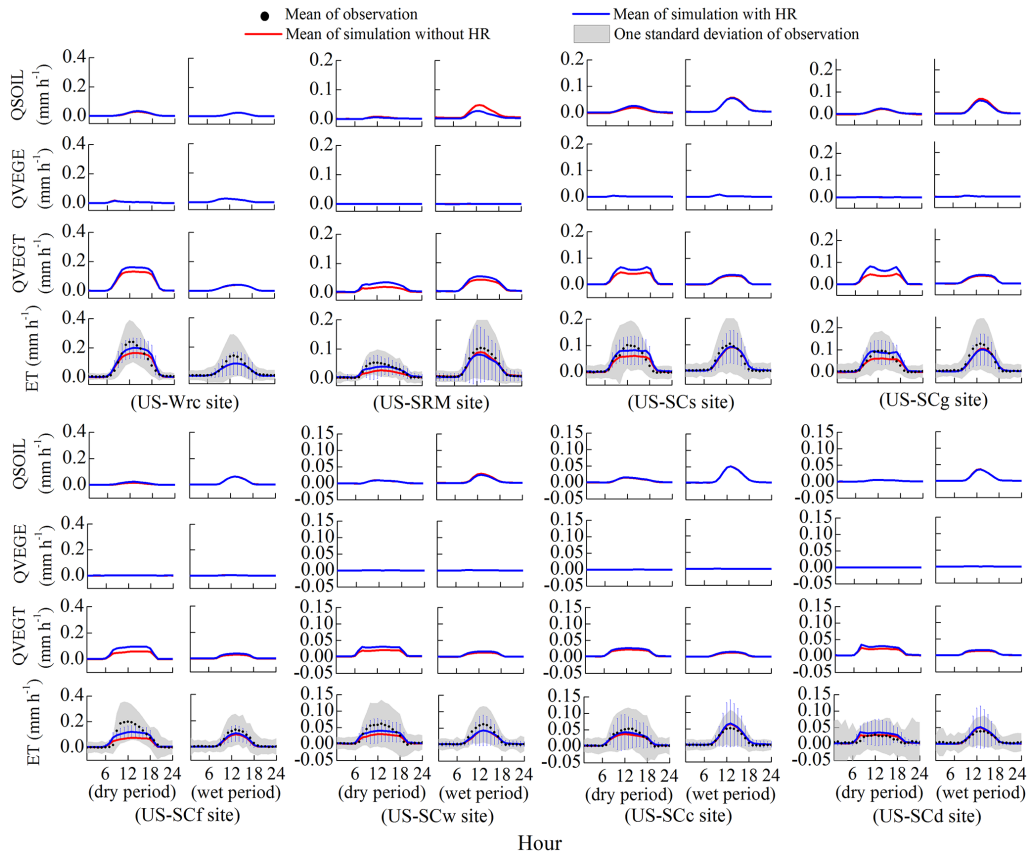


Figure 7. Observed and simulated hourly ET and its components at the eight study sites. “QSOIL” is ground evaporation, “QVEGE” is canopy evaporation, and “QVEGT” is transpiration. “Observation” represents observed ET. “Dry period” and “wet period” represent average values over dry season and wet season (defined in Table 6) for all simulation years, respectively. The thin vertical lines represent 1 standard deviation of simulation with HR.

face or earth system models thus should be considered as a source of error when modeling seasonally dry ecosystems with deep-rooted plant species.

4.1 HR seasonal dynamics and site dependence

Several of the AmeriFlux sites investigated here have hosted previous field investigations of impacts of HR on soil moisture. CLM4.5+HR was able to capture patterns published from those empirical data, and added to those data a more comprehensive view of the seasonal dynamics in the systems (Fig. 5). For example, at US-Wrc (a ~450-year-old stand of Douglas fir), the CLM4.5+HR results indicated that HR-induced soil moisture increases during dry seasons were mainly limited to the upper 60 cm of soil (Fig. 4), which is consistent with field measurements (soil moisture and soil water potential) in a ~20-year-old and a ~450-year-old Douglas fir stand in the Pacific Northwest (Brooks et al., 2002; Brooks et al., 2006; Meinzer et al., 2004). The US-Wrc panel in Fig. 5 also shows that as soil drying progressed, more water was redistributed to depth of 20–60 cm from lower layers in late summer than in early sum-

mer. (It is worth noting that the CLM4.5+HR model does not include the temperature-fluctuation-driven vapor transport within soil shown by Warren et al. (2011) to occur at the site.)

US-Wrc is the site with the highest annual rainfall (>2000 mm yr⁻¹) among those modeled (Table 1), and HR is constrained to the mid-year dry season and dominated by hydraulic lift (Fig. 5). Hydraulic descent is limited with an average value of 5.0 mm H₂O yr⁻¹ during 1999–2012, perhaps because soil moisture is higher with depth, limiting the driving gradient for hydraulic descent. In contrast, hydraulic lift and hydraulic descent are active nearly year round at five of the other seven AmeriFlux sites (Fig. 5). At the two driest sites US-SCc and US-SCd, due to the scarcity of water that can be moved and the sparse vegetation, the HR-associated dynamics in soil water content are relatively subdued (Fig. 4). At the US-SCf site, Kitajima et al. (2013) simulated hydraulic lift from 2007 to 2011 using the HYDRUS-1D model on a daily scale (without simulating the diel fluctuation of soil moisture), and the simulated hydraulic lift averaged ~28 mm per month in July and August, which was

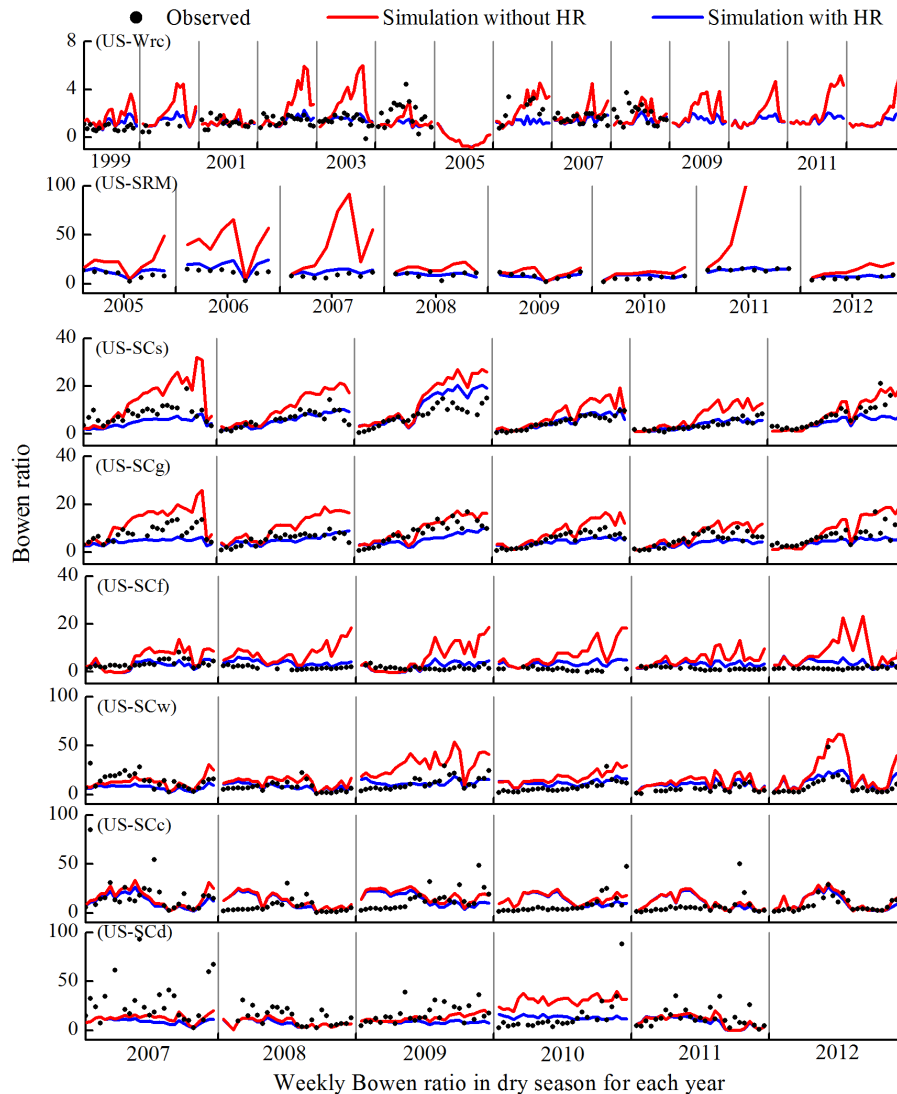


Figure 8. Observed and simulated weekly Bowen ratio during dry periods.

close to the 24.7 mm per month from CLM4.5+HR. The annual hydraulic lift was ~ 112 mm in Kitajima et al. (2013), and was 121 mm in CLM4.5+HR. However, the two modeling approaches are quite different. Kitajima et al. (2013) attributed the source of hydraulic lift to deep moisture in the weathered bedrock, and did not account for the hydraulic redistribution within the soil layers. In contrast, CLM4.5+HR included HR among the soil layers but not the hydraulic lift from deep bedrock. Hydraulic descent occurring after rain was not included in Kitajima et al. (2013), but featured prominently at year end in the output from CLM4.5+HR (Fig. 5, panel US-SCf, right-hand side). The missing representation of hydraulic lift from deep bedrock as shown in Kitajima et al. (2013) is also a possible reason for the reduced model performance in soil moisture modeling at depth for a site like US-Wrc.

Though sap flow indicated little hydraulic lift during 2004–2005 (Scott et al., 2008), CLM4.5+HR simulated significant hydraulic lift during dry periods at the US-SRM site (Fig. 5), and diel fluctuations of soil moisture indicative of HR were observed during soil drydown (Fig. 2). Scott et al. (2008) calculated hydraulic descent using the downward flow in taproots, and calculated hydraulic lift using lateral root flow moving away from the tree base. Flow was more concentrated and more easily measured in the taproot than in lateral roots, which was considered the reason why hydraulic descent was far more detectable than hydraulic lift.

4.2 HR-induced evapotranspiration change

The influence of HR on transpiration and/or ET has been estimated in many studies, including at sites studied here. At the US-Wrc site, Brooks et al. (2002) used diel fluctuations

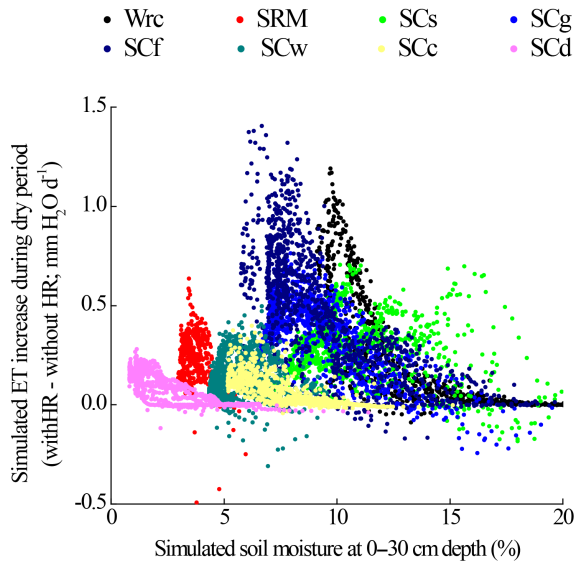


Figure 9. Simulated changes in ET caused by HR as a function of soil moisture at all eight sites.

in soil moisture, and total soil water use, to calculate that HR supplied about 28 % of the total daily water use from the top 2 m soil layer in a 20-year-old Douglas fir stand during dry August, comparable to the 32 % estimated here (Table 6). At the US-SRM site and seasonal scale, Scott et al. (2008) reported that the hydraulic descent during the dormant season (DOY 31–109) represented 15–49 % of the estimated transpiration of the growing season (DOY 110–335) in 2004; the corresponding simulated value during the same period in the present study is 36 %. ET was notably underestimated at the US-SCf site by both CLM4.5+HR and HYDRUS-1D (Kitajima et al., 2013). The lack of hydraulic lift from bedrock in this study, and the lack of HR within soil layers in Kitajima et al. (2013) might be reasons for this underestimation.

4.3 Sources of uncertainty

Results in this study are subject to uncertainties from a number of sources. As noted in the methods, data essential for the CLM4.5 and HR models were drawn from each site when available, but otherwise were drawn from large data sets commonly used in large-scale models (Table 2). Also, as noted in the methods and notes in the Supplement Sect. S2, soil moisture measurements were challenging at the southern California sites because large temperature gradients developed along CS-616 probes, soils dried outside the range of CS-229 probes, and there appeared to be a thermal gradient between reference thermistor and sensor connection points in measurement junction boxes aboveground. More subtle and interesting sources of uncertainty also likely influenced the model-measurement match. For example, strong inter-annual variation of precipitation, fire, and recovery from fire caused rather abrupt changes of PFT coverage and LAI at

the US-SCs site. The US-SCg site is undergoing restoration to a native grassland community, and a large community of ephemeral annuals comes up following winter or summer rains at the US-SCc site. These variations were difficult to capture by satellite remote sensing data but undoubtedly affected soil moisture and ET in interesting ways. Without detailed ground-observational data to quantify them, simulations in this study used a climatological LAI seasonal cycle.

Another potentially important source of uncertainty is the parameters C_{RT} , b , and φ_{50} in the HR model. Quantifying these parameters remains a major challenge. Results from our sensitivity experiments show that CLM4.5+HR output is relatively insensitive to variation in the parameter b , so of the three parameters, giving b a default value is least problematic. As shown in Ryel et al. (2002), maximum conductance C_{RT} can be determined from site-specific data (soil moisture, soil water potential, and root distribution). But in the absence of such data, an approach might be developed based on the hypothesis that in any ecosystem there must be sufficient maximum soil–whole plant conductance (C_{RT}) to support the annual maximum observed LAI when soil is saturated (Wullschleger et al. 1998). Determining a reasonable way to estimate φ_{50} may require the most effort. Field measurements combined with modeling may be necessary to enable setting the value of φ_{50} and to ground truth a relationship between C_{RT} and annual maximum LAI, ideally across a range of ecosystem types, vegetation densities, soil textures, and/or other site-specific properties that are already input variables for earth system models. In addition, the effects of several important factors warrant further investigation, including, for example, the root architecture (Yu and D’Odorico, 2014), dynamic root water uptake (Zheng and Wang, 2007), deep tap roots (Markewitz et al., 2010), above-ground storage capacity (Hultine et al., 2003), temperature fluctuation-driven vapor transport within soil (Warren et al., 2015), and macro-pore flow (Fu et al., 2012, 2014). It is also important to compare different representations of HR models (Amenu and Kumar, 2008; Quijano and Kumar, 2015) to examine uncertainties related to model structure.

5 Main findings

The key findings in this study are as follows:

- Simulated hydraulic lift was largest at the two forested sites with highest annual rainfall (0.60 US-Wrc and $0.71 \text{ mm H}_2\text{O d}^{-1}$ US-SCf; Table 6), and smallest at US-SRM and the three driest southern California sites (from 0.10 US-SCc to $0.22 \text{ mm H}_2\text{O d}^{-1}$ US-SCw; Table 6).
- Hydraulic descent was a dominant hydrologic feature during wet seasons at semi-arid US-SRM (Figs. 1, 4) and four (moister) of the six southern California sites (Fig. 4, Figs. S2–S6 in the Supplement) with annual pre-

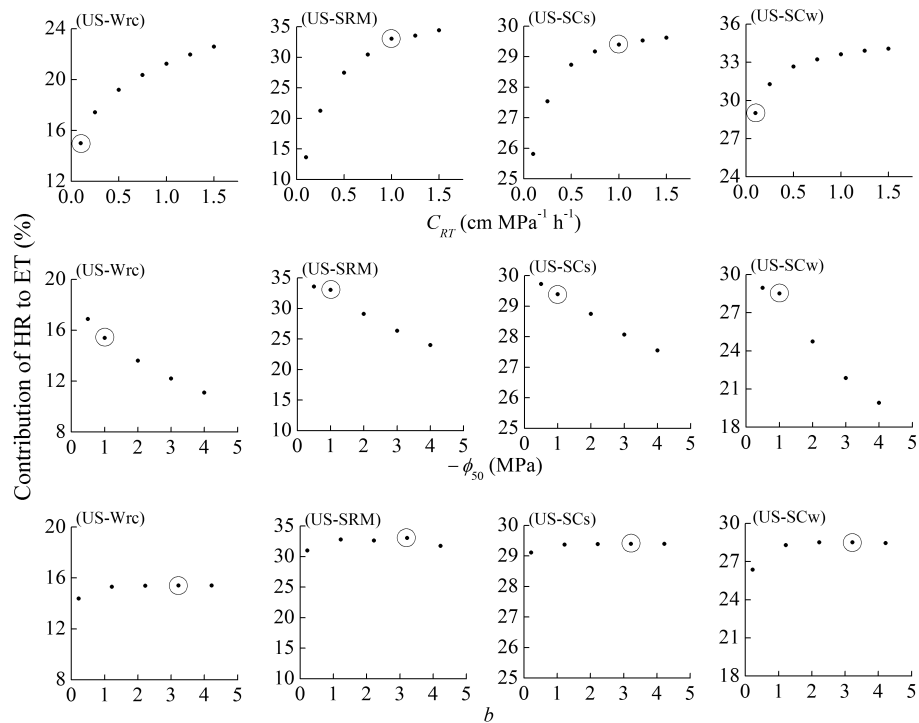


Figure 10. Sensitivity of simulated contribution of HR to ET (defined in Table 6) to selected parameters in the HR scheme of Ryel et al. (2002). Circled parameter set was used in Table 6.

precipitation $\leq \sim 500$ mm (Table 1), contributing to significant dynamism in soil moisture at depth.

- HR caused modeled ET to increase, particularly during dry periods; values for the increase ranged from 0.06, 0.10, and 0.13 mm H₂O d⁻¹ at the driest sites (US-SCc, US-SCd, and US-SCw, respectively; Table 6) to 0.18, 0.26, 0.29, 0.35, and 0.47 mm H₂O d⁻¹ at the wetter sites (US-SRM, US-SCs, US-Wrc, US-SCg, and US-SCf, respectively; Table 6).
- Measurement and modeling both demonstrate that the timing, magnitude, and direction (upward or downward) of HR vary across ecosystems, and incorporation of HR into CLM4.5 improved model-measurement match for Bowen ratio, evapotranspiration, and soil moisture (e.g. shallow layers), particularly during dry seasons.
- Modeling and measurements indicate that HR has hydrological impact (on evapotranspiration, Bowen ratio, and soil moisture) in ecosystems that have a pronounced dry season but are not overall so dry that sparse vegetation and very low soil moisture limit HR.
- CLM4.5+HR output was relatively insensitive to variation in the parameter b in the HR scheme of Ryel et al. (2002), but was somewhat sensitive to variation in C_{RT} and φ_{50} . Variation of approximately an order of

magnitude in C_{RT} and φ_{50} resulted in less than a doubling of the magnitude of hydraulic lift during the periods with high HR flux, but hydraulic descent was more sensitive.

Previous modeling studies either focus on model–data comparison at one site or conduct large scale simulations with few concrete data to compare against, making it very difficult to answer the fundamental question: when and where must HR be included to appropriately model hydrologic characteristics of diverse ecosystems? HR has been confirmed in various ecosystems where plant root systems span soil water potential gradients (Neumann and Cardon, 2012; Prieto et al., 2012; Sardans and Peñuelas, 2014). For this reason, one might argue that HR should be included for all ecosystems. However, our comparative study using combined empirical data and modeling helps hone the answer by including eight AmeriFlux sites that differ in vegetation, soil, and climate regimes. The summary suggestions are (a) hydrological modeling will not be clearly influenced if not including HR for overall drier sites that have little water to redistribute and sparse vegetation to carry out HR and overall wetter sites/periods that are likely to develop little driving gradient to support HR, while HR should be included for the seasonally dry ecosystems with mid-range annual rainfall and soil moisture, and (b) quantifying parameters in the HR model is a key if including HR in hydrological modeling.

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